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Persistence in mean and extinction on stochastic competitive Gilpin-Ayala systems with regime switching

Xiuli He¹, Lei Liu^{1,2*} and Quanxin Zhu³

*Correspondence: liulei_hust@hhu.edu.cn *College of Science, Hohai University, Nanjing, Jiangsu 210098, China *School of Mathematics, Southeast University, Nanjing, Jiangsu 210096, China Full list of author information is available at the end of the article

Abstract

We are interested in the persistence in mean and extinction for a stochastic competitive Gilpin-Ayala system with regime switching. Based on the stochastic LaSalle theorem and the space-decomposition method, we derive generalized sufficient criteria on persistence in mean and extinction. By constructing a novel Lyapunov function we establish sufficient criteria on partial persistence in mean and partial extinction for the system. Finally, we provide two examples to demonstrate the feasibility and validity of our proposed methods.

Keywords: Lotka-Volterra model; random environments; Brownian motions; Itô formula; persistence in mean; extinction

1 Introduction

Many species live in the same environment, share the basic necessities, and compete for the limited recourses. This is a common phenomenon in the ecosystem. One of the most famous models is the classical competitive Lotka-Volterra system

$$\frac{dx_i}{dt} = x_i \left(b_i - \sum_{j=1}^n a_{ij} x_j \right), \quad i = 1, 2, \dots, n,$$

$$\tag{1}$$

where $x_i(t)$ represents the population size of species *i* at time *t*, the constant b_i is the growth rate of species *i*, and a_{ij} represents the effect of interspecific $(i \neq j)$ or intraspecific (i = j) interaction. One disadvantage is that the rate of change in the density of each species is a linear function. It might not describe the interaction behaviors of cross terms. Later on, to make up for this disadvantage and get more accurate results, Gilpin and Ayala have made some improvements on (1) and proposed the Gilpin-Ayala system

$$\frac{dx_i}{dt} = x_i \left(b_i - a_{ii} x_i^{\theta_i} - \sum_{j \neq i} a_{ij} x_j \right), \quad i = 1, 2, \dots, n,$$

$$\tag{2}$$

where θ_i is the parameter to modify the classical Lotka-Volterra model. It is a nonlinear function and can better simulate the rate of density change.

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Afterward, the facts have been noticed that the population systems are inevitably affected by the environmental noise. One important type is the telegraph noise, which can be molded as a switching between two or more environment regimes. It is influenced by food and environmental factors. The other type is the widely known white noise, which is simulated by Brownian motion. Perturbed by these two important environmental noises, system (2) becomes the stochastic competitive Gilpin-Ayala system with regime switching

$$dx_{i} = x_{i} \left(b_{i} (r(t)) - a_{ii} (r(t)) x_{i}^{\theta_{i}} - \sum_{j \neq i} a_{ij} (r(t)) x_{j} \right) dt + \sigma_{i} (r(t)) x_{i} dB_{i}(t),$$

$$i = 1, 2, \dots, n.$$
(3)

The stochastic competitive population system has been studied extensively because of its universal existence and importance (see e.g. [1-4]). The extinction and persistence in mean are the important and interesting properties of population systems, which mean that the population system will die out or survive in the future respectively. Therefore it has attracted considerable attention (see e.g. [5-8]). Li and Mao have investigated the dynamic behavior of several stochastic competitive Lotka-Volterra systems based on some novel Lyapunov functions, and some sufficient conditions are obtained in [4, 6, 7], which insure the stochastic permanence or extinction. More recently, some improved sufficient conditions on persistence in mean or extinction for stochastic competitive Lotka-Volterra systems are provided by Liu and Shen [8] based on the space decomposition method. More details can be referred to [9, 10], and [11].

However, the approaches proposed by these authors (see e.g. [12–14], and [15]) for Lotka-Volterra systems cannot be easily used in stochastic Gilpin-Ayala systems because of the nonlinear item. Meanwhile, the methods proposed in [16] and [17] cannot be readily applied to the asymptotic analysis owing to the existence of regime-switching mechanism, which can make the problem insolvable. Moreover, to the best of our knowledge, the stochastic competitive Gilpin-Ayala system with regime switching and its asymptotic behavior have not been studied yet. The nonlinear item and the regime-switching mechanism exist in the model simultaneously, which might make the problem more complicated (see e.g. [18, 19], and [17] for more details). Based on this motivation, our aim is to tackle this issue. We first establish the detailed criteria for whole persistence in mean and whole extinction. Then we investigate the asymptotic properties for the partial persistence in mean and partial extinction. Finally, we give two examples to verify the feasibility and validity of our proposed methods.

2 Notation

Throughout this paper, unless otherwise specified, let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t\geq 0}, \mathbb{P})$ be a complete probability space with filtration $\{\mathcal{F}_t\}_{t\geq 0}$ satisfying the usual conditions (i.e. it is increasing and right continuous, and \mathcal{F}_0 contains all \mathbb{P} -null sets). Let $B(t) = (B_t^1, \ldots, B_t^n)$ be an *n*-dimensional Brownian motion defined on the probability space.

Let $\{r(t), t \ge 0\}$ be a right-continuous Markovian chain on the probability space taking values in $S = \{1, 2, ..., N\}$ with generator $\Gamma = (\gamma_{ij})_{N \times N}$ given by

$$P\{r(t + \Delta) = j | r(t) = i\} = \begin{cases} \gamma_{ij}\Delta + o(\Delta), & i \neq j, \\ 1 + \gamma_{ii}\Delta + o(\Delta), & i = j, \end{cases}$$

For convenience and simplicity, we define

$$\hat{a}_{ij} = \min_{k \in S} a_{ij}(k), \qquad \check{a}_{ij} = \max_{k \in S} a_{ij}(k), \qquad M_{ij} = \frac{\check{a}_{ij}}{\hat{a}_{jj}}, \qquad m_{ij} = \frac{\hat{a}_{ij}}{\check{a}_{jj}}, \quad i, j = 1, \dots, n.$$

For the sake of discussion, the whole frame is based on several basic assumptions.

Assumption 1 $\theta_i \ge 1, a_{ii} > 0, a_{ij} \ge 0, i, j = 1, 2, ..., n, i \neq j$.

Assumption 2 $\sum_{k \in S} \pi_k(b_i(k) - \frac{\sigma_i^2(k)}{2}) > 0.$

Assumption 3
$$\sum_{k \in S} \pi_k((b_i(k) - \frac{\sigma_i^2(k)}{2}) - \sum_{j \neq i} a_{ij}(k)(\frac{b_j(k) - \frac{\sigma_j^2(k)}{2}}{a_{ij}(k)})^{\frac{1}{\theta_j}}) > 0, \forall j \neq i.$$

We are motivated in particular by the work of Mao [13] and obtain the existence of a global positive solution.

Lemma 2.1 ([20]) Under Assumption 1, for any given initial values $x_0 \in R_+^n$ and $r_0 \in S$, there are a unique positive solution $x(t, x_0, r_0)$ of system (3) and a constant $K_p > 0$ such that

$$\sup_{0 \le t < +\infty} \sum_{i=1}^{n} E x_i^p(t, x_0, r_0) \le K_p, \quad i = 1, 2, \dots, n.$$

In the following sections, let $x_i(t) = x_i(t, x_0, r_0)$ for simplicity.

3 Persistence in mean

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In this section, we investigate the persistence in mean.

Definition 1 System (3) is called persistent in mean if there exist constants $\alpha_i > 0$, $\beta_i > 0$, and $\gamma_i \ge 1$ such that

$$\limsup_{t\to\infty}\frac{1}{t}\int_0^t x_i^{\gamma_i}(s)\,ds\leq\alpha_i,\qquad \liminf_{t\to\infty}\frac{1}{t}\int_0^t x_i^{\gamma_i}(s)\,ds\geq\beta_i\quad\text{a.s. }i=1,2,\ldots,n.$$

Consider two auxiliary stochastic differential equations

$$\begin{cases} dy_i = y_i(b_i(r(t)) - a_{ii}(r(t))y_i^{\theta_i}) dt + \sigma_i(r(t))y_i dB_i(t), \\ y_i(0) = x_i(0), \quad r(0) = r_0, \quad i = 1, 2, \dots, n; \end{cases}$$

$$(4)$$

$$\begin{cases} dz_i = z_i(b_i(r(t)) - a_{ii}(r(t))z_i^{\sigma_i} - \sum_{j \neq i} a_{ij}(r(t))y_j) dt + \sigma_i(r(t))z_i dB_i(t), \\ z_i(0) = x_i(0), \quad r(0) = r_0, \quad i = 1, 2, \dots, n. \end{cases}$$
(5)

Then it follows from the comparison principle (see [21]) that

$$z_i(t) \le x_i(t) \le y_i(t), \quad i = 1, ..., n.$$
 (6)

Lemma 3.1 Let Assumption 1 and the inequality $\sum_{k \in S} \pi_k(b_i(k) - \frac{\sigma_i^2(k)}{2}) \ge 0$ hold. Then we have

$$\lim_{t \to \infty} \frac{\log y_i(t)}{t} = 0, \quad i = 1, 2, \dots, n, \ a.s.$$
(7)

The proof is omitted here; see [7] for more details.

