



Spacelike Mean Curvature Flow

Ben Lambert¹ · Jason D. Lotay²

Received: 16 August 2018 / Published online: 31 August 2019
© The Author(s) 2019

Abstract

We prove long-time existence and convergence results for spacelike solutions to mean curvature flow in the pseudo-Euclidean space $\mathbb{R}^{n,m}$, which are entire or defined on bounded domains and satisfying Neumann or Dirichlet boundary conditions. As an application, we prove long-time existence and convergence of the G_2 -Laplacian flow in cases related to coassociative fibrations.

Keywords Mean curvature flow · G_2 -Laplacian flow · Boundary conditions · Coassociative fibrations

Mathematics Subject Classification 53C50 · 53C44 · 53C10

1 Introduction

Whilst mean curvature flow (MCF) in Euclidean space, particularly in the case of hypersurfaces, has been much studied with many celebrated results, and continues to be a very active area of research, the corresponding MCF in pseudo-Euclidean space $\mathbb{R}^{n,m}$ has received relatively little attention. A simple but important observation is that the condition for an n -dimensional submanifold M of $\mathbb{R}^{n,m}$ to be *spacelike*, in the sense that the ambient quadratic form of signature (n, m) restricts to be a Riemannian metric on M , is preserved by MCF, naturally leading to the notion of spacelike mean curvature flow, whose critical points are called *maximal* submanifolds. Surprisingly, as we shall demonstrate in this article, spacelike MCF is very well-behaved in $\mathbb{R}^{n,m}$ for any $m \geq 1$ (i.e. regardless of the codimension of the flowing spacelike submanifold). This is in marked contrast to the usual mean curvature flow of n -dimensional submanifolds in \mathbb{R}^{n+m} , where the difference between the setting of hypersurfaces (i.e. $m = 1$) and

✉ Ben Lambert
b.lambert@ucl.ac.uk
Jason D. Lotay
jason.lotay@maths.ox.ac.uk

¹ Department of Mathematics, University College London, Gower Street, London WC1E 6BT, UK

² Mathematical Institute, University of Oxford, Woodstock Road, Oxford OX2 6GG, UK

higher codimension submanifolds is significant. We show that spacelike MCF for entire graphs in any codimension always has smooth long-time existence under weak initial assumptions. We also show the same is true for spacelike MCF on bounded domains satisfying the natural Neumann and Dirichlet boundary conditions, where we also get convergence to a maximal submanifold. These results for the boundary value problems are particularly striking in the context of the Dirichlet problem, since it is known that for higher codimension MCF with Dirichlet boundary conditions in Euclidean space one cannot always have convergence by results in [23]. Moreover, our result in the Dirichlet case can be seen as an extension of the very recent work in [25] on the Dirichlet problem for maximal submanifolds in $\mathbb{R}^{n,m}$.

There is a direct, yet surprising, link between spacelike mean curvature flow and Bryant's [5] G_2 -Laplacian flow in 7 dimensions, whose critical points define metrics with exceptional holonomy G_2 (and are thus Ricci-flat). Finding holonomy G_2 metrics is a challenging problem, and the G_2 -Laplacian flow is a potentially powerful and attractive means for tackling it. For a simply connected domain B in \mathbb{R}^3 , spacelike MCF of B in $\mathbb{R}^{3,3}$ is equivalent to the G_2 -Laplacian flow on $Z^7 = B \times T^4$, where the evolving closed G_2 -structure φ is T^4 -invariant and Z is a (trivial) coassociative T^4 -fibration over B . Here, coassociative means the submanifold is calibrated by $*\varphi$, and the aforementioned correspondence is an extension of a result in [2]. Moreover, it follows from work in [9] that spacelike MCF in $\mathbb{R}^{3,19}$ is the *adiabatic limit* of the G_2 -Laplacian flow on Z^7 which is a coassociative K3 fibration: i.e., spacelike MCF appears in the limit as the G_2 -Laplacian flow in this setting as one sends the volume of the coassociative K3 fibres to zero. Coassociative fibrations are expected to play a key role in G_2 geometry, motivated by ideas both from mathematics (e.g. [2,9]) and M-Theory in theoretical physics (e.g. [1,18]).

Despite recent progress in the study of the G_2 -Laplacian flow, it seems difficult in general to obtain long-time existence. By utilizing the link to spacelike MCF, we obtain long-time existence and convergence results for the G_2 -Laplacian flow in settings pertinent to the study of the important topic of coassociative fibrations. These are the first such general results for the G_2 -Laplacian flow without assumptions about closeness to a critical point or curvature bounds along the flow.

1.1 Main Results

Let Ω be a domain in \mathbb{R}^n (which we will often identify with the standard spacelike \mathbb{R}^n in $\mathbb{R}^{n,m}$) and let $\hat{X}_0 : \Omega \rightarrow \mathbb{R}^{n,m}$ be an initial smooth spacelike immersion. We consider unparameterised mean curvature flow starting at \hat{X}_0 : a one-parameter family of immersions, given by $\hat{X} : \Omega \times [0, T) \rightarrow \mathbb{R}^{n,m}$ with

$$\begin{cases} \left(\frac{d\hat{X}}{dt} \right)^\perp = H & \text{on } \Omega \times [0, T), \\ \hat{X}(\cdot, 0) = \hat{X}_0(\cdot) & \text{on } \Omega, \end{cases} \quad (1.1)$$

where H is the mean curvature of M_t , the image of \hat{X} at time t , in $\mathbb{R}^{n,m}$. Locally (in space and time) there exists a parametrisation X of M_t which satisfies the standard mean curvature flow equation:

$$\frac{dX}{dt} = H. \tag{1.2}$$

Since any spacelike submanifold in $\mathbb{R}^{n,m}$ is a graph over a domain in the standard spacelike \mathbb{R}^n , we may consider (1.1) as (locally) equivalent to a parabolic system for graph function $\hat{u} = (\hat{u}^1, \dots, \hat{u}^m) : \Omega \times [0, T) \rightarrow \mathbb{R}^m$ with initial condition \hat{u}_0 (see Appendix A for details):

$$\begin{cases} \frac{d\hat{u}}{dt} - g^{ij}(D\hat{u})D_{ij}^2\hat{u} = 0 & \text{on } \Omega \times [0, T), \\ \hat{u}(\cdot, 0) = \hat{u}_0(\cdot) & \text{on } \Omega, \end{cases} \tag{1.3}$$

for $i, j \in \{1, \dots, n\}$, where g^{ij} is the inverse of the induced metric.

Spacelike mean curvature flow has been studied in codimension 1 by Ecker and Huisken [14], Ecker [11,12] and also Gerhardt [17]. The first author has also worked on boundary conditions for this flow [21,22]. The elliptic counterpart was studied by Bartnik [3] and Bartnik and Simon [4]. For higher codimensions, less is known. The flow of compact manifolds was investigated by Li and Salavessa [24]. The higher codimensional maximal surface equation was recently studied by Li [25].

Entire Graphs

There are several well-known explicit long-time solutions to spacelike MCF. Throughout the article we let $\langle \cdot, \cdot \rangle$ denote the standard quadratic form with signature (n, m) on $\mathbb{R}^{n,m}$ and let $|x|^2 = \langle x, x \rangle$ for $x \in \mathbb{R}^{n,m}$. Recall that $x \neq 0$ is spacelike if $|x|^2 > 0$, lightlike or null if $|x|^2 = 0$ and timelike if $|x|^2 < 0$. The light cone is the set of lightlike vectors.

Example 1.1 (Grim Reaper). The *Grim Reaper* is the unique translating solution to (1.3) in $\mathbb{R}^{1,1}$ (up to translations, dilations and rotations), given by

$$\hat{u}(x, t) = \log \cosh x + t.$$

Example 1.2 (Hyperbolic space). In $\mathbb{R}^{n,1}$,

$$M_t := \{x \in \mathbb{R}^{n,1} \mid |x|^2 = -2nt\}$$

is a self-expander for (1.2) (i.e. $X^\perp = tH$) coming out of the light cone. For each t , M_t is an embedded hyperbolic space in $\mathbb{R}^{n,1}$.

Explicit solutions may be constructed from Examples 1.1 and 1.2 in higher codimension, simply by evolving in $\mathbb{R}^{n,1} \subset \mathbb{R}^{n,m}$.

All the examples described thus far are entire graphs, and so it is natural to study this setting, where we have the following existence theorem.

Theorem 1.3 *Let $\Omega = \mathbb{R}^n$, so the initial spacelike submanifold M_0 is an entire graph. There exists a spacelike solution M_t of mean curvature flow starting at M_0 which is smooth and exists for all $t > 0$. Furthermore, if the mean curvature of M_0 is bounded, then M_t attains the initial data M_0 smoothly as $t \rightarrow 0$.*

See Theorem 5.2 for further details. Notice that we make no assumption on the space-like condition at infinity, so we can start with initial data that asymptotically develops lightlike directions (like the Grim Reaper), and that we obtain long-time existence even without an initial bound on the mean curvature. This theorem is an extension and improvement of the codimension 1 result proven in [11, Theorem 4.2] (see also Remark 4.4).

Remark 1.4 As is to be expected for entire flows we make no statement about uniqueness in Theorem 1.3, and solutions to (1.3) are not unique in general. For example, if we take M_0 to be the Grim Reaper in Example 1.1 at $t = 0$, which is a translating solution, then any solution constructed by our proof of Theorem 1.3 cannot remain a translator (since it would satisfy $|\hat{u}(x, t) - \hat{u}_0(x)| \leq \sqrt{2nt}$).

We also prove results on the qualitative behaviour of entire flows. In Sect. 8 we develop further estimates for entire spacelike MCF in which, in particular, demonstrate the following result.

Proposition 1.5 *There are no shrinking or translating solutions to spacelike MCF with bounded gradient and mean curvature.*

Finally, in Sect. 9 we show that if M_0 is asymptotic to a strictly spacelike cone, then the entire renormalised flow converges subsequentially to a self-expanding solution to MCF, see Theorem 9.2 for full details.

Boundary Conditions

To prove Theorem 1.3, we solve auxiliary problems on compact domains with boundary conditions. In this article we solve for both the Neumann and Dirichlet cases. A key step in the proof of Theorem 1.3 is that quasi-sphere expanders acts as barriers to the flow on compact domains, a notion we now define.

Definition 1.6 (Quasi-sphere expander). A *quasi-sphere expander* with centre p and starting square radius $-R^2$ is given by

$$S_t := \{x \in \mathbb{R}^{n,m} \mid |p - x|^2 = -R^2 - 2nt\}.$$

We define the *inside* of S_t to be

$$I_t := \{x \in \mathbb{R}^{n,m} \mid |p - x|^2 \geq -R^2 - 2nt\}.$$

An expanding quasi-sphere S_t is said to be an *outer barrier* if the property $M_t \subset I_t$ is preserved by the mean curvature flow.

We have the following existence and convergence theorems for mean curvature flow with Neumann and Dirichlet boundary conditions. Here we need the initial submanifold to be uniformly spacelike, i.e. the submanifold does not asymptotically develop lightlike directions at the boundary. We first state the Neumann case.

Theorem 1.7 *Let Ω be a bounded convex domain with smooth boundary and let M_0 be uniformly spacelike satisfying the Neumann boundary condition. There exists a unique spacelike solution M_t of mean curvature flow starting at M_0 satisfying the Neumann boundary condition, which is smooth, exists for all $t > 0$, and converges smoothly to a translate of Ω as $t \rightarrow \infty$. Furthermore, expanding quasi-spheres with centre in $\Omega \times \mathbb{R}^m$ act as outer barriers to the flow.*

See Theorem 6.2 for a more precise statement, including conditions for regularity up to $t = 0$.

For the Dirichlet condition, we require a constraint on the boundary data, which is called *acausal* (see (7.1) for a definition): this condition is necessary on a convex domain to have a spacelike graph with the given boundary data.

Theorem 1.8 *Let Ω be a bounded domain with smooth boundary and let M_0 be uniformly spacelike with acausal boundary. There exists a unique spacelike solution M_t to mean curvature flow starting at M_0 satisfying $\partial M_t = \partial M_0$ which is smooth, exists for all $t > 0$ and converges smoothly to the unique maximal submanifold with boundary ∂M_0 as $t \rightarrow \infty$. Furthermore, expanding quasi-spheres with centre in $\Omega \times \mathbb{R}^m$ act as outer barriers to the flow.*

See Theorem 7.2 for further details and a more precise statement, including conditions for improved regularity up to the initial time. We emphasise that existence and uniqueness of a maximal submanifold with given acausal boundary data, given as a graph on a bounded convex domain, is shown in [25, Theorem 2.1]. Theorem 1.8 extends this result to the MCF setting.

1.2 Applications to G_2 -Laplacian Flow

If we view $\mathbb{R}^7 = \mathbb{R}^3 \times \mathbb{R}^4$ and let (x_1, x_2, x_3) be coordinates on \mathbb{R}^3 and (y_0, y_1, y_2, y_3) be coordinates on \mathbb{R}^4 , we can define a 3-form φ_0 on \mathbb{R}^7 by

$$\varphi_0 = -dx_1 \wedge dx_2 \wedge dx_3 + dx_1 \wedge \omega_1 + dx_2 \wedge \omega_2 + dx_3 \wedge \omega_3, \tag{1.4}$$

where

$$\begin{aligned} \omega_1 &= dy_0 \wedge dy_1 + dy_2 \wedge dy_3, & \omega_2 &= dy_0 \wedge dy_2 + dy_3 \wedge dy_1, \\ \omega_3 &= dy_0 \wedge dy_3 + dy_1 \wedge dy_2. \end{aligned} \tag{1.5}$$

The stabilizer of φ_0 , under the action of $GL(7, \mathbb{R})$, is the exceptional Lie group G_2 . Given an oriented 7-manifold Z^7 , we can define a 3-form φ to be *positive* if at every point $p \in Z$ there exists an orientation preserving isomorphism between $T_p Z$ and \mathbb{R}^7 identifying $\varphi|_p$ with φ_0 . A positive 3-form (which will exist if and only if Z is also spin) naturally defines a principal G_2 -subbundle of the oriented frame bundle of Z ; in other words, a G_2 -structure. We therefore often call a choice of positive 3-form (or simply the 3-form itself) a G_2 -structure.

The interest in G_2 -structures φ comes from the fact that they always define a metric g_φ and an orientation (since $G_2 \subset SO(7)$) and one sees that the holonomy group of g_φ is contained in G_2 when φ is *torsion-free*, which is equivalent to

$$d\varphi = 0 \quad \text{and} \quad d_\varphi^* \varphi = 0. \quad (1.6)$$

It should be noted here that the first equation is linear, whilst the second is nonlinear, since the adjoint d_φ^* of the exterior derivative depends on g_φ and the orientation φ defines. A metric with holonomy contained in G_2 is Ricci-flat, and this is the only known means to obtain non-trivial examples of Ricci-flat metrics in odd dimensions.

Solving the torsion-free conditions (1.6) is very challenging in general, with the only compact examples arising from sophisticated gluing techniques, going back to work of Joyce (see [20]). The key to these methods is the fundamental work of Joyce, which allows one to perturb a closed G_2 -structure (i.e. one with $d\varphi = 0$) which is “close” to torsion-free in a suitable sense, to become torsion-free. As an alternative approach to the problem of solving (1.6), Bryant [5] proposed the following G_2 -Laplacian flow for closed G_2 -structures:

$$\begin{cases} \frac{d\varphi}{dt} = \Delta_\varphi \varphi = (dd_\varphi^* + d_\varphi^* d)\varphi, \\ d\varphi = 0. \end{cases} \quad (1.7)$$

Important foundational results for this flow have been developed [6,27–29] and recent impressive results have been obtained in the special case when $Z^7 = T^3 \times N^4$, where N^4 is compact and the flow is T^3 -invariant [16]. In general, however, there are many unresolved questions concerning the G_2 -Laplacian flow, in particular regarding long-time existence, convergence and the formation of singularities.

Semi-flat Coassociative T^4 -Fibrations

For our applications, we let B be a domain in \mathbb{R}^3 and consider $Z^7 = B \times T^4$, where $T^4 = \mathbb{R}^4/\mathbb{Z}^4$ is the standard flat 4-torus, which we can view as a trivial T^4 -fibration over B . Everything we now describe can be found in [2,9,10].

Recall the model G_2 -structure φ_0 in (1.4). This can equivalently be written as

$$\varphi_0 = -\text{vol}_{\mathbb{R}^3} + d(x_1\omega_1 + x_2\omega_2 + x_3\omega_3).$$

Therefore, to define a G_2 structure on Z we need to find a 2-form on Z to play the role of $x_1\omega_1 + x_2\omega_2 + x_3\omega_3$. Notice that constant 2-forms on T^4 are in one-to-one correspondence with cohomology classes in $H^2(T^4)$. We now observe that the cup product on $H^2(T^4)$ naturally identifies $H^2(T^4)$ with $\mathbb{R}^{3,3}$ via

$$\langle [\alpha], [\beta] \rangle = \int_{T^4} \alpha \wedge \beta.$$

Thus, given an immersion $X : B \rightarrow \mathbb{R}^{3,3} \cong H^2(T^4)$, we have that

$$\frac{\partial X}{\partial x_i} = [\omega_i]$$

for some unique constant 2-forms ω_i . We therefore see that we can write

$$dx_1 \wedge \omega_1 + dx_2 \wedge \omega_2 + dx_3 \wedge \omega_3 = dX.$$

We may then define

$$\varphi = -X^* \text{vol}_{X(B)} + dX. \tag{1.8}$$

It is observed in [9] that the condition for φ in (1.8) to be positive, and thus to define a G_2 -structure, is precisely that $X : B \rightarrow \mathbb{R}^{3,3}$ is spacelike. Notice that at each point p of $X(B)$, the mean curvature H of $X(B)$ in $\mathbb{R}^{3,3} \cong H^2(T^4)$ lies in the orthogonal complement of the maximal positive definite subspace $T_p X(B) = \text{Span}\{[\omega_1], [\omega_2], [\omega_3]\}$, and so $H(p)$ can be identified with an anti-self-dual 2-form on T^4 using the metric determined by the ω_i . Moreover, by construction, $d\varphi = 0$ and one finds from [9, Lemma 6] that

$$d_\varphi^* dX = H, \tag{1.9}$$

where H is identified with a 2-form on Z as described above. Using the formula (1.9), we see that if X satisfies spacelike mean curvature flow (1.2) then φ in (1.8) satisfies the G_2 -Laplacian flow (1.7). This correspondence can also be deduced from the relationship between the volume form on Z and the induced volume form on $X(B)$, since the G_2 -Laplacian flow (1.7) is the gradient flow for the volume on Z determined by φ , and spacelike mean curvature flow (1.2) is the gradient flow for the volume on $X(B)$.

Remark 1.9 Formula (1.9) shows that the *torsion* of the closed G_2 -structure φ in (1.8) is essentially the mean curvature H of $X(B)$ in $\mathbb{R}^{3,3}$. The (necessarily non-positive) scalar curvature of g_φ is thus proportional to $\|H\|^2$, and so a bound on the scalar curvature (or equivalently the torsion) along the G_2 -Laplacian flow in this setting directly corresponds to a bound on the mean curvature in spacelike MCF.

Notice that for the closed G_2 -structure φ in (1.8) on Z^7 we have that φ vanishes on the T^4 fibres. It follows, by the choice of orientation, that the restriction of the 4-form $*_\varphi \varphi$ to a T^4 fibre is equal to the volume form of the induced metric. This means the fibres are *coassociative*, i.e. they are calibrated by $*_\varphi \varphi$. Moreover, the fibres are obviously flat orbits of an isometric T^4 -action for the metric g_φ , so the fibration is called *semi-flat*.

Suppose we have a 7-manifold Z^7 with a closed G_2 -structure φ that is a semi-flat coassociative T^4 -fibration over a simply connected domain B in \mathbb{R}^3 , i.e. φ is T^4 -invariant and the fibres are flat orbits of the action. Then the discussion above shows the following.

Proposition 1.10 *Suppose we have a 7-manifold Z^7 with a closed G_2 -structure φ_0 that is a semi-flat coassociative T^4 -fibration over a simply connected domain B in \mathbb{R}^3 . The G_2 -Laplacian flow on Z^7 starting at φ_0 is equivalent to spacelike MCF of B in $\mathbb{R}^{3,3}$.*

This extends the correspondence in [2] between torsion-free G_2 -structures on semi-flat coassociative T^4 -fibrations and maximal submanifolds in $\mathbb{R}^{3,3}$.

Proposition 1.10, together with our Theorems 1.3 and 1.8, provides immediate long-time existence and convergence results for the G_2 -Laplacian flow.

Theorem 1.11 *Let (Z^7, φ_0) be a semi-flat coassociative T^4 -fibration over B as in Proposition 1.10.*

- (a) *If $B = \mathbb{R}^3$, there is a solution φ_t to G_2 -Laplacian flow (1.7) starting at φ_0 which is smooth and exists for all time.*
- (b) *If B is a bounded domain in \mathbb{R}^3 with smooth boundary, suppose that φ_0 is such that the boundary data for the corresponding initial immersion of B in $\mathbb{R}^{3,3}$ is acausal. There is a solution φ_t to the G_2 -Laplacian flow (1.7) starting at φ_0 satisfying $\varphi_t|_{\partial Z} = \varphi_0|_{\partial Z}$, which is smooth, exists for all time and converges to a torsion-free G_2 -structure φ_∞ on Z with $\varphi_\infty|_{\partial Z} = \varphi_0|_{\partial Z}$.*

Further discussion of the boundary value problem for semi-flat coassociative T^4 -fibrations, as well as coassociative K3 fibrations, can be found in [10]. In particular, it is expected that notions of convexity for the boundary value of a closed G_2 structure suggested in [10] will imply the acausal boundary condition for the corresponding immersion of B in $\mathbb{R}^{3,3}$.

Adiabatic Limits

Another important area of study in G_2 geometry is that of coassociative K3 fibrations. Here, the curvature of the K3 fibres makes the torsion-free condition more difficult to analyse. However, one can still make a similar ansatz for a closed G_2 -structure as in (1.8), now using a spacelike immersion $X : B \rightarrow \mathbb{R}^{3,19} \cong H^2(K3)$. In [9], Donaldson studies the torsion-free condition in the *adiabatic limit* as the volume of the fibres tends to zero. If the volume of the fibres is ϵ , then the G_2 -Laplacian flow corresponds to spacelike MCF in the limit as $\epsilon \rightarrow 0$. Thus, our long-time existence and convergence results for spacelike MCF in $\mathbb{R}^{3,19}$ have significant implications for the study of the G_2 -Laplacian flow for coassociative K3 fibrations.

1.3 Summary

We briefly summarise the contents of this article.

Sects. 2–4 consist of background material and the derivation of the key evolution inequalities we shall require for our study.

- In Sect. 2 we introduce the basic notation and quantities.
- In Sect. 3 we derive essential evolution equations and inequality for key quantities.
- We then localise these evolution inequalities in Sect. 4.

Sects. 5–7 contain the proofs of our main results.

- In Sect. 5 we establish long-time existence of entire graphical solutions to spacelike MCF, assuming the long-time existence of solutions on bounded convex domains satisfying Neumann boundary conditions, which we prove in Sect. 6.

- We also prove the convergence of spacelike MCF with Neumann conditions in Sect. 6.
- In Sect. 7, we prove long-time existence and convergence of spacelike MCF on bounded domains satisfy Dirichlet boundary conditions; namely, that the fixed boundary data is acausal (see Definition 7.1). Here, we make use of work in [25].

Sects. 8–9 concern the properties of entire solutions.

- Since we have non-uniqueness for entire spacelike MCF, in Sect. 8 we introduce the notion of tame solutions which satisfy mild natural assumptions. We show that tame solutions satisfy estimates similar to expanders, and deduce some immediate consequences.
- In Sect. 9 we show that under the assumption that M_0 converges to a spacelike cone at infinity (in C^0), then the renormalised flow converges subsequentially in C^∞_{loc} to a self-expanding solution to the flow.

Appendices A–C consist of further technical results.

- In Appendix A we derive the expression of spacelike MCF and describe the Neumann boundary condition in terms of graphs.
- In Appendix B we demonstrate uniqueness for the flow over compact domains.
- In Appendix C we derive the evolution equation for an ambient symmetric 2-tensor along the flow.
- In Appendix D we demonstrate that boundary quantities may be suitably extended.

2 Preliminaries

In this section we introduce some notation we shall employ throughout the article, and we describe the basic quantities that are needed for our study.

2.1 Basic Notation

Throughout this paper we employ summation convention between raised and lowered indices, where lower-case Latin indices range over $1 \leq i, j, k, \dots \leq n$, upper-case Latin indices range over $1 \leq A, B, C, \dots \leq m$, and Greek indices range over $1 \leq \alpha, \beta, \gamma, \dots \leq n + m$.

We take the standard orthonormal basis $\{f_1, \dots, f_n, e_1, \dots, e_m\}$ of $\mathbb{R}^{n,m}$ such that each f_i is spacelike and each e_A is timelike. Therefore, if $x = x^i f_i + x^{n+A} e_A$ and $y = y^i f_i + y^{n+A} e_A$ then the $\mathbb{R}^{n,m}$ scalar product is given by

$$\langle x, y \rangle = x^i \delta_{ij} y^j - x^{n+A} \delta_{AB} y^{n+B}.$$

We recall that for any vector $x \in \mathbb{R}^{n,m}$, we let

$$|x|^2 = \langle x, x \rangle,$$

and reiterate that (despite appearances) this quantity can be negative.

