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On multivariate orthogonal polynomials and elementary symmetric functions

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Abstract

We study families of multivariate orthogonal polynomials with respect to the symmetric weight function in d variables

$$B_{\gamma}(\mathbf{x}) = \prod_{i=1}^{d} \omega(x_i) \prod_{i < j} |x_i - x_j|^{2\gamma + 1}, \quad \mathbf{x} \in (a, b)^d,$$

for $\gamma > -1$, where $\omega(t)$ is an univariate weight function in $t \in (a, b)$ and $x = (x_1, x_2, \dots, x_d)$ with $x_i \in (a, b)$. Applying the change of variables x_i , $i = 1, 2, \dots, d$, into u_r , $r = 1, 2, \dots, d$, where u_r is the *r*-th elementary symmetric function, we obtain the domain region in terms of the discriminant of the polynomials having x_i , $i = 1, 2, \dots, d$, as its zeros and in terms of the corresponding Sturm sequence. Choosing the univariate weight function as the Hermite, Laguerre, and Jacobi weight functions, we obtain the representation in terms of the variables u_r for the partial differential operators such that the respective Hermite, Laguerre, and Jacobi generalized multivariate orthogonal polynomials are the eigenfunctions. Finally, we present explicitly the partial differential operators for Hermite, Laguerre, and Jacobi generalized polynomials, for d = 2 and d = 3 variables.

Keywords Multivariate orthogonal polynomials · Symmetric polynomials · Elementary symmetric functions

Dedicated to professor Claude Brezinski on the occasion of his 80th birthday.

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1 Introduction

In 1974 (see [8, 9]), Koornwinder considered the family of orthogonal polynomials $p_{n,k}^{\alpha,\beta,\gamma}(u,v)$, with $n \ge k \ge 0$, obtained by orthogonalization of the sequence $1, u, v, u^2, uv, v^2, u^3, u^2v, ...$ with respect to the weight function $(1 - u + v)^{\alpha}(1 + u + v)^{\beta}(u^2 - 4v)^{\gamma}$ for $\alpha, \beta, \gamma > -1, \alpha + \gamma + 3/2 > 0, \beta + \gamma + 3/2 > 0$, on the region bounded by the lines 1 - u + v = 0 and 1 + u + v = 0 and by the parabola $u^2 - 4v = 0$ (see Fig. 1). In the special case $\gamma = -1/2$, orthogonal polynomials $p_{n,k}^{\alpha,\beta,-1/2}(u, v)$ can be explicitly obtained by the identity

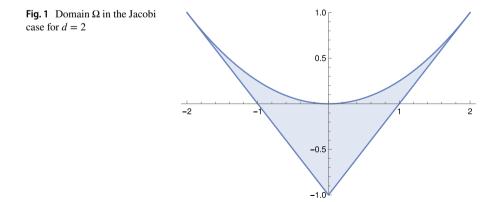
$$p_{n,k}^{\alpha,\beta,-1/2}(u,v) = P_n^{(\alpha,\beta)}(x)P_k^{(\alpha,\beta)}(y) + P_k^{(\alpha,\beta)}(x)P_n^{(\alpha,\beta)}(y)$$

and the change of variables u = x + y, v = xy, where $P_n^{(\alpha,\beta)}(x)$ are Jacobi polynomials in one variable. The author obtained two explicit linear partial differential operators $D_1^{\alpha,\beta,\gamma}$ and $D_2^{\alpha,\beta,\gamma}$ of order two and four, respectively, such that the polynomials $p_{n,k}^{\alpha,\beta,\gamma}(u,v)$ are their common eigenfunctions. In fact, $D_1^{\alpha,\beta,\gamma}$ and $D_2^{\alpha,\beta,\gamma}$ were the generators of the algebra of differential operators having the polynomials $p_{n,k}^{\alpha,\beta,\gamma}(u,v)$ as eigenfunctions. The polynomials $p_{n,k}^{\alpha,\beta,\gamma}(u,v)$ are not classical in the Krall and Sheffer sense [10] since the corresponding eigenvalues of $D_1^{\alpha,\beta,\gamma}$ depend on *n* and *k*.

In several variables, we find different extensions of Koorwinder's polynomials connected with symmetrical multivariate weight functions constructed from classical univariate weights. In fact, the so-called **generalized classical orthogonal polynomials** are multivariable polynomials which are orthogonal with respect to the weight functions

$$B_{\gamma}(\mathbf{x}) = \prod_{i=1}^{d} \omega(x_i) \prod_{i < j} |x_i - x_j|^{2\gamma + 1},$$

with $\omega(t)$ being one of the classical weight functions (Hermite, Laguerre, or Jacobi) on the real line.



The multivariable Hermite, Laguerre, and Jacobi families associated with the weight functions $B_{\gamma}(\mathbf{x})$ were introduced by Lassalle [11–13] and Macdonald [16] as a generalization of a previously known special case in which the parameter γ is being fixed at the value 0, [7]. Later, these multivariable generalizations of the classical Hermite, Laguerre, and Jacobi polynomials occur as the polynomial part of the eigenfunctions of certain Schrödinger operators for Calogero-Sutherland-type quantum systems [1]. In fact, if we denote by

$$L(p(t)) = \phi(t)p''(t) + \psi(t)p'(t)$$

the second-order differential operator having the classical orthogonal polynomials as eigenfunctions then the multivariable Hermite, Laguerre, and Jacobi are eigenfunctions of the differential operators

$$\mathcal{H}_{\gamma} = \sum_{i=1}^{d} \left(\phi(x_i) \partial_i^2 + \psi(x_i) \partial_i + (2\gamma + 1) \sum_{k \neq i} \frac{\phi(x_i)}{x_i - x_k} \partial_i \right).$$

Lassalle expressed the generalized classical orthogonal polynomials in terms of the basis of symmetric monomials

$$m_{\lambda}(x) = \sum_{\sigma \in \mathcal{S}_d(\lambda)} x_{\sigma(1)}^{\lambda_1} \cdots x_{\sigma(d)}^{\lambda_d}, \qquad (1.1)$$

with $\lambda \in \mathbb{Z}^d$ satisfying $\lambda_1 \ge \lambda_2 \ge ... \ge \lambda_d \ge 0$. Here the summation in (1.1) is over the orbit of λ with respect to the action of the symmetric group S_d which permutes the vector components $x_1, x_2, ..., x_d$ (see [11–13]).

Rather than study the eigenfunctions of \mathcal{H}_{γ} in terms of the monomial symmetric polynomials, in some previous studies (see [16]), it has been shown that it is convenient to change basis from the monomial symmetric polynomials to the Jack polynomials, that is, the unique (up to normalization) symmetric eigenfunctions of the operator

$$\mathcal{J}_{\alpha} = \sum_{i=1}^{d} \left(x_i^2 \partial_i^2 + \frac{2}{\alpha} \sum_{k \neq i} \frac{x_i^2}{x_i - x_k} \partial_i \right).$$

In this work, we will consider $\omega(t)$ a univariate weight function in $t \in (a, b)$. For $\gamma > -1$, we define a symmetric weight function in *d* variables on the hypercube $(a, b)^d$ as

$$B_{\gamma}(\mathbf{x}) = \prod_{i=1}^{d} \omega(x_i) \prod_{i < j} |x_i - x_j|^{2\gamma + 1}, \quad \mathbf{x} \in (a, b)^d.$$

where $\mathbf{x} = (x_1, x_2, \dots, x_d)$, with $x_i \in (a, b), i = 1, 2, \dots, d$. Next, we apply the change of variables

$$\mathbf{x} = (x_1, x_2, \dots, x_d) \mapsto \mathbf{u} = (u_1, u_2, \dots, u_d)$$

where u_r are the *r*-th elementary symmetric functions defined by

$$u_r = \sum_{1 \leqslant k_1 < k_2 < \cdots < k_r \leqslant d} x_{k_1} x_{k_2} \cdots x_{k_r}, \quad 1 \leqslant r \leqslant d.$$

In [2], the change of variables $x = (x_1, x_2, ..., x_d) \mapsto u = (u_1, u_2, ..., u_d)$ was considered to construct multivariate gaussian cubature formulae in the case $\gamma = \pm \frac{1}{2}$. This construction is based on the common zeroes of multivariate quasi-orthogonal polynomials, which turns out to be expressed in terms of Jacobi polynomials (see also [3]).

