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# H-convergence of a class of quasilinear equations in perforated domains beyond periodic setting 

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#### Abstract

In this paper, we aim to study the asymptotic behavior (when $\varepsilon \rightarrow 0$ ) of the solution of a quasilinear problem of the form $-\operatorname{div}\left(A^{\varepsilon}\left(\cdot, u^{\varepsilon}\right) \nabla u^{\varepsilon}\right)=f$ given in a perforated domain $\Omega \backslash T_{\varepsilon}$ with a Neumann boundary condition on the holes $T_{\varepsilon}$ and a Dirichlet boundary condition on $\partial \Omega$. We show that, if the holes are admissible in certain sense (without any periodicity condition) and if the family of matrices $(x, d) \mapsto A^{\varepsilon}(x, d)$ is uniformly coercive, uniformly bounded and uniformly equicontinuous in the real variable $d$, the homogenization of the problem considered can be done in two steps. First, we fix the variable $d$ and we homogenize the linear problem associated to $A^{\varepsilon}(\cdot, d)$ in the perforated domain. Once the $H^{0}$-limit $A^{0}(\cdot, d)$ of the pair $\left(A^{\varepsilon}, T^{\varepsilon}\right)$ is determined, in the second step, we deduce that the solution $u^{\varepsilon}$ converges in some sense to the unique solution $u^{0}$ in $H_{0}^{1}(\Omega)$ of the quasilinear equation $-\operatorname{div}\left(A^{0}\left(\cdot, u^{0}\right) \nabla u\right)=\chi^{0} f\left(\right.$ where $\chi^{0}$ is $L^{\infty}$ weak ${ }^{\star}$ limit of the characteristic function of the perforated domain). We complete our study by giving two applications, one to the classical periodic case and the second one to a non-periodic one.


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## 1 Introduction

The main goal of this work is to give, in the framework of the $H^{0}$-convergence notion (the generalization of the $H$-convergence to perforated domains), a general homogenization result of a type of quasilinear equations with a mixed Neumann-Dirichlet boundary conditions, beyond the periodic setting. More precisely, we study the asymptotic behaviour of the solution of the following problem:

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{\varepsilon}\left(\cdot, u^{\varepsilon}\right) \nabla u^{\varepsilon}\right)=f \text { in } \Omega \backslash T_{\varepsilon}, \\
A^{\varepsilon}\left(\cdot, u^{\varepsilon}\right) \nabla u^{\varepsilon} \cdot v=0 \text { on } \partial T_{\varepsilon}, \\
u^{\varepsilon}=0 \text { on } \partial \Omega,
\end{array}\right.
$$

where $\Omega$ is a bounded open subset of $\mathbb{R}^{n},\left\{T_{\varepsilon}\right\}$ is sequence of compact subsets of $\Omega$, not necessarily periodically distributed, and where $f \in L^{2}(\Omega), A^{\varepsilon}:(x, d) \in(\Omega, \mathbb{R}) \longmapsto A^{\varepsilon}(x, t) \in \mathbb{R}^{n \times n}$ is a sequence of Caratheodory functions uniformly coercive, uniformly bounded and uniformly equicontinuous matrix fields in the variable $d$. We show that, under a suitable conditions on the equicontinuity modulus and $L^{p}$-estimate assumption, there exists a subsequence of $\varepsilon$ (still denoted by $\varepsilon$ ), a positive function $\chi^{0} \in L^{\infty}(\Omega)$ and a matrix field $A^{0}(\cdot, \cdot)$ which satisfies the same properties as $A^{\epsilon}(\cdot, \cdot)$ such that $\chi^{\varepsilon} \rightharpoonup \chi^{0}$ weakly ${ }^{\star}$ in $L^{\infty}(\Omega)$,

$$
\left(A^{\varepsilon}(\cdot, d), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} A^{0}(\cdot, d) \quad \text { in } \Omega, \forall d \in \mathbb{R}^{n},
$$

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and, if we denote by $\sim$ the extension by 0 from $\Omega_{\varepsilon}$ to $\Omega$, we have

$$
\left\{\begin{array}{l}
\tilde{u^{\varepsilon}} \vec{\sim} \chi^{0} u^{0} \text { weakly in } L^{2}(\Omega) \\
A^{\varepsilon} \widetilde{\left(u^{\varepsilon}\right) \nabla} u^{\varepsilon} \rightharpoonup A^{0}\left(u^{0}\right) \nabla u^{0} \text { weakly in } L^{2}(\Omega)^{n}
\end{array}\right.
$$

where $u^{0}$ is the solution of

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{0}\left(\cdot, u^{0}\right) \nabla u^{0}\right)=\chi^{0} f \text { in } \Omega \\
u^{0}=0 \text { on } \partial \Omega
\end{array}\right.
$$

We complete our study by giving two applications of the established compactness results. The first application is for the classical periodic case, where the obtained result coincides (in our framework) with a result given in [7]. While, the second one which concerns a non-periodic case introduced in [5] is an original result.

Our work generalizes that of Murat-Bocardo given in [4] which treated in the general framework of H convergence the same type of quasilinear equations in fixed domains without holes. The periodic case with Lipschitz continuous coefficients was subsequently processed by Artola-Duvaut in [1]. On the other hand, for periodically perforated domains, the same type of quasilinear equations was firstly studied in Bendib [2] and Bendib-Tcheugoué Teboué [3], with Lipschitz continuous coefficients and linear Robin conditions. After this Cabarrubias-Donato have studied in [7] this equation with a nonlinear Robin condition boundary of the holes and the module of equicontinuity satisfies a suitable assumption introduced by Chipot in [9], but not assumed to be Lipschitz continuous. For the homogenization of other type of Neumann quasilinear equations in perforated domains with data satisfying a general assumptions of abstract homogenization, see for example $[8,13]$ among others.

This article is organized as follows: Sect. 2 is devoted to some preliminary results on the $H^{0}$-convergence as introduced by [5]. This notion generalizes that of $H$-convergence in fixed domains due to Murat-Tartar (see $[12,14]$ ). We give at the end of this section, a new result about a pointwise estimate of the dierence of two $H^{0}$-limits. In Sect. 3, we present our main compactness results for a class of quasilinear equations in perforated domains in the general framework of $H^{0}$-convergence. Section 4 is devoted to the proofs of our results. Finally, in Sect. 5, we give two applications of the obtained compactness results, namely the classical periodic case and a certain non-periodic case.

