# Commutativity of Cho and structure Jacobi operators of a real hypersurface in a complex projective space 

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#### Abstract

We consider real hypersurfaces $M$ in complex projective space equipped with both the Levi-Civita and generalized Tanaka-Webster connections. For any non-null constant $k$ and any vector field $X$ tangent to $M$, we can define an operator on $M, F_{X}^{(k)}$, related to both connections. We study commutativity problems of these operators and the structure Jacobi operator of $M$.


Keywords g-Tanaka-Webster connection • Complex projective space . Real hypersurface $\cdot k$ th Cho operator

Mathematics Subject Classification 53C15 53B25

## 1 Introduction

Let $\mathbb{C} P^{m}, m \geq 2$, be a complex projective space endowed with the metric $g$ of constant holomorphic sectional curvature 4 . Let $M$ be a connected real hypersurface of $\mathbb{C} P^{m}$ without boundary. Let $\nabla$ be the Levi-Civita connection on $M$ and $J$ the complex structure of $\mathbb{C} P^{m}$. Take a locally defined unit normal vector field $N$ on $M$ and denote by $\xi=-J N$. This is a tangent vector field to $M$ called the structure vector field on $M$. On $M$, there exists an almost contact metric structure ( $\phi, \xi, \eta, g$ ) induced by the Kaehlerian structure of $\mathbb{C} P^{m}$, where $\phi$ is the tangent component of $J$ and $\eta$ is an one form given by $\eta(X)=g(X, \xi)$ for any $X$ tangent to $M$. The classification of homogeneous real hypersurfaces in $\mathbb{C} P^{m}$ was obtained by Takagi, see [5,12-14]. His classification contains 6 types of real hypersurfaces. Among them, we find type $\left(A_{1}\right)$ real hypersurfaces that are geodesic hyperspheres of radius $r, 0<r<\frac{\pi}{2}$ and type $\left(A_{2}\right)$ real hypersurfaces that are tubes of radius $r, 0<r<\frac{\pi}{2}$, over totally geodesic complex projective spaces $\mathbb{C} P^{n}, 0<n<m-1$. We will call both types of real hypersurfaces type $(A)$ real hypersurfaces.

[^0]Ruled real hypersurfaces can be described as follows: take a regular curve $\gamma$ in $\mathbb{C} P^{m}$ with tangent vector field $X$. At each point of $\gamma$, there is a unique $\mathbb{C} P^{m-1}$ cutting $\gamma$ so as to be orthogonal not only to $X$ but also to $J X$. The union of these hyperplanes is called a ruled real hypersurface. It will be an embedded hypersurface locally, although globally it will in general have self-intersections and singularities. Equivalently, a ruled real hypersurface satisfies that the maximal holomorphic distribution on $M, \mathbb{D}$, given at any point by the vectors orthogonal to $\xi$, is integrable or $g(A \mathbb{D}, \mathbb{D})=0$. For examples of ruled real hypersurfaces, see [6] or [8].

The Tanaka-Webster connection, [15-17], is the canonical affine connection defined on a non-degenerate, pseudo-Hermitian CR manifold. As a generalization of this connection, Tanno, [16], defined the generalized Tanaka-Webster connection for contact metric manifolds by

$$
\begin{equation*}
\hat{\nabla}_{X} Y=\nabla_{X} Y+\left(\nabla_{X} \eta\right)(Y) \xi-\eta(Y) \nabla_{X} \xi-\eta(X) \phi Y \tag{1.1}
\end{equation*}
$$

Using the naturally extended affine connection of Tanno's generalized Tanaka-Webster connection, Cho defined the g-Tanaka-Webster connection $\hat{\nabla}^{(k)}$ for a real hypersurface $M$ in $\mathbb{C} P^{m}$ given, see $[3,4]$, by

$$
\begin{equation*}
\hat{\nabla}_{X}^{(k)} Y=\nabla_{X} Y+g(\phi A X, Y) \xi-\eta(Y) \phi A X-k \eta(X) \phi Y \tag{1.2}
\end{equation*}
$$

for any $X, Y$ tangent to $M$ where $k$ is a nonzero real number. Then, $\hat{\nabla}^{(k)} \eta=0, \hat{\nabla}^{(k)} \xi=0$, $\hat{\nabla}^{(k)} g=0, \hat{\nabla}^{(k)} \phi=0$. In particular, if the shape operator of a real hypersurface satisfies $\phi A+A \phi=2 k \phi$, the g-Tanaka-Webster connection coincides with the Tanaka-Webster connection.

Here, we can consider the tensor field of type $(1,2)$ given by the difference in both connections $F^{(k)}(X, Y)=g(\phi A X, Y) \xi-\eta(Y) \phi A X-k \eta(X) \phi Y$, for any $X, Y$ tangent to $M$, see [7] Proposition 7.10, pages 234-235. We will call this tensor the $k$ th Cho tensor on $M$. Associated to it, for any $X$ tangent to $M$ and any non-null real number $k$, we can consider the tensor field of type $(1,1) F_{X}^{(k)}$, given by $F_{X}^{(k)} Y=F^{(k)}(X, Y)$ for any $Y \in T M$. This operator will be called the $k$ th Cho operator corresponding to $X$. The torsion of the connection $\hat{\nabla}^{(k)}$ is given by $\hat{T}^{(k)}(X, Y)=F_{X}^{(k)} Y-F_{Y}^{(k)} X$ for any $X, Y$ tangent to $M$.

The Jacobi operator $R_{X}$ with respect to a unit vector field $X$ is defined by $R_{X}=R(., X) X$, where $R$ is the curvature tensor field on $M$. Then, we see that $R_{X}$ is a self-adjoint endomorphism of the tangent space. It is related to Jacobi vector fields, which are solutions of the second-order differential equation (the Jacobi equation) $\nabla_{\dot{\gamma}}\left(\nabla_{\dot{\gamma}} Y\right)+R(Y, \dot{\gamma}) \dot{\gamma}=0$ along a geodesic $\gamma$ in $M$. The Jacobi operator with respect to the structure vector field $\xi, R_{\xi}$, is called the structure Jacobi operator on $M$.