Lemma 3.2 Let Assumptions 1 and 3 and the inequality $\sum_{k \in S} \pi_k(b_i(k) - \frac{\sigma_i^2(k)}{2}) \ge 0$ hold. Then the solution of system (3) satisfies

$$\lim_{t \to \infty} \frac{\log x_i(t)}{t} = 0, \quad i = 1, 2, \dots, n, \ a.s.$$
(8)

Proof By Lemma 3.1 and (6) we have derived $\limsup_{t\to\infty} \frac{\log x_i(t)}{t} \le 0, i = 1, 2, ..., n$, a.s. Thus we still need to prove that $\liminf_{t\to\infty} \frac{\log x_i(t)}{t} \ge 0, i = 1, 2, ..., n$, a.s. It suffices to show that

$$\liminf_{t \to \infty} \frac{\log z_i(t)}{t} \ge 0, \quad i = 1, 2, \dots, n, \text{ a.s.}$$
(9)

Applying Itô's formula to $z_i^{\theta_i}(t)$, we can readily verify that

$$\frac{1}{z_{i}^{\theta_{i}}(t)} = \frac{1}{x_{i}^{\theta_{i}}(0)} \exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t))\right)\theta_{i}t + \theta_{i}\sum_{j\neq i}\int_{0}^{t}a_{ij}(r(t))y_{j}(s)\,ds\right\}
- \theta_{i}\sigma_{i}(r(t))B_{i}(t) + a_{ii}(r(t))\theta_{i}\int_{0}^{t}\exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t))\right)\theta_{i}(t-s)
- \theta_{i}\sigma_{i}(r(t))(B_{i}(t) - B_{i}(s)) + \theta_{i}\sum_{j\neq i}\int_{s}^{t}a_{ij}(r(t))y_{j}(\tau)\,d\tau\right\}ds
:= E_{i1} + E_{i2}.$$
(10)

A simple computation from (4) shows that

$$\int_{s}^{t} y_{i}^{\theta_{i}}(\tau) d\tau$$

$$= \frac{b_{i}(r(t))}{a_{ii}(r(t))}(t-s) + \frac{\sigma_{i}(r(t))}{a_{ii}(r(t))} (B_{i}(t) - B_{i}(s)) + \frac{1}{a_{ii}(r(t))} (\ln y_{i}(s) - \ln y_{i}(t))$$

$$=: c_{i}(t-s) + m_{i} (B_{i}(t) - B_{i}(s)) + d_{i} (\log y_{i}(s) - \log y_{i}(t)), \quad i = 1, 2, ..., n.$$
(11)

The Hölder inequality then gives

$$\begin{split} \int_{s}^{t} y_{i}(\tau) d\tau &\leq (t-s)^{1-\frac{1}{\theta_{i}}} \left(\int_{s}^{t} y_{i}^{\theta_{i}}(\tau) d\tau \right)^{\frac{1}{\theta_{i}}} \\ &= (t-s)^{1-\frac{1}{\theta_{i}}} \left(c_{i}(t-s) + m_{i} \big(B_{i}(t) - B_{i}(s) \big) + d_{i} \big(\log y_{i}(s) - \log y_{i}(t) \big) \big)^{\frac{1}{\theta_{i}}}, \\ &i = 1, 2, \dots, n. \end{split}$$
(12)

It follows from the inequality $(a + b + c)^p \le 3^{(p-1)\vee 0}(a^p + b^p + c^p)$ that

$$\int_{s}^{t} y_{i}(\tau) d\tau$$

$$\leq (t-s)^{1-\frac{1}{\theta_{i}}} \left(c_{i}^{\frac{1}{\theta_{i}}}(t-s)^{\frac{1}{\theta_{i}}} + m_{i}^{\frac{1}{\theta_{i}}} \left(B_{i}(t) - B_{i}(s) \right)^{\frac{1}{\theta_{i}}} + d_{i}^{\frac{1}{\theta_{i}}} \left(\log y_{i}(s) - \log y_{i}(t) \right)^{\frac{1}{\theta_{i}}} \right),$$

$$i = 1, 2, \dots, n.$$
(13)

For $i = 1, 2, \ldots, n$, we define

$$B_i^*(t) := B_i(t) - \min_{0 \le s \le t} B_i(s),$$

$$\xi_i(t) := \max_{0 \le s \le t} \log y_i(s) - \log y_i(t).$$

Substituting the previous inequality into (10) yields

$$\begin{split} E_{i1} &\leq \frac{1}{x_{i}^{\theta_{i}}(0)} \exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t))\right)\theta_{i}t - \theta_{i}\sigma_{i}(r(t))B_{i}(t) \\ &+ \theta_{i}\sum_{j\neq i}a_{ij}(r(t))(t-s)^{1-\frac{1}{\theta_{j}}}\left(c_{j}^{\frac{1}{\theta_{j}}}(t-s)^{\frac{1}{\theta_{j}}}\right) \\ &+ m_{j}^{\frac{1}{\theta_{j}}}\left(B_{j}(t) - \min_{0\leq s\leq t}B_{j}(s)\right)^{\frac{1}{\theta_{j}}} + d_{j}^{\frac{1}{\theta_{j}}}\left(\max_{0\leq s\leq t}\log y_{j}(s) - \log y_{j}(t)\right)^{\frac{1}{\theta_{j}}}\right)\right\} \\ &\leq \frac{1}{x_{i}^{\theta_{i}}(0)} \exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t))\right)\theta_{i}t + \theta_{i}\sigma_{i}(r(t))\left(\max_{0\leq s\leq t}B_{i}(s) - B_{i}(t)\right) \\ &+ \theta_{i}\sum_{j\neq i}a_{ij}(r(t))t^{1-\frac{1}{\theta_{j}}}\left(c_{j}^{\frac{1}{\theta_{j}}}t^{\frac{1}{\theta_{j}}} + m_{j}^{\frac{1}{\theta_{j}}}\left(B_{j}^{*}(t)\right)^{\frac{1}{\theta_{j}}} + d_{j}^{\frac{1}{\theta_{j}}}\left(\xi_{j}(t)\right)^{\frac{1}{\theta_{j}}}\right)\right\} \\ &\leq \frac{1}{x_{i}^{\theta_{i}}(0)} \exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t)) + \sum_{j\neq i}a_{ij}(r(t))c_{j}^{\frac{1}{\theta_{j}}}\right)\theta_{i}t \\ &+ \theta_{i}\sigma_{i}(r(t))\left(\max_{0\leq s\leq t}B_{i}(s) - B_{i}(t)\right) \\ &+ \theta_{i}\sum_{j\neq i}a_{ij}(r(t))t^{1-\frac{1}{\theta_{j}}}\left(m_{j}^{\frac{1}{\theta_{j}}}\left(B_{j}^{*}(t)\right)^{\frac{1}{\theta_{j}}} + d_{j}^{\frac{1}{\theta_{j}}}\left(\xi_{j}(t)\right)^{\frac{1}{\theta_{j}}}\right)\right\}, \quad i = 1, 2, ..., n. \end{split}$$
(14)

In the same way, we get

$$\begin{split} E_{i2} &\leq a_{ii} \big(r(t) \big) \theta_i \int_0^t \exp \left\{ \left(\frac{\sigma_i^2(r(t))}{2} - b_i \big(r(t) \big) \right) \theta_i(t-s) \\ &- \theta_i \sigma_i \big(r(t) \big) \big(B_i(t) - B_i(s) \big) + \theta_i \sum_{j \neq i} a_{ij} \big(r(t) \big) \big(t-s \big)^{1 - \frac{1}{\theta_j}} \left(c_j^{\frac{1}{\theta_j}}(t-s)^{\frac{1}{\theta_j}} \right) \\ &+ m_j^{\frac{1}{\theta_j}} \left(B_j(t) - \min_{0 \leq s \leq t} B_j(s) \right)^{\frac{1}{\theta_j}} + d_j^{\frac{1}{\theta_j}} \left(\max_{0 \leq s \leq t} \log y_j(s) - \log y_j(t) \right)^{\frac{1}{\theta_j}} \right) \right\} ds \end{split}$$

$$\leq a_{ii}(r(t))\theta_{i}\int_{0}^{t} \exp\left\{\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t)) + \sum_{j\neq i}a_{ij}(r(t))c_{j}^{\frac{1}{\theta_{j}}}\right)\theta_{i}(t-s) + \theta_{i}\sigma_{i}(r(t))\left(\max_{0\leq s\leq t}B_{i}(s) - B_{i}(t)\right) + \theta_{i}\sum_{j\neq i}a_{ij}(r(t))t^{1-\frac{1}{\theta_{j}}}\left(m_{j}^{\frac{1}{\theta_{j}}}\left(B_{j}^{*}(t)\right)^{\frac{1}{\theta_{j}}} + d_{j}^{\frac{1}{\theta_{j}}}\left(\xi_{j}(t)\right)^{\frac{1}{\theta_{j}}}\right)\right\}ds, \quad i = 1, 2, ..., n.$$

