



Computational Techniques Based on Artificial Intelligence for Extracting Optimal Parameters of PEMFCs: Survey and Insights

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Abstract

For the sake of precise simulation, and proper controlling of the performance of the proton exchange membrane fuel cells (PEMFCs) generating systems, robust and neat mathematical modelling is crucially needed. Principally, the robustness and precision of modelling strategy depend on the accurate identification of PEMFC's uncertain parameters. Hence, in the last decade, with the noteworthy computational development, plenty of meta-heuristic algorithms (MHAs) are applied to tackle such problem, which have attained very positive results. Thus, this review paper aims at announcing novel inclusive survey of the most up-to-date MHAs that are utilized for PEMFCs stack's parameter identifications. More specifically, these MHAs are categorized into swarm-based, nature-based, physics-based and evolutionary-based. In which, more than 350 articles are allocated to attain the same goal and among them only 167 papers are addressed in this effort. Definitely, 15 swarm-based, 7 nature-based, 6 physics-based, 2 evolutionary-based and 4 others-based approaches are touched with comprehensive illustrations. Wherein, an overall summary is undertaken to methodically guide the reader to comprehend the main features of these algorithms. Therefore, the reader can systematically utilize these techniques to investigate PEMFCs' parameter estimation. In addition, various categories of PEMFC's models, several assessment criteria and many PEMFC commercial types are also thoroughly covered. In addition to that, 27 models are gathered and summarized in an attractive manner. Eventually, some insights and suggestions are presented in the conclusion for future research and for further room of improvements and investigations.

1 Introduction

In the last decades, the necessities of using clean energy sources are rapidly increasing due to the ecological devastating impacts of the fossil fuels [1–4]. As a result, renewable energy sources (RESs) are targeted to somehow replace the conventional ones due to their advantageous characteristics. Virtually, no emissions, static nature of most RESs types, higher efficiency, availability upon wide range of output power (from mW to MW's) and convenient for all applications (portable, transportation and stationery). Amongst the several alternatives of RESs; fuel cells (FCs), solar and wind

have attracted decision-makers and industry-stakeholders to utilize them as prime energy supplies [1–3, 5].

Particularly, FCs have been considered as a new booming energy conversion source as they have penetrated several applications whether portable, stationery or transportation [1, 2, 6]. Depending on the electrolyte type, FCs are categorized and utilized in the market for different applications [1, 2]. Examples of FC types are; (i) Proton exchange membrane FCs (PEMFCs) [7, 8], (ii) Solid oxide FCs (SOFCs) [9, 10], (iii) Molten carbonate FCs (MCFCs) [11], (iv) Phosphoric acid FCs (PAFCs) [8], (v) Alkaline FCs (AFCs) [12, 13] and furthermore. Specifically, the basic characteristics of the latter-mentioned types are illustrated in Table 1.

PEMFCs have distinguished by their flexibility, high power density, short startup time, fast response for load changes, low operating temperatures and pressures and no safety issues. Thus, they have been involved in the widest range of applications, mainly in transportation applications [1, 2, 14–18]. Nevertheless, the expensive cost of PEMFCs hinders their competitive penetration in the market [1, 2].

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Table 1 Basic features of five kinds of FCs

FC types	Electrolyte material	Fuel	Oxidant	Operating temperature (°C)	Power rating (kW)	Merits	Demerits	Electrical efficiency (%)
PEMFCs [1, 7, 8]	Solid Nafion	Hydrogen	Air-oxygen	60–80	0.001–100	<ul style="list-style-type: none"> ✓ Modularity ✓ Compact size ✓ High power density ✓ Low operating temperature ✓ Short startup time ✓ Fast dynamic action ✓ High electrical efficiency ✓ High-scale heat ✓ Less sensitivity to pollutants ✓ Applicability of internal reforming ✓ Low-cost catalyst 	<ul style="list-style-type: none"> ✗ Sophisticated thermal and water management ✗ High-cost catalyst ✗ Highly affected by pollutants ✗ Low-scale heat ✗ Long startup time ✗ Low power density ✗ Thermal stresses ✗ Durability problems ✗ High fabrication cost 	40–60
SOFCs [1, 8–10]	Solid yttria-stabilized zirconia (YSZ)	Methane-natural gas-coal gas	Air-oxygen	800–1000	1–2000	<ul style="list-style-type: none"> ✓ High electrical efficiency ✓ High-scale heat ✓ Less sensitivity to pollutants ✓ Applicability of internal reforming ✓ Low-cost catalyst 	<ul style="list-style-type: none"> ✗ Long startup time ✗ Low power density ✗ Thermal stresses ✗ Durability problems ✗ High fabrication cost 	55–65
MCFCs [1, 8, 11]	Liquid alkali carbonate Li_2CO_3 , Na_2CO_3 , K_2CO_3 in Lithium aluminate (LiAlO_2)	Methane-natural gas-coal gas	Air-oxygen	600–700	500–10,000	<ul style="list-style-type: none"> ✓ High electrical efficiency ✓ High-scale heat ✓ Less sensitivity to pollutants ✓ Applicability of internal reforming ✓ Low-cost catalyst ✓ Material flexibility 	<ul style="list-style-type: none"> ✗ Long startup time ✗ Low power density ✗ Corrosion of the electrolyte ✗ Corrosion of the mineral parts ✗ Vaporization losses ✗ The defrost of the catalyst in the electrolyte 	55–65
PAFCs [1, 8]	Concentrated liquid phosphoric acid (H_3PO_4) in silicon carbide (SiC)	Hydrogen	Air-oxygen	160–220	200–10,000	<ul style="list-style-type: none"> ✓ reliability and maturity ✓ Unpretentious water management ✓ High-scale heat 	<ul style="list-style-type: none"> ✗ Comparatively long startup time ✗ Low power density ✗ Highly affected by pollutants ✗ High cost of auxiliary systems ✗ Modest electrical efficiency ✗ High-cost catalyst ✗ Comparatively large size 	36–45

Table 1 (continued)

FC types	Electrolyte material	Fuel	Oxidant	Operating temperature (°C)	Power rating (kW)	Merits	Demerits	Electrical efficiency (%)
AFCs [1, 8, 12, 13]	Potassium hydroxide (KOH) water solution Anion exchange membrane (AEM)	Hydrogen	Pure oxygen	Under zero–230	1–100	<ul style="list-style-type: none"> ✓ High electrical efficiency ✓ Broad range of operating temperatures and pressures ✓ Low-cost catalyst ✓ Flexible catalyst 	<ul style="list-style-type: none"> ✗ Excessively affected by pollutants ✗ Require pure hydrogen and oxygen for reactions ✗ Low power density ✗ High corrosion of the electrolyte and sophisticated and high-cost electrolyte management for mobile electrolyte systems 	60–70

To appraise the features of PEMFCs systems, several modelling methods have been proposed, such as theoretical [19], empirical [20], and semi-empirical [21] models. Herein, a semi-empirical model, developed by Amphlett is adopted to simulate the polarization characteristics, which are represented by the output current versus voltage (I–V) curve, under various operating situations [21, 22].

In addition, precise PEMFC modelling is crucial for assessing the performance [23], optimum controlling [23], accurate simulating [24], and maximum power tracking [25, 26] of the PEMFCs units. Thus, in the recent years, numerous researchers have attempted to define the unknown parameters of PEMFCs’ model by the aid of several parameter estimation techniques. Examples of these techniques are electrochemical impedance spectroscopy-based approaches [27–29], black box-based methods [30, 31], adaptive filter-based techniques [32–34], current switching methods [35] and many more.

Nevertheless, these techniques are not broadly utilized because of their plain drawbacks, such as inflexibility and impracticability [7]. Moreover, the PEMFC’s model is high nonlinear, multi-variant and its variables are strongly coupled and severely affected by the operating conditions. Hence, the dynamics and accurate modelling have become more complicated and time-consuming when employed by such conventional techniques [36–42]. Therefore, there is an imperative demand to derive robust and feasible techniques to tackle such issue.

Since the rapid development of computer-based and artificial intelligence (AI)-based methods, meta-heuristic algorithms (MHAs) have attained distinct results when applied on several highly nonlinear optimization problems [43]. Principally, the problem of defining the unknown parameters of the PEMFCs can be easily dealt with as an optimization task. So, utilizing MHAs, as a reliable and precise tool to obtain the optimal solutions offers low computational effort and high accuracy.

Consequently, numbers of MHAs are employed for extracting the unspecified parameters of PEMFCs. Samples of such approaches are genetic algorithm [44, 45], differential evolution [46, 47], artificial bee colony [48], backtracking search algorithm [49], Biogeography-based optimizer [50], Artificial bee swarm optimizer [51], seeker optimizer [52], Artificial immune system [53], quantum-based optimizer [54], and etc.

Thereupon, an extensive survey article is urgently demanded to summarize these MHAs. A previous survey on several MHAs for PEMFC’s parameter estimation was performed in [5], where only fifteen algorithms are illustrated without methodical classification and comparison among various approaches. Furthermore, detailed discussions and simulation consequences of the algorithms have not been addressed. In addition, another recent survey was

undertaken in [7], where only twenty-eight algorithms are discussed. However, it lacks details about the various PEMFC's models in terms of their classification as well as their applications. Moreover, Amphlett model hasn't been fully described in terms of mathematical representations.

Thus, a comprehensive literature survey on numerous MHAs implemented for extracting the unknown parameters of PEMFC's model is undertaken. In accordance, this paper can represent a unified reference for future in-depth research projects in the same field, while the major contributions can be epitomized as follows:

- (i) An overall discussion of various PEMFC models, besides their categories are presented,
- (ii) A summarized table gathering twenty-seven up-to-date models with their category-fulfill features,
- (iii) A total of thirty up-to-date MHAs with several simulation results are discussed, which are classified into four categories, swarm-based, nature-based, physics-based, and evolutionary-based, respectively, and
- (iv) A concluded Table offers the main characteristics of the MHAs, besides the technical specifications and operating conditions of each mentioned paper.

The rest of this paper is structured as follows: an overview of various PEMFC models found in the literature is revealed in Sect. 2. The mathematical model of PEMFC is described in Sect. 3. Section 4 announces some broadly utilized assessment criteria. Numerous MHAs for parameter identification of PEMFC are thoroughly illustrated in

Sect. 5. The subsequent discussion is provided in Sect. 6. Finally, Sect. 7 represents the conclusion.

2 PEMFCs' Generating Unit Models

Accurate modelling plays a significant role when the investigation of the FC's performance is needed. FC models can be categorized in terms of scale, approach, state, spatial dimensions, and covered phenomena, as depicted in Fig. 1 [55, 56].

A summarized comparison among the various FC model techniques is tabulated in Table 2 [57].

