



Data analytics approach for travel time reliability pattern analysis and prediction

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Abstract Travel time reliability (TTR) is an important measure which has been widely used to represent the traffic conditions on freeways. The objective of this study is to develop a systematic approach to analyzing TTR on roadway segments along a corridor. A case study is conducted to illustrate the TTR patterns using vehicle probe data collected on a freeway corridor in Charlotte, North Carolina. A number of influential factors are considered when analyzing TTR, which include, but are not limited to, time of day, day of week, year, and segment location. A time series model is developed and used to predict the TTR. Numerical results clearly indicate the uniqueness of TTR patterns under each case and under different days of week and weather conditions. The research results can provide insightful and objective information on the traffic conditions along freeway segments, and the developed data-driven models can be used to objectively predict the future TTRs, and thus to help transportation planners make informed decisions.

Keywords Travel time reliability · Probe vehicle data · Time series model · Planning time index

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1 Introduction

Travel time reliability (TTR) is an important measure which has been widely used to represent the traffic conditions on freeways. Accurately modeling TTR is very important to both transportation agencies and road users. Different definitions of TTR have been developed in different studies. The Federal Highway Administration (FHWA) [1] gave a formal definition of TTR, i.e., the consistency or dependability in travel times, as measured from day-to-day and/or across different times of the day. In a Strategic Highway Research Program 2 (SHRP 2) project conducted by Vandervalk et al. [2], TTR was defined as the variability in travel times that occur on a facility or for a trip over the course of time and the number of times (trips) that either "fail" or "succeed" in accordance with a predetermined performance standard or schedule. Table 1 provides a summary of existing TTR definitions in chronological order.

Different types of measures have also been widely applied to assess traffic performances and reliability in recent years. There are four most widely used TTR measures recommended by FHWA and they are 90th/95th percentile travel times, buffer index (BI), planning time index (PTI), and frequency of congestion (FOC). Other important measures include the standard deviation [11], coefficient of variation (COV) [12], present variation [5], skew and width of travel time distribution [13], and misery index [5]. Table 2 provides a summary of the TTR measures that were developed and used in past studies in alphabetical order.

Nowadays, anonymous vehicle probe data have been greatly improved in both data coverage and data fidelity, and thus have become a reliable source for freeway TTR analysis. However, in most cases, TTR



Table 1 Summary of existing TTR definitions

Author/agency	Year	Reliability/TTR definition
Turner et al. [3]	1996	Range of travel times experienced during a large number of daily trips
Charles [4]	1997	Probability that a component or system will perform a required function for a given period of time when used understated operating conditions. It is the probability of a non-failure over time
Lomax et al. [5]	1997	Impact of nonrecurrent congestion on the transportation system
NCHRP Report 399 [6]	1998	Measure of the variability of travel time
1998 California Transportation Plan [7]	1998	Level of variability between the expected travel time and the actual travel time experienced
Fowkes et al. [8]	2004	Percent of on-time performance for a given time schedule
FHWA [1]	2006	Consistency or dependability in travel times, as measured from day-to-day and/or across different times of the day
Elefteriadou and Cui [9]	2007	Probability of a device performing its purpose adequately for the period of time intended under the stated operating conditions
Florida Department of Transportation [10]	2011	Percent of travel that takes no longer than the expected travel time plus a certain acceptable additional time
Vandervalk et al. (SHRP 2 project) [2]	2014	Variability in travel times that occur on a facility or for a trip over the course of time and the number of times (trips) that either "fail" or "succeed" in accordance with a predetermined performance standard or schedule

Table 2 Summary of TTR measures

Measure	Author/agency	Equation			
90th/95th percentile travel times:	FHWA [1]	90th/95th percentile travel times			
Buffer index (BI)	FHWA [1]	$\frac{\text{95th precentile time-average travel time}}{\text{average travel time}} \times 100\%$			
Coefficient of variation (COV)	Pu [12]	<u>Standard deviation</u> Average travel time			
Frequency of congestion (FOC)	FHWA [1]	Frequency of trips exceeding a threshold value			
Misery index	Lomax et al. [5]	$\frac{\text{Average travel rate (Top 20\% trips)}}{\text{Average travel rate}} - 1$			
Planning time PTI	FHWA [1]	95th percentile travel time free flow travel time			
Present variation	1998 California Transportation Plan [7];	$\frac{\text{Standard deviation}}{\text{Average travel time}} \times 100\%$			
	Lomax et al. [5];	Average traver time			
	NCHRP Report 618 [14]				
Skew of travel time distribution	Van Lint and Van Zuylen [13]	$\lambda^{ m skew} = rac{T_{90} - T_{50}}{T_{50} - T_{10}}$			
Standard deviation	Dowling et al. [11];	Standard deviation			
	Pu [12]				
Variability index	Lomax et al. [5];	Difference in peak period confidence intervals			
	Albert [15]	Difference in off peak period confidence intervals			
Width of travel time distribution	Van Lint and Van Zuylen [13]	$\lambda^{ ext{width}} = rac{T_{90} - T_{50}}{T_{50} - T_{10}}$			

 T_{90} denotes the 90th percentile travel time T_{50} denotes the 50th percentile travel time T_{10} denotes the 10th percentile travel time

data are analyzed in the short term, which may not be able to account for the TTR variability characteristics for all the segments of a corridor in the long term. Therefore, the detailed analysis of the TTR patterns in different cases which can represent different traffic conditions will be helpful. The purpose of this study is to develop a systematic approach to illustrating how TTR distributes and varies with respect to the time of day (TOD), day of week (DOW), year, and weather. Case studies are conducted to present different TTR patterns under different conditions. The analysis of TTR conducted and the prediction model



developed can greatly help decision makers plan, design, operate, and manage a more efficient highway system.