The purpose of the present paper was to study real hypersurfaces $M$ in $\mathbb{C} P^{m}$ such that the covariant and g -Tanaka-Webster derivatives of the structure Jacobi operator coincide. $\nabla R_{\xi}=\hat{\nabla}^{(k)} R_{\xi}$ is equivalent to the fact that, for any $X$ tangent to $M, R_{\xi} F_{X}^{(k)}=F_{X}^{(k)} R_{\xi}$. The meaning of this condition is that every eigenspace of $R_{\xi}$ is preserved by the $k$ th Cho operator $F_{X}^{(k)}$ for any $X$ tangent to $M$.

On the other hand, $T M=\operatorname{Span}\{\xi\} \oplus \mathbb{D}$. Thus, we will obtain the following
Theorem 1 Let $M$ be a real hypersurface in $\mathbb{C} P^{m}, m \geq 3$. Let $k$ be a non-null constant. Then, $F_{X}^{(k)} R_{\xi}=R_{\xi} F_{X}^{(k)}$ for any $X \in \mathbb{D}$ if and only if $M$ is locally congruent to a ruled real hypersurface.

Theorem 2 Let $M$ be a real hypersurface in $\mathbb{C} P^{m}, m \geq 3$. Let $k$ be a non-null constant. Then, $F_{\xi}^{(k)} R_{\xi}=R_{\xi} F_{\xi}^{(k)}$ if and only if $M$ is locally congruent to either a tube of radius $\frac{\pi}{4}$ over a complex submanifold of $\mathbb{C} P^{m}$ or to a type ( $A$ ) real hypersurface with radius $r \neq \frac{\pi}{4}$.

As a direct consequence of these Theorems, we have
Corollary There do not exist real hypersurfaces $M$ in $\mathbb{C} P^{m}, m \geq 3$, such that for a non-null constant $k, F_{X}^{(k)} R_{\xi}=R_{\xi} F_{X}^{(k)}$ for any $X$ tangent to $M$.

## 2 Preliminaries

Throughout this paper, all manifolds, vector fields, etc., will be considered of class $C^{\infty}$ unless otherwise stated. Let $M$ be a connected real hypersurface in $\mathbb{C} P^{m}, m \geq 2$, without boundary. Let $N$ be a locally defined unit normal vector field on $M$. Let $\nabla$ be the Levi-Civita connection on $M$ and $(J, g)$ the Kaehlerian structure of $\mathbb{C} P^{m}$.

For any vector field $X$ tangent to $M$, we write $J X=\phi X+\eta(X) N$, and $-J N=\xi$. Then, ( $\phi, \xi, \eta, g$ ) is an almost contact metric structure on $M$, see [1], that is, we have

$$
\begin{equation*}
\phi^{2} X=-X+\eta(X) \xi, \quad \eta(\xi)=1, \quad g(\phi X, \phi Y)=g(X, Y)-\eta(X) \eta(Y) \tag{2.1}
\end{equation*}
$$

for any tangent vectors $X, Y$ to $M$. From (2.1), we obtain

$$
\begin{equation*}
\phi \xi=0, \quad \eta(X)=g(X, \xi) . \tag{2.2}
\end{equation*}
$$

From the parallelism of $J$, we get

$$
\begin{equation*}
\left(\nabla_{X} \phi\right) Y=\eta(Y) A X-g(A X, Y) \xi \tag{2.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{X} \xi=\phi A X \tag{2.4}
\end{equation*}
$$

for any $X, Y$ tangent to $M$, where $A$ denotes the shape operator of the immersion. As the ambient space has holomorphic sectional curvature 4, the equations of Gauss and Codazzi are given, respectively, by

$$
\begin{align*}
R(X, Y) Z= & g(Y, Z) X-g(X, Z) Y+g(\phi Y, Z) \phi X-g(\phi X, Z) \phi Y \\
& -2 g(\phi X, Y) \phi Z+g(A Y, Z) A X-g(A X, Z) A Y, \tag{2.5}
\end{align*}
$$

and

$$
\begin{equation*}
\left(\nabla_{X} A\right) Y-\left(\nabla_{Y} A\right) X=\eta(X) \phi Y-\eta(Y) \phi X-2 g(\phi X, Y) \xi \tag{2.6}
\end{equation*}
$$

for any tangent vectors $X, Y, Z$ to $M$, where $R$ is the curvature tensor of $M$. We will call the maximal holomorphic distribution $\mathbb{D}$ on $M$ to the following one: at any $p \in M, \mathbb{D}(p)=$ $\left\{X \in T_{p} M \mid g(X, \xi)=0\right\}$. We will say that $M$ is Hopf if $\xi$ is principal, that is, $A \xi=\alpha \xi$ for a certain function $\alpha$ on $M$.

From the above formulas, we have that the structure Jacobi operator on $M$ is given by

$$
\begin{equation*}
R_{\xi}(X)=X-\eta(X) \xi+g(A \xi, \xi) A X-g(A X, \xi) A \xi \tag{2.7}
\end{equation*}
$$

for any $X$ tangent to $M$
In the sequel, we need the following results:
Theorem 2.1 [10] Let $M$ be a real hypersurface of $\mathbb{C} P^{m}, m \geq 2$. Then, the following are equivalent:

1. $M$ is locally congruent to either a geodesic hypersphere or a tube of radius $r, 0<r<\frac{\pi}{2}$ over a totally geodesic $\mathbb{C} P^{n}, 0<n<m-1$.
2. $\phi A=A \phi$.

Theorem 2.2 [9] If $\xi$ is a principal curvature vector with corresponding principal curvature $\alpha$ and $X \in \mathbb{D}$ is principal with principal curvature $\lambda$, then $\phi X$ is principal with principal curvature $\frac{\alpha \lambda+2}{2 \lambda-\alpha}$.

