

D

List of Notations

Notation	Description	First occurrence
$I = [0, T]$	time interval	2.3
$\mathcal{G} \in \mathbb{R}^d, \mathcal{G}_h \in \mathbb{R}^d$	continuous and discrete computational domain	2.3
ρ_h	discrete (scalar) variable corresponding to ρ	2.3
τ	element of a triangulation	2.3
h	mesh size parameter, also used as discrete subscript	2.4
η, η_τ	(local) refinement criterion	2.3
$\theta_{\text{ref}}, \theta_{\text{crs}}$	refinement/coarsening tolerance	2.4
\mathcal{T}	a triangulation	2.4
$\mathcal{T}_1 \prec \mathcal{T}_2$	hierarchically refined triangulations	3.1.7
ϑ	inner angle of triangulation	3.1
v_i	vertex of a triangulation	3.3
$\tau^{3\text{D}}$	element/tetrahedron in 3D triangulation	3.4
(λ, ϕ, r)	spherical coordinates	3.5
∂_x, ∂_t	first order partial differential operators	4.2.1
Δ	Laplace's operator	4.2.2
$\mathcal{L}, \mathcal{E}, \mathcal{R}$	Load balancing, edge cut, and re-partitioning cost	B
$G(V, E)$	graph with vertex set V and edges E	5.1
$\Delta x, \Delta t$	spatial and time step	3.5, 4.2.1
$\cdot _x, \cdot _y$	x - and y -component of (\cdot)	6.1.1
b, b_i	usually a basis function	6.1.3
$\mathcal{V}, \mathcal{V}_h$	continuous and discrete function space	6.1.3
$\varepsilon, [\varepsilon]$	true error and error estimate	2.4, 2.6.3
δ_{ij}	Dirac delta function	6.1.3
$\mathcal{D}, \mathcal{D}^*$	abstract differential operator, and adjoint	6.1.3, 8.2
φ	radial basis function	6.1.4

Notation continued:		
Notation	Description	First occurrence
$\tilde{\mathbf{x}}$	trajectory or particle path	A
$V(t), V$	material volume, control volume	A, 7.2.2
$\frac{d}{dt}$	material derivative	A
\mathbf{n}	outward unit normal	A.0.1
σ_{surf}	surface stress tensor	7.1.2
\mathcal{F}	force term	7.1.2
Ω	angular velocity	C
\mathbf{v}	velocity (vector)	C
Φ	geopotential height	C
f_C	Coriolis parameter	C
∇_s, Δ_s	tangential gradient/divergence, and Laplacian	C, 8.3.1

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