# Application of the Exp-function method for solving the combined KdV-mKdV and Gardner-KP equations 

Jalil Manafianheris ${ }^{\text {** }}$ and Mehdi Fazli Aghdaei ${ }^{2}$


#### Abstract

Purpose: In this article, we establish the exact solutions for the combined KdV-mKdV and Gardner-KP equations. Methods: The Exp-function method (EFM) is used to construct solitary and soliton solutions of nonlinear evolution equations. Results: This method is developed for searching the exact travelling wave solutions of nonlinear partial differential equations. Conclusions: It is shown that the EFM, with the help of symbolic computation, provides a straightforward and powerful mathematical tool for solving nonlinear evolution equations in mathematical physics.


Keywords: Nonlinear partial differential equation, Combined KdV-mKdV and Gardner-KP equations, Travelling wave solution

## Introduction

In the recent decade, the study of nonlinear partial differential equations in modelling physical phenomena has become an important tool. Nonlinear phenomena play a fundamental role in applied mathematics and physics. Also, the investigation of the travelling wave solutions plays an important role in nonlinear sciences. A variety of powerful methods has been presented, such as the inverse scattering transform [1], Hirota's bilinear method [2], sine-cosine method [3], homotopy perturbation method [4], homotopy analysis method [5,6], variational iteration method $[7,8]$, tanh-function method $[9,10]$, Bäcklund transformation [11], and ( $\frac{G^{\prime}}{G}$ )-expansion method [12,13]. Here we use an effective method for constructing a range of exact solutions for the following nonlinear partial differential equations which was first presented by He [14]. A new method called the Exp-function method (EFM) is presented to look for travelling wave solutions of nonlinear evolution equations. The EFM has successfully been applied to many situations. For example, He and Wu [15] have solved the nonlinear wave equations by EFM. He

[^0]and Abdou [16] have used EFM to give new periodic solutions for nonlinear evolution equations. By applying EFM, generalized solitary solution and compacton-like solution of the Jaulent-Miodek equations have been obtained by He [17]. Abdou [18] has solved the generalized solitonary and periodic solutions for nonlinear partial differential equations by EFM. Manafian and Bagheri [19] have applied EFM for the modified KdV and the generalized KdV equations. Authors of [20] have studied the periodic solutions and compacton-like solutions using EFM. The EFM has been applied to nonlinear equations by Wu and He [21]. Zhu [22] also examined the hybrid-lattice system by using EFM. The EFM has recently been used by Zhang [23] in the high-dimensional nonlinear evolution equation. The positive and negative models of the Gardner equation [24,25], or the combined KdV-mKdV equations, are given by
\[

$$
\begin{equation*}
u_{t}+6 u u_{x} \pm 6 u^{2} u_{x}+u_{x x x}=0 \tag{1.1}
\end{equation*}
$$

\]

which describe internal solitary waves in shallow seas. Those two models will be classified as positive Gardner equation and negative Gardner equation depending on the sign of the cubic nonlinear term. The Gardner equation (Equation 1.1), like the KdV and the mKdV
equation, is completely integrable with a Lax pair and inverse scattering transform [26]. Kadomtsov and Petviashivilli extended the KdV equation to obtain the Kadomtsov-Petviashivilli (KP) equation

$$
\begin{equation*}
\left(u_{t}+6 u u_{x}+u_{x x x}\right)_{x}+u_{y y}=0 \tag{1.2}
\end{equation*}
$$

Kadomtsov and Petviashivilli relaxed the restriction that the waves be strictly one-dimensional [26], namely, the $x$ direction of the $K d V$ equation, to derive the completely integrable KP in Equation 1.2. In this article, we used EFM to investigate the Gardner-KP (GKP) equations [26] given by

$$
\begin{equation*}
\left(u_{t}+6 u u_{x} \pm 6 u^{2} u_{x}+u_{x x x}\right)_{x}+u_{y y}=0 \tag{1.3}
\end{equation*}
$$

that will be shown to be completely integrable. We want to obtain the analytical solutions of nonlinear combined KdV-mKdV and GKP equations and to determine the accuracy of the EFM in solving these kinds of problems. The article is organized as follows: in the section 'Basic idea of Exp-function method', first we briefly give the steps of the method and apply the method to solve nonlinear partial differential equations; in sections 'The combined KdV-mKdV equations' and 'The Gardner-KP equations', we examine the combined $K d V-m K d V$ equations and the GKP equations, respectively; and a conclusion is given in the 'Conclusions' section.

## Methods

## Basic idea of Exp-function method

We first consider the nonlinear equation of the form

$$
\begin{equation*}
\mathcal{N}\left(u, u_{t}, u_{x}, u_{x x}, u_{y y}, u_{t t}, u_{t x}, u_{t y}, \ldots\right)=0 \tag{2.1}
\end{equation*}
$$

and introduce the transformation

$$
\begin{equation*}
u(x, y, t)=u(\eta), \eta=x+y-c t \tag{2.2}
\end{equation*}
$$

where $c$ is constant to be determined later. Therefore Equation 2.1 is reduced to an ordinary differential equation (ODE) as

$$
\begin{equation*}
\mathcal{M}\left(u,-c u^{\prime}, u^{\prime}, u^{\prime \prime}, u^{\prime \prime}, \ldots\right)=0 \tag{2.3}
\end{equation*}
$$

EFM is based on the assumption that the travelling wave solutions in [15] can be expressed in the form

$$
\begin{equation*}
u(\eta)=\frac{\sum_{n=-c}^{d} a_{n} \exp (n \eta)}{\sum_{m=-p}^{q} b_{m} \exp (m \eta)} \tag{2.4}
\end{equation*}
$$

where $c, d, p$, and $q$ are positive integers which could be freely chosen, $a_{n}$ and $b_{m}$ are unknown constants to be determined. To determine the values of $c$ and $p$, we balance the linear term of highest order in Equation 2.3 with the highest-order nonlinear term. Also, to determine the values of $d$ and $q$, we balance the linear term of lowest order in Equation 2.3 with the lowest-order nonlinear term.

