# Traveling waves for a diffusive SEIR epidemic model with standard incidences 

TIAN BaoChuan* \& YUAN Rong<br>School of Mathematical Sciences, Beijing Normal University, Beijing 100875, China<br>Email: baochuan.tian@mail.bnu.edu.cn, ryuan@bnu.edu.cn

Received August 4, 2016; accepted November 14, 2016; published online March 29, 2017


#### Abstract

This paper is devoted to the existence of the traveling waves of the equations describing a diffusive susceptible-exposed-infected-recovered (SEIR) model. The existence of traveling waves depends on the basic reproduction rate and the minimal wave speed. We obtain a more precise estimation of the minimal wave speed of the epidemic model, which is of great practical value in the control of serious epidemics. The approach in this paper is to use the Schauder fixed point theorem and the Laplace transform. We also give some numerical results on the minimal wave speed.


Keywords traveling waves, SEIR model, Schauder fixed point theorem
MSC(2010) 35K57, 92D30

Citation: Tian B C, Yuan R. Traveling waves for a diffusive SEIR epidemic model with standard incidences. Sci China Math, 2017, 60: 813-832, doi: 10.1007/s11425-016-0487-3

## 1 Introduction

In 1927, Kermack and McKendrick [8] proposed the Kermack-McKendrick equations

$$
\begin{aligned}
\frac{d}{d t} S(t) & =-\beta S(t) I(t) \\
\frac{d}{d t} I(t) & =\beta S(t) I(t)-\gamma I(t) \\
\frac{d}{d t} R(t) & =\gamma I(t)
\end{aligned}
$$

to describe the susceptible-infected-recovered (SIR) model, where $S$ denotes the number of the susceptible population, $I$ and $R$ denote the numbers of the infected and the recovered, respectively, $\beta$ is the transmission rate between the susceptible and the infected, and $\gamma$ is the removing rate of the infected. Let $S(0)=S_{0}$ be the number of the susceptible at the beginning of the epidemic. If the so-called reproductive number $R_{0}:=\beta / \gamma>1, I(t)$ increases first and then decreases to 0 , i.e., an epidemic takes place; whereas $R_{0}<1, I(t)$ decreases directly to 0 , indicating no epidemic happens. If the effect of spacial diffusion is taken into account, the Kermack-McKendrick equations with standard incidences are

$$
\begin{equation*}
\frac{\partial S}{\partial t}=d_{1} \frac{\partial^{2} S}{\partial x^{2}}-\frac{\beta S I}{S+I} \tag{1.1}
\end{equation*}
$$

[^0]\[

$$
\begin{align*}
& \frac{\partial I}{\partial t}=d_{2} \frac{\partial^{2} I}{\partial x^{2}}+\frac{\beta S I}{S+I}-\gamma I  \tag{1.2}\\
& \frac{\partial R}{\partial t}=d_{3} \frac{\partial^{2} R}{\partial x^{2}}+\gamma I \tag{1.3}
\end{align*}
$$
\]

where $d_{i}$ is the rate of diffusion of each sub-population, $i=1,2,3$ (see [7]). There is no $R$ in the first two equations of the above system according to the assumption that the recovered sub-population is removed from population. Brauer [3] gave the detailed epidemiological consideration of this assumption.

Much work has been done on the existence of traveling waves of System (1.1)-(1.3). By using the Schauder fixed point theorem, Wang et al. [14] proved the existence of traveling wave solution of this system. They proved that for $R_{0}:=\beta / \gamma>1$ and $c>c^{*}:=2 \sqrt{d_{2}(\beta-\gamma)}$, System (1.1)-(1.3) has a traveling wave solution $\left(S(x+c t), I(x+c t)\right.$ ) satisfying the boundary conditions $S( \pm \infty)=S_{ \pm \infty}$, $I( \pm \infty)=0$ and $S_{-\infty}>S_{+\infty}$. On the other hand, there is no non-negative non-trivial traveling wave solution if $0<c<c^{*}$ or $R_{0} \leqslant 1$. More work is done to get the existence of traveling waves in other cases, for example, the diffusion term is non-local, and the reaction term is non-local even with time delay (see $[4,9,10,13,15,16,18,19]$ ). We also notice some recent work on the traveling waves of free boundary problems (see $[5,6]$ ).
In this paper, we consider the corresponding SEIR model with standard incidences and use the assumption that the exposed are of no infectiousness and the recovered are removed from population. We focus on the following diffusive system:

$$
\begin{align*}
& \frac{\partial S}{\partial t}=d_{1} \frac{\partial^{2} S}{\partial x^{2}}-\frac{\beta S I}{S+I+E}  \tag{1.4}\\
& \frac{\partial E}{\partial t}=d_{2} \frac{\partial^{2} E}{\partial x^{2}}+\frac{\beta S I}{S+I+E}-\alpha E  \tag{1.5}\\
& \frac{\partial I}{\partial t}=d_{3} \frac{\partial^{2} I}{\partial x^{2}}+\alpha E-\gamma I  \tag{1.6}\\
& \frac{\partial R}{\partial t}=d_{4} \frac{\partial^{2} R}{\partial x^{2}}+\gamma I \tag{1.7}
\end{align*}
$$

where $E$ is the number of the exposed population and $\alpha$ is the rate of the exposed becoming infected. The number $1 / \alpha$ is the average period of the exposed becoming infected. However, it should be pointed out that this system is not the same as the SIR model (1.1)-(1.3) with a time delayed reaction term in that the exposed population has its own spacial diffusion rate.

Many diseases reduce the mobility of the infected individuals, while the exposed individuals are not influenced so much. The classical SIR model (1.1)-(1.3) may underestimate the spread speed of diseases in this case. If a disease is so serious that it disables the infected immediately, it can hardly spread without the participation of the exposed population. On the other hand, several diseases increase the mobility of the infected and Rabies is such an example. The neglect of the exposed population will underestimate or overestimate the spread speed of diseases.

Furthermore, in some scenarios of some serious infectious diseases, such as severe acute respiratory syndrome (SARS) and Ebola, the exposed individuals are traced and their mobility is limited. Thus the diffusion rate $d_{2}$ which describes the mobility of the exposed is reduced significantly and the propagation of these diseases is controlled.

The minimal wave speed $c^{*}$ is the minimum value of $c$ such that System (1.4)-(1.6) has the solution of the form $\left(\xi_{1}(x+c t), \xi_{2}(x+c t), \xi_{2}(x+c t)\right)$, where $\xi_{1}, \xi_{2}$ and $\xi_{3}$ are non-negative and non-trivial. Without ambiguity, we will use $S, E$ and $I$ to denote $\xi_{1}, \xi_{2}$ and $\xi_{3}$, respectively hereinafter. The minimal wave speed $c^{*}$ is important to describe the spread speed of diseases (see [2,5,6,12]). It is interesting to give the relation between these two speeds for our model, which is still an open problem. Our present work shows that the minimal traveling wave speed $c^{*}$ depends not only on $d_{3}$ but also on $d_{2}$. Furthermore, we prove that for $R_{0}:=\beta / \gamma>1$ and $c>c^{*}$, System (1.4)-(1.6) has a non-negative and non-trivial traveling wave solution $(S(x+c t), E(x+c t), I(x+c t))$ satisfying $S(\infty)=S_{\infty}, S(-\infty)=S_{-\infty}$ and $E( \pm \infty)=I( \pm \infty)=0$. In addition, there is no non-negative and non-trivial traveling wave solution if $0<c<c^{*}$ or $R_{0} \leqslant 1$.

The methods used in this paper are based on Wang et al. [14] and other early studies. First, we use $E$ presenting $I$ and reduce System (1.4)-(1.6) into a two-dimensional problem, which is inspired by Zhao and Wang's work [20] on a two-population epidemic model. We will apply the Schauder fixed point theorem to a non-monotone operator. The most challenging part is to build a suitable invariant convex set for this operator. We use two-side Laplace transform to give the proof of the non-existence of traveling wave solutions.

This paper is organized as follows. In Section 2, we present our main theorem on the existence and non-existence of traveling waves. In Section 3, we outline some properties of the differential and integral operators which will be used in the definition of a non-monotone operator. We also show that the traveling wave solution is the fixed point of this non-monotone operator. To apply the Schauder fixed point theorem, we give the definition of the invariant convex set of this operator. In Sections 4 and 5, we prove some properties of the traveling wave solution and show the existence and non-existence of traveling wave solutions under different values of $c$ and $\beta / \gamma$. In Section 6 , we give the discussion.

## 2 Main results

Since $R$ does not appear in the SEIR model (1.4)-(1.6), it suffices to consider the three-dimensional system for $(S, E, I)$. We look for the non-trivial and non-negative traveling wave solution of the form $(S(x+c t), E(x+c t), I(x+c t))$, which satisfies the following boundary conditions at infinity:

$$
\begin{equation*}
S(-\infty)=S_{-\infty}, \quad S(\infty)=S_{\infty}<S_{-\infty}, \quad E( \pm \infty)=I( \pm \infty)=0 \tag{2.1}
\end{equation*}
$$

Then System (1.4)-(1.6) can be reduced to an ODE system

$$
\begin{align*}
& c S^{\prime}=d_{1} S^{\prime \prime}-\frac{\beta S I}{S+I+E}  \tag{2.2}\\
& c E^{\prime}=d_{2} E^{\prime \prime}+\frac{\beta S I}{S+I+E}-\alpha E  \tag{2.3}\\
& c I^{\prime}=d_{3} I^{\prime \prime}+\alpha E-\gamma I \tag{2.4}
\end{align*}
$$

Our main results are the following.
Theorem 2.1. There exists a positive constant number $c^{*}$ such that if $c>c^{*}$ and $R_{0}:=\beta / \gamma>1$, then System (2.2)-(2.4) has a non-trivial and non-negative traveling wave solution ( $S, E, I$ ) satisfying the boundary conditions (2.1). Furthermore, $S$ monotonically decreases, $0 \leqslant E(x) \leqslant S_{-\infty}-S_{\infty}$ and $0 \leqslant I(x) \leqslant S_{-\infty}-S_{\infty}$ for all $x \in \mathbb{R}$, and

$$
\int_{-\infty}^{\infty} \alpha E(x) d x=\int_{-\infty}^{\infty} \gamma I(x) d x=\int_{-\infty}^{\infty} \frac{\beta S(x) I(x)}{S(x)+I(x)+E(x)} d x=c\left[S_{-\infty}-S_{\infty}\right] .
$$

On the other hand, if $R_{0}>1,0<c<c^{*}$, or $R_{0} \leqslant 1$, there exists no non-trivial and non-negative traveling wave solution ( $S, E, I$ ) satisfying the boundary conditions (2.1).
Remark 2.2. In the SIR model (1.1)-(1.3), the minimal wave speed is given by $c^{*}:=2 \sqrt{d_{2}(\beta-\gamma)}$, where $d_{2}$ is the diffusive coefficient of $I$. For the SEIR model, as we will see, the minimal wave speed $c^{*}$ depends not only on $d_{3}$, the diffusive rate of $I$, but also on $d_{2}$, the diffusive rate of $E$.