## 3 Proof of Theorem 1

If we suppose that $F_{X}^{(k)} R_{\xi}=R_{\xi} F_{X}^{(k)}$ for any $X \in \mathbb{D}$, we get

$$
\begin{align*}
& g(Y, \phi A X) \xi+\eta(A \xi) g(\phi A X, A Y) \xi-\eta(A Y) g(\phi A X, A \xi) \xi \\
& \quad+\eta(Y) \phi A X+\eta(Y) \eta(A \xi) A \phi A X-\eta(Y) \eta(A \phi A X) A \xi=0 \tag{3.1}
\end{align*}
$$

for any $X \in \mathbb{D}, Y \in T M$. Let us suppose that $M$ is non-Hopf. Thus, locally we can write $A \xi=\alpha \xi+\beta U$, where $U$ is a unit vector field in $\mathbb{D}, \alpha$ and $\beta$ are functions on $M$ and $\beta \neq 0$. We also call $\mathbb{D}_{U}$ to the orthogonal complementary distribution in $\mathbb{D}$ to the one spanned by $U, \phi U$.

If we take $X=Y=\phi U$ in (3.1), we get

$$
\begin{equation*}
g(A U, \phi U)=0 \tag{3.2}
\end{equation*}
$$

And taking $Y=\xi$ in (3.1), we obtain

$$
\begin{equation*}
\phi A X+\alpha A \phi A X-\alpha \beta g(\phi A X, U) \xi-\beta^{2} g(\phi A X, U) U=0 \tag{3.3}
\end{equation*}
$$

for any $X \in \mathbb{D}$. In particular, from (3.2) and (3.3), we have

$$
\begin{equation*}
\phi A U+\alpha A \phi A U=0 . \tag{3.4}
\end{equation*}
$$

The scalar product of (3.3) and $U$ yields

$$
\begin{equation*}
\left(\beta^{2}-1\right) g(A \phi U, X)-\alpha g(A \phi A U, X)=0 \tag{3.5}
\end{equation*}
$$

for any $X \in \mathbb{D}$. Thus, $\left(\beta^{2}-1\right) A \phi U-\alpha A \phi A U$ has not a component in $\mathbb{D}$, and taking its scalar product with $\xi$, it follows

$$
\begin{equation*}
\left(\beta^{2}-1\right) A \phi U-\alpha A \phi A U=0 . \tag{3.6}
\end{equation*}
$$

From (3.4) and (3.6), we get

$$
\begin{equation*}
\phi A U=\left(1-\beta^{2}\right) A \phi U . \tag{3.7}
\end{equation*}
$$

Therefore, we can write $A \phi U=\delta \phi U+\omega Z_{1}$, where $Z_{1} \in \mathbb{D}_{U}$ is a unit vector field. The scalar product of (3.3) and $Y \in \mathbb{D}_{U}$ yields $A \phi Y+\alpha A \phi Y$ has not component in $\mathbb{D}$. Then,

$$
\begin{equation*}
A \phi Y+\alpha A \phi A Y=-\alpha \beta g(A \phi U, Y) \xi \tag{3.8}
\end{equation*}
$$

for any $Y \in \mathbb{D}_{U}$. Taking $Y=\phi Z_{1}$, we obtain $-A Z_{1}+\alpha A \phi A \phi Z_{1}=0$. Its scalar product with $\xi$ gives

$$
\begin{equation*}
\alpha \beta \omega\left(\beta^{2}-1\right)=0 . \tag{3.9}
\end{equation*}
$$

As $\beta \neq 0$, the following cases appear
Case 1. $\alpha=0$.
Case 2. $\beta^{2}=1$. In this case, from (3.7), $A U=\beta \xi$.
Case 3. $\omega=0$, thus $\mathbb{D}_{U}$ is $A$-invariant.

Case 1. $\alpha=0$. From (3.4) $\phi A U=0$, that is, $A U=\beta \xi$ and $A \xi=\beta U$ and from (3.6) $\left(\beta^{2}-1\right) A \phi U=0$. So we have the following subcases

Subcase 1.1. Let us suppose that $\beta^{2} \neq 1$. Then, $A \phi U=0$. Moreover, from (3.8) for any $Y \in \mathbb{D}_{U} A \phi Y=0$. That means that $M$ is a minimal ruled hypersurface.

Subcase 1.2. $\alpha=0, \beta^{2}=1$. We can suppose $\beta=1$, maybe after changing $\xi$ by $-\xi$. As above, $A \phi Y=0$ for any $Y \in \mathbb{D}_{U}, A U=\xi, A \xi=U$. Then, $A Z_{1}=0$ and $\omega=g\left(A \phi U, Z_{1}\right)=0$. Thus, $A \phi U=\delta \phi U$.

By the Codazzi equation $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \phi U\right)=1$ yields

$$
\begin{equation*}
\delta g\left(\nabla_{\xi} U, \phi U\right)+g\left(\nabla_{U} U, \phi U\right)=0 . \tag{3.10}
\end{equation*}
$$

From $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, \xi\right)=0$, we obtain

$$
\begin{equation*}
g\left(\nabla_{\xi} \phi U, U\right)=-3 \delta . \tag{3.11}
\end{equation*}
$$

From (3.10) and (3.11), we have

$$
\begin{equation*}
g\left(\nabla_{U} U, \phi U\right)=-3 \delta^{2} \tag{3.12}
\end{equation*}
$$

As $g\left(\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U, \xi\right)=-2$, it follows

$$
\begin{equation*}
g\left(\nabla_{U} U, \phi U\right)=-2 \tag{3.13}
\end{equation*}
$$

and from $g\left(\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U, U\right)=0$, we get

$$
\begin{equation*}
\delta g\left(\nabla_{U} \phi U, U\right)+2 \delta=0 \tag{3.14}
\end{equation*}
$$

From (3.13) and (3.14), we have $\delta=0$. Therefore, $M$ is still a minimal ruled real hypersurface.