$$(15)$$

Substituting this into (10) yields

$$\frac{1}{z_{i}^{\theta_{i}}(t)} \leq \left\{ \frac{1}{x_{i}^{\theta_{i}}(0)} \exp\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t)) + \sum_{j \neq i} a_{ij}(r(t))c_{j}^{\frac{1}{\theta_{j}}}\right) \theta_{i}t \\
+ a_{ii}(r(t))\theta_{i} \int_{0}^{t} \exp\left[\left(\frac{\sigma_{i}^{2}(r(t))}{2} - b_{i}(r(t)) + \sum_{j \neq i} a_{ij}(r(t))c_{j}^{\frac{1}{\theta_{j}}}\right) \theta_{i}(t-s)\right] ds \right\} \\
\times \exp\left\{\theta_{i}\sigma_{i}(r(t))\left(\max_{0\leq s\leq t} B_{i}(s) - B_{i}(t)\right) \\
+ \theta_{i} \sum_{j \neq i} a_{ij}(r(t))t^{1-\frac{1}{\theta_{j}}}\left(m_{j}^{\frac{1}{\theta_{j}}}(B_{j}^{*}(t))^{\frac{1}{\theta_{i}}} + d_{j}^{\frac{1}{\theta_{j}}}(\xi_{j}(t))^{\frac{1}{\theta_{j}}}\right) \right\} \\
:= \phi_{i}^{-1}(t)\exp\left\{\theta_{i}\sigma_{i}(r(t))\left(\max_{0\leq s\leq t} B_{i}(s) - B_{i}(t)\right) \\
+ \theta_{i} \sum_{j\neq i} a_{ij}(r(t))t^{1-\frac{1}{\theta_{j}}}\left(m_{j}^{\frac{1}{\theta_{j}}}(B_{j}^{*}(t))^{\frac{1}{\theta_{j}}} + d_{j}^{\frac{1}{\theta_{j}}}(\xi_{j}(t))^{\frac{1}{\theta_{j}}}\right) \right\}, \quad i = 1, 2, ..., n, \quad (16)$$

where $\phi_i(t)$ satisfies the system

$$\begin{cases} \dot{\phi}_i(t) = \theta_i \phi_i(b_i(r(t)) - \frac{\sigma_i^2(r(t))}{2} - \sum_{j \neq i} a_{ij}(r(t)) c_j^{\frac{1}{\theta_j}} - a_{ii}(r(t))\phi_i(t)), \\ \phi_i(0) = x_i^{\theta_i}(0), \quad i = 1, 2, \dots, n. \end{cases}$$

It follows from (16) that

$$\frac{\log z_i(t)}{t} \ge \frac{\log \phi_i(t)}{\theta_i t} - \frac{\max_{0 \le s \le t} B_i(s) - B_i(t)}{t} \sigma_i(r(t))$$
$$- \sum_{j \ne i} \left(\frac{m_j B_j^*(t)}{t}\right)^{\frac{1}{\theta_j}} - \sum_{j \ne i} \left(\frac{d_j \xi_j(t)}{t}\right)^{\frac{1}{\theta_j}}, \quad \text{a.s. } i = 1, 2, \dots, n.$$
(17)

The Brownian motion implies

$$\lim_{t \to \infty} \frac{\max_{0 \le s \le t} B_i(s) - B_i(t)}{t} = 0,$$

$$\lim_{t \to \infty} \frac{B_j(t) - \min_{0 \le s \le t} B_j(s)}{t} = 0, \quad i = 1, 2, \dots, n.$$
(18)

When $b_i(r(t)) - \frac{\sigma_i^2(r(t))}{2} - \sum_{j \neq i} a_{ij}(r(t))c_j^{\frac{1}{\theta_j}} > 0$, from (16) we can easily see that

$$\lim_{t \to \infty} \frac{\log \phi_i(t)}{t} = 0, \quad \text{a.s. } i = 1, 2, \dots, n.$$
(19)

Note that Lemma 3.1 implies

$$\lim_{t \to \infty} \frac{\max_{0 \le s \le t} \log y_j(s) - \log y_j(t)}{t} = 0 \quad \text{a.s., } i = 1, 2, \dots, n.$$
(20)

From (17) along with (18)-(20) we can verify that

$$\liminf_{t \to \infty} \frac{\log z_i(t)}{t} \ge 0, \qquad \limsup_{t \to \infty} \frac{\log z_i(t)}{t} \le 0 \quad \text{a.s.}, i = 1, 2, \dots, n,$$
(21)

as desired.

Remark 1 The convergence of (8) plays a prominent role in analyzing the asymptotic behavior for stochastic population systems. The property for stochastic Lotka-Volterra systems was discussed in [7], and the property for stochastic Gilpin-Ayala systems was studied in [18] as well. We discuss the system with highly nonlinear item and regime switching. These two factors limit the effectiveness, so the approach used in [7] and [18] is not applicable to system (3). By utilizing some novel techniques the asymptotic behavior for stochastic Gilpin-Ayala systems with regime switching has been studied, which might have a wider application.

Theorem 3.1 Let system (3) satisfy the hypotheses of Assumptions 1-3. Then it is said to be persistent in mean, that is,

$$\begin{split} \liminf_{t \to \infty} \frac{1}{t} \int_{0}^{t} x_{i}^{\theta_{i}}(s, x_{0}, r_{0}) \, ds \\ &\geq \frac{1}{\check{a}_{ii}} \left(\sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right) - \sum_{j \neq i} \check{a}_{ij} \left(\frac{1}{\hat{a}_{jj}} \sum_{k \in S} \pi_{k} \left(b_{j}(k) - \frac{\sigma_{j}^{2}(k)}{2} \right) \right)^{\frac{1}{\theta_{j}}} \right), \\ &\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} x_{i}^{\theta_{i}}(s, x_{0}, r_{0}) \, ds \leq \frac{1}{\hat{a}_{ii}} \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right) \quad a.s., i = 1, 2, \dots, n. \end{split}$$

Proof Our proof is adapted from the works [8] and [18]. It follows by Itô's formula that

$$\log y_i(t) = \log y_i(0) + \int_0^t \left(b_i(r(s)) - \frac{\sigma_i^2(r(s))}{2} \right) ds$$
$$- \int_0^t a_{ii}(r(s)) y_i^{\theta_i}(s) \, ds + \int_0^t \sigma_i(r(s)) \, dB_i(s) \quad \text{a.s.}, i = 1, 2, \dots, n.$$

Thus, it satisfies

$$\frac{1}{t} \int_{0}^{t} a_{ii}(r(s)) y_{i}^{\theta_{i}}(s) ds = \frac{1}{t} \left(\log y_{i}(0) - \log y_{i}(t) \right) + \frac{1}{t} \int_{0}^{t} \left(b_{i}(r(s)) - \frac{\sigma_{i}^{2}(r(s))}{2} \right) ds + \frac{1}{t} \int_{0}^{t} \sigma_{i}(r(s)) dB_{i}(s) a.s., i = 1, 2, ..., n.$$
(22)

$$\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} \sigma_{i}(r(s)) dB_{i}(s) = 0 \quad \text{a.s.,}$$

$$\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} \left(b_{i}(r(s)) - \frac{\sigma_{i}^{2}(r(s))}{2} \right) ds = \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right)$$

$$\text{a.s., } i = 1, 2, \dots, n.$$
(23)

By Lemma 3.1 we obtain from (22) that

$$\lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} a_{ii}(r(s)) y_{i}^{\theta_{i}}(s) \, ds = \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right)$$

a.s., *i* = 1, 2, ..., *n*. (24)

Therefore, for i = 1, 2, ..., n, we have

$$\begin{split} \limsup_{t \to \infty} \frac{1}{t} \int_0^t x_i^{\theta_i}(s) \, ds &\leq \limsup_{t \to \infty} \frac{1}{t} \int_0^t y_i^{\theta_i}(s) \, ds \\ &\leq \frac{1}{\hat{a}_{ii}} \limsup_{t \to \infty} \frac{1}{t} \int_0^t a_{ii}(r(s)) y_i^{\theta_i}(s) \, ds \\ &= \frac{1}{\hat{a}_{ii}} \sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) \quad \text{a.s.} \end{split}$$

Applying Itô's formula to $z_i^{\theta_i}(t)$ yields

$$\log z_{i}(t) = \log z_{i}(0) + \int_{0}^{t} \left(b_{i}(r(s)) - \frac{\sigma_{i}^{2}(r(s))}{2} \right) ds - \int_{0}^{t} a_{ii}(r(s)) z_{i}^{\theta_{i}}(s) ds$$
$$- \int_{0}^{t} \sum_{j \neq i} a_{ij}(r(s)) y_{j}(s) ds + \int_{0}^{t} \sigma_{i}(r(s)) dB_{i}(s)$$
a.s., $i = 1, 2, ..., n.$ (25)