## The combined KdV-mKdV equations

In this section, we employ the Exp-function method to the combined KdV-mKdV equation

$$
\begin{equation*}
u_{t}+6 u u_{x} \pm 6 u^{2} u_{x}+u_{x x x}=0 \tag{3.1}
\end{equation*}
$$

and we use the transformation $u=v \mp \frac{1}{2}$ to convert the model 3.1 into the modified KdV equations as

$$
\begin{equation*}
v_{t} \mp \frac{3}{2} v_{x} \pm 6 v^{2} v_{x}+v_{x x x}=0 \tag{3.2}
\end{equation*}
$$

This shows that the Gardner equation, like the modified KdV equation, is completely integrable. The Gardner equation was first derived rigorously within the asymptotic theory for long internal waves in a two-layer fluid with a density jump at the interface. The competition among dispersion, quadratic, and cubic nonlinearities constitutes the main interest of this equation [26]. The Gardner equation has been investigated in the literature because it is used to model a variety of nonlinear phenomena.

## Case 1: positive Gardner equation

We use the equation

$$
\begin{equation*}
u_{t}+6 u u_{x}+6 u^{2} u_{x}+u_{x x x}=0 \tag{3.3}
\end{equation*}
$$

and we use transformation

$$
\begin{equation*}
u=v-\frac{1}{2} \tag{3.4}
\end{equation*}
$$

to convert the model 3.3 into the modified KdV equation of

$$
\begin{equation*}
v_{t}-\frac{3}{2} v_{x}+6 v^{2} v_{x}+v_{x x x}=0 \tag{3.5}
\end{equation*}
$$

and by using the wave variable $\eta=x-c t$ reduces it to an ODE

$$
\begin{equation*}
-\left(c+\frac{3}{2}\right) v+2 v^{3}+v^{\prime \prime}=0 \tag{3.6}
\end{equation*}
$$

in which Equation 3.6 is obtained by integrating and neglecting the constant of integration. In order to the determine values of $c$ and $p$, we balance the linear term of the highest order $v^{\prime \prime}$ with the highest order nonlinear term $v^{3}$ in Equation 3.6 to get

$$
\begin{equation*}
v^{\prime \prime}=\frac{c_{1} \exp ((c+3 p) \eta)+\ldots}{c_{2} \exp (4 p \eta)+\ldots} \tag{3.7}
\end{equation*}
$$

and

$$
\begin{equation*}
v^{3}=\frac{c_{3} \exp (3 c \eta)+\ldots}{c_{4} \exp (3 p \eta)+\ldots}=\frac{c_{3} \exp ((3 c+p) \eta)+\ldots}{c_{4} \exp (4 p \eta)+\ldots} \tag{3.8}
\end{equation*}
$$

respectively. Balancing the highest order of the Expfunction in 3.7 and 3.8 and getting $c+3 p=3 c+p$ lead to the result of $c=p$. Similarly, to determine the values of
$d$ and $q$ for the terms $v^{\prime \prime}$ and $v^{3}$ in Equation 3.6 by simple calculation, we obtain

$$
\begin{equation*}
v^{\prime \prime}=\frac{\ldots+d_{1} \exp (-(d+3 q) \eta)}{\ldots+d_{2} \exp (-4 q \eta)} \tag{3.9}
\end{equation*}
$$

and

$$
\begin{equation*}
v^{3}=\frac{\ldots+d_{3} \exp (-3 d \eta)}{\ldots+d_{4} \exp (-3 q \eta)}=\frac{\ldots+d_{3} \exp (-(3 d+q) \eta)}{\ldots+d_{4} \exp (-4 q \eta)} \tag{3.10}
\end{equation*}
$$

respectively. By balancing the highest order of EFM in 3.9 and 3.10 gives us $-(d+3 q)=-(3 d+q)$, which leads to the result $d=q$. For simplicity, we set $p=c=1$ and $d=q=1$. Then Equation 2.4 reduces to

$$
\begin{equation*}
v(\eta)=\frac{a_{1} \exp (\eta)+a_{0}+a_{-1} \exp (-\eta)}{b_{1} \exp (\eta)+b_{0}+b_{-1} \exp (-\eta)} \tag{3.11}
\end{equation*}
$$

