

Appendix

A.1 Simple Linear Algebra

For the vector $x \in \mathbf{R}^n$ we use $|x|$ to denote the Euclidean norm. For two vectors $x, y \in \mathbf{R}^n$ we denote their inner product by

$$\langle x, y \rangle := \sum_{i=1}^n x_i y_i .$$

For an $n \times n$ -matrix A we use $|A|$ to denote the operator norm, i.e.

$$|A| = \sup\{|Ax| : x \in \mathbf{R}^n \text{ and } |x| \leq 1\} .$$

It is easy to see that other norms are equivalent.

By I we denote the unit $n \times n$ -matrix with 1 on the diagonal and 0 elsewhere. We use the notation $\text{adj } A$ to denote the adjoint (or adjugate) matrix of matrix A . It contains the $(n-1) \times (n-1)$ -subdeterminants of the matrix A and it satisfies the formula

$$A \text{ adj } A = I \det A, \tag{A.1}$$

where $\det A$ denotes the determinant of A .

A.2 Covering Theorems

We use covering theorems to select subcollections that consists of balls B_j that are disjoint or that have bounded overlap.

Theorem A.1 (Vitali). *Let \mathcal{B} be a collection of closed balls in \mathbf{R}^n such that*

$$\sup\{\text{diam } B : B \in \mathcal{B}\} < \infty.$$

Then there are B_1, B_2, \dots (possibly a finite sequence) from this collection such that $B_i \cap B_j = \emptyset$ for $i \neq j$ and

$$\bigcup_{B \in \mathcal{B}} B \subset \bigcup_j 5B_j.$$

For a proof we refer the reader to [95]. Let us anyhow briefly explain the idea in a simple case. Suppose that the family \mathcal{B} consists of balls $B(x, r_x)$, where $x \in A$ and A is bounded. Let $M = \sup_{x \in A} r_x$. Choose a ball $B_1 = B(x, r_x)$ so that $r_x > 3M/4$. Continue by considering points in $A \setminus 3B_1$, and repeating the first step (now letting $M_1 = \sup_{y \in A \setminus 3B_1} r_y$) and after that continue by induction.

In the Euclidean setting, a subcollection often can be chosen so that we only have uniformly bounded overlap for the cover.

Theorem A.2 (Besicovitch). *Let \mathcal{B} be a collection of closed balls in \mathbf{R}^n such that the set A consisting of the centers is bounded. Then there is a countable (possibly finite) subcollection B_1, B_2, \dots such that*

$$\chi_A(x) \leq \sum_j \chi_{B_j}(x) \leq C(n)$$

for all x .

In more general settings, say, in the Heisenberg group, Besicovitch fails. The reason it holds in the Euclidean setting, is basically the following geometric fact:

Suppose that we are given $B(x_1, r_1)$ and $B(x_2, r_2)$ so that $0 \in B(x_1, r_1) \cap B(x_2, r_2)$, $x_1 \notin B(x_2, r_2)$ and $x_2 \notin B(x_1, r_1)$. Then the angle between the vectors x_1 and x_2 is at least 60° .

For a proof of the Besicovitch covering theorem, we again refer to [95].

A.3 L^p -Spaces

Recall that $L^p(\Omega)$, $1 \leq p < \infty$, consists of (equivalence classes) of measurable functions u with

$$\int_{\Omega} |u|^p < \infty.$$

We write

$$\|u\|_{L^p} = \|u\|_p := \left(\int_{\Omega} |u|^p \right)^{1/p}.$$

Furthermore, $L^\infty(\Omega)$ consists of those measurable functions on Ω that are essentially bounded. Then $\|u\|_{L^\infty} = \|u\|_\infty$ is the essential supremum of $|u|$ over Ω . If $1 < p < \infty$, we set $p' = p/(p-1)$, and we define $1' = \infty$. With this notation, we have the Minkowski

$$\|u + v\|_p \leq \|u\|_p + \|v\|_p$$

and Hölder

$$\|uv\|_1 \leq \|u\|_p \|v\|_{p'}$$

inequalities.

One often needs the following spherical coordinates. Given a Borel function $u \in L^1(B(0, 1))$ we have that

$$\int_{B(0,1)} u = \int_{S^{n-1}(0,1)} \int_0^1 u(tw) t^{n-1} dt dw.$$

Here we use the notation $\int_{S^{n-1}(c,t)} f(x) dx$ to denote integration with respect to the surface measure, which is a constant multiple of the Hausdorff measure \mathcal{H}^{n-1} .

We say that a sequence $\{u_i\}_i$ converges to u in $L^p(\Omega)$ if all these functions belong to $L^p(\Omega)$ and if $\|u - u_i\|_p \rightarrow 0$ when $i \rightarrow \infty$. We then write $u_i \rightarrow u$ in $L^p(\Omega)$. If $u_i \rightarrow u$ in $L^p(\Omega)$, then there is a subsequence $\{u_{i_k}\}_k$ of $\{u_i\}_i$ which converges to u pointwise almost everywhere. For $1 \leq p < \infty$, continuous functions are dense in $L^p(\Omega)$: given $u \in L^p(\Omega)$ one can find continuous u_i with $u_i \rightarrow u$ both in $L^p(\Omega)$ and almost everywhere. This can be easily seen by first approximating u by simple functions, then approximating the associated measurable sets by compact sets and finally approximating the characteristic functions of the compact sets by continuous functions.

The dual of $L^p(\Omega)$ is $L^{p/(p-1)}(\Omega)$ when $1 < p < \infty$. Then

$$\|u\|_p = \sup_{\|\varphi\|_{\frac{p}{p-1}}=1} \|u\varphi\|_1.$$

One of the inequalities easily follows by Hölder's inequality and the other by choosing φ to be a suitable constant multiple of $|u|^{p-1}$.

We also need the following weak compactness property: if $\{u_j\}_j$ is a bounded sequence in $L^p(\Omega)$, $1 < p < \infty$, then there is a subsequence $\{u_{j_k}\}_k$ and a function $u \in L^p(\Omega)$ so that

$$\lim_{k \rightarrow \infty} \int_{\Omega} u_{j_k} \varphi = \int_{\Omega} u \varphi$$

for each $\varphi \in L^{p/(p-1)}(\Omega)$. We then write

$$u_{j_k} \rightharpoonup u.$$

This notation should in principle include the exponent p , but the exponent in question is typically only indicated when its value is not obvious. This function u , called the weak limit, is unique and satisfies

$$\|u\|_p \leq \liminf_{k \rightarrow \infty} \|u_{j_k}\|_p.$$

The existence of the weak limit u follows from the fact that $L^p(\Omega)$, $1 < p < \infty$, is reflexive. Furthermore, the norm estimate on u is a consequence of a general result according to which a norm is lower semicontinuous with respect to the associated weak convergence. In general, weak convergence is defined by considering bounded linear mappings $T : X \rightarrow \mathbf{R}$; in the case of $L^p(\Omega)$, $1 < p < \infty$, they can be identified with elements of $L^{p/(p-1)}(\Omega)$. If $v_j = (v_1^j, \dots, v_n^j) \in L^p(\Omega)$, then

$$v_j \rightharpoonup u$$

means that

$$v_i^j \rightharpoonup u_i$$

for each $1 \leq i \leq n$.

When we apply the above to a sequence $A_j(x)$ of $n \times n$ -matrix functions, we conclude that the boundedness in $L^p(\Omega)$, $1 < p < \infty$ of the sequence $\{|A_j(x)|\}_j$ guarantees the existence of an $n \times n$ -matrix function $A(x) \in L^p(\Omega)$ so that the rows (or columns) of a subsequence of $\{|A_j(x)|\}_j$ converge weakly to the corresponding rows (or columns) of $A(x)$. Notice that boundedness above is independent of the initial norm (like the operator or Hilbert-Schmidt one). Then $\|A\|_p \leq C_n \liminf_{k \rightarrow \infty} \|A_{j_k}\|_p$. In fact, one can show that

$$\|A\|_p \leq \liminf_{k \rightarrow \infty} \|A_{j_k}\|_p;$$

the L^p -norms generated by the operator or Hilbert-Schmidt norms are equivalent and so the associated concepts of weak convergence coincide.

We need the following sufficient condition for weak compactness in L^1 .

