



# Global well-posedness of the two-dimensional stochastic viscous nonlinear wave equations

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## Abstract

We study well-posedness of viscous nonlinear wave equations (vNLW) on the two-dimensional torus with a stochastic forcing. In particular, we prove pathwise global well-posedness of the stochastic defocusing vNLW with an additive stochastic forcing  $D^\alpha \xi$ , where  $\alpha < \frac{1}{2}$  and  $\xi$  denotes the space–time white noise.

**Keywords** Viscous nonlinear wave equation · Stochastic viscous nonlinear wave equation · Global well-posedness

**Mathematics Subject Classification** 35L05 · 35L71 · 35R60 · 60H15

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# 1 Introduction

## 1.1 Viscous nonlinear wave equations

In this paper, we consider the following nonlinear wave equation (NLW) on the two-dimensional torus  $\mathbb{T}^2 = (\mathbb{R}/\mathbb{Z})^2$ , augmented by viscous effects:

$$\begin{cases} \partial_t^2 u + (1 - \Delta)u + D\partial_t u + |u|^{p-1}u = D^\alpha \xi \\ (u, \partial_t u)|_{t=0} = (u_0, u_1), \end{cases} \tag{1.1}$$

where  $p > 1$ ,  $D = |\nabla| = \sqrt{-\Delta}$ ,  $\alpha < \frac{1}{2}$ , and  $\xi$  denotes the (Gaussian) space–time white noise on  $\mathbb{R}_+ \times \mathbb{T}^2$ . Our main goal in this paper is to prove pathwise global well-posedness of (1.1) in  $C(\mathbb{R}_+; H^s(\mathbb{T}^2))$  for some  $\alpha \leq \alpha_p$  and  $s \geq s_p$ , where  $H^s(\mathbb{T}^2)$  is the  $L^2$ -based Sobolev space on  $\mathbb{T}^2$  with regularity  $s$  (see Sect. 2 for more details).

In [21], Kuan–Čanić proposed the following viscous NLW on  $\mathbb{R}^2$ :

$$\partial_t^2 u - \Delta u + 2\mu D\partial_t u = F(u), \tag{1.2}$$

where  $\mu > 0$  and  $F(u)$  is a general external forcing. This equation typically shows up in fluid–structure interaction problems, such as the interaction between a stretched membrane and a viscous fluid. The viscosity term  $2\mu D\partial_t u$  in (1.2) comes from the Dirichlet–Neumann operator typically arising in fluid–structure interaction problems in three dimensions. See [21, 23] for the derivation of (1.2). It is easy to see that, when  $\mu \geq 1$ , the Eq. (1.2) is purely parabolic (see [23, 26]). On the other hand, when  $0 < \mu < 1$ , the viscous NLW (1.2) exhibits an interesting mixture of dispersive effects and parabolic smoothing. Since the precise value of  $0 < \mu < 1$  does not play an important role, we simply set  $\mu = \frac{1}{2}$ . In addition, we consider a defocusing power-type nonlinearity of the form

$$F(u) = -|u|^{p-1}u,$$

for positive real numbers  $p > 1$ . This power-type nonlinearity has been studied extensively for nonlinear dispersive equations (see, for example, [40]). With  $\mu = \frac{1}{2}$  and  $F(u) = -|u|^{p-1}u$ , the general form of vNLW (1.2) becomes the following version of vNLW:

$$\partial_t^2 u - \Delta u + D\partial_t u + |u|^{p-1}u = 0 \tag{1.3}$$

We now consider the analytical aspects of vNLW (1.3). Note that as in the case of the usual NLW:

$$\partial_t^2 u - \Delta u + |u|^{p-1}u = 0,$$

the viscous NLW (1.3) on  $\mathbb{R}^2$  enjoys the following scaling symmetry:  $u(t, x) \mapsto u_\lambda(t, x) := \lambda^{\frac{2}{p-1}} u(\lambda t, \lambda x)$ . Namely, if  $u$  is a solution to (1.3), then  $u_\lambda$  is also a solution to (1.3) for any  $\lambda > 0$  with rescaled initial data. This scaling symmetry induces the scaling critical Sobolev regularity  $s_{\text{scaling}}$  on  $\mathbb{R}^2$  given by

$$s_{\text{scaling}} = 1 - \frac{2}{p-1}$$

such that under this scaling symmetry, the homogeneous Sobolev norm on  $\mathbb{R}^2$  remains invariant. While there is no scaling symmetry on  $\mathbb{T}^2$ , the scaling critical regularity  $s_{\text{scaling}}$  still plays an important role in studying nonlinear partial differential equations in the periodic setting, especially for dispersive equations. Namely, in both periodic and non-periodic settings, a dispersive equation is usually well-posed in  $H^s$  for  $s > s_{\text{scaling}}$  and is usually ill-posed in  $H^s$  for  $s < s_{\text{scaling}}$ . On the one hand, there is a good local well-posedness theory for dispersive equations above the scaling regularities (see [3, 31, 38] for the references therein). Moreover, we show in this paper that vNLW (1.3) is locally well-posed in  $H^s(\mathbb{T}^2)$  for all  $s \geq s_{\text{crit}}$  (with a strict inequality when  $p = 3$ ), where  $s_{\text{crit}}$  is defined by

$$s_{\text{crit}} := \max(s_{\text{scaling}}, 0) = \max\left(1 - \frac{2}{p-1}, 0\right), \quad (1.4)$$

for a given  $p > 1$ . See “Appendix A”. Here, the second regularity restriction 0 is required to make sense of powers of  $u$ . On the other hand, many dispersive equations are known to be ill-posed below the scaling critical regularity. Among these ill-posedness results, many of them are in the form of *norm inflation* (see [6, 8–10, 13, 20, 31, 33, 36, 37, 41]), which is a stronger notion of ill-posedness. In [21], Kuan–Čanić proved norm inflation for vNLW (1.3) in  $\mathcal{H}^s(\mathbb{R}^d)$  for  $0 < s < s_{\text{scaling}}$  and any odd integers  $p \geq 3$ . Moreover, they pointed out that the viscous term has the potential to slow down the growth of the  $H^s$  norm, i.e. to slow down the speed of the norm inflation. For details, see [21]. Also, it is of interest to see if norm inflation for vNLW holds in negative Sobolev spaces. See [12].

Let us now turn our attention to the viscous NLW with a stochastic forcing. In [22], Kuan–Čanić studied the stochastic viscous wave equation with a multiplicative noise on  $\mathbb{R}^d$ ,  $d = 1, 2$ :

$$\partial_t^2 u - \Delta u + D\partial_t u = f(u)\xi,$$

where  $f$  is Lipschitz and  $\xi$  is the (Gaussian) space–time white noise on  $\mathbb{R}_+ \times \mathbb{R}^2$ . In [26], Oh and the author studied (the renormalized version of) SvNLW (1.1) with  $\alpha = \frac{1}{2}$ . When  $\alpha = \frac{1}{2}$ , the solution is not a function but is only a distribution and thus a renormalization on the nonlinearity is required to give a proper meaning to the dynamics (which in particular forces us to consider  $|u|^{p-1}u$  only for  $p \in 2\mathbb{N} + 1$  or  $u^k$  for an integer  $k \geq 2$ ). See [26] for details. In the cubic case, we proved pathwise global well-posedness. For an odd integer  $p \geq 5$ , we also used an invariant measure argument to prove almost sure global well-posedness with suitable random initial

data.<sup>1</sup> In this paper, our goal is to investigate further well-posedness of SvNLW (1.1) with an additive forcing  $D^\alpha \xi$  and, in particular, prove pathwise global well-posedness for any  $p > 1$ , where the range of  $\alpha < \frac{1}{2}$  depends on the degree  $p > 1$  of the nonlinearity.

### 1.2 SvNLW with an additive stochastic forcing

We say that  $u$  is a solution to SvNLW (1.1) if  $u$  satisfies the following Duhamel formulation of (1.1):

$$u(t) = V(t)(u_0, u_1) - \int_0^t S(t - t')(|u|^{p-1}u)(t')dt' + \Psi. \tag{1.5}$$

Here,  $V(t)$  is the linear propagator defined by

$$\begin{aligned} V(t)(u_0, u_1) = & e^{-\frac{D}{2}t} \left( \cos(t\llbracket D \rrbracket) + \frac{D}{2\llbracket D \rrbracket} \sin(t\llbracket D \rrbracket) \right) u_0 \\ & + e^{-\frac{D}{2}t} \frac{\sin(t\llbracket D \rrbracket)}{\llbracket D \rrbracket} u_1 \end{aligned} \tag{1.6}$$

and  $S(t)$  is defined by

$$S(t) = e^{-\frac{D}{2}t} \frac{\sin(t\llbracket D \rrbracket)}{\llbracket D \rrbracket}, \tag{1.7}$$

where

$$\llbracket D \rrbracket = \sqrt{1 - \frac{3}{4}\Delta},$$

and  $\Psi$  denotes the stochastic convolution defined by

$$\Psi := \Psi_\alpha = \int_0^t S(t - t')D^\alpha \xi(dt'). \tag{1.8}$$

A standard argument shows that  $\Psi$  belongs to  $C(\mathbb{R}_+; W^{\frac{1}{2}-\alpha-\varepsilon, \infty}(\mathbb{T}^2))$  almost surely, where  $\varepsilon > 0$  can be arbitrarily small; see Lemma 2.5 below. In particular, when  $\alpha < \frac{1}{2}$ ,  $\Psi$  is a well-defined function on  $\mathbb{R}_+ \times \mathbb{T}^2$ .

We first state a local well-posedness result for SvNLW (1.1).

**Theorem 1.1** *Let  $p > 1$  and  $\alpha < \frac{1}{2}$ . Define  $q, r$ , and  $\sigma$  as follows.*

- (i) *When  $1 < p < 2$ , set  $q = 2 + \delta$ ,  $r = \frac{4+2\delta}{1+\delta}$ , and  $\sigma = 0$ , for some sufficiently small  $\delta > 0$ .*

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<sup>1</sup> Strictly speaking, almost sure global well-posedness holds for the noise  $\sqrt{2}D^{\frac{1}{2}}\xi$ , which makes the Gibbs measure for the standard NLW invariant under the SvNLW dynamics. For pathwise global well-posedness, a precise coefficient in front of the noise  $D^{\frac{1}{2}}\xi$  does not play any role.

- (ii) When  $p \geq 2$ , set  $q = p + \delta$ ,  $r = 2p$ , and  $\sigma = 1 - \frac{1}{p+\delta} - \frac{1}{p}$  for some arbitrary  $\delta > 0$ .

Let  $s \geq \sigma$ . Then, SvNLW (1.1) is pathwise locally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$ . More precisely, given any  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$ , there exists  $T = T_\omega(u_0, u_1)$  (which is positive almost surely) and a unique solution  $u$  to (1.1) with  $(u, \partial_t u)|_{t=0} = (u_0, u_1)$  in the class

$$\Psi + C([0, T]; H^\sigma(\mathbb{T}^2)) \cap L^q([0, T]; L^r(\mathbb{T}^2)).$$

We present the proof of Theorem 1.1 in Sect. 3. The proof of Theorem 1.1 is based on the following first order expansion [5, 11, 28]:

$$u = v + \Psi, \tag{1.9}$$

where the residual term  $v$  satisfies the following equation:

$$\begin{cases} \partial_t^2 v + (1 - \Delta)v + D\partial_t v + |v + \Psi|^{p-1}(v + \Psi) = 0 \\ (v, \partial_t v)|_{t=0} = (u_0, u_1). \end{cases} \tag{1.10}$$

See Proposition 3.1 for the pathwise local well-posedness result at the level of the residual term  $v$  using the homogeneous Strichartz estimates for the viscous wave equation (Lemma 2.8).

The main idea of the proof of pathwise local well-posedness of SvNLW (1.1) comes from [23]. Note that the nonlinearity  $|u|^{p-1}u$  in SvNLW (1.1) is not necessarily algebraic for general  $p > 1$ , which creates a difficulty for obtaining the difference estimate when applying the contraction argument. To deal with this issue, we apply the idea from Oh–Okamoto–Pocovnicu [32] using the fundamental theorem of calculus.

**Remark 1.2** (i) Using the same argument, the proof of Theorem 1.1 works for both the defocusing case (with the nonlinearity  $|u|^{p-1}u$ ) and the focusing case (with the nonlinearity  $-|u|^{p-1}u$ , i.e. with the negative sign).

The proof of Theorem 1.1 also works for SvNLW with nonlinearity  $u^k$ , where  $k \geq 2$  is an integer. In fact, a simple argument based on Sobolev’s inequality can be applied to prove local well-posedness of SvNLW with nonlinearity  $u^k$  in the class  $\Psi + C([0, T]; \mathcal{H}^s(\mathbb{T}^2))$  for  $s \geq 1$ . See, for example, Proposition 3.1 in [26].