We let M be an n -dimensional spacelike submanifold of $\mathbb{R}^{n,m}$. We let $X : \Omega \rightarrow \mathbb{R}^{n,m}$, for some $\Omega \subset \mathbb{R}^n$, denote the position vector of M . We also let x^i be coordinates on Ω and let

$$X_i := \frac{\partial X}{\partial x^i}.$$

We write the usual Levi-Civita connection on $\mathbb{R}^{n,m}$ by $\bar{\nabla}$. For any tangent vector fields U, V on M and normal vector field ν we write the induced and normal connection as

$$\nabla_U V = (\bar{\nabla}_U V)^\top, \quad \nabla_U^\perp \nu = (\bar{\nabla}_U \nu)^\perp,$$

respectively. We will often use the abbreviated notation $\bar{\nabla}_i = \bar{\nabla}_{X_i}$, $\nabla_i = \nabla_{X_i}$ and $\nabla_i^\perp = \nabla_{X_i}^\perp$. We may now use the usual definition to extend tensor derivatives to tensors taking values in the normal bundle, for example for a tensor (1+1)-covariant tensor $T = T(V, \nu)$ (for U, V and ν as above) then

$$\nabla_U T(V, \nu) = U(T(V, \nu)) - T(\nabla_U V, \nu) - T(U, \nabla_U^\perp \nu). \tag{2.1}$$

Throughout we will assume that at any point $p \in M$, ν_1, \dots, ν_m are an orthonormal frame of $N_p M$. To avoid sign confusion for timelike quantities, for any timelike $z \in \mathbb{R}^{n,m}$ we write

$$0 \leq \|z\|^2 = -|z|^2.$$

This defines a norm on NM .

When dealing with a graph defined by $\hat{u}^A : \Omega \rightarrow \mathbb{R}$ for $1 \leq A \leq m$, we will write

$$\hat{u} = \sum_{A=1}^m \hat{u}^A e_A.$$

2.2 Gradients

As in [3] we will require a quantity on a spacelike manifold M that measures how close to lightlike the manifold is at a point. To this end we define the projection matrix

$$W_{AB} := \langle e_A, \nu_B \rangle$$

and the partial gradients

$$w_A^2 := \|e_A^\perp\|^2 = \sum_{B=1}^m W_{AB} W_{AB}.$$

We define the full gradient to be

$$v^2 = \sum_A w_A^2 = \sum_A \|e_A^\perp\|^2, \tag{2.2}$$

which is essentially a matrix norm of W_{AB} . We note that this is different to the ‘‘determinant-type’’ gradient in [24] (although, due to the arithmetic-geometric inequality, they are equivalent). We see that a bound on $v(p)$ gives a measure of how close T_pM is to the lightcone and so is a key quantity. In particular, it leads to the following definition.

Definition 2.1 An n -dimensional submanifold M of $\mathbb{R}^{n,m}$ is *uniformly spacelike* if there is $C > 0$ such that for all $p \in M$, $v(p) < C$, where v is defined in (2.2).

The gradient also plays a vital role in the estimate of ambient tensors on the flowing submanifold. Suppose T is an $(a + b)$ -covariant tensor on $\mathbb{R}^{n,m}$. Defining

$$T_{i_1, \dots, i_a, A_1, \dots, A_b} := T(X_{i_1}, \dots, X_{i_a}, \nu_{A_1}, \dots, \nu_{A_b}),$$

we have that

$$|T_{i_1, \dots, i_a, A_1, \dots, A_b}| \leq v^{a+b} |T|_{\mathbb{R}^{n+m}}. \tag{2.3}$$

It will also be useful to consider the evolution of $\|X^\perp\|^2$. This will be used to calculate the gradient of cutoff functions, ultimately allowing us to obtain local gradient estimates that only depend on C^0 bounds. We will repeatedly use that, since $\bar{\nabla}|X|^2 = 2X$, we have

$$|\nabla|X|^2|^2 = 4|X - X^\perp|^2 = 4(|X|^2 - |X^\perp|^2) = 4(|X|^2 + \|X^\perp\|^2). \tag{2.4}$$

2.3 Flow Quantities

Suppose V is any time-dependent vector field on M . As in [30], for any given local coordinates y^α on $\mathbb{R}^{n,m}$ in a neighbourhood of a point in M we define

$$\bar{\nabla}_{\frac{d}{dt}} V = \bar{\nabla}_{\frac{d}{dt}} \left[V^\alpha \frac{\partial}{\partial y^\alpha} \right] = \left[\frac{\partial V^\alpha}{\partial t} + V^\beta H^\gamma \bar{\Gamma}_{\beta\gamma}^\alpha \right] \frac{\partial}{\partial y^\alpha},$$

where $\bar{\Gamma}_{\beta\gamma}^\alpha$ are the Christoffel symbols of $\bar{\nabla}$ with respect to the coordinates y^α . This is compatible with the metric:

$$\frac{d}{dt} \langle V, W \rangle = \left\langle \bar{\nabla}_{\frac{d}{dt}} V, W \right\rangle + \left\langle V, \bar{\nabla}_{\frac{d}{dt}} W \right\rangle.$$

Furthermore, it is easy to see that

$$\bar{\nabla}_{\frac{d}{dt}} X_i = \bar{\nabla}_{X_i} \frac{dX}{dt} = \bar{\nabla}_i H,$$

and if V is a vector field on $\mathbb{R}^{n,m}$ then along MCF we have

$$\bar{\nabla}_{\frac{d}{dt}} V = \bar{\nabla}_H V.$$

For example, since $\langle v_A, X_i \rangle = 0$, we have

$$\left\langle \bar{\nabla}_{\frac{d}{dt}} v_A, X_i \right\rangle = -\langle v_A, \bar{\nabla}_{X_i} H \rangle.$$

On the other hand $\left\langle \bar{\nabla}_{\frac{d}{dt}} v_A, v_B \right\rangle$ is not determined by the flow. However, we may make the following choice.

Lemma 2.2 *Suppose that V is a set with compact closure in the preimage of X and at some time $t_0 > 0$, for all $p \in V$ there exists a smoothly varying orthonormal basis $v_1(p, t_0), \dots, v_m(p, t_0)$ of $N_{X(p)}M_{t_0}$. Then there exists an $\epsilon > 0$ such that for all $t \in (t_0 - \epsilon, t_0 + \epsilon)$ and $p \in V$ there exists an orthonormal basis $v_1(p, t), \dots, v_m(p, t)$ of N_pM_t such that*

$$\bar{\nabla}_{\frac{d}{dt}} v_A = -\left\langle v_A, \nabla_i^\perp H \right\rangle g^{ij} X_j.$$

Proof Due to the above calculations there exists an orthonormal frame $\tilde{v}_1, \dots, \tilde{v}_m$ such that

$$\bar{\nabla}_{\frac{d}{dt}} \tilde{v}_A = -\left\langle v_A, \nabla_i^\perp H \right\rangle g^{ij} X_j + C_A^B \tilde{v}_B,$$

where C_A^B is smooth in both time and space and satisfies $C_A^B = -C_B^A$ (as $\langle \tilde{v}_A, \tilde{v}_B \rangle$ is constant). We suppose that $Z(p, t)$ is a time-dependent $m \times m$ matrix and define

$$v_A = Z_A^B \tilde{v}_B.$$

We see that

$$\bar{\nabla}_{\frac{d}{dt}} v_A = -\left\langle v_A, \nabla_i^\perp H \right\rangle g^{ij} X_j + \left[\frac{dZ_A^D}{dt} + Z_A^B C_B^D \right] \tilde{v}_D.$$

By the Picard–Lindelöf Theorem, there exists a unique solution on V to $\frac{dZ_A^D}{dt} = -Z_A^B C_B^D$ for $t \in (t_0 - \epsilon, t_0 + \epsilon)$ starting from $Z_A^B(p, t_0) = \delta_A^B$ for all $p \in V$. We see that for such a solution, writing Z^t for the transpose of Z ,

$$\frac{d}{dt} (Z_A^B Z^t C_B) = -Z_A^D C_D^B Z^t C_B - Z_A^B C^t D_B Z^t C_D = 0,$$

due to the skew-symmetry of C . Since Z_A^B is orthogonal at time t_0 , Z_A^B is orthogonal for all $t \in (t_0 - \epsilon, t_0 + \epsilon)$. The v_A therefore form an orthonormal frame with the claimed property. □

All normal quantities in evolution equations below will be calculated locally in such a basis. Furthermore, to avoid sign changes we raise and lower normal indices by minus the normal metric:

$$T^A = T_B \delta^{BA}.$$

2.4 Curvature

For $U, V \in T_p M$, we define the second fundamental form by

$$II(U, V) = (\bar{\nabla}_U V)^\perp$$

and we use the notation

$$II_{ij} = II(X_i, X_j) = (\bar{\nabla}_{X_i} X_j)^\perp.$$

Therefore, for $\nu \in NM$,

$$(\bar{\nabla}_i \nu)^\top = -\langle \nu, II_{ij} \rangle g^{jk} X_k$$

We write

$$h_{ij}^A = -\langle II_{ij}, \nu_A \rangle \quad \text{so that} \quad II_{ij} = h_{ij}^A \nu_A.$$

Similarly we define

$$H^A = -\langle H, \nu_A \rangle = g^{ij} h_{ij}^A.$$

We observe that

$$\nabla_k^\perp II_{ij} = \nabla_k h_{ij}^A \nu_A.$$

The Codazzi–Mainardi equations imply that

$$\nabla_U^\perp II(V, W) = \nabla_V^\perp II(W, U) = \nabla_W^\perp II(U, V).$$

3 Evolution Equations

In this section we derive equations and inequalities that are satisfied by key quantities along the spacelike MCF. We will use the notation $\Delta = g^{ij} \nabla_{ij}^2$ for the Laplacian on M and recall that M_t denotes the spacelike submanifold at time t along the mean curvature flow starting at M .

3.1 C^0 Quantities

We begin with the following standard observation.

Lemma 3.1 *Let $f : \mathbb{R}^{n,m} \rightarrow \mathbb{R}$ be a C^2 function. Then under MCF we have*

$$\left(\frac{d}{dt} - \Delta \right) f = -g^{ij} \bar{\nabla}_{ij}^2 f.$$

Proof We have:

$$\begin{aligned} \nabla_i f &= \langle \bar{\nabla} f, X_i \rangle, \\ \nabla_{ij}^2 f &= \langle \bar{\nabla}_{X_j} (\bar{\nabla} f), X_i \rangle + \langle \bar{\nabla} f, \bar{\nabla}_{X_j} X_i - \nabla_{X_j} X_i \rangle = \bar{\nabla}_{X_i X_j}^2 f + \langle \bar{\nabla} f, H_{ij} \rangle, \\ \Delta f &= g^{ij} \bar{\nabla}_{X_i X_j}^2 f + \langle \bar{\nabla} f, H \rangle, \\ \frac{d}{dt} f &= \langle \bar{\nabla} f, H \rangle. \end{aligned}$$

The result follows immediately from these formulae. \square

We define the following quantities at $x \in \mathbb{R}^{n,m}$:

$$\begin{aligned} u_A &:= -\langle e_A, x \rangle, \\ r^2 &:= |x|^2 + \sum_A u_A^2. \end{aligned}$$

Since $\bar{\nabla}_{UV}^2 |x|^2 = 2 \langle U, V \rangle$ we have the following corollary to Lemma 3.1.

Corollary 3.2 *Under mean curvature flow,*

$$\begin{aligned} \left(\frac{d}{dt} - \Delta \right) |X|^2 &= -2n, & \left(\frac{d}{dt} - \Delta \right) (R^2 - 2nt - |X|^2) &= 0, \\ \left(\frac{d}{dt} - \Delta \right) u_A &= 0, & \left(\frac{d}{dt} - \Delta \right) r^2 &= -2n - 2 \sum_A (w_A^2 - 1). \end{aligned}$$

The second equation in Corollary 3.2 shows that we have a good cutoff function with support on shrinking quasi-spheres.

3.2 Gradient Quantities

We first write down a general observation.

Lemma 3.3 *Suppose that V is a smooth 1-form on $\mathbb{R}^{n,m}$. We write the components of the restriction of this tensor to NM_t as*

$$V_A = V(v_A).$$

Then V_A satisfies

$$\nabla_k V_A = \bar{\nabla}_k V_A + V(X_l)h_k^{lA},$$

and, choosing v_1, \dots, v_m locally as in Lemma 2.2, we have that

$$\left(\frac{d}{dt} - \Delta\right) V_A = -g^{ij}\bar{\nabla}_i\bar{\nabla}_j V_A - 2\bar{\nabla}_i V(X_l)h_A^{il} - V_B h_{ij}^B h_A^{ij}.$$

Proof We see that

$$\frac{d}{dt} V_A = \bar{\nabla}_H V(v_A) + V(\bar{\nabla}_{\frac{d}{dt}} v_A) = \bar{\nabla}_H V(v_A) - V(X_j) \left\langle \nabla_j^\perp H, v_A \right\rangle.$$

We calculate

$$\nabla_k V_A = \bar{\nabla}_k V_A + V((\bar{\nabla}_k v_A)^\top) = \bar{\nabla}_k V_A - V(X_l) \left\langle H_l^l, v_A \right\rangle.$$

Furthermore, recalling (2.1) we have that

$$\begin{aligned} \nabla_j \nabla_i V_A &= \frac{\partial}{\partial x^j} (\nabla_i V_A) - \nabla_{\nabla_{X_j} X_i} V(v_A) - \nabla_{X_i} V(\nabla_{X_j}^\perp v_A) \\ &= \bar{\nabla}_{X_j} \bar{\nabla}_{X_i} V(v_A) + \bar{\nabla}_{\bar{\nabla}_{X_j} X_i} V(v_A) + \bar{\nabla}_{X_i} V(\bar{\nabla}_{X_j} v_A) \\ &\quad - \bar{\nabla}_{X_j} V(X_l) \left\langle H_l^l, v_A \right\rangle - V(H_{jl}) \left\langle H_l^l, v_A \right\rangle \\ &\quad - V(X_l) \left[\left\langle \nabla_j^\perp H_l^l + H(X^l, \nabla_{X_j} X_l), v_A \right\rangle + \left\langle H_l^l, \nabla_{X_j}^\perp v_A \right\rangle \right] \\ &\quad - \nabla_{\nabla_{X_j} X_i} V(v_A) - \nabla_{X_i} V(\nabla_{X_j}^\perp v_A) \\ &= \bar{\nabla}_{X_j} \bar{\nabla}_{X_i} V(v_A) + \bar{\nabla}_{H_{ij}} V(v_A) + \bar{\nabla}_{X_i} V((\bar{\nabla}_{X_j} v_A)^\top) + \bar{\nabla}_{X_j} V(X_l) h_{iA}^l \\ &\quad - V(H_{jl}) \left\langle H_l^l, v_A \right\rangle - V(X_l) \left\langle \nabla_j^\perp H_l^l, v_A \right\rangle \\ &= \bar{\nabla}_j \bar{\nabla}_i V_A + \bar{\nabla}_{H_{ij}} V_A + \bar{\nabla}_i V_k h_{jA}^k + \bar{\nabla}_j V(X_l) h_{iA}^l + V_B h_{jl}^B h_{iA}^l \\ &\quad - V(X_l) \left\langle \nabla_j^\perp H_l^l, v_A \right\rangle. \end{aligned}$$

Finally, using Codazzi–Mainardi gives the claimed result. □

Lemma 3.4 *Along MCF we have that*

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) w_A^2 &= -2 \langle e_A, H_{ik} \rangle g^{ij} g^{kl} \langle H_{jl}, e_A \rangle + 2g^{ij} \left\langle H(X_i, e_A^\top), H(X_j, e_A^\top) \right\rangle, \\ \left(\frac{d}{dt} - \Delta\right) \|X^\perp\|^2 &= -2 \langle X, H_{ij} \rangle \langle H^{ij}, X \rangle - 4 \langle H, X \rangle + 2 \left\langle H(X_i, X^\top), H(X^i, X^\top) \right\rangle, \\ \nabla_i w_A^2 &= 2 \langle e_A, H(X_i, e_A^\top) \rangle \quad \text{and} \quad \nabla_i \|X^\perp\|^2 = 2 \langle X, H(X_i, X^\top) \rangle. \end{aligned}$$

Proof We define the 1-form $V(Z) = \langle e_A, Z \rangle$ on $\mathbb{R}^{n,m}$, and note that $\bar{\nabla}V = 0$, and $\bar{\nabla}^2 V = 0$. We deduce from Lemma 3.3 that

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) V_B &= -V_C h_{ij}^C h_B^{ij} = \langle e_A, II_{ij} \rangle \langle II_{ij}, v_B \rangle, \\ \nabla_k V_B &= V(X_l) h_{kB}^l = -\langle II(e_A^\top, X_k), v_B \rangle. \end{aligned}$$

As $w_A^2 = \|e_A^\perp\|^2 = \sum_{B=1}^m (\langle e_A, v_B \rangle)^2 = \sum_{B=1}^m V_B^2$, we see that

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) w_A^2 &= \sum_B \left[2V_B \left(\frac{d}{dt} - \Delta\right) V_B - 2\nabla_i V_B \nabla^i V_B \right] \\ &= \sum_B \left[2\langle v_B, e_A \rangle \langle v_B, II_{ik} \rangle g^{ij} g^{kl} \langle II_{jl}, e_A \rangle \right. \\ &\quad \left. - 2\langle v_B, II(X_i, e_A^\top) \rangle g^{ij} \langle v_B, II(X_j, e_A^\top) \rangle \right] \\ &= -2\langle e_A, II_{ik} \rangle g^{ij} g^{kl} \langle II_{jl}, e_A \rangle \\ &\quad - 2\sum_B \langle v_B, II(X_i, e_A^\top) \rangle g^{ij} \langle v_B, II(X_j, e_A^\top) \rangle. \end{aligned}$$

We also have

$$\nabla_i w_A^2 = 2\sum_B V_B \nabla_i V_B = -2\sum_B \langle v_B, e_A \rangle \langle v_B, II(X_i, e_A^\top) \rangle = 2\langle e_A, II(X_i, e_A^\top) \rangle.$$

Similarly, we define the 1-form $U = \langle X, Z \rangle$, where X is the position vector, and we see that $\bar{\nabla}_Y U(X) = \langle Y, X \rangle$ and $\bar{\nabla}^2 U = 0$. An identical argument to the above yields the claimed equations for $\|X^\perp\|^2$. □

As is often the case with MCF in indefinite spaces, the key to a local gradient estimate is to estimate the first term in the evolution of w_A^2 in Lemma 3.4 by slightly more than twice the gradient of w_A using an eigenvalue estimate, originally employed by Bartnik [3, Theorem 3.1] (see also [11,12,14] for similar arguments).

Corollary 3.5 *We may estimate*

$$\left(\frac{d}{dt} - \Delta\right) w_A^2 \leq -\frac{|\nabla w_A^2|^2}{w_A^2}$$

or

$$\left(\frac{d}{dt} - \Delta\right) w_A^2 \leq -\left(1 + \frac{1}{2n}\right) \frac{|\nabla w_A^2|^2}{w_A^2} + 2w_A^2 \|H\|^2.$$

Proof For the second term in the evolution of w_A^2 in Lemma 3.4, we have that

$$\begin{aligned} |\nabla w_A^2|^2 &= 4\|e_A^\perp\|^2 \left\langle \frac{e_A^\perp}{\|e_A^\perp\|}, II(X_i, e_A^\top) \right\rangle g^{ij} \left\langle \frac{e_A^\perp}{\|e_A^\perp\|}, II(X_j, e_A^\top) \right\rangle \\ &\leq -4w_A^2 \left\langle II(X_i, e_A^\top), II(X_j, e_A^\top) \right\rangle g^{ij}. \end{aligned}$$

We now estimate the first term in the evolution of w_A^2 in Lemma 3.4. Write $t_{ij} = \langle e_A, II_{ij} \rangle$ and the eigenvalues of t_{ij} as $\lambda_1, \dots, \lambda_n$ where λ_1 is the largest in absolute value. Using $-1 = |e_A^\top|^2 - w_A^2$, we have that

$$|\nabla w_A^2|^2 \leq 4\lambda_1^2 |e_A^\top|^2 = 4\lambda_1^2 (w_A^2 - 1) \leq 4\lambda_1^2 w_A^2.$$

The first estimate in the statement follows from the fact that $|t|^2 \geq \lambda_1^2$.

Since for any symmetric tensor b_{ij} , $n|b|^2 \geq (\text{tr}b)^2$, we have that

$$|t|^2 = \lambda_1^2 + \dots + \lambda_n^2 \geq \lambda_1^2 + \frac{1}{n-1} \left(\sum_{i=2}^n \lambda_i \right)^2 \geq \left(1 + \frac{1}{n} \right) \lambda_1^2 - g^{ij} t_{ij},$$

where we used Young’s inequality for the last estimate. We now see that

$$\begin{aligned} -2 \langle e_A, II_{ik} \rangle g^{ij} g^{kl} \langle II_{jl}, e_A \rangle &\leq -2 \left(1 + \frac{1}{n} \right) \lambda_1^2 + 2(\langle e_A, H \rangle)^2 \\ &\leq - \left(1 + \frac{1}{n} \right) \frac{|\nabla w_A^2|^2}{2w_A^2} + 2w_A^2 \|H\|^2. \end{aligned}$$

The second estimate in the statement now follows. □

Remark 3.6 The second estimate in Corollary 3.5 is the same as the evolution inequality satisfied by the codimension 1 gradient (see [11, Corollary 2.5]).

We now derive an evolution inequality for $\|X^\perp\|$ in a similar way.

Corollary 3.7 For $\epsilon \in (0, 1)$, at any point such that $|X|^2 < \epsilon \|X^\perp\|^2$ we have that

$$\left(\frac{d}{dt} - \Delta \right) \|X^\perp\|^2 \leq - \left(\frac{1}{2} + \frac{1 + \frac{1}{n}}{2(1 + \epsilon)} \right) \frac{|\nabla \|X^\perp\|^2|^2}{\|X^\perp\|^2} - 4 \langle X, H \rangle + 2 \langle X, H \rangle^2.$$

Proof Since

$$|\nabla \|X^\perp\|^2|^2 = 4 \left\langle X, II(X^\top, X_i) \right\rangle \left\langle II(X^i, X^\top), X \right\rangle,$$

we immediately see that

$$-2 \left| \left\langle II(X_i, X^\top), II(X^i, X^\top) \right\rangle \right| \leq - \frac{|\nabla \|X^\perp\|^2|^2}{2\|X^\perp\|^2}.$$

Using Eq. (2.4), and estimating as in Corollary 3.5, we have

$$-2 \langle X, II_{ij} \rangle \langle II^{ij}, X \rangle \leq - \left(1 + \frac{1}{n} \right) \frac{|\nabla \|X^\perp\|^2|^2}{2(|X|^2 + \|X^\perp\|^2)} + 2 \langle H, X \rangle^2.$$

Altogether these estimates imply

$$\begin{aligned} \left(\frac{d}{dt} - \Delta \right) \|X^\perp\|^2 &\leq -\frac{1}{2} \left(1 + \left(1 + \frac{1}{n} \right) \frac{\|X^\perp\|^2}{|X|^2 + \|X^\perp\|^2} \right) \frac{|\nabla \|X^\perp\|^2|^2}{\|X^\perp\|^2} \\ &\quad - 4 \langle H, X \rangle + 2 \langle H, X \rangle^2. \end{aligned}$$

The upper bound on $|X|^2$ now yields the claim. □

We also observe we may use the height function to get a large negative evolution for the gradient (depending on local bounds on u). Similar ideas were used in [17].

Lemma 3.8 *We have that*

$$\left(\frac{d}{dt} - \Delta \right) w_A^2 e^{u_A^2} \leq -2e^{u_A^2} w_A^2 (w_A^2 - 1).$$

Proof Recall Corollary 3.2, Corollary 3.5 and $|\nabla u_A|^2 = (w_A^2 - 1)$. We may estimate using Young’s inequality, for any smooth positive function $\phi : \mathbb{R} \rightarrow \mathbb{R}$:

$$\begin{aligned} \left(\frac{d}{dt} - \Delta \right) w_A^2 \phi(u_A) &\leq -\phi \frac{|\nabla w_A^2|^2}{w_A^2} - 2\phi' \langle \nabla w_A^2, \nabla u_A \rangle - \phi'' w_A^2 |\nabla u_A|^2 \\ &\leq w_A^2 \left(\frac{(\phi')^2}{\phi} |\nabla u_A|^2 - \phi'' |\nabla u_A|^2 \right). \end{aligned}$$

We choose to write $\phi = e^\psi$. Then

$$\phi' = \psi' \phi, \quad \phi'' = \psi'' \phi + (\psi')^2 \phi$$

and

$$\left(\frac{d}{dt} - \Delta \right) w_A^2 \phi(u_A) \leq -\psi'' \phi w_A^2 |\nabla u_A|^2 = -\psi'' \phi w_A^2 (w_A^2 - 1).$$

Setting $\psi = u_A^2$ yields the claim. □

3.3 Curvature Quantities

We recall the following evolution equations which may be found in [24, Proposition 4.1, Eq. (5.7)].