Lemma A.3. *Let $\{g_j\}_{j \in \mathbf{N}}$ be a sequence of measurable functions on a domain $\Omega \subset \mathbf{R}^n$ of finite measure. Suppose that there is $H \in L^1(\Omega)$ such that for almost every $y \in \Omega$ and for every $j \in \mathbf{N}$ we have $|g_j(y)| \leq H(y)$. Then there is a subsequence $\{\tilde{g}_j\}_{j \in \mathbf{N}}$ of $\{g_j\}_{j \in \mathbf{N}}$ and $g \in L^1(\Omega)$ such that the subsequence $\{\tilde{g}_j\}_{j \in \mathbf{N}}$ converges weakly to g in $L^1(\Omega)$.*

Proof. We may assume that $H > 0$ everywhere on Ω . Define

$$h_j = \frac{g_j}{H}.$$

Since $0 \leq h_j \leq 1$, the sequence $\{h_j\}_{j \in \mathbb{N}}$ is bounded in $L^2(\Omega)$. Hence, after passing to a suitable subsequence, we may assume that $h_j \rightarrow h \in L^2(\Omega)$ in $L^2(\Omega)$. Thus

$$\int_{\Omega} h_j \eta \, dx \rightarrow \int_{\Omega} h \eta \, dx \quad (\text{A.2})$$

for each $\eta \in L^2(\Omega)$. It is easy to show that $0 \leq h \leq 1$ a.e. and hence $h \in L^\infty$. Given $k \in \mathbb{N}$, set

$$H_k = \min\{H, k\}.$$

Let $\varphi \in L^\infty(\Omega)$. Then $H_k \varphi \in L^\infty(\Omega) \subset L^2(\Omega)$. By the triangle inequality

$$\begin{aligned} \left| \int_{\Omega} (g_j \varphi - h H \varphi) \, dx \right| &= \left| \int_{\Omega} (h_j H \varphi - h H \varphi) \, dx \right| \\ &\leq \left| \int_{\Omega} (h_j H_k \varphi - h H_k \varphi) \, dx \right| \\ &\quad + \left| \int_{\Omega} (h_j \varphi - h \varphi)(H - H_k) \, dx \right|. \end{aligned}$$

With the help of (A.2) we now obtain

$$\begin{aligned} \limsup_{j \rightarrow \infty} \left| \int_{\Omega} (g_j \varphi - h H \varphi) \, dx \right| &\leq \limsup_{j \rightarrow \infty} \left| \int_{\Omega} (h_j \varphi - h \varphi)(H - H_k) \, dx \right| \\ &\leq C \int_{\Omega} |H - H_k| \, dx. \end{aligned}$$

Since $H \in L^1(\Omega)$, we conclude that

$$\lim_{j \rightarrow \infty} \int_{\Omega} g_j \varphi \, dx = \int_{\Omega} h H \varphi.$$

Since $h H \in L^1(\Omega)$, the claim follows. \square

On several occasions we will need Jensen's inequality.

Theorem A.4 (Jensen's Inequality). *Let $G \subset \mathbf{R}^n$ be a measurable set with $0 < |G| < \infty$ and let $\Phi : [0, \infty) \rightarrow [0, \infty)$ be a convex function. Then for every nonnegative measurable function $h : G \rightarrow [0, \infty)$ we have*

$$\Phi\left(\oint_G h(x) \, dx\right) \leq \oint_G \Phi(h(x)) \, dx.$$

A.4 Maximal Operator

Let $u \in L^1_{\text{loc}}(\mathbf{R}^n)$. The non-centered maximal function of u is

$$Mu(x) = \sup_{x \in B(y,r)} \oint_{B(y,r)} |u|.$$

Recall that for a measurable set A with $0 < |A| < \infty$,

$$\oint_A v = v_A = \frac{1}{|A|} \int_A v.$$

Remark A.5. (1) According to the Lebesgue differentiation theorem

$$Mu(x) \geq |u(x)|$$

almost everywhere.

- (2) There are many other maximal functions. For example the restricted, centered maximal function

$$M^C_\delta u(x) = \sup_{0 < r < \delta} \oint_{B(x,r)} |u|.$$

- (3) We always have $M^C_\infty u(x) \leq Mu(x) \leq 2^n M^C_\infty u(x)$.
 (4) Notice that $\{Mu > t\}$ is open for each $t \geq 0$ and, consequently, Mu is measurable. Indeed, if $x \in \{Mu > t\}$, then it immediately follows from the definition that $B(y, r) \subset \{Mu > t\}$, for some $B(y, r)$ containing x .

Theorem A.6. *If $u \in L^1(\mathbf{R}^n)$ and $t > 0$, then*

$$|\{Mu > t\}| \leq \frac{5^n}{t} \int_{\{Mu > t\}} |u| \leq \frac{5^n}{t} \|u\|_1. \quad (\text{A.3})$$

Proof. We may assume that $M := \int_{\{Mu > t\}} |u| < \infty$. For each $x \in \{Mu > t\}$ there is a ball B such that $x \in B$ and

$$\oint_B |u| > t$$

and hence

$$|B| < t^{-1} \int_B |u|.$$

If $y \in B$, then $Mu(y) > t$ and thus $B \subset \{Mu > t\}$. So

$$|B| < \frac{1}{t} \int_B |u| \leq \frac{1}{t} \int_{\{Mu > t\} \cap B} |u|.$$

By the Vitali covering theorem, Theorem A.1, we find pairwise disjoint balls B_1, B_2, \dots as above so that $\{Mu > t\} \subset \bigcup 5B_j$. Then

$$|\{Mu > t\}| \leq \sum |5B_j| = 5^n \sum |B_j| \leq \frac{5^n}{t} \sum \int_{B_j} |u| \leq \frac{5^n}{t} \int_{\{Mu > t\}} |u|.$$

□

The following lemma implies (by sending $\lambda \rightarrow 0$) that the maximal operator is bounded from L^p to L^p for $p > 1$.

Lemma A.7. *Let $p > 1$, $\lambda > 0$ and $v \in L^p$. Then*

$$\int_{\{Mv > \lambda\}} (Mv)^p \leq C(n, p) \int_{\{|v| > \frac{\lambda}{2}\}} |v|^p.$$

Proof. Using the Fubini theorem and the estimate (A.3) we see that

$$\begin{aligned} \int_{\{Mv > \lambda\}} (Mv)^p &= \int_{\{Mv > \lambda\}} \int_0^{Mv(x)} p t^{p-1} dt dx \\ &= p \int_{\lambda}^{\infty} t^{p-1} |\{Mv > t\}| dt + \lambda^p |\{Mv > \lambda\}| \\ &\leq C \int_{\lambda}^{\infty} t^{p-2} \int_{\{|v| > \frac{t}{2}\}} |v(x)| dx dt + C \lambda^{p-1} \int_{\{|v| > \frac{\lambda}{2}\}} |v(x)| dx \\ &\leq C \int_{\lambda}^{\infty} \int_{\{|v| > \frac{t}{2}\}} |v(x)|^{p-1} dx dt + C \int_{\{|v| > \frac{\lambda}{2}\}} |v(x)|^p dx \\ &= C \int_{\{|v| > \frac{\lambda}{2}\}} |v(x)|^{p-1} \int_{\lambda}^{2|v(x)|} dt dx + C \int_{\{|v| > \frac{\lambda}{2}\}} |v(x)|^p dx \\ &\leq C \int_{\{|v| > \frac{\lambda}{2}\}} |v(x)|^p dx. \end{aligned}$$

□

Remark A.8. Suppose that $u \in L^p(\Omega)$, $p > 1$. Applying the previous lemma to the zero extension of u we conclude that $\int_{\Omega} (Mu)^p \leq C(p, n) \int_{\Omega} |u|^p$. Similarly, the inequality (A.3) can be restricted to Ω when $u \in L^1(\Omega)$.

The case $p = 1$ was not left out by accident from the previous lemma.

Example A.9. If $u(x) = \chi_{B(0,1)}(x)$, then Mu behaves like $\frac{C}{|x|^n}$ close to ∞ and hence $Mu \notin L^1(\mathbf{R}^n)$. In fact, $Mu \notin L^1(\mathbf{R}^n)$ unless u is the zero function.

We continue with a powerful tool from harmonic analysis, the Calderón-Zygmund decomposition, and some consequences of this decomposition.

The dyadic decomposition of a cube Q_0 consists of open cubes $Q \subset Q_0$ with faces parallel to the faces of Q_0 and of edge length $l(Q) = 2^{-i}l(Q_0)$, where $i = 1, 2, \dots$ refer to the generation in the construction. The cubes in each generation cover Q_0 up to a set of measure zero and the closures of the cubes in a fixed generation cover Q_0 ; there are 2^{in} cubes of edge length $2^{-i}l(Q_0)$ in the i th generation and the cubes corresponding to the same generation are pairwise disjoint. For almost every $x \in Q_0$, there is a (unique) decreasing sequence $Q_0 \supset Q_1 \supset \dots$ of cubes in the dyadic decomposition so that $\{x\} = \bigcap Q_i$. In what follows, Q, Q_0, Q_x etc. are cubes.

Theorem A.10 (Calderón-Zygmund Decomposition). *Let $Q_0 \subset \mathbf{R}^n$, $u \in L^1(Q_0)$, and suppose that*

$$0 \leq \int_{Q_0} u \leq t.$$

Then there is a subcollection $\{Q_j\}$ from the dyadic decomposition of Q_0 so that $Q_i \cap Q_j = \emptyset$ when $i \neq j$,

$$t < \int_{Q_j} u \leq 2^n t$$

for each j , and $u(x) \leq t$ for almost every $x \in Q_0 \setminus \bigcup Q_j$.

Proof. For almost every $x \in Q_0$ there is a decreasing sequence $\{Q_j\}$ of dyadic cubes so that $\{x\} = \bigcap Q_j$. By the Lebesgue differentiation theorem

$$\lim_{j \rightarrow \infty} \int_{Q_j} u = u(x)$$

for almost every such x . Let $u(x) > t$ and assume that the above holds for x with the sequence $\{Q_j\}$. Then there must be maximal $Q_x := Q_{j(x)}$ so that

$$\int_{Q_x} u > t.$$

For this cube we have

$$t < \int_{Q_x} u \leq 2^n \int_{Q_{j(x)-1}} u \leq 2^n t.$$

We can pick such a cube Q_x for almost every x with $u(x) > t$. It is then easy to choose the desired subcollection from the cubes Q_x . \square

The dyadic maximal function of a measurable function u (with respect to a cube Q_0) is defined by

$$M_{Q_0}u(x) = \sup_{x \in \overline{Q} \subset Q_0} \int_Q |u|,$$

where the supremum is taken over all cubes Q that belong to the dyadic decomposition of Q_0 and whose closures contain x .

