



Picture fuzzy tolerance graphs with application

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Abstract

In this study, the notions of picture fuzzy tolerance graphs, picture fuzzy interval containment graphs and picture fuzzy ϕ -tolerance graphs are established. Three special types of picture fuzzy tolerance graphs having bounded representations are introduced and studied corresponding properties of them taking ϕ as max, min and sum functions. Also, picture fuzzy proper and unit tolerance graphs are established and some related results are investigated. The class of picture fuzzy ϕ -tolerance chain graphs which is the picture fuzzy ϕ -tolerance graphs of a nested family of picture fuzzy intervals are presented. A real-life application in sports competition is modeled using picture fuzzy min-tolerance graph. Also a comparison is given between picture fuzzy tolerance graphs and intuitionistic fuzzy tolerance graphs.

Keywords Picture fuzzy graphs · Picture fuzzy tolerance graphs · Picture fuzzy ϕ -tolerance graphs · Picture fuzzy proper and unit tolerance graphs · Picture fuzzy ϕ -tolerance chain graphs

Abbreviations

FG	Fuzzy graph
PF	Picture fuzzy
PFG	Picture fuzzy graph
FPG	Fuzzy planar graph
PFC	Picture fuzzy clustering
CG	Competition graph
IG	Interval graph
TG	Tolerance graph
TR	Tolerance representation
IC	Interval containment
SL	Support length
CL	Core length
PFI	Picture fuzzy interval
PFT	Picture fuzzy tolerance
PFIG	Picture fuzzy interval graph

PFTG	Picture fuzzy tolerance graph
PFICG	Picture fuzzy interval containment graph
PF ϕ -TG	Picture fuzzy ϕ -tolerance graph
PF ϕ -TCG	Picture fuzzy ϕ -tolerance chain graph
PF max, min and sum TG	Picture fuzzy max, min and sum tolerance graph, respectively
PFmax, min, sum TCG	Picture fuzzy max, min and sum-tolerance chain graph, respectively
TMS, AMS and FMS	Degree of truth, abstinence and false membership, respectively

Introduction

Research background

In 1965, the notion of fuzzy set (FS) was initially posed by Zadeh [51] to model the problems having uncertainties. It was seen that FS with one component may fail to modeled some problems properly. To illustrate those problems Atanassov [2] invited another component namely non-membership value and defined intuitionistic fuzzy (IF) set. But, in some cases, an extra component namely ‘neutrality’ is needed to explain an existing information completely. To recover this situation, Cuong [6] initiated the idea of picture fuzzy (PF) set as an extended version of IF set. After that, Son [43] introduced generalized picture distance mea-

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sure with its applications in PF clustering (PFC) and he described some measuring analogousness in PF sets [44]. Based on PFC method, Thong and Son presented weather now casting from satellite image sequences in [45] and particle swarm optimization with picture composite cardinality in [46]. They also explained PFC: a new computational intelligence method [47] and PFC for complex data [48]. Graph theory was well studied by many researcher in discrete mathematics, computer science, railway network, traffic network, ecological modeling, archaeology, etc. for its wide applications. The concept of fuzziness was initiated in graph theory by Rosenfeld [33] and defined fuzzy graph (FG), whereas in 1973 Kauffman [22] initially posed its basic idea. After that, in the domain of FG many works have been done by the researchers in several directions such as Samanta and Pal defined the notion of fuzzy competition graphs (CGs) [36] and fuzzy planar graphs (FPGs) [37]. Samanta et al. explained m -step fuzzy CGs [38] and they investigated completeness and regularity of generalized FGs in [39]. Several new concepts of bipolar FGs with applications were proposed by Poulík and Ghorai in [29–31]. Later on, Naz et al. [26] introduced the novel concepts of energy of a graph in the context of a bipolar fuzzy environment with its application in decision making problem. Ghorai and Pal introduced some operations on m -polar FGs [15], some isomorphic properties of m -polar FGs with applications [16] and m -polar FPGs [17]. They also studied certain types of product bipolar FGs in [18]. The concept of IF graph was first given by Shannon and Atanassov [34]. Sahoo and Pal introduced IF competition graph [40] and explained certain types of edge irregular IF graphs in [42]. Next, Karaaslan [24] exhibited structure of hesitant FGs with their applications in decision making. Recently, Akram et al. [3] proposed the concept of CGs under complex fuzzy environment and designed an application of it in ecology.

Al-Hawary et al. [1] proposed the notion of PF graph (PFG) with some operations as an extended version of IF graph. Later on, Zuo et al. presented the new concepts of PFGs with application in [50]. Mohamedlsmayil and Asha-Bosely [25] described domination in PFGs. Recently, Das and Ghorai [8] have defined picture FPGs and applied it to construct road map designs. They have also applied the idea of PF sets to CGs, PF genus graphs [9–11]. Xiao et al. studied on regular PFG and its application in communication networks in [49].

Golumbic and Monma [12] first initiated tolerance graphs (TGs) as a natural generalization of interval graphs (IGs) using tolerances and examined TG in [13]. Jacobson et al. [19,20] introduced tolerance intersection graph and established some general results of it. The equivalence relation between proper and unit intervals for sum-TGs are explained by Jacobson and McMorris in [21]. Bogart and Fishburn [5] described proper and unit TGs. The idea of tolerance CGs was

initiated by Brigham et al. [4]. Samanta and Pal [35] defied fuzzy TGs. Pramanik et al. introduced fuzzy ϕ -tolerance CGs [27] and interval-valued fuzzy ϕ -tolerance CGs [28]. Then TGs with application in IF environment were explained by Sahoo and Pal [41]. Kiersteda and Saoubb [23] discussed about the first-fit coloring of bounded TGs. Max-point-TGs were studied by Catanzaro et al. [7] in 2017 and recently, Paul [32] discussed on central max-point-TGs.

Research challenges and gaps

- The TG is a well-known topic. But till now, no work has been done on it in PF environment.
- The PF tolerance graph (PFTG) can model the conflicts of events occurring in a block of time and can also fix up the relation between them.
- PFTG models are very effective to solve certain scheduling and resource allocation problems in operations research than the models in other fields.
- All the introduced TGs are crisp graphs which cannot describe all the real-world problems that contains uncertainty or haziness and fuzzy in nature.
- The PFTG models give more legibility, flexibility and suitability to the system as compared with the models in other fields due to uncertainty.

Motivation and contribution of this study

In graph theory, an intersection graph represents the pattern of overlap of collection of sets. An IG is the intersection of the intervals on a real line R_L . In certain scheduling and resource allocation problems of operations research the IG model is very fruitful. Moreover, IGs have numerous applications in several fields such as ecological model, developmental psychology, archaeology, mathematical modeling, etc. TGs were invited to generalize few well-known applications of IGs. The original purpose was to model certain scheduling and resource allocation problems for sharing of vehicles and rooms, etc. We have presented a new classification of TGs in PF environment. Due to uncertainty in the description of TGs, it is a necessity to design PFTG models. We have generalized IGs by using tolerance and constructed PFTG models by assuming PFIs as the vertices. And two vertices are combined by an edge iff the intersection of the corresponding picture fuzzy intervals (PFIs) are at least as large as the picture fuzzy tolerance (PFT) associated with one of the PF vertices. The PFTG, a worthwhile generalization of IF tolerance graph (IFTG), is a proficient model to deal with uncertainties of human judgement in more comprehensive and logical way due to the presence of an additional term known as ‘neutral membership’. This graph has an acuity over the other existing models of the literature due to its additional features of

handling the uncertainties. On the other hand, if we remove the ‘neutral membership’ of PFTG, the PFTG reduces to conventional IFTG. Thus, PFTG is an effective generalization of IFTG. The TGs developed under PF environment are useful enough to tackle all the tolerances of real world which possess the information with more possible types of vagueness and uncertainties.

