CORRECTION



Correction to: Circular motion analysis for a novel 4-DOF parallel kinematic machine

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Published online: 15 October 2019 © The Brazilian Society of Mechanical Sciences and Engineering 2019

Correction to:

Journal of the Brazilian Society of Mechanical Sciences and Engineering (2019) 41:215 https://doi.org/10.1007/s40430-019-1716-9

In the original publication of the article, the affiliation of the authors was incorrectly published. The corrected affiliation is given in this correction article.

The original article can be found online at https://doi.org/10.1007/s40430-019-1716-9.

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