

Sequential quadratic programming particle swarm optimization for wind power system operations considering emissions



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Abstract In this paper, a computation framework for addressing combined economic and emission dispatch (CEED) problem with valve-point effects as well as stochastic wind power considering unit commitment (UC) using a hybrid approach connecting sequential quadratic programming (SQP) and particle swarm optimization (PSO) is proposed. The CEED problem aims to minimize the scheduling cost and greenhouse gases (GHGs) emission cost. Here the GHGs include carbon dioxide (CO_2), nitrogen dioxide (NO_2), and sulphur oxides (SO_x). A dispatch model including both thermal generators and wind farms is developed. The probability of stochastic wind power based on the Weibull distribution is included in the CEED model. The model is tested on a standard system involving six thermal units and two wind farms. A set of numerical case studies are reported. The performance of the hybrid computational method is validated by comparing with other solvers on the test system.

Keywords Combined economic and emission dispatch, Unit commitment, Particle swarm optimization, Sequential quadratic programming, Weibull distribution, Wind power

1 Introduction

Power system generation scheduling problem can be divided into two sub-problems, unit commitment (UC) and economic dispatch (ED). ED is an important task in the

power system operation, which aims to allocate power generation match load demand at minimal possible cost while satisfying all the units and system constraints [1–3]. Suitable improvements in the unit outputs scheduling can contribute to significant cost savings.

Nowadays, with the awareness of environmental pollution contributed by the combustion of fossil fuels, building a low-carbon world has attracted widespread attentions. Many countries are trying to exploit clean energy in order to mitigate the greenhouse effects. The primary source of greenhouse gases (GHGs) is the combustion of fossil fuels. Coal, oil, and gas are the three major types of regular fuels, which produce emissions represented by GHGs, such as CO_2 , NO_2 , and SO_x . In order to reduce the GHGs emissions, the combined economic emission dispatch (CEED) considering with UC was proposed, which can take account of fuel cost and emission tax together. Because the amount of emission from fossil-based thermal generators depends on the amount of generated power, therefore the emission cost increase leads to reduced overall power generated by thermal units, which in turn lowers emissions. Moreover, the natural economic forces will also help to catalyse the move to greater energy efficiency and use of renewable sources. Wind energy is among the major contributors to an overall reduction in GHGs emissions. Dispatch strategies normally can provide quick solutions to improve the current situation of system operation and reduce carbon emissions dramatically. On the other hand, exploiting renewable energy is another effective way to mitigate energy source deficiency, control GHGs emissions, and achieve smart grid vision [4–6]. Wind power being one of the most appealing renewable energy resources has gained widespread concerns during the last decades. Along with the introduction of various emission reduction schemes, increasing number of wind turbines have been installed around the world [7]. However, due to the intermittent and

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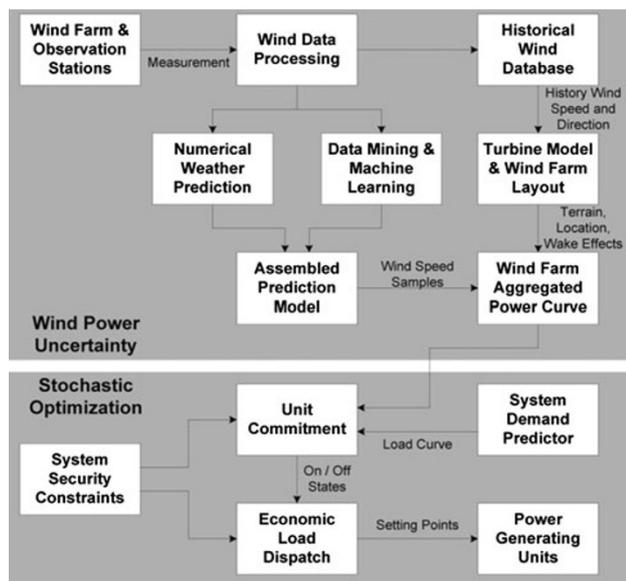


Fig. 1 Computational framework considering wind power uncertainties

stochastic characteristics of wind resource, wind power brings great challenges to power system economic dispatch problems. One of the major challenges is how to effectively accommodate the wind forecasting errors. Because variations of wind speed directly influence the power output of wind farms, which then causes difficulties in estimating suitable system reserve margin to ensure secure and reliable system operations. As a result, high penetration of wind power also causes high potential risks and more difficulties in power system operation. Although wind speed is difficult to forecast by single predictor, composite forecast model can statistically produce an optimal forecast by computing prediction results from a number of different methods. The fundamental concept is that if the errors in the forecasts produced by different methods are unbiased and have a low degree of correlation with each other, the random errors from the individual forecasts will tend to offset each other, with the result that a composite of the forecasts will have lower errors than any individual forecast. Moreover, huge number of publications has indicated that wind speed follows Weibull distribution approximately [8]. In order to assist with management of the uncertainties of wind forecasts, extensive researches have been conducted to develop kinds of probabilistic optimization strategies [9, 10]. In this paper, a schematic representation of computational framework contains wind power forecast and stochastic unit commitment/economic dispatch, which is adopted from [38], is shown in Fig. 1.