## 2 Notations and preliminary results

### 2.1 Notations

- $\{\varepsilon\}$ denotes a strictly decreasing sequence converging to zero,
- if $\zeta=\left(\zeta_{i}\right)_{1 \leq i \leq n}$ and $\xi=\left(\xi_{i}\right)_{1 \leq i \leq n}$ are two vectors, we set

$$
\zeta \cdot \xi=\sum_{i=1}^{n} \zeta_{i} \xi_{i} \quad \text { and } \quad|\xi|=\left(\sum_{i=1}^{n} \xi_{i}^{2}\right)^{\frac{1}{2}}
$$

- for matrix $A$ in $R^{n \times n}$, we set

$$
|A|=\sup \left\{|A \xi| \text { s.t. }|\xi|=1 \text { and } \xi \in \mathbb{R}^{n}\right\}
$$

- $\chi_{\mathcal{O}}$ denotes the characteristic function of a subset $\mathcal{O}$ of $\mathbb{R}^{n}$,
- for two real numbers $\alpha$ and $\beta$ such that $0<\alpha<\beta, M(\alpha, \beta ; \Omega)$ is the set of the matrix fields $A=$ $\left(A_{i j}\right)_{1 \leq i, j \leq n}$ defined on $\Omega$ such that almost everywhere in $\Omega$, we have

$$
\left\{\begin{array}{l}
\text { (i) } A_{i j} \in L^{\infty}(\Omega), \text { for } i, j=1, \ldots, n, \\
\text { (ii) } \alpha|\xi|^{2} \leq A \xi \cdot \xi, \text { for } \xi \in \mathbb{R}^{n}, \\
\text { (iii) } A^{-1} \xi \cdot \xi \geq \beta^{-1}|\xi|^{2}, \text { for } \xi \in \mathbb{R}^{n} .
\end{array}\right.
$$

2.2 Preliminary results on the H -convergence for perforated domains

Since we work in the framework of the $H^{0}$-convergence, we recall in this subsection some preliminary results about this notion and we give at the end a useful new result on the pointwise estimate of the dierence of two $H^{0}$-limits.

We introduce the perforated domain by

$$
\Omega_{\varepsilon}=\Omega \backslash T_{\varepsilon},
$$

where $\left\{T_{\varepsilon}\right\}$ is a sequence of compact subsets of $\Omega$ and set

$$
V_{\varepsilon}=\left\{v \in H^{1}\left(\Omega_{\varepsilon}\right) \text { s.t. } v=0 \text { on } \partial \Omega\right\} .
$$

We denote by $\sim$ the extension by 0 from $\Omega_{\varepsilon}$ to $\Omega$ and set $\chi^{\varepsilon}=\chi_{\Omega_{\varepsilon}}$. In the following $v$ denotes the outward normal unit vector to the boundary of $\Omega_{\varepsilon}$.

Definition 2.1 ([5]) The sequence $\left\{T_{\varepsilon}\right\}$ is said to be admissible (in $\Omega$ ) if i) every $L^{\infty}$ weak * limit point of $\left\{\chi^{\varepsilon}\right\}$ is positive almost everywhere in $\Omega$, ii) there exists a positive real $C$, independent of $\varepsilon$, and a sequence $\left\{P_{\varepsilon}\right\}$ of linear extension operators such that for each $\varepsilon$

$$
\left\{\begin{array}{l}
P_{\varepsilon} \in \mathcal{L}\left(V_{\varepsilon}, H_{0}^{1}(\Omega)\right), \\
\left(P_{\varepsilon} v\right)_{\mid \Omega_{\varepsilon}}=v, \quad \forall v \in V_{\varepsilon}, \\
\left\|\nabla P_{\varepsilon} v\right\|_{L^{2}(\Omega)^{n}} \leq C\|\nabla v\|_{L^{2}\left(\Omega_{\varepsilon}\right)^{n}}, \quad \forall v \in V_{\varepsilon} .
\end{array}\right.
$$

We denote by $P_{\varepsilon}^{\star}$ the adjoint operator of $P_{\varepsilon}$, which is defined from $H^{-1}(\Omega)$ to $V_{\varepsilon}^{\prime}$ (dual of $V_{\varepsilon}$ ) with $P_{\varepsilon}^{\star}$ given for every $g \in H^{-1}(\Omega)$ by

$$
\forall v \in V_{\varepsilon},\left\langle P_{\varepsilon}^{\star} g, v\right\rangle_{V_{\varepsilon}^{\prime}, V_{\varepsilon}}=\left\langle g, P_{\varepsilon} v\right\rangle_{H^{-1}(\Omega), H_{0}^{1}(\Omega)} .
$$

Definition 2.2 ([5]) Let $A^{\varepsilon} \in M(\alpha, \beta ; \Omega)$ and $T_{\varepsilon}$ be admissible in $\Omega$. We say that the pair ( $A^{\varepsilon}, T_{\varepsilon}$ ) $H^{0}{ }^{0}$ converges to the matrix $A^{0} \in M\left(\alpha^{\prime}, \beta^{\prime} ; \Omega\right)$ and we write $\left(A^{\varepsilon}, T_{\varepsilon}\right) \xrightarrow{H^{0}} A^{0}$ in $\Omega$ if and only if for every function $g$ of $L^{2}(\Omega)$, and every subsequence of $\varepsilon$ (still denoted by $\varepsilon$ ) such that $\chi^{\varepsilon} \rightharpoonup \chi^{0}$ weakly * in $L^{\infty}(\Omega)$ ( $\chi^{0}$ depending upon the subsequence), the solution $v^{\varepsilon}$ of