By substituting Equation 3.11 into Equation 3.6 and by using the well-known Maple software, we will have

$$
\begin{align*}
\frac{1}{A}\left[C_{3} \exp (3 \eta)\right. & +C_{2} \exp (2 \eta)+C_{1} \exp (\eta)+C_{0}+C_{-1} \exp (-\eta) \\
& \left.+C_{-2} \exp (-2 \eta)+C_{-3} \exp (-3 \eta)\right]=0 \tag{3.12}
\end{align*}
$$

where

$$
\begin{equation*}
A=\left[b_{-1} \exp (-\eta)+b_{0}+b_{1} \exp (\eta)\right]^{3} \tag{3.13}
\end{equation*}
$$

and $C_{n} s$ are coefficients of $\exp (n \eta)$ s. By equating the coefficients of $\exp (n \eta)$ to zero, we obtain the following set of algebraic equations for $a_{1}, a_{0}, a_{-1}, b_{1}, b_{0}, b_{-1}$, and $c$, as

$$
\left\{\begin{array}{l}
C_{3}=0, C_{2}=0, C_{1}=0  \tag{3.14}\\
C_{0}=0 \\
C_{-3}=0, C_{-2}=0, C_{-1}=0
\end{array}\right.
$$

Solving this system of algebraic equations with the help of Maple gives the following sets of non-trivial solutions:
(I) The first set is

$$
\begin{align*}
& a_{1}=0, a_{-1}=0, a_{0}=a_{0}, b_{0}=0, b_{-1}=b_{-1} \\
& b_{1}=\frac{a_{0}^{2}}{4 b_{-1}}, c=-\frac{1}{2}  \tag{3.15}\\
& v_{1}(x, t)=\frac{a_{0}}{b_{-1} \exp \left(-x-\frac{1}{2} t\right)+\frac{a_{0}^{2}}{4 b_{-1}} \exp \left(x+\frac{1}{2} t\right)} \tag{3.16}
\end{align*}
$$

If we choose $a_{0}=2 b_{-1}$, then by using 3.4 , we would get

$$
\begin{align*}
& v_{1,1}(x, t)=\operatorname{sech}\left(x+\frac{1}{2} t\right) \\
& u_{1,1}(x, t)=-\frac{1}{2}+\operatorname{sech}\left(x+\frac{1}{2} t\right) \tag{3.17}
\end{align*}
$$

(II) The second set is

$$
\begin{align*}
& a_{-1}= \pm \frac{1}{2} i b_{-1}, a_{1}=0, a_{0}=a_{0}, b_{0}= \pm 2 i a_{0} \\
& b_{-1}=b_{-1}, b_{1}=0, c=-2 \tag{3.18}
\end{align*}
$$

$$
\begin{equation*}
v_{2}(x, t)= \pm \frac{i}{2} \frac{b_{-1} \exp (-x-2 t) \mp 2 i a_{0}}{b_{-1} \exp (-x-2 t) \pm 2 i a_{0}} \tag{3.19}
\end{equation*}
$$

If we choose $b_{-1}=2 i a_{0}$, then by using 3.4, we would get

$$
\begin{align*}
& v_{2,1}(x, t)=-\frac{i}{2} \tanh \left(\frac{x+2 t}{2}\right),  \tag{3.20}\\
& v_{2,2}(x, t)=\frac{i}{2} \operatorname{coth}\left(\frac{x+2 t}{2}\right), \\
& u_{2,1}(x, t)=-\frac{1}{2}-\frac{i}{2} \tanh \left(\frac{x+2 t}{2}\right), \\
& u_{2,2}(x, t)=-\frac{1}{2}+\frac{i}{2} \operatorname{coth}\left(\frac{x+2 t}{2}\right) . \tag{3.21}
\end{align*}
$$

(III) The third set is
$a_{1}= \pm i b_{1}, a_{-1}=a_{-1}, a_{0}=0, b_{0}=0, b_{-1}= \pm i a_{-1}$,
$b_{1}=b_{1}, c=-\frac{7}{2}$,

$$
\begin{equation*}
v_{3}(x, t)= \pm i \frac{b_{1} \exp (x-c t) \mp i a_{-1}}{b_{1} \exp (x-c t) \pm i a_{-1}} . \tag{3.23}
\end{equation*}
$$

If we choose $b_{1}=i a_{-1}$, then by using 3.4 , we would get

$$
\begin{align*}
& v_{3,1}(x, t)=i \tanh \left(x+\frac{7}{2} t\right)  \tag{3.24}\\
& v_{3,2}(x, t)=-i \operatorname{coth}\left(x+\frac{7}{2} t\right) \\
& u_{3,1}(x, t)=-\frac{1}{2}+i \tanh \left(x+\frac{7}{2} t\right), \\
& u_{3,2}(x, t)=-\frac{1}{2}-i \operatorname{coth}\left(x+\frac{7}{2} t\right) . \tag{3.25}
\end{align*}
$$

(IV) The forth set is

$$
\begin{aligned}
a_{1} & =\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}}, a_{-1}=a_{-1}, a_{0}=a_{0}, \\
b_{0} & =b_{0}, b_{-1}= \pm 2 i a_{-1}, c=-2, \\
b_{1} & =\mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i, \\
v_{5}(x, t) & =\frac{a_{-1} \exp (-x+c t)+a_{0}+\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} \exp (x-c t)}{ \pm 2 i a_{-1} \exp (-x+c t)+b_{0} \mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i \exp (x-c t)} .
\end{aligned}
$$

