

# SESSION XI GENERAL APPLICATIONS I

James H. Johnson, *Presider*

## A microcomputer-based cardiotachometer with video display

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A KIM-1 single board microcomputer implementation of a cardiotachometer that provides a low-cost versatile heart-rate data acquisition system is described. Unique features include telemetry, a composite video output signal of a video frame displaying elapsed time and heart-rate, and a TV camera signal of the behavior. Data is videotape- and/or audiotape-recorded for further analysis with a larger computer.

There is a need for more research on anxiety using physiological measures (Hodges, 1976). However, according to Sieber, O'Neil, and Tobias (1977, p. 34), "it is not feasible to locate physiological recording equipment in school settings, to have electrodes attached to students while they attempt to do academic work." Obviously, an instrument that does not require electrodes with leads running to a physiograph would be more suitable to naturalistic settings and allow research of a broader range of behavior. The instrument to be described here uses a KIM-1 microprocessor to combine telemetric monitoring of heart rate with a video camera signal. A unique feature of this cardiotachometer is the capability of providing a composite video output signal of a frame displaying elapsed time in minutes and seconds, together with a subject's measured R-R interval. This can be mixed with a television camera signal to provide a composite view of a subject's behavior and his or her heart rate. This apparatus should open new avenues to researchers who wish to use heart rate to monitor the physiological response of subjects in various settings, such as schools and offices, as well as a laboratory environment.

### SYSTEM OVERVIEW

Our cardiotachometer is similar in principle to others described recently by Dejong (1980) and Klosterhalfen (1980). The unique feature of the system described here is the combination of telemetry to acquire sensor data

and superimposing heart-rate data with a video image of the subject. All of the components, with the exception of the transducer and interface, are standard off-the-shelf components.

An overall view of the system is shown in Figure 1. The input sensor consists of a simple photoplethysmograph mounted on a finger of the subject. The output of the sensor can be either connected directly to the cardiotachometer via suitable signal conditioning electronics or transmitted via a small FM transmitter to a nearby receiver whose output drives the transducer interface. R-wave pulses are amplified, filtered, and peak detected

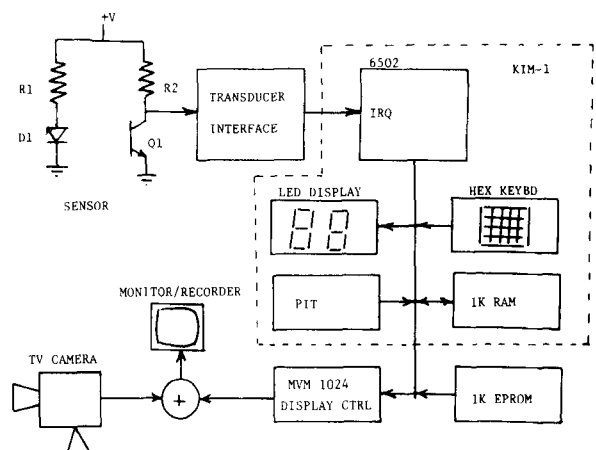


Figure 1. Cardiotachometer block diagram.

by the transducer interface to produce an interrupt request (IRQ) to the 6502 microprocessor.

The number of 10-msec intervals that occur between interrupts are counted by a program residing in non-volatile read-only memory (1K EPROM). The 10-msec intervals are produced by an on-board crystal-controlled programmable interval timer (PIT). The reciprocal of the R-R intervals are calculated, and a running average of four consecutive rates is maintained. The resulting heart rate in beats per minute is displayed on the integral LED display and output to an alphanumeric frame buffer (MVM-1024). Elapsed time in minutes and seconds is also displayed in the frame buffer for convenience, and the display is updated every 1 sec.

The video output from the frame buffer is mixed with video from a small television camera, and the resulting composite image can either be displayed on a local display or be tape-recorded for off-line analysis.