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{\varepsilon} \nabla v^{\varepsilon}\right)=g \text { in } \Omega_{\varepsilon},  \tag{2.1}\\
\left(A^{\varepsilon} \nabla v^{\varepsilon}\right) \cdot v=0 \text { on } \partial T_{\varepsilon}, \\
v^{\varepsilon}=0 \text { on } \partial \Omega,
\end{array}\right.
$$

satisfies the weak convergence

$$
\left\{\begin{array}{l}
\text { i) } P_{\varepsilon}\left(v^{\varepsilon}\right) \rightharpoonup v^{0} \text { weakly in } H_{0}^{1}(\Omega),  \tag{2.2}\\
\text { ii) } A^{\varepsilon} \nabla v^{\varepsilon} \\
A^{0} \nabla v^{0} \text { weakly in } L^{2}(\Omega)^{n},
\end{array}\right.
$$

where $v^{0}$ is the unique solution of the problem

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{0} \nabla v^{0}\right)=\chi^{0} g \text { in } \Omega,  \tag{2.3}\\
v^{0}=0 \text { on } \partial \Omega .
\end{array}\right.
$$

Remark 2.3 (1) In [5] the definition of $H^{0}$-convergence is given for $f \in H^{-1}(\Omega)$. This latter and Definition 2.2 are equivalent in view of [5, Theorem 1.5].
(2) In the case of $T_{\varepsilon}=\emptyset$, this definition reduces to the definition of $H$-convergence.

The main properties of the $H^{0}$-convergence are given by the results below.
Theorem 2.4 (Compactness [5]) Let $A^{\varepsilon} \in M(\alpha, \beta ; \Omega)$ and $T_{\varepsilon}$ be admissible in $\Omega$. Then, there exists a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\}$ ) and a matrix $A^{0} \in M\left(\frac{\alpha}{C^{2}}, \beta ; \Omega\right)$ such that $\left\{\left(A^{\varepsilon}, T_{\varepsilon}\right)\right\} H^{0}$-converges to $A^{0}$.
Proposition 2.5 [5] The pair $\left(A^{\varepsilon}, T_{\varepsilon}\right) H^{0}$-converges to $A^{0}$ if and only if $\left({ }^{t} A^{\varepsilon}, T_{\varepsilon}\right) H^{0}$-converges to ${ }^{t} A^{0}$.


Finally, we complete the preliminary results by giving a pointwise estimate of the dierence of two $H^{0}$-limits. This result needs the following lemma (which is a directly consequence of [5, Proposition 1.14]):

Lemma 2.6 Assume that $\left(A^{\varepsilon}, T_{\varepsilon}\right) \xrightarrow{H^{0}} A^{0}$ in $\Omega$ and suppose that for every $\lambda \in \mathbb{R}^{n \times n}$, there exists a sequence $\left\{v_{\lambda}^{\varepsilon}\right\}$ bounded in $H^{1}(\Omega)$ such that

Then, if we set

$$
\begin{equation*}
N^{\varepsilon} \lambda=\nabla v_{\lambda}^{\varepsilon}, \forall \lambda \in \mathbb{R}^{n}, \tag{2.5}
\end{equation*}
$$

we will have $\chi^{\varepsilon} A^{\varepsilon} N^{\varepsilon} \rightarrow A^{0} \lambda$ weakly in $L^{2}(\Omega)^{n}$ and $N^{\varepsilon}$ is a corrector for the pair $\left(A^{\varepsilon}, T_{\varepsilon}\right)$ in the sense that

$$
\lim _{\varepsilon \rightarrow 0}\left\|\nabla v^{\varepsilon}-N^{\varepsilon} v^{0}\right\|_{L^{1}\left(\Omega_{\varepsilon}\right)^{n}}=0,
$$

where $v^{\varepsilon}$ and $v^{0}$ are solutions of (2.1) and (2.3) respectively.
We are now able to give a pointwise estimate of the dierence of two $H^{0}$-limits.
Theorem 2.7 Let $T_{\varepsilon}^{1}$ and $T_{\varepsilon}^{2}$ be admissible in $\Omega, A_{1}^{\varepsilon} \in \mathcal{M}(\alpha, \beta ; \Omega)$ and $A_{2}^{\varepsilon} \in \mathcal{M}\left(\alpha^{\prime}, \beta^{\prime} ; \Omega\right)$ such that

$$
\left\{\begin{array}{l}
\left(A_{1}^{\varepsilon}, T_{\varepsilon}^{1}\right) \xrightarrow{H^{0}} A_{1}^{0} \text { in } \Omega, \\
\left(A_{2}^{\varepsilon}, T_{\varepsilon}^{2}\right) \xrightarrow{H^{0}} A_{2}^{0} \text { in } \Omega, \\
\chi_{2}^{\varepsilon}\left|A_{1}^{\varepsilon}(x)-A_{2}^{\varepsilon}(x)\right| \leq h^{\varepsilon}(x) \text { a.e. in } \Omega, \\
\text { with } h^{\varepsilon} \longrightarrow h^{0} \text { strongly in } L^{1}(\Omega) .
\end{array}\right.
$$

Assume that
(i) $\chi_{1}^{\varepsilon}-\chi_{2}^{\varepsilon} \rightarrow 0$ strongly in $L^{1}(\Omega)$,
(ii) $\left(A_{1}^{\varepsilon}, T_{\varepsilon}^{1}\right)$ admits a corrector satisfying (2.4)-(2.5),
(iii) $\left(A_{2}^{\varepsilon}, T_{\varepsilon}^{2}\right)$ admits a corrector $N^{\varepsilon}$ satisfying (2.4)-(2.5) and

$$
\left\{\begin{array}{l}
\exists p>2, \text { such that }\left\|N^{\varepsilon}\right\|_{L^{p}\left(\Omega, \Omega^{n \times n}\right.} \leq \rho, \\
\text { with } \rho>0 \text { is independent of } \varepsilon .
\end{array}\right.
$$

Then,

$$
\begin{equation*}
\left|A_{1}^{0}-A_{2}^{0}\right| \leq \sqrt{\frac{\beta \beta^{\prime}}{\alpha \alpha^{\prime}}} h^{0} \quad \text { a.e. in } \Omega . \tag{2.6}
\end{equation*}
$$

Proof The proof is obtained by using Lemma 2.6 and Proposition 2.5 , and by following the same techniques used to prove a similar result given for the elasticity case in [11, Theorem 28].

