ORIGINAL ARTICLE



Shared pooled mobility essential complement to decarbonize China's transport sector until 2060

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Abstract

Greenhouse gas emission reduction in the passenger transport sector is a main challenge for China's climate mitigation agenda. Electrification and shared mobility provide encouraging options for carbon emissions reduction in road transport. Based on an integrated scenario-based assessment framework, a provincial-level projection is made for vehicle growth and CO₂ emissions in China under shared socioeconomic pathways (SSPs). This work illustrates how passenger car electrification and sharing contribute to China's "30-60" climate goals (peaking of CO₂ emissions by 2030 and carbon neutrality by 2060). The results demonstrate that China is en route to achieving the goal of a 2030 carbon peak (1.0Gt CO₂) under current conditions, and could reach peak emissions around 2026 with optimistic growth in EVs and shared mobility. Compared with no policy action, the single EV policy (shifting from ICEVs to EVs) can reduce 71% of emissions by 2060, thus narrowing but not closing the mitigation gap to carbon neutrality in passenger cars (302 Mt CO₂). Shared mobility can provide further emission reduction support, reducing emissions by 83% in 2060. Comprehensive climate actions (including electrification, sharing mobility to reduce car use, and improving vehicle efficiency and fuel carbon intensity) are needed to achieve deep decarbonization to net-zero by 2060 in the passenger transport sector.

Keywords Carbon neutrality · Electric vehicles · Shared mobility · China

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1 Introduction

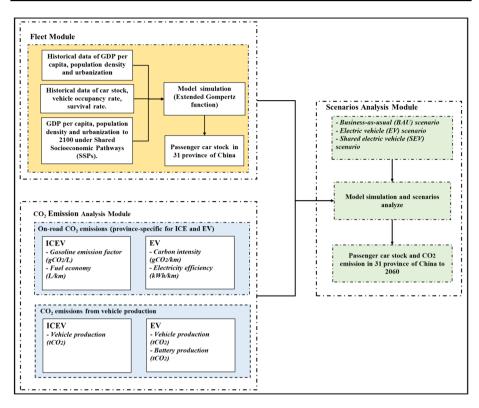
China's climate targets—peaking of CO₂ emissions by 2030 and carbon neutrality by 2060—are an important step for global-scale climate change mitigation and planetary health. The transport sector is a key and growing emissions source, accounting for 9% of total emissions in China in 2019, largely due to passenger cars (Xue et al. 2022). The rapid growth in both passenger car stock and carbon emissions necessitates effective strategies for emission reduction.

Electric vehicles (EVs) are currently the most widely discussed solution for decarbonizing urban transportation (Hill et al. 2019; Wolfram et al. 2021). To execute strategies toward carbon neutrality in the transport sector, many studies have applied a multiple-scenario approach to make flexible EV development policy on energy consumption and emissions in China (Peng et al. 2021; Zhang and Hanaoka 2021; Chen et al. 2022; Fang et al. 2023; Shen et al. 2023). Based on an integrated modeling framework, Fang et al. (2023) demonstrate that electrification of the passenger fleet, which is charged by a slightly cleaner power source, yields significant co-benefits of CO₂ reduction and air quality improvement. Shen et al. (2023) evaluated the CO₂ reduction and health benefits with the banning of new sales of internal combustion engine vehicles (ICEVs) in the private vehicle sector in Chinese provinces, and found that if there were no carbon neutrality and air pollution control goals in electricity generation, 53% of CO₂ reduction would be offset by the increased power demand and consequent carbon emission and health damage in 2050.

However, the introduction of EVs alone is insufficient to reach ambitious climate targets (Zhang and Fujimori 2020; Milovanoff et al. 2020). Although many studies reflect the huge potential of electric vehicles to reduce emissions in the transport sector, they have not yet taken into account issues like production emissions and materials demand of EVs under the scenario where a large number of EVs replace ICEVs caused by vehicle growth. Betting solely on EVs to remain within suitable sectoral CO₂ emission budgets for the US light-duty vehicle (LDV) fleet would imply more than 350 million on-road EVs in 2050, requiring an excessive amount of critical materials (Milovanoff et al. 2020). Hence, the question that must be addressed remains not only limited to the consistency of climate mitigation strategies building on electrification in the land transport sector, but also going beyond that.

Replacing ICEVs with EVs is just one of the common methods (Avoid-Shift-Improve options) in achieving emissions reduction from the passenger car sector (Bongardt et al. 2013; Creutzig et al. 2018). Another important strategy is shifting travel demand to the lowest-carbon mode, such as cycling and using shared mobility by restricting the sales of vehicles (Yi and Yan 2020; Arbeláez Vélez and Plepys 2021; Hu and Creutzig 2021). Sharing vehicles can improve both vehicle usage efficiency and occupancy, thus reducing the overall number of cars while maintaining mobility improvement (Creutzig 2021). Especially, electric shared vehicles and shared bikes have been proven to have significant emission reduction potential (Ding et al. 2019; International Transport Forum 2020; Yi and Yan 2020; Creutzig 2021). Combining the growth of shared mobility with electrification and optimizing climate strategies to reduce vehicle carbon emission may hence improve the chances of decarbonizing land transport early. Unfortunately, the emission reduction potential of this comprehensive strategy is currently unclear. Furthermore, to our best knowledge, the emission reduction potential of shared mobility in different provinces has not been explicitly explored in any previous studies.