Our main goal is the study of multivariate orthogonal polynomials in the variable u associated with the weight function $W_{\gamma}(u)$ obtained from the change of variables $x \mapsto u$. Obviously, generalized classical orthogonal polynomials are included in our study.

To this end, in Section 2, some basic definitions will be introduced and some properties of the derivatives of elementary symmetric functions will be obtained.

In Section 3, we analyze the structure of the domain of the weight function $W_{\gamma}(u)$, that is, the image of the map $x \mapsto u$. Orthogonal polynomials with respect to $W_{\gamma}(u)$ are defined in Section 4.

Finally, in Section 5, generalized classical orthogonal polynomials are considered. Our main result states that, under the change of variables $x \mapsto u$, the differential operators $\mathcal{H}^H_{\gamma}, \mathcal{H}^L_{\gamma}$ and \mathcal{H}^J_{γ} can be represented as linear partial differential operators in the form

$$\sum_{r=1}^{d} \sum_{s=1}^{d} a_{rs}(\mathbf{u}) \frac{\partial^2}{\partial u_r \partial u_s} + \sum_{r=1}^{d} b_r(\mathbf{u}) \frac{\partial}{\partial u_r},$$

where $a_{rs}(u)$ for r, s = 1, ..., d are polynomials of degree 2 in u and $b_r(u)$ for r = 1, ..., d are polynomials of degree 1 in u. Those operators have the multivariate orthogonal polynomials with respect to $W_{\gamma}(u)$ as eigenfunctions. In particular, we explicitly give the representation of these operators in the cases d = 2 and d = 3.

2 Definitions and first properties

Let $d \ge 1$ denote the number of variables. If $\alpha = (\alpha_1, \alpha_2, ..., \alpha_d) \in \mathbb{N}_0^d$, $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$, is a *d*-tuple of non-negative integers α_i , we call α a multi-index which has degree $|\alpha| = \alpha_1 + \alpha_2 + \cdots + \alpha_d$. We order the multi-indexes by means of the **graded reverse lexicographical order**, that is, $\alpha < \beta$ if and only if $|\alpha| < |\beta|$, and in the case $|\alpha| = |\beta|$, the first entry of $\alpha - \beta$ different from zero is positive.

A multi-index $\lambda = (\lambda_1, \lambda_2, ..., \lambda_d) \in \mathbb{N}_0^d$ will be called a **partition** if $\lambda_1 \ge \lambda_2 \ge ... \ge \lambda_d \ge 0$.

Observe that for every multi-index $\mu = (\mu_1, \mu_2, ..., \mu_d)$ there exists a unique partition $\lambda = (\lambda_1, \lambda_2, ..., \lambda_d)$ satisfying

$$\mu_1 = \lambda_1 - \lambda_2, \mu_2 = \lambda_2 - \lambda_3, \dots, \mu_d = \lambda_d.$$

If α is a multi-index and $\mathbf{x} = (x_1, x_2, \dots, x_d) \in \mathbb{R}^d$, we denote by \mathbf{x}^{α} the monomial $x_1^{\alpha_1} x_2^{\alpha_2} \dots x_d^{\alpha_d}$ which has total degree $|\alpha|$. A polynomial *P* in *d* variables is a finite linear combination of monomials $P(\mathbf{x}) = \sum_{\alpha} c_{\alpha} \mathbf{x}^{\alpha}$. The total degree of *P* is defined as the highest degree of its monomials.

Following [14], the *r*-th elementary symmetric function u_r is the sum of all products of *r* different variables x_i , i.e.,

$$u_r = \sum_{1 \le k_1 < k_2 < \dots < k_r \le d} x_{k_1} x_{k_2} \cdots x_{k_r}, \quad 1 \le r \le d,$$
(2.1)

and $u_0 = 1$. The elementary symmetric functions u_r and r = 1, 2, ..., d are harmonic homogeneous polynomials of degree r and can be obtained from the generating polynomial of degree d on the variable t, P(t), defined by

$$P(t) := \prod_{i=1}^{d} (1 + x_i t) = \sum_{r=0}^{d} u_r t^r.$$
 (2.2)

For a given multivariate function f, we will denote by $\partial_k f$ the partial derivative of f with respect to de variable x_k . In this work, we are going to deal frequently with partial derivatives of the elementary symmetric functions. The following lemma provides some recursive and closed expressions for $\partial_k u_r$.

Lemma 2.1 For r = 1, 2, ... d, partial derivatives of the elementary symmetric functions satisfy

$$\partial_k u_r = u_{r-1} - x_k \partial_k u_{r-1}, \quad k = 1, 2, \dots d,$$
 (2.3)

$$\partial_k u_r = \sum_{i=0}^{r-1} (-1)^i x_k^i u_{r-1-i}, \quad k = 1, 2, \dots d,$$
(2.4)

$$\partial_i \partial_k u_r = -\frac{\partial_i u_r - \partial_k u_r}{x_i - x_k}, \quad k \neq i, \quad k, i = 1, 2, \dots d.$$
(2.5)

Proof Taking partial derivatives in (2.2), we get

$$\partial_k P(t) := t \prod_{\substack{j=1\\ j \neq k}}^d (1+x_j t) = \sum_{i=0}^d \partial_k u_i t^i.$$

Next, multiply by $(1 + x_k t)$ in the above equality to obtain

$$(1+x_kt)\partial_k P(t) := t \prod_{j=1}^d (1+x_jt) = (1+x_kt) \sum_{r=0}^d \partial_k u_r t^r,$$

and (2.3) follows equating coefficients in both sides of the last equality. Next, (2.4) is obtained iterating (2.3).

Finally, taking partial derivatives in (2.3), for $k \neq i$, we get

$$\partial_k \partial_i u_{r+1} = \partial_k u_r - x_i \partial_k \partial_i u_r,$$

changing the role of k and i we obtain

$$\partial_i \partial_k u_{r+1} = \partial_i u_r - x_k \partial_i \partial_k u_r,$$

and therefore, (2.5) follows.

3 The domain

Given a univariate weight function $\omega(t)$ on $t \in (a, b)$ (where $a = -\infty$ and $b = \infty$ are allowed) consider the variable $\mathbf{x} = (x_1, x_2, \dots, x_d)$, with $x_i \in (a, b)$. For $\gamma > -1$, we define a weight function in *d* variables on the hypercube $(a, b)^d$ as

$$B_{\gamma}(\mathbf{x}) = \prod_{i=1}^{d} \omega(x_i) \prod_{i < j} |x_i - x_j|^{2\gamma + 1}, \quad \mathbf{x} \in (a, b)^d.$$
(3.1)

Since B_{γ} is obviously symmetric in the variables x_1, x_2, \dots, x_d , it suffices to consider its restriction on the domain Δ given by

 $\Delta = \{ x : a < x_1 < x_2 < \dots < x_d < b \}.$

Let E(t) be the monic polynomial of degree d on the variable t, having $x_i, i = 1, 2, ..., d$ as its roots, From (2.2), E(t) satisfies

$$E(t) := \prod_{i=1}^{d} (t - x_i) = \sum_{r=0}^{d} (-1)^r u_r t^{d-r}.$$
(3.2)

Let us consider the mapping

$$\mathbf{x} = (x_1, x_2, \dots, x_d) \mapsto \mathbf{u} = (u_1, u_2, \dots, u_d)$$

and the corresponding Jacobian matrix

$$T = \left(\partial_k u_r\right)_{1 \le k, r \le d}.$$

Using (2.4) and subtracting suitable combinations of columns in |T|, we get

$$V := |T| = \left| \sum_{i=0}^{r-1} (-1)^{i} x_{k}^{i} u_{r-1-i} \right|_{1 \le k, r \le d}$$

