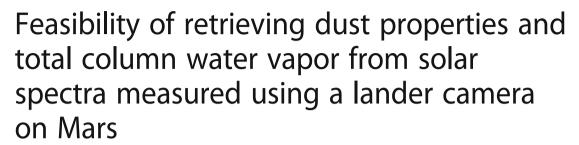
RESEARCH ARTICLE

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Abstract

Dust and water vapor are important constituents in the Martian atmosphere, exerting significant influence on the heat balance of the atmosphere and surface. We have developed a method to retrieve optical and physical properties of Martian dust from spectral intensities of direct and scattered solar radiation to be measured using a multi-wavelength environmental camera onboard a Mars lander. Martian dust is assumed to be composed of silicate-like substrate and hematite-like inclusion, having spheroidal shape with a monomodal gamma size distribution. Error analysis based on simulated data reveals that appropriate combinations of three bands centered at 450, 550, and 675 nm wavelengths and 4 scattering angles of 3°, 10°, 50°, and 120° lead to good retrieval of four dust parameters, namely, aerosol optical depth, effective radius and variance of size distribution, and volume mixing ratio of hematite. Retrieval error increases when some of the observational parameters such as color ratio or aureole are omitted from the retrieval. Also, the capability of retrieving total column water vapor is examined through observations of direct and scattered solar radiation intensities at 925, 935, and 972 nm. The simulation and error analysis presented here will be useful for designing an environmental camera that can elucidate the dust and water vapor properties in a future Mars lander mission.

Keywords: Mars atmosphere, Dust particles, Total column water vapor, Direct solar radiation, Scattered solar radiation, Radiative transfer simulation, Inverse analysis

Introduction

Dust floating in the Martian atmosphere plays an important role in determining the circulation of atmosphere, since dust is an important heat source in the atmosphere due to the absorption of solar radiation (Gierasch and Goody 1972; Moriyama 1975; Smith 2008). Accurate knowledge of the temporal and spatial distribution of dust particles, as well as their optical parameters, is indispensable for understanding their impact on the heat balance of the planet. Also, it is known that a trace amount of water vapor exists in the Martian atmosphere (Fedorova et al. 2009; Smith 2009; Smith, et

al. 2009; Whiteway et al. 2009). The condensation of water vapor leads to the formation of water ice clouds, which can also affect the heat balance of the Martian atmosphere (Flasar and Goody 1976; Haberle et al. 2001; Hinson and Wilson 2004).

Observations of air-borne dust and water vapor in the Martian atmosphere have been performed by Mars orbiters and landers as well as ground-based observations (Smith 2008). As compared with orbiter observations, lander measurements are less likely to be influenced by changes in surface albedo. The dust source is on the surface of Mars, and the concentration of dust is highest near the surface. Thus, compared with orbiters, more accurate measurement can be done from landers. Also, local parameters such as pressure and temperature can be measured precisely from landers. Among the various

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observational methods used so far, the measurements of direct solar radiation (DSR) and scattered solar radiation (SSR) with cameras onboard Mars landers have brought a wealth of information on dust properties. The optical depth of dust can be retrieved as a function of wavelength from DSR measurement, while other optical properties and information on the composition of dust particles can be extracted by coupled analysis of DSR and SSR intensities.

The first observation of dust in the Martian atmosphere was made with the Imaging Camera (Patterson et al. 1977) onboard the Viking Lander (Pollack et al. 1977, 1979, 1995). The optical depth of dust was measured with the Imager for Mars Pathfinder (IMP) experiment (Smith et al. 1997), which revealed seasonal variation similar to the result of the Viking observation, with limited inter-annual variations (Smith and Lemmon 1999; Tomasko et al. 1999; Markiewicz et al. 1999). Subsequently, similar observations were made with Panchromatic Cameras (Pancam, onboard the Spirit and Opportunity rovers) (Bell et al. 2003; Bell et al. 2004a, 2004b; Lemmon et al. 2004), a Surface Stereo Imager (SSI) (onboard the Phoenix) (Lemmon et al. 2008; Moores et al. 2010), and Mastcam (onboard Curiosity) (Malin et al. 2010; Moore et al. 2016). The first observation of water vapor in the Martian atmosphere was carried out with the IMP (Titov et al. 1999), in which 6 spectral bands around 940 nm were employed.

The effective radius ($r_{\rm eff}$) and its variance ($v_{\rm eff}$) are the most important parameters that determine dust's optical behavior. As reviewed by Tomasko et al. (1999), the most plausible values for $r_{\rm eff}$ and $v_{\rm eff}$ from early observations are in a range of 1.2–1.8 µm and 0.2–1.0, respectively. In subsequent missions such as Spirit and Opportunity, the value of $r_{\rm eff}$ was estimated to be ~1.5 µm (with the value of $v_{\rm eff}$ fixed at 0.2). The lidar observation of Phoenix reported values between 1.2 and 1.4 µm (Komguem et al. 2013). The variation in the $r_{\rm eff}$ estimated by several missions may indicate that there are temporal and spatial variations of dust properties. Thus, it is desirable to carry out long-term observations at various locations on the Mars surface to monitor changes in dust properties.

The most dominant composition of Martian dust is considered to be basalt, and its weathering products due presumably to past volcanic activity (Dabrowska et al. 2015). The reflectance spectrum in the wavelength range of 0.3–2.5 μ m suggests that the rock type is most likely palagonites, the partially recrystallized products of basalt-glass influenced by wind erosion (Dlugach et al. 2003). The value of the real part of the refractive index (RI) is ~1.5 at a wavelength of 0.5 μ m, which is close to the value of silicate. The imaginary part, on the other hand, is negligibly small in visible and near-infrared

wavelengths, but its value substantially increases toward the shorter wavelengths, suggesting the contribution of iron oxide components (Dlugach et al. 2003). Thus, it is possible that dust particles contain small amounts of crystalline ferric materials such as goethite, hematite, and/or maghemite.

In this paper, we examine the feasibility of retrieving dust properties and total column water vapor (TCWV) in the Martian atmosphere with a camera system onboard a lander. Such camera observation can be realized by modifying a lander camera system with the addition of optical filters. We develop a dust model in which dust properties are parameterized with a small number of "dust model parameters", including optical depth, effective radius/variance of dust size distribution, volume mixing ratio of hematite, complex RI of silicate, and scale height of dust. Since Martian dust's properties are simpler than those of terrestrial aerosols, we can safely assume a simple dust model. A relatively small number (seven) of dust model parameters are used in this model, which helps to alleviate the underconstrained (ill-posed) nature of the inverse problem. These parameter values are optimized by fitting a small number of "observational parameters" based on DSR and SSR measurements. Only three wavelength bands are utilized for dust observations, which helps keep camera hardware size and data transmission requirements small. Another set of two or three wavelengths around 935 nm is postulated for extracting TCWV from DSR/SSR measurements. We also examine the feasibility of such a camera measurement on the basis of sensor specifications currently available.

Methods/Experimental

Dust model based on non-spherical shape and monomodal size distribution

First, we describe the model used to parameterize the optical and physical properties of Martian dust. Basically, the present model is relevant to the physical conditions of dust particles including their composition, shape, and spatial distribution in the Martian atmosphere. The dust composition can be parameterized with a complex RI that depends on substance and wavelength, λ . From past studies (e.g., Hamilton and Christensen 2005 and references therein), it is plausible that Martian dust is mostly composed of silicates, with small amounts of iron oxides such as hematite. Thus, in the present analysis, we assume a two-component dust model with silicate substrate and hematite inclusion. Similar treatment of a multi-component aerosol was employed in the analysis of the terrestrial atmosphere (Manago and Kuze 2010; Manago et al. 2011). The complex RI value of silicate $(n_0 = m_0 - k_0 i, i$: imaginary unit) can be characterized with $m_0 \sim 1.5$ and $k_0 \ll 1$, representing small absorption of visible light (e.g., Table 1 in Dabrowska et al. 2015, Table 5 in Levoni et al. 1997), while that of hematite is parameterized as $n_A(\lambda) = m(\lambda) - k(\lambda)i$, in which we should consider the large absorbance of blue light. Referring to Querry (1985) for the wavelength dependence of m (λ) and k (λ), the RI of their mixture, n, can be calculated using Maxwell-Garnett theory (Ehlers et al. 2014) as

$$n^{2} = n_{0}^{2} \frac{n_{A}^{2} + 2n_{0}^{2} + 2\rho_{A}(n_{A}^{2} - n_{0}^{2})}{n_{A}^{2} + 2n_{0}^{2} - \rho_{A}(n_{A}^{2} - n_{0}^{2})}.$$
 (1)

Here, ρ_A is the volume mixing ratio of hematite. Figure 1 shows the wavelength dependence of dust RI reported in Wolff et al. (2009). Figure 1 also shows an example of the fitting we did using Eq. (1), resulting in $n_0 = 1.48 - 0.000942i$ ($m_0 = 1.48$ and $k_0 = 0.000942$) for the complex RI of silicate and $\rho_A = 1.77\%$ for the volume mixing ratio of hematite. The agreement between the fitting curves and literature curves is satisfactory when considering the small sensitivity of radiance values to m_0 and k_0 , and the derived values of m_0 and k_0 are consistent with reported values for silicate. The advantage of our dust model is that it can reproduce the important features of measured data in spite of the simplicity of the model, being based on just three parameters, m_0 , k_0 , and ρ_A . We have assumed internal mixing in Fig. 1 as the Maxwell-Garnett theory is applicable to dust particles having internal mixing. Although we tested another model assuming external mixing of silicate and hematite particles, the result exhibited much poorer agreement as compared with internal mixing treatment illustrated in Fig. 1.

