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Determining polar ionospheric electrojet currents from *Swarm* satellite constellation magnetic data

Cecilie Drost Aakjær , Nils Olsen and Christopher C. Finlay

Abstract

We determine the strength and location of the ionospheric currents responsible for the polar electrojets from magnetic data collected by the *Swarm* satellite constellation on an orbit-by-orbit basis. The ionospheric currents are modelled using a simple, yet robust, method by a series of line currents at 110 km altitude (corresponding to the ionospheric E-layer) perpendicular to the satellite orbit, separated by 1° (about 113 km). We assess the reliability of our method, with the aim of a possible near-real-time application. A study of the effect of different regularization methods is therefore carried out. An L_1 model regularization of the second-order spatial differences, and robust treatment of the data (to account for non-Gaussian error distributions), yields the most encouraging results. We apply our approach to two three-weekly data periods in March 2014 (geomagnetic quiet conditions) and March 2015 (more disturbed conditions), respectively. Our orbit-by-orbit approach also allows the temporal evolution of the polar electrojets to be investigated. We find remarkable agreement of the ionospheric activity in Northern and Southern polar regions, with correlation exceeding 0.9 for periods longer than two days. Reliability of the approach is shown by three key results: (1) a common regularization parameter for all orbits with enough data coverage, (2) 0.95 squared coherence with the Auroral Electrojet index, and (3) 0.97 squared coherence is found between the side-by-side flying satellites, Alpha and Charlie, indicating a method invariant to small changes in data input. All these results indicate a possible automated near-real-time application.

Keywords: Geomagnetism, Field modelling, Ionosphere, *Swarm*

Introduction

Geomagnetic reference models provide a good description of the main parts of Earth's magnetic field, including contributions from the core and crust, as well as the large-scale magnetospheric (e.g. Finlay et al. 2016; Lesur et al. 2010; Olsen et al. 2014). Non-ionospheric field (e.g. Sabaka et al. 2004, 2015) contributions are also well described by modern models. The situation is, however, different in the polar regions, where the large temporal and spatial variability of electric currents in the polar ionosphere makes their description difficult, and their prediction almost impossible.

These ionospheric currents give rise to a variety of important space weather effects, influencing the performance and reliability of spaceborn and ground-based technological systems. Problems in ground-based systems occur for instance due to the secondary, Earth-induced, electric fields and corresponding currents. For directional drilling in polar regions disturbances in the magnetic field caused by strong ionospheric currents may hamper accurate well positioning (Poedjono et al. 2013). Ionospheric currents may also lead to increased drag on low-altitude spacecraft (Liu and Lühr 2005; Pirjola et al. 2005). Better understanding of the time-space structure of polar ionospheric currents and in particular their improved modelling are therefore of great importance, not only for advances in fundamental space research but also regarding practical applications.

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There are two major constituents to magnetic disturbance fields at polar latitudes: (1) electrical currents in the ionospheric E-layer (at an altitude of about 110 km) form the *polar electrojets* (PEJs) and (2) currents flowing along field lines of the ambient magnetic field feeding the PEJs by connecting the ionosphere and the magnetosphere. These so-called *field-aligned currents* (FACs) result in large magnetic field disturbances at satellite altitude, in particular in the east-west magnetic field component.

The PEJs have been successfully estimated from ground magnetic data (e.g. Amm 1997; Friis-Christensen et al. 1985; Kamide et al. 1981; Richmond et al. 1998). Indices monitoring the electrojet activity, such as the *Auroral Electrojet* (AE) index (Sugiura and Davis 1966) have been developed. These indices provide important information on the state of the polar ionosphere, but are restricted by the positions of the magnetometer stations. Since primarily stations from the Northern Hemisphere are used, the resulting indices mainly reflect PEJ activity in that hemisphere.

From magnetic ground observations it is only possible to estimate the equivalent currents, e.g. (hypothetic) horizontal ionospheric currents that would cause the same magnetic field disturbance as the observed one. Magnetic observations taken at satellite height in addition allow the estimation of the FACs, which is a clear advantage compared to ground observations. Furthermore, satellites allow access to the entire, mainly north-south-directed, current density profile, in contrast to what is possible from ground observations, and thereby provide a better description of the currents position and magnitude as a function of latitude. The global coverage of satellite data also enables interhemispheric comparisons. With these advantages in mind, several studies of ionospheric currents have been conducted using satellite measurements from, e.g., the *Magsat*, *Ørsted*, and *CHAMP* satellites (Olsen 1996; Ritter et al. 2003).

The magnetic field produced by an electric current is, at least in the vicinity of the current, always perpendicular to the current direction. This means that the magnetic field caused by FACs is perpendicular to the field line and hence not observable in the magnetic component parallel to the field line. As a consequence, the magnetic field intensity, $F = |\mathbf{B}|$, which by definition is the field component parallel to the magnetic field, is only marginally affected by FACs. Field intensity, F , is, however, sensitive to contributions from the horizontal currents in the ionospheric E-layer that form the PEJs. Observations of F collected by satellites can therefore be used to determine these currents.

A model study of the PEJ's using *Magsat* scalar magnetic satellite data and a current model consisting of

a series of line currents perpendicular to the satellite track was presented by Olsen (1996) and later applied to *CHAMP* satellite data by Ritter et al. (2003) and Ritter et al. (2004). The use of scalar magnetic satellite data is a simplification compared to using the full vector data, resulting in similar results to a ground magnetic chain. The line current method has been applied to multi-satellite data by Olsen et al. (2002) and Moretto et al. (2002).

Juusola et al. (2006) proposed an alternative approach for monitoring the auroral activity from magnetic satellite data. They worked with a 1D version of the 2D *Spherical Elementary Current System* (SECS) method developed by Amm (1997) for application to *CHAMP* satellite vector data. By using vector data they were able to estimate not only the horizontal currents but also the FACs. The use of vector data in the 1D SECS method may, however, introduce both a complication in computation and an error source due to stronger contamination by unwanted sources such as the FAC in the radial magnetic vector component compared to only using measurements of the magnetic field intensity.

A simple approach to determine the location and strength of the PEJs from magnetic satellite data was presented by Vennerstrom and Moretto (2013). Their method corresponds roughly to finding the position and amplitude of the PEJs in the current profiles determined using the line current model of Olsen (1996).

With the aim of a possible near-real-time monitoring of the time-space structure of polar electrojet activity, we aim at developing a reliable and simple approach, while still estimating entire current profile along the satellite tracks. We therefore applied the line current model of Olsen (1996) to *Swarm* satellite magnetic data and investigated how different regularization methods affect the model results. By applying the method to *Swarm* magnetic data, we do not only gain new insights concerning the current system in the ionosphere, but also have the opportunity to explore previously unavailable results regarding longitudinal variations of the PEJs thanks to the unique constellation of the *Swarm* satellites.

The trio of *Swarm* satellites (e.g. Friis-Christensen et al. 2008) has been in orbit since 22 November 2013. Two of the satellites, called Alpha and Charlie, fly side by side at an altitude of about 450 km (as of January 2016) in a near-polar orbit of inclination 87.4° with an east-west separation of 1.4° in longitude (corresponding to about 160 km at the equator). The third satellite, Bravo, has an orbital inclination of 88° and is flying at an altitude of approximately 520 km. The different orbital inclination of the satellites results in different drift rates in local time (LT). The Bravo satellite in November 2015 (i.e. two years after launch) measured the magnetic field at a local time 2.6 h ahead of the lower satellite pair Alpha and Charlie.

Each of the three satellites carry, amongst other instruments, an absolute scalar magnetometer (ASM) for measuring the magnetic field intensity F , a vector fluxgate magnetometer (VFM) measuring the three vector components of the magnetic field, and a triple-head star imager to determine orientation.

The first part of the paper presents the chosen model parametrization along with a description of the model estimation scheme and an exploration of various regularization methods. Next we present results from a single orbit crossing and then move on to consider time dependence in three weeks of data for both the Northern and Southern Hemisphere. We also compare our results with the Auroral Electrojet index, a ground-based measure of PEJ activity. Finally, results obtained with data from all three *Swarm* satellites are compared, and the effects of secondary, Earth-induced, currents are discussed.