In this research article, we present the innovative concept of PFTGs. Moreover, we consider PF ϕ -tolerance graphs (PF ϕ -TGs), PF max, min and sum TGs, PF unit TGs, PF proper TGs and PF ϕ -tolerance chain graphs (PF ϕ -TCGs) with interesting properties. In addition, we discuss an application of PFmin TG in sports competition to emphasize the superiority of this graphs in real life. The main contribution to this article is TGs with its remarkable specializations are developed in PF environment to overcome the deficiencies of other existing TGs of the literature. An algorithm is initiated to find the tolerances among the real-world entities with an application in sports competition. A comparison between PFTG and IFTG is provided to show the superiority and authenticity of our proposed TGs.

Framework of this study

This work is constructed as follows: some basic observations connected to PFTGs are provided in ‘‘Preliminaries’’. ‘‘Picture fuzzy tolerance graphs’’ presents new notions of PF max, min and sum TGs and studies several properties of them. ‘‘Picture fuzzy ϕ -tolerance chain graph’’ gives the idea of PF ϕ -TCGs with some properties. An application of PFmin TG in sports competition is given in ‘‘Application of tolerance graph in sports competition’’. Before the concluding section, comparison of the proposed TGs with existing IFTGs is given. Finally, the conclusion is presented in ‘‘Conclusion’’.

Preliminaries

This section, we reminisce some preliminary observations related to our study such as TG, bounded TG, unit TG, proper TG, interval containment graph, max TG, PF set and PFG.

Definition 2.1 [13] A graph $G = (V, B)$ is a TG if \exists a collection of the closed intervals $I = \{I_r : r \in V\}$ on R_L with the corresponding positive tolerances $t = \{t_r : r \in V\}$ satisfying $rs \in B \Leftrightarrow |I_r \cap I_s| \geq \min\{t_r, t_s\}$, where $|I|$ is the length of I and the pair (I, t) is known as tolerance representation (TR) of G .

A TR (I, t) is bounded if $t_r \leq |I_r|$ for all $r \in V$. A TG is bounded [13] if it confess a bounded TR. An interval representation (IR) is an unit-IR when all intervals are of equal

length and it will be proper-IR when no interval contained completely in another.

Definition 2.2 [13] A vertex $r \in G$ is an assertive if for every TR (I, t) of G replacing t_r by $\min\{t_r, |I_r|\}$ leaves the TG unchanged. An assertive vertex is one which never requires unbounded tolerance. If each vertex of a TG G is assertive, then G is bounded TG.

If r be a vertex of G and $\text{adj}(r) - \text{adj}(s) \neq \emptyset, \forall s \neq r$ in G , then r is assertive, where $\text{adj}(r)$ is the set of all vertices adjacent to r by an edge in G .

Definition 2.3 [5] A unit TG is one that has a TR in which all intervals are of equal length and proper TG is one that has a TR in which no interval contained properly in another.

Now we define interval containment (IC) graph and max TG below.

Definition 2.4 [13] An IC graph $G = (V, B)$ is represented by the set of intervals $I = \{I_r : r \in V\}$ such that an edge $(r, s) \in B(G)$ if one of I_r, I_s contains the other. This representation is known as IC representation.

Definition 2.5 [14] A graph $G = (V, B)$ is a max TG if \exists a collection of the closed intervals $I = \{I_r : r \in V\}$ on R_L with the corresponding positive tolerances $t = \{t_r : r \in V\}$ satisfying $rs \in B \Leftrightarrow |I_r \cap I_s| \geq \max\{t_r, t_s\}$. For max TGs, we may assume $t_r \leq |I_r| \forall r \in V$; otherwise, r becomes isolated. A max TG is a unit-max TG if $I_r = I_s \forall r, s \in V$.

Definition 2.6 [6] A PF set A is defined on an universe X as $A = \{p, (\mu_A(p), \eta_A(p), \nu_A(p)) : p \in X\}$, where $\mu_A(p), \eta_A(p), \nu_A(p) \in [0, 1]$ are the degree of truth membership (TMS), degree of abstinence membership (AMS), degree of false membership (FMS) of $p \in A$, respectively, with $0 \leq \mu_A(p) + \eta_A(p) + \nu_A(p) \leq 1 \forall p \in X$. Also $\forall p \in X, D_A(p) = 1 - (\mu_A(p) + \eta_A(p) + \nu_A(p))$ represent denial degree of $p \in A$.

Now, we define support, core and height of a PF set. Also, define PFG with an example as follows:

Definition 2.7 [9] Let $A = \{p, (\mu_A(p), \eta_A(p), \nu_A(p)) : p \in X\}$ be a PF set. The support of A is defined as $\text{Supp}(A) = \{p \in V : \mu_A(p) \geq 0, \eta_A(p) \geq 0 \text{ and } \nu_A(p) \geq 0\}$ and its support length (SL) is $s(A) = |\text{Supp}(A)|$. The core of A is defined as $\text{Core}(A) = \{p \in V : \mu_A(p) = 1, \eta_A(p) = 0 \text{ and } \nu_A(p) = 0\}$ and its core length (CL) is $c(A) = |\text{Core}(A)|$. The height of A is defined as $h(A) = (\sup_{p \in V} \mu_A(p), \sup_{p \in V} \eta_A(p), \inf_{p \in V} \nu_A(p)) = (h_\mu(A), h_\eta(A), h_\nu(A))$.

Definition 2.8 [1] A PFG is $G = (V, A, B)$ where $A = (\mu_A, \eta_A, \nu_A), B = (\mu_B, \eta_B, \nu_B)$ and

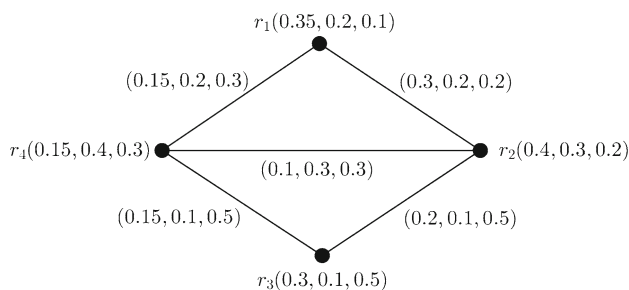


Fig. 1 Example of a PFG

- (i) $V = \{r_1, r_2, \dots, r_n\}$ such that $\mu_A, \eta_A, \nu_A : V \rightarrow [0, 1]$ are the TMS, AMS and FMS of $r_i \in V$, respectively, with $0 \leq \mu_A(r_i) + \eta_A(r_i) + \nu_A(r_i) \leq 1 \forall r_i \in V$, ($i = 1, 2, \dots, n$).
- (ii) $\mu_B, \eta_B, \nu_B : V \times V \rightarrow [0, 1]$ are the TMS, AMS and FMS of edge (r_i, r_j) , respectively, such that $\mu_B(r_i, r_j) \leq \min\{\mu_A(r_i), \mu_A(r_j)\}$, $\eta_B(r_i, r_j) \leq \min\{\eta_A(r_i), \eta_A(r_j)\}$ and $\nu_B(r_i, r_j) \leq \max\{\nu_A(r_i), \nu_A(r_j)\}$ with $0 \leq \mu_B(r_i, r_j) + \eta_B(r_i, r_j) + \nu_B(r_i, r_j) \leq 1$ for every (r_i, r_j) , ($i, j = 1, 2, \dots, n$).

Example 2.9 We consider a PFG $G = (V, A, B)$ as shown in Fig. 1, where $V = \{r_1, r_2, r_3, r_4\}$, $A = \{(r_1, (0.35, 0.2, 0.1)), (r_2, (0.4, 0.3, 0.2)), (r_3, (0.3, 0.1, 0.5)), (r_4, (0.15, 0.4, 0.3))\}$ is a PF set on V and $B = \{(r_1r_2, (0.3, 0.2, 0.2)), (r_1r_4, (0.15, 0.2, 0.3)), (r_2r_3, (0.2, 0.1, 0.5)), (r_2r_4, (0.1, 0.3, 0.3)), (r_3r_4, (0.15, 0.1, 0.5))\}$ is the PF relation on a PF subset of $V \times V$. The TMS, AMS and FMS of the vertex r_1 are 0.35, 0.2 and 0.1, respectively, and similarly for other vertices and edges.