= $\left| (-1)^{i-1} x_{k}^{i-1} \right|_{1 \le i, k \le d}$
= $\prod_{1 \le i < k \le d} (x_{i} - x_{k}),$ (3.3)

the Vandermonde determinant. Thus, the determinant of the matrix TT^{t} can be given as

$$D(\mathbf{u}) := V^2 = \det(TT^t) = \prod_{1 \le i < k \le d} (x_i - x_k)^2.$$

It turns out that D(u) coincides with the **discriminant** (see [17, p. 23]) of the polynomial E(t). In this way, D(u) can be expressed in terms of the elementary symmetric functions since the discriminant can be obtained from the **resultant** (see [17, section 1.3.1]) of *E* and its derivative *E'* in the following way:

$$D(\mathbf{u}) = (-1)^{\frac{d(d-1)}{2}} R(E, E').$$

with

$$R(E, E') = \begin{vmatrix} a_0 & a_1 & \dots & a_d \\ a_0 & a_1 & \dots & a_d \\ & \ddots & \ddots & & \ddots \\ & & a_0 & a_1 & \dots & a_d \\ b_0 & b_1 & \dots & b_{d-1} \\ & & \ddots & & \ddots \\ & & & b_0 & b_1 & \dots & b_{d-1} \end{vmatrix}$$

where $a_i = (-1)^i u_i$ for i = 0, ..., d, and $b_i = (-1)^i (d - i) u_i$ for i = 0, ..., d - 1.

As it is well known, the existence of *d* different roots of the polynomial E(t) as defined in (3.2) (x_i for i = 1, ..., d) is equivalent to the positivity of D(u), the discriminant of E(t). Moreover, that all these different roots are contained in the interval (*a*, *b*) can be characterized in terms of the corresponding **Sturm sequence** (see [17, p. 30]). Consider the polynomials $p_0(t) = E(t)$ and $p_1(t) = E'(t)$ and let us construct a sequence { $p_k(t)$ }^{*d*}_{*k*=0} with the help of Euclid's algorithm to seek the greatest common divisor of *E* and *E'*

$$p_{0}(t) = E(t),$$

$$p_{1}(t) = E'(t),$$
...
$$p_{k-1}(t) = q_{k}(t)p_{k}(t) - m_{k}p_{k+1}(t),$$
...
$$p_{d-1}(t) = q_{d}(t)p_{d}(t),$$

where m_k is a positive constant for k = 1, ..., d - 1.

Since the roots of E(t) are simple, $p_d(t)$ is a nonzero constant. Sturm's theorem states that if v(t) is the number of sign changes in the sequence

$$\{p_0(t), p_1(t), \dots, p_d(t)\},\$$

then the number of roots of $p_0(t)$ (without taking multiplicities into account) confined between *a* and *b* is equal to v(a) - v(b). If all the roots of E(t) satisfy $a < x_1 < x_2 < \cdots < x_d < b$ then, according to Sturm's theorem the sequence $\{p_0(b), p_1(b), \dots, p_d(b)\}$ has no sign changes and $\{p_0(a), p_1(a), \dots, p_d(a)\}$ has exactly *d* sign changes.

In [4], explicit expressions for the polynomials in a Sturm sequence were provided. These explicit representations were given in terms of the *d* different roots of the first polynomial in the sequence $p_0(t)$ (x_i for i = 1, ..., d in our case). In particular, the author shows that the constant value of $p_d(t)$ coincides with the discriminant of $p_0(t)$ up to a positive multiplicative factor. Therefore, the condition D(u) > 0 is equivalent to $p_d(t) > 0$.

Consequently, the following result holds.

Proposition 3.1 The region

$$\Omega = \{ u : D(u) > 0, p_k(b) > 0, (-1)^{d-k} p_k(a) > 0, k = 0, 1, \dots, d-1 \},\$$

is the image of Δ under the mapping $\mathbf{x} = (x_1, x_2, \dots, x_d) \mapsto \mathbf{u} = (u_1, u_2, \dots, u_d)$ defined by (2.1).

As a consequence, the orthogonality measure and its support in terms of the coordinates u_1, \ldots, u_d can be obtained explicitly using the determinant R(E, E') combined with a simple algorithm.

3.1 The case *d* = 2

Let ω be a weight function defined on (a, b). For $\gamma > -1$, let us define a weight function of two variables,

$$B_{\gamma}(x_1, x_2) := \omega(x_1)\omega(x_2)|x_1 - x_2|^{2\gamma+1},$$

defined on the domain Δ given by

$$\Delta := \{ (x_1, x_2) : a < x_1 < x_2 < b \}.$$

Let us consider the mapping $x \mapsto u$ defined by

$$u_1 = x_1 + x_2, \quad u_2 = x_1 x_2.$$

Then, $E(t) = t^2 - u_1 t + u_2$ and the Jacobian of the change of variables is $|x_1 - x_2|$. Expressed in terms of the variable u, the discriminant of the polynomial E(t) is

$$D(\mathbf{u}) = - \begin{vmatrix} 1 & -u_1 & u_2 \\ 2 & -u_1 & 0 \\ 0 & 2 & -u_1 \end{vmatrix} = u_1^2 - 4u_2.$$

And the Sturm sequence reads

$$p_0(t) = t^2 - u_1 t + u_2,$$

$$p_1(t) = 2t - u_1$$

$$p_2(t) = \frac{1}{4}(u_1^2 - 4u_2).$$

In the **Jacobi** case, we have (a, b) = (-1, 1) and $\omega(t) = (1 - t)^{\alpha}(1 + t)^{\beta}$, with $\alpha > -1, \beta > -1$. In fact, this is the case originally considered by Koornwinder (see [8]). Then, using Proposition 3.1, the mapping $x \mapsto u$ is a bijection between Δ and the domain Ω given by

$$\Omega := \{(u_1, u_2) : 1 + u_1 + u_2 > 0, 1 - u_1 + u_2 > 0, 2 > u_1 > -2, u_1^2 > 4u_2\}$$

which is depicted in Fig. 1.

In the **Laguerre** case, we have $(a, b) = (0, +\infty)$ and $\omega(t) = t^{\alpha}e^{-t}$, with $\alpha > -1$. Therefore, using again Proposition 3.1, the domain Ω is given by

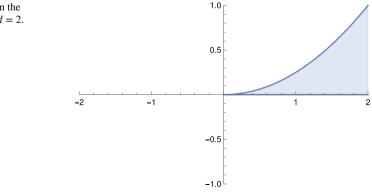
$$\Omega := \{ (u_1, u_2) : u_1 > 0, u_2 > 0, u_1^2 > 4u_2 \},\$$

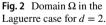
the region described in Fig. 2.

In the **Hermite** case, we have $(a, b) = (-\infty, +\infty)$ and $\omega(t) = e^{-t^2}$. The domain Ω is

$$\Omega := \{ (u_1, u_2) : u_1^2 > 4u_2 \}$$

as we show in Fig. 3.