Lemma 3.9 *The following evolution equations hold:*

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) h_{ij}^A &= -h_{kr}^A h_B^{kr} h_{ij}^B + 2h_{kl}^A h_i^{Bl} h_{Bj}^k - h_{il}^A h^{Blk} h_{Bkj} - h_{jl}^A h^{Blk} h_{Bki} \\ &\quad + h_{ik}^A h_j^{Bk} H_B + h_{jk}^A h_i^{Bk} H_B; \\ \left(\frac{d}{dt} - \Delta\right) H^A &= -h_{kr}^A h_B^{kr} H^B; \\ \left(\frac{d}{dt} - \Delta\right) \|H\|^2 &= -2\langle H, II_{ij} \rangle \langle H, II^{ij} \rangle - 2\|\nabla^\perp H\|^2; \\ \left(\frac{d}{dt} - \Delta\right) \|II\|^2 &= -2h^{iA} h_i^B h_A^{kr} h_{krB} - 2|h_{iA}^k h_{kjB} - h_{iB}^l h_{jA}^l|^2 - 2|\nabla_p h_{ik}^A|^2. \end{aligned}$$

Corollary 3.10 *The following evolution inequalities hold:*

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) \|H\|^2 &\leq -\frac{2}{n} \|H\|^4 - 2\|\nabla^\perp H\|^2; \\ \left(\frac{d}{dt} - \Delta\right) \|II\|^2 &\leq -\frac{2}{m} \|II\|^4 - 2\|\nabla^\perp II\|^2. \end{aligned}$$

Proof Setting $r_{ij} = \langle H, II_{ij} \rangle$, we have $|r|^2 \geq n^{-1}(\text{tr } r)^2 = n^{-1}\|H\|^2$, which gives the first inequality. The second follows by the same trick applied to $S^{AB} = h^{iA} h_{ij}^B$. \square

4 Local Estimates

In this section we localise the estimates for our key quantities using an appropriate cut-off function. To this end, we introduce the following notation.

Definition 4.1 We define the solid cylinder of radius R centred at p to be

$$C_R(p) := \{x \in \mathbb{R}^{n,m} \mid r^2(x - p) < R^2\} \subset \mathbb{R}^{n,m},$$

and the solid quasi-sphere centred at $p \in \mathbb{R}^{n,m}$ by

$$Q_R(p) := \{x \in \mathbb{R}^{n,m} \mid |x - p|^2 < R^2\} \subset \mathbb{R}^{n,m},$$

where if the centre is omitted, it is assumed to be $0 \in \mathbb{R}^{n,m}$, that is

$$C_R := \{x \in \mathbb{R}^{n,m} \mid r^2(x) < R^2\} \quad \text{and} \quad Q_R := \{x \in \mathbb{R}^{n,m} \mid |x|^2 < R^2\}.$$

We now define

$$\eta_R := (R^2 - |X|^2 - 2nt)_+$$

and note that $\eta_R(X) > 0$ for $t < (2n)^{-1}R^2$ if and only if $X \in Q_{\sqrt{R^2 - 2nt}}$.

We remark that the above quasi-spheres have *positive* square radius, and the support of the cutoff function collapses on to the interior of the light cone as t goes to $\frac{R^2}{2n}$. These should not be confused with the (negative square radius) expanding quasi-spheres of Definition 1.6.

We now include a lemma which is essentially [11, Lemma 3.3].

Lemma 4.2 *Suppose that, along MCF, a C^2 -function $f : \mathbb{R}^{n,m} \rightarrow \mathbb{R}^+$ satisfies*

$$\left(\frac{d}{dt} - \Delta\right) f \leq g - (1 + \delta) \frac{|\nabla f|^2}{f}$$

for some function g and $\delta > 0$. Then there exists $p = p(\delta) > 0$ such that, writing $\eta_R = \eta_R(X)$, we have

$$\left(\frac{d}{dt} - \Delta\right) f \eta_R^p \leq g \eta_R^p.$$

Furthermore for any $\Lambda > 0$, there exists $q = q(\delta, \Lambda) > 0$ such that

$$\left(\frac{d}{dt} - \Delta\right) f \eta_R^q \leq g \eta_R^q - \Lambda f \eta_R^{q-2} |\nabla |X|^2|^2.$$

Proof Let $p \geq 2$. If $t < (2n)^{-1} R^2$ and $x \in \mathcal{Q}_{\sqrt{R^2 - 2nt}}$ then at (x, t) :

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) f \eta_R^p &\leq f \eta_R^{p-2} \left[\eta_R^2 f^{-1} g - (1 + \delta) \eta_R^2 \frac{|\nabla f|^2}{f^2} - 2p \eta_R \left\langle \frac{\nabla f}{f}, \nabla \eta_R \right\rangle \right. \\ &\quad \left. - p(p-1) |\nabla \eta_R|^2 \right] \\ &\leq f \eta_R^{p-2} \left[\eta_R^2 f^{-1} g + p \left(1 - \frac{\delta}{1 + \delta} p\right) |\nabla |X|^2|^2 \right]. \end{aligned}$$

Setting $p = \max\{\frac{1+\delta}{\delta}, 2\}$ gives the first equation. The second equation follows simply by making q sufficiently larger than p . \square

We first observe we may easily get a local estimate for w_A^2 if $\|H\|^2$ is bounded.

Lemma 4.3 *Suppose that for all $t \in [0, \frac{R^2}{2n})$, $\text{supp } \eta_R \cap M_t$ is compact and for all $y \in \text{supp } \eta_R \cap M_t$,*

$$\|H\|^2(y, t) < C_H.$$

Then there exists $p > 0$ such that for all $t \in [0, \frac{R^2}{2n})$,

$$\sup_{M_t} w_A^2 \eta_R^p \leq e^{2C_H t} \sup_{M_0} w_A^2 \eta_R^p.$$

Proof Using Corollary 3.5 and Lemma 4.2, there exists $p > 0$ such that

$$\left(\frac{d}{dt} - \Delta\right) w_A^2 \eta_R^p e^{-2C_H t} \leq 0.$$

The maximum principle now yields the result. □

Remark 4.4 As w_A and $\|H\|^2$ have the same evolution as the gradient and square of the mean curvature in the codimension 1 case, we may follow an identical proof to [11, Theorem 3.1]. However, note that to apply the maximum principle to

$$g = \frac{w_A^2}{(\Lambda - \|H\|^2)^{\frac{1}{q}}} (R^2 - |X|^2 - 2nt)^p$$

we require that it is (at least) continuous; i.e. we require a bound on $\|H\|^2$ so that the denominator is never zero (which is seemingly absent from the hypotheses of [11, Theorem 3.1]). Lemma 4.3 therefore yields an equivalent statement.

In general, we may not have a uniform bound on $\|H\|^2$ as assumed in Lemma 4.3. However, in the applications in Sect. 5, we will have bounds of the form

$$t\|H\|^2 \leq \frac{n}{2},$$

and we now prove local estimates under this assumption.

Lemma 4.5 *Suppose that for all $t \in [0, \frac{R^2}{2n})$, $\text{supp } \eta_R \cap M_t$ is compact and there is some $L > 0$ such that, for all $y \in \text{supp } \eta_R \cap M_t$,*

$$t\|H\|^2(y, t) \leq \frac{n}{2} \quad \text{and} \quad |X|^2(y, t) > -L.$$

There exists $q = q(n)$ and $C = C(n, R, L)$ such that for all $t \in [0, \frac{R^2}{2n})$,

$$\sup_{M_t} t\|X^\perp\|^2 \eta_R^q(y, t) \leq C.$$

Proof Due to Corollary 3.7 (setting $\epsilon = (1 + 2n)^{-1}$), we have that at any point where $|X|^2 < \frac{\|X^\perp\|^2}{1+2n}$:

$$\left(\frac{d}{dt} - \Delta\right) \|X^\perp\|^2 \leq -\left(1 + \frac{1}{4n}\right) \frac{|\nabla\|X^\perp\|^2|^2}{\|X^\perp\|^2} + \frac{2\sqrt{2n}\|X^\perp\|}{\sqrt{t}} + n \frac{\|X^\perp\|^2}{t}.$$

We consider $f = t\|X^\perp\|^2 \eta_R^q$ where q is chosen as in Lemma 4.2 with $\Lambda = 1$, which we want to show is uniformly bounded to prove the statement.

Suppose that at time t_0 , $y_0 \in M_{t_0}$ is an increasing maximum of f (that is, f has a maximum in space at y_0 and $\frac{df}{dt}(y_0, t_0) \geq 0$). Then we have that either $\|X^\perp\|^2 \leq (1 + 2n)|X|^2$ (which implies that $f \leq C(n, R)$), or at (y_0, t_0)

$$\begin{aligned}
 0 &\leq \left(\frac{d}{dt} - \Delta\right) t \|X^\perp\|^2 \eta_R^q \\
 &\leq -t \|X^\perp\|^2 |\nabla |X|^2|^2 \eta_R^{q-2} + 2\sqrt{2nt} \|X^\perp\| \eta_R^q + n \|X^\perp\|^2 \eta_R^q + \|X^\perp\|^2 \eta_R^q \\
 &\leq -4t \|X^\perp\|^4 \eta_R^{q-2} + 4tL \|X^\perp\|^2 \eta_R^{q-2} + 2\sqrt{2nt} \|X^\perp\| \eta_R^q + (n + 1) \|X^\perp\|^2 \eta_R^q.
 \end{aligned}$$

Therefore at any increasing maximum of $f = t \|X^\perp\|^2 \eta_R^q$ such that $R^2(1 + 2n) < \|X^\perp\|^2$, we have

$$f^2 \leq 2n^{-1}LR^2 f \eta_R^q + t\sqrt{8nf} \eta_R^{\frac{3}{2}q+2} + (n + 1) f \eta_R^{q+2},$$

which implies $f \leq C(R, n, L)$ due to our chosen range of t . □

We now use Lemma 4.5 to show a full local gradient bound.

Lemma 4.6 *Suppose that for all $t \in [0, \frac{R^2}{2n})$, $\text{supp } \eta_R \cap M_t$ is compact and there is some $C_u > 0$ such that, for all $y \in \text{supp } \eta_R \cap M_t$,*

$$t \|H\|^2(y, t) \leq \frac{n}{2} \quad \text{and} \quad \|u\|^2(y, t) < C_u.$$

There exists $p = p(n)$ and $C = C(n, R, C_u)$ such that for all $t \in [0, \frac{R^2}{2n})$,

$$\sup_{M_t} t v^2 \eta_R^p(y, t) \leq C.$$

Proof The bound on $\|u\|^2$ implies that $|X|^2 > -C_u$. As a result we may apply Lemma 4.5 to give that

$$t \|X^\perp\| \eta_R^q < C(n, R, C_u).$$

Setting $f = w_A^2 e^{u_A^2}$, by Lemma 3.8 we have

$$\left(\frac{d}{dt} - \Delta\right) f \leq -cf^2 + Cf$$

where c and C depend only on C_u . Therefore at an increasing maximum of $tf \eta_R^p$, for $p \geq q + 2$, we may calculate:

$$0 \leq \left(\frac{d}{dt} - \Delta\right) t f \eta_R^p = -ct \eta_R^p f^2 + C f t \eta_R^p + f \eta_R^p - 2 \langle \nabla f, \nabla \eta_R^p \rangle$$

$$\begin{aligned}
 &+ tf \left(-p(p-1)\eta_R^{p-2} |\nabla|X|^2|^2 \right) \\
 &\leq -ct\eta_R^p f^2 + Cft\eta_R^p + f\eta_R^p + tfp(p+1)\eta_R^{p-2} |\nabla|X|^2|^2,
 \end{aligned}$$

where we used that $\nabla(tf\eta_R^p) = 0$ on the final line. Using the estimate on $\|X^\perp\|^2$ and $|X|^2$,

$$ctf^2\eta_R^p \leq Cft\eta_R^p + f\eta_R^p + tCf\eta_R^{p-2} + Cf,$$

We therefore obtain that $t w_A^2 e^{u_A} \eta_R^p = tf\eta_R^p < C$, where C depends only on n, R, C_u . Summing the estimates on the w_A^2 and using the bound on $\|u\|^2$ gives the lemma. \square

We now prove local estimates on the second fundamental form.

Lemma 4.7

(a) *Suppose the hypotheses of Lemma 4.3 hold, and additionally we have a uniform estimate*

$$v^2(y, t) \leq C_v$$

for all $y \in M_t$. There exists $C_1 = C_1(n, R, C_v)$ such that

$$\|II\|^2 \eta_R^p \leq C_1 \sup_{M_0} \|II\|^2 \eta_R^p.$$

(b) *Suppose the hypotheses of Lemma 4.6 hold. There exists $C_2 = C_2(c, R, C_u)$ such that*

$$t \|II\|^2 \eta_R^p \leq C_2.$$

Proof Part (a) follows by a calculation similar to the proof of Lemma 4.6, but estimating $|\nabla|X|^2|^2$ and using the estimates of Lemma 4.3 instead of Lemma 4.5.

Part (b) is identical to the proof of Lemma 4.6, replacing f with $f = \|II\|^2$, and using that $(\frac{d}{dt} - \Delta) \|II\|^2 \leq -\frac{2}{m} \|II\|^4$. \square

Remark 4.8 Once we have a uniform bound $v^2 < C_v$, we may use an identical proof to Lemma 4.7 but replacing η_R^p with $\tilde{\eta}_R^2(r) = (R^2 - r^2)_+^2$. This is exactly as in [11, Proposition 3.6] and yields estimates in cylinders of the form

$$\sup_{M_t} \|II\|^2 \tilde{\eta}_R^2(r) \leq \sup_{M_0} \|II\|^2 \tilde{\eta}_R^2(r).$$

We conclude this section with local higher order estimates on the second fundamental form.

Lemma 4.9 *Suppose that for all $t \in [0, T)$, $y \in \mathcal{C}_R \cap M_t$,*

$$v^2(y, t) < C_v, \quad \|II\|^2(y, t) < C_{II},$$

for some constants C_v, C_{II} . Then there exists a constant

$$C_k := C_k \left(C_v, C_{II}, n, m, k, \max_{1 \leq l \leq k} \sup_{M_0 \cap \mathcal{C}_R} \|\nabla^l II\|^2 \right)$$

such that for all $t \in [0, T)$,

$$\sup_{M_t \cap \mathcal{C}_{\frac{R}{2}}} \|\nabla^k II\|^2 \leq C_k.$$

Proof All required evolution equations may be estimated as in the codimension one case, so the proof of [11, Proposition 3.7] applies without alteration. \square

5 Entire Solutions

We now demonstrate the long-time existence of entire graphical solutions to spacelike MCF, assuming the long-time existence of solutions on bounded convex domains satisfying Neumann boundary conditions, which we defer to Sect. 6.

The following lemma will be used to give the compactness hypothesis required in our local estimates, and is a higher codimension version of [7, Proposition 1].

Lemma 5.1 *Suppose $0 \in M_0$, M_0 is spacelike and is given by the graph of $\hat{u}_0 : \mathbb{R}^n \rightarrow \mathbb{R}^m$. Then*

$$\lim_{R \rightarrow \infty} \inf_{x \in \mathbb{R}^n \setminus B_R} \left[|x|^2 - \|\hat{u}_0\|^2 \right] = \infty, \quad (5.1)$$

or equivalently (recalling the notation of Definition 4.1),

$$\lim_{R \rightarrow \infty} \inf_{M_0 \setminus \mathcal{C}_R} |X|^2 = \infty.$$

Moreover, there exists $\epsilon > 0$ such that

$$\|\hat{u}_0\| \leq \chi_\epsilon \quad (5.2)$$

where

$$\chi_\epsilon(x) := \begin{cases} 1 - \epsilon & \text{for } x \in \overline{B_1(0)}, \\ |x| - \epsilon & \text{for } x \in \mathbb{R}^n \setminus B_1(0). \end{cases}$$

Proof Suppose (5.1) does not hold. Then there exists a constant $C > 0$ and a sequence of points $x_i \in \mathbb{R}^n$ such that $1 < |x_i| \rightarrow \infty$ but $y_i := x_i + \hat{u}_0(x_i) \in M_0$ has

$$|y_i|^2 = |x_i|^2 - \|\hat{u}_0(x_i)\|^2 < C. \tag{5.3}$$

Since M_0 is spacelike there exists $\epsilon > 0$ such that for all $x \in \partial B_1(0)$,

$$\epsilon \leq |x|^2 - \|\hat{u}_0(x)\|^2 = 1 - \|\hat{u}_0(x)\|^2. \tag{5.4}$$

We define $\tilde{x}_i := \frac{x_i}{|x_i|} \in \partial B_1(0)$ and $\tilde{y}_i := \tilde{x}_i + \hat{u}_0(\tilde{x}_i) \in M_0$. Since M_0 is spacelike,

$$0 \leq |\tilde{y}_i - y_i|^2 = (|x_i| - 1)^2 - \|\hat{u}_0(\tilde{x}_i) - \hat{u}_0(x_i)\|^2. \tag{5.5}$$

Equations (5.4) and (5.5) and the triangle inequality for the norm $\|\cdot\|$ now imply

$$\begin{aligned} |y_i|^2 &\geq |x_i|^2 - (\|\hat{u}_0(x_i) - \hat{u}_0(\tilde{x}_i)\| + \|\hat{u}_0(\tilde{x}_i)\|)^2 \\ &\geq |x_i|^2 - (|x_i| - 1 + 1 - \epsilon)^2 = 2\epsilon|x_i| - \epsilon^2. \end{aligned}$$

This contradicts (5.3) as $i \rightarrow \infty$.

Equation (5.2) follows from (5.4) and the fact that M_0 is spacelike. □

We now prove our claimed long-time existence result in the entire setting.

Theorem 5.2 *Suppose that M_0 is smooth, spacelike and given by the graph of $\hat{u}_0 : \mathbb{R}^n \rightarrow \mathbb{R}^m$. There exists a solution*

$$\hat{u} \in C_{loc}^\infty(\mathbb{R}^n \times (0, \infty)) \cap C_{loc}^{0,\alpha}(\mathbb{R}^n \times [0, \infty))$$

to graphical spacelike MCF (1.3) satisfying

$$|\hat{u}(x, t) - \hat{u}_0(x)| \leq \sqrt{2nt}.$$

Furthermore, if there exists a constant $C_H > 0$ such that

$$\sup_{M_0} \|H\|^2 < C_H, \tag{5.6}$$

then $\hat{u} \in C_{loc}^\infty(\mathbb{R}^n \times [0, \infty))$ and

$$\|H\|^2 \leq \frac{1}{(C_H + 1)^{-1} + \frac{2}{n}t}.$$

Proof Case 1: $\|H\|^2$ bounded initially. We first suppose (5.6) holds. Without loss of generality we assume that $\hat{u}_0(0) = 0$.

By Lemma 5.1 there exist radii R_i such that the graph of \hat{u}_0 over $\mathbb{R}^n \setminus B_{R_i}$ satisfies

$$\inf_{x \in \mathbb{R}^n \setminus B_{R_i}} \left[|x|^2 - \|\hat{u}_0(x)\|^2 \right] \geq 2i + 1 \tag{5.7}$$

and therefore $M_0 \cap \partial C_{R_i}$ lies outside \mathcal{Q}_{R_i} , in the notation of Definition 4.1.

We will now solve a sequence of auxiliary problems for spacelike MCF with Neumann boundary conditions and use our interior estimates to show that these converge to a solution of (1.3). Unfortunately, to get a solution to our auxiliary problem which is smooth to $t = 0$, we need our initial data to satisfy compatibility conditions. To this end we now describe a way to modify \hat{u}_0 so the initial data satisfies compatibility conditions of all orders.

For some $\Lambda > 0$, we define

$$\tilde{u}_{0,i}(x) = \begin{cases} \hat{u}_0(x) & \text{for } x \in B_{R_i+\Lambda}, \\ \hat{u}_0((R_i + \Lambda - |x|)|\frac{x}{|x|}) & \text{for } x \in B_{2R_i+2\Lambda} \setminus B_{R_i+\Lambda}, \\ 0 & \text{for } x \in \mathbb{R}^n \setminus B_{2R_i+2\Lambda}. \end{cases}$$

Clearly $\tilde{u}_{0,i}$ is continuous (as $\hat{u}_0(0) = 0$) and smooth away from the boundary $(\partial B_{R_i+\Lambda}) \cup (\partial B_{2R_i+2\Lambda})$ of the annulus. We now let $\hat{u}_{0,i}$ be a smoothing of $\tilde{u}_{0,i}$ such that $\hat{u}_{0,i} = \tilde{u}_{0,i}$ on $\overline{B_{R_i}}$ and $\hat{u}_{0,i} \equiv 0$ on $\mathbb{R}^n \setminus B_{2R_i+3\Lambda}$. By choosing Λ large enough depending only on C_H , we may assume that the mean curvature of $\hat{u}_{0,i}$ satisfies $\|H\|^2 < C_H + 1$ and $|\hat{u}_{0,i}|^2 < |\hat{u}_0|^2 + 1$.

We now consider the spacelike MCF problems with Neumann boundary conditions given by

$$\begin{cases} \frac{d\hat{u}_i}{dt} - g^{kl}(D\hat{u})D_{kl}^2\hat{u}_i = 0 & \text{on } B_{2R_i+3\Lambda+1} \times [0, T), \\ D_{\frac{x}{|x|}}\hat{u}_i = 0 & \text{on } \partial B_{2R_i+3\Lambda+1} \times [0, T), \\ \hat{u}_i(\cdot, 0) = \hat{u}_{0,i}(\cdot) & \text{on } B_{2R_i+3\Lambda+1}. \end{cases} \tag{5.8}$$

Since compatibility conditions of all orders are satisfied, Theorem 6.2 below implies there exists a solution $\hat{u}_i \in C^\infty(B_{2R_i+2\Lambda} \times [0, \infty))$. Furthermore, as \hat{u}_i is sufficiently regular, we have the bound

$$\|H_i\|^2 \leq ((1 + C_H)^{-1} + 2n^{-1}t)^{-1},$$

which is uniform in i .

We let $M_{t,i} := \text{graph } \hat{u}_i$. By Lemma 5.1 and the preservation of height bounds for $\|u_i\|$, for all $t > 0$ and $j > i$ we have $\partial M_{t,j} \cap \mathcal{Q}_{R_i} = \emptyset$. Therefore, each $M_{t,j} \cap \mathcal{Q}_{R_i}$ has compact closure. We may now apply the interior estimates of Lemma 4.3 to obtain that for all $x \in M_{t,j} \cap \mathcal{Q}_{\sqrt{R_i^2 - 2nt}}$, we have a uniform bound on v . In particular, for all

$t < \frac{R_i^2}{4n}$ and $j > i$, we may apply Lemmas 4.7 and 4.9 on $M_{t,j} \cap C_{\frac{R_i}{2}}$ to imply uniform $C^{k;\frac{k}{2}}$ bounds for all k .

We now use the Arzelà–Ascoli theorem to take a diagonal sequence which converges in C_{loc}^∞ to the claimed solution $\hat{u} \in C_{\text{loc}}^\infty(\mathbb{R}^n \times [0, \infty))$ satisfying (1.3).

Case 2: No initial $\|H\|^2$ bound. If $\|H\|^2$ is not bounded initially, we proceed solving auxiliary problems as above, but this time on the solutions \hat{u}_i , we only have

$$|\hat{u}_{0,i}(x) - \hat{u}_i(x, t)| \leq \sqrt{2nt} \quad \text{and} \quad \|H\|^2 \leq \frac{n}{2t}. \tag{5.9}$$

However since $\|\hat{u}_0\| < \chi_\epsilon$ by Lemma 5.1, we see that for any $x \in \partial B_1(0)$ the quasi-sphere centred at ϵx of radius $-(1 - \epsilon)^2$ contains \hat{u}_0 and therefore $\hat{u}_{0,i}$ is contained within this quasi-sphere for any i . We therefore see, by evolving such solutions that

$$\|\hat{u}_i(\cdot, t)\| < \chi_{\epsilon,t},$$

where

$$\chi_{\epsilon,t}(x) = \sqrt{\left|x - \epsilon \frac{x}{|x|}\right|^2 + 1 - \epsilon^2 + 2nt} = \sqrt{|x|^2 - 2\epsilon|x| + 1 + 2nt}.$$

We also observe that (writing points in $\mathbb{R}^{n,m}$ as pairs (x, z) for $x \in \mathbb{R}^n$ and $z \in \mathbb{R}^m$)

$$V = \{(x, z) \in \mathbb{R}^{n,m} \mid \|z\| < \chi_{\epsilon,t}(x)\}$$

has compact intersection with \mathcal{Q}_R for any finite R . Indeed, at any point $(x, z) \in V \cap \mathcal{Q}_R$,

$$|x|^2 - R^2 < \|z\|^2 < |x|^2 - 2\epsilon|x| + 1 + 2nt,$$

which implies that $|x| \leq (2\epsilon)^{-1}(1 + 2nt + R^2)$. As a result of the above, writing $M_t^i = \text{graph } \hat{u}_i(\cdot, t)$, for any time $t \in [0, T)$ and any point $(x, \hat{u}_i(x, t)) \in M_t^i \cap \mathcal{Q}_R$, we have the estimate

$$\|\hat{u}_i(x, t)\| < C(\epsilon, T, R),$$

which is uniform in i .

We may now apply Lemmas 4.6 and 4.7 to obtain estimates on gradient and curvature on $M_t^i \cap \mathcal{Q}_R$ for all $t \in (0, \frac{R^2}{4n})$ which are uniform in i . Uniform higher order estimates also follow from Lemma 4.9.