Model parameterization

We describe the polar ionospheric currents by a series of line currents placed at an altitude of 110 km in the ionospheric E-layer, perpendicular to the satellite track and separated in horizontal (along-track) direction by $\Delta = 113$ km corresponding to 1° . The geometry of the model is shown in Fig. 1. The magnetic field due to ionospheric E-layer currents is a Laplacian potential field at

satellite altitude, and thus the strength of the magnetic field, and the spatial structure of the ionospheric currents, depends on the distance to the measurements. A typical rule of thumb in this case is that one cannot resolve structure of scale smaller than half the distance to the measurements. Since the *Swarm* satellites measure at a height of minimum 340 km above the ionosphere, it is hardly possible to distinguish between a continuous current distribution and a series of discrete line currents separated by 1° (corresponding to about 113 km). We therefore use a series of discrete line current separated by 1° .

As mentioned previously, electric currents at satellite altitudes are predominantly confined to flow parallel to the field lines of the ambient magnetic field \mathbf{B}_0 due to the nearly vanishing transverse electrical conductivity in this region. These FACs do, at least to first order, not contribute to the magnetic field component $F = B_{\parallel}$ parallel to the ambient field \mathbf{B}_0 . In the ionospheric E-layer, however, the transverse conductivity is comparably large, resulting in horizontal currents causing magnetic signatures that do not contribute to $F = B_{\parallel}$. The magnetic field intensity F can therefore be used to investigate the horizontal currents flowing in the ionospheric E-layer. Although this is strictly true only for a uniform ambient field \mathbf{B}_0 , FACs give, even for a real distribution of currents, only a very small contribution to F .

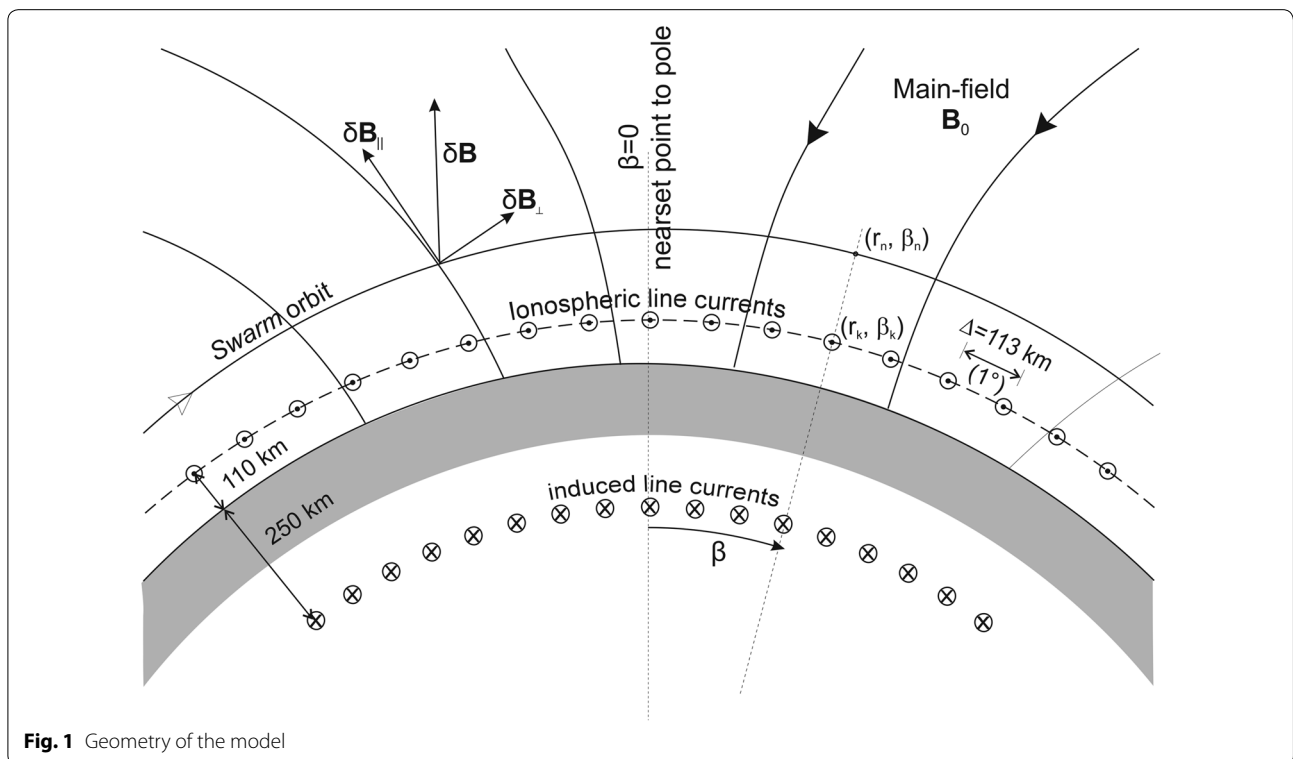


Fig. 1 Geometry of the model

As input data we use field intensity anomaly values $\delta F = F^{\text{obs}} - F^{\text{mod}}$ obtained from satellite observations of the Mag LR 1 Hz L1b magnetic field intensity, F^{obs} down-sampled to 10 s, after removal of model values, F^{mod} , given by the CHAOS-5 field model (Finlay et al. 2015). This model provides estimates for the core and crustal field contributions as well as the contributions from the large-scale magnetospheric field, the time dependence of which is given by the RC index, which describes the strength of the magnetospheric ring current (Olsen et al. 2014).

The contribution from one single line current to the magnetic field intensity δF is given, following Olsen (1996), by

$$\begin{aligned} \delta F_n &= \frac{\mu_0}{2\pi} \frac{\xi_{n,k} \cos I_n + \eta_{n,k} \sin I_n}{\xi_{n,k}^2 + \eta_{n,k}^2} \cdot j_k \\ \eta_{n,k} &= r_k \sin(\beta_n - \beta_k) \\ \xi_{n,k} &= r_n - r_k \cos(\beta_n - \beta_k) \end{aligned} \quad (1)$$

where $\mu_0 = 4\pi \cdot 10^{-7}$ Vs/Am is vacuum magnetic permeability, I_n is the magnetic inclination of the main field model, \mathbf{B}_0 , at the satellite location (r_n, β_n) , and j_k is the amplitude of the k th line current at location (r_k, β_k) . η_n and ξ_n measure the radial and horizontal distance, respectively. β_n and β_k are along-track arc parameters describing the distance from the closest approach to the magnetic North geomagnetic pole (or South geomagnetic pole) for the observation locations and line current locations, respectively, as shown in Fig. 1.

The magnetic field disturbance caused by a superposition of the contributions from single line currents described by Eq. (1) results in a model of the form

$$\mathbf{d} = \mathbf{G}\mathbf{m} \quad (2)$$

where \mathbf{d} is the data vector consisting of the N observations, δF_n , with $n = 1, \dots, N$, \mathbf{m} is the vector of the M model parameters (the line current amplitudes), j_k , with $k = 1, \dots, M$, and \mathbf{G} is the design matrix of size $N \times M$ with elements

$$g_{n,k} = \frac{\mu_0}{2\pi} \frac{\xi_{n,k} \cos I_n + \eta_{n,k} \sin I_n}{\xi_{n,k}^2 + \eta_{n,k}^2}. \quad (3)$$

The sheet current density $J(\beta_k)$ is estimated from the model parameters by dividing the line current amplitudes j_k (the model parameters) by the distance, $\Delta\beta = 113$ km, between the line currents that corresponds to 1° at 110 km altitude. Since the spacing is equidistant in β , the sheet current density is simply found as

$$J(\beta_k) = \frac{j_k}{\Delta\beta} = \frac{j_k}{113 \text{ km}} \quad (4)$$

Model estimation

The M model parameters j_k are estimated by solving the linear inverse problem described in Eq. (2). An *iteratively reweighted least squares* (IRLS) approach with Huber weights (Constable 1988; Huber 1964) is used in order to handle a possibly non-Gaussian data error distribution. Although formally overdetermined (since $N > M$), the problem is ill-conditioned, and thus, the use of unconstrained least squares results in huge variations of the amplitudes of neighbouring line currents. In order to avoid this instability, we adopt a regularization approach (Aster et al. 2005; Menke 2012).