Picture fuzzy tolerance graphs

In this section, first we define PF intersection graph and then PF ϕ -TG. Here ϕ is restricted as one of the functions of maximum, minimum and sum. We describe PF max, min and sum TGs, respectively, and study some important properties of them.

Definition 3.1 Let $F = \{A_i : i = 1, 2, \dots, n\}$ be the finite collection of PF sets defined on X and consider each PF set as vertex of the PFG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set. Then the PF intersection graph of F is a PFG $\text{Int}(F) = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(A_i)$, $\eta_A(r_i) = h_\eta(A_i)$ and $\nu_A(r_i) = h_\nu(A_i)$. Also, the TMS, AMS and FMS of an edge $(r_j, r_k) \in \text{Int}(F)$ are given by $\mu_B(r_j, r_k) = \begin{cases} h_\mu(A_j \cap A_k), & \text{if } j \neq k \\ 0, & \text{if } j = k, \end{cases}$

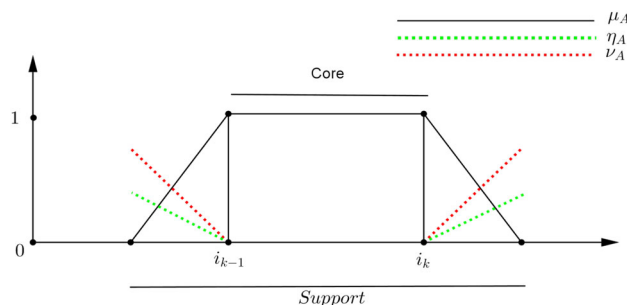


Fig. 2 Example of a PFT

$$\eta_B(r_j, r_k) = \begin{cases} h_\eta(A_j \cap A_k), & \text{if } j \neq k \\ 0, & \text{if } j = k, \end{cases} \quad \text{and}$$

$$\nu_B(r_j, r_k) = \begin{cases} h_\nu(A_j \cap A_k), & \text{if } j \neq k \\ 0, & \text{if } j = k. \end{cases}$$

Now, we will discuss about the notion of PFI, PFTG and PF ϕ -TG.

Definition 3.2 A PFI I on a real interval I is a PF set $I : I \rightarrow [0, 1]$, it is denoted by $I = (I, (\mu_A(I), \eta_A(I), \nu_A(I)))$. A PFI I is normal and convex PF-subset of I . A PFI I is normal if \exists a $r \in I$ such that $h(r) = (1, 0, 0)$ and convex if the ordering $r \leq s \leq t$ implies that

$$\mu_A(s) \geq \min\{\mu_A(r), \mu_A(t)\},$$

$$\eta_A(s) \leq \min\{\eta_A(r), \eta_A(t)\},$$

$$\nu_A(s) \leq \max\{\nu_A(r), \nu_A(t)\}.$$

Definition 3.3 The PFT T of a PFI is an arbitrary PFI whose CL is a positive real number. If the real number is taken as L and $|i_n - i_{n-1}| = L$, where $i_n, i_{n-1} \in R$, then the PFT is the PF set of the interval $[i_n - i_{n-1}]$. $s(T)$ and $c(T)$ are, respectively, the SL and CL of T . PFT may be a PF number. The PFT is shown in Fig. 2.

PF ϕ -TG is the generalization of PF interval graph (PFIG) which is defined below and explained a general characterization of it as follows:

Definition 3.4 Let $\phi : R^+ \times R^+ \rightarrow R^+$ be a function, where R^+ is the set of all positive real numbers. Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite family of PFIs on R_L along with corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Consider each PFI as vertex of the PF ϕ -TG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding PF ϕ -TG is the PF graph $G = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(I_i)$, $\eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$. Also the TMS, AMS and FMS of the edge (r_i, r_j) in G are, respectively, the following:

$$\begin{aligned} \mu_B(r_i, r_j) &= \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \phi\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \phi\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases} \\ \eta_B(r_i, r_j) &= \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \phi\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \phi\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases} \\ \nu_B(r_i, r_j) &= \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \phi\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \phi\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases} \end{aligned}$$

where $c(I_i \cap I_j)$ and $s(I_i \cap I_j)$ are the CL and SL of $I_i \cap I_j$, respectively. Also, $h_\mu(I_i \cap I_j)$, $h_\eta(I_i \cap I_j)$ and $h_\nu(I_i \cap I_j)$ are the TMS, AMS and FMS of the height of $I_i \cap I_j$, respectively.

Theorem 3.5 Let $G = (V, A, B)$ be the PF ϕ -TG. If $h(I_i \cap I_j) = (1, 0, 0)$ and $s(I_i \cap I_j) \geq 2\phi\{s(T_i), s(T_j)\}$. Then $\mu_B(r_i, r_j) \leq \frac{1}{2}$, $\eta_B(r_i, r_j) \leq \frac{1}{2}$ and $\nu_B(r_i, r_j) \leq \frac{1}{2}$ $\forall (r_i, r_j) \in G$.

Proof Let $G = (V, A, B)$ be a PF ϕ -TG of the PFIs $I = \{I_i : i = 1, 2, \dots, n\}$ with the corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Since $h(I_i \cap I_j) = (1, 0, 0)$, then $h_\mu(I_i \cap I_j) = 1$, $h_\eta(I_i \cap I_j) = 0$ and $h_\nu(I_i \cap I_j) = 0$. Also, since $s(I_i \cap I_j) \geq 2\phi\{s(T_i), s(T_j)\}$, then $s(I_i \cap I_j) \geq \phi\{s(T_i), s(T_j)\}$. Therefore, $\mu_B(r_i, r_j) = \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j) = [1 - \frac{\phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)}] \times 1 \leq 1 - \frac{1}{2} = \frac{1}{2}$, $\eta_B(r_i, r_j) = \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j) = [1 - \frac{\phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)}] \times 0 = 0 < \frac{1}{2}$ and $\nu_B(r_i, r_j) = \frac{s(I_i \cap I_j) - \phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j) = [1 - \frac{\phi\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)}] \times 0 = 0 < \frac{1}{2}$.

Picture fuzzy min-tolerance graphs

The PF min-tolerance graph (PFmin TG) is a PF ϕ -TG in which ϕ is restricted to the minimum (min) function defined by $\phi(r, s) = \min\{r, s\}$. The PFmin-TG is defined below.

Definition 3.6 Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L along with corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Consider each PFI as vertex of the PFmin-TG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding PFmin-TG is the PF graph $G = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(I_i)$, $\eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$. Also the TMS, AMS and FMS of the edge (r_i, r_j) in G are, respectively, the following:

$$\begin{aligned} \mu_B(r_i, r_j) &= \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases} \\ \eta_B(r_i, r_j) &= \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases} \\ \nu_B(r_i, r_j) &= \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases} \end{aligned}$$

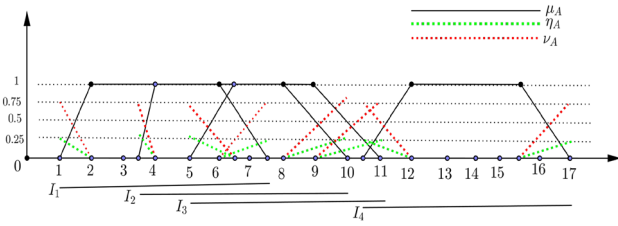


Fig. 3 Representation of PFIs

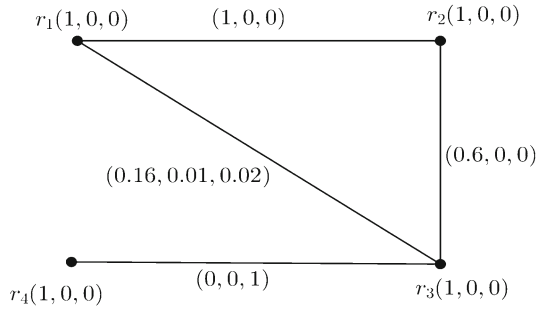


Fig. 4 Corresponding PFmin-TG

We explain it by the following example:

Example 3.7 We consider four PFIs $\{I_i : i = 1, 2, 3, 4\}$ on R_L along with corresponding PFTs $\{T_i : i = 1, 2, 3, 4\}$. Suppose PFIs are the vertices and $V = \{r_i : i = 1, 2, 3, 4\}$ is the vertex set of PFmin TG $G = (V, A, B)$. Let the support of these PFIs are respectively $[1, 7.5], [3.5, 10], [5, 11], [10.5, 17]$. Also the cores are respectively $[2, 6], [4, 8], [6.5, 9], [12, 15.5]$ and $s(T_1) = 5, s(T_2) = 4.25, s(T_3) = 2, s(T_4) = 2.75$ and $c(T_1) = 1.5, c(T_2) = 3, c(T_3) = 4.5, c(T_4) = 1.25$. The corresponding PFIs are shown in Fig. 3.