Taking a diagonal sequence as before now yields C_{loc}^∞ convergence to a solution \hat{u} which is smooth for $t > 0$. Since for each \hat{u}_i the estimates (5.9) hold, these estimates pass to the limit, providing the claimed regularity of \hat{u} to time $t = 0$. \square

6 Neumann Boundary Conditions

In this section we suppose that our spacelike MCF is over a compact domain $\Omega \subset \mathbb{R}^n \subset \mathbb{R}^{n,m}$ with smooth boundary $\partial\Omega$. We shall prove long-time existence and convergence

of spacelike MCF under the assumption of Neumann boundary conditions. This, in particular, completes the proof of long-time existence in the entire setting of Sect. 5.

Definition 6.1 We define the *boundary manifold* to be the hypersurface

$$\Sigma := \partial\Omega \times \mathbb{R}^m \subset \mathbb{R}^n \times \mathbb{R}^m = \mathbb{R}^{n,m}.$$

We denote the unit outwards (spacelike) normal to Σ by μ and, by abuse of notation, we will also write the outward pointing unit normal to $\partial\Omega \subset \mathbb{R}^n$ as μ . We denote the second fundamental form of Σ by

$$II^\Sigma(X, Y) = -\langle \bar{\nabla}_X Y, \mu \rangle,$$

and observe that this tensor has m zero eigenvectors in the directions e_1, \dots, e_m . The sign has been chosen so that the remaining eigenvalues are nonnegative if Ω is convex.

We consider a Neumann boundary condition by requiring that at Σ , the normal space to M_t must be contained in $T\Sigma$; that is, for any basis ν_1, \dots, ν_m ,

$$\langle \nu_A, \mu \rangle = 0 \tag{6.1}$$

for $A = 1, \dots, m$. MCF with a Neumann boundary condition is therefore a one-parameter family of immersions of a disk, $X : D^n \times [0, T) \rightarrow \mathbb{R}^{n,m}$, such that

$$\begin{cases} \left(\frac{dX}{dt}\right)^\perp = H & \text{on } D^n \times [0, T), \\ X(\cdot, t) = X_0(\cdot) & \text{on } D^n, \\ X(\partial D^n, t) \subset \Sigma & \text{for all } t \in [0, T), \\ \langle \nu_A, \mu \rangle = 0 & \text{on } \partial D^n \times [0, T). \end{cases} \tag{6.2}$$

Equivalently this may be rewritten in graphical coordinates. We say that $\hat{u} : \Omega \times [0, T) \rightarrow \mathbb{R}$ satisfies MCF with a Neumann boundary condition if

$$\begin{cases} \frac{d\hat{u}}{dt} - g^{ij}(D\hat{u})D_{ij}^2\hat{u} = 0 & \text{on } \Omega \times [0, T), \\ D_\mu\hat{u} = 0 & \text{on } \partial\Omega \times [0, T), \\ \hat{u}(\cdot, 0) = \hat{u}_0(\cdot) & \text{on } \Omega. \end{cases} \tag{6.3}$$

See Appendix A for details.

Since we have boundary conditions, if we want a solution which does not “jump” at time $t = 0$, we need some compatibility conditions (as mentioned in Sect. 5). Clearly we will require the zero order compatibility condition

$$D_\mu\hat{u}_0(x) = 0$$

for all $x \in \partial\Omega$ and more generally the l th order compatibility condition

$$D_\mu \frac{d^l}{dt^l} \hat{u}_0(x) = 0$$

for all $x \in \partial\Omega$, where $\frac{d}{dt}\hat{u}_0$ is defined recursively using the first line of (6.3). Higher order regularity is important as otherwise we cannot apply the maximum principle to quantities such as curvature to get estimates that depend on the initial data.

We now state our long-time existence and convergence theorem in this Neumann setting. The proof is somewhat lengthy and technical, and forms the remainder of this section. Here we give an outline of the proof assuming the key technical results we shall prove below. Recall the notion of uniformly spacelike from Definition 2.1 and what it means for a quasi-sphere to be an outer barrier in Definition 1.6.

Theorem 6.2 *Suppose Ω is a bounded convex domain with smooth boundary $\partial\Omega$ and \hat{u}_0 is smooth, uniformly spacelike and satisfies compatibility conditions to l th order for some $l \geq 0$. There exists a solution*

$$\hat{u} \in C^{1+2l+\alpha; \frac{1+2l+\alpha}{2}}(\Omega \times [0, \infty)) \cap C^\infty(\Omega \times (0, \infty))$$

of (6.3) which is unique if $l \geq 1$ and converges smoothly to a constant function as $t \rightarrow \infty$. Furthermore, expanding quasi-spheres centred in $\Omega \times \mathbb{R}^m$ act as outer barriers to the flow, and we have the uniform bounds

$$|\hat{u}_0(x) - \hat{u}(x, t)| \leq \sqrt{2nt} \quad \text{and} \quad \|\hat{u}\|^2 \leq \sup_{M_0} \|\hat{u}_0\|^2,$$

and, if $l \geq 1$,

$$\|H\|^2 \leq \frac{1}{(\sup_{M_0} \|H\|^2)^{-1} + \frac{2}{n}t}.$$

Proof Although (6.3) is a system, it has linear boundary conditions and is in the form of m parabolic PDEs. Therefore, standard application of fixed point theory and Schauder estimates for parabolic PDEs, for example by minor modifications of [26, Theorem 8.2], one obtains short time existence: there exists $T > 0$ such that a solution to (6.3) exists with $\hat{u} \in C^{l+1+\alpha; \frac{l+1+\alpha}{2}}(\Omega \times [0, T)) \cap C^\infty(\Omega \times (0, T))$.

As stated in Appendix A, the components \hat{u}^A of \hat{u} satisfy a uniformly parabolic PDE (given by the first line of (6.3)) if and only if v^2 is bounded. Furthermore, we may apply standard Schauder estimates as soon as we know that $\hat{u}^A \in C^{1+\alpha; \frac{1+\alpha}{2}}(\Omega \times [0, T))$ for all $A \in \{1, \dots, m\}$.

In Lemma 6.9 we demonstrate uniform C^0 estimates for solutions to (6.2). In Lemma 6.10 we give uniform estimates on v^2 , which imply both uniform parabolicity and C^1 estimates on \hat{u} . As the Nash–Moser–De Giorgi estimates do not hold for systems we then derive uniform curvature estimates (which imply C^2 estimates) in Proposition 6.13. As Schauder estimates now apply, by bootstrapping we have the long time existence claimed.

Lemma 6.15 then implies that the solution converges smoothly to a constant. Uniqueness of the solution is proven in Proposition B.1. □

6.1 Boundary Derivatives

We first study derivative conditions at the boundary, particularly those which are consequences of the Neumann boundary condition. We begin with two elementary observations.

Lemma 6.3 *On ∂M_t we have that*

$$\nabla_\mu u^A = 0.$$

Proof We see that $\nabla_\mu u^A = \langle \mu, e_A \rangle = 0$. □

Lemma 6.4 *Suppose that Ω is convex and $0 \in \Omega$. Then, at any $y \in \partial M_t$ we have*

$$\nabla_\mu |X|^2(y) > 0.$$

Proof We have that $\nabla_\mu |X|^2 = 2 \langle \mu, X \rangle > 0$ due to the convexity of Ω . □

By differentiating the Neumann boundary condition (6.1), we immediately have the following consequences. As these estimates will be applied to curvature quantities, we need a sufficiently differentiable solution for the curvature evolution equations to be valid. From now on we will assume that $\hat{u} \in C^{4+\alpha; \frac{4+\alpha}{2}}(\Omega \times [0, T])$, but remark that often this is overkill, for example for estimates on the gradient we only really require $\hat{u} \in C^{1+\alpha; \frac{1+\alpha}{2}}(\Omega \times [0, T]) \cap C^{3+\alpha; \frac{3+\alpha}{2}}(\Omega \times (0, T))$. Some of the boundary identities below hold in even weaker function spaces.

Lemma 6.5 *Suppose that we have a solution to (6.3) in $C^{4+\alpha; \frac{4+\alpha}{2}}(\Omega \times [0, T])$. Then for any $t \in [0, T]$, $y \in \partial M_t$ and $U \in T_y M \cap T_y \Sigma$,*

$$II(U, \mu) + \sum_A II^\Sigma(v_A, U)v_A = 0 \quad \text{and} \quad \nabla_\mu^\perp H + \sum_A II^\Sigma(v_A, H)v_A = 0.$$

Proof We differentiate (6.1) in direction U to obtain

$$0 = U \langle v_A, \mu \rangle = \langle \bar{\nabla}_U v_A, \mu \rangle + \langle v_A, \bar{\nabla}_U \mu \rangle = - \langle v_A, II(U, \mu) \rangle + II^\Sigma(v_A, U),$$

which yields the first claimed equation.

We differentiate (6.1) in time to get

$$0 = \left\langle \bar{\nabla}_{\frac{d}{dt}} v_A, \mu \right\rangle + \left\langle v_A, \bar{\nabla}_{\frac{d}{dt}} \mu \right\rangle = - \left\langle v_A, \nabla_\mu^\perp H \right\rangle + II^\Sigma(v_A, H),$$

giving the second claimed equation. □

Corollary 6.6 *Suppose that we have a solution to (6.3) in $C^{4+\alpha; \frac{4+\alpha}{2}}(\Omega \times [0, T])$. Then for any $t \in [0, T]$ on ∂M_t we may calculate that*

$$\nabla_\mu w_A^2 = -2II^\Sigma(e_A^\top, e_A^\top) \quad \text{and} \quad \nabla_\mu \|H\|^2 = -2II^\Sigma(H, H).$$

Proof We have

$$\nabla_\mu w_A^2 = -2 \sum_B \langle v_B, e_A \rangle \langle v_B, II(\mu, e_A^\top) \rangle = 2 \langle e_A^\perp, II(\mu, e_A^\top) \rangle.$$

Lemma 6.5 implies

$$\nabla_\mu w_A^2 = 2II^\Sigma(e_A^\perp, e_A^\top) = 2II^\Sigma(e_A - e_A^\top, e_A^\top) = -2II^\Sigma(e_A^\top, e_A^\top).$$

We have that $\nabla_\mu \|H\|^2 = -\nabla_\mu |H|^2 = -2 \langle \nabla_\mu^\perp H, H \rangle$. From Lemma 6.5 we have

$$\langle \nabla_\mu^\perp H, H \rangle - II^\Sigma(H, H) = 0,$$

so the result follows. □

We now calculate the second derivatives in space of the boundary condition. At any point $p \in \partial M_t$ we choose an orthonormal basis E_1, \dots, E_{n-1} of $T_p M_t \cap T_p \Sigma$. For the rest of this section, indices written with a hat such as $\hat{i}, \hat{j}, \hat{k}, \dots$ will be assumed to have values in $1, \dots, n - 1$.

Lemma 6.7 *Suppose that we have a solution to (6.3) in $C^{4+\alpha; \frac{4+\alpha}{2}}(\Omega \times [0, T])$. Then for any $t \in [0, T]$, $y \in \partial M_t$ and $U, V \in T_y M \cap T_y \Sigma$ we calculate that at y ,*

$$\begin{aligned} \nabla_\mu^\perp II(U, V) &= \sum_{A=1}^m [-\nabla_{v_A}^\Sigma II^\Sigma(U, V) - II^\Sigma(v_A, II(U, V))] v_A \\ &\quad + II^\Sigma(U, V) II(\mu, \mu) \\ &\quad - \sum_{\hat{i}=1}^{n-1} [II(V, E_{\hat{i}}) II^\Sigma(E_{\hat{i}}, U) + II(U, E_{\hat{i}}) II^\Sigma(E_{\hat{i}}, V)]. \end{aligned}$$

Proof We have that

$$\begin{aligned} 0 &= V[\langle v_A, II(U, \mu) \rangle - II^\Sigma(v_A, U)] \\ &= \langle \nabla_V^\perp v_A, II(U, \mu) \rangle + \langle v_A, \nabla_V^\perp II(U, \mu) \rangle + \langle v_A, II(\nabla_V U, \mu) \rangle \\ &\quad + \langle v_A, II(U, \nabla_V \mu) \rangle \\ &\quad - \nabla_V^\Sigma II^\Sigma(v_A, U) - II^\Sigma(\nabla_V^\Sigma v_A, U) - II^\Sigma(v_A, \nabla_V^\Sigma U) \\ &= \langle v_A, \nabla_V^\perp II(U, \mu) \rangle - \nabla_V^\Sigma II^\Sigma(v_A, U) + \langle \nabla_V^\perp v_A, II(U, \mu) \rangle - II^\Sigma(\nabla_V^\Sigma v_A, U) \\ &\quad + \langle v_A, II(\nabla_V U, \mu) \rangle - II^\Sigma(v_A, \nabla_V^\Sigma U) + \langle v_A, II(U, \nabla_V \mu) \rangle \\ &= \langle v_A, \nabla_\mu^\perp II(U, V) \rangle - \nabla_{v_A}^\Sigma II^\Sigma(U, V) - II^\Sigma(U, V) \langle v_A, II(\mu, \mu) \rangle \end{aligned}$$

$$\begin{aligned}
 & - II^\Sigma(v_A, II(U, V)) + \sum_{\hat{i}=1}^{n-1} [\langle v_A, II(V, E_{\hat{i}}) \rangle II^\Sigma(E_{\hat{i}}, U) \\
 & + \langle v_I, II(U, E_{\hat{i}}) \rangle II^\Sigma(E_{\hat{i}}, V)]
 \end{aligned}$$

where we used Lemma 6.5 repeatedly to obtain the third equality. □

Corollary 6.8 *Suppose that we have a solution to (6.3) in $C^{4+\alpha; \frac{4+\alpha}{2}}(\Omega \times [0, T])$. Then, for all $t \in [0, T)$, on ∂M_t we calculate that,*

$$\begin{aligned}
 \nabla_\mu^\perp II(\mu, \mu) &= \sum_{A=1}^m \sum_{\hat{i}=1}^{n-1} [\nabla_{v_A}^\Sigma II^\Sigma(E_{\hat{i}}, E_{\hat{i}}) v_A] + 2 \sum_{\hat{i}, \hat{j}=1}^{n-1} [II^\Sigma(E_{\hat{i}}, E_{\hat{j}}) II(E_{\hat{i}}, E_{\hat{j}})] \\
 &\quad - \sum_{A=1}^m II^\Sigma(v_A, II(\mu, \mu)) v_A - \sum_{\hat{i}=1}^{n-1} II^\Sigma(E_{\hat{i}}, E_{\hat{i}}) II(\mu, \mu).
 \end{aligned}$$

Proof Noting that $II(\mu, \mu) = H - \sum_{\hat{i}} II(E_{\hat{i}}, E_{\hat{i}})$, the result follows immediately from Lemmas 6.5 and 6.7. □

6.2 C^0 and Gradient Estimates

We now derive height, gradient and mean curvature bounds for solutions to spacelike MCF with Neumann boundary conditions.

Lemma 6.9 *Suppose we have a spacelike solution to (6.3) for $t \in [0, T)$ and Ω is convex.*

- (a) *Expanding quasi-spheres centred in $\Omega \times \mathbb{R}^m$ act as outer barriers to the flow.*
- (b) *For all $y \in M_t$ and $1 \leq A \leq m$,*

$$\inf_{M_0} u^A \leq u^A(y, t) \leq \sup_{M_0} u^A.$$

- (c) *As a graph over $x_0 \in \Omega$,*

$$\|\hat{u}(x_0, 0) - \hat{u}(x_0, t)\| \leq \sqrt{2nt}.$$

Proof Lemma 6.4 implies that $\nabla_\mu(|X|^2 + 2nt) \geq 0$. Corollary 3.2 and the maximum principle (see [31, Theorem 3.1]) therefore imply that if $|X|^2 + 2nt \geq -R^2$ initially, then this is preserved, giving (a).

The claim in (b) follows similarly from Corollary 3.2 and Lemma 6.3.

The final statement follows by attaching an expanding quasi-sphere of radius 0 at $x \in \text{graph } \hat{u}_0$. At $t = 0$, this is exactly the lightcone. Since \hat{u}_0 is spacelike the lightcone cannot touch the graph anywhere except this point and so we may apply (a) to see that M_t stays inside the expanding quasi-sphere. This implies (c). □

Lemma 6.10 *Suppose that Ω is convex. Then for all $t \in [0, T)$ and $y \in M_t$,*

$$w_A^2(y, t) \leq \sup_{M_0} w_A^2, \quad v^2(y, t) \leq \sup_{M_0} v^2, \quad \|H\|(y, t) \leq \sup_{M_0} \|H\|^2.$$

Proof Convexity implies that II^Σ is nonnegative definite and so Corollary 6.6 yields

$$\nabla_\mu w_A^2 \leq 0, \quad \nabla_\mu v^2 \leq 0, \quad \nabla_\mu \|H\|^2 \leq 0.$$

The maximum principle (see [31, Theorem 3.1]), Lemmas 3.8 and 3.9 then give the estimates. □

6.3 Curvature Estimates

The main difficulty in estimating $\|II\|^2$ for MCF with a Neumann boundary condition is that we cannot obtain useful estimates on $\nabla_\mu \|II\|^2$ directly (in general), as the boundary derivatives we studied above give us no information on $\nabla_\mu II(\mu, E_i)$. However, since we have a uniform gradient estimate we may use methods similar to those of Edelen [15] to obtain curvature estimates. The idea is to perturb II so that μ is an eigenvector, and then get estimates on the perturbed second fundamental form. This is the core of the technical work in this Neumann problem.

The curvature estimates will rely on our earlier gradient and mean curvature estimates, and throughout this subsection we will assume that

$$v^2 \leq C_v, \quad \|H\|^2 \leq C_H. \tag{6.4}$$

We take smooth uniformly bounded extensions of the tensor II^Σ and the vector μ to $\mathbb{R}^{n,m}$ which, by abuse of notation we will also write as II^Σ and μ respectively. For simplicity we also assume that at Σ ,

$$\bar{\nabla}_\mu \mu = 0, \quad \bar{\nabla}_\mu II^\Sigma = 0.$$

Such smooth extensions exist, see Lemma D.1. By assumption we may estimate using (2.3) and (6.4) to obtain that on M_t , in normal coordinates we have that there exists a constant C depending only on the extension II^Σ and C_v such that

$$|\bar{\nabla}_k \bar{\nabla}_i II^\Sigma(X_j, \nu_A)| \leq C.$$

Similar estimates hold for all other derivatives of II^Σ and μ , and this will be used liberally in the following lemmas.

We now define the NM -valued tensor

$$\bar{II}(U, V) = II(U, V) + c \langle U, V \rangle e_1^\perp + \sum_{A=1}^m [\bar{T}(U, V, \nu_A)] \nu_A,$$

for some $c > 0$ to be defined later, where

$$\bar{T}(U, V, W) = II^\Sigma(U, W) \langle V, \mu \rangle + II^\Sigma(V, W) \langle U, \mu \rangle.$$

We note that due to our assumptions on the extensions of II^Σ and μ , on Σ , $\bar{\nabla}_\mu T(\cdot, \cdot, \cdot) = 0$.

One key property of \bar{II} is that, by Lemma 6.5, at the boundary we have that

$$\bar{II}(\mu, E_{\hat{i}}) = II(E_{\hat{i}}, \mu) + \sum_{A=1}^m II^\Sigma(E_{\hat{i}}, \nu_A) \nu_A = 0$$

holds for all $E_{\hat{i}}$; that is, μ is an eigenvector of $\langle \bar{II}(U, V), \nu_A \rangle$ for all $A \in \{1, \dots, m\}$. A second important property is that we may choose c , depending on our bounds on v^2 , $\|H\|^2$ and the tensor \bar{T} , to be sufficiently large so that

$$\|\bar{H}\|^2 := \|g^{ij} \bar{II}_{ij}\|^2 \geq n.$$

This implies an important lower bound, namely

$$\|\bar{II}\|^2 \geq 1. \quad (6.5)$$

From now on we assume $c = c(C_v, C_H, \bar{T}) > 0$ is sufficiently large so that (6.5) holds. As a result, we also have that there exists a constant $C = C(C_v, C_H, \bar{T})$ such that

$$\|II\|^2 \leq C(\|\bar{II}\|^2 + 1) \leq 2C\|\bar{II}\|^2. \quad (6.6)$$

We now estimate the boundary derivative of the size of the perturbed curvature tensor \bar{II} in this Neumann setting.

Lemma 6.11 *Suppose we have a solution of (6.3) satisfying (6.4). Then, there exists a constant $\kappa > 0$ depending only on $n, m, II^\Sigma, \nabla^\Sigma II^\Sigma, \bar{T}, C_v$ and C_H such that at any point $p \in \partial M_t$,*

$$\nabla_\mu \|\bar{II}\|^2 \leq \kappa \|\bar{II}\|^2.$$

Proof We see that (using Lemma 3.3)

$$\begin{aligned} & \nabla_\mu^\perp \bar{II}(E_{\hat{i}}, E_{\hat{j}}) \\ &= \nabla_\mu^\perp II(E_{\hat{i}}, E_{\hat{j}}) + c \delta_{\hat{i}\hat{j}} II(e_1^\perp, \mu) \\ &+ \sum_{I=1}^m \left[\bar{\nabla}_\mu \bar{T}(E_{\hat{i}}, E_{\hat{j}}, \nu_I) + \bar{T}(II(\mu, E_{\hat{i}}), E_{\hat{j}}, \nu_I) \right. \\ & \left. + \bar{T}(E_{\hat{i}}, II(\mu, E_{\hat{j}}), \nu_I) - \bar{T}(E_{\hat{i}}, E_{\hat{j}}, X^j) \langle II(X_j, \mu), \nu_I \rangle \right] \nu_I \end{aligned}$$

$$\begin{aligned}
 &= \nabla_{\mu}^{\perp} II(E_{\hat{i}}, E_{\hat{j}}) + c\delta_{\hat{i}\hat{j}}II(e_1^{\top}, \mu) \\
 &\quad + \sum_{l=1}^m [\bar{T}(II(\mu, E_{\hat{i}}), E_{\hat{j}}, \nu_l) + \bar{T}(E_{\hat{i}}, II(\mu, E_{\hat{j}}), \nu_l)] \nu_l .
 \end{aligned}$$

Using the inequalities (6.4), (6.5) and (6.6) and Lemma 6.7, we may therefore estimate that

$$\|\nabla_{\mu}^{\perp} \bar{II}(E_{\hat{i}}, E_{\hat{j}})\| \leq \kappa_1 \|\bar{II}\| ,$$

where κ_1 depends on $n, m, II^{\Sigma}, \nabla^{\Sigma} II^{\Sigma}, \bar{T}, C_v$ and C_H . Similarly,

$$\begin{aligned}
 &\nabla_{\mu}^{\perp} \bar{II}(\mu, \mu) \\
 &= \nabla_{\mu}^{\perp} II(\mu, \mu) + cII(e_1^{\top}, \mu) \\
 &\quad + \sum_{l=1}^m \left[\bar{T}(II(\mu, \mu), \mu, \nu_l) + \bar{T}(\mu, II(\mu, \mu), \nu_l) \right. \\
 &\quad \left. - \bar{T}(\mu, \mu, X^i) \langle II(\mu, X_i), \nu_l \rangle \right] \nu_l ,
 \end{aligned}$$

and again we may estimate

$$\|\nabla_{\mu}^{\perp} \bar{II}(\mu, \mu)\| \leq \kappa_2 \|\bar{II}\| ,$$

where again κ_2 depends on $n, m, II^{\Sigma}, \nabla^{\Sigma} II^{\Sigma}, \bar{T}, C_v$ and C_H . Hence, due to the eigenvector property of μ in \bar{II} , we see that

$$\begin{aligned}
 \nabla_{\mu} \|\bar{II}\|^2 &= -2 \left\langle \bar{II}_{ij}, \nabla_{\mu}^{\perp} \bar{II}^{ij} \right\rangle \\
 &= -2 \left\langle \bar{II}(\mu, \mu), \nabla_{\mu}^{\perp} \bar{II}(\mu, \mu) \right\rangle - 2 \sum_{\hat{i}, \hat{j}=1}^{n-1} \left\langle \bar{II}(E_{\hat{i}}, E_{\hat{j}}), \nabla_{\mu}^{\perp} \bar{II}(E_{\hat{i}}, E_{\hat{j}}) \right\rangle \\
 &\leq \kappa \|\bar{II}\|^2
 \end{aligned}$$

as required. □

We now estimate the evolution of $\|\bar{II}\|^2$.