## 3 Preliminaries

Lemma 3.1. If $(S, E, I)$ is a non-trivial and non-negative solution of System (2.2)-(2.4), satisfying the boundary conditions (2.1), it holds that $\int_{-\infty}^{\infty} E(x) d x<\infty$.
Proof. Integrating (2.2) from $-\infty$ to $x$ yields

$$
\begin{equation*}
d_{1} S^{\prime}(x)=c\left[S(x)-S_{-\infty}\right]+\int_{-\infty}^{x} \frac{\beta S(y) I(y)}{S(y)+I(y)+E(y)} d y \tag{3.1}
\end{equation*}
$$

Since $S(x)$ is uniformly bounded, the integral on the right-hand side of (3.1) should be uniformly bounded. Otherwise, $S^{\prime}(x) \rightarrow \infty$ as $x \rightarrow \infty$, thus $S(x) \rightarrow \infty$, which leads to a contradiction. Hence,

$$
\begin{equation*}
\int_{-\infty}^{x} \frac{\beta S(y) I(y)}{S(y)+I(y)+E(y)} d y \tag{3.2}
\end{equation*}
$$

is integrable on $\mathbb{R}$ and bounded. Integrating (2.3) yields

$$
\begin{aligned}
E(x)= & \frac{1}{\rho_{2}} \int_{-\infty}^{x} \mathrm{e}^{\lambda_{2}^{-}(x-y)} \frac{\beta S(y) I(y)}{S(y)+I(y)+E(y)} d y+\frac{1}{\rho_{2}} \int_{x}^{\infty} \mathrm{e}^{\lambda_{2}^{+}(x-y)} \frac{\beta S(y) I(y)}{S(y)+I(y)+E(y)} d y \\
& +C_{1} \mathrm{e}^{\lambda_{2}^{-} x}+C_{2} \mathrm{e}^{\lambda_{2}^{+} x}
\end{aligned}
$$

where $C_{1}$ and $C_{2}$ are constants and

$$
\lambda_{2}^{ \pm}:=\frac{c \pm \sqrt{c^{2}+4 d_{2} \alpha}}{2 d_{2}}, \quad \rho_{2}:=\sqrt{c^{2}+4 d_{2} \alpha}=d_{2}\left(\lambda_{2}^{+}-\lambda_{2}^{-}\right)
$$

The integrals in the expression of $E(x)$ are well-defined for the integrability of (3.2). Moreover, by the boundary condition $E( \pm \infty)=0, C_{1}$ and $C_{2}$ must be zeros. By using Fubini's theorem, we have

$$
\int_{-\infty}^{\infty} E(x) d x=\frac{1}{\alpha} \int_{-\infty}^{\infty} \frac{\beta S(x) I(x)}{S(x)+I(x)+E(x)} d x<\infty
$$

We finish the proof.
From (2.4), we get the solution

$$
I(x)=C_{1} \mathrm{e}^{\lambda_{1}^{-} x}+C_{2} \mathrm{e}^{\lambda_{1}^{+} x}+\frac{\alpha}{\rho_{1}}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-y)} E(y) d y+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-y)} E(y) d y\right)
$$

where $C_{1}$ and $C_{2}$ are constant numbers, and $\lambda_{1}^{-}<0<\lambda_{1}^{+}$are the two roots of the equations

$$
\begin{equation*}
f_{1}(\lambda):=-d_{3} \lambda^{2}+c \lambda+\gamma=0 \tag{3.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\rho_{1}:=d_{3}\left(\lambda_{1}^{+}-\lambda_{1}^{-}\right) \tag{3.4}
\end{equation*}
$$

Together with the boundary condition of $E$ in (2.1) and L'Hôpital's rule, the only solution of (2.4) satisfying $\lim _{x \rightarrow \pm \infty} I(x)=0$ is of the form

$$
\begin{equation*}
[I(E)](x):=\frac{\alpha}{\rho_{1}}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-y)} E(y) d y+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-y)} E(y) d y\right) \tag{3.5}
\end{equation*}
$$

where Lemma 3.1 guarantees the integrability of the integrals. Substituting (3.5) into (2.3), we obtain

$$
\begin{equation*}
c E^{\prime}=d_{2} E^{\prime \prime}+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E \tag{3.6}
\end{equation*}
$$

At the equilibrium $\left(S_{-\infty}, 0,0\right)$, (3.6) can be linearized as $c E^{\prime}=d_{2} E^{\prime \prime}+\beta I(E)-\alpha E$. To study the characteristic function we use the form $E(t)=\mathrm{e}^{\lambda t}$, where $\lambda \in\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$, then

$$
c \lambda=d_{2} \lambda^{2}+\frac{\alpha \beta}{-d_{3} \lambda^{2}+c \lambda+\gamma}-\alpha .
$$

The characteristic function of (3.6) is defined as

$$
\begin{equation*}
f(\lambda, c):=-d_{2} \lambda^{2}+c \lambda+\alpha-\frac{\alpha \beta}{-d_{3} \lambda^{2}+c \lambda+\gamma} \tag{3.7}
\end{equation*}
$$

for $\lambda \in\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$.

Lemma 3.2. Assume $\beta / \gamma>1$. There exist $\lambda_{0} \in\left(0, \lambda_{1}^{+}\right)$and $c^{*}>0$ such that

$$
f\left(\lambda_{0}, c^{*}\right)=0 \quad \text { and } \quad \frac{\partial f\left(\lambda_{0}, c^{*}\right)}{\partial \lambda}=0
$$

Furthermore, if $c>c^{*}, f(\lambda, c)=0$ has two different real roots $\lambda_{1}$ and $\lambda_{2}$ with $0<\lambda_{1}<\lambda_{0}<\lambda_{2}<\lambda_{1}^{+}$and $f(\lambda, c)>0$ if $\lambda \in\left(\lambda_{1}, \lambda_{2}\right) ; f(\lambda, c)<0$ if $\lambda \in\left(0, \lambda_{1}\right) \cup\left(\lambda_{2}, \lambda_{1}^{+}\right)$. If $0<c<c^{*}, f(\lambda, c)<0$ for $\lambda \in\left(0, \lambda_{1}^{+}\right)$.
Proof. By calculation, we have

$$
\begin{aligned}
& f(0, c)=\alpha-\frac{\alpha \beta}{\gamma}<0, \quad f(\lambda, \infty)=\infty \quad \text { for } \quad \lambda \in\left(0, \lambda_{1}^{+}\right) \\
& \frac{\partial f(0, c)}{\partial \lambda}=c\left(1+\alpha \beta / \gamma^{2}\right)>0 \\
& \frac{\partial f(\lambda, c)}{\partial c}=\lambda+\frac{\alpha \beta \lambda}{\left(-d_{3} \lambda^{2}+c \lambda+\gamma\right)^{2}}>0 \quad \text { for } \quad \lambda \in\left(0, \lambda_{1}^{+}\right) \\
& \frac{\partial^{2} f(\lambda, c)}{\partial \lambda^{2}}=-2 d_{2}-\frac{2 \alpha \beta d_{3}}{\left(-d_{3} \lambda^{2}+c \lambda+\gamma\right)^{2}}-\frac{2 \alpha \beta\left(-2 d_{3} \lambda+c\right)^{2}}{\left(-d_{3} \lambda^{2}+c \lambda+\gamma\right)^{3}}<0 \quad \text { for } \quad \lambda \in\left(0, \lambda_{1}^{+}\right)
\end{aligned}
$$

By a simple discussion, we can get the existence of such a pair of $\left(\lambda_{0}, c^{*}\right)$ from the above inequalities.
Let $c>c^{*}$ be fixed. We use the notation

$$
\begin{equation*}
f(\lambda):=f(\lambda, c) \tag{3.8}
\end{equation*}
$$

and want to find a $\lambda_{*} \in\left(0, \lambda_{1}^{+}\right)$such that

$$
\begin{equation*}
f\left(\lambda_{*}\right)=0 \quad \text { and } \quad f^{\prime}\left(\lambda_{*}\right)>0 \tag{3.9}
\end{equation*}
$$

By Lemma 3.2, we can choose $\lambda_{*}=\lambda_{1}$. To get the minimal wave speed $c^{*}$, we need to deal with a quartic equation and there is a formula giving its discriminant.
Theorem 3.3. Given positive numbers $d_{2}, d_{3}, \alpha, \beta$ and $\gamma$, the minimal wave speed $c^{*}$ is the unique positive solution of $\Delta(c)=0$, where $\Delta(c)$ is defined as follows:

$$
\begin{aligned}
\Delta(c):= & 256 A^{3} E^{3}-192 A^{2} B D E^{2}-128 A^{2} C^{2} E^{2}+144 A^{2} C D^{2} E-27 A^{2} D^{4} \\
& +144 A B^{2} C E^{2}-6 A B^{2} D^{2} E-80 A B C^{2} D E+18 A B C D^{3}+16 A C^{4} E \\
& -4 A C^{3} D^{2}-27 B^{4} E^{2}+18 B^{3} C D E-4 B^{3} D^{3}-4 B^{2} C^{3} E+B^{2} C^{2} D^{2} \\
= & A_{4} c^{8}+A_{3} c^{6}+A_{2} c^{4}+A_{1} c^{2}+A_{0}
\end{aligned}
$$

where

$$
\begin{aligned}
& A=d_{2} d_{3}, \quad B=-c\left(d_{2}+d_{3}\right), \quad C=c^{2}-d_{2} \gamma-d_{3} \alpha \\
& D=c(\alpha+\gamma), \quad E=\alpha(\gamma-\beta)
\end{aligned}
$$

and

$$
\begin{aligned}
A_{4}= & -2 d_{2} d_{3} \alpha^{2}+4 d_{2} d_{3} \alpha \gamma-2 d_{2} d_{3} \gamma^{2}-2 \alpha d_{3}^{2} \gamma+4 \alpha d_{3}^{2} \beta-8 \alpha d_{2} d_{3} \beta-2 \alpha d_{2}^{2} \gamma+4 \alpha d_{2}^{2} \beta \\
& +d_{3}^{2} \alpha^{2}+d_{3}^{2} \gamma^{2}+d_{2}^{2} \alpha^{2}+d_{2}^{2} \gamma^{2} \\
A_{3}= & -18 d_{2} d_{3}^{2} \alpha^{2} \gamma+24 d_{2} d_{3}^{2} \alpha \gamma^{2}+24 d_{2}^{2} d_{3} \alpha^{2} \gamma-18 d_{2}^{2} d_{3} \alpha \gamma^{2}+14 d_{2} d_{3}^{2} \alpha^{2} \beta+18 \alpha d_{3}^{3} \gamma \beta \\
& -38 d_{3} d_{2}^{2} \alpha^{2} \beta+6 \alpha d_{2}^{3} \gamma \beta+14 d_{2}^{2} d_{3} \alpha \gamma \beta-38 \alpha d_{2} d_{3}^{2} \gamma \beta+2 d_{2} d_{3}^{2} \alpha^{3}-8 d_{2} d_{3}^{2} \gamma^{3}-8 d_{2}^{2} d_{3} \alpha^{3} \\
& +2 d_{2}^{2} d_{3} \gamma^{3}-8 d_{3}^{3} \alpha \gamma^{2}-8 d_{2}^{3} \alpha^{2} \gamma+2 d_{2}^{3} \alpha \gamma^{2}+6 d_{3}^{3} \alpha^{2} \beta+18 d_{2}^{3} \alpha^{2} \beta+2 d_{3}^{3} \alpha^{3}+4 d_{3}^{3} \gamma^{3} \\
& +4 d_{2}^{3} \alpha^{3}+2 d_{2}^{3} \gamma^{3}+2 d_{3}^{3} \alpha^{2} \gamma \\
A_{2}= & -8 d_{2}^{2} d_{3}^{2} \alpha^{4}+8 d_{2} d_{3}^{3} \alpha^{4}-6 d_{3}^{4} \alpha^{3} \beta-27 \alpha^{2} d_{3}^{4} \beta^{2}-27 \alpha^{2} d_{2}^{4} \beta^{2}-8 d_{2}^{2} d_{3}^{2} \gamma^{4}+8 d_{2}^{3} d_{3} \gamma^{4} \\
& +8 d_{3}^{4} \alpha^{3} \gamma-8 d_{3}^{4} \alpha^{2} \gamma^{2}-8 d_{2}^{4} \gamma^{2} \alpha^{2}+8 d_{2}^{4} \gamma^{3} \alpha+d_{3}^{4} \alpha^{4}+d_{2}^{4} \gamma^{4}-14 d_{2}^{2} d_{3}^{2} \alpha^{3} \beta
\end{aligned}
$$