2 Literature review

Basically, TTR can be analyzed using travel time distribution data, including both single mode distribution [16] and multimode distribution [17, 18]. Eliasson [19] investigated the relationship between travel time distribution and different TOD periods. The result showed that travel times are approximately normally distributed under severe congestion conditions. However, the travel time distribution was skewed under low levels of congestion conditions. Emam and Ai-Deek [16] employed the Anderson-Darling (AD) goodness-of-fit statistics and error percentages to evaluate the performances of different distribution types. The results indicated that the lognormal distribution provided the best model fit and that it was more efficient to use the same day of the week (e.g., Mondays) in the estimation of TTR on a roadway segment than to use mixed data (i.e., data collected across multiple weekdays), because of the significant differences between traffic patterns across multiple weekdays. In addition, the researchers also noticed that the new reliability estimation method showed higher sensitivity to geographical locations. Chen et al. [18] explored the travel time distribution and variability patterns for different road types in different time periods. The authors compared the goodness-of-fit results of several distribution types and analyzed TTR patterns with BI and COV.

However, to investigate the impact of nonrecurring congestion on TTR, different sources of travel time variability (including traffic incidents, inclement weather, and work zones) were studied by different researchers around the world. With the consideration of incident, Hojati et al. [20] developed a method to quantify the impact of traffic incidents on TTR on freeways. The authors conducted a Tobit regression analysis to identify and quantify factors that affect extra buffer time index based on the Queensland DOT and STREAMS Incident Management System (SIMS) database. The results indicated that changes in TTR as a result of traffic incidents are related to the characteristics of the incidents. Charlotte et al. [21] modeled TTR on urban roads in the year 2010 in the region of Paris, France. The 90th percentile of the travel time distribution was modeled with linear regression using explanatory variables including the number of lanes, mean value of the travel time distribution, travel direction, time of the day, number of accidents, and roadworks. With the consideration of weather condition, Martchouk et al. [22] studied the travel time variability using the travel time data on freeway segments in Indianapolis collected with the help of anonymous Bluetooth sampling techniques. The effects of adverse weather were discussed in the study. The results showed that the travel time increased during adverse weather period, and the variance in travel times during the same time period also increased. Li et al. [23] conducted a study which focused on studying the weather impact on traffic operations. Different rainfall intensity data in 72 sample days in Florida were incorporated into the TTR model along with the historical speed database. Different scenarios for each hour (under clear weather, light rain, and heavy rain conditions) were created and applied to the respective roadway segments. The results showed that speed reductions on arterials were 10% for light rain and 12% for heavy rain. Kamga and Yazici [24] conducted a study via merging taxi trips' GPS records and historical weather records of New York City from 2009 to 2010 and then calculated the descriptive statistics of travel time under different TOD, DOW and various weather conditions. The authors used the classification and regression trees (C&RT) model to extract the travel time distribution information under each DOW-TOD-Weather category. With the analysis results of COV, the authors pointed out inclement weather may not only result in increased travel time but also result in higher TTR. With the consideration of multiple influencing factors, Tu [25] developed a TTR model with the consideration of four influencing factors including road geometry, adverse weather, speed limits, and traffic accidents. The model was validated using traffic data from urban freeways in Netherlands in the year 2005. The results of road geometry impacts indicated that there was a threshold value L for the length of ramp/weaving section. If the actual length was less than L, the TTR would decrease with the decreasing length of ramp/weaving sections. If the actual length was larger than L, the length would have far less impact on TTR. Javid and Javid [26] developed a framework to estimate travel time variability caused by traffic incidents based on integrated traffic, road geometry, incident, and weather data. A series of robust regression models were developed using the data from a stretch in California's highway system in 2 years. The results of the split-sample validation showed the effectiveness of the proposed models in estimating the travel time variability. In conclusion, for incidents occurring on weekends, the highway clearance time would be shorter. Shoulder existence and lane width would adversely impact downstream highway clearance time. Kwon et al. [27] developed a linear regression model to study the TTR with the consideration of factors under three categories: traffic influencing events (traffic incidents and crashes, work zone activity, weather, and environmental conditions), traffic demand (fluctuations in day-to-day demand and special events), and physical road features (traffic control devices and inadequate base capacity). The model was tested using the data collected from San Francisco Bay Area in the year 2008 and used to identify how each variable contributes to the TTR. The results of this study provided useful insights into predicting the TTR. Schroeder et al. [28] presented a methodology to conduct the freeway reliability analysis based on freeway data in North Carolina. The variability impact considerations included TOD, DOW, month-of-year differences, and various nonrecurring congestion sources (such as weather, incidents, work zones, and special events). The freeway scenario generator (FSG) was used and resulted in 2508 scenarios based on freeway facility data in North Carolina. The resulting travel time distribution was presented, and a sensitivity analysis was conducted to explore the relationship between weather and incidents and the overall reliability of the facility. Table 3 provides a summary of several previous studies on TTR analysis and modeling in chronological order.

Although useful, most of the studies did not consider the long-term variation of TTR. This study focuses on the long-term TTR analysis step-by-step in order to present data analysis results. The developed data-driven models can be used to objectively predict the future TTRs. This study is novel since it identifies the segments with various TTR patterns at different locations of a corridor, which can help reveal the travel time characteristics of these locations under different traffic conditions. The research results can provide insightful and objective information on the traffic conditions along freeway segments to help the transit planners make informed decisions.