The well-known Hölder inequality then gives

$$\frac{1}{t} \int_0^t x_i \, ds \le \left(\frac{1}{t} \int_0^t x_i^{\theta_i}(s)\right)^{\frac{1}{\theta_i}}, \quad i = 1, 2, \dots, n.$$

Using Lemma 3.2 along with the Hölder inequality and the ergodic property of r(t), we have

$$\frac{1}{t} \int_0^t a_{ii}(r(s)) z_i^{\theta_i}(s) \, ds$$

= $\frac{1}{t} \left(\log z_i(0) - \log z_i(t) \right) + \frac{1}{t} \int_0^t \left(b_i(r(s)) - \frac{\sigma_i^2(r(s))}{2} \right) ds$

$$-\frac{1}{t} \int_{0}^{t} \sum_{j \neq i} a_{ij}(r(s)) y_{j}(s) ds + \frac{1}{t} \int_{0}^{t} \sigma_{i}(r(s)) dB_{i}(s)$$

$$\geq \frac{1}{t} (\log z_{i}(0) - \log z_{i}(t)) + \frac{1}{t} \int_{0}^{t} \left(b_{i}(r(s)) - \frac{\sigma_{i}^{2}(r(s))}{2} \right) ds$$

$$- \sum_{j \neq i} \check{a}_{ij} \left(\frac{1}{t} \int_{0}^{t} y_{j}^{\theta_{j}}(s) ds \right)^{\frac{1}{\theta_{j}}} + \frac{1}{t} \int_{0}^{t} \sigma_{i}(r(s)) dB_{i}(s)$$

$$\geq \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right) - \sum_{j \neq i} \check{a}_{ij} \left(\frac{1}{\hat{a}_{jj}} \sum_{k \in S} \pi_{k} \left(b_{j}(k) - \frac{\sigma_{j}^{2}(k)}{2} \right) \right)^{\frac{1}{\theta_{j}}}.$$
(26)

We therefore have

,

$$\begin{split} \liminf_{t \to \infty} \frac{1}{t} \int_0^t x_i^{\theta_i}(s) \, ds \\ &\geq \liminf_{t \to \infty} \frac{1}{t} \int_0^t z_i^{\theta_i}(s) \, ds \geq \frac{1}{\check{a}_{ii}} \limsup_{t \to \infty} \frac{1}{t} \int_0^t a_{ii}(r(s)) z_i^{\theta_i}(s) \, ds \\ &\geq \frac{1}{\check{a}_{ii}} \left(\sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) - \sum_{j \neq i} \check{a}_{ij} \left(\frac{1}{\hat{a}_{jj}} \sum_{k \in S} \pi_k \left(b_j(k) - \frac{\sigma_j^2(k)}{2} \right) \right)^{\frac{1}{\theta_j}} \right), \end{split}$$

as desired. For i = 1, 2, ..., n, system (3) is persistent in mean.

Remark 2 When $\theta_i = 1$, i = 1, 2, ..., n, system (3) reduces to the stochastic competitive Lotka-Volterra systems with regime switching, the conditions on persistence in mean are in accordance with the results in [8].

4 Extinction

In this section, we verify that the system will become extinct if the noise is sufficiently large.

Theorem 4.1 Suppose that Assumption 1 holds and there exists an integer $m \le n$ such that

$$\sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) < 0, \quad i = 1, 2, ..., m,$$

$$\sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) = 0, \quad i = m + 1, ..., n.$$
(27)

Then we have

(i) The previous m species of system (3) are almost surely exponentially extinct with the exponential rate of the ith species $-\sum_{k \in S} \pi_k (\frac{\sigma_i^2(k)}{2} - b_i(k))$, that is,

$$\lim_{t \to \infty} \frac{\log x_i(t, x_0, r_0)}{t} = -\sum_{k \in S} \pi_k \left(\frac{\sigma_i^2(k)}{2} - b_i(k) \right) \quad a.s.$$
(28)

(ii) The following n - m species will extinct with zero exponential rate, that is,

$$\lim_{t \to \infty} x(t, x_0, r_0) = 0 \quad a.s.$$
⁽²⁹⁾

Proof We begin by proving the exponential extinction for the top *m* species of system (3) when $\sum_{k \in S} \pi_k(b_i(k) - \frac{\sigma_i^2(k)}{2}) < 0, i = 1, 2, ..., m$. The next goal is to show the zero exponential extinction for the bottom n - m species when $\sum_{k \in S} \pi_k(b_i(k) - \frac{\sigma_i^2(k)}{2}) = 0, i = m + 1, ..., n$. *Step 1*. We aim to prove assertion (28). By Itô's formula we get

$$\log x_{i}(t) = \log x_{i}(0) + \int_{0}^{t} \left(b_{i}(r(s)) - \frac{\sigma_{i}^{2}(r(s))}{2} \right) ds$$
$$- \int_{0}^{t} \left(a_{ii}(r(s)) x_{i}^{\theta_{i}}(s) + \sum_{j \neq i} a_{ij}(r(s)) x_{j}(s) \right) ds + M_{i}(t),$$

 $i=1,2,\ldots,n,$

where $M_i(t) = \int_0^t \sigma_i(r(s)) dB_i(s)$, i = 1, 2, ..., n. Dividing both sides by t yields

$$\frac{\log x_i(t)}{t} = \frac{\log x_i(0)}{t} + \frac{1}{t} \int_0^t \left(b_i(r(s)) - \frac{\sigma_i^2(r(s))}{2} \right) ds - \frac{1}{t} \int_0^t \left(a_{ii}(r(s)) x_i^{\theta_i}(s) + \sum_{j \neq i} a_{ij}(r(s)) x_j(s) \right) ds + \frac{M_i(t)}{t}, i = 1, 2, \dots, n.$$
(30)

By the strong law of large numbers for martingales (see [20]) we derive $\lim_{t\to\infty} \frac{1}{t} \times \int_0^t \sigma_i(r(s)) dB_i(s) = 0$ a.s., i = 1, 2, ..., n. For i = 1, 2, ..., m, letting $t \to \infty$ on both sides of (30), we have

$$\limsup_{t \to \infty} \frac{\log x_i(t)}{t} \le -\sum_{k \in S} \pi_k \left(\frac{\sigma_i^2(k)}{2} - b_i(k) \right) < 0, \quad i = 1, 2, \dots, m, \text{ a.s.}$$
(31)

By (31), for any $1 \le i \le k$ and $\varepsilon \in (0, \min_{1 \le i \le k} \sum_{k \in S} \pi_k(\frac{\sigma_i^{2}(k)}{2} - b_i(k)))$, we can select a random variable $T(\varepsilon)$ such that

$$x_i(t) \le \exp\left(-\sum_{k \in S} \pi_k \left(\frac{\sigma_i^2(k)}{2} - b_i(k)\right) t + \varepsilon t\right), \quad \forall t > T(\varepsilon), i = 1, 2, \dots, m, \text{ a.s.}$$
(32)

Thus it follows that

$$x_i^{\theta_i}(t) \le \exp\left(-\theta_i \sum_{k \in S} \pi_k \left(\frac{\sigma_i^2(k)}{2} - b_i(k)\right) t + \theta_i \varepsilon t\right), \quad \forall t > T(\varepsilon), i = 1, 2, \dots, m, \text{ a.s.}$$

Then we can readily verify that

$$\int_0^\infty \left(a_{ii}(r(s)) x_i^{\theta_i}(s) + \sum_{j \neq i} a_{ij}(r(s)) x_j(s) \right) ds < \infty, \quad i = 1, 2, \dots, m, \text{ a.s.}$$
(33)

By (30) and (33) we have

$$\lim_{t\to\infty}\frac{\log x_i(t)}{t}=-\sum_{k\in S}\pi_k\left(\frac{\sigma_i^2(k)}{2}-b_i(k)\right),\quad i=1,2,\ldots,m, \text{ a.s.}$$

Step 2. We only need to show assertion (29). Applying Itô's formula to $\log x_i^{\theta_i}(t)$, we get

$$\frac{\log x_i(t)}{t} = \frac{\log x_i(0)}{t} - \frac{1}{t} \int_0^t a_{ii}(r(s)) x_i^{\theta_i}(s) \, ds - \frac{1}{t} \sum_{j=1, j \neq i}^n \int_0^t a_{ij}(r(s)) x_i(s) \, ds + \frac{1}{t} \int_0^t \sigma_i \, dB_i(s).$$
(34)

Based on the convergence of the integral $\int_0^\infty x_i(s) \, ds$, the sample space Ω can be decomposed into two mutually exclusive events

$$G_{i1} = \left\{ \omega : \int_0^\infty x_i(s) \, ds < \infty \right\} \quad \text{and} \quad G_{i2} = \left\{ \omega : \int_0^\infty x_i(s) \, ds = \infty \right\}.$$

Furthermore, we can also divide Ω into three mutually exclusive events

$$F_{i1} = \left\{ \omega : \limsup_{t \to \infty} x_i(t) \ge \lim_{t \to \infty} \inf_{t \to \infty} x_i(t) = \gamma_i > 0 \right\},$$

$$F_{i2} = \left\{ \omega : \limsup_{t \to \infty} x_i(t) > \lim_{t \to \infty} \inf_{t \to \infty} x_i(t) = 0 \right\}, \text{ and }$$

$$F_{i3} = \left\{ \omega : \lim_{t \to \infty} x_i(t) = 0 \right\}.$$

The proof of $\lim_{t\to\infty} x_i(t) = 0$ a.s. is equivalent to showing that $G_{i1} \subset F_{i3}$ and $G_{i2} \subset F_{i3}$ a.s. The following is an outline of the proof.