$$
\begin{aligned}
& +40 d_{2} d_{3}^{3} \alpha^{3} \beta-12 d_{2}^{3} d_{3} \alpha^{3} \beta+36 d_{2} d_{3}^{3} \alpha^{2} \beta^{2}-2 d_{2}^{2} d_{3}^{2} \alpha^{2} \beta^{2}+36 d_{2}^{3} d_{3} \alpha^{2} \beta^{2}-40 d_{2}^{2} d_{3}^{2} \alpha^{3} \gamma \\
& +102 d_{2}^{2} d_{3}^{2} \alpha^{2} \gamma^{2}-40 d_{2}^{2} d_{3}^{2} \alpha \gamma^{3}-4 d_{2} d_{3}^{3} \alpha^{3} \gamma-40 d_{2} d_{3}^{3} \alpha^{2} \gamma^{2}+32 d_{2} d_{3}^{3} \alpha \gamma^{3}+32 d_{2}^{3} d_{3} \alpha^{3} \gamma \\
& -40 d_{2}^{3} d_{3} \alpha^{2} \gamma^{2}-4 d_{2}^{3} d_{3} \alpha \gamma^{3}-6 \alpha d_{2}^{4} \gamma^{2} \beta+36 d_{3}^{4} \alpha^{2} \gamma \beta+36 d_{2}^{4} \gamma \alpha^{2} \beta-192 d_{2}^{2} d_{3}^{2} \alpha^{2} \gamma \beta \\
& -14 d_{2}^{2} d_{3}^{2} \alpha \gamma^{2} \beta+52 d_{2} d_{3}^{3} \alpha^{2} \gamma \beta-12 d_{2} d_{3}^{3} \alpha \gamma^{2} \beta+52 d_{2}^{3} d_{3} \alpha^{2} \gamma \beta+40 d_{2}^{3} d_{3} \alpha \gamma^{2} \beta \\
A_{1}= & 4 d_{2} d_{3}^{4} \alpha^{5}-4 d_{3}^{5} \alpha^{4} \beta+4 d_{2}^{4} d_{3} \gamma^{5}+4 d_{3}^{5} \alpha^{4} \gamma+4 \alpha d_{2}^{5} \gamma^{4}+88 d_{2}^{3} d_{3}^{2} \alpha^{3} \gamma^{2}-32 d_{2}^{3} d_{3}^{2} \alpha^{2} \gamma^{3} \\
& +32 d_{2}^{4} d_{3} \alpha \gamma^{4}+32 d_{2} d_{3}^{4} \alpha^{4} \gamma-48 d_{2}^{3} d_{3}^{2} \alpha \gamma^{4}-48 d_{2}^{2} d_{3}^{3} \alpha^{4} \gamma-48 d_{2} d_{3}^{4} \alpha^{3} \gamma^{2}-48 d_{2}^{4} d_{3} \alpha^{2} \gamma^{3} \\
& -4 \alpha d_{2}^{5} \gamma^{3} \beta+48 d_{2}^{3} d_{3}^{2} \alpha^{3} \beta^{2}-24 d_{2} d_{3}^{4} \alpha^{4} \beta+60 d_{2}^{2} d_{3}^{3} \alpha^{4} \beta-144 d_{2} d_{3}^{4} \alpha^{3} \beta^{2}-32 d_{2}^{2} d_{3}^{3} \alpha^{3} \gamma^{2} \\
& +88 d_{2}^{2} d_{3}^{3} \alpha^{2} \gamma^{3}-104 d_{2}^{2} d_{3}^{3} \alpha^{3} \gamma \beta-124 d_{2}^{2} d_{3}^{3} \alpha^{2} \gamma^{2} \beta+48 d_{2}^{2} d_{3}^{3} \alpha^{2} \gamma \beta^{2}-124 d_{2}^{3} d_{3}^{2} \alpha^{3} \gamma \beta \\
& -104 d_{2}^{3} d_{3}^{2} \alpha^{2} \gamma^{2} \beta+160 d_{2}^{3} d_{3}^{2} \alpha^{2} \gamma \beta^{2}-24 d_{2}^{4} d_{3} \alpha \gamma^{3} \beta+60 d_{2}^{3} d_{3}^{2} \alpha \gamma^{3} \beta+196 d_{2} d_{3}^{4} \alpha^{3} \gamma \beta \\
& +196 d_{2}^{4} d_{3} \alpha^{2} \gamma^{2} \beta-144 d_{2}^{4} d_{3} \alpha^{2} \gamma \beta^{2}+160 d_{2}^{2} d_{3}^{3} \alpha^{3} \beta^{2}, \\
A_{0}= & -352 d_{2}^{3} d_{3}^{3} \alpha^{3} \gamma^{2} \beta+512 d_{2}^{3} d_{3}^{3} \alpha^{3} \gamma \beta^{2}+192 d_{2}^{4} d_{3}^{2} \alpha^{2} \gamma^{3} \beta-128 d_{2}^{4} d_{3}^{2} \alpha^{2} \gamma^{2} \beta^{2}+192 d_{2}^{4} d_{3}^{4} \gamma \beta \\
& -16 d_{2}^{5} d_{3} \alpha \gamma^{4} \beta+16 d_{2}^{5} d_{3} \alpha \gamma^{5}+16 d_{2} d_{3}^{5} \alpha^{5} \gamma-16 d_{2} d_{3}^{5} \alpha^{5} \beta-64 d_{2}^{4} d_{3}^{2} \alpha^{2} \gamma^{4}-64 d_{2}^{2} d_{3}^{4} \alpha^{4} \gamma^{2} \\
& +96 d_{2}^{3} d_{3}^{3} \gamma^{3}-256 d_{2}^{3} d_{3}^{3} \beta^{3}-128 d_{2}^{2} d_{3}^{4} \beta^{2} .
\end{aligned}
$$

Proof. To study the roots of $f(\lambda)$, we rewrite $f(\lambda)=0$ as

$$
\begin{equation*}
G(\lambda):=\left(-d_{2} \lambda^{2}+c \lambda+\alpha\right)\left(-d_{3} \lambda^{2}+c \lambda+\gamma\right)-\alpha \beta=0 . \tag{3.10}
\end{equation*}
$$

$f(\lambda)=0$ and $G(\lambda)=0$ are of the same roots. Obviously, (3.10) always has two simple real roots $\lambda_{\max }>\max \left\{\lambda_{1}^{+}, \lambda_{2}^{+}\right\}$and $\lambda_{\text {min }}<\min \left\{\lambda_{1}^{-}, \lambda_{2}^{-}\right\}$; if (3.10) has other real roots, they must be in the interval $\left(0, \min \left\{\lambda_{1}^{+}, \lambda_{2}^{+}\right\}\right)$, where $\lambda_{1}^{ \pm}$and $\lambda_{2}^{ \pm}$are the roots of $-d_{3} \lambda^{2}+c \lambda+\gamma=0$ and $-d_{2} \lambda^{2}+c \lambda+\alpha=0$, respectively, and $\lambda_{i}^{-}<0<\lambda_{i}^{+}, i=1,2$. We rewrite (3.10) as

$$
\begin{equation*}
d_{2} d_{3} \lambda^{4}-c\left(d_{2}+d_{3}\right) \lambda^{3}+\left(c^{2}-d_{2} \gamma-d_{3} \alpha\right) \lambda^{2}+c(\alpha+\gamma) \lambda+\alpha(\gamma-\beta)=0 \tag{3.11}
\end{equation*}
$$

By the theory of the quartic equation, the discriminant of $G(\lambda)$ is $\Delta$ defined in Theorem 3.3; $\Delta=0 \Leftrightarrow$ (3.11) has the multiple roots; $\Delta<0 \Leftrightarrow(3.11)$ has two simple real roots and two simple complex roots; $\Delta>0 \Leftrightarrow$ the four simple roots of (3.11) are either all real or all complex (see [11]). Since (3.11) already has two simple real roots $\lambda_{\max }$ and $\lambda_{\min }, c^{*}$ must be the solution of $\Delta(c)=0$. Furthermore, we show that $\Delta(c)=0$ has only one real root on $(0, \infty)$. By Lemma 3.2, when $c>c^{*}>0$, (3.7) has two simple real roots on $\left(0, \min \left\{\lambda_{1}^{+}, \lambda_{2}^{+}\right\}\right)$, which means (3.10) has four simple real roots on $\mathbb{R}$ thus $\Delta(c)>0$; when $0<c<c^{*},(3.7)$ has no real roots on $\left(0, \min \left\{\lambda_{1}^{+}, \lambda_{2}^{+}\right\}\right)$, which means (3.10) has two simple real roots and two simple complex roots on $\mathbb{R}$ thus $\Delta(c)<0$. Thus for fixed $d_{2}, d_{3}, \alpha, \beta$ and $\gamma$, there exists only one $c^{*}>0$ satisfying $\Delta\left(c^{*}\right)=0$.
Example 3.4. Given $\alpha=1, \beta=3, \gamma=2, d_{2}=4$ and $d_{3}=7$, then $\Delta(c)=117 c^{8}+9804 c^{6}+$ $115828 c^{4}+7085364 c^{2}-50878912$. It can be regarded as a quartic equation of $c^{2}$. We use the formula of roots of quartic equation to solve $\Delta=0$ and get the eight roots $\pm 2.489728494362, \pm 9.031162429666 \mathrm{i}$ and $\pm 3.543444284346 \pm 4.095346122859$ i. The only positive real root is $c^{*}=2.489728494362$. We choose different values of $c$ and the figures of $G(\lambda)$ defined by (3.10) are in Figure 1.
Remark 3.5. The minimal wave speed $c^{*}$ is important for describing the transmission speed of infectious diseases. We are interested in the relation between the minimal wave speed $c^{*}$ and the diffusive rates $d_{2}$ and $d_{3}$. The explicit expression of $c^{*}$ is too complicated and the surfaces of $c^{*}$ about $d_{2}$ and $d_{3}$ are in Figure 2.

The following lemma gives a simple sufficient condition that ensures such a $\lambda_{*}$ satisfying (3.9).
Lemma 3.6. If $d_{2}<d_{3}$, let $c>2 \sqrt{d_{3}(\beta-\gamma)}$. If $d_{2} \geqslant d_{3}$, let $c>2 \sqrt{d_{2}(\beta / \gamma-1) \alpha}$. Then there exists a $\lambda_{*} \in\left(0, \lambda_{1}^{+}\right)$such that

$$
f\left(\lambda_{*}\right)=0 \quad \text { and } \quad f^{\prime}\left(\lambda_{*}\right)>0
$$



Figure 1 The curves of $G(\lambda)$ when $c$ takes different values. Let $\alpha=1, \beta=3, \gamma=2, d_{2}=4$ and $d_{3}=7$ be fixed. We can see that if $c=c^{*}=2.489728494362, G(\lambda)$ has two simple real roots and a double real root; if $c=1.9<c^{*}, G(\lambda)$ has two real roots; if $c=3.1>c^{*}, G(\lambda)$ has four real roots


Figure 2 The surface of $c^{*}\left(d_{2}, d_{3}\right)$, where $\alpha, \beta$ and $\gamma$ take the same values as they are in Example 3.4. As it is expected, $c^{*}$ increases with respect to $d_{2}$ and $d_{3}$

Proof. First, we define some new notation

$$
g_{1}(\lambda):=\frac{\alpha \beta}{f_{1}(\lambda)}=\frac{\alpha \beta}{-d_{3} \lambda^{2}+c \lambda+\gamma}
$$

and

$$
f_{2}(\lambda):=-d_{2} \lambda^{2}+c \lambda+\alpha
$$

such that

$$
f(\lambda)=f_{2}(\lambda)-g_{1}(\lambda)
$$

We show that if $c>0$ is small enough, $f(\lambda)=0$ has no positive solution in $\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$, where $\lambda_{1}^{ \pm}$are the roots of $f_{1}=0$. If we take $c=0$, then $g_{1}(0)=\alpha \beta / \gamma>\alpha$ is its minimum value on $\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$, while for $f_{2}$, the maximum value is $\alpha$. Thus $f(\lambda)=0$ has no solution in $\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$. Furthermore, $f$ is continuous with respect to $c$, thus there is no solution in $\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$for $c>0$ small enough.

