

Stability of Einstein metrics on symmetric spaces of compact type

Paul Schwahn¹

Received: 11 May 2021 / Accepted: 11 October 2021 / Published online: 26 November 2021 © The Author(s) 2021

Abstract

We prove the linear stability with respect to the Einstein-Hilbert action of the symmetric spaces SU(n), $n \ge 3$, and E_6/F_4 . Combined with earlier results, this resolves the stability problem for irreducible symmetric spaces of compact type.

Keywords Symmetric spaces · Einstein metrics · Stability · Lichnerowicz Laplacian

Mathematics Subject Classification 53C24 · 53C25 · 53C30 · 53C35

1 Introduction

Let M be a closed manifold of dimension n > 2. It is a well-known fact (see [2]) that Einstein metrics are critical points of the total scalar curvature functional

$$g \mapsto S(g) = \int_M \operatorname{scal}_g \operatorname{vol}_g,$$

also called the Einstein-Hilbert action, restricted to the space of Riemannian metrics of a fixed volume. In general, these critical points are neither maximal nor minimal. If we, however, restrict S to the set $\mathfrak S$ of all Riemannian metrics on M of the same fixed volume that have constant scalar curvature, then some Einstein metrics are maximal, while others form saddle points. To examine this, one considers the second variation S_g'' of S at a fixed Einstein metric g on M. If we exclude the case where (M, g) is a standard sphere, the tangent space of $\mathfrak S$ at g consists precisely of tt-tensors, i.e. symmetric 2-tensors that are transverse (divergence-free) and traceless. In these directions, the coindex and nullity of S_g'' are always finite. The stability problem is to decide whether they vanish for a given Einstein manifold (M, g).

The stability of an Einstein metric g is determined by the spectrum of a Laplace-type operator Δ_L , called the Lichnerowicz Laplacian, on tt-tensors. There is a critical eigenvalue, corresponding to null directions for S_g'' , which is equal to 2E, where E is the Einstein constant of g. The metric g is called *linearly (strictly) stable* if $\Delta_L \geq 2E$ (resp. $\Delta_L > 2E$)

Institut f
ür Geometrie und Topologie, Fachbereich Mathematik, Universit
ät Stuttgart, Pfaffenwaldring 57, 70569 Stuttgart, Germany



 [□] Paul Schwahn paul.schwahn@mathematik.uni-stuttgart.de

on tt-tensors, and *infinitesimally deformable* if there is a tt-eigentensor of Δ_L for the critical eigenvalue.

Suppose that (M,g) is a locally symmetric Einstein manifold of compact type. The Cartan–Ambrose–Hicks theorem implies that its universal cover (\tilde{M},\tilde{g}) is a simply connected symmetric space. As such, (\tilde{M},\tilde{g}) can be written as a Riemannian product of irreducible symmetric spaces of compact type. For many of these spaces, the stability problem has been decided by N. Koiso. The following theorem collects the results of Koiso in [10] together with a result of J. Gasqui and H. Goldschmidt in [7] about the complex quadric $SO(5)/(SO(3) \times SO(2))$.

Theorem 1.1 1. The only irreducible symmetric spaces of compact type that are infinitesimally deformable are

$$SU(n)$$
, $SU(n)/SO(n)$, $SU(2n)/Sp(n)$ $(n \ge 3)$, $SU(p+q)/S(U(p) \times U(q))$ $(p \ge q \ge 2)$,

as well as E_6/F_4 .

2. The irreducible symmetric spaces

$$\operatorname{Sp}(n) \ (n \ge 2), \ \operatorname{Sp}(n)/\operatorname{U}(n) \ (n \ge 3),$$

as well as the complex quadric $SO(5)/(SO(3) \times SO(2))$ are unstable.

3. Let (M, g) be an irreducible symmetric space of compact type. If (M, g) is none of the spaces from 1. and 2., nor one of

$$\operatorname{Sp}(p+q)/(\operatorname{Sp}(p)\times\operatorname{Sp}(q)) \quad (p\geq q\geq 2 \text{ or } p=2, q=1)$$

nor F_4 /Spin(9), then g is strictly stable.

Moreover, the smallest eigenvalue of Δ_L on trace-free symmetric 2-tensors has been computed in each case (see [3]). Among the spaces that possess infinitesimal deformations, we have $\Delta_L \geq 2E$ on $\mathscr{S}_0^2(M)$ on the spaces

$$SU(n)/SO(n)$$
, $SU(2n)/Sp(n)$ $(n \ge 3)$, $SU(p+q)/S(U(p) \times U(q))$ $(p \ge q \ge 2)$,

which shows that they are linearly stable.

However, this did not fully settle the stability problem on irreducible symmetric spaces of compact type. In particular, it had not been decided whether unstable directions exist on the spaces

SU(n) (where
$$n \ge 3$$
), E_6/F_4 , $F_4/\operatorname{Spin}(9)$,
Sp $(p+q)/(\operatorname{Sp}(p) \times \operatorname{Sp}(q))$ (where $p \ge q \ge 2$ or $p=2, q=1$).

In these cases, we know that Δ_L has eigenvalues smaller than 2E on the space of trace-free symmetric 2-tensors, but it had not been checked whether the corresponding eigentensors are also divergence-free. In a recent paper [14], U. Semmelmann and G. Weingart show the following results.

Theorem 1.2 1. The quaternionic Grassmannians $\operatorname{Sp}(p+q)/(\operatorname{Sp}(p) \times \operatorname{Sp}(q))$ are linearly stable for p=2 and q=1, but unstable for $p\geq q\geq 2$.

2. The Cayley plane $\mathbb{O}P^2 = F_4/\operatorname{Spin}(9)$ is linearly stable.

The current article finally resolves the question of stability for the last remaining cases by proving the following.



Theorem 1.3 The symmetric spaces SU(n), where $n \geq 3$, as well as E_6/F_4 are linearly stable.

Consider a manifold (M, g) that is a Riemannian product of Einstein manifolds. Then (M, g) is Einstein if and only if the factors have the same Einstein constant E. It turns out that if E > 0, then (M, g) is always unstable (see [12], Prop. 3.3.7). For example, if (M, g) is the Riemannian product of two Einstein manifolds $(M_i^{n_i}, g_i)$ (i = 1, 2) with the same Einstein constant, then an unstable direction is given by

$$h := n_2 \pi_1^* g_1 - n_1 \pi_2^* g_2,$$

where $\pi_i: M \to M_i$ are the projections onto each factor, respectively. In particular, a product of symmetric spaces of compact type is always unstable since the factors have positive curvature.

If we take (M, g) to be locally symmetric of compact type, we cannot in general conclude its instability from the instability of its universal cover (\tilde{M}, \tilde{g}) . The same holds for the existence of infinitesimal Einstein deformations. On the other hand, if (\tilde{M}, \tilde{g}) is infinitesimally non-deformable (resp. stable), then the same follows for (M, g). In [11], N. Koiso has proved the infinitesimal non-deformability of a large class of such manifolds:

Theorem 1.4 Let (M, g) be a locally symmetric Einstein manifold of compact type. Let (\tilde{M}, \tilde{g}) be its universal cover and $(\tilde{M}, \tilde{g}) = \prod_{i=1}^{N} (M_i, g_i)$ its decomposition into irreducible symmetric spaces.

- 1. For N=1, see Theorem 1.1, 1.
- 2. If N = 2 and M_i are neither of the spaces listed in Theorem 1.1, 1., nor G_2 or any Hermitian space except S^2 , then (M, g) is infinitesimally non-deformable.
- 3. If $N \geq 3$ and M_i are neither of the above nor S^2 , then (M,g) is infinitesimally non-deformable.

A closely related notion of stability arises in the study of the Ricci flow. The fixed points (modulo diffeomorphisms and scaling) of the Ricci flow are called Ricci solitons. The *ventropy* defined by G. Perelman is a quantity that increases monotonically under the Ricci flow. Its critical points are the *shrinking gradient Ricci solitons*, which include Einstein manifolds. An Einstein metric is called *v-linearly stable* if the second variation of the *v*-entropy is negative-semidefinite. H.-D. Cao, R. Hamilton and T. Ilmanen first studied the *v*-linear stability of Einstein metrics (see [4]). It turns out that an Einstein metric is *v*-linearly stable if and only if $\Delta_L \geq 2E$ on tt-tensors and if the first nonzero eigenvalue of the ordinary Laplacian on functions is bounded below by 2E as well. In particular, *v*-linear stability implies linear stability with respect to the Einstein-Hilbert action. In [3], the *v*-linear stability of irreducible symmetric spaces of compact type is completely decided.

There is yet another notion of stability worth mentioning. It is motivated, for example, by the investigation of Anti-de Sitter product spacetimes and generalized Schwarzschild-Tangherlini spacetimes (see [5] or [8]). An Einstein manifold (M^n, g) with Einstein constant E is called *physically stable* if

$$\Delta_L \ge \frac{E}{n-1} \left(4 - \frac{1}{4} (n-5)^2 \right) = \frac{9-n}{4} E$$

on tt-tensors. This critical eigenvalue is significantly smaller than the one from stability with respect to the Einstein-Hilbert action, and even negative for n > 9. As it turns out, all irreducible symmetric spaces of compact type are physically stable (see [5]). If (M, g) is a



product of at least two symmetric spaces of compact type, then the smallest eigenvalue of Δ_L on tt-tensors is actually equal to 0; hence (M, g) is physically stable if and only if $n \ge 9$.

In Sect. 2, we fix the notation and definitions used throughout this work. In particular, we elaborate on the notion of stability of an Einstein metric. In Sect. 3, we recall some tools from the harmonic analysis of homogeneous spaces that are routinely employed. Furthermore, we prove a technical lemma that allows us to make explicit computations involving the divergence operator. A helpful formula for the dimension of tt-eigenspaces of the Lichnerowicz Laplacian is worked out in Sect. 4, generalizing a proposition of Koiso and utilizing properties of Killing vector fields on Einstein manifolds. Sect. 5 uses representation theory to determine the stability of SU(n), making use of the formula from Sect. 4; in Sect. 6, the same is done for E_6/F_4 . A different approach for proving the stability of both spaces that involves explicit computations of the divergence operator can be found in the Appendix.

2 Preliminaries

Throughout what follows, let (M, g) be a compact, orientable Riemannian manifold. Let ∇ denote the Levi-Civita connection of g. The Riemannian curvature tensor, Ricci tensor and scalar curvature are in our convention given as

$$R(X, Y)Z := \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X,Y]} Z,$$

$$Ric(X, Y) := tr(Z \mapsto R(Z, X)Y),$$

$$scal := tr_g Ric,$$

respectively. The action of the Riemannian curvature extends to an endomorphism on tensor bundles as

$$R(X, Y) = \nabla_X \nabla_Y - \nabla_Y \nabla_X - \nabla_{[X,Y]},$$

where ∇ also denotes the induced connection on the respective tensor bundle. Furthermore, let $\mathscr{S}^p(M) = \Gamma(\operatorname{Sym}^p T^*M)$ for $p \ge 0$. We denote by

$$\delta: \mathcal{S}^{p+1}(M) \to \mathcal{S}^p(M)$$

the divergence operator on symmetric tensors, given by

$$\delta = -\sum_{i} e_i \, \lrcorner \nabla_{e_i}.$$

The space of tt-tensors, i.e. trace- and divergence-free symmetric 2-tensors on M, is denoted by $\mathcal{S}_{r^2}^{r}(M)$.