3.2 The case *d* = 3

For d = 3, we set $x = (x_1, x_2, x_3)$ and $u = (u_1, u_2, u_3)$, with $u_1 = x_1 + x_2 + x_3$,

$$u_2 = x_1 x_2 + x_1 x_3 + x_2 x_3,$$

$$u_3 = x_1 x_2 x_3.$$

Then, $E(t) = t^3 - u_1t^2 + u_2t - u_3$ and the discriminant D(u) can be expressed in terms of the elementary symmetric functions

$$D(\mathbf{u}) = - \begin{vmatrix} 1 & -u_1 & u_2 & -u_3 & 0\\ 0 & 1 & -u_1 & u_2 & -u_3\\ 3 & -2u_1 & u_2 & 0 & 0\\ 0 & 3 & -2u_1 & u_2 & 0\\ 0 & 0 & 3 & -2u_1 & u_2 \end{vmatrix}$$
$$= u_1^2 u_2^2 - 4u_1^3 u_3 - 4u_2^2 - 27u_3^2 + 18u_1 u_2 u_3.$$

The Sturm sequence reads

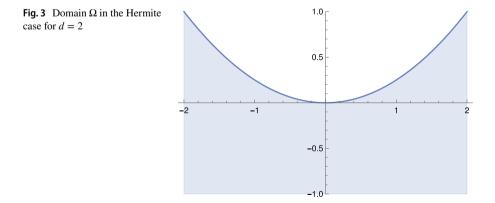
$$p_{0}(t) = t^{3} - u_{1}t^{2} + u_{2}t - u_{3},$$

$$p_{1}(t) = 3t^{2} - 2u_{1}t + u_{2}$$

$$p_{2}(t) = \frac{1}{9} \left((2u_{1}^{2} - 6u_{2})t - u_{1}u_{2} + 9u_{3} \right)$$

$$p_{3}(t) = \frac{9}{4 \left(u_{1}^{2} - 3u_{2} \right)^{2}} \left(u_{1}^{2}u_{2}^{2} - 4u_{1}^{3}u_{3} - 4u_{2}^{2} - 27u_{3}^{2} + 18u_{1}u_{2}u_{3} \right).$$

And finally, the region Ω for d = 3 can be described by the following inequalities

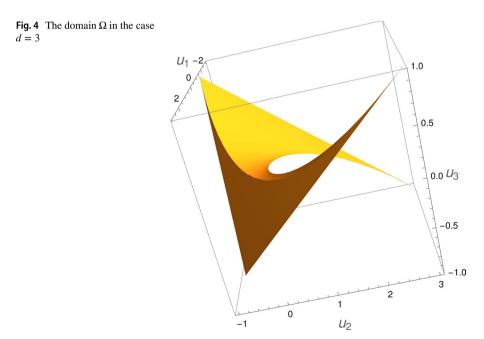


$$\begin{split} D(\mathbf{u}) &= u_1^2 u_2^2 - 4u_1^3 u_3 - 4u_2^3 - 27u_3^2 + 18u_1 u_2 u_3 > 0, \\ p_0(1) &= 1 - u_1 + u_2 - u_3 > 0, \\ -p_0(-1) &= 1 + u_1 + u_2 + u_3 > 0, \\ p_1(1) &= 3 - 2u_1 + u_2 > 0, \\ p_1(-1) &= 3 + 2u_1 + u_2 > 0, \\ p_2(1) &= 2u_1^2 - 6u_2 - u_1 u_2 + 9u_3 > 0, \\ -p_2(-1) &= 2u_1^2 - 6u_2 + u_1 u_2 - 9u_3 > 0. \end{split}$$

The region Ω is depicted in Fig. 4. This picture has been obtained from the parametric representation of the images under the map defined by (2.1) of the four triangular faces of the domain Δ given by

$$\Delta = \{ \mathbf{x} : -1 < x_1 < x_2 < x_3 < 1 \}.$$

 Ω is a solid limited by two flat faces and two curved faces. The first thing we have to notice is that Ω is invariant under the change of variables $(u_1, u_2, u_3) \rightarrow (-u_1, u_2, -u_3)$. In the image, the brown face is part of the plane $p_0(1) = 0$. There is another symmetrical flat face contained in the plane $-p_0(-1) = 0$. The two flat faces intersect in the line segment from A = (1, -1, -1) to B = (-1, -1, 1). The other line segment bounding the brown region (which is the intersection of the planes $p_0(1) = 0$ and $p_1(1) = 0$) is the line segment from A = (1, -1, -1) to C = (3, 3, 1). The third boundary part of the brown region is the part from *B* to *C* of a parabola touching at the endpoints *A* and *C* of the boundary



193

Deringer

line segments. The orange curved faces are the part of the quartic surface D(u) = 0 which is bounded by the line segments *AC* and *BD* (where the surface touches the planes $p_0(1) = 0$ and $-p_0(-1) = 0$, respectively), and by the parabola segments *CB* (where the surface intersects the plane $p_0(1) = 0$) and *DA* (where the surface intersects the plane $-p_0(-1) = 0$).

Figure 5 shows the projection of Ω on the u_1u_3 plane. Notice the two triangles, sharing one edge, and each having one parabolic side, namely, part of the parabolas $u_3 = \frac{1}{4}(u_1 - 1)^2$ and $u_3 = -\frac{1}{4}(u_1 + 1)^2$.

4 Orthogonal polynomials

Under the mapping defined by (2.1), the weight function B_{γ} , given in (3.1), becomes a weight function defined on the domain Ω by

$$W_{\gamma}(\mathbf{u}) = \prod_{i=1}^{d} \omega(x_i) D(\mathbf{u})^{\gamma}, \quad \mathbf{u} \in \Omega.$$
(4.1)

Now, it is possible to define the polynomials orthogonal with respect to $W_{\gamma}(u)$ on Ω .

Proposition 4.1 Define monic polynomials $P^{(\gamma)}_{\mu}(\mathbf{u})$ under the graded reverse lexicographic order \prec ,

$$P^{(\gamma)}_{\mu}(\mathbf{u}) = \mathbf{u}^{\mu} + \sum_{\alpha \prec \mu} \mathbf{u}^{\alpha}$$
(4.2)

that satisfy the orthogonality condition

$$\int_{\Omega} P^{(\gamma)}_{\mu}(\mathbf{u})\mathbf{u}^{\alpha}W_{\gamma}(\mathbf{u})d\mathbf{u} = 0$$

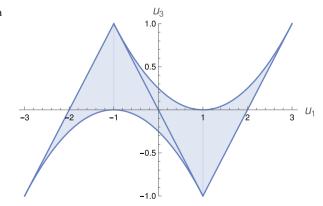


Fig. 5 The projection of domain Ω on the u_1u_3 plane

for $\alpha \prec \mu$, then these polynomials are uniquely determined and are mutually orthogonal with respect to $W_{\nu}(u)$.

Proof Since the graded reverse lexicographic order \prec is a total order, applying the Gram–Schmidt orthogonalization process to the monomials so ordered, the uniqueness follows from the fact that $P_{\mu}^{(\gamma)}(u)$ has leading coefficient 1.

In the cases $\gamma = \pm 1/2$, a family of orthogonal polynomials in the variable u can be given explicitly in terms of orthogonal polynomials of one variable (see [2] and [3, p.155]).

Proposition 4.2 Let $\{p_k\}_{k\geq 0}$ be the sequence of monic orthogonal polynomials with respect to w on (a, b). For $\gamma = -1/2$, $n \in \mathbb{N}_0$, and $\mu = (\mu_1, \mu_2, \dots, \mu_d)$ satisfying $0 \leq \mu_1 \leq \mu_2 \leq \dots \leq \mu_d = n$, we define

$$P_{\mu}^{(-1/2)}(\mathbf{u}) = \sum_{\sigma \in \mathcal{S}_d} p_{\mu_1}(x_{\sigma(1)}) p_{\mu_2}(x_{\sigma(2)}) \cdots p_{\mu_d}(x_{\sigma(d)})$$
(4.3)

where x and u are related by (2.1), and the sum in the right-hand side of (4.3) runs over all distinct permutations σ in the symmetric group S_d . Then, $P_{\mu}^{(-1/2)}(u)$ is an orthogonal polynomial of degree n in the variable u.

For $\gamma = 1/2$, $n \in \mathbb{N}_0$, and $\mu = (\mu_1, \mu_2, ..., \mu_d)$ satisfying $0 \le \mu_1 < \mu_2 < ... < \mu_d = n + d - 1$, we define

$$P_{\mu}^{(1/2)}(\mathbf{u}) = \frac{1}{V} \begin{vmatrix} p_{\mu_1}(x_1) & p_{\mu_1}(x_2) & \cdots & p_{\mu_1}(x_d) \\ p_{\mu_2}(x_1) & p_{\mu_2}(x_2) & \cdots & p_{\mu_2}(x_d) \\ \vdots & \vdots & \vdots \\ p_{\mu_d}(x_1) & p_{\mu_d}(x_2) & \cdots & p_{\mu_d}(x_d) \end{vmatrix},$$

where x and u are related by (2.1). Then, $P_{\mu}^{(1/2)}(u)$ is an orthogonal polynomial of degree n in the variable u.

