Uniqueness for solutions of the Schrödinger equation on trees

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Abstract

We prove that if a solution of the time-dependent Schrödinger equation on an homogeneous tree with bounded potential decays fast at two distinct times then the solution is trivial. For the free Schrödinger operator, we use the spectral theory of the Laplacian and complex analysis and obtain a characterization of the initial conditions that lead to a sharp decay at any time. We then adapt the real variable methods first introduced by Escauriaza, Kenig, Ponce and Vega to establish a general sharp result in the case of bounded potentials.

Keywords Schrödinger equation · Bethe lattice · homogeneous trees · Uncertainty principle

Mathematics Subject Classification 05C05 · 31C20 · 39A12 · 81Q10

1 Introduction

The aim of the present paper is to study uniqueness results for Schrödinger equations with bounded potentials on homogeneous trees. These results can be seen as a version for homogeneous trees of a dynamical interpretation of the Hardy uncertainty principle.

The Schrödinger equation $i\partial_t u = \Delta u + Vu$ has been extensively studied by mathematicians and physicists. Those studies are carried out in various underlying spaces, both continuous ($\mathbb{R}^d$, manifolds, etc.) and discrete. In the discrete setting, on $\mathbb{Z}^d$ and on the homogeneous tree (also known as a *Bethe lattice* in the physics community), this equation has first been considered by Anderson and collaborators in [1,5] in order to describe the behavior of a quantum particle in disordered medium.

Our aim here is to further investigate properties of solutions of the Schrödinger equation on an homogeneous tree. We will prove that solutions of the Schrödinger equation $i\partial_t u =$

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$\Delta u + Vu$ on an homogeneous tree cannot be too sharply localized at two different times when the potential V is bounded. Our results may thus be seen as a dynamical version of the uncertainty principle. Before outlining our results more precisely, let us first explain what we mean by “localizing” and further explain our motivations in this paper.

Let us start by recalling Hardy’s uncertainty principle [32] on the real line: assume $f \in L^2(\mathbb{R})$ satisfies a decrease property like

$$|f(x)| \leq Ce^{-x^2/\beta^2}, \quad |\hat{f}(\xi)| \leq Ce^{-4\xi^2/\alpha^2}. \quad (1.1)$$

Then, if $\alpha\beta < 4$, $f \equiv 0$, while, in the endpoint case, $\frac{1}{\alpha\beta} = \frac{1}{4}$, $f = Ce^{-x^2/\beta^2}$. In other words, both a function and its Fourier transform cannot be localized below two sharply localized Gaussians.

Numerous authors have extended this result to higher dimensions, replacing the point-wise estimate (1.1) by integral or even distributional conditions (see, e.g., the works of Hörmander, Bonami, Demange and the second author [12, 13, 19, 34]) and also replacing the underlying space $\mathbb{R}^d$ by various Lie groups (as can be found, for instance, in the work of Baklouti, Kaniuth, Sitaram, Sundari, Thangavelu, etc. including [7, 8, 42, 44, 45]). The survey [30] and the books [33, 46] may be taken as a starting point to further investigate the subject. Most of this work requires either complex analysis or a reduction to a real variable setting in which complex variable tools are available. A first difficulty appears here as the decrease in the space variable and in the Fourier variable can no longer be measured in the same way. This problem becomes even more striking in the discrete setting. For instance, for functions on $\mathbb{Z}$, the Fourier transform is a periodic function, so that there is no decrease at infinity.

To overcome this, one way is to consider a dynamical interpretation of the uncertainty principle. To explain what we mean by this, let us go back to the real line. Recall that the solution of the free Schrödinger equation $i\partial_t u = \Delta u$, $u(0, x) = u_0(x)$ is given by the following representation formula:

$$\begin{aligned} u(x, t) &= (4\pi it)^{-n/2} \int_{\mathbb{R}^n} e^{\frac{-i|x-y|^2}{4t}} u_0(y) dy \\ &= (2\pi it)^{-n/2} e^{\frac{-i|x|^2}{4t}} \widehat{e^{-i\frac{| \cdot |^2}{4t}} u_0} \left(-\frac{x}{2t} \right). \end{aligned}$$

Hence, the solution at a fixed time has, roughly speaking, the same size as the Fourier transform of the initial data, and we can translate decay properties of u_0 and $\widehat{u_0}$ into decay properties of u_0 and $u(x, T)$ for a fixed time T , to have

$$|u_0(x)| \leq Ce^{-x^2/\beta^2}, \quad |u(x, T)| \leq Ce^{-x^2/\alpha^2}, \quad \frac{T}{\alpha\beta} > \frac{1}{4} \implies u \equiv 0$$

and, if $\frac{T}{\alpha\beta} = \frac{1}{4}$, $u_0(x) = Ce^{-x^2(1/\beta^2 + i/4T)}$.

This point of view has been used by Chanillo [15] to prove a dynamical uncertainty principle on complex semi-simple Lie groups by reducing the problem to Hardy’s uncertainty principle on the real line. At the same time, Escauriaza, Kenig, Ponce and Vega started a series of papers [22–24] where they provide the first proof of Hardy’s uncertainty principle in its dynamical version in the presence of a potential, using real calculus. Their motivation is to consider solutions of general linear Schrödinger equations $i\partial_t u = \Delta u + Vu$, only assuming size conditions for the space and time-dependent potential V . The robustness of both methods allows to extend their results to different settings, such as for covariant Schrödinger evolutions by Barceló, Cassano, Fanelli, Gutiérrez, Ruiz, Vilela [9, 14], or heat evolutions [25] but also

to other underlying spaces; see, e.g., the work of Ben Saïd, Dogga, Ludwig, Müller, Pasquale, Sundari, Thangavellu [11,38,40].

More recently, independently in [26,27,35], together with Lyubarskii, Malinnikova, Perfekt and Vega, we began to extend the previous results to the discrete setting, understanding the Laplace operator as a finite-difference operator, acting on complex-valued functions $f : \mathbb{Z} \rightarrow \mathbb{C}$,

$$\Delta_d f(n) := f(n+1) + f(n-1) - 2f(n).$$

For the free evolution, or for the linear evolution with a bounded time-independent potential, as shown in [39], one can use complex analysis tools, more precisely refined versions of the Phragmén–Lindelöf principle, to give a discrete version of the Hardy uncertainty principle. As in the continuous case, the critical decay is given by the discrete heat kernel, given in terms of modified Bessel functions. However, this similarity leads also to the main difference between both settings, because the critical decay is not Gaussian. More precisely, it is shown in [35] that for $0 < \alpha < 1$ and u a $C^1([0, 1], \ell^2(\mathbb{Z}))$ solution of $\partial_t u = i\Delta_d u$ (a so-called *strong* solution), if u satisfies the estimate

$$|u(n, 0)| + |u(n, 1)| \leq C I_n(\alpha) \sim \frac{C}{\sqrt{|n|}} \left(\frac{e\alpha}{2|n|} \right)^{|n|}, \quad n \in \mathbb{Z} \setminus \{0\}, \quad (1.2)$$

then $u \equiv 0$. In the endpoint case, $\alpha = 1$, $u(n, t) = \gamma i^{-n} e^{-2it} J_n(1-2t)$, where γ is a constant and J_n is the Bessel function. Note that classical estimates of Bessel functions show that, for any $\gamma > 0$, there is a $C > 0$ such that this solution indeed satisfies (1.2). This argument is also extended to other type of problems, as shown by Alvarez-Romero and Teschl [2,3] for Jacobi operators.

In the case of linear Schrödinger equations, one can give a dynamical version of the Hardy uncertainty principle, only assuming that the potential is bounded, which makes another difference with the continuous case, since in the continuous case, all results in [22–24] require to have some decay in the potential, and the result is still open for bounded potentials. To be more precise, the first author and Vega [27] showed that if u is a strong solution of $\partial_t u = i(\Delta_d u + V u)$ on $\mathbb{Z}$ (with $V = V(n, t)$ bounded) and if u satisfies the decay condition

$$\sum_{n \in \mathbb{Z}} e^{2\mu(|n|+1) \log(|n|+1)} (|u(n, 0)|^2 + |u(n, 1)|^2) < \infty \quad (1.3)$$

for some $\mu > 1$, then $u = 0$. In view of the free case, as $u(n, t) = \gamma i^{-n} e^{-2it} J_n(1-2t)$ is a solution of the free Schrödinger equation and it satisfies (1.3) with $\mu = 1 - \epsilon$, $\forall \epsilon > 0$ (as one can deduce from (1.2)), the condition $\mu > 1$ is optimal. It is worth mentioning that $\mu = 1$ gives the leading term in the asymptotic expression for $I_n(\alpha)$ in (1.2). Note also that [26,35] both contain similar results but only in non-optimal cases $\mu > \mu_0 > 1$. A higher-dimensional version of this result can be found in [27], although the rate of decay μ obtained there depends on the dimension and the sharp result is still open. The key tool here is to establish Carleman-type estimates, that is, a weighted inequality of the form $C_w \|wu\|_{L^2(\mathbb{Z}^d)} \leq \|w(i\partial_t + \Delta_d)u\|_{L^2(\mathbb{Z}^d)}$ for an appropriate weight w and a constant C_w depending on this weight. We refer to [36] for more on Carleman estimates and their use in the continuous setting.

Therefore, the results in [27,35,39] are based on two different approaches. For the linear evolution with time-independent bounded potential, one uses complex analysis, while in the presence of a time-dependent bounded potential the Phragmén–Lindelöf principle is not

available and one replaces this by a suitable Carleman inequality (using real variable methods instead of complex analysis).

In this paper, we extend both approaches to homogeneous trees of degree $q + 1$ (*Bethe lattices*), which we denote by $\mathbf{T}_q$. This is a connected graph with no loops, rooted in a point denoted by o , where every vertex is adjacent to $q + 1$ other vertices, a relation denoted by $y \sim x$. Thus, one can see $\mathbf{T}_q$ as a natural extension of the line $\mathbb{Z}$, which can be seen as a homogeneous tree of degree 2. One may then ask whether the behavior for solutions of Schrödinger evolutions is similar on $\mathbb{Z}$ and on $\mathbf{T}_q$. As in the line $\mathbb{Z}$, we understand the Laplacian as the combinatorial Laplacian, that is, a finite-difference operator $\mathcal{L}$ only taking into account interactions between nearest neighbors (see Sect. 2 for a precise definition).

It is our aim here to contribute to the understanding of the behavior of solutions of Schrödinger equations on trees (*see e.g.*, the recent papers by Anantharaman, Colin de Verdière, Eddine, Sabri, Truc [4, 18, 21] for other directions) by establishing uncertainty principles on trees. (So far, we are only aware of one article by Astengo [6] dealing with that issue.)