Lemma 6.12 *Suppose we have a solution of (6.3) satisfying (6.4). Then there exists a constant $C > 0$ depending only on $n, m, II^{\Sigma}, \nabla^{\Sigma} II^{\Sigma}, \mu, \bar{\nabla}\mu, \bar{T}, \bar{\nabla}\bar{T}, C_v$ and C_H such that*

$$\left(\frac{d}{dt} - \Delta \right) \|\bar{II}\|^2 \leq -\frac{2}{m} \|\bar{II}\|^4 + C \|\bar{II}\|^3 .$$

Proof We write C for any constant depending only on the quantities in the statement of the lemma, where C is allowed to change from line to line. We write $\overline{II} = II + S$ and note that

$$\|\overline{II}\|^2 = \|II\|^2 - 2h_{ij}^A S_A^{ij} + |S|^2,$$

where $S_{ijA} = \overline{T}(X_i, X_j, \nu_A) + g_{ij} \langle e_1, \nu_A \rangle$. We have that

$$\begin{aligned} \overline{T}(X_i, X_j, \nu_A) &= \sum_{l=1}^m [II^\Sigma(X_i, e_l) \langle X_j, \mu \rangle + II^\Sigma(X_j, e_l) \langle X_i, \mu \rangle] \langle e_l, \nu_A \rangle \\ &+ \sum_{j=1}^m [II^\Sigma(X_i, f_k) \langle X_j, \mu \rangle + II^\Sigma(X_j, f_k) \langle X_i, \mu \rangle] \langle f_k, \nu_A \rangle. \end{aligned}$$

As we have written \overline{T} (and therefore S) as a concatenation of tensors of the forms considered in Lemma C.1 (for the square brackets) and Lemma 3.3 (for the normal inner product), we may see that there exists a C such that (in orthonormal coordinates),

$$\left| \left(\frac{d}{dt} - \Delta \right) S_{ijA} \right| \leq C(\|II\|^2 + 1) \leq C\|\overline{II}\|^2.$$

Since the same lemmas also imply that $|\nabla_k S_{ijA}| \leq C\|\overline{II}\|$, we have that

$$\left(\frac{d}{dt} - \Delta \right) |S|^2 \leq C\|\overline{II}\|^2.$$

Similarly we see that using Lemma 3.9

$$\begin{aligned} \left(\frac{d}{dt} - \Delta \right) (-h_{ij}^A S_A^{ij}) &= -S_A^{ij} \left(\frac{d}{dt} - \Delta \right) h_{ij}^A - h_{ij}^A \left(\frac{d}{dt} - \Delta \right) S_A^{ij} + 2\nabla_k h_{ij}^A \nabla^k S_A^{ij} \\ &\leq C\|\overline{II}\|^3 + 2\nabla_k h_{ij}^A \nabla^k S_A^{ij}. \end{aligned}$$

Therefore,

$$\begin{aligned} \left(\frac{d}{dt} - \Delta \right) \|\overline{II}\|^2 &\leq -\frac{2}{m} \|II\|^4 - 2\|\nabla^\perp II\|^2 + 4\nabla_k h_{ij}^A \nabla^k \overline{S}_A^{ij} + C\|\overline{II}\|^3 \\ &\leq -\frac{2}{m} \|\overline{II}\|^4 + C\|\overline{II}\|^3, \end{aligned}$$

where we used Young’s inequality to estimate the third term on the right hand side of the first line. □

Putting all of the results of this subsection together provides the following curvature estimate.

Proposition 6.13 *Suppose we have a solution of (6.3) satisfying (6.4). Then there exists a constant C depending on $n, m, H^\Sigma, \nabla^\Sigma H^\Sigma, \mu, \bar{\nabla}\mu, \bar{T}, \bar{\nabla}\bar{T}, M_0, C_v$ and C_H such that*

$$\|H\|^2 \leq C.$$

Proof Let C be as in the previous lemma. We take the standard Euclidean distance to $\partial\Omega$ in \mathbb{R}^n and extend it to $\mathbb{R}^{n,m}$ by pullback under the standard projection. We call this function d and see that due to the gradient estimate for all $t \in [0, T)$

$$\left(\frac{d}{dt} - \Delta\right)d \leq C \text{ on } M_t \quad \text{and} \quad \nabla_\mu d = -1 \text{ on } \partial M_t.$$

Lemma 6.11 implies that the function $f = \|\bar{H}\|^2 e^{\lambda d}$ satisfies

$$\nabla_\mu f = (\kappa - \lambda)f$$

on ∂M_t . We choose λ sufficiently large so that $\nabla_\mu f$ is negative, meaning that no boundary maxima may occur. At any interior increasing maximum,

$$\begin{aligned} 0 &\leq \left(\frac{d}{dt} - \Delta\right)f \\ &\leq e^{\lambda d} \left[-\frac{2}{m}\|\bar{H}\|^4 + C\|\bar{H}\|^3 - 2\lambda \langle \nabla\|\bar{H}\|^2, \nabla d \rangle + C\lambda\|\bar{H}\|^2 - \lambda^2|\nabla d|^2\|\bar{H}\|^2\right] \\ &= e^{\lambda d} \left[-\frac{2}{m}\|\bar{H}\|^4 + C\|\bar{H}\|^3 + C\lambda\|\bar{H}\|^2 + \lambda^2|\nabla d|^2\|\bar{H}\|^2\right] \\ &\leq e^{\lambda d} \left[-\frac{2}{m}\|\bar{H}\|^4 + C\|\bar{H}\|^3\right]. \end{aligned}$$

Hence at any increasing stationary point, $\|\bar{H}\|^2$ is bounded, and so f is bounded. The maximum principle indicates that f is therefore bounded (as d is bounded) and hence $\|\bar{H}\|^2$ is bounded everywhere. The result now follows. \square

Remark 6.14 The above proof holds for much more general boundary manifolds Σ . In fact, for any mean curvature flow in $\mathbb{R}^{n,m}$ with a perpendicular boundary condition on a smooth manifold Σ , an identical proof will show that gradient and mean curvature estimates imply full boundary curvature estimates. This therefore replaces the missing Nash–Moser–De Giorgi estimates for this parabolic system.

6.4 Convergence

We now complete the proof of Theorem 6.2 by proving convergence of spacelike MCF under Neumann boundary conditions.

Lemma 6.15 *Suppose that we have a solution \hat{u} to (6.3) for $T = \infty$ with uniform $C^{k;\frac{k}{2}}(\Omega \times [0, \infty))$ estimates for all $k \geq 0$. Then \hat{u} converges uniformly in C^∞ to a constant function as $t \rightarrow \infty$.*

Proof The proof is in fact identical to the codimension one case [21], which we include here for the convenience of the reader.

By Lemma 6.9 we have that $\|\hat{u}\|^2$ is uniformly bounded for all time by its initial value. By considering the metric in terms of the graph function \hat{u} , we see that

$$\int_{M_t} dV = \int_{\Omega} \sqrt{\det g_{ij}} dx \leq |\Omega|.$$

We therefore see that since

$$\frac{d}{dt} \int_{M_t} dV = \int_{M_t} \|H\|^2 dV$$

(which follows from [24, equation (4.1)] and the Neumann boundary condition) we have that

$$\int_0^T \int_{M_t} \|H\|^2 \leq |\Omega| - |M_0| < |\Omega|.$$

By Corollary 3.2, Lemma 6.3, the L^2 estimate on H , and divergence theorem we see that

$$\begin{aligned} \frac{d}{dt} \int_{M_t} u_A^2 dV &= -2 \int_{M_t} |\nabla u_A|^2 + \int_{M_t} u_A^2 \|H\|^2 dV \\ &= -2 \int_{M_t} (w_A^2 - 1) dV + \int_{M_t} u_A^2 \|H\|^2 dV \end{aligned}$$

or, due to the uniform estimate on u_A and $|M_t|$, and calculations in Appendix A,

$$\int_0^\infty \int_{M_t} (w_A^2 - 1) dV dt \leq C(M_0, \Omega).$$

Rewriting this over Ω , using the uniform gradient bound and (A.1) gives

$$\int_0^\infty \int_{\Omega} |D\hat{u}_A|^2 dx dt \leq \tilde{C}(M_0, \Omega).$$

The uniform $C^{k;\frac{k}{2}}$ estimates imply $|D\hat{u}_A| \rightarrow 0$ as $t \rightarrow \infty$. The range of \hat{u}_A is also monotonically decreasing with time due to estimates as in Lemma 6.9. Therefore, each \hat{u}_A converges uniformly to a constant as $t \rightarrow \infty$. The uniform $C^{k;\frac{k}{2}}$ estimates and Ehrling’s lemma now imply that the convergence is in fact smooth. \square

7 Dirichlet Boundary Conditions

In this section we wish to consider evolving a topological disk by spacelike mean curvature flow, where the boundary is held on some fixed $(n - 1)$ -dimensional spacelike submanifold of $\mathbb{R}^{n,m}$.

We state this boundary condition graphically. Suppose that $\Omega \subset \mathbb{R}^n$ is a compact domain with smooth boundary $\partial\Omega$. We denote the outward unit normal to $\partial\Omega$ by μ . The boundary data for the Dirichlet problem is given by smooth functions $\phi : \overline{\Omega} \rightarrow \mathbb{R}^m$.

To ensure that the Dirichlet problem is well-posed we require a constraint on our choice of boundary data as follows.

Definition 7.1 We say that $\phi : \overline{\Omega} \rightarrow \mathbb{R}^m$ is *acausal* if for all $x, y \in \partial\Omega$

$$\|\phi(x) - \phi(y)\| \leq |x - y|. \tag{7.1}$$

Clearly, in a convex domain this is a necessary condition if we are to have a spacelike graph, due to the mean value theorem. Due to compactness, the boundary data is in fact *strictly acausal*: there exists a $\delta > 0$ such that

$$\|\phi(x) - \phi(y)\| \leq (1 - \delta)|x - y|.$$

The acausal condition for the Dirichlet problem for maximal spacelike submanifolds in $\mathbb{R}^{n,m}$ arises in the recent work of Yang Li [25]. We shall assume that our chosen Dirichlet data ϕ is acausal.

Mean curvature flow with a Dirichlet boundary condition starting at an initial graph \hat{u}_0 is now defined by $\hat{u} : \Omega \times [0, T) \rightarrow \mathbb{R}^m$ where

$$\begin{cases} \frac{d\hat{u}}{dt} - g^{ij}(D\hat{u})D_{ij}\hat{u} = 0 & \text{on } \Omega \times [0, T), \\ \hat{u} = \phi & \text{on } \partial\Omega \times [0, T), \\ \hat{u}(\cdot, 0) = \hat{u}_0(\cdot) & \text{on } \Omega. \end{cases} \tag{7.2}$$

As previously, we define $M_t := \text{graph } \hat{u}(\cdot, t)$. As in the Neumann case, to have higher order regularity initially, we require some assumptions on \hat{u}_0 .

The zeroth order compatibility condition is defined to be that

$$\hat{u}_0(x) = \phi(x) \quad \text{for all } x \in \partial\Omega$$

We define the k th order compatibility condition is given by

$$\frac{d^k}{dt^k} \hat{u}_0(x) = 0 \quad \text{for all } x \in \partial\Omega,$$

where $\frac{d}{dt} \hat{u}_0$ is defined recursively by the first line of (7.2).

The key difficulty in proving long time existence for 7.2 is in obtaining suitable boundary gradient estimates. Fortunately, Li [25] has recently produced suitable barriers for the Dirichlet problem for the higher codimensional maximal submanifold system (i.e. the elliptic equivalent of (7.2)): these are the higher codimensional equivalents of the barriers in [4]. We will show below that (unsurprisingly) these also act as barriers to (7.2).

We now state our long-time existence and convergence theorem in the Dirichlet setting. The proof is again quite long and technical, and forms the remainder of the section. We shall, as in the Neumann case, give an outline of the proof where we assume the key technical results proved below. We again recall the definitions for an expanding quasi-sphere to be an outer barrier and of uniformly spacelike, from Definitions 1.6 and 2.1 respectively.

Theorem 7.2 *Suppose Ω is a bounded domain with smooth boundary $\partial\Omega$, ϕ is acausal boundary data and $\hat{u}_0 : \Omega \rightarrow \mathbb{R}^m$ is uniformly spacelike satisfying compatibility conditions to the l th order for some $l \geq 0$. There exists a solution*

$$\hat{u} \in C^{2l+\alpha; \frac{2l+\alpha}{2}}(\Omega \times [0, \infty)) \cap C^\infty(\Omega \times (0, \infty))$$

of (7.2) which is unique if $l \geq 1$ and converges smoothly to the unique maximal submanifold with boundary data ϕ as $t \rightarrow \infty$. Furthermore, expanding quasi-spheres centred in $\Omega \times \mathbb{R}^m$ act as barriers to the flow and we have the uniform bounds

$$|\hat{u}_0(x) - \hat{u}(x, t)| \leq \sqrt{2nt} \quad \text{and} \quad \|u\|^2 \leq \sup_{M_0} \|u\|^2,$$

and, if $l \geq 1$,

$$\|H\|^2 \leq \frac{1}{(\sup_{M_0} \|H\|^2)^{-1} + \frac{2}{n}t}.$$

Proof The system (7.2) is in the form of m parabolic PDEs with linear boundary conditions. This implies that short time existence (the existence of $T > 0$ such that there is a solution $\hat{u} \in C^{l+1+\alpha; \frac{l+1+\alpha}{2}}(\Omega \times [0, T)) \cap C^\infty(\Omega \times (0, T))$ to (7.2)) follows from a standard application of fixed point theory and Schauder estimates for parabolic PDEs, for example by very minor modifications of [26, Theorem 8.2].

As stated in Appendix A, each component \hat{u}^A of \hat{u} satisfies a uniformly parabolic PDE (given by the first line of (7.2)) if and only if v^2 is bounded. Furthermore, we may apply standard Schauder estimates as soon as we know that our solution satisfies $\hat{u}^A \in C^{1+\alpha; \frac{1+\alpha}{2}}(\Omega \times [0, T))$ for all A .

In Lemma 7.4 we demonstrate uniform C^0 estimates for solutions to (7.2). In Proposition 7.9 we give uniform estimates on v^2 , which imply both uniform parabolicity and C^1 estimates on \hat{u} . Lemma 7.11 then implies that we have uniform estimates in $C^{1+\alpha; \frac{1+\alpha}{2}}$. As Schauder estimates now apply, by bootstrapping we have uniform higher order estimates and the long time existence claimed.

Lemma 7.12 finally implies that the solution converges smoothly to the unique maximal submanifold with boundary data ϕ . The fact that the maximal submanifold is unique is a consequence of [25, Theorem 2.1]. Uniqueness of the flow solution is proven in Proposition B.1. \square

Remark 7.3 The existence and uniqueness of a solution to the Dirichlet problem for maximal submanifolds in $\mathbb{R}^{n,m}$ with acausal boundary data is given in [25, Theorem 2.1]. Theorem 7.2 can be viewed as an extension of this result.

Throughout this section we will write a point $(x, y) \in \mathbb{R}^{n,m} = \mathbb{R}^n \oplus \mathbb{R}^m$. For any two vectors $y, z \in \mathbb{R}^m$ we will write the inner product associated to the norm $\|\cdot\|$ as $y \cdot z$: this is just the standard Euclidean inner product on \mathbb{R}^m .

7.1 C^0 Estimates

We first derive some simple C^0 bounds on solutions to spacelike MCF with Dirichlet boundary conditions, just as in the Neumann case.

Lemma 7.4 *For any spacelike solution of (7.2) we have the following.*

- (a) *Expanding quasi-spheres centred in $\Omega \times \mathbb{R}^m$ act as outer barriers.*
- (b) *For all $(x, t) \in \Omega \times [0, T)$,*

$$|\hat{u}(x, t)| \leq \sup_{y \in \Omega} |\hat{u}_0(y)|.$$

- (c) *For all $x \in \Omega$,*

$$\|\hat{u}_0(x) - \hat{u}(x, t)\| \leq \sqrt{2nt}.$$

Proof Let $p \in \mathbb{R}^{n,m}$. Suppose that for all $y \in M_0$, $|y - p|^2 \geq -R^2$. Clearly, as the boundary of M_t is fixed, this implies that for all $z \in \partial M_t$, $|z - p|^2 \geq -R^2 \geq -R^2 - 2nt$. The weak maximum principle applied to $f = |X - p|^2 + 2nt$ and Corollary 3.2 now imply (a).

Similarly, (b) follows from Corollary 3.2 and the weak maximum principle.

Part (c) follows from considering an expanding quasi-sphere starting from a light cone centred at $(x, \hat{u}(x))$. \square

7.2 C^1 Estimates

Our goal now is to obtain bounds on the gradient and mean curvature of solutions to spacelike MCF with Dirichlet boundary conditions. This forms the main technical work required in this Dirichlet problem.

We first recall the barriers constructed in [25]. We consider a 2-parameter family of curves $\Gamma_{K,\Lambda} \subset \mathbb{R}^{1,1} \subset \mathbb{R}^{n,m}$ from which we will produce a hypersurface $\tilde{\Gamma}_{K,\Lambda} \subset \mathbb{R}^{n,m}$ by assuming an $SO(n - 1) \times SO(m - 1)$ symmetry.

Definition 7.5 Let $K > 0$ and let $\Lambda \leq 0$. Taking orthogonal coordinates r, w of $\mathbb{R}^{1,1}$ (where $\frac{\partial}{\partial r}$ is spacelike) we write $\Gamma_{K,\Lambda}$ graphically as

$$\Gamma_{K,\Lambda} := \{(r, w) \in \mathbb{R}^{1,1} \mid w = f_{K,\Lambda}(|r|)\},$$

where

$$f_{K,\Lambda}(r) = \int_0^r \frac{K + n^{-1}\Lambda t^n}{\sqrt{t^{2n-2} + (K + n^{-1}\Lambda t^n)^2}} dt.$$

Let $\xi \in \mathbb{R}^n$ and $\eta \in \mathbb{R}^m$. We define the functions

$$r(x, y) := |x - \xi|, \quad w(x, y) := |y - \eta|$$

for $(x, y) \in \mathbb{R}^{n,m}$. We then define the barrier hypersurface $\tilde{\Gamma}_{K,\Lambda}$, centred at (ξ, η) by

$$\tilde{\Gamma}_{K,\Lambda} := \{(x, y) \in \mathbb{R}^{n,m} \mid w(x, y) = f_{K,\Lambda}(r(x, y))\}.$$

When $f'_{K,\Lambda} < 1$ we write the unit normal to $\tilde{\Gamma}_{K,\Lambda}$ at (x, y) by

$$\tilde{n}(x, y) = \frac{1}{\sqrt{1 - (f'_{K,\Lambda})^2}} (-\bar{\nabla}w + f'_{K,\Lambda} \bar{\nabla}r).$$

Several observations in [25, Sect. 3.1] will be of use to us. We note that

$$f'_{K,\Lambda} = \frac{Kr^{1-n} + \Lambda n^{-1}r}{\sqrt{1 + (Kr^{1-n} + \Lambda n^{-1}r)^2}} \quad \text{and} \quad \frac{f'_{K,\Lambda}}{\sqrt{1 - (f'_{K,\Lambda})^2}} = \Lambda n^{-1}r + Kr^{1-n}.$$

We will therefore always assume that

$$0 < r < \left(\frac{nK}{|\Lambda|}\right)^{\frac{1}{n}}.$$

Within this range \tilde{n} is timelike, $\tilde{\Gamma}_{K,\Lambda}$ has a nondegenerate semi-Riemannian metric, and $\Gamma_{K,\Lambda}$ is a spacelike curve. As $r \rightarrow 0$, both $\Gamma_{K,\Lambda}$ and $\tilde{\Gamma}_{K,\Lambda}$ are tangent to the lightcone.

We may estimate that if $K = \epsilon^{-1}$, $\Lambda < 0$ such that $\epsilon < \left(\frac{n}{2|\Lambda|}\right)^{\frac{1}{n+1}}$ then

$$f_{K,\Lambda}(\epsilon) = \int_0^\epsilon \sqrt{1 - \frac{t^{2n-2}}{t^{2n-2} + (K - n^{-1}|\Lambda|t^n)^2}} dt > \epsilon \sqrt{1 - 4\epsilon^{2n}}. \tag{7.3}$$

At any point $p \in \tilde{\Gamma}_{K,\Lambda} \cap \mathcal{C}_{\left(\frac{nK}{|\Lambda}\right)^{\frac{1}{n}}}(\xi)$ and any n -dimensional spacelike hyperplane $\Pi \subset T_p \tilde{\Gamma}_{K,\Lambda}$, we define

$$H_{\Pi} := - \sum_i \langle b_i, \bar{\nabla}_{b_i} \tilde{n} \rangle,$$

where b_1, \dots, b_n is an orthonormal basis of Π . The following observation, proven in [25, Lemma 3.1], will be vital in demonstrating that the $\tilde{\Gamma}_{K,\Lambda}$ are barriers.

Lemma 7.6 *Let $p \in \tilde{\Gamma}_{K,\Lambda} \cap \mathcal{C}_{\left(\frac{nK}{|\Lambda}\right)^{\frac{1}{n}}}(\xi)$ and $\Pi \subset T_p \tilde{\Gamma}_{K,\Lambda}$ be an n -dimensional spacelike hyperplane. Then*

$$H_{\Pi} \geq -\Lambda .$$

The following demonstrates that the solutions $\tilde{\Gamma}_{K,\Lambda}$ act as barriers and is a parabolic version of [25, Lemma 3.2].

Lemma 7.7 *Suppose that M_t is a spacelike solution to (7.2) and $\xi \in \mathbb{R}^n \setminus \bar{\Omega}$, $\eta \in \mathbb{R}^m$, $K > 0$ and $\Lambda < 0$ are chosen such that*

$$r(z) < \left(\frac{nK}{|\Lambda}\right)^{\frac{1}{n}} \text{ for all } z \in \Omega \text{ and } M_0 \subset \{(x, y) \in \mathbb{R}^{n,m} \mid w(x, y) \leq f_{K,\Lambda}(r(x, y))\}.$$

For all $t \in [0, T)$,

$$M_t \subset \{(x, y) \in \mathbb{R}^{n,m} \mid w(x, y) \leq f_{K,\Lambda}(r(x, y))\}.$$

Proof Let $\tilde{K} > K$, and observe that

$$\begin{aligned} M_0 &\subset \{(x, y) \in \mathbb{R}^{n,m} \mid w(x, y) \leq f_{K,\Lambda}(r(x, y))\} \\ &\subset \{(x, y) \in \mathbb{R}^{n,m} \mid w(x, y) < f_{\tilde{K},\Lambda}(r(x, y))\}. \end{aligned}$$

We consider the function

$$h := w - f_{\tilde{K},\Lambda}.$$

Clearly this is negative on M_0 . We suppose that t_0 is the first time when there exists $p_0 \in M_{t_0}$ such that $h(p_0) = 0$. As $\partial M_t = \partial M_0$ for all t and h is negative on \bar{M}_0 , p_0 cannot be a boundary point. Furthermore, $p_0 \in \tilde{\Gamma}_{\tilde{K},\Lambda}$ and $\nabla h(p_0) = 0$, so $T_{p_0} M_{t_0} \subset T_{p_0} \tilde{\Gamma}_{\tilde{K},\Lambda}$.

Let b_1, \dots, b_n be an orthonormal basis of $T_{p_0} M_{t_0}$. Since $\bar{\nabla} h = -\sqrt{1 - (f'_{\tilde{K},\Lambda})^2} \tilde{n}$,

$$g^{ij} \bar{\nabla}_{ij} h = - \left\langle \bar{\nabla}_{b_i} \left(\sqrt{1 - (f'_{\tilde{K},\Lambda})^2} \tilde{n} \right), b_i \right\rangle = \sqrt{1 - (f'_{\tilde{K},\Lambda})^2} H_{T_{p_0} M_{t_0}}.$$

As p_0 is a nondecreasing interior maximum, Lemma 3.1 implies

$$0 \leq \left(\frac{d}{dt} - \Delta\right)h(p_0) = -g^{ij}\nabla_{ij}^2 h = -\sqrt{1 - (f'_{\tilde{K},\Lambda})^2} H_{T_{p_0}M_{t_0}} \leq \sqrt{1 - (f'_{\tilde{K},\Lambda})^2} \Lambda.$$

The assumption $\Lambda < 0$ yields a contradiction. Therefore,

$$M_t \subset \{(x, y) \in \mathbb{R}^{n,m} | w(x, y) < f_{\tilde{K},\Lambda}(r(x, y))\}$$

for all $t \in [0, T)$ and all $\tilde{K} > K$. Limiting \tilde{K} to K yields the statement. □

We now demonstrate that suitable barriers may be attached to ∂M_0 .

Lemma 7.8 *Let \hat{u}_0 be smooth uniformly spacelike initial data on Ω with acausal boundary values. Then for any $\hat{x} \in \partial\Omega$, $\theta \in \mathbb{R}^m$ and $\Lambda < 0$ there exists $\xi \in \mathbb{R}^n$, $\eta \in \mathbb{R}^m$, $K > 0$ and $\delta \in (0, 1)$ such that the following hold.*

- (a) $\Omega \subset B_{\left(\frac{nK}{|\Lambda|}\right)^{\frac{1}{n}}}(\xi)$.
- (b) $M_0 \subset \{(x, y) \in \mathbb{R}^{n,m} | w(x, y) \leq f_{K,\Lambda}(r(x, y))\}$.
- (c) $(\hat{x}, \hat{u}_0(\hat{x})) \in \tilde{\Gamma}_{K,\Lambda}$.
- (d) Let $\tilde{M} := \text{graph } \tilde{u}$ for some smooth $\tilde{u} : \Omega \rightarrow \mathbb{R}^m$, such that $\partial\tilde{M} = \partial M_0$ and $\tilde{M} \subset \{(x, y) \in \mathbb{R}^{n,m} | w(x, y) \leq f_{K,\Lambda}(r(x, y))\}$. Then

$$D_{-\mu}\tilde{u} \cdot \theta \leq 1 - \delta.$$

Furthermore, K and δ can be chosen to depend only on n , Λ , Ω , $\sup_{M_0} v$ and $|\hat{u}_0|_{C^3(\Omega)}$.

