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# Predicting the mechanical characteristics of hydrogen functionalized graphene sheets using artificial neural network approach

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## Abstract

The mechanical properties of hydrogen functionalized graphene (HFG) sheets were predicted in this work by using artificial neural network approach. The predictions of tensile strength of HFG sheets made by the proposed approach are compared to those generated by molecular dynamics simulations. The results indicate that our proposed computing technique can be used as a powerful tool for predicting the tensile strength of the HFG sheet.

**Keywords:** Hydrogen functionalized graphene; Tensile; Atomistic simulation; Nanomechanics; Artificial neural network

## Background

Research in graphene has attracted significant interest in recent years due to its remarkable mechanical [1] and physical properties [2,3]. A single-layer graphene sheet has the thickness of only one carbon atom which makes it the thinnest material [4] with a large specific surface area [5]. This feature of graphene makes it an ideal candidate for nanoelectromechanical systems (NEMS) [6] and nanofluidic devices. These future applications require a critical understanding of the exceptional mechanical properties of graphene for its application in NEMS and nanolevel biological devices. Theoretical studies on graphene are a popular mode of research, employing *ab initio* calculations or molecular dynamics (MD) simulation technique.

Application of soft computing methods such as artificial neural networks (ANN), genetic programming, and fuzzy logic can be used as an alternative method for modeling complex behavior of materials such as graphene. These methods require input training data which can be obtained from the analytical tools such as MD that is based on a specific geometry and temperature. Based on the input, the proposed computing method can then be able to generate meaningful solutions for complicated problems [7-11]. Additionally, among the

various soft computing methods described above, ANN offers the advantage of a fast and cost-effective formulation of a mathematical model based on multiple variables with no existing analytical models [12,13]. It is to the best of author's knowledge that limited or no work exists on the application of soft computing models on the tensile properties of graphene sheets.

Hence, in the present work, we have proposed ANN method to model the elastic characteristics of hydrogen functionalized graphene (HFG). The values of tensile strength of HFG generated by MD simulations are further fed into the paradigm of ANN.

## Nanoscale material modeling by MD simulation

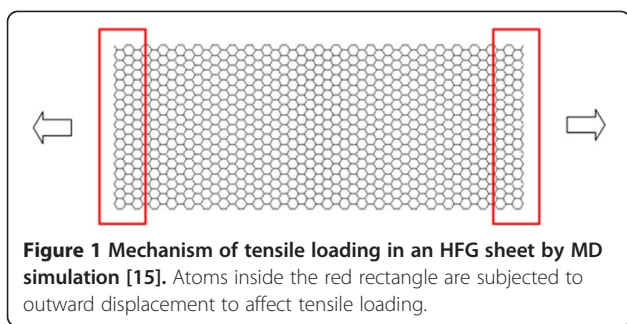
The classical MD method is deployed to carry out the numerical simulation. In this capacity, Newton's equations of motion are computed by means of Brenner's second-generation bond order (REBO) function [14] for the set of atoms which are covalently bonded. The REBO potential is able to accurately describe the properties of solid-state and molecular carbon nanostructures [15,16] while maintaining the accuracies of the *ab initio* and semi-empirical methods in simulating large systems [15-21]. The mathematical form of the potential equations is defined as

$$E_{\text{REBO}} = V_{\text{R}}(r_{ij}) - b_{ij} V_{\text{A}}(r_{ij}), \quad (1)$$

where  $V_{\text{R}}(r_{ij})$  and  $V_{\text{A}}(r_{ij})$  are the repulsive and attractive pair terms and  $b_{ij}$  term is used to include the reactive empirical bond order between the atoms.

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**Figure 1** Mechanism of tensile loading in an HFG sheet by MD simulation [15]. Atoms inside the red rectangle are subjected to outward displacement to affect tensile loading.

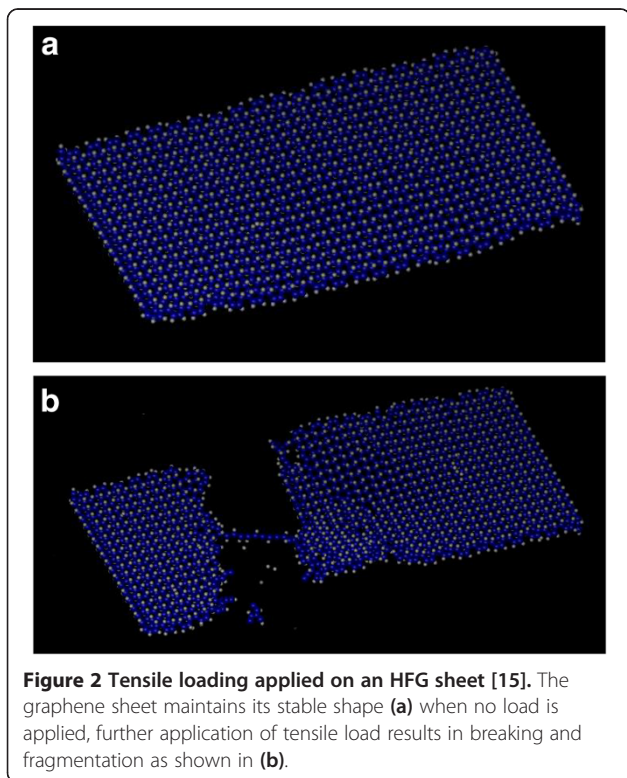
The MD simulation procedure described here is similar to our previous work as can be seen in [15]. The tensile loading procedure of HFG sheet is shown in Figure 1. As an illustration, the morphological characteristics of the HFG sheet of length 100 Å under tension is depicted in Figure 2. The data hence generated by our MD simulation agrees very well with the literature [15,20], and hence, we can validate the reliability of our MD simulation.

