

Solid Mechanics and Its Applications

Volume 198

Series Editor

G.M.L. Gladwell

Department of Civil Engineering, University of Waterloo, Canada

For further volumes:

<http://www.springer.com/series/6557>

Aims and Scope of the Series

The fundamental questions arising in mechanics are: *Why?*, *How?*, and *How much?* The aim of this series is to provide lucid accounts written by authoritative researchers giving vision and insight in answering these questions on the subject of mechanics as it relates to solids.

The scope of the series covers the entire spectrum of solid mechanics. Thus it includes the foundation of mechanics; variational formulations; computational mechanics; statics, kinematics and dynamics of rigid and elastic bodies: vibrations of solids and structures; dynamical systems and chaos; the theories of elasticity, plasticity and viscoelasticity; composite materials; rods, beams, shells and membranes; structural control and stability; soils, rocks and geomechanics; fracture; tribology; experimental mechanics; biomechanics and machine design.

The median level of presentation is the first year graduate student. Some texts are monographs defining the current state of the field; others are accessible to final year undergraduates; but essentially the emphasis is on readability and clarity.

André Preumont

Twelve Lectures on Structural Dynamics

 Springer

André Preumont
Active Structures Laboratory
Université Libre de Bruxelles
Brussels
Belgium

ISSN 0925-0042
ISBN 978-94-007-6382-1 ISBN 978-94-007-6383-8 (eBook)
DOI 10.1007/978-94-007-6383-8
Springer Dordrecht Heidelberg New York London

Library of Congress Control Number: 2013932555

© Springer Science+Business Media Dordrecht 2013

This work is subject to copyright. All rights are reserved by the Publisher, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilms or in any other physical way, and transmission or information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed. Exempted from this legal reservation are brief excerpts in connection with reviews or scholarly analysis or material supplied specifically for the purpose of being entered and executed on a computer system, for exclusive use by the purchaser of the work. Duplication of this publication or parts thereof is permitted only under the provisions of the Copyright Law of the Publisher's location, in its current version, and permission for use must always be obtained from Springer. Permissions for use may be obtained through RightsLink at the Copyright Clearance Center. Violations are liable to prosecution under the respective Copyright Law. The use of general descriptive names, registered names, trademarks, service marks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

While the advice and information in this book are believed to be true and accurate at the date of publication, neither the authors nor the editors nor the publisher can accept any legal responsibility for any errors or omissions that may be made. The publisher makes no warranty, express or implied, with respect to the material contained herein.

Printed on acid-free paper

Springer is part of Springer Science+Business Media (www.springer.com)

Il n'y a que la vérité qui persuade, même sans avoir besoin de paraître avec toutes les preuves.

Elle entre si naturellement dans l'esprit, que quand on l'apprend pour la première fois, il semble qu'on ne fasse que s'en souvenir.

Fontenelle

Entretiens sur la pluralité des mondes (1686)

Preface

Nowadays, with the amazing computing capability of computers and the availability of sophisticated, user-friendly computer-aided analysis software, the main difficulty for the analyst is to interpret the results and to make sure that the analysis includes all the relevant physical phenomena. The majority of structural failures occur because physical phenomena are overlooked, or greatly underestimated, rather than as a result of computational errors (e.g., the flutter of the Takoma suspension bridge, or the recent Fukushima tsunami disaster). To build confidence in the design, the analyst first develops a crude model, a model of minimum complexity which still reflects the main physical phenomena. What minimum complexity means depends on the problem; for example, a point mass with two degrees of freedom is sufficient to explain the stable operation of a rotor at supercritical velocities, but it is impossible to account for the dependency of the natural frequencies on the rotor speed without including the gyroscopic effects; the effect of prestresses on the natural frequencies cannot be accounted for without the inclusion of nonlinear strains (Green strain tensor). Similarly, analytical results may appear unnecessary at a time where extensive parametric studies may be performed numerically very quickly, but knowledge of the parametric dependence of critical properties such as natural frequency on design parameters (dimensions, material properties,...) is invaluable in design, especially when scale effects are involved.

This book is based on the vibration course that I teach in the joint masters program ULB/VUB at the university of Brussels, and the random vibration course that I taught for a decade at the university of Liege. It has also been strongly influenced by my research work in the active control of structures, where we usually work with models of moderate size, but which accounts for all the relevant features of the system dynamics. The book is focused on modeling, with very little, if any, attention paid to the numerical methods that I consider as mature and well established, and which are well covered in the excellent books written by those more qualified than me (e.g., Geradin and Rixen).

I would like to pay a tribute to my own teachers at the university of Liege where I was initiated into structural analysis. Some 40 years later, I still have vivid memories of the sparkling lectures of Prof. Ch. Massonnet on the strength of materials and of Prof. B. Fraeijs de Veubeke on vibrations (all without notes); and

later Michel Geradin advised me during my doctorate. Reading the wonderful books from S. H. Crandall; Y. C. Fung; Y. K. Lin; and L. Meirovitch, and a few others also made a lasting impression on me. Finally, I wish to thank my coworkers at ULB for their enthusiasm and raising many questions that I have attempted to answer in this book. A special thanks goes to Renaud Bastaits who helped me to produce these notes, and did artfully most of the figures.