3 Descriptive analysis of TTR

3.1 Data description

This study focuses on the travel time data gathered from the Regional Integrated Transportation Information System (RITIS) web site and uses the collected data to conduct the TTR analysis. A series of major freeway segments are selected for the case study: Interstate 77 (I-77) southbound (Fig. 1) is one of the most heavily traveled Interstate highways in Charlotte area and runs from north to south. A total of 32 roadway segments of I-77 southbound are selected in this study, which start from the intersection with Harris Oak Blvd and end at the interchange with I-485 (Exit 2) at the south part of the city. The total length of the selected segments is 19 miles. In this study, travel time and speed data are obtained from the RITIS web site which gathered information about roadway speeds and vehicle counts from 300 million realtime anonymous mobile phones, connected cars, trucks,

delivery vans, and other fleet vehicles equipped with GPS locator devices. Travel time data from January 2011 to December 2015 aggregated at 15-min intervals are used in the present study. A sample of raw travel time data utilized in this study is shown in Table 4, which contains the following information:

TMC_Code The RITIS Probe Data Analytics Suite uses the TMC (traffic message channel) standard to uniquely identify each road segment. This field indicates the segment ID.

Measurement_tstamp This field indicates the time stamp of the record.

Speed This field indicates the current estimated harmonic mean speed for the roadway segment in miles per hour.

Travel_time_seconds This field indicates the time it takes to drive along the roadway segment.

3.2 Study location identification

The historical weather data aggregated at 1-h intervals near the Charlotte Douglas International airport can be found at the www.wunderground.com web site. From previous studies, it is widely accepted that only severe weather events can cause a significant impact on speeds and travel times. Due to the weather characteristics in the Charlotte area and the distribution of each weather category, detailed weather conditions are further classified into three groups including normal, rain, and snow/fog/ ice. Table 5 presents the detailed classification of the weather conditions. Conditions such as overcast or mostly cloudy are assumed to be no different from clear conditions due to no obvious impact on traffic conditions. These conditions are classified into normal. All the conditions such as rain or thunderstorm are categorized as rain. In order to ensure the acceptable sample size, snow, fog, ice pellet, and other similar conditions are combined together due to their rate of occurrence.

There are four most widely used TTR measures in previous studies and they are BI, PTI, COV, and FOC. However, BI and COV have a limitation since their values depend on the average travel time, which may change over time [30]. Therefore, the PTI is chosen and used as the primary measure of TTR in this study. It is calculated as the 95th percentile travel time divided by the free-flow travel time so as to represent the percentage of extra travel time that most people will need to add on to their trip in order to ensure on-time arrival. For example, a PTI value of 1.5 at 5 p.m. means that for a 20-minute trip in light traffic, 30 min should be planned at 5 p.m. to make sure that he or she is on time. The equation of PTI is provided below:

Table 3 Summary of previous studies on TTR analysis and modeling

Year	Author	Location	on Data Data source Study periods aggregation interval		Study periods	TTR measure(s)	Modeling algorithm
2006	Emam and Ai-Deek [16]	Orlando, FL, US	5 min	RTMC	3:30–6:30 p.m.	Buffer index, coefficient of variation	Weibull, exponential, lognormal, and normal distribution testing
2007	Eliasson [19]	Stockholm, Sweden	15 min	Camera detectors	6:30 a.m.–8:30 p.m.	Standard deviation	N/A
2008	Tu [25]	Delft, Netherlands	N/A	Regiolab-Delft monitoring system.	N/A	$\lambda^{\text{skew}}, \lambda^{\text{width}}$	Dynamic traffic assignment
2010	Guo et al. [17]	San Antonio, TX, US	N/A	Automatic vehicle identification (AVI) stations	6:00–10:00 a.m. 3:00–7:00 p.m.	Standard deviation, 90th percentile travel time	Maximum likelihood function; Mixture normal model
2010	Martchouk et al. [22]	Indiana, US	N/A	Microwave detectors	N/A	Standard deviation	Hazards-based model
2011	Kwon et al. [27]	San Francisco, CA, US	N/A	PeMS database	7–9 a.m.	Buffer time	FDOT TTR model
2013	Schroeder et al. [28]	Durham, NC, US	15 min	INRIX	2–8 p.m.	Travel time index	FREEVAL HCM model
2014	Kamga and Yazici [24]	NYC, US	N/A	Taxis GPS data	N/A	Standard deviation, average travel time, coefficient of variation	Classification and regression trees (C&RT) model
2016	Li [23]	FL, US	N/A	FDOT database	N/A	Actual travel time	FDOT TTR model
2016	Hojati et al. [20]	Queensland, Australia	N/A	Queensland database	N/A	Extra buffer time index	Tobit model
2017	Charlotte et al. [21]	Paris, France	6 min	Loop detectors	7–10 a.m. 5–8 p.m. 10 p.m.–5 a.m.	90th percentile travel time	N/A
2017	Wang et al. [29]	Seattle, WA, US	20 s	GPS data	5:00–11:00 a.m.	Coefficient of variation	Maximum likelihood method; K-means analysis
2018	Javid and Javid [26]	California, US	5 min	PeMS database	N/A	Index of agreement, correlation coefficient	Robust regression
2018	Chen et al. [18]	Beijing, China	1 min	Probe vehicle data	Typical peak/off- peak hours	Coefficient of variation, buffer time index	Weibull, exponential, lognormal, and normal distribution testing

$$PTI_i = \frac{T_{i95}}{FFTT_i},$$

where PTI_i is the planning time index of segment I; T_{i95} is the 95th percentile travel time on the TMC segment i during the study period across multiple days (e.g., a month) or a year; $FFTT_i$ is free-flow travel time on TMC i during the same observation period as mentioned above.

For each roadway segment, the free-flow travel time is computed by dividing the length of segment by the freeflow speed, which is defined as the 85th percentile speed during overnight hours (10 p.m. to 5 a.m.) [10, 30, 31].