- (ii) As it is written in Theorem 1.1, we point out that the regularity of initial data can be lowered to the subcritical case, i.e.  $s \geq s_{\text{crit}}$  (with a strict inequality when  $p = 3$ ), where  $s_{\text{crit}}$  is the critical regularity as defined in (1.4) (note that  $s_{\text{crit}} \leq \sigma$  with  $\sigma$  defined in Theorem 1.1). See Theorem A.6 and Remark A.7 for details.
- (iii) One can also directly prove local well-posedness of (1.1) for  $u \in L^q([0, T]; L^r(\mathbb{T}^2))$  for some appropriate  $q, r \geq 2$ . Specifically, in the Duhamel formulation (1.5), the linear term  $V(t)(u_0, u_1)$  can be estimated by the Strichartz estimate (Lemma 2.8), the nonlinear perturbation term  $\int_0^t S(t - t')(|u|^{p-1}u)(t')dt'$  can be estimated by the Schauder estimate (Lemma 2.7) along with Young’s convolution inequality, and the stochastic convolution  $\Psi$  can also be bounded in

$L^q([0, T]; L^r(\mathbb{T}^2))$  (Lemma 2.5). This approach yields a stronger uniqueness result since the solution does not depend on any specific structure such as (1.9). Nevertheless, this paper is meant to be a continuation of the work in [26], and so we choose to study (1.1) from a dispersive point of view. Due to the assumption that the initial data lies in the Sobolev space  $\mathcal{H}^s(\mathbb{T}^2)$  for some  $s \geq 0$ , it is more natural to construct the solution in  $C([0, T]; H^s(\mathbb{T}^2))$  for  $T > 0$ . The Strichartz spaces  $L^q([0, T]; L^r(\mathbb{T}^2))$  can be viewed as “helper” spaces that allow us to show local well-posedness for rough initial data (i.e. with  $s \geq 0$  as small as possible).

We now turn our attention to pathwise global well-posedness of SvNLW (1.1), and we restrict our attention to the defocusing case. Our pathwise global well-posedness result reads as follows.

**Theorem 1.3** *Let  $p > 1$  and  $\alpha < \min(\frac{1}{2}, \frac{2}{p-1} - \frac{1}{2})$ . Let  $\sigma = \max(0, 1 - \frac{1}{p+\delta} - \frac{1}{p})$  for some arbitrary  $\delta > 0$  and let  $s \geq \sigma$ . Then, SvNLW (1.1) is pathwise globally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$ . More precisely, given any  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^s)$ , there exists a unique global-in-time solution  $u$  to (1.1) with  $(u, \partial_t u)|_{t=0} = (u_0, u_1)$  in the class*

$$\Psi + C(\mathbb{R}_+; H^\sigma(\mathbb{T}^2)).$$

In Theorem 1.3, the uniqueness holds in the following sense. For any  $t_0 \in \mathbb{R}_+$ , there exists a time interval  $I(t_0) \ni t_0$  such that the solution  $u$  to (1.1) is unique in

$$\Psi + C(I(t_0); H^\sigma(\mathbb{T}^2)) \cap L^q(I(t_0); L^r(\mathbb{T}^2)),$$

where  $q, r \geq 2$  are as in Theorem 1.1.

As stated in Theorem 1.3, when  $1 < p \leq 3$ , we have the condition  $\alpha < \frac{1}{2}$ ; when  $p > 3$ , we have the condition  $\alpha < \frac{2}{p-1} - \frac{1}{2}$ . As  $p \rightarrow \infty$ , the condition for  $\alpha$  becomes  $\alpha \leq -\frac{1}{2}$ . Note that when  $1 < p < 5$ , we can prove pathwise global well-posedness of SvNLW (1.1) with the space–time white noise (i.e.  $\alpha = 0$ ).

We prove Theorem 1.3 by studying (1.10) for the residual term  $v$  in Sect. 4. From the proof of Theorem 1.1, we see that pathwise global well-posedness follows once we control the  $\mathcal{H}^1$ -norm of  $\vec{v}(t) := (v(t), \partial_t v(t))$ . For this purpose, we study the evolution of the energy

$$E(\vec{v}) = \frac{1}{2} \int_{\mathbb{T}^2} (v^2 + |\nabla v|^2) dx + \frac{1}{2} \int_{\mathbb{T}^2} (\partial_t v)^2 dx + \frac{1}{p+1} \int_{\mathbb{T}^2} |v|^{p+1} dx, \tag{1.11}$$

which is conserved under the (deterministic) usual NLW:

$$\partial_t^2 u + (1 - \Delta)u + |u|^{p-1}u = 0.$$

Note that for our problem, we proceed with the first order expansion (1.9), where the residual term  $v = \Psi - u$  only satisfies (1.10). In this case, the energy  $E(\vec{v})$  is not conserved under the Eq. (1.10) because of the perturbative term  $|v + \Psi|^{p-1}(v +$

$\Psi) - |v|^{p-1}v$ . For our problem, we first follow the globalization argument by Burq–Tzvetkov [7] and establish an exponential growth bound on  $E(\vec{v})$ , which works in the sub-cubic case  $1 < p \leq 3$ . For the super-cubic case  $p > 3$ , this argument no longer works due to the high homogeneity of the non-linearity. When  $3 < p \leq 5$ , we use an integration by parts trick introduced by Oh–Pocovnicu [34]. In the super-quintic case  $p > 5$ , we use a trick involving the Taylor expansion, where the idea comes from Latocca [24].

One important prerequisite for studying the evolution of the energy  $E(\vec{v})$  is that the local-in-time solution  $\vec{v}$  lies in  $\mathcal{H}^1(\mathbb{T}^2)$ , which is not guaranteed by the pathwise local well-posedness result (Theorem 1.1) as it is written. Nonetheless, due to the dissipative nature of the equation, we show that  $\vec{v}(t)$  indeed belongs to  $\mathcal{H}^1(\mathbb{T}^2)$  for any  $t > 0$  by using the Schauder estimate (Lemma 2.7) along with Theorem 1.1. See Sect. 4 for details.

We conclude our introduction by stating several remarks.

**Remark 1.4** (i) We point out that Theorem 1.1 and 1.3 also hold if we have  $-\Delta$  instead of  $1 - \Delta$  in (1.1) by using an essentially identical proof.

(ii) In Oh [26] and the author studied SvNLW (1.1) with  $\alpha = \frac{1}{2}$ . In this case, due to  $\alpha = \frac{1}{2}$ , the stochastic term  $\Psi$  defined in (1.8) turns out to be merely a distribution, so that we studied a renormalized version of (1.1) and proved pathwise global well-posedness in the cubic case. Because of the singular nature of the stochastic convolution in this setting, the standard Gronwall argument does not work, and so we used a Yudovich-type argument to bound the corresponding energy.

In the same paper, we also proved almost sure global well-posedness of (1.1) with  $p \in 2\mathbb{N} + 1$  and with random initial data, using the formal invariance of the Gibbs measure. However, the argument only works for  $\alpha = \frac{1}{2}$ , so it does not apply to our problem with  $\alpha < \frac{1}{2}$  in this paper. Instead, in this paper, we establish pathwise global well-posedness of SvNLW (1.1).

(iii) We can also consider the vNLW with randomized initial data:

$$\begin{cases} \partial_t^2 u + (1 - \Delta)u + D\partial_t u + |u|^{p-1}u = 0 \\ (u, \partial_t u)|_{t=0} = (u_0^\omega, u_1^\omega). \end{cases} \tag{1.12}$$

Here, the randomization  $(u_0^\omega, u_1^\omega)$  of the initial data  $(u_0, u_1)$  is defined by

$$(u_0^\omega, u_1^\omega) := \left( \sum_{n \in \mathbb{Z}^2} g_{n,0}(\omega) \widehat{u}_0(n) e^{in \cdot x}, \sum_{n \in \mathbb{Z}^2} g_{n,1}(\omega) \widehat{u}_1(n) e^{in \cdot x} \right), \tag{1.13}$$

where for  $j = 0, 1$ ,  $\widehat{u}_j(-n) = \overline{\widehat{u}_j(n)}$  for all  $n \in \mathbb{Z}^2$  and  $\{g_{n,j}\}_{n \in \mathbb{Z}^2}$  is a sequence of mean zero complex-valued random variables such that  $g_{-n,j} = \overline{g_{n,j}}$  for all  $n \in \mathbb{Z}^2$ . Moreover, we assume that  $g_{0,j}$  is real-valued for  $j = 0, 1$ ,  $\{g_{0,j}, \Re g_{n,j}, \Im g_{n,j}\}_{n \in \mathbb{I}, j=0,1}$  are independent with  $\mathbb{I} = (\mathbb{Z}_+ \times \{0\}) \cup (\mathbb{Z} \times \mathbb{Z}_+)$ , and there exists a constant  $c > 0$  such that on the probability distributions  $\mu_{n,j}$  of

$g_{n,j}$ , we have

$$\int e^{\gamma \cdot x} d\mu_{n,j}(x) \leq e^{c|\gamma|^2}, \quad j = 0, 1 \tag{1.14}$$

for all  $\gamma \in \mathbb{R}^2$  when  $n \in \mathbb{Z}^2 \setminus \{0\}$  and all  $\gamma \in \mathbb{R}$  when  $n = 0$ . Note that (1.14) is satisfied for standard complex-valued Gaussian random variables, standard Bernoulli random variables, and any random variables with compactly supported distributions.

The randomization (1.13) allows us to consider almost sure global well-posedness of (1.12) for  $(u_0, u_1)$  living in negative Sobolev spaces. For almost sure local well-posedness, we consider the following first order expansion similar to (1.9):

$$u = v + z,$$

where  $z$  is the solution of the linear viscous wave equation with initial data  $(u_0^\omega, u_1^\omega)$ :

$$z(t) = z^\omega(t) := V(t)(u_0^\omega, u_1^\omega)$$

with  $V(t)$  defined as in (1.6). By using the Schauder estimate (Lemma 2.7), we can establish similar (but stronger) probabilistic Strichartz estimates for  $z$  and  $\langle \nabla \rangle^{-1} \partial_t z$  as in [34, 35]. This enables us to prove almost sure local well-posedness of (1.12) using a similar argument as for proving Theorem 1.1, as long as  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$  with  $s > -\frac{1}{p}$ . On the other hand, the proof for almost sure global well-posedness of (1.12) is much simpler than that for Theorem 1.3, since  $z(t)$  is smooth for  $t > 0$  thanks to the parabolic smoothing. We omit details since this is not the main focus in this paper.

## 2 Preliminary lemmas

In this section, we discuss some notations and lemmas that are necessary for proving our well-posedness results.

We use  $A \lesssim B$  to denote  $A \leq CB$  for some constant  $C > 0$ , and we write  $A \sim B$  if  $A \lesssim B$  and  $B \lesssim A$ . Also, we use  $a+$  (and  $a-$ ) to denote  $a + \varepsilon$  (and  $a - \varepsilon$ , respectively) for arbitrarily small  $\varepsilon > 0$ . In addition, we use short-hand notations to work with space–time function spaces. For example,  $C_T H_x^s = C([0, T]; H^s(\mathbb{T}^d))$ .

### 2.1 Sobolev spaces and Besov spaces

Let  $s \in \mathbb{R}$ . We denote  $H^s(\mathbb{T}^d)$  as the  $L^2$ -based Sobolev space with the norm:

$$\|u\|_{H^s(\mathbb{T}^d)} = \|\langle n \rangle^s \widehat{u}(n)\|_{\ell_n^2(\mathbb{Z}^d)},$$

where  $\widehat{u}(n)$  is the Fourier coefficient of  $u$  and  $\langle \cdot \rangle = (1 + |\cdot|)^{\frac{1}{2}}$ . We then define  $\mathcal{H}^s(\mathbb{T}^d)$  as

$$\mathcal{H}^s(\mathbb{T}^d) = H^s(\mathbb{T}^d) \times H^{s-1}(\mathbb{T}^d).$$



Also, we denote  $W^{s,p}(\mathbb{T}^d)$  as the  $L^p$ -based Sobolev space with the norm:

$$\|u\|_{W^{s,p}(\mathbb{T}^d)} = \|\mathcal{F}^{-1}(\langle n \rangle^s \widehat{u}(n))\|_{L^p(\mathbb{T}^d)},$$

where  $\mathcal{F}^{-1}$  denotes the inverse Fourier transform on  $\mathbb{T}^d$ . When  $p = 2$ , we have  $H^s(\mathbb{T}^d) = W^{s,2}(\mathbb{T}^d)$ .

Let  $\varphi : \mathbb{R} \rightarrow [0, 1]$  be a bump function such that  $\varphi \in C_c([-\frac{8}{5}, \frac{8}{5}])$  and  $\varphi \equiv 1$  on  $[-\frac{5}{4}, \frac{5}{4}]$ . For  $\xi \in \mathbb{R}^d$ , we define  $\varphi_0(\xi) = \varphi(|\xi|)$  and

$$\varphi_j(\xi) = \varphi\left(\frac{|\xi|}{2^j}\right) - \varphi\left(\frac{|\xi|}{2^{j-1}}\right)$$

for  $j \in \mathbb{Z}_+$ . Note that

$$\sum_{j \in \mathbb{Z}_{\geq 0}} \varphi_j(\xi) = 1 \tag{2.1}$$

for any  $\xi \in \mathbb{R}^d$ . For  $j \in \mathbb{Z}_{\geq 0}$ , we define the Littlewood-Paley projector  $\mathbf{P}_j$  as

$$\mathbf{P}_j u = \mathcal{F}^{-1}(\varphi_j \widehat{u}).$$

Due to (2.1), we have

$$u = \sum_{j=0}^{\infty} \mathbf{P}_j u. \tag{2.2}$$

We also recall the definition of Besov spaces  $B_{p,q}^s(\mathbb{T}^d)$  equipped with the norm:

$$\|u\|_{B_{p,q}^s(\mathbb{T}^d)} = \|2^{sj} \|\mathbf{P}_j u\|_{L_x^p(\mathbb{T}^d)}\|_{\ell_j^q(\mathbb{Z}_{\geq 0})}.$$

Note that  $H^s(\mathbb{T}^d) = B_{2,2}^s(\mathbb{T}^d)$ .

