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# Some fixed point theorems in $b$ -metric-like spaces

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## Abstract

In this work, some fixed point and common fixed point theorems are investigated in  $b$ -metric-like spaces. Some of our results generalize related results in the literature. Also, some examples and an application to integral equation are given to support our main results.

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**Keywords:**  $b$ -metric-like spaces; common fixed point; fixed point

## 1 Introduction and preliminaries

There exist many generalizations of the concept of metric spaces in the literature. In [1, 2], Matthews introduced the notion of a partial metric space as a part of the study of denotational semantics of dataflow networks. A lot of fixed point theorems were investigated in partial spaces (see, *e.g.*, [3–11] and references therein). The notions of metric-like spaces [12] and  $b$ -metric spaces [13–16] were introduced in the literature, which are generalizations of metric spaces. Recently, the concept of  $b$ -metric-like spaces which is a generalization of metric-like spaces and  $b$ -metric spaces and partial metric spaces was introduced in [17]. Recently, Hussain *et al.* [18] discussed topological structure of  $b$ -metric-like spaces and proved some fixed point results in  $b$ -metric-like spaces.

**Definition 1.1** [17] A  $b$ -metric-like on a nonempty set  $X$  is a function  $D : X \times X \rightarrow [0, +\infty)$  such that for all  $x, y, z \in X$  and a constant  $s \geq 1$ , the following three conditions hold true:

- (D<sub>1</sub>) if  $D(x, y) = 0$  then  $x = y$ ;
- (D<sub>2</sub>)  $D(x, y) = D(y, x)$ ;
- (D<sub>3</sub>)  $D(x, z) \leq s(D(x, y) + D(y, z))$ .

The pair  $(X, D)$  is then called a  $b$ -metric-like space.

**Example 1.1** Let  $X = \{0, 1, 2\}$ , and let

$$D(x, y) = \begin{cases} 2, & x = y = 0, \\ \frac{1}{2}, & \text{otherwise.} \end{cases}$$

Then  $(X, D)$  is a  $b$ -metric-like space with the constant  $s = 2$ .

In [17], some concepts in  $b$ -metric-like spaces were introduced as follows.

Each  $b$ -metric-like  $D$  on  $X$  generalizes a topology  $\tau_D$  on  $X$  whose base is the family of open  $D$ -balls  $B_D(x, \varepsilon) = \{y \in X : |D(x, y) - D(x, x)| < \varepsilon\}$ , for all  $x \in X$  and  $\varepsilon > 0$ .

A sequence  $\{x_n\}$  in the  $b$ -metric-like space  $(X, D)$  converges to a point  $x \in X$  if and only if  $D(x, x) = \lim_{n \rightarrow +\infty} D(x, x_n)$ .

A sequence  $\{x_n\}$  in the  $b$ -metric-like space  $(X, D)$  is called a Cauchy sequence if there exists  $\lim_{n, m \rightarrow +\infty} D(x_m, x_n)$  (and it is finite).

A  $b$ -metric-like space is called complete if every Cauchy sequence  $\{x_n\}$  in  $X$  converges with respect to  $\tau_D$  to a point  $x \in X$  such that  $\lim_{n \rightarrow +\infty} D(x, x_n) = D(x, x) = \lim_{n, m \rightarrow +\infty} D(x_m, x_n)$ .

**Remark 1.1** In Example 1.1, let  $x_n = 2$  for each  $n = 1, 2, \dots$ , then it is clear that  $\lim_{n \rightarrow +\infty} D(x_n, 2) = D(2, 2)$  and  $\lim_{n \rightarrow +\infty} D(x_n, 1) = D(1, 1)$ , hence, in  $b$ -metric-like spaces, the limit of a convergent sequence is not necessarily unique.

**Remark 1.2** It should be noted that in general, a  $b$ -metric-like function  $D(x, y)$  need not be jointly continuous in both variables. The following example illustrates this fact.