Proof Our strategy is to find a suitable $\tilde{\Gamma}_{K,\Lambda}$ which touches M_0 only at the point $(\hat{x}, \hat{u}_0(\hat{x})) \in \partial M_0$. We take $\epsilon > 0$ and begin by setting $K = \epsilon^{-1}$.

Step 1 Pick $\tilde{\Gamma}_{K,\Lambda}$ so that (c) holds. We translate and rotate coordinates so that $\hat{x} = 0$, $\hat{u}(0) = 0$ and $\mu = -e_n$. Then, we rotate coordinates in $\mathbb{R}^{n-1} = T_0\partial\Omega$ so

$$D^\partial(\hat{u}_0 \cdot \theta)|_0 = ae_1$$

for some $a \in (0, 1)$, where D^∂ is the gradient operator on $\partial\Omega$.

We now show that we can choose a centre for $\tilde{\Gamma}_{K,\Lambda}$ so that (c) holds and $\tilde{\Gamma}_{K,\Lambda}$ is tangent to ∂M_0 . Concretely, for any $\epsilon > 0$, we set

$$\xi = -\frac{\epsilon}{\sqrt{1+b^2}}(b, 0, \dots, 0, 1), \quad \eta = -f_{\Lambda,K}(\epsilon)\theta,$$

for some b to be determined. We observe that for this choice, $\tilde{\Gamma}_{K,\Lambda}$ goes through the origin and so (c) is satisfied.

Step 2 Pick ϵ so that (a) holds. We observe that for $\epsilon < \epsilon_1 = \epsilon_1(\Lambda, n, \text{diam } \Omega) < 1$,

$$\text{diam } \Omega + 2 \leq \left(\frac{nK}{|\Lambda|}\right)^{\frac{1}{n}}.$$

As ξ is at most distance ϵ from the origin, this implies that (a) is satisfied.

Step 3 Pick b so that $\tilde{\Gamma}_{K,\Lambda}$ is tangential to ∂M_0 at $(\hat{x}, \hat{u}_0(\hat{x}))$. For $\tilde{\Gamma}_{K,\Lambda}$ to be tangent to ∂M_0 at 0, we require that

$$D^\delta [w(x, \hat{u}_0(x)) - f_{K,\Lambda}(r(x, \hat{u}_0(x)))](0) = 0;$$

that is,

$$D^\delta (\hat{u}_0 \cdot \theta) - f'_{K,\Lambda}(\epsilon) \frac{b}{\sqrt{1+b^2}} e_1 = 0.$$

We now want to choose $b = b(\epsilon, a)$ so that

$$f'_{K,\Lambda}(\epsilon) \frac{b}{\sqrt{1+b^2}} = a,$$

which is only possible if $f'_{K,\Lambda} > a$. By our choice of K ,

$$f'_{K,\Lambda}(\epsilon) = \frac{1 + n^{-1} \Lambda \epsilon^{1+n}}{\sqrt{\epsilon^{2n} + (1 + n^{-1} \Lambda \epsilon^{n+1})^2}}.$$

Since M_0 is uniformly spacelike, we deduce that $f'_{K,\Lambda} > a$ is satisfied for all $\epsilon < \epsilon_2(a, n, \Lambda, \epsilon_1) \leq \epsilon_1$, and for such ϵ we have that

$$b = \frac{a}{\sqrt{(f'_{K,\Lambda}(\epsilon))^2 - a^2}}.$$

Step 4 Show that for sufficiently small $\epsilon > 0$, (b) holds. We consider the function

$$g = w(x, \hat{u}(x)) - f_{K,\Lambda}(r(x, \hat{u}(x))) = |\hat{u}_0(x) + f_{K,\Lambda}(\epsilon)\theta| - f_{K,\Lambda}(|x - \xi|)$$

on $B_{R_1}(0) \subset \mathbb{R}^n \cap \bar{\Omega}$. By our construction so far we have that $g(0) = 0$ and $D^\delta g(0) = 0$, and our aim is to show that this is nonpositive everywhere. We first note that

$$\begin{aligned} D_\mu g(0) &= D_\mu \hat{u}_0 \cdot \theta + f'_{K,\Lambda}(\epsilon) \frac{\xi \cdot \mu}{|\xi|} \leq D_\mu \hat{u}_0 \cdot \theta - \frac{1}{\sqrt{1+b^2}} f'_{K,\Lambda}(\epsilon) \\ &= D_\mu \hat{u}_0 \cdot \theta - \sqrt{(f'_{K,\Lambda}(\epsilon))^2 - a^2}. \end{aligned}$$

As M_0 is spacelike at 0, $|D(\hat{u}_0 \cdot \theta)|^2 = |D_\mu \hat{u}_0 \cdot \theta|^2 + a^2 < 1$, and so there exists an $\epsilon_2 > \epsilon_3 = \epsilon_3(\sup_{M_0} v, n, \Lambda)$ such that for all $\epsilon < \epsilon_3$, $D_\mu g(0) < 0$.

Furthermore, we may calculate that

$$D_{ij}^2 g(0) = \frac{D_i \hat{u}_0 \cdot D_j \hat{u}_0 - D_i(\hat{u}_0 \cdot \theta) D_j(\hat{u}_0 \cdot \theta)}{f_{K,\Lambda}(\epsilon)} + D_{ij}(\hat{u}_0 \cdot \theta) - f''_{K,\Lambda}(\epsilon) \frac{\xi_i \xi_j}{|\xi|^2} - \frac{f'_{K,\Lambda}(\epsilon)}{\epsilon} \left(\delta_{ij} - \frac{\xi_i \xi_j}{|\xi|^2} \right).$$

We now suppose that $\epsilon < \epsilon_4 = \epsilon_4(\Lambda, n, \epsilon_3) \leq \epsilon_3$ is sufficiently small so that for $\epsilon < \epsilon_4$ the estimate (7.3) holds. We shall now restrict our attention to $1 \leq i, j \leq n - 1$; that is, to $T_0 \partial \Omega$. On this range we have that

$$D_{ij}^2 g(0) = \frac{D_i \hat{u}_0 \cdot D_j \hat{u}_0 - a^2 \delta_{i1} \delta_{j1}}{f_{K,\Lambda}(\epsilon)} + D_{ij}(\hat{u}_0 \cdot \theta) - \delta_{1i} \delta_{1j} f''_{K,\Lambda}(\epsilon) \frac{b^2}{1 + b^2} - \frac{f'_{K,\Lambda}(\epsilon)}{\epsilon} \left(\delta_{ij} - \delta_{1i} \delta_{1j} \frac{b^2}{1 + b^2} \right).$$

Again using the fact that M_0 is uniformly spacelike, there exists $\tau := \tau(\sup_{M_0} v) \in [0, 1)$ such that, as matrices, $D_i \hat{u}_0 \cdot D_j \hat{u}_0 \leq (1 - \tau) \delta_{ij}$ (see Appendix A). Hence,

$$\begin{aligned} & D_i \hat{u}_0 \cdot D_j \hat{u}_0 - a^2 \delta_{i1} \delta_{j1} - f_{K,\Lambda}(\epsilon) \frac{f'_{K,\Lambda}(\epsilon)}{\epsilon} \left(\delta_{ij} - \delta_{1i} \delta_{1j} \frac{b^2}{1 + b^2} \right) \\ & \leq (1 - \tau) \delta_{ij} - a^2 \delta_{i1} \delta_{j1} - \sqrt{1 - 2\epsilon^{2n}} f'_{K,\Lambda}(\epsilon) \left(\delta_{ij} - \delta_{1i} \delta_{1j} \frac{b^2}{1 + b^2} \right) \\ & = (1 - \tau) \delta_{ij} + \left[\frac{\sqrt{1 - 2\epsilon^{2n}}}{f'_{K,\Lambda}(\epsilon)} - 1 \right] a^2 \delta_{i1} \delta_{j1} - \sqrt{1 - 2\epsilon^{2n}} f'_{K,\Lambda}(\epsilon) \delta_{ij} \\ & \leq (1 - \tau) \delta_{ij} + \epsilon^{2n} a^2 \delta_{i1} \delta_{j1} - \sqrt{1 - 2\epsilon^{2n}} f'_{K,\Lambda}(\epsilon) \delta_{ij} \\ & \leq -\frac{\tau}{2} \delta_{ij} \end{aligned}$$

for all $\epsilon < \epsilon_5 = \epsilon_5(\sup_{M_0} v, \epsilon_4) \leq \epsilon_4$. Estimating $|f''_{K,\Lambda}| < |\Lambda| + n - 1$, $D_{ij} \hat{u}_0 \cdot \theta < C \delta_{ij}$ we finally see that for all $\epsilon < \epsilon_6 = \epsilon_6(n, \Lambda, |\hat{u}_0|_{C^2(\Omega)}, \epsilon_5) \leq \epsilon_5$ we have

$$D_{ij}^2 g(0) \leq (C + |\Lambda| + n - 1) \delta_{ij} - \frac{\tau}{2\epsilon} \delta_{ij} < 0.$$

Therefore, for any $\epsilon < \epsilon_6$ there exists $R_1 = R_1(\Lambda, n, \sup_{M_0} v, |\hat{u}_0|_{C^3})$ such that on $B_{R_1} \cap \partial \Omega$, the Hessian of g is negative definite and $\nabla_\mu g < 0$. We deduce that $g \leq 0$. Moreover, there exists $R_2 < R_1$ depending on the same quantities such that $g \leq 0$ on $\Omega \cap B_{R_2}(0)$.

For ϵ small enough we have that $\text{dist}(\xi, \partial B_{R_2}) > \frac{R_2}{2}$. As the gradient $f'_{K,\Lambda}$ monotonically increases as $\epsilon \rightarrow 0$, we may choose $\epsilon < \epsilon_7(\epsilon_6, \sup_{M_0} v, R_2, \partial\Omega, \phi) \leq \epsilon_6$ sufficiently small so that outside B_{R_2} , $f'_{K,\Lambda} > \max\{|Du^1|, \dots, |Du^m|\}$. Integration now implies (b) where we note that our estimate here also depends on $\partial\Omega$ and acausality to cross any nonconvex regions.

Step 5 Show that (d) now holds. Suppose now that we have some other function \tilde{u} such that $\tilde{u} = \hat{u}_0$ on $\partial\Omega$ and $|\tilde{u} - \eta| \leq f_{K,\Lambda}$ in Ω . Then, for all $\lambda > 0$,

$$\frac{1}{\lambda} (|\tilde{u}(\hat{x} - \lambda\mu) - \eta| - |\eta|) \leq \frac{1}{\lambda} (f_{K,\Lambda}(\hat{x} - \lambda\mu) - f_{K,\Lambda}(\hat{x})).$$

Taking the limit as $\lambda \rightarrow 0$,

$$D_{-\mu}\tilde{u} \cdot \theta = \frac{d}{d\lambda} \Big|_{\lambda=0} |\tilde{u}(\hat{x} - \lambda\mu) - \eta| \leq f'_{K,\Lambda}(\epsilon) \left\langle \mu, \frac{\xi}{|\xi|} \right\rangle = \frac{f'_{K,\Lambda}(\epsilon)}{1 + b^2}$$

Since $f'_{K,\Lambda}(\epsilon) < 1$ depends only on ϵ_7 , (d) holds. □

Proposition 7.9 Suppose we have a solution of (7.2) over a compact domain Ω with smooth uniformly spacelike initial data which is acausal at the boundary. There exists a constant C_v depending only on M_0 such that for all $t \in [0, T)$ and $y \in M_t$,

$$v(y, t) \leq C_v.$$

Proof For any $\hat{x} \in \partial\Omega$ and unit vectors $\theta \in \mathbb{R}^m$, we attach barriers to M_0 at \hat{x} as constructed in Lemma 7.8. Lemma 7.7 implies that for all t we have

$$M_t \subset \{(x, y) \in \mathbb{R}^{n,m} | w(x, y) \leq f_{K,\Lambda}(r(x, y))\},$$

and so Lemma 7.8 yields

$$|D_{-\mu}u(\hat{x}, t) \cdot \theta| \leq 1 - \delta,$$

for all θ as above. For any $v \perp \mu$, we also have that

$$|D_vu(\hat{x}, t) \cdot \theta| \leq 1 - \tilde{\delta},$$

for some $\tilde{\delta} > 0$, due to the uniform spacelikeness of M_0 . These conditions now imply that at \hat{x} , $v < C(\delta, \tilde{\delta})$ and so

$$\sup_{y \in \partial M_t} v^2(y) \leq C_v = C_v(\delta, \tilde{\delta}).$$

Applying the maximum principle (using Corollary 3.5) gives the result. □

We now observe that the above estimates give us decay for the mean curvature.

Lemma 7.10 *Suppose that $\hat{u} \in C^{4;2}(\Omega \times [0, T])$ is a solution to (7.2). Suppose further that the estimates of Proposition 7.9 hold and*

$$\sup_{M_0} \|H\|^2 \leq C_H.$$

For all $t \in [0, T)$,

$$\|H\|^2 \leq \frac{1}{C_H^{-1} + \frac{2}{n}t}.$$

Proof Clearly at $\hat{x} \in \partial\Omega$ we have $\frac{d\hat{u}}{dt} = 0$. Recall $\hat{g}_{AB} = -\sum_{C=1}^m \langle e_A, v_C \rangle \langle v_C, e_B \rangle$ from Appendix A, and as M_t is spacelike at $\partial\Omega$, \hat{g}_{AB} is invertible with inverse \hat{g}^{AB} . We compute

$$0 = \frac{d\hat{u}^A}{dt} = \langle H, e_B \rangle \hat{g}^{BA} = H^C \langle v_C, e_B \rangle \hat{g}^{BA}.$$

Invertibility of \hat{g}_{AB} implies $\langle H, e_B \rangle = 0$ for all $1 \leq B \leq m$, and this in turn implies $H = 0$, as $\langle v_D, e_C \rangle = 0$ for all $1 \leq C \leq m$ contradicts that v_D is timelike. As a result, on ∂M_t ,

$$\|H\|^2 = 0.$$

We may now apply the maximum principle to $f = (C_H^{-1} + \frac{2}{n}t)\|H\|^2$. □

7.3 $C^{1+\alpha}$ Estimates

We now prove the final estimates required for the long-time existence of spacelike MCF with Dirichlet boundary conditions.

Lemma 7.11 *Suppose that we have a solution to (7.2) such that there is a uniform constant $C_v > 0$ so that*

$$v^2 \leq C_v. \tag{7.4}$$

Then for any $\epsilon > 0$, there exists a constant C depending only on $\epsilon, \partial\Omega, \hat{u}_0$ and C_v such that

$$|\hat{u}|_{C^{1+\alpha; \frac{1+\alpha}{2}}(\Omega \times [\epsilon, T])} \leq C.$$

Proof By Remark 4.8, we may take sufficiently small cylinders near the boundary $\partial\Omega$ to deduce there exists $C > 0$, depending on M_0 and the maximum curvature of $\partial\Omega$, so that for all t such that the flow exists,

$$\sup_{M_t} \|II\| \text{dist}(x, \partial\Omega) < C_1.$$

The gradient bound (7.4) now implies that $|D^2\hat{u}| \text{dist}(x, \partial\Omega) < C_2$. To conclude, we must now deal with boundary estimates.

We may apply an observation of Krylov, see [26, Lemma 7.47], to (7.2), which implies that for all $\lambda < R \leq R_0 = R_0(\partial\Omega, C_v)$ we have

$$\text{osc}_{B_R \cap \Omega} \frac{\hat{u}^A(\hat{x} - \lambda\mu, t) - \phi^A(\hat{x})}{\lambda} \leq C \left(\frac{R}{R_0} \right)^\alpha$$

for all $\hat{x} \in \partial\Omega$, where C and α depend on C_v and n . Interpolation estimates may now be applied, exactly as in [25, Proposition 4.3] to yield the claim. □

7.4 Convergence

We finally demonstrate convergence of spacelike MCF in the Dirichlet setting, as in [11, Theorem 4.1], thus completing the proof of Theorem 7.2. We recall that [25, Theorem 2.1] proves the uniqueness of maximal submanifolds with prescribed acausal boundary data.

Lemma 7.12 *Suppose \hat{u} is a smooth solution of (7.2) with $T = \infty$ with uniform $C^{k; \frac{k}{2}}(\Omega \times [0, \infty))$ estimates for all $k \geq 0$, such that for all $t > 0$ and $y \in M_t$*

$$v^2(y) < C_v.$$

Then, M_t converges smoothly to the unique maximal surface with boundary data given by ∂M_0 .

Proof Lemma 7.10 implies that

$$\sup_{M_t} \|H\| \rightarrow 0.$$

Furthermore, Lemma 7.11 and Schauder theory imply that we have uniform higher order estimates on \hat{u} .

Using the uniform $C^{k; \frac{k}{2}}$ estimates and the Arzelà–Ascoli theorem, any sequence of times $t_i \rightarrow \infty$ has a subsequence $t_{i(j)}$ such that $M_{t_{i(j)}}$ converges uniformly to a maximal submanifold $\tilde{M} = \text{graph } \tilde{u}$ for some $\tilde{u} : \Omega \rightarrow \mathbb{R}^m$. [25, Theorem 2.1] states that this limit is the unique maximal submanifold with the given boundary data. Therefore, $\hat{u}(x, t) \rightarrow \tilde{u}(x)$ uniformly as $t \rightarrow \infty$ as otherwise we may construct a sequence of times contradicting subsequential convergence to \tilde{u} . Smooth convergence now follows using higher order regularity and Ehrling’s Lemma. □

8 Global Properties of Entire Solutions

In this section we consider graphs M_0 over \mathbb{R}^n such that for some $C_v, C_H > 0$

$$\sup_{M_0} v^2 \leq C_v \quad \text{and} \quad \sup_{M_0} \|H\|^2 < C_H. \tag{8.1}$$

Although we have constructed a solution for such initial data, since M_0 is noncompact we do not know that the solution from Theorem 5.2 is the only solution and it is plausible that quite wild behaviour is possible in general.

To deal with this issue, we introduce the following natural class of entire solutions to spacelike MCF.

Definition 8.1 An entire solution of (1.3) with initial data satisfying (8.1) will be called *tame* if there exists a continuous real-valued function $f = f(t)$ such that $f(0) = C_H$ and

$$\sup_{M_t} \|H\|^2 \leq f(t).$$

We note tame solutions always exist due to Theorem 5.2. We will show that tame solutions satisfy estimates which are similar to expander solutions.

First we demonstrate a noncompact maximum principle under the assumption of a uniform gradient bound.

Proposition 8.2 *Suppose that for all $t \in [0, T)$, $v^2 \leq C_v$ uniformly on M_t . Suppose that $f \in C_{loc}^\infty(M^n \times [0, T))$ is a smooth function such that $f \geq 0$,*

$$C_f := \sup_{M_0} f < \infty,$$

and there exists $\delta > 0$ such that

$$\left(\frac{d}{dt} - \Delta\right) f \leq -\delta f^2.$$

Then for all $t \in [0, T)$ and $y \in M_t$

$$f(y, t) \leq \frac{1}{C_f^{-1} + \delta t}.$$

Proof Let $\varphi_R : \mathbb{R} \rightarrow [0, \infty)$ be a smooth cutoff function such that:

- $|\varphi_R(x)| \leq 1$ and $\varphi_R(x) = 1$ on $(-\infty, 1]$, $\varphi_R(x) = 0$ on $[1 + R, \infty)$;
- $|\varphi'_R| \leq \frac{2}{R}$, $|\varphi''_R| < \frac{10}{R^2}$.

It is easy to see that such a cutoff function exists by considering cubic polynomials.

For r as in Corollary 3.2, we see that when $r \geq 1$, we have that

$$\left|\left(\frac{d}{dt} - \Delta\right) r\right| \leq C v^2, \quad |\nabla r| \leq C v^2,$$

where C depends only on n . Assuming $R \gg 1$, $p \geq 3$ and writing C for any bounded constant that depends only on n and p which may vary from line to line, we have that at any increasing maximum point of $g := f\varphi_R^p(r)$,

$$\begin{aligned}
 0 &\leq \left(\frac{d}{dt} - \Delta\right) f\varphi_R^p \\
 &\leq -\delta\varphi_R^p f^2 - 2\langle \nabla f, \nabla\varphi_R^p \rangle \\
 &\quad + f\left(p\varphi'_R\varphi_R^{p-1}\left(\frac{d}{dt} - \Delta\right)r - \left[p(p-1)(\varphi'_R)^2\varphi_R^{p-2} + p\varphi_R^{p-1}\varphi''_R\right]|\nabla r|^2\right) \\
 &= -\delta\varphi_R^p f^2 + f\left(p\varphi'_R\varphi_R^{p-1}\left(\frac{d}{dt} - \Delta\right)r\right. \\
 &\quad \left.+ \varphi_R^{p-2}\left[p(p+1)(\varphi'_R)^2 - p\varphi_R\varphi''_R\right]|\nabla r|^2\right) \\
 &\leq -\delta\varphi_R^p f^2 + fC(R^{-1} + R^{-2})\varphi_R^{p-2}v^2,
 \end{aligned}$$

where we used that $\nabla(f\varphi_R^p) = 0$. We therefore see that for $p = 3$,

$$\delta(\varphi_R^3 f)^2 \leq \varphi_R^4 fC(R^{-1} + R^{-2})C_v,$$

which implies that

$$\varphi_R^3 f \leq \max\left\{\frac{\sqrt{2}C(R^{-1} + R^{-2})C_v}{\sqrt{\delta}}, C_f\right\} =: \Lambda.$$

Now setting $p = 5$, the above evolution inequality for $g = f\varphi_R^p$ implies that for any $\tau \in (0, 1)$, if

$$g > \sqrt{\tau^{-1}\delta^{-1}CC_v(R^{-1} + R^{-2})\Lambda}$$

then

$$\left(\frac{d}{dt} - \Delta\right)g \leq -\delta g^2 + CC_v(R^{-1} + R^{-2})\Lambda \leq -\delta(1 - \tau)g^2,$$

where we used that $f \geq g$ everywhere. Therefore,

$$g \leq \max\left\{\frac{1}{(\sup_{M_0} g)^{-1} + \delta(1 - \tau)t}, \sqrt{\tau^{-1}\delta^{-1}CC_v(R^{-1} + R^{-2})\Lambda}\right\}.$$

Setting $\tau = R^{-\frac{1}{2}}$ and sending $R \rightarrow \infty$ now implies that on $M_t \cap \mathcal{C}_1$,

$$g \leq \frac{1}{(\sup_{M_0} f)^{-1} + \delta t}.$$

As the center of the cylinder was arbitrary, this estimate holds everywhere. □

The next proposition shows that tame solutions satisfy estimates similar to expander solutions.

Proposition 8.3 *Suppose that on M_0 , (8.1) holds and additionally that we have a solution to (1.3) that is tame. Then for all $t \in [0, \infty)$,*

$$v^2 \leq C_v, \quad \|H\|^2 \leq \frac{1}{C_H^{-1} + 2n^{-1}t} \quad \text{and} \quad \|H\|^2 \leq \frac{m}{2t}.$$

Proof Since the function f given by Definition 8.1 of a tame solution \hat{u} is continuous, there exists a maximal time \hat{T} such that for all $t \in [0, \hat{T})$, $\sup_{M_t} \|H\|^2 < 2C_H$. We may now apply Lemma 4.3 to obtain the existence of $p = p(n)$ such that at the point $y \in M_t$ with $r(y) = 0$ (where r is as in Corollary 3.2),

$$v^2(y, t) \leq C_v \left(\frac{R^2}{R^2 + \|\hat{u}\|^2 - 2nt} \right)^p e^{4C_H t}$$

for all $t < \min \left\{ \hat{T}, \frac{R^2}{2n} \right\}$. We now choose $R = 1$ and \tilde{T} to be sufficiently small so that for all $t < \tilde{T}$, $\left(\frac{1}{1-2nt} \right)^p e^{4C_H t} < 2$. Clearly \tilde{T} depends only on C_H and n . Let $\bar{T} = \min\{\tilde{T}, \hat{T}\}$. As the origin may be chosen arbitrarily, we see that for $t < \bar{T}$, $v < 2C_v$ everywhere on M_t , and we may apply Proposition 8.2 to $\|H\|^2$ (using Corollary 3.10) to obtain that on M_t ,

$$\|H\|^2 \leq \frac{1}{C_H^{-1} + \frac{2t}{n}}. \tag{8.2}$$

We therefore see that $\bar{T} = \tilde{T}$.