In order to accommodate the revised dispatch strategy, more efficient solvers are needed. Different heuristic techniques have been developed to solve the classical ED

problems with constraints, to namely simulated annealing (SA) [11], genetic algorithm (GA) [12], evolutionary programming (EP) [13, 14], tabu search (TS) [15], pattern search (PS) [16], particle swarm optimization (PSO) [17, 18], as well as differential evolution (DE) [19, 20]. Based on our experience, when compared with other approaches, the PSO is computationally inexpensive in terms of memory and speed. However, these heuristic methods do not always guarantee discovering globally optimal solutions in finite time, especially when being applied into large-scale optimization problems. Therefore, more sophisticated computational tools are required. Recently, hybrid optimization techniques which combine different approaches receive widespread concerns. In [21], the authors presented a hybrid EP and sequential quadratic programming (SQP) for solving the ED problem with non-smooth fuel cost function. A hybrid self-tuning DE was proposed to solve the ED problem with kinds of constraints in [22]. In [23], a hybrid approach combining DE with biogeography-based optimization (DE/BBO) was developed to address both convex and non-convex ED problem. These hybrid optimization methods were found to be more effective and accurate. SQP is one of best nonlinear-programming method for constrained optimization. SQP-PSO technique is an effective nonlinear-programming method over a large number of test problems in terms of accuracy, efficiency and percentage of successful solutions.

In this paper, a CEED model incorporating wind power to minimize the total cost is proposed. Because of the stochastic nature of wind speed, wind power output is not deterministic. As a sequence, the probability distribution of wind speed must be taken into account in the CEED model.

In our CEED model, wind power is described as the three-parameter Weibull distribution. As ED problem in consideration of emission issue, there are some works reducing the NO_2 , as well as SO_2 , however, there are few papers on CEED in consideration of the CO_2 emission. In this paper, the reduction of CO_2 emission is one of the main concerns in the CEED model. In terms of the problem solver, we present a hybrid technique which combines SQP and PSO together. In the proposed algorithm, SQP is firstly used to solve the CEED problem without considering the valve-point effects, and then based on the obtained initial solution and boundaries PSO is employed to solve the CEED problem with non-smooth fuel cost function.

The rest of this paper is organized as follows. Section 2 introduces the probability of wind power. Section 3 describes the mathematical formulation of CEED considering UC problem with stochastic wind power. The basic concepts of SQP and PSO are introduced in Section 4, and the hybrid algorithm is also summarized in this section. Section 5 presents the numerical case studies solving the

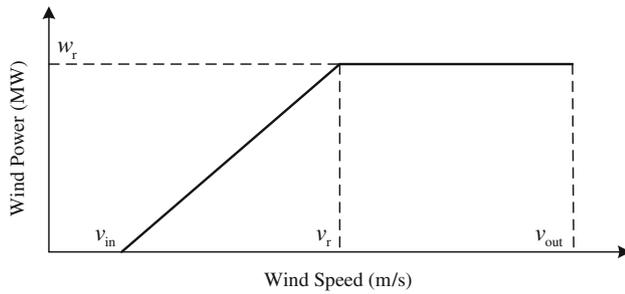


Fig. 2 Simplified wind turbine power curve

ED and CEED problems with and without wind power. Remarks and conclusions are given in Section 6.

2 Probabilistic modeling of wind power for edmodeling

Wind power, one of the most appealing renewable energy sources, has been widely developed in the recent years. Wind power energy has lots of advantages such as no pollution, relatively low capital cost involved, and the short gestation period required. However, the wind resource changes with locations and climates resulting in high uncertainties in the produced energy. The total power available from a wind turbine is equal to the product of the mass flow rate of the wind m_w , and $V^2/2$. Assuming constant area or ducted flow, the continuity equation states that $m_w = \rho AV$, where ρ is the density of the air in kg/m^3 , A is the blades area in m^2 , and V is the velocity in m/s . Thus, the total wind power becomes $P_w = (m_w V^2)/2 = (\rho AV^3)/2$ (MW). In this equation, the wind speed V is a random variable. Ignoring minor nonlinearities, the function relation between a given wind speed and power output can be described in Fig. 2.

In the above figure, w (MW) is the wind energy conversion systems (WECS) output power; w_r (MW) is the WECS output rated power; v_{in} (m/s), v_r (m/s), v_{out} (m/s) is the WECS cut-in speed, rated speed, and cut-out speed, respectively. Figure 1 shows that there is no power generated at wind speeds below v_{in} or above v_{out} ; at wind speeds between v_r and v_{out} , the output is equal to the rated power of the generator; at wind speeds between cut-in wind speed and rated wind speed, the output is a linear function power.

Therefore, the wind power output can be described as,

$$\begin{cases} W = 0, & V < v_{in} \text{ or } V > v_{out} \\ W = aV + b, & v_{in} \leq V \leq v_r \\ W = w_r, & v_r \leq V \leq v_{out} \end{cases} \quad (1)$$

where $a = \frac{w_r}{v_r - v_{in}}$, $b = -\frac{v_{in} w_r}{v_r - v_{in}}$.