**Example 1.2** Let  $X = \mathbb{N} \cup \{+\infty\}$  (where  $\mathbb{N}$  is the set of all natural numbers, similarly hereinafter), and let  $D : X \times X \rightarrow R$  be defined by

$$D(x, y) = \begin{cases} 0, & m \text{ and } n \text{ are } +\infty, \\ 1, & m = n = 1, \\ |\frac{1}{m} - \frac{1}{n}|, & \text{if one of } m, n \text{ is odd which is larger than 1 and} \\ & \text{the other is odd or } +\infty, \\ 7, & \text{if one of } m, n \text{ is even and the other is even or } +\infty, \\ 2, & \text{otherwise.} \end{cases}$$

Then considering all possible cases, it can be checked that, for all  $m, n, p \in X$ , we have

$$D(m, n) \leq \frac{7}{2} [D(m, p) + D(p, n)].$$

Thus,  $(X, D)$  is a  $b$ -metric-like space with  $s = \frac{7}{2}$ . Let  $x_n = 2n + 1$  for each  $n \in \mathbb{N}$ , then  $D(x_n, +\infty) = D(2n + 1, +\infty) = \frac{1}{2n+1} \rightarrow 0$ , as  $n \rightarrow +\infty$ , that is,  $x_n \rightarrow +\infty$ , but  $D(x_n, 2) = 2 \rightarrow D(+\infty, 2) = 7$ .

**Definition 1.2** Suppose that  $(X, D)$  is a  $b$ -metric-like space. A mapping  $T : X \rightarrow X$  is said to be continuous at  $x \in X$ , if for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that  $T(B_D(x, \delta)) \subseteq B_D(Tx, \varepsilon)$ . We say that  $T$  is continuous on  $X$  if  $T$  is continuous at all  $x \in X$ .

Let  $(X, D)$  be a  $b$ -metric-like space, and let  $f : X \rightarrow X$  be a continuous mapping. Then

$$\lim_{n \rightarrow +\infty} D(x_n, x) = D(x, x) \implies \lim_{n \rightarrow +\infty} D(fx_n, fx) = D(fx, fx).$$

In this paper, we investigate some new fixed point and common fixed point theorems in  $b$ -metric-like spaces. Some of our results generalize and improve related results in the literature. Some examples and an application are presented to support our main results.

## 2 Main results

In this section, we begin with the following definitions and lemma which will be needed in the sequel.

**Definition 2.1** [19] Let  $f$  and  $g$  be two self-mappings on a set  $X$ . If  $\omega = fx = gx$  for some  $x$  in  $X$ , then  $x$  is called a coincidence point of  $f$  and  $g$ , where  $\omega$  is called a point of coincidence of  $f$  and  $g$ .

**Definition 2.2** [19] Let  $f$  and  $g$  be two self-mappings defined on a set  $X$ . Then  $f$  and  $g$  are said to be weakly compatible if they commute at every coincidence point, i.e., if  $fx = gx$  for some  $x \in X$ , then  $fgx = gfx$ .

**Lemma 2.1** [17] Let  $(X, D)$  be a  $b$ -metric-like space with the constant  $s \geq 1$ . Let  $\{y_n\}$  be a sequence in  $(X, D)$  such that

$$D(y_n, y_{n+1}) \leq \lambda D(y_{n-1}, y_n) \tag{2.1}$$

for some  $\lambda$ ,  $0 < \lambda < \frac{1}{s}$ , and each  $n = 1, 2, \dots$

Then  $\lim_{m, n \rightarrow +\infty} D(y_m, y_n) = 0$ .

Let  $\Phi$  denote the set of all functions  $\phi : [0, +\infty) \rightarrow [0, +\infty)$  satisfying:

- (1)  $\phi$  is continuous and nondecreasing;
- (2)  $\phi(t) = 0$  if and only if  $t = 0$ .

Now we prove our main results.

**Theorem 2.1** Let  $(X, D)$  be a complete  $b$ -metric-like space with the constant  $s \geq 1$  and let  $T : X \rightarrow X$  be a mapping such that

$$D(Tx, Ty) \leq \frac{D(x, y)}{s} - \varphi(D(x, y)) \tag{2.2}$$

for all  $x, y \in X$ , where  $\varphi \in \Phi$ . Then  $T$  has a unique fixed point.