## Remark 2.8 Assumptions

(i)-(iii) of Theorem 2.7 are reasonable. Indeed,
-(i) is obviously satisfied when $T_{\varepsilon}^{1}=T_{\varepsilon}^{2}$ for every $\varepsilon$,
-(ii) is satisfied when there exists a bounded domain $O$ in $\mathbb{R}^{n}$ in which $\Omega$ is relatively compact and for which $T_{\varepsilon}$ is admissible (see the proof of [5, Proposition 1.15]),
-(iii) is satisfied for the classical periodic case and also for the non-periodic case considered in [5].


## 3 Statement of compactness results

In this section, we give our compactness results for the $H^{0}$-convergence of a class of elliptic and uniformly equicontinuous operators in perforated domains. Firstly, we introduce the set $\mathcal{M}_{\text {Equi }}(\alpha, \beta, \omega ; \Omega)$ in the following definition :
Definition 3.1 For two real numbers $\alpha, \beta$ such that $0<\alpha<\beta$ and $\omega$ a function defined from $\mathbb{R}^{+}$to $\mathbb{R}^{+}$ nondecreasing and continuous at $0, \mathcal{M}_{\text {Equi }}(\alpha, \beta, \omega ; \Omega)$ denotes the set of all Caratheodory functions

$$
A:(x, d) \in(\Omega, \mathbb{R}) \longmapsto A(x, d) \in \mathbb{R}^{n \times n}
$$

satisfying the following assumptions:
(i) for every $d \in \mathbb{R}, \quad A(d) \doteq A(\cdot, d) \in \mathcal{M}(\alpha, \beta ; \Omega)$,
(ii) for almost every $x$ in $\Omega$ and for every $d, d^{\prime} \in \mathbb{R}$, one has

$$
\left|A(x, d)-A\left(x, d^{\prime}\right)\right| \leq \omega\left(\left|d-d^{\prime}\right|\right) .
$$

Our first main result is the following:
Theorem 3.2 Let $\left\{T_{\varepsilon}\right\}$ be a sequence admissible in $\Omega$ and $\left\{A^{\varepsilon}\right\}$ be a sequence of elements of $\mathcal{M}_{E q u i}(\alpha, \beta, \omega ; \Omega)$. Assume that $\omega(0)=0$ and

$$
\left\{\begin{array}{l}
\forall d \in \mathbb{R}, \exists p>2 \text { s.t. }\left(A^{\varepsilon}(d), T_{\varepsilon}\right) \text { admits a corrector which } \\
\text { satisfies (2.4)-(2.5) and is bounded in } L^{p}(\Omega) \text { independently of } \varepsilon . \tag{3.1}
\end{array}\right.
$$

Then, there exists a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\})$, and an element $A^{0} \in \mathcal{M}_{\text {Equi }}\left(\frac{\alpha}{C^{2}}, \beta, \frac{\beta}{\alpha} \omega ; \Omega\right)$ such that

$$
\begin{equation*}
\left(A^{\varepsilon}(d), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} A^{0}(d) \text { in } \Omega, \forall d \in \mathbb{R} . \tag{3.2}
\end{equation*}
$$

Moreover, if we suppose that there exists a bounded domain $O$ in $\mathbb{R}^{n}$ in which $\Omega$ is relatively compact and for which $T_{\varepsilon}$ is also admissible, we have

$$
\begin{equation*}
\left(A^{\varepsilon}(v), T_{\varepsilon}\right) \stackrel{H^{0}}{\longrightarrow} A^{0}(v) \text { in } \Omega, \forall v \in L^{1}(\Omega) . \tag{3.3}
\end{equation*}
$$

Remark 3.3 (i) A similar property to (3.2) is given in [14] in the case of fixed domain when the mapping $d \rightarrow A^{\varepsilon}(\cdot, d)$ is of class $C^{k}$ (or real analytic) from an open set $D$ of $\mathbb{R}^{p}$ into $L^{\infty}\left(\Omega ; L\left(\mathbb{R}^{n} ; \mathbb{R}^{n}\right)\right.$ ) for every $p \in \mathbb{N}^{*}$.
(ii) Theorem 3.2 still holds if $d \in \mathbb{R}^{p}$ and $v \in L^{1}(\Omega)^{p}$ for every $p \in \mathbb{N}^{*}$.

As a consequence of Theorem 3.2, we obtained a general homogenization result for some quasilinear equations in perforated domain beyond periodic setting.

Theorem 3.4 Let $\left\{T_{\varepsilon}\right\}$ be a sequence admissible in $\Omega$ and suppose that there exists a bounded domain $O$ in $\mathbb{R}^{n}$ in which $\Omega$ is relatively compact and for which $T_{\varepsilon}$ is also admissible. Let $\left\{A^{\varepsilon}\right\}$ be a sequence in $\mathcal{M}_{\text {Equi }}(\alpha, \beta, \omega ; \Omega)$ which satisfies (3.1). Assume that $\omega$ is continuous with $\omega(d)>0 \forall d>0$ and

$$
\begin{equation*}
\text { for any } r>0, \quad \lim _{s \rightarrow 0} \int_{s}^{r} \frac{\mathrm{~d} t}{\omega(t)}=+\infty . \tag{3.4}
\end{equation*}
$$

Then, there exists subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\}$ ) with $\chi^{\varepsilon}$ converges to a some $\chi^{0}$ weakly * in $L^{\infty}(\Omega)$, such that for every function $f$ of $L^{2}(\Omega)$, the (unique) solution $u^{\varepsilon}$ of the problem:

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon}\right)=f \text { in } \Omega_{\varepsilon},  \tag{3.5}\\
A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon} \cdot v=0 \text { on } \partial T_{\varepsilon}, \\
u^{\varepsilon}=0 \text { on } \partial \Omega,
\end{array}\right.
$$

satisfies

$$
\left\{\begin{array}{l}
\text { (i) } P_{\varepsilon}\left(u^{\varepsilon}\right) \rightharpoonup u^{0} \text { weakly in } H_{0}^{1}(\Omega),  \tag{3.6}\\
\text { (ii) } \widetilde{u^{\varepsilon}} \rightharpoonup \chi^{0} u^{0} \text { weakly in } L^{2}(\Omega), \\
\text { (iii) } A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon} \rightharpoonup A^{0}\left(u^{0}\right) \nabla u^{0} \text { weakly in } L^{2}(\Omega)^{n},
\end{array}\right.
$$

where $u^{0}$ is the (unique) solution of

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{0}\left(u^{0}\right) \nabla u^{0}\right)=\chi^{0} f \quad \text { in } \Omega  \tag{3.7}\\
u^{0}=0 \text { on } \partial \Omega
\end{array}\right.
$$

with $A^{0}$ the family of matrices given by Theorem 3.2.
Remark 3.5 Assumption (3.4) introduced initially in [9] implies that $\lim _{d \rightarrow 0} \omega(d)=0$. If this assumption is replaced by just the fact that $\lim _{d \rightarrow 0} \omega(d)=0$, the uniqueness will no longer be guaranteed for the solutions of (3.5) and (3.7).

