





Research Article

# An ensemble learning estimation of the effect of magnetic coupling on switching frequency value in wireless power transfer system for electric vehicles



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#### **Abstract**

Wireless power transmission (WPT) systems of small power levels used in the medical and communications sectors have been developed in recent years for tens of kW power levels for charging stations of electric vehicles. In wireless charging systems, power transfer is provided by magnetic coupling using coreless transformers, and in these systems, power electronics circuit design is the crucial point. The inductor behavior as a series resonance circuit element required in the power electronics circuit of WPT systems varies according to the magnetic coupling positioning errors between the primary and secondary sides of the coreless transformer. Therefore, the considering that the resonant capacitor value is constant in the resonance tank circuit, the switching frequency value in the power electronics circuit must be adaptively controlled so that the transferred power value can be carried out efficiently. In this study, the parametric simulations have been performed using Ansys-Electronics software to adaptively control the switching frequency value in the inverter circuit depending on the magnetic coupling coefficients in the WPT circuit designed at a power value of 25 kW. Based on the data obtained from these simulation studies according to different scenarios, the switching frequency value can be changed adaptively and thus the WPT efficiency can be kept at a certain level by providing resonance in each condition. Also, 105 efficiency data were obtained by using Ansys-Electronics parametric solver for many variables such as coreless transformer, resonant circuit parameters of power electronic circuit, switching frequency and magnetic coupling. The WPT efficiency is predicted by ensemble decision trees algorithm. The results show that the estimation with ensemble decision trees is quite successful.

**Keywords** Wireless charging systems  $\cdot$  Electric vehicle  $\cdot$  Coreless transformer  $\cdot$  Magnetic coupling  $\cdot$  Resonant converter  $\cdot$  Ensemble decision trees

### 1 Introduction

Environmental damage of fossil fuel vehicles and the possibility of depletion of fossil fuels in the future have accelerated the development of electric vehicles (EVs) in recent years [1]. Because of the increasing number of electric vehicles, charging stations can be designed as wired and/or wireless systems for charging. Efforts to improve the efficiency of wireless charging systems

are still ongoing, but they also have advantages due to mechanical and safety problems in wired systems [2]. The use of coreless transformers is common in WPT charging systems and the determination of electromagnetic behavior is an important issue in power electronics circuit design. However, in conventional core transformers, it has been shown that the use of low frequency magnetic waves is effective for WPT from reinforced concrete walls when a magnetic wave under 400 Hz is

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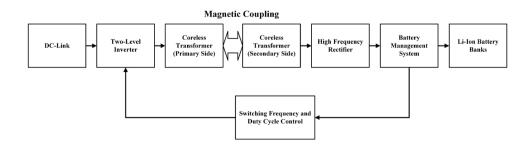
used [3]. On the other hand, in coreless WPT systems, the switching elements of the inverters generally operate at medium and high frequency values. Designs with high frequency soft magnetic materials (such as Ferrite core) are also available in the literature.

The resonance frequency changes continuously depending on the length of the air gap between the primary (transmitter) and the secondary (receiver) coils, and the positioning errors. The maximum efficiency does not change up to a certain distance. Large air gaps result in loosely magnetic coupling. With a tightly magnetic coupling in the resonance, electrical energy can be transferred in high efficiency. In a study conducted in this context, the applicability of WPT with high efficiency was proposed by using small size antennas that can be placed under the EVs [4]. The design of the series resonant coils and the switching frequency selection are the main design factors for the high efficiency of WPT system, for the high power transmission efficiency and reduction of the electromagnetic fields emitted around the system [5–7].

In [8], the basic principles of WPT using magnetic field resonance are introduced and techniques for the design of a series of resonance magnetic coils, the formation of magnetic field distribution, and electromagnetic field (EMF) noise reduction methods are described. Various electric vehicle charging methods without cable extensions are under development, or are now used as aftermarket options in the automotive market. WPT is an accepted term for wireless charging. It is also used synonymously with Inductive Power Transmission (IPT) and Magnetic Resonance Coupling (MRC). WPT technology is on the onset; it lacks methods for standardization, in particular interoperability, switching frequency selection, magnetic fringe field suppression, and power flow regulation. A new analysis concept is proposed which is the similar to the power transmission grid with primary frequency selection and reactive power voltage control with the set secondary side for the power flow in WPT [9].