We are now in a position to describe our results. First, since the spectral theory of the Laplacians on homogeneous trees is known (*see* Cowling and Setti [16]), we have all the ingredients to give a dynamic interpretation of the Hardy uncertainty principle on $\mathbf{T}_q$ when there is no potential:

Theorem A *There exists a function U_q on $\mathbf{T}_q$ such that, if u is a strong solution of the equation*

$$i \partial_t u(x, t) = \mathcal{L}u(x, t) = u(x, t) - \frac{1}{q+1} \sum_{y \sim x} u(y, t), \quad x \in \mathbf{T}_q$$

with $u(x, 0) = u_0(x)$ and if at times $t_0 = 0$ and $t_1 = 1$, there is a κ such that, for $x \neq o$

$$|u(x, t_i)| \leq \frac{\kappa}{\sqrt{|x|}} \left(\frac{e}{2(q+1)|x|} \right)^{|x|} \quad (1.4)$$

then $u_0 = \gamma U_q$ for some $\gamma \in \mathbb{C}$.

The function U_q is explicitly given by an integral formula; *see* below. In order to compare our results with the case of $\mathbb{Z}$, let us rewrite (1.4) as

$$|u(x, t_i)| \leq \kappa |x|^{-1/2} e^{(1 - \ln 2(q+1))|x|} e^{-|x| \ln |x|}.$$

We thus see that the main term $e^{-|x| \ln |x|}$ does not depend on the tree and is the same as for $\mathbb{Z}$ and that the dependence on the degree of the tree is rather mild. It is somewhat unexpected that the behavior is the same in both cases as the tree is the Caley graph of the free group which is non-amenable and has exponential growth, while $\mathbb{Z}$ is amenable and has polynomial growth.

Further, as an immediate corollary, we obtain

Corollary B *Let $\mu > 1$. If u is a strong solution of the equation*

$$i \partial_t u(x, t) = \mathcal{L}u(x, t) = u(x, t) - \frac{1}{q+1} \sum_{y \sim x} u(y, t), \quad x \in \mathbf{T}_q$$

with $u(x, 0) = u_0(x)$ and if at times $t_0 = 0$ and $t_1 = 1$,

$$\sum_{x \in \mathbf{T}_q} e^{2\mu|x| \log(|x|+1)} (|u(x, 0)|^2 + |u(x, 1)|^2) < +\infty \quad (1.5)$$

then $u \equiv 0$.

Our second aim is to show that this corollary stays true for the Schrödinger equation in the presence of a potential: $i\partial_t u(x) = \mathcal{L}u(x) + V(x, t)u(x)$, with a bounded time-dependent potential V . This time, we will use real variable calculus.

This approach combines the main techniques of [27, 35], to prove first that a fast decaying solution at two different times preserves this decay at any interior time, and, later, via a Carleman estimate with Gaussian weight, we give a lower bound for the ℓ^2 -norm of the solution in a region far from the origin (see Theorem 4.7). A combination of these two facts leads then to:

Theorem C (Uniqueness result) *Let $u \in C^1([0, 1] : \ell^2(\mathbf{T}_q))$ be a solution of $i\partial_t u(x) = \mathcal{L}u(x) + V(x, t)u(x)$ with V a bounded potential. If for $\mu > 1$*

$$\sum_{x \in \mathbf{T}_q} e^{2\mu|x| \log(|x|+1)} (|u(x, 0)|^2 + |u(x, 1)|^2) < +\infty,$$

then $u \equiv 0$.

This shows that Corollary B is also valid in the presence of a bounded potential; in particular, the condition $\mu > 1$ is essentially sharp up to the endpoint $\mu = 1$ which is open. This result is exactly the same as in the case of $\mathbb{Z}$ [27]. This is no longer surprising in view of Theorem A and Corollary B as the influence of the tree in the optimal decay is very mild. However, one may ask whether this result is true for any infinite graph or whether it can be extended to large classes of graphs. We provide some examples of infinite graphs for which the behavior of the solutions is different.

The paper is organized as follows: In Sect. 2, we introduce some notation and preliminaries from the theory of entire functions as well as a summary of the spectral theory of the adjacency matrix on $\mathbf{T}_q$. These notions can be found in [18, 37], but we include them here to clarify our presentation. Section 3 studies the free Schrödinger equation and includes the proof of Theorem A. Section 4 covers the real variable approach, proving Theorem C via a Carleman inequality and logarithmic convexity of ℓ^2 weighted norms. We conclude in Sect. 5 with some considerations on other graphs.

2 Notation and preliminaries

2.1 Entire functions of exponential type

As in [35], we will use methods from complex analysis. For the reader's convenience, we begin by briefly outlining some definitions and facts on entire functions of exponential type that we need. Details can be found in [37] (see, in particular, Lectures 8 and 9). Recall that an entire function f is said to be of exponential type if for some $k > 0$

$$|f(z)| \leq C \exp(k|z|). \quad (2.1)$$

In this case, the type of an entire function f is defined by

$$\sigma = \limsup_{r \rightarrow \infty} \frac{\log \max\{|f(re^{i\phi})|; \phi \in [0, 2\pi]\}}{r} < \infty. \quad (2.2)$$

In particular, an entire function f is of zero exponential type if for any $k > 0$ there exists $C = C(k)$ such that (2.1) holds.

Let $f(z)$ be an entire function of exponential type, $f(z) = \sum_{n=0}^{\infty} c_n z^n$. Then the type of f can be expressed in terms of its Taylor coefficients as

$$\limsup_{n \rightarrow \infty} n |c_n|^{1/n} = e\sigma. \quad (2.3)$$

The growth of a function f of exponential type along different directions is described by the indicator function

$$h_f(\varphi) = \limsup_{r \rightarrow \infty} \frac{\log |f(re^{i\varphi})|}{r}.$$

This function is the support function of some convex compact set $I_f \subset \mathbb{C}$ which is called the indicator diagram of f :

$$h_f(\varphi) = \sup\{\Re(ae^{-i\varphi}), a \in I_f\}.$$

In particular,

$$h_f(\varphi) + h_f(\pi + \varphi) \geq 0. \quad (2.4)$$

For example, the indicator function of e^{az} for $a \in \mathbb{C}$ is $h(\varphi) = \Re(ae^{i\varphi})$ and its indicator diagram consists of a single point, $\bar{a}$.

Clearly, $h_{fg}(\varphi) \leq h_f(\varphi) + h_g(\varphi)$, implying that

$$I_{fg} \subset I_f + I_g := \{z = z_1 + z_2 : z_1 \in I_f, z_2 \in I_g\}.$$

2.2 Trees

In this section, we recall some basics of harmonic analysis on trees. For more on this subject, one may refer to, e.g., [16,17,28,29] and references therein.

Throughout this paper, q will be an integer, $q \geq 2$. We will denote by $\mathbf{T} = \mathbf{T}_q$ the homogeneous tree of degree $q + 1$. This means that the tree is formed by a connected graph with no loops where every vertex is adjacent to $q + 1$ other vertices, relation denoted by $y \sim x$.

A *geodesic path* (resp. *geodesic ray*, *infinite geodesic*) in $\mathbf{T}$ is a finite (resp. one-sided infinite, resp. doubly infinite) sequence (x_n) such that two consecutive terms are adjacent, $x_n \sim x_{n-1}$ and that does not turn back $x_{n+1} \neq x_{n-1}$. We can then define the distance $d(x, y)$ as the number of points in the geodesic path which goes from x to y . In particular, in a geodesic, $d(x_n, x_m) = |n - m|$.

Moreover, we fix a vertex of the tree $\mathbf{T}$ to be the root o and write $|x| = d(x, o)$. For an integer $\ell \geq 0$, we denote by $S_\ell = \{x \in \mathbf{T} : |x| = \ell\}$. The boundary $\partial\mathbf{T}$ of $\mathbf{T}$ is defined as the set of infinite paths starting at the root o . Then, we define, for a point $x \in \mathbf{T}$ and $w \in \partial\mathbf{T}$, the confluence point of x and w , denoted by $x \wedge w$ as the last point lying on w in the geodesic path joining o and x . Attached to this confluence point, we define the *Busemann function* h_w and the *horocycles* $\mathcal{H}_k^w$, $k \in \mathbb{Z}$ by

$$h_w(x) = |x| - 2|x \wedge w| \quad \text{and} \quad \mathcal{H}_k^w = \{x \in \mathbf{T} : h_w(x) = k\}.$$

We call k the height of the horocycle $\mathcal{H}_k^w$. Every horocycle is infinite and every $x \in \mathcal{H}_k^w$ has one neighbor $x^- \in \mathcal{H}_{k-1}^w$ (its predecessor) and q neighbors in $\mathcal{H}_{k+1}^w$ (its successors) (Fig. 1).

Fig. 1 Tree $\mathbf{T}_2$ and horocycles

Now let $\psi_{\ell,k} = |S_\ell \cap \mathcal{H}_k^w|$ be the number of elements in an horocycle $\mathcal{H}_k$ that are of length ℓ . When $k \geq 0$,

$$\psi_{\ell,k} = \begin{cases} q^k & \text{if } \ell = k \\ (q-1)q^{k+p-1} & \text{if } \ell = k+2p, \ p \geq 1 \\ 0 & \text{otherwise} \end{cases}$$

and for $k \geq 1$,

$$\psi_{\ell,-k} = \begin{cases} 1 & \text{if } \ell = k \\ (q-1)q^{p-1} & \text{if } \ell = k+2p, \ p \geq 1 \\ 0 & \text{otherwise} \end{cases}.$$

The so-called Helgason–Fourier transform (see, e.g., [16]) of a function f on the tree is defined by the formula

$$\mathcal{F}_{\mathbf{T}}[f](s, w) := \sum_{x \in \mathbf{T}} f(x) q^{-(1/2+is)h_w(x)}, \quad s \in \mathbb{T}, \quad w \in \partial \mathbf{T},$$

where $\mathbb{T} = \mathbb{R}/\tau\mathbb{Z}$, usually identified with the interval $[-\tau/2, \tau/2)$, with $\tau = 2\pi/\log q$.

Moreover, the following inversion formula holds,

$$f(x) = \int_{\mathbb{T}} \int_{\partial \mathbf{T}} q^{-(1/2-is)h_w(x)} \mathcal{F}_{\mathbf{T}}[f](s, w) \, d\nu(w) \, d\mu(s), \quad x \in \mathbf{T}. \quad (2.5)$$

We refer to [16] for the exact definitions of the measures ν and μ .

We will also need to distinguish between the neighbors and double neighbors of a vertex of the tree. More precisely, for $x \in \mathbf{T}$ with $|x| = n$ we set

- $x_f = \{y \in \mathbf{T} : |y| = n+1\}$ and, if $x \neq o$, x_p to be the unique $y \in \mathbf{T}$ such that $y \sim x$ and $|y| = n-1$. Note that $|o_f| = q+1$ and, if $x \neq o$, $|x_f| = q$.

