Modulation of the attentional blink by on-line response selection: Evidence from speeded and unspeeded Task₁ decisions

PIERRE JOLICOEUR University of Waterloo, Waterloo, Ontario, Canada

Two critical target stimuli (T_1 and T_2) were embedded in a stream of white letters shown on a black background, using a rapid serial visual presentation paradigm (RSVP, 100 msec/item). T_1 was a red H or S; T_2 was an X or a Y. Performance in a two-alternative discrimination on T_2 was impaired when processing of T_1 was required—a result often called an attentional blink (AB). In previous work, the response in Task₁ has been an unspeeded and delayed response at the end of the trial. Three experiments compared performances in Task₂ that depended on whether Task₁ required an unspeeded delayed response or a speeded immediate response. A larger AB was found when a speeded response was required. Furthermore, in the speeded conditions, faster responses in Task₁ were associated with a smaller and shorter AB effect than were slower responses. The results show that manipulations affecting a relatively late stage of processing—response selection—affect the magnitude and duration of the AB phenomenon. A new central inhibition theory is proposed to account for these results. According to this theory, the AB is similar to the psychological refractory period effect and is caused by central postponement of short-term consolidation of T_2 .

This article focuses on the effects of requiring a speeded response to the first of two critical stimuli in the attentional blink (AB) paradigm. Using this technique, the relationship between the duration of processing in Task₁ and performance in Task₂ can be investigated in a more direct way than in previous investigations of the AB phenomenon. The next section describes one of the paradigms that has been used to study the AB phenomenon, and the following sections describe four theoretical accounts designed to explain the principal features of the phenomenon. These sections are followed by a discussion of the potential effects of requiring a speeded response in Task, in the usual paradigm used to study the AB phenomenon. Three experiments are then presented. In these experiments the effects of speeded versus delayed Task response requirements are compared. The results show that the nature of the response requirements in Task, has systematic effects on the shape of the AB function, as does the speed of the response when Task₁ requires an immediate response. The implications of the results are discussed in the General Discussion section.

The Attentional Blink Phenomenon

Several researchers have demonstrated a strikingly large and long-lasting deficit in the ability to perform a simple judgment on a second critical stimulus, T_2 , when this judgment follows another stimulus, T_1 , that also requires a simple judgment. For example, Raymond, Shapiro, and Arnell (1992, Experiment 2) presented letters, using rapid serial visual presentation (RSVP) at the same location on the screen, with 90 msec separating the onsets of consecutive letters. The letters were black, except for T_1 , which was white. There were two blocks of trials that differentiated the experimental from the control condition. In the experimental condition, there were two tasks: Task₁ and Task₂. Task₁ was to report the identity of T_1 (the white letter). Task₂ was to report whether an X had also been shown in the RSVP stream after T_1 . The responses in both tasks were made at the end of the trial, without speed pressure, after the termination of the RSVP stream. T₁ was presented in every trial, whereas T₂ (black X) was presented in half of the trials. In the control condition, only Task, was performed, and subjects were asked to ignore T_1 .

The proportion of hits in Task₂ (subject reported seeing an X when one was shown) for each position of T_2 in the RSVP stream relative to the position of the white letter is plotted in Figure 1. In the control condition, performance was uniformly high across the positions in the RSVP stream in which T_2 could occur, with the highest performance being when T_2 itself was white (position 0) or when it was the last letter in the stream (position +8). Nothing followed the last position in the RSVP stream, so this item was not subject to backward masking, which accounts for the upswing in performance relative to position +7 in both the control and experimental conditions. In contrast, accuracy (the proportion of hits) in the experimental condition was much lower for positions +2 to +6, although remaining roughly equivalent to that in the control con-

This work was supported by a Research Grant from the Natural Sciences and Engineering Research Council of Canada. I thank Margaret Ingleton for technical assistance and Jim Johnston, Rob McCann, Ritske De Jong, Kim Shapiro, Molly Potter, Gordon Logan, and David Irwin for helpful comments and criticisms of this work. Correspondence concerning this article should be sent to P. Jolicoeur, Department of Psychology, University of Waterloo, Waterloo, ON N2L 3G1, Canada (e-mail: pjolicoe@cgl.uwaterloo.ca).

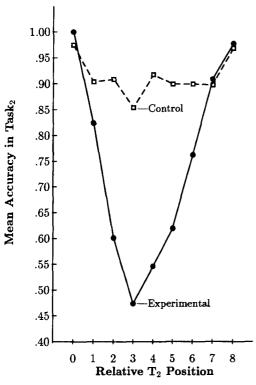


Figure 1. Results from Raymond, Shapiro, and Arnell (1992), Experiment 2. Mean proportion correct report of T_2 on T_2 -present (X-present) trials. (Estimated from their figure.)

dition for relative stream positions 0, +1, +7, and +8. The performance deficit in Task₂ in the experimental condition relative to the control condition at the intermediate stream positions following T₁ was called an *attentional blink* (AB) by Raymond et al. (1992). Several other researchers have reported similar findings in paradigms that were significantly different (see, e.g., D. E. Broadbent & M. H. P. Broadbent, 1987; Chun & Potter, 1995; Weichselgartner & Sperling, 1987), attesting to the robustness of the effect.

Models of the Attentional Blink Phenomenon

The sections below contain a brief review of four models that have been proposed to account for the results of the AB phenomenon as found in the type of paradigm described in the previous section.

Attentional gate model. Raymond et al. (1992) proposed that the processing of T_1 in the experimental condition of the experiment described in the previous section begins with a preattentive detection of the white letter. This preattentive detection was postulated to initiate an attentional response, leading to the identification of T_1 . The identification of T_1 involves the opening and closing of an attentional gate whose purpose is to regulate the flow of visual information to pattern-recognition centers of the brain (see Weichselgartner & Sperling, 1987). Raymond et al. (1992) hypothesized that the at-

tentional gate would close for a longer time when information following T_1 could be potentially confused with T_1 . The perception of T_2 suffers if it is presented while the attentional gate is closed. "In the blink analogy, the locking of the gate is like the closing of an eyelid" (Raymond et al., 1992, p. 859).

Similarity theory. Shapiro, Raymond, and Arnell (1994) proposed an account of the AB phenomenon that is different from the attentional gate model account of 1992 (see also Raymond, Shapiro, & Arnell, 1995). They revised their position on the basis of results from experiments in which T_1 was a period of time during the RSVP stream in which there was no patterned stimulus (achieved by replacing a letter in the stream by a blank field). They found a very much reduced AB effect, despite the fact that Task₁ was quite difficult to perform (as indexed by error rates in Task₁) relative to other experiments producing a substantial AB effect.

Shapiro et al. (1994) and Shapiro and Raymond (1994) interpreted the small AB effect in the temporal gap experiments as an indication that visual patterned stimulation in the T_1 stimulus is a necessary condition for the manifestation of an AB. This led them to propose an alternative theory-similarity theory-that has three components. First, there is an early and parallel stage of visual information processing that produces representations of items in the visual field. Second, a selection template for T_1 (and T_2) is matched against the representations produced by the first stage. Third, items that match the template for T_1 and T_2 are selected for entry into visual short-term memory (VSTM), which has limited capacity. Items that gain entry into VSTM are assigned weights that determine the probability of report from VSTM. The similarity between distractor items (most importantly the item following T_1 and the selection template for T_1 (and between the item following T_2 and the template for T_2) is an important determinant of entry into VSTM. When similarity is low, distractors are less likely to match the selection template and thus less likely to gain access to VSTM. Shapiro et al. argued that, as a result of temporal limitations in the speed of selection, the item immediately following T_1 and the item immediately following T_2 both have a high likelihood of gaining entry into VSTM. The weights assigned to items in VSTM also depend on a pool of limited resources. Items that enter VSTM earlier are assigned larger weights, all else being equal, because there are more available resources. Later items receive smaller weights, because resources have been depleted by the entry of earlier items in VSTM.

The probability of report from VSTM at the end of a trial is determined by weights that are assigned to each item in VSTM. A higher weight results in a higher probability of output from VSTM. The weights are a function of the goodness of match to the selection templates. Although distractors, in general, will have lower weights than T_1 and T_2 , distractors that match the selection templates partially may nonetheless have a weight that is sufficiently high to result in performance decrements when items are selected for report from VSTM. Both the number of items in VSTM and their weights are postulated to influence performance. The AB effect, in this theory, occurs at the time of output from VSTM, as a function of the weights associated with the items in VSTM. In order to account for the recovery of performance in Task₂ (the task associated with T_2) as the delay between T_1 and T_2 is increased, Shapiro and Raymond (1994) propose that T_1 either decays or is *flushed* from VSTM in the 450 msec following its presentation, so that T_1 no longer interferes with T_2 . Presumably, T_1 has had time to be transferred from VSTM to another system (short-term memory [STM]?), but this is not made clear by Shapiro and Raymond.

Attentional dwell model. Duncan, Ward, and Shapiro (1994) and Ward, Duncan, and Shapiro (1996) proposed that attention should be thought of as a sustained state that is necessary in order to make representations of relevant objects available for guiding behavior. They contrast their theoretical position with the view that attention can proceed in a high-speed serial fashion, moving from item to item very quickly (say, 30 msec per item, as might be suggested by visual search studies; see, e.g., Wolfe, 1994).

Ward et al. (1996) are admirably clear about what they believe should not cause an AB effect. They claim that the AB effect is not due to perceptual masking, the number of object attributes identified, the number of responses made, limits in the number of locations that must be attended, or the particular details of their presentation methods. In their experiments, T_1 was a simple pattern (say, a digit) presented at one of two possible locations and followed by a pattern mask. T_2 was another simple pattern (say, a letter) presented at one of two different locations and also followed by a mask. The stimulus onset asynchrony (SOA) between T_1 and T_2 was varied. Report of the identity of T_2 showed a pattern like the one displayed in Figure 1, whereas report of T_1 was generally good, regardless of SOA.

They proposed that the AB phenomenon is caused by a limited visual-processing capacity for encoding objects into a form that can make contact with other cognitive mechanisms. A greater demand on capacity is made when a larger number of objects is attended. One of their experiments provided good support for this last claim. Either one (T_1) or two $(T_1 \text{ and } T_1')$ stimuli had to be encoded in a first observation interval, and, at a variable SOA from this event, a second observation interval presented another pattern (T_2) . Report of T_2 showed a larger AB effect when two patterns had to be reported from the first event than when only one had to be reported.

In this model, objects compete for a share of limited capacity visual-processing resources, according to their match to a target template. The competition for limited resources resolves gradually over several hundred milliseconds, and the winners engage visual-processing mechanisms at the expense of the losers. This theory makes the clear prediction that the response selection (RS) requirements of Task₁ should not modulate the magnitude of the AB effect.

Two-stage model. Chun and Potter (1995) proposed a two-stage model for the AB phenomenon. In the first stage, called *rapid detection*, almost every item presented in RSVP streams at a rate of about 10 items/sec is identified and can be selected for access to processing in subsequent stages of processing. Stage 1 representations are subject to rapid forgetting when there is interference from subsequent items in the RSVP stream, unless they are selected for further processing.