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Fig. 1 Flow chart of the model estimation process

To address the abovementioned knowledge gaps, this study develops a scenario-based assessment framework to provide extensive analysis on the policy mix of the "Shift" (i.e., to reduce car stock by providing high-quality shared mobility) and "Improve" (i.e., vehicle technology from ICEVs to EVs) strategies to achieve deep decarbonization in the passenger transport sector of China. Specifically, the research addresses three pivotal subquestions: (1) How much can EV development policies reduce emissions if their production emissions are taken into account? (2) Can shared mobility complement EVs to further enhance emission reductions in China's passenger transportation sector? (3) What regional variations in CO₂ reduction can be attributed to EV and shared mobility policies across different provinces? The model results could help achieve maximum emission reductions with a more comprehensive policy perspective.

2 Methodology and data

2.1 Model overview

This work aims to develop a scenario-based assessment framework of the passenger car fleet, taking shared socioeconomic pathways (SSPs) as a starting point. Figure 1 illustrates the general modeling process and main exogenous inputs. The evaluation framework consists of 3



main modules: fleet estimation, CO₂ emission assessment, and scenario analysis. The fleet module simulates the annual car stocks. An extended Gompertz model is used to estimate future passenger car stock of 31 provinces in China (Dargay et al. 2007). The CO₂ emission model quantifies the direct and indirect emissions (i.e., vehicle manufacturing, fuel production, and fuel use) for EVs and ICEVs. Finally, three main scenarios are built to evaluate policy tool effects. On the basis of these results, the carbon emission of passenger cars in China from 2010 to 2100 is evaluated at the provincial level.

2.2 Socioeconomic framework

The shared socioeconomic pathways (SSPs) are used to quantify socioeconomic components, such as GDP, population, and urban share. The SSPs represent five global development pathways, describing the future evolution of key aspects of society that would together imply a range of challenges for mitigating and adapting to climate change (Riahi et al. 2017; Kasera et al. 2016). SSPs have been widely used in forecasting future energy demand and GHG emissions (Xing et al. 2015; Milovanoff et al. 2020; Wolfram et al. 2021). The five global development pathways are SSP1 (Sustainability), SSP2 (Middle of the Road), SSP3 (Regional Rivalry), SSP4 (Inequality), and SSP5 (Fossil-fueled Development). A brief description of SSP1-5 is shown in the supplementary information (Table S1). The SSP database only provides national-level economic forecast data. China's provincial GDP data is from Jiang et al. (2018), the population data is from Jiang et al. (2017), and the urbanization rates data is from Chen et al. (2020). We briefly show the changes in population and urbanization rates under SSPs in the supplementary information (Table S2 and Fig S1). As mainly referenced, we use SSP1, which is regarded as the most sustainable path among all SSPs, to then demonstrate the differential impact of passenger cars and carbon emissions in three scenarios (BAU, EV, and SEV—see Fig. 1).

2.3 Fleet module for total vehicle ownership

In the "fleet" module, we developed a demand-based extended Gompertz function to simulate car stocks retrospectively (1995–2019) and prospectively (2020–2100) for 31 provinces in China. The historical data (such as passenger car ownership, car sales, GDP, and population) are from national statistics (National Bureau of Statistics of China 2020) and the China Automotive Technology And Research Center (CATARC 2020).

The traditional Gompertz function (Eq. (1)) is widely applied to measure the S-shaped relationship between vehicle ownership and per-capita income (Dargay and Gately 1999; Dargay et al. 2007; Zheng et al. 2015; Zeng et al. 2016; Ma et al. 2019). Compared to other more intricate models such as Dynamic Simulation (Levin et al. 2017) or Linear Programming (Jones and Leibowicz 2019; Zhang et al. 2022) which offer greater flexibility in handling diverse factors but with greater data and computational intensity requirements, the Gompertz function can simply facilitate a clearer understanding and provide vehicle ownership prediction trends based on economic conditions, proving valuable for policymakers and stakeholders who may not have an extensive technical background (Shen et al. 2023). Further, the Gompertz function allows for the adjustment of parameters to match the unique characteristics of each region.

$$V_{it} = \gamma e^{\alpha e^{\beta_i GDP_{it}}} \tag{1}$$



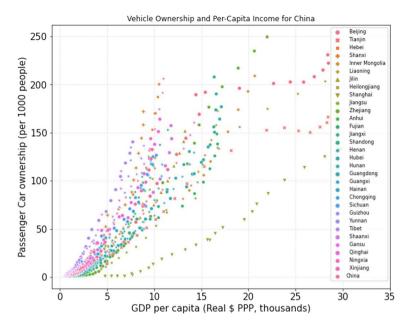


Fig. 2 Passenger car ownership per thousand people based on GDP per capita from 1995 to 2019. Note GDP per capita is in PPP (constant 2005 international \$)

where V_{it} is the vehicle ownership (per 1000 people) in province i in year t, GDP_{it} is the GDP in province i in year t, $\gamma > 0$ is the saturation level, and $\alpha < 0$ and $\beta < 0$ are parameters defining the shape of the curve.