Next, we want to get such a $\lambda_{*} \in\left(\lambda_{1}^{-}, \lambda_{1}^{+}\right)$satisfying (3.9) when $c$ is large enough. Notice that $g_{1}(0)=\alpha \beta / \gamma$ and $f_{2}(0)=\alpha$. By the assumption $\beta / \gamma>1$, we obtain $g_{1}(0)>f_{2}(0)$. The axis of symmetry of $g_{1}(\lambda)$ is $\lambda=c /\left(2 d_{3}\right)>0$ and for $f_{2}(\lambda)$, the axis of symmetry is $\lambda=c /\left(2 d_{2}\right)>0$. Furthermore, $g_{1}(\lambda)$
takes its minimum value

$$
b_{1}=\frac{4 \alpha \beta d_{3}}{c^{2}+4 d_{3} \gamma}
$$

at $\lambda=c /\left(2 d_{3}\right)$, while $f_{2}(\lambda)$ takes its maximum value

$$
b_{2}=\frac{c^{2}}{4 d_{2}}+\alpha
$$

at $\lambda=c /\left(2 d_{2}\right)$. If $c$ is large enough, $b_{1}$ is a sufficiently small positive number and $b_{2}$ can be sufficiently large, thus there must be a $\lambda_{*}$ satisfying (3.9).

If $c /\left(2 d_{2}\right)>c /\left(2 d_{3}\right), g_{1}(\lambda)$ decreases on $\left[0, c /\left(2 d_{3}\right)\right)$. When $c>2 \sqrt{d_{3}(\beta-\gamma)}$,

$$
g_{1}\left(\frac{c}{2 d_{3}}\right)<\alpha
$$

Since $f_{2}$ increases on $\left[0, \frac{c}{2 d_{3}}\right]$ and $f_{2}(0)=\alpha$, we can see that

$$
f_{2}\left(\frac{c}{2 d_{3}}\right)>\alpha
$$

Hence, there exists a solution $\lambda_{*} \in\left(0, c /\left(2 d_{3}\right)\right)$ such that

$$
f\left(\lambda_{*}\right)=0, \quad f^{\prime}\left(\lambda_{*}\right)>0
$$

If $c /\left(2 d_{2}\right) \leqslant c /\left(2 d_{3}\right), f_{2}(\lambda)$ increases on $\left[0, c /\left(2 d_{2}\right)\right)$. Let

$$
c>2 \sqrt{d_{2}\left(\frac{\beta}{\gamma}-1\right) \alpha}
$$

Then

$$
f_{2}\left(\frac{c}{2 d_{2}}\right)>\frac{\alpha \beta}{\gamma}
$$

while $g_{1}(0)=\alpha \beta / \gamma$ and $g_{1}$ decreases on $\left[0, \frac{c}{2 d_{2}}\right)$, which means

$$
g_{1}\left(\frac{c}{2 d_{2}}\right)<\frac{\alpha \beta}{\gamma}
$$

Thus there exists a solution $\lambda_{*} \in\left(0, c /\left(2 d_{2}\right)\right)$ such that $f\left(\lambda_{*}\right)=0, f^{\prime}\left(\lambda_{*}\right)>0$.
For $i=1,2$, we give the second-order linear differential operator $\Delta_{i}$ and its inverse $\Delta_{i}^{-1}$. Given $a_{1}>\beta$ and $a_{2}>\alpha$, the roots of the equation

$$
-d_{i} \Lambda^{2}+c \Lambda+a_{i}=0
$$

are

$$
\Lambda_{i}^{ \pm}:=\frac{c \pm \sqrt{c^{2}+4 d_{i} a_{i}}}{2 d_{i}}
$$

$a_{i}$ is chosen so large that

$$
-\Lambda_{i}^{-}>\lambda_{*}
$$

We introduce a new symbol

$$
R_{i}:=d_{i}\left(\Lambda_{i}^{+}-\Lambda_{i}^{-}\right)=\sqrt{c^{2}+4 d_{i} a_{i}}
$$

The differential operator $\Delta_{i}$ is defined by

$$
\Delta_{i}(h):=-d_{i} h^{\prime \prime}+c h^{\prime}+a_{i} h
$$

for $h \in C^{2}(\mathbb{R})$. The corresponding inverse operator $\Delta_{i}^{-1}$ is

$$
\Delta_{i}^{-1}(h(x)):=\frac{1}{R_{i}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{i}^{-}(x-y)} h(y) d y+\frac{1}{R_{i}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{i}^{+}(x-y)} h(y) d y
$$

for $h \in C_{\mu^{-}, \mu^{+}}(\mathbb{R})$, where

$$
\mu^{-}>\Lambda_{i}^{-}, \quad \mu^{+}<\Lambda_{i}^{+}
$$

and

$$
\begin{equation*}
C_{\mu^{-}, \mu^{+}}(\mathbb{R}):=\left\{h \in C^{2}(\mathbb{R}): \sup _{x \leqslant 0} h(x) \mathrm{e}^{-\mu^{-} x}+\sup _{x \geqslant 0} h(x) \mathrm{e}^{-\mu^{+} x}<\infty\right\} \tag{3.12}
\end{equation*}
$$

Furthermore, by a simple calculation,

$$
\left(\Delta_{i}^{-1} h\right)^{\prime}(x)=\frac{\Lambda_{i}^{-}}{R_{i}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{i}^{-}(x-y)} h(y) d y+\frac{\Lambda_{i}^{+}}{R_{i}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{i}^{+}(x-y)} h(y) d y
$$

and

$$
\left(\Delta_{i}^{-1} h\right)^{\prime \prime}(x)=\frac{\left(\Lambda_{i}^{-}\right)^{2}}{R_{i}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{i}^{-}(x-y)} h(y) d y+\frac{\left(\Lambda_{i}^{+}\right)^{2}}{R_{i}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{i}^{+}(x-y)} h(y) d y+\frac{\Lambda_{i}^{-}}{R_{i}} h(x)-\frac{\Lambda_{i}^{+}}{R_{i}} h(x)
$$

The following Lemmas 3.7 and 3.8 on the properties of operators $\Delta_{i}$ and $\Delta_{i}^{-1}$ are from Wang et al. [14]. These two lemmas can be checked by a direct calculation.
Lemma 3.7. For $i=1,2$,

$$
\Delta_{i}^{-1}\left(\Delta_{i} h\right)=h
$$

for any $h \in C^{2}(\mathbb{R})$ such that $h, h^{\prime}, h^{\prime \prime} \in C_{\mu^{-}, \mu^{+}}(\mathbb{R})$. Furthermore,

$$
\Delta_{i}\left(\Delta_{i}^{-1} h\right)=h
$$

for $h \in C_{\mu^{-}, \mu^{+}}(\mathbb{R})$, where $\mu^{-}>\Lambda_{i}^{-}$and $\mu^{+}<\Lambda_{i}^{+}$.
Next, define

$$
g(x):= \begin{cases}\mathrm{e}^{\lambda x}\left(1-M \mathrm{e}^{\varepsilon x}\right), & x \leqslant x^{*}  \tag{3.13}\\ 0, & x>x^{*}\end{cases}
$$

where $x^{*}=-(\ln M) / \varepsilon . g(x)$ can be rewritten as

$$
g(x)=\mathrm{e}^{\lambda x}\left(1-M \mathrm{e}^{\varepsilon x}\right) \vee 0
$$

by using the new symbol $\vee$ defined as follows:

$$
a \vee b:=\max \{a, b\}
$$

Lemma 3.8. For $i=1,2$, given any $M>0$ and $\varepsilon>0$,

$$
\Delta_{i}^{-1}\left(\Delta_{i} g\right) \geqslant g
$$

holds for $g(x)=\mathrm{e}^{\lambda x}\left(1-M \mathrm{e}^{\varepsilon x}\right) \vee 0$, where

$$
\Lambda_{i}^{-}<\lambda<\lambda+\varepsilon<\Lambda_{i}^{+}
$$

Remark 3.9. Although $g(x)$ is not differentiable at $x^{*}$, the integral $\Delta_{i}^{-1}\left(\Delta_{i} g\right)$ is well-defined in the sense of distribution.

Choosing $\mu$ such that

$$
\begin{equation*}
\lambda_{*}<\mu<-\Lambda_{i}^{-}<\Lambda_{i}^{+}, \quad i=1,2 \tag{3.14}
\end{equation*}
$$

we define the functional space

$$
B_{\mu}\left(\mathbb{R}, \mathbb{R}^{2}\right)=\left\{\phi=\left(\phi_{1}, \phi_{2}\right): \phi_{i} \in C(\mathbb{R}), \sup _{x \in \mathbb{R}} \mathrm{e}^{-\mu|x|}\left|\phi_{i}(x)\right|<\infty, i=1,2\right\}
$$

with the norm

$$
\begin{equation*}
|\phi|_{\mu}:=\max \left\{\left|\phi_{i}\right|_{\mu}, i=1,2\right\}, \tag{3.15}
\end{equation*}
$$

where

$$
\left|\phi_{i}\right|_{\mu}:=\sup _{x \in \mathbb{R}} \mathrm{e}^{-\mu|x|}\left|\phi_{i}(x)\right| .
$$

We give the definitions as follows:

$$
\begin{align*}
& S_{+}:=S_{-\infty},  \tag{3.16}\\
& S_{-}:=S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right) \vee 0,  \tag{3.17}\\
& E_{+}:=\mathrm{e}^{\lambda_{*} x}  \tag{3.18}\\
& E_{-}:=\mathrm{e}^{\lambda_{*} x}\left(1-M_{2} \mathrm{e}^{\varepsilon_{2} x}\right) \vee 0, \tag{3.19}
\end{align*}
$$

where $M_{i}>0$ is sufficiently large and $\varepsilon_{i}>0$ is sufficiently small, $i=1,2$. We denote

$$
\begin{align*}
& F_{1}(S, E):=\Delta_{1}^{-1}\left[a_{1} S-\frac{\beta S I(E)}{S+I(E)+E}\right]  \tag{3.20}\\
& F_{2}(S, E):=\Delta_{2}^{-1}\left[a_{2} E+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E\right] \tag{3.21}
\end{align*}
$$

$\Gamma$ is the convex cone defined by using (3.16)-(3.19), i.e.,

$$
\Gamma:=\left\{(S, E) \in B_{\mu}\left(\mathbb{R}, \mathbb{R}^{2}\right): S_{-} \leqslant S \leqslant S_{+}, E_{-} \leqslant E \leqslant E_{+}\right\}
$$