In the literature for WPT systems, studies have generally been carried out on systems with a single-phase transformer. On the other hand, [10] proposes a system capable of dynamically transmitting three-phase power system and tested on an electric train prototype [11, 12].

**Fig. 1** Block diagram of the three-phase WPT charging system



In this study, parametric simulation has been proposed to prevent breaks from resonance due to magnetic coupling coefficient and to realize adaptive frequency and duty cycle control. After the simulation studies, in order to provide adaptive frequency control, various switching frequency and duty cycle values according to the magnetic coupling coefficients were determined. Thus, the switching frequency values were reported graphically according to the coupling coefficients in order to achieve optimum efficiency, and 105 efficiency data were obtained by using parametric solver for many variables such as coreless transformer, resonant circuit parameters of power electronic circuit, switching frequency and magnetic coupling.

## 2 Coreless transformer equivalent circuit and coupling effect

The proposed block diagram of the three-phase WPT system is shown in Fig. 1. This system consists of a star/star-connected three-phase coreless transformer and a three-phase two-level voltage source inverter circuit. The power supply of the charging station is the AC–DC converter circuit that rectifies the three-phase grid with the power-factor-correction (PFC) rectifier circuit.

The switching of the inverter circuit is performed at the switching frequency value determined by the leakage inductance value of the coreless transformer and the series resonant capacitor with fixed value. However, the magnetic coupling between the primary and the secondary sides may vary in positioning errors and in this condition the resonance is disturbed. In this context, the switching frequency must be changed in order to restore the resonance.

The primary and secondary sides of the three-phase coreless transformer, which is recommended for WPT, are connected as star/star in Fig. 2. Since the equivalent inductance value from the primary side of this transformer is an important variable for the resonance circuit, equations can be written for the coupling coefficient. The coupling effect between the primary and secondary depends on the distance between each other, and for loosely/tightly coupling. If the coupling coefficient is less than 0.5, it can be said as

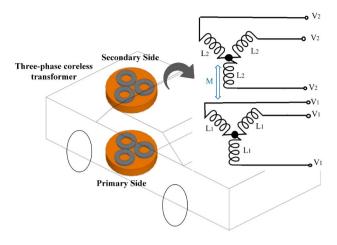


Fig. 2 WPT system modeling and the three-phase coreless transformer connection

loosely coupling, and if it is above 0.5, it can be said as tightly coupling. Furthermore, the magnetic coupling is made worse if the electric vehicle stops at the charging point, not exactly on the axis. Thus, both resonance circuit parameters are affected and system efficiency is deteriorated [13].

The topology of the resonant circuit is shown in Fig. 3, wherein the three-phase coreless transformer is analyzed in a single phase equivalent circuit.  $R_1$  and  $R_2$  are defined as the primary and secondary coil equivalent series resistance (ESR). Thus, a simple AC circuit analysis can be performed. By using the relationship between primary current  $I_1$  and secondary current  $I_2$  in Eqs. 1–3, WPT efficiency can be approximately obtained as in Eq. 3.

As can be seen in Eqs. 1–3, energy transfer efficiency is closely related to the coupling factor and the quality factor of the resonant network. If the squares of the operating frequencies are sufficiently large than  $R_1(R_L + R_2)/M_2$ , the maximum efficiency can be obtained approximately by Eq. 3 [8, 14, 15].

