



# On missing Bianchi identities in cohomology formulation

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**Abstract** In this article, we perform a deep analysis of the Bianchi identities in the two known formulations developed for the four-dimensional effective type IIA supergravity theory with (non-)geometric fluxes. In what we call the ‘first formulation’, fluxes are expressed in the real six-dimensional indices while in the ‘second formulation’, fluxes are written in the cohomology form. We find that the set of flux constraints arising from these two known formulations are not equivalent, and there are missing identities in the cohomology version which need to be supplemented to match with the first formulation. By analyzing two explicit examples, we conjecture a model independent form for (the most of) the missing identities. These identities have been mostly overlooked in the previous attempts of studying moduli stabilization, particularly for the models developed in the beyond toroidal frameworks, where they could play some important role.

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## 1 Introduction

In the context of Type II supergravity theories, a successive application of the T-duality on the NS-NS three-form flux  $H_3$  results in a chain of geometric and non-geometric fluxes, which can be given as under [1–7],

$$H_{ijk} \longrightarrow \omega_{ij}{}^k \longrightarrow Q_i{}^{jk} \longrightarrow R^{ijk}. \quad (1.1)$$

A consistent incorporation of the various possible fluxes makes the compactification background richer and more flexible for model building. In this regard, a continuous progress has been made since more than a decade towards moduli stabilization [8–11], in constructing de-Sitter vacua [12–16] and also in realizing the minimal aspects of inflationary cosmology [17–20].

One of the important aspects of model building in non-geometric flux compactification is to consistently satisfy all the quadratic flux constraints coming from the various Bianchi identities and the tadpole cancellation conditions. This can be very crucial as sometimes it can simplify the scalar potential to a great length by canceling many terms. In this regard, it is worth to mention that the 4D non-geometric scalar potentials arising from a concrete construction, very often consist of quite huge number of terms. For example, in

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the two concrete setups which we will consider in this article, we find that there are thousands of terms in the scalar potential. Subsequently, it is anticipated that it can get even hard to analytically solve the extremization conditions because the same would demand to solve very high degree polynomials. Unfortunately there is nothing like LARGE volume scenarios [21] in these non-geometric constructions, and therefore all the terms being at tree level are equally important and cannot be naturally hierarchical. The difficulty in dealing with the extremization conditions is so much involved that one has to look either for simplified ansatz by switching-off certain flux components at a time, or else one has to opt for an involved numerical analysis [13, 15, 17, 22–24].

Moreover, it is still not fully known how many and which type of fluxes can be simultaneously turned-on on a given background. In this regard, there are two main formulations of Bianchi identities which one utilizes for simplifying the type II effective potentials. One formulation involves fluxes denoted by the real six dimensional indices (e.g.  $H_{ijk}$  etc.) [6, 10] while in the latter one, all flux components are written out using cohomology indices of the complex threefold  $X_3$ ; e.g.  $H_K, \omega_{aK}$  etc., where  $K \in \{0, 1, \dots, h^{2,1}(X_3)\}$  and  $a \in \{1, 2, \dots, h^{1,1}(X_3)\}$  [10, 25–28]. The first formulation has been always utilized for simplifying the scalar potential of the toroidal examples [13, 15, 17, 22–24] while the recent interests beyond the toroidal setups have used the second formulation [11, 16, 20, 29, 30]. However, it turns out that the known versions of these two formulations of Bianchi identities do not produce an equivalent set of constraints. To the best of our knowledge, this mismatch has been observed/emphasized only in [10, 31, 32], which might play some important role in moduli stabilization and any subsequent phenomenological applications, e.g. such missing identities might be relevant in the recent interesting studies made in [11, 16, 20, 29, 30]. Therefore, it is worth as well as timely to bring the attention of the model builders on this aspect. On these lines we have the following plans.

- We carefully investigate the two formulations of the Bianchi identities in two concrete setups. This analysis is motivated by some observations made in [10, 31, 32], in which it has been found that the two formulations in their currently known version do not result in an equivalent set of flux constraints. The first formulation has all the second formulation identities along with some additional ones, which we call as ‘missing’ identities. In this article, we plan to investigate the (1, 1)- and the (2, 1)-cohomology structure in the missing identities in some detail.
- Unlike the type IIB studies made in [31, 32] along these motivations, we show that in type IIA orientifold setup it is easier to observe this mismatch for some simpler class of models. In particular, the ones in which orientifold

involution results in a trivial even (1,1)-cohomology. As we will explain later, this leads to the fact that we have just a single identity in the ‘second formulation’ while the ‘first formulation’ consists of five distinct classes of identities.

- Recently in [33], we have presented a symplectic formulation of the 4D type IIA scalar potential with non-geometric fluxes. Being very compact, this formulation creates the possibility of studying the model independent moduli stabilization, i.e. for an arbitrary number of Kähler- and complex structure- moduli. In this regard, knowing the generic form of the missing Bianchi identities is a crucial step to take.

The main strategy which we follow in our approach is such that first we extract the second formulation identities from the set of constraints which arise from translating the identities of the first formulation into cohomological form. We take this step in great detail for both of the explicit models. Subsequently we separate out one version of the ‘missing’ identities which are not the part of the second formulation. This is a tricky step because there are non-unique ways of reshuffling the set of missing Bianchi identities such that one could create more than one equivalent sets of constraints which apparently possess distinct cohomological structure, and therefore it is hard to club them into a particular form for claiming their generality. For that purpose one would need as many explicit examples as possible to check the mutual consistency for any generic guess.

However, it is not impossible to invoke some structure among the missing identities from the two concrete models. For example we show how the (1, 1)-cohomology structure in the missing Bianchi identities can be encoded in the triple intersection numbers of the complex threefold while the (2, 1)-cohomology structure has some insights from the complex structure moduli dependent prepotential. We compare these cohomology sectors for both the explicit examples to look for a model independent generalization which could produce them as particular cases, and this is what we mainly aim to achieve in this work.

The article is organized as follows: Firstly, in Sect. 2 we provide the relevant details on the two formulation of the Bianchi identities, and subsequently in Sect. 3 we perform a deep investigation of the Bianchi identities for the two concrete examples to illustrate that the two known formulations of Bianchi identities do not result in an equivalent set of flux constraints. In Sect. 4, we study the possibility of rewriting the missing identities in a model independent manner by investigating the (1, 1)- and the (2, 1)-cohomology sectors in the two explicit examples. Finally the important conclusions are presented in the Sect. 5 followed by three appendices. The first Appendix A provides a derivation of Bianchi identities in the second formulation. The Appendix B presents

**Table 1** Representation of various forms and their counting

Cohomology group	$H_+^{(1,1)}$	$H_-^{(1,1)}$	$H_+^{(2,2)}$	$H_-^{(2,2)}$	$H_+^{(3)}$	$H_-^{(3)}$
Dimension	$h_+^{1,1}$	$h_-^{1,1}$	$h_+^{1,1}$	$h_+^{1,1}$	$h^{2,1} + 1$	$h^{2,1} + 1$
Basis	$\mu_\alpha$	$\nu_a$	$\tilde{\nu}^a$	$\tilde{\mu}^\alpha$	$\alpha_I$	$\beta^J$

the relevant details about the two concrete setups while the Appendix C consists of the Bianchi identities which are too lengthy to be part of the main sections.

### 2 Two formulations of the Bianchi identities

In this work, we consider type IIA superstring theory compactified on an orientifold of a Calabi Yau (CY) threefold  $X_3$  with the presence of  $O6$ -planes. In this regard, the orientifold is constructed via modding out the CY with a discrete symmetry  $\mathcal{O}$  which includes the world-sheet parity  $\Omega_p$  combined with the space-time fermion number in the left-moving sector  $(-1)^{F_L}$ . In addition  $\mathcal{O}$  can act non-trivially on the CY manifold so that one has altogether,

$$\mathcal{O} = \Omega_p (-1)^{F_L} \sigma \tag{2.1}$$

where  $\sigma$  is an involutive symmetry (i.e.  $\sigma^2 = 1$ ) of the internal CY and acts trivially on the four flat dimensions. The massless states in the four dimensional effective theory are in one-to-one correspondence with various involutively even/odd harmonic forms, and hence do generate the equivariant cohomology groups  $H_\pm^{(p,q)}(X_3)$ . Subsequently, the various field ingredients can be expanded in appropriate bases of the equivariant cohomologies. To begin with, let us fix our conventions by considering the following representations for the various involutively even and odd harmonic forms [34] (Table 1).

Here  $\mu_\alpha$  and  $\nu_a$  denote the bases of even and odd real harmonic two-forms respectively, while  $\tilde{\mu}^\alpha$  and  $\tilde{\nu}^a$  denote the bases of odd and even four-forms. Further,  $\alpha_I$  and  $\beta^J$  form the bases of even and odd real three-forms. In addition, the zero form  $\mathbf{1}$  is even while there is an involutively odd six-form  $\Phi_6$ . Moreover, the triple intersection numbers and the normalization of the various forms are fixed as under,

$$\begin{aligned} \int_{X_3} \Phi_6 \equiv f = 1, \quad \int_{X_3} \nu_a \wedge \nu_b \wedge \nu_c &= \kappa_{abc}, \\ \int_{X_3} \nu_a \wedge \mu_\alpha \wedge \mu_\beta &= \hat{\kappa}_{\alpha\beta}, \\ \int_{X_3} \nu_a \wedge \tilde{\nu}^b \equiv d_a^b &= \delta_a^b, \quad \int_{X_3} \mu_\alpha \wedge \tilde{\mu}^\beta \equiv \hat{d}_\alpha^\beta = \delta_\alpha^\beta, \\ \int_{X_3} \alpha_I \wedge \beta^J &= \delta_I^J. \end{aligned} \tag{2.2}$$

Our above convention slightly differs from the normalizations considered in [10,31]. The effective four-dimensional supergravity theory is governed by the dynamics of the complexified chiral variables  $T^a$  and  $N^K$  which are defined as under,

$$\begin{aligned} \mathcal{J}_c &\equiv B_2 + i \mathcal{J} = b^a \nu_a + i t^a \nu_a = T^a \nu_a \\ \Omega_c &\equiv C_3 + 2i e^{-D} \text{Re}(\Omega_3) = \xi^K \\ \alpha_K + 2i e^{-D} \mathcal{X}^K \alpha_K &= 2 N^K \alpha_K, \end{aligned} \tag{2.3}$$

where the Kähler form  $\mathcal{J}$  is expanded as  $\mathcal{J} = t^a \nu_a$  where  $t^a$ 's are volume of the two-cycles, and the holomorphic three-form  $\Omega_3$  is expanded in terms of the period vectors  $(\mathcal{X}^K, \mathcal{F}_K)$  as  $\Omega_3 = \mathcal{X}^K \alpha_K - \mathcal{F}_K \beta^K$ . Further,  $B_2 = b^a \nu_a$  and  $C_3 = \xi^K \alpha_K$  respectively denote the NS-NS two-form potential and the RR three-form potential expanded in their respective odd/even bases, and  $D$  denotes the four-dimensional dilaton which is related to the ten-dimensional dilaton  $\phi$  via  $e^{-D} = e^{-\phi} \sqrt{\mathcal{V}}$  where  $\mathcal{V}$  is the volume of the complex threefold.

For studying moduli stabilization and any subsequent phenomenology, a very crucial step to follow is to impose the constraints from various NS-NS Bianchi identities as well as RR tadpoles to get the true non-vanishing contribution to the effective four dimensional scalar potential. We have two formulations for representing the (NS-NS) Bianchi identities, and we emphasize here that both sets of Bianchi identities have their own advantages and limitations. The ‘first formulation’ is in which all fluxes, moduli and fields are expressed using the real six-dimensional indices. e.g.  $B_{lm}, H_{lmn}, \omega_{lm}^n, Q_l^{mn}$  and  $R^{lmn}$  where  $l, m, n$  are indices corresponding to the real coordinates of the real sixfold. In the ‘second formulation’, all the fluxes, moduli and fields are counted by cohomology indices.

In the generic case, some naive counting suggests that there is an upper bound on the maximum number of flux components which can be non-trivial in a given setting, and they have to further satisfy several constraints arising from the orientifold action and the non-trivial Bianchi identities, and subsequently it is hard to present a model independent counting for the number of independent flux components. However, for the fluxes in both the formulations, we have presented the counting for the upper bound on the number of fluxes as mentioned in Table 2, where we have only assumed the anti-symmetry of the various flux components in the so-called ‘first formulation’. It is well anticipated that in a given orientifold construction, many of the flux components would be non-trivially coupled, and so would significantly reduce the number of ‘independent’ flux components. Also note that in our current conventions, the flux components  $H^K, R^K, \omega_a^K, Q^{aK}, \hat{\omega}_{\alpha K}$  and  $\hat{Q}^\alpha_K$  are projected out, and so they do not appear in the flux counting presented in Table 2. As said before, let us reiterate that this simple counting corresponds

**Table 2** Maximum number of flux components in the two formulations

Flux type	Max. number of flux components	Flux type	Max. number of flux components
$H_{ijk}$	20	$H_K$	$h^{2,1} + 1$
$\omega_{ij}{}^k$	90	$\omega_{aK}$	$h_{-}^{1,1} (h^{2,1} + 1)$
		$\hat{\omega}_{\alpha}{}^K$	$h_{+}^{1,1} (h^{2,1} + 1)$
$Q_i{}^{jk}$	90	$Q^a{}_K$	$h_{-}^{1,1} (h^{2,1} + 1)$
		$\hat{Q}^{\alpha K}$	$h_{+}^{1,1} (h^{2,1} + 1)$
$R^{ijk}$	20	$R_K$	$h^{2,1} + 1$
Total	220	Total	$2 (h^{1,1} + 1) (h^{2,1} + 1)$

**Table 3** Bianchi identities of the first formulation and their counting

Class	Bianchi Identities of the First formulation	Maximum no. of identities
(I)	$H_{m[ij} \omega_{kl]}{}^m = 0$	15
(II)	$\omega_{[ij}{}^m \omega_{k]m}{}^l = Q_{[l}{}^{lm} H_{jk]m}$	120
(III)	$H_{ijm} R^{mkl} + \omega_{ij}{}^m Q_m{}^{kl} = 4 Q_{[l}{}^{m[k} \omega_{j]m}{}^{l]}$	225
(IV)	$Q_m{}^{[ij} Q_{k]m}{}^l = \omega_{lm}{}^{[i} R^{jk]m}$	120
(V)	$R^{m[ij} Q_m{}^{kl]} = 0$	15
Extra constraint	$\frac{1}{6} H_{ijk} R^{ijk} + \frac{1}{2} \omega_{ij}{}^k Q_k{}^{ij} = 0$	1
Total		496

to an upper bound for the maximum number of the flux components which can be further significantly constrained by the Bianchi identities, and hence can influence the moduli stabilization and any subsequent phenomenology.

Further, let us note that it is not necessary to have a bijection among the two sets of fluxes mentioned in Table 2, especially among the respective set of  $\omega$ -flux and the non-geometric  $Q$ -flux. Nevertheless in several examples, the bijection between the respective set of fluxes in the two formulation does hold; e.g. the orientifold setups built from the orbifolds  $\mathbb{T}^6/\Gamma$ , where  $\Gamma$  corresponds to the crystallographic actions  $\mathbb{Z}_2 \times \mathbb{Z}_2, \mathbb{Z}_3, \mathbb{Z}_3 \times \mathbb{Z}_3, \mathbb{Z}_4$  and  $\mathbb{Z}_6$ -I [10,35–38]. However, there is always a bijection between the respective  $H$ -flux and  $R$ -flux components for which the ‘actual’ counting follows from the cohomology formulation.

### 2.1 First formulation

This formulation has five classes of Bianchi identities supplemented by an extra constraint as presented in Table 3. For our current interest, we consider the fluxes to be constant parameters, however for the non-constant fluxes and in the presence of sources, these Bianchi identities are modified [38–41]. In addition, let us also note that the ‘‘Extra

constraint’’ is automatically satisfied in the orientifold setting since there are no scalars which are invariant under the orbifolding and odd under the involution.

There have been several ways of deriving these sets of constraints; for example see [6, 8, 10, 38–42]. We do not intend to provide the detailed derivation, however let us sketch a couple of routes to arrive at these constraints. One way to derive these identities is via the Jacobi identities of the following Lie brackets for the NS-NS fluxes [6, 8, 10],

$$\begin{aligned}
 [Z_i, Z_j] &= \omega_{ij}{}^k Z_k - H_{ijk} X^k, \\
 [Z_i, X^j] &= Q_i{}^{jk} Z_k - \omega_{ik}{}^j X^k, \\
 [X^i, X^j] &= Q_k{}^{ij} X^k - R^{ijk} Z_k,
 \end{aligned}
 \tag{2.4}$$

where  $Z_i$  and  $X^i$ ’s are generators of the gauge transformations corresponding to the two gauge groups consisting of two sets of  $d$ -dimensional vectors obtained, from the metric and the  $B$ -field respectively, via the reduction of type II superstring theory on a  $d$ -dimensional torus.

Another route to derive these identities is via considering the nilpotency of a twisted differential operator  $\mathcal{D}$  defined as under [43],

$$\mathcal{D} = d + H \wedge . - \omega \lrcorner . + Q \triangleright . - R \bullet . ,
 \tag{2.5}$$

where the action of various (non-)geometric fluxes via  $\lrcorner, \triangleright$  and  $\bullet$  on a  $p$ -form changes them into a  $(p + 1)$ -form, a  $(p - 1)$ -form and a  $(p - 3)$ -form respectively. To be more specific, if we consider a generic  $p$ -form to be given as  $X_p = \frac{1}{p!} X_{i_1 \dots i_p} dx^1 \wedge \dots \wedge dx^p$ , then the various flux-actions can be defined as under [31, 43],

$$\begin{aligned}
 (\omega \lrcorner X)_{i_1 i_2 \dots i_{p+1}} &= \binom{p+1}{2} \omega_{[i_1 i_2}{}^j X_{j| i_3 \dots i_{p+1}}] \\
 &+ \frac{1}{2} \binom{p+1}{1} \omega_{[i_1}{}^j X_{i_2 i_3 \dots i_{p+1}}] , \\
 (Q \triangleright X)_{i_1 i_2 \dots i_{p-1}} &= \frac{1}{2} \binom{p-1}{1} Q_{[i_1}{}^{jk} X_{jk| i_2 \dots i_{p-1}}] \\
 &+ \frac{1}{2} \binom{p-1}{0} Q_j{}^{kj} X_{k| i_1 i_2 \dots i_{p-1}} , \\
 (R \bullet X)_{i_1 i_2 \dots i_{p-3}} &= \frac{1}{3!} \binom{p-3}{0} R^{jkl} X_{jkl| i_1 \dots i_{p-3}} ,
 \end{aligned}
 \tag{2.6}$$

where the underlined indices inside the brackets [...] are anti-symmetrized. The set of Bianchi identities and the ‘extra constraint’ given in Table 3 can be derived from the nilpotency of twisted differential operator  $\mathcal{D}$  via  $\mathcal{D}^2 A_p = 0$ .