We can see that $\Gamma$ is uniformly bounded under the norm $|\cdot|_{\mu}$ defined in (3.15). We show that $\Gamma$ is invariant under the map $F=\left(F_{1}, F_{2}\right)$.
Lemma 3.10. $F=\left(F_{1}, F_{2}\right)$ maps $\Gamma$ to $\Gamma$, i.e., for $(S, E) \in \Gamma, S_{-} \leqslant S \leqslant S_{+}$and $E_{-} \leqslant E \leqslant E_{+}$, we have

$$
S_{-} \leqslant F_{1}(S, E) \leqslant S_{+}
$$

and

$$
E_{-} \leqslant F_{2}(S, E) \leqslant E_{+}
$$

Proof. First, since

$$
\Delta_{1} F_{1}(S, E)=a_{1} S-\frac{\beta S I(E)}{S+I(E)+E} \leqslant a_{1} S_{+}=\Delta_{1} S_{+}
$$

by Lemma 3.7, we have

$$
F_{1}(S, E) \leqslant \Delta_{1}^{-1}\left(\Delta_{1} S_{+}\right)=S_{+}
$$

Next, we show that $F_{1}(S, E) \geqslant S_{-}$. For $x>x_{1}:=-\varepsilon_{1}^{-1} \ln M_{1}, S_{-}(x)=0$, thus $\Delta_{1} S_{-}=0$. Since $a_{1}>\beta$, we have

$$
a_{1} S-\frac{\beta S I(E)}{S+I(E)+E} \geqslant a_{1} S-\beta S \geqslant 0=\Delta_{1} S_{-}
$$

which implies that $F_{1}(S, E) \geqslant S_{-}$holds for $x \geqslant x_{1}$. For $x<x_{1}$, we need to show

$$
-\beta I\left(E_{+}\right) \geqslant-d_{1} S_{-}^{\prime \prime}+c S_{-}^{\prime}
$$

Since $S_{-}(x)=S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right)$, the above inequality is

$$
-\beta I\left(E_{+}\right) \geqslant-d_{1} S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right)^{\prime \prime}+c S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right)^{\prime} .
$$

By the definition of $I(E)$ and $E_{+}(x)=\mathrm{e}^{\lambda_{*} x}$, it implies to prove

$$
S_{-\infty} M_{1} \varepsilon_{1}\left(-d_{1} \varepsilon_{1}+c\right) \geqslant \frac{\alpha \beta}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma} \mathrm{e}^{\left(\lambda_{*}-\varepsilon_{1}\right) x} .
$$

Choosing $\varepsilon_{1} \in\left(0, \lambda_{*}\right)$ sufficiently small, since the right-hand side of the above inequality monotonically increases with respect to $x$ and $x \leqslant-\varepsilon_{1}^{-1} \ln M_{1}$, we only need to show

$$
S_{-\infty} M_{1} \varepsilon_{1}\left(-d_{1} \varepsilon_{1}+c\right) \geqslant \frac{\alpha \beta}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma} \mathrm{e}^{-\varepsilon_{1}^{-1}\left(\lambda_{*}-\varepsilon_{1}\right) \ln M_{1}}
$$

This inequality holds for $0<\varepsilon_{1}<\min \left\{\lambda_{*}, c / d_{1}\right\}$ and $M_{1}$ large enough.
Next, we verify $E_{-} \leqslant F_{2}(S, E) \leqslant E_{+}$. Since $f\left(\lambda_{*}\right)=0$ in (3.8), it holds that

$$
\begin{equation*}
a_{2} E+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E \leqslant a_{2} E_{+}+\beta I\left(E_{+}\right)-\alpha E_{+}=a_{2} E_{+}-d_{2} E_{+}^{\prime \prime}+c E_{+}^{\prime}=\Delta_{2} E_{+} \tag{3.22}
\end{equation*}
$$

By Lemma 3.7, it holds that

$$
F_{2}(S, E) \leqslant \Delta_{2}^{-1}\left(\Delta_{2} E_{+}\right)=E_{+}
$$

Next, to check

$$
a_{2} E+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E \geqslant a_{2} E_{-}+\frac{\beta S_{-} I\left(E_{-}\right)}{S_{-}+I\left(E_{-}\right)+E_{+}}-\alpha E_{-} \geqslant a_{2} E_{-}-d_{2} E_{-}^{\prime \prime}+c E_{-}^{\prime}=\Delta_{2} E_{-}
$$

it suffices to show

$$
\frac{\beta S_{-} I\left(E_{-}\right)}{S_{-}+I\left(E_{-}\right)+E_{+}}-\alpha E_{-} \geqslant-d_{2} E_{-}^{\prime \prime}+c E_{-}^{\prime}
$$

For $x \geqslant x_{2}:=-\varepsilon_{2}^{-1} \ln M_{2}, E_{-}(x)=0$ and the above inequality holds. For $x<x_{2}$, we subtract both sides by $\beta I\left(E_{-}\right)-\alpha E_{-}$and obtain

$$
\begin{equation*}
-\frac{\beta I^{2}\left(E_{-}\right)}{S_{-}+I\left(E_{-}\right)+E_{+}}-\frac{\beta I\left(E_{-}\right) E_{+}}{S_{-}+I\left(E_{-}\right)+E_{+}} \geqslant-d_{2} E_{-}^{\prime \prime}+c E_{-}^{\prime}+\alpha E_{-} \beta I\left(E_{-}\right) . \tag{3.23}
\end{equation*}
$$

In view of $f\left(\lambda_{*}\right)=0$ and $E_{-}=\mathrm{e}^{\lambda_{*} x}\left(1-M_{2} \mathrm{e}^{\varepsilon_{2} x}\right)$, we obtain

$$
-d_{2} E_{-}^{\prime \prime}+c E_{-}^{\prime}+\alpha E_{-}-\beta I\left(E_{-}\right)=f\left(\lambda_{*}\right) \mathrm{e}^{\lambda_{*} x}-M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x}=-M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x}
$$

To prove (3.23), it suffices to show

$$
\begin{equation*}
\frac{\beta I^{2}\left(E_{-}\right)+\beta I\left(E_{-}\right) E_{+}}{S_{-}} \leqslant M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x} \tag{3.24}
\end{equation*}
$$

We take $\varepsilon_{2} \in\left(0, \min \left\{\varepsilon_{1}, \lambda_{*}, \lambda_{2}-\lambda_{*}\right\}\right)$ small enough, where $\lambda_{2}$ is defined in Lemma 3.2. It holds that

$$
\begin{equation*}
I\left(E_{-}\right)(x)=\frac{\alpha \mathrm{e}^{\lambda_{*} x}}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma}-M_{2} \frac{\alpha \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x}}{-d_{3}\left(\lambda_{*}+\varepsilon_{2}\right)^{2}+c\left(\lambda_{*}+\varepsilon_{2}\right)+\gamma} \tag{3.25}
\end{equation*}
$$

For simplicity, we introduce new notation $K_{1}$ and $K_{2}$ such that $I\left(E_{-}\right)$can be rewritten as

$$
I\left(E_{-}\right)(x)=K_{1} \mathrm{e}^{\lambda_{*} x}-K_{2}\left(\varepsilon_{2}\right) M_{2} \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x}>0
$$

for $x<x_{2}$. (3.24) becomes

$$
\frac{\beta \mathrm{e}^{2 \lambda_{*} x}\left[\left(K_{1}-K_{2}\left(\varepsilon_{2}\right) M_{2} \mathrm{e}^{\varepsilon_{2} x}\right)^{2}+K_{1}-K_{2}\left(\varepsilon_{2}\right) M_{2} \mathrm{e}^{\varepsilon_{2} x}\right]}{S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right)} \leqslant M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) \mathrm{e}^{\left(\lambda_{*}+\varepsilon_{2}\right) x}
$$

It suffices to verify

$$
M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) S_{-\infty}\left(1-M_{1} \mathrm{e}^{\varepsilon_{1} x}\right) \geqslant \beta \mathrm{e}^{\left(\lambda_{*}-\varepsilon_{2}\right) x}\left(K_{1}^{2}+K_{1}\right)
$$

holds for small $\varepsilon_{2}$. For $x<x_{2}=-\varepsilon_{2}^{-1} \ln M_{2}$, we need to show

$$
M_{2} f\left(\lambda_{*}+\varepsilon_{2}\right) S_{-\infty}\left(1-M_{1} M_{2}^{-\varepsilon_{1} / \varepsilon_{2}}\right) \geqslant \beta M_{2}^{-\left(\lambda_{*}-\varepsilon_{2}\right) / \varepsilon_{2}}\left(K_{1}^{2}+K_{1}\right)
$$

Let $M_{2}=1 / f\left(\lambda_{*}+\varepsilon_{2}\right)$. As $\varepsilon_{2}$ goes to zero, the left-hand side of the above inequality goes to $S_{-\infty}$ while the right-hand side goes to zero and thus (3.24) holds. Together with Lemma 3.8, it yields that

$$
F_{2}(S, E) \geqslant \Delta_{2}^{-1}\left(\Delta_{2} E_{-}\right) \geqslant E_{-}
$$

Lemma 3.11. For $E \in C_{-\mu, \mu}(\mathbb{R})$ whose norm $|E|_{\mu}$ is bounded, where $|\cdot|_{\mu}$ is defined in (3.15), there exists a constant $K_{0} \geqslant 1$ such that $|I(E)|_{\mu}<K_{0}|E|_{\mu}$.
Proof. Recall the integral form of $I(E)(x)$ is

$$
I(E)(x)=\frac{\alpha}{\rho_{1}} \int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-y)} E(y) d y+\frac{\alpha}{\rho_{1}} \int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-y)} E(y) d y
$$

where $\rho_{1}$ and $\lambda_{1}^{ \pm}$are defined in (3.4) and (3.3). For any $x$, we have

$$
\begin{aligned}
\mathrm{e}^{-\mu|x|} I(E)(x) & =\frac{\alpha}{\rho_{1}}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-s)} \mathrm{e}^{-\mu|x|} E(s) d s+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-s)} \mathrm{e}^{-\mu|x|} E(s) d s\right) \\
& \leqslant \frac{\alpha}{\rho_{1}}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-s)} d s+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-s)} d s\right)|E|_{\mu} \\
& =\frac{\alpha}{\rho_{1}}\left(\frac{-1}{\lambda_{1}^{-}}+\frac{1}{\lambda_{1}^{+}}\right)|E|_{\mu}=(\alpha / \gamma)|E|_{\mu} .
\end{aligned}
$$

Take $K_{0}=\max \{1, \alpha / \gamma\}$. This completes the proof.
Lemma 3.12. The map $F=\left(F_{1}, F_{2}\right): \Gamma \rightarrow \Gamma$ is continuous and compact with respect to the norm $|\cdot|_{\mu}$.
Proof. For $\left(S_{1}, E_{1}\right) \in \Gamma$ and $\left(S_{2}, E_{2}\right) \in \Gamma$, since

$$
\left|\frac{\beta S_{1} I\left(E_{1}\right)}{S_{1}+I\left(E_{1}\right)+E_{1}}-\frac{\beta S_{2} I\left(E_{2}\right)}{S_{2}+I\left(E_{2}\right)+E_{2}}\right| \leqslant \beta\left(\left|S_{1}-S_{2}\right|+\left|I\left(E_{1}\right)-I\left(E_{2}\right)\right|\right)
$$

we have

$$
\left|a_{1} S_{1}-a_{1} S_{2}-\frac{\beta S_{1} I\left(E_{1}\right)}{S_{1}+I\left(E_{1}\right)+E_{1}}+\frac{\beta S_{2} I\left(E_{2}\right)}{S_{2}+I\left(E_{2}\right)+E_{2}}\right| \leqslant\left(a_{1}+\beta\right)\left(\left|S_{1}-S_{2}\right|+\left|I\left(E_{1}\right)-I\left(E_{2}\right)\right|\right)
$$

