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Three kinds of new hybrid projection methods for a finite family of quasi-asymptotically pseudocontractive mappings in Hilbert spaces

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Abstract

In the present paper, we propose three kinds of new algorithms for a finite family of quasi-asymptotically pseudocontractive mappings in real Hilbert spaces. By using some new analysis techniques, we prove the strong convergence of the proposed algorithms. Some numerical examples are also included to illustrate the effectiveness of the proposed algorithms. The results presented in this paper are interesting extensions of those well-known results.

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1 Introduction

Throughout this paper, we assume that H is a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and the induced norm $\| \cdot \|$, respectively. Let C be a nonempty, closed, and convex subset of H and $T : C \rightarrow C$ a self-mapping of C into itself. We use $\text{Fix}(T)$ to denote the fixed point set of T , i.e., $\text{Fix}(T) = \{x \in C : x = Tx\}$.

Over the past century or so, fixed point theory of Lipschitzian and non-Lipschitzian mappings has been developed into a really important and active field of study in both pure and applied mathematics. Especially, the research on the existence and convergence of fixed points for nonexpansive mappings and pseudocontractive mappings in the framework of Hilbert and Banach spaces has made great advancements since 1965; see, for instance, [1–3] and the references therein.

As generalizations of nonexpansive mappings and pseudocontractive mappings, the classes of asymptotically nonexpansive mappings and asymptotically pseudocontractive mappings were introduced by some authors, respectively; see, for instance, [4–6].

Let E be a Banach space and C a nonempty subset of E .

Recall that a mapping $T : C \rightarrow C$ is said to be asymptotically nonexpansive [4] if there exists a sequence $\{k_n\}$ of positive real numbers with $k_n \rightarrow 1$ such that

$$\|T^n x - T^n y\| \leq k_n \|x - y\|, \quad (1.1)$$

for all $x, y \in C$ and all $n \geq 1$.

The class of asymptotically nonexpansive mappings was introduced by Goebel and Kirk [4] in 1972. From (1.1), we know that if T is nonexpansive, then it is asymptotically nonexpansive with a constant sequence $\{1\}$, but the converse may be not true in general, which can be seen from the example in [4] that is asymptotically nonexpansive but it is not nonexpansive, thus, the class of asymptotically nonexpansive mappings includes properly the class of nonexpansive mappings as a subclass. An early fundamental result, due to Goebel and Kirk [4], states that if C is a nonempty, bounded, closed, and convex subset of a uniformly convex Banach space E , then every asymptotically nonexpansive self-mapping T of C has a fixed point. Further, the set $\text{Fix}(T)$ of fixed points of T is closed and convex. Since 1972, many authors have studied the weak and strong convergence problems of the iterative algorithms for such a class of mappings; see, for instance, [7–9] and the references therein.

The class of asymptotically pseudocontractive mappings was introduced by Schu [5] in 1991.

Recall that a mapping $T : C \rightarrow H$ is called asymptotically pseudocontractive if there exists a sequence $\{k_n\} \subset [1, \infty)$ with $k_n \rightarrow 1$ for which the following inequality holds:

$$\langle T^n x - T^n y, x - y \rangle \leq k_n \|x - y\|^2, \tag{1.2}$$

for all $x, y \in C$ and all $n \geq 1$.

T is said to be quasi-asymptotically pseudocontractive if $\text{Fix}(T) \neq \emptyset$ and there exists a sequence $\{k_n\} \subset [1, \infty)$ with $k_n \rightarrow 1$ for which the following inequality holds:

$$\langle T^n x - p, x - p \rangle \leq k_n \|x - p\|^2, \tag{1.3}$$

for all $x \in C, p \in \text{Fix}(T)$ and all $n \geq 1$.

Without loss of generality, we can assume that $1 \leq k_n < 2$, for all $n \geq 1$.

In 1996, Liu [6] introduced the class of κ -strictly asymptotically pseudocontractive mappings in Hilbert spaces. A mapping $T : C \rightarrow C$ is called κ -strictly asymptotically pseudocontractive if there exist some $\kappa \in [0, 1)$ and some real sequence $\{k_n\} \subset [1, \infty)$ with $k_n \rightarrow 1$ such that

$$\|T^n x - T^n y\|^2 \leq k_n^2 \|x - y\|^2 + \kappa \|(I - T^n)x - (I - T^n)y\|^2, \tag{1.4}$$

for all $x, y \in C$ and all $n \geq 1$.

A mapping $T : C \rightarrow C$ is called quasi- κ -strictly asymptotically pseudocontractive if $\text{Fix}(T) \neq \emptyset$, and there exist some $\kappa \in [0, 1)$ and some real sequence $\{k_n\} \subset [1, \infty)$ with $k_n \rightarrow 1$ such that

$$\|T^n x - y\|^2 \leq k_n^2 \|x - y\|^2 + \kappa \|(I - T^n)x\|^2, \tag{1.5}$$

for all $x \in C, y \in \text{Fix}(T)$ and $n \geq 1$.

A mapping $T : C \rightarrow C$ is said to be uniformly L -Lipschitzian if there exists some $L > 0$ such that

$$\|T^n x - T^n y\| \leq L \|x - y\|, \tag{1.6}$$

for all $x, y \in C$ and for all $n \geq 1$.