## 4 Proofs of compactness results

We give in this section the proofs of our main results. The proofs are an adaptation of the similar ones given in [4] for fixed domains.

Proof of Theorem 3.2 We give the proof in two steps.
Step 1. Let us prove that there exists $A^{0} \in \mathcal{M}_{E q u i}\left(\frac{\alpha}{C^{2}}, \beta, \frac{\beta}{\alpha} \omega ; \Omega\right)$ which satisfies convergence (3.2) up to subsequence. Using Theorem 2.4 and the diagonal subsequence procedure, we extract a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\}$ ) such that, for every $d \in \mathbb{Q}$, we will have

$$
\begin{equation*}
\left(A^{\varepsilon}(d), T_{\varepsilon}\right) H^{0} \text {-converges to a limit } A^{0}(d) \in \mathcal{M}\left(\frac{\alpha}{C^{2}}, \beta ; \Omega\right) \tag{4.1}
\end{equation*}
$$

Hence, by the fact that $A^{\varepsilon} \in \mathcal{M}_{E q u i}(\alpha, \beta, \omega ; \Omega)$, Assumption (3.1) and Theorem 2.7, we obtain

$$
\left|A^{0}(x, d)-A^{0}\left(x, d^{\prime}\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|d-d^{\prime}\right|\right) \quad \text { a.e. } x \in \Omega, \forall d, d^{\prime} \in \mathbb{Q}
$$

Thus, the mapping

$$
\begin{aligned}
A^{0}: \mathbb{Q} & \longrightarrow \mathbb{L}^{\infty}(\Omega)^{n \times n} \\
d & \longmapsto A^{0}(d)
\end{aligned}
$$

is uniformly continuous. Hence, it is extensible to a mapping (denoted again by $A^{0}$ ) defined and uniformly continuous on all $\mathbb{R}$ (since $\mathbb{Q}$ is dense in $\mathbb{R}$ ), namely

$$
\begin{equation*}
\left|A^{0}(x, d)-A^{0}\left(x, d^{\prime}\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|d-d^{\prime}\right|\right), \quad \text { a.e. } x \in \Omega, \forall d, d^{\prime} \in \mathbb{R} \tag{4.2}
\end{equation*}
$$

On the other hand, let $d \in \mathbb{R}$ and $\left\{d_{m}\right\}$ be a sequence in $\mathbb{Q}$ which converges to $d$ as $m \rightarrow \infty$. Thanks to Theorem 2.4, there exists a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\}$ ) such that

$$
\begin{equation*}
\left(A^{\varepsilon}(d), T_{\varepsilon}\right) H^{0} \text {-converges to some } A \in \mathcal{M}\left(\frac{\alpha}{C^{2}}, \beta ; \Omega\right) \tag{4.3}
\end{equation*}
$$

Since, for every $\varepsilon>0$, we have

$$
\left|A^{\varepsilon}(x, d)-A^{\varepsilon}\left(x, d_{m}\right)\right| \leq \omega\left(\left|d-d_{m}\right|\right), \quad \text { a.e. } x \in \Omega
$$

then from this, (4.1), (4.3), Assumption (3.1) and Theorem 2.7, it comes

$$
\left|A(x)-A^{0}\left(x, d_{m}\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|d-d_{m}\right|\right), \quad \text { a.e. } x \in \Omega
$$

This, with (4.2) and by the triangle inequality, we deduce that for almost every $x$ in $\Omega$

$$
\begin{aligned}
\left|A(x)-A^{0}(x, d)\right| & \leq\left|A(x)-A^{0}\left(x, d_{m}\right)\right|+\left|A^{0}(x, d)-A^{0}\left(x, d_{m}\right)\right| \\
& \leq 2 \frac{\beta}{\alpha} \omega\left(\left|d-d_{m}\right|\right)
\end{aligned}
$$

Using the continuity of $\omega$ at 0 , passing to the limit in this inequality as $m \rightarrow \infty$, we find

$$
A(x)=A^{0}(x, d), \quad \text { a.e. } x \in \Omega .
$$

Step 2. We now show property (3.3). Let $v \in L^{1}(\Omega)$. Then, $A^{\varepsilon}(v(\cdot)) \doteq A^{\varepsilon}(\cdot, v(\cdot))$ belongs to $\mathcal{M}(\alpha, \beta ; \Omega)$. Hence, taking into account Theorem 2.4, there exists $B^{0} \in \mathcal{M}\left(\frac{\alpha}{C^{2}}, \beta ; \Omega\right)$ such that to up a subsequence, we have

$$
\begin{equation*}
\left(A^{\varepsilon}(v), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} B^{0} . \tag{4.4}
\end{equation*}
$$

On the other hand, since $v \in L^{1}(\Omega)$, there exists a sequence of step functions $\left\{v^{m}\right\}$ such that $v^{m} \rightarrow v$ strongly in $L^{1}(\Omega)$, and $v^{m}$ is of the form

$$
\begin{equation*}
v^{m}=\sum_{i=1}^{i=k} l_{i}^{m} \chi_{Y_{i}}, \quad \text { a.e. in } \Omega, \tag{4.5}
\end{equation*}
$$

where $\left\{Y_{i}\right\}_{1 \leq i \leq k}$ is a family of disjoint rectangles of $\mathbb{R}^{n}$ included in $\Omega$ and $l_{i}^{m}$ real constants. Set

$$
\left\{\begin{array}{l}
Y_{0}=\Omega \backslash \cup \underset{1 \leq i \leq k}{\cup} \overline{Y_{i}}, \\
\chi_{i}=\chi_{Y_{i}} \\
\chi_{0}=\chi_{Y_{0}} .
\end{array}\right.
$$

