Erratum to: Distributed active fault tolerant control design against actuator faults for multiple mobile robots

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In the published article there are two typesetting errors:

1) the paragraph below equation (27) at Page 375:

“The differentiation of (26) is given by” should be

“The differentiation of (27) is given by”; and

2) the paragraph below equation (36) at Page 375:

“Based on Geršgorin Circle Criterion [20], the eigenvalues of the Laplacian matrix in (38) are in the left-half plane. This implies that . . . the end of the proof.” should be

“Based on Geršgorin Circle Criterion [20], the eigenvalues of the Laplacian matrix in (36) are in the left-half plane. This implies that . . . the end of the proof.”

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