Appearance-based mapping using minimalistic sensor models

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The original version of this article unfortunately contained a typographical error; this is a publisher error. The presentation of Equation 23 should be corrected. The corrected version is given below.

$$X = \hat{X} + \left(\sum_{i=1}^{n-1} H_{y_i}^T P_i^{-1} H_{y_i} + \sum_{i=1}^n H_{z_i}^T R_i^{-1} H_{z_i} \right)^{-1} \left(\sum_{i=1}^{n-1} H_{y_i} P_i^{-1} (y_i - h_{y_i}(\hat{X})) + \sum_{i=1}^n H_{z_i} R_i^{-1} (z_i - h_{z_i}(\hat{X})) \right).$$

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