We then recall the definition of paraproducts introduced by Bony [4]. For details, see [1, 16]. For given functions  $u$  and  $v$  on  $\mathbb{T}^d$  of regularities  $s_1$  and  $s_2$ , respectively. By (2.2), we can write the product  $uv$  as

$$\begin{aligned} uv &= u \odot u + u \ominus v + u \otimes v \\ &:= \sum_{j < k-2} \mathbf{P}_j u \mathbf{P}_k v + \sum_{|j-k| \leq 2} \mathbf{P}_j u \mathbf{P}_k v + \sum_{k < j-2} \mathbf{P}_j u \mathbf{P}_k v. \end{aligned}$$

The term  $u \otimes v$  (and the term  $u \ominus v$ ) is called the paraproduct of  $v$  by  $u$  (and the paraproduct of  $u$  by  $v$ , respectively), and it is well defined as a distribution of regularity  $\min(s_2, s_1 + s_2)$  (and  $\min(s_1, s_1 + s_2)$ , respectively). The term  $u \ominus v$  is called the resonant product of  $u$  and  $v$ , and it is well defined in general only if  $s_1 + s_2 > 0$ .

With these definitions in hand, we recall some basic properties of Besov spaces.

**Lemma 2.1** (i) *Let  $s_1, s_2 \in \mathbb{R}$  and  $1 \leq p, p_1, p_2, q \leq \infty$  which satisfies  $\frac{1}{p} = \frac{1}{p_1} + \frac{1}{p_2}$ . Then, we have*

$$\|u \odot v\|_{B_{p_2,q}^{s_2}(\mathbb{T}^d)} \lesssim \|u\|_{L^{p_1}(\mathbb{T}^d)} \|v\|_{B_{p_2,q}^{s_2}(\mathbb{T}^d)}. \tag{2.3}$$

When  $s_1 + s_2 > 0$ , we have

$$\|u \odot v\|_{B_{p,q}^{s_1+s_2}(\mathbb{T}^d)} \lesssim \|u\|_{B_{p_1,q}^{s_1}(\mathbb{T}^d)} \|v\|_{B_{p_2,q}^{s_2}(\mathbb{T}^d)}. \tag{2.4}$$

(ii) *Let  $s_1 < s_2$  and  $1 \leq p, q \leq \infty$ . Then, we have*

$$\|u\|_{B_{p,q}^{s_1}(\mathbb{T}^d)} \lesssim \|u\|_{W^{s_2,p}(\mathbb{T}^d)}. \tag{2.5}$$

In particular, when  $q = \infty$ , we have

$$\|u\|_{B_{p,\infty}^{s_1}(\mathbb{T}^d)} \lesssim \|u\|_{W^{s_1,p}(\mathbb{T}^d)}. \tag{2.6}$$

See [1, 30] for the proofs of (2.3) and (2.4) in the  $\mathbb{R}^d$  setting, which can be easily extended to the  $\mathbb{T}^d$  setting. The embedding (2.5) follows from the  $L^p$  boundedness of  $\mathbf{P}_j$  and the  $\ell^q$ -summability of  $\{2^{(s_1-s_2)j}\}_{j \in \mathbb{Z}_{\geq 0}}$ , and the embedding (2.6) follows easily from the  $L^p$  boundedness of  $\mathbf{P}_j$ .

Using (2.3) and (2.4), we get the following product estimate.

**Corollary 2.2** *Let  $s > 0, 1 \leq p, q \leq \infty$  and  $1 \leq p_1, p_2, q_1, q_2 \leq \infty$  satisfying*

$$\frac{1}{p_1} + \frac{1}{q_1} = \frac{1}{p_2} + \frac{1}{q_2} = \frac{1}{p}.$$

Then,

$$\|uv\|_{B_{p,q}^s(\mathbb{T}^d)} \lesssim \|u\|_{B_{p_1,q}^s(\mathbb{T}^d)} \|v\|_{L^{q_1}(\mathbb{T}^d)} + \|u\|_{L^{p_2}(\mathbb{T}^d)} \|v\|_{B_{q_2,q}^s(\mathbb{T}^d)}.$$

Next, we recall the following chain rule estimates.

**Lemma 2.3** *Let  $u$  be a smooth function on  $\mathbb{T}^d, s \in (0, 1), r \geq 2$ . Let  $F$  denote the function  $F(u) = |u|^{r-1}u$  or  $F(u) = |u|^r$ .*

(i) *Let  $1 < p, p_1 < \infty$  and  $1 < p_2 \leq \infty$  satisfying  $\frac{1}{p} = \frac{1}{p_1} + \frac{1}{p_2}$ . Then, we have*

$$\|F(u)\|_{W^{s,p}(\mathbb{T}^d)} \lesssim \|u\|_{W^{s,p_1}(\mathbb{T}^d)} \| |u|^{r-1} \|_{L^{p_2}(\mathbb{T}^d)}. \tag{2.7}$$

(ii) *Let  $1 \leq p, q \leq \infty$  and  $1 \leq p_1, p_2 \leq \infty$  satisfying  $\frac{1}{p} = \frac{1}{p_1} + \frac{1}{p_2}$ . Then, we have*

$$\|F(u)\|_{B_{p,q}^s(\mathbb{T}^d)} \lesssim \|u\|_{B_{p_1,q}^s(\mathbb{T}^d)} \| |u|^{r-1} \|_{L^{p_2}(\mathbb{T}^d)}. \tag{2.8}$$

The estimate (2.7) follows immediately from the fractional chain rule on  $\mathbb{T}^d$  in [14]. For the proof of (2.8), see, for example, Lemma 3.5 in [24] in the  $\mathbb{R}^d$  setting, which can be easily extended to the  $\mathbb{T}^d$  setting.

Lastly, we recall the following Gagliardo-Nirenberg interpolation inequality.

**Lemma 2.4** *Let  $p_1, p_2 \in (1, \infty)$  and  $s_1, s_2 > 0$ . Let  $p > 1$  and  $\theta \in (0, 1)$  satisfying*

$$-\frac{s_1}{d} + \frac{1}{p} = (1 - \theta)\left(\frac{1}{p_1} - \frac{s_2}{d}\right) + \frac{\theta}{p_2} \quad \text{and} \quad s_1 \leq (1 - \theta)s_2.$$

*Then, for  $u \in W^{s_2, p_1}(\mathbb{T}^d) \cap L^{p_2}(\mathbb{T}^d)$ , we have*

$$\|u\|_{W^{s_1, p}(\mathbb{T}^d)} \lesssim \|u\|_{W^{s_2, p_1}(\mathbb{T}^d)}^{1-\theta} \|u\|_{L^{p_2}(\mathbb{T}^d)}^\theta.$$

This inequality follows from a direct application of Sobolev’s inequality on  $\mathbb{T}^d$  (see [2]) and then interpolation.

### 2.2 On the stochastic term

In this subsection, we discuss the regularity properties of the stochastic term  $\Psi$  defined in (1.8). Given  $N \in \mathbb{N}$ , we denote  $\Psi_N = \pi_N \Psi$  as the truncated stochastic convolution, where  $\pi_N$  is the frequency cutoff onto the spatial frequencies  $\{|n| \leq N\}$ . Then, we have the following regularity result for  $\Psi$ .

**Lemma 2.5** *For any  $\varepsilon > 0$  and  $T > 0$ ,  $\Psi_N$  converges to  $\Psi$  in  $C([0, T]; W^{1-2\alpha-\varepsilon, \infty}(\mathbb{T}^2))$  almost surely. In particular, we have*

$$\Psi \in C([0, T]; W^{\frac{1}{2}-\alpha-\varepsilon, \infty}(\mathbb{T}^2))$$

*almost surely.*

The proof of Lemma 2.5 follows from a straightforward modification of the proof in [18, Lemma 3.1], and so we omit details. See also [17, Proposition 2.1].

**Remark 2.6** One can use an integration by parts to write

$$\widehat{\Psi}(t, n) = - \int_0^t B_n(t') \frac{d}{ds} \Big|_{s=t'} \left( e^{-\frac{|n|}{2}(t-s)} \frac{\sin((t-s)\llbracket n \rrbracket)}{\llbracket n \rrbracket} |n|^\alpha \right) dt'$$

almost surely, which allows us to compute that

$$\begin{aligned} \partial_t \widehat{\Psi}(t, n) = \int_0^t & \left( - \frac{|n|}{2\llbracket n \rrbracket} e^{-\frac{|n|}{2}(t-t')} \sin((t-t')\llbracket n \rrbracket) \right. \\ & \left. + e^{-\frac{|n|}{2}(t-t')} \cos((t-t')\llbracket n \rrbracket) \right) |n|^\alpha dB_n(t') \end{aligned}$$

almost surely. Using a similar argument as in [18, Lemma 3.1] or [17, Proposition 2.1], we have  $\partial_t \Psi \in C([0, T]; W^{-\frac{1}{2}-\alpha-, \infty}(\mathbb{T}^2))$  almost surely. This will be useful in the proof of pathwise global well-posedness of SvNLW (1.1) in Sect. 4.2.

### 2.3 Linear estimates

In this subsection, we show some relevant linear estimates and the Strichartz estimates that are used to prove our well-posedness results.

Let

$$P(t) = e^{-\frac{D}{2}t}$$

be the Poisson kernel with a parameter  $\frac{t}{2}$ , which appears in the viscous wave linear propagator  $V(t)$  defined in (1.6). We first recall the following Schauder-type estimate for the Poisson kernel  $P(t)$ . For a proof, see Lemma 2.3 in [26].

**Lemma 2.7** *Let  $1 \leq p \leq q \leq \infty$  and  $\beta \geq 0$ . Then, we have*

$$\|D^\beta P(t)\phi\|_{L^q(\mathbb{T}^d)} \lesssim t^{-\beta-d(\frac{1}{p}-\frac{1}{q})} \|\phi\|_{L^p(\mathbb{T}^d)}$$

for any  $0 < t \leq 1$ .

Next, we turn our attention to the Strichartz estimates for the homogeneous linear viscous wave equation on  $\mathbb{T}^d$ . We recall that the linear propagator  $V(t)$  is defined in (1.6).

**Lemma 2.8** *Given  $s \geq 0$ , suppose that  $2 < q \leq \infty, 2 \leq r \leq \infty$  satisfy the following scaling condition:*

$$\frac{1}{q} + \frac{d}{r} = \frac{d}{2} - s. \tag{2.9}$$

Then, we have

$$\|V(t)(\phi_0, \phi_1)\|_{C([0, T]; \mathcal{H}^{s-1}(\mathbb{T}^d))} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^s(\mathbb{T}^d)} \tag{2.10}$$

and

$$\|V(t)(\phi_0, \phi_1)\|_{L^q([0, T]; L^r_x(\mathbb{T}^d))} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^s(\mathbb{T}^d)} \tag{2.11}$$

for all  $0 < T \leq 1$ .

**Proof** The bound (2.10) can be immediately seen from the definition of the  $\mathcal{H}^s$ -norm and the fact that  $e^{-\frac{|n|}{2}t} \leq 1, |\cos(t\llbracket n \rrbracket)| \leq 1$ , and  $|\sin(t\llbracket n \rrbracket)| \leq 1$ .