The first step to identify the study segments is to plot the two-dimensional PTI matrix for each road segment along the corridor. This would provide a straightforward and visualized tool for decision makers to grasp the average traffic conditions along a corridor. The long-term (in one-year period) PTI values of each segment from 2011 to 2015 were calculated and shown in Fig. 2. Note that in this



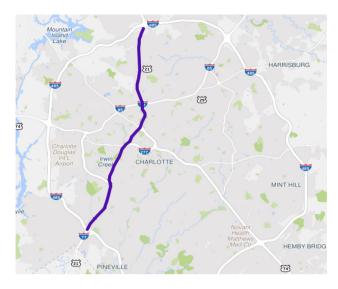


Fig. 1 Selected I-77 southbound segments

Table 4 Sample raw travel time data

TMC Code	Measurement_tstamp	Speed (mph)	Travel_time_seconds (s)
125N04784	1/1/2015 0:00	62.91	53.58
125N04783	1/1/2015 0:00	61.17	12.82
125N04786	1/1/2015 0:00	60.43	47.56
125N04785	1/1/2015 0:00	61.3	11.85
125N04780	1/1/2015 0:00	63.97	14.59
125N04782	1/1/2015 0:00	63.04	21.73
125N04781	1/1/2015 0:00	62.79	12.42
125N04788	1/1/2015 0:00	65.03	29.6
125N04787	1/1/2015 0:00	63.5	53.76
125-04783	1/1/2015 0:00	62.98	33.22
125-04782	1/1/2015 0:00	62.75	35.68

figure, the horizontal axis denotes the time of day and the vertical axis represents TMC segments along the selected section on I-77 southbound. Each cell represents the PTI value. The darker the color, the higher the PTI.

In order to select the sections which can represent different traffic conditions, the qualitative ratings for each freeway segment in the study area are conducted and further classified into different categories/levels based on the qualitative criteria of a previous study [32]. The ratings, based on the PTI values, are given as: (1) reliable (PTI < 1.5); (2) moderately to heavily unreliable (1.5 < PTI < 2.5); and (3) extremely unreliable (PTI > 2.5).

Based on the rating criteria mentioned above, eight segments (shown in Fig. 3) which contain four PTI rating cases are selected as the sample study segments. The four cases are

Case 1 (p.m. peak only): The average PTI during a.m. peak period is reliable and during PM peak period is

Table 5 Classification of the weather conditions

New weather category	Original weather condition
Snow/fog/ice	Haze
	Fog
	Smoke
	Patches of fog
	Mist
ormal	Shallow fog
	Light freezing
	Light ice pellet
	Ice pellets
	Light snow
	Snow
	Heavy snow
Normal	Clear
	Partly cloudy
	Mostly cloudy
	Scattered clouds
	Overcast
	Unknown
Rain	Light rain
	Rain
	Heavy rain
	Light drizzle
	Heavy thunderstorm
	Light thunderstorm
	Thunderstorm
	Squalls
	Drizzle

unreliable/extremely unreliable. The selected segments are 125-04779 and 125N04780.

Case 2 (a.m. peak only): The average PTI during a.m. peak period is unreliable/extremely unreliable and during PM peak period is reliable. The selected segments are 125N04788 and 125-04788.

Case 3 (Double peak): The average PTI during both a.m. and p.m. peak periods are unreliable/extremely unreliable. The selected segments are 125N04784 and 125N04785.

Case 4 (No peak): The average PTI during both a.m. and p.m. peak periods are reliable. The selected segments are 125-04790 and 125N04791.

3.3 TTR variability patterns at different study locations

3.3.1 TTR variability pattern under all conditions

The PTIs of each segment from 2011 to 2015 are shown in Fig. 4. The TTR variability pattern in each case can be categorized as follows:



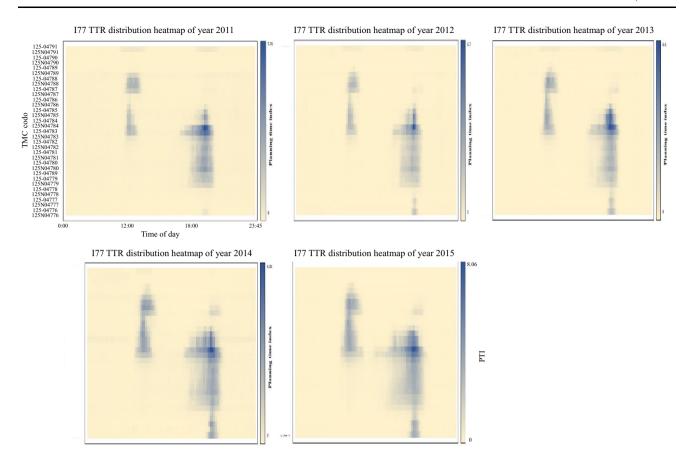


Fig. 2 PTI heat maps of I-77 segments in 5 years

Case 1 These two sections are located at the south part of the Charlotte downtown area. The volume of outbound traffic during p.m. hours is high and therefore contributes to the frequent congestion under p.m. peak condition. In more detail, in the year 2015, these two segments had obviously higher PTI values during peak hours than those in the years of 2011-2014. The condition like this may be attributed to different factors such as the traffic volume, weather condition, and accidents. One potential reason behind this could be the traffic volume on the segments of case 1 from 2011 to 2015 (annual average daily traffic (AADT): 15,300, 15,200, 15,400, 15,900, and 15,900, respectively). The correlation values between the AADT and average daily PTIs of these two segments are 0.86 and 0.83, respectively, which means that they are highly correlated. Therefore, the traffic volume may be a primary reason of the TTR distribution characteristics. Based on the historical weather data, the frequency of adverse weather in the year 2015 is higher than that in the years from 2011 to 2014. In order to eliminate the possible influence of adverse weather, the TTR distributions under only normal conditions during each year are also tested and the average daily PTI of 2015 is reduced a little bit (from 2.1

to 2.0) but is still higher than those of years 2011–2014. With respect to traffic accident, no detailed historical crash information about I-77 is found. However, the number of total crashes in Mecklenburg county in each year had been increasing from 2011 to 2015 (15,476, 15,915, 16,790, 19,847, and 21,096, respectively) [33]. This can also be another potential reason that contributes to the worsening of the traffic condition in the year 2015.