Remark 1.1 We note that every κ -strictly asymptotically pseudocontractive mapping is uniformly L -Lipschitzian with the Lipschitz constant $L = \frac{M+\sqrt{\kappa}}{1-\sqrt{\kappa}}$, where $M = \sup_n \{k_n\}$. In particular, every asymptotically nonexpansive mapping is uniformly L -Lipschitzian with $L = \sup\{k_n : n \geq 1\}$.

Remark 1.2 It is clear that every asymptotically nonexpansive mapping is 0-strictly asymptotically pseudocontractive; while every asymptotically pseudocontractive mapping with sequence $\{k_n\}$ is 1-strictly asymptotically pseudocontractive with sequence $\{2k_n - 1\}$.

Remark 1.3 It is also clear that every asymptotically pseudocontractive mapping with $\text{Fix}(T) \neq \emptyset$ is quasi-asymptotically pseudocontractive, but the converse may be not true in general, which can be seen from the following counterexample.

Take $C = [0, 2\pi]$ and define a mapping $T : C \rightarrow \mathbb{R}$ by

$$Tx = \frac{2}{3}x \cos(x), \quad x \in C.$$

Then T is quasi-asymptotically pseudocontractive, but it is not asymptotically pseudocontractive. Indeed, assume that $x = Tx$, then $x = 0$, and hence $\text{Fix}(T) = \{0\}$.

For all $x \in C$, we have

$$|Tx - 0| = \left| \frac{2}{3}x \cos(x) \right| \leq |x - 0|,$$

which means that T is quasi-nonexpansive, and hence it is quasi-asymptotically pseudocontractive. On the other hand, if we take $x = 2\pi$ and $y = \pi$, then we have

$$\langle Tx - Ty, x - y \rangle = 2\pi^2 \geq k_1\pi^2 = k_1|x - y|^2,$$

which means that T is not asymptotically pseudocontractive.

Remark 1.4 The class of asymptotically pseudocontractive mappings is a generalization of the class of pseudocontractive mappings, and the former contains properly the class of asymptotically nonexpansive mappings as a subclass, which can be seen from the following example.

For $x \in [0, 1]$, define a mapping $T : [0, 1] \rightarrow [0, 1]$ by

$$Tx = \left(1 - x^{\frac{2}{3}}\right)^{\frac{3}{2}}, \quad x \in [0, 1].$$

Then T is asymptotically pseudocontractive but it is not asymptotically nonexpansive.

Recently, as a generalization of Haugazeau’s algorithm, the so-called hybrid projection algorithm was developed rapidly for finding the nearest fixed point of certain quasi-nonexpansive mappings; see, for instance, Bauschke and Combettes [10] and the references therein.

By virtue of the hybrid projection methods, Nakajo and Takahashi [11] established some strong convergence results for nonexpansive mappings and nonexpansive semigroups in

a real Hilbert space; Marino and Xu [12] proved a strong convergence theorem for strict-pseudo-contractions in a real Hilbert space; Zhou [13] extended Marino and Xu's strong convergence theorem to the more general class of Lipschitz pseudocontractive mappings; Zhou [14] generalized and extended the main results of [13] to the class of asymptotically pseudocontractive mappings; Zhou and Su [15] further extended the main results in [14] to a family of uniformly L -Lipschitz continuous and quasi-asymptotically pseudocontractive mappings.

We observe that the construction of the half-spaces C_n in [15] is complicated, and hence the computation of the metric projections P_{C_n, x_1} is difficult.

Our concern now is the following: Can one design some simple and new hybrid projection algorithms for finding a common fixed point for a finite family of quasi-asymptotically pseudocontractive mappings?

The purpose of this paper is to propose three kinds of new hybrid projection algorithms for constructing a common fixed point of a finite family of quasi-asymptotically pseudocontractive mappings in a real Hilbert space. By using some new analysis techniques, we prove the strong convergence of the proposed algorithms. Some numerical examples are also included to illustrate the effectiveness of the proposed algorithms. The results presented in this paper improve and extend the related ones obtained by some authors.

2 Preliminaries

For uniformly L -Lipschitzian mappings, the following fixed point theorem is well known; see, for example, Cassini and Maluta [16].

Theorem CM *Let E be a uniformly convex Banach space with $N(E) > 1$, C be a nonempty, bounded, and closed convex subset of E and $T : C \rightarrow C$ be a uniformly L -Lipschitzian mapping. If $L < \sqrt{N(E)}$, where $N(E)$ denotes the normal structure coefficient of E , then T has a fixed point in C .*

Remark 2.1 It is well known that $N(H) = \sqrt{2}$. Thus, in the setting of a Hilbert space H , every uniformly L -Lipschitzian mapping $T : C \rightarrow C$ from a nonempty, bounded, and closed convex subset C of H into itself has a fixed point in C provided that $L < \sqrt[4]{2}$.

In [14], a fixed point theorem was established for asymptotically pseudocontractive mappings in Hilbert spaces.

Theorem Z *Let C be a nonempty, bounded, and closed convex subset of a real Hilbert space H and $T : C \rightarrow C$ be a uniformly L -Lipschitzian and asymptotically pseudocontractive mapping which is also uniformly asymptotically regular, i.e., $\lim_{n \rightarrow \infty} \sup_{x \in C} \{\|T^{n+1}x - T^n x\|\} = 0$. Then T has a fixed point in C .*

Theorem Z is the first fixed point theorem for asymptotically pseudocontractive mappings in Hilbert spaces, which is of importance and interest.

