Room temperature tensile deformation behavior of a Ni-based superalloy with high W content

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Abstract: K416B Ni-based superalloy with high W content has good high temperature properties and low cost, which has a great development potential. To investigate the room temperature tensile property and the deformation feature of K416B superalloy, tensile testing at room temperature was carried out, and optical microscopy (OM), scanning electron microscopy (SEM) and transmission electron microscopy (TEM) were used to analyze the deformation and damage mechanisms. Results show that the main room temperature tensile deformation features of the K416B nickel-based superalloy are dislocations slipping in the matrix and shearing into γ' phase. The $\langle 110 \rangle$ super-dislocations shearing into γ' phase can form the anti-phase boundary two coupled $(a/2)\langle 110 \rangle$ partial-dislocations or decompose into the configuration of two $(a/3)\langle 112 \rangle$ partial dislocations plus stacking fault. In the later stage of tensile testing, the slip-lines with different orientations are activated in the grain, causing the stress concentration in the regions of block carbide or the porosity, and cracks initiate and propagate along these regions.

Key words: Ni-based superalloy; high W content; microstructure; tensile behavior; deformation feature

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1 Introduction

Due to their good oxidation resistance, high heat-resistant capability and good mechanical properties, Ni-based superalloys have been widely used for preparing the parts of aero-engine, such as turbine guide-vane, turbine disks and other bearing parts^[1-3]. The microstructure of the Ni-based superalloy mainly consists of γ matrix, γ' phase and carbides^[4-6]. To increase the solid solution strengthening level of the alloy, alloying elements with high melting points, such as W, Re, Ru, and so on, are commonly added during composition designs^[7]. However, the application of the nickel-based superalloys containing Re and Ru is limited, mainly due to the prices of these two elements being much more expensive than the others. The element W, by contrast, has a lower price and could well improve the high temperature properties of the alloy^[8,9], which is thought to be an ideal alloying element to some extent to replace Re and Ru^[10]. W mainly distributes in γ matrix

and improves the mechanical properties of the alloy by solid solution strengthening^[11]. Furthermore, the element W could reduce the coarsening rate of γ' phase during the alloy servicing at high temperature, due to its low diffusion coefficient^[12]. It has been reported that the fatigue and stress rupture properties of a typical high W content polycrystalline superalloy K416B, containing 16wt.% W, are comparable to those of a first-generation single crystal superalloy^[13]. Therefore, the nickel-based superalloy with high W content has a great research value.

Some related research works^[14,15] show that the tensile properties of the Ni-based superalloy may be affected by the applied temperatures, which is closely related to the deformation mechanisms during tensile testing^[16,17]. The deformation mechanisms of the alloy during tensile testing under different temperatures include dislocation loops formation, stacking fault (SF) and anti-phase boundary (APB)-coupled dislocation pairs formation, dislocation tangle formation, and finally, cross-slip and dislocation climb processes^[18,19]. Although the deformation features of the Ni-based superalloy have been reported, but there are few reports on the tensile deformation behavior of the Ni-based superalloy with high W content at room temperature.

Because the properties of the K416B nickel-based superalloy with high W content at high temperature

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almost reaches the levels of the first-generation single crystal superalloy^[13], and the casting techniques of the polycrystalline alloys are much easier than the single crystal alloy, it is firmly believed that the K416B alloy has great advantages in use-cost, which means the alloy has a great potential for investigation and application. However, the research works on the nickel-based superalloy are mainly focused on the temperature-bearing capacities of the alloys, fewer on their properties at room temperature. For instance, the room temperature tensile behavior of the Ni-based superalloy with high W content is rarely investigated.

In this study, the tensile property of Ni-based superalloy with high W content was measured at room temperature. The microstructures of the alloy after tensile testing were observed by scanning electron microscopy (SEM) and transmission electron microscopy (TEM), and the tensile deformation mechanisms of the alloy were deeply investigated.

2 Experimental procedure

By means of 10 kg vacuum induction melting furnace, an ingot of Ni-based superalloy with high W content was prepared and cast into equiaxed crystal bars, and followed with refining at 1,600 °C for 5 min and pouring at 1,520 °C and the cooling condition was air cooling. The nominal chemical composition of the alloy was given as follows (wt.%): 0.13C-4.90Cr-6.82Co-2.06Nb-5.75Al-16.0W-1.0Ti-1.0Hf-Ni. The alloy bars were processed into cylindrical specimens with a working gauge of 25 mm and a diameter of 5 mm. The tensile testing was performed in an AG-25KNE model tensile testing machine at room temperature.