We have $I_1 \cap I_2 = [3.5, 7.5], I_1 \cap I_3 = [5, 7.5], I_2 \cap I_3 = [5, 10], I_3 \cap I_4 = [10.5, 11]$. Also, $s(I_1 \cap I_2) = 4, s(I_1 \cap I_3) = 2.5, s(I_2 \cap I_3) = 5, s(I_3 \cap I_4) = 0.5$ and $c(I_1 \cap I_2) = 2, c(I_1 \cap I_3) = 0, c(I_2 \cap I_3) = 1.5, c(I_3 \cap I_4) = 0$. Here, $h(I_1 \cap I_2) = (1, 0, 0), h(I_1 \cap I_3) = (0.83, 0.05, 0.12), h(I_2 \cap I_3) = (1, 0, 0), h(I_3 \cap I_4) = (0.14, 0.22, 0.64)$. Since, $I_1 \cap I_2 \neq \emptyset$ and $c(I_1 \cap I_2) \geq \min\{c(T_1), c(T_2)\}$, (r_1, r_2) is an edge of G with TMS, AMS and FMS $(1, 0, 0)$. Also, $I_1 \cap I_3 \neq \emptyset$ and $s(I_1 \cap I_3) \geq \min\{s(T_1), s(T_3)\}$. Hence (r_1, r_3) is an edge of G with TMS, AMS and FMS $(0.16, 0.01, 0.02)$. Again, $I_2 \cap I_3 \neq \emptyset$ and $s(I_2 \cap I_3) \geq \min\{s(T_2), s(T_3)\}$. So (r_2, r_3) is an edge of G with TMS, AMS and FMS $(0.6, 0, 0)$. As, $I_3 \cap I_4 \neq \emptyset$ and $c(I_3 \cap I_4) \not\geq \min\{c(T_3), c(T_4)\}, s(I_3 \cap I_4) \not\geq \min\{s(T_3), s(T_4)\}$, then (r_3, r_4) is an edge of G with TMS, AMS and FMS $(0, 0, 1)$. The corresponding PFmin TG is shown in Fig. 4.

Definition 3.8 Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L along with corresponding PFTs

$T = \{T_i : i = 1, 2, \dots, n\}$. Let $c(I_i), s(I_i)$ be the CL and SL of the PFI I_i and $c(T_i), s(T_i)$ be the CL and SL of the PFT T_i , respectively, such that $c(I_i) \geq c(T_i)$ and $s(I_i) \geq s(T_i)$ of the PFTG. Then the PFTG is called bounded PFTG.

Theorem 3.9 If G is a PFIG, then G is PFmin TG with constant CL and constant SL.

Proof Let G be a PFIG with PFI I_i that is assigned to be the vertex of V . Let CL of the PFIs I_i, I_j be denoted by $c(I_i), c(I_j)$ and SL of that be denoted by $s(I_i), s(I_j)$, respectively. Let $c(I_i \cap I_j) = \min\{c(I_i), c(I_j)\}$ and $s(I_i \cap I_j) = \min\{s(I_i), s(I_j)\}$.

Let n_1, n_2 be two positive real numbers such that $c(I_i \cap I_j) > n_1$ and $s(I_i \cap I_j) > n_2$. Then $\min\{c(I_i), c(I_j)\} > n_1$ and $\min\{s(I_i), s(I_j)\} > n_2$. Therefore, the PFI I_i together with PFT with CL n_1 and SL n_2 give PFT representation.

Theorem 3.10 If G is a PFTG with constant CL and constant SL, then G is bounded PFTG.

Proof Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L along with corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Let $G = (V, A, B)$ be PFTG with PFI I and PFT T . Let n_1, n_2 be two positive real numbers such that $c(T_i) = n_1$ and $s(T_i) = n_2$ for $i = 1, 2, \dots, n$.

If $c(I_i) \geq n_1$ and $s(I_i) \geq n_2$, then $c(I_i) \geq c(T_i)$ and $s(I_i) \geq s(T_i) \forall i = 1, 2, \dots, n$. Then G is bounded PFTG.

If $c(I_i) < n_1$ and $s(I_i) < n_2$ for some i and j , we take $c(I_i) = n_1$ and $s(I_i) = n_2$ to make G is bounded. Therefore, G is bounded PFTG.

Definition 3.11 Let G be a PFTG. A vertex r of G is an assertive if for every PFTR of G replacing $c(T_r)$ by $\min\{c(T_r), |c(I_r)|\}$ and $s(T_r)$ by $\min\{s(T_r), |s(I_r)|\}$ leaves the PFTG unchanged. An assertive vertex is one which never requires unbounded PFT. If each vertex of a PFTG G is assertive, then G is bounded PFTG.

If r be a vertex of G and $\text{adj}(r) - \text{adj}(s) \neq \emptyset, \forall s \neq r$ in G , then r is assertive, where $\text{adj}(r)$ is the set of all vertices adjacent to r by an edge in G .

Theorem 3.12 Let G be a PFTG that is not bounded and let U be the set of all non assertive vertices. Then, the graph G^* formed in addition to a new pendant vertex to each member of U , is not a PFTG.

Proof If possible let, G^* be a PFTG along with arbitrary PFTs associated to each vertex of G^* . Since each $r \in U$ has an exclusive new neighbor in G^* , then each r of U is assertive in G^* . Therefore, we may assume that $c(I_r) \geq c(T_r)$ and $s(I_r) \geq s(T_r) \forall r \in U$. Thus, we obtain a TR for G in which all non assertive vertices have bounded PFT. This shows that G is a bounded PFTG, which contradicts the assumption that G is not a bounded PFTG. Hence G^* is not a PFTG.

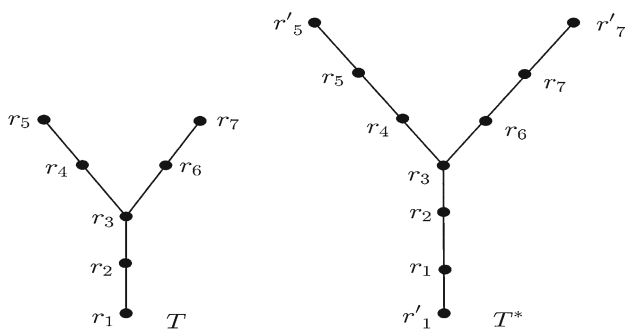


Fig. 5 Unbounded PFTG (T) and non PFTG (T^*)

We will explain it by the following example:

Example 3.13 We consider an unbounded PFTG T . The non assertive vertices of T are its three leaves r_1, r_5 and r_7 . If we add a new pendant vertex to each non assertive vertices of T , then it will form a new graph T^* as shown in Fig. 5. By Theorem 3.12, it is not a PFTG.

Picture fuzzy interval containment graphs

Now, we define PF interval containment graphs (PFICGs).

