## **EDITORIAL**



## From the Editor-in-Chief

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## Dear Colleagues:

The issue at hand completes Volume 85, the first Volume of 2017. It is a double issue composed of five contributed papers and special issue papers. The special issue is on Applications on Non-Linear Techniques in Robot Control. All special issue papers have gone through the same thorough review process as contributed papers.

Enjoy the issue.

Kimon P. Valavanis Editor-in-Chief

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