In the second stage, called *capacity-limited processing*, items selected for further processing are transferred into a more durable representation (such as verbal STM). Stage 1 representations cannot serve as the basis for a later verbal report or for a manual response. The information must first be transferred to STM, which results in full identification and consolidation for subsequent report. Stage 2 processing is capacity limited and is initiated by a transient attentional response that occurs on Stage 1 detection of a probable target. The AB phenomenon is caused by the capacity limit in Stage 2 processing. If T_2 is presented while T_1 is processed in Stage 2, Stage 2 processing of T_2 must wait, and T_2 may be forgotten.

The central interference theory. Another account of the AB phenomenon, called the central interference theory, is described in the General Discussion section. Although this account was developed independently from the two-stage model, and from the perspective of postponement models of psychological refractory period (PRP) interference, it is similar to the model proposed by Chun and Potter (1995). Such convergence of views arrived at from different perspectives is encouraging. The main difference between the two-stage model and the central interference theory is that the latter makes an explicit identification between the dual-task interference observed in the PRP paradigm and that observed in the AB paradigm. (The theory is presented in more detail in subsequent sections of the article.) The explicit identification of AB interference with the type of interference believed to be the cause of the PRP phenomenon suggests that some (or all) of the AB effect should be caused by a relatively late, postperceptual, locus of dual-task interference, such as response selection (McCann & Johnston, 1992; Pashler, 1994). The experiments in this article provide an initial investigation of this possibility.

The Present Experiments

The experiments presented below introduced a simple modification to the paradigms used to study the AB phenomenon to date. In some cases, Task₁ required an immediate and speeded response to T_1 rather than a delayed response at the end of the trial. The purpose of the empirical work was twofold. One was to discover whether requiring an immediate response to T_1 would have any impact on the magnitude and shape of the AB effect. The second was to discover whether there would be a relationship between response times (RTs) in Task₁ and the magnitude of the AB effect.

If the AB and PRP phenomena are produced by fundamentally different causes—with AB reflecting an earlier stage of processing, such as a late stage of stimulus encoding, and PRP reflecting a later stage of processing, such as response selection—one might expect that the response requirements of Task₁ would have little impact on the results in the AB paradigm. In this view, changing the response requirements of Task₁ would affect stages of processing taking place after the processes involved in the AB effect have already run to completion.

On-line versus off-line processing of T_1. The most obvious consequence of requiring a speeded response in Task, is to force a temporal overlap between operations associated with response-related stages of processing required to perform Task₁, such as response selection, and the operations required to perform Task₂. That is, response selection must be made on line in this case. When the response to T_1 is delayed, operations like selecting a response can take place off line, long after the time-critical processing for Task₂ has already taken place. The AB effect is a processing deficit observed in Task₂ performance. In order to investigate whether a relatively late process, such as response selection, has any potential involvement in the AB effect, one must create a situation in which there is at least a reasonable possibility of some temporal overlap between the operations required to perform Task₂ and these later stages of processing for Task₁. If an immediate response must be made to T_1 , operations like response selection cannot be deferred to a later time (such as the end of the trial). These operations must be performed soon after the presentation of T_1 , while the processing of T_2 may be proceeding concurrently. Thus, the delayed-response paradigm may be inherently ill suited to investigate the question of whether response selection can influence the critical process (or processes) producing the AB phenomenon. This could explain why some previous work has failed to observe interactions between response-level manipulations and the AB phenomenon (see, e.g., Ward et al., 1996).

The foregoing arguments suggest that one effect (perhaps the principal effect) of requiring an immediate and speeded response in Task₁ is to increase the likelihood of a temporal overlap between postperceptual processing, such as response selection, and the processes required to perform Task₂. This is why the manipulation of the nature of the response in Task₁—delayed versus speeded is important. If this manipulation has an obvious effect on the magnitude of the AB effect, it will be difficult to escape the conclusion that the causal mechanism(s) mediating the AB phenomenon cannot be uniquely associated with relatively early perceptual capacity limitations.

The foregoing sections described four models (other than the central interference theory) designed to account for the AB phenomenon. None of these models predicts that requiring an immediate response in Task₁ should have an effect on the magnitude, duration, or shape of the AB function. Ward et al. (1996) were the clearest on this point in that their attentional dwell model explicitly excludes late processes, such as those associated with response selection, as being causally involved in the AB phenomenon. Furthermore, none of the other three models-the attentional gate model (Raymond et al., 1992), the similarity theory (Shapiro et al., 1994), or the two-stage model (Chun & Potter, 1995)—has an obvious way to relate the AB phenomenon to mechanisms, such as response selection, that might come into play when a speeded response is required. All of these models assume that the locus of the AB effect takes place in stages of processing that occur before response selection. Showing that a manipulation of the response requirements in Task, (immediate vs. delayed) modulates the magnitude of the AB phenomenon would suggest either that the locus of the AB effect is later in processing than has been supposed so far or that there are multiple loci (e.g., one early and one late).

In this article, the theoretical issue of the relationship between the AB phenomenon and response selection is operationalized in terms of two empirical issues. The first is the manipulation of the response requirements associated with Task₁—namely, whether the response in Task₁ (R_1) is immediate or delayed. As the experiments will show, the magnitude of the AB effect is larger when R_1 is performed on-line than when R_1 is performed off line. The introduction of speeded Task, responses also introduces new possibilities for data analysis. In particular, it allows us to measure on-line processing time across various manipulations in Task1 and trial-to-trial variation in processing time within a particular $Task_1$. The second empirical issue is related to these trial-to-trial variations in processing time in Task₁. The main finding here is that the magnitude of the AB effect increases as RT₁ becomes longer. The implications of these findings is considered in the General Discussion section.

GENERAL METHOD

This section contains an outline of the methods that were common across the experiments. The reader can assume that the method was as specified here unless a specific mention of a difference is noted in the section describing a particular experiment.

General Stimuli

The stimuli were uppercase letters, presented in white on a black background, on an SVGA color computer screen controlled by a 386, 486, or 586 CPU. The letters were presented in RSVP, at the same location at the center of the screen, at a rate of 10 letters/sec. Each letter was exposed for 100 msec with no blank interstimulus interval. These parameters are identical to those used by Chun and Potter (1995) and thus are known to create conditions under which an AB can be observed.

There were 6–9 letters (this number selected randomly at run time) presented prior to T_1 and 9–12 (also randomized at run time) following T_1 . T_2 could occur in any of the eight positions following T_1 with equal probability. Thus, even in the last position for T_2 , there were between 1 and 4 letters following T_2 , which means that the effective masking conditions required to observe an AB in Task₂ were always in effect (Giesbrecht & Di Lollo, in press).

On every trial, the background stream items were selected at random, without replacement, from the letters of the alphabet, excluding H, S, X, and Y.

The letters subtended about 1° of visual angle. White letters had an approximate luminance of 25 cd/m² and CIE(x, y) coordinates of (.278, .306), as measured by a CS-100 Minolta meter. Red letters had an approximate luminance of 26 cd/m² and CIE(x, y) coordinates of (.355, .286). The background was black with a luminance of less than 1 cd/m². These values are approximate, because the experiments were conducted on several computer systems; average values are reported above. Small variations in these parameters are not likely to be important. Note that the luminances of white and red letters were very similar, effectively ruling out the possibility that T_1 would mask T_2 more than would distractor stimuli.

General Procedure

A pair of symbols (e.g., ++) was presented at the center of the screen, in green, at the beginning of each trial. The symbols provided feedback on performance in the previous trial and acted as a fixation point in the current trial. The left member of the pair indicated performance in Task₁, the right member in Task₂. A + sign indicated a correct response and a - sign indicated an error. The fixation symbols for the first trial in a block were always pluses, so there was no feedback for the last trial in a block of trials.

Each trial was initiated by pressing the space bar on the computer keyboard, which caused the fixation/feedback symbols to disappear and the onset of the RSVP stream.

The critical stimulus for Task₁, T₁, was a red letter that could be either an H or an S. T₁ was presented on half of the trials and not presented on the other half, with these two types of trials occurring equally often but intermixed at random within each block of trials. T₁-present trials were thus the experimental trials. T₁-absent trials were used as within-session within-subjects control trials in which no AB should occur because there was no stimulus to trigger Task₁. These trials provided a good control for dual-task costs of maintaining the processes required to perform Task₁ in a prepared state (De Jong & Sweet, 1994; Pashler, 1994). This type of control trial does not control for potential sensory masking effects of T₁ on T₂. However, considerable prior work shows that such masking does not occur, even when T₁ is considerably more luminous than T₂ (see, e.g., Raymond et al., 1992).

Task₁ was to discriminate between H and S when a red letter was shown. If no red letter was shown, the space bar was to be pressed at the end of the RSVP sequence, without speed pressure. When a red letter was shown, the response in Task₁ was either speeded or delayed. When delayed, the program requested a response for Task₁ at the end of the trial. When speeded, a response was expected as quickly as possible, while the remainder of the RSVP stream was displayed. The .> key was to be pressed for H or the /? key for S. Both of these response keys were at the lower right of the keyboard, and the index and middle fingers of the right hand could rest comfortably on them during a block of trials. The same response keys were used in every experiment.

In every experiment, one of the eight positions following T_1 in the RSVP sequence contained T_2 , which was always either an X or a Y. The streams for T_1 -absent trials were created in the same way as in T_1 -present trials, except that T_1 was replaced by a randomly selected distractor letter. This procedure allowed the stream positions in which T_2 was shown to be labeled in the same way across T_1 -present and T_1 -absent trials.

Task₂ was to decide whether T_2 was an X or a Y, and subjects knew that one or the other was always shown. Task₂ was unspeeded in all cases. The response for Task₂ was always performed after the response for Task₁. The X key on the keyboard was used to indicate the presence of an X; the C key was used to indicate the presence of a Y. The SOA between T_1 (or the position T_1 would have occupied when T_1 was not shown) and T_2 was 100, 200, ..., 700, or 800 msec. Each subject performed 640 experimental trials (10 blocks of 64) following 64 practice trials (2 blocks of 32). Each block of experimental trials had an equal number of trials for each combination of T_1 -present/absent, H versus S, X versus Y, and SOA.

General Method of Analysis

Because of the rapid presentation rate of the stimuli in the RSVP streams, some subjects found it difficult to perform $Task_2$, even when T_1 was not presented, resulting in performance constrained by a floor effect. The following procedure was adopted to deal with this problem. First, the mean performance in $Task_2$ in the T_1 -absent condition was computed for each subject, pooling trials from all SOAs. Any subject whose performance fell below 69% correct was excluded from further analyses. In analyses of $Task_2$ performance (including the screening procedure described above), only trials with correct responses in $Task_1$ were included. Given that $Task_1$ performance was very good, this conditional analysis excluded few trials. Analyses that included the rejected subjects, error trials in $Task_1$, or both produced patterns of results that were very similar to the ones that are reported below, so these procedures did not distort the empirical picture.