We carried out tests on a range of different regularization norms including; zeroth-order Tikhonov regularization (Tikhonov 1963), i.e. minimizing the sum of the squares of the line current strengths; higher-order Tikhonov regularization (Aster et al. 2005) considering finite differences of the line current strengths in the along-track direction; maximum entropy regularization (Jackson et al. 2007) as well as the use of L1 rather than L2 norms (Farquharson and Oldenburg 1998). Below we focus on the two following approaches that were found to perform well:

- 1 Minimization of an L_2 norm of the model parameters [i.e. zeroth-order Tikhonov regularization, see Aster et al. (2005)] and a Huber-weighted misfit measure. This is implemented through an IRLS technique, where the model at the $(i + 1)$ th iteration is determined by

$$\mathbf{m}_{i+1}^{L_2} = (\mathbf{G}^T \mathbf{W}_i^d \mathbf{G} + \alpha^2 \mathbf{I})^{-1} \mathbf{G}^T \mathbf{W}_i^d \mathbf{d}. \quad (5)$$

Here \mathbf{I} is the identity matrix of size $M \times M$, α^2 is a parameter controlling the strength of the regularization, and \mathbf{W}_i^d is the data weight matrix. α^2 is adjusted to achieve the desired trade-off between data misfit and model complexity. Its value and choice thereof is discussed further in the section “Choice of regularization parameter, α^2 ”. The Huber-weighted misfit approach allows non-Gaussian errors to be handled by applying small weights to outliers through a series of iterations. \mathbf{W}_i^d is the Huber weight matrix for the i th iteration with diagonal elements $w_{i,n} = \min\left(\frac{c\sigma_i}{|\Delta\delta F|}\right) \cdot c$

is here a constant typically 1.5, σ is the standard deviation of the model residuals $\Delta\delta F = \delta F^{\text{obs}} - \delta F^{\text{mod}}$, where δF^{mod} are the model predictions of the observations. This solution will be referred to below as the L_2 norm solution.

- 2 Minimization of an L_1 norm of the second-order differences of model parameters and a Huber-weighted

misfit measure. This is also implemented via IRLS via the scheme

$$\mathbf{m}_{i+1}^{L_1} = (\mathbf{G}^T \mathbf{W}_i^d \mathbf{G} + \alpha^2 \mathbf{D}^T \mathbf{W}_i^m \mathbf{D})^{-1} \mathbf{G}^T \mathbf{W}_i^d \mathbf{d}. \quad (6)$$

\mathbf{D} is the second-order finite-difference operator, controlling the second-order difference minimization of the model parameters (Aster et al. 2005), and \mathbf{W}_i^m is a reweighting matrix implementing the L_1 minimization of the model parameters (Farquharson and Oldenburg 1998). The elements of the diagonal matrix \mathbf{W}_i^m are found using Ekbloms measure, where ($W_{kk}^m = (j_k^2 + \epsilon^2)^{-1/2}$ Ekblom (1987)). ϵ ensures a non-singular solution at $j_k = 0$. A sufficiently small value of ϵ compared to the magnitude of the model parameters was chosen. Note that $\mathbf{D}^T \mathbf{W}_i^m \mathbf{D}$ is non-dimensional and α^2 in Eq. 6 will therefore have a different unit than in Eq. 5. This solution will be referred to below as the L_1 norm solution.

Results and discussion

Examples of geomagnetically quiet and disturbed periods

We first illustrate our approach with a few examples, representing geomagnetic quiet and disturbed conditions, respectively. We have chosen *Swarm* Alpha orbit no. 6248 on 4 January 2015 13:36 to 14:01 UT, corresponding to a *magnetic local time* (MLT) of midnight around 60° *Quasi-Dipole* (QD) latitude. Since ionospheric conductivity and currents are guided by the geometry of Earth's main field, it is advantageous to describe the currents using magnetic coordinates like the QD latitude (Richmond 1995). This was a moderately disturbed period, with index of global geomagnetic activity $K_p = 4^+$. As an example of quiet-time conditions, we have chosen orbit no. 6493 from 20 January 12:37 to 13:02 UT, at a similar MLT but with a K_p index of 0^+ .

The top row of Fig. 2 shows the observations of magnetic field intensity F , and the obtained data fit, the middle row shows the corresponding model residuals, and the bottom row presents the estimated sheet current density, J , for the disturbed day (left), and the quiet day (right).

Shown in green is the observed magnetic field signature δF (after removal of core, crust, and magnetospheric contributions), along with model predictions obtained using L_1 (black) and L_2 (red) norm regularization. A simple least squares solution with zeroth-order Tikhonov regularization is given in blue for comparison. Both regularization schemes, with $\alpha^2 = 6.4 \cdot 10^{-15} \text{ nT} \cdot \text{A}^{-2}$ (L_1) and $\alpha^2 = 3.6 \cdot 10^{-27} \text{ nT} \cdot \text{A}^{-2}$ (L_2), are able to produce an extremely good fit to the observed field intensity. The

chosen values of α^2 are discussed in the section “Choice of regularization parameter, α^2 ”.

The variance ratios,

$$\frac{\sigma_{\Delta\delta F}^2}{\sigma_{\delta F}^2}, \quad (7)$$

where $\Delta\delta F$ are the residuals between observations and the model predictions for the L_1 or for the L_2 solution are found to: $4.1 \cdot 10^{-6}$ (L_1) and $9.2 \cdot 10^{-6}$ (L_2) for the disturbed day (orbit 6248), and $39 \cdot 10^{-6}$ (L_1) and $67 \cdot 10^{-6}$ (L_2) during quiet conditions (orbit 6493). This reveals that L_1 regularization results in slightly lower misfit than L_2 regularization, although both approaches describe almost all of the variance in the measurements. The small model residuals, $\Delta\delta F$, given in the middle row of Fig. 2 support the very low variance ratios with residuals lower than 1 nT ($\approx 0.5\%$ of the signal strength) for the disturbed day.

Considering the mean variance ratios for 1000 orbits between 28 December 2014 to 3 March 2015 (orbit nos. 6142 to 7142) for satellite *Swarm* Alpha, we find that the L_1 solution in general gives a better description (mean variance ratio of $120 \cdot 10^{-6}$) compared to the L_2 solution ($400 \cdot 10^{-6}$). This tells us that the model gives a very good data fit not only for the single orbits presented above, but for all tested orbits at least on average. The largest values of the variance ratio of the 1000 tested orbits was $820 \cdot 10^{-6}$ for the L_1 solution and $2000 \cdot 10^{-6}$ for the L_2 solution. Thus even for the orbits with the worst data fits (highest variance ratios), the model still performs very well. The orbits with highest variances are mainly from quiet days, since on disturbed days the signal amplitude is larger compared to the noise level.

The sheet current densities, J , are presented in the bottom row of Fig. 2 for both the L_1 (black) and L_2 (red) norm inversions as a function of QD latitude. A positive current is defined as a current flowing from midnight to noon (sunward). Compared to the reference least squares zeroth-order Tikhonov solution (blue curve), there are no major differences between the sheet current densities from L_1 (black curve) and L_2 (red curve) norm regularization. We expect that the sheet current densities are weak or absent where there are no currents (e.g. in non-polar regions) and not wildly fluctuating. The L_1 solution correctly estimates the currents outside the polar region (auroral oval) to be zero, or very close to zero, while the L_2 solution displays non-physical small-scale oscillations around zero. These cannot be damped sufficiently by increasing α^2 without also reducing the amplitude of the peak of the sheet current density. The results obtained