Bruxelles, December 2012

André Preumont

Contents

1	Single Degree-of-Freedom Linear Oscillator	1
1.1	Free Response	1
1.2	Impulse Response	3
1.3	Convolution Integral	5
1.4	Harmonic Response	5
	1.4.1 Undamped Oscillator	5
	1.4.2 Damped Oscillator	7
1.5	Frequency Response Function	8
1.6	Beat Phenomenon	10
1.7	State Space Form	11
1.8	Problems	12
2	Multiple Degree-of-Freedom Systems	15
2.1	Governing Equations	15
2.2	Free Response of the Undamped System	18
	2.2.1 Eigenvalue Problem	18
	2.2.2 Orthogonality Relationships	20
	2.2.3 Multiple Natural Frequencies	21
	2.2.4 Rigid Body Modes	21
	2.2.5 Free Response From Initial Conditions	22
2.3	Modal Decomposition	23
	2.3.1 Modal Truncation	24
2.4	Damping	24
2.5	Dynamic Flexibility Matrix	25
	2.5.1 Structure with Rigid Body Modes*	28
	2.5.2 Example*	30
2.6	Anti-Resonances	32
	2.6.1 Anti-Resonances and Constrained System	34
2.7	Natural Frequencies of a n-storey Building*	36
2.8	Problems	38

3	Lagrangian Dynamics	43
3.1	Introduction	43
3.2	Generalized Coordinates, Kinematic Constraints	44
3.2.1	Virtual Displacements	46
3.3	Principle of Virtual Work	47
3.4	D'Alembert's Principle	49
3.5	Hamilton's Principle	50
3.6	Lagrange's Equations	53
3.6.1	Vibration of a Linear Non-gyroscopic Discrete System	55
3.6.2	Dissipation Function	55
3.6.3	Example 1: Pendulum with a Sliding Mass	56
3.6.4	Example 2: Rotating Pendulum	57
3.6.5	Example 3: Rotating Spring Mass System	59
3.6.6	Example 4: Gyroscopic Effects	60
3.7	Lagrange's Equations with Constraints	63
3.8	Conservation Laws	64
3.8.1	Jacobi Integral	64
3.8.2	Ignorable Coordinate	66
3.8.3	Example: The Spherical Pendulum	67
3.9	Prestresses, Geometric Strain Energy	68
3.9.1	Green Strain Tensor	68
3.9.2	Geometric Strain Energy Due to Prestress	70
3.9.3	Buckling	72
3.10	Negative Stiffness	73
3.11	Problems	74
4	Continuous Systems	77
4.1	Planar Vibration of a Beam (Euler–Bernoulli)	77
4.1.1	Hamilton's Principle	79
4.2	Beam with Axial Prestress	82
4.3	Free Vibration of a Beam	83
4.3.1	Decoupling the Boundary Conditions	84
4.3.2	Simply Supported Beam	85
4.3.3	Free–Free Beam	87
4.4	Orthogonality Relationships	89
4.5	Modal Decomposition	91
4.6	Vibration of a String	92
4.7	Axial Vibration of a Bar	94
4.7.1	Free Vibration	95
4.8	Static Buckling of a Beam*	96
4.8.1	Simply Supported Beam	97
4.8.2	Clamped-Free Beam	98

4.9	Bending Vibration of Thin Plates*	99
4.9.1	Kirchhoff Plate.	99
4.9.2	Free Vibration of a Simply Supported Rectangular Plate	101
4.9.3	Free Vibration of a Clamped Circular Plate	103
4.9.4	Rotating Modes	107
4.10	Response of a Disk to a Rotating Point Force*	108
4.10.1	Constant Rotating Point Force	108
4.10.2	Harmonic Rotating Point Force	110
4.11	Problems	111
5	Rayleigh-Ritz Method	113
5.1	Introduction	113
5.2	Shape Functions	114
5.3	Axial Vibration of a Bar	116
5.4	Planar Vibration of a Beam	119
5.4.1	Damping	121
5.4.2	Beam with Axial Load	122
5.4.3	Simply Supported Beam with Uniform Axial Load.	123
5.5	Rayleigh Quotient.	124
5.5.1	Continuous Beam	124
5.5.2	Discrete System	125
5.5.3	Principle of Stationarity.	125
5.5.4	Recursive Search of Eigenvectors.	127
5.6	Building with Gravity Loads	128
5.6.1	Single Storey Building	128
5.6.2	Building with n -Identical Floors.	130
5.7	Problems	130
6	Finite Elements	135
6.1	Introduction	135
6.2	Formulation for a Plane Truss	136
6.2.1	Bar Element.	137
6.2.2	Truss Structure	138
6.3	Planar Structure Made of Beams	140
6.3.1	Beam Element	140
6.3.2	Beam Structure.	143
6.3.3	Boundary Conditions.	143
6.3.4	Convergence	145
6.3.5	Geometric Stiffness of a Planar Beam Element	146
6.4	Guyan Reduction	147
6.4.1	Examples.	149