*Proof* Let  $x_0$  be an arbitrary point in  $X$ . Define  $x_{n+1} = Tx_n$  for  $n = 0, 1, 2, \dots$ , then we can claim that

$$\lim_{n \rightarrow +\infty} D(x_n, x_{n+1}) = 0. \tag{2.3}$$

In fact, by (2.2), we have

$$D(x_{n+1}, x_{n+2}) = D(Tx_n, Tx_{n+1}) \leq \frac{D(x_n, x_{n+1})}{s} - \varphi(D(x_n, x_{n+1})) \leq D(x_n, x_{n+1}), \tag{2.4}$$

it means that sequence  $\{D(x_n, x_{n+1})\}$  is non-increasing and hence there exists some non-negative number  $r_0$  such that

$$\lim_{n \rightarrow +\infty} D(x_n, x_{n+1}) = r_0. \tag{2.5}$$

Since

$$\begin{aligned}
 D(x_{n+1}, x_{n+2}) &= D(Tx_n, Tx_{n+1}) \leq \frac{D(x_n, x_{n+1})}{s} - \varphi(D(x_n, x_{n+1})) \\
 &\leq D(x_n, x_{n+1}) - \varphi(D(x_n, x_{n+1})),
 \end{aligned}$$

taking  $n \rightarrow +\infty$  in the above inequalities, the continuity of  $\varphi$  and (2.5) shows that  $r_0 \leq r_0 - \varphi(r_0)$ , yielding  $r_0 = 0$ , hence we conclude our claim.

Now, we show that  $\{x_n\}$  is a Cauchy sequence. For arbitrary  $\varepsilon > 0$ , we choose  $N \in \mathbb{N}$  such that

$$D(x_n, x_{n+1}) < \min \left\{ \frac{\varepsilon}{2s}, \varphi \left( \frac{\varepsilon}{2s} \right) \right\} \tag{2.6}$$

for  $n \geq N$ .

We claim that if  $D(x, x_{N_0}) \leq \varepsilon$  for  $N_0 > N$ , then  $D(Tx, x_{N_0}) \leq \varepsilon$ . For this, we distinguish two cases.

*Case 1.* If  $D(x, x_{N_0}) \leq \frac{\varepsilon}{2s}$ , then

$$\begin{aligned}
 D(Tx, x_{N_0}) &\leq s(D(Tx, Tx_{N_0}) + D(Tx_{N_0}, x_{N_0})) \\
 &= sD(Tx, Tx_{N_0}) + sD(Tx_{N_0}, x_{N_0}) \\
 &\leq D(x, x_{N_0}) - s\varphi(D(x, x_{N_0})) + sD(x_{N_0+1}, x_{N_0}) \\
 &< \frac{\varepsilon}{2s} + \frac{\varepsilon}{2} \\
 &\leq \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon.
 \end{aligned}$$

*Case 2.* If  $\frac{\varepsilon}{2s} < D(x, x_{N_0}) \leq \varepsilon$ , then  $\varphi(D(x, x_{N_0})) \geq \varphi(\frac{\varepsilon}{2s})$ , from which we obtain

$$\begin{aligned}
 D(Tx, x_{N_0}) &\leq s(D(Tx, Tx_{N_0}) + D(Tx_{N_0}, x_{N_0})) \\
 &= sD(Tx, Tx_{N_0}) + sD(Tx_{N_0}, x_{N_0}) \\
 &\leq D(x, x_{N_0}) - s\varphi(D(x, x_{N_0})) + sD(x_{N_0+1}, x_{N_0}) \\
 &\leq \varepsilon - s\varphi \left( \frac{\varepsilon}{2s} \right) + s\varphi \left( \frac{\varepsilon}{2s} \right) = \varepsilon.
 \end{aligned} \tag{2.7}$$

By the above two cases, we show that our claim is true. From (2.6), we have  $D(x_{N_0+1}, x_{N_0}) < \varepsilon$ , which together with our claim implies that  $D(Tx_{N_0+1}, x_{N_0}) \leq \varepsilon$ , that is,  $D(x_{N_0+2}, x_{N_0}) \leq \varepsilon$ . Continue this process, one can deduce that  $D(x_n, x_{N_0}) < \varepsilon$  for each  $n > N_0$ . Therefore, for any  $m, n > N$ , we have  $D(x_n, x_m) \leq s(D(x_n, x_{N_0}) + D(x_{N_0}, x_m)) < 2s\varepsilon$ , it follows that  $\lim_{n,m \rightarrow +\infty} D(x_m, x_n) = 0$  and  $\{x_n\}$  is a Cauchy sequence in  $(X, D)$ . Since  $(X, D)$  is complete, there exists some  $u \in X$  such that

$$\lim_{n \rightarrow +\infty} D(x_n, u) = D(u, u) = \lim_{m,n \rightarrow +\infty} D(x_m, x_n) = 0. \tag{2.8}$$