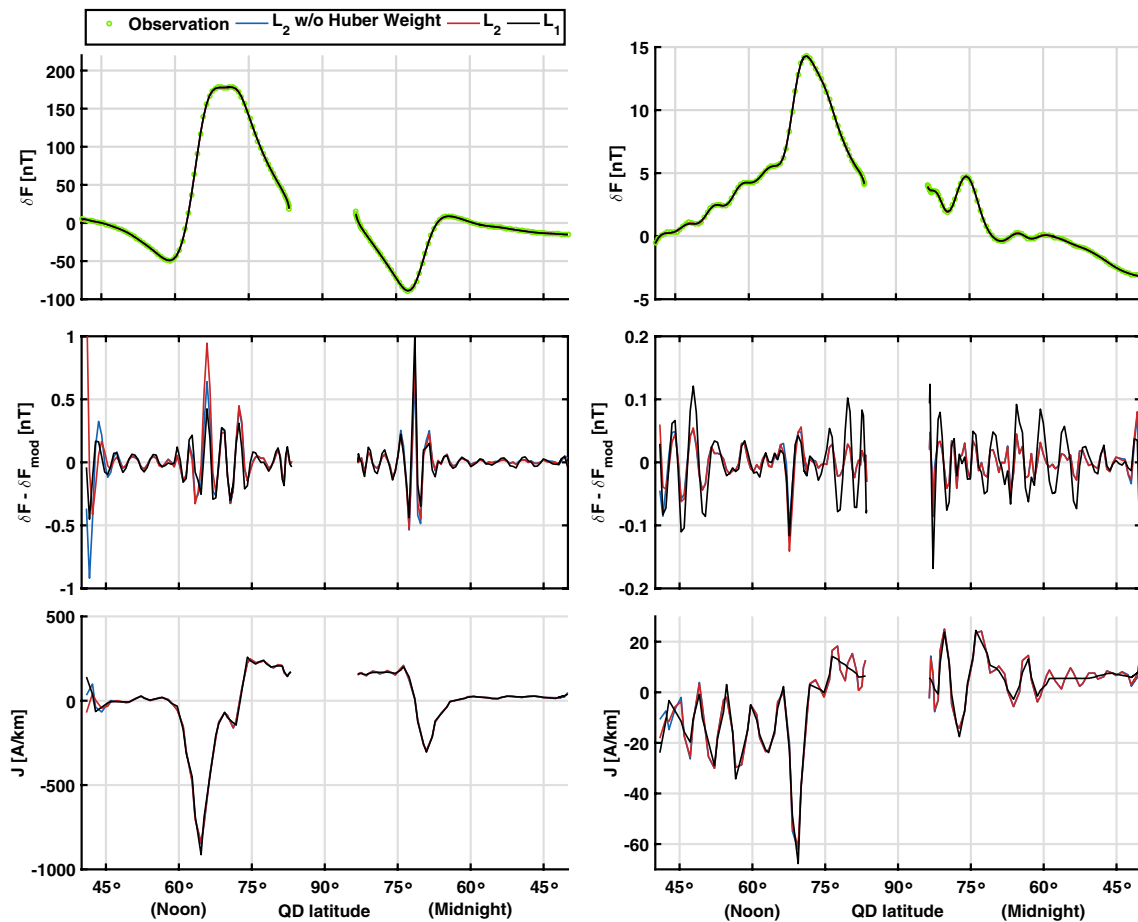


Fig. 2 Top row shows observations, δF , in green along with the model predictions, δF^{mod} , for three solution methods, L_1 norm (black), L_2 norm (red), and L_2 norm without Huber-weighted misfit (blue). The middle row shows the model residuals, $\Delta \delta F$, for the same inversion methods, and the bottom row shows the corresponding sheet current densities, J , again for all three methods. Data are from satellite Alpha for 2 days: (left column) orbit 6248 on 04.01.2015 13:36 to 14:01 UT, corresponding to a magnetic local time (MLT) of midnight around 60° magnetic latitude (disturbed, $K_p = 4^-$) and (right column) orbit 6493 on 20.01.2015 12:37 to 13:02 UT, a similar MLT (quiet, $K_p = 0^+$). The sheet current densities are found using $\alpha^2 = 6.4 \cdot 10^{-15} \frac{\text{nT}^2}{\text{A}^2}$ for the L_1 norm solution and $\alpha^2 = 3.6 \cdot 10^{-27} \frac{\text{nT}^2}{\text{A}^2}$ for the L_2 norm solutions. A positive current flows from midnight to noon (sunward)

with the L_1 norm, therefore, give a representation of the model parameters slightly closer to what we expect on physical grounds, compared to the results found in the L_2 norm solution.

The simple least square zeroth-order Tikhonov regularization solution (blue curve in Fig. 2) gives a rather similar solution as the L_2 norm solution for these orbits, which also involves a Huber-weighted misfit measure. We prefer, however, to use the latter since the distribution of residuals (data minus model predictions) is non-Gaussian.

A similar argument also applies on going from L_2 to L_1 norm regularization. When solving with an L_2 regularization norm, we assume that the model parameters are Gaussian distributed. The distribution of the obtained

model parameters is highly non-Gaussian, in particular shown in long tails; in this case it is more consistent to use an L_1 norm regularization scheme.

Choice of regularization parameter, α^2

Both the L_2 and L_1 norm regularization methods require specification of a regularization parameter α^2 . The choice is a trade-off between goodness of data fit and model complexity. Too small values of α^2 will result in interpretation of non-physical noise, while a value too large leads to a model for which the desired signal is suppressed, resulting in a decreased data fit. So the question is: when does damping regularization of a non-physical noise become damping of a physical signal?. One way to objectively choose α^2 is by plotting the norm of the

model vector, $\|m\|/\max(\|m\|)$ (individually normalized to the range between 0 and 1 for better comparison between different orbits) versus the norm of data misfit, $\|Gm - d^{obs}\|$ for various values of the regularization parameter α^2 .

The individually normalized norm of the model vector as a function of α^2 and data misfit is shown in a so-called L-curve (Hansen 1992) in Fig. 3 for the six example orbits. The L-curves are based on the model parameters obtained using the L_1 norm solution. The chosen orbits (nos. 200 (orange), 2000 (yellow), 3334 (dark blue), 6248 (light green), 6493 (light blue), and 8000 (purple)) represent orbit crossings for both disturbed and quiet times.

The range of α^2 was chosen between $10^{-16} \text{nT} \cdot \text{A}^{-2}$ and $10^{-12} \text{nT} \cdot \text{A}^{-2}$. According to Hansen (1992), the optimal choice of α^2 is in, or near, the corner of the L-curve. The corner value of $\alpha^2 = 1.2 \cdot 10^{-15} \text{nT} \cdot \text{A}^{-2}$ (red) seems to provide a good balance between the model misfit and complexity, but a visual inspection of the data fit and current profile revealed unwanted small-scale oscillations. This value was therefore increased slightly to obtain the final choice of $\alpha^2 = 6.4 \cdot 10^{-15} \text{nT} \cdot \text{A}^{-2}$ (approximately the purple marked value, $6.3 \cdot 10^{-15} \text{nT} \cdot \text{A}^{-2}$). The fact that the chosen α^2 stays in almost the same position of the L-curve for different classes of Kp indicates that a common choice in α^2 is possible for different geomagnetic activity conditions.

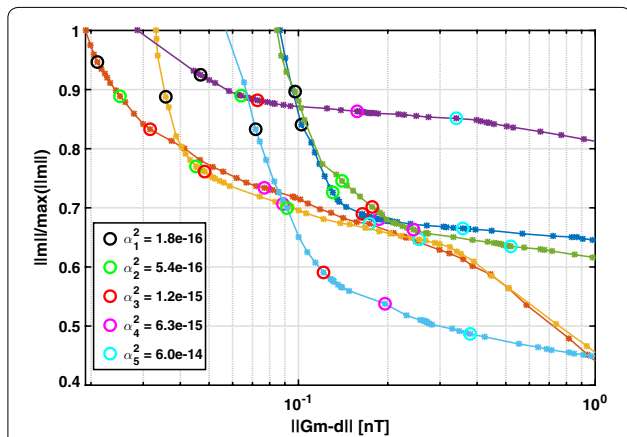


Fig. 3 Normalized L-curves for 6 individual orbits: orbit no. 200 with Kp index of 1⁻ (orange), orbit no. 2000 with Kp index of 1⁺ (yellow), orbit no. 3334 with Kp index of 3⁻ (dark blue), orbit no. 6248 with Kp index of 4⁻ (light green), orbit no. 6493 with Kp index of 0⁺ (light blue), and orbit no. 8000 with Kp index of 1⁺ (purple). Five different α^2 s are highlighted to show how changes in complexity and model fit change with changing values of α^2 , $\alpha_1^2 = 1.8 \cdot 10^{-16} \frac{\text{nT}^2}{\text{A}}$, $\alpha_2^2 = 5.4 \cdot 10^{-16} \frac{\text{nT}^2}{\text{A}}$, $\alpha_3^2 = 1.2 \cdot 10^{-15} \frac{\text{nT}^2}{\text{A}}$, $\alpha_4^2 = 6.3 \cdot 10^{-15} \frac{\text{nT}^2}{\text{A}}$, and $\alpha_5^2 = 6.0 \cdot 10^{-14} \frac{\text{nT}^2}{\text{A}}$

The preferred α^2 will not only depend on the choice of regularization norm, but also on the number of observations, since a change in the size of G will result in a change in the weight between the two terms in the parenthesis of Eq. 5, and hence affect the choice in α^2 . Therefore, we need to be aware that orbits with large data gaps might need a different choice in α^2 .