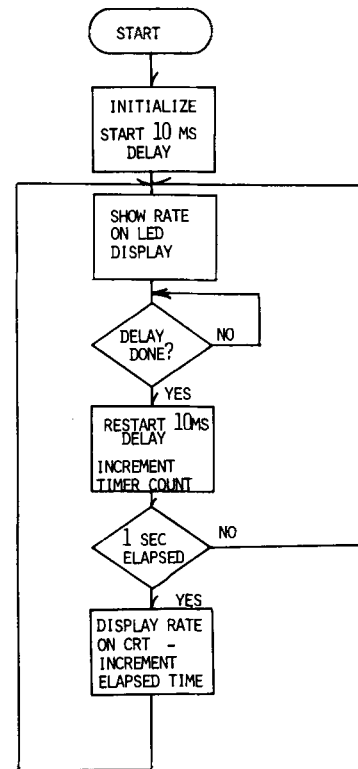
### MICROCOMPUTER-BASED CARDIOTACHOMETER

#### Microcomputer

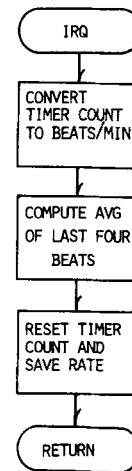
The primary component of our system is a KIM-1 single-board computer. The KIM-1 is a familiar component in many instrumentation systems used in psychology and will not be described further here. In order to expand the basic KIM, we used a Riverside Electronics KEM expansion motherboard, an MVM-1024 alphanumeric display module and a KIMSI power supply. Regulators to supply +5, -5, and +12 V dc had to be added to the unregulated power supply. The KEM is an S-100 bus-compatible adaptor for the KIM-1 that also contains room for four 2708 EPROMs. These provide an extra 4,096 bytes of program storage. The cardiotech program and video driver routines are stored in a single 1,024-byte EPROM. This storage is nonvolatile and need not be reloaded after power is removed.

A flowchart of the cardiotech program is shown in Figure 2. A complete listing is provided in Appendix A. As seen in Figure 2a, the main timer loop increments a count of the number of 10-msec intervals elapsed since the last interrupt, restarts a 10-msec timer, and displays the current rate on the LED display. The KIM-1 LED display is controlled by software and must be refreshed frequently to provide a flicker-free display. This takes about 2 msec during the 10-msec countdown interval. After 100 10-msec intervals have elapsed, the CRT display is updated with the current rate and elapsed time in minutes and seconds.

Each sensor pulse results in an interrupt that causes control to be passed to IRQ. This routine, shown in Figure 2b, takes the count of the number of 10-msec intervals since the last interrupt, converts it to beats per minute, and computes a running average of the four most recent values. This tends to smooth out short-term variations in R-R intervals and "short beats" due to noise-generated interrupts.



MAIN TIMER AND DISPLAY LOOP



IRQ ENTERED ONCE EACH BEAT

Figure 2. (a) Flowchart of main tachometer program. (b) Interrupt service routine and heart-rate calculation.

#### Transducer Interface

The transducer interface is shown in Figure 3. This is similar to a circuit used by Dejong (1980) and seems to work reasonably well. A band-pass filter was added to reduce noise from the telemetry system. The threshold

detector approach to R-wave detection works fairly well and is simple to implement but must be "tuned" to a particular subject, since there is considerable variation in sensor signal level from subject to subject. A better R-wave detection system is currently being investigated.

### VIDEO DISPLAY

The primary component of the video display consists of a Riverside Electronics MVM-1024 microprocessor video display driver. The MVM is capable of displaying 16 rows of 64 alphanumeric characters on a standard television monitor, and contains its own 1,024-character display buffer. We use the lower left-hand corner for display purposes, with the rest of the area available for future display of additional parameters. Subroutines used to drive the MVM-1024 are listed in Appendix B.

The MVM-1024 was slightly modified by the addition of two connectors for horizontal and vertical synchronization signals. The MVM's own sync signals are used to externally synchronize the television camera and thus eliminate the need for a common external synchronization source. A simple resistor network suffices to mix the two video signals to provide a composite data/image video signal for recording and/or display.

### INPUT TRANSDUCER

The input transducer shown schematically in Figure 1 consists of a simple photodiode-phototransistor pair (Radio Shack 276-142) mounted inside a small plastic finger-cuff. R1 is approximately 370 ohms to provide a diode current of about 20 mA. Load Resistor R2 is 200 kohms and is not at all critical. Supply voltage (V) is 9 V taken from a small 9-V battery. The output is a pulse of about .2-V pulse-to-pulse (p-p) amplitude superimposed on a 4- to 5-V dc bias.

The finger-cuff and battery are mounted inside a child's glove, together with a small FM transmitter. This apparatus provides a rather unobtrusive instrumentation package. Dummy packages can be made up and passed off as "space commando gloves," so subjects do not know who is being monitored.

As an alternative, various commercial types of finger-cuffs or photoplethysmographs are available (e.g., Lafayette Instrument Company). Some commercial telemetry systems can use a variety of transducers and/or disposable electrode attachments (e.g., Midgard Electronics).

