RETRACTION NOTE

Retraction Note: Alternating-direction-method-of-multipliers-based fast model predictive control for an aerial trees-pruning robot

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The Publisher has retracted this article in agreement with the Editor-in-Chief. The article was submitted to be part of a guest-edited issue. An investigation by the publisher found a number of articles, including this one, with a number of concerns,

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The online version of the original article can be found at https://doi.org/10.1007/s10878-023-01071-0.

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including but not limited to compromised editorial handling and peer review process, inappropriate or irrelevant references or not being in scope of the journal or guest-edited issue. Based on the investigation's findings the publisher, in consultation with the Editor-in-Chief therefore no longer has confidence in the results and conclusions of this article.

The authors have not responded to correspondence regarding this retraction.

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