Let C be a nonempty, closed, and convex subset of a real Hilbert space H . For every point $x \in H$ there exists a unique nearest point in C , denoted by $P_C x$, such that

$$\|x - P_C x\| \leq \|x - y\|, \quad \text{for all } y \in C, \quad (2.1)$$

where P_C is called the metric projection of H onto C . We know that P_C is a nonexpansive mapping.

The following first two lemmas are well known.

Lemma 2.1 (see, e.g., [1–3]) *Let C be a nonempty, closed, and convex subset of real Hilbert space H . Given $x \in H$ and $z \in C$. Then $z = P_C x$ if and only if we have the relation*

$$\langle x - z, y - z \rangle \leq 0, \quad \text{for all } y \in C. \tag{2.2}$$

Lemma 2.2 (see, e.g., [1–3]) *Let C be a nonempty closed convex subset of a real Hilbert space H and $P_C : H \rightarrow C$ be the metric projection from H onto C . Then the following inequality holds:*

$$\|y - P_C x\|^2 + \|x - P_C x\|^2 \leq \|x - y\|^2, \quad \forall x \in H, \forall y \in C. \tag{2.3}$$

The next lemma is due to Zhou and Su [15]. For the sake of completeness, we include its proof here.

Lemma 2.3 *Let C be a nonempty, bounded, and closed convex subset of a real Hilbert space H . Let $T : C \rightarrow C$ be a uniformly L -Lipschitzian and quasi-asymptotically pseudocontractive mapping. Then $\text{Fix}(T)$ is a closed convex subset of C .*

Proof Since T is uniformly L -Lipschitzian continuous, $\text{Fix}(T)$ is closed. We need to show that $\text{Fix}(T)$ is convex. To this aim, let $p_i \in \text{Fix}(T)$ ($i = 1, 2$) and write $p = tp_1 + (1 - t)p_2$ for $t \in (0, 1)$. We plan to show that $p = Tp$. To see this, we take $\alpha \in (0, \frac{1}{1+L})$, and define $y_{\alpha,n} = (1 - \alpha)p + \alpha T^n p$ for each $n \geq 1$. Then, in view of the quasi-asymptotic pseudocontractiveness of T , we have, $\forall z \in \text{Fix}(T)$,

$$\begin{aligned} \|p - T^n p\|^2 &= \langle p - T^n p, p - T^n p \rangle \\ &= \frac{1}{\alpha} \langle p - y_{\alpha,n}, p - T^n p \rangle \\ &= \frac{1}{\alpha} \langle p - y_{\alpha,n}, p - T^n p - (y_{\alpha,n} - T^n y_{\alpha,n}) \rangle + \frac{1}{\alpha} \langle p - y_{\alpha,n}, y_{\alpha,n} - T^n y_{\alpha,n} \rangle \\ &\leq \frac{1+L}{\alpha} \|p - y_{\alpha,n}\|^2 + \frac{1}{\alpha} \langle p - z, y_{\alpha,n} - T^n y_{\alpha,n} \rangle \\ &\quad + \frac{1}{\alpha} \langle z - y_{\alpha,n}, (I - T^n) y_{\alpha,n} \rangle \\ &\leq \frac{1+L}{\alpha} \|p - y_{\alpha,n}\|^2 + \frac{1}{\alpha} \langle p - z, (I - T^n) y_{\alpha,n} \rangle + \frac{1}{\alpha} (k_n - 1) (\text{diam } C)^2 \\ &= \alpha(1+L) \|p - T^n p\|^2 + \frac{1}{\alpha} \langle p - z, (I - T^n) y_{\alpha,n} \rangle \\ &\quad + \frac{1}{\alpha} (k_n - 1) (\text{diam } C)^2, \end{aligned}$$

from which it turns out that

$$\alpha [1 - (1+L)\alpha] \|p - T^n p\|^2 \leq \langle p - z, (I - T^n) y_{\alpha,n} \rangle + (k_n - 1) (\text{diam } C)^2. \tag{2.4}$$

Taking $z = p_i$ ($i = 1, 2$) in (2.4), multiplying t and $(1 - t)$ on both sides of (2.4), respectively, and adding up yield

$$\alpha[1 - (1 + L)\alpha] \|p - T^n p\|^2 \leq (k_n - 1)(\text{diam } C)^2. \tag{2.5}$$

Letting $n \rightarrow \infty$ in (2.5) yields $T^n p \rightarrow p$. Since T is continuous, we have $T^{n+1} p \rightarrow Tp$ as $n \rightarrow \infty$, so that $p = Tp$. This proves that $\text{Fix}(T)$ is a closed convex subset of C . \square

Remark 2.2 In the proof of Lemma 2.3 above, the assumption of quasi-asymptotic pseudocontractiveness of mapping T has been used.

3 Main results

In this section, we present three kinds of new hybrid projection algorithms for finding a common fixed point for a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings in Hilbert spaces. Let N be a fixed positive integer. We put $I = \{0, 1, 2, \dots, N - 1\}$. For any positive integer n , we write $n = (h(n) - 1)N + i(n)$, where $h(n) \rightarrow \infty$ as $n \rightarrow \infty$ and $i(n) \in I$, for all $n \geq 0$.