### TELEMETRY SYSTEM

An existing Bio-Sentry Telemetry Model 4200 FM instrumentation receiver and Model 201 transmitter are used to telemeter sensor output to the transducer interface. The transmitter operated on IRIG Channel 7. There is nothing at all special about this system, which was used simply because it was available. A smaller transmitter package and one tailored specifically for this application would have been desirable. The current package measures 6.00 x 1.65 x 3.81 cm, excluding the battery and sensor. The Bio-Sentry Telemetry Model 2200 voltage-controlled oscillator and amplifier were originally designed to monitor ECG and had to be preceded with a resistive voltage divider to reduce the sensor output signal to a level compatible with the transmitter. Many alternative telemetry packages are available.

### FUTURE PLANS

We plan to use the system in a normal classroom environment to collect data in order to study factors influencing classroom anxiety in children. The system will allow an investigator to conveniently and systematically analyze physiological data (heart rate) and behavior in relationship to events preceding and following significant arousals.

We intend to extend this single-subject pilot model to a multiple-subject system. The use of a microprocessor will allow us to conveniently modify the system with minimum impact on hardware design. Other physiological measures such as GSR and T-wave amplitude can be readily accommodated. We are also currently developing such a system for animals; in the system, heart-rate data are transmitted via an implantable transmitter (e.g., Konigsburg Instruments). The combination of a video image of a subject and a physiological parameter in an unobtrusive manner promises to open up new vistas for the behavioral investigator.

### REFERENCES

- DEJONG, M. L. A digital cardi tachometer implemented with the AIM 65. *Compute II*, August/September 1980, pp. 32-35.
- HODGES, L. The psychophysiology of anxiety. In M. Zuckerman & C. D. Spielberger (Eds.), *Emotions and anxiety: New concepts, methods, and applications*. Hillsdale, N.J.: Erlbaum, 1976.
- KLOSTERHALFEN, W. A computer-controlled cardi tachometer. *Behavior Research Methods & Instrumentation*, 1980, 1, 58-62.
- SIEBER, J. E., O'NEIL, H. F., JR., TOBIAS, S. *Anxiety, learning and instruction*. New York: Wiley, 1977.

### Appendix A Cardiotachometer Program Listing

CTACH

KIM-1 CROSS ASSEMBLER

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1 ; CTACH
2 ; CARDIOTACHOMETER PROGRAM FOR THE KIM-1 MICROCOMPUTE
3 ; 9-1-80
4 ; PAM SCHROETER, UMR EE DEPT
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;
; .LOC $1000
; EQU $1706
TIMER EQU $1707
TIMOT EQU $1700
PAD EQU $1701
PADD EQU $0A
CLOCK EQU $0B
SEC EQU $0C
MIN EQU $B1
POINTR EQU $00
COUNTR EQU $03
CNT EQU $02
CNTHI EQU $01
CNTLO EQU $03
CNTMI EQU $1F1F
SCANDS EQU $09
TEMP EQU $F1
STATUS EQU $124C
ERASE EQU $04
BUFFER EQU $05
PNTL EQU $06
IN EQU $F9
INH EQU $FA
POINTL EQU $FB
POINTH EQU $1200 ; VIDEO DISPLAY DRIVER
;
; INITIALIZATION
;
START SEI ; DISABLE INTERRUPTS
LDA #$62
STA $17FE ; SET UP INTERRUPT VECTOR
LDA #$10
STA $17FF
LDA #$00
STA STATUS
STA POINTR
STA SEC
STA MIN
LDX #$01
STA PAD ; SET UP DATA DIRECTION REG
STA PADD
LDA #$64
STA CLOCK
JSR ERASE ; ERASE THE SCREEN
DEC PAD
LDX #$FF
STX COUNTR
CLI ; ENABLE INTERRUPTS
;
; LOOP TO MEASURE THE TIME BETWEEN EACH HEARTBEAT AND
; MEASURE THE REAL TIME ELAPSED.
; UPDATES PULSE AND TIME EACH SECOND.
;
LOOP LDA #$9C ; START TIMER FOR 10 MSEC
STA TIMER
INC COUNTR
DEC CLOCK
BNE NOMIN ; WAIT 1 SECOND
LDA #$64
STA CLOCK ; RESET CLOCK
JSR VIDSP ; DISPLAY PULSE AND REAL TIME
SED
CLC
LDA SEC
ADC 01 ; INCR SECONDS
CMP #$60
BNE CONT ; BRANCH IF .LT. 60 SEC
LDA MIN
CLC
ADC #$01 ; INCR MIN
STA MIN
LDA #$00
STA SEC ; SAVE SECONDS
CLD
NOMIN JSR SCANDS ; DISPLAY PULSE RATE
JSR SCANDS ; DO IT AGAIN
CHECK LDA TIMOT ; CHECK TIMER, IF NOT FINISHE
BPL CHECK ; BRANCH TO CHECK AGAIN