Definition 3.14 Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L . Consider each PFI as vertex as the PFICG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding PFICG $G = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(I_i)$, $\eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$. Also the TMS, AMS and FMS of the edge (r_i, r_j) in G are, respectively, as follows:

$$\mu_B(r_i, r_j) = \begin{cases} 1, & \text{if support and core of one of } I_i, I_j \text{ include the other} \\ \frac{1}{2} \left[\frac{c(I_i \cap I_j)}{\min\{c(I_i), c(I_j)\}} + \frac{s(I_i \cap I_j)}{\min\{s(I_i), s(I_j)\}} \right] h_\mu(I_i \cap I_j), & \text{otherwise} \end{cases}$$

$$\eta_B(r_i, r_j) = \begin{cases} 0, & \text{if support and core of one of } I_i, I_j \text{ include the other} \\ \frac{1}{2} \left[\frac{c(I_i \cap I_j)}{\min\{c(I_i), c(I_j)\}} + \frac{s(I_i \cap I_j)}{\min\{s(I_i), s(I_j)\}} \right] h_\eta(I_i \cap I_j), & \text{otherwise} \end{cases}$$

$$\nu_B(r_i, r_j) = \begin{cases} 0, & \text{if support and core of one of } I_i, I_j \text{ include the other} \\ \frac{1}{2} \left[\frac{c(I_i \cap I_j)}{\min\{c(I_i), c(I_j)\}} + \frac{s(I_i \cap I_j)}{\min\{s(I_i), s(I_j)\}} \right] h_\nu(I_i \cap I_j), & \text{otherwise} \end{cases}$$

We will explain it by the following example:

Example 3.15 We consider four PFIs $\{I_i : i = 1, 2, 3, 4\}$ on R_L along with corresponding PFTs $\{T_i : i = 1, 2, 3, 4\}$. Let the support of these PFIs be, respectively, $[1, 7.5], [3.5, 10], [5, 11], [10.5, 17]$. Also the cores are, respectively, $[2, 6], [4, 8], [6.5, 9], [12, 15.5]$ and $s(T_1) = 5, s(T_2) = 4.25, s(T_3) = 2, s(T_4) = 2.75$ and $c(T_1) = 1.5, c(T_2) = 3,$

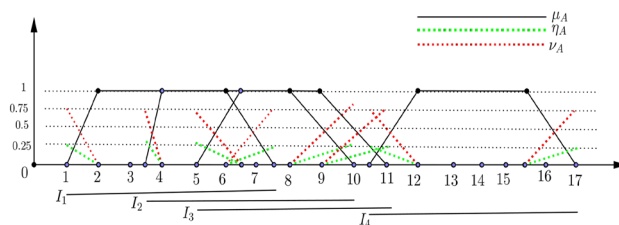


Fig. 6 Representation of PFIs

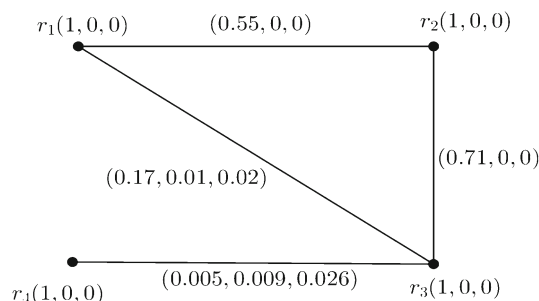


Fig. 7 Corresponding PFICG

$c(T_3) = 4.5, c(T_4) = 1.25$. The corresponding PFIs are shown in Fig. 6.

Then $h(I_1 \cap I_2) = (1, 0, 0), h(I_1 \cap I_3) = (0.83, 0.05, 0.12), h(I_2 \cap I_3) = (1, 0, 0), h(I_3 \cap I_4) = (0.14, 0.22, 0.64)$. Therefore, the TMS, AMS and FMS of the edges $(r_1, r_2), (r_2, r_3), (r_1, r_3)$ and (r_3, r_4) are, respectively, $(0.55, 0, 0), (0.71, 0, 0), (0.17, 0.01, 0.02)$ and $(0.005, 0.009, 0.026)$. The corresponding PFICG is shown in Fig. 7.

Theorem 3.16 If $G = (V, A, B)$ is a PFICG with either $(\mu_B(r, s), \eta_B(r, s), \nu_B(r, s)) = (1, 0, 0)$ or $(0, 0, 1)$ for any edge $(r, s) \in B$, then G has PFT representation with CL and SL of a PFI are equal to the CL and SL of the corresponding PFT, respectively.

Proof Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L . Consider each PFI as vertex of

the PFICG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set. If $(\mu_B(r, s), \eta_B(r, s), \nu_B(r, s)) = (1, 0, 0)$ for the edge $(r, s) \in B$. Then the support and core of one PFI include the other PFI. Let $G^* = (V, A, B')$ be a PFTG with PFI I with the corresponding PFT $T = \{T_i : i = 1, 2, \dots, n\}$ such that $c(I_r) = c(T_r)$ and $s(I_r) = s(T_r)$. Then, $c(I_r \cap I_s) = \min\{c(I_r), c(I_s)\} = \min\{c(T_r), c(T_s)\}$. So, $(\mu_{B'}(r, s), \eta_{B'}(r, s), \nu_{B'}(r, s)) = (1, 0, 0)$.

Again, if $(\mu_B(r, s), \eta_B(r, s), \nu_B(r, s)) = (0, 0, 1)$. Then there is no common part of the support and core between two PFIs. Therefore, $(\mu_{B'}(r, s), \eta_{B'}(r, s), \nu_{B'}(r, s)) = (0, 0, 1)$.

This proves that G has PFT representation with CL and SL of a PFI are equal to the CL and SL of the corresponding PFT, respectively.

Picture fuzzy max-tolerance graphs

A PF max-tolerance graph (PFmax TG) is a $PF\phi$ -TG in which ϕ is restricted to the maximum (max) function defined by $\phi(r, s) = \max\{r, s\}$. The PFmax TG is defined below as follows:

Definition 3.17 Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L along with corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Consider each PFI as vertex of the PFmax-TG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding PFmax-TG is the PF graph $G = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(I_i)$, $\eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$. Also the TMS, AMS and FMS of the edge (r_i, r_j) in G are, respectively, as follows:

$$\mu_B(r_i, r_j) = \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \max\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \max\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \max\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\eta_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \max\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \max\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \max\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\nu_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \max\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \max\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \max\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases}$$

An example is given to explain the above.

Example 3.18 We consider three PFIs $\{I_i : i = 1, 2, 3\}$ on R_L along with corresponding PFTs $\{T_i : i = 1, 2, 3\}$. Let the support of these PFIs are respectively $[1, 6]$, $[4.5, 13]$, $[9.5, 16.5]$ and also the cores are respectively $[2, 5]$, $[7, 10]$, $[12, 15]$ and $s(T_1) = 1.5$, $s(T_2) = 2.5$, $s(T_3) = 3$ and $c(T_1) = 0.75$, $c(T_2) = 1.25$, $c(T_3) = 2$. The corresponding PFIs are shown in Fig. 8.

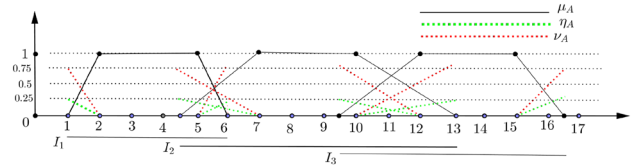


Fig. 8 Representation of PFIs

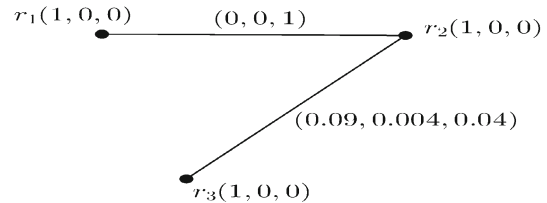


Fig. 9 Corresponding PFmax TG

Then $h(I_1 \cap I_2) = (0.42, 0.17, 0.41)$, $h(I_2 \cap I_3) = (0.63, 0.03, 0.34)$. Therefore the TMS, AMS and FMS of the edges (r_1, r_2) and (r_2, r_3) are, respectively, $(0, 0, 1)$ and $(0.09, 0.004, 0.04)$. The corresponding PFmax TG is shown in Fig. 9.

Now, we define PF unit TG and PF proper TG. The class of PF unit TG is a subset of the class of PF proper TG.

Definition 3.19 The PF unit max TG is a PFTG that has TR in which all PFIs have same SL and same CL. A PF proper TG is one that has a TR in which no PFI support and core contain completely in another PFI support and core.