Notice that if $u(x, t)=v(x, t)-\frac{1}{2}$, we would have

$$
\begin{align*}
u_{5}(x, t)= & -\frac{1}{2} \\
& +\frac{a_{-1} \exp (-x-2 t)+a_{0}+\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} \exp (x+2 t)}{ \pm 2 i a_{-1} \exp (-x-2 t)+b_{0} \mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i \exp (x+2 t)} . \tag{3.27}
\end{align*}
$$

## Case 2: negative Gardner equation

Let

$$
\begin{equation*}
u_{t}+6 u u_{x}-6 u^{2} u_{x}+u_{x x x}=0 \tag{3.28}
\end{equation*}
$$

and use the transformation

$$
\begin{equation*}
u=v+\frac{1}{2} \tag{3.29}
\end{equation*}
$$

which converts the model 3.28 into the modified KdV equation

$$
\begin{equation*}
v_{t}+\frac{3}{2} v_{x}-6 v^{2} v_{x}+v_{x x x}=0 \tag{3.30}
\end{equation*}
$$

and by using the wave variable $\eta=x-c t$ reduces it to an ODE

$$
\begin{equation*}
-\left(c-\frac{3}{2}\right) v-2 v^{3}+v^{\prime \prime}=0 \tag{3.31}
\end{equation*}
$$

in which Equation 3.31 is obtained by integrating and neglecting the constant term of integration. By manipulating the above procedure, we get the following sets.
(I) The first set is

$$
\begin{aligned}
& a_{1}=0, a_{-1}=a_{-1}, a_{0}=a_{0}, b_{0}=2 a_{0}, b_{-1}=-2 a_{-1}, \\
& b_{1}=0, c=1
\end{aligned}
$$

$$
\begin{equation*}
v_{1}(x, t)=\frac{a_{-1} \exp (-x+t)+a_{0}}{-2 a_{-1} \exp (-x+t)+2 a_{0}} . \tag{3.33}
\end{equation*}
$$

If we choose $a_{0}=a_{-1}$, then by using 3.29 , we would get

$$
\begin{align*}
& v_{1,1}(x, t)=\frac{1}{2} \operatorname{coth}\left(\frac{x-t}{2}\right), \\
& u_{1,1}(x, t)=\frac{1}{2}+\frac{1}{2} \operatorname{coth}\left(\frac{x-t}{2}\right) . \tag{3.34}
\end{align*}
$$

(II) The second set is

$$
\begin{align*}
& a_{-1}=0, a_{1}=0, a_{0}=a_{0}, b_{0}=0, b_{-1}=b_{-1}, \\
& b_{1}=-\frac{1}{4} \frac{a_{0}^{2}}{b_{-1}}, c=\frac{5}{2} \tag{3.35}
\end{align*}
$$

$$
\begin{equation*}
v_{2}(x, t)=\frac{a_{0}}{b_{-1} \exp \left(-x+\frac{5}{2} t\right)-\frac{1}{4} \frac{a_{0}^{2}}{b_{-1}} \exp \left(x-\frac{5}{2} t\right)} \tag{3.36}
\end{equation*}
$$

If we choose $2 b_{-1}=a_{0}$, then by using 3.29 , we would get

$$
\begin{align*}
& v_{2,1}(x, t)=-\operatorname{csch}\left(x-\frac{5}{2} t\right)  \tag{3.37}\\
& u_{2,1}(x, t)=\frac{1}{2}-\operatorname{csch}\left(x-\frac{5}{2} t\right)
\end{align*}
$$

(III) The third set is

$$
\begin{align*}
& a_{-1}=-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}}, a_{1}=a_{1}, a_{0}=a_{0}, b_{0}=b_{0} \\
& b_{-1}=\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \tag{3.38}
\end{align*}
$$

$$
b_{1}=\mp 2 a_{1}, c=1 \text {, }
$$

$$
v_{3}(x, t)=\frac{-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x+t)+a_{0}+a_{1} \exp (x-t)}{\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x+t)+b_{0} \mp 2 a_{1} \exp (x-t)} .
$$

Notice that if $u(x, t)=v(x, t)+\frac{1}{2}$, we would obtain
$u_{3}(x, t)=\frac{1}{2}+\frac{-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x+t)+a_{0}+a_{1} \exp (x-t)}{\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x+t)+b_{0} \mp 2 a_{1} \exp (x-t)}$.
(IV) The fourth set is
$a_{1}=a_{1}, a_{-1}=a_{-1}, a_{0}=0, b_{0}=0, b_{-1}=a_{-1}, c=-\frac{1}{2}$,
$b_{1}=-a_{1}, v_{4}(x, t)=\frac{a_{-1} \exp \left(-x-\frac{1}{2} t\right)+a_{1} \exp \left(x+\frac{1}{2} t\right)}{a_{-1} \exp \left(-x-\frac{1}{2} t\right)-a_{1} \exp \left(x+\frac{1}{2} t\right)}$.

If we choose $a_{-1}=a_{1}$, then by using 3.29 , we would get

$$
\begin{align*}
& v_{4}(x, t)=-\operatorname{coth}\left(x+\frac{1}{2} t\right)  \tag{3.41}\\
& u_{4}(x, t)=\frac{1}{2}-\operatorname{coth}\left(x+\frac{1}{2} t\right)
\end{align*}
$$

which are the exact solutions of the combined KdV-mKdV equation. We obtain solitary wave and complex wave solutions for the combined $K d V-m K d V$ equation. It can be seen that the results are the same as the results in [26].