Weibull distribution is the most popular density function that can be used to describe wind speed frequency curve

[24–26]. An extensive review of various probability density functions of wind speed was provided in [26], and comparisons were made. The results indicated that the two-parameter Weibull distribution is the widely accepted model. Using two-parameter Weibull distribution, cumulative distribution function (CDF) and probability density function (pdf) of wind speed are

$$F_V(v) = 1 - \exp\left[-\left(\frac{v}{c}\right)^k\right], \quad (v \geq 0) \quad (2)$$

$$f_V(v) = \frac{k}{c} \left(\frac{v}{c}\right)^{k-1} \exp\left[-\left(\frac{v}{c}\right)^k\right] \quad (3)$$

where $k > 0$ is the shape parameter, $c > 0$ is the scale parameter.

According to (1), three portions of WECS power output can be analysed and the corresponding probabilities (CDF or pdf) can be calculated.

(i) For $V < v_{in}$ or $V > v_{out}$,

$$\begin{aligned} P(W = 0) &= P(V < v_{in}) + P(V > v_{out}) \\ &= F_V(v_{in}) + [1 - F_V(v_{out})] \\ &= 1 - \exp\left[-\left(\frac{v_{in}}{c}\right)^k\right] + \exp\left[-\left(\frac{v_{out}}{c}\right)^k\right] \end{aligned} \quad (4)$$

(ii) For $v_{in} \leq V \leq v_r$, $W = aV + b = \frac{(V - v_{in})w_r}{v_r - v_{in}}$, depending on the definition of cumulative distribution function (CDF), the CDF of WECS output power can be described as,

$$\begin{aligned} F_W(w) &= P\{W \leq w\} = P\left\{W = \frac{(V - v_{in})w_r}{v_r - v_{in}} \leq w\right\} \\ &= P\left\{V \leq \frac{(v_r - v_{in})w}{w_r} + v_{in}\right\} = F_V\left\{\frac{(v_r - v_{in})w}{w_r} + v_{in}\right\} \end{aligned} \quad (5)$$

We can obtain the pdf of W by differentiating with respect to w . The chain rule for derivatives can be used, $\frac{dF}{dw} = \frac{dF}{du} \frac{du}{dw}$, where u is the argument of F , $u = \left\{\frac{(v_r - v_{in})w}{w_r} + v_{in}\right\}$, and then we obtain

$$\begin{aligned} f_W(w) &= \frac{k(v_r - v_{in})}{c w_r} \cdot \left[\frac{(v_r - v_{in})w}{w_r} + v_{in}\right]^{k-1} \\ &\quad \exp\left[-\left(\frac{(v_r - v_{in})w}{w_r} + v_{in}\right)^k\right] \end{aligned} \quad (6)$$

(iii) For $v_r \leq V \leq v_{out}$,

$$\begin{aligned} P(W = w_r) &= P(v_r \leq V \leq v_{out}) \\ &= F_V(v_{out}) - F_V(v_r) \\ &= \exp\left[-\left(\frac{v_r}{c}\right)^k\right] - \exp\left[-\left(\frac{v_{out}}{c}\right)^k\right] \end{aligned} \quad (7)$$



3 Mathematical formulation of CEED problem with wind power

This section describes the problem formulation of the proposed CEED considering UC model including wind power. The model aims at minimizing the total operation costs (including fuel cost, wind farm cost) and emission cost while satisfying the given constraints. In [27], an economic dispatch (ED) model incorporating wind power is developed. In order to accurately characterize the uncertainty in the availability of wind energy, penalty costs functions for both underestimation and overestimation cases were added. Inspired by the practical application, a similar CEED model are developed with an additional term incorporated to account for government wind farm subsidy. To address the uncertainties in wind power production, wind speed distribution probability functions are applied in formulating the optimization model.

3.1 Objective function

The objective function is formulated to minimize the total system operation costs and greenhouse gases (CO₂ and NO₂) emission costs. A cost function is obtained based on the ripple curve for more accurate modelling which contains higher order nonlinearity and discontinuity due to the valve point effect [16] and should be refined by a sine function [28]. The overall objective function can be expressed as the sum of these two terms,

$$\text{Min. } (Cost_1 + Cost_2) \tag{8}$$

1) Total system scheduling costs

$$\begin{aligned}
 Cost_1 = & \sum_{i=1}^M C_i(p_i) + \sum_{j=1}^N C_{w,j}(w_{j,av}) \\
 & + \sum_{j=1}^N C_{u,j}(W_{j,av} - w_j) + \sum_{j=1}^N C_{o,j}(w_j - W_{j,av}) \\
 & - \sum_{j=1}^N C_{s,j}(w_{j,av}) \tag{9}
 \end{aligned}$$

$$C_i(p_i) = a_i + b_i p_i + c_i p_i^2 + |d_i \sin(e_i(p_{i,min} - p_i))| \tag{10}$$