We have

$$
\left\{\begin{array}{l}
\forall i \in\{1, \ldots, k\},\left|A^{\varepsilon}(x, v(x))-A^{\varepsilon}\left(x, l_{i}^{m}\right)\right| \leq \omega\left(\left|v(x)-l_{i}^{m}\right|\right) \quad \text { a.e. in } \Omega,  \tag{4.6}\\
\left|A^{\varepsilon}(x, v(x))-A^{\varepsilon}(x, 0)\right| \leq \omega(|v(x)-0|) \text { a.e. in } \Omega,
\end{array}\right.
$$

and (3.2) gives

$$
\left\{\begin{array}{l}
A^{\varepsilon}\left(l_{i}^{m}, T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} A^{0}\left(l_{i}^{m}\right),  \tag{4.7}\\
A^{\varepsilon}\left((0), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} A^{0}(0) .
\end{array}\right.
$$

Hence, using (4.4), (4.6), (4.7), Assumption (3.1), point (ii) of Remark 2.8 and by Theorem 2.7, we obtain

$$
\left\{\begin{array}{l}
\forall i \in\{1, \ldots, k\},\left|B^{0}(x)-A^{0}\left(x, l_{i}^{m}\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|v(x)-l_{i}^{m}\right|\right) \quad \text { a.e. in } \Omega, \\
\left|B^{0}(x)-A^{0}(x, 0)\right| \leq \frac{\beta}{\alpha} \omega(|v(x)-0|) \quad \text { a.e. in } \Omega,
\end{array}\right.
$$

which implies that for almost every $x$ in $\Omega$

$$
\begin{aligned}
\left|B^{0}(x)-A^{0}\left(x, v^{m}\right)\right| & =\left|B^{0}(x)-\sum_{i=1}^{i=k} A^{0}\left(x, l_{i}^{m}\right) \chi_{i}(x)+A^{0}(x, 0) \chi_{0}(x)\right| \\
& \leq \sum_{i=1}^{i=k} \chi_{i}(x) \frac{\beta}{\alpha} \omega\left(\left|v(x)-l_{i}^{m}\right|\right)+\chi_{0}(x) \frac{\beta}{\alpha} \omega(|v(x)-0|) \\
& =\frac{\beta}{\alpha} \omega\left(\left|v(x)-v^{m}(x)\right|\right) .
\end{aligned}
$$

Moreover, thanks to (4.2), we have

$$
\left|A^{0}(x, v(x))-A^{0}\left(x, v^{m}(x)\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|v(x)-v^{m}(x)\right|\right) \quad \text { a.e. in } \Omega \text {. }
$$

Hence, from this two latter inequalities, it follows from triangle inequality that

$$
\begin{aligned}
\left|B^{0}(x)-A^{0}(x, v(x))\right| & \leq\left|B^{0}(x)-A^{0}\left(x, v^{m}(x)\right)\right|+\left|A^{0}\left(x, v^{m}(x)\right)-A^{0}(x, v(x))\right| \\
& \leq 2 \frac{\beta}{\alpha} \omega\left(\left|v(x)-v^{m}(x)\right|\right) \quad \text { a.e. in } \Omega .
\end{aligned}
$$

Since $\omega$ is continuous at 0 , passing to the limit in this inequality when $m \rightarrow \infty$, one obtains

$$
B^{0}(x)=A^{0}(x, v(x)) \text { a.e. in } \Omega,
$$

which, with (4.4), gives (3.3).
Proof of Theorem 3.4 First, note that problem (3.5) (respect. (3.7) has a unique solution in $H_{0}^{1}\left(\Omega_{\varepsilon}\right)$ (respect. $\left.H_{0}^{1}(\Omega)\right)$ thanks to [6].

Second, taking $u^{\varepsilon}$ as a test function in the variational formulation of (3.5), we obtain

$$
\left\|P_{\varepsilon} u^{\varepsilon}\right\|_{H_{0}^{1}(\Omega)} \leq C\left\|u^{\varepsilon}\right\|_{H_{0}^{1}\left(\Omega_{\varepsilon}\right)} \leq \frac{C}{\alpha}\|f\|_{L^{2}(\Omega \varepsilon)} .
$$

Hence, we can extract a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\}$ ), such that

$$
P_{\varepsilon} u^{\varepsilon} \rightharpoonup u^{0} \text { weakly in } H_{0}^{1}(\Omega),
$$

hence

$$
P_{\varepsilon} u^{\varepsilon} \rightarrow u^{0} \text { strongly in } L^{2}(\Omega) .
$$

This implies, for every $m$, that

$$
P_{\varepsilon} u^{\varepsilon}-v^{m} \rightarrow u^{0}-v^{m} \quad \text { strongly in } L^{2}(\Omega),
$$

where $\left\{v^{m}\right\}$ is a sequence of functions introduced in (4.5) such that $v^{m} \rightarrow u^{0}$ strongly in $L^{1}(\mathbb{R})$. So, thanks to continuity of $\omega$, we get

$$
\begin{equation*}
\omega\left(\left|P_{\varepsilon} u^{\varepsilon}-v^{m}\right|\right) \rightarrow \omega\left(\left|u^{0}-v^{m}\right|\right) \quad \text { strongly in } L^{1}(\Omega) . \tag{4.8}
\end{equation*}
$$

On the other hand, since $A^{\varepsilon}\left(P_{\varepsilon} u^{\varepsilon}\right) \doteq A^{\varepsilon}\left(\cdot, P_{\varepsilon} u^{\varepsilon}(\cdot)\right) \in \mathcal{M}(\alpha, \beta ; \Omega)$, there exists a subsequence of $\{\varepsilon\}$ (still denoted by $\{\varepsilon\})$ and $C^{0} \in \mathcal{M}\left(\frac{\alpha}{C^{2}}, \beta ; \Omega\right)$, such that

$$
\begin{equation*}
\left(A^{\varepsilon}\left(P_{\varepsilon} u^{\varepsilon}\right), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} C^{0}, \tag{4.9}
\end{equation*}
$$

but

$$
\forall \varepsilon>0,\left|A^{\varepsilon}\left(x, P_{\varepsilon} u^{\varepsilon}(x)\right)-A^{\varepsilon}\left(x, v^{m}(x)\right)\right| \leq \omega\left(\left|P_{\varepsilon} u^{\varepsilon}(x)-v^{m}(x)\right|\right) \text {, a.e. in } \Omega \text {, }
$$

hence by this last inequality, (4.8), (4.9), Theorem 3.2, Assumption (3.1), point (ii) of Remark 2.8 and Theorem 2.7, it comes

$$
\left|C^{0}(x)-A^{0}\left(x, v^{m}(x)\right)\right| \leq \frac{\beta}{\alpha} \omega\left(\left|u^{0}(x)-v^{m}(x)\right|\right), \text { a.e. in } \Omega .
$$

