



Retraction Note to: Robot acquisition, control and interfacing using multimodal feedback

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Retraction Note to:
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The Editor-in-Chief and the publisher have retracted this article. This article was submitted to be part of a guest-edited issue. An investigation concluded that the editorial process of this guest-edited issue was compromised by a third party and that the peer review process has been manipulated.

Based on the investigation's findings the Editor-in-Chief therefore no longer has confidence in the results and conclusions of this article.

The authors have not responded to correspondence regarding this retraction.

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The original article can be found online at <https://doi.org/10.1007/s12652-020-01738-0>.

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