where M is the number of thermal power generators; N the number of wind turbines; a_i, b_i, c_i the cost coefficients of thermal generator i ; d_i, e_i are valve-point effects coefficients of thermal generator i ; C_i the cost function of thermal generator i ; $C_{u,j}$ the cost coefficient for not using all generated wind power due to the underestimation case; $C_{o,j}$ the cost coefficient for purchasing reserve power from other source due to overestimation case; $C_{s,j}$ the government subsidy parameter of turbine j ; $C_{w,j}$ the cost coefficient of wind turbine j ; p_i the actual power generated by

thermal generator i ; w_j the predicted wind power generated by turbine j ; $W_{j,av}$ the actual wind power generated by wind turbine j ; $C_i(p_i)$ the fuel cost function of thermal generator i ; $C_{w,j}(w_{j,av})$ the wind power cost of the wind farm.

If the wind farm is owned by the system operator, this term may not exist. In this paper, the wind farm is assumed to be owned by the operator, so this cost is equal to zero. The underestimation cost $C_{u,j}(W_{j,av} - w_j)$ occurs if the actual generated wind power is more than the predicted, thus the system operator should compensate for the surplus wind power cost. On the other hand, if the actual wind power is less the predicted scheduling power, the operator needs to purchase from an alternate source and pay the overestimation cost $C_{o,j}(w_j - W_{j,av})$. The last term in the Eq. (9) is the wind power subsidy cost $C_{s,j}(w_{j,av})$. As one of the renewable energy subsidy projects, wind farm in many countries receive a largely covert subsidy. An excellent example is the Renewable Obligation (RO) in UK. The RO is designed to encourage generation of electricity from eligible renewable sources in the UK [29]. In this paper, the wind farm was assumed to receive a fix cost subsidy for generating every MW wind power.

According to [29], the cost of underestimation will be assumed as follow,

$$\begin{aligned}
 C_{u,j}(W_{j,av} - w_j) &= C_{u,j} \int_{w_j}^{w_{r,j}} (w - w_j) f_W(w) dw \\
 &= C_{u,j} \left[\int_{w_j}^{w_{r,j}} w f_W(w) dw - w_j \int_{w_j}^{w_{r,j}} f_W(w) dw \right] \tag{11}
 \end{aligned}$$

where $w_{r,j}$ is the rated wind power from wind turbine j .

In terms of overestimation case, the cost equation will be in the similar manner,

$$\begin{aligned}
 C_{o,j}(w_j - W_{j,av}) &= C_{o,j} \int_0^{w_j} (w_j - w) f_W(w) dw \\
 &= C_{o,j} \left[w_j \int_0^{w_j} f_W(w) dw - \int_0^{w_j} w f_W(w) dw \right] \tag{12}
 \end{aligned}$$

Equations (11) and (12) can be solved through the wind power probability (4)–(7).

2) Greenhouse gases (GHGs) emission costs

$$Cost_2 = \sum_{i=1}^M F_{GHG,i}(p_i) \tag{13}$$

where $F_{GHG,i}(p_i)$ is the emission cost of thermal unit i .

$$F_{GHG,i}(p_i) = h \cdot EM_i(p_i) \tag{14}$$

$$EM_i(p_i) = e f_i (f_i + g_i p_i + h_i p_i^2) \tag{15}$$

where $EM_i(p_i)$ is the GHGs emissions of thermal generator i ; $e f_i$ the fuel emission factor of GHGs for thermal generator i ; f_i, g_i, h_i the fuel consumption coefficients of thermal

unit; h is the given GHGs emissions price which is determined by regulations and markets. GHGs are CO₂ and NO₂ in this paper

Equation (13) represents the fuel cost function of thermal generators. Equation (14) expresses the GHGs emission cost function.

3.2 System constraints

$$p_{i,\min} \leq p_i \leq p_{i,\max} \tag{16}$$

$$0 \leq w_j \leq w_{r,j} \tag{17}$$

$$\sum_{i=1}^M p_i + \sum_{j=1}^N w_j = p_d + p_{\text{loss}} \tag{18}$$

where p_d is total system loads; and p_{loss} is total transmission losses.

Inequality constraint (16) defines the limitations of thermal units output from the lower to the upper bound. And constraint (17) shows the wind power output limitations. Equation (18) gives the power balance between generations and loads including the transmission losses.

4 Hybrid optimization algorithm

In this section, a hybrid optimization algorithm is presented, which combines SQP and PSO together.