## Results and discussion

## The Gardner-KP equations

In this section, we study the Gardner-KP equations with EFM as

$$
\begin{equation*}
\left(u_{t}+6 u u_{x} \pm 6 u^{2} u_{x}+u_{x x x}\right)_{x}+u_{y y}=0 \tag{4.1}
\end{equation*}
$$

and we use transformation $u=v \mp \frac{1}{2}$ to convert the model 4.1 into the Gardner-KP equation

$$
\begin{equation*}
\left(v_{t} \mp \frac{3}{2} v_{x} \pm 6 v^{2} v_{x}+v_{x x x}\right)_{x}+v_{y y}=0 . \tag{4.2}
\end{equation*}
$$

This shows that the positive GKP equation is completely integrable like the modified KdV equation.

## Case 1:positive Gardner-KP equation

Consider

$$
\begin{equation*}
\left(u_{t}+6 u u_{x}+6 u^{2} u_{x}+u_{x x x}\right)_{x}+u_{y y}=0 \tag{4.3}
\end{equation*}
$$

and we use the transformation

$$
\begin{equation*}
u=v-\frac{1}{2} \tag{4.4}
\end{equation*}
$$

to reduce to the model 4.3 into the Gardner-KP equation as

$$
\begin{equation*}
\left(v_{t}-\frac{3}{2} v_{x}+6 v^{2} v_{x}+v_{x x x}\right)_{x}+v_{y y}=0 \tag{4.5}
\end{equation*}
$$

and by using the wave variable $\eta=x+y-c t$ reduces it to an ODE of

$$
\begin{equation*}
-\left(c+\frac{1}{2}\right) v+2 v^{3}+v^{\prime \prime}=0 \tag{4.6}
\end{equation*}
$$

in which Equation 4.6 is obtained by integrating and neglecting the constant term of integration. In order to the determine values of $c$ and $p$, we balance $v^{\prime \prime}$ with $v^{3}$ in Equation 4.6 to get

$$
\begin{equation*}
v^{\prime \prime}=\frac{c_{1} \exp ((c+3 p) \eta)+\ldots}{c_{2} \exp (4 p \eta)+\ldots} \tag{4.7}
\end{equation*}
$$

and

$$
\begin{equation*}
v^{3}=\frac{c_{3} \exp (3 c \eta)+\ldots}{c_{4} \exp (3 p \eta)+\ldots}=\frac{c_{3} \exp ((3 c+p) \eta)+\ldots}{c_{4} \exp (4 p \eta)+\ldots} \tag{4.8}
\end{equation*}
$$

respectively. By balancing the highest order of EFM in 4.7 and 4.8 , we will have $c+3 p=3 c+p$ which leads to the result $c=p$. Similarly, to determine values of $d$ and $q$ for the terms $v^{\prime \prime}$ and $v^{3}$ in Equation 4.6, by simple calculation we obtain

$$
\begin{equation*}
v^{\prime \prime}=\frac{\ldots+d_{1} \exp (-(d+3 q) \eta)}{\ldots+d_{2} \exp (-4 q \eta)} \tag{4.9}
\end{equation*}
$$

and

$$
\begin{equation*}
v^{3}=\frac{\ldots+d_{3} \exp (-3 d \eta)}{\ldots+d_{4} \exp (-3 q \eta)}=\frac{\ldots+d_{3} \exp (-(3 d+q) \eta)}{\ldots+d_{4} \exp (-4 q \eta)} \tag{4.10}
\end{equation*}
$$

respectively. By balancing the highest order of EFM in 4.9 and 4.10 , we have $-(d+3 q)=-(3 d+q)$ which leads to the result $d=q$. Moreover, by substituting Equation 3.11 into Equation 4.6, using the well-known Maple software, and applying the same manipulation as illustrated above, we have the following set of solutions.
(I) The first set is

$$
\begin{align*}
& a_{1}=0, a_{-1}=0, a_{0}=a_{0}, b_{0}=0, b_{-1}=b_{-1}, \\
& b_{1}=\frac{a_{0}^{2}}{4 b_{-1}}, c=\frac{1}{2}, \tag{4.11}
\end{align*}
$$

$$
\begin{equation*}
v_{1}(x, y, t)=\frac{a_{0}}{b_{-1} \exp \left(-x-y+\frac{1}{2} t\right)+\frac{a_{0}^{2}}{4 b_{-1}} \exp \left(x+y-\frac{1}{2} t\right)} . \tag{4.12}
\end{equation*}
$$

If we choose $a_{0}=2 b_{-1}$, then by using 4.4 , we would get

$$
\begin{align*}
& v_{1,1}(x, y, t)=\operatorname{sech}\left(x+y-\frac{1}{2} t\right) \\
& u_{1,1}(x, y, t)=-\frac{1}{2}+\operatorname{sech}\left(x+y-\frac{1}{2} t\right) \tag{4.13}
\end{align*}
$$