First, we prove the following strong convergence theorem for a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings in Hilbert spaces.

Theorem 3.1 *Let C be a bounded, closed, and convex subset of a real Hilbert space H . Let $\{T_i\}_{i=0}^{N-1} : C \rightarrow C$ be a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings such that $F = \bigcap_{i=0}^{N-1} \text{Fix}(T_i) \neq \emptyset$. Assume the control sequence $\{\alpha_n\}$ is chosen so that $\alpha_n \in [a, b]$ for some $a, b \in (0, \frac{1}{1+L})$, where $L = \max\{L_i : 0 \leq i \leq N - 1\}$. Let a sequence $\{x_n\}$ be generated by the following manner:*

$$\begin{cases} x_0 \in C \text{ chosen arbitrarily,} \\ y_n = (1 - \alpha_n)x_n + \alpha_n T_{i(n)}^{h(n)} x_n, \quad n \geq 0, \\ C_n = \{z \in C : \alpha_n [1 - (1 + L)\alpha_n] \|x_n - T_{i(n)}^{h(n)} x_n\|^2 \\ \leq \langle x_n - z, (y_n - T_{i(n)}^{h(n)} y_n) \rangle + (k_{h(n)} - 1)(\text{diam } C)^2\}, \quad n \geq 0, \\ Q_0 = C, \\ Q_n = \{z \in Q_{n-1} : \langle z - x_n, x_0 - x_n \rangle \leq 0\}, \quad n \geq 1, \\ x_{n+1} = P_{C_n \cap Q_n} x_0, \quad n \geq 0, \end{cases} \tag{3.1}$$

where $k_{h(n)} = \max\{k_{h(n),i(n)} : 0 \leq i(n) \leq N - 1\}$ and $k_{h(n),i(n)}$ are asymptotic sequences for $\{T_i\}_{i=0}^{N-1}$. Then the sequence $\{x_n\}$ generated by (3.1) converges strongly to $P_F x_0$.

Proof We split the proof into ten steps.

Step 1. Show that $P_F x_0$ is well defined for every $x_0 \in C$.

By Lemma 2.3, we know that $\text{Fix}(T_i)$ is a closed convex subset of C for every $i \in I$. Hence, $F = \bigcap_{i=0}^{N-1} \text{Fix}(T_i)$ is a nonempty, closed, and convex subset of C , consequently, $P_F x_0$ is well defined for every $x_0 \in C$.

Step 2. Show that both C_n and Q_n are closed and convex, for all $n \geq 0$. This follows from the constructions of C_n and Q_n . We omit the details.

Step 3. Show that

$$F \subset C_n \cap Q_n, \quad \text{for all } n \geq 0. \tag{3.2}$$

To this aim, we prove first that $F \subset C_n$, for all $n \geq 0$.

Using (3.2), the uniform L_i -Lipschitz continuity of T_i and quasi-asymptotic pseudocontractiveness of T_i , we obtain, for any $z \in F$,

$$\begin{aligned} \|x_n - T_{i(n)}^{h(n)} x_n\|^2 &= \langle x_n - T_{i(n)}^{h(n)} x_n, x_n - T_{i(n)}^{h(n)} x_n \rangle \\ &= \frac{1}{\alpha_n} \langle x_n - y_n, x_n - T_{i(n)}^{h(n)} x_n \rangle \\ &= \frac{1}{\alpha_n} \langle x_n - y_n, (I - T_{i(n)}^{h(n)})x_n - (I - T_{i(n)}^{h(n)})y_n \rangle \\ &\quad + \frac{1}{\alpha_n} \langle x_n - y_n, (I - T_{i(n)}^{h(n)})y_n \rangle \\ &\leq \frac{1+L}{\alpha_n} \|x_n - y_n\|^2 + \frac{1}{\alpha_n} \langle x_n - z, (I - T_{i(n)}^{h(n)})y_n \rangle \\ &\quad + \frac{1}{\alpha_n} (k_{h(n)} - 1)(\text{diam } C)^2 \\ &= (1+L)\alpha_n \|x_n - T^n x_n\|^2 + \frac{1}{\alpha_n} \langle x_n - z, (I - T_{i(n)}^{h(n)})y_n \rangle \\ &\quad + \frac{1}{\alpha_n} (k_{h(n)} - 1)(\text{diam } C)^2, \end{aligned}$$

from which it turns out that

$$\alpha_n [1 - (1+L)\alpha_n] \|x_n - T_{i(n)}^{h(n)} x_n\|^2 \leq \langle x_n - z, (I - T_{i(n)}^{h(n)})y_n \rangle + (k_{h(n)} - 1)(\text{diam } C)^2, \tag{3.3}$$

which shows that $z \in C_n$, for all $n \geq 0$. This proves that $F \subset C_n$, for all $n \geq 0$.

As shown in Marino and Xu [12], by a simple induction, we can show that

$$F \subset Q_n, \quad \text{for all } n \geq 0. \tag{3.4}$$

Because this is routine, we omit the details. We have shown that (3.2) holds. Hence $P_{C_n \cap Q_n} x_0$ is well defined. Consequently, the iteration algorithm (3.1) is well defined.

Step 4. Show that $\lim_{n \rightarrow \infty} \|x_n - x_0\|$ exists.