Dust particles in the Martian atmosphere can possibly have various shapes, but limited information from direct observations (e.g., Pike et al. 2011) makes it difficult to theoretically formulate their shapes precisely. Moreover, it is difficult to reproduce the effects of non-spherical shapes in a radiative transfer simulation for the Martian atmosphere. To cope with these difficulties, here we propose the use of equivalent volume spheroids with random rotation axes as employed by Dubovik et al.

Table 1 Dust model parameters $(X_1 - X_7)$

Parar	neter (X)	X _a	X_{\min}	$X_{\rm max}$	ΔΧ	$\Delta X/X_{\alpha}$	Reference
$\overline{X_1}$	τ	0.4	0.1	1.0	0.9	2.25	1
X_2	$r_{\rm eff}$	1.6 µm	1.2 µm	2.0 µm	0.8 µm	0.5	2
X_3	$V_{ m eff}$	0.2	0.1	0.4	0.3	1.5	2
X_4	ρ_A	0.03	0	0.05	0.05	1.67	3
X_5	m_0	1.5	1.4	1.6	0.2	0.133	4
X_6	k_0	0.001	0	0.002	0.002	2	4
X_7	Z_{S}	14 km	5 km	20 km	15 km	1.07	5

References (1) Smith and Lemmon 1999; (2) Tomasko et al. 1999; (3) Ehlers et al. 2014; (4) Dabrowska et al. 2015; (5) Hoekzema et al. 2010.

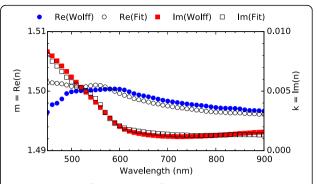


Fig. 1 Complex refractive index of Martian dust plotted against wavelength. Observational results (*filled symbols*) reported by Wolff et al. (2009) are compared with our fitting results (*open symbols*). In this example, the fitting leads to a silicate complex refractive index of $n_0 = 1.48 - 0.000942i$ and a hematite volume mixing ratio of $\rho_A = 1.77\%$

(2006) to estimate the influence of particle shapes for feldspar samples collected from terrestrial soil. Similarly, here we fix the aspect ratio distribution in such a way that the distribution is zero at aspect ratios less than 1.44, and gradually increases in the aspect ratio range between 1.44 and 3. A detailed discussion on the non-spherical shape effect will be given later. In general, when Maxwell-Garnett theory is applied to spheroids, the resulting RIs exhibit dependence on polarization. Such polarization dependence disappears only for the special case of spherical particles. Nevertheless, we assume the polarization-independent form of Eq. (1) for simplicity, though the light scattering calculations are implemented assuming non-spherical dust shapes.

In this research, we assume that the dust size distribution can be expressed with a monomodal gamma distribution including only coarse mode particles (Hansen and Travis 1974; Tomasko et al 1999). This assumption is based on the fact that for the optical properties of desert dust on the Earth, submicron (fine mode) particles can be ignored, and the size distribution can be treated as virtually monomodal, since most of particles are supermicron and in coarse mode (Dubovik et al. 2006). For completeness, the sensitivity of our model to the existence of fine mode particles will be discussed later. A monomodal gamma distribution can be expressed as

$$\frac{\mathrm{d}N}{\mathrm{d}\ln r} = \frac{r^{\xi}}{\left(r_{\mathrm{eff}}\nu_{\mathrm{eff}}\right)^{\xi}\Gamma(\xi)} \exp\left[-\frac{r}{r_{\mathrm{eff}}\nu_{\mathrm{eff}}}\right],\tag{2}$$

with

$$\xi = \frac{1}{\nu_{\text{eff}}} - 2. \tag{3}$$

Here, r is the particle radius and Nis the number of particles. The gamma function (Γ) is used to normalize

the integral of Eq. (2). Parameters $r_{\rm eff}$ and $v_{\rm eff}$ are the effective radius and effective variance, respectively, and they are defined as

$$r_{\text{eff}} = \int_{-\infty}^{\infty} r^3 \frac{dN}{d \ln r} d \ln r / \left[\int_{-\infty}^{\infty} r^2 \frac{dN}{d \ln r} d \ln r \right]$$
 (4)

and

$$\nu_{\text{eff}} = \int_{-\infty}^{\infty} r^2 (r - r_{\text{eff}})^2 \frac{dN}{d \ln r} d \ln r / \left[r_{\text{eff}}^2 \int_{-\infty}^{\infty} r^2 \frac{dN}{d \ln r} d \ln r \right].$$
(5)

Since our observation is made optically, the most relevant parameter is the dust extinction coefficient (α_e), which is governed by the size distribution and extinction cross-section of dust particles. We consider the extinction value at wavelength 550 nm, the peak wavelength of solar radiation. It is assumed that α_e is homogeneous horizontally, and it decreases exponentially with increasing altitude, z:

$$\alpha_e(z) = \frac{\tau}{z_s} \exp\left(-\frac{z}{z_s}\right). \tag{6}$$

Here, τ is the dust optical depth at wavelength 550 nm and z_s is the scale height. The typical scale height of aerosols on the Earth is ~2 km. On the other hand, the scale height of Martian dust is typically 10–15 km (Thomas et al. 1999), which is similar to the scale height of pressure (Hoekzema et al. 2010), since the lower atmosphere is well-mixed on Mars. Besides, the variation range of optical depth of Martian dust is larger than that of terrestrial aerosols: namely, on Mars, typical values of τ are 0.2 (non-dimensional) for relatively clear periods, 1–2 for hot southern summers, and 4–5 during major dust storms (Savijärvi 2014).

In summary, our dust model can be described with only seven parameters: real (m_0) and imaginary (k_0) parts of RI of silicate substrate, volume mixing ratio of hematite inclusion (ρ_A), effective radius ($r_{\rm eff}$) and effective variance ($v_{\rm eff}$) of size distribution, and optical depth (τ) and scale height (z_s) of extinction coefficient at wavelength 550 nm. Hereafter, these model parameters will be collectively denoted as X. Table 1 lists "a priori" (i.e., the most plausible value before observation, X_a), minimum values (X_{\min}) , maximum values (X_{\max}) , and variation ranges ($\Delta X = X_{\text{max}} - X_{\text{min}}$) of the seven parameters utilized in the present model. When evaluating the impact of changes to dust model parameters, it is desirable that the parameters be normalized beforehand so that their variabilities will be on the same scale. Here, we use dust model parameters divided by the variation range (ΔX) listed in Table 1. These normalized dust model parameters will be collectively denoted as x. The 7th column of Table 1 shows the ratio between ΔX and X_a , which will be used in our later analysis.

Radiative transfer simulation of Martian atmosphere

In this research, a radiative transfer simulation code, MODTRAN5 (Berk et al. 2006) is employed to calculate the theoretical spectra of DSR and SSR that would be observed by a Mars lander. Although MODTRAN is a simulation code originally developed for the terrestrial atmosphere, it is applicable to Martian atmosphere by changing parameters such as distance from the Sun and the concentrations of gas components. The main parameters to be configured for Mars are listed in Table 2. The atmosphere between 0 and 100 km is divided into 36 layers of stratified spherical atmosphere, with the assumption of horizontal uniformity. The use of the DIS-ORT algorithm (Stamnes et al. 1988) is desirable for the detailed analysis of SSR in the observation data. In the present simulation study, however, we use Isaacs' two stream algorithm (Isaacs et al. 1987), which is much faster and the resulting differences in SSR values are estimated to be less than 20% (Isaacs et al. 1987). The single scattering algorithm includes spherical geometry of ray transmission, while multiple scattering contributions are calculated using plane parallel geometry (the solar

Table 2 Main parameters of MODTRAN to be configured for Martian atmosphere

Martian auriosphere	
Item	Value
Solar constant	608 W/m ²
Radius of Mars	3396 km
Vertical profile of pressure	Mean value of MCD ^a (7.6 hPa @ground)
Vertical profile of temperature	Mean value of MCD (267 K @ground)
CO ₂ volume mixing ratio	95.32%
O ₂ volume mixing ratio	0.13%
O ₃ volume mixing ratio	30 ppb
H ₂ O volume mixing ratio	300 ppm (<10 km), 0 (>10 km)
Volume mixing ratio of other gases	0
Vertical profile of dust extinction coefficient	Calculated from the dust model
Wavelength dependence of dust extinction	Calculated from the dust model
Wavelength dependence of dust absorption	Calculated from the dust model
Wavelength/scattering angle dependence of dust phase function	Calculated from the dust model
Surface albedo	Desert model (0.21@450 nm, 0.34@675 nm)

^aMCD stands for the Mars Climate Database (Millour et al. 2012)

illumination impinging upon each atmospheric level is determined with spherical refractive geometry). The extinction/absorption coefficients and phase function are calculated from the dust model by using a Fortran program developed by Dubovik et al. (2006); this software calculates optical parameters of spheroidal aerosols by using a look-up table prepared by coupling the T-matrix (Mishchenko and Travis 1998) and approximate geometric-optics integral-equation (Yang and Liou 1996) methods.