5 Generalized classical orthogonal polynomials

In this section, multivariable orthogonal polynomials are considered associated with the weight functions

$$\begin{split} B^{H}_{\gamma}(\mathbf{x}) &= \prod_{i=1}^{d} e^{-x_{i}^{2}} \prod_{i < j} |x_{i} - x_{j}|^{2\gamma + 1}, \quad \mathbf{x} \in \mathbb{R}^{d}, \\ B^{L}_{\gamma}(\mathbf{x}) &= \prod_{i=1}^{d} x_{i}^{\alpha} e^{-x_{i}} \prod_{i < j} |x_{i} - x_{j}|^{2\gamma + 1}, \quad \mathbf{x} \in (0, +\infty)^{d}, \\ B^{J}_{\gamma}(\mathbf{x}) &= \prod_{i=1}^{d} (1 - x_{i})^{\alpha} (1 + x_{i})^{\beta} \prod_{i < j} |x_{i} - x_{j}|^{2\gamma + 1}, \quad \mathbf{x} \in (-1, 1)^{d}, \end{split}$$

with $\alpha, \beta, \gamma > -1$.

Under the change of variables $x \mapsto u$ defined by (2.1) the corresponding weight functions $W_{\nu}(\mathbf{u})$, as defined in (4.1), are given by

$$\begin{split} W_{\gamma}^{H}(\mathbf{u}) &= e^{-u_{1}^{2}+2u_{2}}D(\mathbf{u})^{\gamma}, \\ W_{\gamma}^{L}(\mathbf{x}) &= u_{d}^{\alpha}e^{-u_{1}}D(\mathbf{u})^{\gamma} \\ W_{\gamma}^{J}(\mathbf{x}) &= (1-u_{1}+u_{2}+\ldots+(-1)^{d}u_{d})^{\alpha}(1+u_{1}+u_{2}+\ldots+u_{d})^{\beta}D(\mathbf{u})^{\gamma}, \end{split}$$

with $\alpha, \beta, \gamma > -1$.

The multivariable Hermite, Laguerre, and Jacobi families associated with the weight functions $B_{\gamma}^{H}(\mathbf{x}), B_{\gamma}^{L}(\mathbf{x})$, and $B_{\gamma}^{H}(\mathbf{x})$ (see [1, (2.1)]), respectively, are eigenfunctions of the differential operators

$$\begin{aligned} \mathcal{H}_{\gamma}^{H} &= \sum_{i=1}^{d} \left(\partial_{i}^{2} - 2x_{i}\partial_{i} + (2\gamma + 1)\sum_{k \neq i} \frac{1}{x_{i} - x_{k}} \partial_{i} \right), \\ \mathcal{H}_{\gamma}^{L} &= \sum_{i=1}^{d} \left(x_{i}\partial_{i}^{2} + (\alpha + 1 - x_{i})\partial_{i} + (2\gamma + 1)\sum_{k \neq i} \frac{x_{i}}{x_{i} - x_{k}} \partial_{i} \right), \\ \mathcal{H}_{\gamma}^{J} &= \sum_{i=1}^{d} \left((1 - x_{i}^{2})\partial_{i}^{2} + (\beta - \alpha - (\alpha + \beta + 2)x_{i})\partial_{i} + (2\gamma + 1)\sum_{k \neq i} \frac{1 - x_{i}^{2}}{x_{i} - x_{k}} \partial_{i} \right), \end{aligned}$$

with $\alpha, \beta, \gamma > -1$.

We are going to obtain the representation of the differential operators $\mathcal{H}_{\gamma}^{H}, \mathcal{H}_{\gamma}^{L}$ and \mathcal{H}^{J}_{γ} , under the change of variables $x \mapsto u$. For h = 0, 1, 2, let us define the operators

$$\begin{split} \mathcal{D}_h &= \sum_{i=1}^d x_i^h \partial_i^2, \\ \mathcal{E}_h &= \sum_{i=1}^d x_i^h \partial_i, \\ \mathcal{F}_h &= \sum_{i=1}^d \sum_{k \neq i} \frac{x_i^h}{x_i - x_k} \partial_i \end{split}$$

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then

$$\begin{split} \mathcal{H}^{H}_{\gamma} = &\mathcal{D}_{0} - 2\mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{0}, \\ \mathcal{H}^{L}_{\gamma} = &\mathcal{D}_{1} + (\alpha + 1)\mathcal{E}_{0} - \mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{1}, \\ \mathcal{H}^{J}_{\gamma} = &\mathcal{D}_{0} - \mathcal{D}_{2} + (\beta - \alpha)\mathcal{E}_{0} - (\alpha + \beta + 2)\mathcal{E}_{1} + (2\gamma + 1)(\mathcal{F}_{0} - \mathcal{F}_{2}). \end{split}$$

Under the change of variables $x \mapsto u$, we get

$$\partial_i = \sum_{r=1}^d \partial_i u_r \frac{\partial}{\partial u_r},\tag{5.1}$$

and since $\partial_i^2 u_r = 0$ we obtain

$$\partial_i^2 = \sum_{r=1}^d \sum_{s=1}^d \partial_i u_r \partial_i u_s \frac{\partial^2}{\partial u_r \partial u_s},$$

Proposition 5.1 *The operator* \mathcal{E}_h *satisfies*

$$\mathcal{E}_0 = \sum_{r=1}^d (d-r+1)u_{r-1}\frac{\partial}{\partial u_r},\tag{5.2}$$

$$\mathcal{E}_1 = \sum_{r=1}^d r u_r \frac{\partial}{\partial u_r}.$$
(5.3)

Proof From (5.1), we have

$$\mathcal{E}_h = \sum_{i=1}^d x_i^h \partial_i = \sum_{r=1}^d \left(\sum_{i=1}^d x_i^h \partial_i u_r \right) \frac{\partial}{\partial u_r}.$$

For h = 0, using (2.3) and Euler's identity for homogeneous polynomials, we get

$$\sum_{i=1}^{d} \partial_{i} u_{r} = \sum_{i=1}^{d} u_{r-1} - \sum_{i=1}^{d} x_{i} \partial_{i} u_{r-1} = (d-r+1)u_{r-1},$$

which gives (5.2). Identity (5.3) follows in the same way, since for h = 1 we get

$$\sum_{i=1}^d x_i \partial_i u_r = r u_r.$$

Proposition 5.2 *The operator* \mathcal{D}_h *can be represented as*

$$\mathcal{D}_h = \sum_{i=1}^d x_i^h \partial_i^2 = \sum_{r=1}^d \sum_{s=1}^d a_{rs}^h(\mathbf{u}) \frac{\partial^2}{\partial u_r \partial u_s}.$$

197

where the coefficients

$$a_{rs}^{h}(\mathbf{u}) = \sum_{i=1}^{d} x_{i}^{h} \partial_{i} u_{r} \partial_{i} u_{s},$$

satisfy

$$a_{rs}^{0}(\mathbf{u}) = (d-s+1)u_{r-1}u_{s-1} - (d-r+2)u_{r-2}u_s + a_{r-1\,s+1}^{0}(\mathbf{u}),$$
(5.4)

$$a_{rs}^{0}(\mathbf{u}) = (d-s+1)u_{r-1}u_{s-1} + \sum_{j=2}^{r} (r-s-2j+2)u_{r-j}u_{s+j-2},$$
(5.5)

$$a_{rs}^{1}(\mathbf{u}) = (d-s+1)u_{r}u_{s-1} - a_{r+1s}^{0}(\mathbf{u}),$$
(5.6)

$$a_{rs}^{2}(\mathbf{u}) = (-d + r + s)u_{r}u_{s} + a_{r+1\,s+1}^{0}(\mathbf{u}),$$
(5.7)

taking into account that $a_{rs}^{h}(\mathbf{u}) = 0$, for $r \leq 0$, $s \leq 0$, r > d, or s > d. Obviously, we have $a_{rs}^{h}(\mathbf{u}) = a_{sr}^{h}(\mathbf{u})$ so we may assume that $r \leq s$.