As a side remark, let us note from the Table 3 that the maximum number of flux-constraints in the first formulation is bounded by 496 which is quite a peculiar number in string theory, and it would be interesting to know if there is

any fundamental reason behind this, or its just a matter of counting.

*A weaker set of identities*

Let us mention that demanding the vanishing of  $\mathcal{D}^2$  on a generic  $p$ -form  $X_p$  apparently also results in the following additional set of constraints [10],

$$\begin{aligned} H_{kl[\bar{i}} Q_{\bar{j}}^{kl} - \frac{1}{2} Q_k^{kl} H_{lij} - \frac{1}{2} \omega_{kl}^k \omega_{ij}^l &= 0, \\ H_{kli} R^{klj} - Q_i^{kl} \omega_{kl}^j - \omega_{kl}^k Q_i^{lj} - Q_k^{kl} \omega_{li}^j &= 0, \\ \omega_{kl}[\bar{i} R^{kl\bar{j}}] + \frac{1}{2} \omega_{kl}^k R^{lij} + \frac{1}{2} Q_k^{kl} Q_l^{ij} &= 0, \\ 2 H_{klm} R^{klm} + 3 \omega_{kl}^k Q_m^{ml} &= 0. \end{aligned} \tag{2.7}$$

However, a closer look ensures that all these identities in Eq. (2.7) can be obtained by contracting more indices from their respective main identities given in Table 3. It is worth to note that the last constraint in Eq. (2.7) generically holds by the orientifold construction itself as there are generically no zero-forms (scalars) which are odd under involution. Thus, these apparently additional identities are effectively not the new ones to worry about. Nevertheless, we will explain their relevance in a different sense while we compare the two formulations in explicit examples later on.

*Tracelessness condition*

In order for the  $\omega$ -flux and  $Q$ -flux to be individually  $T$ -dual to the  $H$ -flux, they must satisfy the following so-called tracelessness condition [7, 43],

$$\omega_{ij}^i = 0, \quad Q_i^{ij} = 0, \tag{2.8}$$

It might be worth to mention that imposing this condition (2.8) has been quite common in the literature [7, 43]. Also, a Calabi Yau threefold does not have any homologically non-trivial one- as well as five-cycles, and hence for the Calabi Yau orientifold cases it would be well justified to demand that all flux components having effectively one (real six-dimensional) free-index are trivial.

2.2 Second formulation

Considering the relevant flux actions for the type IIA orientifold setup as given in Eq. (A.1), and ensuring the nilpotency of the twisted differential  $\mathcal{D}$  on the harmonic forms via  $\mathcal{D}^2 = 0$  results in 10 Bianchi identities [31] which can be further classified into the five classes as mentioned in the first formulation. These identities are collected in Table 4, and a proof of the same has also been presented in the Appendix A.

Before coming to the specific models, let us mention that if one uses an orientifold involution such that the even (1,1)-cohomology and its dual odd (2,2)-cohomology are trivial,

**Table 4** Bianchi identities of the second formulation and their counting

Class	Bianchi Identities of the Second formulation	Maximum no. of identities
(I)	$H_K \hat{\omega}_\alpha^K = 0$	$h_+^{1,1}$
(II)	$H_K \hat{Q}^{\alpha K} = 0$ $\omega_{aK} \hat{\omega}_\alpha^K = 0$	$h_+^{1,1}$ $h_+^{1,1} h_-^{1,1}$
(III)	$\omega_{aK} \hat{Q}^{\alpha K} = 0$ $\hat{\omega}_\alpha^K Q^a_K = 0$ $\hat{\omega}_\alpha^{[K} \hat{Q}^{\alpha J]} = 0$ $H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}$	$h_+^{1,1} h_-^{1,1}$ $h_+^{1,1} h_-^{1,1}$ $\frac{1}{2} h^{2,1} (h^{2,1} + 1)$ $\frac{1}{2} h^{2,1} (h^{2,1} + 1)$
(IV)	$R_K \hat{\omega}_\alpha^K = 0$ $Q^a_K \hat{Q}^{\alpha K} = 0$	$h_+^{1,1}$ $h_+^{1,1} h_-^{1,1}$
(V)	$R_K \hat{Q}^{\alpha K} = 0$	$h_+^{1,1}$
	If $h_+^{1,1} \neq 0$ ,	Total = $4 h_+^{1,1} (1 + h_-^{1,1}) + h^{2,1} (1 + h^{2,1})$
	If $h_+^{1,1} = 0$ ,	Total = $\frac{1}{2} h^{2,1} (h^{2,1} + 1)$

i.e.  $h_+^{1,1} (X_3/\sigma) = 0$ , then all the ‘hatted’ fluxes which are counted via  $\alpha \in h_+^{1,1}$  are projected out. The choice of such involutions are quite common in Type IIA Calabi Yau orientifold compactification as these are simpler setups to study, and subsequently the second formulation tells us that the only Bianchi identities which could be non-trivial turns out to be the following one,

$$H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}. \tag{2.9}$$

This happens because all the other identities involve ‘hatted’ fluxes which are projected out. Such a situation provides a strong constraint on the set of second formulation identities as it suggests that all the Bianchi identities of the class (I), (II), (IV) and (V) are identically trivial ! Moreover, even only one of the four Identities within the class (III) is non-trivial. However, as we will see in the two explicit models, the identities in class (I), (II), (IV) and (V) indeed provide non-trivial flux constraints while being computed from the first formulation. This has been possible to check in the concrete toroidal models in which both formulations can be explicitly computed. We will exemplify these arguments in two concrete models:

- **Model A:** In this setup we will consider the orientifold of a  $\mathbb{T}^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$  orbifold, with an anti-holomorphic involution which results in  $h_+^{1,1} (X_3/\sigma) = 0$ , and hence no ‘hatted’ fluxes being present in this construction.
- **Model B:** In this setup we will consider the orientifold of a  $\mathbb{T}^6/\mathbb{Z}_4$  orbifold, with an anti-holomorphic involution which results in  $h_+^{1,1} (X_3/\sigma) \neq 0$ , and hence there



would be non-trivial ‘hatted’ fluxes being present in this construction.

From the Table 4 we see that given the topological data about the orientifold, the maximum number of the (non-trivial) Bianchi identities in the second formulation can be read-off in terms of some Hodge numbers. To summarize this part, we have five classes of Bianchi identities in the first formulation while the second formulation has in total 10 distinct types of constraints. However, all the identities are coupled in a complex manner and generically it is hard to find the set of inequivalent flux constraints. The maximum number of such constraints is bounded by 496 in the first formulation while in the second formulation this number is bounded by  $4h_+^{1,1}(1+h_-^{1,1})+h^{2,1}(1+h^{2,1})$ . However, there is generically no bijection between the set of constraints because there is no bijection at first place between the respective  $\omega$ -flux and the  $Q$  flux representations in the two formulations.

It has been observed in [10,31,32] that these two formulations of Bianchi identities do not lead to equivalent set of constraints. In fact, the first formulation has some additional constraints which cannot be derived from the identities of the second formulation. As most of the non-geometric scalar potential studies are motivated from toroidal examples, such an observation is worth to explore more insights of this mismatch. To be specific in this regard, let us mention that the mismatch in the two formulations of Bianchi identities have been observed for type IIA case in [10], however without having much attention on the insights of the mismatch, for example so that one could promote the same to the case of beyond toroidal setups such as those using CY orientifold. Moreover, motivated by the interesting type IIB model building efforts as made in [11,16,20,29,30] which have used the second formulation identities only, if one attempts to make similar efforts for type IIA model building, then it is very much anticipated that such models and any subsequently realized vacua should be heavily under-constrained as most of the Bianchi identities would not be captured in the second formulation. Such a clear manifestation of the mismatch between the Bianchi identities of the two formulations, which we see from the type IIA setup, cannot be observed from type IIB setups, and our aim in this article is to investigate more on this and invoke the possible structure which could be generalised in a model independent manner to some more generic (beyond-toroidal) setups.

### 3 Bianchi identities in the cohomology formulation

In this section we will compute the Bianchi identities for two toroidal models using the two formulations we have described, and subsequently we will compare if the set of Bianchi identities are equivalent or not. The main idea is

to translate the first formulation identities into cohomology version using some flux conversion relations for the two formulations, and subsequently to perform some reshuffling in the first formulation constraints to recover the second formulation, and then the rest is what we term as the ‘missing identities’ which cannot be obtained from the known version of the second formulation, i.e. from the Table 4. However, let us mention at the outset that we will provide more than one equivalent set of the ‘missing’ constraints as there are non-unique ways of rewriting or clubbing the identities for invoking some model independent insights out of a complicated collection of flux-squared relations.

#### 3.1 Missing identities in Model A

In this section we will compute the Bianchi identities using the two formulations for our Model A, which corresponds to a type IIA setup with a  $\mathbb{T}^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$ -orientifold. The various explicit details about this model can be found in [33], and the relevant ingredients have been also briefly collected in the Appendix B. For this setup, focussing only on the untwisted sector, we have  $h_+^{1,1} = 0$ ,  $h_-^{1,1} = 3$  and  $h^{2,1} = 3$ , and therefore there are six second-formulation identities which are to be imposed on 32 flux components. For translating the first formulation identities into the cohomology form, we will need the following flux conversion relations,

$$\begin{aligned}
 H_K &= [-H_{135}, H_{146}, H_{236}, H_{245}], \\
 \omega_{aK} &= \begin{bmatrix} -\omega_{35}^2, & \omega_{46}^2, & -\omega_{36}^1, & -\omega_{45}^1 \\ -\omega_{51}^4, & -\omega_{61}^3, & \omega_{62}^4, & -\omega_{52}^3 \\ -\omega_{13}^6, & -\omega_{14}^5, & -\omega_{23}^5, & \omega_{24}^6 \end{bmatrix}, \\
 Q_K^a &= \begin{bmatrix} -Q_1^{46}, & Q_1^{35}, & -Q_2^{45}, & -Q_2^{36} \\ -Q_3^{62}, & -Q_4^{52}, & Q_3^{51}, & -Q_4^{61} \\ -Q_5^{24}, & -Q_6^{23}, & -Q_6^{14}, & Q_5^{13} \end{bmatrix}, \\
 R_K &= [-R^{246}, R^{235}, R^{145}, R^{136}].
 \end{aligned}
 \tag{3.1}$$

Let us restate that the fluxes appearing with three indices always correspond to the first formulation, i.e. the non-cohomology case. Moreover, as all the indices are denoted by numbers, in order to avoid any possible confusion let us also mention that the flux components in the second formulation are given with the ‘ordering’ as per denoted in  $\{\omega_{aK}, Q^a_K\}$  where the first index ‘a’ is counted by  $h_-^{1,1}$  while the second index ‘K’ is counted by  $(1+h^{2,1})$ . In this example, we have  $a = \{1, 2, 3\}$  and  $K = \{0, 1, 2, 3\}$ . As we see from the Eq. (3.1), there are no flux components present which are of the type  $\omega_{ij}^i$  and  $Q_i^{ij}$ , and so the tracelessness conditions given in Eq. (2.8) are automatically satisfied after imposing the full orientifold requirements. In addition, the normalization of the various forms is appropriately fixed as mentioned in Eq. (2.2).

Second formulation

In this setup we have  $h_+^{1,1}(X_3/\sigma) = 0$ , and so no ‘hatted’ fluxes counted by  $\alpha$  indices are present, and subsequently the ten identities mentioned in Table 4 produce only one class of non-trivial constraints given as under,

$$H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}. \tag{3.2}$$

This subsequently results in six identities as  $a \in \{1, 2, 3\}$  and  $J, K \in \{0, 1, 2, 3\}$ . It is clear that the  $(HQ + \omega^2)$ -type and  $(R\omega + Q^2)$ -type identities, which would be obtained via translating the first formulation later on, cannot be obtained from the second formulation. This is one of the main message we want to convey and so it is worth emphasising.

Cohomology version of the first formulation

Now the plan is to compute the five classes of Bianchi identities of the first formulation using Table 3 and subsequently to translate the same into cohomology form via using the conversion relations in Eq. (3.1). First we note that we have  $H_{ijk} R^{ijk} = 0 = \omega_{jk}^i Q_i^{jk}$ , and therefore the ‘extra constraint’ of Table 3 is trivially satisfied. This is well anticipated by the choice of the orientifold action itself which in the present setup also guarantees the so-called tracelessness conditions for the fluxes denotes as  $\omega_{ij}^i = 0 = Q_i^{ij}$ . Further, it turns out that the Bianchi identities in the class (I) and class (V) of the first formulation as presented in Table 3, are trivially satisfied. Moreover, the remaining three classes of identities result in a total of 48 flux constraints in which  $(HQ + \omega^2)$ -type and  $(R\omega + Q^2)$ -type have 12 constraints each while the remaining 24 constraints correspond to  $(HR + \omega Q)$ -type. Using the conversion relations, these identities can be classified as we discuss below.

**(II).  $(HQ + \omega\omega)$  -type :** This identity results in 12 flux constraints which are explicitly given in the Eq. (C.1) of the Appendix C. All these 12 identities can be equivalently expressed in terms of two simple relations given as under

$$\begin{aligned} H_{(\underline{i} Q^a_{\underline{0}})} &= \omega_{b(\underline{i} \omega_{c\underline{0}})}, \quad a \neq b \neq c \ \& \ i \neq a, \\ H_{(\underline{i} Q^a_{\underline{j}})} &= \omega_{b(\underline{i} \omega_{c\underline{j}})}, \quad a \neq b \neq c \ \& \ i \neq a = j, \end{aligned} \tag{3.3}$$

where the bracket (..) denotes the symmetrization of the underlined indices, and we have  $\{a, b, c\} \in \{1, 2, 3\}$  and  $\{i, j\} \in \{1, 2, 3\}$ . Now let us take a note on the presence of  $a \neq b \neq c$  in the above identity along with the existence of the only non-trivial triple-intersection number being  $\kappa_{123} = 1$  for this setup. This can be considered as indicative of some insight in the (1, 1)-cohomology sector. The same

leads to the observation that the above identities can be also expressed by using the intersection number as under,

$$\begin{aligned} H_{(\underline{i} Q^a_{\underline{0}})} &= \frac{1}{2} \kappa_{abc}^{-1} \omega_{b(\underline{i} \omega_{c\underline{0}})}, \quad i \neq a, \\ H_{(\underline{i} Q^a_{\underline{j}})} &= \frac{1}{2} \kappa_{abc}^{-1} \omega_{b(\underline{i} \omega_{c\underline{j}})}, \quad i \neq j = a, \end{aligned} \tag{3.4}$$

where we have defined  $\kappa_{abc}^{-1} = 1/\kappa_{abc}$  for the all the fixed values of  $a, b$  and  $c$ , whenever  $\kappa_{abc}$  is non-zero.