Since

$$D(x_{n+1}, Tu) = D(Tx_n, Tu) \leq \frac{D(x_n, u)}{s} - \varphi(D(x_n, u)), \tag{2.9}$$

the continuity of  $\varphi$  shows, from (2.8) and (2.9), that  $\lim_{n \rightarrow +\infty} D(x_n, Tu) = 0$ , which together with the inequality  $D(u, Tu) \leq sD(x_n, u) + sD(x_n, Tu)$  and (2.8) yields  $D(u, Tu) = 0$ , hence  $u = Tu$ . Let  $v$  be a fixed point of  $T$ , that is,  $Tv = v$ , we have

$$D(u, v) = D(Tu, Tv) \leq \frac{D(u, v)}{s} - \varphi(D(u, v)) \leq D(u, v) - \varphi(D(u, v)),$$

it implies that  $D(u, v) = 0$  and so  $u = v$ , this means that  $T$  has a unique fixed point.  $\square$

In Theorem 2.1, taking  $\varphi(t) = \frac{t}{s} - \lambda t$  with  $0 < \lambda < \frac{1}{s}$ , we can get the following corollary.

**Corollary 2.1** *Let  $(X, D)$  be a complete  $b$ -metric-like space with the constant  $s \geq 1$  and let  $T : X \rightarrow X$  be a mapping such that*

$$D(Tx, Ty) \leq \lambda D(x, y) \tag{2.10}$$

for all  $x, y \in X$ , where  $0 < \lambda < \frac{1}{s}$ . Then  $T$  has a unique fixed point in  $X$ .

**Remark 2.1** By taking  $s = 1$  in Theorem 2.1, we get Theorem 2.7 in [12].

**Theorem 2.2** *Let  $(X, D)$  be a complete  $b$ -metric-like space with the constant  $s \geq 1$  and let  $T : X \rightarrow X$  be a surjection such that*

$$D(Tx, Ty) \geq a_1 D(x, y) + a_2 D(x, Tx) + a_3 D(y, Ty) + a_4 D(x, Ty) \tag{2.11}$$

for all  $x, y \in X$ , where  $a_i \geq 0$  ( $i = 1, 2, 3, 4$ ) satisfy  $s(a_1 + a_2) + a_4 + s^2(a_3 - a_4) > s^2$  and  $1 - a_3 + a_4 > 0$ . Then  $T$  has a fixed point.

*Proof* Let  $x_0 \in X$ . Since  $T$  is surjective, choose  $x_1 \in X$  such that  $Tx_1 = x_0$ . Continuing this process, we can define a sequence  $\{x_n\}$  such that  $x_{n-1} = Tx_n$ ,  $n \geq 1$ ,  $n \in \mathbb{N}$ . Without loss of generality, we assume that  $x_{n-1} \neq x_n$  for all  $n \geq 1$ ,  $n \in \mathbb{N}$ . Due to (2.11), we have

$$\begin{aligned} D(x_n, x_{n-1}) &= D(Tx_{n+1}, Tx_n) \\ &\geq a_1 D(x_{n+1}, x_n) + a_2 D(x_{n+1}, Tx_{n+1}) + a_3 D(x_n, Tx_n) + a_4 D(x_{n+1}, Tx_n) \\ &= a_1 D(x_{n+1}, x_n) + a_2 D(x_{n+1}, x_n) + a_3 D(x_n, x_{n-1}) + a_4 D(x_{n+1}, x_{n-1}). \end{aligned} \tag{2.12}$$

By  $D(x_{n+1}, x_{n-1}) \geq \frac{D(x_n, x_{n+1}) - sD(x_n, x_{n-1})}{s}$ , (2.12) implies that

$$D(x_{n+1}, x_n) \leq \frac{s - sa_3 + sa_4}{sa_1 + sa_2 + a_4} D(x_n, x_{n-1}). \tag{2.13}$$

Letting  $\lambda = \frac{s - sa_3 + sa_4}{sa_1 + sa_2 + a_4}$ , by  $s(a_1 + a_2) + a_4 + s^2(a_3 - a_4) > s^2$ , we have  $0 < \lambda < \frac{1}{s}$ . Applying Lemma 2.1, we see that  $\lim_{m, n \rightarrow +\infty} D(x_m, x_n) = 0$  and  $\{x_n\}$  is a Cauchy sequence. Since  $(X, D)$  is complete, there exists  $z \in X$  such that

$$\lim_{n \rightarrow +\infty} D(x_n, z) = D(z, z) = \lim_{m, n \rightarrow +\infty} D(x_m, x_n) = 0. \tag{2.14}$$