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84 105F 4C 2C 10          JMP LOOP          ; START TIMER AGAIN
85                          ;
86                          ; IRQ
87                          ; EACH PULSE GENERATES AN INTERRUPT
88 1062 EE 00 17          IRQ   INC PAD          ; PAD = 1
89 1065 A5 00              LDA COUNTR        ; IF COUNTR = 0, GO TO AGN
90 1067 D0 03              BNE IRQ1
91 1069 4C                 JMP AGN
92 106C 85 03              IRQ1  STA CNT
93 106E A9 00              LDA #$00
94 1070 85 F9              STA INH
95 1072 85 FA              STA POINTL
96 1074 85 FB              STA POINTH
97                          ;
98                          ; DIVIDE
99                          ; FIND RECIPROCAL OF INTER-PULSE INTERVAL
100                         ;
101 1076 A2 0A              LDX #$0A
102 1078 A9 DC              LDA #$DC
103 107A 85 02              STA CNTHI
104 107C A9 05              LDA #$05
105 107E 85 00              STA 0 CNTLO
106 1080 38                 SEC
107 1081 E5 03              SBC CNT
108 1083 30 15              BRANCH BMI NEG
109 1085 CA                 PDS   DEX
110 1086 D0 03              BNE DIV1
111 1088 4C                 JMP ENDIV
112 108B 85 01              DIV1 STA CNTLO
113 108D 38                 SEC
114 108E 26 02              ROL CNTHI
115 1090 26 01              ROL CNTLO
116 1092 A5 01              LDA CNTLO
117 1094 38                 SEC
118 1095 E5 03              SBC CNTMI
119 1097 4C 83 10          JMP BRANCH
120 109A CA                 NEG   DEX
121 109B D0 03              BNE DIV2
122 109D 4C                 JMP ENDIV
123 10A0 85 01              DIV2 STA CNTLO
124 10A2 18                 CLC
125 10A3 26 02              ROL      CNTHI
126 10A5 26 01              ROL CNTLO
127 10A7 A5 01              LDA CNTLO
128 10A9 18                 CLC
129 10AA 65 03              ADC CNTMI
130 10AC 4C 83 10          JMP BRANCH
131 10AF A6 04              ENDIV LDX BUFFER
132                          ;
133                          ; BUFSTO
134                          ; STORE THE RESULT IN A BUFFER AT $0004
135                          ;
136 10B1 C5 81              BUFSTO CMP POINTR
137 10B3 D0 04              BNE BST1
138 10B5 A5 00              LDA COUNTR
139 10B7 85 81              STA POINTR
140 10B9 A5 02              BST1  LDA CNTHI
141 10BB A6 81              LDX POINTR
142 10BD 95 04              STA BUFFER,X
143 10BF E6 81              INC POINTR
144                          ;
145                          ; ADD
146                          ; ADD FOUR BYTES ($0004 - $0007),
147                          ; FORMING THE AVERAGE OF FOUR BEATS
148                          ;
149 10C1 18                 ADD   CLC
150 10C2 A9 00              LDA #$00
151 10C4 A2 04              LDX #$04
152 10C6 75 04              ADLOOP ADC BUFFER,X
153 10C8 CA                 DEX
154 10C9 D0 FB              BNE ADLOOP
155 10CB 20 DE 10          ADL1 JSR CNVT
156 10CE A5 05              LDA PNTL
157 10D0 85 FA              STA POINTL
158 10D2 A5 06              LDA IN
159 10D4 85 F9              STA INH
160                          ;
161                          ; AGN
162                          ; RE-INIT THE COUNTER