Case 2 These two sections are located at the north part of the Charlotte downtown area. The volume of inbound traffic during a.m. hours is high and therefore contributes to the frequent congestion under a.m. peak condition. Similar to case 1, in the year 2015, these two segments had obviously higher PTI values during peak hours than those of years from 2011 to 2014. The condition like this may also be explained by the potential factors such as traffic volume (with the correlation values being 0.83 and 0.89, respectively), adverse weather and accident that contribute to the worsening of the traffic condition in the year 2015, as presented in case 1.

Case 3 These two sections are located adjacent to Charlotte downtown area. The volume of inbound traffic during a.m. hours and outbound traffic during p.m. hours are both



Fig. 3 Location of selected I-77 segments

high and therefore contributes to the frequent congestion under double peak conditions. Similar to cases 1 and 2, in the year 2015, these two segments had obviously higher PTI values during peak hours than those in the years of 2011–2014. However, the correlation values between traffic volume and average daily PTIs are not statistically significant (i.e., 0.56 and 0.71, respectively). Therefore, the condition like this may be explained by other potential factors (such as adverse weather and accident) that contribute to the worsening of the traffic condition in the year 2015.

Case 4 These two sections are located far away from Charlotte downtown area. The traffic volumes during both AM and PM hours are low and therefore contribute to the no peak condition. The variation of PTIs throughout the day of each year does not change significantly (from 1.02 to 1.13, and 1.04 to 1.15, respectively).

3.3.2 TTR variability patterns for different days of week

The PTIs of each segment from Monday to Sunday are shown in Fig. 5, and the average PTIs are shown in Table 6. The TTR variability patterns for different days of week in each case can be categorized as follows:

Case 1 For the segments showing the p.m. peak characteristics, the travel time on Friday is least reliable. This result is consistent with a previous study [29]. The TTR variability patterns on weekends are significantly different from weekdays. There are no PM peak characteristics of the TTR of these two segments on weekends as the PTIs

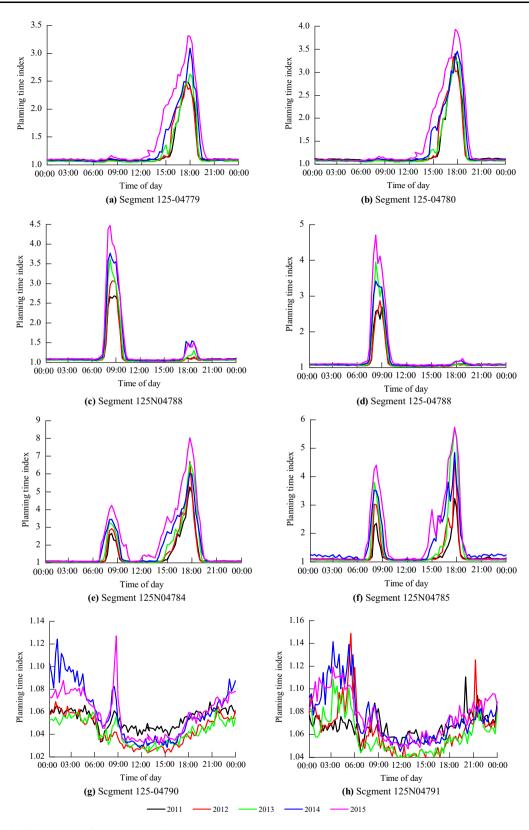


Fig. 4 TTR variability pattern of each segment in 5 years

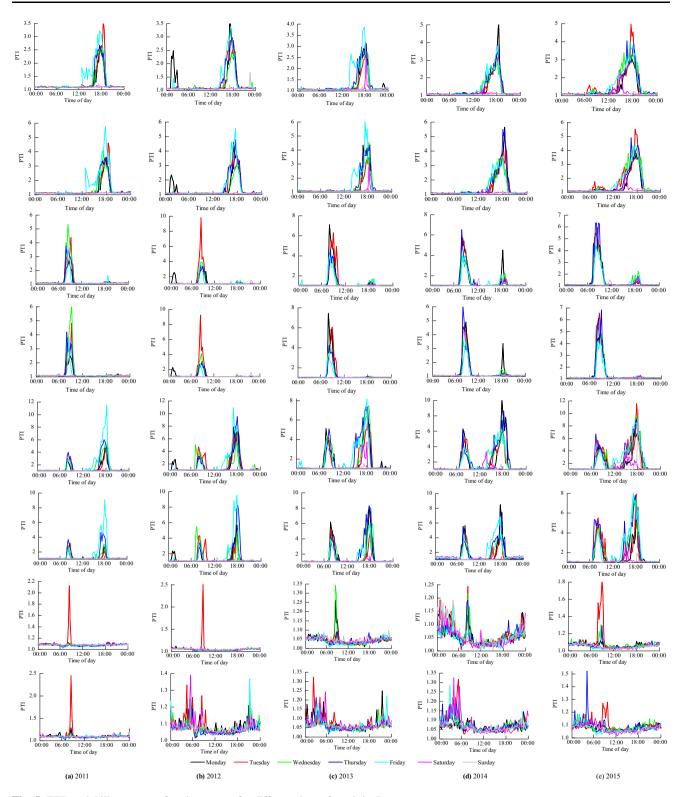


Fig. 5 TTR variability pattern of each segment for different days of week in 5 years