Let $\delta^*: \mathscr{S}^p(M) \to \mathscr{S}^{p+1}(M)$ be the formal adjoint of the divergence operator. It can be written as

$$\delta^* = \sum_i e_i^{\flat} \odot \nabla_{e_i},$$

where (e_i) is a local orthonormal basis of TM. Here, \odot denotes the (associative) symmetric product, defined by

$$\alpha \odot \beta := \frac{(k+l)!}{k!l!} \operatorname{sym}(\alpha \otimes \beta)$$

² That is, with respect to the inner product $\langle \cdot, \cdot \rangle_g$ on $\operatorname{Sym}^p T^*M$ with orthonormal basis $(e_{i_1}^{\flat} \odot \ldots \odot e_{i_n}^{\flat})$.



 $^{^{1}}$ We use the index g only when the metric-dependence of an object is to be emphasized.

for $\alpha \in \operatorname{Sym}^k T$, $\beta \in \operatorname{Sym}^l T$, where T is any vector space and the symmetrization map $\operatorname{sym}: T^{\otimes k} \to \operatorname{Sym}^k T$ is given by

$$\operatorname{sym}(X_1 \otimes \ldots \otimes X_k) := \frac{1}{k!} \sum_{\sigma \in S_k} X_{\sigma(1)} \otimes \ldots \otimes X_{\sigma(k)}$$

for $X_1, \ldots, X_k \in T$. This is analogous to the definition of the wedge product via the alternation map. For tensors α, β of rank 1, we have

$$\alpha \odot \beta = \alpha \otimes \beta + \beta \otimes \alpha.$$

It should be noted that $\delta^* X^{\flat} = L_X g$ for any vector field $X \in \mathfrak{X}(M)$. Consequently, the kernel of δ^* on $\Omega^1(M)$ is (via the metric) isomorphic to the space of Killing vector fields on (M, g). More generally, symmetric tensors $\alpha \in \mathscr{S}^k(M)$ with $\delta^* \alpha = 0$ are called *Killing tensors* of rank k, and δ^* is sometimes called the *Killing operator*.

Definition 2.1 On tensors of any rank, the following operators are defined:

1. The *curvature endomorphism* q(R) is defined by

$$q(R) := \sum_{i < j} (e_i \wedge e_j)_* R(e_i, e_j),$$

where (e_i) is a local orthonormal basis of TM and the asterisk indicates the natural action of $\Lambda^2T \cong \mathfrak{so}(T)$.

2. The *Lichnerowicz Laplacian* Δ_L is defined by

$$\Delta_L := \nabla^* \nabla + q(R).$$

Recall that on $\Omega^p(M)$, p > 0, this coincides with the Hodge Laplacian Δ .

On the space of Riemannian metrics on M, which is an open cone in $\mathcal{S}^2(M)$, the *total scalar curvature functional* or *Einstein-Hilbert action* is given by

$$S(g) = \int_{M} \operatorname{scal}_{g} \operatorname{vol}_{g}$$

for any Riemannian metric g on M. As mentioned earlier, if we restrict this functional to the space of metrics of a fixed total volume, then Einstein metrics are precisely the critical points of the restriction of S.

Let (M, g) be an Einstein manifold with Einstein constant $E \in \mathbb{R}$, that is

$$Ric = Eg$$
,

and suppose that (M, g) is not isometric to a standard round sphere. Denote

$$C_g^{\infty}(M) = \left\{ f \in C^{\infty}(M) \middle| \int_M f \operatorname{vol}_g = 0 \right\}.$$

It is well known (see [2]) that there is a decomposition of $\mathcal{S}^2(M)$, which is orthogonal with respect to the second variation S_g'' of the total scalar curvature functional, into the four summands

$$\mathscr{S}^2(M) = \mathbb{R}g \oplus C_g^{\infty}(M)g \oplus \operatorname{im} \delta^* \oplus \mathscr{S}_{\operatorname{tt}}^2(M).$$



These correspond to infinitesimal changes in the metric by homothety, volume-preserving conformal scaling, the action of diffeomorphisms, and moving within \mathfrak{S} , respectively. The second variation S_p'' is positive on $C_p^{\infty}(M)g$, zero on im δ^* and is given by

$$S_g''(h, h) = -\frac{1}{2} (\Delta_L h - 2Eh, h)_g$$

on $\mathscr{S}^2_{\mathrm{tt}}(M)$, where it has finite coindex and nullity; that is, the maximal subspace of $\mathscr{S}^2_{\mathrm{tt}}(M)$ where S''_g is nonnegative is finite-dimensional. In fact, the null directions in $\mathscr{S}^2_{\mathrm{tt}}(M)$ are precisely the *infinitesimal Einstein deformations* of g, i.e. infinitesimal deformations of g that preserve the Einstein property, the total volume and are orthogonal to the orbit of g under diffeomorphisms.

Definition 2.2 An Einstein metric g on M is called

- 1. (linearly) stable (with respect to the Einstein-Hilbert action) if $S_g'' \leq 0$ on $\mathcal{S}_{tt}^2(M)$ or, equivalently, if $\Delta_L \geq 2E$ on $\mathcal{S}_{tt}^2(M)$. Otherwise it is called (linearly) unstable.
- 2. strictly (linearly) stable (with respect to the Einstein-Hilbert action) if $S_g'' < 0$ on $\mathcal{S}_{tt}^2(M)$ or, equivalently, if $\Delta_L > 2E$ on $\mathcal{S}_{tt}^2(M)$.
- 3. *infinitesimally deformable* if $\Delta_L h = 2Eh$ for some nonzero $h \in \mathscr{S}^2_{tt}(M)$.

3 Invariant differential operators

Let G be a compact Lie group with Lie algebra $\mathfrak g$ and K a closed subgroup such that (M=G/K,g) is a reductive Riemannian homogeneous space with K-invariant decomposition $\mathfrak g=\mathfrak k\oplus\mathfrak m$, where $\mathfrak k$ is the Lie algebra of K and $\mathfrak m$ is the reductive complement which is canonically identified with the tangent space T_oM at the base point $o:=eK\in M$. Recall that for some representation $\rho:K\to \operatorname{Aut} V$, the *left-regular representation* on the space of K-equivariant smooth functions $C^\infty(G,V)^K$ is defined as

$$\ell: G \to \operatorname{Aut} C^{\infty}(G, V)^{K}: (\ell(x) f)(y) := f(x^{-1}y)$$

for $x, y \in G$. Furthermore, the space $C^{\infty}(G, V)^K$ is identified with the space of sections of the associated bundle $G \times_{\varrho} V$ over M. The identification is given by

$$\Gamma(G \times_{o} V) \to C^{\infty}(G, V)^{K} : s \mapsto \hat{s},$$

where \hat{s} is defined by $s([x]) = [x, \hat{s}(x)]$ for any $x \in G$. If V can be expressed in terms of the isotropy representation \mathfrak{m} , then $G \times_{\rho} V$ is a tensor bundle; for example, we have

$$\begin{split} \mathfrak{X}(M) &= \varGamma(TM) \cong \varGamma(G \times_{\rho} \mathfrak{m}) \cong C^{\infty}(G, \mathfrak{m})^{K}, \\ \Omega^{1}(M) &= \varGamma(T^{*}M) \cong \varGamma(G \times_{\rho} \mathfrak{m}^{*}) \cong C^{\infty}(G, \mathfrak{m})^{K}, \\ \mathscr{S}^{2}(M) &= \varGamma(\operatorname{Sym}^{2} T^{*}M) \cong \varGamma(G \times_{\rho} \operatorname{Sym}^{2} \mathfrak{m}^{*}) \cong C^{\infty}(G, \operatorname{Sym}^{2} \mathfrak{m})^{K}, \\ \mathscr{S}^{2}_{0}(M) &= \varGamma(\operatorname{Sym}^{2} T^{*}M) \cong \varGamma(G \times_{\rho} \operatorname{Sym}^{2} \mathfrak{m}^{*}) \cong C^{\infty}(G, \operatorname{Sym}^{2} \mathfrak{m})^{K}, \end{split}$$

where Sym_0^2 , \mathscr{S}_0^2 denotes the space of trace-free elements with respect to the metric. Note that the invariant Riemannian metric yields an equivalence between \mathfrak{m} and \mathfrak{m}^* .

Suppose that V is a complex representation. Choose a maximal torus T inside G with Lie algebra t. Recall that up to equivalence, every irreducible finite-dimensional complex



representation of G is characterized by its highest weight $\gamma \in \mathfrak{t}^*$. By the Peter-Weyl theorem and Frobenius reciprocity (cf. [15]), the left-regular representation $C^{\infty}(G,V)^K$ can be decomposed into irreducible summands as³

$$C^{\infty}(G, V)^K \cong \overline{\bigoplus_{\gamma}} V_{\gamma} \otimes \operatorname{Hom}_K(V_{\gamma}, V),$$
 (PW)

where γ runs over all highest weights of *G*-representations and $(V_{\gamma}, \rho_{\gamma})$ is the (up to equivalence) unique irreducible representation of *G* with highest weight γ . For any

$$\alpha \otimes A \in V_{\gamma} \otimes \operatorname{Hom}_{K}(V_{\gamma}, V),$$

the corresponding element of $C^{\infty}(G, V)^K$ is defined by

$$f_{\alpha}^{A}: G \to V: x \mapsto A(\rho_{\gamma}(x^{-1})\alpha).$$

Since the Lichnerowicz Laplacian Δ_L on $\Gamma(G \times_{\rho} V)$ is a G-invariant differential operator, Schur's Lemma implies that on each of the isotypical subspaces

$$V_{\gamma} \otimes \operatorname{Hom}_{K}(V_{\gamma}, V),$$

 Δ_L acts as an endomorphism of the finite-dimensional vector space $\operatorname{Hom}_K(V_{\gamma}, V)$, that is,

$$\Delta_L f_{\alpha}^A = f_{\alpha}^{L_{\gamma}(A)}$$

for some $L_{\gamma} \in \text{End Hom}_K(V_{\gamma}, V)$.

In order to obtain the spectrum of Δ_L , one would have to find the eigenvalues of each L_{γ} – a potentially very cumbersome task. We will shortly see that this matter is considerably simpler in the symmetric case.

Fix an Ad-invariant inner product $\langle \cdot, \cdot \rangle_{\mathfrak{g}}$ on the Lie algebra \mathfrak{g} . If we assume that G is semisimple, one such inner product is given by -B, where B is the Killing form on \mathfrak{g} , defined by

$$B(X, Y) := \operatorname{tr}(\operatorname{ad}(X) \circ \operatorname{ad}(Y))$$

for $X, Y \in \mathfrak{g}$. Recall that for any representation $\pi : G \to \operatorname{Aut} W$, the Casimir operator $\operatorname{Cas}_{\pi}^{G}$ with respect to the chosen inner product is an equivariant endomorphism of W, defined as

$$\operatorname{Cas}_{\pi}^G := -\sum_i d\pi(e_i) \circ d\pi(e_i)$$

for any orthonormal basis (e_i) of \mathfrak{g} .