Consequently, we can find  $u \in X$  such that  $z = Tu$ . Now, we show that  $z = u$ . From (2.11), we get

$$\begin{aligned} D(x_n, z) &= D(Tx_{n+1}, Tu) \\ &\geq a_1D(x_{n+1}, u) + a_2D(x_{n+1}, Tx_{n+1}) + a_3D(u, Tu) + a_4D(x_{n+1}, Tu) \\ &= a_1D(x_{n+1}, u) + a_2D(x_{n+1}, x_n) + a_3D(u, z) + a_4D(x_{n+1}, z) \end{aligned}$$

and

$$\begin{aligned} D(z, x_n) &= D(Tu, Tx_{n+1}) \\ &\geq a_1D(u, x_{n+1}) + a_2D(u, Tu) + a_3D(x_{n+1}, Tx_{n+1}) + a_4D(u, Tx_{n+1}) \\ &= a_1D(u, x_{n+1}) + a_2D(u, z) + a_3D(x_{n+1}, x_n) + a_4D(u, x_n). \end{aligned}$$

Adding the above inequalities, we have

$$\begin{aligned} 2D(z, x_n) &\geq 2a_1D(u, x_{n+1}) + (a_2 + a_3)D(u, z) + (a_2 + a_3)D(x_{n+1}, x_n) + a_4D(u, x_n) \\ &\quad + a_4D(x_{n+1}, z). \end{aligned} \tag{2.15}$$

Since  $D(u, x_{n+1}) \geq \frac{D(u,z) - sD(x_{n+1},z)}{s}$  and  $D(u, x_n) \geq \frac{D(u,z) - sD(x_n,z)}{s}$ , (2.15) gives

$$\begin{aligned} 2D(z, x_n) &\geq 2a_1 \frac{D(u, z) - sD(x_{n+1}, z)}{s} + (a_2 + a_3)D(u, z) + (a_2 + a_3)D(x_{n+1}, x_n) \\ &\quad + a_4 \frac{D(u, z) - sD(x_n, z)}{s} + a_4D(x_{n+1}, z). \end{aligned}$$

Letting  $n \rightarrow +\infty$  in the above inequality, we obtain

$$0 \geq \left( \frac{2a_1}{s} + a_2 + a_3 + \frac{a_4}{s} \right) D(u, z),$$

it implies that  $D(u, z) = 0$ , hence  $u = z$ , that is,  $u = z = Tu$ . This shows that  $u$  is a fixed point of  $T$ . □

**Corollary 2.2** *Let  $(X, D)$  be a complete  $b$ -metric-like space with the constant  $s \geq 1$  and let  $T : X \rightarrow X$  be a surjection such that*

$$D(Tx, Ty) \geq kD(x, y) \tag{2.16}$$

*for all  $x, y \in X$  and  $k > s$ . Then  $T$  has a unique fixed point.*

*Proof* Letting  $a_i = 0$  ( $i = 2, 3, 4$ ) and  $a_1 = k$ , we find that  $T$  has a fixed point from Theorem 2.2. Suppose that  $u$  and  $v$  are fixed points of  $T$ , then we get  $D(u, v) = 0$  (otherwise  $D(u, v) = D(Tu, Tv) \geq kD(u, v) > D(u, v)$ , which is a contradiction), hence  $u = v$ , therefore  $T$  has a unique fixed point. □

**Lemma 2.2** [20] *Let  $X$  be a nonempty set and  $T : X \rightarrow X$  a function. Then there exists a subset  $E \subseteq X$  such that  $T(E) = T(X)$  and  $T : E \rightarrow X$  is one-to-one.*

**Corollary 2.3** *Let  $(X, D)$  be a complete  $b$ -metric-like space with the constant  $s \geq 1$  and the self-mappings  $F$  and  $T$  satisfy the following condition:*

$$D(Fx, Fy) \geq kD(Tx, Ty) \tag{2.17}$$

for all  $x, y \in X$ , where  $k > s$  is a constant. If  $F(X) \subseteq T(X)$  and  $T(X)$  is complete subset of  $X$ , then  $F$  and  $T$  have a unique point of coincidence in  $X$ . Moreover, if  $F$  and  $T$  are weakly compatible, then  $F$  and  $T$  have a unique common fixed point.