In view of (3.1) and Lemma 2.1, we have $x_n = P_{Q_n} x_0$ and $x_{n+1} \in Q_n$, which means that $\|x_n - x_0\| \leq \|x_{n+1} - x_0\|$, for all $n \geq 0$. As $z \in F \subset Q_n$, we have also $\|x_n - x_0\| \leq \|z - x_0\|$, consequently, $\lim_{n \rightarrow \infty} \|x_n - x_0\|$ exists.

Step 5. Show that $x_{n+1} - x_n \rightarrow 0$ as $n \rightarrow \infty$.

By using Lemma 2.2, we have

$$\|x_{n+1} - x_n\|^2 \leq \|x_{n+1} - x_0\|^2 - \|x_n - x_0\|^2 \rightarrow 0$$

as $n \rightarrow \infty$.

Step 6. Show that $x_n - T_{i(n)}^{h(n)} x_n \rightarrow 0$ as $n \rightarrow \infty$.

It follows from Step 5 that $x_{n+1} - x_n \rightarrow 0$ as $n \rightarrow \infty$. Since $x_{n+1} \in C_n$, noting that $\alpha_n \in [a, b]$ for $a, b \in (0, \frac{1}{1+L})$, $\{y_n\}$ and $\{T_{i(n)}^{h(n)} y_n\}$ are all bounded, from the definition of C_n , we have $x_n - T_{i(n)}^{h(n)} x_n \rightarrow 0$ as $n \rightarrow \infty$.

Step 7. Show that $x_n - T_{i(n)} x_n \rightarrow 0$ as $n \rightarrow \infty$.

Since $n = (h(n) - 1) + i(n)$, we have

$$n - N = (h(n) - 1 - 1)N + i(n).$$

On the other hand, since $n - N = (h(n - N) - 1)N + i(n - N)$, we have $h(n) - 1 = h(n - N)$ and $i(n) = i(n - N)$. Observe that

$$\begin{aligned} \|x_n - T_{i(n)}x_n\| &\leq \|x_n - T_{i(n)}^{h(n)}x_n\| + \|T_{i(n)}^{h(n)}x_n - T_{i(n)}x_n\| \\ &\leq \|x_n - T_{i(n)}^{h(n)}x_n\| + L\|T_{i(n)}^{h(n)-1}x_n - x_n\| \\ &\leq \|x_n - T_{i(n)}^{h(n)}x_n\| + L\|T_{i(n)}^{h(n-N)}x_n - T_{i(n-N)}^{h(n-N)}x_{n-N}\| \\ &\quad + \|T_{i(n-N)}^{h(n-N)}x_{n-N} - x_{n-N}\| + \|x_{n-N} - x_n\| \\ &\leq \|x_n - T_{i(n)}^{h(n)}x_n\| + (1 + L^2)\|x_{n-N} - x_n\| + \|T_{i(n-N)}^{h(n-N)}x_{n-N} - x_{n-N}\|, \end{aligned}$$

from which it turns out that $x_n - T_{i(n)}x_n \rightarrow 0$ as $n \rightarrow \infty$ in view of Steps 5 and 6.

Step 8. Show that $\forall j \in I, x_n - T_{i(n)+j}x_n \rightarrow 0$ as $n \rightarrow \infty$.

Observing that

$$\begin{aligned} \|x_n - T_{i(n)+j}x_n\| &\leq \|x_n - x_{n+j}\| + \|x_{n+j} - T_{i(n)+j}x_{n+j}\| \\ &\quad + \|T_{i(n)+j}x_{n+j} - T_{i(n)+j}x_n\| \\ &\leq \|x_n - x_{n+j}\| + \|x_{n+j} - T_{i(n)+j}x_{n+j}\| + L\|x_{n+j} - x_n\| \\ &= (1 + L)\|x_n - x_{n+j}\| + \|x_{n+j} - T_{i(n)+j}x_{n+j}\|, \end{aligned}$$

by using Steps 5 and 7, we reach the desired conclusion.

Step 9. Show that $\forall l \in I, x_n - T_lx_n \rightarrow 0$ as $n \rightarrow \infty$.

Indeed, for arbitrary given $l \in I$, we can choose $j \in I$ such that $j = l - i(n)$ if $l \geq i(n)$ and $j = N + l - i(n)$ if $l < i(n)$. Then, we have $l = i(n + j) = i(n) + j$, for all $n \geq 0$. In view of Step 8, we obtain $x_n - T_lx_n = x_n - T_{i(n)+j}x_n = x_n - T_{i(n)+j}x_n \rightarrow 0$ as $n \rightarrow \infty$.

Step 10. Show that $x_n \rightarrow p$, where $p = P_Fx_0$.