Remark A.11. As for the usual maximal function, we have the weak-type estimate

$$|\{x \in Q_0 : M_{Q_0}u(x) > t\}| \leq \frac{2 \cdot 5^n}{t} \int_{\{x \in Q_0 : |u(x)| > \frac{t}{2}\}} |u|$$

for the dyadic maximal function. Moreover,

$$\int_{Q_0} (M_{Q_0}u)^p \leq C(p, n) \int_{Q_0} |u|^p$$

for $p > 1$. The proof of the weak type estimate is actually easier than for the usual maximal operator because no covering theorem is needed.

The following simple consequence of the Calderón-Zygmund decomposition is essentially the converse of the weak type estimate for the dyadic maximal function.

Lemma A.12. *Let $u \in L^1(Q_0)$ and suppose $t \geq \int_{Q_0} |u|$. Then*

$$\int_{\{x \in Q_0 : |u(x)| > t\}} |u| \leq 2^n t |\{x \in Q_0 : M_{Q_0}u(x) > t\}|.$$

Proof. By the Calderón-Zygmund decomposition we find pairwise disjoint cubes Q_1, Q_2, \dots so that

$$t < \int_{Q_j} |u| \leq 2^n t$$

for all j , and $|u(x)| \leq t$ almost everywhere in $Q_0 \setminus \bigcup Q_j$. Then

$$\begin{aligned} \int_{\{x \in Q_0 : |u(x)| > t\}} |u| &\leq \sum \int_{Q_j} |u| \\ &\leq \sum 2^n t |Q_j| \\ &\leq 2^n t |\{x \in Q_0 : M_{Q_0}u(x) > t\}|, \end{aligned}$$

because

$$M_{Q_0}u(x) \geq \int_{Q_j} |u| > t$$

for each $x \in Q_j$. □

A.5 Sobolev Spaces

Definition A.13. Let $\Omega \subset \mathbf{R}^n$ be open and $u \in L^1_{\text{loc}}(\Omega)$. A function $v \in L^1_{\text{loc}}(\Omega, \mathbf{R}^n)$ is called a weak derivative of u if

$$\int_{\Omega} \varphi(x)v(x)dx = - \int_{\Omega} u(x)\nabla\varphi(x)dx$$

for every $\varphi \in C^\infty_c(\Omega)$. We refer to v by Du . For $1 \leq p \leq \infty$ we define the Sobolev space

$$W^{1,p}(\Omega) = \{u \in L^p(\Omega) : Du \in L^p(\Omega, \mathbf{R}^n)\}$$

and we define the norm

$$\|u\|_{W^{1,p}(\Omega)} = \left(\int_{\Omega} |u|^p + \int_{\Omega} |Du|^p \right)^{\frac{1}{p}}.$$

Further $W^{1,p}(\Omega, \mathbf{R}^n)$ refers to mappings $f : \Omega \rightarrow \mathbf{R}^n$ whose each component function f_j , $j = 1, \dots, n$, belongs to $W^{1,p}(\Omega)$. The definitions of $W^{1,p}_{\text{loc}}(\Omega)$ and $W^{1,p}_{\text{loc}}(\Omega, \mathbf{R}^n)$ should then be obvious.

A function \hat{u} is called a representative of $u \in W^{1,p}(\Omega)$ if $u = \hat{u}$ almost everywhere.

Definition A.14. Let $\Omega \subset \mathbf{R}^n$ be open and let $1 \leq p \leq \infty$. We define the Sobolev space of functions with zero boundary value $W^{1,p}_0(\Omega)$ as the collection of all functions $u \in W^{1,p}(\Omega)$ for which there are $u_j \in C^\infty_c(\Omega)$ such that $u_j \rightarrow u$ in $W^{1,p}(\Omega)$.

Theorem A.15 (Definitions of Sobolev Spaces). Let $u \in L^p(\Omega)$, $1 \leq p < \infty$, $\Omega \subset \mathbf{R}^n$. Then the following are equivalent:

- (1) **(ACL)** The function u has a representative \tilde{u} that is absolutely continuous on almost all line segments in Ω parallel to the coordinate axes and whose (classical) partial derivatives belong to $L^p(\Omega)$.
- (2) **(H)** There is a sequence $\{\varphi_j\}_j \subset C^\infty(\Omega)$ so that $\varphi_j \rightarrow u$ in $L^p(\Omega)$ and $\{\nabla\varphi_j\}_j$ is Cauchy in $L^p(\Omega)$.

(3) **(W)** The function u belongs to $W^{1,p}(\Omega)$.

Proof (sketch).

(2) \Rightarrow (1): Passing to a subsequence, we may assume that $\{\varphi_j(x)\}_j$ converges for almost every x . We define

$$\tilde{u}(x) = \lim_{j \rightarrow \infty} \varphi_j(x)$$

whenever the limit exists, and set, say, $\tilde{u}(x) = 0$ for the remaining $x \in \Omega$. Then $\tilde{u}(x) = u(x)$ almost everywhere in Ω . Since $\nabla \varphi_j$ is Cauchy in L^p it is easy to see that $\nabla \varphi_j$ converge to Du in L^p .

We fix $[a_1, b_1] \times \dots \times [a_n, b_n] \subset \Omega$. By the Fubini theorem we obtain that for \mathcal{L}_{n-1} -a.e. $[x_2, \dots, x_n] \in [a_2, b_2] \times \dots \times [a_n, b_n]$ we have

$$\int_I |Du - \nabla \varphi_j|^p \xrightarrow{j \rightarrow \infty} 0$$

where $I = [a_1, a_2] \times [x_2, \dots, x_n]$ and moreover, we may assume that $\varphi_j(x) \rightarrow u(x)$ for \mathcal{H}^1 -a.e. $x \in I$. Let us fix disjoint intervals $[c_i, d_i] \subset [a_1, a_2]$ such that $\varphi_j(c_i, x_2, \dots, x_n) \rightarrow u(c_i, x_2, \dots, x_n)$ and $\varphi_j(d_i, x_2, \dots, x_n) \rightarrow u(d_i, x_2, \dots, x_n)$. By the fundamental theorem of calculus applied to the functions φ_j we obtain

$$|\varphi_j(c_i, x_2, \dots, x_n) - \varphi_j(d_i, x_2, \dots, x_n)| \leq \int_{I_i} |\nabla \varphi_j|$$

where $I_i = [c_i, d_i] \times [x_2, \dots, x_n]$. We let $j \rightarrow \infty$ and then sum over i to obtain

$$\sum_i |u(c_i, x_2, \dots, x_n) - u(d_i, x_2, \dots, x_n)| \leq \sum_i \int_{I_i} |Du|.$$

As $Du \in L^1$ this implies that u is absolutely continuous on I by the absolute continuity of the integral. More precisely, u has a representative which is absolutely continuous on I .

(1) \Rightarrow (3): Integration by parts is valid in one dimension for absolutely continuous functions. Hence we can integrate by parts over line segments and then use the Fubini theorem. The weak derivatives v_j are the classical partial derivatives of absolutely continuous functions.

(3) \Rightarrow (2): We use the (smooth) convolution approximation: Let

$$\psi_1(x) = \begin{cases} 0, & |x| \geq 1 \\ C \exp\left(\frac{1}{|x|^2-1}\right), & |x| < 1, \end{cases}$$

where C is chosen so that $\int_{\mathbf{R}^n} \psi_1 dx = 1$. Define

$$\psi_\varepsilon(x) = \frac{1}{\varepsilon^n} \psi_1\left(\frac{x}{\varepsilon}\right). \quad (\text{A.4})$$

If $v \in L^p_{\text{loc}}$, set

$$v^\varepsilon(x) = (\psi_\varepsilon * v)(x) = \int_{\Omega} \psi_\varepsilon(x-y)v(y) dy,$$

when $B(x, \varepsilon) \subset\subset \Omega$. If $v \in L^p(\mathbf{R}^n)$, then $v^\varepsilon \rightarrow v$ in $L^p(\mathbf{R}^n)$. Indeed, this is easy to see for a continuous function v and for a general function we find a sequence of continuous functions that converge to it in L^p . Also $v^\varepsilon(x) \rightarrow v(x)$ when x is a Lebesgue point of u .

Fix $x \in \Omega$ and $\varepsilon > 0$ small compared to $\text{dist}(x, \partial\Omega)$. Now

$$\begin{aligned} \frac{u^\varepsilon(x + he_i) - u^\varepsilon(x)}{h} &= \frac{1}{\varepsilon^n} \int_{\Omega} \underbrace{\frac{1}{h} \left[\psi_1\left(\frac{x + he_i - y}{\varepsilon}\right) - \psi_1\left(\frac{x - y}{\varepsilon}\right) \right]}_{\xrightarrow{h \rightarrow 0} \frac{1}{\varepsilon} \frac{\partial \psi_1}{\partial x_i}\left(\frac{x - y}{\varepsilon}\right) = \varepsilon^n \frac{\partial \psi_\varepsilon}{\partial x_i}(x - y)} u(y) dy \\ &\xrightarrow{h \rightarrow 0} \int_{\Omega} \frac{\partial \psi_\varepsilon}{\partial x_i}(x - y) u(y) dy \end{aligned}$$

by the dominated convergence theorem:

$$\int_{\Omega} \left| \frac{1}{h} \left[\psi_1\left(\frac{x + he_i - y}{\varepsilon}\right) - \psi_1\left(\frac{x - y}{\varepsilon}\right) \right] u(y) \right| dy \leq \frac{1}{\varepsilon} \int_{\Omega} \|\nabla \psi_1\|_{L^\infty} |u(y)| dy.$$

Thus there exists a derivative of u^ε and

$$\frac{\partial u^\varepsilon}{\partial x_i}(x) = \int_{\Omega} \frac{\partial \psi_\varepsilon}{\partial x_i}(x - y) u(y) dy$$

and because ψ_ε is smooth, we see that u^ε is C^1 . By repeating this argument one can check that u_ε is actually C^∞ . Moreover, when $u \in W^{1,p}$,

$$\begin{aligned} \frac{\partial u^\varepsilon}{\partial x_i}(x) &= \int \frac{\partial \psi_\varepsilon(x - y)}{\partial x_i} u(y) dy \\ &= - \int \frac{\partial \psi_\varepsilon(x - y)}{\partial y_i} u(y) dy \\ &= \int \psi_\varepsilon(x - y) v_i(y) dy. \end{aligned}$$

If $v_i \in L^p(\mathbf{R}^n)$, then this convolution sequence converges to v_i in $L^p(\mathbf{R}^n)$. When u is given on Ω , use a partition of unity to reduce the setting to that of \mathbf{R}^n . \square

The weak derivative coincides with the usual derivative if both derivatives exist.