It's worth saying, some of the recent publications relative to the various FC model specifications are presented in Table 3.

3 PEMFC Mathematical Representation

As previously illustrated, since the FC is a multi-physics device, there are various classifications of the PEMFC models. Each model is constructed to tackle a certain aspect of the PEMFC. In this article, the polarization features' effects on the PEMFC performance are particularly addressed in terms of the thermodynamics potential, activation, ohmic and concentration losses. The difficulty of modelling the PEMFC polarization characteristics stems from their complexity, multi-variance, and strong coupling. However, the mathematical semi-empirical model deduced by Amphlett and Mann [21, 22] has gain the acceptance through its accurate forecasting the performance of PEMFC in form of I-V

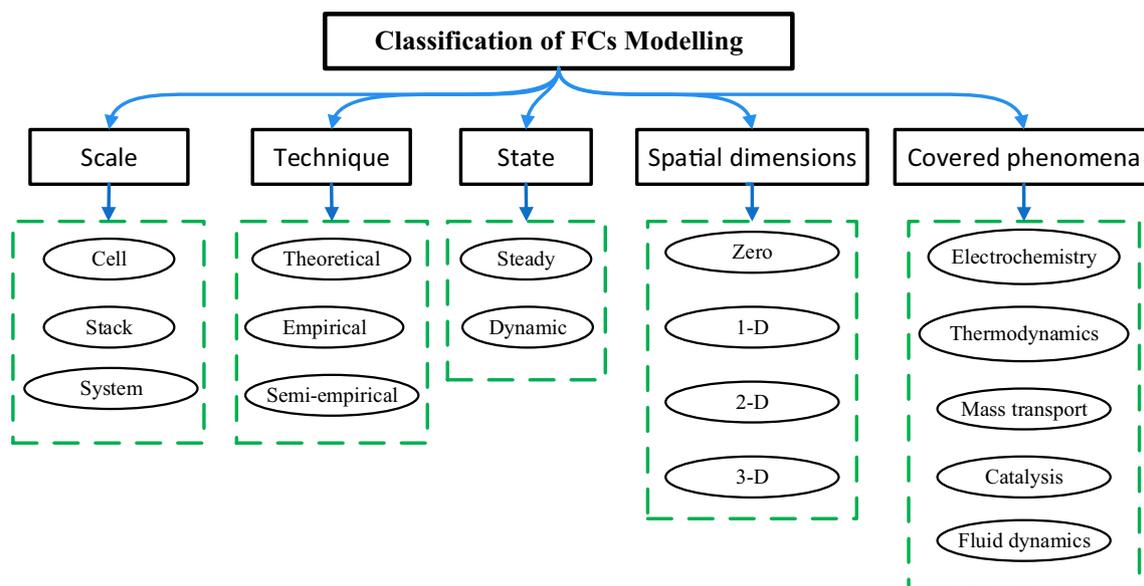


Fig. 1 Various modelling categories of PEMFC

Table 2 Summary of the comparative characteristics of various FC model techniques

Comparison item	Mechanistic	Empirical	Semi-empirical
Dependency on laboratory data	Low	High	Moderate
Computational consumed time	High	Low	Moderate
Accuracy	High	Acceptable	Acceptable
Dependency of physical expressions	High	Very low	Acceptable
Applications	Cell level	Stack/System level	Stack/system level
Online simulation possibility	Impossible	Possible	Possible

polarization curve under several steady state and dynamic operating conditions [5, 7]. Accordingly, numerous researchers have been biased to utilize this model for identifying the performance and the polarization characteristics of the PEMFC.

As depicted in Fig. 2, the I–V polarization curve of a single PEMFC can be divided into three regions: activation, ohmic and concentration losses, respectively. At the startup period with light load, a rapid decay of the PEMFC output voltage is noticed. This is due to the initial slow rate of the electrochemical reactions which is represented by the activation losses. Then, a linear decay of the output voltage due to the total resistance seen by the protons and electrons, which is represented by the ohmic losses. Again, the output voltage rapidly falls at higher load conditions due to the excessive water content reducing the concentration of the reactants in both electrodes. This voltage drop is represented by the concentration losses [1–3, 5, 7, 85].

Hence, the total output voltage of a single cell $V_{o/cell}$ is given by (1) [22]:

$$V_{o/cell} = E_{nernst} - V_{act} - V_{\Omega} - V_{con} \tag{1}$$

where E_{nernst} is the cell open circuit voltage in (V) that is calculated by the Nernst equation. V_{act} is the activation over-potential in (V). V_{Ω} is the ohmic voltage drop and V_{con} is the concentration over-potential in (V).

When connecting N_C multiple cells in series to form the stack, the stack output voltage $V_{o/stack}$ in (V) is described by (2).

$$V_{o/stack} = N_C \times V_{o/cell} \tag{2}$$

It’s worth mentioning, Eq. (2) assumes that all the connected cells exhibit the same polarization characteristics.

E_{nernst} is calculated by the Nernst equation with the addition of the temperature variation effect, which is given by (3) [86].

$$E_{nernst} = 1.22 - 8.5 \times 10^{-4}(T - 298.15) + 4.3085 \times 10^{-5} \times T \left[\ln \left(P_{H_2} \sqrt{P_{O_2}} \right) \right] \tag{3}$$

where T is the cell operating temperature in (Kelvin) and $T \leq 100^\circ\text{C}$. P_{H_2} and P_{O_2} are the partial regulating pressures of the hydrogen and oxygen in (atm), respectively.

Since P_{H_2} and P_{O_2} vary with the load current values, they are expressed as follows:

$$P_{H_2} = 0.5 \times R_{H_a} \times P_{H_2O} \times \left[\left[\frac{1}{\frac{R_{H_a} \times P_{H_2O}}{P_a} \times \exp \left(\frac{1.635 I_{cell}}{AT^{1.334}} \right)} \right] - 1 \right] \tag{4}$$

While, calculating P_{O_2} is dependable of whether the oxidant is pure oxygen or natural air. Thus, Eqs. (5) and (6) are applied for pure oxygen and natural air, respectively [86].

$$P_{O_2} = R_{H_c} \times P_{H_2O} \times \left[\left[\frac{1}{\frac{R_{H_c} \times P_{H_2O}}{P_c} \times \exp \left(\frac{4.192 I_{cell}}{AT^{1.334}} \right)} \right] - 1 \right] \tag{5}$$

$$P_{O_2} = P_c - R_{H_c} \times P_{H_2O} - \frac{0.79}{0.21} \times P_{O_2} \times \exp \left[\frac{0.291 I_{cell}}{AT^{0.832}} \right] \tag{6}$$

where R_{H_a} and R_{H_c} are the relative humidity of the vapor at anode and cathode, respectively. P_{H_2O} is the saturation pressure of the water vapor in (atm). P_a and P_c the anode and cathode inlet pressure in (atm), respectively. I_{cell} and A are the cell current in (A) and the membrane effective area in (cm²), respectively.

As P_{H_2O} depends on the cell operating temperature, it’s given by:

$$\log_{10}(P_{H_2O}) = 2.95 \times 10^{-2}(T - 273.15) - 9.18 \times 10^{-5}(T - 273.15)^2 + 1.44 \times 10^{-7}(T - 273.15)^3 - 2.18 \tag{7}$$

Table 3 Various recent examples of PEMFC models

Ref	Year	Scale	Technique	State	Dim	Covered phenomena	Objective
[58]	2017	System	Empirical	Steady-dynamic	Zero	Electrochemistry-thermodynamics	A proposed model that simulates the hydrogen consumption and the coolant fluid out temperature of the PEMFC system based on the load demand, inlet temperature of the coolant fluid and the coolant fluid flow
[59]	2017	Cell	Semi-empirical	Dynamic	3-D	Thermodynamics-electrochemistry-mass and heat transport-fluid dynamics	A developed model that investigates the water elimination processes in a PEMFC while purging the gas before its shutdown
[60]	2017	Cell	Mechanistic	Steady	3-D	Thermodynamics-electrochemistry-mass and heat transport-fluid dynamics	A proposed model that identifies the impact of the cooling flow field on a PEMFC performance
[61]	2018	System	Mechanistic	Steady-dynamic	Zero	Thermodynamics-heat transport-fluid dynamics	A model that has the capability of determining outlet temperature of the cooling fluid and the hydrogen flow rate of the PEMFC depending on the input temperature, the cooling fluid flow rate, and the electrical load
[62]	2018	System	Semi-empirical	dynamic	Zero	Electrochemistry-mass and heat transport	Developing of an energy management system and utilizing SCADA system to implement three progressing control techniques at PEMFCs
[63]	2018	Cell	Semi-empirical	Steady	3-D	Fluid dynamics-mass transport-electrochemistry	A model that identifies the performance of the PEMFC, in terms of I-V polarization curves and maximum power density, under various operating conditions
[64]	2018	Cell	Semi-empirical	Steady	3-D	Electrochemistry-fluid dynamics-mass transport	Investigating the transport characteristics and the performance of PEMFCs considering the impacts of agglomerate parameters
[65]	2018	Cell	Semi-empirical	Steady	2-D	Electrochemistry-species transport-ionic transport-heat transport-electronic transport	Developing a model that compromise between along the channel and rib-channel models to optimize the PEMFC bipolar plates rib-channel patterns based on the current collection and oxygen supply competition
[66]	2018	Cell	Semi-empirical	Steady-dynamic	Zero	Electrochemistry-thermodynamics-fluid dynamics	Developing a model that foresees pressure, temperature, current density, and the distribution of double-phase water flow for the PEMFC
[67]	2018	Cell	Semi-empirical	Dynamic	3-D	Mass and heat transport-electrochemistry-thermodynamics	A novel model capable of precisely generating the polarization curves of PEMFCs when supplied by contaminated hydrogen (CO and CO ₂)
[68]	2018	Stack	Semi-empirical	Dynamic	Zero	Electrochemistry-thermodynamics	A proposed model to obtain not only the FC stack output voltage but also, its subcomponents such as no-load, activation and concentration voltage drops
[69]	2018	Cell	Semi-empirical	Steady	3-D	Thermodynamics-electrochemistry-heat transport	An electric circuit-based model to obtain the temperature and voltage distribution throughout the PEMFC
[70]	2018	System	Semi-empirical	Steady	3-D	Thermodynamics-electrochemistry-heat transport	A developed model to simulate a hybrid system comprises the FC stack and thermoelectric device
[71]	2019	Cell	Semi-empirical	Steady	1-D	Heat transfer-mass transport-electrochemistry-thermodynamics	A developed model which can accurately foresee the FC performance under dry operating circumstances
[72]	2019	System	Semi-empirical	Dynamic	2-D	Heat transfer-mass transport-electrochemistry-thermodynamics	A developed comprehensive model comprising FC stack, membrane humidifier, hydrogen pump, radiator, and air compressor