The results for Task₂ were based on the proportion of correct trials. These proportions were usually submitted to analyses of variance (ANOVAs) in which SOA (8) and the presence/absence of T_1 were within-subjects factors. These ANOVAs were used to estimate 95% within-subjects confidence intervals (Loftus & Masson, 1994), which are given in the graphs displaying the results of each separate experiment, as opposed to graphs produced to compare results across experiments. In these latter graphs, the error bars are 95% confidence intervals computed from separate ANOVAs performed on the results from each SOA (for T_1 -present trials). Departures from these conventions are indicated where appropriate.

In the present experiments, the AB effect manifested itself as a deficit in performance in Task₂ in the T₁-present condition, relative to the T₁-absent condition, usually over the first 400 msec following T₁. For SOAs ranging between 500 and 800 msec, performance across the T_1 -present and T_1 -absent conditions was more similar, suggesting that the blink was essentially over across these SOAs (for most trials for most subjects). These observations were used to create a method of analysis designed to estimate the magnitude of the AB effect that could also be used to compare the magnitude of the AB effect across conditions. The method consisted of taking the mean difference between the experimental condition $(T_1$ -present) and the control condition (T1-absent) across the first four SOAs (100-400 msec), and again across the last four SOAs (500-800 msec). Because performance in the control condition (T1-absent trials) was essentially unaffected by SOA (e.g., see Figures 2-3), the overall mean performance level, \overline{C} , for the control condition was computed by averaging the mean performance for each SOA for the T1-absent condition:

$$\overline{C} = \frac{\sum_{i=1}^{8} C_i}{\frac{8}{8}}$$

where C_i is the mean for the *i*th SOA. In a typical analysis, each subject's data were first reduced to 16 means, 8 in the T₁-present condition (1 for each SOA) and 8 in the T₁-absent condition (again, 1 for each SOA). This procedure described above reduced these 16 means to just 2: the mean difference between the T₁-present condition and the T₁-absent condition across the shorter SOAs,

$$AB_{1,4} = \frac{\sum_{i=1}^{4} (\overline{C} - E_i)}{4}$$

and the mean difference between the T_1 -present condition and the T_1 -absent condition across the longer SOAs,

$$AB_{5,8} = \frac{\sum_{i=5}^{8} (\overline{C} - E_i)}{4}$$

where E_i is the mean for the experimental condition (T₁-present) in the *i*th SOA condition. A significantly larger number for the shorter SOAs than for the longer SOAs was expected when a condition produced an AB effect. For example, for the results shown in Figure 2, the mean $AB_{1,4}$ score was $.167 \pm .026$, and the mean $AB_{5,8}$ score was $.055 \pm .026$, as would be expected if there was a large deficit in Task₂ performance immediately following T₁ and if this effect was attenuated at longer SOAs. The error estimates following the means, here and elsewhere in the article, are 95% confidence intervals for either within-subjects or between-subjects comparisons, as appropriate for the particular means and intended comparison (Loftus & Masson, 1994).

Differences in AB magnitudes across conditions are revealed by interactions between the difference of the estimates of control minus experimental performance for shorter versus longer SOAs, with the variable defining the conditions under study.

Accuracy in Task₂ is plotted as a function of the SOA between T_1 and T_2 , expressed in units of deciseconds (1 dsec = 100 msec), or equivalently as a function of the position of T_2 in the RSVP stream, relative to the position of T_1 (relative T_2 position).

General Subjects

Most of the subjects were undergraduate students at the University of Waterloo who volunteered to participate for pay or for course credit. A few were graduate students or staff. All had normal or corrected-to-normal visual acuity, and all reported having normal color vision. Table 1 gives some statistics for each experiment.

EXPERIMENT 1 Task₁ Unspeeded, Task₂ = X/Y 2AD

The purpose of Experiment 1 was to establish the appropriateness of the general experimental methods described above, to replicate the AB phenomenon, and to provide a comparison group for Experiment 2. T_1 was a red H or a red S, and Task₁ required an unspeeded twoalternative discrimination (2AD) between H and S. T_2 was an X or a Y in the same color as other distractor RSVP stream items. Task₂ was an unspeeded 2AD between X or Y. Both responses were made after the end of the RSVP stream.

 Table 1

 Subject Information for Each Experiment

| Exp | N | Males | Females | N _{rejt} | N _{rej 2} | Age |
|-----|----|-------|---------|-------------------|--------------------|------|
| 1 | 19 | 7 | 12 | 4 | 0 | 20.1 |
| 2 | 19 | 10 | 9 | 4 | 0 | 20.0 |
| 3 | 22 | 7 | 15 | 6 | 1 | 20.6 |

Note—Exp, experiment number; N, number of subjects in final sample, after rejection criteria; Males, males in final sample; Females, females in final sample; N_{rej_1} , rejected because Task₂ accuracy was below .69 in control trials; N_{rej_2} , rejected for responding after the end of the trial rather than on line; Age, mean age.

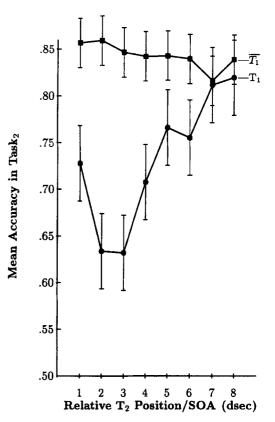


Figure 2. Results from Experiment 1. Mean proportion correct discrimination of T_2 (X vs. Y) in T_1 -absent trials (control trials, labeled $\overline{T_1}$) versus T_1 -present trials (experimental trials, labeled T_1). 1 decisecond (dsec) = 100 msec. The error bars are 95% within-subjects confidence intervals appropriate for comparisons of means across SOAs within each function (T_1 or $\overline{T_1}$).

Results and Discussion

The mean proportion of correct responses in Task₂ is shown in Figure 2 for each SOA between T₁ and T₂ and for trials in which there was a red letter (T₁-present) and trials in which there was no red letter (T₁-absent). On average, performance was 84% in the T₁-absent condition and did not differ appreciably across SOAs (F < 1, in a separate ANOVA). In contrast, accuracy in the targetpresent condition displayed the classic U-shaped AB function, with a pronounced deficit at SOAs of 200–300 msec and a sharp recovery as SOA was increased.

The mean $AB_{1,4}$ score was $.167 \pm .026$, whereas the mean $AB_{5,8}$ score was $.055 \pm .026$ [F(1,18) = 40.40, $MS_e = 0.002975$, p < .0001], confirming the clear-cut and substantial AB effect evident in the figure.

Performance in Task₁, for the T₁-present trials, was good, with a mean of 91.1% correct. Accuracy in Task₁ did not depend on the SOA at which T₂ was presented (F < 1).

These results demonstrated a large AB effect when $Task_2$ required a 2AD between an X and a Y. The large and clear AB effect found with this task validated the methodology used in Experiment 1 and provided a comparison group for the subjects tested in Experiment 2.

EXPERIMENT 2 Task₁ Speeded, Task₂ = X/Y 2AD

Experiment 2 was like Experiment 1, except that $Task_1$ required a speeded on-line response. The purpose of the experiment was to compare the effects of requiring a speeded response in $Task_1$ with performance measured in Experiment 1, in which $Task_1$ involved a delayed response.

Results and Discussion

The mean proportion correct in Task₂ is shown in Figure 3 for each SOA between T_1 and T_2 and for trials in which there was a red letter (T_1 -present) and trials in which there was no red letter (T_1 -absent). On average, performance was 82% in the T_1 -absent condition and did not differ appreciably across SOAs (F < 1). In contrast, accuracy in the target-present condition displayed the classic U-shaped AB function, with a pronounced deficit at SOAs of 200–300 msec and a sharp recovery as SOA was increased.

As expected from Figure 3, there was a large statistical difference between the $AB_{1,4}$ score (.226 ± .035) and the

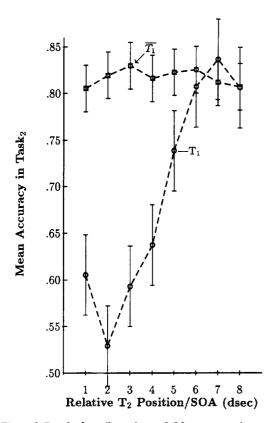


Figure 3. Results from Experiment 2. Mean proportion correct discrimination of T_2 (X vs. Y) in T_1 -absent trials (control trials, labeled $\overline{T_1}$) versus T_1 -present trials (experimental trials, labeled T_1). 1 decisecond (dsec) = 100 msec. The error bars are 95% within-subjects confidence intervals appropriate for comparisons of means across SOAs within each function (T_1 or $\overline{T_1}$).

 $AB_{5,8}$ score [.020 ± .035; F(1,18) = 76.23, $MS_e = 0.005273$, p < .0001].

Performance in Task₁, for the T₁-present trials, was very good, with a mean of 93.7% correct. Accuracy in Task₁ did not depend on the SOA at which the X or Y was presented [F(7,126) = 1.06, $MS_e = 0.0016$, p > .39].

The mean RT in Task₁ was 530 ± 8 msec and did not differ appreciably across SOA [F(7,126) = 1.47, $MS_e = 310.2$, p > .18]. These results suggest that the occurrence of T₂ did not significantly influence the processing of T₁.

As in Experiment 1, a large AB was obtained with a 2AD between X and Y in Task₂.

COMBINED ANALYSIS OF EXPERIMENTS 1 AND 2

The means for Experiments 1 and 2 are shown in Figure 4. The error bars are 95% confidence intervals computed from separate ANOVAs, one for each SOA, in which the speeded versus unspeeded factor was a between-subjects variable. The interaction between $AB_{1,4}$ versus $AB_{5,8}$ scores with experiments $[F(1,36) = 10.01, MS_e = 0.004124, p < .0035]$ confirms what is evident in Figure 4: There was a larger AB effect in the speeded condition than in the unspeeded condition. This interpretation was corroborated further by a direct comparison of the $AB_{1,4}$ scores across the unspeeded (.167 ± .026) versus the speeded (.226 ± .035) condition $[F(1,36) = 7.95 MS_e = 0.004110, p < .008]$.

EXPERIMENT 3 Task₁ Unspeeded/Speeded, Task₂ = X/Y 2AD

The results of Experiments 1-2 produced interesting evidence concerning the effects of requiring a speeded response in Task₁. This experiment provided additional evidence, using a within-subjects design. A within-subjects manipulation of the Task₁ requirements (speeded vs. delayed response) provided a replication of the effects found in the previous experiments and showed that these effects can be made to come and go, from block to block, depending on the instructions (and presumably on how the subjects scheduled the operations required to perform Task₁).

This experiment was like Experiments 1 and 2, except that each subject performed both unspeeded and speeded versions of Task₁, in different blocks of trials. Each subject performed 640 trials, 320 with an unspeeded Task₁ and 320 with a speeded Task₁. These trials were performed in blocks of 64, with the speeded/unspeeded variable alternating from block to block. Half of the subjects started with Task₁ unspeeded; the other half started with Task₁ speeded. The experiment began with 2 practice blocks of 32 trials, one speeded and one unspeeded.