Corollary A.16. *Let $\Omega \subset \mathbf{R}^n$, $d \in \mathbf{N}$ and let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^d)$ be differentiable a.e. Then the classical derivative $\nabla f(x)$ equals to the weak derivative $Df(x)$ for a.e. $x \in \Omega$.*

Proof. From the proof of previous theorem (1) \Rightarrow (3) we see that $Df(x)$ equals almost everywhere to the classical derivatives of the absolutely continuous representative. If $\nabla f(x)$ exists, then also classical partial derivatives exist at this point and they must equal a.e. to the derivatives of the absolutely continuous representative. \square

It is well known that a Sobolev function satisfies the Poincaré inequality (see [29, Sect. 5.6.1]).

Theorem A.17. *Let $B \subset \mathbf{R}^n$ be a ball. If $u \in W^{1,1}(B)$, then*

$$\int_B |u(x) - u_B| dx \leq C \text{diam}(B) \int_B |Du(x)| dx.$$

Moreover, we also use the Sobolev-Poincaré inequality (see [29, Sect. 4.5.2]).

Theorem A.18. *Let $B \subset \mathbf{R}^n$ be a ball, $1 \leq p < n$ and $p^* = \frac{np}{n-p}$. If $u \in W^{1,p}(B)$, then $u \in L^{p^*}(B)$ and*

$$\left(\int_B |u(x) - u_B|^{p^*} dx \right)^{\frac{1}{p^*}} \leq C \text{diam}(B) \left(\int_B |Du(x)|^p dx \right)^{\frac{1}{p}}.$$

The following theorem tells us that Sobolev functions are Hölder continuous for $p > n$ (see [122, proof of Theorem 2.4.4]).

Theorem A.19. *Let $u \in W^{1,p}(5B)$ and let $p > n$. Then*

$$|u(x) - u(y)| \leq C(n, p) |x - y|^{1-n/p} \left(\int_{B(x, 2|x-y|)} |Du|^p \right)^{1/p}$$

for all Lebesgue points $x, y \in B$ of u .

Actually, with some work one can relax the assumption to $u \in W^{1,p}(B)$ and replace $B(x, 2|x - y|)$ with $B(x, 2|x - y|) \cap B$.

Regarding the Poincaré inequality, each function that satisfies a Poincaré inequality is in fact a Sobolev function. The proof of the following theorem is from [32].

Theorem A.20. *Let $\Omega \subset \mathbf{R}^n$ be open and let $u, g \in L_{\text{loc}}^1(\Omega)$. Assume that there is $C > 0$ such that for every ball $B \subset \Omega$ we have*

$$\int_B |u(x) - u_B| dx \leq C \operatorname{diam}(B) \int_B |g(x)| dx.$$

Then $u \in W_{\text{loc}}^{1,1}(\Omega)$.

Proof. Let $A \subset \subset \Omega$ be a fixed domain. First we construct approximations of u . Let $k \in \mathbf{N}$ be such that $\{x : \operatorname{dist}(x, A) < \frac{4n}{k}\} \subset \Omega$ and denote the $1/k$ -grid in \mathbf{R}^n by

$$G_k = \{z \in (\frac{1}{k}\mathbf{Z} \times \dots \times \frac{1}{k}\mathbf{Z}) : \operatorname{dist}(z, A) < \frac{n}{k}\}.$$

Pick a partition of unity $\{\phi_z\}_{z \in G_k}$ such that

$$\begin{aligned} &\text{each } \phi_z : \mathbf{R}^n \rightarrow \mathbf{R} \text{ is continuously differentiable;} \\ &\operatorname{spt} \phi_z \subset B(z, \frac{n}{k}) \text{ and } |\nabla \phi_z| \leq Ck; \\ &\sum_{z \in G_k} \phi_z(y) = 1 \text{ for every } y \in A. \end{aligned} \tag{A.5}$$

Now we set

$$u_k(y) = \sum_{z \in G_k} \phi_z(y) u_{B(z, \frac{1}{k})} \text{ for every } y \in A. \tag{A.6}$$

The supports of ϕ_z have bounded overlap and hence this sum is locally finite and $u_k \in C^1(A)$. It is not difficult to show that $u_k \rightarrow u$ in $L^1(A)$. Indeed, this is simple for a continuous function u by uniform continuity, and the general case follows by approximation by continuous functions.

Next we need to estimate the derivative of u_k . For $y \in A$ we choose $z_0 \in G_k$ so that $y \in B(z_0, \frac{n}{k})$. Since $\sum \phi_z = 1$ and we have a locally finite sum we may write

$$Du_k(y) = D\left(\sum_{z \in G_k} \phi_z(y) (u_{B(z, \frac{1}{k})} - u_{B(z_0, \frac{2n}{k})})\right) = \sum_{z \in G_k} D\phi_z(y) (u_{B(z, \frac{1}{k})} - u_{B(z_0, \frac{2n}{k})}). \tag{A.7}$$

Since $y \in B(z_0, \frac{n}{k})$ it is easy to see that

$$\phi_z(y) \neq 0 \Rightarrow B(z, \frac{1}{k}) \subset B(z_0, \frac{2n}{k}).$$

Hence we may use (A.7) and (A.5) to estimate

$$\begin{aligned}
|Du_k(y)| &\leq \sum_{\{z \in G_k: \phi_z(y) \neq 0\}} Ck |u_{B(z, \frac{1}{k})} - u_{B(z_0, \frac{2n}{k})}| \\
&\leq \sum_{\{z \in G_k: \phi_z(y) \neq 0\}} Ck \left| \int_{B(z, \frac{1}{k})} (u(x) - u_{B(z_0, \frac{2n}{k})}) dx \right| \\
&\leq \sum_{\{z \in G_k: \phi_z(y) \neq 0\}} Ck \frac{1}{|B(z_0, \frac{2n}{k})|} \frac{|B(z_0, \frac{2n}{k})|}{|B(z, \frac{1}{k})|} \int_{B(z_0, \frac{2n}{k})} |u(x) - u_{B(z_0, \frac{2n}{k})}| dx.
\end{aligned}$$

Only a bounded number of terms above are nonzero and hence we can use our assumption and $B(z_0, \frac{2n}{k}) \subset B(y, \frac{3n}{k})$ to obtain

$$\begin{aligned}
|Du_k(y)| &\leq Ck \int_{B(z_0, \frac{2n}{k})} |u(x) - u_{B(z_0, \frac{2n}{k})}| dx \\
&\leq C \int_{B(z_0, \frac{2n}{k})} |g(x)| dx \leq C \int_{B(y, \frac{3n}{k})} |g(x)| dx.
\end{aligned} \tag{A.8}$$

Since $\int_{B(y, \frac{3n}{k})} |g| \rightarrow \int_{B(y, \frac{3n}{k_j})} |g|$ in $L^1(A)$ as $k \rightarrow \infty$, there is a subsequence $k_j \rightarrow \infty$ such that $\int_{B(y, \frac{3n}{k_j})} |g|$ has a majorant $H \in L^1(A)$. From this, (A.8) and Lemma A.3, we obtain that there is a subsequence $k_i \rightarrow \infty$ and $g \in L^1(A, \mathbf{R}^n)$ such that $Du_{k_i} \rightarrow g$ weakly in L^1 . Since $u_k \in C^1$ we have

$$\int_A Du_{k_i}(y) \varphi(y) dy = - \int_A u_{k_i}(y) D\varphi(y) dy \tag{A.9}$$

for every test function $\varphi \in C_c^\infty(A)$. Since $u_k \rightarrow u$ in L^1 , we obtain, after passing to the limit, that

$$\int_A g(y) \varphi(y) dy = - \int_A u(y) D\varphi(y) dy$$

which means that g is a weak gradient of u in A and therefore $u \in W^{1,1}(A)$. \square

There is also a version of the previous theorem for BV -functions (recall that BV -functions were defined in Definition 5.1).

Theorem A.21. *Let $\Omega \subset \mathbf{R}^n$ be open, $u \in L^1_{\text{loc}}(\Omega)$ and let μ be a Radon measure on Ω . Assume that there is $C > 0$ such that for every ball $B \subset \Omega$ we have*

$$\int_B |u(x) - u_B| dx \leq C \text{diam}(B) \mu(B).$$

Then $u \in BV_{\text{loc}}(\Omega)$.