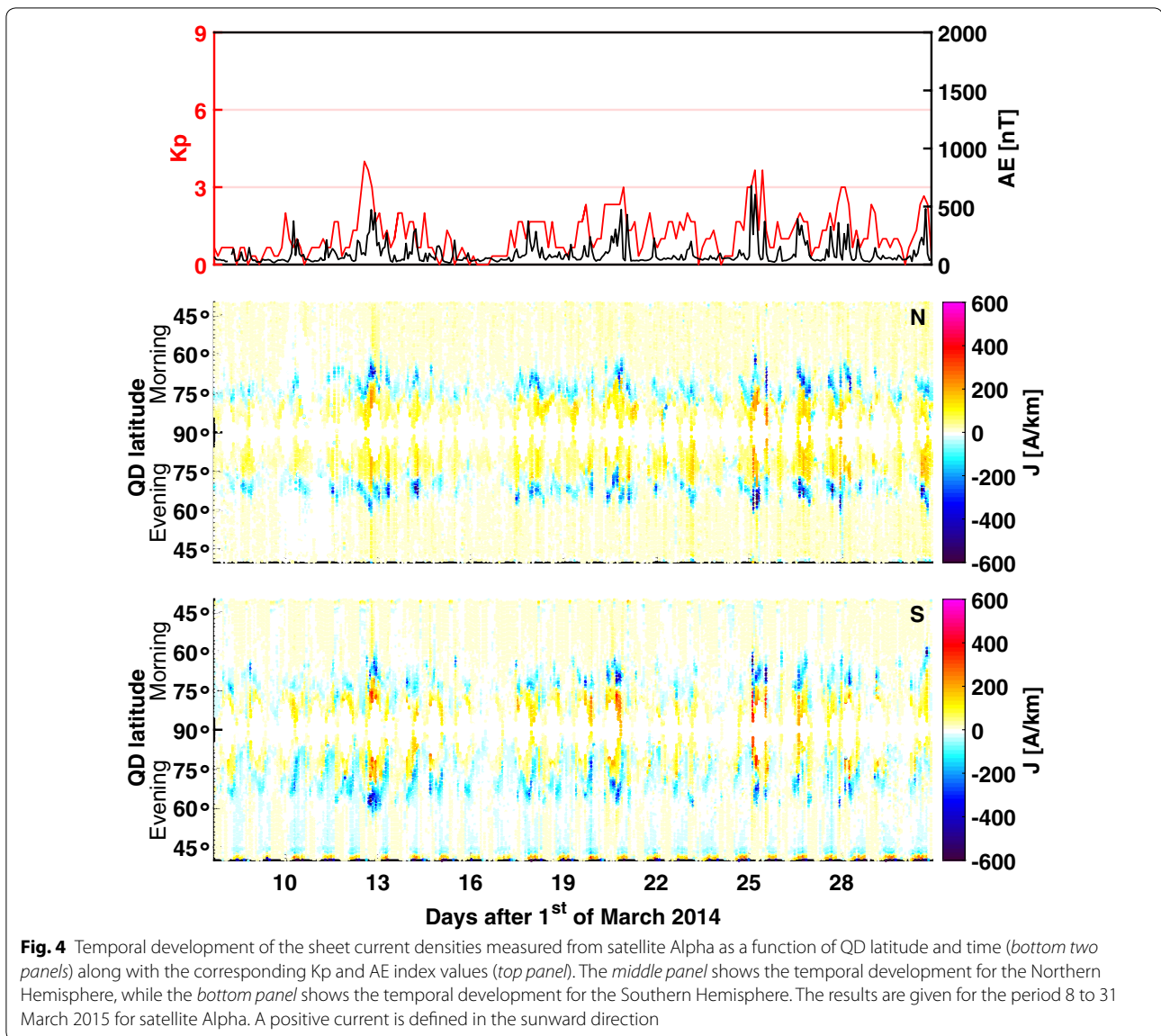
Temporal variations

By looking at periods of several weeks, one can investigate the space–time evolution of ionospheric currents during both disturbed and quiet periods. Studying variations as a function of QD latitude, we can estimate where the currents are located, and whether the location changes with time and/or disturbance level. Figure 4 shows the sheet current densities as a function of time and QD latitude for a period of three weeks around spring equinox 2015 (10 to 31 March 2015). The top plot shows the Kp and AE indices; the Northern (middle panel), respectively, Southern (bottom panel) Hemisphere. Each plot is divided into a morning and an evening side. The sign of the current is defined as positive if directed from midnight to noon (sunward).

The oscillating gap around QD latitude 90 is not zero current, but comes from the satellite orbit inclination compared to the geographical pole and not the magnetic pole. The satellite will therefore only sometimes cross the magnetic pole. We find that the ionospheric electrojet current system is confined to the auroral oval ($\approx 70^\circ$ to 80° QD latitude), and the strengths of the electrojets may therefore be estimated from the sheet current densities in this region. Densities of approximately 1 kA/km near the pole reveal polar cap currents, while the sheet current densities equatorward of the auroral oval are expected to be small. From the temporal development, we can see that deviations from zero at lower latitudes are largest during disturbed periods.

MLT changes by about 1.5 h at non-polar latitudes during the three weeks under consideration; at QD latitude 60° it drifts on the evening side from approximately 20:30 to 19:00 for the example shown in Fig. 4. The period in question is mainly quiet, with low Kp and AE index values (see top plot), but indicates three more active intervals, around 13, 21, and 25 to 28 March 2015. Corresponding higher values of Kp are found for these periods.

Figure 4 reveals a large degree of consistency between the two hemispheres—strong sheet current densities are found in the Northern Hemisphere at the same times as in the Southern Hemisphere, as expected. The small interhemispheric differences may be due to the time difference of 45 min between the pole crossings. This will mainly be an issue during substorms, where changes in the current system can happen very rapidly.