Table 3 (continued)

Ref	Year	System	Technique	State	Dim	Covered phenomena	Objective
[73]	2019	System	Semi-empirical	Dynamic	Zero	Electrochemistry-thermodynamics-heat transfer	A developed sliding mode control scheme based on reduced-order nonlinear observer is utilized in an integrated PEMFC system
[74]	2019	Cell	Empirical	Steady	Zero	Electrochemistry-mass transport	Implementing an artificial neural network method for optimizing the PEMFC impedance model resulting in analyzing the PEMFC failure modes (flooding and drying)
[75]	2019	Stack	Empirical	Dynamic	Zero	Electrochemistry-mass transport	A derived model of dead-end PEMFC stack relying on artificial neural network method
[76]	2020	System	Semi-empirical	Dynamic	Zero	Electrochemistry-heat and mass transfer	A proposed model that forces the outlet temperature of the FC stack to follow the desired value under various load conditions
[77]	2020	System	Semi-empirical	Dynamic	Zero	Electrochemistry-heat and mass transfer-thermodynamics	A proposed model that investigates the liquid-to-liquid cooling technique for air independent FC system
[78]	2020	Stack	Semi-empirical	Steady	Zero	Electrochemistry-thermodynamics	A proposed optimization technique that defines the unknown parameters of Mann' model for the investigation of the PEMFC polarization features
[79]	2021	Stack	Semi-empirical	Steady-dynamic	Zero	Electrochemistry-thermodynamics	An alternative model that investigates I-V polarization curve and hydrogen consumption of PEMFCs stack under various operating conditions
[80]	2021	Stack	Semi-empirical	Dynamic	Zero	Electrochemistry-thermodynamics	An optimized model for predicting the PEMFCs stack behavior and identifying its unknown parameters that affect the stack efficiency
[81]	2021	Cell	Semi-empirical	Dynamic	Zero	Electrochemistry-thermodynamics	A developed model that can investigate the dynamic response of an air breathing PEMFC under load variations
[82]	2021	Stack	Semi-empirical	Dynamic	Zero	Electrochemistry-thermodynamics	A developed voltage model based on the system identification approach
[83]	2021	Cell	Semi-empirical	Steady	3-D	Electrochemistry-heat and mass transfer-thermodynamics	A proposed model that identifies impacts of gas diffusion layer and catalyst layer porosity on the PEMFC performance
[84]	2021	Cell	Semi-empirical	Dynamic	3-D	Electrochemistry-thermodynamics	A proposed model that investigates how the gas purging with various purge intervals affects the performance of the PEMFC

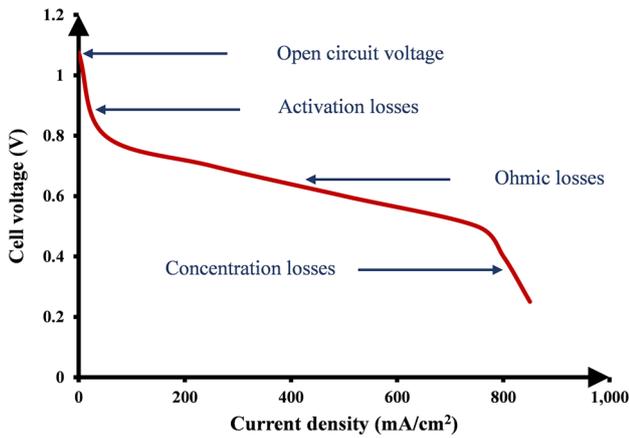


Fig. 2 A typical I–V curve of the PEMFC

To express the reactions slowness when starting to load the cell, the activation losses V_{act} is given by:

$$V_{act} = -[\varphi_1 + \varphi_2 T + \varphi_3 T \ln(C_{O_2}) + \varphi_4 T \ln(I_{cell})] \quad (8)$$

where $\varphi_j (j = 1 \dots 4)$ are defined as the semi-empirical coefficients in $(V, VK^{-1}, VK^{-1}, VK^{-1})$ and C_{O_2} represents the concentration of the oxygen at the catalytic layer of the cathode in (mol/cm^3) which is expressed by:

$$C_{O_2} = \frac{P_{O_2}}{5.08 \times 10^6} \times \exp\left(\frac{498}{T}\right) \quad (9)$$

Also, the concentration of the hydrogen at the catalytic layer of the anode C_{H_2} in (mol/cm^3) is described by [87]:

$$C_{H_2} = \frac{P_{H_2}}{10.9 \times 10^5} \times \exp\left(\frac{-77}{T}\right) \quad (10)$$

Moreover, the ohmic voltage drop V_{Ω} which exhibits a linear relation in the polarization curve is given by:

$$V_{\Omega} = I_{cell}(R_M + R_C) \quad (11)$$

where R_C in (Ω) represents the resistance shown by the electrons through the connections to the external circuit. R_M in (Ω) indicates the resistance shown by the protons, through the membrane active area A in (cm^2) and it's described by:

$$R_M = \rho_M \left(\frac{l}{A}\right) \quad (12)$$

where the membrane thickness is symbolized by l in (cm) . The specific resistivity of the membrane is symbolized by ρ_M in (Ωcm) and it's given by:

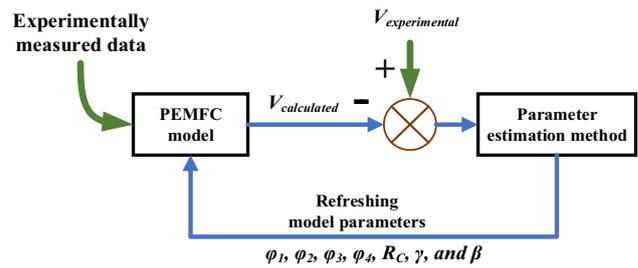


Fig. 3 The sequence of PEMFC modelling

$$\rho_M = \frac{181.6 \left[1 + 0.03 \left(\frac{I_{cell}}{A}\right) + 0.062 \left(\frac{T}{303}\right)^2 \left(\frac{I_{cell}}{A}\right)^{2.5} \right]}{\left[\gamma - 0.634 - 3 \left(\frac{I_{cell}}{A}\right) \right] \exp\left(4.18 \left(\frac{T-303}{T}\right)\right)} \quad (13)$$

where γ is a unitless parametric coefficient that indicates the water content in the membrane.

Lastly, the phenomenon, that affects the I–V curve when heavy loading the FC, is the concentration over-potential V_{con} or mass transport losses and it's determined by:

$$V_{con} = -\beta \ln\left(\frac{J_{Max} - J}{J_{Max}}\right) \quad (14)$$

where β is a parametric coefficient in (V) , J_{Max} and J are the maximum cell current density and the actual operating current density in (Acm^{-2}) , respectively.

4 Model Identification and Assessment Criteria

It's self-explanatory from the aforesaid formulas that for obtaining a fully defined electrochemical-based model, at least seven parameters ($\varphi_1, \varphi_2, \varphi_3, \varphi_4, R_C, \gamma$, and β) are assigned. Nonetheless, the indispensability, difficulty, and complexity of the model identification process stem from the significant dependence of the model parameters on the operating conditions. As expected, the quality of the polarization curves and the heavy nonlinear characteristics of such model are significantly affected. In addition, the unknown parameters are strongly coupled and aren't illustrated in the manufacturer's specifications sheet [57]. Thus, to simply, accurately and with low time-effort define the unknown parameters, it is studied as an optimization problem and solved by numerous optimization techniques. Amongst the various optimization methods, AI-based approaches are widely utilized to obtain the anonymous parameters of the PEMFC model [43]. Summarily, the procedures of modelling of the PEMFCs stacks, depending on the extracted

information from the datasheet and the experiment-based data, are depicted in Fig. 3.

Not only the identification method that affects the accuracy of the estimated parameters but also the assessment criteria play a vital role to precisely determine the unknown parameters and fit the calculated I–V curve to the experimental one. Proper picking of the objective function (OF) simplifies the parameter determination process and differentiates among the various model identification methods quantitatively and qualitatively in terms of the acceptable range of results. Thus, a summary of the most utilized OFs in the parameter estimation of PEMFC, is collected in Table 4.

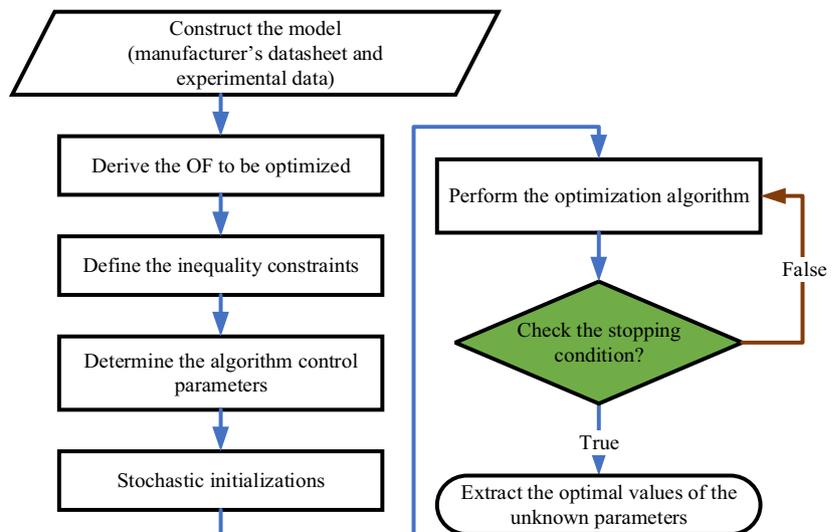
5 MHAs for PEMFC’s model parameters identification

Amongst the various AI-based optimization techniques, MHAs have proven their accuracy and higher computation efficiency when compared with the other conventional optimization techniques [7]. Therefore, MHAs have been adopted to get the optimum solutions for several engineering problems such as power systems problems, as presented in [95–104]. Besides, depending on the no free-lunch theory [105], many researchers have utilized various algorithms for accurate and effective investigation of the polarization characteristics of the PEMFC, as reported in [5, 7, 16, 57]. It’s worth saying that this section highlights the most recent works regarding presenting a new MHA to identify the undefined parameters of the PEMFC