Table 6 Average PTIs from Monday to Sunday

	Monday	Tuesday	Wednesday	Thursday	Friday	Saturday	Sunday
Segment 125-04779							
Average PTI	1.29	1.30	1.30	1.32	1.40	1.10	1.08
Rank	5	3	4	2	1	6	7
Morning peak (7–9 a.m.) PTI	1.10	1.14	1.11	1.10	1.11	1.06	1.06
Rank	5	1	2	4	3	6	7
peak (4-7 p.m.) PTI	2.39	2.42	2.31	2.47	2.63	1.13	1.09
Rank	4	3	5	2	1	6	7
Segment 125N04780							
Average PTI	1.37	1.39	1.38	1.44	1.51	1.11	1.09
Rank	5	3	4	2	1	6	7
Morning peak (7–9 a.m.) PTI	1.11	1.15	1.12	1.12	1.11	1.07	1.08
Rank	4	1	2	3	5	7	6
Afternoon peak (4-7 p.m.) PTI	2.89	2.89	2.81	3.19	3.26	1.16	1.11
Rank	4	3	5	2	1	6	7
Segment 125N04788							
Average PTI	1.28	1.32	1.28	1.27	1.18	1.06	1.06
Rank	3	1	2	4	5	7	6
Morning peak (7–9 a.m.) PTI	3.09	3.74	3.13	3.23	2.55	1.04	1.05
Rank	4	1	3	2	5	7	6
Afternoon peak (4-7 p.m.) PTI	1.23	1.16	1.28	1.18	1.25	1.14	1.05
Rank	3	5	1	4	2	6	7
Segment 125-04788							
Average PTI	1.32	1.37	1.31	1.31	1.25	1.07	1.07
Rank	2	1	4	3	5	6	7
Morning peak (7–9 a.m.) PTI	2.91	3.53	3.11	3.01	2.14	1.04	1.05
Rank	4	1	2	3	5	7	6
Afternoon peak (4-7 p.m.) PTI	1.14	1.08	1.12	1.09	1.09	1.07	1.05
Rank	1	5	2	3	4	6	7
Segment 125N04784							
Average PTI	1.74	1.78	1.85	1.97	2.02	1.15	1.12
Rank	5	4	3	2	1	6	7
Morning peak (7–9 a.m.) PTI	2.98	3.31	3.09	3.08	2.49	1.05	1.05
Rank	4	1	2	3	5	6	7
Afternoon peak (4-7 p.m.) PTI	4.30	3.94	4.41	5.29	5.14	1.35	1.45
Rank	4	5	3	1	2	7	6
Segment 125N04785							
Average PTI	1.49	1.46	1.57	1.73	1.77	1.11	1.11
Rank	4	5	3	2	1	6	7
Morning peak (7–9 a.m.) PTI	2.73	2.94	2.89	2.92	2.30	1.05	1.06
Rank	4	1	3	2	5	7	6
Afternoon peak (4-7 p.m.) PTI	2.84	2.27	3.01	4.18	4.33	1.12	1.10
Rank	4	5	3	2	1	6	7
Segment 125-04790							-
Average PTI	1.06	1.07	1.06	1.06	1.05	1.06	1.06
Rank	3	1	4	6	7	5	2
Morning peak (7–9 a.m.) PTI	1.08	1.22	1.09	1.07	1.04	1.05	1.06
Rank	3	1	2	4	7	6	5
Afternoon peak (4–7 p.m.) PTI	1.05	1.05	1.05	1.05	1.05	1.04	1.05



Table 6 continued

	Monday	Tuesday	Wednesday	Thursday	Friday	Saturday	Sunday
Rank	3	1	4	6	5	7	2
Segment 125N04791							
Average PTI	1.08	1.09	1.07	1.08	1.08	1.08	1.07
Rank	2	1	6	5	4	3	7
Morning peak (7-9 a.m.) PTI	1.09	1.14	1.07	1.07	1.06	1.08	1.07
Rank	2	1	5	4	7	3	6
Afternoon peak (4-7 p.m.) PTI	1.07	1.07	1.07	1.07	1.07	1.06	1.06
Rank	2	1	5	3	4	6	7

throughout the day do not change significantly. The maximum (and average) PTIs on weekends of these two segments are 1.28 (1.10) and 1.24 (1.08), respectively. The results indicate that traffic congestion on weekends becomes less frequent and also travel demand on weekends is perhaps much lower than that on weekdays, which is consistent with previous studies [18, 34].

Case 2 For the segments showing the a.m. peak characteristics, the travel time on Tuesday is the least reliable. Similar to case 1, there are also no a.m. peak characteristics of the TTR of these two segments on weekends as the PTIs throughout the day do not change significantly.

Case 3 For the segments showing the double peak characteristics, the travel time on Friday is least reliable. Similar to case 1, there are also no a.m. peak characteristics of the TTR of these two segments on weekends as the PTIs throughout the day do not change significantly.

Case 4 For the segments showing no peak characteristics, average PTIs of each DOW do not change significantly (from 1.05 to 1.07 and 1.07 to 1.09, respectively). The results indicate that the traffic congestions on these two segments are not frequent on both weekdays and weekends.

