



# Taguchi optimization of integrated flow microfluidic biosensor for COVID-19 detection

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Received: 19 March 2022 / Accepted: 17 October 2022

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**Abstract** In this research, Taguchi's method was employed to optimize the performance of a microfluidic biosensor with an integrated flow confinement for rapid detection of the SARS-CoV-2. The finite element method was used to solve the physical model which has been first validated by comparison with experimental results. The novelty of this study is the use of the Taguchi approach in the optimization analysis. An  $L8(2^7)$  orthogonal array of seven critical parameters—Reynolds number (Re), Damköhler number (Da), relative adsorption capacity ( $\sigma$ ), equilibrium dissociation constant ( $K_D$ ), Schmidt number (Sc), confinement coefficient ( $\alpha$ ) and dimensionless confinement position (X), with two levels was designed. Analysis of variance (ANOVA) methods are also used to calculate the contribution of each parameter. The optimal combination of these key parameters was  $Re = 10^{-2}$ ,  $Da = 1000$ ,  $\sigma = 0.5$ ,  $K_D = 5$ ,  $Sc = 10^5$ ,  $\alpha = 2$  and  $X = 2$  to achieve the lowest dimensionless response time (0.11). Among the all-optimization factors, the relative adsorption capacity ( $\sigma$ ) has the highest contribution (37%) to the reduction of the response time, while the Schmidt number (Sc) has the lowest contribution (7%).

## 1 Introduction

Since the emergence of the COVID-19 pandemic caused by the novel coronavirus, i.e., severe acute respiratory syndrome coronavirus-2 (SARS-CoV-2), at the end of December 2019 in Wuhan, China [1], researchers have not stopped searching for innovative approaches to detect infections as quickly as possible, reliably, and sensitively in order to control and limit the rapid spread of the disease. Among these approaches, microfluidic biosensors have taken a prominent place in the identification of SARS-CoV-2 and thus in the fight against the pandemic [2, 3]. A microfluidic biosensor is an analytical tool composed of a bioreceptor element, which can be an antibody, an enzyme, a DNA fragment, or a whole cell, which allows the identification of the species to be detected due to its particularly selective site. The bioreceptor is linked to a transducer element capable of converting biological information into an electrical signal—a physical, mechanical, thermal, or optical one [4, 5]. The characteristics and performance of these biosensor devices are strongly linked to sensitivity, specificity, reliability, simplicity, low cost and especially to the rapid detection.

Currently, diagnostic techniques for patients with SARS-CoV-2 are the quantitative real-time polymerase chain reaction (qRT-PCR), CT scans, antigenic tests, serological tests, etc. Although qRT-PCR is the most widely used detection method for detecting COVID-19 [6, 7], it requires complex equipment and skilled operators. It is also slow, expensive, and laborious [8, 9]. Point-of-care (POC) biosensors that are also used for rapid diagnosis of COVID-19 disease are polydimethylsiloxane (PDMS) chip-based biosensors or paper-based biosensors, like lateral flow test strips [10, 11]. These tests are generally used to detect antigens, antibodies, or nucleic acids in raw samples (sputum, saliva, and blood) [12]. Antibody tests are appropriate for detecting late-stage infections, whereas nucleic acid tests identify the presence of nucleic acids (viruses) at an early phase of infection, revealing sensitivity and specificity superior to antibody tests. Nevertheless, nucleic acid testing requires more complicated processes than antibody testing such as nucleic acid extraction, amplification, and detection [13]. Compared to existing POC biosensors, qRT-PCR shows higher clinical sensitivity and specificity.

To enhance functionality and detection sensitivity of current biosensors, many numerical and experimental studies have been made. Magnetic effect [14], electrokinetic effect [15–18], optical forces [19], etc., are physical mechanisms that have been applied to agitate the flows in the microchannel to increase the rate of the biosensor binding reaction. Selmi et al. [20, 21] simulated the effect of confining flow (flux injection), added perpendicular to the main flow, to reduce the diffusion layer and improve biosensor

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performance. Also, the adjustment of certain key parameters of microfluidic biosensors was one of the means used to optimize the detection time of these devices. Kaziz et al. [18] performed a 3D study on the effect of reaction surface shape on the response time of microfluidic biosensor with electrothermal force. The obtained results are compared to the same biosensor having a rectangular binding surface [17]. Shahbazi et al. [22] showed that the impact of moving the reaction surface position by just 500  $\mu\text{m}$  decreased the saturation time by further than 50%.

In this article, a 2D finite element simulation on the binding kinetics of SARS-CoV-2 was performed to optimize the performance of the flow-confinement microfluidic biosensor. To determine the degree of influence of some input factors on the detection time, Taguchi's numerical plan of experiment, based on analysis of variance (ANOVA) and mean effect, was adopted as a support for the modeling of the microfluidic biosensor, in order to have the minimum number of simulations to be performed. Design of experiments (DOE) is a methodology for determining the links between process input variables and a quantity of interest, called the response. The variables, physical quantities modifiable by the experimenter, are supposed to influence the variations of the response. Using the plans of experiments, one obtains the maximum of information with the minimum of experiments [23]. A full factorial experiment takes all possible combinations of each key parameter to study their effects on the response variable. If there are  $n$  parameters with 2 levels each, then the full-factor design has  $2^n$  tests. This large number of experiments is costly in terms of time and energy. To overcome this problem, Taguchi introduced an experiment design technique using an orthogonal array (OA) to study the whole range of factors with a reduced number of experiments [24]. Therefore, the time as well as the cost is significantly reduced. ANOVA is then used to determine the significance and contribution of each process parameter to the output characteristic. With main effects and ANOVA analyses, a possible combination of optimal parameters can be predicted. Finally, a confirmation experiment is conducted to verify the obtained optimal process parameters.