To prove (2.11), we use the  $TT^*$  method. We first consider the case when  $s = 0$ . Let

$$V_1(t) = e^{-\frac{D}{2}t} \cos(t\llbracket D \rrbracket), \quad V_2(t) = e^{-\frac{D}{2}t} \frac{D}{2\llbracket D \rrbracket} \sin(t\llbracket D \rrbracket),$$

so that

$$V(t)(\phi_0, \phi_1) = V_1(t)\phi_0 + V_2(t)\phi_1 + S(t)\phi_1.$$

Let  $L : L^2(\mathbb{T}^d) \rightarrow L^q_T L^r_x(\mathbb{T}^d)$  be the linear operator given by  $L\phi = V_1(t)\phi$ . Note that  $L^*$  is the linear operator given by

$$L^*f = \int_0^T V_1(t')f(t')dt'$$

for any space–time Schwartz function  $f$ . By Minkowski’s integral inequality, the Schauder estimate (Lemma 2.7) twice, the scaling condition (2.9), and the Hardy–Littlewood–Sobolev inequality, we have

$$\begin{aligned} \|LL^*f\|_{L^q_T L^r_x} &\leq \left\| \int_0^T \|e^{-\frac{D}{2}(t+t')} \cos(t\llbracket D \rrbracket) \cos(t'\llbracket D \rrbracket) f(t')\|_{L^r_x} dt' \right\|_{L^q_T} \\ &\lesssim \left\| \int_0^T \frac{1}{|t-t'|^{2(\frac{1}{2}-\frac{1}{r})}} \|e^{-\frac{D}{4}(t+t')} \cos(t\llbracket D \rrbracket) \cos(t'\llbracket D \rrbracket) f(t')\|_{L^2_x} dt' \right\|_{L^q_T} \\ &\lesssim \left\| \int_0^T \frac{1}{|t-t'|^{2(\frac{1}{r}-\frac{1}{r})}} \|f(t')\|_{L^r_x} dt' \right\|_{L^q_T} \\ &= \left\| \int_0^\infty \frac{1}{|t-t'|^{2/q}} \|\mathbf{1}_{[0,T]} f(t')\|_{L^r_x} dt' \right\|_{L^q_T} \\ &\lesssim \|f\|_{L^q_T L^r_x}. \end{aligned}$$

Thus, by a standard duality argument, we obtain

$$\|V_1(t)\phi_0\|_{L^q_T L^r_x(\mathbb{T}^d)} \lesssim \|\phi_0\|_{L^2(\mathbb{T}^d)}.$$

By using similar arguments, we obtain

$$\|V_2(t)\phi_0\|_{L^q_T L^r_x(\mathbb{T}^d)} \lesssim \|\phi_0\|_{L^2}, \quad \|S(t)\phi_1\|_{L^q_T L^r_x} \lesssim \|\phi_0\|_{H^{-1}(\mathbb{T}^d)},$$

so that we have

$$\|V(t)(\phi_0, \phi_1)\|_{L^q_T L^r_x(\mathbb{T}^d)} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^0(\mathbb{T}^d)}. \tag{2.12}$$

When  $s > 0$ , by Sobolev’s inequality, the scaling condition (2.9), and (2.12), we obtain

$$\begin{aligned} \|V(t)(\phi_0, \phi_1)\|_{L_T^q L_x^r} &\lesssim \|V(t)(\langle \nabla \rangle^s \phi_0, \langle \nabla \rangle^s \phi_1)\|_{L_T^q L_x^{1/(\frac{\delta}{q} + \frac{1}{r})}} \\ &= \|V(t)(\langle \nabla \rangle^s \phi_0, \langle \nabla \rangle^s \phi_1)\|_{L_T^q L_x^{d/(\frac{q}{2} - \frac{1}{q})}} \\ &\lesssim \|(\langle \nabla \rangle^s \phi_0, \langle \nabla \rangle^s \phi_1)\|_{\mathcal{H}^0} \\ &= \|(\phi_0, \phi_1)\|_{\mathcal{H}^s}, \end{aligned}$$

as desired. □

**Remark 2.9** (i) Compared to the Strichartz estimates for the usual linear wave equations [15, 17, 19, 25], the Strichartz estimates for the homogeneous linear viscous wave equation on  $\mathbb{T}^d$  hold for a larger class of pairs  $(q, r)$ , thanks to the parabolic smoothing effect.

(ii) In Kuan–Čanić [21] proved the Strichartz estimates for the homogeneous linear viscous wave equation on  $\mathbb{R}^d$ . They used the method from Keel–Tao [19], so that their result requires  $(q, r)$  to be  $\sigma$ -admissible for some  $\sigma > 0$ , i.e.  $(q, r, \sigma) \neq (2, \infty, 1)$  and

$$\frac{2}{q} + \frac{2\sigma}{r} \leq \sigma.$$

We point out that the  $TT^*$  method we use in the proof also works on  $\mathbb{R}^d$  and does not have this  $\sigma$ -admissible restriction on  $q$  and  $r$ . However, our proof works only for  $s \geq 0$ .

We complete this subsection by establishing the following inhomogeneous linear estimates.

**Lemma 2.10** *Let  $p \geq 2$  and let  $S(t)$  be as in (1.7). Then, given  $\delta > 0$ , we have*

$$\left\| \int_0^t S(t-t')F(t')dt' \right\|_{L^{p+\delta}_{[0,T]}; L_x^{2p}(\mathbb{T}^2)} \lesssim \|F\|_{L^1([0,T]; L^2(\mathbb{T}^2))} \tag{2.13}$$

for any  $0 < T \leq 1$ .

**Proof** We let

$$s = 1 - \frac{1}{p + \delta} - \frac{2}{2p} = 1 - \frac{1}{p + \delta} - \frac{1}{p},$$

so that  $(p + \delta, 2p, s)$  satisfies the scaling condition in Lemma 2.8. By Minkowski’s integral inequality and Lemma 2.8, we obtain

$$\begin{aligned} \left\| \int_0^t S(t-t')F(t')dt' \right\|_{L_T^{p+\delta} L_x^{2p}} &\lesssim \int_0^T \|\mathbf{1}_{[0,t]}(t')S(t-t')F(t')\|_{L_T^{p+\delta} L_x^{2p}} dt' \\ &\lesssim \int_0^T \|F(t')\|_{H_x^{s-1}} dt' \end{aligned}$$

$$\leq \|F\|_{L_T^1 L_x^2},$$

so that (2.13) follows. □

**Lemma 2.11** *Let  $S(t)$  be as in (1.7). Then, given  $s \leq 1$ , we have*

$$\left\| \int_0^t S(t-t')F(t')dt' \right\|_{C([0,T]; H_x^s(\mathbb{T}^2))} \lesssim \|F\|_{L^1([0,T]; L_x^2(\mathbb{T}^2))}, \tag{2.14}$$

$$\left\| \partial_t \int_0^t S(t-t')F(t')dt' \right\|_{C([0,T]; H_x^{s-1}(\mathbb{T}^2))} \lesssim \|F\|_{L^1([0,T]; L_x^2(\mathbb{T}^2))} \tag{2.15}$$

for any  $0 < T \leq 1$ .

**Proof** The estimate (2.14) follows from (1.7) and Minkowski’s integral inequality. The estimate (2.15) follows similarly by noting that

$$\partial_t \int_0^t S(t-t')F(t')dt' = \int_0^t \partial_t S(t-t')F(t')dt',$$

where

$$\partial_t S(t) = e^{-\frac{D}{2}t} \left( \cos(t\llbracket D \rrbracket) - \frac{D}{2\llbracket D \rrbracket} \sin(t\llbracket D \rrbracket) \right).$$

□

### 3 Local well-posedness of SvNLW

In this section, we prove Theorem 1.1, pathwise local well-posedness for SvNLW (1.1). As mentioned in Sect. 1.2, we consider the following vNLW:

$$\begin{cases} \partial_t^2 v + (1 - \Delta)v + D\partial_t v + F(v + \Psi) = 0 \\ (v, \partial_t v)|_{t=0} = (u_0, u_1) \end{cases} \tag{3.1}$$

for given initial data  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$ ,  $F(u) = |u|^{p-1}u$ , and  $\Psi$  is the stochastic convolution defined in (1.8). By Lemma 2.5, we can fix a good  $\omega \in \Omega$  such that  $\Psi = \Psi(\omega) \in C([0, T]; W^{\frac{1}{2}-\alpha-\varepsilon, \infty}(\mathbb{T}^2))$  for  $\alpha < \frac{1}{2}$  and sufficiently small  $\varepsilon > 0$ , so that (3.1) becomes a deterministic equation. Then, we have the following pathwise local well-posedness of (3.1).

**Proposition 3.1** *Let  $p > 1$  and  $\alpha < \frac{1}{2}$ . Define  $q, r$ , and  $\sigma$  as follows.*

- (i) *When  $1 < p < 2$ , set  $q = 2 + \delta$ ,  $r = \frac{4+2\delta}{1+\delta}$ , and  $\sigma = 0$ , for some sufficiently small  $\delta > 0$ .*

(ii) When  $p \geq 2$ , set  $q = p + \delta$ ,  $r = 2p$ , and  $\sigma = 1 - \frac{1}{p+\delta} - \frac{1}{p}$ , for some arbitrary  $\delta > 0$ .

Let  $s \geq \sigma$ . Then, (3.1) is pathwise locally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$ . More precisely, given any  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$ , there exists  $0 < T = T_\omega(u_0, u_1) \leq 1$  and a unique solution  $\vec{v} = (v, \partial_t v)$  to (3.1) in the class

$$(v, \partial_t v) \in C([0, T]; \mathcal{H}^\sigma(\mathbb{T}^2)) \quad \text{and} \quad v \in L^q([0, T]; L^r(\mathbb{T}^2)).$$

Note that Theorem 1.1 follows immediately from Proposition 3.1. The main idea of the proof of Proposition 3.1 comes from [23].

**Proof** We first consider the case when  $p \geq 2$ . We write (3.1) in the Duhamel formulation:

$$v(t) = \Gamma(v) := V(t)(u_0, u_1) - \int_0^t S(t - t')F(v + \Psi)(t')dt', \tag{3.2}$$

where  $V(t)$  and  $S(t)$  are as defined in (1.6) and (1.7), respectively. Let  $\vec{\Gamma}(v) = (\Gamma(v), \partial_t \Gamma(v))$  and  $\vec{v} = (v, \partial_t v)$ . Given  $0 < T \leq 1$ , we define the space  $\mathcal{X}(T)$  as

$$\mathcal{X}^\sigma(T) = \mathcal{X}_1^\sigma(T) \times \mathcal{X}_2^\sigma(T),$$

where

$$\begin{aligned} \mathcal{X}_1^\sigma(T) &:= C([0, T]; H^\sigma(\mathbb{T}^2)) \cap L^{p+\delta}([0, T]; L^{2p}(\mathbb{T}^2)), \\ \mathcal{X}_2^\sigma(T) &:= C([0, T]; H^{\sigma-1}(\mathbb{T}^2)). \end{aligned}$$

Here,  $\delta > 0$  is arbitrary and  $\sigma = 1 - \frac{1}{p+\delta} - \frac{1}{p}$ . Note that this choice of  $\sigma$  along with the  $L_T^{p+\delta} L_x^{2p}$  norm satisfies the scaling condition in Lemma 2.8. Our goal is to show that  $\vec{\Gamma}$  is a contraction on a ball in  $\mathcal{X}^\sigma(T)$  for some  $0 < T \leq 1$ .

By (3.2), Lemma 2.8, (1.6), Lemmas 2.10 and 2.11, and Sobolev’s inequality with the fact that  $|\mathbb{T}^2| = 1$ , we have

$$\begin{aligned} \|\vec{\Gamma}(v)\|_{\mathcal{X}^\sigma(T)} &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^\sigma} + \|v + \Psi\|^p_{L_T^1 L_x^2} \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \left( \|v\|_{L_T^{p+\delta} L_x^{2p}}^p + \|\Psi\|_{L_T^{p+\delta} L_x^{2p}}^p \right) \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \left( \|\vec{v}\|_{\mathcal{X}^\sigma(T)}^p + \|\Psi\|_{C_T W_x^{\frac{1}{2}-\alpha-\varepsilon, \infty}}^p \right) \end{aligned} \tag{3.3}$$

for some  $\theta > 0$  and sufficiently small  $\varepsilon > 0$ .

For the difference estimate, we use the idea from Oh–Okamoto–Pocovnicu [32]. Noticing that  $F'(u) = p|u|^{p-1}$ , we use (3.2), Lemmas 2.8, 2.10 and 2.11, the fundamental theorem of calculus, Minkowski’s integral inequality, Hölder’s inequality, and Sobolev’s inequality to obtain



$$\begin{aligned}
 \|\vec{\Gamma}(v) - \vec{\Gamma}(w)\|_{\mathcal{X}^\sigma(T)} &\lesssim \|F(v + \Psi) - F(w + \Psi)\|_{L_T^1 L_x^2} \\
 &= \left\| \int_0^1 F'(w + \Psi + \tau(v - w))(v - w) d\tau \right\|_{L_T^1 L_x^2} \\
 &\lesssim \int_0^1 \|w + \Psi + \tau(v - w)\|_{L_T^p L_x^{2p}}^{p-1} \|v - w\|_{L_T^p L_x^{2p}} d\tau \\
 &\lesssim T^\theta \left( \|v\|_{L_T^{p+\delta} L_x^{2p}}^{p-1} + \|w\|_{L_T^{p+\delta} L_x^{2p}}^{p-1} + \|\Psi\|_{L_T^{p+\delta} L_x^{2p}}^{p-1} \right) \|v - w\|_{L_T^{p+\delta} L_x^{2p}} \\
 &\lesssim T^\theta \left( \|\vec{v}\|_{\mathcal{X}^\sigma(T)}^{p-1} + \|\vec{w}\|_{\mathcal{X}^\sigma(T)}^{p-1} + \|\Psi\|_{C_T W_x^{\frac{1}{2}-\alpha-\varepsilon, \infty}}^{p-1} \right) \|\vec{v} - \vec{w}\|_{\mathcal{X}^\sigma(T)}
 \end{aligned}
 \tag{3.4}$$

for some  $\theta > 0$  and sufficiently small  $\varepsilon > 0$ .

Thus, by choosing  $T = T_\omega(\|(u_0, u_1)\|_{\mathcal{H}^s}) > 0$  small enough, we obtain that  $\vec{\Gamma}$  is a contraction on the ball  $B_R \subset \mathcal{X}^\sigma(T)$  of radius  $R \sim 1 + \|(u_0, u_1)\|_{\mathcal{H}^s}$ . Note that at this point, the uniqueness of the solution  $v$  only holds in the ball  $B_R$ , but we can use a standard continuity argument to extend the uniqueness of  $v$  to the entire  $\mathcal{X}^\sigma(T)$ .