- $x_{ff} = \{y \in \mathbf{T} : |y| = n + 2, y_p \in x_f\}$ so that $|o_{ff}| = q(q + 1)$ and, if $x \neq o$, $|x_{ff}| = q^2$.
- If $|x| \geq 2$, $x_{pp} = (x_p)_p$.
- If $x \neq o$, $x_{pf} = (x_p)_f \setminus \{x\}$ so that $|y| = |x|$ if $y \in x_{pf}$. Note that if $|x| = 1$, $|x_{pf}| = q$, while otherwise $|x_{pf}| = q - 1$.

In other words, x_f is the set of followers (daughters) of x , x_p the predecessor (mother) of x , x_{pp} the grandmother of x , x_{ff} the set of granddaughters of x and x_{pf} the set of sisters of x .

Note that, for any function φ on $\mathbf{T}$, and any $n \geq 1$,

$$\sum_{|x|=n} \sum_{z \in x_{pf}} \varphi(z) = \begin{cases} q \sum_{|x|=1} \varphi(x) & \text{if } n = 1 \\ (q - 1) \sum_{|x|=n} \varphi(x) & \text{if } n \geq 2 \end{cases}. \quad (2.6)$$

Finally, we consider the adjacency operator A_0 and the Laplace operator $\mathcal{L}$ on $\mathbf{T}$: for u a function on $\mathbf{T}$,

$$A_0 u(x) = \sum_{y \sim x} u(y)$$

and¹

$$\begin{aligned} \mathcal{L}u(x) &= \left(I - \frac{1}{q+1} A_0 \right) u(x) = u(x) - \frac{1}{q+1} \sum_{y \sim x} u(y) \\ &= \frac{1}{q+1} \sum_{y \sim x} (u(x) - u(y)). \end{aligned}$$

We will denote by $\|\cdot\|_2$ the $\ell^2(\mathbf{T})$ -norm: if $u : \mathbf{T} \rightarrow \mathbb{C}$,

$$\|u\|_2^2 = \sum_{x \in \mathbf{T}} |u(x)|^2$$

and by $\|\cdot\|_{L^2_{x,t}}$ the $L^2_t \ell^2$ -norm: if $u : [0, 1] \times \mathbf{T} \rightarrow \mathbb{C}$,

$$\|u\|_{L^2_{x,t}}^2 = \int_0^1 \sum_{x \in \mathbf{T}} |u(t, x)|^2 dt.$$

3 Free Schrödinger equation on the tree

We want to study uniqueness properties of solutions of the Schrödinger equation $i \partial_t u = \mathcal{L}u$ assuming that they have fast decay at two different times. Adapting the method developed in [35] in the case of the line $\mathbb{Z}$ to the tree, our main result in this section is Theorem A from the introduction, in a slightly more precise form:

¹ Results in this paper can be adapted in a straightforward way to the Laplacian more commonly used in the physics community

$$\Delta \varphi(x) = \deg x \varphi(x) - \sum_{y \sim x} \varphi(y).$$

Theorem 3.1 Assume that u is a strong solution of the equation

$$i \partial_t u(x, t) = \mathcal{L}u(x, t) = u(x, t) - \frac{1}{q+1} \sum_{y \sim x} u(y, t), \quad x \in \mathbf{T} \quad (3.1)$$

with $u(x, 0) = u_0(x)$. Assume that there is a κ such that, at times $t_0 = 0$ and $t_1 = 1$, for $x \neq o$

$$|u(x, t_i)| \leq \frac{\kappa}{\sqrt{|x|}} \left(\frac{e}{2(q+1)|x|} \right)^{|x|}. \quad (3.2)$$

Then there exists a constant C such that u_0 is the function that only depends on $|x|$ given by the integral representation formula

$$u_0(x) = \frac{C}{q^{|x|/2}} \int_0^\pi \exp\left(-i \frac{q^{1/2}}{q+1} \cos(z)\right) \varphi_{|x|}(z) \sin(z) \, dz,$$

where

$$\varphi_j(z) = \frac{q^{1/2} \sin(z(j+1)) - q^{-1/2} \sin(z(j-1))}{q + q^{-1} - 2 \cos(2z)}.$$

Remark 3.2 A change of variable allows us to write u_0 as

$$u(|x|, 0) = \frac{C}{q^{|x|/2}} \mathcal{F}[\psi_{|x|}]\left(\frac{q^{1/2}}{q+1}\right),$$

where $\mathcal{F}$ is the Fourier transform on $\mathbb{R}$ and

$$\psi_j(s) = \frac{q^{1/2} \sin((j+1) \arccos s) - q^{-1/2} \sin((j-1) \arccos s)}{q + q^{-1} + 2(1 - 2s^2)}$$

on $(-1, 1)$ and $\psi_j = 0$ on $\mathbb{R} \setminus (-1, 1)$.

Proof Let us fix a ray $w = oy_1 y_2 \dots$. Let $k \in \mathbb{Z}$. As we already noticed, if $x \in \mathcal{H}_k^w$, it has exactly one predecessor in $\mathcal{H}_{k-1}^w$ and q successors in $\mathcal{H}_{k+1}^w$. Therefore,

$$\mathcal{L}\left(q^{-(1/2+is)h_w(x)}\right) = \left(1 - \frac{q^{1/2+is}}{q+1} - q \frac{q^{-1/2-is}}{q+1}\right) q^{-(1/2+is)h_w(x)}.$$

For a solution u of (3.1), we consider the Fourier–Hergason transform $\tilde{u}(s, w, t) = \mathcal{F}_{\mathbf{T}}[u(\cdot, t)](s, w)$, whose evolution is given by

$$i \partial_t \tilde{u} = \left(1 - \frac{q^{1/2}}{q+1} (q^{is} + q^{-is})\right) \tilde{u}.$$

Hence, if we set $\sigma = \frac{q^{1/2}}{2(q+1)}$,

$$\tilde{u}(s, w, t) = e^{-i(1-2\sigma(q^{is}+q^{-is}))t} \tilde{u}(s, w, 0). \quad (3.3)$$

Now we decompose,

$$\begin{aligned} \tilde{u}(s, w, t) &= \sum_{x \in \mathbf{T}, h_w(x) > 0} u(x, t) q^{-h_w(x)/2} q^{-is h_w(x)} \\ &\quad + \sum_{x \in \mathbf{T}, h_w(x) \leq 0} u(x, t) q^{-h_w(x)/2} q^{-is h_w(x)} \end{aligned}$$

$$= \sum_{k=0}^{+\infty} \frac{1}{q^{k/2}} \left(\sum_{x \in \mathcal{H}_k^w} u(x, t) \right) \xi^k + \sum_{k=1}^{+\infty} q^{k/2} \left(\sum_{x \in \mathcal{H}_{-k}^w} u(x, t) \right) \left(\frac{1}{\xi} \right)^k,$$

where $\xi = q^{-is}$.

Now write $b_0 = 1$ and, for $\ell \geq 1$, $b_\ell = \frac{1}{\sqrt{\ell}} \left(\frac{e}{2(q+1)\ell} \right)^\ell$ so that if $t_j \in \{0, 1\}$,

$$\left| \sum_{x \in \mathcal{H}_k^w} u(x, t_j) \right| = \left| \sum_{\ell=0}^{\infty} \sum_{x \in \mathcal{H}_k^w \cap S_\ell} u(x, t_j) \right| \leq \kappa \sum_{\ell=0}^{\infty} \psi_{\ell,k} b_\ell \leq \begin{cases} \kappa q^k \left(b_k + (q-1) \sum_{p=1}^{\infty} q^{p-1} b_{k+2p} \right) & \text{for } k \geq 0 \\ \kappa \left(b_{-k} + (q-1) \sum_{p=1}^{\infty} q^{p-1} b_{-k+2p} \right) & \text{for } k \leq -1 \end{cases}.$$

Using that $(k+2p)^{k+2p+1/2} \geq k^{k+1/2}$ when $k, p \geq 1$, and that $(2p)^{2p+1/2} \geq 4$ we get that, for $k \geq 1$,

$$\begin{aligned} \sum_{p=1}^{\infty} q^{p-1} b_{k+2p} &= \left(\frac{e}{2(q+1)} \right)^k \frac{1}{q} \sum_{p=1}^{\infty} \left(\frac{e\sqrt{q}}{2(q+1)} \right)^{2p} \frac{1}{(k+2p)^{k+2p+1/2}} \\ &\leq \frac{1}{\sqrt{k}} \left(\frac{e}{2(q+1)k} \right)^k \frac{e^2}{4(q+1)^2 \left(1 - \frac{e^2 q}{4(q+1)^2} \right)} \leq b_k \end{aligned}$$

and the same bound holds for $k = 0$; thus,

$$\left| \sum_{x \in \mathcal{H}_k^w} u(x, t_j) \right| \leq \begin{cases} \kappa q & \text{for } k = 0 \\ \kappa q^{k+1} b_k = \kappa q \frac{1}{\sqrt{k}} \left(\frac{eq}{2(q+1)k} \right)^k & \text{when } k \geq 1 \\ \kappa q b_{|k|} = \kappa q \frac{1}{\sqrt{|k|}} \left(\frac{e}{2(q+1)|k|} \right)^{|k|} & \text{when } k \leq -1 \end{cases}.$$

It follows that

$$\phi_j^+(\xi, w) := \sum_{k=0}^{+\infty} q^{-k/2} \left(\sum_{x \in \mathcal{H}_k^w} u(x, t_j) \right) \xi^k$$

extends into an entire function in ξ of exponential type σ . Its indicator diagram I_j^+ is therefore included in the closed disk $\bar{D}(0, \sigma)$. On the other hand,

$$\phi_j^-(\zeta, w) := \sum_{k=1}^{+\infty} q^{k/2} \left(\sum_{x \in \mathcal{H}_{-k}^w} u(x, t_j) \right) \zeta^k \quad (3.4)$$

extends into an entire function in ζ of exponential type σ as well and its indicator diagram I_j^- is therefore also included in the disk $\bar{D}(0, \sigma)$. Actually, a little more is shown, namely that

$$|\phi_j^\pm(\xi, w)| \leq C_q \kappa e^{\sigma|\xi|}, \quad (3.5)$$

since we bound the corresponding coefficient of each sum by the k th coefficient of the Taylor series of $e^{\sigma|\xi|}$, fact that motivates the use of the hypothesis (3.2).

Let us now turn back to (3.3) which we write as

$$\tilde{u}(s, w, t) = e^{-i(1-2\sigma(\xi+\xi^{-1}))t} (\phi_0^-(\xi^{-1}, w) + \phi_0^+(\xi, w)).$$

This holds a priori for $\xi = q^{-is}$ and thus extends to $\xi \in \mathbb{C} \setminus \{0\}$ and every t . We write $\tilde{u}(\xi, w, t)$ for the corresponding extension.

For $t = 1$, we obtain

$$\begin{aligned} \phi_1^\pm(\xi, w) &= -\phi_1^\mp(\xi^{-1}, w) \\ &\quad + e^{-i} \exp(2i\sigma(\xi + \xi^{-1})) (\phi_0^\pm(\xi, w) + \phi_0^\mp(\xi^{-1}, w)). \end{aligned}$$

It follows that $I_1^\pm \subset I_0^\pm + 2i\sigma$ which in turn implies that $I_1^\pm$ is reduced to $i\sigma$ and $I_0^\pm$ is reduced to $-i\sigma$.