The Taguchi approach is utilized in several domains like physics [25], medicine [26], environmental sciences [27, 28], chemical processes [29] and statistics [30]. ANOVA is one of the most common techniques used to do statistical analysis of data [31].

## 2 Mathematical model

### 2.1 Confined flow microfluidic biosensor design

Figure 1 shows the design model of the confined flow microfluidic biosensor investigated in this study. The length "L" and the height "H" of the microchannel are 250  $\mu\text{m}$  and 40  $\mu\text{m}$ , respectively.

The reaction surface, of length is  $l_s = 20 \mu\text{m}$ , is placed on the microchannel bottom. On the upper wall of the microchannel, a flow confinement, perpendicular to the main flow, is situated at a distance  $X$  from the entrance of the microchannel.

The carrier fluid, which is water, mixed with the analytes (SARS-CoV-2) flows in the microchannel from left to right. Ligands (antibodies) of constant concentration are initially immobilized on the reaction surface.

### 2.2 Modeling of Navier–Stokes equations

For incompressible fluid, the Navier–Stokes equations describing the flow of the carrier fluid in the microchannel were considered in terms of dimensionless amounts [32] as follows (Eq. (1) and Eq. (2)):

$$\nabla^* \cdot \vec{U}^* = 0 \quad (1)$$

$$\vec{U}^* \cdot (\nabla^* \vec{U}^*) = -\nabla^* p^* + \frac{1}{Re} \Delta^* \vec{U}^* \quad (2)$$

All the variables used in the Navier–Stokes equations are dimensionless. The quantities without and with asterisk designate, respectively, dimensional and dimensionless variables.  $Re = \frac{\rho u_0 H}{\mu}$  represents the Reynolds number where  $\rho$  and  $\mu$  are, respectively, the fluid's density and dynamic viscosity,  $u_0$  is the average inlet velocity, and  $H$  is the microchannel height. The dimensionless components of the velocity vector are  $u^* = \frac{u}{u_0}$  and  $v^* = \frac{v}{u_0}$ . The confinement coefficient,  $\alpha$ , is identified as the velocity confinement ratio of the stream to that of the mainstream containing the target analytes ( $\alpha = \frac{U_{conf}}{u_0}$ ).  $H$ ,  $u_0$  and  $\rho u_0^2$  are the length, the velocity, and the pressure scales, respectively.

### 2.3 Modeling of the analyte transport equation

The combination of convection and diffusion effects within the microchannel contributes to concentration gradients. The convection–diffusion equation [20] describing the spatio-temporal evolution of analyte concentration in the fluid inside the microchannel is expressed by (Eq. (3)):

$$\frac{\partial C^*}{\partial t^*} + Pe \vec{U}^* \cdot \nabla^* C^* = \Delta^* C^* \quad (3)$$