For $m > n$, by the definition of Q_n , we see that $Q_m \subset Q_n$. Noting that $x_m = P_{Q_m}x_0$ and $x_n = P_{Q_n}x_0$, by Lemma 2.3, we conclude that

$$\|x_m - x_n\|^2 \leq \|x_m - x_0\|^2 - \|x_n - x_0\|^2.$$

In view of Step 4, we deduce that $x_m - x_n \rightarrow 0$ as $m, n \rightarrow \infty$, that is, $\{x_n\}$ is Cauchy. Since H is complete and C is closed, we can assume that $x_n \rightarrow p \in C$ as $n \rightarrow \infty$. It follows from Step 9 that $p \in F$. From Step 2, we know that $F \subset Q_n$, for all $n \geq 0$. Hence, for arbitrary $z \in F$, we have

$$\langle z - x_n, x_0 - x_n \rangle \leq 0.$$

This leads to

$$\langle z - p, x_0 - p \rangle \leq 0,$$

for all $z \in F$. By Lemma 2.1, we conclude that $p = P_Fx_0$. This completes the proof. \square

Remark 3.1 In contrast to [15], the main difference with the paper [15] consists in the fact that the sequence $\{y_n\}$ in algorithm (3.1) is globally unique for the whole family of $\{T_i\}_{i=0}^{N-1}$.

Remark 3.2 In the proof of Theorem 3.1, the third step is really key. The assumption of quasi-asymptotic pseudocontractiveness of the mappings $\{T_i\}_{i=0}^{N-1}$ has been used.

Next, we consider a simpler algorithm for a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings in real Hilbert spaces.

Theorem 3.2 *Let C be a bounded, closed, and convex subset of a real Hilbert space H . Let $\{T_i\}_{i=0}^{N-1} : C \rightarrow C$ be a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings such that $F = \bigcap_{i=0}^{N-1} \text{Fix}(T_i) \neq \emptyset$. Assume the control sequence $\{\alpha_n\}$ is chosen so that $\alpha_n \in [a, b]$ for some $a, b \in (0, \frac{1}{1+L})$, where $L = \max\{L_i : 0 \leq i \leq N - 1\}$. Let a sequence $\{x_n\}$ be generated in the following manner:*

$$\begin{cases} x_0 \in H & \text{chosen arbitrarily,} \\ C_1 = C, & x_1 = P_{C_1}x_0, \\ y_n = (1 - \alpha_n)x_n + \alpha_n T_{i(n)}^{h(n)} x_n, & n \geq 1, \\ C_{n+1} = \{z \in C_n : \alpha_n [1 - (1 + L)\alpha_n] \|x_n - T_{i(n)}^{h(n)} x_n\|^2 \\ \qquad \leq \langle x_n - z, (y_n - T_{i(n)}^{h(n)} y_n) \rangle + (k_{h(n)} - 1)(\text{diam } C)^2\}, & n \geq 0, \\ x_{n+1} = P_{C_{n+1}}x_0, & n \geq 1, \end{cases} \tag{3.5}$$

where $k_{h(n)} = \max\{k_{h(n),i(n)} : 0 \leq i(n) \leq N - 1\}$ and $k_{h(n),i(n)}$ are asymptotic sequences for $\{T_i\}_{i=0}^{N-1}$. Then the sequence $\{x_n\}$ generated by (3.5) converges strongly to $P_F x_0$.

Proof Following the proof lines of Theorem 3.1, we can show the following.

(1) F is a nonempty closed and convex subset of C , and hence $P_F x_0$ is well defined for every $x_0 \in H$.

(2) C_n is closed convex and $F \subset C_n$ for every $n \geq 1$.

In fact, for $n = 1$, $C_1 = C$ is closed convex. Assume that C_n is closed convex for some $n \geq 1$; from the definition C_{n+1} , we know that C_{n+1} is also closed convex for the same $n \geq 1$, and hence C_n is closed convex for every $n \geq 1$. For $n = 1$, $F \subset C_1 = C$. Assume that $F \subset C_n$ for some $n \geq 1$; from the induction assumption, (3.3), and the definition of C_{n+1} , we conclude that $F \subset C_{n+1}$, and hence $F \subset C_n$, for all $n \geq 1$.

(3) $\lim_{n \rightarrow \infty} \|x_n - x_0\|$ exists.

In view of (3.5), we have $x_n = P_{C_n} x_0$. Since $C_{n+1} \subset C_n$ and $x_{n+1} \in C_{n+1}$, for all $n \geq 1$, we have

$$\|x_n - x_0\| \leq \|x_{n+1} - x_0\|, \quad \forall n \geq 1. \tag{3.6}$$

On the other hand, as $F \subset C_n$ by (2), it follows that

$$\|x_n - x_0\| \leq \|z - x_0\|, \quad \forall z \in F, \forall n \geq 1. \tag{3.7}$$

Combining (3.6) and (3.7), we see that $\lim_{n \rightarrow \infty} \|x_n - x_0\|$ exists.

(4) $\{x_n\}$ is a Cauchy sequence in C .

For $m > n \geq 1$, we have $x_m = P_{C_m}x_0 \in C_m \subset C_n$. By Lemma 2.2, we have

$$\|x_m - x_n\|^2 \leq \|x_m - x_0\|^2 - \|x_n - x_0\|^2. \tag{3.8}$$

Letting $m, n \rightarrow \infty$ and taking the limit in (3.8), we get $x_m - x_n \rightarrow 0$ as $m, n \rightarrow \infty$, which proves that $\{x_n\}$ is Cauchy. We assume that $x_n \rightarrow p \in C$. The remainder of the proof follows exactly from Steps 5-10 in Theorem 3.1. This completes the proof. \square

Remark 3.3 Algorithm (3.5) is simpler than algorithm (3.1). Also, the sequence $\{y_n\}$ in algorithm (3.5) is globally unique for the whole family of $\{T_i\}_{i=0}^{N-1}$.