Case 2. $\beta^{2}=1$. As above, we suppose $\beta=1$. As the case $\alpha=0$ has been studied, we suppose $\alpha \neq 0$. Then, from (3.6), $A \phi A U=0$, and from (3.4), $\phi A U=0$. Therefore, $A \xi=\alpha \xi+U, A U=\xi$. Moreover, we know that $-A Z_{1}+\alpha A \phi A Z_{1}=0$. Taking its scalar product with $\phi U$, we get $\omega+\alpha \omega g\left(A \phi Z_{1}, \phi Z_{1}\right)=0$. Supposing $\omega \neq 0$, we have $g\left(A \phi Z_{1}, \phi Z_{1}\right)=-\frac{1}{\alpha}$.

Taking $X=Y \in \mathbb{D}_{U}$ in (3.1), we obtain $\phi A Y+\alpha A \phi A Y+\omega g\left(Y, Z_{1}\right) A \xi=0$. Its scalar product with $\phi U$ gives $\alpha g(A \phi A Y, \phi U)=0=-\alpha \omega g\left(Y, A \phi Z_{1}\right)$. As $\alpha \omega \neq 0$, $g\left(Y, A \phi Z_{1}\right)=0$ for any $Y \in \mathbb{D}_{U}$. This yields $A \phi Z_{1}=0$ and $0=-\frac{1}{\alpha}$. This is a contradiction, and we have $\omega=0, A \xi=\alpha \xi+U, A U=\xi$ and $A \phi U=\delta \phi U$.

This yields $\mathbb{D}_{U}$ is $A$-invariant and $\phi$-invariant, and we arrive to Case 3 . As also $\phi A U=$ $\left(1-\beta^{2}\right) A \phi U$, we have two possible subcases:

Subcase 3.1. $\beta^{2}=1$. In this case, $A U=\beta \xi$.
Subcase 3.2. $\beta^{2} \neq 1$ and $A U=\beta \xi+\sigma U$, where $\sigma=\left(1-\beta^{2}\right) \delta$.
If we take $Y=\phi X \in \mathbb{D}_{U}$ in (3.1) for $X \in \mathbb{D}_{U}$ such that $A X=\lambda X$, we have $\lambda+$ $\alpha \lambda g(\phi X, A \phi X)=0$. This yields that either any eigenvalue in $\mathbb{D}_{U}$ is 0 or that if there exists a non-null eigenvalue $\lambda$ in $\mathbb{D}_{U}, \alpha \neq 0$ and $\lambda=-\frac{1}{\alpha}$. In this case, the eigenspace corresponding to this eigenvalue is $\phi$-invariant.

Let us suppose that for any $Y \in \mathbb{D}_{U} A Y=0$. As $g\left(\left(\nabla_{Y} A\right) \phi Y-\left(\nabla_{\phi Y} A\right) Y, \xi\right)=-2$, we obtain

$$
\begin{equation*}
g([\phi Y, Y], U)=-\frac{2}{\beta} \tag{3.15}
\end{equation*}
$$

And as $g\left(\left(\nabla_{Y} A\right) \phi Y-\left(\nabla_{\phi Y} A\right) Y, U\right)=0$, it follows

$$
\begin{equation*}
\sigma g([\phi Y, Y], U)=0 . \tag{3.16}
\end{equation*}
$$

From (3.15) and (3.16), we get $\sigma=0$. If also $\beta^{2} \neq 1, \delta=0$ and our real hypersurface should be ruled.

Let us then suppose that $\beta^{2}=1$. As above, we will take $\beta=1$ and $\sigma=0$. If we develop $g\left(\left(\nabla_{Y} A\right) \phi U-\left(\nabla_{\phi U} A\right) Y, \xi\right)=0$, we get

$$
\begin{equation*}
g\left(\nabla_{Y} \phi U, U\right)=g\left(\nabla_{\phi U} Y, U\right) \tag{3.17}
\end{equation*}
$$

and from $g\left(\left(\nabla_{Y} A\right) \phi U-\left(\nabla_{\phi U} A\right) Y, U\right)=0$, it follows

$$
\begin{equation*}
\delta g\left(\nabla_{Y} \phi U, U\right)=0 \tag{3.18}
\end{equation*}
$$

From (3.17) and (3.18), suppose $g\left(\nabla_{Y} \phi U, U\right)=g\left(\nabla_{\phi U} Y, U\right)=0$. As $g\left(\left(\nabla_{\phi U} A\right) U-\right.$ $\left.\left(\nabla_{U} A\right) \phi U, \xi\right)=2$, we obtain

$$
\begin{equation*}
g\left(\nabla_{U} \phi U, U\right)=2+\alpha \delta \tag{3.19}
\end{equation*}
$$

and from $g\left(\left(\nabla_{\phi U} A\right) U-\left(\nabla_{U} A\right) \phi U, U\right)=0$, we have

$$
\begin{equation*}
2 \delta+\delta g\left(\nabla_{U} \phi U, U\right)=0 \tag{3.20}
\end{equation*}
$$

If $\delta \neq 0$, from (3.20) $g\left(\nabla_{U} \phi U, U\right)=-2$ and from (3.19)

$$
\begin{equation*}
\alpha \delta=-4 \tag{3.21}
\end{equation*}
$$

Now, $g\left(\left(\nabla_{\phi U} A\right) \xi-\left(\nabla_{\xi} A\right) \phi U, U\right)=1$ gives $\delta g\left(\nabla_{\xi} \phi U, U\right)=2-\alpha \delta$. From (3.21)

$$
\begin{equation*}
\delta g\left(\nabla_{\xi} \phi U, U\right)=6 . \tag{3.22}
\end{equation*}
$$

But from $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \phi U\right)=1$, we obtain

$$
\begin{equation*}
-\delta g\left(\nabla_{\xi} U, \phi U\right)=0 \tag{3.23}
\end{equation*}
$$

From (3.22) and (3.23), we arrive to a contradiction. Thus, $\delta=0$ and $M$ is also a ruled real hypersurface.