For the case when  $1 < p < 2$ , we may have  $p + \delta < 2$ , so that Lemma 2.8 may not work for the  $L_T^{p+\delta} L_x^{2p}$  norm. Instead, we consider the  $L_T^q L_x^r$  norm with  $q = 2 + \delta$  and  $r = \frac{4+2\delta}{1+\delta}$ , where  $\delta > 0$  is small enough so that  $r$  is close enough to 4. We also set  $\sigma = 0$ , so that that this choice of  $\sigma$  along with this  $L_T^q L_x^r$  norm satisfies the scaling condition in Lemma 2.8. Note that we also need to modify the definition of  $\mathcal{X}_1^\sigma(T)$  using this  $L_T^q L_x^r$  norm. We then modify (3.3) as follows. By (3.2), Lemma 2.8, (1.6), Lemmas 2.10 and 2.11, and Sobolev’s inequality, we have

$$\begin{aligned}
 \|\vec{\Gamma}(v)\|_{\mathcal{X}^0(T)} &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^0} + \| |v + \Psi|^p \|_{L_T^1 L_x^2} \\
 &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \left( \|v\|_{L_T^{2+\delta} L_x^{2p}}^p + \|\Psi\|_{L_T^{p+\delta} L_x^{2p}}^p \right) \\
 &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \left( \|\vec{v}\|_{\mathcal{X}^0(T)}^p + \|\Psi\|_{C_T W_x^{\frac{1}{2}-\alpha-\varepsilon, \infty}}^p \right)
 \end{aligned}$$

for some  $\theta > 0$ . Here, we can ensure that  $2p \leq r = \frac{4+2\delta}{1+\delta}$  for any  $1 < p < 2$  by choosing  $\delta = \delta(p) > 0$  small enough. A similar modification can be applied to (3.4) to obtain a difference estimate, which then allows us to close the contraction argument. □

**Remark 3.2** We point out that the local well-posedness result of vNLW (3.1) can be improved using the inhomogeneous Strichartz estimates. In particular, we can show that (3.1) is locally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$  as long as  $s \geq s_{\text{crit}}$  (with a strict inequality when  $p = 3$ ), where  $s_{\text{crit}}$  is the critical regularity as defined in (1.4). For details, see Theorem A.6 and Remark A.7.

### 4 Global well-posedness of SvNLW

In this section, we aim to prove Theorem 1.3, i.e. pathwise global well-posedness of SvNLW (1.1). As mentioned in Sect. 1.2, we prove Theorem 1.3 by studying the Eq. (1.10) for  $v$  with  $(v, \partial_t v)|_{t=0} = (u_0, u_1)$ , for given initial data  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$  of (1.1).

Fix an arbitrary  $T \geq 1$ . In view of Proposition 3.1, in order to show well-posedness of (3.1) on  $[0, T]$ , it suffices to show that the  $\mathcal{H}^\sigma$ -norm of the solution  $\vec{v}(t) = (v(t), \partial_t v(t))$  to (3.1) remains finite on  $[0, T]$ , where  $\sigma$  is as defined in Proposition 3.1. This will allow us to iteratively apply the pathwise local well-posedness result in Proposition 3.1.

In fact, we show that the solution  $\vec{v}(t)$  belongs to  $\mathcal{H}^1(\mathbb{T}^2)$ . Let  $0 < t \leq 1$ . From Lemma 2.7, we have

$$\|V(t)(u_0, u_1)\|_{\mathcal{H}^1} \lesssim (1 + t^{-1+\sigma})\|(u_0, u_1)\|_{\mathcal{H}^\sigma}. \tag{4.1}$$

Then, let  $0 < T_0 \leq 1$  be the local existence time as in the proof of Proposition 3.1. Thus, given  $s \geq \sigma$ , by (3.2), (4.1), Lemma 2.11, Hölder’s inequality, and Sobolev’s inequality, we have that for  $0 < t \leq T_0$ ,

$$\begin{aligned} \|\vec{v}(t)\|_{\mathcal{H}^1} &\lesssim (1 + t^{-1+\sigma})\|(u_0, u_1)\|_{\mathcal{H}^\sigma} + \|(v + \Psi)^p\|_{L^1_{T_0} L^2_x} \\ &\lesssim (1 + t^{-1+\sigma})\|(u_0, u_1)\|_{\mathcal{H}^s} + T_0^\theta \left( \|v\|_{L^q_{T_0} L^r_x}^p + \|\Psi\|_{C_{T_0} W_x^{\frac{1}{2}-\alpha-\varepsilon, \infty}}^p \right), \end{aligned} \tag{4.2}$$

where  $\delta > 0, \varepsilon > 0$  are sufficiently small,  $\theta > 0$ , and  $q, r$  are as defined in the statement of Proposition 3.1. Here, due to Lemma 2.5, we can fix a good  $\omega \in \Omega$  such that  $\Psi = \Psi(\omega) \in C([0, T_0]; W^{\frac{1}{2}-\alpha-\varepsilon, \infty}(\mathbb{T}^2))$  for  $\alpha < \frac{1}{2}$  and sufficiently small  $\varepsilon > 0$ , so that we know from (4.2) that  $\|\vec{v}(t)\|_{\mathcal{H}^1} < \infty$ . A standard argument then shows that  $\vec{v} \in C((0, T_0]; \mathcal{H}^1(\mathbb{T}^2))$ . Thus, our main goal is to control the  $\mathcal{H}^1$ -norm of  $\vec{v}(t)$  on  $[0, T]$  by bounding the energy  $E(\vec{v})$  defined in (1.11).

For the following computation, we need to work with the smooth solution  $(v_N, \partial_t v_N)$  to the truncated equation with initial data  $(\pi_N v_0, \pi_N v_1)$ , where  $\pi_N$  is the frequency truncation onto the frequencies  $\{|n| \leq N\}$ . After establishing an upper bound for  $E(\vec{v}(t))$  with the implicit constant independent of  $N$ , we can take  $N \rightarrow \infty$  by using Proposition 3.1 (specifically, the continuous dependence of a solution on the initial data). Here, we omit details and work with  $(v, \partial_t v)$  instead for simplicity. See, for example, [34] for a standard argument.

#### 4.1 Case $1 < p \leq 3$

In this case, we follow the globalization argument by Burq–Tzvetkov [7]. For simplicity of notation, we set  $E(t) = E(\vec{v}(t))$ .

Given  $T > 0$ , we fix  $0 < t \leq T$ . By (1.11) and (1.10), we have

$$\begin{aligned} \partial_t E(t) &= \int_{\mathbb{T}^2} \partial_t v (\partial_t^2 v + (1 - \Delta)v + |v|^{p-1}v) dx \\ &\leq - \int_{\mathbb{T}^2} \partial_t v (|v + \Psi|^{p-1}(v + \Psi) - |v|^{p-1}v) dx. \end{aligned} \tag{4.3}$$

Let  $F(u) = |u|^{p-1}u$ , so that we can compute  $F'(u) = p|u|^{p-1}$ . Thus, by the fundamental theorem of calculus, we have

$$\begin{aligned} |v + \Psi|^{p-1}(v + \Psi) - |v|^{p-1}v &= F(v + \Psi) - F(v) \\ &= \Psi \int_0^1 F'(v + \tau\Psi) d\tau \\ &\lesssim |\Psi| |v|^{p-1} + |\Psi|^p. \end{aligned} \tag{4.4}$$

Combining (4.3) and (4.4) and then applying the Cauchy-Schwartz inequality, we obtain

$$\begin{aligned} \partial_t E(t) &\lesssim \|\Psi\|_{L_x^\infty} \int_{\mathbb{T}^2} |\partial_t v| |v|^{p-1} dx + \int_{\mathbb{T}^2} |\partial_t v| |\Psi|^p dx \\ &\leq \|\Psi\|_{L_x^\infty} \left( \int_{\mathbb{T}^2} (\partial_t v)^2 dx \right)^{\frac{1}{2}} \left( \int_{\mathbb{T}^2} |v|^{2(p-1)} dx \right)^{\frac{1}{2}} \\ &\quad + \|\Psi\|_{L_x^\infty}^{2p} \left( \int_{\mathbb{T}^2} (\partial_t v)^2 dx \right)^{\frac{1}{2}} \\ &\leq C(\Psi) E(t), \end{aligned} \tag{4.5}$$

as long as  $2(p - 1) \leq p + 1$ , or equivalently,  $p \leq 3$ . By Gronwall’s inequality on (4.5), we get

$$E(t) \lesssim e^{C(\Psi)t}$$

for any  $0 < t \leq T$ .

### 4.2 Case $3 < p \leq 5$

In this case, we follow the idea introduced by Oh–Pocovnicu [34]. See also [27, 29, 39] for similar arguments. In this setting, we let  $\alpha < \frac{2}{p-1} - \frac{1}{2}$ , the reason of which will become clear in the following steps.

By (1.11), (1.10), and Taylor’s theorem, we have

$$\begin{aligned}
 \partial_t E(t) &= \int_{\mathbb{T}^2} \partial_t v (\partial_t^2 v + (1 - \Delta)v + |v|^{p-1}v) dx \\
 &= - \int_{\mathbb{T}^2} \partial_t v (|v + \Psi|^{p-1}(v + \Psi) - |v|^{p-1}v) dx - \int_{\mathbb{T}^2} (D^{\frac{1}{2}} \partial_t v)^2 dx \\
 &\leq -p \int_{\mathbb{T}^2} \partial_t v \cdot |v|^{p-1} \Psi dx - \frac{p(p-1)}{2} \int_{\mathbb{T}^2} \partial_t v \cdot |v + \theta \Psi|^{p-3} (v + \theta \Psi) \Psi^2 dx \\
 &=: A_1 + A_2,
 \end{aligned}
 \tag{4.6}$$

where  $\theta \in (0, 1)$ . To estimate  $A_2$ , by the Cauchy-Schwartz inequality and Cauchy’s inequality, we have

$$\begin{aligned}
 |A_2| &\lesssim \int_{\mathbb{T}^2} |\partial_t v| (|v|^{p-2} \Psi^2 + \Psi^p) dx \\
 &\lesssim \left( \int_{\mathbb{T}^2} (\partial_t v)^2 dx \right)^{1/2} \left( \|\Psi\|_{L_x^\infty}^4 \int_{\mathbb{T}^2} |v|^{2(p-2)} dx + \|\Psi\|_{L_x^{2p}}^{2p} \right)^{1/2} \\
 &\lesssim (1 + \|\Psi\|_{L_x^\infty}^4) E(t) + \|\Psi\|_{L_x^{2p}}^p,
 \end{aligned}
 \tag{4.7}$$

where in the last inequality, we need  $2(p - 2) \leq p + 1$ , which is equivalent to  $p \leq 5$ . To estimate  $A_1$ , for  $0 < t_1 \leq t_2 \leq T$ , by integration by parts and Young’s inequality, we have

$$\begin{aligned}
 \int_{t_1}^{t_2} A_1 dt' &= - \int_{t_1}^{t_2} \int_{\mathbb{T}^2} \partial_t (|v|^{p-1}v) \Psi dx dt' \\
 &= - \int_{\mathbb{T}^2} |v(t_2)|^{p-1} v(t_2) \Psi(t_2) dx + \int_{\mathbb{T}^2} |v(t_1)|^{p-1} v(t_1) \Psi(t_1) dx \\
 &\quad + \int_{t_1}^{t_2} \int_{\mathbb{T}^2} |v|^{p-1} v (\partial_t \Psi) dx dt' \\
 &\lesssim \varepsilon \|v(t_2)\|_{L_x^{p+1}}^{p+1} + \frac{1}{\varepsilon} \|\Psi(t_2)\|_{L_x^{p+1}}^{p+1} + \|v(t_1)\|_{L_x^{p+1}}^{p+1} + \|\Psi(t_1)\|_{L_x^{p+1}}^{p+1} \\
 &\quad + \int_{t_1}^{t_2} \int_{\mathbb{T}^2} |v|^{p-1} v (\partial_t \Psi) dx dt',
 \end{aligned}
 \tag{4.8}$$

where  $0 < \varepsilon < 1$ . We see in Remark 2.6 that  $\partial_t \Psi \in C([0, T]; W^{-\frac{1}{2}-\alpha-\infty}(\mathbb{T}^2))$ . By duality, Hölder’s inequality, Lemma 2.3 (i), and Lemma 2.4, we obtain

$$\begin{aligned}
 &\int_{t_1}^{t_2} \int_{\mathbb{T}^2} |v|^{p-1} v (\partial_t \Psi) dx dt' \\
 &= \int_{t_1}^{t_2} \int_{\mathbb{T}^2} \langle \nabla \rangle^{\frac{1}{2}+\alpha+} (|v|^{p-1}v) \langle \nabla \rangle^{-\frac{1}{2}-\alpha-} (\partial_t \Psi) dx dt' \\
 &\lesssim \int_{t_1}^{t_2} \|v\|_{L_x^{p+1}}^{p-1} \|\langle \nabla \rangle^{\frac{1}{2}+\alpha+} v(t')\|_{L_x^{\frac{p+1}{2}}} \|\langle \nabla \rangle^{-\frac{1}{2}-\alpha-} (\partial_t \Psi)(t')\|_{L_x^\infty} dt'
 \end{aligned}$$

$$\begin{aligned}
 &\lesssim \|\partial_t \Psi\|_{C_T W_x^{-\frac{1}{2}-\alpha-\infty}} \int_{t_1}^{t_2} E(t')^{\frac{p-1}{p+1}} \|\langle \nabla \rangle v\|_{L_x^2}^{\frac{2}{p-1}} \|v\|_{L_x^{p+1}}^{\frac{p-3}{p-1}} dt' \\
 &\lesssim \|\partial_t \Psi\|_{C_T W_x^{-\frac{1}{2}-\alpha-\infty}} \int_{t_1}^{t_2} E(t') dt',
 \end{aligned}
 \tag{4.9}$$

where we require that

$$\frac{1}{2} + \alpha + = \frac{2}{p - 1},$$

which is equivalent to  $\alpha < \frac{2}{p-1} - \frac{1}{2}$ . By combining (4.6), (4.7), (4.8), and (4.9), we have

$$E(t_2) \leq (1 + C_1(\Psi)) \int_{t_1}^{t_2} E(t') dt' + C_2(\Psi, v(t_1)).$$

By Gronwall’s inequality, we get

$$E(t) \lesssim e^{C(\Psi)t}$$

for any  $0 < t \leq T$ .