4.1 Sequential quadratic programming (SQP)

Since its popularization in the late 1970s, SQP has arguably become the most successful approaches for solving nonlinearly constrained optimization problems [30]. Backed by a mature and solid theoretical background, SQP has been developed and used to solve a remarkably large number of practical problems. The basic principle of sequential approximations is to replace the given problem by a sequence of quadratic sub-problems that are easier to solve [31, 32]. Consider the application of the SQP methodology to nonlinear optimization problems,

$$\begin{aligned} &\text{Min. } f(x) \\ \text{s.t. } &\begin{cases} h(x) = 0 \\ g(x) \leq 0 \end{cases} \end{aligned} \tag{19}$$

The Lagrangian of this problem can be written as,

$$L(x, \lambda, \mu) = f(x) + \lambda h(x) + \mu^T g(x) \tag{20}$$

where λ and μ are vectors of multipliers. SQP is an iterative procedure which models the problem for a given iterate x^k by a quadratic programming sub-problem, solves that quadratic programming sub-problem, and then uses the solution to construct a new iterate x^{k+1} .

The sub-problem can be constructed by linearizing the constraints of around x^k , and it can be written as,

$$\begin{aligned} &\text{Min } \nabla f(x^k)(x - x^k) + \frac{1}{2}(x - x^k)^T Hf(x^k)(x - x^k) \\ \text{s.t. } &\begin{cases} h(x^k) + \nabla h(x^k)(x - x^k) = 0 \\ g(x^k) + \nabla g(x^k)(x - x^k) \leq 0 \end{cases} \end{aligned} \tag{21}$$

We need to update the estimates of the multipliers, and define the corresponding search directions, and then choose a step size and define the next iterate.

4.2 Particle swarm optimization

PSO is a global search technique originally introduced by Kennedy and Eberhart [33]. It simulates the social evolution knowledge, probing the optimum by evolving the population which may include candidate solutions. In the classical PSO, each individual is treated as a particle in the space, with position and velocity vectors. The algorithm maintains a swarm of particles, where each particle represents a potential solution to the objective problem. For a given n -dimensional problem, the position and velocity vectors of a particle in the PSO can be represented as

$$\begin{cases} x_j(t) = [x_{j,1}(t), x_{j,2}(t) \dots, x_{j,n}(t)] \\ v_j(t) = [v_{j,1}(t), v_{j,2}(t) \dots, v_{j,n}(t)] \end{cases} \tag{22}$$

The core idea of the classical PSO is the exchange of information among the global best, population best, and current particles, which can be done as follows

$$\begin{aligned} v_j(t+1) &= \omega \cdot v_j(t) + \varphi \cdot r_1 \cdot [p_{\text{pb}}(t) - x_j(t)] \\ &\quad + \eta \cdot r_2 \cdot [p_{\text{gb}}(t) - x_j(t)] \\ x_j(t+1) &= x_j(t) + v_j(t+1) \end{aligned} \tag{23}$$

where v_j is velocity vectors; ω the inertia weight; p_{pb} the local best particle; and p_{gb} is global best particle, $\varphi = 1.65$, $\eta = 1.81$.

4.3 Composite computation approach

The procedures of the proposed hybrid algorithm are summarized as the follows,

Step-1. Load history wind data, generators and wind turbines settings, emission parameters, and forecast wind power output;

Step-2. Solve the ED and CEED problem without considering valve-point effects incorporating wind power using SQP;

Step-3. Calculate the updated constraints using (24) [34], and randomly generate initial population around the solution obtained from SQP for PSO;



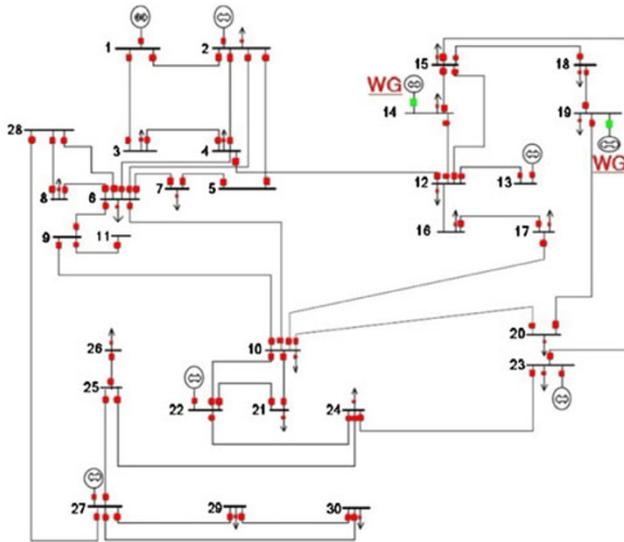


Fig. 3 Modified IEEE 30-bus system

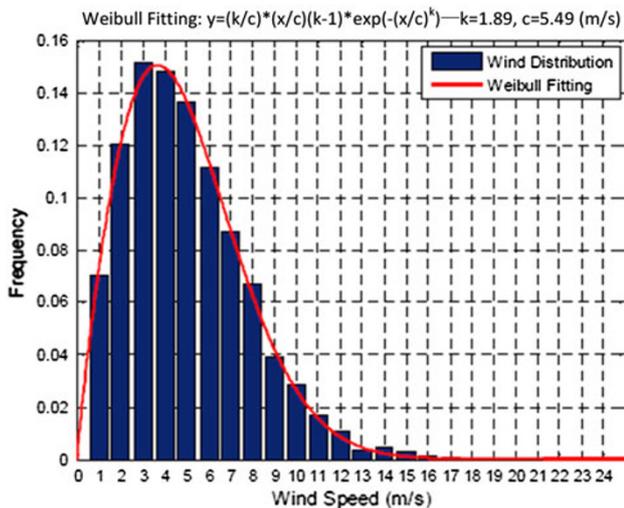


Fig.4 Wind speed distribution and Weibull fitting

$$\begin{cases} p_{i,\min} = \max([p_i - \beta_i], p_{i,\min}) \\ p_{i,\max} = \min([p_i + \beta_i], p_{i,\max}) \\ \beta_i = \pi / (1 + \gamma) e_i \end{cases} \quad (24)$$