This gives

$$
\begin{aligned}
\left|C^{0}(x)-A^{0}\left(x, u^{0}(x)\right)\right| & \leq\left|C^{0}(x)-A^{0}\left(x, v^{m}(x)\right)\right|+\left|A^{0}\left(x, v^{m}(x)\right)-A^{0}\left(x, u^{0}(x)\right)\right| \\
& \leq 2 \frac{\beta}{\alpha} \omega\left(\left|u^{0}(x)-v^{m}(x)\right|\right) \quad \text { a.e. in } \Omega .
\end{aligned}
$$

Since $\lim _{d \rightarrow 0} \omega(d)=0$, passing to the limit in this inequality when $m \rightarrow \infty$, we obtain

$$
C^{0}(x)=A^{0}\left(x, u^{0}(x)\right) \quad \text { a.e. in } \Omega .
$$

Then, from this and (4.9), we find

$$
\left(A^{\varepsilon}\left(P_{\varepsilon} u^{\varepsilon}\right), T_{\varepsilon}\right) \stackrel{H^{0}}{\sim} A^{0}\left(\cdot, u^{0}(\cdot)\right),
$$

which implies by the definition of the $H^{0}$-convergence and the uniqueness of the solutions of (3.5) and (3.7) that

$$
\left\{\begin{array}{l}
P_{\varepsilon} u^{\varepsilon} \rightharpoonup u^{0} \text { weakly in } H_{0}^{1}(\Omega) \\
A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon} \rightharpoonup A^{0}\left(u^{0}\right) \nabla u^{0} \text { weakly in } L^{2}(\Omega)^{n}
\end{array}\right.
$$

where $u^{0}$ is the solution of (3.7), which completes proof of (i) and (iii) of (3.6).
Finally, we deduce (3.6)ii) from the fact that

$$
\chi^{\varepsilon} \rightharpoonup \chi^{0} \text { weakly }^{\star} \text { in } L^{\infty}(\Omega)
$$

and

$$
P_{\varepsilon} u^{\varepsilon} \rightarrow u^{0} \text { strongly in } L^{2}(\Omega)
$$

## 5 Applications

As an application of our results, we consider the classical periodic case and a non-periodic case.
Let $\theta$ a diffeomorphism of class $C^{2}$ from $\mathbb{R}^{n}$ onto $\mathbb{R}^{n}$ and introduce the holes $T_{\varepsilon}$ defined by

$$
\left\{\begin{array}{l}
T_{\varepsilon}=\cup_{k \in \mathbb{Z}^{n}}\left\{S_{\varepsilon}^{k} \text { s.t. } S_{\varepsilon}^{k} \subset \Omega, \operatorname{dist}(\theta(k \varepsilon), \partial \Omega)>2 \varepsilon\right\}, \\
\text { with } S_{\varepsilon}^{k}=\left\{x \in \mathbb{R}^{n} \text { s.t. }|x-\theta(k \varepsilon)| \leq \delta \varepsilon\right\}, k \in \mathbb{Z}^{n},
\end{array}\right.
$$

where $\delta \in] 0,1]$. Let $Y=\left[-\frac{1}{2}, \frac{1}{2}\right]^{n}$ and set

$$
\left.A^{\varepsilon}(x, d)\right)=A\left(\frac{\theta^{-1}(x)}{\varepsilon}\right)
$$

with $A \in \mathcal{M}_{\text {Equi }}(\alpha, \beta, \omega ; Y)$. Assume that $\omega$ is continous with $\omega(d)>0 \forall d>0$ and

$$
\text { for any } r>0, \quad \lim _{s \rightarrow 0} \int_{s}^{r} \frac{\mathrm{~d} t}{\omega(t)}=+\infty
$$

In what follows, the spherical geometry of the holes can be generalized to the case where a regular boundary hole with a finite number of connected components replace a ball.

### 5.1 Classical periodic case

Take here $\theta=I d_{\mathbb{R}^{n}}$ and $\delta=\frac{1}{3}$. Then, the pair $\left(A^{\varepsilon}(\cdot, \cdot), T_{\varepsilon}\right)$ satisfies all assumptions of Theorem 3.4 and it is well-known that in this case (see [10])

$$
\left\{\begin{array}{l}
\forall d \in \mathbb{R},\left(A^{\varepsilon}(\cdot, d), T_{\varepsilon}\right) \stackrel{H^{0}}{\rightharpoonup} A^{0}(d), \\
\chi^{\varepsilon} \rightharpoonup \frac{\left|Y^{*}\right|}{|Y|} \text { weakly }{ }^{\star} \text { in } L^{\infty}(\Omega),
\end{array}\right.
$$

with $A^{0}(d)$ is independent of $x$ and given by

$$
\begin{equation*}
\forall \lambda \in \mathbb{R}^{n}, \quad A^{0}(d) \lambda=\frac{1}{|Y|} \int_{Y^{\star}} A(y, d) \nabla_{y} v_{\lambda}(y, d) \mathrm{d} y, \tag{5.1}
\end{equation*}
$$

where

$$
Y^{*}=Y \backslash T, \quad T=\left\{x \in \mathbb{R}^{n} \quad \text { s.t. }|x| \leq \frac{1}{3}\right\}
$$

and for all $\lambda \in \mathbb{R}^{n}, y \longmapsto v_{\lambda}(y, d)$ be the solution of

$$
\left\{\begin{array}{l}
\left.-\operatorname{div}\left(A(y, d) \nabla v_{\lambda}(y, d)\right)\right)=0 \text { in } Y^{\star} \\
\left(A(y, d) \nabla v_{\lambda}(y, d) \nabla u^{\varepsilon} \cdot v=0 \text { on } \partial T\right. \\
v_{\lambda}(y, d)-\lambda \cdot y \text { is } Y-\text { periodic with mean value } 0 .
\end{array}\right.
$$

