ORIGINAL RESEARCH



Threshold Dynamics of an SEIS Epidemic Model with Nonlinear Incidence Rates

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Accepted: 4 September 2021 / Published online: 15 September 2021 © Foundation for Scientific Research and Technological Innovation 2021

Abstract

In this paper, we consider an *SEIS* epidemic model with infectious force in latent and infected period, which incorporates by nonlinear incidence rates. The local stability of the equilibria is discussed. By means of *Lyapunov* functionals and *LaSalle's* invariance principle, we proved the global asymptotic stability of the disease-free equilibrium and the endemic equilibrium. An application is given and numerical simulation results based on real data of COVID-19 in Morocco are performed to justify theoretical findings.

Keywords SEIS epidemic model · COVID-19 · Latent period · Local stability · Global stability

Introduction

In our life there are various infectious diseases that we face, such as coronavirus (COVID-19) that was first identified in the Chinese city of Wuhan in 2019, and it is a new strain that has not been previously identified in humans. COVID-19 is a fatal illness caused by a severe acute respiratory syndrome that is transmitted from human-to-human [1]. In epidemiology, mathematical models describing the population dynamics of infectious diseases plays an important role in analyzing the spread and controlling these diseases.

Some diseases, such as tuberculosis, measles, AIDS, COVID-19, have a latent or incubation period when a susceptible has become infected but not yet infectious. COVID-19, for example, has about 5-6 days latent period [2]. This latency can be modeled by introducing a new class, called the exposed class, in which the susceptible remains for a given length of time before moving into the infective class. The resulting models are of *SEI*, *SEIR*, *SEIR*, *SEIRS*, or *SEIRI* type (here, *S*, *E*, *I* and *R* denote the numbers of susceptible, exposed, infectious and recovered individuals, respectively), see, e.g., [3-8].

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In many diseases the infection is not only in the infected period but even in the latent period, such as COVID-19 at present [9]. Many epidemic models with the infectious force in the latent period have been performed. Yuang et al. in [10] considered the local stability of an epidemic model having infectious force in both latent period and infected period. Guihua and Zhen [11, 12] studied the global stability of an *SEI* epidemic model with standard incidence rate having infectious force in both latent period and infected period. Global stability of an *SEIS* epidemic model with standard incidence rate having infectious force in both latent period and infected period and infected period given by Mukhopadhyay and Bhattacharyya [13]. The method used in [11–13] for proving global asymptotic stability of epidemic equilibrium is based on the geometric approaches developed by Smith [14], Li and Muldowney [15].

The incidence of a disease is the number of new cases per unit time and plays an important role in the modelling of epidemic dynamics. In many epidemic models, the bilinear incidence rate βSI (β denote the transmission rate, which measures the infection force of the disease) [16, 17] and the standard incidence rate $\frac{\beta SI}{N}$, where N is the total population size [18], are frequently used. However, the bilinear incidence rate may face many problems and challenges when it is used to describe the evolution of infectious diseases among human. Consequently, the bilinear incidence rate should be modified into a nonlinear incidence rate which play a vital role in ensuring that the model can give a reasonable qualitative description of the capture the nonlinear nature of disease propagation law. Initially, Capasso and Serio [19] in the study of the cholera epidemic spread in Bari in 1973, observed that the incidence rate may increase more slowly as I increases rather than linearly increasing, and found the saturated incidence rate $\frac{\beta SI}{M}$ which gives good agreement with observations, where the parameter α measures the inhibitory effect either due to the crowding caused by high numbers of cases or from the behavioral change of susceptible individuals as their number increases. From then on, a number of authors have studied epidemiological models with several nonlinear incidence rates, see, e.g., [20-26].

In this paper we will consider an *SEIS* epidemic model with general incidence rates that the diseases such as COVID-19 can be infected in the latent period and the infected period. Hence, our study will be carried out on the following epidemic model:

$$\begin{cases} \frac{dS(t)}{dt} = \Lambda - \mu S(t) - S(t)f_1(I(t)) - S(t)f_2(E(t)) + \gamma I(t), \\ \frac{dE(t)}{dt} = S(t)f_1(I(t)) + S(t)f_2(E(t)) - (\mu + \sigma)E(t), \\ \frac{dI(t)}{dt} = \sigma E(t) - (\mu + \delta + \gamma)I(t), \end{cases}$$
(1)

where Λ is the recruitment rate of the susceptible, μ is the natural death rate of the population, σ is the transfer rate from the exposed group to the infectious group so that $\frac{1}{\sigma}$ is the mean latent period, δ is the death rate due to disease, γ is the transfer rate from the infectious group to the susceptible group. In this work, we assume that δ and γ are nonnegative constants, and Λ , μ , and σ are positive constants.

To study the dynamics of the model (1), we suppose that the functions $f_i(i = 1, 2)$ are continuously differentiable on $[0, +\infty)$ satisfying the following two hypotheses.