Results and Discussion

Task₂ performance is graphed in Figure 5. The error bars for T_1 -present trials (except at 400-msec SOA; see

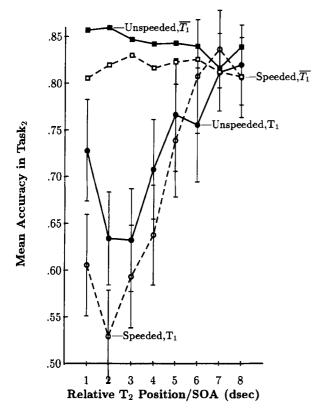


Figure 4. Results from Experiments 1 and 2. Mean proportion correct discrimination of T_2 (X vs. Y) in T_1 -absent trials (control trials, labeled $\overline{T_1}$) versus T_1 -present trials (experimental trials, labeled T_1). Circles are for T_1 -present trials; squares are for T_1 absent ($\overline{T_1}$) trials. Solid lines and filled symbols are for unspeeded Task₁ conditions (Experiment 1); dashed lines and unfilled symbols are for speeded Task₁ conditions (Experiment 2). 1 decisecond (dsec) = 100 msec. The error bars are 95% between-subjects confidence intervals appropriate for comparing the means in T_1 present trials at a given SOA.

below) show 95% within-subjects confidence intervals estimated from separate ANOVAs at each SOA in which only the results from T_1 -present trials were considered. Clearly, the means for T_1 -present trials at 400-msec SOA did not differ. The error bars for this SOA are the 95% within-subjects confidence interval appropriate for estimating the effects of SOA for T_1 -present trials (estimated from a separate ANOVA in which results across speeded and unspeeded trials were pooled). As in Experiments 1–2, there was a robust AB effect in Task₂, which required a 2AD between X and Y. The error bars shown at the 200-msec SOA for the T_1 -absent condition show the within-subjects 95% confidence interval appropriate for comparisons among the means for T_1 -absent trials.

The mean $AB_{1,4}$ score was $.144 \pm .023$ in the unspeeded condition and $.187 \pm .023$ in the speeded condition, whereas the $AB_{5,8}$ score was $.055 \pm .023$ in the unspeeded condition and $.006 \pm .023$ in the speeded condition, resulting in a significant interaction indicating a larger AB effect in the speeded condition than in the unspeeded con-

dition $[F(1,21) = 16.93, MS_e = 0.002725, p < .0005]$. A separate ANOVA comparing just the $AB_{1,4}$ scores confirmed that the deficit in Task₂ performance was greater for the speeded condition than for the unspeeded condition $[F(1,21) = 5.56, MS_e = 0.003675, p < .03]$.

The RTs for Task₁ speeded trials had a mean of 530 ± 13 msec that did not vary significantly across SOA (F < 1), suggesting that the time at which T₂ was presented did not strongly affect the processing of T₁. The proportion of correct responses in Task₁ was .975 for the unspeeded condition and .950 for the speeded condition [F(1,21) = 16.45, $MS_e = 0.003267$, p < .0006]. Accuracy did not vary significantly with SOA [F(7,147) = 1.75, $MS_e = 0.001993$, p > .10], and the interaction between SOA and Task₁ condition was also not significant [F(7,147) = 1.10, $MS_e = 0.001440$, p > .36].

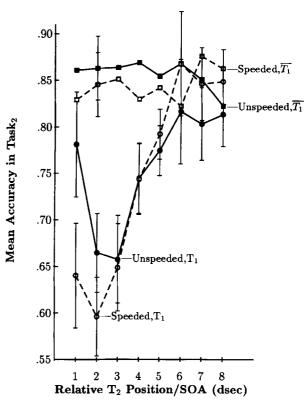


Figure 5. Results from Experiment 3. Mean proportion correct discrimination of T_2 (X vs. Y) in T_1 -absent (control) versus T_1 -present (experimental) trials for unspeeded versus speeded Task₁ conditions. $\overline{T_1}$ designates T_1 -absent trials. T_1 designates T_1 -present trials. Circles are for T_1 -present trials; squares are for T_1 -absent ($\overline{T_1}$) trials. Solid lines and filled symbols are for unspeeded Task₁ conditions; dashed lines and unfilled symbols are for speeded Task₁ conditions. 1 decisecond (dsec) = 100 msec. The error bars are 95% within-subjects confidence intervals appropriate for comparing the means in T_1 -present trials at a given SOA. The error bars for T_1 -present trials at the 4-dsec SOA are appropriate for comparisons across SOAs of the mean of speeded and unspeeded trials in T_1 -present. The error bars at the 2-dsec SOA for T_1 -absent trials are appropriate for comparisons across SOAs of solve trials at the 2-dsec SOA for T_1 -absent trials are appropriate for comparisons across SOAs of the mean of speeded and unspeeded trials in T_1 -present. The error bars at the 2-dsec SOA for T_1 -absent trials are appropriate for comparisons across SOAs of the mean of speeded and unspeeded trials in T_1 -present. The error bars at the 2-dsec SOA for T_1 -basent trials are appropriate for comparisons across SOAs of the mean of speeded and unspeeded trials in T_1 -present. The error bars at the 2-dsec SOA for T_1 -basent trials are appropriate for comparisons across SOAs within T_1 -basent conditions.

COMBINED ANALYSES OF EXPERIMENTS 1–3

In order to maximize the precision of the estimates of condition means and thus maximize statistical power to corroborate the effects that appeared in the pattern of means when comparing performance across unspeeded versus speeded versions of Task₁, all of the available results from Experiments 1–3 were combined into a single analysis. The results from Experiments 1 and 2 were shown in Figure 4, and those for Experiment 3 in Figure 5. In order to facilitate the analysis, the results from Experiment 3 in the combined ANOVA were treated as an independent group design. (Although this method of analysis reduced power to detect effects for those subjects, it made it easier to combine the results with those from the first two experiments.) The resulting analysis treated speeded versus unspeeded Task₁ requirements as a between-subjects factor and T₁-absent/present and SOA as within-subjects factors. The means are shown in Fig-

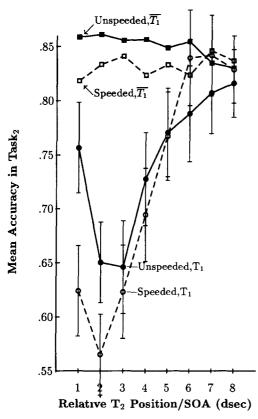


Figure 6. Results from Experiments 1–3 combined. Mean proportion correct performance in Task₂ in T₁-absent (control) versus T₁-present (experimental) trials for unspeeded versus speeded Task₁ conditions. $\overline{T_1}$ designates T₁-absent trials. T₁ designates T₁-present trials. Circles are for T₁-present trials; squares are for T₁-absent ($\overline{T_1}$) trials. Solid lines and filled symbols are for unspeeded Task₁ conditions; dashed lines and unfilled symbols are for speeded Task₁ conditions. 1 decisecond (dsec) = 100 msec. The error bars are 95% within-subjects confidence intervals appropriate for comparing the means in T₁-present trials at a given SOA.

ure 6. The error bars are 95% between-subjects confidence intervals estimated for T_1 -present trials in a separate ANOVA for each SOA.

For unspeeded Task₁ trials, the $AB_{1,4}$ score was .155 ± .023 and the $AB_{5,8}$ score was .055 ± .023; for speeded Task₁ trials, the $AB_{1,4}$ score was .205 ± .023 and the $AB_{5,8}$ score was .013 ± .023. This pattern of means produced a significant two-way interaction between the unspeeded versus speeded factor and the AB scores factor [short vs. long SOAs; F(1,80) = 16.55, $MS_e = 0.005282$, p < .0001]. As can be inferred from the confidence intervals, the $AB_{1,4}$ scores differed across the speeded versus unspeeded groups—confirmed in a separate ANOVA in which just these scores were analyzed in a between-subjects analysis [F(1,80) = 8.21, $MS_e = 0.006319$, p < .006].

As can be seen in Figure 6, the results for T_1 -present trials in the speeded condition converged with those of T_1 -absent trials at the longer SOAs. In contrast, those for the unspeeded condition appeared to approach an asymptote that was below the control level for T_1 -absent unspeeded trials. These impressions were corroborated by the following analyses. First, there was a significant difference between the mean $AB_{5,8}$ scores for the unspeeded versus the speeded condition $[F(1,80) = 7.06, MS_e = 0.005131, p < .01]$; second, the mean $AB_{5,8}$ score for the unspeeded condition was significantly different from zero $[F(1,40) = 25.55, MS_e = 0.0048, p < .0001]$; whereas third, the mean $AB_{5,8}$ score for the speeded condition was not significantly different from zero $[F(1,40) = 1.19, MS_e = 0.0055, p > .28]$.

These results are discussed further in later discussion sections. For the moment, it is sufficient to note that requiring a speeded response appears to cause differences in the results in $Task_2$, both at shorter SOAs and at longer SOAs, relative to the results obtained in the delayed-response paradigm.

DISCUSSION OF THE EFFECTS OF TASK₁ RESPONSE REQUIREMENTS

The new empirical discoveries described in Experiments 1–3 have been made possible by comparing the results from a delayed-response Task₁ paradigm with those from an otherwise identical paradigm, except that a speeded response was required in Task₁. There were two principal findings. First, the AB effect was larger at short SOAs when Task₁ involved a speeded on-line response than when Task₁ involved a delayed response. Second, the results from T₁-present trials produced a crossover interaction, with better performance in the speeded condition than in the unspeeded condition at longer SOAs. Each of these results is discussed below.

For T_1 -absent trials, the effects of requiring a speeded response to T_1 (when it occurred) were minor. The means suggest that there might be a small additional cost in the speeded condition relative to the unspeeded condition, but, in separate statistical analyses of the combined results, the difference was not significant. The possibility of a small cost is mentioned here only because a difference was found (although not significant) in the comparison of Experiments 1 and 2 and within Experiment 3. The main conclusion that can be drawn from these results is that, although there may have been some differential task preparation across the speeded versus unspeeded conditions, these differences were small and had only modest effects on the results. Thus, it seems reasonably safe to focus on the pattern of results obtained from trials in which T_1 was presented.

The results from T_1 -present trials show that the AB effect was larger when the response in Task, must be performed immediately, or on line. A smaller AB effect was observed when the response in Task₁ was made at the end of the trial, off line, without speed pressure. As can be seen in Figure 6, performance in Task₂ was lower in the speeded condition than in the delayed condition at the shorter SOAs, but the opposite was found at longer SOAs. It is likely that the extra cost at the short SOAs caused by requiring an immediate response was due to the overlap between response selection and operations required to perform Task₂. It is likely that this overlap is not present when the subject can make a delayed response. The results thus suggest that relatively late stages of processing, such as response selection, can modulate the magnitude of the AB phenomenon. A model based on the central interference theory designed to explain these findings is described in the General Discussion section.