Therefore, we have only to study the following case: $A \xi=\alpha \xi+\beta U, A U=\beta \xi+\sigma U$, $A \phi U=\delta \phi U, \mathbb{D}_{U}$ is $A$-invariant, and there exists $Z \in \mathbb{D}_{U}$ such that $A Z=-\frac{1}{\alpha} Z, A \phi Z=$ $-\frac{1}{\alpha} \phi Z$. As $\left(1-\beta^{2}\right) A \phi U=\phi A U$, two subcases appear

Subcase 1. $\beta^{2}=1$, and then $\sigma=0$.
Subcase 2. $\beta^{2} \neq 1, \sigma=\left(1-\beta^{2}\right) \delta$.
From $g\left(\left(\nabla_{Z} A\right) \phi Z-\left(\nabla_{\phi Z} A\right) Z, \xi\right)=-2$, we obtain

$$
\begin{equation*}
\beta g([\phi Z, Z], U)=\frac{2}{\alpha^{2}} \tag{3.24}
\end{equation*}
$$

and from $g\left(\left(\nabla_{Z} A\right) \phi Z-\left(\nabla_{\phi Z} A\right) Z, U\right)=0$, we get

$$
\begin{equation*}
\left(\frac{1}{\alpha}+\sigma\right) g([\phi Z, Z], U)=\frac{2 \beta}{\alpha} . \tag{3.25}
\end{equation*}
$$

From (3.24) and (3.25), we obtain

$$
\begin{equation*}
1+\alpha \sigma=\alpha^{2} \beta^{2} \tag{3.26}
\end{equation*}
$$

In Subcase 1 , as $\beta^{2}=1$ and $\sigma=0$, we should obtain $\alpha^{2}=1$. Changing, if necessary, $\xi$ by $-\xi$, we can take $\alpha=1$. This case cannot occur by Proposition 3.2, page 1607 in [11]. Therefore, we have $\beta^{2} \neq 1$ and from (3.26) $1+\alpha \delta\left(1-\beta^{2}\right)=\alpha^{2} \beta^{2}$. Thus,

$$
\begin{equation*}
\delta=\frac{\alpha^{2} \beta^{2}-1}{\alpha\left(1-\beta^{2}\right)} \tag{3.27}
\end{equation*}
$$

Now, $g\left(\left(\nabla_{Z} A\right) \phi Z-\left(\nabla_{\phi Z} A\right) Z, \phi U\right)=0$ yields

$$
\begin{equation*}
\left(\frac{1}{\alpha}+\delta\right) g([Z, \phi Z], \phi U)=0 \tag{3.28}
\end{equation*}
$$

Let us suppose that $\delta=-\frac{1}{\alpha}$. Then, $\sigma=\frac{\beta^{2}-1}{\alpha}$ and from (3.26) $\alpha^{2}=1$. As above, we suppose $\alpha=1$. Thus, $A \xi=\xi+\beta U, A U=\beta \xi+\left(\beta^{2}-1\right) U, A \phi U=-\phi U$, and there exists a unit $Z \in \mathbb{D}_{U}$ such that $A Z=-Z, A \phi Z=-\phi Z$.

Suppose that there exists a unit $W \in \mathbb{D}_{U}$ such that $A W=A \phi W=0$. From $g\left(\left(\nabla_{W} A\right) \xi-\right.$ $\left.\left(\nabla_{\xi} A\right) W, \xi\right)=0$, we obtain $g\left(\nabla_{\xi} W, U\right)=0$, and from $g\left(\left(\nabla_{W} A\right) \xi-\left(\nabla_{\xi} A\right) W, U\right)=0$, we get $W(\beta)+\left(\beta^{2}-1\right) g\left(\nabla_{\xi} W, U\right)=0$. Thus, $W(\beta)=0$. This fact and the proof of Proposition 3.3, page 1608 in [11], yield $\operatorname{grad}(\beta)=-\left(2 \beta^{2}+1\right) \phi U$. The same proof yields this case cannot occur. Therefore, $\delta \neq-\frac{1}{\alpha}$ and $g([Z, \phi Z], \phi U)=0$.

Then, from $g\left(\left(\nabla_{Z} A\right) \phi Z-\left(\nabla_{\phi Z} A\right) Z, Z\right)=g\left(\left(\nabla_{Z} A\right) \phi Z-\left(\nabla_{\phi Z} A\right) Z, \phi Z\right)=0$, we get

$$
\begin{equation*}
Z(\alpha)=(\phi Z)(\alpha)=0 \tag{3.29}
\end{equation*}
$$

From $g\left(\left(\nabla_{Z} A\right) \xi-\left(\nabla_{\xi} A\right) Z, \xi\right)=0$, it follows

$$
\begin{equation*}
Z(\alpha)+\beta g\left(\nabla_{\xi} Z, U\right)=0 . \tag{3.30}
\end{equation*}
$$

From (3.29) and (3.30), we obtain

$$
\begin{equation*}
g\left(\nabla_{\xi} Z, U\right)=0 . \tag{3.31}
\end{equation*}
$$

As $g\left(\left(\nabla_{Z} A\right) \xi-\left(\nabla_{\xi} A\right) Z, U\right)=0$, we have, bearing in mind (3.31),

$$
\begin{equation*}
Z(\beta)=0 \tag{3.32}
\end{equation*}
$$

From $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \xi\right)=0$, we get

$$
\begin{equation*}
\xi(\beta)=U(\alpha) \tag{3.33}
\end{equation*}
$$

and as $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, U\right)=0$, it follows

$$
\begin{equation*}
\xi(\sigma)=U(\beta) . \tag{3.34}
\end{equation*}
$$

Now, $g\left(\left(\nabla_{Z} A\right) U-\left(\nabla_{U} A\right) Z, \xi\right)=0$ yields

$$
\begin{equation*}
Z(\beta)+\sigma g\left(\nabla_{U} Z, U\right)=0 \tag{3.35}
\end{equation*}
$$

and from (3.26) and $g\left(\left(\nabla_{Z} A\right) U-\left(\nabla_{U} A\right) Z, U\right)=0$, we obtain

$$
\begin{equation*}
Z(\sigma)+\alpha \beta^{2} g\left(\nabla_{U} Z, U\right)=0 \tag{3.36}
\end{equation*}
$$