The following proposition combines two well-known results that allow us to compute the eigenvalues of Δ_L on compact symmetric spaces, the latter being a formula due to H. Freudenthal (cf. [6]).

Proposition 3.1 Let (M = G/K, g) be a compact Riemannian symmetric space where the Riemannian metric is induced by an Ad-invariant inner product $\langle \cdot, \cdot \rangle_{\mathfrak{g}}$ on \mathfrak{g} , and let $\rho : K \to \operatorname{Aut} V$ be a representation.

1. On the left-regular representation $\Gamma(G \times_{\rho} V)$, the Lichnerowicz Laplacian Δ_L coincides with the Casimir operator Cas_{ℓ}^G of the representation $\ell: G \to \mathsf{Aut}\ \Gamma(G \times_{\rho} V)$.

³ Here, the bar over the direct sum denotes the closure in $C^{\infty}(G,V)^K$ (with the L^2 inner product). In other words, $\bigoplus_{\gamma} V_{\gamma} \otimes \operatorname{Hom}_K(V_{\gamma},V)$ is dense in $C^{\infty}(G,V)^K$. In fact, it is dense in $L^2(G,V)^K$, but for our purposes, it suffices to consider smooth sections.



2. On each irreducible representation V_{ν} , the Casimir eigenvalue is given by

$$\operatorname{Cas}_{\gamma}^G = \langle \gamma, \gamma + 2\delta_{\mathfrak{g}} \rangle_{\mathfrak{t}^*},$$

where $\delta_{\mathfrak{g}}$ is the half-sum of positive roots and $\langle \cdot, \cdot \rangle_{\mathfrak{t}^*}$ is the inner product on \mathfrak{t}^* induced by the inner product on $\mathfrak{t} \subset \mathfrak{g}$.

Remark 3.2 The first statement is a consequence of a more general result. Let G be a compact Lie group and (M = G/K, g) be a reductive Riemannian homogeneous space. To the reductive decomposition corresponds a canonical G-invariant connection on M (also called the *Ambrose-Singer connection*), which we denote by $\bar{\nabla}$. This connection in turn defines a curvature tensor \bar{R} and an analogue to the Lichnerowicz Laplacian via

$$\bar{\Delta} := \bar{\nabla}^* \bar{\nabla} + q(\bar{R}),$$

called the *standard Laplacian* of this connection (introduced in [13]). Then, in fact, $\bar{\Delta} = \operatorname{Cas}_{\ell}^G$ on $\Gamma(G \times_{\rho} V)$. The above statement follows when we note that on Riemannian symmetric spaces, the Ambrose-Singer connection coincides with the Levi-Civita connection.

According to (PW), we can write the complexified left-regular representation on trace-free symmetric 2-tensors as

$$\mathscr{S}_0^2(M)^{\mathbb{C}} \cong \overline{\bigoplus_{\gamma}} V_{\gamma} \otimes \operatorname{Hom}_K(V_{\gamma}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}).$$

Recall that irreducible symmetric spaces of compact type can be endowed with a Riemannian metric induced by the Killing form (the so-called standard metric). In this case, the critical eigenvalue of Δ_L is 2E=1. Supposing we have a representation V_γ with subcritical Casimir eigenvalue $\operatorname{Cas}_\gamma^G < 1$ occurring in this decomposition, it remains to check whether the tensors in the corresponding subspace are divergence-free. By Schur's Lemma, the G-invariant operator

$$\delta: \mathscr{S}_0^2(M)^{\mathbb{C}} \to \Omega^1(M)^{\mathbb{C}}$$

is constant on each irreducible subspace. This means that we can regard δ as a linear mapping

$$\delta: \operatorname{Hom}_K(V_{\nu}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) \to \operatorname{Hom}_K(V_{\nu}, \mathfrak{m}^{\mathbb{C}}),$$

the so-called *prototypical differential operator* associated to δ and V_{γ} . For a further discussion of invariant differential operators on homogeneous spaces, we refer the reader to Section 2 of [14].

The following lemma is of use when we need to calculate δ explicitly. A derivation of essentially the same formula can also be found in [14], Section 2.

Lemma 3.3 Suppose (M, g) is a Riemannian symmetric space. Let $h \in \mathcal{S}^2(M)^{\mathbb{C}}$ correspond to an element

$$\alpha \otimes A \in V_{\gamma} \otimes \operatorname{Hom}_{K}(V_{\gamma}, \operatorname{Sym}^{2} \mathfrak{m}^{\mathbb{C}})$$

in the decomposition (PW) of $\mathscr{S}^2(M)^{\mathbb{C}}$. Let further (e_i) be an orthonormal basis of \mathfrak{m} . Then we have

$$(\delta h)_o(X) = \sum_i \langle A(d\rho_\gamma(e_i)\alpha), e_i \odot X \rangle$$

for any $X \in \mathfrak{m} \cong T_o M$.



Proof The element of $C^{\infty}(G, \operatorname{Sym}^2 \mathfrak{m}^{\mathbb{C}})^K$ corresponding to $h \in \mathscr{S}^2(M)$ is given by

$$\hat{h} = f_{\alpha}^{A} : G \to \operatorname{Sym}^{2} \mathfrak{m}^{\mathbb{C}} : x \mapsto A(\rho_{\nu}(x^{-1})\alpha),$$

where ρ_{γ} is the representation of G on V_{γ} . The covariant derivative of h at the base point may be expressed by

$$(\nabla h)_o(X, Y) = \langle d\hat{h}_e, X \odot Y \rangle$$

for $X, Y \in \mathfrak{m} \cong T_oM$, since ∇ coincides with the Ambrose-Singer connection on M as a reductive homogeneous space. This implies that

$$\begin{split} (\delta h)_o(X) &= -\sum_i e_i \, \lrcorner \nabla_{e_i} h(X) = -\sum_i \nabla_{e_i} h(e_i, X) = -\sum_i \langle d\hat{h}(e_i), e_i \odot X \rangle \\ &= -\sum_i \langle df_\alpha^A(e_i), e_i \odot X \rangle = \sum_i \langle A(d\rho_\gamma(e_i)\alpha), e_i \odot X \rangle. \end{split}$$

4 tt-Eigenspaces of the Lichnerowicz Laplacian

We return to the general setting of a compact Einstein manifold (M, g). Define

$$\theta: \Omega^1(M) \to \mathscr{S}_0^2(M): \alpha \mapsto \delta^*\alpha + \frac{2}{n}\delta\alpha \cdot g,$$

so that $\theta \alpha$ is precisely the trace-free part of $\delta^* \alpha \in \mathscr{S}^2(M)$. The kernel of this operator is (via the metric) isomorphic to the space of *conformal Killing fields* on (M, g), that is, the space of vector fields $X \in \mathfrak{X}(M)$ such that $L_X g = fg$ for some $f \in C^{\infty}(M)$. We thus call θ the *conformal Killing operator*.

The following lemma is a generalization of a proposition by Koiso [11, Prop. 3.3]. For the proof, we refer the reader to the Appendix.

Lemma 4.1 Let (M, g) be a compact Einstein manifold of dimension $n \ge 3$. For any $\lambda \in \mathbb{R}$, the dimension of the eigenspace of Δ_L to the eigenvalue λ on tt-tensors is given by

$$\begin{split} \dim \ker (\Delta_L - \lambda) \big|_{\mathscr{S}^2_{\mathrm{tt}}(M)} &= \dim \ker (\Delta_L - \lambda) \big|_{\mathscr{S}^2_0(M)} - \dim \ker (\Delta - \lambda) \big|_{\Omega^1(M)} \\ &+ \dim \left(\ker (\Delta - \lambda) \big|_{\Omega^1(M)} \cap \ker \theta \right). \end{split}$$

At first glance, the third term on the right hand side of the above formula does not look very amenable to computation. However, matters are made easier if we observe the following properties of (conformal) Killing vector fields on Einstein manifolds, both of which are proven in the Appendix.

Lemma 4.2 On any compact Einstein manifold (M, g) not isometric to a standard round sphere, conformal Killing fields are actually Killing, that is, $L_X g = fg$ for some $f \in C^{\infty}(M)$ implies f = 0. Equivalently, $\ker \theta = \ker \delta^*$ on $\Omega^1(M)$.

Lemma 4.3 Any Killing field $X \in \mathfrak{X}(M)$ on an Einstein manifold with Einstein constant E satisfies

$$\Delta X^{\flat} = 2EX^{\flat}.$$

Equivalently, ker $\delta^* \subset \ker(\Delta - 2E)$ on $\Omega^1(M)$.



If we assume that (M, g) is not isometric to a standard sphere, we can immediately conclude that the intersection $\ker(\Delta - \lambda)|_{\Omega^1(M)} \cap \ker \theta$ is trivial if $\lambda \neq 2E$. By virtue of Lemma 4.1, we obtain the following.

Corollary 4.4 Let (M, g) be a compact Einstein manifold that is not isometric to a standard round sphere, and let E be its Einstein constant. For any $\lambda \neq 2E$, the dimension of the eigenspace of Δ_L to the eigenvalue λ on tt-tensors is given by

$$\dim \ker(\Delta_L - \lambda) \big|_{\mathscr{L}^2_n(M)} = \dim \ker(\Delta_L - \lambda) \big|_{\mathscr{L}^2_n(M)} - \dim \ker(\Delta - \lambda) \big|_{\Omega^1(M)}.$$

Remark 4.5 If we set $\lambda = 2E$ in Lemma 4.1 and note that

$$\ker(\Delta - 2E)\big|_{\Omega^1(M)} \cap \ker \theta = \ker \delta^*\big|_{\Omega^1(M)}$$

(as Koiso did in his proof of [11, Prop. 3.3]), we recover the original formula for the critical eigenvalue

$$\dim \ker(\Delta_L - 2E)\big|_{\mathscr{S}^2_{\operatorname{tt}}(M)} = \dim \ker(\Delta_L - 2E)\big|_{\mathscr{S}^2_0(M)} - \dim \ker(\Delta - 2E)\big|_{\Omega^1(M)} + \dim \ker \delta^*\big|_{\Omega^1(M)}.$$

Remark 4.6 Although the dimension formula of Lemma 4.1 works on any compact Einstein manifold (M, g), it is worth mentioning that if additionally, (M, g) carries the structure of a Riemannian homogeneous space M = G/K, the result can be refined in terms of irreducible representations of G. Namely, if V_{γ} is an irreducible representation of G, then the multiplicity of V_{γ} in the (complexified) left-regular representation on tt-tensors is given by

$$\dim \operatorname{Hom}_{G}(V_{\gamma}, \mathscr{S}^{2}_{\operatorname{tt}}(M)^{\mathbb{C}}) = \dim \operatorname{Hom}_{K}(V_{\gamma}, \operatorname{Sym}_{0}^{2} \mathfrak{m}^{\mathbb{C}}) - \dim \operatorname{Hom}_{K}(V_{\gamma}, \mathfrak{m}^{\mathbb{C}}) + \dim \operatorname{Hom}_{G}(V_{\gamma}, (\ker \theta)^{\mathbb{C}}).$$

As in the proof of Lemma 4.1, the dimension formula essentially arises from the short exact sequence

$$0 \longrightarrow \ker \theta \stackrel{\subset}{\longrightarrow} \Omega^1(M) \stackrel{\theta}{\longrightarrow} \mathscr{S}_0^2(M) \stackrel{P}{\longrightarrow} \mathscr{S}_{tt}^2(M) \longrightarrow 0$$

and the fact that the Laplacian commutes with every arrow. In the homogeneous case, we note that we have a short exact sequence of *G*-representations and use Frobenius reciprocity to arrive at the statement.