Why should the T_1 -present functions for unspeeded versus speeded Task, responses cross over as SOA was increased? The account for this effect may be quite straightforward: in the delayed-response condition, a memory representation of T₁ must be maintained in STM throughout the trial in order to make an accurate response at the end of the trial. It is known that memory load can influence the general efficiency of information processing (Logan, 1978). Furthermore, in both the two-stage model and the central interference theory, it is hypothesized that the primary locus of the AB effect is in the processes that consolidate information into STM. Thus, one might expect that memory load would influence performance (Scarborough, 1972). In contrast, in the speeded condition, once the response is selected, there is no further need to maintain an active representation of T_1 in STM. The subject can focus exclusively on Task₂. Removing the need to maintain an active representation of T_1 in STM could reduce the central interference that may cause the AB effect in Task₂. The mean RT in Task₁ was about 530 msec (Experiments 2 and 3), which is close to the point at which the AB functions cross over; this may not be coincidental. The difference in the on-line response selection processes at short SOAs and in the memory requirements at longer SOAs is thus consistent with the observed crossover pattern of results as SOA was increased from 100 to 800 msec.

DEPENDENCY OF THE AB ON RT₁

A hallmark of results consistent with postponement models of PRP effects is that certain aspects of perfor-

mance in Task₂ should be systematically related to the speed of responses in Task₁. In the present paradigm, the RT in Task₁ (RT₁) should reflect the time to perform several key cognitive operations required to perform Task₁. Two critical processes should contribute significantly to the variance in RT₁: stimulus classification and response selection (Pashler, 1994). Thus, on trials in which RT₁ was long, there is a higher probability that stimulus classification and response selection operations were slower than usual. Conversely, on trials in which RT₁ was short, chances are that stimulus classification and response selection operations were faster than usual. Thus, when RT₁ was short, the central operations that occupy the hypothetical central bottleneck likely did so for less time than when RT₁ was long. If bottleneck processes are involved in the AB phenomenon, one would expect a smaller AB for fast responses to T_1 than for slow responses.

To examine the prediction that the magnitude of the AB effect would depend on speed of response in Task₁, performance in $Task_2$ was conditionalized on RT_1 . The general method of analysis was as follows. First, T_1 present trials (in which Task, was speeded) were sorted by SOA separately for each subject. The RTs for correct responses in each cell were first screened for outliers, using a procedure that is a slight modification of the one described by Van Selst and Jolicoeur (1994b; the modification involves temporarily excluding the most extreme observation rather than the largest observation).¹ No more than 2.5% of the correct trials were rejected, using this procedure. Note that removing outliers is likely to attenuate any Task₂ dependency on RT₁, since at least some of the long RT₁s so excluded were probably associated with poor performance in Task₂ (as will become clear below).

The trials in each SOA category for each subject were then split into two categories, short versus long, by doing a median split on the RT₁s within each cell. Performance in Task₂ was then computed separately at each SOA (and subject) within each category. In Experiment 2, this resulted in about 20 trials per SOA per subject, whereas the number was about 10 in Experiment 3. A finer split of the results was also performed by dividing the RT₁s into quartiles (within each cell for each subject) and aggregating the results across Experiments 2 and 3.

The results for Experiment 2 are shown in Figure 7. The error bars show 95% within-subjects confidence intervals, appropriate for comparisons among the displayed means (estimated from an ANOVA in which the 16 means were treated as a single within-subjects factor). The interaction between SOA and short/long-RT₁s was significant [F(7,126) = 2.35, $MS_e = 0.0068$, p < .028]. The mean for short RT₁s (.72) was higher than for long RT₁s [.67; $F(1,18) = MS_e = 0.0095$, p < .0001]. Two aspects of the results are apparent in the figure. First, accuracy in Task₂ at shorter SOAs was lower when RT₁ was longer than when RT₁ was shorter (except at an SOA of 200 msec, where accuracy was equivalent across short and long RT₁s). This difference was similar at intermediate SOAs, with some convergence between the two

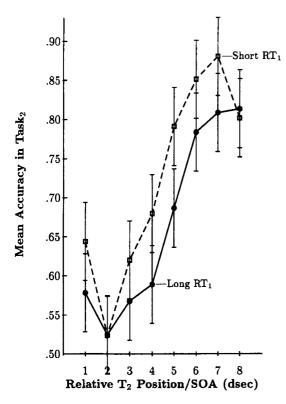


Figure 7. Results from Experiment 2. Mean proportion correct discrimination of T_2 (X vs. Y) depending on response times (RTs) in Task₁ (based on a median split of T_1 -present trials only, following outlier screening). Unfilled squares and dashed lines are for short RT₁s; filled circles and solid lines are for long RT₁s. The error bars are 95% within-subjects confidence intervals appropriate for comparisons of the means in the figure. 1 decisecond (dsec) = 100 msec.

functions at the longest SOA. The lower accuracy in Task₂ for longer RT₁s than for shorter RT₁s at almost every SOA suggests that a larger AB effect was associated with longer RT₁s. Second, given that performance in Task₂ appeared to recover to near-baseline levels only at the longest SOA, the results also suggest that the AB effect had a longer duration when RT₁ was longer.

The mean RT₁ was 456 msec for RTs shorter than the median and 606 msec for RTs longer than the median. RTs did not vary significantly with SOA [F(7,126) = 1.94, $MS_e = 636.104$, p > .06], and the pattern of RT₁s for faster versus slower trials did not interact with SOA [F(7,126) = 1.47, $MS_e = 373.708$, p > .18].

The means showing the dependence of Task₂ performance on RT₁ for Experiment 3 are in Figure 8. Task₂ performance was better when the response to T₁ was fast (.78) than when it was slow [.72; F(1,21) = 19.70, $MS_e = 0.0150$, p < .0003]. The interaction between short/long-RT₁ and SOA was not significant, however [F(7,147) = 1.42, $MS_e = 0.0178$, p > .20].

The mean RT₁ was 451 msec for RTs shorter than the median and 608 msec for RTs longer than the median. RTs did not vary significantly with SOA (F < 1), and the pat-

tern of RT_1s for faster versus slower trials did not interact with SOA (F < 1).

The results from speeded Task, trials in Experiments 2 and 3 were also combined into a single analysis. Given the larger number of subjects contributing to the analysis, the trials were split on the basis of RT_1 quartiles. The resulting means are in Figure 9. The error bars are 95% within-subjects confidence intervals estimated from the error term in an ANOVA in which the SOA \times quartile interaction was treated as a single factor with 32 levels (Loftus & Masson, 1994). Error bars are plotted only for the means for the first (shortest RT_1s) and fourth quartiles to reduce clutter. Task₂ performance was .77 for the first quartile, .74 for the second quartile, .73 for the third quartile, and .67 for the fourth quartile [averaging across all SOAs; F(3,120) = 20.85, $MS_e = 0.025977$, p < 0.025977.0001]. The interaction between quartiles and SOA was also significant $[F(21,840) = 2.12, MS_e = 0.025682,$ p < .0025]. The rank ordering of the means from the first to the fourth quartile was reasonably well preserved at most SOAs, except for the longest ones, where, as ex-

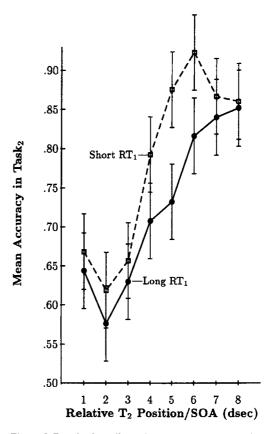


Figure 8. Results from Experiment 3. Mean proportion correct discrimination of T_2 (X vs. Y) depending on response times (RTs) in Task₁ (based on a median split of T_1 -present trials only, following outlier screening). Unfilled squares and dashed lines are for short RT₁s; filled circles and solid lines are for long RT₁s. The error bars are 95% within-subjects confidence intervals appropriate for comparisons of the means in the figure. 1 decisecond (dsec) = 100 msec.

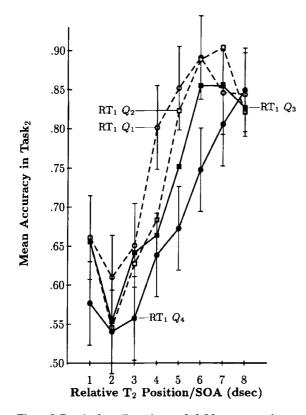


Figure 9. Results from Experiments 2–3. Mean proportion correct discrimination of T_2 (X vs. Y) depending on response times (RTs) in Task₁ (based on a quartile split of T_1 -present trials only, following outlier screening). Q_1 designates means for the first quartile (fastest responses), Q_2 the second quartile, Q_3 the third quartile, and Q_4 the fourth quartile (slowest responses). To facilitate interpretation, the Q_1 function is plotted with unfilled circles joined by dashed lines; the Q_2 function is plotted with unfilled squares joined by solid lines; and the Q_4 function is plotted with filled circles joined by solid lines. The error bars are 95% within-subjects confidence intervals appropriate for comparisons of the means in the figure. 1 decisecond (dsec) = 100 msec.

pected, the functions converged. This convergence was expected because the response in Task₁ (R₁) was already executed on most trials by the time T₂ was shown at the longest SOA (mean RT₁ = 416 msec for the first quartile, 490 msec for the second quartile, 552 msec for the third quartile, and 664 msec for the fourth quartile). Central involvement required to process T₁ should usually be over for the longer SOAs. Thus, on the view that the association between RT₁ and AB magnitude is mediated by differential durations of central involvement required to perform Task₁, there is no reason to expect RT₁ variations to continue to affect performance in Task₂ long after R₁.

As can be seen in Figures 7–9, performance in $Task_2$ showed a strong dependence on the speed of the response in $Task_1$ within both experiments and in the combined analysis. The analyses were based on a within-SOA within-

subjects split of the RTs in Task₁. The results show a micro dependence (De Jong & Sweet, 1994) between the trial-to-trial processing speed in Task₁ and performance in Task₂.

GENERAL DISCUSSION

The AB phenomenon is interesting because it is likely that it reveals a fundamental limitation in our ability to process perceptual input. Performance in Task₂ suffers for a period of time when T_2 is presented shortly after T_1 , but only when T_1 is actively processed by the observer. The experiments reported in the foregoing sections have revealed several new properties of the AB phenomenon that can be used to advance our theoretical understanding of this phenomenon and of the human information processing system in general. These new properties can be summarized as follows. First, the shape of the AB function (T_1 -present trials) changes in a characteristic way when the response in Task $_{1}$ is changed from off line to on line. Accuracy in Task₂ was worse at short SOAs when R_1 was performed on-line than off-line, whereas the opposite was true at longer SOAs. The second observation, made possible by requiring a speeded R_1 and measuring RT_1 , was that the magnitude of the AB effect was larger for longer RT_1s than for shorter RT_1s (see Figures 7–9).

Task₁ Response Requirements

It is likely that the effects of requiring an immediate versus a delayed response in Task 1 occur at a relatively late stage of processing (i.e., at a postperceptual stage). It is likely that response selection (a postperceptual stage of processing) was engaged during the display of the RSVP stream in the speeded-response condition but that response selection was delayed until the end of the trial in the delayed-response condition. Other evidence (Jolicoeur, in press-a, in press-b) also suggests that manipulations of the duration of response-level stages of processing, most likely response selection, can have significant effects on the shape and duration of the AB effect. The following paragraphs contain a discussion of the finding that the magnitude of the AB effect was modulated by the response requirements (speeded vs. delayed) in Task₁ in the context of the models presented in the introduction.