Let us now take $t = 1/2$. Then

$$\tilde{u}(\xi, w, 1/2) = e^{-i/2} e^{i\sigma(\xi+\xi^{-1})} (\phi_0^-(\xi^{-1}, w) + \phi_0^+(\xi, w)).$$

Write $\tilde{u}(\xi, w, 1/2) = u_+(\xi) + u_-(\xi^{-1})$ where u_+ (resp. u_-) contains all terms of positive (resp. negative) exponent in the Laurent series of $\tilde{u}$. The indicator diagram of those functions coincides with $\{0\}$; thus, $u_\pm$ are entire functions of 0 exponential type. On the other hand, (3.5) shows that $u_\pm$ are bounded on $i\mathbb{R}$. Indeed, when $\xi \rightarrow +\infty$,

$$\begin{aligned} |u_+(i\xi)| &\sim |\tilde{u}(i\xi, w, 1/2)| = |e^{-\sigma(\xi+\xi^{-1})}| |\phi_0^-(i\xi^{-1}, w) + \phi_0^+(i\xi, w)| \\ &\sim e^{-\sigma\xi} |\phi_0^+(i\xi, w)| \leq C_q \kappa. \end{aligned}$$

To see that $u_+(i\xi)$ is also bounded when $\xi \rightarrow -\infty$, let us write

$$\tilde{u}(\xi, w, 1/2) = e^{-i/2} e^{-i\sigma(\xi+\xi^{-1})} (\phi_1^-(\xi^{-1}, w) + \phi_1^+(\xi, w)).$$

Then

$$\begin{aligned} |u_+(i\xi)| &\sim |\tilde{u}(i\xi, w, 1/2)| = |e^{\sigma(\xi+\xi^{-1})}| |\phi_1^-(i\xi^{-1}, w) + \phi_1^+(i\xi, w)| \\ &\sim e^{\sigma\xi} |\phi_1^+(i\xi, w)| \leq C_q \kappa. \end{aligned}$$

The proof for $|u_-(i\xi)|$ is similar but this time $\xi \rightarrow 0^\pm$.

Now, according to the Phragmén–Lindelöf principle (see, e.g., [37, Lecture 6]) u_+ and u_- are constant, and thus, $\tilde{u}(\xi, w, 1/2)$ does not depend on ξ . It then follows from (3.3) that

$$\tilde{u}(s, w, 0) = C_w \exp(-i\sigma(q^{is} + q^{-is}))$$

for some constant C_w that depends on the ray w . But, by definition, for $\xi = q^{-is}$

$$\tilde{u}(\xi, w, 0) = \sum_{x \in \mathbf{T}} u(x, 0) \left(\frac{\xi}{\sqrt{q}} \right)^{h_w(x)}$$

and this extends to all $\xi \in \mathbb{C} \setminus \{0\}$, in particular to $\xi = \sqrt{q}$. This shows that

$$C_w = \exp(i\sigma(q^{1/2} + q^{-1/2})) \sum_{x \in \mathbf{T}} u(x, 0)$$

does not depend on w . We thus write $C_w = C$.

The integral formula for $u(|x|, 0)$ then comes from the inversion formula (2.5) and (see [16])

$$\int_{\partial \mathbf{T}} q^{-(1/2-is)h_w(x)} d\nu(w) = c(-s)q^{(-is-1/2)|x|} + c(s)q^{(is-1/2)|x|},$$

where $c(s) = \frac{q^{1/2}}{q+1} \frac{q^{1/2+is} - q^{-1/2-is}}{q^{is} - q^{-is}}$. □

As an immediate corollary, we have the following uniqueness property for strong solutions of (3.1):

Corollary 3.3 *Assume that u is a strong solution of equation (3.1). Assume that there exists $\epsilon > 0$ and κ such that, for $x \neq 0$*

$$|u(x, t_i)| \leq \frac{\kappa}{\sqrt{|x|}} \left(\frac{e}{(2+\epsilon)(q+1)|x|} \right)^{|x|}, \quad t_0 = 0, \quad t_1 = 1.$$

Then $u \equiv 0$.

Remark 3.4 Note that $\tilde{u}(s, w, 0) = C \exp(-i\sigma(q^{is} + q^{-is}))$, and therefore, $\tilde{u}(s, w, t) = C \exp(-i(t + \sigma(1-2t)(q^{is} + q^{-is})))$. Applying the inversion formula (2.5) to this function, we get an integral representation formula for the evolution $u(x, t)$.

This could also be obtained by analytic continuation of the well-known solution of the heat equation on the tree.

Remark 3.5 We leave as an exercise to the reader to check that, if u is a strong solution of the equation $i\partial_t u(x, t) = \lambda \mathcal{L}u(x, t)$, with $u(x, 0) = u_0(x)$, $\lambda > 0$ and if

$$|u(x, t_i)| \leq \frac{\kappa}{\sqrt{|x|}} \left(\frac{e\lambda}{2(q+1)|x|} \right)^{|x|} \quad (3.6)$$

then

$$u_0(x) = \frac{C}{q^{|x|/2}} \int_0^\pi \exp\left(-i \frac{q^{1/2}\lambda}{q+1} \cos(z)\right) \varphi_{|x|}(z) \sin(z) dz$$

for some constant C .

Note that when $\lambda = q+1$, condition (3.6) is the same for the tree $\mathbf{T}_q$ and for $\mathbb{Z}$ so that the dependence on the tree is hidden.

Remark 3.6 The only other uncertainty principle on the tree we are aware of is due to Astengo [6]. It is of a rather different nature to our results. More precisely, Astengo states an uncertainty principle in terms of a function on the tree and the modulus of its Fourier–Hergason transform. In view of Formula (3.3), Astengo’s result immediately translates into a result for solutions of the free Schrödinger equation on the tree:

Assume that u is a strong solution of the equation

$$i\partial_t u(x, t) = \mathcal{L}u(x, t) = u(x, t) - \frac{1}{q+1} \sum_{y \sim x} u(y, t), \quad x \in \mathbf{T} \quad (3.7)$$

with $u(x, 0) = u_0(x)$. Assume that there is a time t_0 such that

- (i) $|u_0(x)| \leq C e^{-\alpha|x|}$ for some $C > 0$ and some $\alpha > \frac{1}{2} \log q$;
- (ii) $s \rightarrow \|\mathcal{F}_{\mathbf{T}} u(\cdot, s, t_0)\|_{L^2(\partial \mathbf{T})} \in L^1(\mathbb{T})$;
- (iii) $\int_{\mathbb{T}} \log \|\mathcal{F}_{\mathbf{T}} u(\cdot, s, t_0)\|_{L^2(\partial \mathbf{T})} \frac{ds}{s} < +\infty$;

then $u = 0$.

4 Uniqueness for perturbed problems using Carleman estimates

In this section, we consider the problem

$$\partial_t u = i(\mathcal{L}u + Vu), \quad (4.1)$$

where $V = V(x, t)$ is a bounded potential.

We are going to begin this section by pointing out that a fast decaying solution at times $t = 0$ and $t = 1$ extends the fast decay to the whole interval $[0, 1]$. This is given by an immediate extension of part of the results in [35]. For convenience, the equation is written in a different way. In any case, by doing a suitable change of variables one can see that the results described in this section can be rewritten in terms of a solution of $i\partial_t u = \mathcal{L}u + Vu$. We first need an auxiliary lemma:

Lemma 4.1 *Let $u \in C^1([0, T], \mathbf{T})$ satisfy (4.1) where V is a complex-valued functions in $\mathbf{T} \times [0, T]$ and bounded. Let*

$$\psi_\alpha(x, t) = (1 + |x|)^{\alpha|x|/(1+t)}, \quad \alpha \in (0, 1].$$

Then, for $T > 0$,

$$\|\psi_\alpha(T)u(T)\|_2^2 \leq e^{CT} \|\psi_\alpha(0)u(0)\|_2^2,$$

provided the right-hand side is finite.

Remark 4.2 This is a tree analogue of [35, Proposition 3.1]. We may as well consider the more general equation

$$\partial_t u(x, t) = i(\mathcal{L}u(x, t) + V(x, t)u + F(x, t)),$$

where V and F are complex-valued functions in $\mathbf{T} \times [0, T]$ and bounded. In this case, a simple adaptation of the proof below shows that

$$\|\psi_\alpha(T)u(T)\|_2^2 \leq e^{CT} \left(\|\psi_\alpha(0)u(0)\|_2^2 + \int_0^T \|\psi_\alpha(s)F(s)\|_2^2 ds \right),$$

provided the right-hand side is finite.

Proof Define $f(x, t) = \psi_\alpha(x, t)u(x, t)$ and $H(t) = \|f(t)\|_2^2$ for a fixed α . We will just write $\psi = \psi_\alpha$. Notice that ψ only depends on $|x|$, so for $|x| = n$ we write $\psi(x) = \psi(n)$.

Formally,

$$\partial_t f = i\psi\mathcal{L}(\psi^{-1}f) + \phi_t f + iVf = \mathcal{S}f + \mathcal{A}f + iVf,$$

where $\phi = \log \psi$ and

$$\begin{aligned}\mathcal{S}f &= \phi_t f + \frac{i}{q+1} \sum_{y \sim x} \sinh(\phi(x, t) - \phi(y, t)) f(y) \\ \mathcal{A}f &= \frac{i}{q+1} \sum_{y \sim x} \cosh(\phi(x, t) - \phi(y, t)) f(y) - if(x)\end{aligned}$$

are symmetric and skew-symmetric operators, respectively. Since

$$\partial_t H(t) = 2\Re(\partial_t f, f),$$

it is easy to check that $\partial_t H(t)$ is

$$\begin{aligned}&\leq \|V\|_\infty \|f\|_2 \\&\quad + \left(2\phi_t(0) + \frac{2}{\sqrt{q}} |\sinh(\phi(1) - \phi(0))| \right) |f(o)|^2 \\&\quad + \sum_{n \geq 1, |x|=n} \left(2\phi_t(n) + \frac{2\sqrt{q}}{q+1} |\sinh(\phi(n) - \phi(n-1))| \right) |f(x)|^2 \\&\quad + \frac{2\sqrt{q}}{q+1} \sum_{n \geq 1, |x|=n} |\sinh(\phi(n+1) - \phi(n))| |f(x)|^2.\end{aligned}$$

The result follows after proving that the last three terms are bounded by $C\|f\|_2$, in the same spirit as in [35]. To justify this formal argument, we can prove again the same result (now rigorously) for a truncated weight ψ_N and then let $N \rightarrow \infty$ (see [35] for this argument in the line). $\square$

This result shows that if we have a solution of (4.1) with fast decay at time $t = 0$, the solution has fast decay at any future time, although the decay gets worse with time. Our aim now is to use also the fast decay at time $t = 1$ to improve the decay at future times.