Theorem 3.20 The chordless PF cycle C_n is a PF unit max TG.

Proof For $1 \leq i \leq n$, we define core of PFI $I_i = [i, i + n]$. Then the CL of PFI I_i is $c(I_i) = n$. Also, let the CL of the corresponding PFT $c(T_1) = c(T_n) = 1$ and $c(T_j) = n - 1$ for $2 \leq j \leq n - 1$. Then it is simple to verify that this is a PF unit max TG.

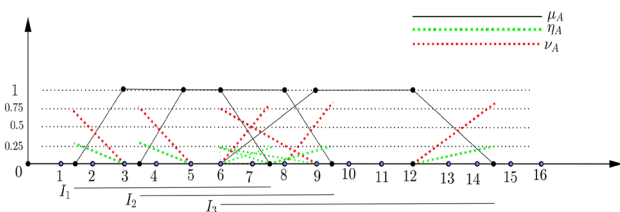


Fig. 10 Representation of PFIs

Picture fuzzy sum-tolerance graphs

A PF sum-tolerance graph (PFsum TG) is a $PF\phi$ -TG in which ϕ is restricted to the sum function defined by $\phi(r, s) = \text{sum}\{r, s\}$. The PFsum TG is defined below as follows:

Definition 3.21 Let $I = \{I_i : i = 1, 2, \dots, n\}$ be a finite collection of PFIs on R_L along with corresponding PFTs $T = \{T_i : i = 1, 2, \dots, n\}$. Consider each PFI as vertex of the PFsum TG. Let $V = \{r_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding PFsum-TG is the PF graph $G = (V, A, B)$. The TMS, AMS and FMS of the vertices are given by $\mu_A(r_i) = h_\mu(I_i)$, $\eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$. Also the TMS, AMS and FMS of the edge (r_i, r_j) in G are, respectively, as follows:

$$\mu_B(r_i, r_j) = \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \text{sum}\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \text{sum}\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \text{sum}\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\eta_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \text{sum}\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \text{sum}\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \text{sum}\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\nu_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \text{sum}\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \text{sum}\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \text{sum}\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases}$$

We explain it by the following example:

Example 3.22 We consider three PFIs $\{I_i : i = 1, 2, 3\}$ on R_L along with corresponding PFTs $\{T_i : i = 1, 2, 3\}$. Let the support of these PFIs are, respectively, $[1.5, 7.5]$, $[3.5, 9.5]$, $[6, 14.5]$ and also the cores are, respectively, $[3, 6]$, $[5, 8]$,

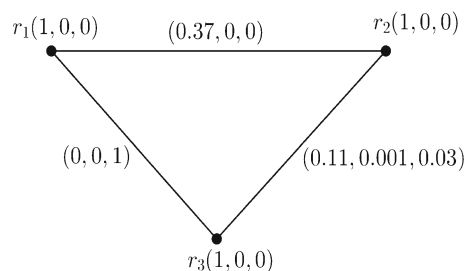


Fig. 11 Corresponding PFsum TG

$[9, 12]$ and $s(T_1) = 1.5, s(T_2) = 1, s(T_3) = 2$ and $c(T_1) = 1, c(T_2) = 0.5, c(T_3) = 1.5$. The corresponding PFIs are shown in Fig. 10.

Then $h(I_1 \cap I_2) = (1, 0, 0), h(I_1 \cap I_3) = (0.33, 0.07, 0.6), h(I_2 \cap I_3) = (0.77, 0.01, 0.22)$. Therefore, the TMS, AMS and FMS of the edges $(r_1, r_2), (r_1, r_3)$ and (r_2, r_3) are, respectively, $(0.37, 0, 0), (0, 0, 1)$ and $(0.11, 0.001, 0.03)$. The corresponding PFsum TG is shown in Fig. 11.

Theorem 3.23 Every PFmin TG $G = (V, A, B)$ with $c(T_i) = c(I_i)$ and $s(T_i) = s(I_i) \forall i \in V(G)$ is a PFICG.

Proof Let $G = (V, A, B)$ be a PFmin TG with PFIs $I = \{I_i : i = 1, 2, \dots, n\}$ and PFTs $T = \{T_i : i = 1, 2, \dots, n\}$ such that $c(T_i) = c(I_i)$ and $s(T_i) = s(I_i) \forall i \in V(G)$. We have by the definition of PFmin TG

$$\mu_B(r_i, r_j) = \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\eta_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\nu_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases}$$

Now, $c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} = \min\{c(I_i), c(I_j)\}$ is true iff when the core of I_i, I_j contains another. Also, $s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} = \min\{s(I_i), s(I_j)\}$ is true iff when the support of I_i, I_j contains another. This gives $\mu_B(r_i, r_j) \geq 0, \eta_B(r_i, r_j) \geq 0$ and $\nu_B(r_i, r_j) \geq 0$. Therefore, one of I_i, I_j contains another. Hence G is a PFICG.

Theorem 3.24 Any PF proper or unit TR be assumed to have bounded PFT.

Proof Let $G = (V, A, B)$ be a PF proper or unit TG with PFIs $I = \{I_r : r \in V\}$ and PFTs $T = \{T_r : r \in V\}$. We assume that all endpoints of support and core in this representation are distinct. We replace $c(T_r)$ by $|c(I_r)|$ for each $r \in V$ when $c(T_r) \geq |c(I_r)|$ and $s(T_r)$ by $|s(I_r)|$ for each $r \in V$ when $s(T_r) \geq |s(I_r)|$. Since there are no containment of support and core of the PFIs, this will not change any adjacency. Therefore, any PF proper or unit TR be assumed to have bounded PFT.

: We explain it by the following example:

Example 3.25 We consider four PFIs $\{I_i : i = 1, 2, 3\}$ on R_L along with corresponding PFTs $\{T_i : i = 1, 2, 3\}$. Assume that PFIs are the vertices and $V = \{r_i : i = 1, 2, 3\}$ be the vertex set of the TG. Let the support of these PFIs are, respectively, $[1, 7.5], [3.5, 10], [8.5, 15]$ and cores are, respectively, $[2, 6], [4, 8], [9, 13]$ and $s(T_1) = 6.5, s(T_2) = 4, s(T_3) = 1$ and $c(T_1) = 4, c(T_2) = 2, c(T_3) = 0.5$. The corresponding PFIs are shown in Fig. 12.

We have $I_1 \cap I_2 = [3.5, 7.5], I_2 \cap I_3 = [8.5, 10]$. Also, $s(I_1 \cap I_2) = 4, s(I_2 \cap I_3) = 1.5$ and $c(I_1 \cap I_2) = 2, c(I_2 \cap I_3) = 0$. Here, $h(I_1 \cap I_2) = (1, 0, 0), h(I_2 \cap I_3) = (0.6, 0.1, 0.3)$. Therefore, the TMS, AMS and FMS of the edges (r_1, r_2) and (r_2, r_3) are, respectively, $(1, 0, 0)$ and $(0.2, 0.03, 0.1)$. Here, no PFI core and support properly contain another PFI core and support. Also, all PFIs have same CL(=4) and same SL(=6.5). So the PFIs together with PFTs represent PF proper (unit)-TG. The corresponding PF proper (unit) TG is shown in Fig. 13. It has bounded PFTs as

$c(I_r) \geq c(T_r)$ and $s(I_r) \geq s(T_r)$ for each $r \in V$. Otherwise, to make bounded PFTs we may replace $c(T_r)$ by 4 and $s(T_r)$ by 6.5. This replacement will not change any adjacency, as there are no containment of support and core of the PFIs.

Theorem 3.26 All PFmax TGs and PFsum TGs have bounded representations.

Proof Let $r \in V$ be a vertex in a PFmax TG or PFsum TG such that $c(T_r) > c(I_r)$ and $s(T_r) > s(I_r)$; then r is an isolated vertex. In that case we reassign this vertex with a different PFI which is disjoint from other PFIs and an arbitrary bounded PFT. This theorem is true for any PF ϕ -TG and also applies to PF proper and unit TRs.