From (3.32) and (3.36), we have $\sigma g\left(\nabla_{U} Z, U\right)=0$. This and (3.36) yield $Z(\sigma)+$ $\frac{1}{\alpha} g\left(\nabla_{U} Z, U\right)=0$. As $Z(\alpha)=Z(\beta)=0$, from (3.26) $Z(\sigma)=0$. Therefore,

$$
\begin{equation*}
g\left(\nabla_{U} Z, U\right)=0 \tag{3.37}
\end{equation*}
$$

As $g\left(\left(\nabla_{Z} A\right) U-\left(\nabla_{U} A\right) Z, \phi U\right)=0$, this gives

$$
\begin{equation*}
(\sigma-\delta) g\left(\nabla_{Z} U, \phi U\right)+\left(\delta+\frac{1}{\alpha}\right) g\left(\nabla_{U} Z, \phi U\right)=0 \tag{3.38}
\end{equation*}
$$

and $g\left(\left(\nabla_{Z} A\right) U-\left(\nabla_{U} A\right) Z, Z\right)=0$ yields

$$
\begin{equation*}
U\left(\frac{1}{\alpha}\right)=\left(\sigma+\frac{1}{\alpha}\right) g\left(\nabla_{Z} Z, U\right) \tag{3.39}
\end{equation*}
$$

From $g\left(\left(\nabla_{Z} A\right) \xi-\left(\nabla_{\xi} A\right) Z, Z\right)=0$, we obtain

$$
\begin{equation*}
\xi\left(\frac{1}{\alpha}\right)=\beta g\left(\nabla_{Z} Z, U\right) \tag{3.40}
\end{equation*}
$$

and from $g\left(\left(\nabla_{Z} A\right) \phi U-\left(\nabla_{\phi U} A\right) Z, U\right)=0$, we get

$$
\begin{equation*}
(\delta-\sigma) g\left(\nabla_{Z} \phi U, U\right)+\left(\sigma+\frac{1}{\alpha}\right) g\left(\nabla_{\phi U} Z, U\right)=0 . \tag{3.41}
\end{equation*}
$$

We also have from $\left.g\left(\left(\nabla_{Z} A\right) \phi U\right)-\left(\nabla_{\phi U} A\right) Z, \xi\right)=0$

$$
\begin{equation*}
g([\phi U, Z], U)=0 . \tag{3.42}
\end{equation*}
$$

Thus, from (3.41) and (3.42), we have a homogeneous system of linear equations where $g\left(\nabla_{Z} \phi U, U\right)$ and $g\left(\nabla_{\phi U} Z, U\right)$ are unknown. The determinant of its matrix of coefficients is $\delta+\frac{1}{\alpha}$. As $\delta \neq-\frac{1}{\alpha}$, we obtain

$$
\begin{equation*}
g\left(\nabla_{Z} \phi U, U\right)=g\left(\nabla_{\phi U} Z, U\right)=0 \tag{3.43}
\end{equation*}
$$

As $g\left(\left(\nabla_{Z} A\right) \phi U-\left(\nabla_{\phi U} A\right) Z, \phi Z\right)=0$, we have $\left(\delta+\frac{1}{\alpha}\right) g\left(\nabla_{Z} \phi U, \phi Z\right)=0$. As $\delta \neq-\frac{1}{\alpha}$, $g\left(\nabla_{Z} \phi U, \phi Z\right)=0$. By (2.3), this gives $g\left(\nabla_{Z} U, Z\right)=0$. From (3.39) and (3.40), it follows

$$
\begin{equation*}
\xi(\alpha)=U(\alpha)=0 \tag{3.44}
\end{equation*}
$$

From $g\left(\left(\nabla_{Z} A\right) \phi U-\left(\nabla_{\phi U} A\right) Z, Z\right)=0$, we have $\left(\delta+\frac{1}{\alpha}\right) g\left(\nabla_{Z} \phi U, Z\right)+(\phi U)\left(\frac{1}{\alpha}\right)=0$. Now, from (2.3)

$$
\begin{equation*}
(\phi U)\left(\frac{1}{\alpha}\right)=\left(\frac{1}{\alpha}+\delta\right) g\left(\nabla_{Z} U, \phi Z\right) . \tag{3.45}
\end{equation*}
$$

Developing $g\left(\left(\nabla_{Z} A\right) U-\left(\nabla_{U} A\right) Z, \phi Z\right)=0$ and bearing in mind (3.26), we get

$$
\begin{equation*}
\alpha^{2} \beta^{2} g\left(\nabla_{Z} U, \phi Z\right)=\beta \tag{3.46}
\end{equation*}
$$

Now, from (3.45) and (3.46), we obtain

$$
\begin{equation*}
(\phi U)(\alpha)=-\frac{1+\alpha \delta}{\alpha \beta}=\frac{\beta\left(1-\alpha^{2}\right)}{\alpha\left(1-\beta^{2}\right)} . \tag{3.47}
\end{equation*}
$$

From (3.33) and (3.44), we have

$$
\begin{equation*}
\xi(\beta)=U(\beta)=0 \tag{3.48}
\end{equation*}
$$

The equality $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \phi U\right)=1$ yields

$$
\begin{equation*}
\beta g\left(\nabla_{U} U, \phi U\right)=\beta^{2}+\sigma^{2}-\alpha \sigma-1 \tag{3.49}
\end{equation*}
$$

From $g\left(\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U, \xi\right)=-2$, we arrive to $-2 \delta \sigma+\alpha \sigma+\alpha \delta-$ $\beta g\left(\nabla_{U} \phi U, U\right)-(\phi U)(\beta)=2$. This and (3.49) yield

$$
\begin{equation*}
(\phi U)(\beta)=-2 \delta \sigma+\alpha \delta+\beta^{2}+\sigma^{2}+1 \tag{3.50}
\end{equation*}
$$