In this framework, we have the following result about the convergence of problem (3.5):
Proposition 5.1 For every $f \in L^{2}(\Omega)$, the solution $u^{\varepsilon}$ of problem (3.5) satisfies

$$
\left\{\begin{array}{l}
\text { (i) } P_{\varepsilon}\left(u^{\varepsilon}\right) \rightharpoonup u^{0} \text { weakly in } H_{0}^{1}(\Omega), \\
\text { (ii) } u^{\varepsilon} \rightharpoonup \chi^{0} u^{0} \quad \text { weakly in } L^{2}(\Omega), \\
\text { (iii) } A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon} \rightharpoonup A^{0}\left(u^{0}\right) \nabla u^{0} \quad \text { weakly in } L^{2}(\Omega)^{n}
\end{array}\right.
$$

where $u^{0}$ is the solution of

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(A^{0}\left(u^{0}\right) \nabla u^{0}\right)=\chi^{0} f \quad \text { in } \Omega \\
u^{0}=0 \text { on } \partial \Omega
\end{array}\right.
$$

and where $A^{0}$ defined by (5.1) belongs to $\mathcal{M}_{E q u i}\left(\frac{\alpha}{C^{2}}, \beta, \frac{\beta}{\alpha} \omega ; \Omega\right)$.
Remark 5.2 In the geometric framework of this example, Proposition 5.1 coincides with a result given in [7] by using the periodic unfolding, when the nonlinear Robin boundary condition on the holes reduces to the homogeneous Neumann condition.

### 5.2 Non-periodic case

Consider here the non-periodic perforated domain introduced in [5, Section 3] when studying the corresponding linear case. We suppose that $\theta^{-1}$ has a Lipschitz constant $\kappa^{-1}$ with $\kappa>2$ and take $\delta=1$. In this case, from [5, Sections 3-4], we deduce easily that for every $d \in \mathbb{R}$, the pair $\left(A^{\varepsilon}, T_{\varepsilon}\right)$ satisfies all assumptions of Theorem 3.4 and

$$
\left\{\begin{array}{l}
\left.\forall d \in \mathbb{R},\left(A^{\varepsilon}(\cdot, d), T_{\varepsilon}\right)\right) \stackrel{H^{0}}{\rightharpoonup} A^{0}(\cdot, d) \text { in } \Omega, \\
\chi^{\varepsilon}(\cdot) \rightharpoonup \frac{\left|Y^{*}(\cdot)\right|}{|Y(\cdot)|} \text { weakly }{ }^{\star} \text { in } L^{\infty}(\Omega),
\end{array}\right.
$$

with

$$
A^{0}(x, d)=B_{x}^{0}(d)
$$

where $B_{x}^{0}(d)$ is defined by

$$
\begin{equation*}
\forall \lambda \in \mathbb{R}^{n}, \quad B_{x}^{0}(d) \lambda=\frac{1}{|Y(x)|} \int_{Y(x)^{\star}} B(x, y, d) \nabla_{y} v_{\lambda}(x, y, d) \mathrm{d} y \tag{5.2}
\end{equation*}
$$

and where we have

$$
\left\{\begin{array}{l}
B(x, y, d)=A\left(\left[\nabla \theta\left(\theta^{-1}(x)\right)\right]^{-1} y, d\right) \\
Y(x)=\left\{\nabla \theta\left(\theta^{-1}(x)\right) z \quad \text { s.t. } z \in Y\right\} \\
T_{1}=\left\{z \in \mathbb{R}^{n} \quad \text { s.t. }|z| \leq 1\right\} \\
Y(x)^{\star}=Y(x) \backslash T_{1}
\end{array}\right.
$$

and for all $\lambda \in \mathbb{R}^{n}, y \longmapsto v_{\lambda}(x, y, d)$ be the solution of

$$
\left\{\begin{array}{l}
\left.-\operatorname{div}\left(B(x, y, d) \nabla v_{\lambda}(x, y, d)\right)\right)=0 \text { in } Y(x)^{\star} \\
\left(B(x, y, d) \nabla v_{\lambda}(x, y, d) \cdot v=0 \text { on } \partial T_{1}\right. \\
v_{\lambda}(x, y, d)-\lambda \cdot y \text { is } Y(x)-\text { periodic with mean value } 0 .
\end{array}\right.
$$

In this framework, we have the following result about the convergence of problem (3.5):

Proposition 5.3 For every $f \in L^{2}(\Omega)$, the solution $u^{\varepsilon}$ of problem (3.5) satisfies

$$
\left\{\begin{array}{l}
\text { (i) } P_{\varepsilon}\left(u^{\varepsilon}\right) \rightharpoonup u^{0} \text { weakly in } H_{0}^{1}(\Omega), \\
\text { (ii) } u^{\varepsilon} \rightharpoonup \chi^{0} u^{0} \text { weakly in } L^{2}(\Omega), \\
\text { (iii) } A^{\varepsilon}\left(u^{\varepsilon}\right) \nabla u^{\varepsilon} \rightharpoonup B_{x}^{0}\left(u^{0}\right) \nabla u^{0} \text { weakly in } L^{2}(\Omega)^{n},
\end{array}\right.
$$

where $u^{0}$ is the solution of

$$
\left\{\begin{array}{l}
-\operatorname{div}\left(B_{x}^{0}\left(u^{0}(x)\right) \nabla u^{0}(x)\right)=\frac{\left|Y^{*}(x)\right|}{|Y(x)|} f(x) \quad \text { in } \Omega \\
u^{0}(x)=0 \text { on } \partial \Omega
\end{array}\right.
$$

and where $(x, d) \mapsto B_{x}^{0}(d)$ defined by (5.2) belongs to $\mathcal{M}_{\text {Equi }}\left(\frac{\alpha}{C^{2}}, \beta, \frac{\beta}{\alpha} \omega ; \Omega\right)$.

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