(H1) $f_i(x)$ is strictly monotone increasing on $[0, +\infty)$ with $f_i(0) = 0$. (H2) $\frac{f_i(x)}{x}$ is monotone decreasing on $(0, +\infty)$. The hypothesis (*H*1) is a basic requirement for any biologically feasible incidence rate, since it is obvious that the disease cannot spread when the number of exposed and infected individuals is zero. In addition, the incidence $Sf_1(I)$ (resp., $Sf_2(E)$) becomes faster as the number of the infectious (resp., exposed) individuals increases.

Since the incidence $Sf_1(I)$ (resp., $Sf_2(E)$) can be rewritten as $\frac{f_1(I)}{I}SI$ (resp., $\frac{f_2(E)}{E}SE$). Then, function $\frac{f_1(I)}{I}$ (resp., $\frac{f_2(E)}{E}$) refers to effective contact rate between an infective (resp., exposed) and a susceptible individuals. The hypothesis (H2) implies that the effective contact rate between infective (resp., exposed) and susceptible individuals is decreasing with increase of infectives since the individuals tend to reduce the number of contacts among them per unit time when they are under intervention policies. The idea of hypothesis (H2) has first been explored in [19].

By the hypotheses (H1)-(H2), it can be seen that f_i satisfying

$$0 < \frac{f_i(x)}{x} \le f'_i(0) \text{ for all } x > 0,$$
 (2)

and consequently, the effective contact rates are bounded.

The functions f_i (i = 1, 2) includes a number of especial incidence rates. For instance:

 $\begin{array}{ll} 1. & f_i(x) = \frac{\beta_i x}{1 + \alpha_i x^{p_i}}, \alpha_i \geq 0, \, 0 < p_i \leq 1 \, [27]. \\ 2. & f_i(x) = \left(\beta_i - \frac{\sigma_i x}{m_i + x}\right) x, \, \beta_i > \sigma_i, m_i > 0 \, [28, \, 29]. \end{array}$

On the positivity and boundedness of solutions, we have the following result. Since the proof is simple, we here omit it.

Proposition 1 Let (S(t), E(t), I(t)) be any solution of system (1) with any nonnegative initial condition, then $S(t) \ge 0$, $E(t) \ge 0$ and $I(t) \ge 0$ for all $t \ge 0$. In addition, we have $\limsup_{t \to +\infty} (S(t) + E(t) + I(t)) \le \frac{\Lambda}{\mu}$.

The rest of this paper is organized as follows. In the next section, we discuss the existence and the local stability of the equilibria. In Section 3, by using *Lyapunov* functionals and *LaSalle's* invariance principle, we establish the global asymptotic stability of the equilibria. An application and illustrative numerical simulations have been given in Section 4, and the numerical results of real data of COVID-19 in Morocco is conducted in the same section. Finally, conclusion is given in Section 5.

Equilibria and Their Local Stability

In this section, we discuss the existence and the local stability of the equilibria of system (1). It is easy to visualize that the system (1) always has a disease-free equilibrium $E_0 = (S_0, 0, 0)$, where $S_0 = \frac{\Lambda}{\mu}$, that is, there is no infection present in the population and all individuals are susceptible.

By applying the next generation matrix approach provided by van den Driessche and Watmough [30], the basic reproduction number of model (1) is defined as follows

$$R_0 = S_0 \frac{\sigma f_1'(0) + \omega_2 f_2'(0)}{\omega_1 \omega_2},$$

where $\omega_1 = \mu + \sigma$ and $\omega_2 = \mu + \delta + \gamma$. Biologically, R_0 represents the average number of secondary infectious cases produced by an exposed individual and an infectious individual during their effective infectious period when introduced in a completely susceptible population [31].

Now, we obtain the following lemma which gives the result on the unique existence of the endemic equilibrium E_* for $R_0 > 1$.

Lemma 1 System (1) has a unique positive endemic equilibrium $E_* = (S^*, E^*, I^*)$ if and only if $R_0 > 1$.

Proof Assume that $R_0 > 1$. Suppose that (S, E, I) is any positive equilibrium of system (1), then

$$\begin{cases} \Lambda - \mu S - Sf_1(I) - Sf_2(E) + \gamma I = 0, \\ Sf_1(I) + Sf_2(E) - \omega_1 E = 0, \\ \sigma E - \omega_2 I = 0. \end{cases}$$
(3)

From the third equation of system (3), we have

$$E = \frac{\omega_2}{\sigma} I, \tag{4}$$

and by summing all equations of system (3), we find that

$$S = \frac{\Lambda - \phi I}{\mu},\tag{5}$$

where $\phi = \frac{\mu\omega_2}{\sigma} + \mu + \delta$. We have $S \ge 0$ implies that $I \in \left(0, \frac{\Lambda}{\phi}\right]$. Hence, no positive equilibrium exists if $I \ge \frac{\Lambda}{\phi}$. On the other hand, by the second equation of (3) and equation (4), it follows that

$$S = \frac{\omega_1 \omega_2}{\sigma} \frac{1}{\frac{f_1(I)}{I} + \frac{f_2\left(\frac{\omega_2}{\sigma}I\right)}{I}}.$$
(6)