None of the models, other than the central interference theory, predicted that requiring an immediate response in Task₁ would have an effect on the magnitude, duration, or shape of the AB function. Ward et al. (1996) were the clearest on this point in that their attentional dwell model explicitly excludes late processes, such as those associated with response selection, as being causally involved in the AB phenomenon. In the attentional dwell model, the locus of the AB effect is in the capacity-limited process of transferring representations from Level 1 to Level 2, which occurs before additional processing, such as response selection, can take place.

Although the authors of the other models did not explicitly exclude response selection as being causal in the AB phenomenon, the models have no natural way to account for effects at this stage of processing. In the attentional gate model (Raymond et al., 1992), the AB is caused by the closing of an attentional filter designed to protect pattern recognition mechanisms from posttarget patterned noise. The opening and closing of the gate were postulated to depend on the characteristics of perceptual stimulation (e.g., whether $T_1 + 1$ in an RSVP stream was a patterned stimulus or a blank interval). There is no mechanism in the model that can allow processing that takes place after T_1 has been identified (e.g., response selection) to influence the opening and closing of the attentional gate or to affect the efficiency of the filter.

In the similarity theory (Shapiro et al., 1994), the AB effect is caused by limited resources in the assignment of weights to items that enter VSTM. Output from VSTM is then based on these weights. Presumably, responses are made to items only after they have been transferred out of VSTM and passed on to a later stage of processing that makes contact with other cognitive control mechanisms. According to the model, the causal mechanisms that produce the AB effect all take place before responserelated processes. Thus, according to this model, there was no reason to expect that requiring an immediate versus a delayed response should have had any effect on the magnitude or shape of the AB effect.

According to the two-stage model (Chun & Potter, 1995), the locus of the AB effect is a capacity-limited process by which items are transferred from a fragile and temporary form of representation (Level 1 in Duncan, 1980) to a more permanent form of representation (Level 2) that can serve as the basis for overt responses and recall. As in the attentional dwell model, the manipulation of the response requirements in Task₁ (delayed vs. immediate response) should have an effect at a stage of processing that occurs after the hypothesized locus of the AB effect. Therefore, this model also has no obvious way to deal with the effects of Task₁ response requirements.

Dependency of the AB on RT₁

Requiring a speeded response in Task₁ provided a way to estimate the duration of processing required to perform Task₁ and to relate it to the magnitude of the AB effect observed in Task₂. A larger AB effect was found when RT_1 was longer than when RT_1 was shorter (see Figures 7–9). Such trial-to-trial dependencies have been used to argue against resource accounts of dual-task slowing in the PRP literature (Pashler, 1994). The argument has the following form: Suppose that there is a fixed pool of resources that can be divided for allocation to either Task₁ or Task₂. On trials in which RT_1 was short, the inference would be that more of the available resources had been allocated to Task₁ and, therefore, fewer were available for Task₂. Conversely, if \mathbf{RT}_1 was long, fewer resources were allocated to Task₁, leaving more for Task₂. In this view, therefore, short RT₁s should be associated with worse performance in Task₂, and long RT₁s

should be associated with better performance in $Task_2$ in other words, exactly the opposite of what was found. Thus, the observed pattern of results is not consistent with this interpretation of resource sharing.

The similarity theory (Shapiro et al., 1994) and the attentional dwell model (Duncan et al., 1994; Ward et al., 1996) both incorporate aspects of resource models. In similarity theory, the notion of resources appears in how strongly items are represented in VSTM. Items in VSTM receive weights that depend on two factors: how well they match selection templates for T_1 and T_2 and the level of available resources. Resources must be shared by the items in VSTM, with larger weights assigned to the first items to enter VSTM because available resources have not been allocated to previous items. That is, the weights that items receive depend on a pool of resources that must be shared by all the items in VSTM. In the attentional dwell model, objects compete for passage from a first level of representation to a second level (Duncan, 1980), and it is assumed that resources devoted to one item are not available for others. If we suppose that the pool of available resources in these models is fixed and that items that receive more resources are processed faster, the models should predict that faster RT₁s should be associated with larger AB effects. The observed dependency between RT_1 and the magnitude of the AB is inconsistent with this prediction, however.

Another interpretation of the notion of resources could predict simple positive correlations between RT1 and AB magnitude. In this interpretation, we relax the assumption that the pool of resources is fixed. For example, suppose that there are momentary fluctuations in total available resources. Some trials would occur while the total available resources are low. On these trials, performance in both tasks would be poor-a longer RT₁ in Task₁ and lower accuracy in Task, would result. On other trials, the available resources might be high, resulting in good performance in both tasks. This line of argument leads to a difficulty, however. It is not clear why performance in Task₂ would converge to a common level at longer SOAs (see, e.g., Figure 9). If we assume that the relationship observed between RT₁ and AB magnitude is the result of fluctuating levels of total available resources, on trials initiated at a time when resources were scarce, performance in Task₂ should remain lower at all SOAs. Therefore, although the notion of a fluctuating pool of available resources could explain a simple main effect relationship between the duration of RT_1 and performance in Task₂, it cannot easily account for the more complex interaction that was observed.

In the context of the similarity theory and of the attentional dwell model, one would also expect that accuracy in Task₁ would be strongly related to RT_1 , if the relationship between RT_1 and accuracy in Task₂ is to be explained by appeal to fluctuating resources. On trials with a smaller pool of resources, lower accuracy in Task₁ and longer RT_1 s should be found. To test this prediction, the trials for each subject and for each SOA were divided into four bins on the basis of RT₁ quartiles. The mean accuracy in Task₁ was computed within each bin. The patterns of results were similar in Experiments 2 and 3 (interaction F < 1), and so only the results from a combined analysis that considered speeded Task₁ trials from all 41 subjects are presented here. The mean accuracy in Task₁ was .915 for the first quartile (fast RT₁s), .958 for the second quartile, .951 for the third quartile, and .956 for the fourth quartile [F(3,120) = $10.90, MS_e = 0.012217, p < .0001$]. Accuracy in Task₁ did not depend on when T₂ was presented [F(7,280) = $1.53, MS_e = 0.008093, p > .15$] or on the interaction between RT₁ quartile and SOA [$F(21,840) = 1.28, MS_e =$ 0.006876, p > .18].

The results were clearcut: Accuracy in Task₁ was slightly lower when RT_1 was short (first quartile) but did not vary as a function of RT_1 for longer RT_1 s (accuracy was constant across the remaining three quartiles). This pattern of results provides evidence against a resources account of the relationship between RT_1 and accuracy in Task₁ and Task₂. On that account, fewer resources should have produced longer RT_1 s and worse accuracy in both tasks. Instead, the relationship between RT_1 and accuracy in Task₁ was of one kind (worse performance at shorter RT_1 than at longer RT_1 , and only for the first quartile), whereas it was altogether different in Task₂ (accuracy decreased monotonically as RT_1 increased). These considerations suggest that the results are not explained very well by resource models.

The relationship between AB magnitude and RT_1 is also not easily accounted for by the attentional gate model (Raymond et al., 1992). There is simply no a priori way to relate the speed of processing of T_1 to the filtering efficiency of the gate or to the speed of the gate.

On the other hand, there is a way to relate the duration of processing devoted to T_1 to the magnitude of the AB on the basis of the two-stage model (Chun & Potter, 1995). All we need to suppose is that RT_1 will depend, at least in part, on how long T_1 is processed through Stage 2. The duration of Stage 2 processing for T_1 directly affects how long T_2 has to wait before it can be processed through Stage 2 and, therefore, how long the Stage 1 representation of T₂ decays during the waiting period. A longer period of waiting leads to more decay. Thus, a longer RT₁ should be associated with a longer period of Stage 2 processing for T_1 , which, in turn, should produce a larger AB effect in Task₂, which is what was observed. The central interference theory makes the same prediction for the same fundamental reason, as outlined in the section entitled Central Interference Theory.

One or More Loci?

How well each model can account for the two main new results of the experiments can be summarized as follows:

Attentional Gate Model Cannot explain the effects of Task₁ response requirements Cannot explain the relationship between RT_1 and AB magnitude

Similarity Theory

Cannot explain the effects of Task₁ response requirements

The VSTM resources component of the model predicts a different relationship between RT_1 , AB magnitude, and accuracy in Task₁ than was observed

Attentional Dwell Model

Cannot explain the effects of Task₁ response requirements

Resources account of processing in Stage 2 predicts a different relationship between RT_1 , AB magnitude, and accuracy in Task₁ than was observed

Two-stage Model

Cannot explain the effects of $Task_1$ response requirements Can explain the relationship between RT_1 and

Can explain the relationship between RT_1 and AB magnitude

On this report card, the two-stage model fares the best, because it is the only one that can provide an account of the relationship between RT1 and AB magnitude without further elaboration or assumptions. None of the models has a good way to deal with effects of Task, response requirements, because, in every case, response selection operations take place after the locus of dual-task interference postulated in the model. One way in which we could deal with the effects of Task₁ response requirements is to hypothesize that there are multiple loci for the AB phenomenon. In this view, response selection effects would constitute a new phenomenon, a new attentional blink, which we might label AB^{RS}, to distinguish it from the previously discovered effect, AB. For the attentional gate model, we might label the effects of the attentional gate ABG, and the effects observed in this article could be represented as $AB^G \oplus AB^{RS}$. For the two-stage model and the attentional dwell model, we might label the AB effect produced by the transfer from Level 1 to Level 2 as $AB^{1\rightarrow 2}$, and the effects observed in this article as $AB^{1\rightarrow 2} \oplus AB^{RS}$. Similarly, for the similarity theory, we might have a combined effect represented by $AB^{VSTM} \oplus$ AB^{RS}. We could go as far as to suppose that there are more than two loci and that the observed AB effect reflects some combination of all of the postulated loci proposed by various authors, which we could represent by

$$AB \equiv AB^{G} \oplus AB^{VSTM} \oplus AB^{1 \rightarrow 2} \oplus AB^{RS}.$$

Other combinations involving AB^{RS} are also possible. The present results cannot rule out any of these possibilities.

Central Interference Theory

The present results cannot refute models involving multiple loci. On the other hand, it may be possible to account for the results in a framework in which there is a single locus of interference in terms of the series of stages required to perform Task₂. The purpose of this section is to present the outline of a theory in which there is only one fundamental locus of interaction between the two tasks.

The theory extends postponement models of the PRP effect to account for the AB phenomenon. The theory supposes that the critical stage of processing required to perform Task₂ that is affected by concurrent processing in Task₁ is short-term consolidation (STC). STC is the process of encoding information into STM. The key concept in the theory is that certain cognitive processes require central mechanisms that are capacity limited. This capacity limitation imposes a seriality in the sequence of operations for certain combinations of operations but not for others. It is assumed that STC requires central capacity-limited processing. STC for Task₂ can be delayed by a number of different operations that could be required for Task₁.