By the definition of the norm $|\cdot|_{\mu}$ and Lemma 3.11,

$$
\begin{aligned}
\left|F_{1}\left(S_{1}, E_{1}\right)-F_{1}\left(S_{2}, E_{2}\right)\right|(x) \mathrm{e}^{-\mu|x|} \leqslant & \mathrm{e}^{-\mu|x|} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{1}^{-}(x-y)}\left(a_{1}+\beta\right)\left(\left|S_{1}-S_{2}\right|+\left|I\left(E_{1}\right)-I\left(E_{2}\right)\right|\right) d y \\
& +\mathrm{e}^{-\mu|x|} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{1}^{+}(x-y)}\left(a_{1}+\beta\right)\left(\left|S_{1}-S_{2}\right|+\left|I\left(E_{1}\right)-I\left(E_{2}\right)\right|\right) d y \\
\leqslant & \frac{a_{1}+\beta}{R_{1}}\left(\left|S_{1}-S_{2}\right|_{\mu}+K_{0}\left|E_{1}-E_{2}\right|_{\mu}\right) C(x) \\
\leqslant & \frac{\left(a_{1}+\beta\right) K_{0}}{R_{1}}\left(\left|S_{1}-S_{2}\right|_{\mu}+\left|E_{1}-E_{2}\right|_{\mu}\right) C(x)
\end{aligned}
$$

where

$$
C(x):=\mathrm{e}^{-\mu|x|}\left(\int_{-\infty}^{x} \mathrm{e}^{\Lambda_{1}^{-}(x-y)+\mu|y|} d y+\int_{x}^{\infty} \mathrm{e}^{\Lambda_{1}^{+}(x-y)+\mu|y|} d y\right)
$$

We have

$$
C(-\infty)=\frac{1}{\mu+\Lambda_{1}^{+}}-\frac{1}{\mu+\Lambda_{1}^{-}}
$$

and

$$
C(\infty)=\frac{1}{-\mu+\Lambda_{1}^{+}}+\frac{1}{\mu-\Lambda_{1}^{-}}
$$

Thus $C(x)$ is uniformly bounded on $\mathbb{R}$ and consequently $F_{1}$ is continuous with respect to the norm $|\cdot|_{\mu}$. Similarly, $F_{2}$ is also continuous with respect to this norm. To prove the compactness of $F$, we use the Arzela-Ascoli theorem and the diagonal process. Denote

$$
I_{k}:=[-k, k], \quad k \in \mathbb{N}
$$

and consider $\Gamma$ as the bounded subset of $C\left(I_{k}, \mathbb{R}^{2}\right)$ with the maximum norm. Obviously, $F$ is uniformly bounded on $I_{k}$. Next, we show that $F$ is equi-continuous on $I_{k}$. For any $(S, E) \in \Gamma$,

$$
\begin{aligned}
\left|F_{1}^{\prime}(S, E)\right| & \leqslant \frac{-\Lambda_{1}^{-} a_{1} S_{-\infty}}{R_{1}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{1}^{-}(x-y)} d y+\frac{\Lambda_{1}^{+} a_{1} S_{-\infty}}{R_{1}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{1}^{+}(x-y)} d y \\
& =\frac{2 a_{1} S_{-\infty}}{R_{1}}
\end{aligned}
$$

and

$$
\begin{aligned}
\left|F_{2}^{\prime}(S, E)\right| \leqslant & \frac{-\Lambda_{2}^{-}\left(a_{2}+\frac{\alpha \beta}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma}-\alpha\right)}{R_{2}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{2}^{-}(x-y)+\lambda_{*} y} d y \\
& +\frac{\Lambda_{2}^{+}\left(a_{2}+\frac{\alpha \beta}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma}-\alpha\right)}{R_{2}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{2}^{+}(x-y)+\lambda_{*} y} d y \\
= & \frac{1}{R_{2}}\left(\frac{-\Lambda_{2}^{-}}{\lambda_{*}-\Lambda_{2}^{-}}+\frac{\Lambda_{2}^{+}}{\Lambda_{2}^{+}-\lambda_{*}}\right)\left(a_{2}+\frac{\alpha \beta}{-d_{3} \lambda_{*}^{2}+c \lambda_{*}+\gamma}-\alpha\right) \mathrm{e}^{\lambda_{*} x}
\end{aligned}
$$

Let $\left\{u_{n}\right\}$ be a subsequence of $\Gamma$. $\left\{u_{n}\right\}$ can also be regarded as a bounded subsequence of $C\left(I_{k}\right)$. Since $\left\{F\left(u_{n}\right)\right\}$ is uniformly bounded and equi-continuous on $I_{k}$, by the Arzela-Ascoli theorem, we can choose a subsequence $\left\{u_{n_{k}}\right\}$ such that

$$
v_{n_{k}}=F u_{n_{k}}
$$

converges in $C\left(I_{k}\right), k \in \mathbb{N}$.
Let $v$ denote the limit of $\left\{v_{n_{k}}\right\}$. We can see that $v \in C\left(\mathbb{R}, \mathbb{R}^{2}\right)$. Since $F(\Gamma) \subset \Gamma$ and $\Gamma$ is closed, thus $v \in \Gamma$. Furthermore, $\mu>\lambda_{*}>0$, hence $\left|E_{+}\right|_{\mu}$ is bounded and $\Gamma$ is also uniformly bounded under the norm $|\cdot|_{\mu}$. Thus $\left|v_{n_{k}}-v\right|_{\mu}$ is uniformly bounded for all $n \in \mathbb{N}$. Given any $\varepsilon>0$, we can choose $M \in \mathbb{N}$ independent of $u_{n_{k}}$ such that

$$
\mathrm{e}^{-\mu|x|}\left|v_{n_{k}}(x)-v(x)\right|<\varepsilon, \quad n \in \mathbb{N}
$$

holds for any $|x|>M$. On the compact interval $[-M, M],\left\{v_{n_{k}}\right\}$ converges to $v$ with the maximum norm. Thus there exists $K \in \mathbb{N}$ such that

$$
\mathrm{e}^{-\mu|x|}\left|v_{n_{k}}(x)-v(x)\right|<\varepsilon
$$

for $|x|<M$ and $n>K$. Hence, $\left\{v_{n_{k}}\right\}$ converges to $v$ under the norm $|\cdot|_{\mu}$. We have finished the proof of the compactness of the map $F$.

## 4 Existence theorem

Since $F$ is continuous and compact on $\Gamma$, by the Schauder fixed point theorem, $F$ has a fixed point $(S, E) \in \Gamma$ such that

$$
\begin{aligned}
& S=F_{1}(S, E)=\Delta_{1}^{-1}\left(a_{1} S-\frac{\beta S I(E)}{S+I(E)+E}\right) \\
& E=F_{2}(S, E)=\Delta_{2}^{-1}\left(a_{2} E+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E\right)
\end{aligned}
$$

Since $S, E \in C_{-\mu, \mu}(\mathbb{R})$ and $\Lambda_{i}^{-}<-\mu<\mu<\Lambda_{i}^{+}, i=1,2$, it holds that

$$
\begin{align*}
& \Delta_{1} S=a_{1} S-\frac{\beta S I(E)}{S+I(E)+E}  \tag{4.1}\\
& \Delta_{2} E=a_{2} E+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E \tag{4.2}
\end{align*}
$$

By the definition of $\Delta_{i},(S, E)$ satisfies

$$
\begin{align*}
& c S^{\prime}=d_{1} S^{\prime \prime}-\frac{\beta S I(E)}{S+I(E)+E}  \tag{4.3}\\
& c E^{\prime}=d_{2} E^{\prime \prime}+\frac{\beta S I(E)}{S+I(E)+E}-\alpha E \tag{4.4}
\end{align*}
$$

Next, we verify that the boundary conditions hold. Since

$$
S_{-} \leqslant S \leqslant S_{+} \quad \text { and } \quad E_{-} \leqslant E \leqslant E_{+}
$$

it holds that

$$
S(x) \rightarrow S_{-\infty}, \quad E(x) \sim \mathrm{e}^{\lambda_{*} x} \quad \text { as } \quad x \rightarrow-\infty
$$

In the proof of Lemma 3.1, we have

$$
d_{1} S^{\prime}(x)=c\left[S(x)-S_{-\infty}\right]+\int_{-\infty}^{x} \frac{\beta S(y) I(y)}{S(y)+I(E)(y)+E(y)} d y
$$

Together with the integrability of (3.2), it holds that $S^{\prime}$ is uniformly bounded. We have

$$
\left(\mathrm{e}^{-c x / d_{1}} S^{\prime}(x)\right)^{\prime}=\mathrm{e}^{-c x / d_{1}}\left(S^{\prime \prime}(x)-c S^{\prime}(x) / d_{1}\right)=\mathrm{e}^{-c x / d_{1}} \frac{\beta S(x) I(E)(x)}{d_{1}[S(x)+I(E)(x)+E(x)]}
$$

Integrating the above equality yields

$$
\mathrm{e}^{-c x / d_{1}} S^{\prime}(x)=-\int_{x}^{\infty} \mathrm{e}^{-c y / d_{1}} \frac{\beta S(y) I(E)(y)}{d_{1}[S(y)+I(E)(y)+E(y)]} d y
$$

Hence $S$ is non-increasing. Since $I(x)$ is not trivial, the integral

$$
\int_{x}^{\infty} \mathrm{e}^{-c y / d_{1}} \frac{\beta S(y) I(E)(y)}{d_{1}[S(y)+I(E)(y)+E(y)]} d y
$$

cannot be identically 0 . Thus $S^{\prime}$ is not trivial and

$$
S(\infty)<S(-\infty)
$$

By L'Hopital's rule and

$$
I(x)=\frac{\alpha}{\rho_{1}}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-y)} E(y) d y+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-y)} E(y) d y\right)
$$

we obtain

$$
\lim _{x \rightarrow-\infty} I(x)=\lim _{x \rightarrow-\infty} \frac{\alpha}{\rho_{1}}\left(\frac{\mathrm{e}^{-\lambda_{1}^{-} x} E(x)}{-\lambda_{1}^{-} \mathrm{e}^{-\lambda_{1}^{-} x}}\right)+\lim _{x \rightarrow-\infty} \frac{\alpha}{\rho_{1}}\left(\frac{\mathrm{e}^{-\lambda_{1}^{+} x} E(x)}{\lambda_{1}^{+} \mathrm{e}^{-\lambda_{1}^{+} x}}\right)=\lim _{x \rightarrow-\infty} \frac{\alpha}{\gamma} E(x)=0 .
$$

Recall the integral representation of the first derivative

$$
\left(\Delta_{i}^{-1} h\right)^{\prime}(x)=\frac{\Lambda_{i}^{-}}{R_{i}} \int_{-\infty}^{x} \mathrm{e}^{\Lambda_{i}^{-}(x-y)} h(y) d y+\frac{\Lambda_{i}^{+}}{R_{i}} \int_{x}^{\infty} \mathrm{e}^{\Lambda_{i}^{+}(x-y)} h(y) d y
$$

where $h \in C_{-\mu, \mu}(\mathbb{R})$. By the definition of $F_{1}$ and L'Hopital's rule, we obtain

$$
\lim _{x \rightarrow-\infty} S^{\prime}(x)=\lim _{x \rightarrow-\infty} \frac{\Lambda_{1}^{-}}{R_{1}}\left(\frac{\mathrm{e}^{-\Lambda_{1}^{-} x} a_{1} S(x)}{-\Lambda_{1}^{-} \mathrm{e}^{-\Lambda_{1}^{-} x}}\right)+\lim _{x \rightarrow-\infty} \frac{\Lambda_{1}^{+}}{R_{1}}\left(\frac{\mathrm{e}^{-\Lambda_{1}^{+} x} a_{1} S(x)}{\Lambda_{1}^{+} \mathrm{e}^{-\Lambda_{1}^{+} x}}\right)=0
$$