Figure 2 shows passenger car ownership per thousand people based on China's national and provincial GDP per capita from 1995 to 2019. The passenger car ownership is around 109–250 per thousand people in 2019. The passenger car ownership in areas with good economic development such as Beijing and Zhejiang is significantly higher than that of other provinces such as Gansu and Jiangxi, major destinations for migrant workers in the west. For example, while the passenger car ownership in Zhejiang is 249 vehicles per thousand people, Gansu has the lowest car ownership rate, with only 109 vehicles per thousand people. Due to the strict vehicle purchase limitation policy, there is a flattening of the curve in Beijing, Tianjin, and Shanghai. However, most provinces in China are still in the initial stage of the "S shape," which means that the passenger car stock will continue to grow. The differences between different provinces are obvious.

As acknowledged, the conventional Gompertz function is limited to capturing the long-term correlation between vehicle ownership and per-capita income, while lacking the capacity to depict the dynamics of new vehicle sales and retirements. We are actively addressing this concern in the formulation of our Gompertz model. Firstly, following Dargay et al. (2007), we built an extended Gompertz function that explicitly models the vehicle saturation level as a function of observable country characteristics: urbanization and population density. Although there are many other factors that influence the modal shift on the usage of cars such as travel patterns and driver characteristics, such factors are difficult to take into account as they would require more data that are mostly unavailable for all provinces. Then, we postulated a simple partial adjustment mechanism in the econometric model to quantify the short-term relationship between



the current period's vehicle count and that of the preceding period (Eq. (2)). In this way, we used demographic and economic data to reassess vehicle production and usage from the demand side. We verified the validity and reliability of the extended Gompertz function and related parameters by comparing predicted values and historical data in the supplementary information (Fig S2-S3).

$$V_{it} = (\gamma_{max} + \lambda \overline{D_{it}} + \varphi \overline{U_{it}})(\theta_R R_{it} + \theta_F F_{it})e^{\alpha e^{\theta_i GDP_{it}}} + (1 - \theta_R R_{it} - \theta_F F_{it})V_{it-1}$$
(2)

where adjustment parameters $\theta_R > 0$, $\theta_F > 0$, $\alpha < 0$, $\lambda < 0$, and $\varphi < 0$ are constrained to be the same for all provinces, while $\beta_i < 0$ is allowed to vary across provinces. Based on the provincial historical data in China and iterative least squares regression coefficients, we obtain parameters as shown in the supplementary information (Table S3–S4). V_{it} is the vehicle ownership (in numbers per 1000 people) in province i in year t. We assume that the maximum saturation level (γ_{max}) will be that estimated for Beijing because other provinces are less urbanized and less densely populated than Beijing. Under the government policy of restricting car purchases, research generally estimated that the saturation level in cities such as Beijing, Shanghai, or Tianjin will be approximately 250–400 (Zeng et al. 2016; Zheng et al. 2015; Gan et al. 2020; Huo and Wang 2012). In this study, we assumed γ_{max} to be 400 vehicles per 1000 people in Beijing. Furthermore, the saturation level in other provinces can be calculated according to the difference in the population density and the level of urbanization from Beijing (Eq. (3)

$$\overline{D_{it}} = \begin{cases}
D_{it} - D_{\text{Beijng},t}, ifD_{it} - D_{\text{Beijng},t} > 0 \\
0, \text{ otherwise} \\
\overline{U_{it}} = \begin{cases}
U_{it} - U_{\text{Beijng},t}, ifU_{it} - U_{\text{Beijng},t} > 0 \\
0, \text{ otherwise}
\end{cases}$$
(3)

where $\overline{D_{it}}$ is the population density and $\overline{U_{it}}$ is the level of urbanization.

Income asymmetry (i.e., many provinces have experienced negative as well as positive GDP per-capita growth over the period) is taken into consideration in the extended Gompertz function in Eq. (2) as $\theta_R R_{it} + \theta_F F_{it}$ (Dargay et al. 2007) where $\theta = \theta_R$ for income increases and $\theta = \theta_F$ for income decreases. R_{it} and F_{it} are shown in Eq. (4):

$$R_{it} = \begin{cases} 1, ifGDP_{it} - GDP_{it-1} > 0\\ 0, \text{ other wise} \end{cases}$$

$$F_{it} = \begin{cases} 1, ifGDP_{it} - GDP_{it-1} < 0\\ 0, \text{ other wise} \end{cases}$$
(4)

2.4 Scenarios settings for EV and shared mobility

Three main scenarios for passenger car fleet are developed to evaluate the impact of two policy tools (i.e., shift to EVs and reduce car stock with shared mobility) on decarbonizing the passenger transport sector of China. Table 1 presents their descriptions. Specific details about the scenarios are shown in the supplementary information (section SI4). To ensure the robustness of the scenarios, we carry out a sensitivity analysis (from 2030 to 2050) because the prohibition time of fuel vehicles has a high degree of uncertainty in various provinces.