3.3.3 TTR variability patterns under different weather conditions

The PTIs of each segment under different weather conditions are shown in Fig. 6. The TTR variability patterns in each case under different weather conditions can be categorized as follows:

Case 1 The TTR variability patterns of these two segments under normal and rain conditions are similar, and the pattern is unique under the snow/ice/fog condition. In more detail, the PTIs under rain condition have obviously higher values than those under normal condition throughout the day. This probably suggests that rain can cause several travel problems (such as visibility issues) while driving a vehicle. Heavy rainfall may lead to hydroplaning, slippery surfaces for tires, and road flooding. Therefore, the values of PTIs

under rain condition also increase and the traffic congestion becomes more frequent. This result is consistent with other studies [23, 35]. The PTIs under snow/ice/fog conditions are also higher than those under normal condition throughout the day because of the influence of road surfaces and visibility problems [36]. Results clearly show that snow/fog/ice can contribute to unexpected condition on the roadway anytime throughout the day, resulting in the unique TTR variability pattern under the snow/fog/ice conditions. This result is also consistent with a previous study [37]. In particular, there is an extremely high PTI value at noon. Since the geometric design characteristics of all the segments are similar, the potential reason behind this unique pattern could be the nonrecurrent condition such as the incidents happened during snow condition on the case segments. This hypothesis should be checked in the future if more detailed data are available.

Case 2 and Case 3 Similar to case 1, the PTIs under rain condition have obviously higher values than those under normal condition throughout the day. PTIs under the snow/ice/fog condition are also higher than the PTIs under normal condition throughout the day and demonstrate unique variability pattern.

Case 4 For segments 125-04790 and 125N04791, the PTIs under rain condition have higher values than those under normal condition but do not increase significantly. However, the PTIs under the snow/ice/fog conditions are much higher than the PTIs under normal condition throughout the day. This result shows the adverse weather (such as snow, fog, and ice) can significantly affect the traffic condition of the segment, and the traffic congestion becomes more frequent no matter when.

4 TTR prediction

4.1 Time series-based TTR prediction methodology

Exponential smoothing (ETS) model is a commonly used method in time series analysis and has been widely adopted



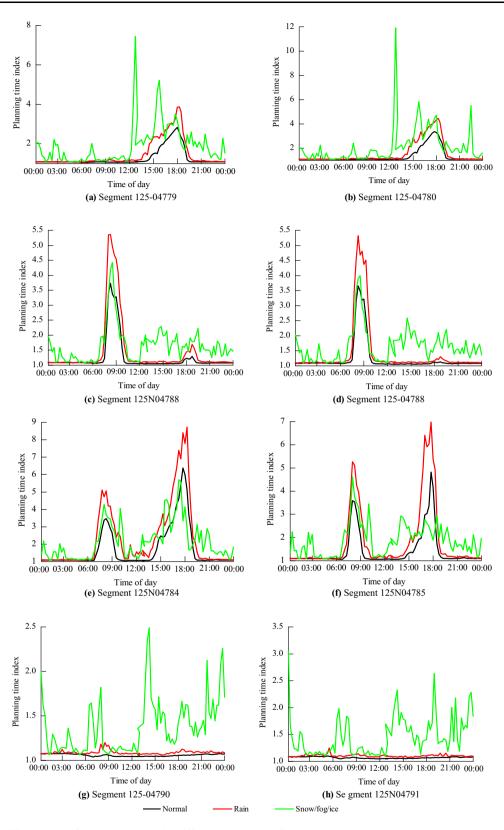


Fig. 6 TTR variability pattern of each segment under different weather conditions

in traffic forecasting for decades. The ETS model is an intuitive forecasting method that weights the observed time series unequally [38]. Recent observations are weighted more heavily than remote observations. The ETS equation [39] is shown as follows:

$$S_t = \alpha x_t + (1 - \alpha)S_{t-1},$$

where S_t is the output of the exponential smoothing algorithm; α is smoothing factor, $0 \le \alpha \le 1$; x_t is the raw data sequence.

Based on the historical travel time data, the PTIs from Monday to Sunday in each year and the PTIs of each month can be calculated. Those values can be used as the input to the exponential smoothing model. The ETS model is utilized in this study to predict the PTIs from Monday to Sunday and the PTIs in each month in the year 2015. Note that the TTRs under different weather conditions are not predicted due to its limited sample size in a single year. The PTIs from Monday to Sunday and the PTIs in each month from 2011 to 2014 are used as the raw input in the model to predict the PTIs in 2015. In order to select the best smoothing factor α , the grid search method is adopted in this study (with an accuracy level of 0.1). The comparison results indicate that α with the value of 1 can provide the best prediction result. Therefore, the smoothing factor α with the value of 1 is utilized in this study to minimum prediction error.

The mean absolute percentage error (MAPE) is used in this study to evaluate the prediction results. The MAPE equation is shown as follows:

$$M = \frac{100\%}{n} \sum_{t=0}^{n} \left| \frac{A_t - F_t}{A_t} \right|,$$

where M is the absolute percentage error; n is the number of predicted points; A_t is the actual TTR value; F_t is the predicted TTR value.

4.2 TTR prediction results

4.2.1 TTR prediction results considering DOW

Table 7 shows the MAPE of prediction results from Monday to Sunday. The result shows that for the segments showing PM peak characteristics, the prediction model can provide reliable prediction results for each DOW with the MAPEs being 8.42% and 8.18%, respectively. The prediction model can provide most reliable prediction results on Monday with the MAPEs being 6.54% and 5.72%, respectively. For the segments showing AM peak characteristics, the prediction model can provide reliable prediction results for each DOW with the MAPEs being 9.38% and 7.91%, respectively. The prediction model can provide most reliable prediction results on Monday with the MAPEs being 8.07% and 7.55%, respectively. For the segments showing double peak characteristics, the prediction model can provide prediction results for each DOW with the MAPEs being 17.33% and 21.21%, respectively. The prediction model can provide most reliable prediction results on Monday with the MAPEs being 11.52% and 18.06%, respectively. For the segments showing no peak characteristics, the prediction model can provide prediction results for each DOW with the MAPEs being 2.83% and 2.73%, respectively. The prediction model can provide most reliable prediction results on Sunday with the MAPEs being 2.20% and 2.24%, respectively.