*Proof* By Lemma 2.2, there exists  $E \subseteq X$  such that  $T(E) = T(X)$  and  $T : E \rightarrow X$  is one-to-one. Now, we define a mapping  $h : T(E) \rightarrow T(E)$  by  $h(Tx) = Fx$ . Since  $T$  is one-to-one on  $E$ ,  $h$  is well defined. Note that  $D(h(Tx), h(Ty)) \geq kD(Tx, Ty)$  for all  $Tx, Ty \in T(E)$ . Since  $T(E) = T(X)$  is complete, by using Corollary 2.2, there exists a unique  $x_0 \in X$  such that  $h(Tx_0) = Tx_0$ , hence  $Fx_0 = Tx_0$ , which means that  $F$  and  $T$  have a unique point of coincidence in  $X$ . Let  $Fx_0 = Tx_0 = z$ , since  $F$  and  $T$  are weakly compatible,  $Fz = Tz$ , which together with the uniqueness of point of coincidence implies that  $Fz = Tz = z$ , therefore,  $z$  is the unique common fixed point of  $F$  and  $T$ . □

Now, we introduce some examples to illustrate the validity of our main results.

**Example 2.1** Let  $X = \{0, 1, 2\}$ . Define  $D : X \times X \rightarrow [0, +\infty)$  as follows:  $D(0, 0) = 0, D(1, 1) = 3, D(2, 2) = 1, D(0, 1) = D(1, 0) = 8, D(0, 2) = D(2, 0) = 1, D(1, 2) = D(2, 1) = 4$ . Let  $\varphi(t) = \frac{t}{1+t}$ , and define the mapping  $T : X \rightarrow X$  by  $T0 = 0, T1 = 2, T2 = 0$ . Then one has the following.

- (1)  $(X, D)$  is a complete  $b$ -metric-like space with the constant  $s = \frac{8}{5}$ .
- (2) For all  $x, y \in X$ , we have  $D(Tx, Ty) \leq \frac{D(x,y)}{s} - \varphi(D(x, y))$ .

*Proof* It is clear that  $(X, D)$  is a complete  $b$ -metric-like space with the constant  $s = \frac{8}{5}$ . Now, we show that (2) is true. Since

$$\begin{aligned} D(T0, T0) &= 0 = \frac{D(0, 0)}{s} - \varphi(D(0, 0)); \\ D(T0, T1) &= 1 < 5 - \frac{8}{9} = \frac{D(0, 1)}{s} - \varphi(D(0, 1)); \\ D(T0, T2) &= 0 < \frac{5}{8} - \frac{1}{2} = \frac{D(0, 2)}{s} - \varphi(D(0, 2)); \\ D(T1, T1) &= 1 < \frac{15}{8} - \frac{3}{4} = \frac{D(1, 1)}{s} - \varphi(D(1, 1)); \\ D(T1, T2) &= 1 < \frac{5}{2} - \frac{4}{5} = \frac{D(1, 2)}{s} - \varphi(D(1, 2)); \\ D(T2, T2) &= 0 < \frac{5}{8} - \frac{1}{2} = \frac{D(2, 2)}{s} - \varphi(D(2, 2)), \end{aligned}$$

then, for all  $x, y \in X$ , we have  $D(Tx, Ty) \leq \frac{D(x,y)}{s} - \varphi(D(x, y))$ . Hence we conclude that (2) holds, therefore all the required hypotheses of Theorem 2.1 are satisfied, and thus we deduce the existence and uniqueness of the fixed point of  $T$ . Here, 0 is the unique fixed point of  $T$ . □

**Example 2.2** Let  $X = [0, +\infty)$  and let a  $b$ -metric-like  $D : X \times X \rightarrow [0, +\infty)$  by

$$D(x, y) = (x + y)^2.$$

Clearly,  $(X, D)$  is a complete  $b$ -metric-like space with the constant  $s = 2$ . Define self-mappings  $F$  and  $T$  on  $X$  as follows:  $Fx = \frac{x}{2}$  and  $Tx = \ln(1 + \frac{x}{4})$ . Since  $t \geq \ln(1 + t)$  for each  $t \in [0, +\infty)$ , for all  $x, y \in X$ , we have