Similarly, by the definition of $F_{2}$ and L'Hopital's rule,

$$
E^{\prime}(x) \rightarrow 0, \quad I^{\prime}(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow-\infty
$$

By (2.2)-(2.4), we obtain the limits of the second derivatives

$$
S^{\prime \prime}(x) \rightarrow 0, \quad E^{\prime \prime}(x) \rightarrow 0, \quad I^{\prime \prime}(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow-\infty .
$$

Next, we give the asymptotic behaviors of $S(x), E(x)$ and $I(x)$ as $x \rightarrow \infty$.
Similarly, by (3.5), we have

$$
\begin{equation*}
\int_{-\infty}^{\infty} I(x) d x=\frac{\alpha}{\gamma} \int_{-\infty}^{\infty} E(x) d x=\frac{1}{\gamma} \int_{-\infty}^{\infty} \frac{\beta S(x) I(E)(x)}{S(x)+I(E)(x)+E(x)} d x \tag{4.5}
\end{equation*}
$$

Since

$$
E^{\prime}(x)=\frac{\lambda_{2}^{-}}{\rho_{2}} \int_{-\infty}^{x} \mathrm{e}^{\lambda_{2}^{-}(x-y)} \frac{\beta S(y) I(E)(y)}{S(y)+I(E)(y)+E(y)} d y+\frac{\lambda_{2}^{+}}{\rho_{2}} \int_{x}^{\infty} \mathrm{e}^{\lambda_{2}^{+}(x-y)} \frac{\beta S(y) I(E)(y)}{S(y)+I(E)(y)+E(y)} d y
$$

we obtain

$$
\left|E^{\prime}(x)\right| \leqslant \frac{\beta}{d_{2}} \int_{-\infty}^{\infty} I(E)(x) d x
$$

We can see that

$$
E(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow \infty .
$$

Otherwise, since $\left|E^{\prime}\right|$ is bounded, we can choose a sequence $x_{i} \rightarrow \infty, \varepsilon>0$ and $\delta>0$, such that $E(x)>\varepsilon$ on ( $x_{i}-\delta, x_{i}+\delta$ ), which contradicts the integrability of $E$ on $\mathbb{R}$. Similarly,

$$
I(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow \infty
$$

Furthermore, we use the same methods dealing with $I^{\prime}(x)$ and $E^{\prime}(x)$ and obtain

$$
E^{\prime}(x) \rightarrow 0, \quad I^{\prime}(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow \infty
$$

From (2.2)-(2.4), we also have

$$
S^{\prime \prime}(x) \rightarrow 0, \quad E^{\prime \prime}(x) \rightarrow 0, \quad I^{\prime \prime}(x) \rightarrow 0, \quad \text { as } \quad x \rightarrow \infty
$$

Integrating (4.3) from $-\infty$ to $\infty$ yields

$$
\int_{-\infty}^{\infty} \frac{\beta S(x) I(E)(x)}{S(x)+I(E)(x)+E(x)} d x=c[S(-\infty)-S(\infty)]
$$

We want to prove that

$$
E(x) \leqslant S(-\infty)-S(\infty)
$$

for all $x \in \mathbb{R}$. Define

$$
\begin{equation*}
J(x):=E(x)+\frac{\alpha}{c} \int_{-\infty}^{x} E(y) d y+\frac{\alpha}{c} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{2}}(x-y)} E(y) d y \tag{4.6}
\end{equation*}
$$

By the property at infinity of $E(x)$ and L'Hopital's rule,

$$
\lim _{x \rightarrow-\infty} J(x)=0, \quad \lim _{x \rightarrow \infty} J(x)=\frac{\alpha}{c} \int_{-\infty}^{\infty} E(y) d y=S(-\infty)-S(\infty)
$$

Similarly, by differentiating (4.6), together with $E(x) \rightarrow 0$ as $x \rightarrow \pm \infty$, we obtain

$$
J^{\prime}(x)=E^{\prime}(x)+\frac{\alpha}{d_{2}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{2}}(x-y)} E(y) d y
$$

Hence,

$$
\lim _{x \rightarrow-\infty} J^{\prime}(x)=0, \quad \lim _{x \rightarrow \infty} J^{\prime}(x)=0
$$

from the above equality. We differentiate (4.6) twice, i.e.,

$$
J^{\prime \prime}(x)=E^{\prime \prime}(x)-\frac{\alpha}{d_{2}} E(x)+\frac{c \alpha}{d_{2}^{2}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{2}}(x-y)} E(y) d y
$$

and obtain

$$
-d_{2} J^{\prime \prime}+c J^{\prime}=-d_{2} E^{\prime \prime}+c E^{\prime}+\alpha E=\beta S I(E) /(S+I(E)+E) .
$$

We integrate the above equality from $x$ to $\infty$ and obtain

$$
\begin{equation*}
J^{\prime}(x)=\frac{1}{d_{2}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{2}}(x-y)} \frac{\beta S(y) I(E)(y)}{S(y)+I(E)(y)+E(y)} d y \geqslant 0 . \tag{4.7}
\end{equation*}
$$

We have

$$
J(\infty)=S(-\infty)-S(\infty)
$$

and from (4.7) we can see that $J(x)$ is non-decreasing and thus

$$
J(x) \leqslant S(-\infty)-S(\infty)
$$

for all $x \in \mathbb{R}$. Recall that $E(x) \leqslant J(x)$ by (4.6), so

$$
E(x) \leqslant S(-\infty)-S(\infty)
$$

for all $x \in \mathbb{R}$.
To study $I$, define

$$
H(x):=I(x)+\frac{\gamma}{c} \int_{-\infty}^{x} I(y) d y+\frac{\gamma}{c} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{3}}(x-y)} I(y) d y .
$$

Using the similar methods as in studying (4.6), we obtain

$$
\lim _{x \rightarrow-\infty} H(x)=0, \quad \lim _{x \rightarrow \infty} H(x)=\frac{\gamma}{c} \int_{-\infty}^{\infty} I(y) d y=S(-\infty)-S(\infty) .
$$

Differentiating $H(x)$ we obtain

$$
H^{\prime}(x)=I^{\prime}(x)+\frac{\gamma}{d_{3}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{3}}(x-y)} I(y) d y,
$$

and furthermore,

$$
\lim _{x \rightarrow-\infty} H^{\prime}(x)=0, \quad \lim _{x \rightarrow \infty} H^{\prime}(x)=0 .
$$

Differentiate $H(x)$ twice, i.e.,

$$
H^{\prime \prime}(x)=I^{\prime \prime}(x)-\frac{\gamma}{d_{3}} I(x)+\frac{c \gamma}{d_{3}^{2}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{\tau_{3}}(x-y)} I(y) d y,
$$

and thus

$$
-d_{3} H^{\prime \prime}+c H^{\prime}=-d_{3} I^{\prime \prime}+c I^{\prime}+\gamma I=\alpha E .
$$

From the above equality, we have

$$
H^{\prime}(x)=\frac{1}{d_{3}} \int_{x}^{\infty} \mathrm{e}^{\frac{c}{d_{3}}(x-y)} E(y) d y .
$$

Since $H(\infty)=S(-\infty)-S(\infty)$ and $H^{\prime}(x) \geqslant 0$,

$$
I(x) \leqslant H(x) \leqslant S(-\infty)-S(\infty)
$$

holds for all $x \in \mathbb{R}$. This completes the proof.

## 5 Non-existence

Theorem 5.1. If $\beta / \gamma \leqslant 1$, for any $c>0$, there is no non-trivial non-negative traveling wave solution satisfying the boundary conditions (2.1).
Proof. Recall (4.5), i.e.,

$$
\int_{-\infty}^{\infty} I(x) d x=\frac{1}{\gamma} \int_{-\infty}^{\infty} \frac{\beta S(x) I(E)(x)}{S(x)+I(E)(x)+E(x)} d x
$$

If $\beta \leqslant \gamma$ and $I(x)$ is a non-trivial and non-negative function, then

$$
\int_{-\infty}^{\infty} I(x) d x=\frac{\beta}{\gamma} \int_{-\infty}^{\infty} \frac{S(x) I(E)(x)}{S(x)+I(E)(x)+E(x)} d x<\frac{\beta}{\gamma} \int_{-\infty}^{\infty} I(x) d x \leqslant \int_{-\infty}^{\infty} I(x) d x
$$

We get a contradiction.
Theorem 5.2. If $\beta / \gamma>1$ and $0<c<c^{*}$, there is no non-negative and non-trivial traveling wave solution satisfying the boundary conditions (2.1).

Proof. Let $(S, E)$ be the solution of (2.2)-(2.3) satisfying the boundary conditions (2.1). Since

$$
\frac{\beta S}{S+I+E} \rightarrow \beta, \quad \alpha E(x) \rightarrow \gamma I(x)
$$

as $x \rightarrow-\infty$, there exists an $\bar{x}<0$ such that for $x<\bar{x}$,

$$
\beta S I /(S+I+E)-\alpha E>\delta E \geqslant 0,
$$

where $\delta:=\alpha(\beta-\gamma) /(2 \gamma)$. Applying the above inequality to (2.3), we obtain

$$
\begin{equation*}
c E^{\prime}-d_{2} E^{\prime \prime}>\delta E \geqslant 0 \tag{5.1}
\end{equation*}
$$

for $x<\bar{x}$. Since

$$
\begin{equation*}
E( \pm \infty)=0, \quad E^{\prime}( \pm \infty)=0, \quad E^{\prime \prime}( \pm \infty)=0 \tag{5.2}
\end{equation*}
$$

we can see that $c E^{\prime}-d_{2} E^{\prime \prime}$ is integrable at $-\infty$. Together with the Lebesgue dominated convergence theorem and (5.1), $E$ is also integrable at $-\infty$. We denote

$$
K(x):=\int_{-\infty}^{x} E(y) d y
$$

Integrating (5.1) yields

$$
\delta K(x) \leqslant c E(x)-d_{2} E^{\prime}(x)
$$

for $x<\bar{x}$. Integrate the above inequality again and we obtain

$$
\int_{-\infty}^{x} K(y) d y \leqslant \frac{c}{\delta} K(x)
$$

for all $x<\bar{x}$. We also notice that $K(x)$ is non-decreasing, hence

$$
\eta K(x-\eta) \leqslant \int_{x-\eta}^{x} K(y) d y \leqslant \frac{c}{\delta} K(x)
$$

for all $\eta>0$ and $x<\bar{x}$. By choosing $\eta>2 c / \delta$,

$$
K(x-\eta)<K(x) / 2
$$

for all $x<\bar{x}$. Denote $\mu_{0}:=\min \left\{(\ln 2) / \eta, \lambda_{1}^{+} / 2\right\}$ and

$$
L(x):=K(x) \mathrm{e}^{-\mu_{0} x}
$$

It holds that

$$
L(x-\eta)<L(x)
$$

for $x<\bar{x}$, which implies that $L(x)$ is bounded as $x \rightarrow-\infty$. (5.1) and (5.2) yield

$$
c E^{\prime}>d_{2} E^{\prime \prime}, \quad c E>d_{2} E^{\prime}, \quad c K>d_{2} E
$$