Table 4 Summery of the popular-used OFs

Objective function	Ref	Mathematical formula	Characteristics	
			Absolute	Quadratic
Sum of quadratic deviation (SQD)	[88]	$SQD = \sum_{j=1}^K (V_{meas,j} - V_{calc,j})^2$		✓
Mean quadratic deviation (MQD)	[52]	$MQD = \frac{1}{K} \sum_{j=1}^K (V_{meas,j} - V_{calc,j})^2$		✓
Root mean quadratic deviation (RMQD)	[89]	$RMQD = \sqrt{\frac{1}{K} \sum_{j=1}^K (V_{meas,j} - V_{calc,j})^2}$		✓
Mean absolute deviation (MAD)	[90, 91]	$MAD = \frac{1}{K} \sum_{j=1}^K V_{meas,j} - V_{calc,j} $	✓	
Mean absolute percentage deviation (MAPD)	[92]	$MAPD = \frac{1}{K} \sum_{j=1}^K \left \frac{V_{meas,j} - V_{calc,j}}{V_{meas,j}} \right $	✓	
Normalized root mean quadratic deviation (NRMQD)	[93]	$NRMQD = \frac{\sqrt{\frac{1}{K} \sum_{j=1}^K (V_{meas,j} - V_{calc,j})^2}}{V_{meas}}$		✓
Mean relative deviation (MRD%)	[94]	$MRD = 100 \times \frac{1}{K} \sum_{j=1}^K \left \frac{V_{meas,j} - V_{calc,j}}{V_{meas,j}} \right $	✓	

Fig. 4 The main steps for implementing MHAs for PEMFC’s parameter estimation



based on the semi-empirical model given in [21, 22]. One can track the procedures depicted in Fig. 4 to implement the MHAs for obtaining the unknown parameters of the PEMFC model. MHAs can be classified into four categories: swarm-based, nature-based, physics-based, and evolutionary-based, respectively. The reader can get a brief knowledge about the technical specifications of the most widely employed PEMFCs types in the commercial market when perusing Table 5. Also, the lower and upper limits of the PEMFC unknown parameters, popularly used in the state-of-art, are encapsulated in Table 6 [57].

5.1 Swarm-Based MHAs

5.1.1 Grasshopper Optimizer (GO)

The GO imitates the behaviors of grasshopper swarms when searching for food. Substantially, to mathematically derive the GO equations, the intermediate forces among the agents are classified as attraction and repulsion forces [106]. Furthermore, GO merits can be summarized as follows: (i) avoiding falling into local minima as GO is strongly capable of balancing between exploration and exploitation, (ii)

Table 5 Summary of technical specifications of various commercial PEMFCs

PEMFCs' type	Manufacturer's datasheet							
	N_C , cells	A , cm ²	l , μm	J_{Max} , A cm ⁻²	T , Kelvin	P_{H_2} , atm	P_{O_2} , atm	
Ballard Mark V [106]	35	50.6	178	1.5	343	1	1	
SR-12 500 W [107]	48	62.5	25	0.672	323	1.47628	0.2090	
250 W stack [106]	24	27	178	0.68	343	1	1	
BCS 500 W [107]	32	64	178	0.469	333	1	0.2095	
Temasek 1 kW [107]	20	150	51	1.5	323	0.5	0.5	
Ballard V 5 kW [107]	35	232	178	1.5	343	1	1	
NedStack 6 kW [108]	65	240	178	0.9375	343	0.5–5 (bar)	0.5–5 (bar)	
Wns 250 W [109]	24	27	127	0.86	343.15–353.15	1–3 (bar)	1–5 (bar)	
Horizon H-12 [110]	13	8.1	25	0.2469	302.15	0.4935	1	
Horizon 500 W [111]	36	52	25	0.446	278.15–303.15	0.55	1	

Table 6 The minimum and maximum boundaries of the PEMFC's unknown parameters

U.P	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	R_C , m Ω	γ	β
L.L	-1.2000	1.0000	3.6000	-26.0000	0.1000	10.0000	0.0135
U.L	-0.8000	5.0000	9.8000	-9.5400	0.8000	24.0000	0.5000

where, U.P, L.L and U.L denote the unknown parameter, the lower and upper limits, respectively

Table 7 PEMFC parameter estimation using swarm-based MHAs

Row	MHA	PEMFC Type	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	SQD
1	GO [106]	SR-12 500 W	-1.1997	4.2695	9.8000	-10.1371	0.4638	23.0000	0.1486	0.0478
2	GWO [107]	BCS 500 W	-1.0180	2.3151	5.2400	-12.8150	0.75036	18.8547	0.0136	7.1889
3	SSA [108]	NedStack 6 kW	-0.9719	3.3487	7.9111	-9.5435	0.10000	13.0000	0.0534	2.1807
				(calculated)						
4	SSO [117]	Temasek 1 kW	-1.0299	2.4105	4.0000	-9.5400	0.1087	10.0005	0.1274	1.6481
5	CS-EO [119]	BCS 500 W	-1.1365	2.9254	3.7688	-13.9490	0.8000	18.5446	0.0136	5.5604
6	WO [110]	Horizon H-12	-1.1870	2.6697	3.6000	-9.5400	0.8000	13.8240	0.1598	0.1160
7	BO [122]	SR-12 500 W	-1.0973	3.8093	9.8000	-9.5400	0.6723	23.0000	0.1753	1.0566
8	CHHO [86]	Temasek 1 kW	-1.0944	4.4282	8.7656	-21.4650	0.1891	18.6392	0.1016	0.8023
9	MRFO [78]	Horizon H-12	-1.0630	2.3641	4.3272	-9.5400	0.2853	19.8150	0.1829	0.0966
10	MBBO [130]	NedStack 6 kW	-1.0300	3.5300	8.2400	-9.4800	0.1640	15.1100	0.0100	2.1200
11	BWO [132]	Ballard Mark V	-1.1933	1.0000	3.8000	-16.000	0.3200	14.3950	0.2729	1.4×10^{-5}
12	ISSOA [134]	Horizon H-12	-1.1300	2.4400	3.5700	-9.5400	0.7140	18.7900	18.1700	0.0970
13	JSO [136]	BCS 500 W	-0.9689	2.6930	4.6700	-19.0000	0.1000	20.8389	0.0161	0.0117
14	PFO [138]	Horizon H-12	-1.1113	2.0573	3.6000	-9.5400	0.1058	22.9999	0.1868	0.0965

fast convergence and (iii) simple controlling variables [106, 112]. Thus, it has been utilized in the parameter identification of PEMFC, while promising results are encapsulated in Table 7 in the second row [112].

5.1.2 Grey Wolf Optimizer (GWO)

The GWO mimics the intelligent attitude of grey wolves when attacking their preys. As they live in groups, their tasks are assigned according to the swarm hierarchy where the wolves are divided into four kinds: alpha, Beta, delta, and omega. The hunting process passes through three stages, pursuing and chasing, encircling, and attacking which mathematically represent the exploration, OF evaluation and exploitation phases, respectively [107, 113]. Due to GWO advantages such as simple tuning process and lower computational time and burden, it has been employed in the parameter estimation of the PEMFC model, while the results are gathered in Table 7 in the third row [107].

5.1.3 Salp Swarm Algorithm (SSA)

The SSA mimics the salps collective attitude when searching for food in oceans, where the swarm members are combined to form chains. Mathematically, the salp chains are modeled by classifying the group individuals into leader and followers. Thus, the leader position during the searching process can be formulated as in (15) [108, 114].

$$X_i^j = \begin{cases} S_j + b_1 \cdot [(HL_j - LL_j) \cdot c_2 + LL_j], & b_3 \geq 0 \\ S_j - b_1 \cdot [(HL_j - LL_j) \cdot c_2 + LL_j], & b_3 < 0 \end{cases} \quad (15)$$

where X_i^j denotes the leader position, the food source position in the j th dimension is symbolized by S_j . HL_j and LL_j represent the higher and lower limits of the j th dimension, while b_1 , b_2 and b_3 are three random numbers, respectively. SSA has the capability of effectively enhancing the initial haphazard solutions and rapidly converging into the optimum ones. As a result, it has been adopted to estimate the undefined parameters of the PEMFC, as elucidated in Table 7 in the fourth row [108].

5.1.4 Shark Smell Optimizer (SSO)

The SSO imitates the hunting mechanism of the sharks when sensing the prey smell. Employing their strong sense of smelling the prey blood, the hunting process depends on three assumptions: (i) the shark velocity is much greater than the prey velocity. So, the prey is assumed stationary. (ii) The blood is uninterruptedly flowed out from the prey to the sea and the propagation of the prey smell particles isn't affected by the flow of the seawater. (iii) Only one prey (seeking environment) is existed in the search domain [115–117].

Accordingly, SSO exhibits the merits of high precision, low computational effort, and high convergence trend. Consequently, its results have outperformed the other conventional algorithms when utilized in the parameter estimation of the PEMFC model, as indicated in Table 7 in the fifth row [117].

5.1.5 Cuckoo Search Optimizer (CSO)

The CSO mimics the brood parasite attitude of cuckoos where the cuckoos put their eggs surreptitiously in the host birds' nests. Fraudfully, the cuckoos try to empty the nests of the host birds out of their own eggs, keeping only the cuckoos' eggs to enhance the hatching amount. The cuckoos implement a haphazard strategy to pick the host nest. Furthermore, the basic construction of CSO depends on three concepts, relying on which each cuckoo produces next solutions referring to (16) [118–120].

$$XP_i^{t+1} = XP_i^t + \lambda \oplus Levy(\epsilon) \quad (16)$$

where XP_i represents the i th egg position, $\lambda > 0$ indicates the step size, the element-wise multiplications are symbolized by \oplus and ϵ denotes the exponent of Lévy flight.

For the sake of effectively and robustly employ this technique in PEMFC parameter identification, a novel modified approach, called CS-EO, is developed in [119]. In CS-EO, CSO is merged with the explosion operator (EO), derived from fireworks algorithm (FWA). Consequently, the newly proposed hybrid algorithm can effectively improve the search capability and evade from being trapped into local minimum solutions. Eventually, the sixth row in Table 7 elucidates the obtained results from adopting CS-EO in identifying the PEMFC model unknown parameters [119].

5.1.6 Whale Optimizer (WO)

The WO is inspired by the smart attitude of humpback whales when hunting a swarm of small fishes at the ocean surface, which is called bubble net feeding. These whales start the hunting process by diving deeply and surrounding the prey by bubbles. Thereafter, the whales arise to the surface for trapping the small fishes. Consequently, the hunting process mainly includes three phases, encircling prey, making bubbles with various shapes, and looking for the prey. Mathematically, the whales update their positions based on (17)–(18). Upon ending the encircling phase, the whales will try to attack the victim through creating bubbles which mathematically refers to the local exploitation [110, 121].

$$Y(t + 1) = Y_v(t) - A \cdot B \quad (17)$$

$$B = |D \cdot Y_v(t) - Y(t)| \quad (18)$$

where $Y(t)$ is the position vector of the whales, t refers to the iteration counter, $Y_v(t)$ is the position vector of the target victim and A and D represents the coefficient vectors.