### 4.3 Case $p > 5$

In this case, we follow the idea by Latocca [24]. In this setting, we also let  $\alpha < \frac{2}{p-1} - \frac{1}{2}$ .

We need the following lemma to close the energy estimates in the Gronwall argument. We define  $\beta_p := \lceil \frac{p-3}{2} \rceil$ ,  $F(u) := |u|^{p-1}u$ , and  $s_p := \frac{p-3}{p-1}$ .

**Lemma 4.1** *For any  $0 < t \leq T$  and every integer  $1 \leq k \leq \beta_p$ , we have*

$$\begin{aligned}
 &\left| \int_{\mathbb{T}^2} F^{(k-1)}(v(t)) \Psi(t)^{k-1} \partial_t \Psi(t) dx \right| \\
 &\lesssim g(\|\Psi\|_{L^\infty([0,T];X)}, \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{L^\infty([0,T];Y)}) (1 + E(t)),
 \end{aligned}$$

where  $g$  is a polynomial with positive coefficients, and

$$X := L^\infty(\mathbb{T}^2) \cap B_{\frac{p+1}{2},1}^{1-s_p}(\mathbb{T}^2) \quad \text{and} \quad Y := L^\infty(\mathbb{T}^2) \cap B_{\infty,1}^{s_p}(\mathbb{T}^2).$$

Note that given  $\alpha < \frac{2}{p-1} - \frac{1}{2}$ , by Lemma 2.5, Remark 2.6, and Lemma 2.1 (ii), we have

$$g(\|\Psi\|_{L^\infty([0,T];X)}, \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{L^\infty([0,T];Y)}) < \infty$$

almost surely.

Let us first assume Lemma 4.1 and work on the energy bound. As in the case when  $p > 3$ , we can compute that for  $0 < t \leq T$ ,

$$\partial_t E(t) \leq - \int_{\mathbb{T}^2} \partial_t v(F(v + \Psi) - F(v))dx. \tag{4.10}$$

For our convenience we compute that for  $k \in \mathbb{Z}_+$ ,

$$F^{(k)}(u) = \begin{cases} C_{p,k}|u|^{p-k-1}u & \text{for } k \text{ even,} \\ C_{p,k}|u|^{p-k} & \text{for } k \text{ odd.} \end{cases}$$

By Taylor’s formula at the point  $v(t, x)$  with integral remainder up to the order  $\beta_p = \lceil \frac{p-3}{2} \rceil$ , we have

$$F(v + \Psi) - F(v) = \sum_{k=1}^{\beta_p} \frac{1}{k!} F^{(k)}(v)\Psi^k + \int_v^{v+\Psi} \frac{F^{(\beta_p+1)}(\tau)}{\beta_p!} (v + \Psi - \tau)^{\beta_p} d\tau.$$

Let  $0 < t_1 \leq t_2 \leq T$ . By integrating (4.10) from  $t_1$  to  $t_2$ , we can write

$$E(t_2) \leq E(t_1) + \sum_{k=1}^{\beta_p} C_k I_k + C_p R, \tag{4.11}$$

where

$$I_k := - \int_{t_1}^{t_2} \int_{\mathbb{T}^2} \partial_t v F^{(k)}(v)\Psi^k dx dt' \text{ for } 1 \leq k \leq \beta_p,$$

$$R := - \int_{t_1}^{t_2} \int_{\mathbb{T}^2} \int_v^{v+\Psi} \partial_t v F^{(\beta_p+1)}(\tau)(v + \Psi - \tau)^{\beta_p} d\tau dx dt'.$$

We first estimate  $R$ . Note that for  $\tau \in [v, v + \Psi]$ , we have

$$|F^{(\beta_p+1)}(\tau)| \lesssim |v|^{p-\beta_p-1} + |\Psi|^{p-\beta_p-1}.$$

Thus, by Hölder’s inequality and Young’s inequality, we have

$$\begin{aligned} R &\lesssim \int_{t_1}^{t_2} \int_{\mathbb{T}^2} \partial_t v (|v|^{p-\beta_p-1} |\Psi|^{\beta_p+1} + |\Psi|^p) dx dt' \\ &\lesssim \int_{t_1}^{t_2} \|\partial_t v(t')\|_{L_x^2} \|v(t')\|_{L_x^{p+1}}^{p-\beta_p-1} \|\Psi(t')\|_{L_x^{r_p(\beta_p+1)}}^{\beta_p+1} dt' \\ &\quad + \int_{t_1}^{t_2} \|\partial_t v(t')\|_{L_x^2}^2 dt' + \|\Psi\|_{L_T^{2p} L_x^{2p}}^2 \\ &\leq \|\Psi\|_{L_T^{2p} L_x^{2p}}^2 + \left( 1 + \|\Psi\|_{L_T^\infty L_x^{r_p(\beta_p+1)}}^{\beta_p+1} \right) \end{aligned}$$

$$\times \int_{t_1}^{t_2} \max \left\{ E(t'), E(t')^{\frac{1}{2} + \frac{p-\beta p-1}{p+1}} \right\} dt', \tag{4.12}$$

where  $r_p$  satisfies  $\frac{1}{2} + \frac{p-\beta p-1}{p+1} + \frac{1}{r_p} = 1$ . Since  $\beta_p = \lceil \frac{p-3}{2} \rceil \geq \frac{p-3}{2}$ , we have  $\frac{p-\beta p-1}{p+1} \leq \frac{1}{2}$ , so that

$$R \lesssim \|\Psi\|_{L_T^{2p} L_x^{2p}}^{2p} + \left( 1 + \|\Psi\|_{L_T^\infty L_x^{r_p(\beta_p+1)}}^{\beta_p+1} \right) \int_{t_1}^{t_2} (1 + E(t')) dt'.$$

We now estimate  $I_k$ . By Fubini’s theorem and integration by parts in time, we have

$$\begin{aligned} |I_k| &= \left| - \int_{\mathbb{T}^2} \int_{t_1}^{t_2} \partial_t (F^{(k-1)}(v)) \Psi^k dt' dx \right| \\ &\leq \left| \int_{\mathbb{T}^2} F^{(k-1)}(v(t_2)) \Psi^k(t_2) dx \right| + \left| \int_{\mathbb{T}^2} F^{(k-1)}(v(t_1)) \Psi^k(t_1) dx \right| \\ &\quad + \left| k \int_{\mathbb{T}^2} \int_{t_1}^{t_2} F^{(k-1)}(v(t')) \Psi(t')^{k-1} \partial_t \Psi(t') dt' dx \right| \\ &\lesssim \int_{\mathbb{T}^2} |v(t_2)|^{p-k+1} |\Psi(t_2)|^k + |v(t_1)|^{p-k+1} |\Psi(t_1)|^k dx \\ &\quad + \left| \int_{t_1}^{t_2} \int_{\mathbb{T}^2} F^{(k-1)}(v(t')) \Psi(t')^{k-1} \partial_t \Psi(t') dx dt' \right| \\ &= J_k + K_k. \end{aligned} \tag{4.13}$$

To handle  $J_k$ , by Hölder’s inequality and Young’s inequality, we obtain

$$\begin{aligned} J_k &\leq E(t_2)^{\frac{p-k+1}{p+1}} \|\Psi(t_2)\|_{L_x^{p+1}}^k + E(t_1)^{\frac{p-k+1}{p+1}} \|\Psi(t_1)\|_{L_x^{p+1}}^k \\ &\leq \varepsilon E(t_2) + C_1 E(t_1) + C_2 \|\Psi\|_{L_T^\infty L_x^{p+1}}^{p+1}, \end{aligned} \tag{4.14}$$

where  $0 < \varepsilon < 1$ . To deal with  $K_k$ , by Lemma 4.1,

$$K_k \lesssim g(\|\Psi\|_{L^\infty([0, T]; X)}, \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{L^\infty([0, T]; Y)}) \left( 1 + \int_{t_1}^{t_2} E(t') dt' \right). \tag{4.15}$$

By combining (4.11), (4.12), (4.13), (4.14), (4.15), we obtain

$$\begin{aligned} E(t_2) &\lesssim \left( 1 + \|\Psi\|_{L_T^\infty L_x^{r_p(\beta_p+1)}}^{\beta_p+1} + g(\|\Psi\|_{L^\infty([0, T]; X)}, \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{L^\infty([0, T]; Y)}) \right) \\ &\quad \times \left( 1 + \int_{t_1}^{t_2} E(t') dt' \right) + \|\Psi\|_{L_T^{2p} L_x^{2p}}^{2p} + \|\Psi\|_{L_T^\infty L_x^{p+1}}^{p+1} + E(t_1). \end{aligned}$$

We can then use Gronwall’s inequality to get the desired bound.

We now provide the proof of Lemma 4.1.

**Proof of Lemma 4.1** Recall that  $s_p = \frac{p-3}{p-1}$ . We first consider the case when  $k \geq 2$ . By the Fourier–Plancherel theorem, we have

$$\begin{aligned}
 & \left| \int_{\mathbb{T}^2} F^{(k-1)}(v(t))\Psi(t)^{k-1}\partial_t\Psi(t)dx \right| \\
 &= \left| \sum_{j'=-1}^1 \sum_{j \geq 0} \int_{\mathbb{T}^2} \mathbf{P}_j(F^{(k-1)}(v(t))\Psi(t)^{k-1})\mathbf{P}_{j+j'}(\partial_t\Psi(t))dx \right| \\
 &\lesssim \sum_{j>2} \int_{\mathbb{T}^2} |\mathbf{P}_j(F^{(k-1)}(v(t))\Psi(t)^{k-1})| |\mathbf{P}_j(\partial_t\Psi(t))| dx \\
 &\quad + \sum_{j=0}^2 \int_{\mathbb{T}^2} |\mathbf{P}_j(F^{(k-1)}(v(t))\Psi(t)^{k-1})| |\mathbf{P}_j(\partial_t\Psi(t))| dx \\
 &=: I_1 + I_2. \tag{4.16}
 \end{aligned}$$

Let  $r_k := \frac{(k-1)(p+1)}{k}$ . To estimate  $I_2$ , by Hölder’s inequality, Bernstein’s inequality, and Young’s inequality, we have

$$\begin{aligned}
 I_2 &\lesssim \|\Psi(t)\|_{L_x^{r_k}}^{k-1} \|v(t)\|_{L_x^{p+1}}^{p-k+1} \sum_{j=0}^2 \|\mathbf{P}_j\partial_t\Psi(t)\|_{L_x^\infty} \\
 &\lesssim \|\Psi(t)\|_{L_x^{r_k}}^{k-1} \|\langle \nabla \rangle^{-1}\partial_t\Psi(t)\|_{L_x^\infty} E(t)^{\frac{p-k+1}{p+1}} \\
 &\lesssim E(t) + \|\Psi\|_{L_T^\infty L_x^{r_k}}^{r_k} \|\langle \nabla \rangle^{-1}\partial_t\Psi\|_{L_T^\infty L_x^\infty}^{\frac{p+1}{k}}.
 \end{aligned}$$

It remains to estimate  $I_1$ . By Hölder’s inequality, Bernstein’s inequality, and then Hölder’s inequality for series,

$$\begin{aligned}
 I_1 &\lesssim \sum_{j>2} 2^{j(1-s_p)} \|\mathbf{P}_j(F^{(k-1)}(v(t))\Psi(t)^{k-1})\|_{L_x^1} 2^{js_p} \|\mathbf{P}_j(\langle \nabla \rangle^{-1}\partial_t\Psi(t))\|_{L_x^\infty} \\
 &\leq \|F^{(k-1)}(v(t))\Psi(t)^{k-1}\|_{B_{1,\infty}^{1-s_p}} \|\langle \nabla \rangle^{-1}\partial_t\Psi\|_{B_{\infty,1}^{s_p}}.
 \end{aligned}$$