Proof. We proceed similarly to the proof of the previous theorem. Again we fix $A \subset\subset \Omega$ and we define u_k by the same formula (A.6). Again $u_k \in C^1$ and they converge in L^1 to u . Analogously to the estimate (A.8) we obtain using our assumption that

$$|Du_k(y)| \leq Ck \int_{B(z_0, \frac{2n}{k})} |u(x) - u_{B(z_0, \frac{2n}{k})}| dx \leq C \frac{\mu(B(z_0, \frac{2n}{k}))}{|B(z_0, \frac{2n}{k})|}.$$

By the integration of this inequality over A we obtain

$$\int_A |Du_k(y)| dy \leq C \sum_{z \in G_k} \mu(B(z, \frac{2n}{k})) \leq C \mu(\{x \in \Omega : \text{dist}(x, A) < \frac{3n}{k}\}).$$

It follows that Du_k form a bounded sequence in L^1 . Recalling that $u_k \rightarrow u$ in L^1 , we conclude [29, paragraph 5.2.3] that $u \in BV(A)$. In fact, there is a subsequence and vector ν of Radon measures such that Du_{k_i} converge to ν weak star in measures. As before we have (A.9) and by passing to a limit we have

$$\int_A \varphi(y) d\nu(y) = - \int_A u(y) D\varphi(y) dy$$

which means that ν is a weak gradient of u in A and therefore $u \in BV(A)$. \square

We have seen in Theorem A.15 that $W^{1,1}$ -functions can be characterized using the ACL-property. Similarly, it is possible to characterize BV -functions using the BVL-property, i.e. that the function in question has bounded variation on almost all lines parallel to coordinate axes (see [2, Sect. 3.11]).

More precisely, let $i \in \{1, 2, \dots, n\}$, $Q_0 = (0, 1)^n$ and by π_i denote the projection to the hyperplane perpendicular to i -th coordinate axis. For $y \in \pi_i(Q_0)$ we denote $g_{i,y}(t) = g(y + t\mathbf{e}_i)$.

Theorem A.22. *Let $g \in L^1(Q_0)$. Then $g \in BV(Q_0)$ if and only if for every $i \in \{1, \dots, n\}$ the function $g_{i,y}(t) \in BV((0, 1))$ for \mathcal{H}^{n-1} -almost every $y \in \pi_i(Q_0)$ and moreover*

$$\int_{\pi_i(Q_0)} |Dg_{i,y}|((0, 1)) d\mathcal{H}^{n-1}(y) < \infty,$$

where $|Dg_{i,y}|((0, 1))$ denotes the total variation of our BV -function of a single variable. In this case we can estimate the total variation of Dg by

$$|Dg|(Q_0) \leq C \sum_{i=1}^n \int_{\pi_i(Q_0)} |Dg_{i,y}|((0, 1)) d\mathcal{H}^{n-1}(y).$$

A.6 Lipschitz Approximation of Sobolev Functions

We know by Theorem A.15 that, given a Sobolev function u , we can find C^1 -smooth functions u_k such that $u_k \rightarrow u$ in $W^{1,1}$, but in some applications this approximation is not good enough. In this section we construct Lipschitz functions u_k that converge to u in $W^{1,1}$ and moreover $u = u_k$ on a big set. First we need a couple of lemmata.

Lemma A.23 (McShane Extension). *Let $A \subset \mathbf{R}^n$ and $f : A \rightarrow \mathbf{R}^m$ be L -Lipschitz, that is*

$$|f(x) - f(y)| \leq L|x - y|$$

for all $x, y \in A$. Then there exists a $(\sqrt{m}L)$ -Lipschitz $\tilde{f} : \mathbf{R}^n \rightarrow \mathbf{R}^m$ such that $\tilde{f}|_A = f$.

Proof. Let $m = 1$. Define

$$\tilde{f}(x) = \inf_{a \in A} \{f(a) + L|x - a|\}.$$

Then $\tilde{f}(x) = f(x)$ when $x \in A$: Since f is L -Lipschitz on A ,

$$f(x) \leq f(a) + L|x - a| \quad \text{when } x, a \in A,$$

and so $f(x) \leq \tilde{f}(x)$. By the choice $a = x$ in the definition of $\tilde{f}(x)$ we obtain $\tilde{f}(x) \leq f(x)$.

Given $x, y \in \mathbf{R}^n$, we have that

$$\begin{aligned} \tilde{f}(x) &= \inf_{a \in A} \{f(a) + \underbrace{L|x - a|}_{\leq L(|y - a| + |y - x|)}\} \\ &\leq L|y - x| + \tilde{f}(y). \end{aligned}$$

Because this also holds with x replaced by y , we conclude that \tilde{f} is L -Lipschitz.

Let us then consider the case $m \geq 2$. For given $f = (f_1, \dots, f_m)$ define $\tilde{f} = (\tilde{f}_1, \dots, \tilde{f}_m)$ as in the previous case. Now

$$|\tilde{f}(x) - \tilde{f}(y)|^2 = \sum_1^m |\tilde{f}_i(x) - \tilde{f}_i(y)|^2 \leq mL^2|x - y|^2,$$

and the claim follows. □

Remark A.24. By choosing a suitable extension different from the McShane extension, one could require above \tilde{f} to be L -Lipschitz. This can be done using the so-called Kirszbaum extension.

In the following theorem we use the modified maximal function

$$M_{3r_0}u(x) = \sup_{x \in B(y,r) \subset B(x_0, 3r_0)} \int_{B(y,r)} |u|.$$

Lemma A.25. *Let $B = B(x_0, r_0)$ be a ball in \mathbf{R}^n and let $u \in W^{1,1}(B(x_0, 3r_0))$. For $\lambda > 0$ we define*

$$F_\lambda = \{x \in B : M_{3r_0}|Du(x)| < \lambda\} \cap \{x \in B : x \text{ is a Lebesgue point of } u\}. \quad (\text{A.10})$$

There is a constant $C > 0$ such that,

$$|u(x) - u(y)| \leq C\lambda|x - y| \text{ for all } x, y \in F_\lambda.$$

Moreover, the measure of the remaining set satisfies

$$|B \setminus F_\lambda| = o(\frac{1}{\lambda}).$$

Proof. Let $x, y \in F_\lambda$. Choose $B_j = B(x, 2^{-j}|x - y|)$ for $j \geq 0$ and $B_j = B(y, 2^{j+1}|x - y|)$ for $j < 0$. As x and y are Lebesgue points we obtain $u_{B_j} \rightarrow u(x)$ as $j \rightarrow \infty$ and $u_{B_j} \rightarrow u(y)$ as $j \rightarrow -\infty$ and hence

$$|u(x) - u(y)| \leq \sum_{-\infty}^{\infty} |u_{B_{j+1}} - u_{B_j}|.$$

Moreover, for $j > 0$ (and thus $B_{j+1} \subset B_j$) we can estimate the difference

$$\begin{aligned} |u_{B_{j+1}} - u_{B_j}| &= \left| \frac{1}{|B_{j+1}|} \int_{B_{j+1}} (u(x) - u_{B_j}) dx \right| \\ &\leq \frac{1}{|B_{j+1}|} \int_{B_{j+1}} |u(x) - u_{B_j}| dx \leq \frac{C(n)}{|B_j|} \int_{B_j} |u(x) - u_{B_j}| dx \end{aligned} \quad (\text{A.11})$$

and we have similar estimate for $j < 0$. For $|u_{B_0} - u_{B_1}|$ we add and subtract the term $u_{B_0 \cap B_1}$ and easily obtain the bound

$$\frac{1}{|B_0|} \int_{B_0} |u(x) - u_{B_0}| dx + \frac{1}{|B_1|} \int_{B_1} |u(x) - u_{B_1}| dx.$$

Hence we can use the Poincaré inequality, Theorem A.17, to obtain

$$\begin{aligned}
|u(x) - u(y)| &\leq \sum_{-\infty}^{\infty} |u_{B_{j+1}} - u_{B_j}| \leq \sum_{-\infty}^{\infty} C(n) \int_{B_j} |u - u_{B_j}| \\
&\leq C(n) \sum_{-\infty}^{\infty} r_j \int_{B_j} |Du| \\
&\leq C(n) |x - y| (\tilde{M}_{3r_0} |Du(x)| + \tilde{M}_{3r_0} |Du(y)|) \\
&\leq 2C(n) |x - y| \lambda.
\end{aligned}$$

Thus we have $C(n)\lambda$ -Lipschitz continuity on the set F_λ . By Remark A.8 and Theorem A.6 we have

$$|B \setminus F_\lambda| \leq \frac{5^n 2}{\lambda} \underbrace{\int_{\{M_{3r_0} |Du(z)| > \lambda\} \cap 3B} |Du|}_{\xrightarrow{\lambda \rightarrow \infty} 0} = o\left(\frac{1}{\lambda}\right)$$

and the claim follows. \square

Remark A.26. The above proof shows that u is $C(n)\lambda$ -Lipschitz in F_λ , where $|B \setminus F_\lambda| = o\left(\frac{1}{\lambda}\right)$. Use the McShane extension theorem to extend the restriction of u to this set as a $C(n)\lambda$ -Lipschitz function u_λ , defined in entire B . Then

$$\int_B |Du - Du_\lambda| \leq \int_{B \setminus F_\lambda} (|Du| + |Du_\lambda|) \leq \int_{B \setminus F_\lambda} |Du| + C(n)\lambda o\left(\frac{1}{\lambda}\right) \xrightarrow{\lambda \rightarrow \infty} 0$$

because

$$Du_\lambda(x) = Du(x) \tag{A.12}$$

at almost every point $x \in F_\lambda$.

Reason: If $E \subset \Omega$ is measurable, $\partial_i v$ and $\partial_i w$ exist almost everywhere in E and $v = w$ on E , then $\partial_i v = \partial_i w$ almost everywhere in E . Simply notice that almost every point x of E is of linear density one in the x_i -direction.