5 The symmetric space SU(n)

Throughout what follows, let $n \ge 3$. As a symmetric space, SU(n) = G/K where $G = SU(n) \times SU(n)$ and K = SU(n) is diagonally embedded, i.e. via

$$SU(n) \hookrightarrow SU(n) \times SU(n) : k \mapsto (k, k).$$

Let $\mathfrak g$ and $\mathfrak k$ denote the corresponding Lie algebras of G and K, respectively. We endow M with the standard metric g induced by the Killing form on $\mathfrak g$. Hence, M is Einstein with critical eigenvalue 2E=1. The reductive decomposition of $\mathfrak g$ with respect to g is given by

$$\mathfrak{g}=\tilde{\mathfrak{k}}\oplus\mathfrak{m},$$



where

$$\begin{split} \tilde{\mathfrak{k}} &= \{(X, X) \mid X \in \mathfrak{k}\}, \\ \mathfrak{m} &= \{(X, -X) \mid X \in \mathfrak{k}\}. \end{split}$$

The K-representations \mathfrak{k} , $\tilde{\mathfrak{k}}$ and \mathfrak{m} are all equivalent. We denote by $E=\mathbb{C}^n$ the standard representation of K.

Lemma 5.1 Let V_{γ} be an irreducible complex representation of G with $\operatorname{Cas}_{\gamma}^G < 1$ and

$$\operatorname{Hom}_K(V_{\gamma},\operatorname{Sym}_0^2\mathfrak{k}^{\mathbb{C}})\neq 0.$$

Then V_{ν} is equivalent to one of the G-representations $E \otimes E^*$ and $E^* \otimes E$. In fact,

$$\dim \operatorname{Hom}_K(V_{\nu}, \operatorname{Sym}_0^2 \mathfrak{k}^{\mathbb{C}}) = 1$$

and the Casimir eigenvalue is $\operatorname{Cas}_{\gamma}^G = \frac{(n-1)(n+1)}{n^2}$.

Proof Let t be the torus of diagonal matrices in \mathfrak{k} . The dual \mathfrak{t}^* is generated by the weights $\varepsilon_1, \ldots, \varepsilon_n$ of the defining representation E. Explicitly,

$$\varepsilon_j(X) = X_j, \quad 1 \le j \le n$$

for $X = \operatorname{diag}(iX_1, \dots, iX_n) \in \mathfrak{t}$. Note that $\varepsilon_1 + \dots + \varepsilon_n = 0$.

Fix the ordering on roots and weights such that the simple roots of £ are given by

$$\varepsilon_j - \varepsilon_{j+1}, \quad 1 \le j \le n-1.$$

The semigroup of dominant integral weights is then generated by the fundamental weights

$$\omega_j = \sum_{k=1}^{j} \varepsilon_j, \quad 1 \le j \le n-1,$$

cf. [6, $\S15.1$]. The highest weights of representations of K, i.e. all the dominant integral weights, are precisely the linear combinations

$$\gamma = \sum_{r=1}^{n-1} a_r \omega_r$$

with coefficients $a_r \in \mathbb{N}_0$. The fundamental weights themselves correspond to the representations

$$V_{\omega_r} = \Lambda^r E \cong \Lambda^{n-r} E^*.$$

Let $\gamma, \gamma' \in \mathfrak{t}^*$ be two dominant integral weights. In particular, they satisfy

$$\langle \gamma, \gamma' \rangle_{\mathfrak{t}^*} \geq 0.$$

Using Freudenthal's formula for the Casimir operator $\operatorname{Cas}_{\gamma}^K$ of a K-representation V_{γ} , this implies the estimate

$$\begin{aligned} \operatorname{Cas}_{\gamma+\gamma'}^K &= \langle \gamma + \gamma' + 2\delta_{\mathfrak{k}}, \gamma + \gamma' \rangle_{\mathfrak{t}^*} = \langle \gamma + 2\delta_{\mathfrak{k}}, \gamma \rangle_{\mathfrak{t}^*} + 2\langle \gamma, \gamma' \rangle_{\mathfrak{t}^*} + \langle \gamma' + 2\delta_{\mathfrak{k}}, \gamma' \rangle_{\mathfrak{t}^*} \\ &\geq \langle \gamma + 2\delta_{\mathfrak{k}}, \gamma \rangle_{\mathfrak{t}^*} + \langle \gamma' + 2\delta_{\mathfrak{k}}, \gamma' \rangle_{\mathfrak{t}^*} = \operatorname{Cas}_{\gamma}^K + \operatorname{Cas}_{\gamma'}^K. \end{aligned}$$



In particular, we obtain

$$\operatorname{Cas}_{\gamma}^{K} \ge \sum_{r} a_{r} \operatorname{Cas}_{\omega_{r}}^{K}$$
 (*)

for $\gamma=\sum_{r=1}^{n-1}a_r\omega_r$. The Casimir eigenvalues of the fundamental representations are given as

$$\operatorname{Cas}_{\omega_r}^K = \frac{(n+1)r(n-r)}{2n^2}$$

for r = 1, ..., n - 1. Note that this expression is symmetric around $r = \frac{n}{2}$ and strictly increasing for $r \leq \frac{n}{2}$. Furthermore, we can compute that

$$\begin{aligned} \operatorname{Cas}_{\omega_{1}}^{K} &= \frac{(n+1)(n-1)}{2n^{2}} < 1, \\ \operatorname{Cas}_{\omega_{2}}^{K} &= \frac{(n+1)(n-2)}{n^{2}} < 1, \\ \operatorname{Cas}_{\omega_{3}}^{K} &= \begin{cases} \frac{7}{8} < 1, & n=6, \\ \frac{48}{49} < 1, & n=7, \\ \frac{3(n+1)(n-3)}{2n^{2}} > 1, & n \geq 8, \end{cases} \\ \operatorname{Cas}_{\omega_{1}}^{K} + \operatorname{Cas}_{\omega_{2}}^{K} > 1, & n \geq 4, \\ \operatorname{Cas}_{\omega_{1}+\omega_{n-1}}^{K} &= 1, \end{aligned}$$

cf. table on p. 15 of [14]. Combining the above with inequality (*), we can deduce that if γ is a highest weight with $\operatorname{Cas}_{\nu}^{K} < 1$, then necessarily

$$\gamma \in \{0, \omega_1, \omega_{n-1}, \omega_2, \omega_{n-2}, \underbrace{\omega_3, \omega_{n-3}}_{\text{if } n=6,7}\}.$$

These dominant integral weights are, respectively, highest weights of the representations \mathbb{C} , $E, E^*, \Lambda^2 E, \Lambda^2 E^*, \Lambda^3 E, \Lambda^3 E^*$ of K.

The irreducible representations of $G = K \times K$ are precisely the tensor products of irreducible representations of K. Let γ, γ' be highest weights of K-representations such that

$$\operatorname{Cas}_{(\gamma,\gamma')}^G = \operatorname{Cas}_{\gamma}^K + \operatorname{Cas}_{\gamma'}^K < 1$$

holds. Assuming that $\gamma, \gamma' \neq 0$, we conclude that $\gamma, \gamma' \in \{\omega_1, \omega_{n-1}\}$. This yields the four pairwise inequivalent G-representations $E \otimes E$, $E \otimes E^*$, $E^* \otimes E$ and $E^* \otimes E^*$. Furthermore, in the case of $\gamma = 0$ or $\gamma' = 0$ we obtain the representations of K that were listed above, composed with the projection onto one factor,

$$G \to K : (k_1, k_2) \mapsto k_1 \text{ or } (k_1, k_2) \mapsto k_2,$$

respectively. By restricting the mentioned G-representations to K via the embedding

$$K \to G : k \mapsto (k, k),$$

we again obtain the irreducible K-representations \mathbb{C} , E, E^* , $\Lambda^2 E$, $\Lambda^2 E^*$, $\Lambda^3 E$, $\Lambda^3 E^*$ as well as the tensor product representations $E \otimes E$, $E \otimes E^*$ and $E^* \otimes E^*$. The latter are not



irreducible, but decompose into irreducible summands as follows:

$$E \otimes E = \operatorname{Sym}^{2} E \oplus \Lambda^{2} E,$$

$$E \otimes E^{*} = E \otimes_{0} E^{*} \oplus \mathbb{C},$$

$$E^{*} \otimes E^{*} = \operatorname{Sym}^{2} E^{*} \oplus \Lambda^{2} E^{*}.$$

Here $E \otimes_0 E^*$ is the set of trace-free elements of $E \otimes E^*$ when regarded as $n \times n$ -matrices over \mathbb{C} . As a representation of K, we have

$$E \otimes_0 E^* \cong V_{\omega_1 + \omega_{n-1}} \cong \mathfrak{k}^{\mathbb{C}}.$$

The *K*-representation Sym² $\mathfrak{k}^{\mathbb{C}} \cong \text{Sym}^2(E \otimes_0 E^*)$ appears on one hand as a summand of

$$\operatorname{Sym}^2(E \otimes E^*) \cong \operatorname{Sym}^2(E \otimes_0 E^* \oplus \mathbb{C}) \cong \operatorname{Sym}^2(E \otimes_0 E^*) \oplus E \otimes_0 E^* \oplus \mathbb{C}.$$

On the other hand, the symmetric power of the tensor product is given by⁴

$$\operatorname{Sym}^{2}(E \otimes E^{*}) \cong \operatorname{Sym}^{2} E \otimes \operatorname{Sym}^{2} E^{*} \oplus \Lambda^{2} E \otimes \Lambda^{2} E^{*}.$$

The tensor products $\operatorname{Sym}^2 E \otimes \operatorname{Sym}^2 E^*$ and $\Lambda^2 E \otimes \Lambda^2 E^*$ can in turn be decomposed into

$$\operatorname{Sym}^{2} E \otimes \operatorname{Sym}^{2} E^{*} \cong V_{2\omega_{1}+2\omega_{n-1}} \oplus V_{\omega_{1}+\omega_{n-1}} \oplus \mathbb{C},$$

$$\Lambda^{2} E \otimes \Lambda^{2} E^{*} \cong \begin{cases} E^{*} \otimes E \cong V_{\omega_{1}+\omega_{n-1}} \oplus \mathbb{C}, & n = 3, \\ V_{\omega_{2}+\omega_{n-2}} \oplus V_{\omega_{1}+\omega_{n-1}} \oplus \mathbb{C}, & n \geq 4. \end{cases}$$

