AUTHOR CORRECTION

Correction to: Robust control of reaction wheel bicycle robot via adaptive integral terminal sliding mode

Long Chen · Jun Liu · Hai Wang · Youhao Hu · Xuefeng Zheng ·
Mao Ye · Jie Zhang

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Funding information and grant number were omitted from the original article. The original article has been corrected.

The original article can be found online at <https://doi.org/10.1007/s11071-021-06380-9>.

L. Chen · J. Liu · X. Zheng
School of Electronics and Information, Hangzhou Dianzi
University, Hangzhou 310012, China

H. Wang (✉) · Y. Hu · M. Ye · J. Zhang
Discipline of Engineering and Energy, Centre for Water-
Energy-Waste, Murdoch University, Perth,
WA 6150, Australia
e-mail: hai.wang@murdoch.edu.au