#### Methods

The data obtained by the MD simulation are shown in Tables 1 and 2 which represent the data for training and testing samples, respectively. The main inputs considered in our study are the percentage of hydrogen functionalization and simulation temperature. The output of our study is the tensile strength of HFG. In order to explicitly test the extrapolation capability of method, 20

**Table 1** Data for training obtained by MD simulation

Temperature (K)	Percentage of hydrogen functionalization	Tensile strength (GPa)
0	0	157
0	0.1	135
0	0.2	123
0	0.3	109
0	0.4	92
0	0.5	85
0	0.6	82
0	0.7	83
0	0.8	85
0	0.9	81
0	1	87
300	0	101
300	0.1	72
300	0.2	63
300	0.3	52
300	0.4	43
300	0.5	39
300	0.6	34
300	0.7	35
300	0.8	35
300	0.9	41
300	1	43



**Figure 2** Tensile loading applied on an HFG sheet [15]. The graphene sheet maintains its stable shape (a) when no load is applied, further application of tensile load results in breaking and fragmentation as shown in (b).

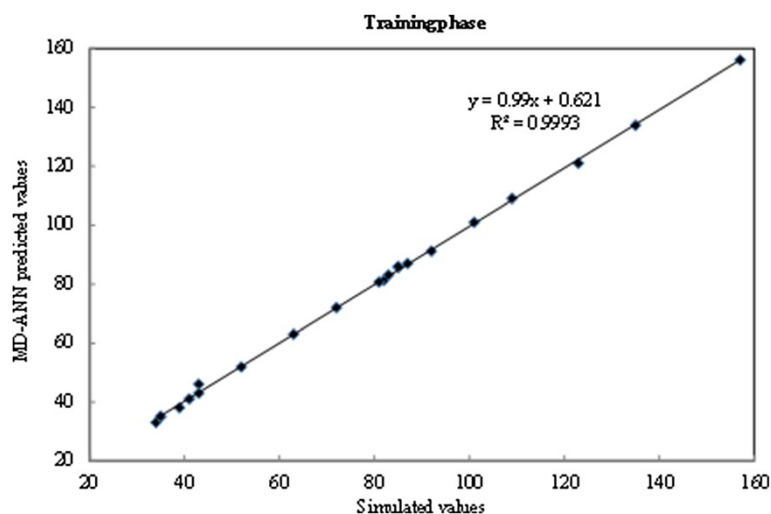
samples are used for training and 11 are used for testing. Training samples consist of values of tensile strength at temperatures of 0 and 300 K, whereas testing samples consist of values of temperature at 600 K.

#### Nanoscale material modeling by ANN approach

In this paper, we proposed ANN approach. In this approach, data obtained from MD is fed into the paradigm

**Table 2** Data for testing obtained by MD simulation

Temperature (K)	Percentage of hydrogen functionalization	Tensile strength (GPa)
600	0	51
600	0.1	35
600	0.2	32
600	0.3	25
600	0.4	20
600	0.5	19
600	0.6	15
600	0.7	18
600	0.8	18
600	0.9	21
600	1	22



**Figure 3** Comparison between predicted values and simulated values on training data.

of ANN for training of network. ANN network consist of three layers: input, hidden, and output layers. Input layer consist of two neurons since there are two inputs [22-31]. The number of neurons in the hidden layer is chosen based on trial-and-error method. The output layer comprise of single neuron, i.e., output of the system. The neurons of one layer to the neurons of pre-and-after layer are connected through weighted links.