**(III).  $(HR + \omega Q)$ -type :** This identity results in a total of 24 flux constraints which are explicitly given the Eq. (C.2) of the Appendix C. However after some reshuffling, we realize that this number can be effectively reduced to 18 constraints, and the same can be collected in the following compact form,

- (i).  $H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}, \forall I, J \in \{0, 1, 2, 3\}$ ,
- (ii).  $H_{(\underline{i} R_{\underline{0}})} = \omega_{a'(\underline{i} Q^{a'}_{\underline{0}})}, i = a', \quad a'$  is not summed,
- (iii).  $H_{(\underline{i} R_{\underline{j}})} = \omega_{a'(\underline{i} Q^{a'}_{\underline{j}})},$   
 $i \neq j \neq a', \quad a'$  is not summed,
- (iv).  $\omega_{a'(\underline{i} Q^{a'}_{\underline{0}})} = \omega_{b'(\underline{i} Q^{b'}_{\underline{0}})},$   
 $a' \neq b' \neq i, \quad a', b'$  are not summed,
- (v).  $\omega_{a'(\underline{i} Q^{a'}_{\underline{j}})} = \omega_{b'(\underline{i} Q^{b'}_{\underline{j}})}, \quad a'=i, j = b', i \neq j,$   
 $a', b'$  are not summed, (3.5)

where the bracket (..) is used to present the symmetrization of the underlined indices while the bracket [..] is used for anti-symmetrization of two indices, and the primed indices  $a'$  and  $b'$  are not summed over. In this collection (3.5), the first identity precisely corresponds to the six identities of the second formulation given in Eq. (3.2) while the remaining 12 identities cannot be derived from the known version of the second formulation. Also there are non-unique ways of reshuffling the set of missing identities, and it is hard to guess any (1, 1)-cohomology sector insights in terms of intersection number  $\kappa_{abc}$  as we have seen in the previous case. However after making some back and forth checks on the compatibility of this model with the model B (to be discussed later on), we propose the following version of the 12 missing identities in Eq. (3.5),

$$\begin{aligned} H_{(\underline{0} R_{\underline{k}})} - \omega_{a(\underline{0} Q^a_{\underline{k}})} \delta_{ak} &= 0, \quad \forall k; H_{(\underline{0} R_{\underline{k}})} \\ -\omega_{a(\underline{0} Q^a_{\underline{k}})} + 2\omega_{a(\underline{0} Q^a_{\underline{j}})} \delta_{aj} &= 0, \quad j \neq k; \\ H_{(\underline{j} R_{\underline{k}})} - \omega_{a(\underline{j} Q^a_{\underline{k}})} + 2\omega_{a(\underline{j} Q^a_{\underline{k}})} \delta_{aj} &= 0, \quad j \neq k; \\ H_{(\underline{j} R_{\underline{k}})} - \omega_{a(\underline{j} Q^a_{\underline{k}})} \delta_{ai} &= 0, \quad i \neq j \neq k. \end{aligned} \tag{3.6}$$

**(IV).  $(R\omega + QQ)$ -type :** This identity results in 12 flux constraints which are explicitly given the Eq. (C.5) of the Appendix C. All these 12 identities can be equivalently expressed in terms of two simple relations given as under

$$\begin{aligned} R_{(\underline{i} \omega_{a0})} &= Q^c_{(\underline{i} Q^b_{0})}, \quad a \neq b \neq c \ \& \ i \neq a; \\ R_{(\underline{i} \omega_{aj})} &= Q^c_{(\underline{i} Q^b_{j})}, \quad a \neq b \neq c \ \& \ i \neq a = j, \end{aligned} \quad (3.7)$$

where the bracket (..) denotes the symmetrization of the underlined indices, and we have  $\{a, b, c\} \in \{1, 2, 3\}$  and  $\{i, j\} \in \{1, 2, 3\}$ . Now let us again note that the presence of  $a \neq b \neq c$  in the above identity and existence of the only non-trivial triple-intersection numbers being  $\kappa_{abc} = 1$  for this setup can be considered as indicative of some insight as one can rewrite the same as under,

$$\begin{aligned} R_{(\underline{i} \omega_{a0})} &= \frac{1}{2} \kappa_{abc} Q^b_{(\underline{i} Q^c_{0})}, \quad i \neq a; \\ R_{(\underline{i} \omega_{aj})} &= \frac{1}{2} \kappa_{abc} Q^b_{(\underline{i} Q^c_{j})}, \quad i \neq j = a. \end{aligned} \quad (3.8)$$

This analysis and the subsequent observations in Model A suggest that it might be possible that the missing identities could be generically determined from the topological numbers such as Hodge number and the intersection numbers of the complex threefold background. This has been our central aim to achieve.

### 3.2 Missing identities in Model B

In this section we will compute the Bianchi identities using the two formulations for our Model B, which corresponds to a type IIA setup with a  $\mathbb{T}^6/\mathbb{Z}_4$ -orientifold. Considering the untwisted sector, in this model we have  $h_+^{1,1} = 1$ ,  $h_-^{1,1} = 4$  and  $h^{2,1} = 1$  which results in 22 second formulation identities for a total number of 24 flux components.

Using the orbifold of  $\mathbb{T}^6/\mathbb{Z}_4$  sixfold we consider *two explicit constructions* which differ in the choice of complexified coordinate of the  $\mathbb{T}^6$  torus and their three-form bases. Despite these differences, as the global topological quantities in the untwisted sector such as the Hodge numbers and the triple intersection numbers are the same in these two constructions, so we naively expected some correlation of their respective sets of Bianchi identities in the cohomology formulations, and hence also among the missing Bianchi identities. This indeed turns out to be the case as we will elaborate in this section. We call these two constructions as Model B1 and Model B2 with the following details,

- **Model B1:** This construction was used for studying moduli stabilization using standard fluxes and without including any non-geometric fluxes [9]. We have explicitly computed all the (non-)geometric flux components allowed in this setup, and the relevant details about the setup is presented in the Appendix B. However, let us present here the following flux conversion relations which we use for translating the first formulation identities to capture the missing identities,

$$\begin{aligned} H_K &= [H_{136}, -H_{135}], \\ \omega_{aK} &= \begin{bmatrix} \omega_{46}^1, & -\omega_{35}^1 \\ \omega_{62}^3, & -\omega_{51}^3 \\ -\omega_{13}^5, & -\omega_{13}^6 \\ \frac{1}{2}(\omega_{26}^1 + \omega_{36}^3), & -\frac{1}{2}(\omega_{15}^1 - \omega_{45}^3) \end{bmatrix}, \\ \hat{\omega}_\alpha^K &= [\frac{1}{2}(\omega_{15}^1 + \omega_{45}^3), -\frac{1}{2}(\omega_{26}^1 - \omega_{36}^3)], \\ Q^a_K &= \begin{bmatrix} Q_1^{35}, & -Q_1^{36} \\ Q_3^{51}, & -Q_3^{61} \\ -Q_6^{13}, & Q_5^{13} \\ \frac{1}{2}(Q_2^{51} - Q_3^{35}), & -\frac{1}{2}(Q_1^{16} - Q_3^{46}) \end{bmatrix}, \\ \hat{Q}^{\alpha K} &= [\frac{1}{2}(Q_1^{16} + Q_3^{46}), -\frac{1}{2}(Q_2^{51} + Q_3^{35})], \\ R_K &= [R^{135}, R^{136}]. \end{aligned} \quad (3.9)$$

- **Model B2:** The second construction uses a different set of complexified coordinates  $z^i$  on the  $\mathbb{T}^6$  torus and also a different set of even/odd three-form bases. This construction was previously used for studying the supersymmetric moduli stabilization in [10] and for a symplectic version of the scalar potential in [33]. The relevant details about the setup is briefly presented in the Appendix B. However, here we present the following flux conversion relations which we use for translating the first formulation identities to capture the missing identities,



$$\begin{aligned}
 H_K &= [H_{135} - H_{136}, -H_{136}], \\
 \omega_{\alpha K} &= \begin{bmatrix} \omega_{36}^1, & -\omega_{46}^1 \\ \omega_{61}^3, & -\omega_{62}^3 \\ \omega_{13}^5 + \omega_{13}^6, & \omega_{13}^5 \\ \frac{1}{2}(\omega_{16}^1 - \omega_{26}^1 - \omega_{36}^3 - \omega_{46}^3), & \frac{1}{2}(-\omega_{16}^1 - \omega_{26}^1 - \omega_{36}^3 + \omega_{46}^3) \end{bmatrix}, \\
 \hat{\omega}_\alpha^K &= [\frac{1}{2}(\omega_{16}^1 - \omega_{26}^1 + \omega_{36}^3 + \omega_{46}^3), \frac{1}{2}(\omega_{16}^1 + \omega_{26}^1 - \omega_{36}^3 + \omega_{46}^3)], \\
 Q^{\alpha K} &= \begin{bmatrix} -Q_1^{35}, & -Q_1^{35} - Q_1^{36} \\ -Q_3^{51}, & -Q_3^{51} - Q_3^{61} \\ -Q_5^{13} + Q_6^{13}, & Q_6^{13} \\ -\frac{1}{2}(Q_1^{15} + Q_2^{51} - Q_3^{35} + Q_4^{53}), & \frac{1}{2}(Q_1^{15} - Q_2^{51} + Q_3^{35} + Q_4^{53}) \end{bmatrix}, \\
 \hat{Q}^{\alpha K} &= [\frac{1}{2}(-Q_1^{15} - Q_2^{51} - Q_3^{35} + Q_4^{53}), \frac{1}{2}(-Q_1^{15} + Q_2^{51} + Q_3^{35} + Q_4^{53})], \\
 R_K &= [-R^{135} - R^{136}, -R^{135}]. \tag{3.10}
 \end{aligned}$$

Unlike the conventions used in [33], here we fix our six-form to be integrated to unity over the Calabi Yau, and the four-forms being dual to the respective two-forms as mentioned in Eq. (2.2). This helps in avoiding many normalization factors which otherwise would appear in the Bianchi identities and make them look more complicated, and hence more difficult to reshuffle and capture the missing identities. The main motivation for considering the two models B1 and B2 which qualitatively look similar has been the fact that as they have different three-form bases, there are different intersection numbers on the mirror threefold, which facilitates some more freedom to make an educated guess for the (2, 1)-cohomology sector of the Bianchi identities.

Considering all the non-zero flux components (for Model B1 and Model B2) as given in Eqs. (B.19) and (B.27), it is evident that the generic tracelessness conditions (involving the summing over indices) as given in Eq. (2.8) are automatically satisfied. However, from the flux conversion relations given in Eqs. (3.9) and (3.10), one can observe a couple of non-zero flux components of the form  $\omega_{i'j'}^{i'}$  or  $Q_{i'j'}^{i'}$ , where  $i'$  is not summed over, being still allowed by the orientifold projection. This may create a curiosity/suspicion that may be after imposing the condition to make such flux components vanish, the mismatch goes away. To prove that it is not the case, one may consider our Model A itself in which the tracelessness condition (2.8) is automatically satisfied along with having no flux components with a single free-index being allowed. For Model B also, we will show that even after imposing such a condition, the ‘mismatch’ between the two formulations does not go away. After imposing that each of the flux components with single free index vanish, we find the following identifications that hold for both of the models B1 and B2,

$$\begin{aligned}
 \omega_{40} &= -\hat{\omega}_1^1, & \omega_{41} &= \hat{\omega}_1^0, \\
 Q^4_0 &= -\hat{Q}^{11}, & Q^4_1 &= \hat{Q}^{10}. \tag{3.11}
 \end{aligned}$$

Thus we find that by imposing this conditions in Eq. (3.11), the effective flux components for  $\omega$ -flux as well as for the  $Q$ -flux get reduced from 10 to 8 in both the (cohomology and the non-cohomology) formulations, and hence the bijection between the respective flux counting in the two formulation remains intact.

*Second formulation*

Unlike the previous model A, this setup has  $h_+^{1,1}(X_3/\sigma) = 1$ , and so the ‘hatted’ fluxes counted by  $\alpha$  indices are non-trivial. Subsequently, none of the second formulation identities mentioned in Table 4 are identically trivial. Therefore, one might expect that this model would help us getting more insights of the Bianchi identities and the mismatch. The ten identities mentioned in Table 4 produce 22 non-trivial constraints for the second formulation. All these constraints and their number can be explicitly read-off from the Table 4 by considering  $\alpha = 1, a \in \{1, 2, 3, 4\}, K \in \{0, 1\}$  and the topological data given in Eq. (B.13). The explicit form of all these 22 second formulation constraints are listed in Eqs. (3.12) and in Eq. (C.7), (C.10) and (C.13) of the Appendix C.

*Cohomology version of the first formulation*

Now we will compute the first formulation Bianchi identities given in Table 3 and subsequently we will translate them into the cohomology formulation using the conversion relations given in Eq. (3.9) for Model B1, and in Eq. (3.10) for Model B2. Performing a similar analysis to what has been done for the Model A, we find that  $H_{ijk}R^{ijk} = 0 = \omega_{jk}^i Q_i^{jk}$ , and therefore the ‘extra constraint’ of Table 3 is trivially satisfied. As argued before, this should always be so due to the orientifold projection. Further, the first and the last Bianchi identities of the first formulation which corresponds to the class (I) and class (V) do not have any mismatch, although

unlike the previous case in Model A, now these identities are generically non-trivial, and are explicitly given as,

$$H_0 \hat{\omega}_1^0 + H_1 \hat{\omega}_1^1 = 0, \quad R_0 \hat{Q}^{10} + R_1 \hat{Q}^{11} = 0. \quad (3.12)$$

These are precisely the second formulation identities  $H_K \hat{\omega}_\alpha^K = 0 = R_K \hat{Q}^{\alpha K}$  where  $\alpha = 1$  and  $K = \{0, 1\}$ . The mismatch in the two formulation lies only in the class (II), (III) and (IV). The explicit forms of all the identities belonging to these three classes are collected in the Appendix C. Let us also mention that in each of the class (II), (III) and (IV) we do recover all the Bianchi identities of the second formulation, which are explicitly presented in Eqs. (C.7), (C.10) and (C.13).

(II).  $(HQ + \omega\omega)$ -type:

A simple conversion of all the identities of this type using the expressions in Table 3 results in 16 identities after making some tedious reshuffling of the constraints. Subsequently we find that 5 of the 16 constraints are exactly the ones which belong to the second formulation and their explicit form is given in Eq. (C.7). In addition, there are 11 constraints collected in Eqs. (C.8) and (C.9) in the Appendix C which cannot be derived from the second formulation. Moreover, imposing the condition in Eq. (3.11) further reduces the number of missing identities to 10, which can be expressed in the following manner,

$$\begin{aligned} \text{Model B1 \& B2: } H_{(\underline{I} Q^a \underline{J})} &= \frac{1}{2} \kappa_{abc}^{-1} \omega_b (\underline{I} \omega_c \underline{J}), \\ &\text{for } a \in \{1, 2, 4\} \text{ and } \forall I, J; \\ \text{Model B1: } H_{(\underline{I} Q^a \underline{0})} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b (\underline{I} \omega_c \underline{0}) \\ &- \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha (\underline{I} \hat{\omega}_\beta^0) = 0, \quad \text{for } a = 3; \\ \text{Model B2: } H_{(\underline{0} Q^a \underline{0})} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b (\underline{0} \omega_c \underline{0}) \\ &- \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha (\underline{0} \hat{\omega}_\beta^0) \\ &= H_{(\underline{I} Q^a \underline{1})} \\ &- \frac{1}{2} \kappa_{abc}^{-1} \omega_b (\underline{I} \omega_c \underline{1}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha (\underline{I} \hat{\omega}_\beta^1), \quad \text{for } a = 3. \end{aligned} \quad (3.13)$$

Here as before, the underlined indices within (..) are symmetrized, and we have considered  $\kappa_{abc}^{-1} = 1/\kappa_{abc}$  and  $\hat{\kappa}_{\alpha\beta}^{-1} = 1/\hat{\kappa}_{\alpha\beta}$  for fixed values of  $\{a, b, c\}$  and  $\{\alpha, \beta\}$ , and whenever these intersections are non-zero. These topological numbers are given in Eq. (B.13).

(III).  $(HR + \omega Q)$ -type:

This constitutes the most complicated part of the Bianchi identities, and a simple conversion of all the identities of

this type using the expressions in Table 3 results in many complicated constraints heavily mixing all the four NS-NS fluxes, and a priori it does not reflect that one would precisely recover all the identities of the second formulation. However some rigorous reshuffling of various flux constraints results in 26 identities which indeed includes all the 10 identities of the second formulation as collected in Eq. (C.10) of the Appendix C. Further, the remaining 16 missing Bianchi identities are collected in Eqs. (C.11) and (C.12) of the Appendix C. These are the ones which cannot be derived from the second formulation. Moreover, imposing the condition in Eq. (3.11) further reduces the number of missing identities into 13, which can be expressed in the following manner,

$$\begin{aligned} \text{Model B1 \& B2: } H_{(\underline{I} R \underline{J})} &= \omega_3 (\underline{I} Q^3 \underline{J}), \quad \forall \{I, J\}; \\ \kappa_{3ac} Q^c (\underline{I} \omega_b \underline{J}) &= \kappa_{3bc} Q^c (\underline{I} \omega_a \underline{J}), \\ &\forall a, b \in \{1, 2, 4\}, \quad \forall \{I, J\}; \\ \text{Model B1: } 3 H_{(\underline{0} R \underline{1})} - \omega_{a(\underline{0} Q^a \underline{1})} - \hat{\omega}_\alpha (\underline{0} \hat{Q}^{\alpha 1}) &= 0; \\ \text{Model B2: } 3 H_0 R_0 - \omega_{a0} Q^a \underline{0} - \hat{\omega}_\alpha (\underline{0} \hat{Q}^{\alpha 0}) \\ &- H_1 R_1 + \omega_{a1} Q^a \underline{1} + \hat{\omega}_\alpha (\underline{1} \hat{Q}^{\alpha 1}) = 0. \end{aligned} \quad (3.14)$$

(IV).  $(R\omega + QQ)$ -type:

A simple conversion of all the identities of this type using the expressions in Table 3 results in 16 constraints after making some tedious reshuffling of pieces. Subsequently we find that 5 of the 16 constraints are exactly the ones which belong to the second formulation and their explicit form is given in Eq. (C.13). In addition, there are 11 constraints collected in Eqs. (C.14) and (C.15) in the Appendix C which cannot be derived from the second formulation. Moreover, imposing the condition in Eq. (3.11) further reduces the number of missing identities to 10, which can be expressed in the following manner,

$$\begin{aligned} \text{Model B1 \& B2: } R_{(\underline{I} \omega_a \underline{J})} &= \frac{1}{2} \kappa_{abc} Q^b (\underline{I} Q^c \underline{J}), \\ &\text{for } a \in \{1, 2, 4\} \text{ and } \forall I, J, \\ \text{Model B1: } R_{(\underline{I} \omega_a \underline{0})} - \frac{1}{2} \kappa_{abc} Q^b (\underline{I} Q^c \underline{0}) \\ &- \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha (\underline{I} \hat{Q}^\beta \underline{0}) = 0, \quad \text{for } a = 3, \\ \text{Model B2: } R_{(\underline{0} \omega_a \underline{0})} - \frac{1}{2} \kappa_{abc} Q^b (\underline{0} Q^c \underline{0}) \\ &- \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha (\underline{0} \hat{Q}^\beta \underline{0}) \\ &= R_{(\underline{I} \omega_b \underline{1})} - \frac{1}{2} \kappa_{abc} Q^b (\underline{I} Q^c \underline{1}) \\ &- \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha (\underline{I} \hat{Q}^\beta \underline{1}), \text{ for } a = 3. \end{aligned} \quad (3.15)$$

### 4 On generic structure of the missing identities

In the previous section we have presented some educated guess for the cohomology structure in the Kähler moduli space, i.e. in the (1, 1)-cohomology sector via intersection numbers  $\kappa_{abc}$  and  $\hat{\kappa}_{\alpha\beta}$ . Now we plan to investigate the (2, 1)-cohomology structure on the side of the complex structure moduli space, via looking at the intersection numbers on the mirror threefold.