Proof For h = 0, using (2.3) and (5.2), we deduce

$$\begin{aligned} a_{rs}^{0}(\mathbf{u}) &= \sum_{i=1}^{d} \partial_{i} u_{r} \partial_{i} u_{s} = \sum_{i=1}^{d} (u_{r-1} - x_{i} \partial_{i} u_{r-1}) \partial_{i} u_{s} \\ &= (d-s+1)u_{r-1}u_{s-1} - \sum_{i=1}^{d} \partial_{i} u_{r-1} x_{i} \partial_{i} u_{s} \\ &= (d-s+1)u_{r-1}u_{s-1} - \sum_{i=1}^{d} \partial_{i} u_{r-1} (u_{s} - \partial_{i} u_{s+1}) \\ &= (d-s+1)u_{r-1}u_{s-1} - (d-r+2)u_{r-2}u_{s} + \sum_{i=1}^{d} \partial_{i} u_{r-1} \partial_{i} u_{s+1}, \end{aligned}$$

and the recurrence formula (5.4) follows. Expression (5.5) can be obtained iterating (5.4).

For h = 1, from (2.3) and (5.2), we obtain

$$a_{rs}^{1}(\mathbf{u}) = \sum_{i=1}^{d} x_{i} \partial_{i} u_{r} \partial_{i} u_{s} = \sum_{i=1}^{d} (u_{r} - \partial_{i} u_{r+1}) \partial_{i} u_{s}$$
$$= (d - s + 1) u_{r} u_{s-1} - \sum_{i=1}^{d} \partial_{i} u_{r+1} \partial_{i} u_{s}.$$

Hence, (5.6) follows.

For h = 2, (5.7) can be obtained in the same way

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$$a_{rs}^{2}(\mathbf{u}) = \sum_{i=1}^{d} x_{i} \partial_{i} u_{r} x_{i} \partial_{i} u_{s} = \sum_{i=1}^{d} (u_{r} - \partial_{i} u_{r+1})(u_{s} - \partial_{i} u_{s+1})$$

= $du_{r} u_{s} - (d - s)u_{r} u_{s} - (d - r)u_{r} u_{s} + a_{r+1\,s+1}^{0}(\mathbf{u}).$

To obtain the representation of the operator \mathcal{F}_h , let us consider the Vandermonde determinant V defined in (3.3). One can see that

$$\frac{1}{V}\partial_i V = \sum_{\substack{k=1\\k\neq i}}^d \frac{1}{x_i - x_k}$$

and therefore

$$\frac{1}{V}\sum_{i=1}^{d}\partial_i V = \sum_{i=1}^{d}\sum_{\substack{k=1\\k\neq i}}^{d}\frac{1}{x_i - x_k} = 0,$$
(5.8)

since every element $1/(x_i - x_k)$ in the above sum appears twice with opposite sign.

On the other hand, since V is an homogeneous symmetric polynomial of total degree d(d-1)/2, again Euler's identity for homogeneous polynomials gives

$$\frac{1}{V}\sum_{i=1}^{d} x_i \partial_i V = \sum_{i=1}^{d} \sum_{\substack{k=1\\k\neq i}}^{d} \frac{x_i}{x_i - x_k} = \frac{d(d-1)}{2} = \binom{d}{2}.$$
(5.9)

Lemma 5.3 *For* r = 1, 2, ..., d, we have

$$\frac{1}{V}\sum_{i=1}^{d}\partial_i V \partial_i u_r = -\binom{d+2-r}{2}u_{r-2}.$$

Proof Using (2.5) and $\partial_{ii}^2 u_r = 0$ for i = 1, 2, ..., d, we get

$$\frac{1}{V}\sum_{i=1}^{d}\partial_i V\partial_i u_r = \sum_{i=1}^{d}\sum_{\substack{k=1\\k\neq i}}^{d}\frac{\partial_i u_r}{x_i - x_k} = \sum_{i=1}^{d}\sum_{\substack{k=i+1\\k=i}}^{d}\frac{\partial_i u_r - \partial_k u_r}{x_i - x_k}$$
$$= -\sum_{i=1}^{d}\sum_{\substack{k=i+1\\k=i+1}}^{d}\partial_i \partial_k u_r = -\frac{1}{2}\sum_{i=1}^{d}\sum_{\substack{k=1\\k=1}}^{d}\partial_i \partial_k u_r.$$

Finally, using (5.2) twice, we conclude

$$\frac{1}{V} \sum_{i=1}^{d} \partial_i V \partial_i u_r = -\frac{1}{2} \sum_{i=1}^{d} \partial_i \left(\sum_{k=1}^{d} \partial_k u_r \right) = -\frac{1}{2} \sum_{i=1}^{d} \partial_i \left((d-r+1)u_{r-1} \right)$$
$$= -\left(\frac{d+2-r}{2} \right) u_{r-2}, \quad r = 1, 2, \dots, d.$$

Proposition 5.4 *The operator* \mathcal{F}_h *satisfies*

$$\mathcal{F}_{0} = -\sum_{r=1}^{d} \left(\frac{d+2-r}{2} \right) u_{r-2} \frac{\partial}{\partial u_{r}},$$
$$\mathcal{F}_{1} = \sum_{r=1}^{d} \left(\frac{d+1-r}{2} \right) u_{r-1} \frac{\partial}{\partial u_{r}},$$
$$\mathcal{F}_{2} = \sum_{r=1}^{d} \left(\left(\frac{d}{2} \right) - \left(\frac{d-r}{2} \right) \right) u_{r} \frac{\partial}{\partial u_{r}},$$
$$U_{r-1} = \int_{r=1}^{d} \left(\left(\frac{d-r}{2} \right) - \left(\frac{d-r}{2} \right) \right) u_{r-1} \frac{\partial}{\partial u_{r}},$$

where $\begin{pmatrix} d-r\\2 \end{pmatrix} = 0$, for r = d or r = d - 1.

Proof First, for h = 0, we have

$$\mathcal{F}_{0} = \sum_{i=1}^{d} \sum_{\substack{k=1\\k\neq i}}^{d} \frac{1}{x_{i} - x_{k}} \partial_{i} = \sum_{r=1}^{d} \left(\sum_{i=1}^{d} \sum_{\substack{k=1\\k\neq i}}^{d} \frac{1}{x_{i} - x_{k}} \partial_{i} u_{r} \right) \frac{\partial}{\partial u_{r}}$$
$$= \sum_{r=1}^{d} \left(\frac{1}{V} \sum_{i=1}^{d} \partial_{i} V \partial_{i} u_{r} \right) \frac{\partial}{\partial u_{r}} = -\sum_{r=1}^{d} \left(\frac{d+2-r}{2} \right) u_{r-2} \frac{\partial}{\partial u_{r}}.$$

For h = 1, using (2.3) and (5.8), we have

$$\begin{aligned} \mathcal{F}_{1} &= \sum_{i=1}^{d} \sum_{\substack{k=1\\k\neq i}}^{d} \frac{x_{i}}{x_{i} - x_{k}} \partial_{i} = \sum_{r=1}^{d} \left(\sum_{i=1}^{d} \sum_{\substack{k=1\\k\neq i}}^{d} \frac{x_{i}}{x_{i} - x_{k}} \partial_{i} u_{r} \right) \frac{\partial}{\partial u_{r}} \\ &= \sum_{r=1}^{d} \left(\frac{1}{V} \sum_{i=1}^{d} \partial_{i} V x_{i} \partial_{i} u_{r} \right) \frac{\partial}{\partial u_{r}} \\ &= \sum_{r=1}^{d} \left(\frac{1}{V} \sum_{i=1}^{d} \partial_{i} V (u_{r} - \partial_{i} u_{r+1}) \right) \frac{\partial}{\partial u_{r}} \\ &= \sum_{r=1}^{d} \left(\frac{d+1-r}{2} \right) u_{r-1} \frac{\partial}{\partial u_{r}}. \end{aligned}$$