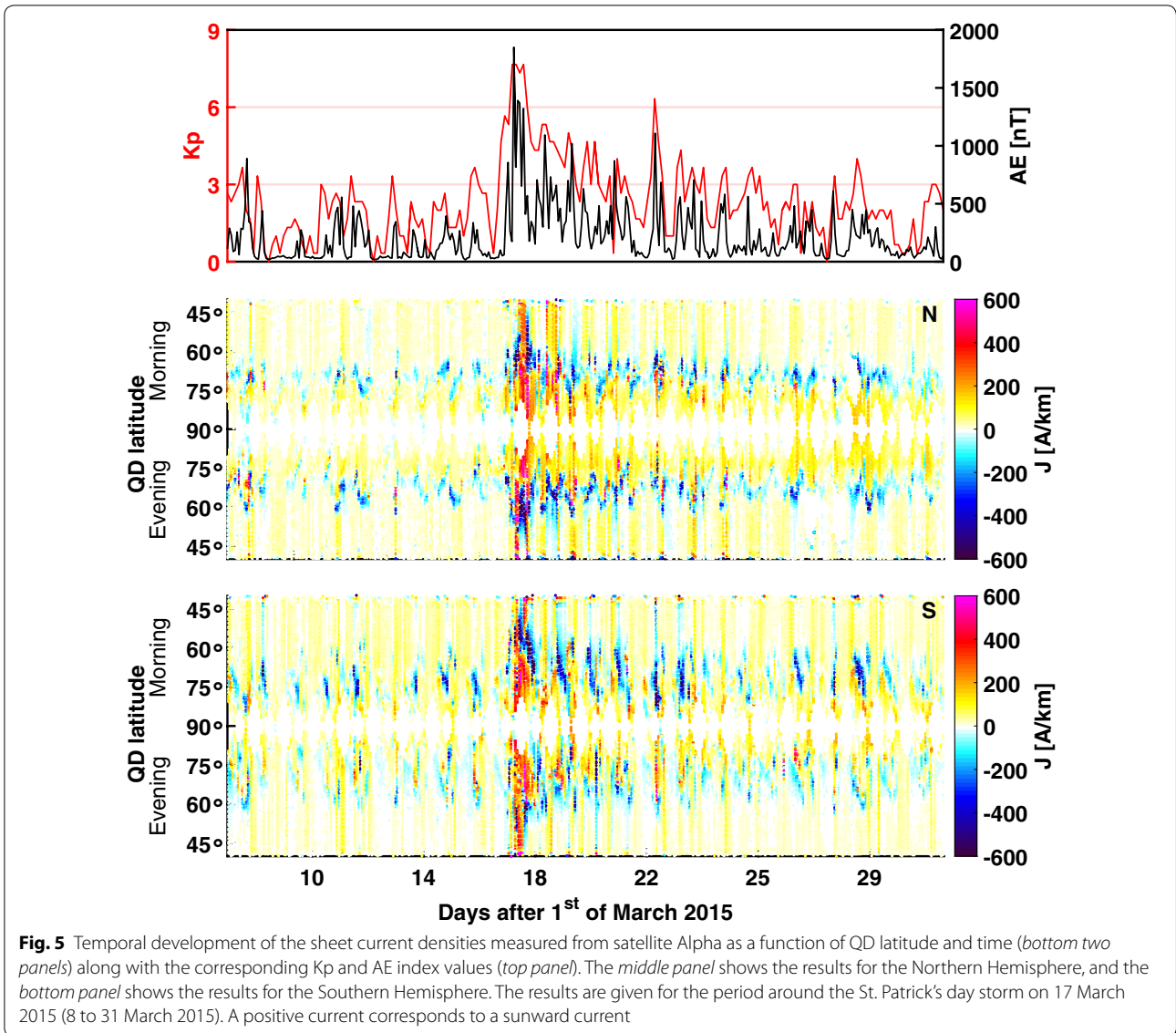


The intensities of the ionospheric currents estimated from this type of plot are a good way to show the development of a substorm event. We see, for example, how quiet periods are followed by a sudden intensification of the currents, and expansion of the auroral oval. An event like this marks the onset of a substorm (Akasofu 1964; McPherron 1991), here showing how plots like these can be used identify substorm events. Despite the rapid changes, especially during disturbed times, and the time of about 20 min that it takes for the satellite to cross one polar hemisphere, we still get a clear picture of the state of the ionospheric current system.

Figure 5 shows an example of a much more disturbed period, namely the period around the St. Patrick's day

storm on 17 March 2015. This was the most severe geomagnetic storm of solar cycle 24, with Kp indices as large as 8⁻, lasting for approximately 18 h. Figure 5 clearly shows how the ionosphere is not only affected during the storm, but also for a long period thereafter. The onset of the storm is difficult to identify due to the effects of a smaller CME ejected from the sun just three days prior to the very large eruption that caused the storm on 17. We see, however, how the oval expands very far south during the storm, consistent with observations of aurora as far south as France.

The interhemispheric differences are larger for the period shown in Fig. 5, compared to that of Fig. 4. This might be due to the more rapid changes during disturbed times but could also indicate interhemispheric



asymmetries. Nevertheless, in both cases we find very similar developments of the sheet current densities.

Auroral Electrojet index

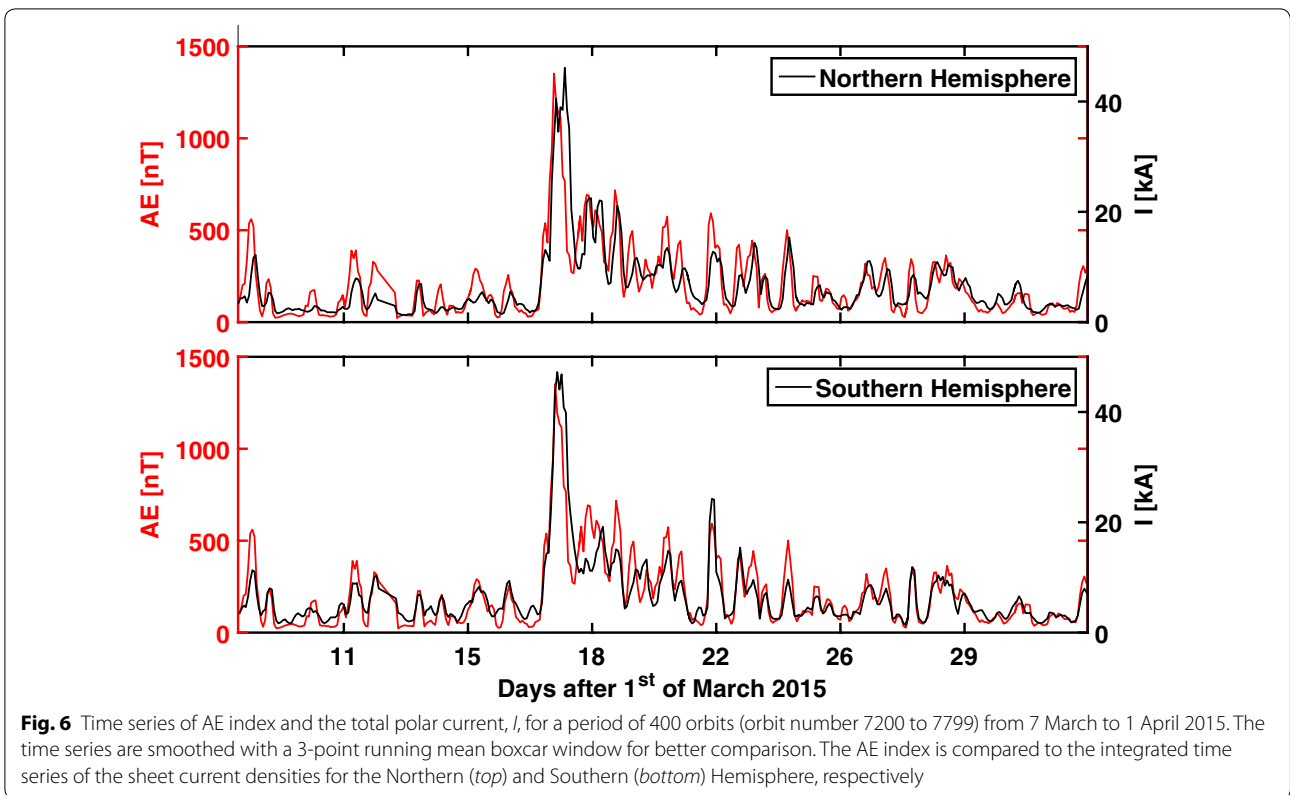
We now compare our estimated sheet current densities with the AE index (Sugiura and Davis 1966). It is derived from geomagnetic variations in the horizontal component at 12 observatories along the northern auroral zone and aims at monitoring auroral electrojet activity (Baker 1985). AE provides an estimate of the combined strengths of Eastward and Westward electrojets. Data are found at the *World Data Center for Geomagnetism* (WDCG 2015).

