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Notice of Modification

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Dear readers,

In the paper “An Anthropomorphic Robot Hand Developed Based on Underactuated Mechanism and Controlled by EMG Signals”, *Journal of Bionic Engineering*, 2009, **6**, 255–263, by Dapeng Yang *et al.*, we adopted an experimental method already developed by the DLR (German Aerospace Center). Unfortunately, we did not cite their main works properly at that time. We sincerely apologize for this mistake to Dr. Castellini, Dr. van der Smagt and other coauthors.

More details about the use of OttoBock's electrodes, the use of a Support Vector Machine for classification, the data analysis and use of the terms "session" and "group", and the presentation of accuracy results can be found in these papers by Castellini *et al.*:

- [1] Castellini C, van der Smagt P, Sandini G, and Hirzinger G. Surface EMG for Force Control of Mechanical Hands. *Proceedings of International Conference on Robotics and Automation*, Pasadena, CA, USA, 2008, 725-730.
- [2] Castellini C, van der Smagt P. Surface EMG in Advanced Hand Prosthetics. *Biological Cybernetics*, 2009, **100**, 35-47.