Although response selection has been identified as one stage of processing that appears to require central limited-capacity processing (see, e.g., McCann & Johnston, 1992; Pashler, 1994), it is not the only operation that can cause central PRP interference with other concurrent processing (see Pashler, 1994, for a recent review). There is good evidence that some aspects of mental rotation (Ruthruff, Miller, & Lachmann, 1995; Van Selst & Jolicoeur, 1994a), and retrieval from long-term memory (LTM; Carrier & Pashler, 1995) also require central processing and cause PRP interference with other tasks.

The central interference theory incorporates the interpretation of PRP interference presented above. In this view, response selection is not the only stage capable of producing central interference; it is only one operation in a family of operations that can do so. In the context of the AB phenomenon, several cognitive operations can cause interference on the STC of T_2 . The set of such operations includes response selection, the STC of T_1 (as in the two-stage model), and mental rotation. It is also likely that central involvement required to switch between two tasks (Rogers & Monsell, 1995) can also interfere with the STC of T₂ (Potter, Chun, Banks, & Muckenhoupt, in press), as might retrieval from LTM (Carrier & Pashler, 1995). This conceptualization should make it clear that the two-stage model is a special case of the central interference theory. In the two-stage model, only Stage 2 processing of T_1 can postpone Stage 2 processing of T_2 . In the central interference theory, the set of operations that can postpone STC₂ includes STC₁, but it also includes other operations, such as response selection, mental rotation, retrieval from LTM, and probably task switching (Potter et al., in press). In this framework, therefore, there is one key stage of processing required to perform Task₂ that is subject to interference—the STC of T_2 —and as such there is only one fundamental locus of interference in the sequence of processing required to perform Task₂. However, there are multiple operations in Task₁ that can interfere with the STC of T_2 . Thus, one could describe interference of STC_2 by STC_1 (STC of T_1), or by RS_1 (response selection in Task₁) as different causes

of the AB effect, with both causes acting on a single stage of processing in Task₂.

Figure 10 illustrates a model of interactions between stages of processing required to perform the two tasks in the AB paradigm that is based on the central interference theory. Figure 10A shows these interactions for the delayedresponse paradigm. The model assumes that the earliest stages of encoding, called sensory encoding (SE) and perceptual encoding (PE), can take place without central involvement and essentially without mutual interference across tasks. The most important assumption of the model is that some central involvement is required to encode information into STM. This encoding process, STC, cannot occur when central mechanisms are occupied with the processing required for another concurrent task.

The top sequence of stages of each panel in Figure 10 shows the stages necessary to perform Task₁. When Task₁ involves a delayed response, the main activity that engages central mechanisms is the process of STC postulated to be necessary to encode T_1 into STM. STM is required because information about T₁ must be maintained throughout the remaining presentation of the RSVP stream until the end of the trial, at which point the encoded information can be passed on to response selection mechanisms, eventually leading to a response. While STC for Task₁ is taking place (STC₁ in the figure), STC for Task₂ is blocked. If T_2 is masked, as it is in the RSVP paradigm used in Experiments 1–3, the representation of T_2 created or activated by PE mechanisms (PE_2 in the figure) begins to decay if it is not immediately subjected to STC $(STC_2 \text{ in the figure})$. For more evidence suggesting the importance of masking T₂, see Giesbrecht and Di Lollo (in press) and Jolicoeur (in press-b). For evidence of very poor memory for briefly identified objects, see Potter (1976, 1993).

We can equate SE and PE with Stage 1 processing in the two-stage model, the attentional dwell model, or Duncan's (1980) model. In the central interference theory, STC is the process of encoding information into STM. This stage is similar to Stage 2 processing in the two-stage model, the attentional dwell model, or Duncan's model. In these models, Stage 2 processing is required to make storage into STM possible. The role played by STC in the central interference theory and Stage 2 processing in the two-stage model or the attentional dwell model is similar. According to all three approaches, it is in this stage that there is a capacity limitation that leads to a decrease in accuracy in Task₂. Because of this similarity, most results that the two-stage model or the attentional dwell model can explain are also explained by the central interference theory. There are differences across models, however, as already discussed. The central interference theory assumes that operations other than STC₁ can cause postponement of the STC₂. This is one major difference between the central interference theory and either the two-stage model or the attentional dwell model. And it is this difference that allows the central interference theory

| A: Delayed Response in Task1: Off-line Response Selection | | | | | | | | | | | | |
|---|---------------------------------|---------------------|------------------|-------------------|-----------------|-----------------|-----------------|--|--|--|--|--|
| A. Denagen theopolise in Tuski. Og-ine theopolise Detection | | | | | | | | | | | | |
| SE ₁ PE ₁ | STC1 | ST | M1 | RS ₁ | RE1 | | | | | | | |
| \leftarrow SOA SE ₂ | PE_2 ··· | STC | 2 | STM_2 | | RS_2 | RE ₂ | | | | | |
| B: Speeded Response in Task ₁ : On-line Response Selection | | | | | | | | | | | | |
| SE ₁ PE ₁ | STC1 | RS_1 | RE1 | | | | | | | | | |
| \leftarrow SOA SE ₂ | PE ₂ | ••••• | STC ₂ | STM ₂ | RS ₂ | RE | 2 | | | | | |
| | | | | | | | | | | | | |
| C : Speeded Task ₁ : Same Postponement as in A at Longer SOA | | | | | | | | | | | | |
| SE ₁ PE ₁ | STC_1 | RS_1 | RE_1 | | | | | | | | | |
| ← SOA | \rightarrow SE ₂ F | \mathbf{PE}_2 ··· | STC_2 | STM ₂ | RS ₂ | RE | , | | | | | |
| | | | | | | | | | | | | |
| D: Speeded Task ₁ : Longer Response Selection in Task ₁ | | | | | | | | | | | | |
| $SE_1 PE_1 $ | STC ₁ | RS_1 | RI | C ₁ | | | | | | | | |
| \leftarrow SOA SE ₂ | PE ₂ | ····· | S | rC ₂ S | ΓM ₂ | RS ₂ | RE ₂ | | | | | |
| E : Speeded Task ₁ : Same Postponement as in B at Longer SOA | | | | | | | | | | | | |
| $[SE_1 PE_1]$ | STC ₁ | RS ₁ | RI | 81 | | | | | | | | |
| SOA → | SE ₂ PE ₂ | ••••• | S. | ΓC_2 S | ГM ₂ | RS ₂ | RE ₂ | | | | | |

Figure 10. Model of task interactions. In each panel there are two stage diagrams. The top diagram illustrates the stages of processing mediating performance in Task₁; the bottom diagram is for Task₂. Panel A: Model for unspeeded Task₁ conditions. In Task₁, following early encoding operations—sensory encoding (SE_1) and perceptual encoding (PE1)-the encoded information is subjected to short-term consolidation (STC_1) processes. STC_1 creates a copy of the information produced by PE_1 in shortterm memory (STM₁). The information is maintained in STM until the end of the trial. At that point, response selection (RS₁) is performed, followed by response execution (RE1). After a variable SOA, T2 is presented (bottom diagram in Panel A). Following early encoding (SE2 and PE2), the system would normally engage STC operations (STC_2) to encode T_2 into STM. At short SOAs (as diagrammed here), however, STC₂ cannot proceed because central mechanisms are busy carrying out STC₁. STC₂ must wait until STC₁ terminates the STC of T₁. During this period of waiting, the representation of T2 produced by PE2 begins to decay (if T2 was masked). Panel B: Model for speeded Task₁ conditions. In Task₁, after STC₁, RS₁ is performed, leading to RE₁. STC₂ is postponed both by STC₁ and RS₁, leading to a longer period of central postponement than when only STC_1 needs to be performed, as is shown in Panel A. The longer postponement results in more decay of T2, leading to worse recall. Panel C: Model for speeded Task₁ conditions, as in Panel B, but with T₂ presented at a longer SOA. Note that the same duration of STC2 postponement as that observed in Panel A is predicted by the model, but at the longer SOA. Panel D: Illustration of the consequences of a longer period of response selection in Task₁ (RS₁) relative to the stage durations in Panel B. A longer delay in STC₂ results, for a given SOA, producing a larger AB deficit in Task₂. Panel E: Illustration that the same duration of postponement of STC₂ produced in Panel B can be produced at a longer SOA if the duration of RS₁ in Task₁ is longer. The AB effect should last longer.

to explain the effects of Task $_1$ response requirements on the magnitude of the AB effect.

If the SOA between T_1 and T_2 is short, a period of waiting can occur after the masking of T_2 and before the time at which STC for Task₂ can begin (illustrated in Figure 10A by declining dots before STC₂). A longer period of waiting will generally be associated with a shorter SOA.

In Figure 10B, the effect of requiring an on-line response in Task₁ is represented by assuming that response selection in Task₁ immediately follows the STC of T_1 . This added processing creates a longer period during which STC of T_2 must wait, leading to more decay of the representation of T_2 and, thus, to a larger AB effect.

For the sake of clarity, consider again Figure 10A and Figure 10B. Note that the same SOA is assumed in both cases. At this constant SOA, the period of postponement of STC_2 is longer when a speeded response was required in Task₁ (Figure 10B) than when a delayed response was required (Figure 10A). A longer period of postponement of STC_2 results in a greater loss of information about T_2 (more decay). Thus, worse accuracy in Task₂ is expected at this SOA with a speeded response than with a delayed response. That is, the AB effect should be larger (at least for intermediate SOAs).

Figure 10C illustrates that the AB effect should last longer when a speeded response is required. The same duration of postponement produced in Figure 10A can be obtained with a longer SOA. Thus, equivalent performance should be observed at these two SOAs, and hence a longer AB should result. This prediction was confirmed, but only for a limited range of SOAs (e.g., in Figure 4, compare performance in the unspeeded condition at 300msec SOA with performance in the speeded condition at the 400-msec SOA).

At longer SOAs, however, better performance was found with a speeded Task₁ response than with a delayed response. At first blush, this finding may appear surprising and problematic for the model shown in Figure 10. It is likely, however, that the difference across conditions was caused by differences in the memory requirements of Task₁ across the speeded and unspeeded conditions. In the unspeeded condition, a memory representation of T_1 must be maintained in STM until after the end of the trial. In contrast, in the speeded condition, once the response has been selected, the representation of T_1 is no longer needed. This difference is illustrated in Figures 10A and 10B. When Task₁ is performed with a delayed response (Figure 10A), the processing of T_2 must take place while a representation of T_1 is maintained in STM, which is likely not to be the case when Task1 is speeded (Figure 10B). If some aspect of the processing of T_2 , such as STC_2 , is not as efficient when it is carried out with a concurrent load in STM (Logan, 1978), better performance would be expected in the speeded condition, but only when interference associated with on-line response selection had come to an end-that is, at longer SOAs.

Figure 10D illustrates the consequence of a longer period of response selection in Task₁ than that shown in

Figure 10B: a longer period of postponement of STC_2 results, leading to a larger AB effect. These postulated interactions are designed to account for the micro dependency between the magnitude of the AB effect and the duration of RT_1 . They can also account for effects of direct manipulations of the duration of response selection in Task₁ when R₁ is made on line (Jolicoeur, in press–a, in press–b). A similar effect would result also if the duration of STC₁ was lengthened (see Jolicoeur & Dell'Acqua, 1996, 1998).