Proposition 4.3 *Let $\gamma > 0$ and V a bounded potential. Let u be a strong solution of (4.1) and assume that at times $t = 0$ and $t = 1$,*

$$\|(1 + |x|)^{\gamma(1+|x|)} u(x, t)\|_2 < +\infty, \quad t \in \{0, 1\}.$$

Then, for all $t \in [0, 1]$, $\|(1 + |x|)^{\gamma(1+|x|)} u(t)\|_2 < +\infty$.

Remark 4.4 This is the tree analogue of [35, Proposition 4.1] on $\mathbb{Z}$.

Proof For $1/2 < b < 1$, let $\phi_b(n) = \gamma(1+n) \log^b(1+n)$, $n \in \mathbb{N} \cup \{0\}$. Set $f = e^{\phi_b(|x|)} u$ and, as before, $H(t) = \|f(t)\|_2^2$. The previous lemma shows that $H(t)$ is finite for all t , so the subsequent formal computations are justified. We will show that, for some $C > 0$,

$$\begin{aligned}H_b(t) &\leq e^{Ct(1-t)} H_b(0)^{1-t} H_b(1)^t \\&\leq e^{Ct(1-t)} \|(1 + |x|)^{\gamma(1+|x|)} u(0)\|_2^{2(1-t)} \|(1 + |x|)^{\gamma(1+|x|)} u(1)\|_2^{2t}.\end{aligned}$$

The result will follow by letting $b \rightarrow 1$ and applying the monotone convergence theorem.

In order to prove our claim, we write again $\partial_t f = \mathcal{S}f + \mathcal{A}f + iVf$ and, as shown in [35], the claim follows from a lower bound

$$\langle [\mathcal{S}, \mathcal{A}]f, f \rangle \geq -C\|f\|^2, \quad (4.2)$$

with $\mathcal{S}, \mathcal{A}$ the operators defined in the previous lemma, in this case for the weight e^{ϕ_b} . Since ϕ_b does not depend on t , it is easy to check that $(q+1)^2[\mathcal{S}, \mathcal{A}]f, f$ is

$$\begin{aligned}
 &= \sum_{x \in \mathbf{T}} \sum_{y \sim x} \sum_{z \sim y} \sinh(2\phi_b(|y|) - \phi_b(|x|) - \phi_b(|z|)) f(z) \overline{f(x)} \\
 &= \sinh(2\phi_b(1) - 2\phi_b(0)) |f(o)|^2 \\
 &\quad + 2 \sinh(2\phi_b(1) - \phi_b(0) - \phi_b(2)) \Re \sum_{z \in o_{ff}} f(z) \overline{f(o)} \\
 &\quad + \sum_{x \in \mathbf{T} \setminus \{o\}} \sinh(2\phi_b(|x| - 1) - 2\phi_b(|x|)) \sum_{z \in x_{pf}} f(z) \overline{f(x)} \\
 &\quad + \sum_{x \in \mathbf{T} \setminus \{o\}} \sinh(2\phi_b(|x| - 1) - 2\phi_b(|x|)) |f(x)|^2 \\
 &\quad + 2 \Re \sum_{x \in \mathbf{T} \setminus \{o\}} \sinh(2\phi_b(|x| + 1) - \phi_b(|x|) - \phi_b(|x| + 2)) \sum_{z \in x_{ff}} f(z) \overline{f(x)} \\
 &\quad + \sum_{x \in \mathbf{T} \setminus \{o\}} q \sinh(2\phi_b(|x| + 1) - 2\phi_b(|x|)) |f(x)|^2 \\
 &= S_1 + \dots + S_6.
 \end{aligned}$$

As for each n , there exists γ_n such that, for every $1/2 < b < 1$, $|\Phi_b(n)| \leq \gamma_n$, there exists a constant C such that $S_1, S_2 \geq -C\|f\|^2$.

As in [35], there exists a constant κ such that, for every n , $|\sinh(2\phi_b(n+1) - \phi_b(n) - \phi_b(n+2))| \leq \kappa$. Further, $|x_{ff}| = q^2$ so that Cauchy–Schwarz shows that there is a constant C such that $S_5 \geq -C\|f\|^2$.

Next, if $|x| \geq 2$,

$$\begin{aligned}
 \left| \sum_{z \in x_{pf}} f(z) \overline{f(x)} \right| &\leq \frac{1}{2} \sum_{z \in x_{pf}} (|f(z)|^2 + |f(x)|^2) \\
 &= \frac{q-1}{2} |f(x)|^2 + \frac{1}{2} \sum_{z \in x_{pf}} |f(z)|^2,
 \end{aligned}$$

while if $|x| = 1$,

$$\left| \sum_{z \in x_{pf}} f(z) \overline{f(x)} \right| \leq \frac{q}{2} |f(x)|^2 + \frac{1}{2} \sum_{z \in x_{pf}} |f(z)|^2.$$

But then

$$\begin{aligned}
 S_3 &\geq -\frac{1}{2} \sum_{x \in \mathbf{T} \setminus \{o\}} \sinh(2\phi_b(|x|) - 2\phi_b(|x| - 1)) \sum_{z \in x_{pf}} |f(z)|^2 \\
 &\quad - \frac{q-1}{2} \sum_{|x| \geq 2} \sinh(2\phi_b(|x|) - 2\phi_b(|x| - 1)) |f(x)|^2 \\
 &\quad - \frac{q}{2} \sum_{|x|=1} \sinh(2\phi_b(1) - 2\phi_b(0)) |f(x)|^2 \\
 &= -(q-1) \sum_{x \in \mathbf{T} \setminus \{o\}} \sinh(2\phi_b(|x|) - 2\phi_b(|x| - 1)) |f(x)|^2
 \end{aligned}$$

$$\begin{aligned}
& - \sum_{|x|=1} \sinh(2\phi_b(1) - 2\phi_b(0)) |f(x)|^2 \\
& = S_3^a + S_3^b
\end{aligned}$$

since each $x \in \mathbf{T} \setminus \{o\}$ appears $q-1$ or q times in the first sum if $|x| \geq 2$ or $|x| = 1$. It follows that $S_3^b \geq -C\|f\|^2$ and

$$S_3^a + S_4 + S_6 \geq q \sum_{x \in \mathbf{T} \setminus \{o\}} \psi_b(|x|) |f(x)|^2 \geq 0,$$

where

$$\psi_b(n) = \sinh(2\phi_b(n+1) - 2\phi_b(n)) - \sinh(2\phi_b(n) - 2\phi_b(n-1)) \geq 0$$

due to the properties of the function $(1+x) \log^b(1+x)$ for $x > 0$ and $1/2 < b < 1$; see [35]. $\square$

As it happens in the continuous case, or in $\mathbb{Z}^d$, uniqueness holds from an argument related to Carleman inequalities. Here we prove the following Carleman inequality:

Lemma 4.5 (Carleman inequality on the tree) *Let $\varphi : [0, 1] \rightarrow \mathbb{R}$ be a smooth function, $\beta > 0$ and $\gamma > \frac{1}{2\beta}$. There exists $R_0 = R_0(\|\varphi\|_\infty + \|\varphi'\|_\infty + \|\varphi''\|_\infty, \beta, \gamma)$ such that, if $R > R_0$, $\alpha \geq \gamma R \log R$ and if g is a function on $\mathbf{T} \times [0, 1]$, $g \in C_0^1([0, 1], \ell^2(\mathbf{T}))$ has its support contained in the set*

$$\{(x, t) : |x|/R + \varphi(t) \geq \beta\},$$

then

$$\begin{aligned}
& \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha\beta}{R} \|e^{\alpha\left(\frac{|x|}{R} + \varphi\right)^2} g \mathbf{1}_{|x| \geq 1}\|_{L_{x,t}^2}^2 \\
& \leq (q+1)^2 \|e^{\alpha\left(\frac{|x|}{R} + \varphi(t)\right)^2} (i\partial_t + \mathcal{L})g\|_{L_{x,t}^2}^2 \\
& \quad + \int_0^1 \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right) \sum_{|x|=1} \left| e^{\alpha\left(\frac{1}{R} + \varphi(t)\right)^2} g(x) \right|^2 dt.
\end{aligned}$$

Remark 4.6 In the case of $\mathbb{Z}$ or, in general, of $\mathbb{Z}^d$, where the combinatorics makes the study of the problem much easier this corresponds to [27, Lemma 2.1]. Further, on the tree, the inequality contains an extra term. Fortunately, this term will be harmless.

Proof Let ϕ be defined by $\phi(n) = \alpha \left(\frac{n}{R} + \varphi(t) \right)^2$. For $f = e^\phi g$, we have

$$e^\phi (i\partial_t + \mathcal{L})g = \mathcal{S}f + \mathcal{A}f,$$

where

$$\begin{aligned}
\mathcal{S}f &= i\partial_t f + \frac{1}{q+1} \sum_{y \sim x} \cosh(\phi(x, t) - \phi(y, t)) f(y, t) - f, \\
\mathcal{A}f &= -i\phi_t f + \frac{1}{q+1} \sum_{y \sim x} \sinh(\phi(x, t) - \phi(y, t)) f(y, t).
\end{aligned}$$

We need to give a lower bound for the commutator, which immediately implies the result using the fact that

$$\|e^{\alpha\left(\frac{|x|}{R}+\varphi(t)\right)^2}(i\partial_t+\mathcal{L})g\|_{L^2_{x,t}}^2 \geq \langle [\mathcal{S}, \mathcal{A}]f, f \rangle.$$

To simplify notation, we will not explicitly write the dependence of f on the time variable t so that $f(x)$ means $f(x, t)$, $x \in \mathbf{T}$, $t \in [0, 1]$. A simple computation shows that

$$\langle [\mathcal{S}, \mathcal{A}]f, f \rangle = \int_0^1 S(t) dt \quad (4.3)$$

where

$$\begin{aligned} S(t) &:= \sum_{x \in \mathbf{T}} \phi_{tt}(x) |f(x)|^2 \\ &+ \frac{2}{q+1} \sum_{x \in \mathbf{T}} \sum_{y \sim x} (\phi_t(x) - \phi_t(y)) \cosh(\phi(x) - \phi(y)) f(y) \overline{f(x)} \\ &+ \frac{1}{(q+1)^2} \sum_{x \in \mathbf{T}} \sum_{y \sim x} \sum_{z \sim y} \sinh(2\phi(y) - \phi(x) - \phi(z)) f(z) \overline{f(x)}. \end{aligned} \quad (4.4)$$

As in the previous proof, we split them into sums over mothers and daughters. Recall that the root has only daughters, while the rest of the points in the tree have a single mother and q daughters. Further, the function $\phi(x, t)$ only depends on $|x|$, the distance of a point in the tree to the root o . We therefore decompose the sums in (4.4) as follows: $S(t) = S_1 + \dots + S_7$ where