Step-4. Solve the ED and CEED problem with valve-point effects incorporating wind power using PSO;
 Step-5. Save and output final solution. Application of this approach in ED and CEED problem incorporating wind power are presented in the following section.

5 Case studies

The QPSO is implemented on a modified IEEE 30-bus system. The benchmark system consists of 6 thermal

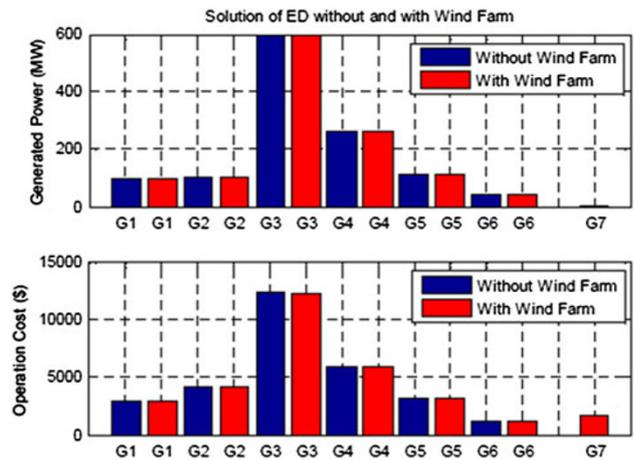


Fig.5 Solutions of ED models without and with wind farm

Table 1 Wind power factors

c	k	θ	v_{in}	v_{out}	v_r	w_r	$C_{w,j}$	$C_{u,j}$	$C_{o,j}$	$C_{s,j}$
5.5	1.89	0	4	25	16	3	0	60	20	10

generators, 2 wind farms, 41 branches, and 21 loads. These thermal generators include 3 coal-fired units, 2 gas-fired units, and 1 oil-fired unit. The test system is shown in Fig. 3 [35].

In the case study part, the CEED model with wind power was evaluated using the historical wind speed dataset from a wind observation station in Tasmania, Australia. The data was provided by the Australian Bureau of Meteorology [36]. Here we assume that the wind speed data from a large wind farm and use the data to estimate the generated wind power. The wind speed distribution frequency and the corresponding Weibull distribution parameters are presented in Fig. 4.

The Vestas V90 3.0 MW wind turbine is selected for the case studies. It is a pitch regulated upwind wind turbine with active yawing and a three-blade rotor. It has a rotor diameter of 90 m with a generator rated at 3.0 MW. The Vestas V90 3.0 MW is widely used in the wind plants in Australia and has a proven high efficiency. The parameters of the associated Weibull distribution factor and wind farm parameters can be calculated from the wind speed data and are given in Table 1.

The wind farm totally consists of 100 Vestas V90 3.0 MW wind turbines located in a coherent geographic area. The predicted power output for each wind turbine is denoted as w_j and is 15 % of the rated power, which is 0.45 MW. Depended on the actual generated wind power, the extra cost will be determined by overestimation case or underestimation case. According, the maximum capacity of the system under investigation is 2,030 and 2,330 MW incorporating with wind power. The fuel cost coefficients,

Table 2 Fuel cost coefficients

Unit	Fuel cost coefficients				
	a_i	b_i	c_i	d_i	e_i
G1 (Coal)	2,000	10	0.002	200	0.084
G2 (Coal)	2,500	15	0.0025	300	0.035
G3 (Coal)	6,000	9	0.0018	400	0.042
G4 (Gas)	923.4	18	0.00315	150	0.063
G5 (Gas)	950	20	0.0032	100	0.084
G6 (Oil)	124.8	23.4	0.003432	80	0.098

The coefficients of a_i , b_i , c_i and e_i are in \$, \$/MW and \$/MW², and \$/MW

Table 3 Fuel consumption coefficients and generator limits

Unit	Fuel consumption coefficients			P_{min}	P_{max}
	f_i	g_i	h_i		
G1 (Coal)	40	0.2	0.00004	20	110
G2 (Coal)	50	0.3	0.00005	20	100
G3 (Coal)	80	0.12	0.000024	120	600
G4 (Gas)	2,462.4	48	0.0084	110	520
G5 (Gas)	2,500	50	0.009	110	500
G6 (Oil)	1.248	0.234	3.43e-05	40	200
G7 (Wind)	0	0	0	0	300

The coefficients of f_i , g_i , and h_i are in t , t /MW and t /MW² for coal/oil units. The coefficients of f_i , g_i , and h_i are in m^3 , m^3 /MW and m^3 /MW² for gas unit