By comparing summands, we see that

$$\operatorname{Sym}^{2}(E \otimes_{0} E^{*}) \cong V_{2\omega_{1}+2\omega_{n-1}} \oplus \underbrace{V_{\omega_{2}+\omega_{n-2}}}_{\text{if } n>4} \oplus E \otimes_{0} E^{*} \oplus \mathbb{C}.$$

Hence, the trace-free part is given by

$$\operatorname{Sym}_0^2(E \otimes_0 E^*) \cong V_{2\omega_1 + 2\omega_{n-1}} \oplus \underbrace{V_{\omega_2 + \omega_{n-2}}}_{\text{if } n > 4} \oplus E \otimes_0 E^*.$$

Now that we have decomposed the relevant representations into irreducible summands, we recognize that $E \otimes E^*$ and $E^* \otimes E$ are the only two of the specified subcritical representations of G that, after restriction to K, have a common summand with $\operatorname{Sym}_0^2 \mathfrak{k}^{\mathbb{C}}$. In each case, the summand in question $E \otimes_0 E^* \cong \mathfrak{k}^{\mathbb{C}}$ appears with multiplicity 1; hence we have

$$\dim \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{k}^{\mathbb{C}}) = \dim \operatorname{Hom}_K(E^* \otimes E, \operatorname{Sym}_0^2 \mathfrak{k}^{\mathbb{C}}) = 1.$$

Moreover, both G-representations exhibit the same Casimir eigenvalue

$$Cas_{(\omega_1,\omega_{n-1})}^G = Cas_{(\omega_{n-1},\omega_1)}^G = Cas_{\omega_1}^K + Cas_{\omega_{n-1}}^K = \frac{(n-1)(n+1)}{n^2}.$$

According to Lemma 5.1, the only representations of G (up to equivalence) with subcritical Casimir eigenvalue that occur in decomposition (PW) of $\mathcal{S}_0^2(M)^{\mathbb{C}}$ are $E \otimes E^*$ and $E^* \otimes E$, and we have

$$\dim \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) = \dim \operatorname{Hom}_K(E^* \otimes E, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) = 1$$

This is a consequence of, for example, the formula $\operatorname{Sym}^d(V \otimes W) = \bigoplus \mathbb{S}_{\lambda}(V) \otimes \mathbb{S}_{\lambda}(W)$ in [6, Ex. 6.11].



(recall that $\mathfrak{m} \cong \mathfrak{k}$), i.e. the summand occurs with multiplicity 1. It remains to check whether the tensors in the corresponding subspaces are divergence-free. Since

$$E \otimes E^* \cong \mathfrak{k}^{\mathbb{C}} \oplus \mathbb{C}$$

as a representation of K, we have

$$\dim \operatorname{Hom}_K(E \otimes E^*, \mathfrak{m}^{\mathbb{C}}) = \dim \operatorname{Hom}_K(E^* \otimes E, \mathfrak{m}^{\mathbb{C}}) = 1,$$

meaning that both summands also occur in the left-regular representation $\Omega^1(M)$ with the same multiplicity. It now follows from Corollary 4.4 that

$$\dim \ker(\Delta_L - \lambda)\big|_{\mathscr{S}^2_{rt}(M)} = 0$$

for $\lambda = \frac{(n-1)(n+1)}{n^2}$. Since this is the only subcritical eigenvalue on $\mathscr{S}_0^2(M)$, we have shown the following.

Proposition 5.2 *The symmetric space* SU(n) *is linearly stable.*

6 The symmetric space E_6/F_4

Let (\mathfrak{H}, \circ) be the Albert algebra, where \mathfrak{H} is the set of Hermitian 3×3 -matrices over the octonions, i.e.

$$\mathfrak{H}:=\left\{\begin{pmatrix} a \ x \ \bar{y} \\ \bar{x} \ b \ z \\ y \ \bar{z} \ c \end{pmatrix} \middle| a,b,c \in \mathbb{R}, \ x,y,z \in \mathbb{O} \right\},$$

and with Jordan multiplication defined by

$$X \circ Y := \frac{1}{2}(XY + YX).$$

The exceptional Lie group E_6 can be realized as

$$E_6 := \left\{ \alpha \in \operatorname{Aut}_{\mathbb{C}} \mathfrak{H}^{\mathbb{C}} \mid \alpha \text{ preserves determinant and inner product} \right\},$$

while F_4 is defined as the set of algebra automorphisms

$$F_4 := \operatorname{Aut}(\mathfrak{H}, \circ).$$

By complex-linearly extending linear automorphisms of \mathfrak{H} , one obtains the inclusion $\operatorname{Aut}_{\mathbb{R}} \mathfrak{H} \subset \operatorname{Aut}_{\mathbb{C}} \mathfrak{H}^{\mathbb{C}}$. In this sense, we have $F_4 \subset E_6$. In fact,

$$F_4 = E_6 \cap \operatorname{Aut}_{\mathbb{R}} \mathfrak{H}.$$

As a representation of E_6 , $\mathfrak{H}^{\mathbb{C}}$ is irreducible. As an F_4 -representation, \mathfrak{H} decomposes into the irreducible summands

$$\mathfrak{H} \cong \mathfrak{H}_0 \oplus \mathbb{R}$$
,

where \mathfrak{H}_0 is the set of trace-free elements of \mathfrak{H} . An invariant inner product on \mathfrak{H} is defined by

$$\langle A, B \rangle := \operatorname{tr}(A \circ B)$$



for $A, B \in \mathfrak{H}$. An orthogonal basis of \mathfrak{H} (cf. Section 2.1 of [16]) is given by the matrices

$$E_{1} := \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad E_{2} := \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad E_{3} := \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

$$F_{1}(x) := \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & x \\ 0 & \bar{x} & 0 \end{pmatrix}, \quad F_{2}(x) := \begin{pmatrix} 0 & 0 & \bar{x} \\ 0 & 0 & 0 \\ x & 0 & 0 \end{pmatrix}, \quad F_{3}(x) := \begin{pmatrix} 0 & x & 0 \\ \bar{x} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix},$$

where x runs through the standard basis of \mathbb{O} as a real vector space.

In this section, we consider the Riemannian symmetric space $M = E_6/F_4$ equipped with the standard metric (hence with critical eigenvalue 2E = 1). The reductive decomposition of \mathfrak{e}_6 with respect to the standard metric is given by

$$\mathfrak{e}_6 = \mathfrak{f}_4 \oplus \mathfrak{m},$$

where $\mathfrak{m} \cong \mathfrak{H}_0$ as a representation of F_4 .

Lemma 6.1 Let V_{γ} be an irreducible complex representation of E_6 with $Cas_{\gamma}^{E_6} < 1$ and

$$\operatorname{Hom}_{F_4}(V_{\gamma},\operatorname{Sym}_0^2\mathfrak{H}_0^{\mathbb{C}})\neq 0.$$

Then V_{γ} is equivalent to one of the E_6 -representations $\mathfrak{H}^{\mathbb{C}}$ and $\overline{\mathfrak{H}^{\mathbb{C}}}$. In fact,

$$\dim \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}},\operatorname{Sym}_0^2\mathfrak{H}_0^{\mathbb{C}})=\dim \operatorname{Hom}_{F_4}(\overline{\mathfrak{H}^{\mathbb{C}}},\operatorname{Sym}_0^2\mathfrak{H}_0^{\mathbb{C}})=1,$$

and the Casimir eigenvalue is $\operatorname{Cas}_{\gamma}^G = \frac{13}{18}$.

Proof We abstain from specifying a particular choice of simple root system and fundamental weights for E_6 and F_4 , since we are merely interested in the corresponding fundamental representations of the respective Lie group. Following the enumerative convention of Bourbaki (as used by the software package LiE), if we denote the fundamental weights of E_6 by $\omega_1, \ldots, \omega_6$ and of F_4 by η_1, \ldots, η_4 , then the associated representations are identified as

$$\begin{split} V_{\omega_{1}} &= \mathbf{27} \cong \mathfrak{H}^{\mathbb{C}}, & V_{\omega_{2}} &= \mathbf{78} \cong \mathfrak{e}_{6}^{\mathbb{C}}, & V_{\omega_{3}} &= \mathbf{351} \cong \Lambda^{2} \mathfrak{H}^{\mathbb{C}}, \\ V_{\omega_{4}} &= \mathbf{2925} \cong \Lambda^{3} \mathfrak{H}^{\mathbb{C}}, & V_{\omega_{5}} &= \overline{\mathbf{351}} \cong \Lambda^{2} \overline{\mathfrak{H}^{\mathbb{C}}}, & V_{\omega_{6}} &= \overline{\mathbf{27}} \cong \overline{\mathfrak{H}^{\mathbb{C}}}, \\ V_{\eta_{1}} &= \mathbf{52} \cong \mathfrak{f}_{4}^{\mathbb{C}}, & V_{\eta_{2}} &= \mathbf{1274}, & V_{\eta_{3}} &= \mathbf{273}, & V_{\eta_{4}} &= \mathbf{26} \cong \mathfrak{H}_{0}^{\mathbb{C}}, \end{split}$$

where the number indicates the dimension.

As in the proof of Lemma 5.1, we have the estimate

$$\operatorname{Cas}_{\gamma}^{E_6} \ge \sum_{r=1}^{6} a_r \operatorname{Cas}_{\omega_r}^{E_6}$$

for any representation V_{γ} of E_6 with highest weight

$$\gamma = \sum_{r=1}^{6} a_r \omega_r.$$

Among the fundamental representations, only the Casimir eigenvalues

$$Cas_{\omega_1}^{E_6} = Cas_{\omega_6}^{E_6} = \frac{13}{18}$$



are smaller than 1 (see table on p. 16 of [14]). Since $\frac{13}{18} + \frac{13}{18} > 1$, it follows that only the representations to the highest weights \mathbb{C} , $\mathfrak{H}^{\mathbb{C}}$ come into question.

Consider now the F_4 -representation $\mathfrak{H}_0^{\mathbb{C}} \cong V_{\eta_4}$. We obtain $\hat{\mathfrak{t}}$ the decomposition

$$\operatorname{Sym}^2 V_{\eta_4} \cong V_{2\eta_4} \oplus V_{\eta_4} \oplus \mathbb{C}$$

into irreducible summands, hence

$$\operatorname{Sym}_0^2 \mathfrak{H}_0^{\mathbb{C}} \cong V_{2\eta_4} \oplus \mathfrak{H}_0^{\mathbb{C}}.$$

Furthermore, we have

$$\mathfrak{H}^{\mathbb{C}}\cong\overline{\mathfrak{H}^{\mathbb{C}}}\cong\mathfrak{H}^{\mathbb{C}}_{0}\oplus\mathbb{C}$$

as a representation of F_4 . The assertion follows by comparison of summands.