Bearing in mind all these facts, we arrive to

$$
\begin{align*}
& \operatorname{grad}(\alpha)=\rho \phi U \\
& \operatorname{grad}(\beta)=\theta \phi U \tag{3.51}
\end{align*}
$$

where $\rho=-\left(\frac{1+\alpha \delta}{\alpha \beta}\right)$ and $\theta=-2 \delta \sigma+\alpha \delta+\beta^{2}+\sigma^{2}+1$. As $g\left(\nabla_{X} \operatorname{grad}(\alpha), Y\right)=$ $g\left(\nabla_{Y} \operatorname{grad}(\alpha), X\right)$ for any $X, Y$ tangent to $M$, we have, taking $X=\xi, \xi(\rho) g(\phi U, Y)+$ $\rho g\left(\nabla_{\xi} \phi U, Y\right)=-\rho g(U, A Y)$. If $Y=\phi U$, this yields $\xi(\rho)=0$. Thus, $\rho g\left(\nabla_{\xi} \phi U, Y\right)=$ $-\rho g(U, A Y)$, for any $Y$ tangent to $M$. As $\rho \neq 0$, taking $Y=U$, we get

$$
\begin{equation*}
g\left(\nabla_{\xi} \phi U, U\right)=-\sigma . \tag{3.52}
\end{equation*}
$$

From $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, \xi\right)=0$ and bearing in mind (3.52), we have

$$
\begin{equation*}
(\phi U)(\alpha)=-3 \beta \delta+\alpha \beta-\beta \sigma . \tag{3.53}
\end{equation*}
$$

From (3.47) and (3.53) $2+\alpha \delta+\alpha \sigma-3 \alpha \beta^{2} \delta+\alpha \sigma \beta^{2}=0$, or equivalently

$$
\begin{equation*}
\alpha^{2}\left(2 \beta^{2}-3 \beta^{4}-\beta^{6}\right)+\beta^{2}\left(2+\beta^{2}\right)-1=0 \tag{3.54}
\end{equation*}
$$

If $2-3 \beta^{2}-\beta^{4}=0$, we should have $\beta^{4}+2 \beta^{2}-1=0$. Both equalities yield $\beta^{2}=1$, that is impossible. From (3.54), we have

$$
\begin{equation*}
\alpha^{2}=\frac{1-\beta^{2}\left(2+\beta^{2}\right)}{2 \beta^{2}-3 \beta^{4}-\beta^{6}} \tag{3.55}
\end{equation*}
$$

If we take the derivative of (3.54) in the direction of $\phi U$ and bear in mind (3.47), (3.48), and (3.54), we find that $\beta$ is a root of a polynomial with constant coefficients. Therefore, $\beta$ is constant. From (3.55), $\alpha$ is also constant, which is impossible.

Thus, we have proved that if $M$ is not Hopf, it is locally congruent to a ruled real hypersurface. It is easy to see that these real hypersurfaces satisfy (3.1).

Let us now suppose that $M$ is a Hopf real hypersurface with $A \xi=\alpha \xi$ and that $M$ satisfies (3.1). Then, we have for any $X \in \mathbb{D}$ that $\phi A X+\alpha A \phi A X=0$. If $\alpha=0$, we get $\phi A X=0$. Thus, $A X=0$ for any $X \in \mathbb{D}$ and $M$ should be totally geodesic, which is impossible.

Suppose now that $\alpha \neq 0$ and take a unit $X \in \mathbb{D}$ such that $A X=\lambda X$. From (3.1), we get either $\lambda=0$ or $A \phi X=-\frac{1}{\alpha} \phi X$. Applying the same reasoning to $\phi X$, we obtain that the eigenspaces in $\mathbb{D}$ are $\phi$-invariant and correspond to the eigenvalues 0 and $-\frac{1}{\alpha}$. This is impossible by Theorem 2.2, and we finish the proof.

## 4 Proof of Theorem 2

If we suppose that $R_{\xi} F_{\xi}^{(k)}=F_{\xi}^{(k)} R_{\xi}$, we get

$$
\begin{align*}
& g(Y, \phi A \xi) \xi+g(A \xi, \xi) g(\phi A \xi, A Y) \xi+\eta(Y) \phi A \xi+\eta(Y) \eta(A \xi) A \phi A \xi \\
& \quad-\eta(Y) \eta(A \phi A \xi) A \xi-k \phi R_{\xi}(Y)+k R_{\xi}(\phi Y)=0 \tag{4.1}
\end{align*}
$$

for any $Y \in T M$. Let us suppose that $M$ is non-Hopf. Thus, we write $A \xi=\alpha \xi+\beta U$ for a unit $U \in \mathbb{D}$ and functions $\alpha$ and $\beta$ on $M, \beta$ being nonvanishing. From (4.1), we have

$$
\begin{gather*}
\beta g(Y, \phi U) \xi+\alpha \beta g(\phi U, A Y) \xi+\beta \eta(Y) \phi U \\
+\alpha \beta \eta(Y) A \phi U=k \phi R_{\xi}(Y)-k R_{\xi}(\phi Y) \tag{4.2}
\end{gather*}
$$

for any $Y \in T M$. Taking $Y=\xi$ in (4.2), we obtain

$$
\begin{equation*}
\beta \phi U+\alpha \beta A \phi U=0 . \tag{4.3}
\end{equation*}
$$

As $\beta \neq 0$, this yields

$$
\begin{align*}
\alpha & \neq 0, \\
A \phi U & =-\frac{1}{\alpha} \phi U . \tag{4.4}
\end{align*}
$$

If now we take $Y=U$ in (4.2), as $k \neq 0$, we get $\phi R_{\xi}(U)=R_{\xi}(\phi U)$. This yields $\alpha \phi A U=\left(\beta^{2}-1\right) \phi U$, that is, $\phi A U=\frac{\beta^{2}-1}{\alpha} \phi U$. By applying $\phi$ to such an equality, it follows

$$
\begin{equation*}
A U=\beta \xi+\frac{\beta^{2}-1}{\alpha} U \tag{4.5}
\end{equation*}
$$

From (4.4) and (4.5), we obtain that $\mathbb{D}_{U}$ is $\phi$-invariant and $A$-invariant. Take a unit $Y \in \mathbb{D}_{U}$ such that $A Y=\lambda Y$. Introducing this $Y$ in (4.2), we get $\phi R_{\xi}(Y)=R_{\xi}(\phi Y)$. This yields $\alpha \lambda \phi Y=\alpha A \phi Y$. As $\alpha \neq 0, A \phi Y=\lambda \phi Y$. Therefore, the eigenspaces in $\mathbb{D}_{U}$ are $\phi$-invariant.