Due to the robustness, accurateness, and effectiveness of WO, it has been applied for the sake of estimating the unknown parameters of several commercial types of PEMFC, as indicated in Table 7 in the seventh row [110].

5.1.7 Bonobo Optimizer (BO)

The BO is inspired by the social attitudes and reproductive process of Bonobos. Essentially, the Bonobos mating process depends on the fission–fusion concept which describes the techniques used by Bonobos groups for looking for food and other. Moreover, the Bonobos lifestyle is classified into two stages. Firstly, the positive stage (PS) at which all living circumstances are available like food, proper mating, and protection. Secondly, the negative stage (NS) which refers to the lack of these circumstances [122]. Recently, the authors in [122] have utilized BO for the sake of proper identifying the unknown parameters of three commercial PEMFCs, due to its ability to converge to the global solution smoothly and rapidly, while the results are indicated in Table 7 in the eighth row.

5.1.8 Harris Hawk’s Optimizer (HHO)

The HHO mimics the hunting strategy of Harris hawks when chasing their preys (rabbits). Mathematically, like any population-based approaches, HHO is divided into two phases, exploration, and exploitation. In the exploration phase, Harris hawks employ two tactics to discover the prey where the first tactic supposes that the hawks’ position is near to the group members and the prey. On the other hand, the second one assumes that the hawks allocate on stochastic trees [123, 124]. Furthermore, an improved HHO using chaotic equations, called chaotic HHO (CHHO), is presented in [86] where the convergence trend is enhanced. As foreseen, CHHO has been employed for identifying the unknown parameters of several commercial types of PEMFCs, while the results are revealed in Table 7 in the ninth row.

5.1.9 Coyote Optimizer (CO)

Basically, the CO imitates the coyotes’ attitude not only while chasing preys but also the community framework of coyotes and the experiences interchange by the coyotes. Mathematically, the coyote’s population consists of N_p packs, each pack has N_c coyotes which is a static number and fixed for all packs. Moreover, each coyote represents a feasible solution for the optimization task and its social circumstance is the cost of the fitness function [125, 126]. CO exhibits advantageous features such as low computational effort, simple tuning variables, and fast convergence trend. Consequently, it has been applied for defining the unspecified parameters of the commercial 250 W PEMFCs stack, while the results are capsulated in Table 8 [127].

5.1.10 Manta Rays Foraging Optimizer (MRFO)

The MRFO is inspired from the manta ray’s mechanism when searching for food (plankton). Hence, the foraging mechanism is subdivided into three phases such as (i) chain foraging, (ii) cyclone foraging, and (iii) somersault foraging. In the chaining phase, the positions of manta rays are updated to the best position of plankton where the plankton exists with high concentration using the mathematical equations given in (19)–(20) [78, 128].

$$X_{i,d}(it + 1) = \begin{cases} F_{i,d}(it) + r \cdot (F_{b,d}(it) - F_{i,d}(it)) + w(F_{b,d}(it) - F_{i,d}(it)) & i = 1 \\ F_{i,d}(it) + r \cdot (F_{i-1,d}(it) - F_{i,d}(it)) + w(F_{b,d}(it) - F_{i,d}(it)) & i = 2, \dots, N_{pop} \end{cases} \quad (19)$$

$$w = 2r\sqrt{|\log(r)|} \quad (20)$$

where $F_{i,d}(it)$ denotes the location of the i th member at it th iteration in d th dimension. r is a randomly generated vector from 0 to 1, w represents a weight coefficient and $F_{b,d}(it)$ refers to the plankton best location (plankton with high concentration). N_{pop} denotes the population size.

It’s worth saying that MRFO requires lesser effort to fine-adjust its controlling parameters. therefore, the authors in [78] have applied it for extracting the unknown parameters of three commercial types of PEMFCs under various operating conditions, where the results are indicated in Table 7 in the tenth row.

Table 8 PEMFC parameter estimation using CO

PEMFC type	U.P	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	$l, \times 10^{-6}$	J_{Max}	A	SQD
250 W stack	C.P	−0.9401	3.0703	8.0935	−15.2860	0.6335	13.0048	0.0204	125.0002	0.8291	27.6150	0.4105

where, C.P stands for the computed parameters

5.1.11 Monarch Butterfly Optimizer (MBO)

The MBO mimics the migration mechanism of monarch butterflies which can be achieved by following the subsequent rules. Starting by dividing the whole population into individuals located only in Land 1 or Land 2. Ending by assuming that the movement to the next generation of the MB individuals, having the best fitness, is automatically performed and there is no operator can change them. Hence, this will prevent any deterioration for the MB population and maintain the effectiveness of the population while increasing the generations [129, 130].

However, a major drawback of MBO is that it sometimes gets trapped into local optimum which leads to premature convergence. As a result, a modified MBO (MMBO) has been utilized in [130] to solve this issue. In MMBO, two mechanisms have been integrated with the basic MBO where the first is the mutation operator and the second is the anti-cosine operator, While the procedures of MMBO are revealed in Fig. 5. Accordingly, MMBO has been utilized for tackling the parameter estimation problem of the PEMFCs, while the results are depicted in Table 7 in the eleventh row [130].

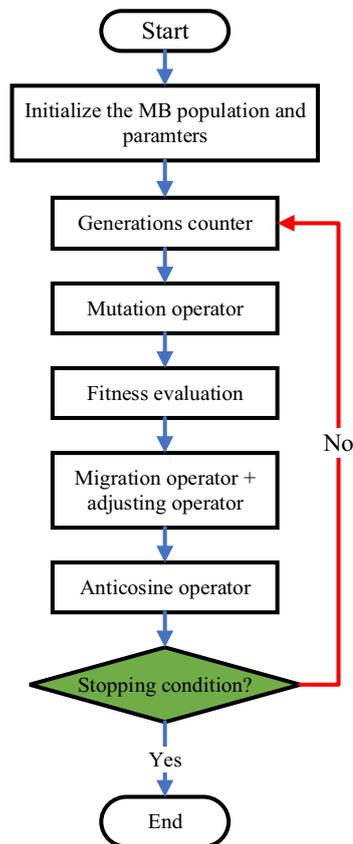


Fig. 5 MMBO flowchart

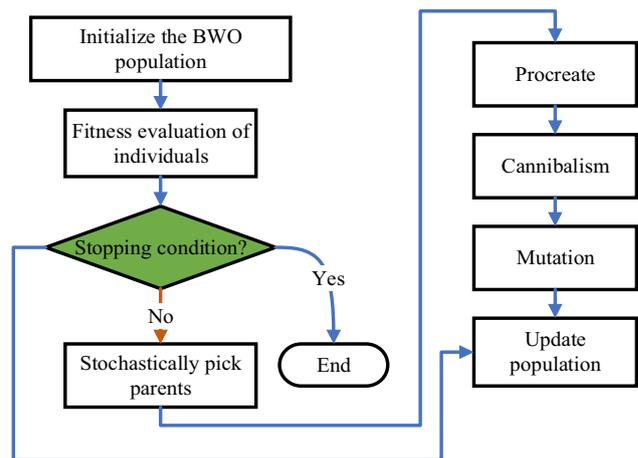


Fig. 6 BWO flowchart

5.1.12 Black Widow Optimizer (BWO)

The BWO imitates the distinguished mating attitude of black widow spiders. Fundamentally, this reproductive behavior is composed of an exclusive phase called cannibalism. Thanks to this phase, the individuals with unwanted fitness value are excluded from the circle, resulting in early convergence. While the main phases of BWO are revealed in Fig. 6 [131, 132].

Consequently, BWO has been applied for the parameter estimation of two commercial PEMFCs, while the results are depicted in Table 7 in the twelfth row [132].

5.1.13 Sparrow Search Optimization Algorithm (SSOA)

Fundamentally, the SSOA simulates the collective wisdom, countering the predators and foraging attitudes of sparrows. Specially, the sparrows are divided into two types of producers and scroungers where the producers seek for obtain their food source. On the other hand, the scroungers are fed by the producers [133, 134]. Despite the advantages of SSOA, such as accuracy, stability and robustness, the convergence speed may be slowed down due to haphazardness walk strategy. Thus, an improved version of SSOA, called improved SSOA (ISSOA), has been introduced in [134] to refine this problem. Basically, ISSOA combines the basic SSA with an adaptive learning factor. As a result, ISSOA has been utilized for extracting the unknown parameter of the PEMFCs, while the results are indicated in Table 7 in the thirteenth row [134].

5.1.14 Jellyfish Search Optimizer (JSO)

The JSO is motivated by the search mechanism and movement of jellyfish in the ocean. Specifically, JSO is composed of three concepts: (a) jellyfish track only one governing rule either the ocean current or inside-swarm movement (passive or active) and a time control technique. (b) Jellyfish are interested towards the locations which contains large amount of food. (c) The food quantity is assigned, and its corresponding cost fitness value is determined accordingly [135, 136]. Fewer control parameter and lesser computational efforts and random trials are such the JSO merits. Hence, the authors in [136] has applied JSO in the field of estimating the PEMFCs unknown parameters, while the outcomes are encapsulated in Table 7 in the fourteenth row.

5.1.15 Pathfinder Optimizer (PFO)

The PFO emulates the haphazard motion and performance of animal's groups following their leader according to their adjoining place, searching for food location or prey. Primarily, PFO is based on the animal competitors' movement which are gathered in groups. On the other side, the way to the target may be picked by the collaboration between the leader and some competitors who have sufficient information. Moreover, there are four parameters that has been tuned to refine the competitors' attitude in the exploration phase, which are (a) the oscillation frequency of the competitors, (b) the competitors' vibration, (c) the communication parameter, and (d) the attraction parameter [137, 138].

PFO has been utilized for extracting the unknown parameters of two commercial PEMFCs. Besides, it has been involved for investigating the steady state and dynamic operation of the PEMFCs, while the results are tabulated in Table 7 in the fifteenth row [138].

5.2 Nature-Based MHAs

5.2.1 Flower Pollination Optimizer (FPO)

Principally, FPO is inspired by the pollination behavior of flowers. Hence, the pollination process can be classified into two techniques, self-pollination (abiotic) and cross pollination (biotic). Herein, the self-pollination, in which pollens of the same flowers inseminate to emanate new flowers via wind as the pollinating medium. While, in the cross pollination, pollens of various flowers inseminate to emanate new flowers via bats, honeybees and birds as the pollinating medium [139].

FPO is characterized by enhancing the convergence tendency, simple variables tuning effort and effectively balancing the global exploration and the local exploitation. Consequently, the authors in [109], have utilized FPO for the parameters estimation purpose of the PEMFC, while the results are indicated in Table 9 in the second row.