Finally, for h = 2, using (2.3) and (5.9), we have

$$\begin{aligned} \mathcal{F}_2 &= \sum_{i=1}^d \sum_{\substack{k=1\\k\neq i}}^d \frac{x_i^2}{x_i - x_k} \partial_i = \sum_{r=1}^d \left(\sum_{i=1}^d \sum_{\substack{k=1\\k\neq i}}^d \frac{x_i^2}{x_i - x_k} \partial_i u_r \right) \frac{\partial}{\partial u_r} \\ &= \sum_{r=1}^d \left(\frac{1}{V} \sum_{i=1}^d x_i \partial_i V x_i \partial_i u_r \right) \frac{\partial}{\partial u_r} \\ &= \sum_{r=1}^d \left(\frac{1}{V} \sum_{i=1}^d x_i \partial_i V (u_r - \partial_i u_{r+1}) \right) \frac{\partial}{\partial u_r} \\ &= \sum_{r=1}^d \left(\left(\frac{d}{2} \right) u_r - \frac{1}{V} \sum_{i=1}^d x_i \partial_i V \partial_i u_{r+1} \right) \right) \frac{\partial}{\partial u_r} \\ &= \sum_{r=1}^d \left(\left(\frac{d}{2} \right) - \left(\frac{d-r}{2} \right) \right) u_r \frac{\partial}{\partial u_r}, \end{aligned}$$

where $\binom{d-r}{2} = 0$, for r = d or r = d - 1. For the last equality, the two last equalities in the proof for h = 1 were used.

In this way, we have shown that, under the change of variables $x \mapsto u$ defined by (2.1), the differential operators $\mathcal{H}^{H}_{\gamma}, \mathcal{H}^{L}_{\gamma}$ and \mathcal{H}^{J}_{γ} can be represented as linear partial differential operators in the form

$$\mathcal{M}_{\gamma} = \sum_{r=1}^{d} \sum_{s=1}^{d} a_{rs}(\mathbf{u}) \frac{\partial^2}{\partial u_r \partial u_s} + \sum_{r=1}^{d} b_r(\mathbf{u}) \frac{\partial}{\partial u_r},$$

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where $a_{rs}(u)$, for r, s = 1, ..., d are polynomials of degree 2 in u and $b_r(u)$, for r = 1, ..., d are polynomials of degree 1 in u.

Remark 5.5 It is well known that, in the x variable, it is possible to derive formulas for Laguerre and Hermite cases by taking limits of formulas in the Jacobi case (see [1, (2.18)-(2.19)]. Similar results hold for the u variable.

Next, it will be proved that the polynomials defined in (4.2) are eigenfunctions of \mathcal{M}_{γ} . The proof is based on two lemmas.

Lemma 5.6 Let $u^{\mu} = u_1^{\mu_1} \dots u_d^{\mu_d}$ a multivariate monomial then $\mathcal{M}_{\nu} u^{\mu} = c(\mu) u^{\mu} + 1.0.m.,$

where l.o.m. stands for lower order degree monomials in the graded reverse lexicographical order. Here $c(\mu) \in \mathbb{R}$.

Proof This result easily follows from Propositions 5.1, 5.2, and 5.4.

Lemma 5.7 For arbitrary polynomials p(u) and q(u), it holds that

$$\int_{\Omega} \mathcal{M}_{\gamma} p(\mathbf{u}) q(\mathbf{u}) \mathcal{W}_{\gamma}(\mathbf{u}) \, \mathrm{d}\mathbf{u} = \int_{\Omega} p(\mathbf{u}) \mathcal{M}_{\gamma} q(\mathbf{u}) \mathcal{W}_{\gamma}(\mathbf{u}) \, \mathrm{d}\mathbf{u}.$$

Proof Integration by parts provides the self-adjoint character of the differential operators $\mathcal{H}^{H}_{\gamma}, \mathcal{H}^{L}_{\gamma}$ and \mathcal{H}^{J}_{γ} for symmetric polynomials in the corresponding domains (see [16]). The result follows after the change of variables $x \mapsto u$.

Theorem 5.8 Let the $p_{\mu}(\mathbf{u})$ one of the monic orthogonal polynomials defined by (4.2). Then,

$$\mathcal{M}_{\gamma}p_{\mu}(\mathbf{u}) = c(\mu)p_{\mu}(\mathbf{u}).$$

Proof By Lemma 5.6, the function $\mathcal{M}_{\gamma}p_{\mu}(u)$ is a polynomial in u whose leading term is $c(\mu)u^{\mu}$. Let $\mu' \prec \mu$, then it follows from Lemmas 5.6 and 5.7 that

$$\int_{\Omega} \mathcal{M}_{\gamma} p(\mathbf{u}) \, \mathbf{u}^{\mu'} \, \mathcal{W}_{\gamma}(\mathbf{u}) \, \mathrm{d}\mathbf{u} = \int_{\Omega} p(\mathbf{u}) \, \mathcal{M}_{\gamma} \mathbf{u}^{\mu'} \, \mathcal{W}_{\gamma}(\mathbf{u}) \, \mathrm{d}\mathbf{u} = 0.$$

Hence, $\mathcal{M}_{\gamma}p_{\mu}(u)$ is a polynomial whose leading term is $c(\mu)u^{\mu}$ orthogonal to all polynomials of lower degree, so $\mathcal{M}_{\gamma}p_{\mu}(u) = c(\mu)p_{\mu}(u)$.

Remark 5.9 If we write $\mu = (\lambda_1 - \lambda_2, \lambda_2 - \lambda_3, ..., \lambda_d)$ then the expression l.o.m. in Lemma 5.6 can stand for lower in the *dominance partial ordering of the* λ , i.e., $\lambda' \leq \lambda$ if and only if $\lambda'_1 \leq \lambda_1, \lambda'_1 + \lambda'_2 \leq \lambda_1 + \lambda_2, ..., \lambda'_1 + \cdots + \lambda'_d \leq \lambda_1 + \cdots + \lambda_d$.

Accordingly, the orthogonal polynomials p_{μ} can also be characterized as $p_{\mu} = u^{\mu} + 1.0.m$. (with 1.0.m. having the same meaning as above) such that they are orthogonal to all $p_{\mu'}$ with corresponding λ' less than λ (corresponding to μ) in

the dominance partial ordering. Since the dominance partial ordering is not a total order, a priori, the polynomials p_{μ} defined in this way could seem different from the polynomials p_{μ} defined in (4.2). However, that they are still equal was first proved by Heckman [5, Theorem 8.3] by using very deep methods. Much easier proofs were given by Macdonald [15, (11.11)] and Heckman [6, Corollary 3.12].

5.1 The case *d* = 2

For d = 2, using Propositions 5.1, 5.2, and 5.4, we can easily deduce the explicit expression of the differential operators \mathcal{H}^H_{γ} , \mathcal{H}^L_{γ} and \mathcal{H}^J_{γ} , under the change of variables $x \mapsto u$.

In the Jacobi case, the operator

$$\mathcal{H}_{\gamma}^{J} = \mathcal{D}_{0} - \mathcal{D}_{2} + (\beta - \alpha)\mathcal{E}_{0} - (\alpha + \beta + 2)\mathcal{E}_{1} + (2\gamma + 1)(\mathcal{F}_{0} - \mathcal{F}_{2}),$$

for d = 2, can be written as follows

$$\begin{aligned} \mathcal{H}_{\gamma}^{J} = & (-u_{1}^{2} + 2u_{2} + 2)\frac{\partial^{2}}{\partial u_{1}^{2}} + 2u_{1}(1 - u_{2})\frac{\partial^{2}}{\partial u_{1}\partial u_{2}} + (u_{1}^{2} - 2u_{2}^{2} - 2u_{2})\frac{\partial^{2}}{\partial u_{2}^{2}} \\ & + [-(\alpha + \beta + 2\gamma + 3)u_{1} + 2(\beta - \alpha)]\frac{\partial}{\partial u_{1}} \\ & + [(\beta - \alpha)u_{1} - (2\alpha + 2\beta + 2\gamma + 5)u_{2} - (2\gamma + 1)]\frac{\partial}{\partial u_{2}}, \end{aligned}$$

and therefore we recover the differential operator given by Koornwinder in [8].