Then, by equations (5) and (6), I is a positive zero of the function F, where

$$F(I) = \Lambda - \phi I - \frac{\mu \omega_1 \omega_2}{\sigma} \frac{1}{\frac{f_1(I)}{I} + \frac{f_2\left(\frac{\omega_2}{\sigma}I\right)}{I}}, \ I \in \left(0, \frac{\Lambda}{\phi}\right].$$

By the hypothesis (H2), the function F is strictly monotone decreasing on $\left(0, \frac{\Lambda}{\phi}\right)$ satisfying

$$\lim_{I \to 0^+} F(I) = \Lambda - \frac{\mu \omega_1 \omega_2}{\sigma} \frac{1}{f_1'(0) + \frac{\omega_2}{\sigma} f_2'(0)} = \Lambda \left(1 - \frac{1}{R_0}\right) > 0,$$

and $F(\frac{\Lambda}{\phi}) < 0$. Hence, there is a unique $I^* \in \left(0, \frac{\Lambda}{\phi}\right)$ such that $F(I^*) = 0$ if $R_0 > 1$. This shows that model (1) has a unique positive endemic equilibrium $E_* = (S^*, E^*, I^*)$ when

 $R_0 > 1$, where E^* and S^* are determined by (4) and (5), respectively. Second we assume $R_0 \le 1$. Then it is obvious that system (1) has no endemic equilibria. Hence the proof is complete.

Next, we focus on the local stability of the disease-free equilibrium E_0 . The Jacobian matrix of system (1) at the equilibrium E_0 is as follows

$$J_{E_0} = \begin{pmatrix} -\mu & -S_0 f'_2(0) & -S_0 f'_1(0) + \gamma \\ 0 & S_0 f'_2(0) - \omega_1 & S_0 f'_1(0) \\ 0 & \sigma & -\omega_2 \end{pmatrix}.$$

Clearly, $\lambda_1 = -\mu < 0$ is a eigenvalue of J_{E_0} . The other two eigenvalues of J_{E_0} are determined by the following equation

$$\lambda^{2} + (\omega_{1} + \omega_{2} - S_{0}f_{2}'(0))\lambda + \omega_{1}\omega_{2} - S_{0}(\sigma f_{1}'(0) + \omega_{2}f_{2}'(0)) = 0.$$

If $R_0 < 1$, one immediately gets $\omega_1 \omega_2 - S_0 (\sigma f'_1(0) + \omega_2 f'_2(0)) = \omega_1 \omega_2 (1 - R_0) > 0$, and by the expression of R_0 , we have $S_0 f'_2(0) < \omega_1$, then $\omega_1 + \omega_2 - S_0 f'_2(0) > 0$. Thus, by the *Routh-Hurwitz* criterion, the eigenvalues λ_j (j = 2, 3) of J_{E_0} have negative real part if $R_0 < 1$. If $R_0 > 1$, then $\omega_1 \omega_2 - S_0 (\sigma f'_1(0) + \omega_2 f'_2(0)) < 0$, and this suggests that J_{E_0} admits a positive real eigenvalue. Consequently, we have the following result.

Theorem 1 If $R_0 < 1$, then the disease-free equilibrium E_0 is locally asymptotically stable. E_0 is unstable if $R_0 > 1$.

Now, we analyze the local stability of the endemic equilibrium of the system (1) by assuming that $R_0 > 1$. The *Jacobian* matrix of system (1) at the equilibrium E_* is as follows

$$J_{E_*} = \begin{pmatrix} -\mu - f_1(I^*) - f_2(E^*) & -S^* f_2'(E^*) & -S^* f_1'(I^*) + \gamma \\ f_1(I^*) + f_2(E^*) & S^* f_2'(E^*) - \omega_1 & S^* f_1'(I^*) \\ 0 & \sigma & -\omega_2 \end{pmatrix}.$$

Therefore, its characteristic equation at E_* is

$$\lambda^{3} + C_{2}\lambda^{2} + C_{1}\lambda + C_{0} = 0, \tag{7}$$

where

$$\begin{split} C_2 &= \mu + \omega_2 + f_1(I^*) + \frac{S^*}{E^*} f_1(I^*) + f_2(E^*) + S^* \left(\frac{f_2(E^*)}{E^*} - f_2'(E^*) \right), \\ C_1 &= \left(\omega_1 + \omega_2 \right) \left(f_1(I^*) + f_2(E^*) \right) + \mu \left(\omega_2 + S^* \left(\frac{f_2(E^*)}{E^*} - f_2'(E^*) \right) \right) + \sigma S^* \left(\frac{f_1(I^*)}{I^*} - f_1'(I^*) \right) \\ &+ \omega_2 S^* \left(\frac{f_2(E^*)}{E^*} - f_2'(E^*) \right), \\ C_0 &= \left(\omega_1 \omega_2 - \sigma \gamma \right) \left(f_1(I^*) + f_2(E^*) \right) + \mu \sigma S^* \left(\frac{f_1(I^*)}{I^*} - f_1'(I^*) \right) + \mu \omega_2 S^* \left(\frac{f_2(E^*)}{E^*} - f_2'(E^*) \right). \end{split}$$