The alloy before or after the tensile testing was ground and polished, and then etched by the solution of 20 mL HCl+5 g CuSO₄+25 mL H₂O in order to observe the microstructures under S-3400N SEM. The specimen after tensile testing was cut into a slice with the thickness of 0.5 mm from the regions near the fracture. After grinding and thinning down to 50 μm mechanically, the TEM foils about Φ3 mm were sectioned from the specimens and thinned by conventional twin jet polishing technique with the electrolyte consisting of 10% perchloric acid and 90% ethanol in volume fraction. By means of microstructure observation under TECNAI-20 TEM, the dislocation configuration and the deformation mechanisms of the alloy were investigated.

3 Results

3.1 Microstructure of K416B Ni-based superalloy

The microstructure of K416B Ni-based superalloy observed by SEM is shown in Fig. 1. The morphology of dendrites in the alloy displays an irregular distribution feature, as shown in Fig. 1(a). The eutectics and M₆C carbides with different sizes distribute in the inter-dendrite regions are marked by the arrow in Fig. 1(a). The morphology and size of γ' phase are different in the dendrite and inter-dendrite areas, as marked by the letters A and B in Fig. 1(b), respectively. The γ' particles with the size of 0.3–0.6 μm dispersedly precipitate in the dendrite of the alloy, while those with the size of about 1–2 μm irregularly distribute in the inter-dendrite, as shown in Fig. 1(b).

Fig. 1: SEM images of K416B Ni-based superalloy: (a) dendrite morphology; (b) γ' phase morphology

3.2 Tensile properties of K416B Ni-based superalloy

The tensile properties of K416B Ni-based superalloy at room temperature are listed in Table 1. The average yield strength and tensile strength of the alloy are 749 MPa and 975 MPa, and the corresponding elongation and reduction of area in the fracture alloy are measured to be 6 % and 9%, respectively.

3.3 Tensile deformation feature of K416B Ni-based superalloy

After room temperature tensile testing, the typical TEM microstructures of K416B Ni-based superalloy were observed, as shown in Fig. 2. The dislocation shearing γ' phase is marked by the white arrow in Fig. 2(a), and the dislocation bowing out in the matrix is marked by the black long arrow. The formation

Table 1: Tensile properties of K416B Ni-based superalloy at room temperature

No.	Yield strength (MPa)	Tensile strength (MPa)	Elongation (%)	Reduction of area (%)
#1	768	977	5.5	10
#2	733	972	6	8
#3	747	976	6.5	8

Fig. 2: TEM images of K416B superalloy after tensile fracture at room temperature: (a) dislocation bowing out and forming loops; (b) stacking fault

of dislocation-loops, marked by the black short arrows in Fig. 2(a), indicates that the moving dislocations bypass the γ' phase by Orowan mechanism. In another local region of the fracture alloy, some stacking faults and the anti-phase boundary (APB) plus a dislocation pair in the γ' phase were observed, respectively marked by the arrows in Fig. 2(b).

After tensile testing at room temperature, the dislocation configurations in the γ' phase with various diffraction contrasts are shown in Fig. 3, which are observed from different diffraction angles. The super-dislocations sheared into γ' phase are marked by 1, 2 and 3, respectively. When the diffraction vectors are g_{020} , $g_{\bar{1}\bar{1}1}$ and $g_{20\bar{2}}$, the Super-Dislocation 1 is out of contrast, as shown in Figs. 3(a), (d) and (f), respectively. According to the criterion of dislocation invisible ($g \cdot b = 0$), the Burgers vector of Dislocation 1 is identified as $b_1 = a[101]$, where "a" is the lattice constant of the γ' phase. The contrast of Dislocation 2 is invisible when the diffraction vectors are g_{020} and $g_{\bar{1}\bar{1}1}$, and the Burgers vector of Dislocation 2 could be calculated by $b_2 = g_{020} \cdot g_{\bar{1}\bar{1}1} = a[10\bar{1}]$. Dislocation 3 is out of contrast when the diffraction vector is $g_{\bar{1}\bar{1}1}$, as shown in Fig. 3(c), indicating its Burgers vector is $b_3 = a[110]$. According to the analysis of the dislocation configuration above, it could be indicated that $a\langle 110 \rangle$ super-dislocations can shear into the γ' phase and slip during tensile testing at room temperature.