#### 4.1 Insights for the (1, 1)-cohomology sector

First we collect the results regarding the (1, 1)-cohomology sector by presenting all the missing identities at one place which are given as under,

*Model A*

$$\begin{aligned}
 \text{(II)} : H_{(\underline{i}} Q^a_{\underline{j})}) &= \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{i} \omega_c \underline{j}), & i \neq a; \\
 H_{(\underline{i}} Q^a_{\underline{j})}) &= \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{i} \omega_c \underline{j}), & i \neq j = a; \\
 \text{(III)} : H_{(\underline{0}} R_k) - \omega_a(\underline{0} Q^a_k) \delta_{ak} &= 0, & \forall k; \\
 H_{(\underline{0}} R_k) - \omega_a(\underline{0} Q^a_k) + 2 \omega_a(\underline{0} Q^a_j) \delta_{aj} &= 0, & j \neq k; \\
 H_{(\underline{j}} R_k) - \omega_a(\underline{j} Q^a_k) + 2 \omega_a(\underline{j} Q^a_k) \delta_{aj} &= 0, & j \neq k; \\
 H_{(\underline{j}} R_k) - \omega_a(\underline{j} Q^a_k) \delta_{ai} &= 0, & i \neq j \neq k; \\
 \text{(IV)} : R_{(\underline{i}} \omega_{a \underline{j})}) &= \frac{1}{2} \kappa_{abc} Q^b(\underline{i} Q^c \underline{j}), & i \neq a; \\
 R_{(\underline{i}} \omega_{a \underline{j})}) &= \frac{1}{2} \kappa_{abc} Q^b(\underline{i} Q^c \underline{j}), & i \neq j = a. \tag{4.1}
 \end{aligned}$$

*Model B*

$$\begin{aligned}
 \text{(II)} : H_{(\underline{I}} Q^a_{\underline{J}})} &= \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{I} \omega_c \underline{J}), \\
 &\text{for } a \in \{1, 2, 4\} \text{ and } \forall I, J, \\
 \text{Model B1} : H_{(\underline{1}} Q^a_{\underline{0}})} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{1} \omega_c \underline{0}) & \\
 - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{1} \hat{\omega}_\beta \underline{0}) &= 0, \quad \text{for } a = 3, \\
 \text{Model B2} : H_{(\underline{0}} Q^a_{\underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{0} \omega_c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{0} \hat{\omega}_\beta \underline{0}) & \\
 = H_{(\underline{1}} Q^a_{\underline{1}})} & \\
 - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{1} \omega_c \underline{1}) & \\
 - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{1} \hat{\omega}_\beta \underline{1}), & \text{for } a = 3.
 \end{aligned}$$

$$\begin{aligned}
 \text{(III)} : H_{(\underline{I}} R_{\underline{J}})} &= \omega_3(\underline{I} Q^3 \underline{J}), \\
 \forall \{I, J\}, & \\
 \kappa_{3ac} Q^c(\underline{I} \omega_b \underline{J}) &= \kappa_{3bc} Q^c(\underline{I} \omega_a \underline{J}), \\
 \forall a, b \in \{1, 2, 4\}, \quad \forall \{I, J\}, & \\
 \text{Model B1} : 3 H_{(\underline{0}} R_{\underline{1}})} - \omega_{a(\underline{0}} Q^a_{\underline{1}})} - \hat{\omega}_\alpha(\underline{0} \hat{Q}^{\alpha \underline{1}})} &= 0, \\
 \text{Model B2} : 3 H_{\underline{0}} R_{\underline{0}} - \omega_{a \underline{0}} Q^a_{\underline{0}} - \hat{\omega}_\alpha^{\underline{0}} \hat{Q}^{\alpha \underline{0}} - H_{\underline{1}} R_{\underline{1}} & \\
 + \omega_{a \underline{1}} Q^a_{\underline{1}} + \hat{\omega}_\alpha^{\underline{1}} \hat{Q}^{\alpha \underline{1}} &= 0, \\
 \text{(IV)} : R_{(\underline{1}} \omega_{a \underline{J}})} &= \frac{1}{2} \kappa_{abc} Q^b(\underline{1} Q^c \underline{J}), \\
 \text{for } a \in \{1, 2, 4\} \text{ and } \forall I, J, & \\
 \text{Model B1} : R_{(\underline{1}} \omega_{a \underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc} Q^b(\underline{1} Q^c \underline{0}) & \\
 - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{1} \hat{Q}^\beta \underline{0}) &= 0, \quad \text{for } a = 3, \\
 \text{Model B2} : R_{(\underline{0}} \omega_{a \underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc} Q^b(\underline{0} Q^c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{0} \hat{Q}^\beta \underline{0}) & \\
 = R_{(\underline{1}} \omega_b \underline{1})} - \frac{1}{2} \kappa_{abc} Q^b(\underline{1} Q^c \underline{1}) & \\
 - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{1} \hat{Q}^\beta \underline{1}), & \text{for } a = 3. \tag{4.2}
 \end{aligned}$$

Let us also mention that using the collection of missing identities given in Eq. (4.2), one can check that the following relations also hold,

$$\begin{aligned}
 \text{Model B1} : H_{(\underline{1}} Q^a_{\underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{1} \omega_c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{1} \hat{\omega}_\beta \underline{0}) &= 0, \quad \forall a, \\
 \text{Model B2} : H_{(\underline{0}} Q^a_{\underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{0} \omega_c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{0} \hat{\omega}_\beta \underline{0}) & \\
 = H_{(\underline{1}} Q^a_{\underline{1}})} & \\
 - \frac{1}{2} \kappa_{abc}^{-1} \omega_b(\underline{1} \omega_c \underline{1}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha(\underline{1} \hat{\omega}_\beta \underline{1}), & \forall a. \tag{4.3}
 \end{aligned}$$

and

$$\begin{aligned}
 \text{Model B1} : R_{(\underline{1}} \omega_{a \underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc} Q^b(\underline{1} Q^c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{1} \hat{Q}^\beta \underline{0}) &= 0, \quad \forall a, \\
 \text{Model B2} : R_{(\underline{0}} \omega_{a \underline{0}})} & \\
 - \frac{1}{2} \kappa_{abc} Q^b(\underline{0} Q^c \underline{0}) - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{0} \hat{Q}^\beta \underline{0}) & \\
 = R_{(\underline{1}} \omega_b \underline{1})} - \frac{1}{2} \kappa_{abc} Q^b(\underline{1} Q^c \underline{1}) & \\
 - \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha(\underline{1} \hat{Q}^\beta \underline{1}), & \forall a. \tag{4.4}
 \end{aligned}$$

These two sets of relations hold for all the values of  $a$ , i.e.  $\forall a \in \{1, 2, 3, 4\}$ , and hence they appear to represent some better insights for the (1, 1)-cohomology sector, and their

completions for the (2, 1)-cohomology sector can be invoked by looking at the prepotential as we discuss in the next step.

### 4.2 Insights for the (2, 1)-cohomology sector

The Kähler potential descending from the  $\mathcal{N} = 2$  quaternion sector is determined by a prepotential  $\mathcal{F}$  via the following relation [34,44],

$$K^Q = -2 \ln \left( 4 i \mathcal{F}(n^I) \right), \tag{4.5}$$

where we have defined  $n^I$  as the imaginary part of the complexified chiral variable  $N^I$  which is defined in Eq. (2.3), i.e.  $n^I \equiv e^{-D} \mathcal{X}^I$  following the notations of [45,46]. Moreover, splitting the index  $I$  as  $\{0, i\}$  where  $i$  is counted via the Hodge number  $h^{2,1}$  of the threefold, the prepotential  $\mathcal{F}(n^I)$  which is a homogeneous function of degree two in variables  $n^I$  can also be written as,

$$\mathcal{F}(n^I) = -i (n^0)^2 f(u^i), \tag{4.6}$$

where  $f(u^i)$  is now a new function of the inhomogeneous variables  $q^i(u^i) = \frac{n^i}{n^0} = \frac{\mathcal{X}^i}{\mathcal{X}^0}$  which implicitly depends on the complex structure moduli  $u^i$  as we will illustrate in our concrete examples. Such a function can be given as a cubic polynomial which can take the following form,

$$f(u^i) = \frac{1}{6} l_{ijk} u^i u^j u^k + \frac{1}{2} l_{0ij} u^i u^j + l_{00i} u^i + \frac{1}{2} l_{000} + \text{non pert.}, \tag{4.7}$$

Here the quantities  $l_{ijk}$  are the triple intersection numbers on the mirror threefold while  $l_{0ij}$ ,  $l_{00i}$  and  $l_{000}$  can be determined from the other topological quantities [47]. Also we would be neglecting the non-perturbative effects in the prepotential assuming the large complex structure limit.

#### Model A

The prepotential for Model A has been computed in the Appendix B in detail, and it is given by the Eq. (B.10), using which we find that

$$\mathcal{F}(n^K) = -i \sqrt{n^0 n^1 n^2 n^3} = -i (n^0)^2 u^1 u^2 u^3, \tag{4.8}$$

where in the second equality we have used

$$q^1 = \frac{n^1}{n^0} = \frac{\mathcal{X}^1}{\mathcal{X}^0} = u^2 u^3, \quad q^2 = \frac{n^2}{n^0} = \frac{\mathcal{X}^2}{\mathcal{X}^0} = u^1 u^3, \\ q^3 = \frac{n^3}{n^0} = \frac{\mathcal{X}^3}{\mathcal{X}^0} = u^1 u^2, \tag{4.9}$$

which follows from the definition of the complex structure moduli as given in Eq. (B.4) and the period vectors given in

Eq. (B.7). Therefore, for Model A, we have the following intersection numbers,

$$l_{123} = 1, \quad l_{0ij} = 0, \quad l_{00i} = 0, \quad l_{000} = 0. \tag{4.10}$$

With these ingredients, the missing identities for Model A can be written as,

$$H_{(i} Q^a_{j)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_{b(i} \omega_{c)j)} = 0, \quad i \neq a; \\ H_{(0} R_k) - \omega_{a(0} Q^a_{k)} \delta_{ak} = 0, \quad \forall k; \\ H_{(0} R_k) - \omega_{a(0} Q^a_{k)} + 2 \omega_{a(0} Q^a_{j)} \delta_{aj} = 0, \quad j \neq k; \\ R_{(i} \omega_{a)j} - \frac{1}{2} \kappa_{abc} Q^b_{(i} Q^c_{j)} = 0, \quad i \neq a; \tag{4.11}$$

and

$$\frac{1}{2} l_{ijk}^{-1} \left[ H_{(j} Q^a_{k)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_{b(j} \omega_{c)k)} \right] = 0, \quad i \neq a; \\ \frac{1}{2} l_{ijk}^{-1} \left[ H_{(j} R_k) - \omega_{a(j} Q^a_{k)} + 2 \omega_{a(j} Q^a_{l)} \delta_{al} \right] = 0, \quad \forall i; \\ \frac{1}{2} l_{ijk}^{-1} \left[ H_{(j} R_k) - \omega_{a(j} Q^a_{k)} \delta_{ai} \right] = 0, \quad \forall i; \\ \frac{1}{2} l_{ijk}^{-1} \left[ R_{(j} \omega_{a)k} - \frac{1}{2} \kappa_{abc} Q^b_{(j} Q^c_{k)} \right] = 0, \quad i \neq a. \tag{4.12}$$

#### Model B1

The prepotential for Model B1 has been computed in the Appendix B in detail, and it is given by the Eq. (B.18), using which we find that

$$\mathcal{F}(n^K) = -i n^0 n^1 = -i (n^0)^2 u, \tag{4.13}$$

where we have used  $q(u) = \left( \frac{n^1}{n^0} \right) = \frac{\mathcal{X}^1}{\mathcal{X}^0} = U = u$  from Eq. (B.15), and therefore we have the following intersection numbers,

$$l_{ijk} = 0, \quad l_{0ij} = 0, \quad l_{001} = 1, \quad l_{000} = 0. \tag{4.14}$$

With these ingredients, (most of) the missing identities for Model B1 can be written as,

$$l_{00i}^{-1} \left[ H_{(i} Q^a_{j)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_{b(i} \omega_{c)j)} \right] \\ = l_{00i} \left[ \frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha^{(i} \hat{\omega}_\beta^{j)} \right], \quad \forall a; \\ l_{00i}^{-1} \left[ H_{(0} R_j) - \omega_{a(0} Q^a_{j)} + 2 \omega_{a(0} Q^a_{l)} \delta_{al} \right] \\ = l_{00i} \hat{\omega}_\alpha^{(0} \hat{Q}^{\alpha j)}, \\ l_{00i}^{-1} \left[ R_{(i} \omega_{a)j} - \frac{1}{2} \kappa_{abc} Q^b_{(i} Q^c_{j)} \right] \\ = l_{00i} \left[ \frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha_{(i} \hat{Q}^{\beta j)} \right], \quad \forall a; \tag{4.15}$$

and

$$\begin{aligned}
 l_{00i}^{-1} \left[ H_{(0} Q^a_{0)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b{}_{(0} \omega_{c0)} \right] &= 0, \quad \forall i, \forall a : \hat{\kappa}_{\alpha\alpha\beta} = 0; \\
 l_{00i}^{-1} \left[ H_{(0} R_{0)} - \omega_a{}_{(0} Q^a_{0)} + 2 \omega_a{}_{(0} Q^a_{0)} \delta_{ai} \right] &= 0, \quad \forall i; \\
 l_{00i}^{-1} \left[ R_{(0} \omega_{a0)} - \frac{1}{2} \kappa_{abc} Q^b{}_{(0} Q^c_{0)} \right] &= 0, \quad \forall i, \forall a : \hat{\kappa}_{\alpha\alpha\beta} = 0.
 \end{aligned}
 \tag{4.16}$$

*Model B2*

The prepotential for Model B2 has been computed in the Appendix B in detail, and it is given by the Eq. (B.26), using which we find that

$$\begin{aligned}
 \mathcal{F}(n'^K) &= -\frac{i}{2} (n'^0)^2 \left[ 1 - \left( \frac{n'^1}{n'^0} \right)^2 \right] \\
 &= -\frac{i}{2} (n'^0)^2 \left[ 1 - u^2 \right],
 \end{aligned}
 \tag{4.17}$$

where we have used  $q(u) = \left( \frac{n'^1}{n'^0} \right) = \frac{\mathcal{X}^1}{\mathcal{X}^0} = u$ , and therefore we have the following intersection numbers,

$$l_{ijk} = 0, \quad l_{011} = -1, \quad l_{00i} = 0, \quad l_{000} = 1.
 \tag{4.18}$$

With these ingredients, the missing identities for Model B2 can be written as,

$$\begin{aligned}
 l_{0IJ}^{-1} \left[ H_{(I} Q^a_{J)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b{}_{(I} \omega_{cJ)} \right] &= l_{0IJ} \left[ \frac{1}{2} \hat{\kappa}_{\alpha\alpha\beta}^{-1} \hat{\omega}_\alpha{}^{(I} \hat{\omega}^{\beta J)} \right], \quad \forall a; \\
 l_{0IJ}^{-1} \left[ H_{(I} R_{J)} - \omega_a{}_{(I} Q^a_{J)} + 2 \omega_a{}_{(I} Q^a_{J)} \delta_{ai} \right] &= l_{0IJ} \hat{\omega}_\alpha{}^{(I} \hat{Q}^{\alpha J)}, \\
 l_{0IJ}^{-1} \left[ 3 H_{(I} R_{J)} - \omega_a{}_{(I} Q^a_{J)} \right] &= l_{0IJ} \hat{\omega}_\alpha{}^{(I} \hat{Q}^{\alpha J)}, \\
 l_{0IJ}^{-1} \left[ R_{(I} \omega_{aJ)} - \frac{1}{2} \kappa_{abc} Q^b{}_{(I} Q^c_{J)} \right] &= l_{0IJ} \left[ \frac{1}{2} \hat{\kappa}_{\alpha\alpha\beta} \hat{Q}^\alpha{}^{(I} \hat{Q}^{\beta J)} \right], \quad \forall a;
 \end{aligned}
 \tag{4.19}$$

and

$$\begin{aligned}
 l_{0IJ}^{-1} \left[ H_{(0} Q^a_{J)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b{}_{(0} \omega_{cJ)} \right] &= 0, \quad \forall I \in \{0, i\}, \forall a : \hat{\kappa}_{\alpha\alpha\beta} = 0; \\
 l_{0IJ}^{-1} \left[ H_{(0} R_{J)} - \omega_a{}_{(0} Q^a_{J)} + 2 \omega_a{}_{(0} Q^a_{J)} \delta_{ai} \right] &= 0; \\
 l_{0IJ}^{-1} \left[ R_{(0} \omega_{aJ)} - \frac{1}{2} \kappa_{abc} Q^b{}_{(0} Q^c_{J)} \right] &= 0, \quad \forall I \in \{0, i\}, \forall a : \hat{\kappa}_{\alpha\alpha\beta} = 0.
 \end{aligned}
 \tag{4.20}$$

As a side remark, let us mention that we have also attempted to look for some identities in the first formulation which could directly translate into the second formulation. A couple of such constraints are presented in Table 9.

**5 Conclusions and discussions**

This article has been focussed on investigating the two formulations of Bianchi identities in type IIA supergravity with the (non-)geometric fluxes. In what we call the ‘first formulation’, all the fluxes are written using real six-dimensional indices ( $H_{ijk}, \omega_{ij}^k$  etc.) while in the ‘second formulation’, the fluxes are expressed using cohomology indices such as  $H_K, \omega_{aK}$  etc., where  $a$  index components are counted to be  $h_-^{1,1}(X_3/\sigma)$  in number while the  $K$  index components are counted to be  $(1 + h^{2,1}(X_3))$ . Assuming the appropriate normalizations of forms, the two formulations of the Bianchi identities are summarized as in the Table 5. We have performed a deep analysis in search of the missing identities in the cohomology formulation, and subsequently we have conjectured a model independent form for (the most of) these identities which are collected in Table 6.