By (H2), $\frac{f_i(x)}{x}$ is decreasing on $(0, +\infty)$, so $\left(\frac{f_i(x)}{x}\right)' \leq 0$, which implies that $\frac{f_i(x)}{x} - f'_i(x) \geq 0$ for all x > 0. Further, we have $\omega_1 \omega_2 - \sigma \gamma = \mu(\mu + \delta + \gamma) + \sigma(\mu + \delta) > 0$. Then it is easy to show that $C_2 > 0$, $C_1 > 0$, $C_0 > 0$ and $C_2C_1 > C_0$. Thus, by the *Routh-Hurwitz* criterion, all roots λ_j (j = 1, 2, 3) of (7) have negative real part. Hence, we have the following theorem.

Theorem 2 When $R_0 > 1$, the endemic equilibrium E_* is locally asymptotically stable.

Global Stability

The aim of this section is to analyze the global stability of the equilibria. First, we consider the global stability of model (1) at the disease-free equilibrium E_0 .

Theorem 3 If $R_0 \leq 1$, then the disease-free equilibrium E_0 is globally asymptotically stable.

Proof Let U be the Lyapunov functional defined as

$$U(t) = U_0(t) + U_1(t),$$

where

$$\begin{split} U_0(t) &= S_0 g\left(\frac{S}{S_0}\right) + E + \frac{\omega_1 f_1'(0)}{\sigma f_1'(0) + \omega_2 f_2'(0)} I,\\ U_1(t) &= \frac{\gamma}{\sigma S_0} \frac{I^2}{2} + \frac{\gamma}{(2\mu + \delta) S_0} \frac{\left(S - S_0 + E + I\right)^2}{2},\\ g(x) &= x - 1 - \ln x, \ x > 0. \end{split}$$

The derivatives of functions U_0 and U_1 along the solution of system (1) are

$$\begin{split} \frac{dU_0}{dt} &= \left(1 - \frac{S_0}{S}\right) \left(\Lambda - \mu S - Sf_1(I) - Sf_2(E) + \gamma I\right) + \left(Sf_1(I) + Sf_2(E) - \omega_1 E\right) \\ &+ \frac{\omega_1 f_1'(0)}{\sigma f_1'(0) + \omega_2 f_2'(0)} \left(\sigma E - \omega_2 I\right) \\ &= \frac{-\mu \left(S - S_0\right)^2}{S} + \left(f_1(I) + f_2(E)\right) S_0 \\ &- \frac{\omega_1 \omega_2}{\sigma f_1'(0) + \omega_2 f_2'(0)} \left(f_1'(0)I + f_2'(0)E\right) + \gamma I \left(1 - \frac{S_0}{S}\right), \end{split}$$

and

$$\begin{split} \frac{dU_1}{dt} &= \frac{\gamma}{\sigma S_0} I \left(\sigma E - \omega_2 I \right) + \frac{\gamma}{(2\mu + \delta)S_0} \left(-\mu (S - S_0 + E)^2 - (\mu + \delta)I^2 - (2\mu + \delta)I \left(S - S_0 \right) - (2\mu + \delta)EI \right) \\ &= -\frac{\gamma}{S_0} \left(\frac{\omega_2}{\sigma} + \frac{\mu + \delta}{2\mu + \delta} \right) I^2 - \frac{\mu\gamma}{(2\mu + \delta)S_0} (S - S_0 + E)^2 - \gamma I \left(\frac{S}{S_0} - 1 \right). \end{split}$$

Then

$$\begin{aligned} \frac{dU}{dt} &= \frac{-\mu \left(S - S_0\right)^2}{S} - \frac{\gamma}{S_0} \left(\frac{\omega_2}{\sigma} + \frac{\mu + \delta}{2\mu + \delta}\right) I^2 - \frac{\mu \gamma}{(2\mu + \delta)S_0} (S - S_0 + E)^2 - \gamma I \frac{\left(S - S_0\right)^2}{SS_0} \\ &+ \left(f_1(I) + f_2(E)\right) S_0 - \frac{\omega_1 \omega_2}{\sigma f_1'(0) + \omega_2 f_2'(0)} \left(f_1'(0)I + f_2'(0)E\right). \end{aligned}$$