The dislocation configuration of Schockley partial dislocations plus stacking fault (SF) in the γ' phase could be observed in Fig. 3, where the partials are marked by A and B, and the SF is marked by C, respectively. When the diffraction vectors are g_{020} , $g_{\bar{1}\bar{1}1}$ and $g_{20\bar{2}}$, the partial Dislocation A is out of contrast, as shown in Figs. 3(a), (d) and (f). According to the

criterion that partial dislocation is invisible in γ' phase when $b \cdot g = \pm (2/3)$ or $b \cdot g = 0$, the Burgers vector of Schockley partial dislocation A is determined to be $b_A = (a/3)[211]$. The contrast of partial Dislocation B is invisible when the diffraction vectors are g_{020} , $g_{31\bar{1}}$, $g_{\bar{1}\bar{1}1}$ and $g_{20\bar{2}}$, as shown in Figs. 3(a), (b), (d) and (f), identifying the Burgers vector of Dislocation B as $b_B = (a/3)[1\bar{1}2]$. At the same time, the phase angles of stacking fault are indicated to be $\alpha = 0$ or $2n\pi$ when the diffraction vectors are $g_{31\bar{1}}$ and $g_{3\bar{1}1}$, and the contrast of stacking fault is invisible, as shown in Figs. 3(b) and (e). The facts analyzed above indicate that the $\langle 110 \rangle$ super-dislocation shearing into γ' phase can decompose into the configuration of two Schockley partial dislocations plus stacking fault. The decomposition reaction can be expressed as follows:

$$a[101] \rightarrow (a/3)[211]_A + (SF)_C + (a/3)[1\bar{1}2]_B \quad (1)$$

The partial dislocation pairs on both sides of APB in the γ' phase are marked by D_1 and D_2 , respectively. When the diffraction vectors are g_{020} , $g_{\bar{1}\bar{1}1}$ and $g_{20\bar{2}}$, the dislocation pair D_1 and D_2 is out of contrast, as shown in Figs. 3(a), (d) and (f). According to the dislocation invisible criteria of $g \cdot b = 0$, it can be identified that the Burgers vector of two partial dislocations is $b_{D1} = b_{D2} = g_{020} \cdot g_{\bar{1}\bar{1}1} = g_{\bar{1}\bar{1}1} \cdot g_{20\bar{2}} = (a/2)[101]$. The decomposition reaction formula can be expressed as follows:

$$a[101] \rightarrow (a/2)[101]_{D1} + APB + (a/2)[101]_{D2} \quad (2)$$

After tensile fracture, the surface morphologies of the alloy are shown in Fig. 4, wherein, the slipping lines are activated along different directions in different grains. The end of the slipping traces at the porosity and the grain boundary may

Fig. 3: Contrast analysis of dislocation configurations in γ' phase after tensile fracture: (a) g_{020} ; (b) g_{311} ; (c) g_{111} ; (d) g_{111} ; (e) g_{311} ; (f) g_{202}

Fig. 4: OM images of alloy after tensile fracture: (a) slipping line ending at grain boundary; (b) slipping lines with different orientations in grain

cause the stress concentration, as shown in Fig. 4(a). In addition, when the slipping trace crosses over the block M_6C carbide, the deformed stress will be accumulated in the region, which may promote the initiation of the micro-crack along the carbide interface, as shown in Fig. 4(b). Meanwhile, because the tensile testing is carried out at room temperature, and the experimental alloy has a high W content (about 16wt.%), it can be indicated that the block M_6C in the alloy is primary carbide precipitated after the alloy being poured, according to the Refs. [20, 21].

The SEM image in the vicinity of the fracture in the alloy after tensile fracture is shown in Fig. 5. The slipping lines

Fig. 5: SEM image of alloy after tensile fracture

parallel to each other are indicated by the arrows. When the slipping lines cross over the block M_6C carbide, the micro-crack may easily initiate at the interface of M_6C and γ matrix, and the M_6C carbide is more likely to be broken, as shown in the right of Fig. 5. This indicates that the block carbide is a weak region of the alloy during tensile testing at room temperature.

The fracture morphology of the alloy is presented in Fig. 6.

The macroscopic fracture is smooth, as shown in Fig. 6(a). In the local fracture, some porosity could be observed, which indicates that the tensile crack can also initiate from the porosity, as shown in Fig. 6(b). In another region, the block M_6C carbide can be observed on the fracture, as shown in Fig. 6(c), where there are many slipping lines in the cleavage plane near the fragmented carbide, which coincides well with the results shown in Fig. 5.

Fig. 6: Fracture images of alloy: (a) macroscopic morphology; (b) crack propagating in porosity; (c) slipping line ending at M_6C carbide

4 Discussion

4.1 Dislocation decomposition behavior during tensile at room temperature

Due to the lattice misfit between γ and γ' phase, dislocations slipping in the γ matrix will pile up and cause the stress concentration at the interface of γ/γ' phase. To release the stress concentration, some dislocations may bypass the γ' phase by Orowan mechanism, as shown in Fig. 2(a), and some may shear into the γ' phase by different models, as shown in Fig. 2(b). According to the contrast analysis of dislocation configuration shown in Fig. 3, there are three models of the dislocations sheared into the γ' phase. One of them is $a\langle 110 \rangle$ dislocation decomposed into two $(a/3)\langle 112 \rangle$ Shockley partial dislocations, marked by A and B, plus SF on $\{111\}$ plane, as the letters A, B and C shown in Fig. 3. Another one is $a\langle 110 \rangle$ dislocation decomposing into $(a/2)\langle 110 \rangle$ partials plus APB, as the letters D_1 and D_2 shown in Fig. 3. The third model is the shearing dislocation in γ' phase that keeps slipping without decomposing, as the numbers 1, 2 and 3 shown in Fig. 3. It could be indicated that the deformation mechanism of the alloy for tensile testing at room temperature is dislocation slipping in γ matrix and shearing γ' phase.

