ERRATUM

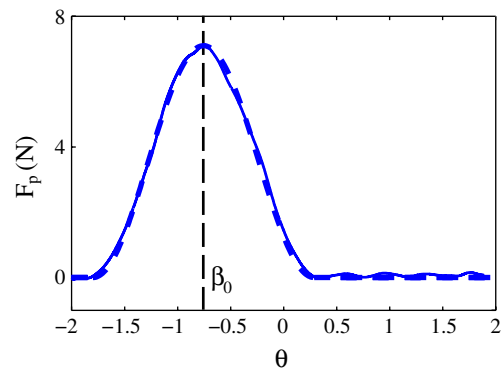# Erratum to: The Effect of Limb Kinematics on the Speed of a Legged Robot on Granular Media

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Erratum to: Experimental Mechanics
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In the above mentioned article, due to a systematic error measuring angular position, the penetration force during rotational intrusion, $F_p(\theta)$, was misreported in Fig. 4b. Correcting the error shifts the angle of peak force (β_0) from -0.5 to -0.75 and increases the maximum value of the force increases by 4% (see figure). Model calculations dependent on $F_p(\theta)$ change slightly with the correction (using $\beta_0 = -0.75$ and $k' = 65$ N/m) and remain qualitatively unchanged as do the conclusions of the paper.

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