According to (2), we have $f_1(I) \le f_1'(0)I$ and $f_2(E) \le f_2'(0)E$. Hence

$$\begin{split} \frac{dU}{dt} &\leq -\frac{\mu S_0 + \gamma I}{SS_0} \big(S - S_0 \big)^2 - \frac{\gamma}{S_0} \left(\frac{\omega_2}{\sigma} + \frac{\mu + \delta}{2\mu + \delta} \right) I^2 \\ &- \frac{\mu \gamma}{(2\mu + \delta)S_0} (S - S_0 + E)^2 + \left(f_1'(0)I + f_2'(0)E \right) S_0 \left(1 - \frac{1}{R_0} \right). \end{split}$$

Therefore, $R_0 \leq 1$ ensures that $\frac{dU}{dt} \leq 0$. Furthermore, it is easy to verify that the singleton $\{E_0\}$ is the largest compact invariant set in $\{(S, E, I) \in \mathbb{R}^3_+ : \frac{dU}{dt} = 0\}$. By LaSalle's invariance principle [32], we get that equilibrium E_0 of system (1) is globally asymptotically stable if $R_0 \leq 1$.

In the following theorem, we study the global stability of the endemic equilibrium E_* .

Theorem 4 Assume that $R_0 > 1$. The endemic equilibrium E_* is globally asymptotically stable if

$$\mu S^* - \gamma I^* \ge 0. \tag{8}$$

Proof Let V be the Lyapunov functional defined as

$$V(t) = V_0(t) + V_1(t),$$

where

$$V_0(t) = S^* g\left(\frac{S}{S^*}\right) + E^* g\left(\frac{E}{E^*}\right) + \frac{S^* f_1(I^*)}{\sigma E^*} I^* g\left(\frac{I}{I^*}\right),$$

and

$$V_1(t) = \frac{\gamma}{\sigma S^*} \frac{(I - I^*)^2}{2} + \frac{\gamma}{(2\mu + \delta)S^*} \frac{(S - S^* + E - E^* + I - I^*)^2}{2}.$$

By means of the equalities

$$\Lambda = \mu S^* + S^* f_1(I^*) + S^* f_2(E^*) - \gamma I^*, \ S^* f_1(I^*) + S^* f_2(E^*) = \omega_1 E^*, \ \omega_2 = \frac{\sigma E^*}{I^*},$$

the derivative of V_0 is

$$\begin{split} \frac{dV_0}{dt} &= \left(1 - \frac{S^*}{S}\right) \left(-\mu \left(S - S^*\right) + S^* f_1(I^*) - Sf_1(I) + S^* f_2(E^*) - Sf_2(E) + \gamma \left(I - I^*\right)\right) \\ &+ \left(1 - \frac{E^*}{E}\right) \left(Sf_1(I) - S^* f_1(I^*) \frac{E}{E^*} + Sf_2(E) - S^* f_2(E^*) \frac{E}{E^*}\right) + S^* f_1(I^*) \left(1 - \frac{I^*}{I}\right) \left(\frac{E}{E^*} - \frac{I}{I^*}\right) \\ &= -\mu \frac{(S - S^*)^2}{S} + S^* f_1(I^*) \left(1 - \frac{S^*}{S} - \frac{Sf_1(I)}{S^* f_1(I^*)} + \frac{f_1(I)}{f_1(I^*)}\right) + S^* f_2(E^*) \left(1 - \frac{S^*}{S} - \frac{Sf_2(E)}{S^* f_2(E^*)} + \frac{f_2(E)}{f_2(E^*)}\right) \\ &+ \gamma \left(I - I^*\right) \left(1 - \frac{S^*}{S}\right) + S^* f_1(I^*) \left(1 - \frac{E}{E^*} - \frac{SE^* f_1(I)}{S^* Ef_1(I^*)} + \frac{Sf_1(I)}{S^* Ef_1(I^*)}\right) \\ &+ S^* f_2(E^*) \left(1 - \frac{E}{E^*} - \frac{SE^* f_2(E)}{S^* Ef_2(E^*)} + \frac{Sf_2(E)}{S^* Ef_1(E^*)}\right) + S^* f_1(I^*) \left(\frac{E}{E^*} - \frac{I}{I^*} - \frac{I^*E}{IE^*} + 1\right) \\ &= -\mu \frac{(S - S^*)^2}{S} + S^* f_1(I^*) \left(3 - \frac{S^*}{S} - \frac{SE^* f_1(I)}{S^* Ef_1(I^*)} - \frac{I}{I^*} - \frac{I^*E}{IE^*} + \frac{f_1(I)}{f_1(I^*)}\right) \\ &+ S^* f_2(E^*) \left(2 - \frac{S^*}{S} - \frac{E}{E^*} - \frac{SE^* f_2(E)}{S^* Ef_2(E^*)} + \frac{f_2(E)}{f_2(E^*)}\right) + \gamma \left(I - I^*\right) \left(1 - \frac{S^*}{S}\right) \\ &= -\mu \frac{(S - S^*)^2}{S} + S^* f_1(I^*) \left(\left(\frac{f_1(I)}{f_1(I^*)} - 1 - \frac{I}{I^*} + \frac{If_1(I^*)}{I^* f_1(I^*)}\right) + \left(4 - \frac{S^*}{S} - \frac{SE^* f_1(I)}{S^* Ef_1(I^*)} - \frac{I^*E}{IE^*} - \frac{If_1(I^*)}{I^* f_1(I)}\right)\right) \\ &+ S^* f_2(E^*) \left(\left(\frac{f_2(E)}{f_2(E^*)} - 1 - \frac{E}{E^*} + \frac{Ef_2(E^*)}{E^* f_2(E^*)}\right) + \left(3 - \frac{S^*}{S} - \frac{SE^* f_2(E)}{S^* Ef_2(E^*)} - \frac{Ef_2(E^*)}{E^* f_2(E^*)}\right)\right) + \gamma \left(I - I^*\right) \left(1 - \frac{S^*}{S}\right) \end{split}$$