First, using stochastic LaSalle methods proposed in [22], we prove that $G_{i1} \subset F_{i3}$. Second, using the novel techniques, we show that $P(G_{i2} \cap F_{i1}) = 0$ and $P(G_{i2} \cap F_{i2}) = 0$, which means that $G_{i2} \subset F_{i3}$ a.s. Now we map out our strategy.

Case 1: The continuity of $x_i(t)$ and definition of G_{in} imply that $P(G_{i1} \cap F_{i1}) = 0$. Now we prove it by a contradiction.

Now let us show that $G_{i1} \subset F_{i3}$. Clearly, $x_i(t) \in C(R_+, R)$ a.s. It is easy to check from G_{i1} that $\liminf_{t\to\infty} x_i(t) = 0$ a.s. Therefore, we obtain that $P(G_{i1} \cap F_{i1}) = 0$. The only thing that remains to show is $P(G_{i1} \cap F_{i2}) = 0$. If $P(G_{i1} \cap F_{i2}) > 0$, then there exists a real number $\varepsilon > 0$ such that

$$P(Q_1 \cap G_{i1}) \ge 2\varepsilon, \tag{35}$$

where $Q_1 = \{\limsup_{t \to \infty} x_i(t) > 2\varepsilon\}$. Define the sequence of stopping times

$$\begin{aligned} &\tau_1 = \inf\{t \ge 0 : x_i(t) \ge 2\varepsilon\}, \qquad \tau_{2k} = \inf\{t \ge \tau_{2k-1} : x_i(t) \le \varepsilon\}, \\ &\tau_{2k+1} = \inf\{t \ge \tau_{2k} : x_i(t) \ge 2\varepsilon\}, \qquad k = 1, 2, \dots. \end{aligned}$$

We have $E(I_{G_{i1}} \int_0^\infty x_i(s) \, ds) < \infty$ from G_{i1} . Then we compute and rearrange

$$E\left(I_{G_{i1}}\int_{0}^{\infty} x_{i}(s) \, ds\right) \ge \sum_{k=1}^{\infty} E\left(I_{\{\tau_{2k-1} < \infty, \tau_{2k} < \infty\} \cap G_{i1}}\int_{\tau_{2k-1}}^{\tau_{2k}} x_{i}(s) \, ds\right)$$
$$\ge \varepsilon \sum_{k=1}^{\infty} E\left(I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}}(\tau_{2k} - \tau_{2k-1})\right),$$

where I_A is the indicator function. Since $\tau_{2k} < \infty$ whenever $\tau_{2k-1} < \infty$, by the above formula we have

$$\varepsilon \sum_{k=1}^{\infty} E(I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}}(\tau_{2k-1} - \tau_{2k})) < \infty.$$
(36)

Integrating equation (3), we have

$$\begin{aligned} x_{i}(t) &= x_{i}(0) + \int_{0}^{t} \sigma_{i} x_{i}(s) \, dB_{i}(s) \\ &+ \int_{0}^{t} x_{i}(s) \left(b_{i}(r(s)) - a_{ii}(r(s)) x_{i}^{\theta_{i}}(s) - \sum_{j=1, j \neq i}^{n} a_{ij}(r(s)) x_{j}(s) \right) ds. \end{aligned}$$
(37)

Compute and rearrange

$$\begin{split} & E\left\{x_{i}^{2}(s)\cdot\left(b_{i}(r(s))-a_{ii}(r(s))x_{i}^{\theta_{i}}(s)-\sum_{j=1,j\neq i}^{n}a_{ij}(r(s))x_{j}(s)\right)^{2}\right\}\\ &\leq \frac{1}{2}E(x_{i}^{4}(s))+\frac{1}{2}E\left(b_{i}(r(s))-a_{ii}(r(s))x_{i}^{\theta_{i}}(s)-\sum_{j=1,j\neq i}^{n}a_{ij}(r(s))x_{j}(s)\right)^{4}\\ &\leq \frac{1}{2}E(x_{i}^{4}(s))+\frac{1}{2}E\left(b^{4}+a_{ii}^{4}x_{i}^{4\theta_{i}}+\sum_{j=1,j\neq i}^{n}a_{ij}^{4}x_{j}^{4}+4a_{ii}^{3}x_{i}^{3\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}x_{j}+4a_{ii}x_{i}^{\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}^{3}x_{j}^{3}\right.\\ &+ 6b^{2}a_{ii}^{2}x_{i}^{2\theta_{i}}+6b^{2}\sum_{j=1,j\neq i}^{n}a_{ij}^{2}x_{j}^{2}+6a_{ii}^{2}x_{i}^{2\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}x_{j}^{2}+12b^{2}a_{ii}x_{i}^{\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}x_{j}\right)\\ &\leq \frac{1}{2}K_{4}+\frac{1}{2}\left(b_{i}^{4}+a_{ii}^{4}K_{4\theta_{i}}+\sum_{j=1,j\neq i}^{n}a_{ij}^{4}K_{4}+4a_{ii}^{3}K_{3\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}K_{1}+4a_{ii}K_{\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}^{3}K_{3}\right.\\ &+ 6b^{2}a_{ii}^{2}K_{2\theta_{i}}+6b^{2}\sum_{j=1,j\neq i}^{n}a_{ij}^{2}K_{2}+6a_{ii}^{2}K_{2\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}^{2}K_{2}+12b^{2}a_{ii}K_{\theta_{i}}\sum_{j=1,j\neq i}^{n}a_{ij}K_{1}\right)\\ &=:\mathcal{U}_{i}^{2}\end{split}$$

and

$$E(\sigma_i^2 \cdot x_i^2(s)) = \sigma_i^2 \cdot E(x_i^2(s)) \le \sigma_i^2 \cdot K_2 =: V_i^2,$$

where K_1 , K_2 , K_3 , K_4 and K_{θ_i} , $K_{2\theta_i}$, $K_{3\theta_i}$, $K_{4\theta_i}$ are defined in Lemma 2.1. By the *BDG* inequality (see [20]) and the Hölder inequality we compute

$$E\left(I_{\{\tau_{2k-1}<\infty\}\cap G_{i1}}\sup_{0\leq t\leq T}\left|x_{i}(\tau_{2k-1}+t)-x_{i}(\tau_{2k-1})\right|^{2}\right)$$

$$\leq 2E\left\{I_{\{\tau_{2k-1}<\infty\}\cap G_{i1}}\sup_{0\leq t\leq T}\left|\int_{\tau_{2k-1}}^{\tau_{2k-1}+t}x_{i}(s)\left(b_{i}(r(s))-a_{ii}(r(s))x_{i}^{\theta_{i}}(s)-\sum_{j=1,j\neq i}^{n}a_{ij}(r(s))x_{j}(s)\right)ds\right|^{2}\right\}$$

$$+ 2E \left(I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}} \sup_{0 \le t \le T} \left| \int_{\tau_{2k-1}}^{\tau_{2k-1}+t} (\sigma_i \cdot x_i(s)) dB_i(s) \right|^2 \right)$$

$$\leq 2TE \left\{ I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}} \int_{\tau_{2k-1}}^{\tau_{2k-1}+T} x_i^2(s) \left(b_i(r(s)) - a_{ii}(r(s)) x_i^{\theta_i}(s) - \sum_{j=1, j \ne i}^n a_{ij}(r(s)) x_j(s) \right)^2 ds \right\}$$

$$+ 8E \left(I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}} \int_{\tau_{2k-1}}^{\tau_{2k-1}+T} (\sigma_i^2 \cdot x_i^2(s)) ds \right)$$

$$\leq 2T \left(U_i^2 + 4V_i^2 \right). \tag{38}$$

Choosing $T = T(\varepsilon) > 0$ sufficiently small for $2T(U_i^2 + 4V_i^2) \le \varepsilon^3$, from (38) we have

$$P(\{\tau_{2k-1} < \infty\} \cap \{H_k \cap J_{i1}\}) \le \frac{2(T+4)T(U_i^2 + V_i^2)}{\varepsilon^2} \le \varepsilon,$$
(39)

where $H_k = {\sup_{1 \le t \le T} |x_i(\tau_{2k-1} + t) - x_i(\tau_{2k-1})| \ge \varepsilon}$, $k = 1, 2, \dots$ Noting that $\tau_k < \infty$ for $k = 1, 2, \dots$ whenever $\omega \in Q_1$, we further compute

$$\begin{split} & P\big(\{\tau_{2k-1} < \infty\} \cap \big\{H_k^c \cap G_{i1}\big\}\big) \\ &= P\big(\{\tau_{2k-1} < \infty\} \cap G_{i1}\big) - P\big(\{\tau_{2k-1} < \infty\} \cap \{H_k \cap G_{i1}\}\big) \\ &\geq 2\varepsilon - \varepsilon = \varepsilon. \end{split}$$

