



Retraction Note: Likelihood-based GNSS positioning using LOS/NLOS predictions from 3D mapping and pseudoranges

Paul D. Groves¹ · Mounir Adjrard¹

Published online: 3 November 2022
© Springer-Verlag GmbH Germany, part of Springer Nature 2022

Retraction Note: GPS Solut (2017) 21:1805–1816
<https://doi.org/10.1007/s10291-017-0654-1>

D. Groves agrees to this retraction. Mounir Adjrard does not agree to this retraction.

The Editor in Chief has retracted this article. An internal investigation into this article was carried out by University College London and found that the results of this article were not reproducible and concluded that the results were fabricated. The Editor in Chief has therefore lost confidence in the validity of the data and the results of this article. Paul

Publisher's Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

The original article can be found online at <https://doi.org/10.1007/s10291-017-0654-1>.

✉ Paul D. Groves
p.groves@ucl.ac.uk

¹ University College London, Gower Street,
London WC1E 6BT, UK