The main findings and observations from our detailed analysis can be summarized in the following points,

- All the identities of the second formulations can be obtained via reshuffling the identities of the first formulation.
- There are certainly several flux constraints in the first formulation which cannot be obtained from the known version of the second formulation.
- In our type IIA orientifold construction, it is easier to generically see the mismatch in the two formulation, in particular for the choice of involution leading to no ‘hatted’ fluxes, which are counted by the even (1,1)-cohomology index  $\alpha$ . Such fluxes are absent for  $h_+^{1,1}(X_3/\sigma) = 0$  and subsequently one can observe that 9 of the 10 second formulation identities as collected in Table 5 are identically and generically trivial. Our Model A demonstrates the explicit insights behind these arguments.
- There is no mismatch between the first ( $H\omega$ -type) and the last ( $RQ$ -type) of the five classes of the constraints presented in Table 5. In Model A both of these classes, namely (I) and (V) are trivial while in Model B, they are non-trivial but identical in the two formulations. So the mismatch is present only in the (II), (III) and (IV) type of the constraints of Table 5.
- We have managed to (partially) express the set of missing Bianchi identities in a model independent manner by using the topological quantities of the complex threefold



**Table 5** Two formulations of the type IIA Bianchi identities

BIs	First formulation	Second formulation
(I)	$H_{m[ij} \omega_{kl]}^m = 0$	$H_K \hat{\omega}_\alpha^K = 0$
(II)	$\omega_{[ij}^m \omega_{kl]}^l = Q_{[i}^{lm} H_{jk]m}$	$H_K \hat{Q}^{\alpha K} = 0, \omega_{aK} \hat{\omega}_\alpha^K = 0$
(III)	$H_{ijm} R^{mkl} + \omega_{ij}^m Q_m^{kl} = 4Q_{[i}^{m[k} \omega_{j]m}^{l]}$	$\omega_{aK} \hat{Q}^{\alpha K} = 0, \hat{\omega}_\alpha^K Q^a_K = 0, \hat{\omega}_\alpha^{[K} \hat{Q}^{\alpha J]} = 0, H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}$
(IV)	$Q_m^{[ij} Q_l^{k]m} = \omega_{lm}^{[i} R^{jk]m}$	$R_K \hat{\omega}_\alpha^K = 0, Q^a_K \hat{Q}^{\alpha K} = 0$
(V)	$R^{m[ij} Q_m^{kl]} = 0$	$R_K \hat{Q}^{\alpha K} = 0$

**Table 6** A conjectural form for (some of) the missing identities. Here we have considered  $\kappa_{abc}^{-1} = 1/\kappa_{abc}$  and  $\hat{\kappa}_{\alpha\beta}^{-1} = 1/\hat{\kappa}_{\alpha\beta}$  for fixed values of  $\{a, b, c\}$  and  $\{\alpha, \beta\}$ , whenever these intersections are non-zero, and similarly for the triple intersections on the mirror side

BIs	Missing identities
(II)	$l_{0IJ}^{-1} [H_{(I} Q^a_{J)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b_{(I} \omega_{cJ)}] = l_{0IJ} [\frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha^{(I} \hat{\omega}_\beta^{J)}], \forall a;$ $l_{IJ0}^{-1} [H_{(I} Q^a_{J)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b_{(I} \omega_{cJ)}] = 0, \forall I \in \{0, i\} \& \forall a : \hat{\kappa}_{\alpha\beta} = 0;$ $l_{ijk}^{-1} [H_{(i} Q^a_{j)} - \frac{1}{2} \kappa_{abc}^{-1} \omega_b_{(i} \omega_{cj)}] = l_{ijk} [\frac{1}{2} \hat{\kappa}_{\alpha\beta}^{-1} \hat{\omega}_\alpha^{(i} \hat{\omega}_\beta^{j)}], i \neq a;$
(III)	$l_{0IJ}^{-1} [3 H_{(I} R_{J)} - \omega_{a(I} Q^a_{J)}] = l_{0IJ} \hat{\omega}_\alpha^{(I} \hat{Q}^{\alpha J)};$ $l_{IJ0}^{-1} [H_{(I} R_{J)} - \omega_{a(I} Q^a_{J)} + 2 \omega_a_{(I} Q^a_{J)} \delta_{ai}] = l_{IJ0} \hat{\omega}_\alpha^{(I} \hat{Q}^{\alpha J)};$ $l_{ijk}^{-1} [H_{(i} R_{j)} - \omega_{a(i} Q^a_{j)} + 2 \omega_a_{(i} Q^a_{j)} \delta_{aj}] = 0, \forall i;$ $l_{ijk}^{-1} [H_{(i} R_{j)} - \omega_{a(i} Q^a_{j)} \delta_{ai}] = 0, \forall i;$
(IV)	$l_{0IJ}^{-1} [R_{(I} \omega_{aJ)} - \frac{1}{2} \kappa_{abc} Q^b_{(I} Q^c_{J)}] = l_{0IJ} [\frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha_{(I} \hat{Q}^\beta_{J)}], \forall a;$ $l_{IJ0}^{-1} [R_{(I} \omega_{aJ)} - \frac{1}{2} \kappa_{abc} Q^b_{(I} Q^c_{J)}] = 0, \forall I \in \{0, i\} \& \forall a : \hat{\kappa}_{\alpha\beta} = 0;$ $l_{ijk}^{-1} [R_{(i} \omega_{aj)} - \frac{1}{2} \kappa_{abc} Q^b_{(i} Q^c_{j)}] = l_{ijk} [\frac{1}{2} \hat{\kappa}_{\alpha\beta} \hat{Q}^\alpha_{(i} \hat{Q}^\beta_{j)}], i \neq a.$

such as the triple-intersection numbers as defined in Eq. (2.2). These are given in Table 6.

- From Table 3 we observe that in the first formulation the maximum number of Bianchi identities is 496 while from the second formulation as listed in Table 4, we find that the maximum number of identities depend on the hodge number  $h_{\pm}^{1,1}$  and  $h^{2,1}$ . Therefore there will be certainly some redundancy in the second formulation, especially for the orientifold settings having large hodge numbers, so that to make it consistent with the counting in the first formulation. However, it is hard to find/claim that there will be a perfect bijection in terms of the number of “independent” flux constraints.

From the Table 6, we observe that the index structure for the  $h^{1,1}$  and  $h^{2,1}$  indices in the missing Bianchi identities are completely different from those of the second formulation. For example, after looking at the index structure in the generic identities of the cohomology formulation as presented in the Table 4, one can convince that none of the missing identities, namely the ones given in Eqs. (C.1), (C.4), (C.5) for model A and those given in Eqs. (C.8), (C.9), (C.11), (C.12), (C.14), (C.15) for the model B, can be produced from the identities of Table 4.

As it has been very standard thing to follow, we have investigated the two toroidal models by considering ingredients (e.g. fluxes and moduli) only in the untwisted sector,

and therefore one might speculate/suspect that may be after including the twisted sector fluxes, the mismatch between the two sets of Bianchi identities goes away. However, this cannot happen because of the simple reason stated regarding the distinct index structures appearing in the missing Bianchi identities and the ones presented in the cohomology formulation. For the later case, the generic expressions are given in Table 4, and therefore in order to include the twisted sector one has to simply change the range of the  $h_{\pm}^{1,1}$  and  $h_{\pm}^{2,1}$  indices; for example the  $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$  setup will have 48 twisted moduli and hence one would need to change  $a$  from  $a = \{1, 2, 3\}$  to  $a = \{1, 2, \dots, 51\}$  subject to the appropriate choice of the involution. This would surely append/modify the set of identities with additional constraints but those would never fall in line with the index structure of the missing identities, e.g. in the sense of contraction of indices, symmetrization of  $h^{2,1}$  indices etc. However it would be interesting to investigate on these lines by performing some explicit computations including the twisted sector.

At least one reason for the mismatch between the Bianchi identities of the two formulations could be considered to be the fact that the first formulation is derived by imposing the nilpotency of the twisted differential  $\mathcal{D}$  on a generic  $p$ -forms  $A_p$ , while the second formulation can be derived by imposing the nilpotency only on the harmonic forms. By finding some fundamental derivation of all these missing identities of the second formulation, it would be interesting to check/verify

if the conjectured form of (some of) the missing identities proposed in Table 6 generically holds or not.

From our explicit examples, we have observed that the second formulation produces only around 15% of the total number of Bianchi identities in Model A, and that of around 35% in Model B. Therefore, one would expect the scalar potential to have some strong restrictions imposed from the missing identities which can further nullify several terms of the potential making it better or worse for a given model, depending on the outcome. For example, they can kill many terms upto the extent that the no-scale structure could win against some of the terms responsible for the stabilization of (some of) the moduli, and hence this could be risky for an already working model. However, these additional identities could make significant simplifications such that one could even think of studying moduli stabilization analytically, and possibly in a model independent manner, which appears to be extremely challenging task in concrete non-geometric setups. To conclude, we would like to make a cautionary remark that these identities might play some crucial role, particularly in the scenarios where one uses only the second formulation for building the phenomenologically motivated non-geometric models beyond the toroidal orientifolds.

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### A Derivation of the second formulation of Bianchi identities

The twisted differential operator  $\mathcal{D}$  is defined as under,

$$\mathcal{D} = d + H \wedge . - \omega \lrcorner . + Q \triangleright . - R \bullet .$$

Here the action of various fluxes appearing in  $\mathcal{D}$  is such that for an arbitrary  $p$ -form  $A_p$ , the pieces  $H \wedge A_p$ ,  $\omega \lrcorner A_p$ ,  $Q \triangleright A_p$  and  $R \bullet A_p$  denote a  $(p + 3)$ -form, a  $(p + 1)$ -

form, a  $(p - 1)$ -form and a  $(p - 3)$ -form respectively. More specifically, there are the following flux actions on various harmonic-forms [10],

$$\begin{aligned} H \wedge \mathbf{1} &= H_K \beta^K, & H \wedge \alpha_K &= -H_K \Phi_6, & H \wedge \beta^K &= 0, \\ \omega \lrcorner v_a &= \omega_{aK} \beta^K, & \omega \lrcorner \mu_\alpha &= \hat{\omega}_\alpha^K \alpha_K, \\ \omega \lrcorner \alpha_K &= \omega_{aK} \tilde{v}^a, & \omega \lrcorner \beta^K &= -\hat{\omega}_\alpha^K \tilde{\mu}^\alpha, \\ Q \triangleright \tilde{v}^a &= Q_K^a \beta^K, & Q \triangleright \tilde{\mu}^\alpha &= \hat{Q}^{\alpha K} \alpha_K, \\ Q \triangleright \alpha_K &= -Q_K^a v_a, & Q \triangleright \beta^K &= \hat{Q}^{\alpha K} \mu_\alpha, \\ R \bullet \Phi_6 &= R_K \beta^K, & R \bullet \alpha_K &= R_K \mathbf{1}, & R \bullet \beta^K &= 0. \end{aligned} \tag{A.1}$$

Now as can be seen from these flux actions, the operations  $\lrcorner, \triangleright$  and  $\bullet$  changes a  $p$ -form into a  $(p + 1)$ -form, a  $(p - 1)$ -form and a  $(p - 3)$ -form respectively, and we have

$$\begin{aligned} \mathcal{D} A_p &= d A_p + H \wedge A_p - \omega \lrcorner A_p \\ &\quad + Q \triangleright A_p - R \bullet A_p. \end{aligned} \tag{A.2}$$

Subsequently, we find that  $(\mathcal{D}^2 A_p)$  has seven types of pieces written as  $(p + i)$ -forms where  $i \in \{6, 4, 2, 0, -2, -4, -6\}$ . These are collected as under,

$$\begin{aligned} (i). & H \wedge (H \wedge A_p) \\ (ii). & d(H \wedge A_p) + H \wedge (dA_p) - H \wedge (\omega \lrcorner A_p) \\ & \quad - \omega \lrcorner (H \wedge A_p) \\ (iii). & d^2 A_p - d(\omega \lrcorner A_p) - \omega \lrcorner (dA_p) + H \wedge (Q \triangleright A_p) \\ & \quad + Q \triangleright (H \wedge A_p) + \omega \lrcorner (\omega \lrcorner A_p) \\ (iv). & d(Q \triangleright A_p) + Q \triangleright (dA_p) - Q \triangleright (\omega \lrcorner A_p) \\ & \quad - \omega \lrcorner (Q \triangleright A_p) - H \wedge (R \bullet A_p) - R \bullet (H \wedge A_p) \\ (v). & -d(R \bullet A_p) - R \bullet (dA_p) + \omega \lrcorner (R \bullet A_p) \\ & \quad + Q \triangleright (Q \triangleright A_p) + R \bullet (\omega \lrcorner A_p) \\ (vi). & -Q \triangleright (R \bullet A_p) - R \bullet (Q \triangleright A_p) \\ (vii). & R \bullet (R \bullet A_p) \end{aligned} \tag{A.3}$$

For ensuring the identity  $\mathcal{D}^2 A_p = 0$ , each of these seven pieces has to vanish individually. Now given that the internal background is a real six-dimensional manifold, one can observe from collection in Eq. (A.3) that the first (i) and the last (vii) expressions are relevant only for  $A_p$  being zero-form  $\mathbf{1}$  and six-form  $\Phi_6$  respectively. However, the same leads to trivial constraints as,

$$H \wedge (H \wedge \mathbf{1}) = 0, \quad R \bullet (R \bullet \Phi_6) = R_K (R \bullet \beta^K) = 0, \tag{A.4}$$

where we have used R-flux actions given in Eq. (A.1). Now, for further simplifying the remaining five type of identities in Eq. (A.3), we will assume that all fluxes are constant parameters which is considered due to the subsequent simpler phenomenological relevance. Moreover, one observation is very straight that mixing of fluxes in the remaining five constraints

**Table 7** Bases of the various non-trivial forms for Model A

Basis of Forms	Shorthand notation $m \wedge n = dx^m \wedge dx^n$ etc. is used
$v_a$	$v_1 = 1 \wedge 2, \quad v_2 = 3 \wedge 4, \quad v_3 = 5 \wedge 6$
$\alpha_K$	$\alpha_0 = 2 \wedge 4 \wedge 6, \quad \alpha_1 = -2 \wedge 3 \wedge 5, \quad \alpha_2 = -1 \wedge 4 \wedge 5, \quad \alpha_3 = -1 \wedge 3 \wedge 6$
$\beta^K$	$\beta^0 = 1 \wedge 3 \wedge 5, \quad \beta^1 = -1 \wedge 4 \wedge 6, \quad \beta^2 = -2 \wedge 3 \wedge 6, \quad \beta^3 = -2 \wedge 4 \wedge 5$
$\tilde{v}^a$	$\tilde{v}^1 = v_2 \wedge v_3, \quad \tilde{v}^2 = v_3 \wedge v_1, \quad \tilde{v}^3 = v_1 \wedge v_2$
$\Phi_6$	$\Phi_6 \equiv v_1 \wedge v_2 \wedge v_3 = 1 \wedge 2 \wedge 3 \wedge 4 \wedge 5 \wedge 6$

are of  $H\omega$ ,  $(\omega^2 + HQ)$ ,  $(HR + Q\omega)$ ,  $(Q^2 + \omega R)$  and  $(QR)$  types which is in obvious connections with the first formulation of Bianchi identities as given in Table 3. However, for the second formulation our aim is to compute Bianchi identities with fluxes written in various cohomology bases and not in the real six-dimensional indices. Let us take each constraint one-by-one via considering the flux actions in Eq. (A.1).

- Using the fact that  $H_3$  is a three-form constant flux, we find that  $d(H \wedge A_p) + H \wedge (dA_p) = 0$ , and so nullification of terms in the class (ii) simplifies into  $H \wedge (\omega \lrcorner A_p) + \omega \lrcorner (H \wedge A_p) = 0$ . The relevant  $A_p$ -forms for expecting non-trivial relations correspond to  $p = \{0, 2\}$ , and both of these choices result into a single Bianchi identity as under,

$$H_K \hat{\omega}_\alpha^K = 0. \tag{A.5}$$

- Using  $d^2 = 0$  and constancy of fluxes, the nullification of terms in class (iii) are reduced into satisfying:  $H \wedge (Q \triangleright A_p) + Q \triangleright (H \wedge A_p) + \omega \lrcorner (\omega \lrcorner A_p) = 0$ . This results into the following two types of Bianchi identities via considering  $A_p = \{\mathbf{1}, \alpha_K, v_a\}$ ,

$$H_K \hat{Q}^{\alpha K} = 0, \quad \omega_{aK} \hat{\omega}_\alpha^K = 0. \tag{A.6}$$

- Demanding the nullification of terms in collection (iv) results in the following

$$\omega_{aK} \hat{Q}^{\alpha K} = 0, \quad \hat{\omega}_\alpha^K Q^a{}_K = 0, \\ \hat{\omega}_\alpha^{[K} \hat{Q}^{\alpha J]} = 0, \quad H_{[K} R_{J]} = \omega_{a[K} Q^a{}_{J]}, \tag{A.7}$$

where the first two identities follow from the two-forms:  $A_p = \{v_a, \mu_\alpha, \tilde{v}^a, \tilde{\mu}^\alpha\}$  while the third and fourth identities follow from the choice  $A_p = \beta^K$  and  $A_p = \alpha_K$  respectively. In addition, the bracket [...] denotes anti-symmetrization of  $J$  and  $K$  indices.

- Demanding the nullification of collection (v), we get  $\omega \lrcorner (R \bullet A_p) + Q \triangleright (Q \triangleright A_p) + R \bullet (\omega \lrcorner A_p) = 0$ , which results in the following two Bianchi identities,

$$R_K \hat{\omega}_\alpha^K = 0, \quad Q^a{}_K \hat{Q}^{\alpha K} = 0, \tag{A.8}$$

where the first one follows from  $A_p = \{\Phi_6, \mu_\alpha\}$  while the second one from  $A_p = \tilde{v}^a$ .