Note that if $\omega \in \{\tau_{2k-1} < \infty\} \cap \{H_k^c \cap G_{i1}\}$, then

$$\tau_{2k}(\omega) - \tau_{2k-1}(\omega) \ge T. \tag{40}$$

We obtain from (36) and (40) that

$$\infty > \varepsilon \sum_{k=1}^{\infty} E[I_{\{\tau_{2k-1} < \infty\} \cap G_{i1}}(\tau_{2k} - \tau_{2k-1})]$$

$$\geq \varepsilon \sum_{k=1}^{\infty} E[I_{\{\tau_{2k-1} < \infty\} \cap \{H_k^c \cap G_{i1}\}}(\tau_{2k-1} - \tau_{2k})]$$

$$\geq \varepsilon T \sum_{k=1}^{\infty} P(\{\tau_{2k-1} < \infty\} \cap \{H_k^c \cap G_{i1}\})$$

$$\geq \varepsilon T \sum_{k=1}^{\infty} \varepsilon = \infty,$$
(41)

which is a contraction. So $P(G_{i1} \cap F_{i2}) = 0$ holds, and we derive that $G_{i1} \subset F_{i3}$.

Case 2. It remains to prove $G_{i2} \subset F_{i3}$ a.s. We need only to show that $P(G_{i2} \cap F_{i1}) = 0$ and $P(G_{i2} \cap F_{i2}) = 0$. We prove it by a contradiction. If $P(G_{i2} \cap F_{i1}) > 0$, then for any $\omega \in G_{i2} \cap F_{i1}$, $\epsilon_0 \in (0, \frac{\gamma_i}{2})$, there exists $T = (\epsilon_0, \omega)$ such that

$$x_i(t) > \gamma_i - \epsilon_0 > \frac{\gamma_i}{2}, \quad \forall t > T, \text{ a.s.}$$

Then it follows that

$$\frac{1}{t} \int_0^t x_i(s) \, ds = \frac{1}{t} \int_0^T x_i(s) \, ds + \frac{1}{t} \int_T^t x_i(s) \, ds$$
$$\geq \frac{1}{t} \int_0^T x_i(s) \, ds + \frac{t-T}{t} \frac{\gamma_i}{2} \quad \text{a.s.}$$

Letting $t \to \infty$, we get

$$\liminf_{t\to\infty}\frac{1}{t}\int_0^t x_i(s)\,ds>\frac{\gamma_i}{2}>0\quad\text{a.s.}$$

This implies

$$\limsup_{t\to\infty}\frac{\log x_i(t)}{t}\leq -\sum_{j=1}^na_{ij}\frac{\gamma_i}{2}<0\quad\text{a.s.,}$$

which contradicts the definition of J_{i2} and F_{i1} . So $P(G_{i2} \cap F_{i1}) = 0$ must be established. We proceed to show that $P(G_{i2} \cap F_{i2}) > 0$ is false. We need several notations:

$$\begin{split} &\Gamma_t^{\varepsilon}(i) := \left\{ 0 \leq s \leq t : x_i(s) \geq \varepsilon \right\}, \\ &\delta_t^{\varepsilon}(i) := \frac{m(\Gamma_t^{\varepsilon}(i))}{t}, \\ &\delta^{\varepsilon}(i) := \liminf_{t \to \infty} \delta_t^{\varepsilon} i, \\ &\Delta^{\varepsilon}(i) := \left\{ \omega \in J_{i2} \cap F_{i2} : \delta^{\varepsilon}(i) > 0 \right\}, \end{split}$$

where $m(\Gamma_t^{\varepsilon}(i))$ denotes the length of $\Gamma_t^{\varepsilon}(i)$. It is easy to see that $\Delta^0(i) = G_{i2} \cap F_{i2}$. Note that, for any $\varepsilon_1 < \varepsilon_2$,

$$\begin{split} &\Gamma_t^{\varepsilon_1}(i) \supset \Gamma_t^{\varepsilon_2}(i), \qquad m\big(\Gamma_t^{\varepsilon_1}(i)\big) \ge m\big(\Gamma_t^{\varepsilon_2}(i)\big), \\ &\delta_t^{\varepsilon_1}(i) = \frac{m(\Gamma_t^{\varepsilon_1})(i)}{t} \ge \delta_t^{\varepsilon_2}(i) = \frac{m(\Gamma_t^{\varepsilon_2})(i)}{t}, \end{split}$$

which implies

$$\delta^{\varepsilon_2}(i) \leq \delta^{\varepsilon_1}(i), \qquad \Delta^{\varepsilon_2}(i) \subset \Delta^{\varepsilon_1}(i), \quad \forall \varepsilon_1 < \varepsilon_2.$$

By the continuity of probability we have

$$P(\Delta^{\varepsilon}(i)) \to P(\Delta^{0}(i)) = P(G_{2} \cap F_{2}) \text{ as } \varepsilon \to 0.$$

If $P(G_{i2} \cap F_{i2}) > 0$, then there exists $\varepsilon > 0$ such that $P(D^{\varepsilon}) > 0$. For any $\omega \in \Delta^{\varepsilon}(i)$, we have

$$\begin{split} \frac{1}{t} \int_0^t x_i(s) \, ds &= \frac{1}{t} \int_{\Pi_t^{\mathcal{E}}(i)} x_i(s) \, ds + \frac{1}{t} \int_{[0,t] \setminus \Pi_t^{\mathcal{E}}} x_i(s) \, ds \\ &\geq \frac{1}{t} \int_{\Pi_t^{\mathcal{E}}(i)} x_i(s) \, ds \quad \text{a.s.} \end{split}$$

Letting $t \to \infty$, we get

$$\liminf_{t \to \infty} \frac{1}{t} \int_0^t x_i(s) \, ds \ge \liminf_{t \to \infty} \frac{1}{t} \int_{\Pi_t^\varepsilon} x_i(s) \, ds \ge \delta^\varepsilon(i)\varepsilon \quad \text{a.s.}$$
(42)

Substituting (42) into (29), we have

$$\limsup_{t\to\infty}\frac{\log x_i(t)}{t}\leq -\sum_{j=1}^n a_{ij}\delta^{\varepsilon}(i)\varepsilon<0\quad\text{a.s.}$$

This contradicts the definitions of G_{i2} and F_{i2} . Consequently, we conclude that $P(G_{i2} \cap F_{i2}) = 0$. Combining the facts $G_{i1} \subset F_{i3}$, $P(J_{i2} \cap F_{i1}) = 0$, and $P(G_{i2} \cap F_{i2}) = 0$, we derive

$$\lim_{t\to\infty}x_i(t)=0 \quad \text{a.s.,}$$

as desired.

.

Remark 3 The difficulties come from the nonlinearities and regime switching. Based on stochastic LaSalle theorem and the space-decomposition method (see [8] and [22]), we overcome the difficulties. If system (3) does not contain parametric switching and $\theta_i = 1$, i = 1, 2, ..., n, it happens to be the result in [7]. Therefore, Theorem 4.1 generalizes the results in [7] and [8].

5 Partial persistence in mean and partial extinction

We will discuss the partial persistence in mean and partial extinction on certain conditions later. Define the auxiliary stochastic differential equation:

$$\begin{cases} du_i(t) = u_i(b_i(r(t)) - a_{ii}(r(t))u_i^{\theta_i} - \sum_{j=1, j \neq i}^m a_{ij}(r(t))u_j) dt + \sigma_i(r(t)) dB_i(t), \\ u_i(0) = x_i(0), \qquad r(0) = r_0, \quad i = 1, 2, \dots, m. \end{cases}$$
(43)

Theorem 5.1 Suppose that Assumption 1 holds and there exists an integer $1 \le m \le n$ such that

$$\sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) > 0, \qquad a_{ii}(k) - \sum_{j=1, j \neq i}^m a_{ji}(k) > 0, \quad \forall k \in S, i = 1, 2, \dots, m,$$

$$\sum_{k \in S} \pi_k \left(\left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) - \sum_{j=1, j \neq i}^m \frac{a_{ij}(k)}{a_{jj}(k)} \left(b_j(k) - \frac{\sigma_j^2(k)}{2} \right) \right) > 0,$$

$$i = 1, 2, \dots, m,$$

$$\sum_{k \in S} \left(l_k(k) - \frac{\sigma_i^2(k)}{2} \right) = 0 \quad \text{i.}$$
(44)

 $\sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) < 0, \quad i = m + 1, \dots, n.$ (45)

Then we have

(i) For i = 1, 2, ..., m, the solution $x_i(t, x_0, r_0)$ to system (3) satisfies

That is, the species i is persistent in mean for each i = 1, 2, ..., m; (ii) For i = m + 1, ..., n, the solution $x_i(t, x_0, r_0)$ to system (3) satisfies

$$\limsup_{t \to \infty} \frac{\log x_i(t)}{t} \le \sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) \quad a.s.,$$
(48)

that is, system (3) will become extinct.