- The first sum in (4.4) is $S_1 = \sum_{n \geq 0} \sum_{|x|=n} \phi_{tt}(n) |f(x)|^2$.
- For the second sum in (4.4), each pair $x \sim y$ appears twice, once $|x| = |y| + 1$, once with $|x| = |y| - 1$. Therefore, this sum can be rewritten as

$$S_2 = \frac{4}{q+1} \operatorname{Im} \sum_{n \geq 1} \sum_{|x|=n} (\phi_t(n) - \phi_t(n-1)) \cosh(\phi(n) - \phi(n-1)) f(x_p) \overline{f(x)}.$$

- For the last sum in (4.4), we need to distinguish more cases:

a) $x = o$, y any daughter and $z = o$. This happens $q+1$ times and leads to

$$S_3 = \frac{1}{q+1} \sinh 2(\phi(1) - \phi(0)) |f(o)|^2;$$

b) $x \in \mathbf{T} \setminus \{o\}$, i.e., $n := |x| \geq 1$ y is one of the q daughters of x and $z = x$ which leads to

$$S_4 = \frac{q}{(q+1)^2} \sum_{n \geq 1} \sum_{|x|=n} \sinh 2(\phi(n+1) - \phi(n)) |f(x)|^2,$$

while if y is the mother of x and $z = x$, we get

$$S_5 = \frac{1}{(q+1)^2} \sum_{n \geq 1} \sum_{|x|=n} \sinh 2(\phi(n-1) - \phi(n)) |f(x)|^2;$$

- c) $x \in \mathbf{T} \setminus \{o\}$, i.e., $n := |x| \geq 1$, y is the mother of x and z is any of the sisters of x , we get

$$S_6 = \frac{1}{(q+1)^2} \sum_{n \geq 1} \sum_{|x|=n} \sum_{z \in x_{pf}} \sinh 2(\phi(n-1) - \phi(n)) f(z) \overline{f(x)};$$

- Finally, for all other terms x is the grandmother of z and each such couple (x, z) appears twice. As $|z| \geq 2$, this may be written as

$$S_7 = \frac{2}{(q+1)^2} \Re \sum_{n \geq 2} \sum_{|x|=n} \sinh(2\phi(n-1) - \phi(n) - \phi(n-2)) f(x) \overline{f(x_{pp})}.$$

Before estimating those quantities, as $\phi(n) = \alpha \left(\frac{n}{R} + \varphi(t) \right)^2$, we obtain

$$\begin{aligned} \phi_t(n) &= 2\alpha \left(\frac{n}{R} + \varphi \right) \varphi' \\ \phi_{tt}(n) &= 2\alpha \left[\left(\frac{n}{R} + \varphi \right) \varphi'' + (\varphi')^2 \right] \\ \phi_t(n) - \phi_t(n-1) &= \frac{2\alpha}{R} \varphi' \\ \phi(n-1) - \phi(n) &= -\frac{2\alpha}{R} \left(\frac{n-1/2}{R} + \varphi \right) \\ \phi(n) + \phi(n+2) - 2\phi(n+1) &= \frac{2\alpha}{R^2}. \end{aligned}$$

Let us now estimate S_1 to S_7 . We will treat them from the simplest to the most involved one rather than the order in which they appeared in the above decomposition. We start with S_1 , which can be bounded by

$$S_1 \geq -2\|\varphi''\|_\infty \alpha \sum_{n \geq 0} \left| \frac{n}{R} + \varphi \right| \sum_{|x|=n} |f(x)|^2. \quad (4.5)$$

To estimate S_7 , we write $2\Re(f(x)\overline{f(x_{pp})}) = -|f(x) - f(x_{pp})|^2 + |f(x)|^2 + |f(x_{pp})|^2$, then

$$\begin{aligned} S_7 &= \frac{\sinh \frac{2\alpha}{R^2}}{(q+1)^2} \sum_{n \geq 2} \sum_{|x|=n} (|f(x) - f(x_{pp})|^2 - |f(x)|^2 - |f(x_{pp})|^2) \\ &\geq -\frac{\sinh \frac{2\alpha}{R^2}}{(q+1)^2} \left(\sum_{n \geq 2} \sum_{|x|=n} |f(x)|^2 + \sum_{n \geq 2} \sum_{|x|=n} |f(x_{pp})|^2 \right) \\ &\geq -\frac{\sinh \frac{2\alpha}{R^2}}{(q+1)^2} \left(q(q+1)|f(o)|^2 + q^2 \sum_{|x|=1} |f(x)|^2 \right. \\ &\quad \left. + (q^2 + 1) \sum_{n \geq 2} \sum_{|x|=n} |f(x)|^2 \right) \end{aligned} \quad (4.6)$$

since o has $q(q+1)$ granddaughters, it appears $q(q+1)$ times as an x_{pp} , if $|x| \geq 1$, it has q^2 granddaughters and thus will appear q^2 times in the second sum.

Next, for S_6 , we use that $f(z)\overline{f(x)} \geq -\frac{1}{2}(|f(x)|^2 + |f(z)|^2)$ to obtain

$$\begin{aligned} S_6 &\geq -\frac{1}{2(q+1)^2} \sum_{n \geq 1} |\sinh 2(\phi(n-1) - \phi(n))| \times \\ &\quad \times \sum_{|x|=n} \sum_{z \in x_{pf}} (|f(x)|^2 + |f(z)|^2) \\ &= -\frac{1}{(q+1)^2} \left(q |\sinh 2(\phi(0) - \phi(1))| \sum_{|x|=1} |f(x)|^2 \right. \\ &\quad \left. + (q-1) \sum_{n \geq 1} |\sinh 2(\phi(n-1) - \phi(n))| \sum_{|x|=n} |f(x)|^2 \right). \end{aligned}$$

Here we use the fact that x_{pf} has q elements if $|x| = 1$ and $q-1$ elements otherwise for $\sum_{|x|=n} \sum_{z \in x_{pf}} |f(x)|^2$ and we use (2.6) for the second sum. Finally, using the expression of ϕ , we get

$$\begin{aligned} S_6 &\geq -\frac{1}{(q+1)^2} \left(q \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right) \sum_{|x|=1} |f(x)|^2 \right. \\ &\quad \left. + (q-1) \sum_{n \geq 2} \sinh \frac{4\alpha}{R} \left(\frac{n-1/2}{R} + \varphi \right) \sum_{|x|=n} |f(x)|^2 \right). \end{aligned} \quad (4.7)$$

Now, for S_2 , let us first introduce

$$\Psi(n) = \cosh(\phi(n) - \phi(n-1))$$

and

$$\Sigma_n = \sum_{|x|=n} (q^{1/2}|f(x)|^2 + q^{-1/2}|f(x_p)|^2).$$

We use the expression of ϕ_t and the fact that

$$2|f(x)f(x_p)| \leq q^{1/2}|f(x)|^2 + q^{-1/2}|f(x_p)|^2$$

to bound S_2 by

$$\begin{aligned} &\geq -\frac{4\alpha|\varphi'|}{(q+1)R} \sum_{n \geq 1} \Psi(n) \Sigma_n \\ &= -\frac{4\alpha|\varphi'|}{q^{1/2}R} \Psi(1)|f(o)|^2 - \frac{4q^{1/2}\alpha|\varphi'|}{(q+1)R} \sum_{n \geq 1} \sum_{|x|=n} [\Psi(n) + \Psi(n+1)] |f(x)|^2 \end{aligned}$$

since o will appear $q+1$ times as an x_p and each x with $|x| \geq 1$ will appear once as an x and q times as an x_p . Using the expression of ϕ , we conclude that

$$\begin{aligned} S_2 &\geq -\frac{4\alpha\|\varphi'\|_\infty}{Rq^{1/2}} \cosh \frac{2\alpha}{R} \left(\frac{1}{2R} + \varphi \right) |f(o)|^2 \\ &\quad - \frac{4q^{1/2}\alpha\|\varphi'\|_\infty}{(q+1)R} \cosh \frac{\alpha}{R^2} \sum_{n \geq 1} \cosh \frac{2\alpha}{R} \left(\frac{n}{R} + \varphi \right) \sum_{|x|=n} |f(x)|^2. \end{aligned} \quad (4.8)$$

Next, write

$$\begin{aligned} S_4 &= \frac{q-1}{(q+1)^2} \sum_{n \geq 1} \sum_{|x|=n} \sinh 2(\phi(n+1) - \phi(n)) |f(x)|^2 \\ &\quad + \frac{1}{(q+1)^2} \sum_{n \geq 1} \sum_{|x|=n} \sinh 2(\phi(n+1) - \phi(n)) |f(x)|^2 \\ &= S_4^a + S_4^b. \end{aligned}$$

We will group S_4^b and S_5 noticing that

$$\begin{aligned} &\sinh \frac{4\alpha}{R} \left(\frac{n+1/2}{R} + \varphi \right) - \sinh \frac{4\alpha}{R} \left(\frac{n-1/2}{R} + \varphi \right) \\ &= 2 \cosh \frac{4\alpha}{R} \left(\frac{n}{R} + \varphi \right) \sinh \frac{2\alpha}{R^2}. \end{aligned}$$

This leads to

$$S_4^b + S_5 \geq \frac{2}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \sum_{n \geq 1} \cosh \frac{4\alpha}{R} \left(\frac{n}{R} + \varphi \right) \sum_{|x|=n} |f(x)|^2. \quad (4.9)$$

We are now in a position to estimate $S_1 + \dots + S_7$. Let us first isolate all terms containing $|f(o)|^2$. They appear in (4.5), S_3 , (4.6) and (4.8).

The factor of $|f(o)|^2$ is

$$\begin{aligned} A &:= -2\alpha \|\varphi\|_\infty \|\varphi''\|_\infty + \frac{1}{q+1} \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right) \\ &\quad - \frac{q \sinh \frac{2\alpha}{R^2}}{q+1} - \frac{4\alpha \|\varphi'\|_\infty}{Rq^{1/2}} \cosh \frac{2\alpha}{R} \left(\frac{1}{2R} + \varphi \right). \end{aligned}$$

Now, the hypothesis of the lemma show that, if $f(o) \neq 0$, then $\varphi \geq \beta > 0$. Further, as $\alpha > \frac{1}{2\beta} R \log R$, it is easy to see that the dominating term in A is the second one and that the other three can be absorbed in it provided R is large enough. Thus, $A \geq 0$ if R is large enough (depending on q , $\|\varphi\|_\infty$, $\|\varphi'\|_\infty$, $\|\varphi''\|_\infty$ and β).