- Finally, the nullification of collection (vi) which is  $Q \triangleright (R \bullet A_p) + R \bullet (Q \triangleright A_p) = 0$ , gives another Bianchi identity for the relevant  $p$ -forms being  $A_p = \{\Phi_6, \tilde{\mu}^\alpha\}$ ,

$$R_K \hat{Q}^{\alpha K} = 0. \tag{A.9}$$

In summary, we have the following set of Bianchi identities in the second formulation,

$$H_K \hat{\omega}_\alpha^K = 0, \quad H_K \hat{Q}^{\alpha K} = 0, \quad R_K \hat{Q}^{\alpha K} = 0, \\ R_K \hat{\omega}_\alpha^K = 0, \\ \omega_{aK} \hat{\omega}_\alpha^K = 0, \quad \omega_{aK} \hat{Q}^{\alpha K} = 0, \quad Q^a{}_K \hat{Q}^{\alpha K} = 0, \\ \hat{\omega}_\alpha^K Q^a{}_K = 0, \\ \hat{\omega}_\alpha^{[K} \hat{Q}^{\alpha J]} = 0, \quad H_{[K} R_{J]} = \omega_{a[K} Q^a{}_{J]}. \tag{A.10}$$

## B Relevant details on the two orientifold setups

### B.1 Type IIA on a $\mathbb{T}^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$ -orientifold

Let us briefly review the first model which is constructed in the framework of the type IIA compactification on the orientifold of a  $\mathbb{T}^6/(\mathbb{Z}_2 \times \mathbb{Z}_2)$  orbifold. This is the very often studied type IIA setup, and the orientifold related details can also be found in [8, 35, 36, 38]. However to establish the consistency with our current notations, we will briefly present the relevant ingredients about this setup. We consider the complexified coordinates on the torus  $\mathbb{T}^6$  to be defined as under,

$$z^1 = R^1 x^1 + i R^2 x^2, \quad z^2 = R^3 x^3 + i R^4 x^4, \\ z^3 = R^5 x^5 + i R^6 x^6, \tag{B.1}$$

where  $0 \leq x^i \leq 1$  and  $R^i$  denote the circumference of the  $i$ -th circle. Further, the two  $\mathbb{Z}_2$  orbifold actions are defined as:

$$\theta : (z^1, z^2, z^3) \rightarrow (-z^1, -z^2, z^3), \\ \bar{\theta} : (z^1, z^2, z^3) \rightarrow (z^1, -z^2, -z^3). \tag{B.2}$$

In addition an anti-holomorphic involution  $\sigma$  is defined by the following action:

$$\sigma : (z^1, z^2, z^3) \rightarrow (-\bar{z}^1, -\bar{z}^2, -\bar{z}^3). \tag{B.3}$$

Note that the six  $R^i$ 's defining the complex coordinates  $z^i$ 's determine the three complex structure moduli  $u^i$  and three Kähler moduli  $t^i$  which can be given as,

$$t^1 = R^1 R^2, \quad t^2 = R^3 R^4, \quad t^3 = R^5 R^6, \quad u^1 = \frac{R^1}{R^2},$$

$$u^2 = \frac{R^3}{R^4}, \quad u^3 = \frac{R^5}{R^6}. \tag{B.4}$$

The bases of various non-trivial forms are summarized as in Table 7.

As chosen in Eq. (2.2) these basis elements are normalized accordingly as  $\int_{X_3} \alpha_J \wedge \beta^K = \delta_J^K$ , and we find that  $d^a_b = \delta^a_b$  and  $f = 1$ , i.e. the six-form is normalized to unity. Further, there is only one triple intersection number of the type  $\kappa_{abc}$  which is non-zero, namely  $\kappa_{123} = 1$  while all the other intersection numbers including  $\hat{\kappa}_{\alpha\alpha\beta}$  are zero. Using the various even/odd forms in Table 7 and the flux actions given in Eq. (A.1), one finds the following non-zero components for the various  $H, \omega, Q$  and  $R$  fluxes,

$$H_{ijk} : H_{135}, \quad H_{146}, \quad H_{236}, \quad H_{245},$$

$$\omega_{ij}{}^k : \omega_{13}{}^6, \quad \omega_{14}{}^5, \quad \omega_{23}{}^5, \quad \omega_{24}{}^6, \quad \omega_{35}{}^2, \quad \omega_{36}{}^1, \quad \omega_{45}{}^1,$$

$$\omega_{46}{}^2, \quad \omega_{51}{}^4, \quad \omega_{52}{}^3, \quad \omega_{61}{}^3, \quad \omega_{62}{}^4,$$

$$Q_i{}^{jk} : Q_1{}^{46}, \quad Q_1{}^{35}, \quad Q_2{}^{36}, \quad Q_2{}^{45}, \quad Q_3{}^{62},$$

$$Q_3{}^{51}, \quad Q_4{}^{52}, \quad Q_4{}^{61}, \quad Q_5{}^{24}, \quad Q_5{}^{13}, \quad Q_6{}^{14}, \quad Q_6{}^{23},$$

$$R^{ijk} : R_{246}, \quad R_{235}, \quad R_{145}, \quad R_{136}. \tag{B.5}$$

Note that 16 components out of 20 for each of the  $H_{ijk}$  and  $R^{ijk}$  flux, while 78 components out of 90 for each of the  $\omega_{ij}{}^k$  and  $Q_i{}^{jk}$  flux, are identically zero under this orientifold construction. In the cohomology version, these flux components can be rewritten as in Eq. (3.1). Also, from the collection of the various non-zero flux components in Eq. (B.5) it is obvious to observe that the tracelessness condition (2.8) is trivially satisfied.

Now the holomorphic (3, 0) form  $\Omega_3$  can be determined by the choice of the coordinates  $z^i$ 's up to an overall constant factor. The phase is automatically fixed by our choice of anti-holomorphic involution  $\sigma$  via  $\sigma^*(\Omega_3) = \bar{\Omega}_3$  which suggests to consider the following form for the holomorphic three-form  $\Omega_3$ ,

$$\Omega_3 \equiv \mathcal{X}^K \alpha_K - \mathcal{F}_K \beta^K = \frac{i}{\sqrt{2}} dz^1 \wedge dz^2 \wedge dz^3. \tag{B.6}$$

Subsequently, the period vectors  $(\mathcal{X}^I, \mathcal{F}_J)$  are given as,

$$\mathcal{X}^0 = \gamma \sqrt{\frac{1}{u^1 u^2 u^3}}, \quad \mathcal{X}^1 = \gamma \sqrt{\frac{u^2 u^3}{u^1}},$$

$$\mathcal{X}^2 = \gamma \sqrt{\frac{u^1 u^3}{u^2}}, \quad \mathcal{X}^3 = \gamma \sqrt{\frac{u^1 u^2}{u^3}}, \tag{B.7}$$

where  $\gamma = \frac{1}{2}$  and  $\mathcal{F}_I = -i/(8 \mathcal{X}^I)$  for each  $I \in \{0, 1, 2, 3\}$ . One can observe that  $\mathcal{X}^K$ 's are real while  $\mathcal{F}_K$ 's are pure imaginary functions of the complex structure moduli. Moreover, the overall scale factor has been normalized via  $\int_{X_3} i \Omega_3 \wedge \bar{\Omega}_3 = 1$ , which is subsequently equivalent to  $\mathcal{X}^I \mathcal{F}_I = -i/2$  as could be easily verified. Now using the definitions of chiral variable given in Eq. (2.3), we define  $n'^K \equiv \text{Im} N^K = e^{-D} \mathcal{X}^K$ , and observe that the following relation holds,

$$\mathcal{X}^0 \mathcal{X}^1 \mathcal{X}^2 \mathcal{X}^3 = \frac{1}{16} \implies 16 e^{4D} n'^0 n'^1 n'^2 n'^3 = 1, \tag{B.8}$$

which implies that the Kähler potential in the quaternion sector can be written as under,

$$K_Q \equiv 4 D = -\ln \left( 16 n'^0 n'^1 n'^2 n'^3 \right). \tag{B.9}$$

This Kähler potential  $K_Q$  can also be written as  $K_Q = -2 \ln \left( 4 i \mathcal{F}(n'^I) \right)$  [34], and therefore it can be determined by a prepotential of the following form,

$$\mathcal{F}(n'^I) = -i \sqrt{n'^0 n'^1 n'^2 n'^3}, \tag{B.10}$$

which is a homogeneous function of degree 2 in the  $n'^I$  variables.

### B.2 Type IIA on a $\mathbb{T}^6/\mathbb{Z}_4$ -orientifold

Now let us consider the type IIA compactification on the orientifold of a  $\mathbb{T}^6/\mathbb{Z}_4$  orbifold. This type IIA orientifold setup has been considered for a couple of times for different purposes, e.g. regarding (supersymmetric) moduli stabilization in [9, 10]. Here we consider two constructions for this sixfold and will briefly present the relevant necessary ingredients.

#### Model B1

This model has been considered for the standard moduli stabilization without using the non-geometric flux in [9]. The complexified coordinates on the torus  $\mathbb{T}^6$  are defined as

$$z^1 = x^1 + i x^2, \quad z^2 = x^3 + i x^4, \quad z^3 = x^5 + i U x^6, \tag{B.11}$$

where there is a single complex structure modulus  $U$ . Further, the  $\mathbb{Z}_4$  action  $\Theta$  and the anti-holomorphic involution  $\sigma$  acting

**Table 8** Bases of the various non-trivial forms for Model B

Basis of Forms	Shorthand notation $m \wedge n = dx^m \wedge dx^n$ etc. is used
$\nu_a$	$\nu_1 = 1 \wedge 2, \nu_2 = 3 \wedge 4, \nu_3 = 5 \wedge 6$ $\nu_4 = \frac{1}{2} (1 \wedge 3 - 1 \wedge 4 + 2 \wedge 3 + 2 \wedge 4)$
$\mu_\alpha$	$\mu_1 = \frac{1}{2} (1 \wedge 3 + 1 \wedge 4 - 2 \wedge 3 + 2 \wedge 4)$
$\alpha_K$	$\alpha_0 = 1 \wedge 3 \wedge 5 - 2 \wedge 4 \wedge 5 + 1 \wedge 4 \wedge 5 + 2 \wedge 3 \wedge 5$ $\alpha_1 = 1 \wedge 3 \wedge 6 - 2 \wedge 4 \wedge 6 - 1 \wedge 4 \wedge 6 - 2 \wedge 3 \wedge 6$
$\beta^K$	$\beta^0 = 1 \wedge 3 \wedge 6 - 2 \wedge 4 \wedge 6 + 1 \wedge 4 \wedge 6 + 2 \wedge 3 \wedge 6$ $\beta^1 = -1 \wedge 3 \wedge 5 + 2 \wedge 4 \wedge 5 + 1 \wedge 4 \wedge 5 + 2 \wedge 3 \wedge 5$
$\tilde{\nu}^a$	$\tilde{\nu}^1 = \nu_2 \wedge \nu_3, \tilde{\nu}^2 = \nu_3 \wedge \nu_1, \tilde{\nu}^3 = \nu_1 \wedge \nu_2, \tilde{\nu}^4 = -\nu_3 \wedge \nu_4$
$\tilde{\mu}^\alpha$	$\tilde{\mu}^1 = \nu_3 \wedge \mu_1$
$\Phi_6$	$\Phi_6 \equiv \nu_1 \wedge \nu_2 \wedge \nu_3 = -\nu_3 \wedge \nu_4 \wedge \nu_4 = 1 \wedge 2 \wedge 3 \wedge 4 \wedge 5 \wedge 6$

on the various coordinates are defined as:

$$\Theta : (z^1, z^2, z^3) \rightarrow (i z^1, i z^2, -z^3),$$

$$\sigma : (z^1, z^2, z^3) \rightarrow (\bar{z}^1, i \bar{z}^2, \bar{z}^3). \tag{B.12}$$

The bases of various even/odd forms are defined in the Table 8.

The triple intersection numbers surviving under the orientifold action, and the other normalization factors for the integral overs forms are fixed as under:

$$f = 1, \quad d_a^b = \delta_a^b, \quad \hat{d}_\alpha^\beta = \delta_\alpha^\beta,$$

$$\{\kappa_{abc} : \kappa_{123} = 1, \kappa_{344} = -1\}, \quad \{\hat{\kappa}_{\alpha\beta} : \hat{\kappa}_{311} = -1\}, \tag{B.13}$$

which slightly differs from the notations of [9, 10]. Now we consider the holomorphic three-form  $\Omega_3$  to be of the following form,

$$\Omega_3 \equiv \mathcal{X}^K \alpha_K - \mathcal{F}_K \beta^K = \frac{1-i}{2\sqrt{U}} dz^1 \wedge dz^2 \wedge dz^3$$

$$= \frac{1}{2\sqrt{U}} \left[ \alpha_0 + U \alpha_1 + i U \beta^0 + i \beta^1 \right]. \tag{B.14}$$

From this holomorphic three-form  $\Omega_3$ , one reads the period vectors to be given as under,

$$\mathcal{X}^0 = \frac{1}{2\sqrt{U}} = i \mathcal{F}_1, \quad \mathcal{X}^1 = \frac{\sqrt{U}}{2} = i \mathcal{F}_0. \tag{B.15}$$

Now using the definitions of chiral variable given as  $n'^K \equiv \text{Im} N^K = e^{-D} \mathcal{X}^K$ , one observes that the following relation holds,

$$\mathcal{X}^0 \mathcal{X}^1 = \frac{1}{4} \implies 4 e^{2D} n'^0 n'^1 = 1, \tag{B.16}$$

which implies that the Kähler potential in the quaternion sector can be written as under,

$$K_Q \equiv 4 D = -2 \ln (4 n'^0 n'^1). \tag{B.17}$$

Comparing this Kähler potential  $K_Q$  with the relation  $K_Q = -2 \ln (4 i \mathcal{F}(n'^I))$  [34], one finds that  $K_Q$  is determined by a prepotential of the following form,

$$\mathcal{F}(n'^I) = -i n'^0 n'^1, \tag{B.18}$$

which is a homogeneous function of degree 2 in the  $n'^I$  variables.

Using the various even/odd forms in Table 8 and the flux actions given in Eq. (A.1), one finds the following non-zero components for the various  $H, \omega, Q$  and  $R$  fluxes,

$$H_{136} = -H_{246} = H_{146} = H_{236},$$

$$R^{136} = -R^{246} = -R^{146} = -R^{236},$$

$$H_{135} = -H_{245} = -H_{145} = -H_{235},$$

$$R^{135} = -R^{245} = R^{145} = R^{235},$$

$$\omega_{13}^5 = \omega_{14}^5 = \omega_{23}^5 = -\omega_{24}^5,$$

$$Q_1^{35} = -Q_1^{45} = -Q_2^{35} = -Q_2^{45},$$

$$\omega_{13}^6 = -\omega_{14}^6 = -\omega_{23}^6 = -\omega_{24}^6,$$

$$Q_1^{36} = Q_1^{46} = Q_2^{36} = -Q_2^{46},$$

$$\omega_{15}^1 = -\omega_{25}^2,$$

$$Q_6^{13} = Q_6^{14} = Q_6^{23} = -Q_6^{24},$$

$$\omega_{35}^1 = \omega_{35}^2 = -\omega_{45}^2 = \omega_{45}^1,$$

$$Q_1^{16} = -Q_2^{26},$$

$$\omega_{46}^1 = -\omega_{36}^1 = \omega_{36}^2 = \omega_{46}^2,$$

$$Q_3^{51} = -Q_3^{52} = -Q_4^{52} = -Q_4^{51},$$

$$\omega_{36}^3 = -\omega_{46}^4,$$

$$Q_2^{51} = -Q_1^{25},$$

$$\omega_{51}^3 = \omega_{51}^4 = \omega_{52}^3 = -\omega_{52}^4,$$

$$Q_3^{35} = -Q_4^{45},$$

$$\omega_{45}^3 = -\omega_{53}^4,$$

$$Q_3^{61} = Q_4^{61} = Q_3^{62} = -Q_4^{62},$$



$$\begin{aligned}
 \omega_{26}^1 &= -\omega_{61}^2, \\
 Q_3^{46} &= -Q_4^{63}, \\
 \omega_{62}^3 &= -\omega_{61}^3 = \omega_{61}^4 = \omega_{62}^4, \\
 Q_5^{13} &= -Q_5^{14} = -Q_5^{23} = -Q_5^{24}.
 \end{aligned}
 \tag{B.19}$$

Note that 12 components out of 20 for each of the  $H_{ijk}$ -flux and the  $R^{ijk}$ -flux, while 58 components out of 90 for each of the  $\omega_{ij}^k$ -flux and  $Q_i^{jk}$ -flux, are identically zero under this orientifold construction. Moreover, all the non-zero components are not independent, and we find that there are 6 constraints among the 8 non-zero components for each of the  $H_{ijk}$ -flux and the  $R^{ijk}$ -flux while there are 22 constraints among the 32 non-zero components for each of the  $\omega_{ij}^k$ -flux and  $Q_i^{jk}$ -flux. Subsequently it turns out that there are only two independent flux components for each of the  $H_{ijk}$  and  $R^{ijk}$  flux while there are only 10 independent flux components for each of the  $\omega_{ij}^k$  and  $Q_i^{jk}$  fluxes. These details are collected in Eq. (B.19) while the cohomology version of the flux components are presented the Eq. (3.9). Also, from the collection of the various non-zero flux components in Eq. (B.19) it is obvious to observe that the tracelessness condition (2.8) is indeed satisfied.