Table 1 Scenario description

Scenario	Description
Business-as-usual scenario (BAU)	There are no climate mitigation efforts and no EV policy with the continuation of technological improvement at the current pace. The maximum saturation level in China will be 400 vehicles per 1000 people.
Electric vehicle scenario (EV)	Advanced battery electric cars will serve as an alternative to ICEVs to meet travel demand. With a strong EV support policy, the share of ICEV sales to total vehicle sales will be dropped to 0% by 2030 in all provinces. The maximum saturation level in China will be 400 vehicles per 1000 people.
Shared electric vehicle scenario (SEV)	Shared electric vehicles will serve as an alternative to EVs and ICEVs to meet travel demand. Based on the consideration that we aim to minimize the environmental impact of individual vehicle ownership and reduce overall carbon emissions until 2060 to achieve China's carbon neutrality goal, the share of shared mobility will increase to 100% in 2060. The maximum saturation level in China will be 100 vehicles per 1000 people due to the popularity of shared mobility.

3 GHG emissions

3.1 On-road CO₂ emissions

On-road CO_2 emissions from EVs and ICEVs are determined by car stock, traveled distance, and carbon emission factors. The on-road CO_2 emissions can be calculated by Eq. (5).

$$CO_{2usage,i} = \sum_{j} V_{ij} \cdot VKT_{ij} \cdot EMF_{j}$$
(5)

where CO_{2usage} is the on-road CO_2 emissions for passenger cars. i stands for province i. j stands for vehicle type j ($j = \{ICEV, EV\}$). VKT represents the vehicle kilometers (km) traveled. VKT is an important parameter reflecting vehicle usage. The VKT of provinces in China in 2015 are from Liu et al. (2017). Due to the unavailability of provincial-level VKT time series data, we use the national average growth rate of VKT to calculate the future VKT of passenger vehicles in each province. According to Huo et al. 2012; iCET 2018; and Zhang 2024, the annual VKT of private passenger vehicles in China has decreased from 12,489 to 11,660 km between 2015 and 2020 with an average annual decrease rate of 0.93%. We further estimate the VKT of ICEVs and EVs at the provincial level based on the provincial vehicle ownership level, as shown in the supplementary information (Fig. S4). Importantly, the effect of shared mobility on VKT is complex, which depends on many factors such as the substitution of public versus private transport modes and the occupancy rate of substituted modes. Limited researches analyze the changes in VKT for shared mobility (Narayanan et al. 2020). We have compiled some of the related studies and displayed them in the supplementary information (Table S5). Shared mobility fleets are predicted to generate an additional 10~20% of travel miles (VKT/VMT). To account for this uncertainty, we set two different growth rates (10% and 20%) in the VKT of shared mobility (Fig. S5).



EMF represents the emission factors (g CO₂/km). While driving, EVs emit CO₂ emissions from electricity generation and ICEVs emit CO₂ emissions from fuel production and fuel consumption. The detailed information on the calculation of on-road CO₂ emissions is summarized in the supplementary information (section SI5).

3.2 CO₂ emissions from vehicle production

The specific greenhouse gas (GHG) emission reduction potential of electric vehicles not only depends on the carbon intensity of electricity usage, but also on the production process of vehicles. In determining vehicle emissions, it is important to consider not only direct emissions during vehicle use, but also implicit emissions resulting from vehicle production. Vehicles generate massive indirect emissions during the manufacturing stage in the industry sector (Hill et al. 2019; Milovanoff et al. 2021). The exact GHG emissions from the production phase of an EV are about 13.0 t CO₂eq, 24% larger than those of an ICEV (10.5 t CO₂eq) in China in 2015 (Qiao et al. 2019). This part of the emissions may limit the emission reduction potential of EVs. The CO₂ emissions from production will be given by the number of new vehicles produced as shown in Eq. (6).

$$CO_{2 \text{production}, i} = \sum_{j} VP_{ij} \cdot EMF_{ij}$$
(6)

where $CO_{2production}$ is the CO_2 emission of passenger vehicle production in province i and vehicle type j. VP represents new vehicles produced. The detailed information on the calculation of vehicle production CO_2 emissions is summarized in the supplementary information (section SI 5.7).

Total CO₂ emission incorporates production and usage emissions as shown in Eq. (7).

$$CO_{2\text{total}} = CO_{2\text{usage}} + CO_{2\text{production}}$$
 (7)

4 Results

4.1 Car stock and CO₂ emission

4.1.1 Passenger car stock

We verified the validity and reliability of the extended Gompertz function and related parameters by comparing predicted values and historical data, which are shown in the supplementary information (Fig. S2 and S3). The results show that the predicted passenger car stock has good convergent validity and is reliable.