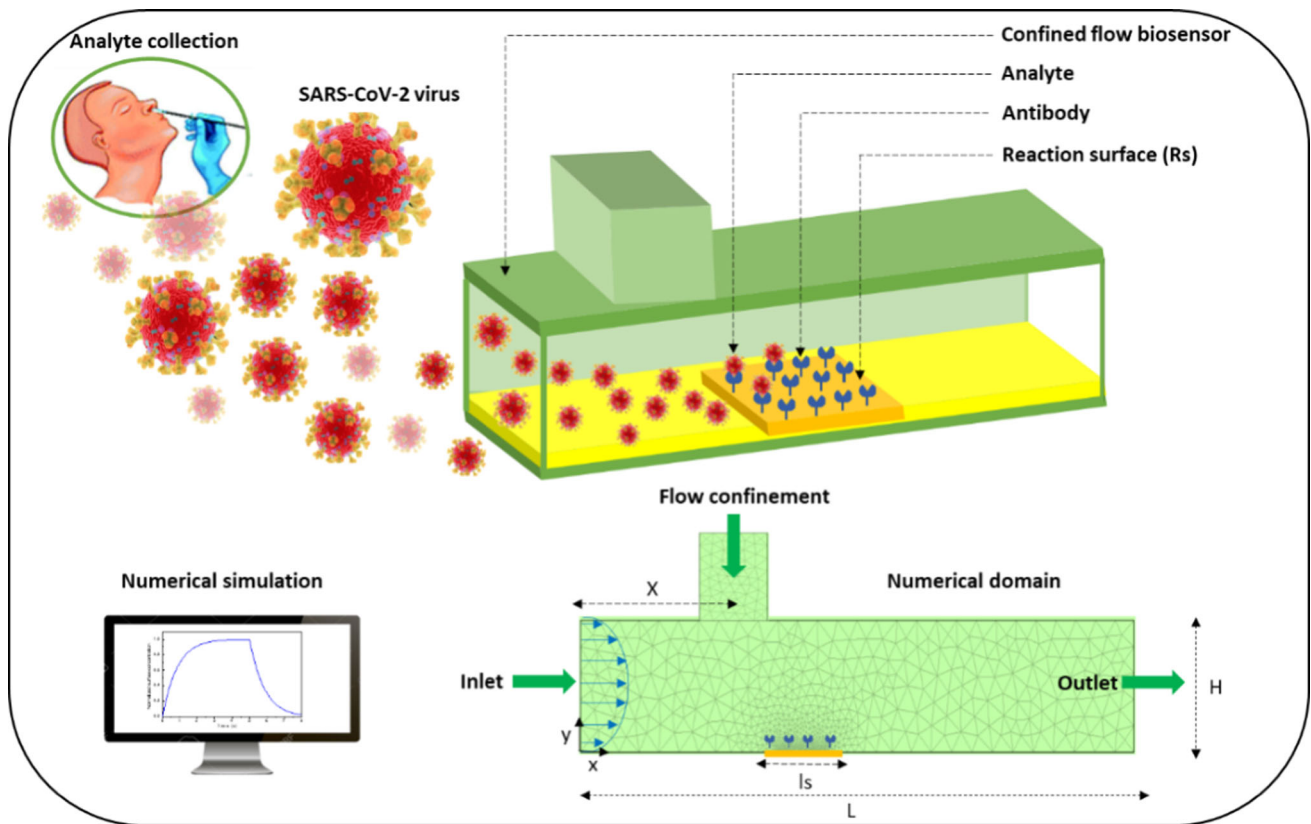


Fig. 1 Sketch of the confined flow microfluidic biosensor

where  $C^* = \frac{C}{C_0}$  is the dimensionless concentration of the analyte, and  $t^* = \frac{t}{t_0}$  is the dimensionless time.  $C_0$  is the inlet analyte concentration,  $\frac{\partial C^*}{\partial t^*}$  is the dimensionless concentration gradient,  $Pe = \frac{u_0 H}{D}$  is the Peclet number. The time scale is  $t_0 = \frac{H^2}{D}$ , and the concentration scale is  $C_0$ . In the context of mass transport, the Peclet number is the product of the Schmidt number (Sc) and the Reynolds number.

### 2.4 Modeling of the kinetic analyte–ligand reaction

The first-order Langmuir–Hinshelwood adsorption model [33, 34] (Eq. (4)) was employed to calculate the analyte–ligand complex concentration formed on the reaction surface.

$$\frac{\partial B^*}{\partial t^*} = Da \cdot \sigma \left[ C_{surf}^* (1 - B^*) - \frac{1}{K_A C_0} B^* \right] \tag{4}$$

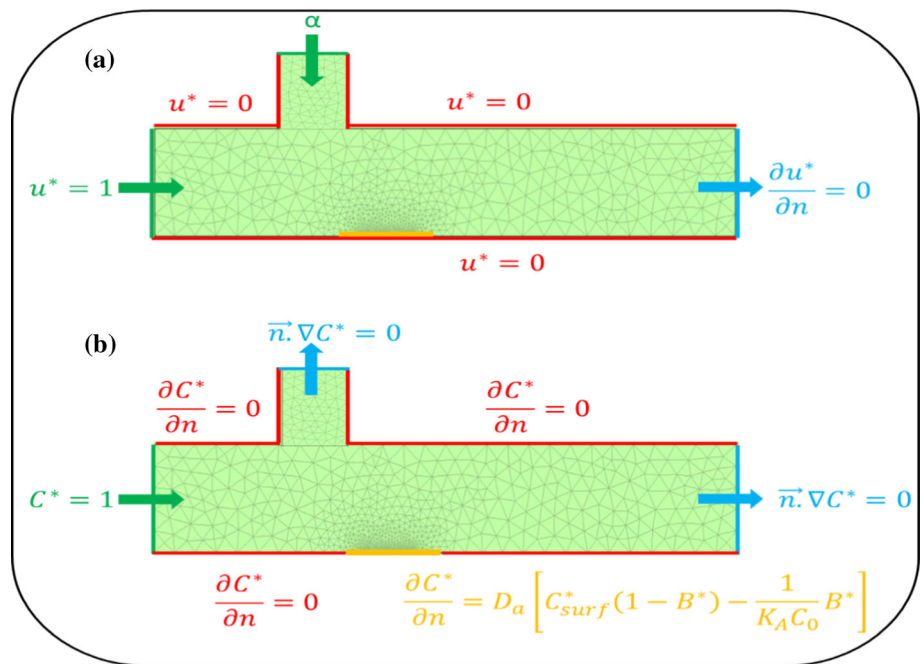
where  $B^* = \frac{B}{B_{max}}$ ,  $B$  is the bound complex concentration, and  $B_{max}$  is the initial concentration of ligand immobilized on the binding surface.  $C_{surf}^* = \frac{C_{surf}}{C_0}$  where  $C_{surf}$  is the analyte concentration at the reaction surface,  $Da = \frac{K_{on} B_{max} H}{D}$  is the Damköhler number,  $\sigma = \frac{H C_0}{B_{max}}$  is the relative adsorption capacity, and  $K_A = \frac{k_{on}}{k_{off}}$  is the affinity constant where  $k_{on}$  and  $k_{off}$  are the adsorption and the desorption constants, respectively.  $K_D = \frac{1}{K_A C_0}$  is the dimensionless equilibrium dissociation constant.

The relative adsorption capacity ( $\sigma$ ) corresponds to the relative density of analytes between the bulk and the fully saturated surfaces (a measure of surface adsorption capacity relative to the bulk). It occurs when matching the units of surface concentration and bulk concentration [35, 36]. The Damkohler number (Da) is used in chemical kinetics to define the operating conditions of a reaction. If  $Da < 1$ , the reaction is very slow and if  $Da > 1$ , the reaction is very fast, and the flow is in chemical equilibrium.