6.5	Craig-Bampton Reduction	153
6.6	Problems	154
7	Seismic Excitation	155
7.1	Introduction	155
7.2	Equation of Motion for a Single Axis Excitation	156
	7.2.1 Modal Coordinates	158
	7.2.2 Support Reaction, Dynamic Mass	159
7.3	Example: n -storey Building	161
7.4	Multi-Axis Excitation*	162
	7.4.1 Modal Coordinates	163
	7.4.2 Support Reactions	165
7.5	Cascade Analysis	166
7.6	Problems	167
8	Random Vibration	169
8.1	Introduction	169
8.2	Stationary Random Process	170
8.3	Correlation Function and Power Spectral Density	170
	8.3.1 PSD Estimation from Time Histories	172
	8.3.2 Cumulative Mean Square Response	173
	8.3.3 Gaussian Process	174
	8.3.4 White Noise	174
8.4	Stationary Response of a SISO Linear System	175
	8.4.1 Random Response of a Linear Oscillator	176
	8.4.2 White Noise Approximation	177
	8.4.3 Band Limited White Noise Excitation	178
	8.4.4 Kanai-Tajimi Spectrum	179
8.5	Spectral Moments, Rice Formulae, Central Frequency	179
8.6	Envelope of a Narrow Band Process	181
8.7	FRF Estimation and Coherence Function	182
8.8	Random Response of MIMO Systems	184
	8.8.1 Response in Modal Coordinates	185
	8.8.2 Correlation and PSD Matrices	187
	8.8.3 Boundary Layer Noise	188
	8.8.4 Wind Response of a Tall Building	189
	8.8.5 Vehicle Moving on a Rough Road	191
8.9	Mean Square Response	192
	8.9.1 Role of the Cross-Correlations	193
8.10	Example: The Seismic Response of a n -storey Building	195
8.11	Problems	196

9	Peak Factor and Random Fatigue	201
9.1	Introduction	201
	9.1.1 Threshold Crossings	202
	9.1.2 Fatigue	202
9.2	Peak Factor	202
	9.2.1 Maxima	202
	9.2.2 First-Crossing Problem	203
	9.2.3 Peak Factor	206
9.3	Response Spectrum	206
	9.3.1 Maximum Structural Response	208
	9.3.2 Relation Between $S_v(\omega, \xi)$ and $\Phi_0(\omega)$	210
9.4	Random Fatigue	211
	9.4.1 S–N Curve	211
	9.4.2 Linear Damage Theory	211
	9.4.3 Uniaxial Loading	212
	9.4.4 Biaxial Loading	213
	9.4.5 Finite Element Formulation	215
9.5	Problems	215
10	Rotor Dynamics	217
10.1	Introduction	217
10.2	Jeffcott Rotor	218
	10.2.1 Unbalance Response	219
	10.2.2 Complex Coordinates	220
	10.2.3 Free Whirl	221
	10.2.4 Jeffcott Rotor with Viscous Damping	221
	10.2.5 Stability in Presence of Damping	223
10.3	Gyroscopic Effects	224
	10.3.1 Kinetic Energy of a Rigid Disk	226
	10.3.2 Dynamics Including Gyroscopic Effects	228
	10.3.3 Free Whirl, Campbell Diagram	229
	10.3.4 Unbalance Response	231
	10.3.5 Response to an Asynchronous Force	232
10.4	Rigid Rotor on Elastic Supports	232
10.5	Anisotropy of the Shaft and the Supports	236
	10.5.1 Anisotropic Supports	236
	10.5.2 Anisotropic Shaft	238
	10.5.3 Unbalance Response of an Anisotropic Shaft	240
	10.5.4 Stability of an Anisotropic Shaft	241
10.6	Vibrating Angular Rate Sensor	243
10.7	Problems	244

11 Vibration Alleviation 247

11.1 Introduction 247

11.2 Dynamic Vibration Absorber 249

11.3 Narrow Band Disturbance 250

11.4 Wide Band Disturbance. 250

 11.4.1 Equal Peak Design 252

11.5 Multiple d.o.f. Systems 255

11.6 Example: n-storey Building 256

 11.6.1 Model Construction. 256

 11.6.2 Design of the DVA. 258

 11.6.3 Random Response of the Structure with DVA 258

11.7 Vibration Isolation 259

11.8 Linear Isolator 260

11.9 Relaxation Isolator 263

11.10 Six-Axis Isolator. 266

11.11 Isolation by Kinematic Coupling 268

11.12 Centrifugal Pendulum Vibration Absorber 270

11.13 Model of a Car Suspension 271

11.14 Problems 274

12 Introduction to Active Vibration Control 275

12.1 The Virtue of Collocated Control 275

 12.1.1 Collocated Control 278

 12.1.2 Non-collocated Control 279

12.2 Active Suspension: The “Sky-Hook” Damper 279

12.3 Active Mass Damper. 281

 12.3.1 System Modeling 284

 12.3.2 System Response 285

12.4 Active Truss 286

 12.4.1 Open-Loop Transfer Function 289

 12.4.2 Active Damping by Integral Force Feedback 290

 12.4.3 Beta Controller. 293

12.5 Problems 295

References 297

Index 301