Here, we compare AE with the total polar current, I ,

$$I = \Delta\beta \int_{-50^\circ}^{50^\circ} |J| d\beta \quad (8)$$

To enable comparison to the sheet current densities, we find the corresponding mean AE index for the period of the selected orbit. An example of this comparison is given in Fig. 6 for the Northern (top) and Southern (bottom) Hemisphere. The AE index is given in red (left y -axis), and the sheet current densities in black (right y -axis). An overall good correlation is found by visual inspection. The total polar current in black follows the AE index very nicely for both the Southern and Northern Hemisphere, despite the fact that they were derived using different methods and data sets (ground-based and spaceborn)

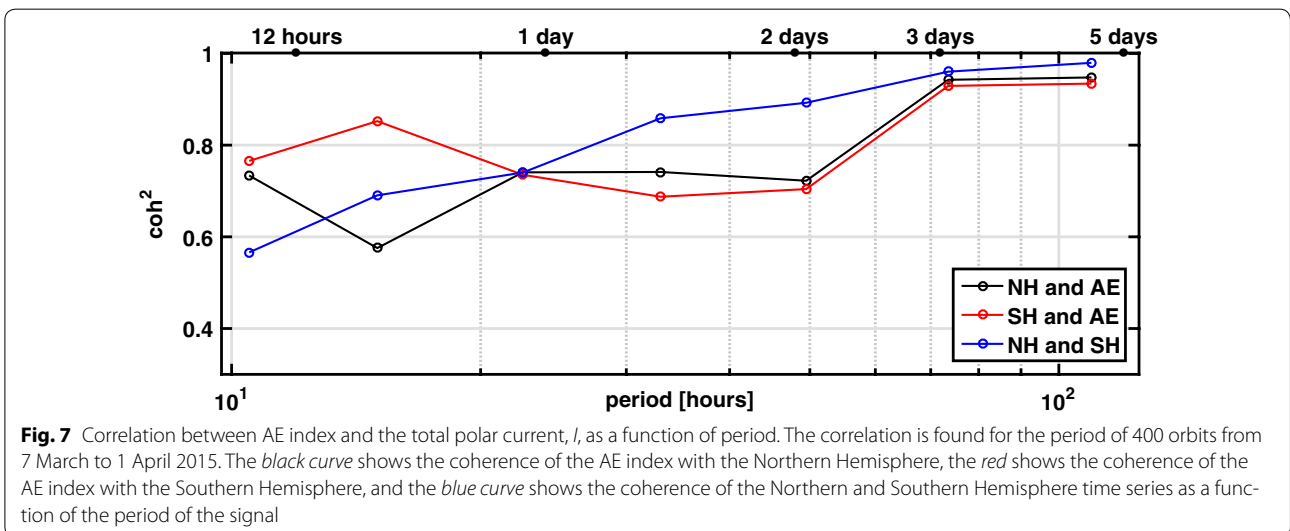
To give an idea of how well the two data series $AE(t)$ and $I(t)$ are correlated, we estimated the squared coherence of the two data series in dependence on frequency, f , and



corresponding period, $T = 1/f$, considering the 400 orbits (orbit number 7200 to 7799) from 7 March to 1 April 2015 given in Fig. 7. The black curve shows the coherence between the Northern Hemisphere sheet current densities and the AE index. The red curve shows the coherence between the Southern Hemisphere sheet current densities and the AE index, and the blue curve shows the coherence

between the sheet current densities for the Northern and Southern Hemisphere. The interval studied here corresponds to a small selection of that presented in Fig. 5.

A Fourier transformation is used to determine $AE(f)$ and the total polar currents ($I(f)$) in the frequency domain. Squared coherence between the two data series are found as a function of T . For all three cases, we find



that the squared coherency for daily variations, and all periods smaller than this, is relatively low, while the squared coherency for periods longer than two days is above 0.9. The interhemispheric coherency is in general a little higher than the coherency with the AE index. The high interhemispheric coherency shows a clear connection between the sheet current densities in the Northern and Southern Hemisphere confining the findings in Fig. 5.

The large coherence values between the total current and the AE index (black and red curve) supports the conclusion from the visual inspection of Figs. 4 and 5 of high correlation between currents (Northern and Southern Hemisphere) and the AE index.

Intersatellites comparison

The AE index provides a good measure of the auroral activity despite some limitations. Summing over longitudes removes any longitudinal dependence of the electrojet activity (see, e.g., Sugiura and Davis 1966). We show here how the integrated absolute values of the sheet current densities measured by satellite give comparable results to the AE index. With the *Swarm* satellite constellation it is not only possible to obtain a result comparable to the AE index, but also to estimate the longitudinal dependence of the electrojets by comparing the satellites Alpha/Charlie and Bravo. An example of the difference between satellite Alpha and Bravo is given in Fig. 8.

Visual inspection of the individual integrated time series of $J(\beta)$ for satellite Alpha and Bravo (top panel) shows high correlation between the two satellites. There are, however, also larger differences mainly during disturbed times. The longitudinal separation between satellites Alpha and Bravo was 24.5° on 17 March 2015 at the equator. The differences are shown in the bottom panel as a function of both magnetic (QD) latitude and time. A positive difference indicates a stronger current for satellite Alpha. Comparing with the temporal development of *Swarm* Alpha (middle plot), we see that the largest differences are found in the auroral oval and during disturbed times (e.g. around 17 March). During disturbed periods, the differences (middle plot) are of comparable size to the sheet current densities found by *Swarm* Alpha (bottom plot). This, together with the longitudinal separation, shows that even smaller longitudinal length scales might be important in auroral electrojet currents during disturbed times.

Sheet current densities from 1000 orbits (orbit number 3000–4000) from Charlie are found to describe 97% of the variance from Alpha. This indicates that our technique is robust and insensitive to small changes in the data set.

Induced currents

Secondary, induced, currents in the electrically conducting Earth's upper mantle and lithosphere have until now

been ignored. They can, however, easily be considered in our current model, by assuming a superconductor at depth, d , acting as a mirror for the primary, ionospheric, currents, placing the induced currents at radius, $r_k = a - 2d$. Induced currents are especially important for observations at ground level, such as directional drilling. The induced currents are implemented in the model by including an additional term (with opposite sign and a different radius of the currents) in the design matrix elements, $g_{n,k}$, presented in Eq. 3. d is set to 125 km, corresponding to a depth of the induced currents of 250 km. The revised design matrix, including the effects of induction, has elements:

$$g_{n,k} = \frac{\mu_0}{2\pi} \left[\frac{\xi_{n,k} \cos I_n + \eta_{n,k} \sin I_n}{\xi_{n,k}^2 + \eta_{n,k}^2} - \frac{(\xi_{n,k})_j \cos I_n + (\eta_{n,k})_j \sin I_n}{(\xi_{n,k})_j^2 + (\eta_{n,k})_j^2} \right]. \quad (9)$$

$$(\eta_{n,k})_j = (a - 2d) \sin(\beta_n - \beta_k) \quad (10)$$

$$(\xi_{n,k})_j = r_n - (a - 2d) \cos(\beta_n - \beta_k). \quad (11)$$

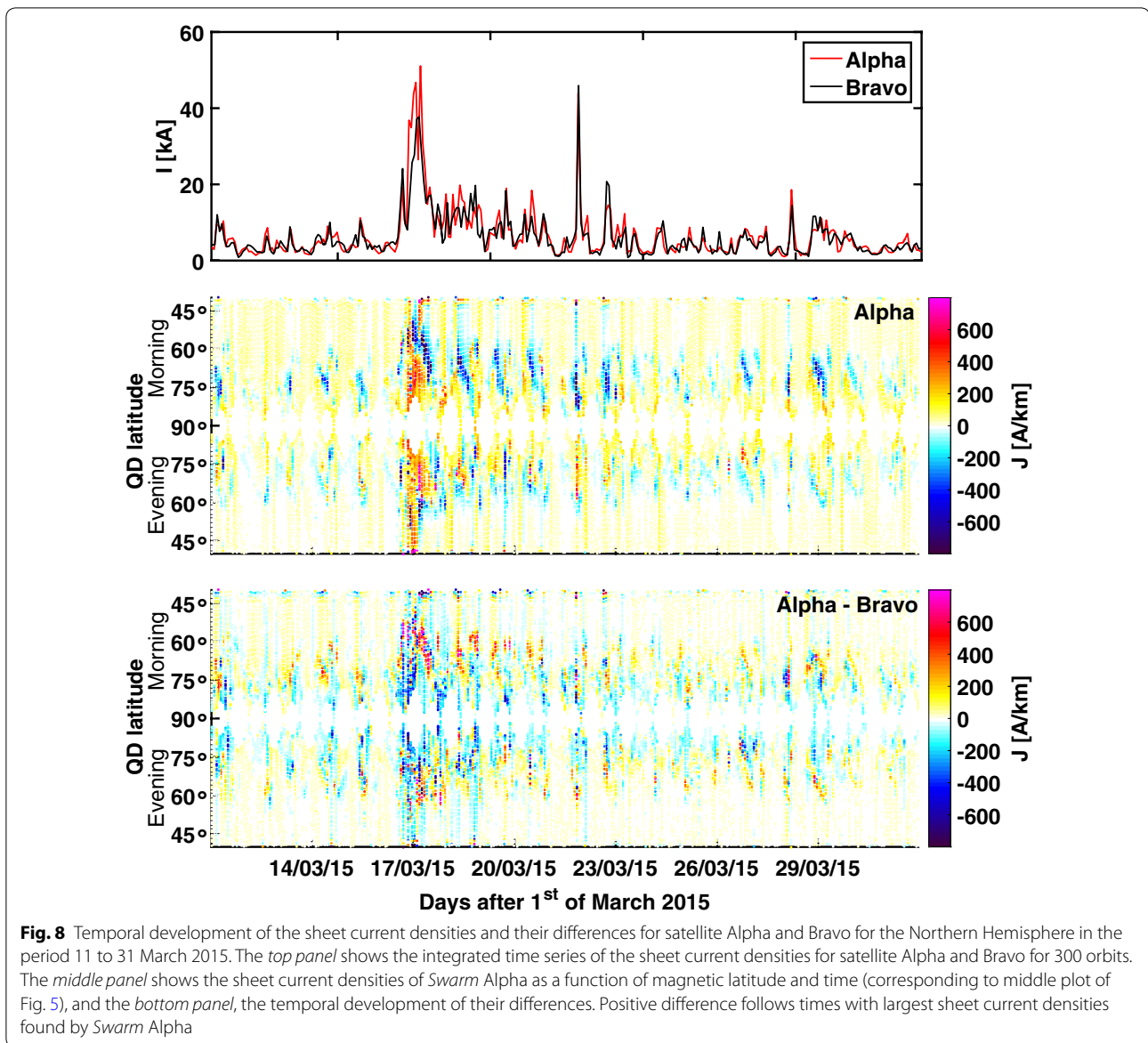
Figure 9 shows the magnetic field estimation (top), the residual magnetic field (middle), and the sheet current density (bottom) for orbit 6493 on 20 January 12:37 to 13:02 UT if induced currents are considered. Comparisons with Fig. 2 (without induced currents) reveal no significant changes in position or in the strength of the sheet current densities.