### 3 Initial and boundary conditions

Initially, the dimensionless fluid velocity ( $U^*$ ) is assumed equal to unity. Also, the concentration of analyte,  $C_{(t=0)}$ , and the surface complex analyte/ligand concentration,  $B_{(t=0)}$ , were initially zero. All boundary conditions for velocity and analyte concentration used in this model are summarized in Fig. 2 where  $\vec{n}$  is the unit normal vector to the surface. For the fluid flow mode, the non-slip

**Fig. 2** Boundary conditions. **a:** Velocity field boundary conditions. **b:** Analyte concentration boundary conditions



**Table 1** Simulation parameters

Parameter	Description	Value	Unit
$\rho$	Fluid density	1000	kg/m <sup>3</sup>
$\mu$	Dynamic viscosity	1,08.10 <sup>-3</sup>	Pa.s
$K_A$	Affinity constant	10 <sup>6</sup>	m <sup>3</sup> /Mol
$B_{max}$	Ligand concentration	3,3.10 <sup>-8</sup>	Mol/m <sup>2</sup>
L	Microchannel length	250	μm
H	Microchannel height	40	μm
ls	Reaction surface length	20	μm

conditions along the walls of the microfluidic device are applied, a parabolic velocity distribution with average value  $u_0$  is given to the carrier fluid at the inlet of the microchannel, the one entering through the confining channel, its velocity was set to  $u_{conf}$  and at the outlet the flow is assumed fully developed. For the transport equation (Eq. (3)), a low concentration of analyte  $C_0$  is injected at the inlet, and the convective flow condition is applied at the outlet. On the sensitive surface, the diffusive flux condition generated by the binding reaction between analytes and ligands is applied and the homogeneous Neumann condition is used for the other walls because they are assumed to be impermeable and do not interact with the target analyte [22].

To evaluate the influence of control parameters on SARS-CoV-2 binding kinetics, we performed numerical simulations using the geometric design of the microfluidic biosensor proposed in Fig. 1. The geometric dimensions, the fluid physical parameters and SARS-CoV-2/Antibody binding factors [22] used for the simulation are shown in Table 1.

#### 4 Parameters and levels selection

In this study, different controllable parameters were selected to be optimized, in order to maximize the efficiency of the biosensor. The Reynolds number  $Re$ , the Damkohler number  $Da$ , the relative adsorption capacity  $\sigma$ , the equilibrium dissociation constant  $K_D$ , the Schmidt number  $Sc$ , the confinement coefficient  $\alpha$  and the confinement position  $X$  are the seven variables that we have considered to optimize by the Taguchi method in order to obtain their optimal combination giving the shortest detection time.

##### 4.1 Reynolds number

In microfluidic devices, flow velocities are typically low (a few tenths of a millimeter per second), resulting in a low Reynolds number [20]. As the carrier fluid in our case is water ( $\rho = 10^3 \text{ kg.m}^{-3}$ ,  $\mu = 1,08.10^{-3}$  Pa.s), then the Reynolds number varies between  $10^{-3}$  and  $10^{-2}$  for flow velocities varying between  $10^{-4}$  and  $10^{-3}$  m.s<sup>-1</sup>.

#### 4.2 Damkohler number

When we fix the surface concentration of binding sites on the biosensor ( $B_{max} = 3, 3 \cdot 10^{-8} \text{ Mol} \cdot \text{m}^{-2}$ ) [16–18, 22] and the height of the microchannel ( $H = 40 \cdot 10^{-6} \text{ m}$ ), the Damkohler number becomes dependent only on the diffusion coefficient of the target analyte ( $D$ ) and the adsorption analyte-antibody constant ( $K_{on}$ ). As the diffusion coefficient can vary from  $10^{-11}$  to  $10^{-10} \text{ m}^2 \cdot \text{s}^{-1}$  and the adsorption constant between  $10^2$  and  $10^4 \text{ m}^3/\text{Mol} \cdot \text{s}$  for SARS-CoV-2 [22], then the Damkohler number can vary between 1 and 1000.

#### 4.3 Relative adsorption capacity

For low concentrations of target analyte (of the order of  $10^{-5} \text{ Mol}/\text{m}^3$  and  $10^{-4} \text{ Mol}/\text{m}^3$ ), the relative adsorption capacity can vary from  $10^{-2}$  to  $10^{-1}$  with the same values of  $B_{max}$  and  $H$ . For high relative adsorption capacity (low  $\sigma$ ), the bulk concentration reaches a steady-state value much before the surface has been significantly saturated [35].

#### 4.4 Schmidt number

As the Schmidt number, which is the ratio of the Peclet number to the Reynolds number ( $Sc = \frac{Pe}{Re}$ ), is inversely proportional to the antigen diffusion coefficient ( $D$ ), for a given density and dynamic viscosity of the carrier fluid, then it can vary between  $10^4$  and  $10^5$  for the same range of variation of  $D$  indicated before.