We now use (8.2) and Corollary 3.5 to estimate for any $\delta \in (0, (2n)^{-1}]$,

$$\left(\frac{d}{dt} - \Delta \right) w_A^2 \leq -(1 + \delta) \frac{|\nabla w_A^2|^2}{w_A^2} + 4n\delta \frac{1}{C_H^{-1} + \frac{2t}{n}} w_A^2.$$

Applying Lemma 4.2 to $w_A^2 (C_H^{-1} + \frac{2t}{n})^{-4n\delta}$ on \mathcal{Q}_R we see that on $M_t \cap \{x \in \mathbb{R}^{n,m} | r(x) = 0\}$,

$$v^2 \leq C_v \left(\frac{R^2}{R^2 - 2nt} \right)^{\frac{1+\delta}{\delta}} \left[1 + \frac{2C_H t}{n} \right]^{4n\delta}.$$

Suppose now that for some $0 < t_0 < \tilde{T}$, and $x_0 \in M_{t_0}$ with $r(x_0) = 0$ that

$$v(x_0, t_0) = C_v + \epsilon.$$

Then we may form a contradiction, for example by choosing δ sufficiently small so that $\left[1 + \frac{2C_H t_0}{n} \right]^{4n\delta} \leq \sqrt{1 + \frac{\epsilon}{2}}$, and then choosing R sufficiently large so that $\frac{1}{(1 - \frac{2nt_0}{R^2})^{\frac{1+\delta}{\delta}}} \leq \sqrt{1 + \frac{\epsilon}{2}}$. Therefore, we see that for all $t \in [0, \tilde{T})$,

$$\sup_{M_t} v^2 \leq C_v.$$

As \tilde{T} depended only on n and C_v , we may iterate the above process to get the statement. The final estimate comes from applying Proposition 8.2 to $\|II\|^2$, using the evolution equation in Corollary 3.10. \square

Corollary 8.4 *Suppose that on M_0 (8.1) holds and that we have a solution to (1.3) that is tame. Then for all $k > 1$ there exists a constant $c_k = c_k(n, m, k, C_v)$ such that for all $t \in [0, \infty)$,*

$$\|\nabla^k II\|^2 t^{k+1} \leq c_m.$$

Proof As noted in [11, Proposition 3.7] the evolution equations for $\|\nabla^k II\|^2$ may be estimated as in the Euclidean graphical case, and we have the same estimate on $\|II\|^2$. The proof of [13, Theorem 3.4] then carries through identically. \square

The estimates in Proposition 8.3 have three straightforward, interesting corollaries.

Corollary 8.5 *The expanding quasi-sphere given by Definition 1.6 acts as an outer barrier to any tame solution to (1.3).*

Proof We consider the function $h_p(x, t) = |x - p|^2 + 2nt + R^2$, and we suppose that $\inf_{M_0} h \geq 0$. The estimates of Proposition 8.3 imply that for any $T > 0$ there exists $\rho = \rho(T, C_v, C_H)$ such that for all $t \in [0, T)$, $\inf_{M_t \setminus \mathcal{C}_\rho(p)} h_p \geq 0$. Therefore, we may apply the maximum principle on $M_t \cap \mathcal{C}_\rho$ to see that this is preserved on the time interval $[0, T)$. As T was arbitrary, the statement now follows. \square

Corollary 8.6 *Let M_t be an entire tame solution to (1.3) and suppose there exists $R > 0$ such that for all $t > 0$, $M_t \cap B_R \neq \emptyset$; i.e. that M_t does not escape to infinity. Then there exists a sequence $t_i \rightarrow \infty$ such that M_{t_i} converges to an n -plane.*

Corollary 8.7 *There are no entire shrinking or translating solutions to spacelike MCF in $\mathbb{R}^{n,m}$ with bounded v and H .*

9 Convergence of Entire Solutions

In this section we prove convergence of tame (in the sense of Definition 8.1) entire solutions to spacelike MCF (1.3) with initial data M_0 which is asymptotic to a spacelike cone.

Suppose that L is a uniformly spacelike cone centred at the origin, smooth away from the origin, given graphically by functions $U : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that for all $\lambda > 0$ and $x \in \mathbb{R}^n$, $U(\lambda x) = \lambda U(x)$.

Definition 9.1 We say that M_0 , given by the graph of \hat{u}_0 , is asymptotic to the cone L if

$$\lim_{R \rightarrow \infty} \sup_{\mathbb{R}^n \setminus B_R} |\hat{u}_0 - U| = 0. \tag{9.1}$$

Note that, in this setting, L satisfies the same gradient estimate as M_0 .

We recall how to renormalise solutions to MCF in the standard way. We write $s = \frac{1}{2} \log(2t + 1)$, and define

$$\tilde{X}(x, s) = \frac{1}{\sqrt{1 + 2t}} X(x, t). \tag{9.2}$$

We will write all quantities for the rescaled flow with a tilde to avoid confusion. We also recall that submanifolds satisfying

$$\tilde{H} = \tilde{X}^\perp \tag{9.3}$$

are called *self-expanders* and are critical points of the renormalised MCF.

We now state the following convergence statement, whose proof shall take up the remainder of the section.

Theorem 9.2 *Suppose that M_t is a tame entire solution to spacelike MCF (1.3) such that M_0 is asymptotic to the cone L as in Definition 9.1. For any sequence $t_i \rightarrow \infty$ there is a subsequence (also labelled t_i) and a self-expander \tilde{M}_∞ such that the renormalised flow satisfies $\tilde{M}_{t_i} \rightarrow \tilde{M}_\infty$ in C_{loc}^∞ as $i \rightarrow \infty$.*

We first show that (9.1) is preserved by the flow, by attaching expanding quasi-spheres of arbitrarily large radius to the initial data. For this purpose, we begin with the following result.

Lemma 9.3 *Let $p \in \mathbb{R}^{n,m}$, let $R > 0$ and recall the inside I_t of the quasi-sphere expander from Definition 1.6. Suppose that $M_0 \subset I_0$ and M_0 has $v^2 \leq C_v$ everywhere. For $\epsilon < 1$, let*

$$O_\epsilon := \{x + y \in \mathbb{R}^{n,m} \mid x \in M_0, y \in \mathbb{R}^m = \text{span}\{e_1, \dots, e_m\}, \|y\| \leq \epsilon\}.$$

There exists $C = C(C_v, R) > 0$ such that, for all $\epsilon < 1$, $O_\epsilon \subset I_{C\epsilon/n}$.

Proof Without loss of generality we may take $p = 0$. By observations in Appendix A, since $v^2 < C_v$ there exists $\tau \in (0, 1)$ such that for any direction $\theta \in \mathbb{R}^m$ (using the notation of Sect. 7),

$$D_i \hat{u}_0 \cdot \theta < \sqrt{1 - \tau}.$$

Hence, a short calculation using the gradient estimate (and mean value theorem) shows that if we take

$$\rho = R \sqrt{\frac{1 - \tau}{\tau}},$$

then the graph of \hat{u}_0 over $\mathbb{R}^n \setminus B_\rho(0) \subset \mathbb{R}^n$ cannot intersect the quasi-sphere S_0 . We may therefore estimate

$$\|\hat{u}_0\| \leq \begin{cases} \sqrt{R^2 + |x|^2} & \text{on } B_\rho(0), \\ \sqrt{1 - \tau} (|x| - \rho) + \sqrt{R^2 + \rho^2} & \text{on } \mathbb{R}^n \setminus B_\rho(0). \end{cases}$$

We consider a point $x + y \in O_\epsilon$. Over $B_\rho(0)$ we have

$$\|y\|^2 \leq (\|\hat{u}_0\| + \epsilon)^2 = \|\hat{u}_0\|^2 + 2\epsilon\|\hat{u}_0\| + \epsilon^2 \leq |x|^2 + R^2 + 2\epsilon\frac{R}{\sqrt{\tau}} + \epsilon^2,$$

and so at any point $x + y \in C_\rho \cap O_\epsilon$ (where C_ρ is as in Definition 4.1),

$$|x + y|^2 > -R^2 - \epsilon \left(2\frac{R}{\sqrt{\tau}} + \epsilon \right).$$

Now we consider the minimum value of $|x + y|^2$ on $O_\epsilon \setminus C_\rho$. We have that

$$\begin{aligned} |x + y|^2 &\geq |x|^2 - \left[\sqrt{1 - \tau} (|x| - \rho) + \sqrt{R^2 + \rho^2} + \epsilon \right]^2 \\ &= \tau|x|^2 + 2 \left[\rho(1 - \tau) - \left(\sqrt{R^2 + \rho^2} + \epsilon \right) \sqrt{1 - \tau} \right] |x| \\ &\quad - (1 - \tau)\rho^2 + 2\rho\sqrt{1 - \tau} \left(\sqrt{R^2 + \rho^2} + \epsilon \right) - \left(\sqrt{R^2 + \rho^2} + \epsilon \right)^2 \\ &:= \psi(|x|). \end{aligned}$$

Note that ψ is a quadratic in $|x|$ with positive highest order term. Therefore, ψ attains its global minimum at

$$|x| = \frac{\left(\sqrt{R^2 + \rho^2} + \epsilon \right) \sqrt{1 - \tau} - \rho(1 - \tau)}{\tau} = \rho + \frac{\sqrt{1 - \tau}}{\tau} \epsilon,$$

and

$$\begin{aligned} \psi &\geq \left(\rho + \frac{\sqrt{1 - \tau}}{\tau} \epsilon \right)^2 - \left[\frac{\epsilon}{\tau} + \sqrt{R^2 + \rho^2} \right]^2 \\ &= \rho^2 - (R^2 + \rho^2) + 2 \left[\rho\sqrt{1 - \tau} - \sqrt{R^2 + \rho^2} \right] \frac{\epsilon}{\tau} + [1 - \tau - 1] \frac{\epsilon^2}{\tau^2} \\ &= -R^2 - 2 \left[\frac{1}{\sqrt{1 - \tau}} - \sqrt{1 - \tau} \right] \frac{\epsilon\rho}{\tau} - \frac{\epsilon^2}{\tau}. \end{aligned}$$

The claim now follows. □

Lemma 9.4 *Suppose that w is a tame solution to (1.3) and the initial data satisfies (9.1). Then, for all $t > 0$,*

$$\lim_{R \rightarrow \infty} \sup_{x \in \mathbb{R}^n \setminus B_R} |w(x, t) - U(x)| = 0.$$

More precisely, for any $\epsilon, T > 0$ there exists $\rho = \rho(\epsilon, T)$ such that for all $t \in [0, T)$,

$$\sup_{(x,t) \in (\mathbb{R}^n \setminus B_\rho) \times [0, T)} |w(x, t) - U(x)| < \epsilon.$$

Proof Our aim is to show that sufficiently far away from the origin we may attach quasi-spheres to M_0 with arbitrarily large negative square radius, which then contain M_0 . As the barriers starting from these quasi-spheres move arbitrarily slowly the theorem will then be achieved. We make this intuitive argument explicit, due to the difficulty in visualising higher codimension submanifolds.

For any p in the asymptotic cone L and any unit vector $v \in N_p L$ we define

$$\phi_{p,v,\lambda}(x) := |x - p - \lambda v|^2 + \lambda^2.$$

We now complete the proof in several steps.

Step 1 *There exists $R_0 > 0$ such that for any $x \in \partial B_1(0) \subset \mathbb{R}^n$ and any $v \in N_{(x,U(x))}L$, we may attach a quasi-sphere of square radius $-R_0^2$ in any unit direction v which contains L ; that is, $\phi_{(x,U(x)),v,R_0} \geq 0$ everywhere on L .*

Proof We observe that at $p = (x, U(x))$, $\phi_{p,v,\lambda}(p) = 0$ for all λ and, since L is spacelike, $\phi_{p,v,0} \geq 0$ on L . Furthermore,

$$\tilde{\lambda}(p) := \inf\{\lambda \in [0, 1] \mid \phi_{p,v,\lambda} \geq 0 \text{ on } L \text{ for all unit } v \in N_p L\} > 0$$

as otherwise we may contradict uniform spacelikeness using the mean value theorem. Furthermore, the fact that L is uniformly spacelike implies that there exists \tilde{R} such that if $\tilde{\lambda}(p) < 1$, then there is $y \in B_{\tilde{R}}$ such that $\phi_{p,v,\tilde{\lambda}}(y, U(y)) = 0$. As $\phi_{p,v,\lambda}$ is smooth in p, v, λ , we see by standard methods that $\tilde{\lambda}$ is (Lipschitz) continuous. Therefore $\tilde{\lambda}$ has a positive minimum, R_0 , on $\partial B_1(0)$ as claimed. □

Step 2 *For any $\epsilon > 0, R > 0$, there exists $\rho_0 = \rho_0(R, \epsilon, \hat{u}_0) > 0$ such that for any $x \in \mathbb{R}^n \setminus B_\rho(0)$, and any $v \in N_{(x,U(x))}L$, M_0 is contained inside a quasi-sphere of square radius $-R^2$ with centre $(x, U(x)) - (R - \epsilon)v$.*

Proof By the scaling properties of the cone and quasi-sphere, we may choose $\rho_1 = \rho_1(R, R_0)$ sufficiently large so that Step 1 implies that for any $p \in L \setminus C_{\rho_1}$ and any unit $v \in N_p L$ we can attach a quasi-sphere of square radius $-R^2$ in direction v which contains L . The condition (9.1) now implies that for any $\tilde{\epsilon} > 0$, there exists $\rho_1 < \rho_2 = \rho_2(M_0, \tilde{\epsilon}, \rho_1)$ such that

$$\sup_{\mathbb{R}^n \setminus B_{\rho_2}(0)} \|\hat{u}_0 - U\| < \tilde{\epsilon}.$$

Lemma 9.3 now implies that by choosing $\tilde{\epsilon}$ to be sufficiently small and relabelling constants the claim follows. □

Step 3 *Completing the proof.* Given any $\tilde{\epsilon} > 0, T > 0$, we choose $R > 0$ so large that the quasi-sphere expander starting from square radius $-R^2$ as in Step 2 moves at most $\frac{\tilde{\epsilon}}{2}$ in direction ν on the time interval $[0, T]$. We now apply Step 2 to find a $\tilde{\rho}$ such that for all $x \in \mathbb{R}^n \setminus B_{\tilde{\rho}}(0)$, we may attach expanding quasi-spheres in any direction as in Step 2. The proof is complete by choosing $\tilde{\epsilon} < \frac{\epsilon}{C_v}$. \square

The following result is proved in a similar way to Proposition 8.2, and indicates that if we have only small osculation of $\|u\|^2$, then v^2 decays exponentially in time.

Lemma 9.5 *For any $\epsilon \in (0, 1)$ and tame entire solution to (1.3) such that*

$$v^2 < C_v, \quad \|H\|^2 < C_H,$$

there exists $R = R(\epsilon, C_v) > 1$ such that: if for all $t \in [0, T)$

$$0 < u_A^2 < C_u < 1 \text{ on } \mathcal{C}_R \cap M_t,$$

then for all $y \in \mathcal{C}_1 \cap M_t$,

$$w_A^2(y, t) \leq (1 + \epsilon)e^{C_u} + e^{-t} \sup_{\mathcal{C}_R \cap M_0} w_A^2 e^{u_A^2}.$$

Proof We see from Lemma 3.8 that for $f = w_A^2 e^{u_A^2}$ we have that

$$\left(\frac{d}{dt} - \Delta\right) f \leq -e^{u_A^2} w_A^2 (w_A^2 - 1) \leq -e^{-C_u} f^2 + f.$$

We choose φ_R as in Proposition 8.2, and set $g = \varphi_R^p f$, where R will be determined later. Arguing as in the proof of Proposition 8.2, we have at an increasing maximum:

$$0 \leq \left(\frac{d}{dt} - \Delta\right) f \varphi_R^p(r) \leq -\delta \varphi_R^p f^2 + f \varphi_R^p + f C(R^{-1} + R^{-2}) \varphi_R^{p-2} v^2,$$

where $\delta = e^{-C_u}$. Taking $p = 3$,

$$\delta(\varphi_R^3 f)^2 \leq \varphi_R^3 f [C(R^{-1} + R^{-2})C_v + 1],$$

which implies that

$$\varphi_R^3 f \leq \max \left\{ \frac{\sqrt{2}(C(R^{-1} + R^{-2})C_v + 1)}{\sqrt{\delta}}, \sup_{M_0 \cap \mathcal{C}_R} f \right\} =: \Lambda.$$

Taking instead $p = 5$,

$$\left(\frac{d}{dt} - \Delta\right) g \leq -\delta g^2 + g + C(R^{-1} + R^{-2})\Lambda C_v$$

or, writing $\tilde{g} = g - \frac{1}{2\delta}$, we have that

$$\left(\frac{d}{dt} - \Delta\right)\tilde{g} \leq -\delta\tilde{g}^2 + C(R^{-1} + R^{-2})\Lambda C_v + \frac{1}{4\delta}.$$

Using the concavity of $y(x) = C - x^2$, we may estimate that for

$$\delta\tilde{g} \geq \sqrt{\delta C(R^{-1} + R^{-2})\Lambda C_v + 1/4} := b$$

we have

$$\left(\frac{d}{dt} - \Delta\right)\tilde{g} \leq -2b\tilde{g}.$$

Hence,

$$\tilde{g} \leq \max \left\{ e^{-2bt} \sup_{M_0} \tilde{g}, \frac{b}{\delta} \right\} < \frac{b}{\delta} + \sup_{M_0} \tilde{g} e^{-2bt}.$$

Picking R sufficiently large depending on ϵ and C_v (where we estimate δ by 1), we may assume that $b \leq \frac{1+2\epsilon}{2}$. Hence on $\mathcal{C}_1 \cap M_t$,

$$w_A^2 e^{u_A^2} \leq (1 + \epsilon)e^{C_u} + e^{-(1+2\epsilon)t} \sup_{\mathcal{C}_R \cap M_0} w_A^2 e^{u_A^2}$$

as claimed. □

Corollary 8.5 implies that there exists a constant c_0 depending only on the initial data such that, on M_t ,

$$0 < r^2 < c_0 + 2nt + |X|^2. \tag{9.4}$$

Hence, on M_0 , there exists C depending on the gradient bound C_v such that

$$\frac{|X^\perp|^2}{c_0 + |X|^2} \leq C.$$

We now use (9.1) to show that $\frac{|X^\perp|^2}{|X|^2}$ decays far away from the origin.

Lemma 9.6 *Suppose M_0 satisfies (9.1). For all $T > 0$, there exists $R(T, L) > 0$ and $C = C(C_v)$ such that for all $t \in [0, T)$ and $p \in M_t \setminus \mathcal{C}_R$,*

$$\frac{\|X^\perp\|^2}{|X|^2} \leq C e^{-\frac{t}{2}}.$$

Proof We pick $\epsilon < e^{-2T}$ sufficiently small such that $(1 + \epsilon)e^\epsilon - 1 < e^{-T}$. Let R be as in Lemma 9.5 with this choice of ϵ .

At $p \in L$, let $\{v_1, \dots, v_m\}$ be an orthonormal basis of $N_p L$. We rotate about 0 in $\mathbb{R}^{n,m}$ so that v_A is in the e_A direction. In rotated coordinates we will write all objects with a check, e.g. \check{p} for the rotation of p , $\check{C}_R(\check{p})$ for a cylinder of radius R at \check{p} in the new rotated coordinates. Since L is a cone, v_1, \dots, v_m is also an orthonormal basis of $N_{\lambda p} L$ for all $\lambda > 0$. From scaling properties of the cone, by assuming $|p|$ is sufficiently large, we see that L may be arbitrarily well approximated by its tangent plane, \mathbb{R}^n . Therefore, due to the gradient bound and Lemma 9.4, there exists $R_1 > 0$ such that for all $p \in M_t \setminus C_{R_1}$ (in the unrotated coordinates),

$$0 < \check{u}_A^2(\check{q}, t) < \epsilon \text{ for all } t \in [0, T), \check{q} \in \check{C}_R(\check{p}) \cap \check{M}_t.$$

We assume we have made R_1 sufficiently large so that $|X| > 1$ (if not, we increase R_1). We therefore may apply Lemma 9.5 so that on $[0, T)$ we have

$$\check{w}_A^2 \leq (1 + \epsilon)e^\epsilon + Ce^{-t},$$

where $C = C(C_v)$. Rotating back, we see that for all $q \in M_t \cap \check{C}_1(\check{p})$ there exist orthonormal timelike constant vectors $\check{e}_1, \dots, \check{e}_m$ such that

$$\|\check{e}_A^\perp\|^2 \leq (1 + \epsilon)e^\epsilon + Ce^{-t}.$$

Let \check{f}_i be an orthonormal basis of $T_p L$ (similarly extended). Since

$$v_A = \sum_i \langle \check{f}_i, v_A \rangle \check{f}_i - \sum_B \langle v_A, \check{e}_B \rangle \check{e}_B,$$

we then have that

$$-1 = |v_A|^2 = \sum_i \langle \check{f}_i, v_A \rangle^2 - \sum_B \langle v_A, \check{e}_B \rangle^2.$$

Thus,

$$\sum_i \|\check{f}_i^\perp\|^2 = \sum_B \|\check{e}_B^\perp\|^2 - n.$$

We deduce that for any $q \in M_t \cap \check{C}_1(\check{p})$, we may write $q = \check{x} + \check{w}$ where $\check{x} \in T_p L$ and $\check{w} \in N_p L$, to estimate

$$\begin{aligned} \frac{\|X^\perp\|}{\sqrt{|X|^2}} &\leq 2 \frac{\|\check{x}^\perp\| + \|\check{w}^\perp\|}{\sqrt{|\check{x}|^2 - \|\check{w}\|^2}} \\ &\leq 2 \frac{\|\check{x}\| \sqrt{n} \sqrt{(1 + \epsilon)e^\epsilon - 1 + Ce^{-t}} + \sqrt{\epsilon}((1 + \epsilon)e^\epsilon + Ce^{-t})}{\sqrt{|\check{x}|^2 - m\epsilon}} \\ &\leq \check{C}e^{-\frac{t}{2}} \end{aligned}$$

due to the chosen bounds on ϵ . As \check{C} depends only on C_v , the statement follows. \square

Recall the renormalising of MCF given in (9.2) and that we write all quantities for the rescaled flow with a tilde. For convenience we define the scaling factor $\lambda(t) = \frac{1}{\sqrt{1+2t}}$. We see that, under the renormalisation,

$$\frac{d\tilde{X}}{ds} = \tilde{H} - \tilde{X}.$$

We want to understand how quantities evolve under the renormalised flow based on their evolution under MCF. We will say a quantity f (for example, a function) is of degree α if when the submanifold is dilated by a factor of λ , the rescaled quantity satisfies $\tilde{f} = \lambda^\alpha f$.

Lemma 9.7 *Suppose f is a function of degree α . Then*

$$\left(\frac{d}{ds} - \tilde{\Delta}\right) \tilde{f} = \lambda^{\alpha-2} \left(\frac{d}{dt} - \Delta\right) f - \alpha \tilde{f}.$$

The same statement is true of tensors.

Proof The proof for functions is exactly as in [19, Lemma 9.1]. The tensor case follows identically, however note that we also rescale the coordinate vectors. \square

We now note that we have the following evolution inequalities along the renormalised flow.

Lemma 9.8 *There exist $\Upsilon, p > 0$ depending on n and C_v such that along the renormalised flow,*

$$\left(\frac{d}{ds} - \tilde{\Delta}\right) \frac{1}{t^p} e^{-\frac{\tilde{r}^2}{\Upsilon t}} \geq 0.$$

where \tilde{r}^2 is the renormalisation of r^2 in Corollary 3.2. Furthermore,

$$\left(\frac{d}{ds} - \tilde{\Delta}\right) \|\tilde{H} - \tilde{X}^\perp\|^2 \leq -2\|\tilde{H} - \tilde{X}^\perp\|^2 - \frac{1}{2} \frac{|\nabla\|\tilde{H} - \tilde{X}^\perp\|^2|^2}{\|\tilde{H} - \tilde{X}^\perp\|^2}.$$

Proof We have that

$$\left(\frac{d}{ds} - \tilde{\Delta}\right) \tilde{r}^2 = -2n - 2\tilde{r}^2 - (\tilde{v}^2 - m).$$

Since

$$\left(\frac{d}{ds} - \tilde{\Delta}\right) e^f = e^f \left(\left(\frac{d}{ds} - \tilde{\Delta}\right) f - |\nabla f|^2\right),$$

if we let $f = -\frac{\tilde{r}^2}{\Upsilon t} - p \log t$, we see that

$$\begin{aligned} & \left(\frac{d}{ds} - \tilde{\Delta} \right) t^{-p} e^{-\frac{\tilde{r}^2}{\Upsilon t}} \\ &= t^{-p} e^{-\frac{\tilde{r}^2}{\Upsilon t}} \left(\frac{1}{\Upsilon t} (2n + 2\tilde{r}^2 + (\tilde{v}^2 - k)) + \frac{\tilde{r}^2}{\Upsilon t^2} - \frac{p}{t} - \frac{4\tilde{r}^2 |\nabla \tilde{r}|^2}{\Upsilon^2 t^2} \right) \\ &\geq t^{-p} e^{-\frac{\tilde{r}^2}{\Upsilon t}} \left(\frac{1}{\Upsilon t} (2n + 2\tilde{r}^2 + (\tilde{v}^2 - k) - \Upsilon p) + \frac{\tilde{r}^2 (\Upsilon - 4C_v)}{\Upsilon^2 t^2} \right). \end{aligned}$$

Hence, taking $\Upsilon = 4C_v$ and $p = \frac{2n}{4C_v}$ gives the first claim.