Next, we compute the factor of $\sum_{|x|=1} |f(x)|^2$. The one stemming from S_4^a and the one appearing in (4.7) give

$$\begin{aligned} &\left[\frac{q-1}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{3}{2R} + \varphi \right) - \frac{q}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right) \right] \\ &\geq -\frac{1}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right). \end{aligned}$$

The remaining terms for $|x| = 1$ come from (4.9), (4.8), (4.6) and (4.5). The factor of $\sum_{|x|=1} |f(x)|^2$ stemming from those terms is

$$\begin{aligned} &\frac{2}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha}{R} \left(\frac{1}{R} + \varphi \right) \\ &\quad - \frac{4q^{1/2}\alpha \|\varphi'\|_\infty}{(q+1)R} \cosh \frac{\alpha}{R^2} \cosh \frac{2\alpha}{R} \left(\frac{1}{R} + \varphi \right) \end{aligned}$$

$$-\frac{q^2 \sinh \frac{2\alpha}{R^2}}{(q+1)^2} - 2\|\varphi''\|_\infty \alpha \left| \frac{1}{R} + \varphi \right|.$$

The three last terms are again absorbed in the first one (see [27] for details). We are thus left with

$$\begin{aligned} & \frac{1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha}{R} \left(\frac{1}{R} + \varphi \right) \sum_{|x|=1} |f(x)|^2 \\ & \geq \frac{1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha\beta}{R} \sum_{|x|=1} |f(x)|^2 \end{aligned}$$

because of the support property of f .

For $n \geq 2$, the factor of $\sum_{|x|=n} |f(x)|^2$ comes from

- first those from S_4^q and from (4.7) which now are

$$\frac{q-1}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{n+1/2}{R} + \varphi \right) - \frac{q-1}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{n-1/2}{R} + \varphi \right) \geq 0,$$

- the remaining ones coming from (4.5), (4.6), (4.8) and (4.9)

$$\begin{aligned} & -2\|\varphi''\|_\infty \alpha \left| \frac{n}{R} + \varphi \right| - \frac{q^2+1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \\ & - \frac{4q^{1/2}\alpha\|\varphi'\|_\infty}{(q+1)R} \cosh \frac{\alpha}{R^2} \cosh \frac{2\alpha}{R} \left(\frac{n}{R} + \varphi \right) \\ & + \frac{2}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha}{R} \left(\frac{n}{R} + \varphi \right). \end{aligned}$$

The first three terms are again absorbed in the last one (see [27] for details). We are thus left with

$$\begin{aligned} & \frac{1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \sum_{n \geq 2} \cosh \frac{4\alpha}{R} \left(\frac{n}{R} + \varphi \right) \sum_{|x|=n} |f(x)|^2 \\ & \geq \frac{1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha\beta}{R} \sum_{n \geq 2} \sum_{|x|=n} |f(x)|^2 \end{aligned}$$

because of the support property of f .

In summary, if R is large enough,

$$\begin{aligned} \langle [S, \mathcal{A}]f, f \rangle & \geq - \int_0^1 \frac{1}{(q+1)^2} \sinh \frac{4\alpha}{R} \left(\frac{1}{2R} + \varphi \right) \sum_{|x|=1} |f(x)|^2 dt \\ & + \frac{1}{(q+1)^2} \sinh \frac{2\alpha}{R^2} \cosh \frac{4\alpha\beta}{R} \int_0^1 \sum_{n \geq 1} \sum_{|x|=n} |f(x)|^2 dt \end{aligned}$$

as announced. $\square$

Even though we need a correction term in order to give the Carleman estimate, we can adapt the argument of the proof of [27, Theorem 1.1] to give again a lower bound for solutions of Schrödinger evolutions on trees.

Theorem 4.7 (Lower bound for solutions of Schrödinger equations) *Let $q \geq 2$, $A, L, \eta > 0$, then there exists $R_0 = R_0(q, A, L) > 0$ and $c = c(q, \eta)$ such that*

- if V is a bounded function on $\mathbf{T}$ with

$$\|V\|_\infty = \sup_{t \in [0, 1], x \in \mathbf{T}} \{|V(x, t)|\} \leq L,$$

- and $u \in C^1([0, 1] : \ell^2(\mathbf{T}))$ is a strong solution of

$$\partial_t u = i(\mathcal{L}u + Vu)$$

that satisfies the bounds

$$\int_0^1 \sum_{x \in \mathbf{T}} |u(x, t)|^2 dt \leq A^2, \quad \int_{1/2-1/8}^{1/2+1/8} |u(x_0, t)|^2 dt \geq 1$$

for some x_0 with $|x_0| = 2$.

Then for $R \geq R_0$,

$$\lambda(R) \equiv \left(\int_0^1 \sum_{\lfloor R \rfloor - 1 \leq |x| \leq \lfloor R \rfloor + 1} |u(x, t)|^2 dt \right)^{1/2} \geq c e^{-(1+\eta)R \log R}.$$

Proof For $\epsilon > 0$ fixed, let us define the following cutoff functions:

- we define θ^R, μ to be $C^\infty(\mathbb{R})$ functions such that $0 \leq \theta^R, \mu \leq 1$ and

$$\theta^R(x) = \begin{cases} 1, & |x| \leq R-1 \\ 0, & |x| \geq R \end{cases} \quad \mu(x) = \begin{cases} 1, & |x| \geq \epsilon^{-1} + 1 \\ 0, & |x| \leq \epsilon^{-1} \end{cases}. \quad (4.10)$$

- and a $C^\infty([0, 1])$ function φ such that $0 \leq \varphi \leq 2 + \epsilon^{-1}$ and

$$\varphi(t) = \begin{cases} 2 + \epsilon^{-1}, & t \in [\frac{1}{2} - \frac{1}{8}, \frac{1}{2} + \frac{1}{8}] \\ 0, & t \in [0, \frac{1}{4}] \cup [\frac{3}{4}, 1] \end{cases}. \quad (4.11)$$

We are going to apply the previous lemma to

$$g(x, t) := \theta^R(|x|) \mu \left(\frac{|x|}{R} + \varphi(t) \right) u(x, t), \quad x \in \mathbf{T}, \quad t \in [0, 1].$$

Notice that the evolution of g is given by the expression

$$\begin{aligned} (i\partial_t + \mathcal{L})g &= \theta^R \left(\frac{|x|}{R} + \varphi \right) (i\partial_t u + \mathcal{L}u) + i\varphi' \theta^R(x) \mu' \left(\frac{|x|}{R} + \varphi \right) u \\ &\quad + \theta^R(x) \frac{1}{q+1} \sum_{y \sim x} \left(\mu \left(\frac{|y|}{R} + \varphi \right) - \mu \left(\frac{|x|}{R} + \varphi \right) \right) u(y, t) \\ &\quad + \frac{1}{q+1} \sum_{y \sim x} \left(\theta^R(|y|) - \theta^R(|x|) \right) \mu \left(\frac{|y|}{R} + \varphi \right) u(y, t). \end{aligned}$$

Using the bounds on the cutoff functions and the fact that $|i\partial_t u + \mathcal{L}u| = |Vu| \leq \|V\|_\infty |u|$, we get

$$|(i\partial_t + \mathcal{L})g| \leq \|V\|_\infty |u| + C_\varphi \left| \mu' \left(\frac{|x|}{R} + \varphi \right) \right| |u|$$

$$\begin{aligned}
& + \frac{1}{q+1} \left| \sum_{y \sim x} \left(\mu \left(\frac{|y|}{R} + \varphi \right) - \mu \left(\frac{|x|}{R} + \varphi \right) \right) u(y, t) \right| \\
& + \frac{1}{q+1} \sum_{y \sim x} \left| \theta^R(|y|) - \theta^R(|x|) \right| |u(y, t)|.
\end{aligned}$$

Thus, by means of the Carleman estimate with $\beta = 1/\varepsilon$ and R large enough,

$$\begin{aligned}
& \sinh(2\alpha/R^2) \cosh(4\alpha/\varepsilon R) \|e^{\alpha \left(\frac{|x|}{R} + \varphi \right)^2} g \mathbf{1}_{|x| \geq 1}\|_{L^2_{x,t}}^2 \\
& \leq c \|V\|_\infty^2 \|e^{\alpha \left(\frac{|x|}{R} + \varphi \right)^2} g\|_{L^2_{x,t}}^2 \\
& \quad + c \int_0^1 \sum_{n \geq 0, |x|=n} e^{2\alpha \left(\frac{n}{R} + \varphi \right)^2} \left| \mu' \left(\frac{n}{R} + \varphi \right) \right|^2 |u(x, t)|^2 dt \\
& \quad + c \int_0^1 \sum_{n \geq 0, |x|=n} \sum_{y \sim x} e^{2\alpha \left(\frac{n}{R} + \varphi \right)^2} \left| \mu \left(\frac{|y|}{R} + \varphi \right) - \mu \left(\frac{|x|}{R} + \varphi \right) \right|^2 |u(y, t)|^2 dt \\
& \quad + c \int_0^1 \sum_{n \geq 0, |x|=n} \sum_{y \sim x} e^{2\alpha \left(\frac{n}{R} + \varphi \right)^2} \left| \theta^R(|y|) - \theta^R(|x|) \right| |u(y, t)|^2 dt \\
& \quad + \int_0^1 \sinh \frac{4\alpha}{R} \left(\frac{1}{2} + \varphi \right) \sum_{|x|=1} e^{2\alpha \left(\frac{1}{R} + \varphi \right)^2} |g(x, t)|^2 dt. \tag{4.12}
\end{aligned}$$

Note that we used Cauchy–Schwarz in the third and fourth sums in the form $\sum_{x \in \mathbf{T}} \left| \sum_{y \sim x} \psi(y) \right|^2 \leq (q+1) \sum_{x \in \mathbf{T}} \sum_{y \sim x} |\psi(y)|^2$.

We now study carefully the support of each term.

For the first term involving V : by taking $\alpha = cR \log R$ with $c \geq \varepsilon/2$

$$\sinh(2\alpha/R^2) \cosh(4\alpha/\varepsilon R) \geq 2cR^{\frac{4c}{\varepsilon}-1} \log R, \tag{4.13}$$

so that, when R large enough (depending on L also now), the term on the right, up to the term involving root o , is absorbed in the left-hand side. Further, the remaining term is bounded by $ce^{2\alpha(2+\varepsilon^{-1})} L^2 A^2$.

For the term involving the derivative of the function μ , we easily see that $\frac{n}{R} + \varphi \leq 1 + \varepsilon^{-1}$, and therefore,

$$\int_0^1 \sum_{n \geq 0, |x|=n} e^{2\alpha \left(\frac{n}{R} + \varphi \right)^2} \left| \mu' \left(\frac{n}{R} + \varphi \right) \right|^2 |u(x, t)|^2 dt \leq ce^{2\alpha(1+\varepsilon^{-1})} A^2.$$

Next, we study the term involving the difference of μ functions, which is similar to the last one. It is easy to check that if $\frac{n}{R} + \varphi \geq \varepsilon^{-1} + 1 + \frac{1}{R}$ both functions μ , the one evaluated at x and the one evaluated at one neighbor of x are 0. Hence,

$$\begin{aligned}
& \int_0^1 \sum_{n \geq 0, |x|=n} \sum_{y \sim x} e^{2\alpha \left(\frac{n}{R} + \varphi \right)^2} \left| \mu \left(\frac{|y|}{R} + \varphi \right) - \mu \left(\frac{|x|}{R} + \varphi \right) \right|^2 |u(y, t)|^2 dt \\
& \leq e^{2\alpha(\varepsilon^{-1}+1+1/R)^2} A^2.
\end{aligned}$$

Now we focus on the term with difference of θ functions. In this case, the only possibilities where the difference is not zero are summarize as

- $|x| = \lfloor R \rfloor - 1$ and y a future neighbor, $|y| = \lfloor R \rfloor$.
- $|x| = \lfloor R \rfloor$ and y any neighbor of x .
- $|x| = \lfloor R \rfloor + 1$ and y the past neighbor, $|y| = \lfloor R \rfloor$.