### 5 Model simulation

The proposed model equations were solved using Galerkin finite element analysis [37]. 1549 triangular geometric elements were used for the whole 2D domain including the refined elements of the reaction surface. First, the pressure and velocity fields were calculated by simultaneously solving stationary Eqs. (1) and (2). The analyte and complex concentrations were simulated from the coupled time-dependent Eqs. (3) and (4). In the numerical model, the reaction surface is taken into account as a boundary condition where the diffusion flux is balanced against the reaction rate. The average complex concentration ( $\langle B^* \rangle$ ) at the reaction surface is calculated by this equation (Eq. (5)):

$$\langle B^* \rangle = \frac{1}{l_s^*} \int_0^{l_s^*} B(x) dx \tag{5}$$

where  $l_s^* = \frac{l_s}{H}$  is the dimensionless length of the binding surface.

The response time corresponds to the time for which the concentration of the complex is 95% is extracted from the time evolution of  $\langle B^* \rangle$ .

### 6 Experimental design

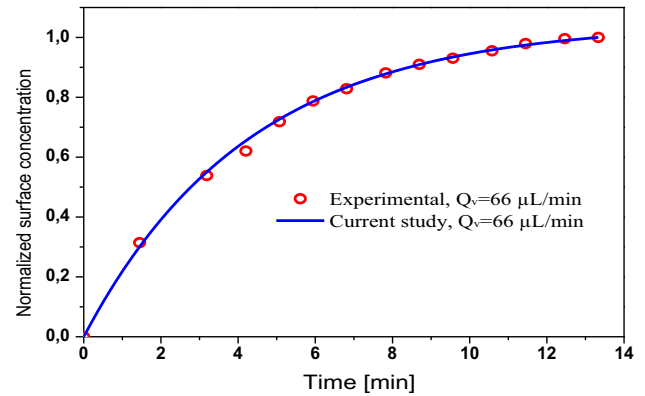
The experiment using Taguchi method was considered in this numerical simulation to decrease the response time of the integrated flow confinement microfluidic biosensor. Table 2 shows seven optimization parameters having two levels each used in the experiment design. If there are seven factors called A, B, C, D, E, F and G, all are examined with two levels called “1” and “2.” A full factorial design requires  $2^7 = 128$  combinations. In order to reduce this number, the orthogonal array of  $L_8(2^7)$ , based on the Taguchi method, was used and is represented in Table 3. This design requires eight experiments with seven simulation parameters at two levels of each neglecting the interactions between them.

**Table 2** Levels of control parameters

Symbol	Control parameter	Level 1	Level 2
Re	Reynolds number	$5 \cdot 10^{-3}$	$10^{-2}$
Da	Damköhler number	5	1000
$\sigma$	Relative adsorption capacity	0.02	0.5
$K_D$	Equilibrium dissociation constant	1	5
Sc	Schmidt number	$10^4$	$10^5$
$\alpha$	Confinement coefficient	0.1	2
X	Dimensionless confinement position	0.5	2

**Table 3** Taguchi's  $L_8(2^7)$  orthogonal array

Standard Order	Factors							X
	Re	Da	$\sigma$	$K_D$	Sc	$\alpha$		
1	1	1	1	1	1	1	1	
2	1	1	1	2	2	2	2	
3	1	2	2	1	1	2	2	
4	1	2	2	2	2	1	1	
5	2	1	2	1	2	1	2	
6	2	1	2	2	1	2	1	
7	2	2	1	1	2	2	1	
8	2	2	1	2	1	1	2	

**Fig. 3** Comparison of our model with the experimental results of Hoffman et al.[33]

## 7 Results and discussion

### 7.1 Model validation

First, the numerical model was tested by comparison with experimental existing data of Hofmann et al. [33], as shown in Fig. 3. The time-normalized surface concentration during the adsorption phase was calculated using the same experimental parameters used for the immunoassay concerning the rabbit Immunoglobulin G (IgG) and Cy-5-labeled anti-rabbit IgG in a microchannel with confinement effect. Validation is performed for small concentration of analyte ( $c_0 = 10 \mu\text{mol}/\text{m}^3$ ) mixed with buffer fluid (water) flowing through a 3D dimensional microfluidic channel of dimensions  $25 \text{ mm} \times 5 \text{ mm} \times 0.02 \text{ mm}$  with a flow rate  $Q_v = 66 \mu\text{L}/\text{min}$ . A circular detection area with a diameter of 4 mm is fixed in the lower microchannel wall. The analyte is characterized by a diffusion coefficient of  $3 \times 10^{-11} \text{ m}^2/\text{s}$ . The surface concentration of the antibody ligand, dissociation and association rate of the biosensor is  $2.387 \times 10^{-7} \text{ mol}/\text{m}^2$ ,  $3.5 \times 10^{-3} \text{ s}^{-1}$  and  $240 \text{ m}^3/\text{mol}\cdot\text{s}$ , respectively.

We can note that the average error between the two results is very small which makes it possible to consider that the model is proven, and that it can be used for other topics.