Conclusions and outlook

The magnetic perturbations due to ionospheric auroral electrojet current system were estimated by applying the line current model of Olsen (1996) to magnetic observations taken by the three satellites Alpha, Bravo, and Charlie of the *Swarm* satellite constellation. Sheet current densities were obtained using two different inversion methods: (1) minimization of an L_2 norm of the model parameters and a Huber-weighted misfit measure and (2) minimization of an L_1 norm of the second-order spatial differences of model parameters and a Huber-weighted misfit measure. The method is illustrated with examples from single orbits with model predictions that match very well the observations for both L_1 and L_2 norm models.

The L_1 norm solution is preferred since it leads to current profiles with weaker currents in non-polar regions. In addition, the distribution of model parameters possessed long tails, favouring the L_1 norm approach.

A study of the regularization parameter, α^2 , revealed that a common choice was possible for all tested orbits. This indicates a robust model, not sensitive to disturbance level or other orbit sensitive factors. The tests also indicate that the results are fairly insensitive to the exact



choice of α^2 . Model robustness was tested by comparing results obtained with data from the side-by-side flying satellites Alpha and Charlie: currents derived with Charlie describe more than 97 % of those derived from Alpha.

Investigations of the time dependence of the sheet current densities for the two hemispheres showed a clear difference between disturbed and quiet times. They also revealed a very high consistency between the two hemispheres, with largest differences occurring during disturbed periods which are attributed to the fast changes in the ionospheric current system during these times. The visual consistency is backed up by a squared coherence analysis that revealed a value of more than 0.9 for periods larger than two days.

Comparison to the AE index also showed a very high squared coherence value (≈ 0.9) for periods longer than two days for the Northern and Southern Hemisphere.

The line currents in this study are placed perpendicular to the satellite track. This can lead to a systematic underestimation of the sheet current densities, dependent on the angle with the actual current. The effect will therefore be largest in the region around the poles, though it will differ from orbit to orbit, dependent on the satellite track. A more accurate approach would be to assume the currents to be parallel to magnetic latitude.

The results pave the way for further research possibilities, such as combining the height-integrated current density estimates with measurements from the *Swarm*

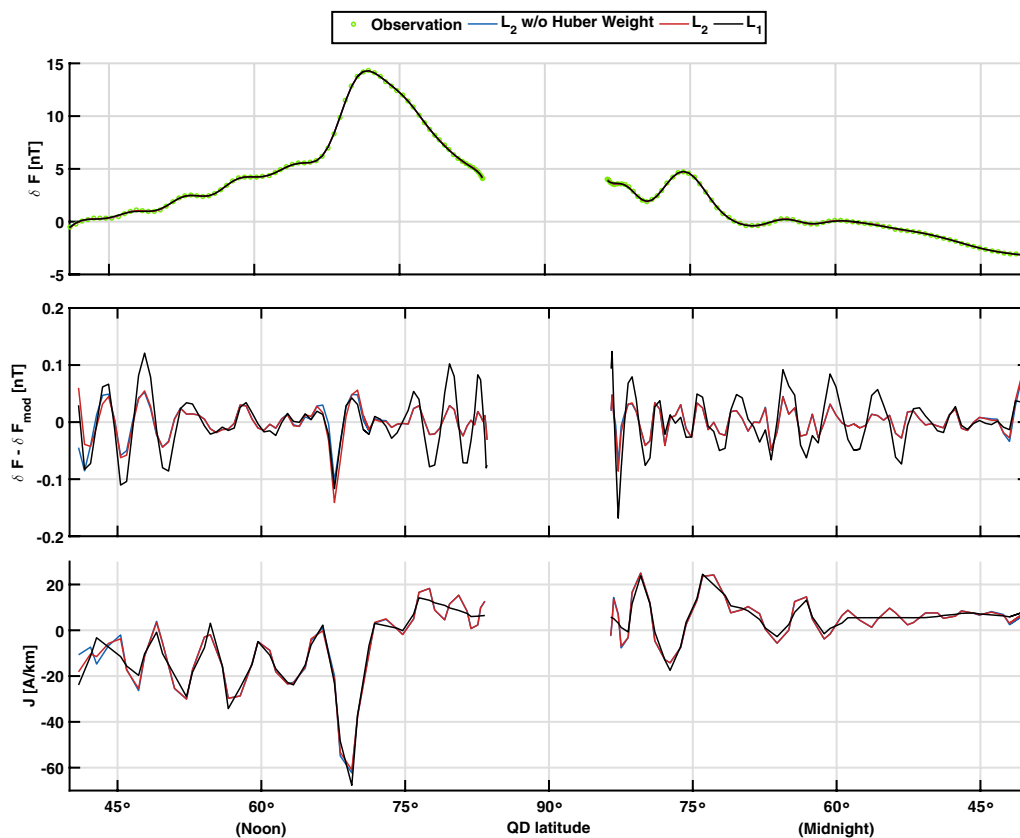


Fig. 9 Corresponding to Fig. 2 for Swarm Alpha, orbit 6493 on 20.01.2015 12:37 to 13:02 UT, including induced currents. The *top panel* shows observations, δF , in green along with the model predictions, δF^{mod} , for three solution methods, L_1 norm (black), L_2 norm (red), and L_2 norm without Huber-weighted misfit (blue). The *middle panel* shows the model residuals, $\Delta\delta F$, for the same inversion methods, and the *bottom panel* shows the corresponding sheet current densities, J , again for all three methods. The sheet current densities are found using $\alpha^2 = 6.5 \cdot 10^{-15} \frac{\text{nT}^2}{\text{A}}$ for the L_1 norm solution and $\alpha^2 = 1 \cdot 10^{-26} \frac{\text{nT}^2}{\text{A}^2}$ for the L_2 norm solutions. A positive current flows from midnight to noon (sunward)

Electric Field Instrument to derive height-integrated Hall conductivities.

Overall, we found that the line current model provides useful estimates of the polar ionospheric sheet current densities. The robustness of the method and the fact that the method worked for all tested orbits reveal a clear opportunity for automatic application and near-real-time estimations of the ionospheric sheet current densities.

Authors' contributions

CDA coded the model, carried out the data analysis, and drafted the manuscript. NO and CCF participated in key discussions of the model and data analysis. All authors read and approved the final manuscript.

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Competing interests

The authors declare that they have no competing interests.

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