Denoting the corresponding orthogonal polynomial, for d = 2, by $P_{n-k,k}^{(\alpha,\beta,\gamma)}(\mathbf{u}) = u_1^{n-k}u_2^k + \cdots$, we get

$$\mathcal{H}^{J}_{\gamma} P^{(\alpha,\beta,\gamma)}_{n-k,k}(\mathbf{u}) = -[n(n+\alpha+\beta+2\gamma+2)+k(k+\alpha+\beta+1))] P^{(\alpha,\beta,\gamma)}_{n-k,k}(\mathbf{u}).$$

In the Hermite case, the explicit expression of the differential operator

$$\mathcal{H}_{\gamma}^{H} = \mathcal{D}_{0} - 2\mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{0},$$

for d = 2, is given by

$$\mathcal{H}_{\gamma}^{H} = 2\frac{\partial^{2}}{\partial u_{1}^{2}} + 2u_{1}\frac{\partial^{2}}{\partial u_{1}\partial u_{2}} + (u_{1}^{2} - 2u_{2})\frac{\partial^{2}}{\partial u_{2}^{2}} - 2u_{1}\frac{\partial}{\partial u_{1}} - (4u_{2} + 2\gamma + 1)\frac{\partial}{\partial u_{2}}.$$

Denoting the orthogonal polynomial, for d = 2, by $H_{n-k,k}^{(\gamma)}(u) = u_1^{n-k}u_2^k + \cdots$, we get

$$\mathcal{H}_{\gamma}^{H}H_{n-k,k}^{(\gamma)}(\mathbf{u}) = -2(n+k)H_{n-k,k}^{(\gamma)}(\mathbf{u}).$$

In the Laguerre case, the explicit expression of the differential operator

$$\mathcal{H}_{\gamma}^{L} = \mathcal{D}_{1} + (\alpha + 1)\mathcal{E}_{0} - \mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{1},$$

for d = 2, is given by

$$\begin{aligned} \mathcal{H}_{\gamma}^{L} = & u_1 \frac{\partial^2}{\partial u_1^2} + 4u_2 \frac{\partial^2}{\partial u_1 \partial u_2} + u_1 u_2 \frac{\partial^2}{\partial u_2^2} + \left[2\alpha + 2\gamma + 3 - u_1 \right] \frac{\partial}{\partial u_1} \\ &+ \left[(\alpha + 1)u_1 - 2u_2 \right] \frac{\partial}{\partial u_2}. \end{aligned}$$

Again, denoting the orthogonal polynomial, for d = 2, by $L_{n-k,k}^{(\gamma)}(u) = u_1^{n-k}u_2^k + \cdots$, we get

$$\mathcal{H}_{\gamma}^{L}L_{n-k,k}^{(\gamma)}(\mathbf{u}) = -(n+k)L_{n-k,k}^{(\gamma)}(\mathbf{u})$$

5.2 The case *d* = 3

For d = 3, using Propositions 5.1, 5.2, and 5.4, we can easily deduce the explicit expression of the differential operators $\mathcal{H}^{H}_{\gamma}, \mathcal{H}^{L}_{\gamma}$ and \mathcal{H}^{J}_{γ} , under the change of variables $x \mapsto u$

In the Jacobi case, the operator

$$\mathcal{H}_{\gamma}^{J} = \mathcal{D}_{0} - \mathcal{D}_{2} + (\beta - \alpha)\mathcal{E}_{0} - (\alpha + \beta + 2)\mathcal{E}_{1} + (2\gamma + 1)(\mathcal{F}_{0} - \mathcal{F}_{2}),$$

for d = 3, can be written as follows

$$\begin{split} \mathcal{H}_{\gamma}^{J} = & (-u_{1}^{2} + 2u_{2} + 3)\frac{\partial^{2}}{\partial u_{1}^{2}} + 2(2u_{1} - u_{1}u_{2} + 3u_{3})\frac{\partial^{2}}{\partial u_{1}\partial u_{2}} \\ & + 2(u_{2} - u_{1}u_{3})\frac{\partial^{2}}{\partial u_{1}\partial u_{3}} + 2(u_{1}^{2} - u_{2}^{2} - u_{2} + u_{1}u_{3})\frac{\partial^{2}}{\partial u_{2}^{2}} \\ & + 2(u_{1}u_{2} - 3u_{3} - 2u_{2}u_{3})\frac{\partial^{2}}{\partial u_{2}\partial u_{3}} + (u_{1}^{2} - 2u_{1}u_{3} - 3u_{3}^{2})\frac{\partial^{2}}{\partial u_{3}^{2}} \\ & + \left[-(\alpha + \beta + 4\gamma + 3))u_{1} + 3(\beta - \alpha) \right]\frac{\partial}{\partial u_{1}} \\ & + \left[-(2\alpha + 2\beta + 6\gamma + 7)u_{2} + 2(\beta - \alpha)u_{1} - 3(2\gamma + 1) \right]\frac{\partial}{\partial u_{2}} \\ & + \left[-(3\alpha + 3\beta + 6\gamma + 9)u_{3} + (\beta - \alpha)u_{2} - (2\gamma + 1)u_{1} \right]\frac{\partial}{\partial u_{3}}. \end{split}$$

In the Hermite case, the explicit expression of the differential operator

$$\mathcal{H}_{\gamma}^{H} = \mathcal{D}_{0} - 2\mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{0},$$

for d = 3, is given by

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$$\begin{aligned} \mathcal{H}_{\gamma}^{H} =& 3\frac{\partial^{2}}{\partial u_{1}^{2}} + 4u_{1}\frac{\partial^{2}}{\partial u_{1}\partial u_{2}} + 2u_{2}\frac{\partial^{2}}{\partial u_{1}\partial u_{3}} + 2(u_{1}^{2} - u_{2})\frac{\partial^{2}}{\partial u_{2}^{2}} \\ &+ 2(u_{1}u_{2} - 3u_{3})\frac{\partial^{2}}{\partial u_{2}\partial u_{3}} + (u_{2}^{2} - 2u_{1}u_{2})\frac{\partial^{2}}{\partial u_{3}^{2}} - 2u_{1}\frac{\partial}{\partial u_{1}} \\ &- [4u_{2} + 3(2\gamma + 1)]\frac{\partial}{\partial u_{2}} - [6u_{3} + (2\gamma + 1)u_{1}]\frac{\partial}{\partial u_{3}}. \end{aligned}$$

In the Laguerre case, the explicit expression of the differential operator

$$\mathcal{H}_{\gamma}^{L} = \mathcal{D}_{1} + (\alpha + 1)\mathcal{E}_{0} - \mathcal{E}_{1} + (2\gamma + 1)\mathcal{F}_{1},$$

for d = 3, is given by

$$\begin{aligned} \mathcal{H}_{\gamma}^{L} = & u_1 \frac{\partial^2}{\partial u_1^2} + 4u_2 \frac{\partial^2}{\partial u_1 \partial u_2} + 6u_3 \frac{\partial^2}{\partial u_1 \partial u_3} + (u_1 u_2 + 3u_3) \frac{\partial^2}{\partial u_2^2} \\ & + 4u_1 u_3 \frac{\partial^2}{\partial u_2 \partial u_3} + u_2 u_3 \frac{\partial^2}{\partial u_3^2} + [3\alpha + 6\gamma + 6 - u_1] \frac{\partial}{\partial u_1} \\ & + [(2\alpha + 2\gamma + 3)u_1 - 2u_2] \frac{\partial}{\partial u_2} + [(\alpha + 1)u_2 - 3u_3] \frac{\partial}{\partial u_3}. \end{aligned}$$

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Data availability Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

Declarations

Conflict of interest The authors declare no competing interests.

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