$$\eta = \frac{I_2^2 R_L}{I_1^2 R_1 + I_2^2 R_2 + I_2^2 R_L} = \frac{R_L}{(R_L + R_2) \left[ 1 + \frac{R_1 (R_L + R_2)}{w_2^2 M^2} \right]} \tag{1}$$

$$\frac{I_1}{I_2} = \frac{(R_2 + R_L)}{w_0 M} \tag{2}$$

**Fig. 3** Equivalent circuit of a three-phase coreless transformer according to one phase

$$\eta_{MAX} = \frac{R_L}{R_2 + R_L} \tag{3}$$

In general, in electromagnetic analysis, *L* represents the coil's self-inductance and is the ratio of the magnetic flux associated with a coil inducing the magnetic flux and the current flowing through the circuit as defined in Eq. 4 [16, 17]:

$$L = \frac{\Psi}{I} = \frac{\int \vec{B} \cdot d\vec{s}}{I} \tag{4}$$

where  $\Phi$ —magnetic flux through one turn of the coil,  $[\Phi] = 1Wb$ ,  $\Psi$ —magnetic flux associated with a coil,  $[\Psi] = 1Wb$ , z—number of turns, L—self-inductanse of coil, [L] = 1H, I—electric current, [I] = 1A.

$$M_{12} = \frac{\Psi_{12}}{I_1}[H] \tag{5}$$

And the same to the secondary side circuit as given in Eq. 6:

$$M_{21} = \frac{\Psi_{21}}{I_2}[H] \tag{6}$$

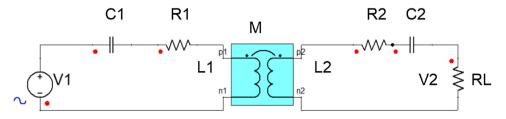
A conventional three-phase voltage source type square-wave inverter is selected as a converter circuit on the primary side [18]. From the magnetic coupling (kc) theory between the two coils, the resonance frequency ( $\omega_0$ ) can be expressed as follows [19]. The mutual inductance values between the primary and secondary are equal to each other so that the coupling coefficient  $L_1$  and  $L_2$  can be easily determined according to the self-inductance values as given in Eqs. 7–9.

$$M_{12} = M_{21} = M (7)$$

$$kc = \frac{M}{\sqrt{L_1 L_2}} \tag{8}$$

$$\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2}} \tag{9}$$

where  $L_1 = L_2$  is the self-inductance of the primary and secondary coils,  $C_1 = C_2$  is the series compensation



capacitance of the primary and secondary sides. Equation 8 can be written for the magnetic coupling coefficient between the two coils. *M* represents the mutual inductance between the primary and secondary coils. The relationship between the coupling coefficient (*kc*) and the distance between the two coils can be expressed as follows according to mechanical parameters in Eq. 10 [20]:

$$kc = \frac{1}{\left[1 + 2^{2/3} \left(\frac{D}{\sqrt{r_1 r_2}}\right)^2\right]^{3/2}}$$
 (10)

where D is the physical distance between the primary and secondary coils;  $r_1$  and  $r_2$  is the radius of the primary and secondary coils, respectively. It may be equivalent to the mutual inductance between the two coils shown in Fig. 4 [20].

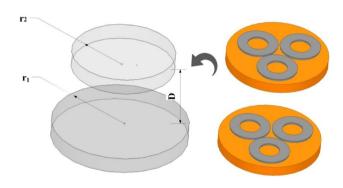


Fig. 4 Mechanical parameters of the coils [20]

### 3 Simulation studies

### 3.1 The parametric simulation of the proposed WPT system

Parametric simulation studies were performed with Ansys-Electronics Desktop 2019R2 software, depending on the switching frequency ( $f_s$ ), switching duty cycle (DC) and coupling coefficient (kc) variables as seen in Fig. 5. Using the obtained data, both switching frequency and duty ratio were tried to be determined depending on the coupling coefficient between the primary and secondary coils. Technical data and step intervals used in parametric simulation studies are given in Table 1.

The change in output voltage according to switching frequency and duty cycle values while coupling coefficient is at a certain value is given in Fig. 6. Fluctuations depending on the switching frequency are observed in low value key duty ratios. Since the coupling value is constant, this graph can only facilitate the determination of the switching frequency value for a given duty cycle value.