Thus,

$$\begin{aligned} & \int_0^1 \sum_{n \geq 0, |x|=n} \sum_{y \sim x} e^{2\alpha(\frac{n}{R} + \varphi)^2} \left| \theta^R(|y|) - \theta^R(|x|) \right| |u(y, t)|^2 dt \\ & \leq c e^{2\alpha(3+\epsilon^{-1}+1/R)^2} \lambda^2(R). \end{aligned}$$

For the last term in the right-hand side, we just bound the function φ to put all the functions out of the sum. Now, by the definition of θ^R and μ , we see that if $x = x_0$ and $t \in [1/2 - 1/8, 1/2 + 1/8]$ then $\left| \frac{|x_0|}{R} + \varphi e_1 \right| = 2 + \epsilon^{-1} + 2/R$, so the cutoff functions are 1 and $g(x_0, t) = u(x_0, t)$. This allows us to bound the left-hand side of the Carleman inequality of the lemma by

$$\|e^{\alpha(\frac{|x|}{R} + \varphi)^2} g \mathbf{1}_{|x| \geq 1}\|_{L^2_{x,t}}^2 \geq e^{(2+\epsilon^{-1}+2/R)^2 2\alpha},$$

since $\int_{1/2-1/8}^{1/2+1/8} |u(x_0, t)|^2 \geq 1$.

Gathering all these results, we have

$$\begin{aligned} & \sinh\left(\frac{2\alpha}{R^2}\right) \cosh\left(\frac{4\alpha}{\epsilon R}\right) e^{2\alpha(2+\epsilon^{-1}+2/R)^2} \\ & \leq e^{2\alpha(2+\epsilon^{-1})} A^2 L^2 + e^{2\alpha(1+\epsilon^{-1}+1/R)^2} A^2 \\ & \quad + \sinh\frac{4\alpha}{R} \left(\frac{1/2}{R} + 2 + \epsilon^{-1}\right) e^{2\alpha(2+\epsilon^{-1}+1/R)^2} A^2 \\ & \quad + e^{2\alpha(3+\epsilon^{-1}+1/R)^2} \lambda^2(R). \end{aligned}$$

It is clear that the first two terms in the right-hand side are smaller than the third term. Let us see that the third term can be absorbed in the left-hand side, for R large enough, depending on A (recall that before we showed that R depends on L as well) and ϵ , which is a fixed number. Indeed, taking into account that $\alpha = cR \log R$ with $c > \frac{\epsilon}{2}$, we have

$$\begin{aligned} & \sinh\left(\frac{2\alpha}{R^2}\right) \cosh\left(\frac{4\alpha}{\epsilon R}\right) e^{2\alpha(2+\epsilon^{-1}+2/R)^2} \\ & \sim 2c \log R R^{2cR(2+\epsilon^{-1})^2+8c(2+\epsilon^{-1})+4c\epsilon^{-1}-1+8c/R} \end{aligned}$$

and

$$\begin{aligned} & \sinh\frac{4\alpha}{R} \left(\frac{1/2}{R} + 2 + \epsilon^{-1}\right) e^{2\alpha(2+\epsilon^{-1}+1/R)^2} A^2 \\ & \sim A^2 R^{2cR(2+\epsilon^{-1})^2+8c(2+\epsilon^{-1})+4c/R}, \end{aligned}$$

which proves our claim.

Finally, we conclude that

$$1 \leq 2c \log R R^{\frac{4c}{\epsilon}-1} \leq c_\epsilon e^{(5+2\epsilon^{-1})2cR \log R - (2+2\epsilon^{-1})2c \log R} \lambda^2(R),$$

so

$$\lambda(R) \geq c_\epsilon e^{-(5+2\epsilon^{-1})cR \log R + (2+2\epsilon^{-1})c \log R}.$$

We just finish this result by taking $c = \epsilon/2 + \epsilon^2$, to have

$$\lambda(R) \geq c_\epsilon e^{-(1+9\epsilon/2+5\epsilon^2)R \log R + (1+3\epsilon+2\epsilon^2) \log R} \quad (4.14)$$

which is of the desired form. $\square$

Once we have the lower bound, since the previous log-convexity properties, *i.e.*, Proposition 4.3, derive upper bounds for the term $\lambda(R)$, we are in a position to prove Theorem B from the introduction, that is,

Theorem 4.8 (Uniqueness result) *Let $u \in C^1([0, 1] : \ell^2(\mathbf{T}))$ be a solution of (4.1) with V a bounded potential. If for $\mu > 1$*

$$\sum_{x \in \mathbf{T}} e^{2\mu|x| \log(|x|+1)} (|u(x, 0)|^2 + |u(x, 1)|^2) < +\infty,$$

then $u \equiv 0$.

Proof Let $\eta > 0$ be such that $\mu > 1 + \eta > 1$.

If u is not zero, after eventually changing the root of the tree and multiplying u by a constant, we may assume that there is an $x_0 \in \mathbf{T}$ with $|x_0| = 2$ such that u satisfies

$$\int_{1/2-1/8}^{1/2+1/8} |u(x_0, t)|^2 dt \geq 1.$$

We can then apply the previous theorem to obtain a lower bound for $\lambda(R)$. More precisely, we know that $\lambda(R)$ satisfies (4.14). On the other hand, by Proposition 4.3 we have

$$\sup_{t \in [0, 1]} \sum_{x \in \mathbf{T}} |u(x, t)|^2 e^{2\mu|x| \log |x|} < +\infty.$$

Hence, $\lambda(R) \leq c e^{-\mu R \log R}$. Combining both bounds,

$$c e^{-\mu R \log R} \geq \lambda(R) \geq c e^{-(1+\eta)R \log R}.$$

We get a contradiction letting $R \rightarrow \infty$. $\square$

5 Other infinite graphs

Let $G = (\mathcal{E}, \mathcal{V})$ be an infinite graph and $\mathcal{L}$ be the associated combinatorial Laplacian. Assume that G is such that $\mathcal{L}$ has a finitely supported eigenfunction $e_\lambda : \mathcal{L}e_\lambda = \lambda e_\lambda$. In this case, the solution of

$$i \partial_t u(x, t) = \mathcal{L}u(x, t), \quad u(x, 0) = e_\lambda(x)$$

is given by $u(x, t) = e^{-i\lambda t} e_\lambda(x)$. This solution is thus finitely supported at all times. In particular, no analogue of Theorems A and C can hold.

Examples of graphs where this may happen are the Diestel–Leader graphs introduced in [20]. Recall that those are defined as follows:

Definition 5.1 Let $q, r \geq 2$. In $\mathbf{T}_q$ (resp. $\mathbf{T}_r$), we fix a geodesic ray ω (resp. ω') and write $h = h_\omega$ (resp. $h = h_{\omega'}$) for the associated Busemann function. The *Diestel–Leader graph* $DL(p, q)$ is

$$DL(q, r) = \{(x, y) \in \mathbf{T}_q \times \mathbf{T}_r : h(x) + h(y) = 0\}$$

and neighborhood is given by $(x, y) \sim (x', y')$ if $x \sim x'$ and $y \sim y'$.

This graph is regular of degree $q + r$. Bartholdi and Woess [10, Theorem 3.15] have shown that $L^2(DL(q, r))$ has an orthonormal basis of finitely supported eigenfunctions of $\mathcal{L}$.

Quint [41] and Taplyaev [43] have, respectively, shown that on the Pascal graph and the Sierpiński graphs there also exists finitely supported eigenfunctions of $\mathcal{L}$. Of course, on trees, there are no nonzero finitely supported eigenfunctions of the Laplacian.

Let us now turn to non-homogeneous trees and prove the following:

Proposition 5.2 Let (ω_n) be a sequence of positive real numbers with $\omega_n \rightarrow 0$. Then there exists a rooted tree $\mathbf{T}$ such that $\mathcal{L}$ has an eigenvector with $|e(x)| \leq C\omega_{|x|}$ for some $C > 0$. In particular, if u is the solution of

$$i\partial_t u(x, t) = \mathcal{L}u(x, t), \quad u(x, 0) = e(x)$$

then $|u(x, t)| \leq C\omega_{|x|}$ for every $t \geq 0$.

Here $|x|$ means of course the distance to the root of $\mathbf{T}$.

Remark 5.3 This does not mean that if $\tilde{\omega}_n = o(\omega_n)$ and u is a solution of $i\partial_t u(x, t) = \mathcal{L}u(x, t)$ such that $|u(x, t_i)| = O(\tilde{\omega}_n)$ at times $t_0 = 0$ and $t_1 = 1$ then $u = 0$.

For instance, for the homogeneous tree $\mathbf{T}_q$, the construction below provides us with an eigenvector for which $\omega_n = q^{-n/2}$. On the other hand, Corollary B shows that decrease rate at which the only solution is 0 is $\tilde{\omega}_n = e^{-\mu n \log(n+1)}$, $\mu > 1$.

For the trees constructed below, we do not know what the maximal rate of decrease is, if such a maximal rate exists.

Proof The tree we consider is a rapidly branching tree as introduced by Fujiwara [31]. Let d_n be a sequence of integers with $d_n \geq 2$ and construct the tree recursively. We start with the root o . We link o to d_0 vertices. Each of these vertices is then linked to $d_1 - 1$ further vertices. We thus construct a tree such the vertices at distance n from the root have degree d_n .

Next, we look for a radial eigenvector e of $\mathcal{L}$ with eigenvalue 1. For simplicity of notation, we write $e(x) = e(|x|)$. Those are constructed in [31], but for the sake of completeness, we reproduce the construction here. Then, $\mathcal{L}e(x) = e(x)$ reads

- if $x = 0$, $e(0) - e(1) = e(0)$; thus, $e(1) = 0$
- if $|x| = n \geq 1$, $e(n) - \frac{1}{d_n}(e(n-1) + (d_n - 1)e(n+1)) = e(n)$; thus, $e(n+1) = -\frac{1}{d_n - 1}e(n-1)$.

It follows that $e(n) = 0$ if n is odd and, if $n = 2p \geq 2$,

$$e(2p) = (-1)^p \left(\prod_{k=1}^p \frac{1}{d_{2k-1} - 1} \right) e(0).$$

It is then easy to inductively construct the d_{2k-1} 's in order to have $\prod_{k=1}^p (d_{2k-1} - 1) \geq \omega_{2n}^{-1}$ and the corresponding e is the eigenvector we are looking for. $\square$

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