(II) The second set is

$$
\begin{align*}
& a_{-1}= \pm \frac{1}{2} i b_{-1}, a_{1}=0, a_{0}=a_{0}, b_{0}= \pm 2 i a_{0} \\
& b_{-1}=b_{-1}, b_{1}=0, c=-1 \tag{4.14}
\end{align*}
$$

$$
\begin{equation*}
v_{2}(x, y, t)= \pm \frac{i}{2} \frac{b_{-1} \exp (-x-y-t) \mp 2 i a_{0}}{b_{-1} \exp (-x-y-t) \pm 2 i a_{0}} \tag{4.15}
\end{equation*}
$$

If we choose $b_{-1}=2 i a_{0}$, then by using 4.4, we would get

$$
\begin{align*}
& v_{2,1}(x, y, t)=-\frac{i}{2} \tanh \left(\frac{x+y+t}{2}\right) \\
& u_{2,1}(x, y, t)=-\frac{1}{2}-\frac{i}{2} \tanh \left(\frac{x+y+t}{2}\right),  \tag{4.16}\\
& v_{2,2}(x, y, t)=\frac{i}{2} \operatorname{coth}\left(\frac{x+y+t}{2}\right), \\
& u_{2,2}(x, y, t)=-\frac{1}{2}+\frac{i}{2} \operatorname{coth}\left(\frac{x+y+t}{2}\right) . \tag{4.17}
\end{align*}
$$

(III) The third set is

$$
\begin{gather*}
a_{1}= \pm i b_{1}, a_{-1}=a_{-1}, a_{0}=0, b_{0}=0 \\
b_{-1}= \pm i a_{-1}, b_{1}=b_{1}, c=-\frac{5}{2}  \tag{4.18}\\
v_{3}(x, y, t)= \pm i \frac{b_{1} \exp (x+y-c t) \mp i a_{-1}}{b_{1} \exp (x+y-c t) \pm i a_{-1}} \tag{4.19}
\end{gather*}
$$

If we choose $b_{1}=i a_{-1}$, then by using 4.4 , we would get

$$
\begin{align*}
& v_{3,1}(x, y, t)=i \tanh \left(x+y+\frac{5}{2} t\right), \\
& u_{3,1}(x, y, t)=-\frac{1}{2}+i \tanh \left(x+y+\frac{5}{2} t\right), \tag{4.20}
\end{align*}
$$

$$
\begin{align*}
& v_{3,2}(x, y, t)=-i \operatorname{coth}\left(x+y+\frac{5}{2} t\right) \\
& u_{3,2}(x, y, t)=-\frac{1}{2}-i \operatorname{coth}\left(x+y+\frac{5}{2} t\right) . \tag{4.21}
\end{align*}
$$

(IV) The fourth set is

$$
\begin{align*}
a_{1} & =\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}}, a_{-1}=a_{-1}, a_{0}=a_{0}, b_{0}=b_{0} \\
b_{-1} & = \pm 2 i a_{-1}, c=-1 \tag{4.22}
\end{align*}
$$

$$
b_{1}=\mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i
$$

$v_{4}(x, y, t)$

$$
=\frac{a_{-1} \exp (-x-y-t)+a_{0}+\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} \exp (x+y+t)}{ \pm 2 i a_{-1} \exp (-x-y-t)+b_{0} \mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i \exp (x+y+t)} .
$$

Notice that $u(x, y, t)=v(x, y, t)-\frac{1}{2}$, we would have

$$
\begin{align*}
& u_{4}(x, y, t)=-\frac{1}{2} \\
& \quad+\frac{a_{-1} \exp (-x-y-t)+a_{0}+\frac{1}{16} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} \exp (x+y+t)}{ \pm 2 i a_{-1} \exp (-x-y-t)+b_{0} \mp \frac{1}{8} \frac{b_{0}^{2}+4 a_{0}^{2}}{a_{-1}} i \exp (x+y+t)} . \tag{4.23}
\end{align*}
$$

## Case 2: negative Gardner-KP equation

Consider

$$
\begin{equation*}
\left(u_{t}+6 u u_{x}-6 u^{2} u_{x}+u_{x x x}\right)_{x}+u_{y y}=0 \tag{4.24}
\end{equation*}
$$

and we use transformation

$$
\begin{equation*}
u=v+\frac{1}{2} \tag{4.25}
\end{equation*}
$$

to convert the model 4.24 into the Gardner-KP equation

$$
\begin{equation*}
\left(v_{t}+\frac{3}{2} v_{x}-6 v^{2} v_{x}+v_{x x x}\right)_{x}+v_{y y}=0 \tag{4.26}
\end{equation*}
$$

and by using the wave variable $\eta=x+y-c t$ reduces it to an ODE

$$
\begin{equation*}
-\left(c-\frac{5}{2}\right) v-2 v^{3}+v^{\prime \prime}=0 \tag{4.27}
\end{equation*}
$$

in which Equation 4.27 is obtained by integrating and neglecting the constant of integration. By manipulating above procedure we get the following sets.
(I) The first set is

$$
\begin{align*}
& a_{1}=0, a_{-1}=a_{-1}, a_{0}=a_{0}, b_{0}=2 a_{0}, b_{-1}=-2 a_{-1}, \\
& b_{1}=0, c=2, \tag{4.28}
\end{align*}
$$

$$
\begin{equation*}
v_{1}(x, y, t)=\frac{a_{-1} \exp (-x-y+c t)+a_{0}}{-2 a_{-1} \exp (-x-y+c t)+2 a_{0}} \tag{4.29}
\end{equation*}
$$