Table 4 Emission factors of units

Emission factor	Coal (kg/kg)	Gas (kg/m ³)	Oil (kg/kg)
efCO ₂	3.1604	1.84	2.8523
efNO ₂	1.29e-03	3.4e-04	3.3e-04

generator limits, and fuel consumption coefficients are shown in Tables 2 and 3 [35]. The proposed algorithm is implemented on a test system including 6 thermal generators and 1 large wind farm. There are 3 coal-fired units, 2 gas-fired units, and 1 oil-fired unit in this test system. The wind farm totally consists of 100 Vestas V90 3.0 MW wind turbines located in a coherent geographic area. The predicted power output for each wind turbine is denoted as w_j and is 15 % of the rated power, which is 0.45 MW. Depended on the actual generated wind power, the extra cost will be determined by overestimation case or underestimation case. The maximum capacity of the system under investigation is 2,030 and 2,330 MW incorporating with wind power. The fuel cost coefficients, generator limits, and fuel consumption coefficients are shown in Tables 2 and 3 [35].

Table 5 Emission prices

Fuel	CO ₂ (\$/t)	NO ₂ (\$/kg)
Price	1.5	5.0

Table 6 Forecast system demand and wind farm output

Case index	Case 1	Case 2
Demand (MW)	1,200	1,600
G7	45	45

Table 7 Solution of ELD without wind farm

Unit	Power (MW)	Operation cost (\$)
G1 (Coal)	96.9286	29,69,047
G2 (Coal)	99.4079	4,122.16
G3 (Coal)	593.5730	12,359.45
G4 (Gas)	259.1281	5,808.68
G5 (Gas)	110.6357	3,207.22
G6 (Oil)	40.3266	1,076.58
Total	1,200.0000	29,538.56
Overall cost (\$)		29,538.56

Table 8 Solution of ELD with wind farm

Unit	Power (MW)	Operation cost (\$)
G1 (Coal)	94.9286	2,967.33
G2 (Coal)	99.9710	4,125.33
G3 (Coal)	592.0273	12,290.35
G4 (Gas)	258.9938	5,802.31
G5 (Gas)	110.0097	3,189.00
G6 (Oil)	40.5473	1,083.54
G7 (Wind)	3.8621	1,657.76
Total	1,200.0000	31,115.63
Overall cost (\$)		31,115.63

In this paper, two of most concerned GHGs emissions, CO₂ and NO₂ are considered in the model. The emission characteristics of the units and emission allowance price are shown in the Tables 4 and 5. The wind farm forecast system demand and output are shown in Table 6.

5.1 Case-I. ELD model without and with wind farm

In this case study, the system load is 1,200 MW and the system loss power is assumed to be zero. The basic ELD model with and without wind farm are tested on the system and the simulation results are shown in Tables 7, 8 and Fig. 5.

It can be shown that the solution of ED with wind farm succeeds in reducing generated power and operation costs



Table 9 Solution of CEED without wind farm

Unit	Power (MW)	Operation cost (\$)	Emission cost (\$)
G1 (Coal)	95.5408	2,986.10	3,202.99
G2 (Coal)	20.7747	2,820.83	3,029.61
G3 (Coal)	598.7496	12,414.63	8,641.41
G4 (Gas)	509.7226	10,924.30	852.97
G5 (Gas)	333.1363	7,978.45	590.56
G6 (Oil)	42.0759	1,131.62	495.65
Total	1,600.0000	38,255.93	16,813.19
Overall cost (\$)		55,069.12	

Table 10 Solution of CEED with wind farm

Unit	Power (MW)	Operation cost (\$)	Emission cost (\$)
G1 (Coal)	95.3455	2,980.80	3,200.81
G2 (Coal)	21.3548	2,835.68	3,039.05
G3 (Coal)	569.0520	11,708.60	8,404.66
G4 (Gas)	507.6528	10,885.02	849.54
G5 (Gas)	296.0316	7,159.18	530.05
G6 (Oil)	40.0636	1,068.30	474.47
G7 (Wind)	70.4998	3,230.97	0.00
Total	1,600.0000	39,868.55	16,498.57
Overall cost (\$)		56,367.12	