5.2.2 Neural Network Optimizer (NNO)

The NNO emulates the artificial neural network (ANN) attitude, in which obtaining the incoming data and the desired data is established first and thereafter forecasting the relation between them. Referring to the ANN framework, it can be divided into two frames feed-forward and frequent NNs. Moreover, it depends on its framework whichever open-loop or closed-loop (feedback). Specifically, in NNO, the targeted solution at a certain iteration is regarded as the output data and the principal aim is to reduce the deviation between this targeted solution and the other forecasted solutions [140, 141].

Additionally, low tuning efforts of the NNO controlling variables and low computation burdens are such the NNO benefits. Hence, the authors in [141] have implemented the NNO to properly define the unknown parameters of the PEMFC, while the results are indicated in Table 9 in the third row.

Table 9 PEMFC parameter estimation using nature-based MHAs

Row	MHA	PEMFC Type	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	SQD
1	FPO [109]	Wns 250 W	-0.8775	2.500	6.4439	-12.5310	0.6369	12.0160	0.0198	0.2872
2	NNO [141]	NedStack 6KW	-0.8535	2.4316	3.7545	-9.5400	0.1000	13.0802	0.0136	2.1449
3	FFO [111]	NedStack 6KW	-1.0357	2.9502	3.7670	-9.5400	0.1622	15.0297	0.0136	2.1671
4	IAEO [144]	250 W stack	-0.8770	2.8000	6.9200	-11.0000	0.2730	21.5177	0.1500	0.3359
5	MPO [148]	BCS 500 W	-0.9864	2.6085	3.6000	-19.2893	0.1000	20.8167	0.0161	0.0116
6	SMO [150]	Ballard Mark V	-1.1942	1.0000	4.1234	-16.8070	0.2000	15.3311	0.2083	1.7729×10^{-5}

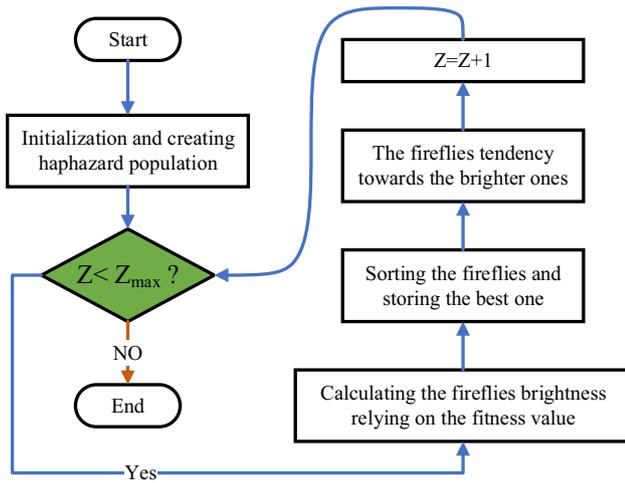


Fig. 7 FFO flowchart

5.2.3 Firefly Optimizer (FFO)

The FFO is inspired by the social attitude of fireflies when courting mates. Basically, FFO procedures relies on three fundamental assumptions, (i) all the fireflies are considered as hermaphrodite where all the agents in the population seek for the same target. (ii) the attraction possibility of the fireflies is proportional to the intensity of their flashlights. (iii) the brightness strength of a firefly is determined by the objective function [111, 142].

Moreover, FFO procedures are revealed in Fig. 7. In addition, as tabulated in Table 9 in the fourth row, FFO has

proven reasonable results in commercial test cases regarding the PEMFC parameter identification [111].

5.2.4 Artificial Ecosystem Optimizer (AEO)

The AEO is inspired by the energy flow in an ecological system on the earth. Specifically, AEO imitates three distinguished attitudes of the living creatures, production, consumption, and decomposition, as revealed in Fig. 8. Mathematically, the production target is to enhance the exploration and exploitation characteristics. Meanwhile, the consumption's endeavor is to improve the exploration capability. Finally, the decomposition's objective is to promote the exploitation ability [143, 144].

Moreover, a new modified AEO, called improved AEO (IAEO), is presented in [144], which overcomes the lack of accurate solution related to the basic AEO. Consequently, IAEO has been utilized in the parameter estimation of the PEMFCs. This is due to its ability to effectively fit the computed voltage datasets to the experimental ones, while the results are depicted in Table 7 in the fifth row [144].

5.2.5 Moth-Flame Optimizer (MFO)

Mainly, the MFO mimics the distinguished navigation techniques of moths in night where they can fly with the aid of the moonlight. Using transverse orientation technique, moths fly by keeping a certain angle with respect to the moon [145, 146]. Recently, a proposed algorithm, called without certainty MFO (WCMFO), has been presented in

Fig. 8 The distinct behaviors of the living creatures

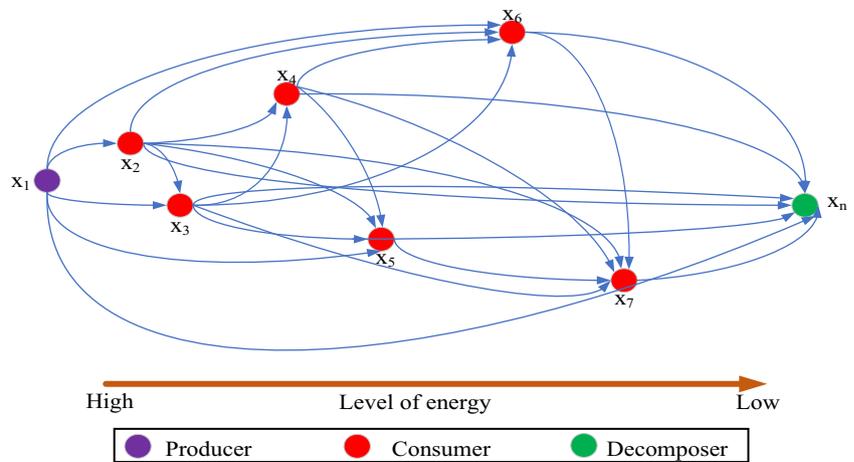


Table 10 PEMFC parameter estimation using WCMFO

PEMFC type	U.P	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	T	P_{H_2}	P_{O_2}	N_C
250 W stack 11 unknowns	C.P SQD=0	-1.1197	3.0186	6.4573	-10.0000	8.1676	24	0.0050	355	2.1610	5	24.9430
							RMQD=0					

[146] which integrates the uncertainty measurement with the conventional algorithm. Hence, the suggested algorithm has gained more robustness to disturbance with respect to the conventional one. Thus, WCFMO has been employed for extracting the unknown parameters of the PEMFCs with various numbers of unknowns and two OFs, while the results are depicted in Table 10 [146].

5.2.6 Marine Predator Optimizer (MPO)

The MPO is inspired from the foraging process implemented by the marine predators to catch their preys. Particularly, the predators follow the Levy mechanism in case of lack of prey. On the other hand, in case of plentiful prey, the predators follow Brownian movements' mechanism. According to the ecological impacts, the relative velocity of the prey v with respect to the predators can be varied relying on the Levy and Brownian mechanisms. Moreover, MPO has exhibited an enhanced global and local search besides, the fast convergence trend [147, 148]. Thus, MPO has been applied for defining the unknown parameters of several commercial PEMFCs, while the results are encapsulated in Table 9 in the sixth row [148].

5.2.7 Slime-Mould Optimizer (SMO)

The SMO is inspired by the natural oscillation state of slime mould. Basically, SMO employs adaptive weights to imitate the concept of generating positive and negative feedback of the spread wave of slime mould. Basically, these feedbacks depend on the bio-oscillator to establish the optimal path for linking food with perfect explorative capability and exploitative tendency [149, 150]. Recently, SMO has been utilized for identifying the unknown parameters of the PEMFCs, while the results are depicted in Table 9 in the seventh row [150].

5.3 Physics-Based MHAs

5.3.1 Multi-Verse Optimizer (MVO)

The MVO is extracted from the multi-verse theory which states that various universes are generated from numerous big-explosions. Each universe is related to each explosion. MVO construction relies on three cosmological concepts, white, black and worm holes. Mathematically, the exploration phase is represented by white and black holes, while the worm holes indicate the exploitation phase [151, 152].

MVO has shown advantageous features such as, simple implementation, less tuning parameters, and less computational effort. Thus, the authors in [152] have encouraged to employ it for identifying the unknown parameters of the PEMFC model, where the results are depicted in Table 11 in the second row.

5.3.2 Atom Search Optimizer (ASO)

Principally, the atoms are the preliminary part that form all the substances. The ASO is inspired by the atoms motion which are moving sustainably based on the classical mechanics. While moving, there are two types of forces that affect the atoms interactions with each other. The first type is the interaction forces deduced from Lennard–Jones potential. While the second one is the constraint forces generated from Bond-Length potential. Referring to Newton's second law, the atom acceleration a_i is a function of the atom mass m_i , the interaction IF_i and the constraint CF_i forces, as given in (21) [153, 154].

$$a_i = \frac{IF_i + CF_i}{m_i} \tag{21}$$

Accordingly, ASO is distinguished by its simple construction and smooth convergent rate. Hence, as expected, it has proven such robustness and accurateness in determining the unknown parameters of the PEMFC model, as illustrated in [154] and revealed in Table 11 in the third row.

Table 11 PEMFC parameter estimation using physics-based MHAs

Row	MHA	PEMFC type	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	SQD
1	MVO [152]	N.M	-0.9182	3.1299	8.7031	-18.0253	0.4223	15.1921	0.0180	3.5846
2	ASO [154]	250 W stack	-1.1132	3.6	10.0000	-20.0000	0.0001	22.1763	0.0248	0.7346
3	VSDE [47]	SR-12 500 W	-0.8576	3.0100	7.7800	-9.5400	0.1339	23.0000	0.1516	1.2660
4	IFSO [157]	Ballard V 5 kW	-1.1200	3.5700	8.0100	-15.9400	0.1000	22.0000	0.0150	0.7840
5	EO [159]	NedStack 6KW	-0.8720	Computed	9.8000	-9.5400	Assumed	13.0000	-	1.9547
6	GBO [161]	SR-12 500 W	-0.8549	2.7339	6.7420	-10.6347	0.2726	21.5149	0.1500	0.0001

5.3.3 Vortex Search Optimizer (VSO)

The VSO simulates the vortex pattern generated by cephalic flow of stirred fluids. This pattern is considered as a set of overlapped circles coordinated in a two-dimensional searching area. Like other metaheuristic approaches, Elementally, VSO is divided into two phases, generation, and replacement. In the generation phase, the existing solution is utilized to produce a group of solutions, while the existing solution is updated in the replacement phase [47, 155]. Furthermore, to improve the computational efficiency and the capability to evade from the local minima, a novel approach called vortex search differential evolution (VSDE) is illustrated in [47]. Thus, VSDE has exhibited robustness and effectiveness in investigating the PEMFC electrical characteristics, while the consequences are arranged in Table 11 in the fourth row.