One can do even better. Consider the set

$$\text{Bad}'_\lambda = \{x \in B : \tilde{M}_{3r_0} u(x) \geq \lambda\}.$$

Then $|\text{Bad}'_\lambda| = o\left(\frac{1}{\lambda}\right)$. So, when λ is large, the distance from any point in Bad'_λ to $B \setminus \text{Bad}'_\lambda$ is at most one. Thus the McShane extension u_λ of u from $F_\lambda \setminus \text{Bad}'_\lambda$ is $C(n)\lambda$ -Lipschitz and bounded in absolute value by $2C(n)\lambda$ on B . It follows that

$$\int_B |u - u_\lambda| + |Du - Du_\lambda| \xrightarrow{\lambda \rightarrow \infty} 0.$$

The final estimate of the preceding remark yields the following corollary:

Corollary A.27. *If $u \in W^{1,1}(3B)$, then there is a sequence $\{u_j\}_{j=1}^\infty$ of Lipschitz functions such that*

$$\{x \in B : u_{j+1}(x) \neq u(x)\} \subset \{x \in B : u_j(x) \neq u(x)\}, \quad |\{x \in B : u_j(x) \neq u(x)\}| \xrightarrow{j \rightarrow \infty} 0$$

and

$$\int_B |u - u_j| + |Du - Du_j| \xrightarrow{j \rightarrow \infty} 0.$$

A.7 Differentiability and Approximative Differentiability

The following differentiability result due to Menchoff was independently also proved by Gehring and Lehto.

Lemma A.28. *Suppose that $f : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ is a homeomorphism that belongs to $W_{\text{loc}}^{1,1}(\mathbf{R}^2, \mathbf{R}^2)$. Then f is differentiable almost everywhere.*

Proof. It suffices to prove the claim for the two component functions of f . So, let $u : \mathbf{R}^2 \rightarrow \mathbf{R}$ be one of them. Then, by the Lebesgue differentiation theorem,

$$\lim_{r \rightarrow 0} \frac{1}{|B(x_0, r)|} \int_{B(x_0, r)} |Du(x) - Du(x_0)| dx = 0 \quad (\text{A.13})$$

for almost every x_0 . Fix such a point x_0 , let $r > 0$, and suppose $x \in B(x_0, r)$. Given an open rectangle R_x contained in $B(x_0, 2r)$ with $x \in R_x$, we define a function $v : \overline{R_x} \rightarrow \mathbf{R}$ by setting

$$v(y) = |u(y) - u(x_0) - \langle Du(x_0), x - x_0 \rangle|.$$

Since f is a homeomorphism, the maximum of v on $\overline{R_x}$ occurs on ∂R_x , say at $y_x^R \in \partial R_x$. We conclude that

$$\begin{aligned} |u(x) - u(x_0) - \langle Du(x_0), x - x_0 \rangle| &\leq v(y_x^R) \\ &\leq |u(y_x^R) - u(x_0) - \langle Du(x_0), y_x^R - x_0 \rangle| \\ &\quad + |Du(x_0)| |y_x^R - x|. \end{aligned}$$

Thus, differentiability of u at x_0 follows if, given $\varepsilon > 0$, we can find $r > 0$ so that, for each $x \in B(x_0, r)$ we can make the right-hand side above smaller than εr , via a suitable choice of R_x .

Towards this end, we first deal with the term $|u(y_x^R) - u(x_0) - \langle Du(x_0), y_x^R - x_0 \rangle|$. We may assume that $Du(x_0) = 0$ by replacing u with the function w defined by setting $w(y) = u(y) - \langle Du(x_0), y - x_0 \rangle$. By yet other replacements, we may assume that $x_0 = 0 = u(x_0)$. Then (A.13) guarantees that

$$\lim_{r \rightarrow 0} \frac{1}{r^2} \int_{-r}^r \int_{-r}^r |Du(s, t)| \, ds \, dt = 0.$$

Set $A_r = \{-r < s < r : \int_{-r}^r |Du(s, t)| \, dt \geq \varepsilon r\}$ and $A^r = \{-r < t < r : \int_{-r}^r |Du(s, t)| \, ds \geq \varepsilon r\}$. Then, for each $\varepsilon > 0$, we can find $r_\varepsilon > 0$ so that

$$|A_r| \leq \varepsilon r \text{ and } |A^r| \leq \varepsilon r \quad (\text{A.14})$$

for all $0 < r < r_\varepsilon$. By Theorem A.15 we know that u is absolutely continuous on almost all lines parallel to coordinate axes and hence we may assume that u is absolutely continuous on $y_1 \times [-r, r]$ for every $y_1 \notin A_r$ and on $[-r, r] \times y_2$ for every $y_2 \notin A^r$. We conclude that $|u(y_1, y_2)| \leq 2\varepsilon r$ provided $y_1 \notin A_r$, $y_2 \notin A^r$ and $0 < r < r_\varepsilon$. Thus we have found plenty of rectangles R_x , on the boundary of whose, $|u(y_x^R) - u(x_0) - \langle Du(x_0), y_x^R - x_0 \rangle| \leq 2\varepsilon r$.

By (A.14) we may moreover assume that the side-length of each rectangle R_x is at most εr . Finally,

$$|Du(x_0)| |y_x^R - x| \leq (\text{dist}(x, \partial R_x) + \text{diam}(R_x)) |Du(x_0)|$$

and hence this term is handled by the estimate for the size of R_x . \square

For the study of the regularity of the inverse we need the following elementary observation.

Lemma A.29. *Let $f : \Omega \rightarrow \mathbf{R}^n$ be a homeomorphism which is differentiable at $x \in \Omega$ with $J_f(x) > 0$. Then f^{-1} is differentiable at $f(x)$ and $Df^{-1}(f(x)) = (Df(x))^{-1}$.*

Proof. Let us denote $y = f(x)$. We know that

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x) - Df(x)h}{\|h\|} = 0 \quad (\text{A.15})$$

and we would like to show that

$$\lim_{t \rightarrow 0} \frac{f^{-1}(y+t) - f^{-1}(y) - (Df(x))^{-1}t}{\|t\|} = 0.$$

Given $t \in \mathbf{R}^n$ we set $h = f^{-1}(y+t) - f^{-1}(y)$ which implies that

$$f(x+h) - f(x) = f(f^{-1}(y+t) - f^{-1}(y) + x) - f(x) = t.$$

By (A.15) and $J_f(x) > 0$ we obtain for small enough $\|h\|$ that

$$\|t\| = \|f(x+h) - f(x)\| \approx \|Df(x)h\| \approx \|h\|.$$

Now (A.15) implies that

$$0 = \lim_{h \rightarrow 0} \frac{(f(x+h) - f(x) - Df(x)h)(Df(x))^{-1}}{\|h\|}$$

which implies that

$$\begin{aligned} 0 &= \lim_{t \rightarrow 0} \frac{(Df(x))^{-1}(f(x+h) - f(x)) - h}{\|t\|} \\ &= \lim_{t \rightarrow 0} \frac{(Df(x))^{-1}t - f^{-1}(y+t) - f^{-1}(y)}{\|t\|} \end{aligned}$$

and we get the desired conclusion. \square

Definition A.30. Let $\Omega \subset \mathbf{R}^n$, $d \in \mathbf{N}$ and let $f : \Omega \rightarrow \mathbf{R}^d$ be a mapping. We say that f is approximatively differentiable at $x \in \Omega$ with approximative derivative $Df(x)$ if there is a set $A \subset \Omega$ of density one at x , i.e. $\lim_{r \rightarrow 0} \frac{|A \cap B(x,r)|}{|B(x,r)|} = 1$, such that

$$\lim_{y \rightarrow x, y \in A} \frac{f(y) - f(x) - Df(x)(y-x)}{\|y-x\|} = 0.$$

It is well known that Sobolev functions are differentiable a.e.

Theorem A.31. Let $\Omega \subset \mathbf{R}^n$, $d \in \mathbf{N}$ and let $f \in W^{1,1}(\Omega, \mathbf{R}^d)$. Then f is approximatively differentiable a.e. in Ω and its approximative derivative coincides with its weak derivative a.e.

Proof. By Corollary A.27 we know that we can find a sequence of Lipschitz mappings $f_j : \Omega \rightarrow \mathbf{R}^d$ such that for

$$A_j := \{x \in \Omega : f_j(x) \neq f(x)\} \text{ we have } A_{j+1} \subset A_j \text{ and } |A_j| \rightarrow 0.$$

The Lipschitz mappings f_j are differentiable a.e. (see Theorem 2.23) and their classical derivatives coincide with the weak derivatives Df_j (see Corollary A.16).

It is easy to see that $\Omega = \bigcup_j A_j \cup S$ where $|S| = 0$. Almost every point of A_j is a point of density of A_j and hence for almost every $x \in \Omega$ we can find j such that

$$\lim_{r \rightarrow 0} \frac{|A_j \cap B(x,r)|}{|B(x,r)|} = 1.$$

Let us pick a point $x \in \Omega$ such that x is a point of density of A_j and f_j is differentiable at x . Since $f = f_j$ on A_j we obtain from the differentiability of f_j that

$$\begin{aligned} 0 &= \lim_{y \rightarrow x} \frac{f_j(y) - f_j(x) - Df_j(x)(y - x)}{\|y - x\|} \\ &= \lim_{y \rightarrow x, y \in A_j} \frac{f(y) - f(x) - Df_j(x)(y - x)}{\|y - x\|} \end{aligned}$$

which implies the approximative derivative of f at x exists and equals to $Df_j(x)$. \square

We need an analogue of Lemma A.29 for approximatively differentiable mappings. For its proof we need the following observation.