Observational parameters for dust retrieval

Spectral irradiance/radiance of DSR/SSR in the visible and near infrared spectral regions is to be measured with an environmental monitor camera onboard a Mars lander. Radiance values of SSR are measured at particular scattering angles (χ); the angle between the original solar ray (hitting the scattering particle) and the line of sight (LOS) from the particle to the observer). Here χ = 0 corresponds to scattering in the forward direction. The expressions DSR(λ) and SSR(λ , χ) can be used to explicitly specify wavelength or scattering angle. To reduce the total volume of data that must be transmitted during the Mars observation mission, it is vitally important to minimize the number of quantities to be measured (i.e., the number of wavelengths and scattering angles) when designing an observation strategy.

Figure 2 summarizes the results of MODTRAN simulation, showing how the values of DSR/SSR depend on wavelength and scattering angle for various values of dust parameters (τ , r_{eff} , v_{eff} , ρ_A , m_0 , k_0 , and z_s). In Fig. 2a, b, DSR/SSR values are plotted for dust optical depths (τ) between 0.1 and 1. At all wavelengths between 400 and 900 nm, decrease in DSR and increase in SSR are observed with increasing τ . Among the seven dust model parameters, DSR shows almost no dependence on parameters other than τ , whereas SSR changes with τ , $r_{\rm eff}$, $v_{\rm eff}$, ρ_A , m_0 , and k_0 (Fig. 2b–g). Figure 2c shows that the SSR intensity of forward scattering ($\chi = 3^{\circ}$) increases at all wavelengths with increasing $r_{\rm eff}$, while Fig. 2d shows that the forward scattering intensity decreases over the absorption band of hematite (blue range around 450 nm) with increasing $v_{\rm eff}$.

Moreover, Fig. 2e, f shows that the SSR intensity of backward scattering ($\chi=120^\circ$) decreases over the hematite absorption band with increasing ρ_A and increasing m_0 , while Fig. 2g shows that the backward scattering intensity decreases at all wavelengths with increasing k_0 . This is due to the fact that absorption is stronger at larger scattering angles due to longer effective path length. As seen from Fig. 2h, SSR is hardly affected by z_s , the dust scale height in the Martian atmosphere.

Thus, in order to derive all the necessary dust information while minimizing redundancy, we selected the wavelengths and scattering angles listed in Table 3. The wavelength band width is chosen to be 10 nm. The measurements of DSR spectra are made at the three wavelengths of $(\lambda_0, \lambda_B, \lambda_R) = (550, 450, 675)$ (in nm), while SSR spectra are measured at the two wavelengths of (λ_B) λ_R) for the four scattering angles $(\chi_0, \chi_A, \chi_B, \chi_B) = (10^\circ, 3^\circ, 3^\circ, 10^\circ)$ 50°, 120°). As a result, 11 values are measured as listed in Table 4. The reason for the choices of $\lambda_B = 450$ nm within the hematite absorption band and $\lambda_R = 675$ nm outside the band is that these wavelengths are close to the peak wavelength of SSR radiance (~550 nm) with reasonable sensitivity of a silicon sensor. As shown in Fig. 3, the measurement of SSR is carried out on the almucantar plane ($\theta_{los} = \theta_{sun}$), where LOS zenith angle (θ_{los}) is the same as the solar zenith angle (θ_{sun}) . When $\chi > 2\theta_{\text{sun}}$, on the other hand, SSR is measured on the principal plane ($\theta_{los} = \chi - \theta_{sun}$, $\phi_{los} = \phi_{sun} + 180^{\circ}$), where LOS azimuth angle (ϕ_{los}) is on the opposite side of the solar azimuth direction (ϕ_{sun}).

So far, we have considered how to choose the minimal set of quantities to be measured that satisfies the necessary and sufficient conditions for estimating the dust model parameters. Additionally, we have to avoid the influence of measurement error as far as possible. For this purpose, the use of relative values of spectral irradiance/radiance, instead of their absolute values, is advantageous for improving the accuracy of the resulting dust parameters, since precise calibration of a lander camera is difficult and the relative values are less sensitive to calibration errors than absolute values. Therefore, in this research, we calculated the appropriate ratios among the 11 measured quantities listed in Table 4, and we propose the final observational parameter set as listed in Table 5. In the second column of this table, the capital letters, D, A, F, and B indicate direct solar radiation, aureole (i.e., scattered solar radiation in close vicinity to the Sun), forward scattering, and backward scattering, respectively, and the subscripts 0, C, B, and R indicate values at the reference wavelength (550 nm), color ratio (i.e., intensity ratio of blue to red), values at the blue wavelength (450 nm), and values at the red wavelength (675 nm), respectively.

Hereafter, raw values of measured quantities and observational parameters will be written in upper-case letters as P and Y, respectively. As in the case of the dust model parameters, we use normalized values of P and Y in order to evaluate their sensitivities. Since relative errors of spectral measurements are expected to be comparable with each other, we use measured quantities divided by the values calculated with a priori model parameters. These normalized measured

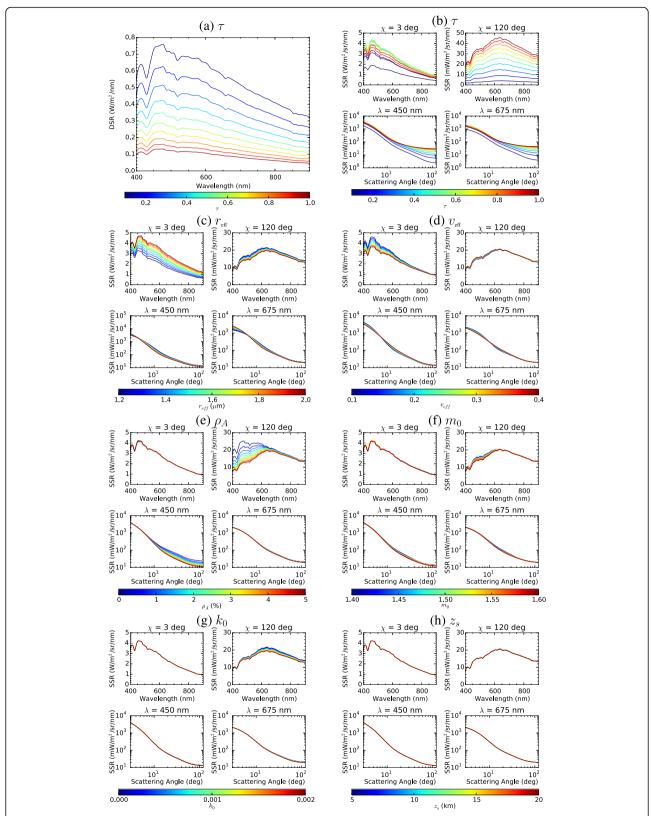


Fig. 2 Sensitivity of (a) DSR and (b-h) SSR to dust model parameters. DSR and SSR intensities for various values of dust model parameters (a: τ , b: τ , c: r_{eff} , d: v_{eff} , e: v_{eff} , v_{eff} , e: v_{eff} , $v_{$

Parameter		Description	Value	DSR	SSR
Wavelength	λο	Reference wavelength	550 nm	✓	
	λ_{B}	Inside absorption band of hematite	450 nm	✓	✓
	λ_R	Outside absorption band of hematite	675 nm	✓	✓
Scattering angle	Χo	Reference scattering angle	10°		✓
	XA	Aureole scattering angle	3°		✓
	XF	Forward scattering angle	50°		✓
	XΒ	Backward scattering angle	120°		✓

Table 3 Wavelengths and scattering angles chosen for dust observation

quantities will be denoted in lower-case letters as p, and observational parameters calculated with the normalized measured quantities will be denoted as y.

Observational parameters for water vapor retrieval

Water vapor absorption bands are located inside the sensitive range (350-1000 nm) of conventional complementary metal-oxide semiconductor (CMOS) sensors to be employed for our environmental monitor camera. By measuring the absorbance in DSR or SSR spectra, we can measure TCWV (c_w) through the Martian atmosphere, where the water vapor concentration is very limited (~300 ppm). Among the nearinfrared absorption bands, it would be reasonable to employ the strongest absorption band around 930-970 nm. Here, we assume the atmospheric model parameters listed in Table 2, and we calculate the value of c_w by assuming that the volume mixing ratio (VMR) of water vapor is constant below 10 km. The a priori value of c_w is 1.43 mg/cm² for a water vapor VMR of 300 ppm. Figure 4 shows transmittance spectra simulated at a solar zenith angle (SZA) of 80° while changing the water vapor VMR as 100, 300, and 500 ppm.

In this study, we calculate values of c_w from the ratio of DSR or SSR at wavelengths inside and outside the water vapor absorption band. Here, we consider the wavelengths and the scattering angles listed in Table 6. The wavelength band width is chosen to be 5 nm. Since the effective optical path length is larger

Table 4 Measured quantities (P_1 – P_{11}) of DSR and SSR for dust retrieval

Parameter (P)	Measured quantity	Parameter (P)	Measured quantity
P_1	$DSR(\lambda_0)$	P ₇	$SSR(\lambda_B, \chi_B)$
P_2	$DSR(\lambda_B)$	P_8	$SSR(\lambda_R, \chi_0)$
P_3	$DSR(\lambda_R)$	P ₉	$SSR(\lambda_R, \chi_A)$
P_4	$SSR(\lambda_B, \chi_0)$	P ₁₀	$SSR(\lambda_R, \chi_F)$
P_5	$SSR(\lambda_B, \chi_A)$	P_{11}	$SSR(\lambda_R, \chi_B)$
P_6	$SSR(\lambda_B, \chi_F)$		

at larger scattering angles, the line-of-sight directions of $\theta_{\rm los}$ = 85° and $\phi_{\rm los}$ = $\phi_{\rm sun}$ + 180° have been chosen for the SSR measurements.