Since H_A is degree -1 , using Lemmas 3.9 and 9.7 we obtain that

$$\left(\frac{d}{ds} - \tilde{\Delta} \right) \tilde{H}_A = -\tilde{H}_B \langle v^B, \tilde{\Pi}_{ij} \rangle \langle \tilde{\Pi}^{ij}, v_A \rangle + \tilde{H}_A.$$

Similarly, for $Q_A := \langle X, v_A \rangle$ of degree 1, we may use Lemmas 3.3 and 9.7 to yield

$$\left(\frac{d}{ds} - \tilde{\Delta} \right) \tilde{Q}_A = -\tilde{Q}_B \langle v^B, \tilde{\Pi}_{ij} \rangle \langle \tilde{\Pi}^{ij}, v_A \rangle - 2\tilde{H}_A - \tilde{Q}_A.$$

Writing $\tilde{W}_A = \tilde{H}_A + \tilde{Q}_A$ and the nonnegative 2-tensor $\tilde{S}_A^B = \langle v^B, \tilde{\Pi}_{ij} \rangle \langle \tilde{\Pi}^{ij}, v_A \rangle$, we have that

$$\left(\frac{d}{ds} - \tilde{\Delta} \right) \tilde{W}_A = -\tilde{W}_B \tilde{S}_A^B - \tilde{W}_A$$

As $\|\tilde{H} - \tilde{X}^\perp\|^2 = \sum_{A=1}^m \tilde{W}_A^2$, we have that

$$\begin{aligned} \left(\frac{d}{ds} - \tilde{\Delta} \right) \|\tilde{H} - \tilde{X}^\perp\|^2 &= -2\tilde{W}_B \tilde{S}^{BA} \tilde{W}_A - 2\|\tilde{H} - \tilde{X}^\perp\|^2 - 2\|\nabla^\perp(\tilde{H} - \tilde{X}^\perp)\|^2 \\ &\leq -2\tilde{W}_B \tilde{S}^{BA} \tilde{W}_A - 2\|\tilde{H} - \tilde{X}^\perp\|^2 - \frac{1}{2} \frac{|\nabla \|\tilde{H} - \tilde{X}^\perp\|^2|^2}{\|\tilde{H} - \tilde{X}^\perp\|^2}. \end{aligned}$$

The second claim follows. □

Given equation (9.4), on \tilde{M}_t , we now know that for $c > c_0$ we have

$$1 < c + |\tilde{X}|^2 =: \tau_c \quad \text{and} \quad \lim_{R \rightarrow \infty} \inf_{\tilde{M}_t \setminus C_R} \tau_c \rightarrow \infty. \tag{9.5}$$

This leads us to a further evolution inequality along the renormalised flow.

Lemma 9.9 *There exists $c > 0$ such that, along the renormalised flow,*

$$\left(\frac{d}{ds} - \tilde{\Delta} \right) \|\tilde{H} - \tilde{X}^\perp\|^2 \tau_c^{-1} \leq 0.$$

Proof Writing $f = \|\tilde{H} - \tilde{X}^\perp\|^2$ and estimating using Young’s inequality:

$$\begin{aligned} \left(\frac{d}{ds} - \tilde{\Delta}\right) f \tau_c^{-1} &\leq -2f \tau_c^{-1} - \frac{|\nabla f|^2}{2f} \tau_c^{-1} - 2\langle \nabla f, \nabla \tau_c^{-1} \rangle \\ &\quad + f \tau_c^{-1} \left(-\tau_c^{-1} \left(\frac{d}{ds} - \tilde{\Delta}\right) |\tilde{X}|^2 - 2\tau_c^{-2} |\nabla |\tilde{X}|^2|^2\right) \\ &\leq f \tau_c^{-1} (-2 + 2(n + |\tilde{X}|^2) \tau_c^{-1}). \end{aligned}$$

For $c > n$, we may estimate $(n + |\tilde{X}|^2) \tau^{-1} < 1$, giving the result. □

Finally, we use an argument similar to [8, Theorem A.2] to get our claimed convergence.

Proof of Theorem 9.2 We write $f = \|\tilde{H} - \tilde{X}^\perp\|^2 \tau_c^{-1}$. Clearly f is bounded. We claim that

$$\limsup_{t \rightarrow \infty} \sup_{M_t} f = 0. \tag{9.6}$$

Let $\epsilon > 0$. We first show that outside cylinders of sufficiently large radii and for sufficiently large times, f is smaller than ϵ : Under the renormalised flow H is bounded, so we only need to show that $\|\tilde{X}^\perp\|^2 \tau_c^{-1}$ is small. We first wait until

$$t_0 = 2 \log \left(\frac{2C}{\epsilon} \right),$$

where C is as in Lemma 9.6. By Lemma 9.6, there exists $R = R(t_0, L)$ such that for all $t \in [0, 2t_0)$, on $M_t \setminus \mathcal{C}_R$,

$$f \leq C e^{-\frac{t}{2}}.$$

In particular, for all $t \in [t_0, 2t_0)$, on $M_t \setminus \mathcal{C}_R$,

$$f \leq \frac{\epsilon}{2}.$$

On the interval $[t_0, \infty)$, for $a, \delta > 0$ we consider the function

$$g = f - \epsilon - a\psi, \quad \text{where } \psi = (t - t_0 + \delta)^{-p} e^{-\frac{\tilde{r}^2}{\Upsilon(t-t_0+\delta)}}.$$

We choose $p, \Upsilon > 0$ as in Lemma 9.8 so that the heat operator acting on ψ is positive. Furthermore, after choosing $\delta > 0$ small (so that this is a smooth function at time $t = t_0$) we observe that there exists $a > 0$ such that at time $t_0, g < 0$. Outside \mathcal{C}_R , this is trivially true, and inside this follows since ψ is strictly positive and continuous, and f is bounded.

For all $t > t_0$, Lemma 9.6 guarantees that the set such that $f \geq \frac{\epsilon}{2}$ is compact. Observing that

$$\left(\frac{d}{dt} - \Delta\right)g \leq 0,$$

we may therefore apply the weak maximum principle on larger and larger compact domains to imply that $g \leq 0$. Since ψ decays uniformly to zero,

$$\limsup_{t \rightarrow \infty} \sup_{\tilde{M}_t} f \leq 2\epsilon.$$

Since ϵ was arbitrary, (9.6) holds.

As a result, for any $t_i \rightarrow \infty$, for all $1 \leq j \in \mathbb{N}$ Proposition 8.3 and Corollary 8.4 we have uniform curvature and higher order estimates on $\mathcal{C}_j \cap \tilde{M}_{t_i}$. Arzelá–Ascoli and (9.6) imply there exists a subsequence which converges to a portion of MCF expander as $i \rightarrow \infty$. Repeating this argument for each j and taking a diagonal sequence implies the statement. \square

Acknowledgements This research was supported by Leverhulme Trust Research Project Grant RPG-2016-174.

Open Access This article is distributed under the terms of the Creative Commons Attribution 4.0 International License (<http://creativecommons.org/licenses/by/4.0/>), which permits unrestricted use, distribution, and reproduction in any medium, provided you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons license, and indicate if changes were made.

Appendix A: Spacelike Mean Curvature Flow of Graphs

In this appendix we consider the mean curvature flow equation in terms of a graph; that is, for a function $\hat{u} : \mathbb{R}^n \times [0, T) \rightarrow \mathbb{R}^m$ defining the parametrisation $\hat{X} : \mathbb{R}^n \times [0, T) \rightarrow \mathbb{R}^{n,m}$ by

$$\hat{X}(x, t) = x^i f_i + \hat{u}^A(x, t)e_A.$$

We see that

$$\hat{X}_i = f_i + D_i \hat{u}(x, t)^A e_A, \quad g_{ij} = \delta_{ij} - D_i \hat{u}^A D_j \hat{u}_A,$$

and we consider the flow only when it is spacelike; i.e. $g_{ij} > 0$ as a matrix. Equation (1.1) now reads

$$\left(\frac{d\hat{X}}{dt}\right)^\perp = H = g^{ij} \left(\frac{\partial^2 \hat{X}}{\partial x^i \partial x^j}\right)^\perp,$$

which implies

$$\left(\frac{d\hat{u}^A}{dt} - g^{ij} D_{ij}^2 \hat{u}^A \right) e_A^\perp = 0.$$

We observe that

$$\begin{aligned} \hat{g}_{AB} &:= \left\langle e_A^\perp, e_B^\perp \right\rangle \\ &= \left\langle e_A - \left\langle e_A, \hat{X}_i \right\rangle g^{ij} \hat{X}_j, e_B - \left\langle e_B, \hat{X}_k \right\rangle g^{kl} \hat{X}_l \right\rangle = -\delta_{AB} - D_l \hat{u}_A g^{lk} D_k \hat{u}_B. \end{aligned}$$

At any point we may take coordinates on \mathbb{R}^n so that $D_i \hat{u}^A D_j \hat{u}_A$ is diagonal with eigenvalues $\lambda_i \in [0, 1)$. We see that (without summation in A),

$$\hat{g}_{AA} = -1 - \sum_j \frac{(D_j \hat{u}_A)^2}{1 - \lambda_j} < -1, \tag{A.1}$$

and so \hat{g} is a symmetric negative definite matrix (which is bounded as $\lambda_i < 1$). Hence, \hat{g} is invertible and spacelike mean curvature flow is equivalent to

$$\frac{d\hat{u}^A}{dt} - g^{ij} (D\hat{u}) D_{ij}^2 \hat{u}^A = 0 \quad \text{for } A = 1, \dots, m \text{ on } \mathbb{R}^n \times [0, T), \tag{A.2}$$

where, as usual, g^{ij} is the inverse of $g_{ij} = \delta_{ij} - D_i \hat{u}^A D_j \hat{u}_A$.

We see that the gradient function

$$v^2 = \sum_A \|e_A^\perp\|^2 = \sum_A -\hat{g}_{AA} = m + D_i \hat{u}_A g^{ij} D_j \hat{u}^A = m - n + \sum_i \frac{1}{1 - \lambda_i}.$$

Clearly while the gradient function is uniformly bounded, $\lambda_i < 1$ and therefore g_{ij} is positive definite and (1.3) is uniformly parabolic. Hence v^2 acts as both an estimate on how spacelike the surface is, and also the parabolicity of the PDE. We observe that this is equivalent to a bound for some $c \in (0, 1)$

$$D_v u \cdot \theta := v^i D_i u^A \theta_A < 1 - c \quad \text{for all } v \in \mathbb{R}^n, \theta \in \mathbb{R}^m \text{ where } \|\theta\| = 1, |v| = 1.$$

One way to see this is to consider v and θ which are maximisers of $D_v u \cdot \theta$ and note that then, due to properties of maximisers, v is the largest eigenvector of $D_i u^A D_j u_A$ with eigenvalue $\lambda_i = (D_v u \cdot \theta)^2$. The claimed equivalence now follows.

In the Neumann boundary condition case, over the domain Ω the same equation (A.2) holds, but we still need to consider the boundary condition. We require that μ , which by abuse of notation is both the unit normal to Σ and the unit normal to $\partial\Omega$, is in TM . Thus

$$\mu = \mu^i f_i = \mu^\top = \left\langle \mu, \hat{X}_i \right\rangle g^{ij} \hat{X}_j = \mu_i g^{ij} \hat{X}_j,$$

so for all $1 \leq A \leq m$,

$$0 = \mu_i g^{ij} D_j \hat{u}^A. \tag{A.3}$$

Multiplying by $D_l \hat{u}_A$ and summing over A we have that

$$0 = \mu_i g^{ij} D_j \hat{u}^A D_l \hat{u}_A = \mu_i g^{ij} (\delta_{jl} - g_{jl}) = \mu_i g^{il} - \mu_l.$$

Substituting this back in to (A.3) yields that for all $1 \leq A \leq m$

$$D_\mu \hat{u}^A = \mu^i D_i \hat{u}^A = 0.$$

In graphical coordinates the spacelike MCF with Neumann boundary condition thus becomes that, for all $I = 1, \dots, m$,

$$\begin{cases} \frac{d\hat{u}^A}{dt} - g^{ij} (D\hat{u}) D_{ij}^2 \hat{u}^A = 0 & \text{on } \Omega \times [0, T), \\ D_\mu \hat{u}^A = 0 & \text{on } \partial\Omega \times [0, T), \\ \hat{u}^A(\cdot, 0) = \hat{u}_0^A(\cdot) & \text{on } \Omega, \end{cases} \tag{A.4}$$

where g^{ij} is strictly positive definite and bounded if and only if $v < C < \infty$.

Appendix B: Uniqueness of MCF over Compact Domains

We demonstrate the uniqueness of solutions to the Dirichlet and Neumann problems simultaneously.

Proposition B.1 *Suppose that $\Omega \subset \mathbb{R}^n$ is bounded, with smooth boundary $\partial\Omega$. Let $u, z \in C^{2;1}(\Omega \times [0, T)) \cap C^\infty(\Omega \times (0, T))$ be solutions to either (6.3) or (7.2) which are uniformly spacelike; i.e. there exists $c \in (0, 1)$ such that*

$$|D\hat{u}^A|, |D\hat{z}^A| < 1 - c \quad \text{for all } 1 \leq A \leq m.$$

If $\hat{u}(\cdot, 0) = \hat{z}(\cdot, 0)$ then for all $t \in [0, T)$, $\hat{u}(\cdot, t) = \hat{z}(\cdot, t)$.

Proof We consider $y^A = \hat{u}^A - \hat{z}^A$.

$$\begin{aligned} \frac{d}{dt} y^A &= g^{ij} (D\hat{u}) D_{ij} y^A + [g^{ij} (D\hat{u}) - g^{ij} (D\hat{z})] D_{ij} \hat{z}^A \\ &= g^{ij} (D\hat{u}) D_{ij} y^A + \int_0^1 \frac{d}{d\tau} g^{ij} (Du_\tau) d\tau D_{ij} \hat{z}^A \\ &= g^{ij} (D\hat{u}) D_{ij} y^A - D_l (\hat{u} - \hat{z})_B \int_0^1 2D_k u_\tau^B g^{ik} (Du_\tau) g^{jl} (Du_\tau) d\tau D_{ij} \hat{z}^A \\ &= g^{ij} (D\hat{u}) D_{ij} y^A - D_l y_B V^{Bl ij} D_{ij} \hat{z}^A \end{aligned}$$

where $u_\tau = \tau \hat{u} - (1 - \tau) \hat{z}$ and V^{Blj} is bounded due to spacelikeness of \hat{u} and \hat{z} . We see that considering everything graphically,

$$\begin{aligned} \frac{d}{dt} \|y\|^2 &= g^{ij} (D\hat{u}) D_{ij} \|y\|^2 - D_l y_B V^{Blj} D_{ij} \hat{z}^A y_A - 2 \sum_{A=1}^m D_i y_A g^{ij} (D\hat{u}) D_j y_A \\ &\leq g^{ij} (D\hat{u}) D_{ij} \|y\|^2 + C \|y\|^2. \end{aligned}$$

where C depends on C_v and $\sup_{\Omega \times [0, T]} |D^2 v|$. If \hat{u}, \hat{z} satisfy (7.2) then on $\partial\Omega, \|y\|^2 = 0$.

On the other hand if \hat{u}, \hat{z} satisfy (6.3) then at the boundary $D_\mu \|y\|^2 = 0$.

In both cases we may apply the maximum principle to yield

$$\sup_{\Omega} \|y\|^2(\cdot, t) \leq e^{Ct} \sup_{\Omega} \|y\|^2(\cdot, 0)$$

which implies the result. □

Appendix C: Evolution of Symmetric 2-tensors

We derive a general evolution equation for a symmetric 2-tensor along a spacelike mean curvature flow M_t .

Lemma C.1 *Suppose that T is a smooth symmetric 2-tensor on $\mathbb{R}^{n,m}$. We write the restriction of this tensor to $T M_t$ as*

$$T_{ij} = T(X_i, X_j).$$

Then

$$\nabla_k T_{ij} = \bar{\nabla}_k T_{ij} + T(H_{ki}, X_j) + T(X_i, H_{kj}).$$

and

$$\begin{aligned} \left(\frac{d}{dt} - \Delta\right) T_{ij} &= H^A h_{Ai}^k T_{kj} + H^A h_{Aj}^k T_{ki} - g^{kl} \bar{\nabla}_k \bar{\nabla}_l T_{ij} - 2 \bar{\nabla}_k T(H_i^k, X_j) \\ &\quad - 2 \bar{\nabla}_k T(X_i, H_j^k) - h_{ki}^B h_{Bl}^p T_{pj} - h_{kj}^B h_{Bl}^p T_{pi} - 2 h_{ik}^A h_j^{Bk} T_{AB}. \end{aligned}$$

Proof We have that

$$\begin{aligned} \frac{d}{dt} T_{ij} &= \bar{\nabla}_H T_{ij} + T(\bar{\nabla}_i H, X_j) + T(X_i, \bar{\nabla}_j H) \\ &= \bar{\nabla}_H T_{ij} + T(\nabla_i^\perp H, X_j) + T(X_i, \nabla_j^\perp H) + H^A h_{Ai}^k T_{kj} + H^A h_{Aj}^k T_{ki}, \end{aligned}$$

where we used that

$$\bar{\nabla}_i H = \nabla_i^\perp H + H^A h_{Ai}^k X_k.$$

We calculate

$$\nabla_k T_{ij} = \bar{\nabla}_k T_{ij} + T(II_{ki}, X_j) + T(X_i, II_{kj}).$$

We also see

$$\begin{aligned} \nabla_l \nabla_k T_{ij} &= \bar{\nabla}_l \bar{\nabla}_k T_{ij} + \bar{\nabla}_{II_{kl}} T_{ij} + \bar{\nabla}_k T(II_{li}, X_j) + \bar{\nabla}_k T(X_i, II_{lj}) \\ &\quad + \bar{\nabla}_l T(II_{ki}, X_j) + T(\nabla_l^\perp II_{ki}, X_j) + h_{ki}^B h_{Bl}^p T_{pj} + T(II_{ki}, II_{lj}) \\ &\quad + \bar{\nabla}_l T(X_i, II_{kj}) + T(X_i, \nabla_l^\perp II_{kj}) + h_{kj}^B h_{Bl}^p T_{ip} + T(II_{li}, II_{kj}). \end{aligned}$$

Putting this together and using Codazzi–Mainardi gives the evolution of T_{ij} . □

Appendix D: An Extension of Boundary Quantities

We demonstrate the following.

Lemma D.1 *For Σ as in Sect. 6, there exists a smooth extension of μ and II^Σ , the outward normal and the second fundamental form of Σ respectively, such that on Σ ,*

$$\bar{\nabla}_\mu \mu = 0, \quad \bar{\nabla}_\mu II^\Sigma(X, Y) = 0.$$

Proof We consider the function $d : \mathbb{R}^n \rightarrow \mathbb{R}$, defined to be the signed minimum distance to $\partial\Omega \subset \mathbb{R}^n$ where d is positive in Ω . Since $\partial\Omega$ is smooth, there exists a c_d, C_d such that on the set $U := \{x \in \mathbb{R}^n \mid d(x) < c_d\}$, d is smooth and $|Dd| + |D^2d| + |D^3d| < C_d$. On U , we define

$$\hat{\mu} = -Dd, \quad \tilde{A}(X, Y) = \langle D_X \hat{\mu}, Y \rangle,$$

and outside U we take both to be zero. Standard properties of the distance function imply that on U , $D_{\hat{\mu}} \hat{\mu} = 0$, and clearly on $\partial\Omega$, \tilde{A} is the second fundamental form of $\partial\Omega$. Since \mathbb{R}^n is flat we have that

$$D_{\hat{\mu}} \tilde{A}(X, Y) = \langle D_{\hat{\mu}}(D_X \hat{\mu}) - D_{D_{\hat{\mu}} X} \hat{\mu}, Y \rangle = \langle D_X(D_{\hat{\mu}} \hat{\mu}) - D_{D_X \hat{\mu}} \hat{\mu}, Y \rangle = -\tilde{A}^2(X, Y).$$

We therefore set

$$\hat{A}(X, Y) = \tilde{A}(X, Y) - d\tilde{A}^2(X, Y)$$

and we see that on $\partial\Omega$, $D_{\hat{\mu}} \hat{A}(X, Y) = 0$. We now choose a smooth cutoff function $\chi : \mathbb{R} \rightarrow \mathbb{R}$ such that $\chi(x) = 1$ for $|x| < \frac{c_d}{3}$, $\chi(x) = 0$ for $|x| > \frac{2c_d}{3}$. For $(x, y) \in \mathbb{R}^n \times \mathbb{R}^m$, define $\mu(x, y) = \chi(d(x))\hat{\mu}(x)$ and define II^Σ to be the pullback of $\chi(d(x))\hat{A}$ by the standard projection. All claimed properties now hold. □

References

1. Acharya, B.S., Witten, E.: Chiral fermions from manifolds of G_2 holonomy. [arXiv:hep-th/0109152](https://arxiv.org/abs/hep-th/0109152). (2001)
2. Baraglia, D.: Moduli of coassociative submanifolds and semi-flat G_2 -manifolds. *J. Geom. Phys.* **60**(12), 1903–1918 (2010)
3. Bartnik, R.: Existence of maximal surfaces in asymptotically flat spacetimes. *Commun. Math. Phys.* **94**(2), 155–175 (1984)
4. Bartnik, R., Simon, L.: Spacelike hypersurfaces with prescribed boundary values and mean curvature. *Commun. Math. Phys.* **87**(1), 131–152 (1982)
5. Bryant, R.L.: Some remarks on G_2 -structures. In: *Proceedings of Gökova Geometry–Topology Conference 2005*, pp. 75–109. Gökova Geometry/Topology Conference (GGT), Gökova (2006)
6. Chen, G.: Shi-type estimates and finite time singularities of flows of G_2 structures. *Q. J. Math.* **69**(3), 779–797 (2018)
7. Cheng, S.-Y., Yau, S.-T.: Maximal spacelike hypersurfaces in the Lorentz–Minkowski spaces. *Ann. Math.* **104**, 407–419 (1974)
8. Clutterbuck, J., Schnürer, O.: Stability of mean convex cones under mean curvature flow. *Math. Z.* **267**(3–4), 535–547 (2011)
9. Donaldson, S.: Adiabatic limits of co-associative Kovalev–Lefschetz fibrations. In: *Algebra, Geometry, and Physics in the 21st Century*, vol. 324 of *Progr. Math.*, pp. 1–29. Birkhäuser/Springer, Cham (2017)
10. Donaldson, S.: Remarks on G_2 -manifolds with boundary. [arXiv:1802.09694](https://arxiv.org/abs/1802.09694). (2018)
11. Ecker, K.: Interior estimates and longtime solutions for mean curvature flow of noncompact spacelike hypersurfaces in Minkowski space. *J. Differ. Geom.* **46**(3), 481–498 (1997)
12. Ecker, K.: Mean curvature flow of spacelike hypersurfaces near null initial data. *Commun. Anal. Geom.* **11**(2), 181–205 (2003)
13. Ecker, K., Huisken, G.: Interior estimates for hypersurfaces moving by mean curvature. *Invent. Math.* **105**, 547–569 (1991)
14. Ecker, K., Huisken, G.: Parabolic methods for the construction of spacelike slices of prescribed mean curvature in cosmological spacetimes. *Commun. Math. Phys.* **135**(3), 595–613 (1991)
15. Edelen, N.: Convexity estimates for mean curvature flow with free boundary. *Adv. Math.* **294**, 1–36 (2016)
16. Fine, J., Yao, C.: Hypersymplectic 4-manifolds, the G_2 -Laplacian flow and extension assuming bounded scalar curvature. *Duke Math. J.* **167**(3), 3533–3589 (2018)
17. Gerhardt, C.: Hypersurfaces of prescribed mean curvature in Lorentzian manifolds. *Math. Z.* **235**, 83–97 (2000)
18. Gukov, S., Yau, S.-T., Zaslow, E.: Duality and fibrations on G_2 -manifolds. *Turkish J. Math.* **27**, 61–97 (2003)
19. Huisken, G.: Flow by mean curvature of convex surfaces into spheres. *J. Differ. Geom.* **20**, 237–266 (1984)
20. Joyce, D.D.: *Compact Manifolds with Special Holonomy*. Oxford Mathematical Monographs. Oxford University Press, Oxford (2000)
21. Lambert, B.: A note on the oblique derivative problem for graphical mean curvature flow in Minkowski space. *Abh. Math. Semin. Univ. Hambg.* **82**(1), 115–120 (2012)
22. Lambert, B.: The perpendicular Neumann problem for mean curvature flow with a timelike cone boundary condition. *Trans. Am. Math. Soc.* **366**, 3373–3388 (2014)
23. Lawson Jr., H.B., Osserman, R.: Non-existence, non-uniqueness and irregularity of solutions to the minimal surface system. *Acta Math.* **139**(1–2), 1–17 (1977)
24. Li, G., Salavessa, I.M.C.: Mean curvature flow of spacelike graphs. *Math. Z.* **269**(3–4), 697–719 (2011)
25. Li, Y.: Dirichlet problem for maximal graphs of higher codimension. [arXiv:1807.11795](https://arxiv.org/abs/1807.11795). (2018)
26. Lieberman, G.M.: *Second Order Parabolic Differential Equations*. World Scientific Publishing Co., Pte. Ltd., Singapore (1996)
27. Lotay, J.D., Wei, Y.: Laplacian flow for closed G_2 structures: Shi-type estimates, uniqueness and compactness. *Geom. Funct. Anal.* **27**(1), 165–233 (2017)
28. Lotay, J.D., Wei, Y.: Laplacian flow for closed G_2 structures: real analyticity. *Commun. Anal. Geom.* **27**, 73–109 (2019)
29. Lotay, J.D., Wei, Y.: Stability of torsion-free G_2 structures along the Laplacian flow. *J. Differ. Geom.* **111**, 495–526 (2019)

30. Smoczyk, K.: Mean curvature flow in higher codimension: introduction and survey. In: Bär, C., Lohkamp, J., Schwarz, M. (eds.) *Global Differential Geometry*, pp. 231–274. Springer, Berlin (2012)
31. Stahl, A.: Regularity estimates for solutions to the mean curvature flow with a Neumann boundary condition. *Calc. Var. Partial Differ. Equ.* **4**, 385–407 (1996)

Publisher's Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.