Finally, we present another kind of iterative algorithm for a finite family of quasi-asymptotically pseudocontractive mappings in real Hilbert spaces.

Theorem 3.3 *Let C be a bounded and closed convex subset of a real Hilbert space H . Let $\{T_i\}_{i=0}^{N-1} : C \rightarrow C$ be a finite family of uniformly L_i -Lipschitzian and quasi-asymptotically pseudocontractive mappings such that $F = \bigcap_{i=0}^{N-1} \text{Fix}(T_i) \neq \emptyset$. Assume the control sequence $\{\alpha_n\}$ is chosen so that $\alpha_n \in [a, b]$ for some $a, b \in (0, \frac{1}{1+L})$, where $L = \max\{L_i : 0 \leq i \leq N - 1\}$. Let a sequence $\{x_n\}$ be generated in the following manner:*

$$\begin{cases} x_0 \in H & \text{chosen arbitrarily,} \\ C_1 = C, & x_1 = P_{C_1}x_0, \\ y_{n,i} = (1 - \alpha_n)x_n + \alpha_n T_i^n x_n, & n \geq 1, i \in I, \\ C_{n+1} = \{z \in C_n : \alpha_n [1 - (1 + L)\alpha_n] \sum_{i=0}^{N-1} \|x_n - T_i^n x_n\|^2 \\ \leq \langle x_n - z, \sum_{i=0}^{N-1} (y_{n,i} - T_i^n y_{n,i}) \rangle + \sum_{i=0}^{N-1} (k_{n,i} - 1)(\text{diam } C)^2\}, & n \geq 0, \\ x_{n+1} = P_{C_{n+1}}x_0, & n \geq 1, \end{cases} \tag{3.9}$$

where $k_{n,i}$ are asymptotic sequences for $\{T_i\}_{i=0}^{N-1}$. Then the sequence $\{x_n\}$ generated by (3.9) converges strongly to P_Fx_0 .

Proof As shown in Theorem 3.2, we easily show that P_Fx_0 is well defined for every $x_0 \in H$, C_n is closed convex and $F \subset C_n$ for every $n \geq 1$. Thus, $\{x_n\}$ is well defined, for all $n \geq 1$. Further, $\{x_n\}$ is a Cauchy sequence in C . Therefore, $x_n \rightarrow p \in C$ as $n \rightarrow \infty$. In particular, we have $x_{n+1} - x_n \rightarrow 0$ as $n \rightarrow \infty$. Since $0 < a \leq \alpha_n \leq b < \frac{1}{1+L}$, $x_{n+1} \in C_{n+1}$, $\{\sum_{i=0}^{N-1} \|(I - T_i^n)y_{n,i}\|\}$ is bounded and $\sum_{i=0}^{N-1} (k_{n,i} - 1) \rightarrow 0$, from the definition of C_{n+1} , we see that $x_n - T_i^n x_n \rightarrow 0$ as $n \rightarrow \infty$, for all $i \in I$. Observe that

$$\begin{aligned} \|x_{n+1} - T_i x_{n+1}\| &\leq \|x_{n+1} - T_i^{n+1} x_{n+1}\| + \|T_i^{n+1} x_{n+1} - T_i^{n+1} x_n\| \\ &\quad + \|T_i^{n+1} x_n - T_i x_n\| + \|T_i x_n - T_i x_{n+1}\| \\ &\leq \|x_{n+1} - T_i^{n+1} x_{n+1}\| + 2L\|x_{n+1} - x_n\| + L\|x_n - T^n x_n\|, \end{aligned}$$

so that $x_n - T_i x_n \rightarrow 0$ as $n \rightarrow \infty$, for all $i \in I$. Since $x_n \rightarrow p$, we have $p = T_i p$, for all $i \in I$ and hence $p \in F$. The remainder of the proof follows exactly from Step 10 of Theorem 3.1. This completes the proof. \square

Remark 3.4 Algorithm (3.9) used in Theorem 3.3 is different from the ones existing in literature.

Remark 3.5 It is interesting to extend the algorithms of this paper to an infinite family of quasi-asymptotically pseudocontractive mappings.

Remark 3.6 The work related to other iterative methods for asymptotically pseudocontractive mappings can be found in [17–21].