As RT_1 lengthens, the AB should also last longer. This is illustrated by comparing Figure 10E with Figure 10B. The same duration of postponement of STC_2 is shown in both cases, but it occurs at a longer SOA when RT_1 is longer (panel E) than when RT_1 is shorter (panel B). This prediction was confirmed, as can be seen in Figure 9. Note that comparisons of the effects of shorter versus longer RT_1 s are made under equivalent memory load conditions, explaining why the prediction of both a larger and a longer AB is borne out.

It should also be noted that manipulations that would affect the duration of perceptual processing of T_1 should also produce effects on the magnitude and duration of the AB effect, according to the models shown in Figure 10. Consider Figure 10A and suppose that the duration of SE_1 were lengthened by some experimental manipulation (e.g., by changing the contrast of T_1 in an RSVP paradigm, or by changing the masking effect of subsequent items). A longer period of SE_1 would cause STC_1 to begin later and, thus, to finish later. The later finishing time of STC₁ means that STC₂ could be postponed for a longer time, depending on just when the perceptual representation of T₂ became ready for STC. The observation here is that increasing the duration of STC₁ itself or of any stage of processing before STC₁ would likely lengthen the period of postponement of STC₂, leading to a larger and longer AB effect. Thus, the fact that manipulations believed to have an effect on the perceptual processing of T₁ (such as different levels of masking) modulate the magnitude of the AB effect is entirely consistent with the central interference theory. The present theory leads to the prediction that affecting the duration of SE in $Task_1$ (SE₁) would produce measurable effects in Task₂ performance; yet SE_1 per se does not interfere with any stage of processing required to perform Task₂. Potential effects of manipulations of the duration of SE₁ on accuracy in Task₂ would all be mediated by changes in the onset and offset times of the operations of more central stages of processing, such as the STC of T_1 (STC₁). The foregoing remarks are intended to highlight the difficulties involved in pinpointing the likely locus (or loci) of dual-task interference producing the AB effect. The fact that a variable believed to affect the encoding of T_1 has effects in the AB paradigm does not, by itself, support the conclusion that AB is a perceptual phenomenon.

According to the central interference theory, the postponement of STC_2 by STC_1 and the postponement of STC_2 by RS_1 are two different causes of the AB effect

because each of these processes (STC₁ and RS₁) directly interferes with STC₂. However, the theory allows us to provide a unified account of both effects by subsuming them as specific manifestations of a more general phenomenon: In both cases, the AB effect is a manifestation of the central postponement of STC₂ by concurrent central processing required to perform Task₁. It is this aspect of the theory that makes it similar to some accounts of the PRP phenomenon. In postponement models of the PRP effect (see, e.g., McCann & Johnston, 1992), central interference is postulated at the level of RS: RS_1 is thought to postpone RS_2 . The central interference theory could provide the basis for a broad unification of the AB and PRP phenomena by subsuming both as manifestations of central interference. However, it is clear that the two phenomena are not identical. According to the central interference theory, AB is produced by central interference of STC₂, whereas PRP is likely produced by central interference of RS₂. Therefore, it would not be surprising to discover that this difference could lead to observable empirical dissociations. Nonetheless, both AB and PRP could be similar in that they may both be manifestations of relatively late capacity limitations in the flow of information processing.

The results presented in this article, by themselves, do not provide unequivocal support for the model illustrated in Figure 10. Clearly, there are unresolved empirical and theoretical issues that will require additional research. For example, it is not clear whether STC must necessarily precede response selection when a speeded response must be performed in $Task_1$. It is possible that a representation of T_1 is made available to RS mechanisms via a late, capacity-demanding, stimulus categorization process (McCann & Johnston, 1992). Perhaps this stage is required before either STC or RS, as suggested by Duncan (1980). Furthermore, this stage of processing, per se, could be capacity demanding and be involved in various dualtask interference phenomena. If STC₁ is not required for RS₁, the models shown in Figures 10B-E will require amendment. The simplest amendment would be to replace the stages labeled STC_1 and RS_1 in the top stage diagrams in Figures 10B-E by a single stage, labeled RS₁. More work will be required to disentangle this and other related issues.

This article reports evidence highlighting the importance of considering relatively late, or postperceptual mechanisms, such as RS, in explanations of the AB phenomenon. A new empirical technique made it possible to observe interactions with such postperceptual processes. The technique consisted of requiring an immediate response in Task₁ rather than a delayed response at the end of the trial. Finally, a new theory was outlined, the central interference theory, which can account for observed effects of Task₁ response requirements on the magnitude of the AB effect and the dependence of AB magnitude on RT₁. The key assumption in this theory is that encoding information into STM involves a process—STC—that requires central mechanisms and that STC is susceptible to dual-task interference. The new theory may provide the basis for a broad unification of several presently nonintersecting lines of research, including the PRP effect, STM, the AB phenomenon, and perhaps other closely related paradigms.

REFERENCES

- BROADBENT, D. E., & BROADBENT, M. H. P. (1987). From detection to identification: Response to multiple targets in rapid serial visual presentation. *Perception & Psychophysics*, 42, 105-113.
- CARRIER, L. M., & PASHLER, H. (1995). Attentional limits in memory retrieval. Journal of Experimental Psychology: Learning, Memory, & Cognition, 21, 1339-1348.
- CHUN, M. M., & POTTER, M. C. (1995). A two-stage model for multiple target detection in rapid serial visual presentation. *Journal of Experimental Psychology: Human Perception & Performance*, 21, 109-127.
- DE JONG, R., & SWEET, J. B. (1994). Preparatory strategies in overlappingtask performance. Perception & Psychophysics, 55, 142-151.
- DUNCAN, J. (1980). The locus of interference in the perception of simultaneous stimuli. *Psychological Review*, 87, 272-300.
- DUNCAN, J., WARD, R., & SHAPIRO, K. L. (1994). Direct measurement of attentional dwell time in human vision. *Nature*, 369, 313-315.
- GIESBRECHT, B. L., & DI LOLLO, V. (in press). Beyond the attentional blink: Visual masking by item substitution. *Journal of Experimental Psychology: Human Perception & Performance.*
- JOLICOEUR, P. (in press-a). Concurrent response selection demands modulate the attentional blink. *Journal of Experimental Psychology: Human Perception & Performance.*
- JOLICOEUR, P. (in press-b). Dual-task interference and visual encoding. Journal of Experimental Psychology: Human Perception & Performance.
- JOLICOEUR, P., & DELL'ACQUA, R. (1996, October). Attentional and structural constraints on short-term memory encoding. Paper presented at the 37th Annual Meeting of the Psychonomic Society, Chicago.
- JOLICOEUR, P., & DELL'ACQUA, R. (1998). The demonstration of shortterm consolidation. Cognitive Psychology, 36, 138-202.
- LOFTUS, G. F., & MASSON, M. E. J. (1994). Using confidence intervals in within-subject designs. Psychonomic Bulletin & Review, 1, 476-490.
- LOGAN, G. D. (1978). Attention in character-classification tasks: Evidence for the automaticity of component stages. *Journal of Experimental Psychology: General*, **107**, 32-63.
- MCCANN, R. S., & JOHNSTON, J. C. (1992). Locus of the single-channel bottleneck in dual-task interference. Journal of Experimental Psychology: Human Perception & Performance, 18, 471-484.
- PASHLER, H. (1994). Dual-task interference in simple tasks: Data and theory. Psychological Bulletin, 116, 220-244.
- POTTER, M. C. (1976). Short-term conceptual memory for pictures. Journal of Experimental Psychology: Human Learning & Memory, 2, 509-522.
- POTTER, M. C. (1993). Very short-term conceptual memory. *Memory & Cognition*, **21**, 156-161.
- POTTER, M. C., CHUN, M. M., BANKS, B. S., & MUCKENHOUPT, M. (in press). Two attentional deficits in serial target search: The visual attentional blink and an amodal task-switch deficit. *Journal of Experimental Psychology: Learning, Memory, & Cognition*.
- RAYMOND, J. E., SHAPIRO, K. L., & ARNELL, K. M. (1992). Temporary suppression of visual processing in an RSVP task: An attentional blink? Journal of Experimental Psychology: Human Perception & Performance, 18, 849-860.
- RAYMOND, J. E., SHAPIRO, K. L., & ARNELL, K. M. (1995). Similarity determines the attentional blink. Journal of Experimental Psychology: Human Perception & Performance, 21, 653-662.
- ROGERS, R. D., & MONSELL, S. (1995). Costs of a predictable switch between simple cognitive tasks. *Journal of Experimental Psychology: General*, 124, 207-231.
- RUTHRUFF, E., MILLER, J., & LACHMANN, T. (1995). Does mental rota-

tion require central mechanisms? Journal of Experimental Psychology: Human Perception & Performance, 21, 552-570.

- SCARBOROUGH, D. L. (1972). Memory for brief visual displays of symbols. Cognitive Psychology, 3, 408-429.
- SHAPIRO, K. L., & RAYMOND, J. E. (1994). Temporal allocation of visual attention: Inhibition or interference? In D. Dagenbach & T. H. Carr (Eds.), *Inhibitory processes in attention, memory, and language* (pp. 151-188). San Diego: Academic Press.
- SHAPIRO, K. L., RAYMOND, J. E., & ARNELL, K. M. (1994). Attention to visual pattern information produces the attentional blink in rapid serial visual presentation. *Journal of Experimental Psychology: Human Perception & Performance*, 20, 357-371.
- VAN SELST, M., & JOLICOEUR, P. (1994a). Can mental rotation occur before the dual-task bottleneck? Journal of Experimental Psychology: Human Perception & Performance, 20, 905-921.
- VAN SELST, M., & JOLICOEUR, P. (1994b). A solution to the effect of sample size on outlier elimination. *Quarterly Journal of Experimen*tal Psychology, 47A, 631-650.
- WARD, R., DUNCAN, J., & SHAPIRO, K. L. (1996). The slow time-course of visual attention. *Cognitive Psychology*, 30,79-100.
- WEICHSELGARTNER, E., & SPERLING, G. (1987). Dynamics of automatic and controlled visual attention. *Science*, 238, 778-780.

WOLFE, J. M. (1994). Guided Search 2.0: A revised model of visual search. *Psychonomic Bulletin & Review*, 1, 202-238.

NOTE

1. The data in each cell are sorted, and the most extreme observation is temporarily excluded from consideration. The mean and standard deviation of the remaining numbers is then computed. Cutoff values are established using the following equations:

$$V_{\text{low}} = \overline{X} - C * SD$$
 $V_{\text{high}} = \overline{X} + C * SD.$

The smallest and largest observation in the cell are then checked against the cutoff values, V_{low} and V_{high} . If one or both are outside the bounds, they are defined as outliers and excluded from further consideration. If an outlier is found, the algorithm is applied anew to the remaining data. The value of *C* depends on the sample size such that the estimated final mean is not influenced by sample size (see Van Selst & Jolicoeur, 1994b).

> (Manuscript received February 26, 1997; revision accepted for publication November 24, 1997.)