Then, by Corollary 2.2, we have

$$\begin{aligned}
 \|F^{(k-1)}(v(t))\Psi(t)^{k-1}\|_{B_{1,\infty}^{1-s_p}} &\lesssim \|F^{(k-1)}(v(t))\|_{B_{\frac{p+1}{p+2-k},\infty}^{1-s_p}} \|\Psi(t)^{k-1}\|_{L^{\frac{p+1}{k-1}}} \\
 &\quad + \| |v(t)|^{p-k+1} \|_{L^{\frac{p+1}{p-k+1}}} \|\Psi(t)^{k-1}\|_{B_{p_k,\infty}^{1-s_p}} \\
 &\lesssim \|F^{(k-1)}(v(t))\|_{B_{\frac{p+1}{p+2-k},\infty}^{1-s_p}} \|\Psi(t)\|_{L^{p+1}}^{k-1}
 \end{aligned}$$



$$+ E(t) \frac{p-k+1}{p+1} \|\Psi(t)^{k-1}\|_{B_{p_k, \infty}^{1-s_p}}, \tag{4.17}$$

where  $p_k$  satisfies  $\frac{1}{p_k} + \frac{p-k+1}{p+1} = 1$ . By Lemma 2.3 (ii), we have

$$\begin{aligned} \|\Psi(t)^{k-1}\|_{B_{p_k, \infty}^{1-s_p}} &\lesssim \|\Psi(t)\|_{B_{p_k, \infty}^{1-s_p}} \|\Psi(t)\|_{L^\infty}^{k-2} \\ &\leq \|\Psi(t)\|_{B_{\frac{p+1}{2}, \infty}^{1-s_p}} \|\Psi(t)\|_{L^\infty}^{k-2}. \end{aligned} \tag{4.18}$$

By Lemma 2.3 (ii), Lemma 2.1 (ii), and Lemma 2.4, we have

$$\begin{aligned} \|F^{(k-1)}(v(t))\|_{B_{\frac{p+1}{p+2-k}, \infty}^{1-s_p}} &\lesssim \|v(t)\|_{B_{\frac{p+1}{2}, \infty}^{1-s_p}} \| |v(t)|^{p-k} \|_{L^{\frac{p+1}{p-k}}} \\ &\lesssim \|v(t)\|_{W^{1-s_p, \frac{p+1}{2}}} E(t)^{\frac{p-k}{p+1}} \\ &\lesssim \|\langle \nabla \rangle v(t)\|_{L^2}^{1-\beta} \|v(t)\|_{L^{p+1}}^\beta E(t)^{\frac{p-k}{p+1}}, \end{aligned}$$

where  $\beta \in [0, s_p]$  satisfies  $\frac{2}{p+1} = \frac{1-s_p}{2} + \frac{\beta}{p+1}$ , and so  $\beta = \frac{p-3}{p-1} = s_p$ . Thus, we obtain

$$\begin{aligned} \|F^{(k-1)}(v(t))\|_{B_{\frac{p+1}{p+2-k}, \infty}^{1-s_p}} &\lesssim E(t)^{\frac{1-\beta}{2} + \frac{\beta}{p+1} + \frac{p-k}{p+1}} = E(t)^{\frac{2}{p+1} + \frac{p-k}{p+1}} \\ &\lesssim 1 + E(t). \end{aligned} \tag{4.19}$$

By combining (4.17), (4.18), and (4.19), we obtain the desired bound for  $I_1$ .

For the case when  $k = 1$ , after (4.16), we have the estimate  $I_2 \lesssim E(t) + \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{L_T^\infty L_x^\infty}^{p+1}$ . For the term  $I_1$ , by the estimate in (4.19), we have

$$I_1 \lesssim \|F(v(t))\|_{B_{1, \infty}^{1-s_p}} \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{B_{\infty, 1}^{s_p}} \lesssim \|\langle \nabla \rangle^{-1} \partial_t \Psi\|_{B_{\infty, 1}^{s_p}} (1 + E(t)),$$

as desired. □

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**Data availability** Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

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### Appendix A: On local well-posedness of subcritical vNLW

In this appendix, we aim to show that the deterministic viscous NLW is locally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$  with  $s \geq s_{\text{crit}}$ , where we recall that  $s_{\text{crit}}$  is defined by

$$s_{\text{crit}} := \max \left( 1 - \frac{2}{p-1}, 0 \right). \tag{A.1}$$

More precisely, we prove local well-posedness of the following subcritical vNLW:

$$\begin{cases} \partial_t^2 u + (1 - \Delta)u + D\partial_t u \pm |u|^{p-1}u = 0 \\ (u, \partial_t u)|_{t=0} = (u_0, u_1), \end{cases} \tag{A.2}$$

where  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$  and  $s \geq s_{\text{crit}}$  (with a strict inequality when  $p = 3$ ). To achieve this, we will need the inhomogeneous Strichartz estimates for the linear viscous wave equation on  $\mathbb{T}^2$ .

#### A.1 The inhomogeneous Strichartz estimates

In this subsection, we prove the Strichartz estimates for the inhomogeneous linear viscous wave equation on  $\mathbb{T}^d$ . To achieve this, we first establish the following estimate for the linear operator  $S(t)$  defined in (1.7).

**Lemma A.1** *Let  $1 \leq p \leq 2 \leq q \leq \infty$ . Then, we have*

$$\|S(t)\phi\|_{L^q(\mathbb{T}^d)} \lesssim t^{1-d(\frac{1}{p}-\frac{1}{q})} \|\phi\|_{L^p(\mathbb{T}^d)}$$

for any  $0 < t \leq 1$

**Proof** By (1.7) and applying the Schauder estimate (Lemma 2.7) twice, we obtain

$$\begin{aligned} \|S(t)\phi\|_{L^q(\mathbb{T}^d)} &= \left\| e^{-\frac{D}{4}t} \frac{\sin(t\llbracket D \rrbracket)}{\llbracket D \rrbracket} e^{-\frac{D}{4}t} \phi \right\|_{L^q(\mathbb{T}^d)} \\ &\lesssim t^{-d(\frac{1}{2}-\frac{1}{q})} \left\| \frac{\sin(t\llbracket D \rrbracket)}{\llbracket D \rrbracket} e^{-\frac{D}{4}t} \phi \right\|_{L^2(\mathbb{T}^d)} \\ &\leq t^{1-d(\frac{1}{2}-\frac{1}{q})} \|e^{-\frac{D}{4}t} \phi\|_{L^2(\mathbb{T}^d)} \\ &\lesssim t^{1-d(\frac{1}{p}-\frac{1}{q})} \|\phi\|_{L^p(\mathbb{T}^d)}, \end{aligned}$$

as desired. □

We now establish the Strichartz estimates for the inhomogeneous linear viscous wave equation on  $\mathbb{T}^d$ . We say that  $u$  is a solution to the following inhomogeneous linear viscous wave equation:

$$\begin{cases} \partial_t^2 u + (1 - \Delta)u + D\partial_t u = f \\ (u, \partial_t u)|_{t=0} = (\phi_0, \phi_1), \end{cases} \tag{A.3}$$

if  $u$  satisfies the following Duhamel formulation:

$$u(t) = V(t)(\phi_0, \phi_1) + \int_0^t S(t - t')f(t')dt',$$

where  $V(t)$  and  $S(t)$  are as defined in (1.6) and (1.7), respectively.

**Lemma A.2** *Given  $s \geq 0$ , suppose that  $1 < \tilde{q} \leq 2 < q < \infty$ ,  $1 \leq \tilde{r} \leq 2 \leq r \leq \infty$  satisfy the following scaling condition:*

$$\frac{1}{q} + \frac{d}{r} = \frac{d}{2} - s = \frac{1}{\tilde{q}} + \frac{d}{\tilde{r}} - 2. \tag{A.4}$$

*Then, a solution  $u$  to the inhomogeneous linear viscous wave Eq. (A.3) satisfies the following inequality:*

$$\|(u, \partial_t u)\|_{C_T \mathcal{H}_x^s(\mathbb{T}^d)} + \|u\|_{L_T^q L_x^r(\mathbb{T}^d)} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^s(\mathbb{T}^d)} + \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}(\mathbb{T}^d)}, \tag{A.5}$$

for all  $0 < T \leq 1$ .

**Proof** By (1.6), we have

$$\|(V(t)(\phi_0, \phi_1), \partial_t V(t)(\phi_0, \phi_1))\|_{C_T \mathcal{H}_x^s(\mathbb{T}^d)} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^s(\mathbb{T}^d)}. \tag{A.6}$$

By Lemma 2.8, we have

$$\|V(t)(\phi_0, \phi_1)\|_{L_T^q L_x^r(\mathbb{T}^d)} \lesssim \|(\phi_0, \phi_1)\|_{\mathcal{H}^s(\mathbb{T}^d)}. \tag{A.7}$$

We then use Lemma 3.5 in [21] (which is in the  $\mathbb{R}^d$  setting, but the proof also works in the  $\mathbb{T}^d$  setting with Lemma A.1 in hand) to obtain

$$\left\| \int_0^t S(t - t')f(t')dt' \right\|_{L_T^q L_x^r(\mathbb{T}^d)} \lesssim \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}(\mathbb{T}^d)}. \tag{A.8}$$

It remains to show

$$\left\| \int_0^t S(t - t')f(t')dt' \right\|_{C_T H_x^s(\mathbb{T}^d)} \lesssim \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}(\mathbb{T}^d)} \tag{A.9}$$

and

$$\left\| \partial_t \int_0^t S(t-t')f(t')dt' \right\|_{C_T H_x^{s-1}(\mathbb{T}^d)} \lesssim \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}(\mathbb{T}^d)}, \tag{A.10}$$

so that (A.5) follows from (A.6), (A.7), (A.8), (A.9), and (A.10).

To show that the inequality (A.9) holds, we use the Littlewood-Paley decomposition as in Lemma 3.6 in [21]. In view of the proof of Lemma 3.6 in [21], we know that it suffices to show (A.9) for all  $f$  such that  $\widehat{f}$  is supported in  $\{n \in \mathbb{Z}^d : 2^{j-1} \leq |n| \leq 2^{j+1}\}$  for all  $j \in \mathbb{Z}_+$  (the case for  $\{n \in \mathbb{Z}^d : 0 \leq |n| \leq 2\}$  follows in a similar manner) with the underlying constant independent of  $j$ . Fix  $0 < t < T$ . By Minkowski’s integral inequality, Hölder’s inequality in  $n$ , Hausdorff-Young inequality, Hölder’s inequality in  $t'$  (along with the fact that the number of lattice points inside a ball of radius  $R$  in  $\mathbb{R}^d$  is  $O(R^d)$ ), and a change of variable, we have

$$\begin{aligned} & \left\| \int_0^t S(t-t')f(t')dt' \right\|_{C_T H_x^s} \\ & \lesssim \int_0^t \left( \sum_{n \in \mathbb{Z}^2} |n|^{2s} \left| e^{-\frac{|n|}{2}(t-t')} \frac{\sin((t-t')\|n\|)}{\|n\|} \widehat{f}(t', n) \right|^2 \right)^{1/2} dt' \\ & \lesssim 2^{(j+1)s} \int_0^t (t-t')e^{2^{j-2}(t-t')} \left( \sum_{n \in \mathbb{Z}^2} |\widehat{f}(t', n)|^2 \right)^{1/2} dt' \\ & \lesssim 2^{(j+1)s} \int_0^t (t-t')e^{2^{j-2}(t-t')} (2^{(j+1)d})^{\frac{\tilde{r}'-2}{2\tilde{r}'}} \|\widehat{f}(t', n)\|_{\ell_n^{\tilde{r}'}} dt' \\ & \lesssim 2^{(j+1)(s+\frac{d}{\tilde{r}}-\frac{d}{2})} \left( \int_0^t |(t-t')e^{2^{j-2}(t-t')}|^{\tilde{q}'} dt' \right)^{1/\tilde{q}'} \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}} \\ & \lesssim 2^{(j+1)(s+\frac{d}{\tilde{r}}-\frac{d}{2}+\frac{1}{\tilde{q}}-2)} \|f\|_{L_T^{\tilde{q}} L_x^{\tilde{r}}}. \end{aligned}$$

By using the second equality in the scaling condition (A.4), we obtain the desired inequality with the underlying constant independent of  $j$ , and so the inequality (A.9) follows. The inequality (A.10) follows in a similar manner. □

**Remark A.3** As in the case of the homogeneous Strichartz estimates (Lemma 2.8), the Strichartz estimates for the inhomogeneous linear viscous wave equation on  $\mathbb{T}^d$  also hold for a larger class of pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  compared to the Strichartz estimates for the usual linear wave equations [15, 17, 19, 25]. Again, this is due to the parabolic smoothing effect. Note that this is also true on  $\mathbb{R}^d$  (see [21]).

We complete this subsection by making the following observation. Recall that we are considering the viscous NLW on  $\mathbb{T}^2$  with nonlinearity  $|u|^{p-1}u$  for  $p > 1$ . Suppose that we can find pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  satisfying the scaling condition (A.4) such that

$$q > p\tilde{q} \quad \text{and} \quad r \geq p\tilde{r}.$$

Then, by Hölder’s inequality and the fact that  $|\mathbb{T}^2| = 1$ , we have

$$\| |u|^{p-1}u \|_{L_T^{\tilde{q}} L_x^{\tilde{r}}} \leq T^{\frac{1}{\tilde{q}} - \frac{p}{\tilde{r}}} \|u\|_{L_T^q L_x^r}^p.$$

Note that the power of  $T$  is positive when  $q > p\tilde{q}$ . The following lemma shows that there exist such pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$ .