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163                                     ;
164 10D6 CE 00 17                     AGN     DEC PAD
165 10D9 A2 FF                         LDX   ##FF
166 10DB 86 00                         STX   COUNTR
167 10DD 40                             RTI
168                                     ;
169                                     ; CNVT
170                                     ; BINARY TO DECIMAL CONVERT
171                                     ; TAKES 8-BIT NUMBER IN THE ACC AND CONVERTS IT
172                                     ; TO A DECIMAL NUMBER WITH LOW ORDER STORED IN 'IN'
173                                     ; HIGH ORDER STORED IN PNTL.
174                                     ;
175 10DE A2 64                         CNVT   LDX   ##64
176 10E0 86 09                         STX   TEMP
177 10E2 20 FE 10                      JSR   SUBT
178 10E5 86 05                         STX   PNTL
179 10E7 A2 0A                         LDX   ##0A
180 10E9 86 09                         STX   TEMP
181 10EB 20 FE 10                      JSR   SUBT
182 10EE 86 06                         STX   IN
183 10F0 06 06                         ASL   IN
184 10F2 06 06                         ASL   IN
185 10F4 06 06                         ASL   IN
186 10F6 06 06                         ASL   IN
187 10F8 18                            CLC
188 10F9 65 06                         ADC   IN
189 10FB 85 06                         STA   IN
190 10FD 60                             RTS
191                                     ;
192 10FE A2 00                         SUBT   LDX   ##00
193 1100 38                             SUB
194 1101 E5 09                         SBC   TEMP
195 1103 90 04                         BCC   SUB1
196 1105 E8                             INX
197 1106 4C 00 11                      JMP   SUB
198 1109 18                             SUB1  CLC
199 110A 65 09                         ADC   TEMP
200 110C 60                             RTS
201                                     ;
202                                     .END
0 UNDEFINED SYMBOLS **

```

### Appendix B Video Display Driver Subroutine Listings

VIDSP

KIM-1 CROSS ASSEMBLER

```

1                                     ; VIDSP
2                                     ; VIDEO DISPLAY ROUTINE FOR CARDIOTACH
3                                     ;
4                                     .LOC $1200
5                                     INIT   EQU $135E
6                                     ERASE  EQU $132F
7                                     CURHI  EQU $13FA
8                                     CURLO  EQU $13F9
9                                     PUTC   EQU $1300
10                                    SEC     EQU $0B
11                                    MIN     EQU $0C
12                                    PLSLO  EQU $0D
13                                    PLSHI  EQU $0E
14                                    ;
15 1200 A9 0E                         VIDSP  LDA   ##0E
16 1202 8D FA 13                      STA   CURHI      ; SET CURSOR TO DISPLAY AREA
17 1205 A9 00                         LDA   ##00
18 1207 8D F9 13                      STA   CURLO
19 120A A5 0C                         LDA   MIN        ; GET MINUTES VALUE
20 120C 20 31 12                      JSR   DISP2     ; DISPLAY 2 DIGITS
21 120F A9 20                         LDA   ##20      ; GET SPACE
22 1211 20 00 13                      JSR   PUTC      ; DO IT
23 1214 A5 0B                         LDA   SEC        ; GET SECONDS VALUE
24 1216 20 31 12                      JSR   DISP2
25
26                                     ;
27 1219 A9 0F                         ; DISPLAY PULSE RATE
28 121B 8D FA 13                      LDA   ##0F
29 121E A9 00                         STA   CURHI
30 1220 8D F9 13                      LDA   ##00
                                     STA   CURLO