4.2.2 TTR prediction results considering MOY

Table 8 shows the average prediction error from January to December. The result shows that for the segments showing PM peak characteristics, the prediction model can provide reliable prediction results with the MAPEs being 7.68% and 8.83%, respectively. The prediction model can provide most reliable prediction results on April with the MAPEs being 3.90% and 7.03%, respectively. For the segments showing AM peak characteristics, the prediction model can provide reliable prediction results with the MAPEs being 8.07% and

 Table 7
 Percentage prediction errors (Monday to Sunday)

Segment	Study case	Average percentage error (%)										
		Monday	Tuesday	Wednesday	Thursday	Friday	Saturday	Sunday	Average			
125-04779	1	6.54	11.67	10.61	6.95	9.89	7.13	6.18	8.42			
125N04780	1	5.72	11.57	10.41	6.31	8.26	7.68	7.33	8.18			
125N04788	2	8.07	8.54	8.36	9.21	8.22	11.75	11.48	9.38			
125-04788	2	7.55	7.69	8.38	8.83	8.15	7.95	6.83	7.91			
125N04784	3	11.52	14.68	16.46	14.64	16.37	22.59	25.05	17.33			
125N04785	3	18.06	18.53	20.46	18.53	18.49	25.52	28.86	21.21			
125-04790	4	2.77	4.40	3.29	2.56	2.26	2.32	2.20	2.83			
125N04791	4	2.84	3.30	2.88	3.08	2.40	2.39	2.24	2.73			

Table 8 Percentage prediction errors (January to December)

Segment	Study case	Average percentage error (%)												
		Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sep.	Oct.	Nov.	Dec.	Average (%)
125-04779	1	6.87	10.67	8.15	3.90	7.28	7.31	5.61	6.07	8.49	6.06	7.53	14.23	7.68
125N04780	1	8.19	9.67	8.73	7.03	9.03	8.54	7.96	8.24	8.90	7.14	7.16	15.37	8.83
125N04788	2	7.69	11.04	6.25	8.00	7.10	5.67	9.16	7.76	6.83	8.36	11.28	7.64	8.07
125-04788	2	6.41	9.93	6.20	6.47	6.38	4.99	6.30	7.22	7.40	6.92	11.42	7.81	7.29
125N04784	3	17.92	16.72	15.86	14.09	13.03	17.84	12.56	19.04	15.90	16.49	12.11	21.66	16.10
125N04785	3	14.08	14.57	14.69	12.84	13.44	24.64	16.19	25.41	16.02	17.87	20.27	25.21	17.94
125-04790	4	1.79	5.64	1.85	2.15	2.65	1.70	2.01	1.82	4.54	2.37	3.88	2.84	2.77
125N04791	4	2.68	5.81	2.15	2.48	2.16	2.36	2.49	2.31	4.56	3.42	3.77	3.63	3.15

7.29%, respectively. The prediction model can provide most reliable prediction results on June with the MAPEs 5.67% and 4.99%, respectively. For the segments showing double peak characteristics, the prediction model can provide prediction results with the MAPEs being 16.10% and 17.94%, respectively. The prediction model can provide most reliable prediction results on May with the MAPEs being 13.03% and 13.44%, respectively. For the segments showing no peak characteristics, the prediction model can provide reliable prediction results with the MAPEs being 2.77% and 3.15%, respectively. The prediction model can provide most reliable prediction results on March with the MAPEs being 1.85% and 2.15%, respectively.

5 Conclusion

With the analysis of the TTR of eight typical segments on the I-77 southbound corridor in Charlotte, NC, the TTR variability patterns could be identified under different conditions. Based on the historical TTR data (2011–2014), the TTR for specific DOW and the TTR of each month in the year 2015 are also predicted. The information gathered out of this study can be concluded as follows.

In general, the TTR variability patterns of different segments along the corridor are different. Different cases including PM peak only, AM peak only, double peak and no peak are analyzed separately since they demonstrate different results. The TTR prediction result also indicates that the TTR of a year could be predicted accurately based on the long-term historical TTR data.

With respect to DOW, the TTR analysis results show that for the segments with noticeable peak hour trend, the TTRs on weekends are much lower than those on weekdays. The TTR prediction results also show that the prediction errors on weekends are lower than those on weekdays. For the segments with no peak hour, the TTRs on weekends are similar to those on weekdays. The TTR prediction results show that the prediction errors on weekends are a little

higher than those on weekdays. In particular, for the segments under cases 1 and 3 (PM peak only and double peak, respectively), the TTR on Friday is the highest. For the segments under case 2 (AM peak only), the TTR on Tuesday is the highest. For the segments under case 4 (no peak hour), the TTR on each DOW does not significantly change.

With respect to weather conditions, the TTR analysis results show that the PTIs under rain condition have obviously higher values than those under normal condition throughout the day. The PTIs under snow/ice/fog conditions are also higher than those under normal condition throughout the day with unique variability patterns.

In most cases, TTR data are analyzed at the segment level in the short term, which may not be able to account for the TTR variability characteristics for the whole section in the long term. This study aims to develop a systematic approach to analyzing TTR of roadway segments with different variability patterns along a corridor in the long term. However, with the limited amount of data, the impacts of accidents and roadworks on TTR are not discussed in this study. In the future, the impacts of these variables will be studied when the data can be made available. Spatial relationships between segments along the corridor and their impacts on the TTR will also be investigated. Furthermore, the TTR analysis will be conducted at a network level and relevant characteristics will be examined in detail.

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