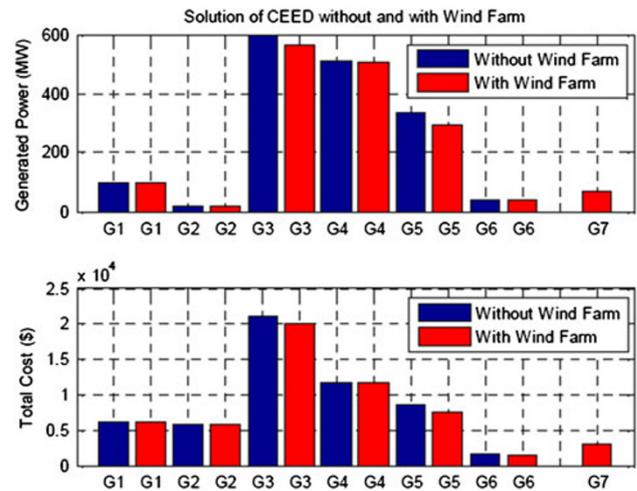
of some fuel units (G1, G3, G4, G5). However, the outputs and scheduling costs of generators (G2, G6) were increased slightly. The reason is that although wind power generators have lots of advantages, the operation cost caused by wind prediction errors is really expensive. With the wind power generator, part of the load of high cost units (G1, G3, G4, G5) is shifted to comparative low cost units (G2, G6). The operation cost of solution of ED with wind farm is highly increased in comparison with solution of ED without wind farm. In addition, the wind power government subsidy is just a little bit due to the low wind power output.

The generated wind power in this case is 3.8621 MW which is far less than the predicted wind power (45 MW), and the cost incurred by overestimation will be applied. The operator needs to purchase more power from another source. Furthermore, the common ED model does not take in account the emission issue. The incorporation of wind power in simple ED problem is not an economic solution due to the really high operation cost of wind power.

5.2 Case-II. CEED model without and with wind farm

In this case study, the system load is 1,600 MW and the system loss power is assumed to be zero. The CEED model with and without wind farm are performed on the test system and the simulation results are shown in Tables 9, 10 and Fig. 6.

The system load is increased to 1,600 MW in this case. But the load is still less than the maximum capacity for

**Fig. 6** Solutions of CEED models without and with wind farm

both thermal units and system with wind power. The objective of CEED is to minimize the total system operation costs and greenhouse gases (CO₂ and NO₂) emission costs. It is clear that part of the load of highly polluted fuel fired units (G1 ~ G6) is shifted to no emission polluted wind power generator (G7). Although the wind power cost is expensive, emission cost were decreased in the solution of CEED with wind farm. The reason is that the government wind power subsidy is directly proportional to the output wind power. In this case, the real generated wind power is 70.4998 MW which is larger than the predicted wind power (45 MW). The underestimation situation will be considerate and the cost for not using all wind power available from wind turbine should be applied. From Tables 9 and 10, we can find that the CEED model with wind farm reduces the emission cost dramatically in comparison with CEED solution without wind power because of the no-emission character of wind energy. In Eq. (9), the government wind power subsidy is directly proportional to the output of wind power. Thus, the overall cost is acceptable from a standpoint of wind farm operator. Therefore, the results have shown that the proposed CEED with wind energy gives a better emission solution efficiently and economically.

5.3 Case-III. Comparisons with other approaches

In order to evaluate the performance of the proposed method, GA, Immune Algorithm (IA) [37], and PSO are employed in the case studies. For comparison purposes, these algorithms are used directly to solve the CEED problem with wind power. For the proposed SQP-PSO algorithm, the population size is 100 and maximum iteration is 3 for PSO. Meanwhile, in order to make a fair comparison of the other approaches, we fixed the same

Table 11 Comparison of different approaches

Algorithm	Best solution (\$)	Average solution (\$)	Average time (s)
GA	57,369.97	57,916.20	13.28
IA	57,180.98	57,669.57	12.57
PSO	56,714.06	57,417.04	8.01
SQP + PSO	56,367.12	56,538.19	1.29

population size as 100 and tested them to reach maximum iteration 100. The initial crossover and mutation rates for GA and IA were all set as 80 % and 5 %. All the programs were run on a 2.66 GHz, Intel Core 2, with 4G RAM desktop. Table 11 shows the results out of 50 runs with each method

A comparison with other approaches is made to evaluate the proposed algorithm which is shown in Table 11. As shown, we can conclude that, the proposed hybrid approach can greatly enhances the searching ability and ensures quality of average solutions, saves computation time, and also efficiently manages the system constraints.

6 Conclusion

UC and ED problem of wind power will start to affect market price of smart grid system, because it became a factor affecting the operation of smart grid and hence the cost. Wind power has impact on the smart grid, since most wind energy flows on to the transmission grid. This paper developed a hybrid method combining the SQP and PSO to achieve faster and better optimization performance. The method was successfully applied to solve the power system ED problem considering GHGs emissions and wind power in an integrated CEED model, where the valve-point effect is also taken into account. In the present work, the wind speed distribution probability functions are applied in formulating the optimization model to address the uncertainties involved. The proposed hybrid method was applied to solve the CEED problem of a test system involving 6 thermal units and 1 wind farm. The comparisons were made between the classical ED and the proposed CEED model with and without wind farm. The proposed CEED model with wind farm shows a better performance in terms of less emission cost. In addition, the resultant overall dispatching cost is also optimized considering the government subsidy. Furthermore, the proposed hybrid optimization method was compared with other optimization approaches for the studied cases. The simulation results show that the hybrid method is better in terms of the speed and accuracy. Compared to the classical PSO and other methods, it can be concluded that the hybrid method

greatly enhances the searching ability and efficiently manages the system constraints, therefore providing a new and efficient tool for the CEED problem.

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