Lemma A.32. *Let $\Omega \subset \mathbf{R}^n$ and let $g : \Omega \rightarrow \mathbf{R}^n$ be Lipschitz mapping that is differentiable at x . Suppose that $J_g(x) \neq 0$ and let A be a set of density 1 at $x \in \Omega$. Then the density of the set $g(A)$ at $g(x)$ is 1.*

Proof. Let us denote $y = g(x)$ and let $r > 0$ be small enough such that $B(y, r) \subset f(\Omega)$. Since g is differentiable at x , continuous and $J_g(x) \neq 0$ we obtain that for r small enough we have

$$B(y, r) \subset g(B(x, C_1 r)) \quad \text{for} \quad C_1 = 2|(Dg(x))^{-1}|. \quad (\text{A.16})$$

We know that

$$\lim_{\tilde{r} \rightarrow 0} \frac{|A \cap B(x, \tilde{r})|}{|B(x, \tilde{r})|} = 1$$

and hence for given $\varepsilon > 0$ we obtain that for small enough r we have

$$|B(x, C_1 r) \setminus A| < \varepsilon |B(x, C_1 r)| = \varepsilon C_1^n |B(x, r)|.$$

Since g is Lipschitz with constant L , (A.16) gives

$$|B(y, r) \setminus g(A)| \leq |g(B(x, C_1 r)) \setminus g(A)| \leq |g(B(x, C_1 r) \setminus A)| < L^n \varepsilon C_1^n |B(x, r)|.$$

This shows that

$$\lim_{r \rightarrow 0} \frac{|g(A) \cap B(y, r)|}{|B(y, r)|} = 1. \quad \square$$

Now we prove the desired analog of Lemma A.29, following [33, Lemma 2.1].

Lemma A.33. *Let $f : \Omega \rightarrow \Omega'$ be a homeomorphism such that $f \in W^{1,1}(\Omega, \Omega')$ and $f^{-1} \in W^{1,1}(\Omega', \Omega)$. Set*

$$E := \{y \in \Omega' : f^{-1} \text{ is approximatively differentiable at } y \text{ and } |J_{f^{-1}}(y)| > 0\}.$$

Then, there exists a Borel set $A \subset E$ with $|E \setminus A| = 0$ such that

$$f^{-1}(A) \subset F := \{x \in \Omega : f \text{ is approximatively differentiable at } x \text{ and } |J_f(x)| > 0\}$$

and we have

$$Df^{-1}(y) = (Df(f^{-1}(y)))^{-1} \text{ for every } y \in A.$$

Proof. From the proof of Theorem A.31 we know that there is a null set N_E such that for every $y \in E \setminus N_E$ we can find a Lipschitz mapping h and set $\tilde{E} \subset E$ such that \tilde{E} has density one at y , $f^{-1} = h$ on \tilde{E} , h is differentiable at y and $Df^{-1}(y) = Dh(y)$. We can also require that $E \setminus N_E$ is a Borel set. Analogously, we can find a null set N_F so that for every $x \in F \setminus N_F$ we can find a Lipschitz mapping g and set $\tilde{F} \subset F$ such that \tilde{F} has density one at x , $f = g$ on \tilde{F} , g is differentiable at x and $Df(x) = Dg(x)$.

By Corollary A.36 we obtain that there is a Borel set $J \subset \{J_f = 0\}$ such that $|f(J)| = 0$ and $|J| = |\{J_f = 0\}|$. This and the a.e. approximative differentiability of f (see Theorem A.31) shows that the set $N_F \cup (\Omega \setminus (F \cup J))$ has measure zero. We can find a Borel set N of measure zero such that $N_F \cup (\Omega \setminus (F \cup J)) \subset N$ and by the Area formula (A.19) applied to f^{-1} we know that

$$\int_{f(N)} |J_{f^{-1}}(y)| dy \leq \int_{f^{-1}(f(N))} dx = |N| = 0.$$

Since $J_{f^{-1}} > 0$ on E , this implies that $|f(N) \cap E| = 0$. For the set

$$A := E \setminus (f(N) \cup N_E \cup f(J))$$

we thus have $|E \setminus A| = 0$ and $f^{-1}(A) \subset F$.

Given $y \in A$ we denote $x = f^{-1}(y) \in F$ and we can find functions h, g and sets \tilde{E} and \tilde{F} as in the first paragraph. Since g is differentiable at x and h is differentiable at y we obtain

$$D(g \circ h)(y) = Dg(h(y))Dh(y) = Dg(x)Dh(y). \quad (\text{A.17})$$

Since $|J_g(x)| = |J_f(x)| > 0$ we obtain by Lemma A.32 that the set $g(\tilde{F}) \cap \tilde{E}$ has density one at y . For every $z \in g(\tilde{F}) \cap \tilde{E}$ we have $g(h(z)) = f(f^{-1}(z)) = z$ and hence $D(g \circ h)(y) = I$. Now (A.17) implies $Dh(y) = (Dg(x))^{-1}$. \square

A.8 Area and Coarea Formula

Let us recall the definition of the Lusin (N) condition.

Definition A.34. Let $\Omega \subset \mathbf{R}^n$ be open. We say that $f : \Omega \rightarrow \mathbf{R}^n$ satisfies the Lusin (N) condition if

$$\text{for each } E \subset \Omega \text{ such that } |E| = 0 \text{ we have } |f(E)| = 0 .$$

Theorem A.35. Let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^n)$ and let η be a nonnegative Borel measurable function on \mathbf{R}^n . Then

$$\int_{\Omega} \eta(f(x)) |J_f(x)| dx \leq \int_{\mathbf{R}^n} \eta(y) N(f, \Omega, y) dy , \quad (\text{A.18})$$

where the multiplicity function $N(f, \Omega, y)$ of f is defined as the number of preimages of y under f in Ω . Moreover, there is an equality in (A.18) if we assume in addition that f satisfies the Lusin (N) condition.

Proof (Sketch of the Proof). It is known that each $f \in W^{1,1}$ is a.e. approximatively differentiable (see Theorem A.31), and by Corollary A.27 we can decompose $\Omega = S \cup \bigcup_{i=1}^{\infty} \Omega_i$ in a such a way that $|S| = 0$ and the restriction $f|_{\Omega_i}$ to each set Ω_i is Lipschitz (see the proof of Theorem A.31). It is well-known that the Area formula holds for Lipschitz mappings and hence on each Ω_i we get

$$\int_{\Omega_i} \eta(f(x)) |J_f(x)| dx = \int_{\mathbf{R}^n} \eta(y) N(f, \Omega_i, y) dy .$$

By summing of these equalities we obtain the left-hand side of (A.18) since $|S| = 0$. The right-hand is bigger or equal since

$$\int_{\mathbf{R}^n} \eta(y) N(f, \Omega, y) dy = \int_{\mathbf{R}^n} \eta(y) N(f, S, y) dy + \sum_{i=1}^{\infty} \int_{\mathbf{R}^n} \eta(y) N(f, \Omega_i, y) dy$$

and the first term is nonnegative and potentially strictly positive if $|f(S)| > 0$. Moreover, if f satisfies the Lusin (N) condition then $|f(S)| = 0$ and hence the first term vanishes and the equality holds in (A.18). \square

Corollary A.36. (a) Let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^n)$ be a homeomorphism, $\tilde{\eta}$ a nonnegative Borel measurable function on \mathbf{R}^n and let $A \subset \Omega$ be a Borel measurable set. Then

$$\int_A \tilde{\eta}(f(x)) |J_f(x)| dx \leq \int_{f(A)} \tilde{\eta}(y) dy . \quad (\text{A.19})$$

- (b) Let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^n)$ be a homeomorphism and let η be a nonnegative Borel measurable function on \mathbf{R}^n . Then there is a set $\Omega' \subset \Omega$ of full measure $|\Omega'| = |\Omega|$ such that

$$\int_{\Omega'} \eta(f(x)) |J_f(x)| dx = \int_{f(\Omega')} \eta(y) dy. \quad (\text{A.20})$$

- (c) Let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^n)$ be a homeomorphism, let η be a nonnegative Borel measurable function on \mathbf{R}^n and let A denote the set where f is differentiable. Then

$$\int_A \eta(f(x)) |J_f(x)| dx = \int_{f(A)} \eta(y) dy.$$

- (d) Let $f \in W_{\text{loc}}^{1,1}(\Omega, \mathbf{R}^n)$ be a mapping whose multiplicity is essentially bounded by N and let $A \subset \Omega$ be a measurable set. Then

$$\int_A |J_f(x)| dx \leq N \int_{f(A)} dy = N |f(A)|.$$

Especially we get that the Jacobian of a mapping with essentially bounded multiplicity is locally integrable.

For the part (a) above, the multiplicity of a homeomorphism is bounded by one and we apply the previous theorem for $\tilde{\eta} = \chi_{f(A)}\eta$. Regarding (b), it is enough to set $\Omega' = \bigcup_{n=1}^{\infty} \Omega_i$, where the sets Ω_i are as in the proof of the previous theorem. The part (c) follows from the previous theorem and the fact that the Lusin condition (N) holds on the set A of differentiability. This can be easily shown from the definition of differentiability with the help of the Vitali covering theorem.

The Sard Theorem [90, Theorem 7.6] tells that the image of the set of critical points is of measure zero.

Theorem A.37 (Sard). *Let $f : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be Lipschitz mapping. Then*

$$\mathcal{L}_n(\{f(x) : J_f(x) = 0\}) = 0.$$

The coarea formula is very useful tool in analysis and its form for Lipschitz functions can be found in Federer [31, 3.2.12].