The passenger car stock in China is expected to grow before 2050 driven by increasing population and higher incomes. Figure 3a shows passenger car stock in China from 2010 to 2100 in three scenarios under SSP1. The passenger car stock will reach its peak of about 500 million vehicles around 2050 in the BAU scenario. Total car stock in the EV scenario is similar to the BAU scenario because EVs are used as alternatives for ICEVs to meet passenger travel demand. Passenger car stock dynamic in the SEV scenario is slower and muted compared to other scenarios. In the SEV scenario, the car stock will reach its peak at 410 million in 2037 and then decline to 214 million in 2060 under SSP1. The results



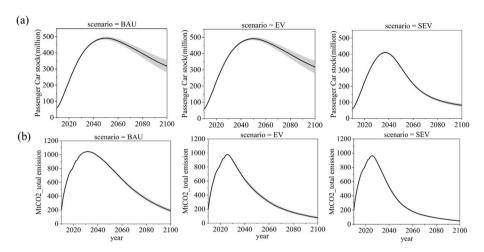


Fig. 3 Passenger car stock and total CO_2 emissions in China from 2010 to 2100 in three scenarios under SSP1 with decarbonization. a Passenger car stock in three scenarios under SSP1 with decarbonization. b Total CO_2 emissions in three scenarios under SSP1 with decarbonization. Note: The shaded area reflects the error interval under SSPs (95% CI)

show that shared mobility reduces vehicle use effectively. Shared mobility not only limits the maximum saturation level of passenger cars, but also slows the growth rate of new vehicles.

4.1.2 CO₂ emission

Figure 3b shows the total $\rm CO_2$ emissions of passenger cars in China from 2010 to 2100 in the three scenarios considered. In all scenarios, $\rm CO_2$ emissions peak around 2030. In the BAU scenario, total emission peaks at 1045 Mt $\rm CO_2$ in 2032. In the EV scenario, total emission peaks at 980 Mt $\rm CO_2$ —6 years earlier (2026). In the SEV scenario, total emission peaks at 963 Mt $\rm CO_2$ in 2026. The rapid and large-scale promotion of EVs and shared mobility accelerates the peak time and magnifies the reduction of carbon emissions in the passenger transport sector.

Shift to EVs and shared mobility also contribute to deep decarbonization and carbon naturality target in China. Within the three scenarios, there is varying decline in passenger transportation emissions. In the BAU scenario, the CO₂ emission of passenger cars decreases to 643 Mt CO₂ (a 38% reduction) by 2060 accounting for continuous decline in fuel carbon intensity. Sharp increase of EVs, mainly fueled by low-carbon electricity, speeds up the decarbonization process. The CO₂ emission from passenger cars fall faster in the EV scenario than in the BAU scenario. By 2060, passenger car emission falls to 302 Mt CO₂ in the EV scenario (a 71% reduction). The residual emissions are coming from the EV production emissions and usage, reflecting that the grid will still have residual carbon emissions. These results imply that EV promotion alone is insufficient to achieve carbon neutrality in the passenger transport sector. In order to reach near-zero emissions, a large number of carbon sinks or negative emissions technology are still necessary for these two scenarios. Shared mobility can significantly reduce carbon emissions by decreasing the use of passenger cars. Under the SEV scenario, the passenger transportation sector is expected to further cut GHG emissions



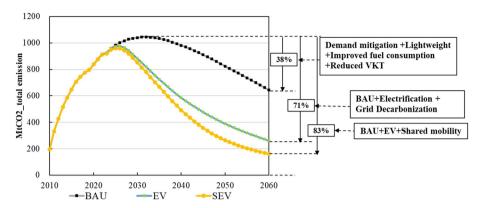


Fig. 4 The contributions to emission reduction of different factors

by two-fifth (181 Mt $\rm CO_2$ in 2060). To achieve the same emission reduction, the total number of vehicles in the shared mobility scenario (SEV) has to be less than half of that in the EV scenario, which will greatly reduce vehicles material demand. Hence, carbon neutrality in the passenger transport sector would rely on a comprehensive climate policy (including electrification, sharing, and rapid replacement of coal and gas power plants with renewables) that maximizes the benefits of emission reduction. To strengthen the role of shared pooled mobility in the Chinese transport sector, we provide a figure that shows the contributions to emission reduction of different factors (Fig. 4). Figure 4 also intuitively shows the emission reduction contributions of different policy mix.

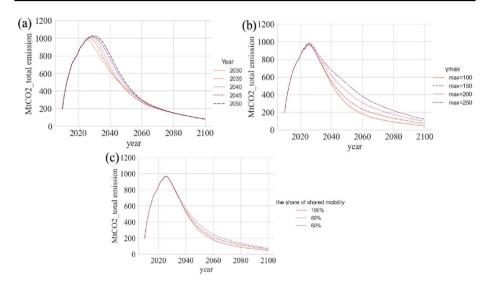
4.1.3 Sensitivity analysis

Figure 5 further alters three key variables to test the robustness of the results. The first assumption is on the share of EV sales to total vehicle sales. Current results are under the assumption that the share of EV sales reach 100% in 2030. Despite Hainan province's proposal to ban the sale of fuel vehicles from 2030, there is much uncertainty about when ICEVs will be delisted in other provinces of China. Figure 5a shows the influence of different electric vehicle development speed. Delaying the ban on the sale of fuel vehicles will increase the emission peak and delay the peak time of emissions in the passenger transport sector.