Model B2

Now we consider a different construction for the same orbifold  $\mathbb{T}^6/\mathbb{Z}_4$ , which has been used for studying supersymmetric moduli stabilization with the non-geometric fluxes in [10]. In this case, the complexified coordinates on the  $\mathbb{T}^6$  torus is defined with a shift in the real component of  $z^3$  as compared to the previous case. This is given as under,

$$\begin{aligned}
 z^1 &= x^1 + i x^2, \quad z^2 = x^3 + i x^4, \\
 z^3 &= x^5 + \left(\frac{1}{2} + i U\right) x^6.
 \end{aligned}
 \tag{B.20}$$

While the orbifold action  $\mathbb{Z}_4$ , the anti-holomorphic involution  $\sigma$ , the two-form bases  $(\mu_\alpha, \nu_a)$ , the four-form bases  $(\tilde{\mu}^\alpha, \tilde{\nu}^a)$  and the six-form  $(\Phi_6)$  remain the same as before, the new three-form basis is taken as under,

$$\begin{aligned}
 \alpha_0 &= 1 \wedge 3 \wedge 5 + 1 \wedge 3 \wedge 6 + 1 \wedge 4 \wedge 5 \\
 &\quad + 2 \wedge 3 \wedge 5 - 2 \wedge 4 \wedge 5 - 2 \wedge 4 \wedge 6, \\
 \alpha_1 &= 1 \wedge 3 \wedge 5 + 1 \wedge 4 \wedge 5 + 1 \wedge 4 \wedge 6 + 2 \wedge 3 \wedge 5 \\
 &\quad + 2 \wedge 3 \wedge 6 - 2 \wedge 4 \wedge 5, \\
 \beta^0 &= -1 \wedge 3 \wedge 5 + 1 \wedge 4 \wedge 5 + 1 \wedge 4 \wedge 6 + 2 \wedge 3 \wedge 5 \\
 &\quad + 2 \wedge 3 \wedge 6 + 2 \wedge 4 \wedge 5, \\
 \beta^1 &= 1 \wedge 3 \wedge 5 + 1 \wedge 3 \wedge 6 - 1 \wedge 4 \wedge 5 - 2 \wedge 3 \wedge 5 \\
 &\quad - 2 \wedge 4 \wedge 5 - 2 \wedge 4 \wedge 6,
 \end{aligned}
 \tag{B.21}$$

where as before  $1 \wedge 3 \wedge 5 = dx^1 \wedge dx^3 \wedge dx^5$  etc., and one can easily check that  $\alpha_K$ 's are even under involution while  $\beta^K$ 's

are odd under the involution. We consider the holomorphic three-form  $\Omega_3$  to take the following form,

$$\begin{aligned}
 \Omega_3 &\equiv \mathcal{X}^K \alpha_K - \mathcal{F}_K \beta^K = \frac{1-i}{2\sqrt{U}} dz^1 \wedge dz^2 \wedge dz^3 \\
 &= \frac{1}{2\sqrt{U}} \left[ \left(\frac{1}{2} + U\right) \alpha_0 + \left(\frac{1}{2} - U\right) \alpha_1 \right. \\
 &\quad \left. + i \left(\frac{1}{2} + U\right) \beta^0 - i \left(\frac{1}{2} - U\right) \beta^1 \right].
 \end{aligned}
 \tag{B.22}$$

From these relations, the period vectors can be read-off as under,

$$\mathcal{X}^0 = \frac{1}{2\sqrt{U}} \left(\frac{1}{2} + U\right) = i \mathcal{F}_0, \quad \mathcal{X}^1 = \frac{1}{2\sqrt{U}} \left(\frac{1}{2} - U\right) = -i \mathcal{F}_1.
 \tag{B.23}$$

Now using the definitions of chiral variable given as  $n'^K \equiv \text{Im} N^K = e^{-D} \mathcal{X}^K$ , one observes that the following relation holds,

$$(\mathcal{X}^0)^2 - (\mathcal{X}^1)^2 = \frac{1}{2} \implies (n'^0)^2 - (n'^1)^2 = \frac{1}{2} e^{-2D},
 \tag{B.24}$$

which implies that the Kähler potential in the quaternion sector can be written as under,

$$K_Q \equiv 4D = -2 \ln \left( 2(n'^0)^2 - 2(n'^1)^2 \right).
 \tag{B.25}$$

Comparing this Kähler potential  $K_Q$  with the relation  $K_Q = -2 \ln \left( 4i \mathcal{F}(n'^I) \right)$  [34], one finds that  $K_Q$  is determined by a prepotential of the following form,

$$\mathcal{F}(n'^I) = -\frac{i}{2} \left[ (n'^0)^2 - (n'^1)^2 \right],
 \tag{B.26}$$

which is again a homogeneous function of degree 2 in the  $n'^I$  variables as expected.

Using the various even/odd forms in Table 8 and the flux actions given in Eq. (A.1), one finds the following non-zero components for the various  $H, \omega, Q$  and  $R$  fluxes [10],

$$\begin{aligned}
 H_{136} &= -H_{246}, \quad R^{135} = -R^{245}, \\
 H_{135} &= -H_{245} = -H_{145} = -H_{235}, \\
 R^{136} &= -R^{246} = -R^{146} = -R^{236}, \\
 H_{146} &= H_{236} = -H_{135} + H_{136} \\
 R^{145} &= R^{235} = R^{135} + R^{136} \\
 \omega_{13}^5 &= -\omega_{24}^5, \quad Q_1^{35} = -Q_2^{45}, \\
 \omega_{13}^6 &= -\omega_{14}^6 = -\omega_{23}^6 = -\omega_{24}^6, \\
 Q_1^{36} &= Q_1^{46} = Q_2^{36} = -Q_2^{46}, \\
 2\omega_{16}^1 &= \omega_{15}^1 = -\omega_{25}^2 = -2\omega_{26}^2, \\
 2Q_1^{15} &= -Q_1^{16} = -2Q_2^{25} = Q_2^{26},
 \end{aligned}$$

$$\begin{aligned}
\omega_{26}^1 &= -\omega_{61}^2, \\
2 Q_4^{35} &= -Q_4^{36} = 2 Q_3^{45} = -Q_3^{46}, \\
\omega_{36}^1 &= -\omega_{46}^2, Q_3^{51} = -Q_4^{52}, \omega_{46}^1 = \omega_{36}^2, \\
Q_2^{51} &= -Q_1^{25}, \omega_{16}^3 = \omega_{62}^4, \\
Q_3^{35} &= -Q_4^{45}, \omega_{26}^3 = \omega_{16}^4, \\
Q_3^{61} &= Q_4^{61} = Q_3^{62} = -Q_4^{62}, \\
\omega_{36}^3 &= -\omega_{46}^4, Q_6^{13} = -Q_6^{24}, \\
2 \omega_{46}^3 &= \omega_{45}^3 = \omega_{35}^4 = 2 \omega_{36}^4, \\
Q_5^{13} &= -Q_5^{14} = -Q_5^{23} = -Q_5^{24}, \\
\text{More constraints :} \\
\omega_{35}^1 &= \omega_{45}^1 = \omega_{35}^2 = -\omega_{45}^2 = \omega_{36}^1 + \omega_{46}^1, \\
Q_6^{14} &= Q_6^{23} = -Q_5^{13} + Q_6^{13}, \\
\omega_{15}^3 &= \omega_{25}^3 = \omega_{15}^4 = -\omega_{25}^4 = \omega_{16}^3 + \omega_{26}^3, \\
Q_4^{15} &= Q_3^{25} = -Q_3^{15} - Q_3^{16}, \\
\omega_{14}^5 &= \omega_{23}^5 = \omega_{13}^5 + \omega_{13}^6, \\
Q_2^{35} &= Q_1^{45} = -Q_1^{35} - Q_1^{36}. \tag{B.27}
\end{aligned}$$

Note that 12 components out of 20 for each of the  $H_{ijk}$ -flux and the  $R^{ijk}$ -flux, while 54 components out of 90 for each of the  $\omega_{ij}^k$ -flux and  $Q_i^{jk}$ -flux, are identically zero under this orientifold construction. Moreover, all the non-zero components are not independent, and we find that there are 6 constraints among the 8 non-zero components for each of the  $H_{ijk}$ -flux and the  $R^{ijk}$ -flux while there are 26 constraints among the 36 non-zero components for each of the  $\omega_{ij}^k$ -flux and  $Q_i^{jk}$ -flux. Subsequently it turns out that there are only two independent flux components for each of the  $H_{ijk}$  and  $R^{ijk}$  flux while there are only 10 independent flux components for each of the  $\omega_{ij}^k$  and  $Q_i^{jk}$  fluxes. These details are collected in Eq. (B.27) while the cohomology version of the flux components are presented the Eq. (3.10). Also, from the collection of the various non-zero flux components in Eq. (B.27) it is obvious to observe that the tracelessness condition (2.8) is trivially satisfied.

### C Cohomology version of the first formulation

#### Model A

In this section, we present a set of lengthy Bianchi identities for Model A.

#### Class (II) identities:

The explicit form of the 12 constraints translated from the first formulation identities using the conversion relations in

Eq. (3.1) can be collectively given as under,

$$\begin{aligned}
\omega_{22} \omega_{30} + \omega_{20} \omega_{32} &= H_2 Q^1_0 + H_0 Q^1_2, \\
\omega_{23} \omega_{30} + \omega_{20} \omega_{33} &= H_3 Q^1_0 + H_0 Q^1_3, \\
\omega_{11} \omega_{30} + \omega_{10} \omega_{31} &= H_1 Q^2_0 + H_0 Q^2_1, \\
\omega_{13} \omega_{30} + \omega_{10} \omega_{33} &= H_3 Q^2_0 + H_0 Q^2_3, \\
\omega_{11} \omega_{20} + \omega_{10} \omega_{21} &= H_1 Q^3_0 + H_0 Q^3_1, \\
\omega_{12} \omega_{20} + \omega_{10} \omega_{22} &= H_2 Q^3_0 + H_0 Q^3_2, \\
\omega_{22} \omega_{31} + \omega_{21} \omega_{32} &= H_2 Q^1_1 + H_1 Q^1_2, \\
\omega_{23} \omega_{31} + \omega_{21} \omega_{33} &= H_3 Q^1_1 + H_1 Q^1_3, \\
\omega_{13} \omega_{32} + \omega_{12} \omega_{33} &= H_3 Q^2_2 + H_2 Q^2_3, \\
\omega_{12} \omega_{31} + \omega_{11} \omega_{32} &= H_2 Q^2_1 + H_1 Q^2_2, \\
\omega_{13} \omega_{22} + \omega_{12} \omega_{23} &= H_3 Q^3_2 + H_2 Q^3_3, \\
\omega_{13} \omega_{21} + \omega_{11} \omega_{23} &= H_3 Q^3_1 + H_1 Q^3_3. \tag{C.1}
\end{aligned}$$

#### Class (III) identities:

The explicit expressions of the 24 constraints directly coming from translating the first formulation identities using the conversion relations in Eq. (3.1) can be collectively given as under,

$$\begin{aligned}
H_0 R_1 + \omega_{31} Q^3_0 &= \omega_{10} Q^1_1 + \omega_{20} Q^2_1, \\
H_1 R_0 + \omega_{30} Q^3_1 &= \omega_{11} Q^1_0 + \omega_{21} Q^2_0, \\
H_0 R_2 + \omega_{12} Q^1_0 &= \omega_{20} Q^2_2 + \omega_{30} Q^3_2, \\
H_2 R_0 + \omega_{30} Q^3_2 &= \omega_{12} Q^1_0 + \omega_{22} Q^2_0, \\
H_0 R_3 + \omega_{23} Q^2_0 &= \omega_{10} Q^1_3 + \omega_{30} Q^3_3, \\
H_3 R_0 + \omega_{10} Q^1_3 &= \omega_{23} Q^2_0 + \omega_{33} Q^3_0, \\
H_1 R_0 + \omega_{20} Q^2_1 &= \omega_{11} Q^1_0 + \omega_{31} Q^3_0, \\
H_0 R_1 + \omega_{21} Q^2_0 &= \omega_{10} Q^1_1 + \omega_{30} Q^3_1, \\
H_2 R_0 + \omega_{10} Q^1_2 &= \omega_{22} Q^2_0 + \omega_{32} Q^3_0, \\
H_0 R_2 + \omega_{32} Q^3_0 &= \omega_{10} Q^1_2 + \omega_{20} Q^2_2, \\
H_3 R_0 + \omega_{20} Q^2_3 &= \omega_{13} Q^1_0 + \omega_{33} Q^3_0, \\
H_0 R_3 + \omega_{13} Q^1_0 &= \omega_{20} Q^2_3 + \omega_{30} Q^3_3, \\
H_2 R_1 + \omega_{21} Q^2_2 &= \omega_{12} Q^1_1 + \omega_{32} Q^3_1, \\
H_2 R_1 + \omega_{11} Q^1_2 &= \omega_{22} Q^2_1 + \omega_{32} Q^3_1, \\
H_1 R_2 + \omega_{12} Q^1_1 &= \omega_{21} Q^2_2 + \omega_{31} Q^3_2, \\
H_1 R_2 + \omega_{22} Q^2_1 &= \omega_{11} Q^1_2 + \omega_{31} Q^3_2, \\
H_2 R_3 + \omega_{23} Q^2_2 &= \omega_{12} Q^1_3 + \omega_{32} Q^3_3, \\
H_2 R_3 + \omega_{33} Q^3_2 &= \omega_{12} Q^1_3 + \omega_{22} Q^2_3, \\
H_3 R_2 + \omega_{22} Q^2_3 &= \omega_{13} Q^1_2 + \omega_{33} Q^3_2, \\
H_3 R_2 + \omega_{32} Q^3_3 &= \omega_{13} Q^1_2 + \omega_{23} Q^2_2, \\
H_1 R_3 + \omega_{13} Q^1_1 &= \omega_{21} Q^2_3 + \omega_{31} Q^3_3, \\
H_1 R_3 + \omega_{33} Q^3_1 &= \omega_{11} Q^1_3 + \omega_{21} Q^2_3, \\
H_3 R_1 + \omega_{31} Q^3_3 &= \omega_{13} Q^1_1 + \omega_{23} Q^2_1,
\end{aligned}$$

$$H_3 R_1 + \omega_{11} Q^1_3 = \omega_{23} Q^2_1 + \omega_{33} Q^3_1. \tag{C.2}$$

However after some reshuffling, these 24 constraints are reduced into 18 constraints which consists of the following six constraints directly coming from the second formulation,

$$H_{[K} R_{J]} = \omega_{a[K} Q^a_{J]}, \quad \forall I, J \in \{0, 1, 2, 3\}. \tag{C.3}$$

In addition, there are 12 missing constraints collected as under,

$$\begin{aligned} H_0 R_1 + H_1 R_0 &= \omega_{11} Q^1_0 + \omega_{10} Q^1_1, \\ \omega_{21} Q^2_0 + \omega_{20} Q^2_1 &= \omega_{31} Q^3_0 + \omega_{30} Q^3_1, \\ H_0 R_2 + H_2 R_0 &= \omega_{22} Q^2_0 + \omega_{20} Q^2_2, \\ \omega_{12} Q^1_0 + \omega_{10} Q^1_2 &= \omega_{32} Q^3_0 + \omega_{30} Q^3_2, \\ H_0 R_3 + H_3 R_0 &= \omega_{33} Q^3_0 + \omega_{30} Q^3_3, \\ \omega_{13} Q^1_0 + \omega_{10} Q^1_3 &= \omega_{23} Q^2_0 + \omega_{20} Q^2_3, \\ H_1 R_2 + H_2 R_1 &= \omega_{32} Q^3_1 + \omega_{31} Q^3_2, \\ \omega_{12} Q^1_1 + \omega_{11} Q^1_2 &= \omega_{22} Q^2_1 + \omega_{21} Q^2_2, \\ H_2 R_3 + H_3 R_2 &= \omega_{13} Q^1_2 + \omega_{12} Q^1_3, \\ \omega_{23} Q^2_2 + \omega_{22} Q^2_3 &= \omega_{33} Q^3_2 + \omega_{32} Q^3_3, \\ H_3 R_1 + H_1 R_3 &= \omega_{23} Q^2_1 + \omega_{21} Q^2_3, \\ \omega_{13} Q^1_1 + \omega_{11} Q^1_3 &= \omega_{33} Q^3_1 + \omega_{31} Q^3_3. \end{aligned} \tag{C.4}$$

*Class (IV) identities:*

The explicit form of the 12 constraints translated from the first formulation identities using the conversion relations in Eq. (3.1) can be collectively given as under,

$$\begin{aligned} R_2 \omega_{30} + R_0 \omega_{32} &= Q^1_2 Q^2_0 + Q^1_0 Q^2_2, \\ R_1 \omega_{30} + R_0 \omega_{31} &= Q^1_1 Q^2_0 + Q^1_0 Q^2_1, \\ R_2 \omega_{10} + R_0 \omega_{12} &= Q^2_2 Q^3_0 + Q^2_0 Q^3_2, \\ R_3 \omega_{10} + R_0 \omega_{13} &= Q^2_3 Q^3_0 + Q^2_0 Q^3_3, \\ R_1 \omega_{20} + R_0 \omega_{21} &= Q^1_1 Q^3_0 + Q^1_0 Q^3_1, \\ R_3 \omega_{20} + R_0 \omega_{23} &= Q^1_3 Q^3_0 + Q^1_0 Q^3_3, \\ R_3 \omega_{32} + R_2 \omega_{33} &= Q^1_3 Q^2_2 + Q^1_2 Q^2_3, \\ R_3 \omega_{31} + R_1 \omega_{33} &= Q^1_3 Q^2_1 + Q^1_1 Q^2_3, \\ R_2 \omega_{11} + R_1 \omega_{12} &= Q^2_2 Q^3_1 + Q^2_1 Q^3_2, \\ R_3 \omega_{11} + R_1 \omega_{13} &= Q^2_3 Q^3_1 + Q^2_1 Q^3_3, \\ R_2 \omega_{21} + R_1 \omega_{22} &= Q^1_2 Q^3_1 + Q^1_1 Q^3_2, \\ R_3 \omega_{22} + R_2 \omega_{23} &= Q^1_3 Q^3_2 + Q^1_2 Q^3_3. \end{aligned} \tag{C.5}$$

Let us give some remarks on the four identities mentioned in Eq. (2.7). These are a set of weaker constraints which can be derived from the first formulation by contracting some more six-dimensional indices. We try to investigate if this collection is somehow directly related with some of the second formulation identities. It turns out that the first, the third and the fourth identities of Eq. (2.7) are trivially satisfied for

Model A while the second identity results in the following set of constraints,

$$\begin{aligned} H_2 R_1 + H_1 R_2 &= \omega_{32} Q^3_1 + \omega_{31} Q^3_2, \\ H_1 R_0 + H_0 R_1 &= \omega_{11} Q^1_0 + \omega_{10} Q^1_1, \\ H_3 R_2 + H_2 R_3 &= \omega_{13} Q^1_2 + \omega_{12} Q^1_3, \\ H_2 R_0 + H_0 R_2 &= \omega_{22} Q^2_0 + \omega_{20} Q^2_2, \\ H_3 R_1 + H_1 R_3 &= \omega_{23} Q^2_1 + \omega_{21} Q^2_3, \\ H_3 R_0 + H_0 R_3 &= \omega_{33} Q^3_0 + \omega_{30} Q^3_3. \end{aligned} \tag{C.6}$$

Notice that all of these identities are indeed contained in the generic constraints of class (III) as collected in Eq. (C.4) or in the compact collection of Eq. (3.5). In particular, the second and third relations in Eq. (3.5) are precisely these identities.