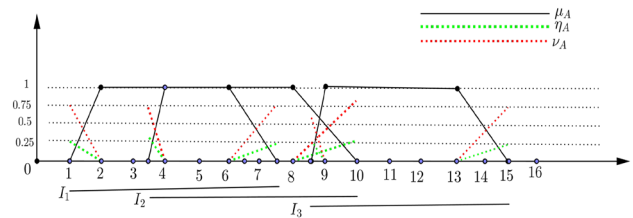


Fig. 12 Representation of PFIs

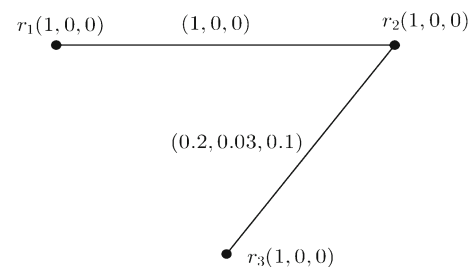


Fig. 13 Corresponding proper (unit)-TG

Picture fuzzy ϕ -tolerance chain graphs

We introduce the normalized representation of PFIs and define a special case of $PF\phi$ -TG, known as the class of $PF\phi$ -TCG which consists of a nested family of PFIs. Here we investigated some specific results when ϕ is the max, min and sum functions.

Definition 4.1 Any nested family of PFIs I_i can be normalized by replacing each PFI I_i by the intervals $[0, r_i]$, where $r_i = |I_i|$. Thus the normalized representation of the nested family of PFIs I_i is of the form $N = \{I_i^* : i = 1, 2, \dots, n\}$, where $I_i^* = [0, r_i]$ and $0 < r_1 \leq r_2 \leq \dots \leq r_n$.

Definition 4.2 In a PFG G , a vertex is an universal if it is adjacent to all other vertices and an isolated if is adjacent to no other vertex of G .

Definition 4.3 A PFG G is a threshold graph iff for each subset $S \subseteq V$, \exists a vertex $r \in S$ which is either isolated or universal in the induced subgraph G_S of G .

Theorem 4.4 A PF min-tolerance chain graph ($PFmin$ -TCG) is a PF threshold graph.

Proof Let $N = \{I_i^* : i = 1, 2, \dots, n\}$ be a nested family of PFIs along with corresponding PFTs $T^* = \{T_i^* : i = 1, 2, \dots, n\}$, where $I_i^* = [0, r_i]$ and $0 < r_1 \leq r_2 \leq \dots \leq r_n$. Consider each nested family of PFI as vertex of the $PFmin$ TCG. Let $V = \{u_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding $PFmin$ TCG be the PFG G^* . We have to prove G^* has an universal or an isolated vertex.

If $c(T_1) \leq c(I_1)$ and $s(T_1) \leq s(I_1)$, then u_1 is an universal vertex as $c(I_1 \cap I_j) = c(I_1) \geq c(T_1) \geq \min\{c(T_1), c(T_j)\}$ and $s(I_1 \cap I_j) = s(I_1) \geq s(T_1) \geq \min\{s(T_1), s(T_j)\}$, $\forall j$.

Again if $c(T_1) > c(I_1)$ and $s(T_1) > s(I_1)$, then u_1 is not an isolated vertex, then u_1 has a neighbor u_k . This implies that $c(T_k) \leq c(I_1)$ and $s(T_k) \leq s(I_1)$, that means u_k is an universal vertex as $c(I_k \cap I_j) = \min\{c(I_k), c(I_j)\} \geq c(I_1) \geq c(T_k) \geq \min\{c(T_k), c(T_j)\}$ and $s(I_k \cap I_j) = \min\{s(I_k), s(I_j)\} \geq s(I_1) \geq s(T_k) \geq \min\{s(T_k), s(T_j)\}$, $\forall j$.

This proves that G^* is a PF threshold graph.

Theorem 4.5 A PF max-tolerance chain graph ($PFmax$ TCG) is an $PFIG$.

Proof Let $N = \{I_i^* : i = 1, 2, \dots, n\}$ be a nested family of PFIs along with corresponding PFTs $T^* = \{T_i^* : i = 1, 2, \dots, n\}$, where $I_i^* = [0, r_i]$ and $0 < r_1 \leq r_2 \leq \dots \leq r_n$. Consider each nested family of PFI as vertex of the $PFmax$ TCG. Let $V = \{u_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding $PFmax$ TCG is the PFG G^* .

Assume that $c(T_i) \leq c(I_i)$ and $s(T_i) \leq s(I_i)$, for $i = 1, 2, \dots, n$, for if $c(T_i) > c(I_i)$ and $s(T_i) > s(I_i)$, then

u_i is an isolated and we disregard u_i . Consequently, u_i and u_j are adjacent iff $\min\{c(I_i), c(I_j)\} \geq \max\{c(T_i), c(T_j)\}$ and $\min\{s(I_i), s(I_j)\} \geq \max\{s(T_i), s(T_j)\}$.

This will be true iff $[T_i, r_i]$ and $[T_j, r_j]$ have a non-empty intersection.

Thus, the $PFmax$ TCG of N is the $PFIG$ of the intervals $\{[T_i, r_i] : i = 1, 2, \dots, n\}$.

Theorem 4.6 A PF sum-tolerance chain graphs ($PFsum$ TCGs) are chordal.

Proof Let $N = \{I_i^* : i = 1, 2, \dots, n\}$ be a nested family of PFIs along with corresponding PFTs $T^* = \{T_i^* : i = 1, 2, \dots, n\}$, where $I_i^* = [0, r_i]$ and $0 < r_1 \leq r_2 \leq \dots \leq r_n$. Consider each nested family of PFI as vertex of the $PFsum$ TCG. Let $V = \{u_i : i = 1, 2, \dots, n\}$ be the vertex set and corresponding $PFsum$ TCG is the PFG G^* .

Let u_j be a vertex with maximum tolerance and let u_i and u_k be two distinct neighbors of u_j . Then we have $c(T_i) + c(T_k) \leq c(T_i) + c(T_j) \leq \min\{c(I_i), c(I_j)\} \leq c(I_i)$. $s(T_i) + s(T_k) \leq s(T_i) + s(T_j) \leq \min\{s(I_i), s(I_j)\} \leq s(I_i)$ and $c(T_i) + c(T_k) \leq c(T_j) + c(T_k) \leq \min\{c(I_j), c(I_k)\} \leq c(I_k)$. $s(T_i) + s(T_k) \leq s(T_j) + s(T_k) \leq \min\{s(I_j), s(I_k)\} \leq s(I_k)$.

So that, $c(T_i) + c(T_k) \leq \min\{c(I_i), c(I_k)\}$ and $s(T_i) + s(T_k) \leq \min\{s(I_i), s(I_k)\}$.

This shows that $PFsum$ TCGs are chordal.

Application of tolerance graph in sports competition

The PFTG is an important tool that can be applied in different types of real life problems. We consider a PFG model of PFIs in Fig. 14 representing the 4×100 meter relay race competition of a group of team, each having 4 runners and assigned them to run for a fixed interval of distance in a lane. The lead off runner starts the race with baton in-hand from the starting point when he hears the starter’s gun. Each runner tries to hand-over the baton without dropping to his next teammate after completing own assigned distance. Also, that teammate must have to receive this baton within 20 m area from his starting point, otherwise his team will be disqualified. A team will win this competition if its last runner successfully cross the finish line first. Each team has some tolerances, because runners have to wait some distances for other. The problem is to schedule the teams to finish the race under certain rules. This problem can be modeled by the $PFmin$ TG, where the runners are considered as vertices and there is an edge between the vertices if interval of distances of two runners intersect. In practical situation, the tolerance of a graph may be a PF -number. For example, each runner tries to receive baton from his earlier teammate in between 0 and 20 m distance, i.e., the baton will be handed over within any distance in between 0 and 20 m. This is an uncertainty. So, we may consider the

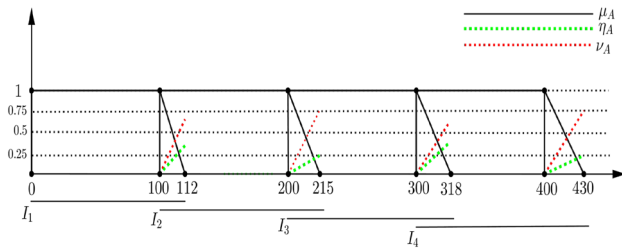


Fig. 14 PFI representation of the problem

tolerances as a PF-number. The following algorithm finds the minimum tolerance between two runners when they run on the same lane.