5.3.4 Fluid Search Optimizer (FSO)

Principally, the FSO simulates the Bernoulli’s law to evaluate the fluid speed relying on the fluid pressure. Where, improving the fluid speed, diminishes the fluid pressure and the potential energy. Herein, the fluid pressure is considered as the fitness function value where improving the fluid pressure, reduces its velocity [156, 157]. Despite all the afore-stated procedures, FSO has an obvious drawback which is the premature convergence. Hence, an improved FSO (IFSO) is proposed in [157] to tackle this problem. Particularly, IFSO is composed of two enhancement techniques, that have been integrated with the basic FSO, which are quasi-oppositional based learning and chaotic concept. IFSO has been applied for tackling the parameter estimation problem of the PEMFCs, while the results are indicated in Table 11 in the fifth row [157].

5.3.5 Equilibrium Optimizer (EO)

The EO emulates the control technique of the balance between mass and volume utilized to evaluate dynamic and equilibrium phases. Particularly, in EO, the search agent is represented by each particle with its concentration. Where, the search agents stochastically update their concentration with respected to the best results, called equilibrium

candidates. Furthermore, the mass balance is mathematically described in (22) [158, 159].

$$V \frac{dC_{in}}{dt} = F_r(C_e - C_{in}) + G_{in} \tag{22}$$

where V refers to the control volume, $V \frac{dC_{in}}{dt}$ represents the mass change rate and F_r denotes the flow rate. C_e is the equilibrium phase concentration, C_{in} denotes the inside concentration and G_{in} symbolizes the inside mass generation rate.

Due to the effectiveness, robustness, and fast convergence trend, EO has been employed for extracting the unknown parameters of various commercial PEMFCs, while the results are tabulated in Table 11 in the sixth row [159].

5.3.6 Gradient-Based Optimizer (GBO)

Mainly, the GBO is inspired by the gradient-based Newton’s concept. Especially, two worthy operators are utilized in GBO, called gradient search approach (GSA) and local escaping coefficient (LEC), respectively. Besides, a group of vectors to explore the search space. Moreover, the exploration features and the convergence trend can be enhanced by implementing the GSA. On the other hand, the LEC is utilized to make GBO evade the local optima problem [160, 161]. Since, GBO has a smooth transition between exploration and exploitation phases and fast convergence features, it has been employed for tackling the parameter estimation issue of the PEMFCs. Hence, the results are revealed in Table 11 in the seventh row [161].

5.4 Evolutionary-Based MHAs

5.4.1 Satin bowerbird Optimizer (SBO)

The SBO is inspired by the satin bowerbirds’ behavior when constructing their own bowers in such a manner to attract satin females during reproduction season. Consequently, various elements like sparkling materials, branches, flowers, and fruits are utilized while building bowers to entice satin females [162, 163]. Owing to the advantageous features of SBO such as algorithm stability and fast convergence trend, it has been employed in [164] to extract the accurate values of the PEMFC unknown parameters, as encapsulated in Table 12 in the second row. Moreover, SBO has shown

Table 12 PEMFC parameter estimation using evolutionary-based MHAs

MHA	PEMFC Type	φ_1	$\varphi_2 \times 10^{-3}$	$\varphi_3 \times 10^{-5}$	$\varphi_4 \times 10^{-5}$	$R_C \times 10^{-3}$	γ	β	SQD
SBO [164]	Ballard V 5 kW	-1.1828	3.7080	9.3600	-11.9250	0.7877	11.7603	0.0137	0.0021
SFLO [111]	Horizon 500 W	-0.8532	2.5220	7.8437	-16.3000	0.7999	13.0000	0.0489	0.0156

Table 13 Comprehensive summary of the MHAs used in PEMFC parameter estimation

Category	Algorithm	Year	State		N_{UP}	OF	Algorithm's settings		N_{IR}	Polarization curves		Various operating conditions		Statistical performance tests		Test cases	N_{Meas}		
			S	D			N_{pop}	Max_{iter}		others	I-V	I-P	Varied P	Varied T	Parametric			Non-parametric	
Swarm	GO [106]	2017	✓	✓	7	SQD	60	100	-	100	✓	✓	✓	✓	✓	Ballard Mark V	13		
	GWO [107]	2017	✓	-	7	SQD	20	500	-	100	✓	-	✓	✓	✓	SR-12 500 W	20		
																		250 W stack	15
																		250 W stack	15
	SSA [108]	2017	✓	-	6	SQD	50	100	-	100	✓	-	✓	-	-	250 W stack	15		
																		SR-12 500 W	18
																		BCS 500 W	7
	SSO [117]	2019	✓	-	7	SQD	NM	500	-	100	✓	-	✓	✓	✓	Ballard V 5 kW	15		
																		SR-12 500 W	15
																		BCS 500 W	7
	CS-EO [119]	2019	✓	-	7	SQD	50	1000	✓	50	✓	-	✓	-	-	Temasek 1 kW	18		
																		N.M	15
																		SR-12 500 W	36
	WO [110]	2019	✓	-	7	SQD	50	200	-	100	✓	-	✓	-	-	Ballard Mark V	14		
																		BCS 500 W	7
																		Ballard Mark V	13
	BO [122]	2020	✓	-	7	SQD	30	200	-	100	✓	✓	✓	✓	-	SR-12 500 W	20		
																		250 W stack	15
Horizon H-12																		19	
															250 W stack	15			
															BCS 500 W	18			
															SR-12 500 W	18			

Table 13 (continued)

Category	Algorithm	Year	State		N_{UP}	OF	Algorithm's settings			N_{IR}	Polarization curves		Various operating conditions		Statistical performance tests		Test cases	N_{Meas}
			S	D			N_{pop}	Max_{iter}	others		I-V	I-P	Varied P_{H_2}/P_{O_2}	Varied T	Parametric	Non-parametric		
	CHHO [86]	2020	✓	-	7	SQD	30	500	-	50	✓	✓	✓	✓	✓	✓	250 W stack	15
																	BCS 500 W	18
	CO [127]	2020	✓	-	7	SQD	100	1000	-	100	✓	✓	✓	✓	✓	✓	SR-12 500 W	18
					10												Temasek 1 kW	17
	MRFO [78]	2020	✓	-	7	SQD	35	200	✓	100	✓	-	✓	✓	✓	✓	250 W stack	15
																	Ballard V 5 kW	13
																	NedStack 6KW	30
	MMBO [130]	2020	✓	-	7	SQD	120	N.M	✓	30	✓	-	✓	✓	✓	✓	Horizon H-12	18
																	250 W stack	15
	BWO [132]	2021	✓	-	7	SQD	50	1000	-	30	✓	✓	-	-	✓	✓	NedStack 6KW	23
																	Ballard Mark V	13
	ISSOA [134]	2021	✓	-	7	SQD	100	200	-	40	✓	-	✓	✓	✓	✓	SR-12 500 W	18
																	Ballard Mark V	12
																	Horizon H-12	15
	JSO [136]	2021	✓	-	7	SQD	30	300	✓	100	✓	✓	✓	✓	✓	✓	NedStack 6KW	14
																	BCS 500 W	18
																	250 W stack	15
	PFO [138]	2021	✓	✓	7	SQD	30	200	-	50	✓	-	✓	-	-	-	NedStack 6KW	29
																	Ballard Mark V	13
																	Horizon H-12	20

Table 13 (continued)

Category	Algorithm	Year	State		N_{UP}	OF	Algorithm's settings			N_{IR}	Polarization curves		Various operating conditions		Statistical performance tests		Test cases	N_{Meas}
			S	D			N_{pop}	Max_{iter}	others		I-V	I-P	Varied P_{H_2}/P_{O_2}	Varied T	Parametric	Non-parametric		
Physics	MVO [152]	2017	✓	-	7	SQD	50	2000	-	NM	✓	-	✓	✓	✓	-	N.M	15
	ASO [154]	2019	✓	-	7	SQD	25	3000	✓	100	✓	✓	✓	✓	✓	-	SR-12 500 W 250 W stack	20
	VSDE [47]	2019	✓	-	7	SQD	50	500	-	100	✓	✓	✓	✓	✓	-	250 W stack	15
	IFSO [157]	2020	✓	-	7	SQD	NM	NM	✓	30	✓	-	✓	✓	✓	-	NedStack 6KW BCS 500 W SR-12 500 W	29
	EO [159]	2021	✓	✓	4	SQD	10	50	-	100	✓	✓	✓	✓	✓	-	Ballard V 5 kW NedStack 6KW Horizon H-12	13
	GBO [161]	2021	✓	-	7	SQD	50	500	-	50	✓	✓	✓	✓	✓	-	SR-12 500 W 250 W stack	20
	SBO [164]	2019	✓	-	7	SQD	20	500	✓	100	✓	-	✓	✓	✓	-	NedStack 6KW 250 W stack Ballard V 5 kW	15
	SFLO [111]	2019	✓	-	7	SQD	50	100	✓	100	✓	-	✓	✓	✓	-	BCS 500 W SR-12 500 W Temasek 1 kW	7
				✓	-	7	SQD	50	100	✓	100	✓	-	✓	✓	-	NedStack 6KW BCS 500 W	18
				✓	-	7	SQD	50	100	✓	100	✓	-	✓	✓	-	Horizon 500 W	18

Table 13 (continued)

Category	Algorithm	Year	State		N_{UP}	OF	Algorithm's settings			N_{IR}	Polarization curves			Various operating conditions			Statistical performance tests		Test cases	N_{Meas}
			S	D			N_{pop}	Max_{iter}	others		I-V	I-P	Varied P_{H_2}/P_{O_2}	Varied T	Parametric	Non-parametric				
Others	ISO [166]	2019	✓	-	11	MQD	30	1000	✓	30	-	-	-	-	-	-	✓	-	M/S Ballard single cell	15
	JAYA [167]	2019	✓	-	7	SQD	30	5000	✓	30	✓	-	✓	-	-	✓	-	-	M/S BCS stack	18
	ICO [111]	2019	✓	-	7	SQD	50	100	✓	100	✓	-	✓	-	-	✓	-	-	M/S Avista stack	54
	PO [148]	2020	✓	-	7	SQD	NM	3000	-	30	✓	✓	-	-	-	✓	-	✓	N.M	15
																			NedStack 6KW	29
																			BCS 500 W	18
																			Horizon 500 W	15
																			BCS 500 W	18
																			SR-12 500 W	18
																			250 W stack	15

where, S and D stand for steady and dynamic states, respectively. N_{UP} refers to the number of unknowns, Max_{iter} denotes the number of maximum iterations, N_{IR} indicates the number of independent runs and N_{Meas} symbolizes the number of measured I-V datasets. Also, NM refers to “not mentioned”.