The second assumption is on the maximum saturation level (γ_{max}) . The maximum saturation level in shared mobility is also highly uncertain. The maximum saturation level determines the upper limit of the total vehicle stock which further limits the reduction potential of total vehicle emissions. Figure 5b shows the difference in total emission with different γ_{max} —demonstrating the high influence of this parameter. In the SEV scenario, in 2060, emissions are 19% and 52% lower when $\gamma_{max} = 200$ and $\gamma_{max} = 100$, respectively, compared to the case of $\gamma_{max} = 250$.

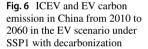
The last assumption is on the proportion of cars shared. The sensitivity analysis results for the share of shared mobility align with our expectations (Fig. 5c). The greater the extent to which shared mobility replaces EVs and ICEVs, the larger the potential for emissions reduction.

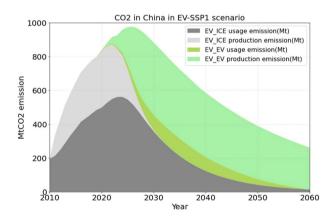




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Fig. 5 The sensitivity analysis of different factors on the CO₂ emissions: **a** the year of complete banning of ICEV sales (100% EVs in 2030 ~ 2050), **b** the maximum saturation level ($\gamma_{max} = 100 \sim 300$), **c** the share of shared mobility in 2060 (60~100%)





4.1.4 Vehicle emission and production emission

GHG emissions originate not only in vehicle use, but also in production. Figure 6 shows the usage emission and production emission of ICEVs and EVs in China from 2010 to 2100 in the EV scenario. The vehicle emission of EV falls to zero by 2060 in SSP1 with decarbonization due to significant electricity grid decarbonization for carbon neutrality. We also compared emissions under different grid decarbonization scenarios in the supplementary information (section SI5.2). The degree of grid decarbonization has a significant impact on EV road emissions. However, from the perspective of life-cycle emissions, there is less impact on total emissions (supplementary information, Fig S8).

Figure 6 shows that a large-scale promotion of EVs will increase their productionrelated emissions, limiting their carbon emission reduction potential. This leads to an



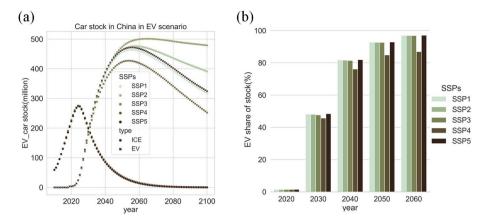


Fig. 7 ICEV and EV stocks in China from 2010 to 2100 under the EV scenario. a On-road fleet stock, b EV share

increase in the peak emissions of passenger cars in the EV scenario. In the initial stage of the rapid development of EVs, the increased emissions from EV production outweigh the emissions reduced by the usage shift from ICEVs to EVs. Moreover, the production emissions of EVs will still be around 248 Mt CO2 in 2060, and – by then – higher than their vehicle usage emissions. The results are based on the current changes in production emissions¹. Taking this into account, the emissions from vehicle production will be higher than the emissions from vehicles driving on the road in the future due to faster-working electricity decarbonization. If production emissions were excluded from the three scenarios, an accelerated shift from ICEVs to EVs would result in greater emissions reduction benefits. Therefore, improving vehicle efficiency and decrease carbon intensity in the EV production is crucial when upscaling EV production.

4.1.5 EVs required

The Chinese government started a new energy vehicle (NEV) subsidy plan to promote the development of NEVs in 2009. Over the last decade, electric vehicles across all transport modes were increasingly adopted. Up to now, China's EV stock has exceeded 5.5 million, accounting for 48% of the global EV stock in 2020 (IEA 2021). Figure 7 briefly analyzes how electric vehicles penetrate the passenger car market. Under the EV scenario, 500 million EVs would need to be on the road of China in 2050 to achieve maximum emission reduction in 2060 (Fig. 7a)—up to 94% of the total passenger cars (Fig. 7b). Attaining this EV share would require up to 210 million EVs by 2030. China has set ambitious electric vehicle development goals. According to the New Energy Vehicle Industry Development Plan (2021–2035), the sales of NEVs will reach about 20% of the total new car sales in 2025 (currently 5%). Pure electric vehicles will become the majority of new vehicle sales

¹ Emission factors are calculated based on the 2015–2020 annual average decline rate of 12 t CO₂eq/vehicle in 2020 and extrapolated to 6.3 t CO₂eq/vehicle in 2060. Taking into account the latest data currently available, we have made this assumption on the production emission factor. Note that the current assumptions are conservative.