$$\begin{aligned} D(Fx, Fy) &= \left(\frac{x}{2} + \frac{y}{2}\right)^2 = \left(2\frac{x}{4} + 2\frac{y}{4}\right)^2 = 4\left(\frac{x}{4} + \frac{y}{4}\right)^2 \\ &\geq 4\left(\ln\left(1 + \frac{x}{4}\right) + \ln\left(1 + \frac{y}{4}\right)\right)^2 = 4D(Tx, Ty), \end{aligned}$$

which means  $D(Fx, Fy) \geq KD(Tx, Ty)$ , where  $K = 4 > s = 2$ . Therefore all the required hypotheses of Corollary 2.3 are satisfied, hence  $F$  and  $T$  have a unique point of coincidence, in fact, 0 is the unique point coincidence. Moreover, by  $FT0 = TF0$ , we find that 0 is the unique common fixed point of  $F$  and  $T$ .

### 3 Existence of a solution for an integral equation

Consider the following integral equation:

$$x(t) = \int_0^T K(t, r, x(r)) \, dr, \tag{3.1}$$

where  $T > 0$  and  $K : [0, T] \times [0, T] \times R \rightarrow R$ .

The purpose of this section is to present an existence theorem for (3.1). Let  $X = C[0, T]$  be the set of continuous real functions defined on  $[0, T]$ . We endow  $X$  with the  $b$ -metric-like

$$D(u, v) = \max_{t \in [0, T]} (|u(t)| + |v(t)|)^p \quad \text{for all } u, v \in X,$$

where  $p > 1$ . Obviously,  $(X, D)$  is a complete  $b$ -metric-like space with the constant  $s = 2^{p-1}$ .

Let  $f(x(t)) = \int_0^T K(t, r, x(r)) \, dr$  for all  $x \in X$  and for all  $t \in [0, T]$ . Then the existence of a solution to (3.1) is equivalent to the existence of a fixed point of  $f$ . Now, we prove the following result.

**Theorem 3.1** *Suppose that the following hypotheses hold:*

- (i)  $K : [0, T] \times [0, T] \times R \rightarrow R$  is continuous;
- (ii) for all  $t, r \in [0, T]$ , there exists a continuous  $\xi : [0, T] \times [0, T] \rightarrow R$  such that

$$|K(t, r, x(r))| + |K(t, r, y(r))| < \lambda^{\frac{1}{p}} \xi(t, r) (|x(r)| + |y(r)|) \tag{3.2}$$

and

$$\sup_{t \in [0, T]} \int_0^T \xi(t, r) \, dr \leq 1, \tag{3.3}$$

where  $0 < \lambda < \frac{1}{s}$ .

Then the integral equation (3.1) has a unique solution  $x \in X$ .



*Proof* From (3.2) and (3.3), for all  $t \in [0, T]$ , we have

$$\begin{aligned}
 (|f(x(t))| + |f(y(t))|)^p &= \left( \left| \int_0^T K(t, r, x(r)) dr \right| + \left| \int_0^T K(t, r, y(r)) dr \right| \right)^p \\
 &\leq \left( \int_0^T |K(t, r, x(r))| dr + \int_0^T |K(t, r, y(r))| dr \right)^p \\
 &= \left( \int_0^T (|K(t, r, x(r))| + |K(t, r, y(r))|) dr \right)^p \\
 &\leq \left( \int_0^T (\lambda^{\frac{1}{p}} \xi(t, r) (|x(r)| + |y(r)|)) dr \right)^p \\
 &= \left( \int_0^T (\xi(t, r) \lambda^{\frac{1}{p}} ((|x(r)| + |y(r)|)^{\frac{1}{p}})) dr \right)^p \\
 &\leq \left( \int_0^T (\xi(t, r) \lambda^{\frac{1}{p}} D^{\frac{1}{p}}(x(t), y(t))) dr \right)^p \\
 &= \lambda D(x(t), y(t)) \left( \int_0^T \xi(t, r) dr \right)^p \\
 &\leq \lambda D(x(t), y(t)),
 \end{aligned}$$

which implies that  $D(f(x(t)), f(y(t))) \leq \lambda D(x(t), y(t))$ .

Now, all the conditions of Corollary 2.1 hold and  $f$  has a unique fixed point  $x \in X$ , which means that  $x$  is the unique solution for the integral equation (3.1).  $\square$

#### Competing interests

The authors declare that they have no competing interests.

#### Authors' contributions

All authors contributed equally to the work. All authors read and approved the final manuscript.

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