Algorithm

Aim: To get a PFTG of the competition such that there is a minimum tolerance between two runners when they run on the same lane under certain rules.

Input: Four PFIs of distances with their cores and supports and the corresponding PFTs with their CLs and SLs.

Output: A PFmin TG having minimum tolerances among the runners.

Step 1: Assign PFIs of distances $\{I_i : i = 1, 2, 3, 4\}$ with their respective cores and supports for the set of runners $\{r_i : i = 1, 2, 3, 4\}$ in the competition.

Step 2: Assign PFTs $\{T_i : i = 1, 2, 3, 4\}$ corresponding to the PFIs with their respective CLs and SLs.

Step 3: Compute $I_i \cap I_j, c(I_i \cap I_j), s(I_i \cap I_j)$ and $h(I_i \cap I_j)$, where $i, j = 1, 2, 3, 4 (i \neq j)$.

Step 4: If $I_i \cap I_j \neq \emptyset$, then draw an edge (r_i, r_j) , where $i \neq j$.

Step 5: Calculate the TMS, AMS and FMS for each of vertices by using the formula $\mu_A(r_i) = h_\mu(I_i), \eta_A(r_i) = h_\eta(I_i)$ and $\nu_A(r_i) = h_\nu(I_i)$.

Step 6: Calculate the TMS, AMS and FMS of edges by using the respective formulas as follows:

$$\mu_B(r_i, r_j) = \begin{cases} 1, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\mu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\eta_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\eta(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 0, & \text{otherwise.} \end{cases}$$

$$\nu_B(r_i, r_j) = \begin{cases} 0, & \text{if } c(I_i \cap I_j) \geq \min\{c(T_i), c(T_j)\} \\ \frac{s(I_i \cap I_j) - \min\{s(T_i), s(T_j)\}}{s(I_i \cap I_j)} h_\nu(I_i \cap I_j), & \text{if } s(I_i \cap I_j) \geq \min\{s(T_i), s(T_j)\} \\ 1, & \text{otherwise.} \end{cases}$$

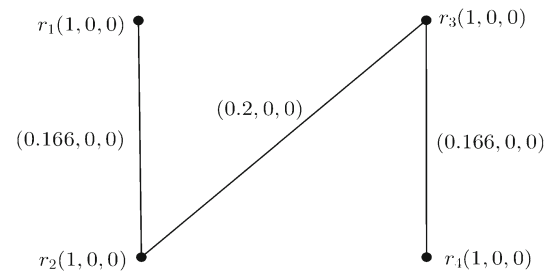


Fig. 15 Corresponding PFmin-TG

Illustration of algorithm

Step 1: Assume that the runners r_1, r_2, r_3 and r_4 can run for the interval of distances I_1, I_2, I_3 and r_4 , respectively. They run actively in the intervals $[0, 100], [100, 200], [200, 300]$ and $[300, 400]$; these are considered as core of the intervals. Also, they run both actively and inactive in the interval of distances $[0, 112], [100, 215], [200, 318]$ and $[300, 430]$; these are considered as support of the intervals as shown in the diagram of Fig. 14.

Step 2: Let $\{T_i : i = 1, 2, 3, 4\}$ are the tolerances corresponding to the intervals $\{I_i : i = 1, 2, 3, 4\}$ with $c(T_1) = 8, c(T_2) = 9, c(T_3) = 13, c(T_4) = 16$ and $s(T_1) = 10, s(T_2) = 12, s(T_3) = 15, s(T_4) = 22$.

Step 3: Here, $I_1 \cap I_2 = [100, 112], I_2 \cap I_3 = [200, 215], I_3 \cap I_4 = [300, 318]$; $s(I_1 \cap I_2) = 12, s(I_2 \cap I_3) = 15, s(I_3 \cap I_4) = 18; c(I_1 \cap I_2) = 0, c(I_2 \cap I_3) = 0, c(I_3 \cap I_4) = 0; h(I_1 \cap I_2) = (1, 0, 0), h(I_2 \cap I_3) = (1, 0, 0), h(I_3 \cap I_4) = (1, 0, 0)$.

Step 4: Since some interval of distances overlapped, then tolerance arises between some runners. There exist tolerances between the runners r_1 and $r_2; r_2$ and $r_3; r_3$ and r_4 .

Step 5: The TMS, AMS and FMS of each vertex are obtained as follows: $(\mu_A(r_i), \eta_A(r_i), \nu_A(r_i)) = (h_\mu(I_i), h_\eta(I_i), h_\nu(I_i)) = (1, 0, 0), i = 1, 2, 3, 4$

Step 6: Using the formula of Definition 3.6, we have the TMS, AMS and FMS of the edges $(r_1, r_2), (r_2, r_3)$ and (r_3, r_4) as $(0.166, 0, 0), (0.2, 0, 0)$ and $(0.166, 0, 0)$

Table 1 The characteristic comparison of PFTGs with IFTGs

Method	Whether have the ability to handle problems with more uncertainties	Whether have the ability to represent PF information	Whether have the characteristics of generalization
Sahoo and Pal [41]	×	×	×
The proposed PFTGs	✓	✓	✓

respectively, in the corresponding PFmin TG (see Fig. 15). The following observations are made from the PFmin TG: There are tolerances between the runners r_1 and r_2 ; r_2 and r_3 ; r_3 and r_4 . But there is no tolerance between r_1 and r_3 ; r_1 and r_4 ; r_2 and r_4 . Thus, the runners are assigned to run for a fixed interval of distance in own lane such that there is a minimum tolerance.

Comparative study with existing IFTG models

In existing papers on IFTGs, all information was taken in IF sense. When more possible types of vagueness and uncertainty occur in information, then the IFTG models are not appropriate to handle such situation. For these cases, the information should be collected or represented as PF sense. The currently developed model plays a vital role in such cases to give a fruitful conclusion.

Sahoo and Pal [41] proposed an IFTG model by considering each vertex and edge with IF information and determined the minimum tolerance among the employees in a company when they scheduled to work on the same work station. In IFTG models, only membership and non-membership values of vertices and edges are considered. So these models are not applicable when the models are considered in other environment like in PF environment. In our currently developed PFTG model, we include another parameter called neutral membership value and it is practically useful in case of real life problem. The PFTG models are more generalized and superior than the IFTG models. Moreover, it will be capable to accommodate more vagueness and uncertainties and provides better results than the existing models. On removing the neutral membership value of PFTG, the PFTG reduces to conventional IFTG. Thus, PFTG can be viewed as an effective generalization of IFTG. The characteristics comparison of our proposed PFTGs with IFTGs is given in Table 1.

Conclusion

In this study, we have applied the powerful tool of fuzziness to generalize PFIGs using tolerances under the PF environment. Our proposed PF model provides more legibility, flexibility

and suitability to the system as compared with the models in other fields due to the existence of additional term named as ‘neutrality’ and which discriminate this model from all other existing models of literature. We have mainly studied the construction methods of several types of PFTGs. Adding more uncertainty to fuzzy ϕ -TGs and IF ϕ -TGs, we have introduced PF ϕ -TGs. Some specific results are established when ϕ is the max, min and sum functions. Also, PF proper TGs and unit TGs are defined and investigated few strong properties related to the stated TGs. Later on, PF ϕ -TCGs have been studied with some results. In addition, to reveal the importance of these TGs in realistic situations, we have applied our proposed model in sports competition. Finally, we have compared our proposed PFTGs with IFTGs to check the superiority and authenticity of proposed graphs which leads us to handle the problems having more possible types of vagueness and uncertainties. In future, we will extend this work to PFT CGs and m -Step PFT CGs.

Declarations

Conflict of interest The authors declare that there is no conflict of interest.

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