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31
32 1223 A5 0E          ; LDA PLSHI
33 1225 20 31 12      ; JSR DISP2
34 1228 A5 0D          ; LDA PLSLO
35 122A 20 31 12      ; JSR DISP2
36 122D 20 46 12      ; JSR UBLK
37 1230 60             ; RTS
38
39                     ; DISPLAY A 2-DIGIT DECIMAL NUMBER AT CURSOR LOC
40                     ; DECIMAL VALUE IS IN ACC
41 1231 4B             DISP2 PHA
42 1232 29 F0         AND  #F0
43 1234 4A             LSR A
44 1235 4A             LSR A
45 1236 4A             LSR A
46 1237 4A             LSR A
47 1238 49 30         EOR  #30
48 123A 20 00 13      ; JSR PUTC
49 123D 6B             PLA
50 123E 29 0F         AND  #0F
51 1240 49 30         EOR  #30      ; MAKE IT AN ASCII DIGIT
52 1242 20 00 13      ; JSR PUTC
53 1245 60             ; RTS
54
55                     ; UNBLANK THE SCREEN
56 1246 A9 10         UBLK  LDA  #10
57 1248 8D FA 13      STA  CURHI
58 124B 60             ; RTS
59
60                     ; ERASE THE SCREEN UTILITY ROUTINE
61 124C 20 5E 13      ; JSR INIT
62 124F 20 2F 13      ; JSR ERASE
63 1252 00            BRK
64                     .END
0  UNDEFINED SYMBOLS **
1                     ; VIDRV
2                     ; DRIVER ROUTINE FOR MVM1024 VIDE0 DISPLAY
3
4                     ; ROUTINES ARE:
5                     ; PUTC - OUTPUT CHAR IN ACC
6                     ; ERASE - CLEAR SCREEN
7                     ; INIT - INITIALIZE VIDE0 DISPLAY
8
9                     ; DEFINE I/O PORT LOCATIONS
10
11 CURHI EQU  #13FA
12 CURLO EQU  #13F9
13 DATA EQU  #13FB
14
15                     ; .LOC #1300
16
17                     ; PUTC
18                     ; OUTPUT CHAR IN ACC
19                     ; UPDATE CURSOR LOCATION
20                     ; INTERPRET CR (#0D) TO BE NEW LINE
21 1300 C9 0D         PUTC  CMP  #0D      ; CR?
22 1302 F0 10         BEQ  CRFND    ; YES
23 1304 8D FB 13      STA  DATA    ; NO, JUST DISPLAY IT
24
25                     ;
26 1307 AD F9 13      LDA  CURLO
27 130A 29 3F         AND  #3F      ; CHECK FOR END OF LINE
28 130C C9 3F         CMP  #3F
29 130E F0 04         BEQ  CRFND    ; END OF LINE, SAME AS CR
30 1310 EE F9 13      INC  CURLO    ; NOPE, JUST INCREMENT COL
31 1313 60             RTS      ; RETURN
32
33 1314 A9 00         CRFND LDA  #00
34 1316 8D F9 13      STA  CURLO    ; NEW LINE
35 1319 AD FA 13      LDA  CURHI
36 131C 29 0F         AND  #0F
37 131E C9 0F         CMP  #0F      ; CHECK FOR END OF SCREEN
38 1320 D0 06         BNE  OK
39 1322 A9 10         LDA  #10
40 1324 8D FA 13      STA  CURHI
41 1327 60             ; RTS
42
43 1328 1B           ; OK  CLC
44 1329 69 11         ADC  #11
45 132B 8D FA 13      STA  CURHI

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45 132E 60          RTS
46
47                ; CLEAR SCREEN
48 132F A9 00      ERASE LDA #00
49 1331 8D FA 13   STA CURHI
50 1334 8D F9 13   STA CURLO
51
52 1337 A9 20      LP1   LDA ##20
53 1339 A2 40      LDX ##40
54 133B 8D FB 13   LOOP  STA DATA
55 133E EE F9 13   INC CURLO
56 1341 CA         DEX
57 1342 D0 F7      BNE LOOP
58
59 1344 A9 00      LDA ##00
60 1346 8D F9 13   STA CURLO
61 1349 EE FA 13   INC CURHI
62 134C AD FA 13   LDA CURHI
63 134F 29 0F      AND ##0F
64 1351 D0 E4      BNE LP1
65 1353 A9 10      LDA ##10
66 1355 8D FA 13   STA CURHI
67 1358 A9 00      LDA ##00
68 135A 8D F9 13   STA CURLO
69 135D 60         RTS
70
71                ; INITIALIZE
72 135E D8         INIT  CLD
73 135F A2 04      LDX ##04
74 1361 A9 00      IN1   LDA ##00
75 1363 9D FA 13   STA CURHI,X
76 1366 A9 1C      LDA ##1C
77 1368 9D FB 13   STA DATA,X
78 136B CA         DEX
79 136C CA         DEX
80 136D 10 F2      BPL IN1
81 136F 60         RTS
82
83                ; DIAGNOSTIC ROUTINE
84                ; DISPLAY ALL CHARACTERS
85 1370 20 5E 13   TEST  JSR INIT
86 1373 20 2F 13   JSR ERASE
87 1376 A9 00      LDA ##00
88 1378 85 00      STA 0
89 137A A2 FF      LDX ##FF
90 137C A5 00      TST1  LDA 0
91 137E E6 00      INC 0
92 1380 20 00 13   JSR PUTC
93 1383 CA         DEX
94 1384 D0 F6      BNE TST1
95 1386 00         BRK
96                .END
0  UNDEFINED SYMBOLS **

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; USE LOC ZERO

; RETURN TO MONITOR