Weights are initialized and are multiplied by input values specified by each neuron. The neuron estimate summation of weighted inputs and passes it to the transfer function ( $A$ ) which produces an output  $Y_p$ .

$$Y_p = A\left(\sum_{i=0}^{n-1} w_i x_i - \delta\right), \quad (2)$$

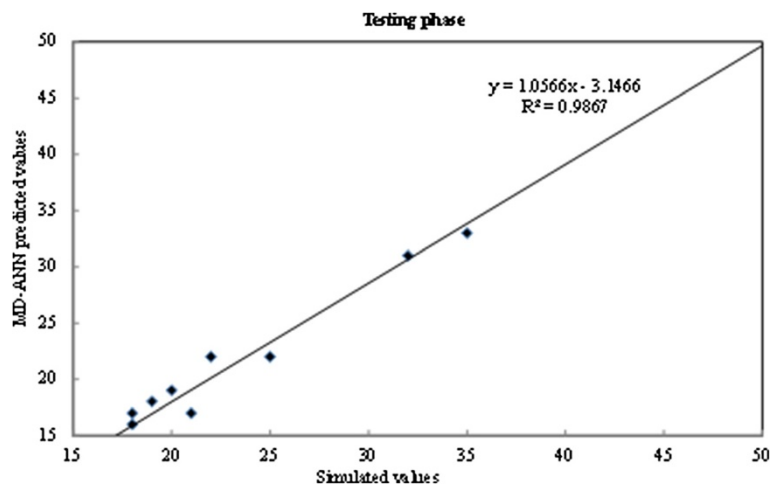
where  $w_i$  is weight,  $x_i$  is the  $i$ th input variable, and  $\delta$  is the threshold or offset of the neuron. The activation function used is sigmoid logistic function given by

$$A(x) = \frac{1}{1 + e^{-x}}. \quad (3)$$

The difference between the output value of network and actual value for a sample  $i$  is given by

$$\text{Error}_m = \frac{1}{2} \sum_{m=1}^M (Ac_i - M_i)^2, \quad (4)$$

where  $Ac_i$  and  $M_i$  are actual and predicted values for  $i$ th sample, respectively, and  $M$  is the number of neurons in



**Figure 4** Comparison between predicted values and simulated values on testing data.

the output of network. The average error for the whole network is given by

$$\text{Error}_m = \frac{1}{2} \sum_{m=1}^M \sum_{i=1}^M (Ac_i - M_i)^2, \quad (5)$$

where  $N$  is the total number of samples. The Levenberg-Marquardt algorithm [32] that works on the principle of the second derivative is used to optimize the  $\text{Error}_p$ . The simpler form of Hessian matrix is used and the algorithm iterates weights using formulae

$$x_{k+1} = x_k - [J^T J + \mu I]^{-1} J^T e, \quad (6)$$

where  $J$  is the Jacobian matrix that consists of the first derivatives of the network errors,  $e$  is a vector of network errors,  $\mu$  is the learning rate, and  $I$  is the identity matrix. The weights are updated by LMA until the threshold error is achieved. The computation of weights is iterative and it consumes time.

In the present work, feed-forward network of three layers is implemented in MATLAB R2010b. The number of neurons in hidden layer is determined based on the minimum value of root-mean-square error (RMSE) of the model on the training data set. A trial-and-error approach is adopted to select the number of neurons in the hidden layers. It was found that for number of neurons six, the RMSE is minimum, and therefore, the ANN model with single hidden layer of six neurons is selected. The performance of the selected ANN model is discussed in the 'Performance comparison of proposed approach' section.

## Results and discussion

The predictions obtained from the proposed approach is compared to those generated using MD simulations based on square of correlation coefficient ( $R^2$ ) given by

$$R^2 = \left( \frac{\sum_{i=1}^n (A_i - \bar{A}_i)(M_i - \bar{M}_i)}{\sqrt{\sum_{i=1}^n (A_i - \bar{A}_i)^2 \sum_{i=1}^n (M_i - \bar{M}_i)^2}} \right)^2, \quad (7)$$

where  $M_i$  and  $A_i$  are predicted and actual values, respectively,  $\bar{M}_i$  and  $\bar{A}_i$  are the average values of predicted and actual, respectively, and  $n$  is number of training samples.

The results obtained from the simulation studies and predicted by using proposed approach on training and testing data is shown in Figures 3 and 4, respectively. The graph shown in Figure 3 indicates that the proposed approach has impressively well learned the non-linear relationship between the input and output process parameters with high correlation values. The result of testing phase shown in Figure 4 indicates that the values predicted by MD-ANN approach are well in agreement with the simulated values.

## Conclusion

The performance of the proposed MD-ANN approach is evaluated in the 'Performance comparison of proposed approach' section. The results conclude that the MD-ANN model have shown excellent generalization ability with high statistical values of  $R^2$  on testing data. The high generalization ability of the MD-ANN model is beneficial for MD experts who are currently looking for high fidelity models that predict the tensile strength of graphene under uncertain input process conditions, and therefore, the cost of having to run additional MD simulations can be avoided. The model can be used offline for prediction and can be further optimized to determine the optimum input process parameters that maximize the tensile strength of nanomaterials.

## Competing interests

The authors declare that they have no competing interests.

## Authors' contributions

VV carried out preliminary simulations to confirm that data generated confirm to literature and is supervised by CHW. AG carried out the computational simulations designed and formulated by YB and is supervised by KT. All authors read and approved the final manuscript.

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