The measured quantities $(P_{12}-P_{17})$ are listed in Table 7, and they are appropriately combined to define the observational parameters as listed in Table 8. When only two wavelengths are available, the outside wavelength should be chosen to be $\lambda_S = 925$ nm,

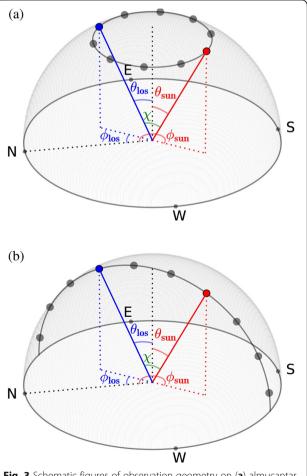


Fig. 3 Schematic figures of observation geometry on (a) almucantar plane and (b) principle plane

Table 5 Observational	parameters $(Y_1 - Y_{11})$	used for dust
retrieval		

Tetrieval					
Parameter (Y)		Relationship	Relationship with measured quantities		
<i>Y</i> ₁	D_0	P_1	$DSR(\lambda_0)$		
Y_2	D_C	P_2/P_3	$DSR(\lambda_B)/DSR(\lambda_R)$		
Y_3	A_C	P ₅ /P ₉	$SSR(\lambda_B, \chi_A)/SSR(\lambda_R, \chi_A)$		
Y_4	A_B	P_{5}/P_{4}	$SSR(\lambda_B, \chi_A)/SSR(\lambda_B, \chi_O)$		
Y_5	A_R	P_9/P_8	$SSR(\lambda_R, \chi_A)/SSR(\lambda_R, \chi_0)$		
Y_6	F_C	P_6/P_{10}	$SSR(\lambda_B, \chi_F)/SSR(\lambda_R, \chi_F)$		
Y_7	F_B	P_{6}/P_{4}	$SSR(\lambda_B, \chi_F)/SSR(\lambda_B, \chi_0)$		
Y_8	F_R	P_{10}/P_{8}	$SSR(\lambda_R, \chi_F)/SSR(\lambda_R, \chi_0)$		
Y_9	B_C	P_7/P_{11}	$SSR(\lambda_B, \chi_B)/SSR(\lambda_R, \chi_B)$		
Y ₁₀	B_B	P_{7}/P_{4}	$SSR(\lambda_B, \chi_B)/SSR(\lambda_B, \chi_0)$		
Y ₁₁	B_R	P_{11}/P_{8}	$SSR(\lambda_R, \chi_B)/SSR(\lambda_R, \chi_O)$		

which is closer to $\lambda_W = 935$ nm. Then, c_w is optimized by matching the calculated ratio of $D_2 = DSR(\lambda_W)/$ $DSR(\lambda_S)$ or similar ratio of SSR (S_2) to the measured one. Alternatively, when three wavelengths are available, non-absorptive wavelengths are chosen at wavelengths shorter ($\lambda_S = 925$ nm) and longer ($\lambda_L =$ 972 nm) than the absorption band. By linear interpolation, a reference intensity at λ_W (DSR₀(λ_W) $= [(\lambda_L - \lambda_W) DSR(\lambda_S) + (\lambda_W - \lambda_S) DSR(\lambda_L)] / (\lambda_L - \lambda_S)$ similar value for SSR) can be obtained that is free of water vapor absorption. Then, c_w is found by matching the calculated ratio $D_3 = DSR(\lambda_W)/DSR_0(\lambda_W)$ or a similar one for SSR (S_3) to the measured ratio. Using three wavelengths, more precise estimation of water vapor absorption is possible with better knowledge of the spectral intensity covering the entire range around the absorption band.

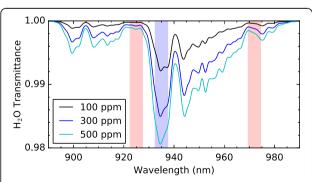


Fig. 4 Transmittance of water vapor in the Martian atmosphere. Values are simulated with a wavelength resolution of 2 nm (FWHM) for volume concentrations of 100, 300, and 500 ppm. The *blue band* indicates the wavelength band around the absorption peak centered at 935 nm with a band width of 5 nm, and the *two red bands* indicate the wavelength band outside the absorption band centered at 935 and 972 nm with a band width of 5 nm

Retrieval of model parameters

We consider the optimization of model parameters (including both dust model parameters and TCWV) through a least squares analysis. We assume a form of

$$\mathbf{y} = \mathbf{F}(\mathbf{x}) + \mathbf{\varepsilon}_{\mathbf{y}},\tag{7}$$

where x and y are vectors composed of the normalized values of model parameters and observational parameters, respectively, F(x) is a forward model function, and ε_y is measurement noise. The Taylor series expansion of Eq. (7) around the a priori value x_a leads to the linear approximation given as

$$y = F(x_a) + K_x(x - x_a) + \varepsilon_y. \tag{8}$$

Here, $K_x = \partial(x)/\partial x$ is the Jacobian matrix. If we ignore measurement noise, Eq. (8) can be solved using a pseudo-inverse matrix of K_x . In reality, however, measurement noise is not negligibly small. In order to avoid the instability of the solution due to a lack of sufficient information from the observation, we consider the following cost function that includes the residuals of both the observational and model parameters:

$$c(\mathbf{x}) = (\mathbf{y} - \mathbf{F}(\mathbf{x}))^{\mathrm{T}} \mathbf{S}_{y}^{-1} (\mathbf{y} - \mathbf{F}(\mathbf{x})) + (\mathbf{x} - \mathbf{x}_{a})^{\mathrm{T}} \mathbf{S}_{a}^{-1} (\mathbf{x} - \mathbf{x}_{a}).$$
(9)

Here, S_y and S_a are the variance-covariance matrices of the observational parameters and a priori of the model parameters, respectively. The (i, j) element of S_y is the covariance of y_i and y_j , which is $\langle (y_i - \langle y_i \rangle)(y_j - \langle y_j \rangle) \rangle$, where $\langle y_i \rangle$ stands for the expectation value of y_i $(1 \le i \le 11$, see Table 5 for the case of dust retrieval). The i-th diagonal element of S_y represents the variance of y_i , i.e. $\langle (y_i - \langle y_i \rangle)^2 \rangle$. Similarly, the off-diagonal and diagonal elements of S_a represent the covariance and variance of a priori, respectively. We optimize the model parameters by minimizing the cost function with iterative calculation based on the non-linear least square method (Rodgers, 2000).

Linear approximation for error estimation

In the following discussion on the retrieval error, for simplicity, we use a linear approximation (the Jacobian is calculated with the a priori). The expectation value (retrieved solution, x_r) of the model parameters can be given as

$$\boldsymbol{x}_r = \boldsymbol{x}_a + \left(\boldsymbol{K}_x^{\mathrm{T}} \boldsymbol{S}_y^{-1} \boldsymbol{K}_x + \boldsymbol{S}_a^{-1}\right)^{-1} \boldsymbol{K}_x^{\mathrm{T}} \boldsymbol{S}_y^{-1} (\boldsymbol{y} - \boldsymbol{F}(\boldsymbol{x}_a)).$$
(10)

Here, we have assumed that the errors of observational and model parameters follow Gaussian distributions.

Table 6 Wavelengths and a scattering angle chosen for TCWV measurement

Parameter		Description	Value
Wavelength	λ_W	Peak wavelength of water vapor absorption	935 nm
	λ_S	Shorter wavelength outside absorption band of water vapor	925 nm
	λ_L	Longer wavelength outside absorption band of water vapor	972 nm
Scattering angle	Xw	Scattering angle for TCWV measurement	$85^{\circ} + \theta_{sun}$

Defining a gain matrix as $G_y = \partial x_r / \partial y = (K_x^T S_y^{-1} K_x + S_a^{-1})^{-1} K_x^T S_y^{-1}$, we can rewrite Eq. (10) as

$$\mathbf{x}_r = \mathbf{x}_a + \mathbf{G}_{\nu}(\mathbf{y} - \mathbf{F}(\mathbf{x}_a)). \tag{11}$$

Furthermore, using $A = \partial x_r / \partial y = G_y K_x = (K_x^T S_y^{-1} K_x + S_a^{-1})^{-1} K_x^T S_y^{-1} K_x$ and $G_a = \partial x_r / \partial x_a = (I_n - A) = (K_x^T S_y^{-1} K_x + S_a^{-1})^{-1} S_a^{-1}$, we can rewrite Eq. (11) as

$$\mathbf{x}_r = A\mathbf{x} + \mathbf{G}_a\mathbf{x}_a. \tag{12}$$

In Eq. (12), the right-hand side can be regarded as a weighted mean of the model parameter obtained from the true state (x) and the a priori (x_a) , with weights of $K_x^T S_y^{-1} K_x$ and S_a^{-1} , respectively. Here, A is a matrix called the averaging kernel matrix (AKM), its diagonal elements indicating the extent to which the true model parameters affect the retrieved solution.