Research shows that the dislocations decomposing in the γ' phase are mainly related to the APB energies and SF energies on various lattice planes [22]. At room temperature, the needed energy is calculated to be about $142 \text{ mJ}\cdot\text{mol}^{-1}$ for the shearing dislocations in the γ' phase to decompose into partials plus

APB on $\{111\}$ plane, while that on $\{001\}$ plane is about $28 \text{ mJ}\cdot\text{mol}^{-1}$ [23]. However, the needed energy is only about $13 \text{ mJ}\cdot\text{mol}^{-1}$ for the dislocations to decompose into Shockley partial dislocations plus SF on $\{111\}$ plane. According to the calculation, it can be indicated that the sheared dislocations in the γ' phase are likely to decompose into partial super-dislocations plus plane defects with lower energies, as shown by D_1 and D_2 in Fig. 3. The great instantaneous strain from the tensile testing is thought to be another main reason that the dislocation sheared into γ' phase could decompose into $(a/3)\langle 112 \rangle$ partials plus SF [24].

The dislocation configuration of partials plus APB on $\{100\}$ plane is the dislocation structure with non-plane core, which can restrain the dislocations from slipping and cross-slipping [25]. Meanwhile, due to the great width of the SF, it is difficult for the Shockley super-dislocations at both ends of the SF to be constricted, which can increase the yield strength of the alloy.

According to the observation and analysis on the deformation feature, K416B superalloy displays a similar deformation mechanism during tensile testing at room temperature with other alloys containing lower W contents, as K444 and DZ951 [21, 26], which suggests that the high W content has no obvious effect on the room temperature tensile deformation mechanism. However, the yield strength of K416B is higher than those of K444 and DZ951. This maybe due to that the higher W content in K416B can provide a greater solution strength level for γ matrix, which improves the strength without reducing the elongation of the alloy.

4.2 Deformation and fracture feature of alloy during tensile testing at room temperature

In the microstructure near the fracture of the alloy, significant slipping lines along two directions appear, as shown in Fig. 4 and Fig. 5. It can be observed that the crack initiation easily occurs when the slipping line crosses over the block M_6C . The deformation and fracture schematic diagrams of the alloy during tensile testing at room temperature are shown in Fig. 7.

During tensile testing, the main deformation mechanism is $\{111\}\langle 110\rangle$ slipping system activated^[25]. Due to the crystal orientations of the grains in the alloys being varied, the effective stress for the slipping systems activated in each grain are different, as shown in Fig. 7(a). As tensile testing goes on, the increase of the effective stress can promote more slipping systems to be

activated, which may cause the microstructure of the alloy to display slipping line morphologies, as shown in Fig. 5.

When significant slipping systems being activated simultaneously, because the M_6C carbide is non-plastic and can hardly compatibly deform with γ/γ' phase, the stress concentration easily occurs at the interface of M_6C and γ matrix, which may cause the crack initiation, as shown in Fig. 7(b). Moreover, the crack initiation can also occur on the edge of various $\{111\}\langle 110\rangle$ primary/secondary slipping systems^[27], as indicated by the arrows shown in Fig. 7(b).

As tensile testing goes on, the crack tip can propagate rapidly along the normal stress orientation to cause the tensile fracture, and the fracture of the alloy may display a smooth feature, as shown in Fig. 7(c). It is well consistent with the observation results from Fig. 4 and Fig. 6.

Fig. 7: Deformation and fracture schematic diagram of the alloy during tensile at room temperature: (a) slipping systems activation in various grains; (b) formation of slipping lines and micro-crack in a grain; (c) crack propagation and macrocrack formation

5 Conclusions

(1) During tensile testing at room temperature, the deformation mechanism of the alloy consists of the dislocation shearing into γ' phase, dislocation bowing, or forming loops by Orowan mechanism. The $\langle 110\rangle$ super-dislocations shearing into γ' phase may form the configuration of an anti-phase boundary coupled $(a/2)\langle 110\rangle$ partial dislocation pair or decompose to form the stacking fault plus two $(a/3)\langle 112\rangle$ partial dislocations.

(2) Different orientation slipping lines are activated in the matrix to cause the stress concentration in the regions of block M_6C carbide or the porosity defect, and the crack can initiate and propagate along these regions during tensile testing, which is thought to be the fracture feature of the alloy.

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