Hence, we conclude that

$$
E^{\prime \prime}(x) \mathrm{e}^{-\mu_{0} x}, \quad E^{\prime}(x) \mathrm{e}^{-\mu_{0} x} \quad \text { and } \quad E(x) \mathrm{e}^{-\mu_{0} x}
$$

are all bounded as $x \rightarrow-\infty$. Together with (5.2), they are uniformly bounded on $\mathbb{R}$. By (3.5),

$$
\lim _{x \rightarrow \pm \infty} E(x) / I(x)=\gamma / \alpha
$$

and we can see that $I(x) \mathrm{e}^{-\mu_{0} x}$ is also bounded on $\mathbb{R}$. Since $I /(S+I+E) \leqslant 1$ and $S(x)+I(x)+E(x) \rightarrow S_{-\infty}$ as $x \rightarrow-\infty$, both

$$
\frac{I(x) \mathrm{e}^{-\mu x}}{S(x)+I(x)+E(x)}
$$

and

$$
\frac{\left[I^{2}(x) / E(x)\right] \mathrm{e}^{-\mu x}}{S(x)+I(x)+E(x)}
$$

are uniformly bounded on $\mathbb{R}$ for $\mu \in\left(0, \mu_{0}\right]$. Since

$$
\frac{\beta S I}{S+I+E}=\beta I-\frac{\beta I^{2}}{S+I+E}-\frac{\beta I E}{S+I+E}
$$

together with (2.3) we obtain

$$
\begin{equation*}
-d_{2} E^{\prime \prime}+c E^{\prime}+\alpha E-\beta I=-\frac{\beta I^{2}}{S+I+E}-\frac{\beta I E}{S+I+E} \tag{5.3}
\end{equation*}
$$

Moreover, it holds that

$$
\begin{aligned}
\int_{-\infty}^{\infty} \mathrm{e}^{-\mu x} I(x) d x & =\int_{-\infty}^{\infty} \mathrm{e}^{-\mu x}[I(E)](x) d x \\
& =\frac{\alpha}{\rho_{1}} \int_{-\infty}^{\infty} \mathrm{e}^{-\mu x}\left(\int_{-\infty}^{x} \mathrm{e}^{\lambda_{1}^{-}(x-y)} E(y) d y+\int_{x}^{\infty} \mathrm{e}^{\lambda_{1}^{+}(x-y)} E(y) d y\right) d x \\
& =\frac{\alpha}{\rho_{1}} \int_{-\infty}^{\infty} \mathrm{e}^{-\mu x}\left(\int_{0}^{\infty} \mathrm{e}^{\lambda_{1}^{-} y} E(x-y) d y-\int_{0}^{\infty} \mathrm{e}^{\lambda_{1}^{+} y} E(x-y) d y\right) d x \\
& =\frac{\alpha}{\rho_{1}} \int_{-\infty}^{\infty} \mathrm{e}^{-\mu(x-y)} E(x-y)\left(\int_{0}^{\infty} \mathrm{e}^{\left(\lambda_{1}^{-}-\mu\right) y} d y-\int_{0}^{\infty} \mathrm{e}^{\left(\lambda_{1}^{+}-\mu\right) y} d y\right) d x \\
& =\frac{\alpha}{-d_{3} \mu^{2}+c \mu-\gamma} \int_{-\infty}^{\infty} \mathrm{e}^{-\mu x} E(x) d x
\end{aligned}
$$

We use the two-side Laplace transform on both sides of (5.3) and then obtain

$$
\begin{equation*}
f(\mu) \int_{-\infty}^{\infty} E(x) \mathrm{e}^{-\mu x} d x=-\beta \int_{-\infty}^{\infty}\left(\frac{I^{2}(x) / E(x)}{S(x)+I(x)+E(x)}+\frac{I(x)}{S(x)+I(x)+E(x)}\right) E(x) \mathrm{e}^{-\mu x} d x \tag{5.4}
\end{equation*}
$$

where

$$
f(\mu)=-d_{2} \mu^{2}+c \mu+\alpha-\frac{\alpha \beta}{-d_{3} \mu^{2}+c \mu+\gamma} .
$$

The integrals on both sides of the above equality are well-defined for any $\mu \in\left(0, \mu_{0}\right)$. By the assumption that $c<c^{*}, f(\mu)$ is always negative for all $\mu \in\left[0, \lambda_{1}^{+}\right.$. All the three integrals in (5.4) can be analytically continued to the interval $\left[0, \lambda_{1}^{+}\right)$. Otherwise, by the theory of convergence region of two-side Laplace transform (see [14, 16, 17]), the integral

$$
\int_{-\infty}^{\infty} E(x) \mathrm{e}^{-\mu x} d x
$$

has a singularity at $\mu=\mu^{*} \in\left(0, \lambda_{1}^{+}\right)$and is analytic for all $\mu \in\left(0, \mu^{*}\right)$. At the same time, we check the integral

$$
\begin{equation*}
\int_{-\infty}^{\infty}\left(\frac{I^{2}(x) / E(x)}{S(x)+I(x)+E(x)}+\frac{I(x)}{S(x)+I(x)+E(x)}\right) E(x) \mathrm{e}^{-\mu x} d x \tag{5.5}
\end{equation*}
$$

Notice

$$
\frac{I(x)}{S(x)+I(x)+E(x)} \mathrm{e}^{-\mu_{1} x}
$$

and

$$
\frac{I^{2}(x) / E(x)}{S(x)+I(x)+E(x)} \mathrm{e}^{-\mu_{1} x}
$$

are uniformly bounded for $\mu_{1}=\min \left\{\left(\lambda_{1}^{+}-\mu^{*}\right) / 2, \mu_{0}\right\}$, so the integral (5.5) is analytic for all $\mu<\mu^{*}+\mu_{1}$. We get a contradiction.

We rewrite (5.4) as

$$
\int_{-\infty}^{\infty} \mathrm{e}^{-\mu x} E(x)\left[f(\mu)+\frac{\beta I^{2}(x) / E(x)}{S(x)+I(x)+E(x)}+\frac{\beta I(x)}{S(x)+I(x)+E(x)}\right] d x=0
$$

This leads to a contradiction again in that

$$
f(\mu)+\frac{\beta I^{2}(x) / E(x)}{S(x)+I(x)+E(x)}+\frac{\beta I(x)}{S(x)+I(x)+E(x)} \rightarrow-\infty
$$

as $\mu \rightarrow \lambda_{1}^{+}-0$, while $\mathrm{e}^{-\mu x} E(x)>0$ for all $\mu \in\left(0, \lambda_{1}^{+}\right)$. Thus we conclude that if $R_{0}>1$ and $c<c^{*}$ there is no non-negative and non-trivial traveling wave solution satisfying the boundary conditions (2.1).

## 6 Discussion

Due to the significant epidemic meaning of our diffusive SEIR model, the speed of spatial spread of epidemics is an important problem in mathematical epidemiology. Aronson and Weinberger [2] have proved the coincidence of the minimal wave speed and the asymptotic speed of propagation for the Fisher's equation, where $c_{0}>0$ is the asymptotic speed if for any $c>c_{0}$ the solution tends to zero uniformly in the spatial-time region $\{(x, t):|x| \geqslant c t\}$, while for any $0<c<c_{0}$ the solution is bounded and away from zero uniformly in the region $\{(x, t):|x| \leqslant c t\}$ as $t \rightarrow \infty$. Aronson [1] also gave an analogous result for an SIR epidemic model with non-local reaction, which is called the Kendall model. This result implies that if you travel toward $+\infty$, then you escape from the epidemic region if your speed is larger than the minimal speed $c^{*}$, but if your speed is less than $c^{*}$, the infection eventually overtakes you.

Recently, the spreading speed of reaction-diffusion has been intensively studied by many researchers. Thieme and Zhao [12] generalized the concept of spreading speeds and monotone traveling waves to the non-linear integral equations and their results can be used to a large number of non-local reaction-diffusion population models. They showed the spreading speed coincides with the minimal wave speed. Despite these existing results, the relation between these two speeds of our diffusive SEIR model is still an open problem and it will be our successive work. Furthermore, as it is mentioned in [16], the non-locality of the reaction and time delay may increase or decrease the speed of traveling waves of a diffusive SIR model. We also get some analogous results for the corresponding diffusive SEIR model.

Acknowledgements This work was supported by National Natural Science Foundation of China (Grant No. 11371058) and the Fundamental Research Funds for the Central Universities. The authors are grateful to the referees for their valuable comments and suggestions which helped us improve the presentation of the paper.

## References

1 Aronson D G. The asymptotic speed of propagation of a simple epidemic. In: Nonlinear Diffusion. Research Notes in Mathematics, vol. 14. London: Pitman, 1977, 1-23

2 Aronson D G, Weinberger H F. Multidimensional nonlinear diffusion arising in population genetics. Adv Math, 1978, 30: 33-76
3 Brauer F, Castillo-Chávez C. Mathematical Models in Population Biology and Epidemiology. Texts in Applied Mathematics, vol. 40. New York: Springer, 2001
4 Cheng H, Yuan R. Traveling waves of a nonlocal dispersal Kermack-McKendrick epidemic model with delayed transmission. J Evol Equ, 2016, doi:10.1007/s00028-016-0362-2
5 Du Y, Lin Z. The diffusive competition model with a free boundary: Invasion of a superior or inferior competitor. Discrete Contin Dyn Syst Ser B, 2014, 19: 3105-3132
6 Du Y, Lou B. Spreading and vanishing in nonlinear diffusion problems with free boundaries. J Eur Math Soc, 2015, 17: 2673-2724
7 Hethcote H W, van den Driessche P. Some epidemiological models with nonlinear incidence. J Math Biol, 1991, 29: 271-287
8 Kermack W O, McKendrick A G. A contribution to the mathematical theory of epidemics. Proc R Soc Lond Ser A Math Phys Eng Sci, 1927, 115: 700-721
9 Li Y, Li W T, Yang F Y. Traveling waves for a nonlocal dispersal SIR model with delay and external supplies. Appl Math Comput, 2014, 247: 723-740
10 Lin G, Ruan S. Traveling wave solutions for delayed reaction-diffusion systems and applications to diffusive LotkaVolterra competition models with distributed delays. J Dynam Differential Equations, 2014, 26: 583-605
11 Rees E L. Graphical discussion of the roots of a quartic equation. Amer Math Monthly, 1922, 29: 51-55
12 Thieme H R, Zhao X Q. Asymptotic speeds of spread and traveling waves for integral equations and delayed reactiondiffusion models. J Differential Equations, 2003, 195: 430-470
13 Wang J B, Li W T, Yang F Y. Traveling waves in a nonlocal dispersal SIR model with nonlocal delayed transmission. Commun Nonlinear Sci Numer Simul, 2015, 27: 136-152
14 Wang X S, Wang H, Wu J. Traveling waves of diffusive predator-prey systems: Disease outbreak propagation. Discrete Contin Dyn Syst, 2012, 32: 3303-3324
15 Wang Z C, Li W T, Ruan S. Existence, uniqueness and stability of pyramidal traveling fronts in reaction-diffusion systems. Sci China Math, 2016, 59: 1869-1908
16 Wang Z C, Wu J. Travelling waves of a diffusive Kermack-McKendrick epidemic model with non-local delayed transmission. Proc R Soc Lond Ser A Math Phys Eng Sci, 2010, 466: 237-261
17 Widder D V. The Laplace Transform. Princeton: Princeton University Press, 1941
18 Wu J, Zou X. Traveling wave fronts of reaction-diffusion systems with delay. J Dynam Differential Equations, 2001, 13: 651-687
19 Yang F Y, Li W T, Wang Z C. Traveling waves in a nonlocal dispersal SIR epidemic model. Nonlinear Anal Real World Appl, 2015, 23: 129-147
20 Zhao X Q, Wang W. Fisher waves in an epidemic model. Discrete Contin Dyn Syst Ser B, 2004, 4: 1117-1128


[^0]:    * Corresponding author