Lemma 6.1 now tells us that the representations of E_6 with subcritical Casimir eigenvalue that occur in decomposition (PW) of $\mathscr{S}_0^2(M)^{\mathbb{C}}$ are precisely $\mathfrak{H}^{\mathbb{C}}$ and $\overline{\mathfrak{H}^{\mathbb{C}}}$, both with multiplicity 1, i.e.

$$\dim \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}},\operatorname{Sym}_0^2\mathfrak{m}^{\mathbb{C}})=\dim \operatorname{Hom}_{F_4}(\overline{\mathfrak{H}^{\mathbb{C}}},\operatorname{Sym}_0^2\mathfrak{m}^{\mathbb{C}})=1,$$

since $\mathfrak{m} \cong \mathfrak{H}_0$. Again, we have to check whether the tensors in the corresponding subspace are divergence-free. It follows from the decomposition $\mathfrak{H} = \mathfrak{H}_0 \oplus \mathbb{R}$ as a representation of F_4 that

$$\dim \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}},\mathfrak{m}^{\mathbb{C}}) = \dim \operatorname{Hom}_{F_4}(\overline{\mathfrak{H}^{\mathbb{C}}},\mathfrak{m}^{\mathbb{C}}) = 1,$$

so as in the previous section, the summand has the same multiplicity in the left-regular representation $\Omega^1(M)$. Again, it follows from Corollary 4.4 that

$$\dim \ker(\Delta_L - \lambda)\big|_{\mathscr{S}^2_{tt}(M)} = 0$$

for $\lambda = \frac{13}{18}$, and since this is the only subcritical eigenvalue on $\mathcal{S}_0^2(M)$, we have shown the following, which, together with Proposition 5.2, finishes the proof of the main theorem.

Proposition 6.2 *The symmetric space* E_6/F_4 *is linearly stable.*

Funding Open Access funding enabled and organized by Projekt DEAL. No funds, grants, or other support was received.

Data availability statement Data sharing not applicable to this article as no datasets were generated or analysed during the current study.

Declarations

Employment During the time of research as well as currently, the author is employed as a research assistant at the University of Stuttgart.

Competing interests The author has no relevant financial or non-financial interests to disclose.

Code availability Not applicable.

⁵ This has been verified through use of the software package LiE v2.1. See, for example, http://young.sp2mi.univ-poitiers.fr/cgi-bin/form-prep/marc/sym-alt.act?x1=0&x2=0&x3=0&x4=1&power=2&kind=sym&rank=4&group=F4 or enter the command sym_tensor(2,[0,0,0,1],F4) into the LiE shell.



Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/.

A Appendix

A.1 Proofs of general statements

Proof of Lemma 4.1 The following is a slightly generalized version of the proof of a result by N. Koiso [11, Prop. 3.3]. We first note that

$$(\delta \alpha \cdot g, h)_g = \int_M \delta \alpha \langle g, h \rangle_g \operatorname{vol}_g = \frac{1}{2} (\delta \alpha, \operatorname{tr}_g h)_g = \frac{1}{2} (\alpha, d \operatorname{tr}_g h)_g$$

for $\alpha \in \Omega^1(M)$, $h \in \mathcal{S}^2(M)$, so the formal adjoint of θ is given by

$$\theta^*: \mathscr{S}_0^2(M) \to \Omega^1(M): h \mapsto \delta h + \frac{1}{n} d \operatorname{tr}_g h.$$

We show that θ is overdetermined elliptic. The principal symbol of θ is

$$\sigma_{\xi}(\theta)\alpha = \sigma_{\xi}(\delta^{*})\alpha + \frac{2}{n}\sigma_{\xi}(\delta)\alpha \cdot g = \xi \odot \alpha - \frac{2}{n}\langle \xi, \alpha \rangle_{g}g$$

for ξ , $\alpha \in T_p^*M$. If $\xi \neq 0$, then $\sigma_{\xi}(\theta)$ is injective: Suppose $\sigma_{\xi}(\theta)\alpha = 0$. Then

$$\xi \odot \alpha = \frac{2}{n} \langle \xi, \alpha \rangle_g g.$$

Take an orthonormal basis (e_i) with respect to g of T_pM and write

$$\xi = \sum_{i} \xi_{i} e_{i}^{\flat}, \ \alpha = \sum_{i} \alpha_{i} e_{i}^{\flat}.$$

For i, j = 1, ..., n, it follows that

$$\xi_i \alpha_j + \xi_j \alpha_i = \frac{2}{n} \langle \xi, \alpha \rangle_g \delta_{ij}$$

and so $\xi_i \alpha_j = -\xi_j \alpha_i$ if $i \neq j$, as well as $\xi_i \alpha_i = \xi_j \alpha_j$ for any i, j. Then

$$\xi_i^2 \alpha_j = -\xi_i \alpha_i \xi_j = -\xi_j^2 \alpha_j.$$

If $\alpha_j \neq 0$, this would imply that $\xi_i^2 + \xi_j^2 = 0$ and so $\xi_i = \xi_j = 0$, which contradicts the assumption that $\xi \neq 0$. Overall, we conclude that $\alpha = 0$ and thus the injectivity is proven.

From ellipticity, we obtain the orthogonal decomposition

$$\mathscr{S}_0^2(M) = \operatorname{im} \theta \oplus \ker \theta^*.$$

Let $h \in \ker(\Delta_L - \lambda)|_{\mathscr{S}^2_0(M)}$. According to the above decomposition, we can write h as

$$h = \theta \alpha + \psi$$



where $\theta^* \psi = 0$. Then also,

$$\delta \psi = \theta^* \psi - \frac{1}{n} d \operatorname{tr}_g \psi = 0.$$

Since (M,g) is Einstein, Δ_L commutes with δ on $\mathscr{S}^2(M)$ and with δ^* on $\Omega^1(M)$ [9, 10.7/10.8]. Furthermore $\Delta_L(fg)=(\Delta f)g$ for any $f\in C^\infty(M)$. We conclude that Δ_L commutes with θ and θ^* as well. This implies that

$$\theta(\Delta - \lambda)\alpha = (\Delta_L - \lambda)\theta\alpha = (\Delta_L - \lambda)(h - \psi) = -(\Delta_L - \lambda)\psi,$$

$$\theta^*(\Delta_L - \lambda)\psi = (\Delta - \lambda)\theta^*\psi = 0,$$

and so

$$\theta^*\theta(\Delta - \lambda)\alpha = -\theta^*(\Delta_L - \lambda)\psi = 0.$$

It follows that

$$\|\theta(\Delta - \lambda)\alpha\|_g^2 = (\theta^*\theta(\Delta - \lambda)\alpha, (\Delta - \lambda)\alpha)_g = 0$$

and so $\theta(\Delta - \lambda)\alpha = 0 = (\Delta_L - \lambda)\psi$. In total, $\psi \in \ker(\Delta_L - \lambda)\big|_{\mathscr{S}^2_{\mathfrak{tt}}(M)}$.

Also, if *h* is an element of $\ker(\Delta_L - \lambda)|_{\mathscr{S}^2_{\mathfrak{n}}(M)}$, then

$$\theta^* h = \delta h + \frac{1}{n} d \operatorname{tr}_g h = 0$$

and so $\psi = h$. This means that the mapping

$$P: \ker(\Delta_L - \lambda) \big|_{\mathscr{S}^2_0(M)} \to \ker(\Delta_L - \lambda) \big|_{\mathscr{S}^2_n(M)} : h \mapsto \psi$$

defines a projection, and the dimension formula

$$\dim \ker(\Delta_L - \lambda)\big|_{\mathscr{S}^2_{\mathfrak{a}}(M)} = \dim \left(\ker(\Delta_L - \lambda)\big|_{\mathscr{S}^2_{\mathfrak{a}}(M)}\right) - \dim \ker P$$

holds.

By definition, the kernel of P consists of those $h \in \ker(\Delta_L - \lambda) \big|_{\mathscr{S}_0^2(M)}$ with $h = \theta \alpha$ for some $\alpha \in \Omega^1(M)$, i.e. $h \in \operatorname{im} \theta$. Hence we know that

$$\ker P = \ker(\Delta_L - \lambda)|_{\mathscr{S}_0^2(M)} \cap \operatorname{im} \theta.$$

Let $\alpha \in \ker(\Delta - \lambda)|_{\Omega^1(M)}$. We have seen that Δ_L commutes with θ , so it follows that $\theta \alpha \in \ker(\Delta_L - \lambda)|_{\mathscr{L}^2_{\alpha}(M)}$ and therefore

$$\theta\left(\ker(\Delta-\lambda)\big|_{\Omega^1(M)}\right)\subset\ker P.$$

Conversely, let $h \in \ker P$. Then there exists some $\alpha \in \Omega^1(M)$ such that $h = \theta \alpha$, and also $h \in \ker(\Delta_L^g - \lambda)|_{\mathscr{L}^2(M)}$. By the ellipticity of the operator $\Delta - \lambda$, we can decompose α into

$$\alpha = \beta + (\Delta - \lambda)\gamma$$



with $\beta \in \ker(\Delta - \lambda)|_{\Omega^1(M)}$, $\gamma \in \Omega^1(M)$. Then

$$0 = (\Delta_L - \lambda)\theta\alpha$$

= $(\Delta_L - \lambda)\theta\beta + (\Delta_L - \lambda)\theta(\Delta - \lambda)\gamma$
= $\theta(\Delta - \lambda)\beta + (\Delta_L - \lambda)^2\theta\gamma$
= $(\Delta_L - \lambda)^2\theta\gamma$.

Since Δ_L is self-adjoint, we have

$$\|(\Delta_L - \lambda)\theta\gamma\|_g^2 = ((\Delta_L - \lambda)^2\theta\gamma, \theta\gamma)_g = 0$$

and thus

$$\theta(\Delta - \lambda)\gamma = (\Delta_L - \lambda)\theta\gamma = 0,$$

i.e. $(\Delta - \lambda)\gamma \in \ker \theta$. This implies that $h = \theta\alpha = \theta\beta$, so

$$\theta : \ker(\Delta - \lambda)|_{\Omega^1(M)} \to \ker P$$

is surjective and we obtain the dimension formula

$$\dim \ker P = \dim \ker (\Delta - \lambda) \big|_{\Omega^1(M)} - \dim \left(\ker (\Delta - \lambda) \big|_{\Omega^1(M)} \cap \ker \theta \right).$$

Proof of Lemma 4.2 Let E be the Einstein constant of (M, g). Let $\alpha \in \Omega^1(M)$ such that

$$\theta \alpha = \delta^* \alpha + \frac{2}{n} \delta \alpha \cdot g = 0.$$

Taking the divergence yields

$$\delta\theta\alpha = \delta\delta^*\alpha - \frac{2}{n}d\delta\alpha = 0,$$

since $\delta(fg) = -df$ for $f \in C^{\infty}(M)$. We make use of the well-known Weitzenböck identities

$$\delta \delta^* - \delta^* \delta = \nabla^* \nabla - q(R) \quad \text{on } \mathscr{S}^k(M),$$

$$\Delta = d^* d + d d^* = \nabla^* \nabla + q(R) \quad \text{on } \Omega^k(M).$$

For k=1 and since $\delta^*=d=\nabla$ on functions and (M,g) is Einstein, these amount to

$$\delta \delta^* \alpha - d \delta \alpha = \nabla^* \nabla \alpha - E \alpha,$$

$$d^* d \alpha + d \delta \alpha = \nabla^* \nabla \alpha + E \alpha.$$

Putting these together, we obtain

$$\delta\theta\alpha = \left(1 - \frac{2}{n}\right)d\delta\alpha + \nabla^*\nabla\alpha - E\alpha = \left(2 - \frac{2}{n}\right)d\delta\alpha + d^*d\alpha - 2E\alpha = 0.$$

Taking the L^2 inner product with α then yields

$$\left(2 - \frac{2}{n}\right) \|\delta\alpha\|_g^2 + \|d\alpha\|_g^2 - 2E\|\alpha\|_g = 0.$$



If E < 0, this directly implies that $\alpha = 0$. If E = 0, it implies $\delta \alpha = 0$ and $d\alpha = 0$, and since $\theta \alpha = 0$, it follows that $\delta^* \alpha = 0$. If E > 0, then applying the codifferential to $\delta \theta \alpha$ yields

$$\left(2 - \frac{2}{n}\right)d^*d\delta\alpha + (d^*)^2d\alpha - 2Ed^*\alpha = \left(2 - \frac{2}{n}\right)\Delta\delta\alpha - 2E\delta\alpha = 0,$$

so $\delta \alpha$ would be an eigenfunction of the Laplacian to the eigenvalue $\frac{En}{n-1} = \frac{\operatorname{scal}_g}{n-1}$. By a theorem of Obata [1, Thm. D.I.6], this eigenvalue can only be attained on the standard sphere, so necessarily $\delta \alpha = 0$. It follows again from $\theta \alpha = 0$ that $\delta^* \alpha = 0$.