The derivative of V_1 is

$$\begin{split} \frac{dV_1}{dt} &= \frac{\gamma}{S^*} \big(I - I^* \big) \big(E - E^* \big) - \frac{\gamma}{\sigma S^*} (\mu + \delta + \gamma) \big(I - I^* \big)^2 + \frac{\gamma}{(2\mu + \delta) S^*} \big(-\mu (S - S^* + E - E^*)^2 \\ &- (\mu + \delta) \big(I - I^* \big)^2 - (2\mu + \delta) \big(S - S^* \big) \big(I - I^* \big) - (2\mu + \delta) \big(I - I^* \big) \big(E - E^* \big) \Big) \\ &= -\frac{\gamma}{\sigma S^*} (\mu + \delta + \gamma) \big(I - I^* \big)^2 - \frac{\mu \gamma}{(2\mu + \delta) S^*} (S - S^* + E - E^*)^2 - \frac{\gamma (\mu + \delta)}{(2\mu + \delta) S^*} \big(I - I^* \big)^2 - \gamma \Big(\frac{S}{S^*} - 1 \Big) \big(I - I^* \big) \\ &= -\frac{\gamma}{S^*} \bigg(\frac{\mu + \delta + \gamma}{\sigma} + \frac{\mu + \delta}{2\mu + \delta} \bigg) \big(I - I^* \big)^2 - \frac{\mu \gamma}{(2\mu + \delta) S^*} (S - S^* + E - E^*)^2 - \gamma \Big(\frac{S}{S^*} - 1 \Big) \big(I - I^* \big). \end{split}$$

Then the sum of these two functions gives

$$\begin{split} \frac{dV}{dt} &= -\left(\left(\mu S^* - \gamma I^*\right) + \gamma I\right) \frac{(S-S^*)^2}{S} - \frac{\gamma}{S^*} \left(\frac{\mu + \delta + \gamma}{\sigma} + \frac{\mu + \delta}{2\mu + \delta}\right) \left(I - I^*\right)^2 - \frac{\mu\gamma}{(2\mu + \delta)S^*} (S - S^* + E - E^*)^2 \\ &+ S^* f_1(I^*) \left(\left(\frac{f_1(I)}{f_1(I^*)} - 1 - \frac{I}{I^*} + \frac{If_1(I^*)}{I^*f_1(I)}\right) + \left(4 - \frac{S^*}{S} - \frac{SE^*f_1(I)}{S^*Ef_1(I^*)} - \frac{I^*E}{IE^*} - \frac{If_1(I^*)}{I^*f_1(I)}\right)\right) \\ &+ S^* f_2(E^*) \left(\left(\frac{f_2(E)}{f_2(E^*)} - 1 - \frac{E}{E^*} + \frac{Ef_2(E^*)}{E^*f_2(E)}\right) + \left(3 - \frac{S^*}{S} - \frac{SE^*f_2(E)}{S^*Ef_2(E^*)} - \frac{Ef_2(E^*)}{E^*f_2(E)}\right)\right). \end{split}$$

By the hypotheses (H1) and (H2), we obtain

$$\frac{f_1(I)}{f_1(I^*)} - 1 - \frac{I}{I^*} + \frac{If_1(I^*)}{I^*f_1(I)} = \frac{1}{I^*} \left(\frac{I^*}{f_1(I^*)} - \frac{I}{f_1(I)}\right) \left(f_1(I) - f_1(I^*)\right) \le 0,$$

$$\frac{f_2(E)}{f_2(E^*)} - 1 - \frac{E}{E^*} + \frac{Ef_2(E^*)}{E^*f_2(E)} = \frac{1}{E^*} \left(\frac{E^*}{f_2(E^*)} - \frac{E}{f_2(E)}\right) \left(f_2(E) - f_2(E^*)\right) \le 0,$$

and using the arithmetic-geometric inequality, we have

$$\begin{split} 4 &- \frac{S^*}{S} - \frac{SE^*f_1(I)}{S^*Ef_1(I^*)} - \frac{I^*E}{IE^*} - \frac{If_1(I^*)}{I^*f_1(I)} \leq 0, \\ 3 &- \frac{S^*}{S} - \frac{SE^*f_2(E)}{S^*Ef_2(E^*)} - \frac{Ef_2(E^*)}{E^*f_2(E)} \leq 0. \end{split}$$

Hence, the condition (8) ensures that $\frac{dV}{dt} \le 0$. Further, the largest invariant set of $\left\{(S, E, I) \in \mathbb{R}^3_+ : \frac{dV}{dt} = 0\right\}$ is the singleton $\{E_*\}$. By applying the *LaSalle's* invariance principle, we can obtain that the endemic equilibrium E_* of model (1) is globally asymptotically stable if $R_0 > 1$ and $\mu S^* - \gamma I^* \ge 0$.