Table 1 Technical properties of the parametric simulation

Parameter	Value	Step interval	
$\overline{V_1}$	400 V	Constant	
$f_{_{\mathrm{SW}}}$	50-80 kHz	5 kHz	
DC	0.30-0.50	0.05	
k	0.1-0.8	0.05	
<i>L</i> 1	100 μΗ	Constant	
L2	100 μΗ	Constant	
C1-C2	150 nF	Constant	
$R_L$	10 ohms	Constant	

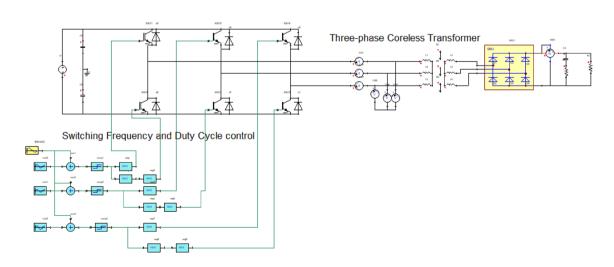
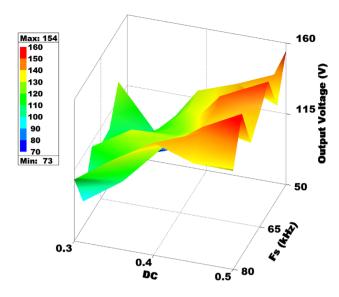
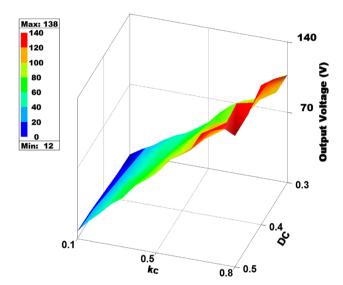


Fig. 5 Parametric simulation circuit



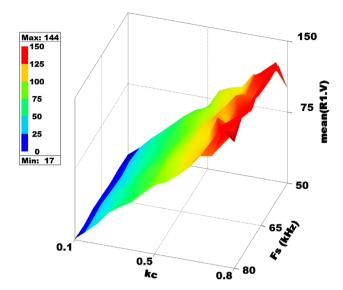
**Fig. 6** Output voltage change based on switching frequency and duty cycle



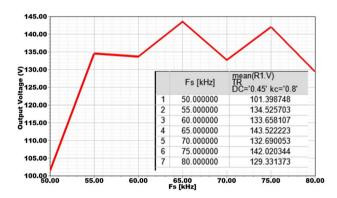
**Fig. 7** Output voltage change depending on magnetic coupling coefficient and duty cycle

In a given switching frequency value, the loose coupling and tight coupling effect can be explained by Fig. 7. According to this graph, if kc < 0.5, the voltage value transferred to the secondary side by loose coupling effect is low value and in this case the efficiency is quite poor. When the kc > 0.5, the voltage value transferred by tight coupling effect can be kept at the desired level by duty cycle control.

When the switching duty ratio is kept constant, the 3D voltage graph according to the change of switching frequency and coupling coefficient is given in Fig. 8. In this



**Fig. 8** Output voltage change depending on magnetic coupling coefficient and switching frequency value

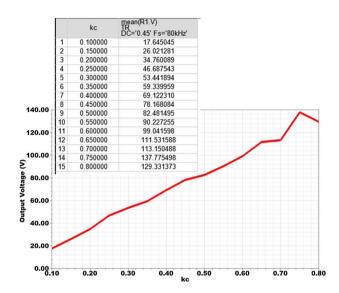


**Fig. 9** Output voltage change depending on switching frequency value when magnetic coupling coefficient and duty cycle are at constant values

graph, the switching frequency value can be determined according to the desired output voltage value for a certain value of the coupling coefficient.

For a constant value of the coupling coefficient, the variation of the voltage value depending on the switching frequency values is more clearly described in Fig. 9. Thus, values below 50 kHz switching frequency for kc = 0.8 and DC = 0.45 have a poor result for efficiency. From this graph, the switching frequency value at which the voltage level is maximum can be determined as 65 kHz. Thus, very useful data can be obtained before the prototype design for the optimum switching frequency value according to the coupling coefficient by parametric simulations of the power electronics circuit.

