Erratum

Erratum to: PATH PLANNING FOR VEHICLE ACTIVE COLLISION AVOIDANCE BASED ON VIRTUAL FLOW FIELD

Jian Liu¹⁾, Jie Ji^{1)*}, Yue Ren¹⁾, Yanjun Huang²⁾ and Hong Wang³⁾

¹⁾College of Engineering and Technology, Southwest University, Chongqing 400715, China

²⁾School of Automotive Studies, Tongji University, Shanghai 201804, China

³⁾School of Vehicle and Mobility, Tsinghua University, Beijing 100091, China

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