Proof of Lemma 4.3 Let $\alpha \in \Omega^1(M)$ such that $\delta^*\alpha = 0$. Then also $\delta\alpha = 0$, since $\delta\alpha = -\operatorname{tr}_g \delta^*\alpha = 0$. By virtue of the Weitzenböck formulae that were already employed in the proof of Lemma 4.2, we conclude that

$$\Delta \alpha = \nabla^* \nabla \alpha + E \alpha = \delta \delta^* \alpha - d \delta \alpha + 2E \alpha = 2E \alpha.$$

A.2 Alternative proof of the stability of SU(n)

An alternative method of checking that the prototypical differential operators

$$\delta: \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) \to \operatorname{Hom}_K(E \otimes E^*, \mathfrak{m}^{\mathbb{C}}),$$

$$\delta: \operatorname{Hom}_K(E^* \otimes E, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) \to \operatorname{Hom}_K(E^* \otimes E, \mathfrak{m}^{\mathbb{C}})$$

are injective is an explicit computation by means of Lemma 3.3. To do so, we first pick out an explicit element

$$A \in \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}})$$

and then proceed to compute the divergence on the corresponding subspace of $\mathcal{S}_0^2(M)$.

Lemma A.1 Let $\pi: \operatorname{Sym}^2(E \otimes E^*) \to E \otimes E^*$ denote the mapping defined by

$$\pi(A \odot B) := AB^* + BA^*,$$

where $A, B \in E \otimes E^*$ are regarded as complex $n \times n$ -matrices. Then

$$\pi \in \operatorname{Hom}_K(\operatorname{Sym}^2(E \otimes E^*), E \otimes E^*).$$

Moreover, the restriction

$$\pi: \operatorname{Sym}_0^2(E \otimes_0 E^*) \to E \otimes_0 E^*$$

is surjective, and $W:=\left(\ker\pi\left|_{\operatorname{Sym}_0^2(E\otimes_0E^*)}\right)^\perp\cong E\otimes_0E^*.$

Proof The equivariance of π under the action of K follows from

$$\pi(kAk^{-1} \odot kBk^{-1}) = kAk^{-1}(k^{-1})^*B^*k^* + k^{-1}Bk(k^{-1})^*A^*k^* = k(AB^* + BA^*)k^{-1}$$

for any $k \in K = SU(n)$ and $A, B \in E \otimes E^*$. Furthermore, we have

$$\operatorname{tr}(\pi(A \odot B)) = \operatorname{tr}(AB^* + BA^*) = \langle A, B \rangle + \langle B, A \rangle = \operatorname{tr}(A \odot B),$$

where the last trace is taken with respect to the inner product on $E \otimes E^*$. This means that

$$\pi(\operatorname{Sym}_0^2(E \otimes E^*)) \subset E \otimes_0 E^*.$$



Next we want to show that π does not vanish when restricted to $\operatorname{Sym}_0^2(E \otimes_0 E^*)$. If we denote by E_{ij} the $n \times n$ -matrix that has entry 1 at position (i, j) and 0 elsewhere, then we have for example E_{21} , $E_{31} \in E \otimes_0 E^*$ and $\langle E_{21}, E_{31} \rangle = 0$, so $E_{21} \odot E_{31} \in \operatorname{Sym}_0^2(E \otimes_0 E^*)$ and

$$\pi(E_{21} \odot E_{31}) = E_{21}E_{13} + E_{31}E_{12} = E_{23} + E_{32} \neq 0.$$

Now, since $E \otimes_0 E^*$ is irreducible, the mapping

$$\pi: \operatorname{Sym}_0^2(E \otimes_0 E^*) \to E \otimes_0 E^*$$

must be surjective. We have seen in the proof of Lemma 5.1 that $E \otimes_0 E^*$ appears in the decomposition of $\operatorname{Sym}_0^2(E \otimes_0 E^*)$ with multiplicity 1; hence $W := \left(\ker \pi \big|_{\operatorname{Sym}_0^2(E \otimes_0 E^*)}\right)^{\perp}$ must be the irreducible summand of $\operatorname{Sym}_0^2(E \otimes_0 E^*)$ that is equivalent to $E \otimes_0 E^*$.

Alternative proof of Proposition 5.2 The properties of π from Lemma A.1 allow us to define

$$\tilde{A} := \pi \big|_{W}^{-1} \in \operatorname{Hom}_{K}(E \otimes_{0} E^{*}, \operatorname{Sym}_{0}^{2}(E \otimes_{0} E^{*}))$$

and extend it with zero to a mapping $\tilde{A} \in \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2(E \otimes_0 E^*))$. Via the identification $\mathfrak{m}^{\mathbb{C}} \cong E \otimes_0 E^*$, this gives rise to a mapping

$$A \in \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}).$$

From the equivariance of $\pi|_W$, the irreducibility of $W \cong E \otimes_0 E^*$ and Schur's Lemma it follows that $\pi|_W$ is unitary up to a positive constant, that is

$$\langle \pi(v), \pi(w) \rangle_{E \otimes_0 E^*} = c \cdot \langle v, w \rangle_{\operatorname{Sym}_0^2(E \otimes_0 E^*)}$$

for all $v, w \in W$ and some c > 0. Denote the tensor product representation of G on $E \otimes E^*$ by

$$\rho: G \to \operatorname{Aut}(E \otimes E^*): \ \rho(k_1, k_2)F = k_1 F k_2^{-1}$$

for $F \in E \otimes E^*$. Its differential is given by

$$d\rho: \mathfrak{q} \to \operatorname{End}(E \otimes E^*): d\rho(X_1, X_2)F = X_1F - FX_2$$

for $X_1, X_2 \in \mathfrak{k}$. In particular,

$$d\rho(X, -X)F = XF + FX.$$

Let (e_i) be an orthonormal basis of \mathfrak{m} , $e_i=(f_i,-f_i)$ with $f_i\in\mathfrak{k}$. Under the identification $\mathfrak{m}^\mathbb{C}\cong E\otimes_0 E^*$, the invariant inner product changes by some positive constant factor, and e_i is mapped to f_i . Hence, (f_i) is an orthonormal basis of $\mathfrak{k}\subset E\otimes_0 E^*$ up to a positive factor.

Now, let $X \in \mathfrak{k}$ and $F \in E \otimes E^*$. Using the formula from Lemma 3.3, it follows that

$$\begin{split} (\delta h)_o(X, -X) &= \sum_i \langle A(d\rho(e_i)F), e_i \odot (X, -X) \rangle_{\operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}} \\ &= c \cdot \sum_i \langle \tilde{A}(f_iF + Ff_i), f_i \odot X \rangle_{\operatorname{Sym}_0^2(E \otimes_0 E^*)} \\ &= c \cdot \sum_i \langle \tilde{A}(f_iF + Ff_i), \operatorname{pr}_W(f_i \odot X) \rangle_{\operatorname{Sym}_0^2(E \otimes_0 E^*)} \\ &= c' \cdot \sum_i \langle f_iF + Ff_i, \pi(\operatorname{pr}_{\operatorname{Sym}_0^2(E \otimes_0 E^*)}(f_i \odot X)) \rangle_{E \otimes_0 E^*} \end{split}$$



for some c, c' > 0. Since the trivial summand of $\operatorname{Sym}^2(E \otimes_0 E^*)$ can only be mapped to the trivial summand of $E \otimes E^*$ under the equivariant map π , we have

$$\pi \circ \operatorname{pr}_{\operatorname{Sym}_0^2(E \otimes_0 E^*)} = \operatorname{pr}_{E \otimes_0 E^*} \circ \pi$$

on Sym²($E \otimes_0 E^*$), implying that

$$\begin{split} (\delta h)_o(X, -X) &= c' \cdot \sum_i \langle f_i F + F f_i, \operatorname{pr}_{E \otimes_0 E^*} (f_i X^* + X f_i^*) \rangle \\ &= -c' \cdot \sum_i \langle f_i F + F f_i, \operatorname{pr}_{E \otimes_0 E^*} (f_i X + X f_i) \rangle. \end{split}$$

Choose the (up to a positive factor) orthonormal basis (f_i) of \mathfrak{k} in such a way that $f_1 = E_{12} - E_{21}$. Furthermore, let $X = F = E_{13} - E_{31}$. Then,

$$f_1F + Ff_1 = (E_{12} - E_{21})(E_{13} - E_{31}) + (E_{13} - E_{31})(E_{12} - E_{21}) = -E_{23} - E_{32} \in E \otimes_0 E^*$$

and we obtain

$$\sum_{i} \langle f_i F + F f_i, \operatorname{pr}_{E \otimes_0 E^*}(f_i X + X f_i) \rangle = \sum_{i} \langle f_i F + F f_i, \operatorname{pr}_{E \otimes_0 E^*}(f_i F + F f_i) \rangle$$

$$\geq \langle f_1 F + F f_1, \operatorname{pr}_{E \otimes_0 E^*}(f_1 F + F f_1) \rangle = \langle E_{23} + E_{32}, E_{23} + E_{32} \rangle = 2 > 0.$$

In particular, we have found $Y \in \mathfrak{m}$ such that $(\delta h)_o(Y) \neq 0$, where $h \in \mathscr{S}_0^2(M)$ is associated to

$$F \otimes A \in (E \otimes E^*) \otimes \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}).$$

This means that the linear mapping

$$\delta: \operatorname{Hom}_K(E \otimes E^*, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) \to \operatorname{Hom}_K(E \otimes E^*, \mathfrak{m}^{\mathbb{C}})$$

is nonzero. Hence, there are no tt-eigentensors for the subcritical Casimir eigenvalue. This proves the assertion.