Proof The proof is divided into two steps. The first step is to show the persistence in mean of the previous *m* species. The second step is to show the extinction of the following n - m species.

Step 1. We analyze the convergence of $x_i^{\theta_i}(t) - u_i^{\theta_i}(t)$ as $t \to \infty$, where $u_i(t)$ is the solution to equation (43). Applying Itô's formula to system (43) yields

$$d(\log u_{i}(t)) = \left(b_{i}(r(t)) - a_{ii}(r(t))u_{i}^{\theta_{i}} - \sum_{j=1, j \neq i}^{m} a_{ij}(r(t))u_{j}\right)dt + \sigma_{i}(r(t))dB_{i}(t).$$
(49)

For *i* = 1, 2, ..., *m*, we have

$$d(\log x_{i}(t) - \log u_{i}(t))$$

$$= -\sum_{j=1, j \neq i}^{m} a_{ij}(r(t))(x_{j} - u_{j}) dt - \sum_{j=m+1}^{n} a_{ij}(r(t))x_{j} dt$$

$$- a_{ii}(r(t))(x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}).$$
(50)

Applying Itô's formula to $V(t) = \sum_{i=1}^{m} |\log x_i^{\theta_i}(t) - \log u_i^{\theta_i}(t)|$ yields

$$D^{+}V(t) = \sum_{i=1}^{m} \operatorname{sign}(x_{i}^{\theta_{i}}(t) - u_{i}^{\theta_{i}}(t)) (d \log x_{i}^{\theta_{i}}(t) - d \log u_{i}^{\theta_{i}}(t))$$

$$= -\sum_{i=1}^{m} \operatorname{sign}(x_{i}^{\theta_{i}}(t) - u_{i}^{\theta_{i}}(t))$$

$$\cdot \left(\sum_{j=1, j \neq i}^{m} a_{ij}(r(t)) (x_{j}^{\theta_{i}} - u_{j}^{\theta_{i}}) dt + \sum_{j=m+1}^{n} a_{ij}(r(t)) x_{j}^{\theta_{i}} dt + a_{ii}(r(t)) (x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}})\right)$$

$$\leq -\sum_{i=1}^{m} a_{ii}(r(t)) |x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}| dt + \sum_{i=1}^{m} \sum_{j=1, j \neq i}^{m} a_{ij}(r(t)) |x_{j}^{\theta_{i}} - u_{j}^{\theta_{i}}| dt + \sum_{i=1}^{m} \sum_{j=m+1}^{n} a_{ij}(r(t)) x_{j}^{\theta_{i}} dt = -\sum_{i=1}^{m} a_{ii}(r(t)) |x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}| dt + \sum_{j=1}^{m} \sum_{i=1, i \neq j}^{m} a_{ji}(r(t)) |x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}| dt + \sum_{i=1}^{m} \sum_{j=m+1}^{n} a_{ij}(r(t)) x_{j}^{\theta_{i}} dt \leq -\sum_{i=1}^{m} a_{ii}(r(t)) |x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}| dt + \sum_{i=1}^{m} \sum_{j=1, j \neq i}^{m} a_{ji}(r(t)) |x_{i}^{\theta_{i}} - u_{i}^{\theta_{i}}| dt + \sum_{i=1}^{m} \sum_{j=m+1}^{n} a_{ij}(r(t)) x_{j}^{\theta_{i}} dt = -\sum_{i=1}^{m} \left(a_{ii}(r(t)) - \sum_{j \neq i} a_{ji}(r(t))\right) |x_{i}^{\theta_{i}}(t) - u_{i}^{\theta_{i}}(t)| dt + \sum_{i=1}^{m} \sum_{j=m+1}^{n} a_{ij}(r(t)) x_{j}^{\theta_{i}}(t) dt.$$

Then we have

$$D^{+}V(t) \leq -\mu \sum_{i=1}^{m} \left| x_{i}^{\theta_{i}}(t) - u_{i}^{\theta_{i}}(t) \right| dt + \sum_{j=m+1}^{n} \alpha_{j} x_{j}^{\theta_{i}}(t) dt, \quad \text{a.s. } i = 1, 2, \dots, m,$$
(51)

where $\mu = \min_{1 \le i \le m} (a_{ii}(r(t)) - \sum_{j \ne i} a_{ji}(r(t))) > 0$ and $\alpha_j = \sum_{i=1}^m a_{ij}(r(t)) \ge 0$. Therefore it satisfies

$$V(t) + \mu \int_{0}^{t} \sum_{i=1}^{m} \left| x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right| ds \leq V(0) + \sum_{j=m+1}^{n} \alpha_{j} \int_{0}^{t} x_{j}^{\theta_{i}}(s) ds$$

a.s. $i = 1, 2, ..., m.$ (52)

Letting $t \to \infty$, we get

$$\int_{0}^{\infty} \left| x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right| ds \leq \int_{0}^{\infty} \sum_{i=1}^{m} \left| x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right| ds$$
$$\leq \frac{1}{\mu} \left(V(0) + \sum_{j=m+1}^{n} \alpha_{j} \int_{0}^{\infty} x_{j}^{\theta_{i}}(s) ds \right).$$
(53)

Note that by Theorem 4.1 and (45)

$$\int_0^\infty x_j^{\theta_i}(s) \, ds < +\infty \quad \text{a.s. } j = m+1, \dots, n.$$
(54)

By (54), the inequality (53) satisfies

$$\int_{0}^{\infty} \left| x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right| ds < +\infty \quad \text{a.s. } i = 1, 2, \dots, m.$$
(55)

Thus by Lemmas 5.1 and 5.2 (see [8] for more details) we have

$$\lim_{t \to +\infty} \left(x_i^{\theta_i}(s) - u_i^{\theta_i}(s) \right) = 0 \quad \text{a.s. } i = 1, 2, \dots, m.$$
(56)

It follows from Theorem 3.1 that system (43) is persistent in mean, namely,

$$\begin{split} \liminf_{t \to \infty} \frac{1}{t} \int_{0}^{t} u_{i}^{\theta_{i}}(s) \, ds \\ &\geq \frac{1}{\check{a}_{ii}} \bigg\{ \sum_{k \in S} \pi_{k} \bigg(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \bigg) - \sum_{j \neq i} \check{a}_{ij} \bigg(\frac{1}{\hat{a}_{jj}} \sum_{k \in S} \pi_{k} \bigg(b_{j}(k) - \frac{\sigma_{j}^{2}(k)}{2} \bigg) \bigg)^{\frac{1}{\theta_{j}}} \bigg\}, \end{split}$$
(57)
$$\\ \begin{split} \limsup_{t \to \infty} \frac{1}{t} \int_{0}^{t} u_{i}^{\theta_{i}}(s) \, ds \leq \frac{1}{\hat{a}_{ii}} \sum_{k \in S} \pi_{k} \bigg(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \bigg), \end{aligned}$$
a.s. $i = 1, 2, \dots, n.$

For *i* = 1, 2, ..., *m*, note that (57) implies

$$\begin{aligned} \liminf_{t \to \infty} \frac{1}{t} \int_{0}^{t} x_{i}^{\theta_{i}}(s) \, ds \\ &= \liminf_{t \to \infty} \frac{1}{t} \int_{0}^{t} \left(x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right) \, ds + \liminf_{t \to \infty} \frac{1}{t} \int_{0}^{t} u_{i}^{\theta_{i}}(s) \, ds \\ &\geq \frac{1}{\check{a}_{ii}} \left\{ \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right) - \sum_{j \neq i} \check{a}_{ij} \left(\frac{1}{\hat{a}_{jj}} \sum_{k \in S} \pi_{k} \left(b_{j}(k) - \frac{\sigma_{j}^{2}(k)}{2} \right) \right)^{\frac{1}{\theta_{j}}} \right\} \\ \text{a.s. } i = 1, 2, \dots, m, \end{aligned}$$

$$(58)$$

$$\limsup_{t \to \infty} \frac{1}{t} \int_{0}^{t} x_{i}^{\theta_{i}}(s) ds$$

$$= \limsup_{t \to \infty} \frac{1}{t} \int_{0}^{t} \left(x_{i}^{\theta_{i}}(s) - u_{i}^{\theta_{i}}(s) \right) ds + \limsup_{t \to \infty} \frac{1}{t} \int_{0}^{t} u_{i}^{\theta_{i}}(s) ds$$

$$\leq \frac{1}{\hat{a}_{ii}} \sum_{k \in S} \pi_{k} \left(b_{i}(k) - \frac{\sigma_{i}^{2}(k)}{2} \right) \quad \text{a.s., } i = 1, 2, \dots, m.$$
(59)