If we choose $a_{0}=a_{-1}$, then by using Equation 4.25, we would get

$$
\begin{align*}
& v_{1,1}(x, y, t)=\frac{1}{2} \operatorname{coth}\left(\frac{x+y-2 t}{2}\right), \\
& u_{1,1}(x, y, t)=\frac{1}{2}+\frac{1}{2} \operatorname{coth}\left(\frac{x+y-2 t}{2}\right) . \tag{4.30}
\end{align*}
$$

(II) The second set is

$$
\begin{align*}
a_{-1} & =0, a_{1}=0, a_{0}=a_{0}, b_{0}=0, \\
b_{-1} & =b_{-1}, b_{1}=-\frac{1}{4} \frac{a_{0}^{2}}{b_{-1}}, c=\frac{7}{2},  \tag{4.31}\\
v_{2}(x, y, t) & =\frac{a_{0}}{b_{-1} \exp (-x-y+c t)-\frac{1}{4} \frac{a_{0}^{2}}{b_{-1}} \exp (x+y-c t)} . \tag{4.32}
\end{align*}
$$

If we choose $2 b_{-1}=a_{0}$, then by using Equation 4.25, we would get

$$
\begin{align*}
& v_{2,1}(x, y, t)=-\operatorname{csch}\left(x+y-\frac{7}{2} t\right) \\
& u_{2,1}(x, y, t)=\frac{1}{2}-\operatorname{csch}\left(x+y-\frac{7}{2} t\right) . \tag{4.33}
\end{align*}
$$

(III) The third set is

$$
\begin{align*}
& a_{-1}=-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}}, a_{1}=a_{1}, a_{0}=a_{0}, b_{0}=b_{0} \\
& b_{-1}=\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \tag{4.34}
\end{align*}
$$

$$
b_{1}=\mp 2 a_{1}, c=2,
$$

$$
v_{3}(x, y, t)
$$

$$
\begin{equation*}
=\frac{-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x-y+2 t)+a_{0}+a_{1} \exp (x+y-2 t)}{\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x-y+2 t)+b_{0} \mp 2 a_{1} \exp (x+y-2 t)} . \tag{4.35}
\end{equation*}
$$

Notice that in $u(x, y, t)=v(x, y, t)+\frac{1}{2}$, we would obtain

$$
\begin{align*}
& u_{3}(x, y, t)=\frac{1}{2} \\
& \quad+\frac{-\frac{1}{16} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x-y+2 t)+a_{0}+a_{1} \exp (x+y-2 t)}{\mp \frac{1}{8} \frac{b_{0}^{2}-4 a_{0}}{a_{1}} \exp (-x-y+2 t)+b_{0} \mp 2 a_{1} \exp (x+y-2 t)} . \tag{4.36}
\end{align*}
$$

(IV) The fourth set is

$$
\begin{align*}
& a_{1}=a_{1}, a_{-1}=a_{-1}, a_{0}=0, b_{0}=0, b_{-1}=a_{-1}, c=\frac{1}{2} \\
& b_{1}=-a_{1} \tag{4.37}
\end{align*}
$$

$$
\begin{equation*}
v_{4}(x, y, t)=\frac{a_{-1} \exp (-x-y+c t)+a_{1} \exp (x+y-c t)}{a_{-1} \exp (-x-y+c t)-a_{1} \exp (x+y-c t)} . \tag{4.38}
\end{equation*}
$$

If we choose $a_{-1}=a_{1}$, then by using Equation 4.25, we would get

$$
\begin{align*}
& v_{4}(x, y, t)=-\operatorname{coth}\left(x+y-\frac{1}{2} t\right) \\
& u_{4}(x, y, t)=\frac{1}{2}-\operatorname{coth}\left(x+y-\frac{1}{2} t\right), \tag{4.39}
\end{align*}
$$

which are the exact solutions of the Gardner-KP equation. We obtain solitary wave and complex wave solutions for the combined $K d V-m K d V$ equation. It
can be seen that the results are the same when compared to the results in [26].

## Conclusions

In this article, we obtained the exact solutions for the combined KdV-mKdV and Gardner-KP equations by Expfunction method. EFM is a useful method for finding travelling wave solutions of nonlinear evolution equations. This method has been successfully applied to obtain some new solitary wave solutions to the combined KdV-mKdV and Gardner-KP equations. Some of these results are in agreement with the results reported in the literature. Also, new results are formally developed in this article considerably. It can be concluded that this method is a very powerful and efficient technique to find the exact solutions for a large class of problems.

## Competing interests

The authors declare that they have no competing interests.

## Authors' contributions

The authors, JMH and MFA, have equal contributions to each part of this article. Both authors read and approved the final manuscript.

## Acknowledgements

The authors would like to thank the referees for their valuable suggestions and comments.

## Author details

${ }^{1}$ Mathematics Department, Islamic Azad University-Ahar Branch, Ahar, Iran
${ }^{2}$ Department of Mathematics, Payame Noor University, P.O. Box 19395-3697 Tehran 51746, Islamic Republic of Iran.