Theorem A.38. *Let $\Omega \subset \mathbf{R}^n$ be an open set and let $f : \Omega \rightarrow \mathbf{R}^m$ be Lipschitz. Then for every measurable set $E \subset \Omega$ we have*

$$\int_E |J_m f(x)| dx = \int_{\mathbf{R}^m} \mathcal{H}^{n-m}(E \cap f^{-1}(y)) dy$$

where $J_m f$ denotes the square root of the sum of the squares of the determinants of the m -by- m minors of the differential of f .

A.9 Estimates for q -Capacity

The following estimate on q -capacity is standard, see e.g. [58, Theorem 5.9].

Theorem A.39. *Let $n - 1 \leq q < n$ and $\varepsilon > 0$. Let $B_0 \subset \mathbf{R}^n$ be a ball of radius r , $n \geq 2$, and let $E, F \subset \frac{1}{2}B_0$. Suppose that $u \in W^{1,q}(B_0)$ is continuous and satisfies $u \leq 0$ on E and $u \geq 1$ on F . Then*

$$r^\varepsilon \int_{B_0} |Du|^q \geq C \min\{\mathcal{H}_\infty^{n-q+\varepsilon}(E), \mathcal{H}_\infty^{n-q+\varepsilon}(F)\}.$$

Moreover, for $n = 2$ and $q = 1$ this estimate is valid also for $\varepsilon = 0$.

Proof. Without loss of generality we may assume that $u_{B_0} \geq \frac{1}{2}$; otherwise we switch the role of E and F . For every $x \in E$ we set $B_i(x) = B(x, 2^{-i+1}r)$, $i \in \mathbf{N}$. As u is continuous we have $u_{B_i(x)} \rightarrow u(x)$ and hence

$$\frac{1}{2} \leq |u(x) - u_{B_0}| \leq \sum_{i=1}^{\infty} |u_{B_i(x)} - u_{B_{i-1}(x)}|.$$

Since $B_i \subset B_{i-1}$, we may estimate the last term similarly to (A.11) and by the Poincaré inequality, Theorem A.17, and Hölder's inequality we obtain

$$\frac{1}{2} \leq \sum_{i=0}^{\infty} \int_{B_i(x)} |u(y) - u_{B_i(x)}| dy \leq C \sum_{i=0}^{\infty} 2^{-i} r \left(\int_{B_i(x)} |Du(y)|^q dy \right)^{\frac{1}{q}}. \quad (\text{A.21})$$

Let $\delta > 0$. We claim that for every $x \in E$ we can find $i_x \in \mathbf{N}$ such that

$$\delta r^{-\varepsilon} (2^{-i_x} r)^{n-q+\varepsilon} \leq \int_{B_{i_x}(x)} |Du(y)|^q dy, \quad (\text{A.22})$$

provided δ is sufficiently small (in terms of q, n, ε). Otherwise (A.21) implies that

$$\frac{1}{2} \leq C \sum_{i=0}^{\infty} 2^{-i} r \left(\frac{1}{|B_i(x)|} \delta r^{-\varepsilon} (2^{-i} r)^{n-q+\varepsilon} \right)^{\frac{1}{q}} \leq C \delta^{\frac{1}{q}} \sum_{i=0}^{\infty} (2^{-i})^{\frac{\varepsilon}{q}} \leq C \delta^{\frac{1}{q}}$$

which gives us a contradiction for small enough $\delta > 0$. Let $\delta > 0$ be fixed and so small that the above holds. For each $x \in E$ we choose a ball $B_{i_x}(x)$ such that (A.22) holds. By the Vitali covering theorem, Theorem A.1, we choose a subcollection of pairwise balls B_k with radii r_k such that $E \subset \bigcup_k 5B_k$. Using (A.22) for B_k we now obtain the desired estimate

$$\mathcal{H}_\infty^{n-q+\varepsilon}(E) \leq \sum_k (5r_k)^{n-q+\varepsilon} \leq C \sum_k \frac{1}{\delta} r_k^\varepsilon \int_{B_k} |Du(y)|^q dy \leq C r^\varepsilon \int_{B_0} |Du(y)|^q dy. \quad (\text{A.23})$$

The proof for $n = 2$ and $q = 1$ with $\varepsilon = 0$ is more demanding and we will not give it here. It follows from a stronger estimate for continuous functions in $W^{1,1}(\mathbf{R}^n)$ (see [1]):

$$\int_0^\infty \mathcal{H}_\infty^1(\{x \in \mathbf{R}^n : M|u(x)| > t\}) dt \leq C(n) \int_{\mathbf{R}^n} |Du(x)| dx.$$

To have a geometric idea, consider the simple situation

$$E = \{0\} \times [0, \text{diam } E] \text{ and } F = \{t\} \times [0, \text{diam } F] \text{ for some } t > 0.$$

Then we can use the fundamental theorem of calculus for each $y \in [0, \min(\text{diam } E, \text{diam } F)]$, $u(0, y) \leq 0$ and $u(t, y) \geq 1$ to obtain

$$\int_0^t |Du(s, y)| ds \geq 1.$$

By Fubini we get the desired estimate

$$\int_{B_0} |Df| \geq \min(\text{diam } E, \text{diam } F)$$

in this simple situation. □

The following result is a consequence of the proof above.

Corollary A.40. *Let $n \geq 2$ and $n - 1 < q < n$. Let $\Omega \subset \mathbf{R}^n$ be an open set and let $F \subset \Omega$ be a continuum. Suppose that $u \in W^{1,q}(\Omega)$ is continuous, has compact support in Ω and satisfies $u \geq 1$ on F . Then*

$$C(q, n) \int_{\Omega} |Du|^q \geq \text{diam}^{n-q}(F).$$

Proof. We extend u outside Ω as zero. Without loss of generality assume that $u \leq 1$. We can clearly fix a ball B_1 such that the support of u is contained in B_1 and we can find a ball $B_0 \subset 2B_1$ such that $F \subset B_0$ and $\text{diam } B_0 \leq 2 \text{diam } F$.

In the case $u_{B_0} \leq \frac{1}{2}$ we proceed similarly to the previous proof. For each $x \in F$ we can find balls $B_i(x)$ such that $u_{B_i(x)} \rightarrow u(x) \geq 1$ and we have (A.21). We can choose ε , so that $n - q + \varepsilon = 1$. Since F is a continuum we obtain $\text{diam } F \leq \mathcal{H}_\infty^1(F)$. As before we obtain (A.23) and hence

$$\text{diam}^{n-q+\varepsilon} F \leq C \text{diam}^\varepsilon B_0 \int_{B_0} |Du(y)|^q dy$$

which gives us the desired estimate as $\text{diam } B_0 \leq 2 \text{diam } F$.

It remains to consider the case $u_{B_0} > \frac{1}{2}$. Note that clearly $u_{2B_1} \leq \frac{1}{4}$ since u is supported in B_1 . Now we can find balls $\tilde{B}_1, \tilde{B}_2, \dots, \tilde{B}_k$ such that $\tilde{B}_1 = B_0$, $\tilde{B}_k = 2B_1$,

$$\tilde{B}_i \subset \tilde{B}_{i+1}, \quad 2 \operatorname{diam} \tilde{B}_i \leq \operatorname{diam} \tilde{B}_{i+1}, \quad \text{and} \quad |\tilde{B}_{i+1}| < C |\tilde{B}_i| \quad \text{for all } i \in \{1, \dots, k-1\}.$$

Similarly to (A.21) we have

$$\frac{1}{4} \leq |u_{B_0} - u_{2B_1}| \leq \sum_{i=1}^k \int_{\tilde{B}_i} |u(y) - u_{\tilde{B}_i}| \, dy \leq C \sum_{i=1}^k \operatorname{diam}(\tilde{B}_i) \left(\int_{\tilde{B}_i} |Du(y)|^q \, dy \right)^{\frac{1}{q}}.$$

Since $2 \operatorname{diam} \tilde{B}_i \leq \operatorname{diam} \tilde{B}_{i+1}$ and $q < n$, this implies that

$$C \leq \sum_{i=1}^k \operatorname{diam}^{1-\frac{n}{q}}(\tilde{B}_i) \left(\int_{\tilde{B}_i} |Du(y)|^q \, dy \right)^{\frac{1}{q}} \leq C \operatorname{diam}^{1-\frac{n}{q}}(\tilde{B}_1) \left(\int_{\Omega} |Du(y)|^q \, dy \right)^{\frac{1}{q}},$$

which gives us the desired estimate as $\operatorname{diam} \tilde{B}_1 = \operatorname{diam} B_0 \geq \operatorname{diam} F$. \square

The following capacity estimate can be found in [34].

Theorem A.41. *Suppose that Ω is a bounded open set, $E \subset \Omega$ is a continuum and that a continuous function $u \in W^{1,n}(\Omega)$ satisfies $u \geq 1$ on E and has compact support in Ω . Then*

$$\int_{\Omega} |Du(x)|^n \, dx \geq \frac{\omega_{n-1}}{\left(\log \left(\frac{C(n) \operatorname{diam} \Omega}{\operatorname{diam} E} \right) \right)^{n-1}}.$$

On the other hand, for $\Omega = B(0, R)$ and $E = \overline{B(0, r)}$ with $0 < r < R$, the above estimate is sharp as can be shown by taking $u(x) = \min\{1, \log \frac{R}{|x|} / \log(\frac{R}{r})\}$.

A.10 Solvability of $\Delta u = \varphi$

Solvability of the Poisson equation follows by convolution with the Green's function, see [28, Chap. 2.2.1 (b)].

Theorem A.42. *Let $\varphi \in C_c(\mathbf{R}^n)$. Then there is $u \in C^2(\mathbf{R}^n)$ such that $\Delta u(x) = \varphi(x)$.*

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