### 7.2 The diffusion boundary layer thickness

The size of SARS-CoV-2 is on the order of 100 nm, so the binding reaction is expected to be strongly restricted by mass transport [38] owing to the low diffusion coefficient and the high affinity for a virus of such large size. The limited mass transport generally causes the development of a diffusion boundary layer above the reaction surface which thickness is written as follows [39] (Eq. (6)):

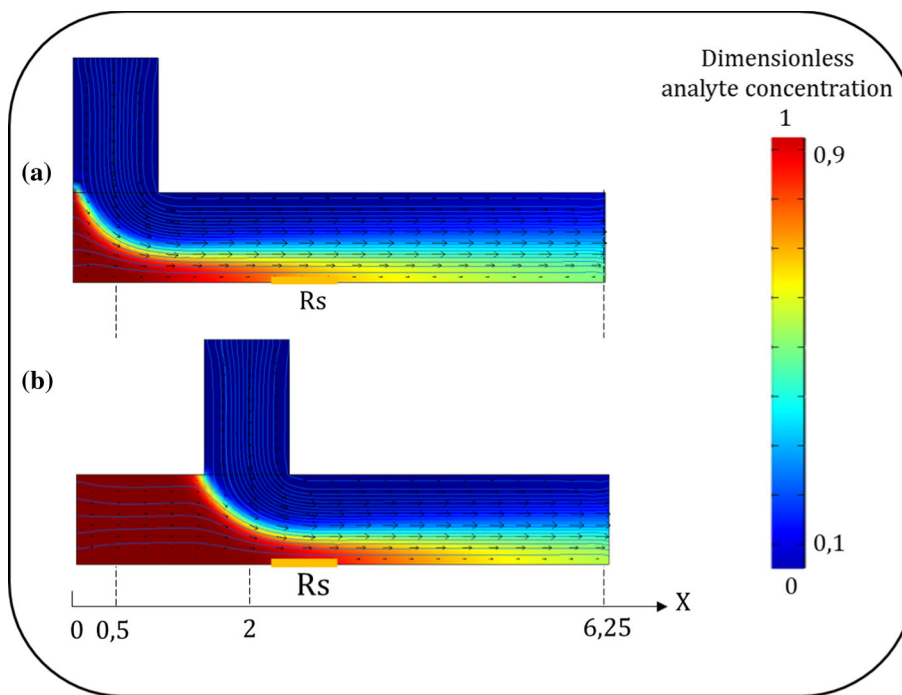
$$d_{diff} = \frac{1}{0.98} \left( \frac{DHl}{u} \right)^{1/3} \quad (6)$$

where  $u$  is the flow velocity,  $D$  is the diffusion constant of the analyte,  $H$  is the channel height, and  $l$  is the position along the binding surface. In dimensionless notation,  $d_{diff}^*$  factor is written as below (Eq. (7)):

$$d_{diff}^* = \frac{1}{0.98} \left( \frac{l^*}{P_e u^*} \right)^{1/3} \quad (7)$$

where  $l^* = \frac{l}{H}$ ,  $P_e = Re \cdot Sc = \frac{u_0 H}{D}$  is the Peclet number and  $u^* = \frac{u}{u_0}$ .

**Fig. 4** Diffusion boundary layers as a function of the dimensionless position ( $X$ ) of the confining flow. **a:**  $X = 0.5$  and **b:**  $X = 2$ . ( $R_S$  is the reaction surface)



**Fig. 5** Diffusion boundary layer thickness as a function of Reynolds number and position along the sensing zone

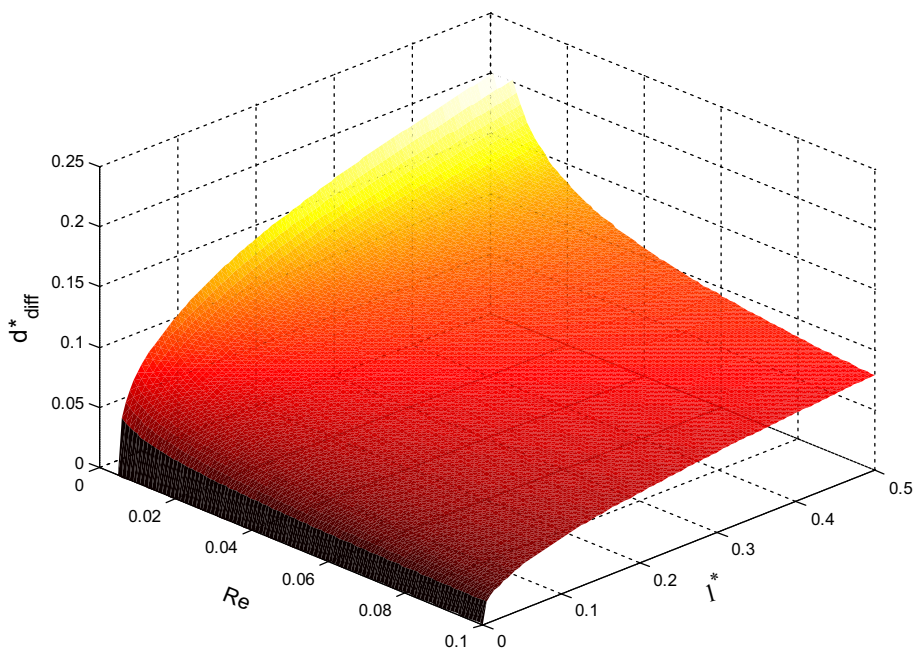
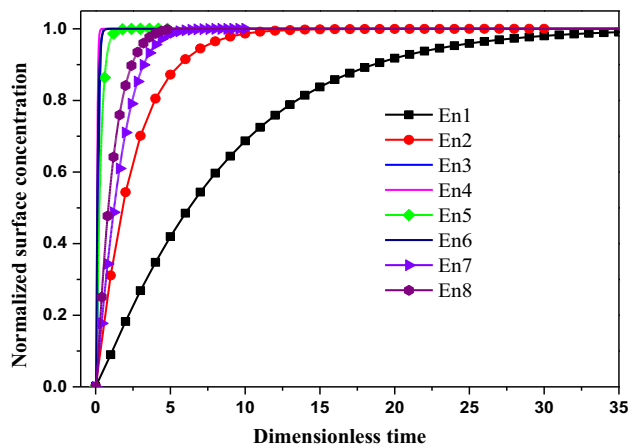


Figure 4 reveals the diffusion boundary layers for the two dimensionless positions of the confinement flow, namely  $X = 0.5$  and  $X = 2$ , for the same confinement coefficient ( $\alpha = 2$ ). As expected, the diffusion boundary layer seems thinner in the case where the confinement of the flow is located roughly opposite the reaction surface because it contributes better to pushing the analytes toward the sensitive surface as evidenced by the shape of the velocity arrows and streamlines plotted in Fig. 4.

