

## From the Editor-in-Chief

**Kimon P. Valavanis**

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Dear Colleagues,

This is a 'double issue'. Most of the papers, a total of five, compose the Special Issue on Airborne Simultaneous Localization and Mapping, A-SLAM, coordinated by Dr. Nabil Aouf from the University of Cranfield. All five accepted papers went through a double thorough review and they were picked out of all those submitted for the Special Issue.

Two more regular papers are included to complete this double issue.

I want to thank Nabil for his efforts to coordinate with me the review process and his enthusiasm to publish this issue. I hope that this sparks additional interest for special issues.

Enjoy the issue.



Kimon P. Valavanis  
Editor-in-Chief

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