Adjustment of regularization strength

The weight of the a priori is determined by the balance between S_y and S_a . From a statistical point of view, the optimum value of S_a would be the actual variance-covariance matrix of a priori (S_e) . However, it is difficult to estimate S_e accurately. In some cases, better solutions can be obtained by using S_a that are different from S_e and adjusting the strength of regularization (i.e., constraint from the a priori data). Here, we introduce a regularization parameter γ as

$$S_{a^{-1}} = \gamma S_e^{-1}. \tag{13}$$

The regularization strength is increased by increasing the value of γ . When we increase the regularization parameter, at some point the weight on the a priori becomes non-negligible and the retrieved parameter tends to be drawn toward its a priori value. This results in a gradual increase in the residuals of the observational parameters, since in general, a priori values are different from true values. In accordance with Tikhonov

Table 7 Measured quantities (P_{12} – P_{17}) of DSR and SSR for TCWV retrieval

Parameter (P)	Measured quantity	Parameter (P)	Measured quantity
P ₁₂	$DSR(\lambda_W)$	P ₁₅	SSR(λ _w , χ _w)
P ₁₃	$DSR(\lambda_S)$	P ₁₆	$SSR(\lambda_S, \chi_W)$
P ₁₄	$DSR(\lambda_L)$	P ₁₇	$SSR(\lambda_L, \chi_W)$

regularization (Doicu et al. 2010), a good regularization strength is achieved by making it stronger within the range in which the residuals of observational parameters, i.e., the first term of the cost function (9), are almost constant.

Error estimation of model parameters

First, we consider the errors in the retrieved model parameters propagated from both measured values and a priori values. A variance-covariance matrix of the model parameters due to propagation error of measurement (S_m) can be calculated as

$$S_m = G_{\nu} S_{\nu} G_{\nu}^{\mathrm{T}}. \tag{14}$$

Similarly, a variance-covariance matrix of model parameters due to a priori error (S_s) can be obtained using $G_a = I_n - A$ as

$$\mathbf{S}_{s} = \mathbf{G}_{a} \mathbf{S}_{e} \mathbf{G}_{a}^{\mathrm{T}}.\tag{15}$$

The combined variance-covariance matrix of model parameters including both measurement error and a priori error is given as

$$S_c = S_m + S_s. (16)$$

The equation $S_c = (K_x^T S_y^{-1} K_x + S_a^{-1})^{-1}$ holds when $\gamma = 1$. If we define error ratio ε_r as

$$\boldsymbol{\varepsilon}_{r} = \left[\operatorname{diag}(\boldsymbol{S}_{s}\boldsymbol{S}_{c}^{-1})\right]^{1/2}$$

$$= \left[\operatorname{diag}(\boldsymbol{G}_{a}\boldsymbol{\gamma}(\boldsymbol{A} + \boldsymbol{G}_{a}\boldsymbol{\gamma})^{-1})\right]^{1/2}, \tag{17}$$

then we have $\mathbf{\varepsilon}_r = [\operatorname{diag}(\mathbf{G}_a)]^{1/2}$ when $\gamma = 1$. Each element of $\mathbf{\varepsilon}_r$ changes from 0 to 1 when γ changes from 0 to ∞ . In addition to the propagation errors described above, imperfectness of the forward model can cause systematic errors. Systematic errors of retrieved model parameters ($\mathbf{\varepsilon}_x$) due to estimation errors of the forward model in the observational parameters ($\mathbf{\varepsilon}_f$) can be estimated as

$$\boldsymbol{\varepsilon}_{x} = \boldsymbol{G}_{y} \boldsymbol{\varepsilon}_{f}. \tag{18}$$

Results and discussion

Sensitivity analysis of observational parameters

In order to examine the sensitivity of observational parameters (Y in Table 5) to the dust model parameters (X in Table 1), we changed the values of X from the

Table 8 Observational parameters $(Y_{12}-Y_{15})$ for TCWV retrieval

Parameter (Y)		Relationship with measured qu	uantities
Y ₁₂	D_2	P ₁₂ /P ₁₃	$DSR(\lambda_W)/DSR(\lambda_S)$
Y ₁₃	S_2	P_{15}/P_{16}	$SSR(\lambda_W, \chi_W)/SSR(\lambda_S, \chi_W)$
Y ₁₄	D_3	$P_{12}/[\alpha P_{13} + \beta P_{14}]$	$DSR(\lambda_W)/[\alpha DSR(\lambda_S) + \beta DSR(\lambda_L)]$
Y ₁₅	S ₃	$P_{15}/[\alpha P_{16} + \beta P_{17}]$	$SSR(\lambda_W,\chi_W)/[\ aSSR(\lambda_S,\chi_W) + \betaSSR(\lambda_L,\chi_W)]$

 $\alpha = (\lambda_1 - \lambda_W)/(\lambda_1 - \lambda_S), \beta = (\lambda_W - \lambda_S)/(\lambda_1 - \lambda_S)$

minimum to the maximum (see Table 1) and calculated the variation range of Y. Only one dust model parameter was changed at a time, with other parameters fixed to their a priori values. The results of this sensitivity analysis are summarized in Fig. 5a–n.

Figure 5a–g shows the results for normalized observational parameters (y) obtained with the SZA fixed at 60°, which is a typical value as indicated in the results shown below. The scales of the vertical axes are the same for these panels except for Fig. 5a. Figure 5a–g indicates that the present choice of observational parameters has led to reasonably large sensitivity (more than 30% of observational parameters calculated with the a priori) to τ , $r_{\rm eff}$, $v_{\rm eff}$, and ρ_A , relatively small sensitivity to m_0 and k_0 , and much less sensitivity to z_s . In Fig. 5a–d, most of the resulting curves show linear (or nearly linear) responses, though some non-linear features are seen as in the case of D_0 vs. τ in Fig. 5a.

In Fig. 5h–n, the results for variation range (Δy) are plotted as functions of SZA. Here, Δy stands for the maximum minus the minimum value ($\Delta y > 0$) if the observational parameter increases with increasing model parameter, otherwise the minimum minus the maximum $(\Delta y < 0)$. For instance, $\Delta D_0(\tau)$ in Fig. 5h shows the SZA dependence of the difference between the minimum D_0 and maximum D_0 when τ is changed between 0.1 and 1, as indicated in Fig. 5a (for $SZA = 60^{\circ}$). Such graphs are useful for estimating how the sensitivity changes with the time of DSR/SSR observations. Although in most cases no dependence on SZA can be seen, in some cases such as D_0 vs. τ , a certain increase in variation (sensitivity) is found with increasing SZA. This is ascribable to the longer path of DSR in the dust layer under large SZA conditions, namely, at dusk and dawn.

For better retrieval of each model parameter, it is required for an observational parameter to have a large sensitivity to that model parameter. It is also desirable that it exhibit sensitivity solely to that specific model parameter, not being affected by other model parameters. For example, $D_0 = \mathrm{DSR}(\lambda_0)$ has sensitivity solely to τ ; thus, the aerosol optical depth, τ , is well retrieved from the DSR measurement. Similarly, the dust effective radius, r_{eff} can be retrieved from $A_R = \mathrm{SSR}(\lambda_R, \chi_A)/\mathrm{SSR}(\lambda_R, \chi_0)$, the hematite volume mixing ratio, ρ_A , from $F_C = \mathrm{SSR}(\lambda_B, \chi_F)/\mathrm{SSR}(\lambda_R, \chi_F)$, and if r_{eff} and ρ_A are

already known, the width parameter of size distribution, $v_{\rm eff}$, can be obtained from $A_B = {\rm SSR}(\lambda_B, \chi_{\rm A})/{\rm SSR}(\lambda_B, \chi_0)$. Therefore, the combination of observational parameters listed in Table 4 can provide information sufficient for retrieving τ , $r_{\rm eff}$, ρ_A , and $v_{\rm eff}$. Although only limited information on dust scale height (z_s) can be obtained from our retrieval, it is necessary to include z_s in our retrieval procedure so as to examine the influence of z_s on the retrieval of other dust model parameters. A detailed discussion on the information content of each dust model parameter will be given later.

Error estimation for dust measurement

In the following discussion, for simplicity, it is assumed that all measured quantities (P in Table 4) have the same relative error, and the propagation errors of observational parameters (Y in Table 5) are estimated by giving a reasonably small relative error of 1%. Since random noise is considered in the measured quantities, the variance-covariance matrix of measured quantities (S_n) is assumed to be diagonal. Errors in the normalized measured quantities (p) propagate to the normalized observational parameters (y) according to the Jacobian matrix $K_p = \partial y/\partial p$ and the variance-covariance matrix can be calculated as $S_v = K_p S_p K_p^T$. Although this matrix can be non-diagonal, we retain only the diagonal elements. If non-diagonal elements are included, the determinant becomes zero (and hence, S_v^{-1} cannot be calculated), since we have assumed the same relative errors (1%) of measured quantities. The uncertainties of the dust model parameters are not yet precisely known. Thus, we assume the standard deviations to be half of the variation range in Table 1, and the variancecovariance matrix S_e is constructed by considering diagonal elements only (i.e., $[\operatorname{diag}(S_e)]^{1/2} = \Delta x/2$).