**Lemma A.4** *Let  $s_{crit}$  be as defined in (A.1). Given  $s_{crit} < s < 1$ , there exist  $1 < \tilde{q} \leq 2 < q < \infty$ ,  $1 \leq \tilde{r} \leq 2 \leq r \leq \infty$  satisfying the scaling condition (A.4) such that*

$$q > p\tilde{q} \text{ and } r \geq p\tilde{r}. \tag{A.11}$$

**Proof** In view of Lemma 3.3 in [17], given  $0 < s < 1$ , we have

$$\min\left(\frac{q}{\tilde{q}}, \frac{r}{\tilde{r}}\right) \leq \frac{3-s}{1-s},$$

and the equality holds by taking, for example,

$$(q, r) = \left(\frac{3-s}{1-s}\delta, \frac{2}{1-s - \frac{1-s}{(3-s)\delta}}\right) \text{ and } (\tilde{q}, \tilde{r}) = \left(\delta, \frac{2}{3-s - \frac{1}{\delta}}\right), \tag{A.12}$$

where  $\delta = \delta(s) > 1$  is sufficiently close to 1. Moreover, we note that  $\frac{3-s}{1-s} > p$  if and only if  $s > 1 - \frac{2}{p-1}$ . Thus, as long as  $s_{crit} < s < 1$ , there exist pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  that satisfy (A.11).  $\square$

**Remark A.5** In the case when  $p > 3$  and  $s = s_{crit} = 1 - \frac{2}{p-1} > 0$ , we have

$$\min\left(\frac{q}{\tilde{q}}, \frac{r}{\tilde{r}}\right) \leq \frac{3-s}{1-s} = p,$$

so that we can only find pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  that satisfy  $q = p\tilde{q}$  and  $r = p\tilde{r}$  instead of  $q > p\tilde{q}$  and  $r \geq p\tilde{r}$ . Such pairs do exist. One can take, for example,  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  as in (A.12).

In the case when  $1 < p \leq 3$  and  $s = s_{crit} = 0$ , there does not exist any pair  $(\tilde{q}, \tilde{r})$  that satisfies  $1 < \tilde{q} \leq 2$ ,  $1 \leq \tilde{r} \leq 2$ , and the scaling condition (A.4) (with  $d = 2$ ) simultaneously. In this case, the inhomogeneous Strichartz estimates (Lemma A.2) no longer applies, so that an alternative approach is needed to deal with this case.

**A.2: Local well-posedness of subcritical vNLW**

In this subsection, we prove the following theorem for the local well-posedness result of vNLW (A.2).

**Theorem A.6** *Let  $p > 1$  and let  $s_{crit}$  be as in (A.1). Then, (A.2) is locally well-posed in  $\mathcal{H}^s(\mathbb{T}^2)$  for*

(i)  $p \neq 3: s \geq s_{crit}$  or (ii)  $p = 3: s > s_{crit}$ .

More precisely, given any  $(u_0, u_1) \in \mathcal{H}^s(\mathbb{T}^2)$ , there exists  $0 < T = T(u_0, u_1) \leq 1$  and a unique solution  $\vec{u} = (u, \partial_t u)$  to (A.2) in the class

$$(u, \partial_t u) \in C([0, T]; \mathcal{H}^s(\mathbb{T}^2)) \text{ and } u \in L^q([0, T]; L^r(\mathbb{T}^2)),$$

for some suitable  $q, r \geq 2$ .

**Proof** For the proof, we only consider the case  $s < 1$ . We first consider the case  $s > s_{crit}$ . We write (A.2) in the Duhamel formulation:

$$u(t) = \Gamma(u) := V(t)(u_0, u_1) - \int_0^t S(t - t')F(u)(t')dt', \tag{A.13}$$

where  $F(u) = |u|^{p-1}u$ ,  $V(t)$  is as defined in (1.6), and  $S(t)$  is as defined in (1.7). Let  $\vec{\Gamma}(u) = (\Gamma(u), \partial_t \Gamma(u))$  and  $\vec{u} = (u, \partial_t u)$ .

Let  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  be as given in Lemma A.4, which guarantees that  $q > p\tilde{q}$  and  $r \geq p\tilde{r}$ . Given  $0 < T \leq 1$ , we define the space  $\mathcal{Y}(T)$  as

$$\mathcal{Y}^s(T) = \mathcal{Y}_1^s(T) \times \mathcal{Y}_2^s(T),$$

where

$$\begin{aligned} \mathcal{Y}_1^s(T) &:= C([0, T]; H^s(\mathbb{T}^2)) \cap L^q([0, T]; L^r(\mathbb{T}^2)), \\ \mathcal{Y}_2^s(T) &:= C([0, T]; H^{s-1}(\mathbb{T}^2)). \end{aligned}$$

Our goal is to show that  $\vec{\Gamma}$  is a contraction on a ball in  $\mathcal{Y}^s(T)$  for some  $0 < T \leq 1$ .

By (A.13), Lemma A.2, and Hölder’s inequality, we have

$$\begin{aligned} \|\vec{\Gamma}(u)\|_{\mathcal{Y}^s(T)} &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + \||u|^p\|_{L_T^{\tilde{q}}L_x^{\tilde{r}}} \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \|u\|_{L_T^qL_x^r}^p \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + T^\theta \|\vec{u}\|_{\mathcal{Y}^s(T)}^p \end{aligned} \tag{A.14}$$

for some  $\theta > 0$ .

For the difference estimate, we use the idea from Oh–Okamoto–Pocovnicu [32]. Noticing that  $F'(u) = p|u|^{p-1}$ , we use (A.13), Lemma A.2, the fundamental theorem of calculus, Minkowski’s integral inequality, and Hölder’s inequality to obtain

$$\begin{aligned} \|\vec{\Gamma}(u) - \vec{\Gamma}(v)\|_{\mathcal{Y}^s(T)} &\lesssim \|F(u) - F(v)\|_{L_T^{\tilde{q}}L_x^{\tilde{r}}} \\ &= \left\| \int_0^1 F'(v + \tau(u - v))(u - v)d\tau \right\|_{L_T^{\tilde{q}}L_x^{\tilde{r}}} \\ &\lesssim \int_0^1 \|v + \tau(u - v)\|_{L_T^{p\tilde{q}}L_x^{p\tilde{r}}}^{p-1} \|u - v\|_{L_T^{p\tilde{q}}L_x^{p\tilde{r}}} d\tau \end{aligned}$$

$$\begin{aligned} &\lesssim T^\theta \left( \|u\|_{L_T^q L_x^r}^{p-1} + \|v\|_{L_T^q L_x^r}^{p-1} \right) \|u - v\|_{L_T^q L_x^r} \\ &\lesssim T^\theta \left( \|\vec{u}\|_{\mathcal{Y}^s(T)}^{p-1} + \|\vec{v}\|_{\mathcal{Y}^s(T)}^{p-1} \right) \|\vec{u} - \vec{v}\|_{\mathcal{Y}^s(T)}. \end{aligned}$$

for some  $\theta > 0$ .

Thus, by choosing  $T = T(\|(u_0, u_1)\|_{\mathcal{H}^s}) > 0$  small enough, we obtain that  $\vec{\Gamma}$  is a contraction on the ball  $B_R \subset \mathcal{Y}^s(T)$  of radius  $R \sim 1 + \|(u_0, u_1)\|_{\mathcal{H}^s}$ .

In the case when  $p > 3$  and  $s = s_{\text{crit}} = 1 - \frac{2}{p-1} > 0$ , we can only find pairs  $(q, r)$  and  $(\tilde{q}, \tilde{r})$  that satisfy  $q = p\tilde{q}$  and  $r = p\tilde{r}$  (see Remark A.5). In this case, we modify the argument as follows. By (A.13), Lemma A.2, and Hölder’s inequality, we obtain

$$\begin{aligned} \|\Gamma(u)\|_{L_T^q L_x^r} &\lesssim \|V(t)(u_0, u_1)\|_{L_T^q L_x^r} + \| |u|^p \|_{L_T^{\tilde{q}} L_x^{\tilde{r}}} \\ &\lesssim \|V(t)(u_0, u_1)\|_{L_T^q L_x^r} + \|u\|_{L_T^q L_x^r}^p \end{aligned}$$

for some  $\theta > 0$  and sufficiently small  $\varepsilon > 0$ . A difference estimate on  $\Gamma(u) - \Gamma(v)$  also holds by a similar computation. By the dominated convergence theorem, we have  $\|u\|_{L_T^q L_x^r}^p \rightarrow 0$  as  $T \rightarrow 0$ . Thus, we can choose  $T = T(u_0, u_1) > 0$  sufficiently small such that  $\|V(t)(u_0, u_1)\|_{L_T^q L_x^r} \leq \frac{1}{2}\eta \ll 1$ , so that we can show that  $\Gamma$  is a contraction on the ball of radius  $\eta$  in  $L_T^q L_x^r$ . Moreover, (A.14) gives

$$\|\vec{u}\|_{C_T \mathcal{H}_x^s} = \|\vec{\Gamma}(u)\|_{C_T \mathcal{H}_x^s} \lesssim \|(u_0, u_1)\|_{\mathcal{H}^s} + \|u\|_{L_T^q L_x^r}^p < \infty,$$

so that  $\vec{u} = (u, \partial_t u) \in C_T \mathcal{H}_x^s$ .

Lastly, we consider the case when  $1 < p < 3$  and  $s = s_{\text{crit}} = 0$ . Note that  $s = 0$  along with the  $L_T^3 L_x^3$  norm satisfies the scaling condition (2.9) in Lemma 2.8. By (A.13), Minkowski’s integral inequality, Lemma 2.8, Sobolev’s inequality, and Hölder’s inequality, we obtain

$$\begin{aligned} \|\Gamma(u)\|_{L_T^3 L_x^3} &\lesssim \|V(t)(u_0, u_1)\|_{L_T^3 L_x^3} + \int_0^T \|\mathbf{1}_{[0,t]}(t') S(t - t') (|u|^{p-1} u)(t')\|_{L_T^3 L_x^3} dt' \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^0} + \int_0^T \|(|u|^{p-1} u)(t')\|_{H_x^{-1}} dt' \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^0} + \| |u|^p \|_{L_T^1 L_x^{1+}} \\ &\lesssim \|(u_0, u_1)\|_{\mathcal{H}^0} + T^\theta \|u\|_{L_T^3 L_x^3} \end{aligned}$$

for some  $\theta > 0$ . Also, by (1.6) and (1.7), we easily obtain

$$\|\vec{\Gamma}(u)\|_{C_T \mathcal{H}_x^0} \lesssim \|(u_0, u_1)\|_{\mathcal{H}^0} + T^\theta \|u\|_{L_T^3 L_x^3}.$$

Similar difference estimates also hold, so that we can conclude using the standard contraction argument. This finishes the proof. □

We finish this appendix by stating several remarks.

- Remark A.7** (i) At this point, we do not know how to prove local well-posedness for the cubic vNLW (with  $p = 3$ ) in  $L^2(\mathbb{T}^2)$ , i.e. with  $s = s_{\text{crit}} = 0$ . It would be of interest to investigate if spaces of functions of bounded  $p$ -variation (i.e.  $U^p$ - and  $V^p$ -spaces) such as those in [3, 32] can be applied to handle the cubic case.
- (ii) A slight modification of the proof of Theorem A.6 yields local well-posedness of SvNLW (1.1) in  $\mathcal{H}^s(\mathbb{T}^2)$  for all  $s \geq s_{\text{crit}}$  (with a strict inequality when  $p = 3$ ), which improves the local well-posedness result for SvNLW (1.1) in Theorem 1.1.
- (iii) One can compare the local well-posedness result for vNLW (A.2) in Theorem A.6 with the local well-posedness result for the usual NLW (see Remark 1.4 in [17]):

$$\partial_t^2 u - \Delta u \pm |u|^{p-1} u = 0.$$

Note that vNLW enjoys a better local well-posedness result than does the usual NLW, thanks to the parabolic smoothing effect.

- (iv) Note that the global well-posedness result of SvNLW (1.1) in Theorem 1.3 easily gives global well-posedness of vNLW (A.2) in the class  $\mathcal{H}^s(\mathbb{T}^2)$  for  $s \geq \max(0, 1 - \frac{1}{p+\delta} - \frac{1}{p})$ , where  $\delta > 0$  is arbitrary. However, at this point, we do not know how to prove global well-posedness of vNLW (A.2) in  $\mathcal{H}^s(\mathbb{T}^2)$  for  $s_{\text{crit}} \leq s < \max(0, 1 - \frac{1}{p+\delta} - \frac{1}{p})$ . The main difficulty for this range of  $s$  is showing  $\vec{v}(t) \in \mathcal{H}^1(\mathbb{T}^2)$  for all small enough  $t > 0$ , which is needed to guarantee the finiteness of the energy  $E(\vec{v})$  defined in (1.11).

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