Remark 1 When $\gamma = 0$, the system (1) reduces to an *SEI* model, and the endemic equilibrium E_* is globally asymptotically stable if $R_0 > 1$.

Corollary 1 For $\gamma > 0$, the endemic equilibrium E_* is globally asymptotically stable if

$$1 < R_0 \le 1 + \frac{\phi}{\gamma},$$

where ϕ given in the proof of Lemma 1.

Proof We prove that the condition (8) in Theorem 4 holds if the condition $R_0 \le 1 + \frac{\phi}{\gamma}$ holds. We have I^* satisfies the following

$$\begin{split} I^* &= \frac{1}{\phi} \left(\Lambda - \frac{\mu \omega_1 \omega_2}{\sigma} \frac{1}{\frac{f_1(I^*)}{I^*} + \frac{f_2\left(\frac{\omega_2}{\sigma}I^*\right)}{I^*}} \right) \leq \frac{1}{\phi} \left(\Lambda - \frac{\mu \omega_1 \omega_2}{\sigma} \frac{1}{f_1'(0) + \frac{\omega_2}{\sigma}f_2'(0)} \right) \\ &= \frac{\mu \omega_1 \omega_2}{\phi \left(\sigma f_1'(0) + \omega_2 f_2'(0) \right)} \left(R_0 - 1 \right). \end{split}$$

Therefore, we obtain that

$$\begin{split} \mu S^* - \gamma I^* &= \frac{\frac{\mu \omega_1 \omega_2 I^*}{\sigma}}{f_1(I^*) + f_2\left(\frac{\omega_2}{\sigma}I^*\right)} - \gamma I^* \\ &= \frac{\frac{\mu \omega_1 \omega_2}{\sigma}I^*}{f_1(I^*) + f_2\left(\frac{\omega_2}{\sigma}I^*\right)} \left(1 - \gamma \frac{\sigma}{\mu \omega_1 \omega_2} \left(f_1(I^*) + f_2\left(\frac{\omega_2}{\sigma}I^*\right)\right)\right) \\ &\geq \frac{\frac{\mu \omega_1 \omega_2}{\sigma}I^*}{f_1(I^*) + f_2\left(\frac{\omega_2}{\sigma}I^*\right)} \left(1 - \gamma \frac{\sigma f_1'(0) + \omega_2 f_2'(0)}{\mu \omega_1 \omega_2}I^*\right) \\ &\geq \frac{\frac{\mu \omega_1 \omega_2}{\sigma}I^*}{f_1(I^*) + f_2\left(\frac{\omega_2}{\sigma}I^*\right)} \left(1 - \frac{\gamma}{\phi}(R_0 - 1)\right), \end{split}$$

which completes the proof.

Application and Numerical Simulations

The main purpose of this section is to give a particular nonlinear incidence rate to illustrate our main results. Consider the system

Parameter	Λ	μ	β_1	β_2	σ	δ	γ	α_1	α2	
Value	130	0.0939	0.00015	0.0002	0.6	0.037	0.8	0.2	0.1	

 Table 1 Parameter values for model (9)

Table 2	Parameter	values for
model ())	

Parameter	Λ	μ	β_1	β_2	σ	δ	γ	α_1	α ₂
Value	130	0.0939	0.001	0.0015	0.6	0.037	0.8	0.2	0.1

$$\begin{cases} \frac{dS(t)}{dt} = \Lambda - \mu S(t) - \frac{\beta_1 S(t)I(t)}{1 + \alpha_1 I(t)} - \frac{\beta_2 S(t)E(t)}{1 + \alpha_2 E(t)} + \gamma I(t), \\ \frac{dE(t)}{dt} = \frac{\beta_1 S(t)I(t)}{1 + \alpha_1 I(t)} + \frac{\beta_2 S(t)E(t)}{1 + \alpha_2 E(t)} - (\mu + \sigma)E(t), \\ \frac{dI(t)}{dt} = \sigma E(t) - (\mu + \delta + \gamma)I(t), \end{cases}$$
(9)

subject to initial conditions

$$S(0) \ge 0, E(0) \ge 0, I(0) \ge 0,$$

where β_1 and β_2 are the rates of the efficient contact in infected period and latent period, respectively. The positive constants α_1 and α_2 measure the saturation or inhibitory effect. The remaining parameters have the same biological significance as those in system (1). Model (9) is a particular case of system (1) by choosing $f_1(I) = \frac{\beta_1 I}{1+\alpha_1 I}$ and $f_2(E) = \frac{\beta_2 E}{1+\alpha_2 E}$.