**Model B**

In this section, we present a set of lengthy Bianchi identities for Model B. Unlike the case for Model A, we do not present the results which directly come from translating the first formulation identities using the conversion relations in Eqs. (3.9) and (3.10) as the same are not only too lengthy to be presented but also are not very illuminating. However after reshuffling such relations, one can separate out the constraints which come from the second formulation, and in addition there are some which cannot be obtained from the second formulation. We present such identities in the following collections.

*Class (II) identities:*

In this case, there are 5 constraints which correspond to the second formulation, and the same are given as under,

$$\begin{aligned} H_0 \hat{Q}^{10} + H_1 \hat{Q}^{11} &= 0, \quad \omega_{10} \hat{\omega}_1^0 + \omega_{11} \hat{\omega}_1^1 = 0, \\ \omega_{20} \hat{\omega}_1^0 + \omega_{21} \hat{\omega}_1^1 &= 0, \quad \omega_{30} \hat{\omega}_1^0 + \omega_{31} \hat{\omega}_1^1 = 0, \\ \omega_{40} \hat{\omega}_1^0 + \omega_{41} \hat{\omega}_1^1 &= 0, \end{aligned} \tag{C.7}$$

while there are 11 constraints which are not the part of the second formulation. Nine of these are the followings which appears in both the Models B1 and B2,

$$\begin{aligned} H_0 Q^1_0 &= \omega_{20} \omega_{30}, \quad H_1 Q^1_1 = \omega_{21} \omega_{31}, \\ H_1 Q^1_0 + H_0 Q^1_1 &= \omega_{21} \omega_{30} + \omega_{20} \omega_{31}, \\ H_0 Q^2_0 &= \omega_{10} \omega_{30}, \quad H_1 Q^2_1 = \omega_{11} \omega_{31}, \\ H_1 Q^2_0 + H_0 Q^2_1 &= \omega_{11} \omega_{30} + \omega_{10} \omega_{31}, \\ H_0 Q^4_0 + \omega_{40} \omega_{30} &= 0, \quad H_1 Q^4_1 + \omega_{41} \omega_{31} = 0, \\ H_1 Q^4_0 + H_0 Q^4_1 + \omega_{31} \omega_{40} + \omega_{30} \omega_{41} &= 0, \end{aligned} \tag{C.8}$$

while there are two more identities which apparently differ in the two constructions, and these are given as under,

$$\text{Model B1 : } H_1 \hat{Q}^{11} - H_0 \hat{Q}^{10} + \omega_{31} \hat{\omega}_1^1 - \omega_{30} \hat{\omega}_1^0 = 0,$$

$$\begin{aligned}
& H_1 Q^3_0 + H_0 Q^3_1 - \omega_{10} \omega_{21} - \omega_{11} \omega_{20} + \omega_{40} \omega_{41} + \hat{\omega}_1^0 \hat{\omega}_1^1 = 0. \\
\text{Model B2 : } & H_1 \hat{Q}^{10} + H_0 \hat{Q}^{11} + \omega_{31} \hat{\omega}_1^0 + \omega_{30} \hat{\omega}_1^1 = 0, \\
& H_0 Q^3_0 - \omega_{10} \omega_{20} + \frac{1}{2} \omega_{40}^2 + \frac{1}{2} (\hat{\omega}_1^0)^2 \\
& = H_1 Q^3_1 - \omega_{11} \omega_{21} + \frac{1}{2} \omega_{41}^2 + \frac{1}{2} (\hat{\omega}_1^1)^2. \quad (\text{C.9})
\end{aligned}$$

*Class (III) identities:*

In this case, there are 10 constraints which correspond to the second formulation, and the same are given as under,

$$\begin{aligned}
& \hat{\omega}_1^0 Q^1_0 + \hat{\omega}_1^1 Q^1_1 = 0, \quad \hat{\omega}_1^0 Q^2_0 + \hat{\omega}_1^1 Q^2_1 = 0, \\
& \hat{\omega}_1^0 Q^3_0 + \hat{\omega}_1^1 Q^3_1 = 0, \\
& \hat{\omega}_1^0 Q^4_0 + \hat{\omega}_1^1 Q^4_1 = 0, \quad \hat{Q}^{10} \omega_{10} + \hat{Q}^{11} \omega_{11} = 0, \\
& \hat{Q}^{10} \omega_{20} + \hat{Q}^{11} \omega_{21} = 0, \\
& \hat{Q}^{10} \omega_{30} + \hat{Q}^{11} \omega_{31} = 0, \quad \hat{Q}^{10} \omega_{40} + \hat{Q}^{11} \omega_{41} = 0, \\
& \hat{\omega}_1^0 \hat{Q}^{11} - \hat{\omega}_1^1 \hat{Q}^{10} = 0, \\
& H_0 R_1 - \omega_{10} Q^1_1 - \omega_{20} Q^2_1 - \omega_{30} Q^3_1 - \omega_{40} Q^4_1 \\
& = H_1 R_0 - \omega_{11} Q^1_0 - \omega_{21} Q^2_0 - \omega_{31} Q^3_0 - \omega_{41} Q^4_0, \quad (\text{C.10})
\end{aligned}$$

while there are 16 constraints which are not the part of the second formulation. Twelve of these constraints are the followings which appear in both the Models B1 and B2,

$$\begin{aligned}
& H_0 R_0 = \omega_{30} Q^3_0, \quad H_1 R_1 = \omega_{31} Q^3_1, \\
& H_0 R_1 + H_1 R_0 = \omega_{30} Q^3_1 + \omega_{31} Q^3_0, \\
& \omega_{10} Q^1_0 = \omega_{20} Q^2_0, \\
& \omega_{11} Q^1_1 = \omega_{21} Q^2_1, \quad \omega_{11} Q^1_0 + \omega_{10} Q^1_1 \\
& = \omega_{21} Q^2_0 + \omega_{20} Q^2_1, \\
& \omega_{40} Q^1_0 + \omega_{20} Q^4_0 = 0, \quad \omega_{41} Q^1_1 + \omega_{21} Q^4_1 = 0, \\
& \omega_{41} Q^1_0 + \omega_{40} Q^1_1 + \omega_{21} Q^4_0 + \omega_{20} Q^4_1 = 0, \\
& \omega_{40} Q^2_0 + \omega_{10} Q^4_0 = 0, \quad \omega_{41} Q^2_1 + \omega_{11} Q^4_1 = 0, \\
& \omega_{41} Q^2_0 + \omega_{40} Q^2_1 + \omega_{11} Q^4_0 + \omega_{10} Q^4_1 = 0, \quad (\text{C.11})
\end{aligned}$$

while there are four more identities which apparently differ in the two constructions, and these are given as under,

$$\begin{aligned}
\text{Model B1 : } & Q^1_0 \hat{\omega}_1^0 - Q^1_1 \hat{\omega}_1^1 \\
& = \omega_{21} \hat{Q}^{11} - \omega_{20} \hat{Q}^{10}, \\
& Q^2_0 \hat{\omega}_1^0 - Q^2_1 \hat{\omega}_1^1 = \omega_{11} \hat{Q}^{11} \\
& - \omega_{10} \hat{Q}^{10}, \quad Q^4_0 \hat{\omega}_1^0 - Q^4_1 \hat{\omega}_1^1 \\
& = \omega_{40} \hat{Q}^{10} - \omega_{41} \hat{Q}^{11}, \\
& H_0 R_1 + H_1 R_0 - \omega_{11} Q^1_0 \\
& - \omega_{10} Q^1_1 - \omega_{21} Q^2_0 - \omega_{20} Q^2_1 \\
& + \omega_{31} Q^3_0 + \omega_{30} Q^3_1 + \omega_{41} Q^4_0 \\
& + \omega_{40} Q^4_1 + \hat{\omega}_1^0 \hat{Q}^{11} + \hat{\omega}_1^1 \hat{Q}^{10} = 0,
\end{aligned}$$

$$\begin{aligned}
\text{Model B2 : } & Q^1_1 \hat{\omega}_1^0 + Q^1_0 \hat{\omega}_1^1 \\
& + \omega_{21} \hat{Q}^{10} + \omega_{20} \hat{Q}^{11} = 0, \\
& Q^2_1 \hat{\omega}_1^0 + Q^2_0 \hat{\omega}_1^1 + \omega_{11} \hat{Q}^{10} + \omega_{10} \hat{Q}^{11} = 0, \\
& Q^4_1 \hat{\omega}_1^0 + Q^4_0 \hat{\omega}_1^1 + \omega_{41} \hat{Q}^{10} \\
& + \omega_{40} \hat{Q}^{11} = 0, \\
& H_0 R_0 - \omega_{10} Q^1_0 - \omega_{20} Q^2_0 + \omega_{30} Q^3_0 \\
& + \omega_{40} Q^4_0 + \hat{\omega}_1^0 \hat{Q}^{10} \\
& = H_1 R_1 - \omega_{11} Q^1_1 - \omega_{21} Q^2_1 + \omega_{31} Q^3_1 \\
& + \omega_{41} Q^4_1 + \hat{\omega}_1^1 \hat{Q}^{11}. \quad (\text{C.12})
\end{aligned}$$

*Class (IV) identities:*

In this case, there are 5 constraints which correspond to the second formulation, and the same are given as under,

$$\begin{aligned}
& R_0 \hat{\omega}_1^0 + R_1 \hat{\omega}_1^1 = 0, \quad Q^1_0 \hat{Q}^{10} + Q^1_1 \hat{Q}^{11} = 0, \\
& Q^2_0 \hat{Q}^{10} + Q^2_1 \hat{Q}^{11} = 0, \quad Q^3_0 \hat{Q}^{10} + Q^3_1 \hat{Q}^{11} = 0, \\
& Q^4_0 \hat{Q}^{10} + Q^4_1 \hat{Q}^{11} = 0, \quad (\text{C.13})
\end{aligned}$$

while there are 11 constraints which are not the part of the second formulation. Nine of these are the followings which appears in both the Models B1 and B2,

$$\begin{aligned}
& Q^1_0 Q^3_0 = R_0 \omega_{20}, \\
& Q^1_1 Q^3_1 = R_1 \omega_{21}, \quad Q^1_1 Q^3_0 + Q^1_0 Q^3_1 \\
& = R_1 \omega_{20} + R_0 \omega_{21}, \\
& Q^2_0 Q^3_0 = R_0 \omega_{10}, \quad Q^2_1 Q^3_1 \\
& = R_1 \omega_{11}, \\
& Q^2_1 Q^3_0 + Q^2_0 Q^3_1 = R_1 \omega_{10} + R_0 \omega_{11}, \\
& Q^4_0 Q^3_0 + R_0 \omega_{40} = 0, \quad Q^4_1 Q^3_1 + R_1 \omega_{41} = 0, \\
& Q^3_1 Q^4_0 + Q^3_0 Q^4_1 + R_1 \omega_{40} + R_0 \omega_{41} = 0, \quad (\text{C.14})
\end{aligned}$$

while there are two more identities which apparently differ in the two constructions, and these are given as under,

$$\begin{aligned}
\text{Model B1 : } & Q^3_0 \hat{Q}^{10} - Q^3_1 \hat{Q}^{11} + R_0 \hat{\omega}_1^0 - R_1 \hat{\omega}_1^1 = 0, \\
& R_0 \omega_{31} + R_1 \omega_{30} - Q^1_1 Q^2_0 - Q^1_0 Q^2_1 + Q^4_0 Q^4_1 \\
& + \hat{Q}^{10} \hat{Q}^{11} = 0.
\end{aligned}$$

**Table 9** A correlation of the weaker first formulation identities in Model A and Model B

BIs	First formulation	Second formulation
(1)	$2 H_{klm} R^{klm} = 3 \omega_{kl}^k Q_m^{lm}$ (Trivial)	Model A: Trivial Model B: Trivial
(2)	$H_{kl[\bar{i}} Q_{\bar{j}]^{kl}} - \frac{1}{2} Q_k^{kl} H_{lij} = \frac{1}{2} \omega_{kl}^k \omega_{ij}^l$	Model A: Trivial Model B: $H_K \hat{Q}^{\alpha K} = 0$
(3)	$\omega_{kl}[\bar{i} R^{kl\bar{j}}] + \frac{1}{2} \omega_{kl}^k R^{lij} + \frac{1}{2} Q_k^{kl} Q_l^{ij} = 0$	Model A: Trivial Model B: $R_K \hat{\omega}_\alpha^K = 0$
(4)	$H_{kli} R^{klj} = Q_i^{kl} \omega_{kl}^j + \omega_{kl}^k Q_i^{lj} + Q_k^{kl} \omega_{li}^j$	Model A: Eq. (C.6) Model B: Eq. (C.18)

$$\begin{aligned} \text{Model B2 : } & Q^3_1 \hat{Q}^{10} + Q^3_0 \hat{Q}^{11} + R_1 \hat{\omega}_1^0 + R_0 \hat{\omega}_1^1 = 0, \\ & R_0 \omega_{30} - Q^1_0 Q^2_0 + \frac{1}{2} (Q^4_0)^2 + \frac{1}{2} (\hat{Q}^{10})^2 = R_1 \omega_{31} \\ & - Q^1_1 Q^2_1 + \frac{1}{2} (Q^4_1)^2 + \frac{1}{2} (\hat{Q}^{11})^2. \end{aligned} \tag{C.15}$$

On the lines of the discussion on the (2, 1)-cohomology structure in Sect. 4, we find that the apparent different constraints in each of the three classes, namely (II), (III) and (IV), are also correlated, and can be combined into the following relations,

$$\begin{aligned} & l_{0JK}^{-1} \left[ H_{(J} Q^3_{K)} - \frac{1}{2} \kappa_{3bc}^{-1} \omega_b{}_{(J} \omega_c{}_{K)} \right] \\ & = l_{0JK} \left[ \frac{1}{2} \hat{\kappa}_{3\alpha\beta}^{-1} \hat{\omega}_\alpha{}_{(J} \hat{\omega}_\beta{}_{K)} \right] \quad \forall J, K, \\ & l_{0JK}^{-1} \left[ 3 H_{(J} R_{K)} - Q^a{}_{(J} \omega_a{}_{K)} \right] = l_{0JK} \hat{Q}^{\alpha(J} \hat{\omega}_\alpha{}^{K)} \quad \forall J, K, \\ & l_{0JK}^{-1} \left[ R_{(J} \omega_{3K)} - \frac{1}{2} \kappa_{3bc} Q^b{}_{(J} Q^c{}_{K)} \right] \\ & = l_{0JK} \left[ \frac{1}{2} \hat{\kappa}_{3\alpha\beta} \hat{Q}^\alpha{}_{(J} \hat{Q}^\beta{}_{K)} \right] \quad \forall J, K. \end{aligned} \tag{C.16}$$

Finally, let us give some remarks on the four identities mentioned in Eq. (2.7). In this case it turns out that the fourth identity in Eq. (2.7) is trivially satisfied while the first and third one give a single constraint each which can be rewritten as

$$H_0 \hat{Q}^{10} + H_1 \hat{Q}^{11} = 0, \quad R_0 \hat{\omega}_1^0 + R_1 \hat{\omega}_1^1 = 0, \tag{C.17}$$

which are the same as those of the second formulation. In addition, the most complicated identity out of (2.7) turns out to be the second one which, with a little bit of reshuffling and after being accompanied with the second formulation constraints along with condition (3.11), can produce the following six ‘missing’ constraints,

$$\begin{aligned} \text{Model B1 : } & H_0 R_0 = \omega_{30} Q^3_0, \quad H_1 R_1 = \omega_{31} Q^3_1, \\ & H_0 R_1 + H_1 R_0 = \omega_{10} Q^1_1 + \omega_{11} Q^1_0 \\ & = \omega_{20} Q^2_1 + \omega_{21} Q^2_0, \\ & \omega_{40} Q^2_0 + \omega_{11} Q^4_1 = \omega_{41} Q^2_1 + \omega_{10} Q^4_0, \\ & \omega_{40} Q^1_0 + \omega_{21} Q^4_1 = \omega_{41} Q^1_1 + \omega_{20} Q^4_0, \\ \text{Model B2 : } & 2H_0 R_0 - \omega_{10} Q^1_0 - \omega_{20} Q^2_0 \\ & = 2H_1 R_1 - \omega_{11} Q^1_1 - \omega_{21} Q^2_1, \end{aligned}$$

$$\begin{aligned} H_0 R_0 + H_1 R_1 &= \omega_{30} Q^3_0 + \omega_{31} Q^3_1, \quad H_0 R_1 \\ &+ H_1 R_0 = \omega_{30} Q^3_1 + \omega_{31} Q^3_0, \\ \omega_{40} Q^1_0 + \omega_{20} Q^4_0 &= \omega_{41} Q^1_1 + \omega_{21} Q^4_1, \\ \omega_{40} Q^2_0 + \omega_{10} Q^4_0 &= \omega_{41} Q^2_1 + \omega_{11} Q^4_1, \\ \omega_{10} Q^1_0 + \omega_{21} Q^2_1 &= \omega_{11} Q^1_1 + \omega_{20} Q^2_0, \end{aligned} \tag{C.18}$$

which is indeed a subset of the identities arising from their respective first formulation.

We summarize the correlation of the weaker first formulation identities for the Model A and Model B in Table 9.

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