AUTHOR CORRECTION

Correction to: Synchronization control for networked mobile robot systems based on Udwadia-Kalaba approach

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The authors would like to point out the following updates to the published article:

1. The e-mail of J. Zhou should be jzhou@shu.edu.cn and the e-mail of J. Ji should be jin.ji@uts.edu.au.

2. In the second paragraph of Section 4.4, Eq. (21) should be Eq. (38) and equations (21), (21e) should be Eqs. (19), (38).

The original article has been corrected.

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