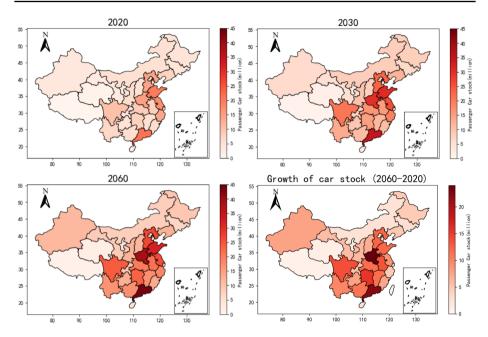


Fig. 8 Provincial passenger car stocks in the BAU scenario under SSP1

in 2035 (State Council Information Office of the People's Republic of China 2020). These policies will contribute to reduce the emissions in the passenger transport sector. However, although the development of EVs can help reduce emissions, the total number of vehicles is not decreasing fast enough. This means that cities will still face restrictions on space for recreation, play, and parking places. Shared cars can offer door-to-door transport, and replace up to three-quarter of car trips, which is a good complement to the sustainable development of the city.

4.2 Province level results

There will be a significant increase in the demand for passenger vehicles in all provinces over the next few decades. The model results show two main characteristics of future changes in passenger cars in China. First, there are strong regional differences. Figure 8 shows the change of provincial passenger vehicle stock in the BAU scenario under SSP1. The numbers of passenger cars in the southeast coastal provinces are significantly higher than those of other regions, especially in Shandong and Guangdong, where the numbers of passenger cars have exceeded 20 million in 2020. Further, vehicle ownership in various provinces continued to rise in the BAU scenario. By 2060, there will be 9 provinces with more than 20 million passenger cars (i.e., Jiangsu, Zhejiang, Shandong, Henan, Hebei, Guangdong, Sichuan, Anhui, and Hunan), most of which will be located in the southeast coastal areas. The demand for passenger cars in these regions is based on larger population and higher economic turnover. Special attention should be paid to provinces such as Guangdong, Henan, and Hunan. These provinces not only have large stocks, but also display strong dynamic increase.



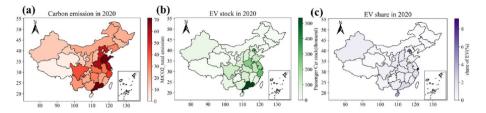


Fig. 9 CO₂ emission from a passenger cars, b EV stock, and c EV share in 31 provinces in 2020

However, although China is the largest EV market in the world, the EV industry in the provinces has just started. The CO₂ emissions from passenger cars, EV stocks, and EV shares in 31 provinces are shown in Fig. 9. In provinces where vehicle ownership continues to grow, EV development is still very slow at this stage. Guangdong and Shandong are the top 2 highest emission releasers in passenger cars with more than 80 Mt CO₂ in 2020 (Fig. 9a). Although their EV holdings are also higher than other provinces (Fig. 9b), the share of EVs is only 1–2% of their total passenger cars (Fig. 9c). The EV scenario is far away from current trends. In the EV scenario, we assume that the EV sales shares in 31 provinces in China will reach 100% in 2030, which is the most optimistic policy scenario. According to the current EV market penetration, electric vehicles need to be heavily promoted in all provinces over the next ten years. The EV share of passenger cars in Shanghai, Beijing, Tianjin, and Hainan is more than 4%, while other provinces' numbers are below 2% (Fig. 9c). These four provinces can be used as pilot provinces for banning the sale of ICEVs.

Figure 10 displays provinces' passenger transport sector emission in 2030 and 2060 under three scenarios. From the perspective of passenger vehicle emissions, provinces differ greatly in their emissions. The south-eastern provinces, which still have a high demand for vehicles, have significantly higher emissions than other provinces. Guangdong will be the highest passenger car emission producer in China with 86 Mt CO₂ by 2030 under the BAU scenario, which is 39 times that of Tibet (2.2 Mt CO₂). Figure 10 clearly shows that EVs and shared mobility can effectively reduce emissions from passenger transport in various provinces. In Guangdong province, GHG emissions will fall to 55 Mt CO₂ by 2060 under the BAU scenario. Under the EV and SEV scenarios, it will further reduce emissions by 72% and 83%, respectively. Overall, south-eastern provinces will benefit more from the development of EVs and shared mobility. They have higher potential in reducing emission levels.

5 Discussion and conclusion

5.1 Implications for China's "30.60" goals

China is expected to achieve 2030 carbon peak from passenger cars under the BAU scenario with 1.3 Gt $\rm CO_2$ in SSP1 with decarbonization (sustainable path). Large-scale shift with the EV promotion can advance passenger car emissions to peak around 2026. However, EVs will not provide a solution for near-term $\rm CO_2$ mitigation because EVs cannot significantly reduce peak emissions.

Deep decarbonization to net-zero by 2060 in the passenger transport sector of China is easier with a comprehensive climate policy (including electrification, sharing mobility to



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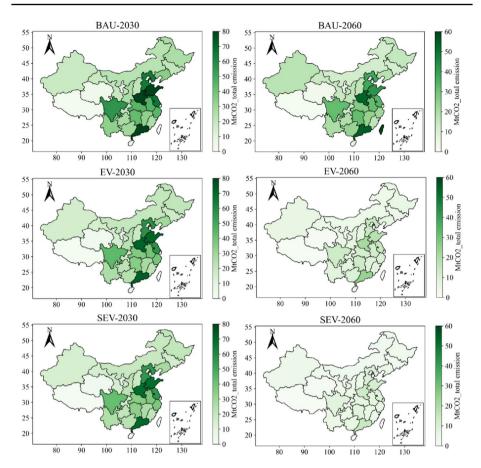