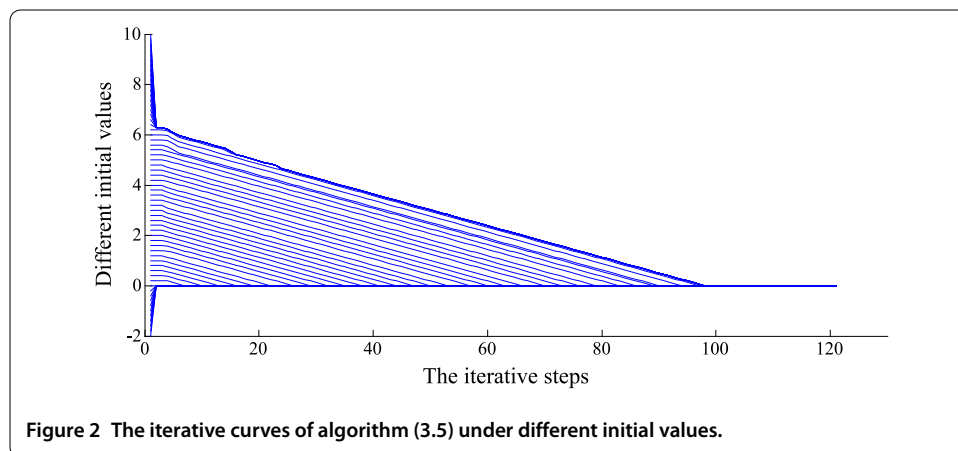
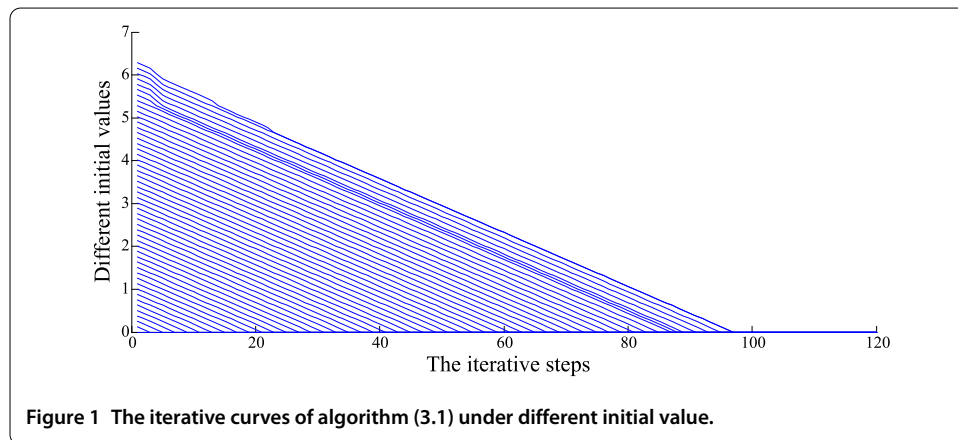
4 Numerical experiments

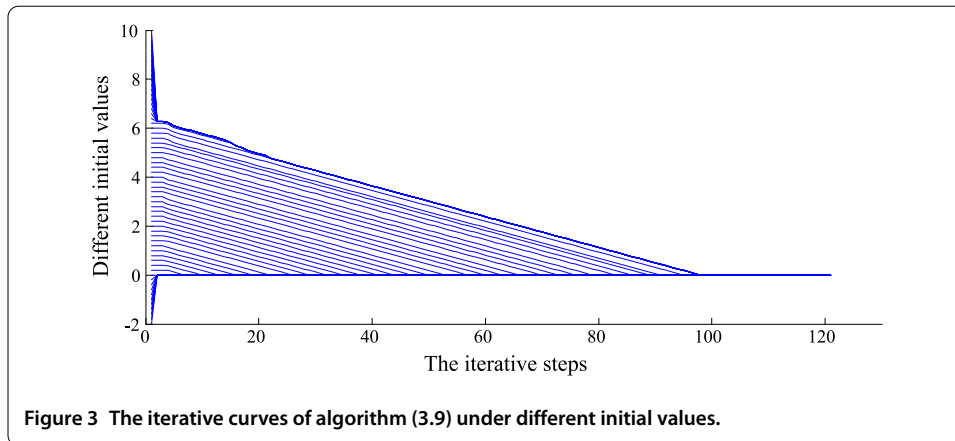
In this section, we provide some numerical experiments to show our algorithms are effective. In our numerical experiments, we consider the case of $N = 2$. We take $T_0 = I$, the identity mapping on \mathbb{R} , and use the example given in Remark 1.3 as T_1 . For such a family $\{T_i\}_{i=0}^1$, we have $L_0 = 1$ and $L_1 = \frac{2+4\pi}{3}$, therefore, $L = \frac{2+4\pi}{3}$. It is easy to see that $k_{h(n)} = 1$, for all $n \geq 0$. Moreover, we know also that $F = \bigcap_{i=0}^1 \text{Fix}(T_i) = \{0\} \neq \emptyset$. We take $\alpha_n = \frac{1}{n+56} + \frac{1}{2+L}$, for all $n \geq 0$. For algorithms (3.1), (3.5), and (3.9), each of them iterates 70 steps.

Firstly, for algorithm (3.1), we choose $x_0 \in [0, 2\pi]$ arbitrarily, then for 51 different initial values, we can see all the results are convergent in Figure 1.

Secondly, for algorithm (3.5), we choose $x_0 \in [-2, 10]$ arbitrarily, then for 61 different initial values, we can see all the results are convergent in Figure 2.

Finally, for algorithm (3.9), we also choose $x_0 \in [-2, 10]$ arbitrarily, then for 61 different initial values, we can also see all the results are convergent in Figure 3.





In addition, for Figures 1, 2, and 3, we can also find that the algorithms need more iterative steps with the nonnegative initial value becoming larger in the majority situation.

5 Conclusion

This work contains our dedicated study aimed to develop and complement hybrid projection algorithms for finding the common fixed points of a finite family of quasi-asymptotically pseudocontractive mappings in Hilbert spaces. We introduced three kinds of new hybrid projection algorithms for this class of problems, and we have proven their strong convergence. Numerical examples have been given to illustrate the effectiveness of the proposed algorithms. The results presented in the paper are a generalization and complement of the well-known ones existing in the literature.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors contributed equally and significantly in writing this paper. All authors read and approved the final manuscript.

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