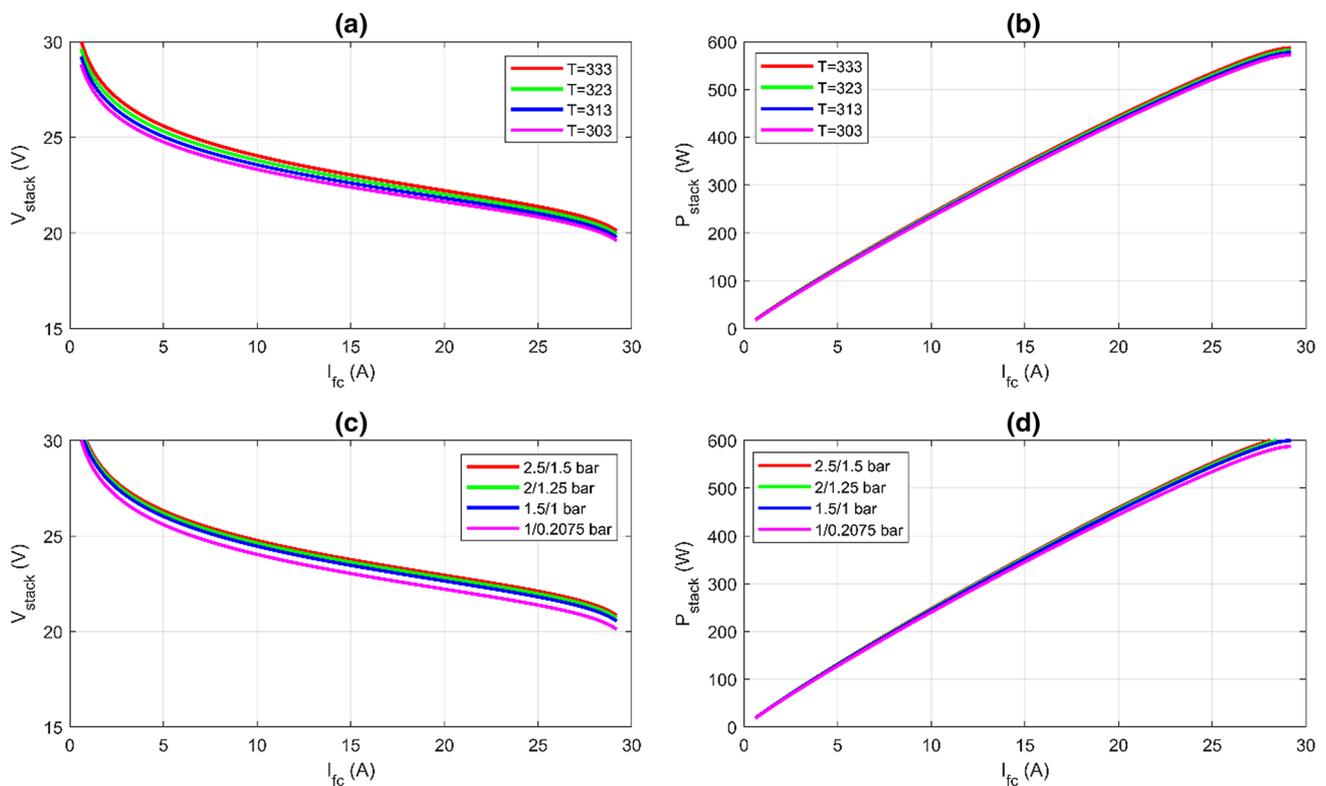


Fig. 9 Principal characteristics of BCS 500 W PEMFC stack under various operating conditions: **a** I–V at varied temperature, **b** I–P at varied temperature, **c** I–V at varied pressure, **d** I–P at varied pressure

a significant fitness between the experimental data and the computed ones.

5.4.2 Shuffled Frog-Leaping Optimizer (SFLO)

The SFLO is a memetic evolution-inspired metaheuristic approach which merges the local search mechanism of the particle swarm optimizer (PSO) into the concept of integrating the data obtained from various local searches to a global solution. Mainly, in SFLO, the number of frogs (solutions) represent the agents (population size), where the agents are split into some subgroups called memplexes. Every memplex represents a set of frogs carrying out a local search [111, 165].

Finally, SFLO performance in terms of robustness, accuracy and reliability has been proven via parametric statistical tests while identifying the unspecified parameters of many PEMFC types. One can track the results obtained by SFLO in Table 12 in the third row [111].

6 Concluding Discussions

For the sake of helping the reader for simply browsing the various earlier-mentioned MHAs, a comprehensive summary is offered in Table 13. Furthermore, it gives a

detailed comparison of thirty MHAs, besides four MHAs that don't fit to any of the previously-mentioned MHAs' categories. Essentially, the comparison is divided into two categories, MHA features and PEMFC characteristics. Especially, MHA features include year of application, controlling variables, number of independent runs and statistical performance tests. On the other hand, PEMFC characteristics are represented by model state, number of unknowns, OF, types of plotted curves, various operating conditions and lastly, number of measured I–V dataset points.

As concluded from the mathematical model of PEMFC, the polarization characteristics depends mainly on the operating temperatures and the partial pressures of the fuel and oxidant. Hence, in order to make the reader fully grasp such dependence, two well-known commercial types of PEMFC have been studied under various operating conditions. Particularly, BCS 500 W and SR-12 500 W PEMFCs have been evaluated in terms of I–V and I–P curves, as revealed in Figs. 9a–d and 10a–d; respectively [148]. Generally, as revealed in Figs. 9a–d and 10a–d, it's clear that the polarization characteristics and the output power of PEMFC are enhanced by increasing the operating temperature at constant pressure. Also, the polarization characteristics are promoted by rising the suppliers' partial

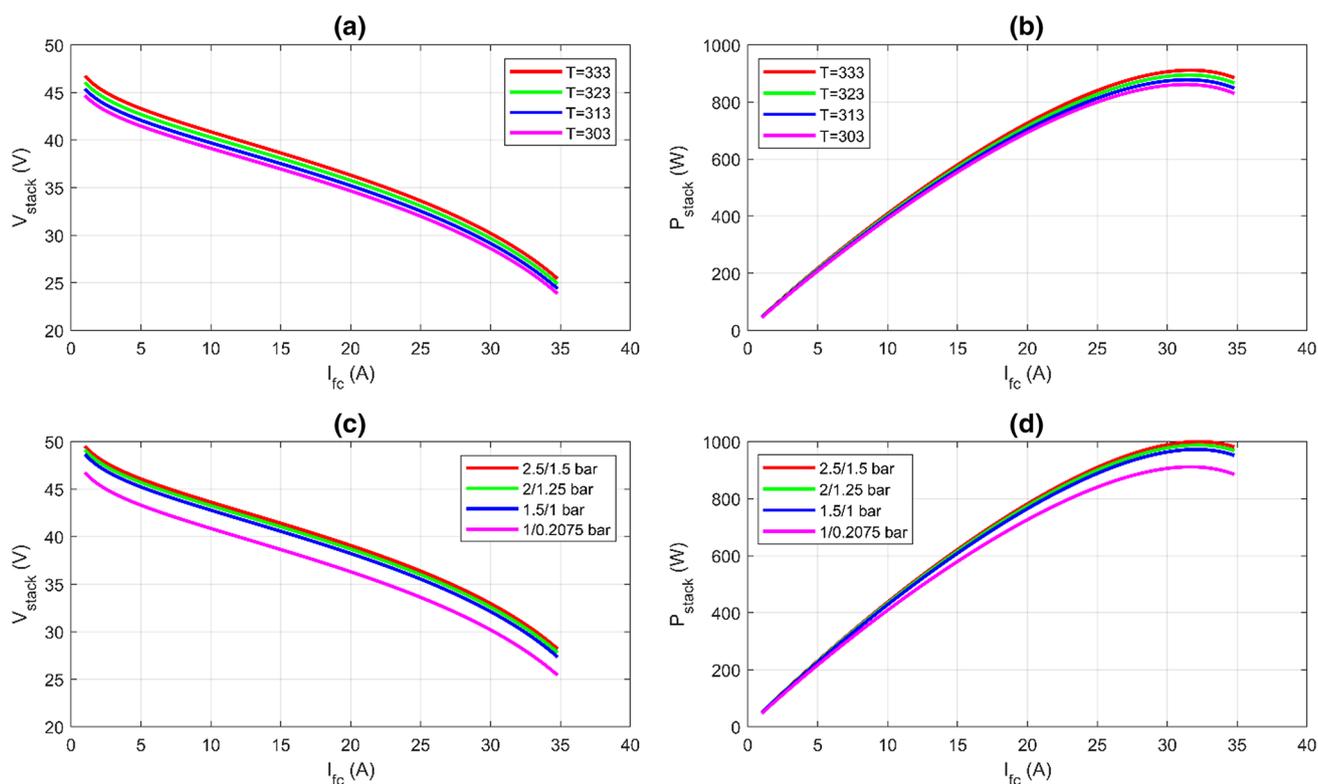


Fig. 10 Principal characteristics of SR-12 500 W PEMFC stack under various operating conditions: **a** I–V at varied temperature, **b** I–P at varied temperature, **c** I–V at varied pressure, **d** I–P at varied pressure

pressures at a constant temperature, as long the minimum and maximum limits haven't been violated.

7 Conclusions

In this paper, an inclusive survey of various models' categories of PEMFC has been carried out. In which, 27 models related to such categories have been gathered and summarized. Besides, a detailed PEMFC mathematical model, widely utilized in identifying the PEMFC electrical characteristics, has been totally represented. In addition, a summary of various commercial types of PEMFCs, in terms of their datasheet-extracted parameters, is encapsulated. Moreover, as the paper core work, 34 MHAs, which have been employed for extracting the unknown parameters of PEMFC, have been thoroughly discussed. Particularly, the discussion has covered their based-category, their inspiration, their features, and lastly their results in PEMFC parameter estimation. Consequently, a comprehensive comparison, among these MHAs, has been applied for clearly help the reader to simply investigate their characteristics. Also, the impact of varying the operating conditions on PEMFC output voltage and power have been demonstrated for sake of elaboration.

Lastly, as a future-wise point of view, further development of newly designed PEMFC models, together with novel optimization techniques are crucial for more properly and accurately evaluate the PEMFC performance. In addition, developing new objective functions play a vital role in effectively and precisely assess the performance of the optimization methods.

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Declarations

Institutional Review Board Statement The study did not involve humans or animals.

Informed consent The study did not involve humans.

Conflicts of interest The authors declare no conflict of interest.

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