A.3 Alternative proof of the stability of E_6/F_4

As we did before in the situation of SU(n), we want to apply Lemma 3.3 to verify that the mappings

$$\begin{split} \delta: \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) &\to \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \mathfrak{m}^{\mathbb{C}}), \\ \delta: \operatorname{Hom}_{F_4}(\overline{\mathfrak{H}^{\mathbb{C}}}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) &\to \operatorname{Hom}_{F_4}(\overline{\mathfrak{H}^{\mathbb{C}}}, \mathfrak{m}^{\mathbb{C}}) \end{split}$$

are injective. Surprisingly, the computation works very similar to the SU(n) case.

Lemma A.2 Let $\pi: \operatorname{Sym}^2 \mathfrak{H} \to \mathfrak{H}$ denote the mapping defined by

$$\pi(A \odot B) := AB + BA = 2A \circ B.$$

Then we have

$$\pi \in \operatorname{Hom}_{F_4}(\operatorname{Sym}^2 \mathfrak{H}_0, \mathfrak{H}).$$

The restriction

$$\pi: \operatorname{Sym}_0^2 \mathfrak{H}_0 \to \mathfrak{H}_0$$



is surjective, and $W := \left(\ker \pi \big|_{\operatorname{Sym}_0^2 \mathfrak{H}_0}\right)^{\perp} \cong \mathfrak{H}_0.$

Proof The proof is completely analogous to the proof of Lemma A.1. First, we note that π is well-defined since (\mathfrak{H}, \circ) is a commutative algebra. The equivariance of π under the action of F_4 follows from

$$\pi(f(A) \odot f(B)) = 2f(A) \circ f(B) = f(2A \circ B) = f(\pi(A \odot B))$$

for any $f \in F_4 = \operatorname{Aut}(\mathfrak{H}, \circ)$ and $A, B \in \mathfrak{H}$. Furthermore, we have

$$\operatorname{tr}(\pi(A \odot B)) = 2\operatorname{tr}(A \circ B) = 2\langle A, B \rangle = \operatorname{tr}(A \odot B),$$

where the last trace is taken with respect to the inner product on \mathfrak{H} . This means that

$$\pi(\operatorname{Sym}_0^2 \mathfrak{H}) \subset \mathfrak{H}_0.$$

Now we want to show that π does not vanish when restricted to $\operatorname{Sym}_0^2 \mathfrak{H}_0$. For example, take $F_1(1)$, $F_2(1) \in \mathfrak{H}_0$. We have $\langle F_1(1), F_2(1) \rangle = 0$ and thus $F_1(1) \odot F_2(1) \in \operatorname{Sym}_0^2 \mathfrak{H}_0$. Also,

$$\pi(F_1(1) \odot F_2(1)) = 2F_1(1) \circ F_2(1) = F_3(1) \neq 0.$$

Since \mathfrak{H}_0 is irreducible over F_4 , the mapping

$$\pi: \operatorname{Sym}_0^2 \mathfrak{H}_0 \to \mathfrak{H}_0$$

must be surjective. From the proof of Lemma 6.1, we know that \mathfrak{H}_0 appears in the decomposition of $\operatorname{Sym}_0^2 \mathfrak{H}_0$ with multiplicity 1; hence $W := \left(\ker \pi \big|_{\operatorname{Sym}_0^2 \mathfrak{H}_0}\right)^{\perp}$ must be the irreducible summand of $\operatorname{Sym}_0^2 \mathfrak{H}_0$ that is equivalent to \mathfrak{H}_0 .

Alternative proof of Proposition 6.2 By Lemma A.2, we can define

$$A := \pi \big|_{W}^{-1} \in \operatorname{Hom}_{F_4}(\mathfrak{H}_0, \operatorname{Sym}_0^2 \mathfrak{H}_0),$$

extend it with zero to \mathfrak{H} and then complex-linearly to a mapping $A \in \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \operatorname{Sym}_0^2 \mathfrak{H}_0^{\mathbb{C}})$. Again, we need that $\pi|_W$ is unitary up to a positive constant, which follows by Schur's Lemma from the equivariance of $\pi|_W$ and the irreducibility of $W \cong \mathfrak{H}_0$. By Theorem 3.2.4 in [16], every element $\alpha \in \mathfrak{e}_6 \subset \operatorname{End}_{\mathbb{C}}(\mathfrak{H}^{\mathbb{C}})$ can be written as

$$\alpha = \beta + iT \circ$$

with unique elements $\beta \in \mathfrak{f}_4 \subset \mathfrak{e}_6$ and $T \in \mathfrak{H}_0$. This corresponds to the F_4 -invariant decomposition

$$\mathfrak{e}_6 \cong \mathfrak{f}_4 \oplus \mathfrak{H}_0$$
.

Throughout what follows, we identify $\mathfrak{m} \cong \mathfrak{H}_0$. If we denote the defining representation by

$$\rho: E_6 \to \operatorname{Aut} \mathfrak{H}^{\mathbb{C}}$$

then in particular,

$$d\rho(X) = iX \circ$$



for $X \in \mathfrak{m}$. Let (e_i) be an orthonormal basis of \mathfrak{H}_0 (again, under the identification $\mathfrak{m} \cong \mathfrak{H}_0$, the invariant inner product changes at most by some positive constant factor), $X \in \mathfrak{m}$ and $F \in \mathfrak{H}^{\mathbb{C}}$. Using Lemma 3.3, we thus obtain

$$\begin{split} (\delta h)_o(X) = & c \cdot \sum_i \langle A(d\rho(e_i)F), e_i \odot X \rangle_{\operatorname{Sym}_0^2 \mathfrak{H}_0^{\mathbb{C}}} = c \cdot \sum_i \langle A(\mathrm{i}e_i \circ F), e_i \odot X \rangle_{\operatorname{Sym}_0^2 \mathfrak{H}_0^{\mathbb{C}}} \\ = & c \cdot \sum_i \langle A(\mathrm{i}e_i \circ F), \operatorname{pr}_W(e_i \odot X) \rangle_{\operatorname{Sym}_0^2 \mathfrak{H}_0^{\mathbb{C}}} \\ = & c' \cdot \sum_i \langle \mathrm{i}e_i \circ F, \pi(\operatorname{pr}_{\operatorname{Sym}_0^2 \mathfrak{H}_0}(e_i \odot X)) \rangle_{\mathfrak{H}_0^{\mathbb{C}}} \end{split}$$

for some c, c' > 0. The trivial summand of Sym² \mathfrak{H}_0 can only be mapped to the trivial summand of \mathfrak{H} under the equivariant map π , implying that

$$\pi \circ \operatorname{pr}_{\operatorname{Sym}_0^2 \mathfrak{H}_0} = \operatorname{pr}_{\mathfrak{H}_0} \circ \pi$$

on Sym² \mathfrak{H}_0 . Thus, we have

$$(\delta h)_o(X) = \mathrm{i} c' \cdot \sum_i \langle e_i \circ F, \operatorname{pr}_{\mathfrak{H}_0}(\pi(e_i \odot X)) \rangle = 2\mathrm{i} c' \sum_i \langle e_i \circ F, \operatorname{pr}_{\mathfrak{H}_0}(e_i \circ X) \rangle.$$

Now let $X = F = F_1(1)$. Choose the (up to a positive factor) orthonormal basis (e_i) of \mathfrak{H}_0 in such a way that $e_1 = F_2(1)$. Then we have

$$e_1 \circ F = F_2(1) \circ F_1(1) = \frac{1}{2} F_3(1) \in \mathfrak{H}_0$$

and it follows that

$$\sum_{i} \langle e_{i} \circ F, \operatorname{pr}_{\mathfrak{H}_{0}}(e_{i} \circ X) \rangle = \sum_{i} \langle e_{i} \circ F, \operatorname{pr}_{\mathfrak{H}_{0}}(e_{i} \circ F) \rangle \ge \langle e_{1} \circ F, \operatorname{pr}_{\mathfrak{H}_{0}}(e_{1} \circ F) \rangle$$
$$= \frac{1}{4} \langle F_{3}(1), F_{3}(1) \rangle = \frac{1}{2} > 0.$$

In particular, we have found $Y \in \mathfrak{m}$ such that $(\delta h)_o(Y) \neq 0$, where $h \in \mathscr{S}_0^2(M)$ is associated to

$$F \otimes A \in \mathfrak{H}^{\mathbb{C}} \otimes \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}).$$

This means that the linear mapping

$$\delta: \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \operatorname{Sym}_0^2 \mathfrak{m}^{\mathbb{C}}) \to \operatorname{Hom}_{F_4}(\mathfrak{H}^{\mathbb{C}}, \mathfrak{m}^{\mathbb{C}})$$

is nonzero. The same argument works for the E_6 -representation $\mathfrak{H}^{\mathbb{C}}$, since we exclusively used real elements and automorphisms in the computation. In total, there are no tt-eigentensors for the subcritical Casimir eigenvalue, which proves the assertion.

References

- Berger, M., Gauduchon, P., Mazet, E.: Le spectre d'une variété Riemannienne, Lecture Notes in Mathematics, Vol. 194. Springer-Verlag Berlin Heidelberg (1971)
- 2. Besse, A.L.: Einstein Manifolds, Classics in Mathematics. Springer-Verlag Berlin Heidelberg (1987)



- Cao, H.-D., He, C.: Linear stability of Perelman's ν-entropy on symmetric spaces of compact type. J. Reine Angew. Math. 709, 229–246 (2015)
- Huai-Dong, C., Hamilton, R.S., Ilmanen, T.: Gaussian densities and stability for some Ricci solitons. arXiv:math/0404165 (2004)
- 5. Dieterich, P.-S.: On the Lichnerowicz Laplace operator and its application to stability of spacetimes (thesis), Universität Stuttgart (2012)
- Fulton, W., Harris, J.: Representation Theory: A First Course, Graduate Texts in Mathematics, vol. 129. Springer-Verlag, New York (1991)
- Gasqui, J., Goldschmidt, H.: Radon transforms and spectral rigidity on the complex quadrics and the real Grassmannians of rank two. J. Reine Angew. Math. 480, 1–69 (1996)
- Gibbons, G.W., Hartnoll, S.A., Pope, C.N.: Bohm and Einstein-Sasaki metrics, black holes, and cosmological event horizons. Phys. Rev. D 67(8), 084024 (2003)
- Lichnerowicz, A.: Propagateurs et commutateurs en relativité générale. Public. Mathématiques de l'I.H.É.S. 10, 5–56 (1961)
- Koiso, N.: Rigidity and stability of Einstein metrics: the case of compact symmetric spaces. Osaka Math. J. 17, 51–73 (1980)
- 11. Koiso, N.: Rigidity and infinitesimal deformability of Einstein metrics. Osaka Math. J. 19, 643-668 (1982)
- 12. Kröncke, K.: Stability of Einstein Manifolds (thesis), University of Potsdam (2013)
- 13. Semmelmann, U., Weingart, G.: Manuscripta Mathematica. The standard Laplacian 158, 273-293 (2019)
- 14. Semmelmann, U., Weingart, G.: Linear stability of symmetric spaces. arXiv:2012.07328 (2020)
- 15. Wallach, N.R.: Harmonic Analysis on Homogeneous Spaces. Marcel Dekker, Inc, New York (1973)
- 16. Yokota, I: Exceptional Lie groups. arXiv:0902.0431 (2009)

Publisher's Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