The relation between the regularization parameter (γ) of dust model parameters and the diagonal elements of AKM is plotted in Fig. 6. The averaging kernel close to 1.0 corresponds to the case that the model parameter is mostly determined by the observed DSR/SSR data while the averaging kernel being close to 0.0 is the case of the model parameter being mainly determined by the a priori data. Since observational parameters have large sensitivity to the four dust model parameters (τ , $r_{\rm eff}$, $v_{\rm eff}$, and ρ_A), the residuals of observational parameters

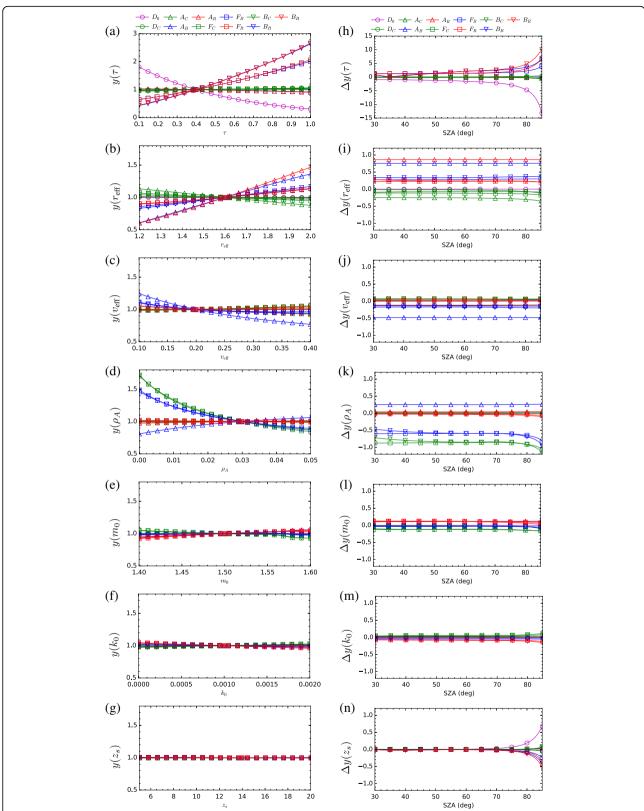


Fig. 5 Sensitivity of observational parameters to dust model parameters. Parameters y and Δy represent the normalized observational parameter, and the difference between the maximum and minimum values of y when the dust model parameter is changed from its minimum to maximum value, respectively. See Table 5 for the definitions of D_0 , D_C , Panels (a) - (g) show the relation between $y(X_i)$ and X_i for $X_1 - X_7$, respectively, and panels (h) - (n) show that between $\Delta y(X_i)$ and SZA for $X_1 - X_7$, respectively

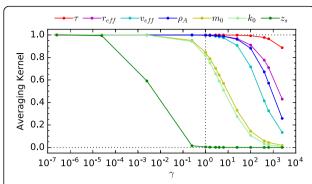


Fig. 6 Relation between regularization parameter (γ) of dust model parameters and diagonal elements of AKM. This graph shows an increased importance of a priori parameters for increasing γ . An SZA of 60° has been assumed for this calculation

increase when γ increases in the range of $\gamma > 1$. Although a matrix form of γ can potentially be adopted so as to enable the separate adjustment of regularization strength for each dust model parameter, here, we use the same regularization parameter of $\gamma = 1$ for all dust model parameters for the sake of simplicity. When $\gamma = 1$, z_s is almost confined to its a priori value (14 km).

Consideration on cases with insufficient data availability

In the actual lander mission, there might be cases in which DSR/SSR cannot be observed at some specific scattering angles or accurate color ratios cannot be obtained due to reasons such as the limited dynamic range of the sensor, bad observation conditions, difficulty in calibration, etc. In view of such possibilities, here, we estimate propagation errors for the following six cases: case 1. Full utilization of all observational parameters; case 2. DSRs (D_0, D_C) are not available; case 3. Aureoles (A_C, A_B, A_R) are not available; case 4. Forward scattering values (F_C, F_B, F_R) are not available; case 5. Backward scattering values (B_C, B_B, B_R) are not available; and case 6. Color ratios (D_C, A_C, F_C, B_C) are not available.

First, the diagonal elements of AKM for these six cases are shown in Fig. 7 (left scale). In case 1, the averaging kernels of τ , $r_{\rm eff}$, $v_{\rm eff}$, and ρ_A are almost in unity and those of m_0 and k_0 are about 0.8. Thus, observation information is well reflected in the retrieved values of these dust model parameters. On the other hand, the averaging kernels of z_s are much smaller and nearly zero at SZA > 55°, which means that z_s is almost confined to its a priori value. In other cases, averaging kernels are smaller as compared with case 1 and dependence on a priori is larger especially in cases 3 and 6.

Combined propagation errors of the dust model parameters ($E_c = [\operatorname{diag}(S_c)]^{1/2}$) are shown in Fig. 8. For

the evaluation of retrieval errors, errors relative to the a priori values are intuitively more understandable than those relative to the variation range, and hence, here errors are expressed as values relative to both variation ranges (ΔX) and a priori values (X_a). Errors relative to a priori values are obtained from errors relative to variation range multiplied by $\Delta X/X_a$ in Table 1. The left and right scales of Fig. 8 are normalized so that $\Delta x = 1$ and $x_a = 1$, respectively. In case 1, the combined propagation errors normalized with Δx (normalized with x_a) are as follows; τ : 0.5–2% (1– 4%), r_{eff} : 3% (2%), v_{eff} : 4% (5%), and ρ_A : 2–3% (4–6%). Compared with case 1, the total propagation errors are larger especially in the following cases; τ : case 2, $r_{\rm eff}$: cases 3 and 6, $v_{\rm eff}$: case 3, and ρ_A : cases 2, 3, and 6. As for m_0 and k_0 , the combined propagation errors of both parameters in case 1 are about 20% of Δx , which is 3 and 40% of x_a for m_0 and k_0 , respectively. The errors of m_0 and k_0 are larger especially in case 3 (without aureole) and case 6 (without color ratio). The combined propagation error of z_s is close to the a priori error $(\Delta x/2)$ since z_s is almost confined to its a priori value. The percentage of a priori error in the combined propagation error is larger if the error ratio shown in Fig. 8 (right scale) is larger. The above propagation errors have been estimated with a relative measurement error of 1%, and it is expected that the propagation error is proportional to the measurement error if it is sufficiently small. Note, however, that the percentage of a priori error changes if the weight ratio of $K_x^T S_y^{-1} K_x$ and S_a^{-1} changes.

Once a retrieval error occurs in a dust model parameter, it may propagate to the other model parameters. This effect becomes significant if the non-diagonal elements of AKM are not negligible. The non-diagonal elements of AKM in the above six cases are shown in Fig. 9. Since we have assumed that all of the diagonal elements of S_a are the same (i.e., $\left[\operatorname{diag}(S_a)\right]^{1/2} = \Delta x/2$), AKM $(A_{ij} = \partial x_{r,i}/\partial x_j)$ is symmetric and we show only elements which satisfy i > j and $A_{ij} > 0.02$ at one of the considered SZAs. We can see that m_0 and k_0 $(x_i.k_0, x: m_0)$ are easily influenced by each other (especially in case 6). Also, in case 3, the correlation becomes larger between m_0 and size distribution parameters $(r_{\rm eff}$ and $v_{\rm eff})$.

Non-spherical dust shape

Previous studies on terrestrial aerosols have shown that the differences in the shapes of coarse mode particles play an important role in the spectra of DSR and SSR, since scattering patterns are dependent on the spherical (hygroscopic) or non-spherical (such as desert dust) shapes of aerosol particles. Dubovik et al. (2006) reported that the light scattering properties of desert dust aerosols in the terrestrial atmosphere can

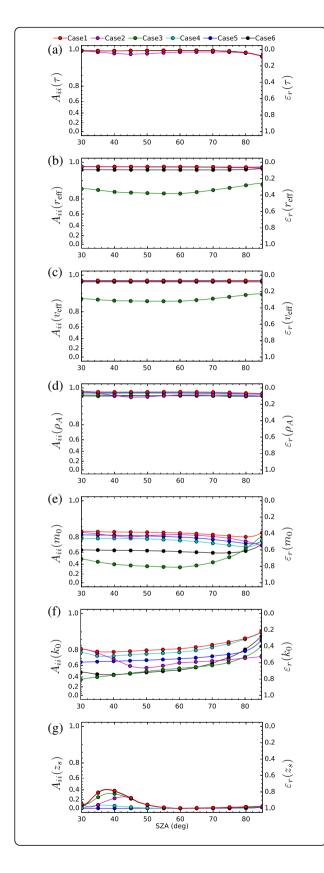


Fig. 7 Diagonal elements of AKM and error ratio of dust model parameters. The left and right scales are for AKM and error ratio, respectively. Case 1, with all observation parameters listed in Table 5; case 2, without DSR; case 3, without aureole; case 4, without forward scattering; case 5 without backward scattering; and case 6, without color ratio. Averaging kernel closer to unity means that information from observations is more significant. Panels (**a**) - (**g**) show the relation between $A_{ij} / \varepsilon_{C,i}$ and SZA for $X_1 - X_7$, respectively

be modeled by considering a mixture of spherical and non-spherical aerosol types. For non-spherical particles, their aspect ratio distribution was estimated from a feldspar sample (Dubovik et al. 2006). Following their treatment, we assume in the present analysis that the optical properties of Martian dust can be modeled by adjusting the volume mixing ratio (ρ_N) of non-spherical particles to spherical particles. Variation ranges for all the observational parameters listed in Table 5 are examined by changing the value of ρ_N between 0 and 1. The results are plotted in Fig. 10a as functions of SZA. Among the 11 observational parameters, $A_B = SSR(\lambda_B, \chi_A)/SSR(\lambda_B, \chi_0)$ exhibits the largest sensitivity to ρ_N ($\Delta y(\rho_N) = 0.15$). Relatively large dependence on SZA is seen for parameters related to backscattering (B_R , B_C , and B_B). Figure 10b shows the systematic errors of retrieved dust model parameters when the wrong assumption of $\rho_N = 0$ (spherical) is adopted to analyze the observational data of dust particles that are totally non-spherical $(\rho_N = 1)$. The parameters except v_{eff} and k_0 have small systematic errors (less than 15%). The parameters $v_{\rm eff}$ and k_0 show errors as large as 25 and 80% of their variation ranges (~40% and 160% of their a priori values), respectively. Thus, it is desirable to take the non-sphericity of dust particles into account in the retrieval of dust model parameters as with our dust model.

