

Erratum to: Active vibration control of a dynamical system via negative linear velocity feedback

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1 **Erratum to: Nonlinear Dyn**
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3 Unfortunately, the following errors remain in the orig-
4 inal publication:

5 In Table 1 the second column header should read
6 ‘Without controller’ and the third one ‘With controller’
7 (instead of the other way around).

In the first paragraph of Sect. 4.2, ‘roll mode ω_1 ’ 8
and ‘pitch mode ω_2 ’ should read ‘first mode ω_1 ’ and 9
‘second mode ω_2 ’, resp. 10

The online version of the original article can be found under
doi:[10.1007/s11071-014-1306-4](https://doi.org/10.1007/s11071-014-1306-4).

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