In order to explain the effect of the magnetic coupling coefficient in more detail, the voltage variation graph in Fig. 10 can be examined. Where, while DC = 0.45 and  $f_s = 80$  kHz, magnetic coupling values were simulated in specific steps in the range of 0.1–0.8 and voltage change was determined. In the simulation studies performed for proposed WPT system, the graphs were obtained according to the voltage value on a load connected to the output of the simulation circuit. Thus, the parametric data were obtained for the voltage value transferred to the load by the three phase coreless transformer design.



**Fig. 10** Output voltage change due to magnetic coupling coefficient value when switching frequency and duty cycle are constant values

The relationship between the change in duty cycle value and the output voltage value in the inverter circuit can be explained by the graph in Fig. 11 when  $f_s$  = 80 kHz and kc = 0.8. When DC = 0.4, voltage transfer is realized at maximum value, thus system efficiency is at highest values. It is seen that the duty cycle value changes the transferred output voltage value in the three phase two level inverter circuit, and the maximum value of the voltage can be determined with the help of this graph.

### 3.2 Ensemble learning

The ensemble learning method helps improve machine learning results by combining multiple learning model. The aim of the community model is that a group of learning methods come together to form a strong learner, thereby increasing the accuracy of the model. In the prediction study with machine learning techniques, the main reasons for the difference in actual and predicted values are caused by noise and variance. These factors are reduced by the ensemble method [21, 22].

In this study, ensemble decision trees were used. Bagging and boosting methods are used to create ensemble decision trees. In application, Bagging (Bootstrap Aggregation) was used to reduce the variance of the decision tree.  $f_s$ , kc and DC values were used as input and efficiency estimation was performed. 105 data obtained as a result of the simulation were separated into 80% training and 20% test. As a result of the application, the estimation error was calculated as 0.15 using Root Mean

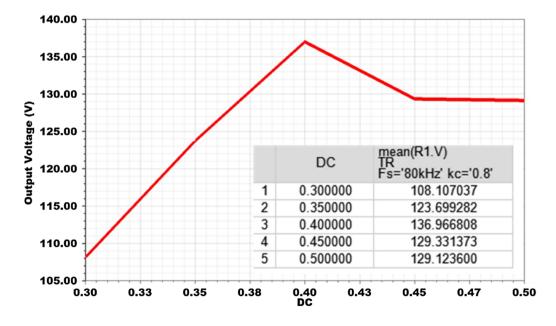
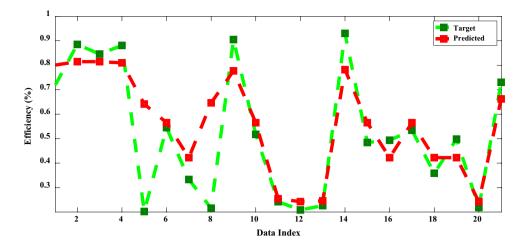


Fig. 11 Output voltage change based on duty cycle value when switching frequency and magnetic coupling values are at constant values

**Fig. 12** Predicted and target data



Squared Error (RMSE) metric. The actual and estimated values of the 21 test data used are shown in Fig. 12.

### 4 Conclusion

In this study, three phase WPT circuit which can be used to charge electric vehicles wirelessly is proposed. The parametric simulation of the switching duty ratio and switching frequency values has been realized with Ansys-Electronics software depending on the change of the magnetic coupling coefficient of the WPT resonant circuit within the system. With the obtained parametric data, 3D and 2D graphs were created, thus the power electronics circuit parameters were determined based on the change of coupling coefficient. The effects of parameter changes in nonlinear behavior which could not be determined with mathematical expressions were analyzed. For future scientific studies, adaptive frequency and duty cycle control of the power electronics circuit is recommended to prevent breakage from the resonance due to changing magnetic coupling due to position and alignment errors of WPT system efficiency. Finally, the WPT efficiency is predicted by ensemble decision trees algorithm. The results show that the estimation with ensemble decision trees is quite successful. For the future studies, the proposed and predicted parameters of the WPT system can be compared with the core transformer system to be designed with soft magnetic material.

### **Compliance with ethical standards**

**Conflict of interest** The authors declare that they have no conflict of interest.

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