Bimodal size distribution

We have so far assumed a monomodal size distribution based on coarse mode dust particles. From the simultaneous observation in the ultraviolet and infrared ranges by SPICAM on Mars Express, however, Fedorova et al. (2014) reported the existence of fine mode (radius 0.04– 0.07 µm) as well as coarse mode (average radius 0.7 µm) particles in the higher altitudes, ranging between 10 and 80 km. Therefore, in this part, we examine the influence of additional fine mode particles in our model calculation. In order to reduce the number of dust model parameters, we assume that the complex RI of the fine mode is the same as that of the coarse mode particles. For the coarse mode, we employ the gamma distribution of Eq. (2) with $r_{\rm eff} = 1.6 \ \mu \rm m$ and $v_{\rm eff} = 0.2$ as before. For the fine mode, we follow the model given by Fedorova et al. (2014), namely, a log-normal distribution with effective

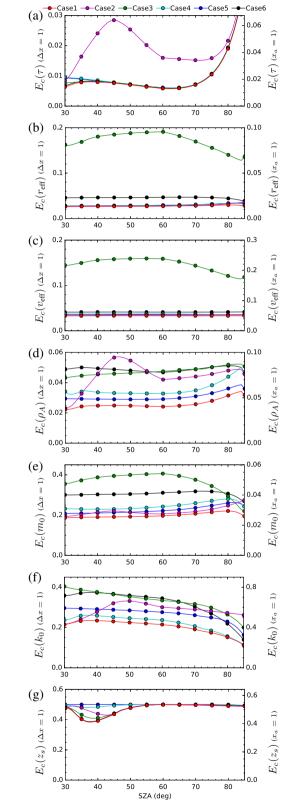


Fig. 8 Combined propagation errors of dust model parameters. The definitions of cases 1–6 are the same as in Fig. 7. The left and right scales are normalized so that $\Delta x = 1$ and $x_a = 1$, respectively, and panels (**a**) - (**g**) show the relation between propagation error and SZA for $X_1 - X_2$ respectively

radius r_2 = 0.06 µm and effective variance v_2 = 0.1. A lognormal distribution is given as

$$\frac{\mathrm{d}N}{\mathrm{d}\ln r} = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(\ln r - \ln r_{\mathrm{mod}})^2}{2\sigma^2}\right]. \tag{19}$$

Here, $r_{\rm mod}$ is the mode radius and σ is the standard deviation. The values of mode radius and standard derivation can be calculated from the effective radius and variance as $r_{\rm mod} = r_2(\nu_2+1)^{-5/2}$ and $\sigma = [\ln(\nu_2+1)]^{1/2}$, respectively. We parameterize the volume mixing ratio of the fine mode (ρ_F) between 0 (the a priori value) and 0.01.

The sensitivities of dust observation parameters to the volume mixing ratio of fine mode dust (ρ_F) are shown in Fig. 11a. Observational parameters such as F_B , F_C , B_B , and B_C (i.e., parameters related to SSR in the blue band except aureole) are particularly sensitive to ρ_F .

Figure 11b shows the systematic errors of retrieved dust model parameters when the wrong assumption of ρ_F = 0 (monomodal) is adopted, while the true value of ρ_F is 0.01 (slightly bimodal). Figure 11b indicates that the magnitudes of error in ρ_A and k_0 are at most 10% of their variation range (~20% of their a priori values) even when the volume mixing ratio of fine mode is as large as 1%. Since the presence of fine mode particles in the lower Mars atmosphere has not been reported conclusively, it would be justified to assume the monomodal size distribution as in the present analysis. Nevertheless, to validate such a monomodal assumption, it is desirable to check the fitting result of real data to be obtained in future Mars lander missions.

Sensitivity analysis and error estimation for TCWV measurement

In a similar way as applied to the dust model parameters, sensitivity analysis for water vapor retrieval is made by changing the value of c_w between 0.476 and 4.76 mg/ cm² (corresponding to 100 and 1000 ppm, respectively). Figure 12 shows the resulting curves of the variation ranges (sensitivities) of the observational parameters plotted against SZA. The SZA dependencies of the sensitivities of $D_2 = DSR(\lambda_W)/DSR(\lambda_S)$ and $D_3 = DSR(\lambda_W)/DSR(\lambda_S)$ $DSR_0(\lambda_W)$ to c_w are very similar. While D_3 is sensitive only to c_w , D_2 exhibits large sensitivity not only to c_w but also to τ . Thus, D_3 is a better parameter than D_2 for the c_w retrieval, as expected from the better knowledge of the spectral intensity around the absorption band. As for SSR, both $S_2 = SSR(\lambda_W)/SSR(\lambda_S)$ and $S_3 = SSR(\lambda_W)/SSR(\lambda_S)$ $SSR_0(\lambda_W)$ exhibit similar SZA dependence of the sensitivities to c_w , and the advantage of using S_2 or S_3 for the retrieval of c_w is that the magnitudes of the sensitivities are approximately three times larger than those of D_2 and D_3 . A drawback, however, is that they show

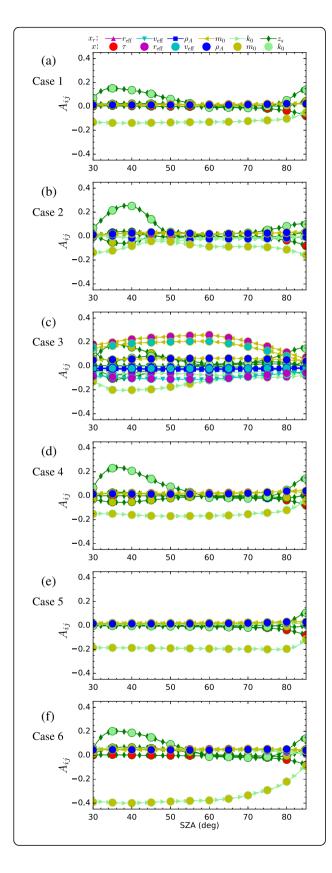


Fig. 9 Non-diagonal elements of AKM ($A_{ij} = \partial x_{r,i}/\partial x_j$) of dust model parameters. The *lines with small symbols* indicate the type of retrieved dust parameters (x_i), while the *large circles* indicate the type of true dust parameters (x_i). Panels (**a**) - (**f**) show the relation between A_{ij} and SZA for cases 1-6, respectively. The definitions of cases 1-6 are the same as in Fig. 7. These graphs are useful for the examination of error propagation from one dust parameter to another (see text)

sensitivities to τ and z_s in addition to c_w . Especially, the dependence on z_s can be problematic, since this parameter cannot be measured accurately through dust observations. This problem is hardly improved even with three wavelengths, since the difference of τ or z_s results in a change of effective optical path length due to multiple scattering, and hence, the change in the amount of water vapor absorption itself. It should be pointed out, however, that we may be able to retrieve the value of z_s if both DSR and SSR can be measured simultaneously. Moreover, a better prospect for z_s retrieval may possibly be achieved by measuring carbon dioxide (CO₂) absorption with the MAX-DOAS technique (Irie et al. 2008), since it would be relatively easy to estimate the vertical distribution of CO₂, and the molecule has strong absorption bands in the near infrared region (e.g., ~1050 nm).

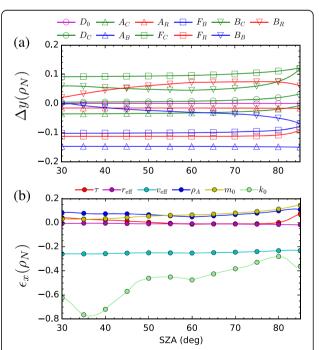


Fig. 10 a Sensitivity of dust observation parameters to the volume mixing ratio of non-spherical dust (ρ_N) . Parameter Δy represents the difference between the maximum and minimum values of the normalized observational parameters when ρ_N is changed from 0 to 1. **b** Systematic error due to non-spherical dust shape. Systematic errors of normalized dust model parameters are estimated from differences between observational parameters calculated with true (1) and wrong (0) values of the volume mixing ratio of non-spherical dust (ρ_N)

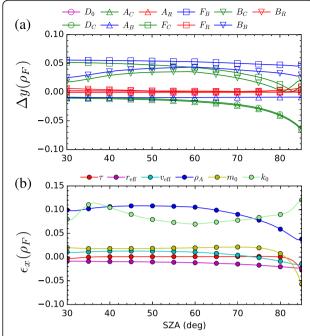


Fig. 11 a Sensitivity of dust observation parameters to the volume mixing ratio of fine mode dust (ρ_F) . Parameter Δy represents the difference between the maximum and minimum values of the normalized observational parameters when ρ_N is changed from 0 to 0.01. **b** Systematic error due to ignorance of bimodal size distribution. The systematic errors of the normalized dust model parameters are estimated from the differences between the observational parameters calculated with true (0.01) and wrong (0) values of the fine mode dust volume mixing ratio (ρ_F)

Here, we estimate the retrieval error of TCWV (c_w) when c_w and dust model parameters are retrieved simultaneously. We assume a relative measurement error of 1%, and a regularization parameter $\gamma_d = 1$ is employed for dust model parameters. Figure 13 shows the relation between the regularization parameter (γ_w) of TCWV and the diagonal elements of AKM. Here, SZA is fixed at 80°. When $\gamma_w = 1$, the diagonal elements of AKM with D_2 or D_3 are about 0.4 and the influence of the a priori information is significant. Hence, we take $\gamma_w = 0.06$, at which the diagonal elements of AKM are larger than 0.9. Weakening the regularization strength results in vulnerability to the random error of measurements, but such influence can be reduced by increasing averaging or exposure time of the camera measurement.