Figure 5 shows the variation of the dimensionless of the diffusion layer as a function of the dimensionless position on the reaction surface and of the Reynolds number (for  $X = 2$  and  $\alpha = 2$ ). This figure shows that for a low Reynolds number and an advanced position along the reaction surface, the diffusion boundary layer is thicker. This means that a long sensitive surface and low flow rate are real mass transport limitations for immunoassay applications.

**Fig. 6** Average normalized complex concentration for the eight-experiment numbers



**Table 4** Taguchi’s L8(2<sup>7</sup>) orthogonal array and numerical results

Experiment number (En <sub>i</sub> )	Response time: $T_R^*$	S/N ratio (dB)
1	23.57	- 2.7447
2	7.23	- 1.7183
3	0.37	0.8636
4	0.20	1.3979
5	0.86	0.131
6	0.33	0.96297
7	3.88	- 1.1777
8	3.02	- 0.96001

7.3 Taguchi optimization

Following the successful model validation, eight numerical simulations were performed using the combinations of design parameters in the specified orthogonal matrix table. Figure 6 illustrates the average normalized complex concentration in the reaction surface for all experiment number (En<sub>i</sub>) of Table 3.

The response time of the microfluidic biosensor constitutes the main parameter of the analyte–ligand chemical kinetics. It corresponds to the time during which the concentration of the complex reaches its threshold value. Table 4 shows the numerical results for the response time and its S/N ratio of microfluidic biosensor using the experimental layout (Table 4).

In order to estimate the effect of the design parameters and to fix their relative importance on the reduction of the detection time of the device, an analysis of means and variance ANOVA was performed.

7.3.1 Analysis of means

The average value of the dimensionless detection times obtained can be calculated as (Eq. (8)):

$$\overline{T_R^*} = \frac{1}{8} \sum_{i=1}^8 T_{Ri}^* = 4.93 \tag{8}$$

7.3.2 Calculation of mean effect

The mean value of response time of each factor is determined by (Eq. (9)):

$$Effect_{(F)} = 2 \frac{\sum Y^+ - \sum Y^-}{N} \tag{9}$$

Here,  $N = 8$  is the total number of experiments,  $Y^+$  and  $Y^-$  terms are the responses when a given factor is at its high and low level, respectively. The average effects of all optimization factors for each level are shown in Table 5 and Fig. 7.

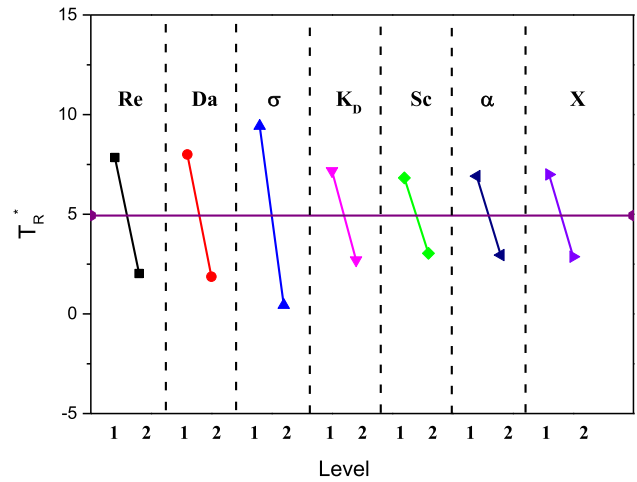
The minimum response time is obtained when all the optimization factors are at high level ( $Re_2, Da_2, \sigma_2, K_{D2}, Sc_2, \alpha_2, X_2$ ). This combination allows us to obtain a minimum detection time equal to 0.11.



**Table 5** Mean value of response time for each level

Level	Re	Da	$\sigma$	$K_D$	Sc	$\alpha$	X
1	7.843	7.998	9.425	7.170	6.823	6.913	6.995
2	2.025	1.868	0.44	2.695	3.043	2.953	2.87
Max-min	5.82	6.13	8.985	4.475	3.78	3.96	4.125
Rank	3	2	1	4	7	6	5

