

# Chapter 1

## Introduction

This book is devoted to the development of a calculus of variations that can apply to a large number of partial differential systems and evolution equations, many of which do not fit in the classical Euler-Lagrange framework. Indeed, the solutions of many equations involving nonlinear, nonlocal, or even linear but non self-adjoint operators are not normally characterized as critical points of functionals of the form  $\int_{\Omega} F(x, u(x), \nabla u(x)) dx$ . Examples include *transport equations* on a smooth domain  $\Omega$  of  $\mathbf{R}^n$  such as

$$\begin{cases} \sum_{i=1}^n a_i \frac{\partial u}{\partial x_i} + a_0 u = |u|^{p-1} u + f & \text{on } \Omega \subset \mathbf{R}^n, \\ u(x) = 0 & \text{on } \Sigma_-, \end{cases} \quad (1.1)$$

where  $\mathbf{a} = (a_i)_i : \overline{\Omega} \rightarrow \mathbf{R}^n$  is a given vector field,  $p > 1$ ,  $f \in L^2(\Omega)$ , and  $\Sigma_-$  is the entrance set  $\Sigma_- = \{x \in \partial\Omega; \mathbf{a}(x) \cdot \mathbf{n}(x) < 0\}$ ,  $\mathbf{n}$  being the outer normal on  $\partial\Omega$ .

Another example is the equation

$$\begin{cases} \operatorname{div}(T(\nabla f(x))) = g(x) & \text{on } \Omega \subset \mathbf{R}^n, \\ f(x) = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.2)$$

where  $T$  is a monotone vector field on  $\mathbf{R}^n$  that is not derived from a potential.

Similarly, dissipative initial-value problems such as the *heat equation*, *porous media*, or the *Navier-Stokes evolution*

$$\begin{cases} \frac{\partial u}{\partial t} + (u \cdot \nabla)u + f = \alpha \Delta u - \nabla p & \text{on } \Omega \subset \mathbf{R}^n, \\ \operatorname{div} u = 0 & \text{on } [0, T] \times \Omega, \\ u = 0 & \text{on } [0, T] \times \partial\Omega, \end{cases} \quad (1.3)$$

where  $\alpha > 0$  and  $f \in L^2([0, T] \times \Omega)$ , cannot be solved by the standard methods of the calculus of variations since they are not Euler-Lagrange equations of action functionals of the form  $\int_0^T L(t, x(t), \dot{x}(t)) dt$ . Our goal here is to describe how these examples and many others can still be formulated and resolved variationally by means of a *self-dual variational calculus* that we develop herein.

The genesis of our approach can be traced to physicists who have managed to formulate – if not solve – variationally many of the basic nonself-adjoint equations of quantum field theory by minimizing their associated action functionals. Indeed,