Received: 31 May 2012 Accepted: 21 July 2012
Published: 22 November 2012

## References

1. Ablowitz, MJ, Clarkson, PA: Solitons, Nonlinear Evolution Equations and Inverse Scattering. Cambridge University, Cambridge (1991)
2. Hirota, R: The Direct Method in Soliton Theory (in English). Cambridge University, Cambridge (2004)
3. Yusufoğlu, E, Bekir, A, Alp, M: Periodic and solitary wave solutions of Kawahara and modified Kawahara equations by using sine-cosine method. Chaos Soliton. Fract. 37, 1193-1197 (2008)
4. Dehghan, $M$, Manafian, $J$ : The solution of the variable coefficients fourth-order parabolic partial differential equations by homotopy perturbation method. Z. Naturforsch. 64a, 420-430 (2009)
5. Dehghan, M, Manafian, J, Saadatmandi, A: The solution of the linear fractional partial differential equations using the homotopy analysis method. Z. Naturforsch. 65a, 935-949 (2010)
6. Dehghan, M, Manafian, J, Saadatmandi, A: Solving nonlinear fractional partial differential equations using the homotopy analysis method. Num. Meth. Part. Diff. Eq. J. 26, 448-479 (2010)
7. He, JH: Variational iteration method - a kind of non-linear analytical technique: some examples. Int. J. Nonlinear Mech. 34, 699-708 (1999)
8. Dehghan, M, Manafian, J, Saadatmandi, A: Application of semi-analytic methods for the Fitzhugh-Nagumo equation, which models the transmission of nerve impulses. Math. Meth. Appl. Sci. 33, 1384-1398 (2010)
9. Fan, E: Extended tanh-function method and its applications to nonlinear equations. Phys. Lett. A. 277, 212-218 (2000)
10. Bai, CL, Zhao, H: Generalized extended tanh-function method and its application. Chaos Soliton. Fract. 27, 1026-1035 (2006)
11. Menga, XH, Liua, WJ, Zhua, HW, Zhang, CY, Tian, B: Multi-soliton solutions and a Bäcklund transformation for a generalized variable-coefficient
higher-order nonlinear Schrödinger equation with symbolic computation. Phys. A. 387, 97-107 (2008)
12. Wang, M, Li, X, Zhang, J: The $\left(\frac{G I}{G}\right)$-expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics. Phys. Lett. A. 372, 417-423 (2008)
13. Zhang, J, Wei, X, Lu, Y: A generalized $\left(\frac{G}{G}\right)$-expansion method and its applications evolution equations in mathematical physics. Phys. Lett. A. 372, 3653-3658 (2008)
14. He, JH: Non-perturbative method for strongly nonlinear problems. Dissertation, de Berlin (2006)
15. $\mathrm{He}, \mathrm{JH}, \mathrm{Wu}, \mathrm{XH}$ : Exp-function method for nonlinear wave equations. Chaos Soliton. Fract. 30, 700-708 (2006)
16. He, JH, Abdou, MA: New periodic solutions for nonlinear evolution equations using Exp-function method. Chaos Soliton. Fract. 34, 1421-1429 (2007)
17. He, JH, Zhang, LN: Generalized solitary solution and compacton-like solution of the Jaulent-Miodek equations using the Exp-function method. Phys. Lett. A. 372, 1044-1047 (2008)
18. Abdou, MA: Generalized solitonary and periodic solutions for nonlinear partial differential equations by the Exp-function method. Nonlinear Dyn. 52, 1-9 (2008)
19. Manafian Heris, J, Bagheri, M: Exact solutions for the modified KdV and the generalized KdV equations via Exp-function method. J. Math. Ext. 4, 75-95 (2010)
20. $\mathrm{Wu}, \mathrm{XH}, \mathrm{He}, \mathrm{JH}$ : Solitary solutions, periodic solutions and compacton-like solutions using the Exp-function method. Comput. Math. Appl. 54, 966-986 (2007)
21. Wu, XH, He, JH: Exp-function method and its application to nonlinear equations. Chaos Soliton. Fract. 38, 903-910 (2008)
22. Zhu, SD: Exp-function method for the hybrid-lattice system. Int. J. Nonlinear Sci. Numer. Solut. 8, 461-464 (2007)
23. Zhang, S: Application of Exp-function method to high-dimensional nonlinear evolution equation. Chaos Soliton. Fract. 38, 270-276 (2008)
24. Gardner, C, Greene, J, Kruskal, M, Miura, R: Method for solving the Korteweg-de Vries equation. Phys. Rev. Lett. 19, 1095-1097 (1967)
25. Wazwaz, AM: New solitons and kink solutions for the Gardner equation. Commun. Nonlinear Sci. Numer. Simul. 12, 1395-1404 (2007)
26. Wazwaz, AM: Solitons and singular solitons for the Gardner-KP equation. Appl. Math. Comput. 204, 162-169 (2008)

## doi:10.1186/2251-7456-6-68

Cite this article as: Manafianheris and Aghdaei: Application of the Expfunction method for solving the combined KdV-mKdV and Gardner-KP equations. Mathematical Sciences 2012 6:68.

## Submit your manuscript to a SpringerOpen ${ }^{\circ}$ journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at $\downarrow$ springeropen.com


[^0]:    *Correspondence: j-manafian@iau-ahar.ac.ir
    ${ }^{1}$ Mathematics Department, Islamic Azad University-Ahar Branch, Ahar, Iran Full list of author information is available at the end of the article