**Fig. 7** Main factor effects on response time



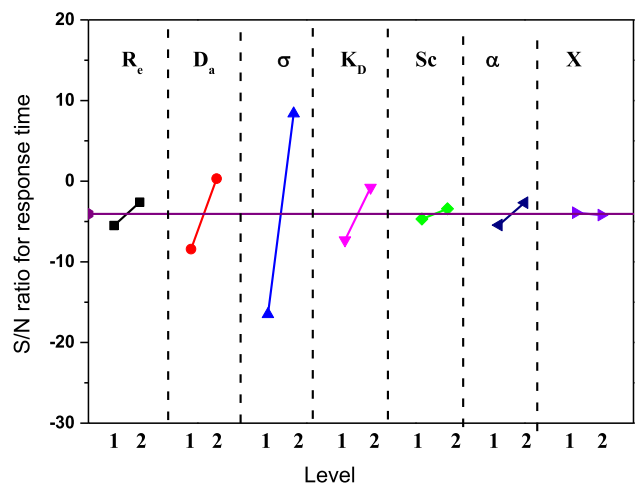
7.3.3 Analysis of variance

The effect of optimization factor in terms of signal-to-noise ratio (S/N) to reach minimum response of microfluidic biosensor is achieved based on lower the better criteria given by this equation [40, 41] (Eq. (10)):

$$S/N = -10\log_{10} \left( \frac{1}{n} \sum_{i=1}^n Y_i^2 \right) \tag{10}$$

Figure 8 illustrates the average effect of S/N ratio of response time for each factor. Table 6 presents the results of analysis of variance:

**Fig. 8** Main effect of S/N ratio for response time



**Table 6** Analysis of variance (ANOVA) for response time  $T_R^*$ 

Symbol	Optimization parameter	D.f	Sum of squares	Mean square	Contribution %
Re	Reynolds number	1	67.745	67.745	15.45
Da	Damköhler number	1	75.154	75.154	17.14
$\sigma$	Relative adsorption capacity	1	161.46	161.46	36.83
$K_D$	Equilibrium constant	1	40.051	40.051	9.13
Sc	Schmidt number	1	28.577	28.577	6.51
$\alpha$	Confinement coefficient	1	31.363	31.363	7.15
X	Confinement position	1	34.031	34.031	7.76
Error		0	0	–	–
Total		7	438.38		100

**Fig. 9** Contribution of key parameters (Re, Da.,  $K_D$ , Sc,  $\alpha$  and X) on the response time

The percentage contribution of each factor on the response time of the microfluidic biosensor is calculated by analysis of variance (Table 6). It is clear from Table 6 that the relative adsorption capacity ( $\sigma$ ) has the highest contribution (36.83%), and the Schmidt number (Sc) has the lowest contribution (6.51%) to reduce the response time among the seven all factors. Further, the contribution of the Reynolds number (Re), Damköhler number (Da), equilibrium constant ( $K_D$ ), confinement coefficient ( $\alpha$ ) and confinement position (X) to the minimization of response time is 15.45%, 17.14%, 9.13%, 7.15% and 7.76%, respectively. D.F is the degree of freedom (= number of level -1) (Fig. 9).

### 7.3.4 Multivariate regression analysis

Multivariate regression analysis is used to determine the relationship between the dependent variables of Reynolds number, Damköhler number, equilibrium constant, relative adsorption capacity, Schmidt number, confinement coefficient and confinement position. The dimensionless detection time  $T_R^*$  value obtained from the regression analysis of these key parameters is expressed by this equation (Eq. (11)):

$$T_R^* = 4.9 - 23.3Re - 24.5Da - 35.9\sigma - 17.9K_D - 15.1Sc - 15.8\alpha - 16.5X \quad (11)$$

The previous model is valid for  $0.005 \leq Re \leq 0.01$ ,  $5 \leq Da \leq 1000$ ,  $0.02 \leq \sigma \leq 0.5$ ,  $1 \leq K_D \leq 5$ ,  $10^4 \leq Sc \leq 10^5$ ,  $0.1 \leq \alpha \leq 2$  and  $0.5 \leq X \leq 2$ . The sign of the coefficients of Eq. (11) indicates that all factors have a significant negative effect on  $T_R^*$ . That is, the increase in these factors contributes to the decrease the response time of microfluidic biosensor with flow confinement.

## 8 Conclusion

This study deals with the optimization of the design parameters of a microfluidic biosensor for the immunoassay of SARS-CoV-2. The detection is based on the efficiency of the reaction kinetics of the binding of SARS-Cov-2 under the effect of a few parameters.

This reaction takes place on a reaction surface, where ligands combine with analytes to create analyte–ligand complexes. A first-order adsorption model is proposed to govern this reaction. Analyte concentration is modeled by a stable distributed convection–diffusion equation in which the advection rate is assumed to satisfy the Navier–Stokes equation. Several numerical tests with critical parameters concerning Reynolds number ( $Re$ ), Damköhler number ( $Da$ ), relative adsorption capacity ( $\sigma$ ), equilibrium dissociation constant ( $K_D$ ), Schmidt number ( $Sc$ ), confinement coefficient ( $\alpha$ ) and confinement position ( $X$ ) with two levels are carried out. The new thing in this study is the use of the Taguchi method in the optimization analysis, and an  $L8(2^7)$  orthogonal table of seven critical parameters was designed. ANOVA methods are also employed to obtain the significance of each key parameter. The optimal combination of the key parameters obtained with current study is  $Re = 10^{-2}$ ,  $Da = 1000$ ,  $\sigma = 0.5$ ,  $K_D = 5$ ,  $Sc = 10^5$ ,  $\alpha = 2$  and  $X = 2$  to achieve the minimum dimensionless response time (0.11). The increase in these factors contributes to the decrease in the response time of microfluidic biosensor with flow confinement. It is expected that our investigation may provide new insights for future advancement in the design of microfluidic biosensor-based diagnostic devices for the detection, control, and prevention of COVID-19.

**Data availability** The data included in this manuscript are available and can be discussed (or shared), upon request to the corresponding author Sameh Kaziz.

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