Obviously, the hypotheses (H1)-(H2) are satisfied. The basic reproduction number of model (9) is

$$R_0 = \frac{\sigma \beta_1 \Lambda}{\mu(\mu + \sigma)(\mu + \delta + \gamma)} + \frac{\beta_2 \Lambda}{\mu(\mu + \sigma)}$$

Now, we give some numerical simulations in order to validate our theoretical results. Firstly, we simulate model (9) with the parameter values as shown in Table 1.

By calculation, we have $R_0 = 0.5919 \le 1$. Hence, by Lemma 1, model (9) has only an disease-free equilibrium $E_0 = (1384.45, 0, 0)$. Fig. 1 shows that the trajectories of S(t), E(t) and I(t), which are the solutions of (9), from different initial values to E_0 . This supports the analytical result obtained in Theorem 3, i.e., the disease-free equilibrium E_0 is globally asymptotically stable provided $R_0 \le 1$. Thus, under the condition $R_0 \le 1$, the disease will be eradicated.

Now, we simulate the case when the basic reproduction number is bigger than one. For this end, we consider model (9) with the parameter values as shown in Table 2.

By computing, we get $R_0 = 4.2787 > 1$ and $\mu S^* - \gamma I^* = 97.0392 \ge 0$. Fig. 2 shows that the trajectories of S(t), E(t) and I(t), which are the solutions of (9), from different initial values to $E_* = (1192.7, 29.0039, 18.6941)$. This confirms the global stability of



Fig. 1 Plot of the time evolution of S(t), E(t) and I(t), which are the solutions of (9). The parameter values are tabulated in Table 1. This plot shows the stability of the disease-free equilibrium E_0 from different values

the endemic equilibrium E_* and thus supports the theoretical result given in Theorem 4, which means that the disease becomes endemic.

Next, we provide a numerical simulation using real data for the transmission of COVID-19 in Morocco during the year 2020 [33]. On 27 October, we have S(0) = 37055403 [34], I(0) = 203733 [33], then we assume E(0) = 400000. Fig. 3 shows that the trajectories of S(t), E(t) and I(t) in the model under investigation (9), for the parameter values as shown in Table 3, converges towards the endemic equilibrium $E_* = (1.9007 \times 10^7, 1.8539 \times 10^6, 2.3607 \times 10^6)$.

In this case, we have the basic reproduction number is greater than unity $R_0 = 1.5159 > 1$ and $\mu S^* - \gamma I^* \ge 0$, which means that the disease persists. In this situation, it will be important to eventually undertake some strategies like quarantine, isolation, wearing of masks, disinfection and if it will be possible vaccination.

Conclusion

This paper presents a mathematical study on the dynamical behavior of an *SEIS* epidemic model with infectivity in incubation period and general incidence rates. From the system, we have found the following basic reproduction number



Fig. 2 Plot of the time evolution of S(t), E(t) and I(t), which are the solutions of (9). The parameter values are tabulated in Table 2. This plot shows the stability of the endemic equilibrium E_* from different values

 Table 3
 Parameter values for model (9)

Parameter	Λ	μ	β_1	β_2	σ	δ	γ	α_1	α2
Value	278.15	0.05861	0.000079	0.0001	0.5	0.017	0.428	0.14	0.145

$$R_0 = \frac{\sigma \Lambda f_1'(0)}{\mu(\mu + \sigma)(\mu + \delta + \gamma)} + \frac{\Lambda f_2'(0)}{\mu(\mu + \sigma)}$$

It determines whether the disease will die out or persist in the population as time increases. We have shown that if $R_0 \leq 1$, the disease-free equilibrium E_0 is globally asymptotically, which means that the disease cannot persist in the population, and the situation is under control. Moreover, we have proved that if $R_0 > 1$, the disease-free equilibrium becomes unstable and the model has an endemic equilibrium E_* which is globally asymptotically stable provided that $\mu S^* \geq \gamma I^*$, so that the disease, if initially present, will be persistent at the unique endemic equilibrium level. An application and some numerical simulations are presented to verify the feasibility of the theoretical results.

We would like to point out here that Theorem 4 leaves us an open problem: whether the endemic equilibrium E_* is globally asymptotically stable when $R_0 > 1$ without the additional condition $\mu S^* - \gamma I^* \ge 0$?. We leave this for future work.



Fig. 3 Plot of the time evolution of S(t), E(t) and I(t), which are the solutions of (9). The parameter values are tabulated in Table 3. This plot shows the dynamics of COVID-19 in Morocco

Declarations

Conflict of Interest The authors declare that they have no competing interests.

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