We consider four cases in which one of D_2 , D_3 , S_2 , or S_3 is used for the retrieval of c_w . The diagonal elements of AKM for the four different cases are shown in Fig. 14 (left scale). The difference between two and three wavelengths turns out to be insignificant. In the cases of DSR (D_2 , D_3), the averaging kernels are around 0.7–0.9, while in the cases of SSR (S_2 , S_3) the averaging kernels are about 0.98.

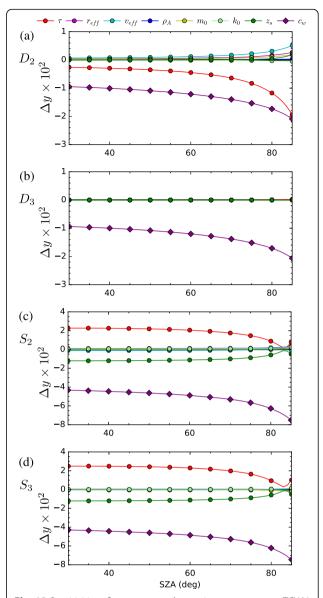


Fig. 12 Sensitivities of water vapor observation parameters to TCWV and dust model parameters. Panels (**a**) - (**d**) show the relation between $\Delta y(c_w)$ and SZA for D_2 , D_3 , S_2 , and S_3 , respectively

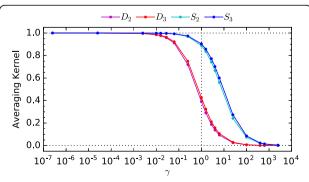


Fig. 13 Relation between regularization parameter (γ_w) of TCWV and diagonal elements of AKM

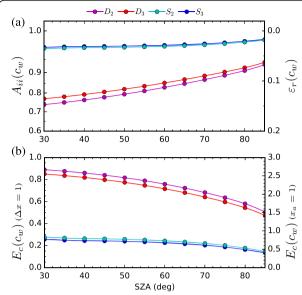


Fig. 14 a Diagonal elements of AKM and error ratio of TCWV. As compared with DSR, SSR results show stronger dependence on observation data of c_w rather than a priori data. **b** Combined propagation errors of TCWV. The left and right scales are normalized so that $\Delta x = 1$ and $x_a = 1$, respectively

The combined propagation errors are shown in Fig. 14b. They include the contributions from both measurement errors and a priori errors according to the error ratio shown in Fig. 14a (right scale). Again, the difference between two and three wavelengths is insignificant. Looking around SZA = 80°, the propagation errors normalized by x_a are 1.7 and 0.5 when we use DSR and SSR, respectively. This means that if we can suppress the measurement error down to 1%, SSR-based retrieval of c_w can achieve a precision of 50% of its a priori value.

As seen above, it is expected that the combined propagation errors are smaller if we use SSR rather than DSR. In the case of SSR, on the other hand, the amplitudes of non-diagonal elements of AKM are larger (Fig. 15), and the retrieved c_w is more affected by the retrieval error of dust model parameters (especially z_s), which is consistent with the results of the present sensitivity analysis (Fig. 12). However, the error of c_w due to the error in z_s is at most ~15% of the variation range (50% of the a priori value). Also, the influence of the water vapor profile on SSR is expected to be small for any particular value of c_w . Therefore, it is advantageous to use SSR, and if available, using both SSR and DSR is desirable.

Applicability of the present algorithm

In order to check the practical applicability of our algorithms, we estimate the measurement noise assuming sensor specifications that can be realized with the current technology. We employ radiative transfer

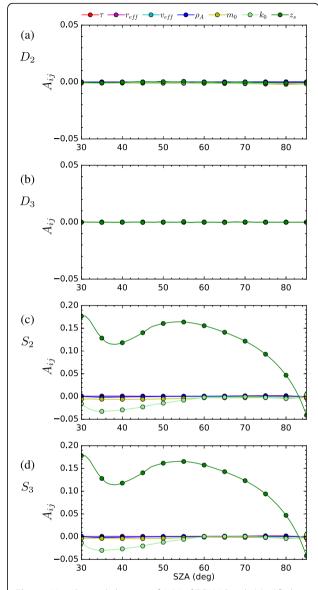


Fig. 15 Non-diagonal elements of AKM of TCWV. Panels (**a**) - (**d**) show the relation between A_{ij} and SZA for D_{2} , D_{3} , S_{2} , and S_{3} , respectively

simulation to estimate the minimum signal strength of SSR. The simulation conditions assumed for minimizing SSR intensity are an SZA of 80°, scattering angle of 120°, and dust optical depth of 0.1. Then, signal-to-noise (S/N) ratio is estimated from the SSR intensity. Only the shot noise of the sensor has been considered in this calculation, on the assumption that the dark noise and readout noise are negligibly small.

If we assume a focal length of 10 mm, an array with 500 pixels, and a field-of-view (FOV) angle of 30°, the sizes of a sensor element and array width are calculated to be approximately 10 and 5.2 mm, respectively. A two-dimensional image sensor that fulfills such specifications is easily available. Even when the signal strength is at its

minimum and the exposure time is as short as 1 s, it is expected that the random noise is less than 0.5%, and hence, an S/N ratio over 200 can be attained. Actually, the exposure time can be much longer than 1 s, since a temporal resolution of 1 min, for example, is still acceptable. Therefore, the proposed scheme of DSR/SSR observation is practical and achievable by means of hardware existing today.

Conclusions

We have constructed a Martian dust model in order to retrieve optical/physical properties of Martian dust from DSR/SSR spectra to be measured by a multi-wavelength environmental camera onboard a Mars lander. We have assumed that Martian dust is composed of silicate-like substrate and hematite-like inclusion. The dust shape is assumed to be spheroid with a monomodal gamma size distribution and a fixed aspect ratio distribution estimated from a terrestrial feldspar sample. The spatial distribution of dust is homogeneous horizontally, and its concentration decreases exponentially with increasing altitude. Our Martian dust model is parameterized with seven parameters, namely, real (m_0) and imaginary (k_0) parts of silicate RI, volume mixing ratio of hematite (ρ_A) , effective radius ($r_{\rm eff}$) and variance ($v_{\rm eff}$) of size distribution, optical depth (τ) , and scale height (z_s) of extinction coefficient at a wavelength of 550 nm. On the other hand, we consider 11 observational parameters, namely, intensity of DSR at 550 nm (D_0) , color ratio of DSR between blue and red bands (D_C) , relative intensities of aureole, forward scattering, and backward scattering with respect to the SSR at the reference scattering angle for the blue and red bands $(A_B, A_R, F_B, F_R, B_B, B_R)$, and color ratio of SSR (A_C , F_C , B_C).

From the result of error analysis using simulated data, relative errors (combined propagation error from both measurement and a priori data) of dust model parameters, comparing them to a measurement error of 1%, have been estimated as τ : 1–4%, $r_{\rm eff}$: 2%, $v_{\rm eff}$: 5%, ρ_A : 4– 6%, m_0 : 3%, and k_0 : 40% of their a priori values. The value of z_s is almost confined to its a priori value, due to the lack of sensitivity in our observation scheme. Increase of retrieval error is observed when some of the observational parameters are omitted from the retrieval procedure. Such observational parameters are τ : DSR (D_0, D_C) , r_{eff} : aureole (A_C, A_B, A_R) and color ratio (D_C, A_B, A_R) A_C , F_C , B_C), $v_{\rm eff}$: aureole, ρ_A : DSR, aureole and color ratio, m_0 and k_0 : aureole and color ratio. If spherical shape is employed to retrieve the dust model parameters from the observational parameters calculated for nonspherical shape, we expect a systematic error of $\nu_{\rm eff}$ as large as 40% of its a priori value. If a monomodal gamma distribution of coarse particles is employed in finding model parameters from observational ones but the true size distribution is bimodal containing 1% fine mode particles by volume, we expect a systematic error of ρ_A as large as 20% of its a priori value.

Water vapor has absorption bands inside the sensitive range of a CMOS sensor, and we can measure TCWV (c_w) from absorbed amount in DSR or SSR intensity. We considered four observational parameters of spectral ratio (D_2, D_3, S_2, S_3) calculated with DSR or SSR at two or three wavelengths. Using simulation, it has been confirmed that if we use SSR instead of DSR for the observational parameter, larger sensitivity can be expected, with the relative error of c_w against 1% of measurement error being 50% of its a priori value.

The measurement noise estimated with currently available sensor specifications is sufficiently small, and thus, we conclude that the proposed scheme of dust retrieval with DSR/SSR observation is practical.

Abbreviations

AKM: Averaging Kernel Matrix; CMOS: Complementary metal-oxide semiconductor; DSR: Direct solar radiation; FOV: Field of view; LOS: Line of sight; MAX-DOAS: Multi-axis differential optical absorption spectroscopy; RI: Refractive index; SSR: Scattered solar radiation; SZA: Solar zenith angle; TCWV: Total column water vapor; VMR: Volume mixing ratio

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Authors' contributions

NM, KN, GLH, and MS proposed the topic, and conceived and designed the study. NM carried out the simulation study. NM and KN wrote the manuscript. HK contributed to editing the manuscript. HS and NO provided ideas for the study. All authors read and approved the final manuscript.

Competing interests

The authors declare that they have no competing interest.

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