Fig. 10 Provincial CO₂ emission from passenger transport in 2030 and 2060 in three scenarios under SSP1 with decarbonization

reduce car use, and improving vehicle efficiency and fuel carbon intensity) instead of a single EV policy. The single EV policy (shift ICEVs to EVs) can reduce GHG emissions by 71% in 2060. There are still 302 Mt CO₂ of emissions that need to be resolved by carbon sinks or negative emissions technology. If electric vehicles are also shared, GHG emissions will be reduced by 83% in 2060 compared to the BAU scenario. The SEV scenario explores the extreme setting of a case when all private trips change to shared trips, a fairly optimistic assumption. In contrast, the scenarios assume conservative values in decarbonization of the electricity grid. One interpretation is that combined intermediate shared mobility and electrification strategies can achieve between 71 and 83% GHG emission reductions between 2020 and 2060 on their own (around 302 Mt CO₂ to 181 Mt CO₂ left by 2060). More aggressive phase out of coal and scale up of renewable energy could then support the decarbonization of the residual emissions. Importantly, because of reduced demand for transport sector electrification, additional energy demand can be more easily covered by renewable energy sources (Creutzig et al. 2021; p. 1).

Additionally, analysis shows that variation of SSP has little implication for mitigation scenarios (supplementary information, Fig. S12-S13). Specifically, variation in



SSPs results in GHG emissions varying little in either the BAU or mitigation scenarios (maximally 15% in 2060). Introducing technological (EV) and mobility system change (SEV) is responsible for the impactful change in GHG emission trajectories.

5.2 Shift to EVs

How fast can transport electrification and shared mobility contribute to China's "30.60" goals depends on their share in total passenger car market. Without limiting the number of vehicles, 500 million EVs would need to be on the road in China in 2050 to achieve max emission reduction in 2060, up to 94% of the total passenger cars, a considerable challenge. In addition, the emission reduction potential in the large-scale promotion of EVs is limited due to higher production-related emissions. Improving vehicle efficiency and carbon intensity in EV production should be the basis for the large-scale promotion of EVs. Also, the increase in power consumption caused by the development of EVs has an impact on the power system. This will also put substantial pressure on the power system. Additional electric vehicle growth could result in substantial material concerns. Milovanoff et al. (2020) estimated that 8% and 29% of the identified world terrestrial resources of lithium and cobalt, respectively, would be needed for the USA alone to achieve its climate goals by electrification. China has a larger passenger car system, meaning that replacing ICEVs with EVs will require more resource consumption. Therefore, the reduction in the passenger car ownership and usage is still critical to reduce their carbon emissions. The development of shared mobility can reduce the vehicle required for emission reduction, which will greatly reduce vehicle material demand.

5.3 Province level solutions for climate change

Electric vehicles and shared mobility can effectively reduce carbon emissions from passenger transport in various provinces. In terms of regional differences, passenger car stock and carbon emission in the southeast coastal provinces is higher than those of other regions under all scenarios. At the same time, they also have higher potential in reducing emission levels. Currently, most provinces have a very low EV share (generally below 2%). The electric vehicle industry will still be in a stage of rapid development in the next decade. In addition, affected by the performance of EVs, it is difficult to use EVs in cold regions (Heilongjiang, Jilin, Liaoning) and western regions (Gansu, Qinghai, Ningxia). The provincial promotion in EVs will hence be an important research topic. The EV share of passenger cars in Shanghai, Beijing, Tianjin, and Hainan is higher. These four provinces can be used as first pilot provinces in banning the sale of ICEVs.

6 Conclusion

We build a scenario-based assessment framework for China's provincial-level projection of passenger vehicle growth and CO₂ emissions under shared socioeconomic pathways (SSPs). The results indicate that the single EV policy (shift ICEVs to EVs) can only reduce emissions by 71% in 2060 but that the SEV (shared EVs) scenario achieves almost 83% mitigation. Both scenarios presuppose improved vehicle efficiency and reduced carbon intensity in the EV production and rapid upscaling of low-carbon renewable power. China's provincial difference in passenger vehicle stocks and emission release show that



the southeastern coastal provinces are huge polluters, but also suitable for advancing EV production. Together, these results demonstrate the importance of fostering rapid technological change hand-in-hand with a reorganization of motorized mobility towards shared pooled transport.

This work is not without limitations. The conclusions are dependent on a large series of assumptions on model parameters and input data, including the share of EV sales, maximum saturation level in car ownership, and carbon intensity. Although settings in this work are based on historical data and related studies, the results in the sensitivity analysis show the uncertainty of these parameters. A large-scale shift to electric vehicles and shared mobility depends on the provision of infrastructure, whose construction will include its own CO₂ footprint. Due to the current diversity in types and forms of automotive batteries, coupled with rapid technological iterations, obtaining some uncertain parameters such as battery life and replacement has become extremely challenging. Although this part of the emissions is beyond the scope of this work, they will require more attention when developing future EV and shared mobility policies.

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Data availability The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request.

Declarations

Conflict of interest The authors declare no competing interests.

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