For i = 1, 2, ..., m, the solution $x_i(t)$ is persistent in mean. Step 2. For i = m + 1, ..., n, applying Itô's formula to $\log x_i^{\theta_i}(t)$ yields

$$\frac{\log x_i(t)}{t} = \frac{\log x(0)}{t} + \frac{1}{t} \int_0^t \left(b_i(r(s)) - \frac{\sigma_i^2(r(s))}{2} \right) ds$$
$$- \frac{1}{t} \int_0^t a_{ii}(r(s)) x_i^{\theta_i}(s) ds - \frac{1}{t} \int_0^t \sum_{j=1}^m a_{ij}(r(s)) x_j(s) ds + \frac{M_i(t)}{t}$$
$$- \frac{1}{t} \int_0^t \sum_{j=m+1, j\neq i}^n a_{ij}(r(s)) x_j(s) ds \quad \text{a.s. } i = m+1, \dots, n.$$
(60)

It follows from Theorem 4.1 and (33) that

$$\lim_{t\to\infty}\frac{1}{t}\int_0^t\sum_{j=m+1,j\neq i}^na_{ij}(r(s))x_j(s)\,ds=0\quad\text{a.s.}$$

By Theorem 3.1, we obtain that $x_i(t)$ is persistent in mean, which means that $\frac{1}{t} \times \int_0^t \sum_{i=1}^m a_{ij}(r(s))x_j(s) ds$ must be bounded. Letting $t \to \infty$ on both sides of (60), we have

$$\limsup_{t \to \infty} \frac{\log x_i(t)}{t} \le \sum_{k \in S} \pi_k \left(b_i(k) - \frac{\sigma_i^2(k)}{2} \right) \quad \text{a.s.}$$
(61)

as desired.

Remark 4 Compared to the whole persistence in mean and whole extinction, there is little literature on partial persistence in mean and partial extinction. By constructing a novel Lyapunov function we derive sufficient conditions for partial persistence in mean and partial extinction, which generalize the results in [8].

6 Examples

Example 6.1 Consider a two-dimensional stochastic Gilpin-Ayala system with regime switching in random environments

$$\begin{cases} dx_1 = x_1(b_1(r(t)) - 0.6x_1^{1.5} - 0.5x_2) dt + \sigma_1(r(t))x_1 dB_1(t), \\ dx_2 = x_2(b_2(r(t)) - 0.3x_1 - x_2^{1.2}) dt + \sigma_2(r(t))x_2 dB_2(t), \end{cases}$$
(62)

where $r(t) \in \{1, 2\}$ is generated by

$$Q = \begin{pmatrix} -1 & 1\\ \frac{1}{3} & -\frac{1}{3} \end{pmatrix},$$

and $\pi = (\pi_1, \pi_2) = (0.25, 0.75)$, $b_1(1) = 0.9$, $b_1(2) = 1.2$, $b_2(1) = 1.0$, $b_2(2) = 1.4$. The initial data can be assumed to be $x_1(0) = 0.6$, $x_2(0) = 0.4$, $r_0 = 1$, and we simulate the solution with different values of $\sigma_i(k)$.

(i) $\sigma_1(1) = 0.2$, $\sigma_1(2) = 1.0$, $\sigma_2(1) = 0.2$, $\sigma_2(2) = 0.5$. We have

$$\sum_{k \in S} \pi_k \left(b_1(k) - \frac{\sigma_1^2(k)}{2} \right) = 0.7450 > 0, \qquad \sum_{k \in S} \pi_k \left(b_2(k) - \frac{\sigma_2^2(k)}{2} \right) \approx 1.2013 > 0,$$
$$\sum_{k \in S} \pi_k \left(\left(b_1(k) - \frac{\sigma_1^2(k)}{2} \right) - \frac{a_{12}}{a_{22}} \left(b_2(k) - \frac{\sigma_2^2(k)}{2} \right) \right) \approx 0.1444 > 0,$$
$$\sum_{k \in S} \pi_k \left(\left(b_2(k) - \frac{\sigma_2^2(k)}{2} \right) - \frac{a_{21}}{a_{11}} \left(b_1(k) - \frac{\sigma_1^2(k)}{2} \right) \right) \approx 0.8288 > 0.$$

System (62) is persistent in mean, and it is completely consistent by Theorem 3.1. The results are presented clearly in Figures 1 and 2. We draw the stochastic trajectories of $\frac{\log x_1(t)}{t}$ and $\frac{\log x_2(t)}{t}$ by data simulating. The figures shows that Heun's method for time step $\Delta = 2^{-5}$ on [0, 200] is superior to others.





(ii) $\sigma_1(1) = \sigma_1(2) = 2, \sigma_2(1) = \sigma_2(2) = 1.8$. Note that

$$\sum_{k \in S} \pi_k \left(b_1(k) - \frac{\sigma_1^2(k)}{2} \right) = -0.8750 < 0, \qquad \sum_{k \in S} \pi_k \left(b_2(k) - \frac{\sigma_2^2(k)}{2} \right) = -0.3200 < 0.$$

Equation (62) is exponentially extinct, and it is completely consistent by Theorem 4.1 for any initial condition $x_0 > 0$. The sample trajectories of $\frac{\log x_1(t)}{t}$ and $\frac{\log x_2(t)}{t}$ are drawn in Figures 3 and 4, and they are generated by the Heun scheme for time step $\Delta = 2^{-5}$ on [20, 200], respectively.

Example 6.2 Consider the three-dimensional stochastic Gilpin-Ayala system with Markovian switching

$$\begin{cases} dx_1 = x_1(b_1(r(t)) - 0.7x_1^{1.1} - 0.4x_2 - 0.3x_3) dt + \sigma_1(r(t))x_1 dB_1(t), \\ dx_2 = x_2(b_2(r(t)) - 0.3x_1 - x_2^{1.5} - 0.3x_3) dt + \sigma_2(r(t))x_2 dB_2(t), \\ dx_3 = x_3(b_3(r(t)) - 0.6x_1 - 0.4x_2 - x_3^{1.2}) dt + \sigma_3(r(t))x_3 dB_3(t), \end{cases}$$
(63)

where the Markovian chain r(t) and generator Q are defined in the previous example, and $b_1(1) = 1$, $b_1(2) = 1.3$, $b_2(1) = 1$, $b_2(2) = 1.5$, $b_3(1) = 1$, $b_3(2) = 0.9$, $\sigma_1(1) = 0.6$, $\sigma_2(1) = \sqrt{5}$,





 $\sigma_3(1) = 2$, $\sigma_1(2) = 0.4$, $\sigma_2(2) = \sqrt{2}$, $\sigma_3(2) = 2$. The initial data $x_1(0) = 0.4$ and $x_2(0) = 0.6$ are given. We can show that the conditions of Theorem 5.1 are met exactly. A simple computation yields

$$\sum_{k \in S} \pi_k \left(b_1(k) - \frac{\sigma_1^2(k)}{2} \right) = 1.12 > 0, \qquad \sum_{k \in S} \pi_k \left(b_2(k) - \frac{\sigma_2^2(k)}{2} \right) = 0$$
$$\sum_{k \in S} \pi_k \left(b_3(k) - \frac{\sigma_3^2(k)}{2} \right) = -1.075 < 0,$$
$$a(11) - a(21) = 0.4 > 0, \qquad a(22) - a(12) = 0.6 > 0,$$
$$\limsup_{t \to \infty} \frac{1}{t} \int_0^t x_1^{\theta_1}(s) \, ds = 1.60, \qquad \limsup_{t \to \infty} \frac{\log x_2(t)}{t} \le 0,$$
$$\limsup_{t \to \infty} \frac{\log x_3(t)}{t} \le -1.075.$$

The species 1 is persistent in mean, and species 2 and 3 are exponentially extinct by Theorem 5.1. The system is tested in detail by the Heun method in Figures 5, 6, and 7, and the data simulating results validate the correctness and effectiveness of the proposed methods.







7 Conclusions

The asymptotic behavior for stochastic competitive Gilpin-Ayala systems with regime switching has been investigated. Firstly, generalized criteria on persistence in mean are established by utilizing stochastic comparison principle and novel analysis techniques. Secondly, sufficient criteria on extinction are obtained by the space-decomposition method and the stochastic LaSalle theorem. Thirdly, sufficient conditions for partial persistence in mean and partial extinction are derived based on the criteria and a novel Lyapunov func-

tion. Two numerical examples are provided to illustrate the superiority and effectiveness of the proposed approaches.

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Competing interests

The authors declare that they have no competing interests.

Authors' contributions

The authors have made the same contribution. All authors read and approved the final manuscript.

Author details

¹College of Science, Hohai University, Nanjing, Jiangsu 210098, China. ²School of Mathematics, Southeast University, Nanjing, Jiangsu 210096, China. ³School of Mathematical Sciences and Institute of Finance and Statistics, Nanjing Normal University, Nanjing, Jiangsu 210023, China.

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