The Codazzi equation gives $\left(\nabla_{\xi} A\right) \phi Y-\left(\nabla_{\phi Y} A\right) Y=-2 \xi$. Taking its scalar product with $\phi Y$, respectively, with $Y$, we have

$$
\begin{equation*}
Y(\lambda)=(\phi Y)(\lambda)=0 . \tag{4.6}
\end{equation*}
$$

Its scalar product with $\xi$ implies

$$
\begin{equation*}
\beta g([\phi Y, Y], U)=2 \lambda^{2}-2 \alpha \lambda-2 \tag{4.7}
\end{equation*}
$$

and its scalar product with $U$ gives

$$
\begin{equation*}
\left(\lambda-\frac{\beta^{2}-1}{\alpha}\right) g([\phi Y, Y], U)=2 \beta \lambda . \tag{4.8}
\end{equation*}
$$

From (4.7) and (4.8), we get

$$
\begin{equation*}
(\alpha \lambda+1)\left(\lambda^{2}-\alpha \lambda-1\right)=\beta^{2}\left(\lambda^{2}-1\right) \tag{4.9}
\end{equation*}
$$

From $g\left(\left(\nabla_{\phi U} A\right) Y-\left(\nabla_{Y} A\right) \phi U, \phi Y\right)=0$, we have $\left(\lambda+\frac{1}{\alpha}\right) g\left(\nabla_{Y} \phi U, \phi Y\right)=0$. Then, either $g\left(\nabla_{Y} \phi U, \phi Y\right)=g\left(\nabla_{Y} U, Y\right)=0$, where we have applied (2.3) or $\lambda=-\frac{1}{\alpha}$. In this second case from (4.9), we have $0=\beta^{2}\left(\lambda^{2}-1\right)$. As $\beta \neq 0$, this yields $\lambda^{2}=1$ and $\alpha^{2}=1$. Changing, if necessary, $\xi$ by $-\xi$, we can suppose $\alpha=1$ and then $\lambda=-1$.

The scalar product of $\left(\nabla_{\xi} A\right) Y-\left(\nabla_{Y} A\right) \xi=\phi Y$ and $Y$ gives

$$
\begin{equation*}
\xi(\lambda)-\beta g\left(\nabla_{Y} U, Y\right)=0 \tag{4.10}
\end{equation*}
$$

As either $\lambda=-1$ or $g\left(\nabla_{Y} U, Y\right)=0$, we always have

$$
\begin{equation*}
\xi(\lambda)=0 \tag{4.11}
\end{equation*}
$$

Developing $\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U=-2 \xi$ and taking its scalar product with $\phi U$, we get

$$
\begin{equation*}
\alpha U\left(\frac{1}{\alpha}\right)=\beta^{2} g\left(\nabla_{\phi U} \phi U, U\right) \tag{4.12}
\end{equation*}
$$

The same procedure applied to $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, \phi U\right)=0$ yields

$$
\begin{equation*}
\xi\left(\frac{1}{\alpha}\right)=\beta g\left(\nabla_{\phi U} \phi U, U\right) . \tag{4.13}
\end{equation*}
$$

From (4.12) and (4.13), we obtain

$$
\begin{equation*}
\alpha U(\alpha)=\beta \xi(\alpha) . \tag{4.14}
\end{equation*}
$$

From $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \xi\right)=0, \xi(\beta)=U(\alpha)$ and from (4.14), we have

$$
\begin{equation*}
\beta \xi(\alpha)=\alpha \xi(\beta) \tag{4.15}
\end{equation*}
$$

By derivating (4.9) in the direction of $\xi$ and bearing in mind (4.11) and (4.15), it follows

$$
\begin{equation*}
\left(\lambda\left(\lambda^{2}-\alpha \lambda-1\right)-\lambda(\alpha \lambda+1)\right) \xi(\alpha)=\frac{2 \beta^{2}}{\alpha}\left(\lambda^{2}-1\right) \xi(\alpha) \tag{4.16}
\end{equation*}
$$

If we suppose $\xi(\alpha) \neq 0$ and bear in mind (4.9), from (4.16), we have

$$
\begin{equation*}
\alpha \lambda^{3}-2 \alpha \lambda+2 \lambda^{2}-2=0 . \tag{4.17}
\end{equation*}
$$

Derivating (4.17) in the direction of $\xi$, we obtain $\left(\lambda^{3}-2 \lambda\right) \xi(\alpha)=0$. As we suppose $\xi(\alpha) \neq 0$, we have $\lambda\left(\lambda^{2}-2\right)=0$. If $\lambda=0$ from (4.9), it follows $\beta^{2}=1$ and $\beta$ should be constant. From (4.15), $\xi(\alpha)=0$, and we arrive to a contradiction. Therefore, $\lambda^{2}=2$. From (4.9), we obtain $1-2 \alpha^{2}=\beta^{2}$. By derivating this equality in the direction of $\xi$ and bearing in mind (4.15) and that we suppose $\xi(\alpha) \neq 0$, we get $-2 \alpha^{2}=\beta^{2}$ and we have a new contradiction. This proves

$$
\begin{equation*}
\xi(\alpha)=\xi(\beta)=U(\alpha)=0 . \tag{4.18}
\end{equation*}
$$

The equality $g\left(\left(\nabla_{\xi} A\right) Y-\left(\nabla_{Y} A\right) \xi, \xi\right)=0$ yields

$$
\begin{equation*}
Y(\alpha)=-\beta g\left(\nabla_{\xi} Y, U\right) . \tag{4.19}
\end{equation*}
$$

Analogously, from $g\left(\left(\nabla_{\xi} A\right) Y-g\left(\nabla_{Y} A\right) \xi, U\right)=0$, we obtain

$$
\begin{equation*}
Y(\beta)=\left(\lambda-\frac{\beta^{2}-1}{\alpha}\right) g\left(\nabla_{\xi} Y, U\right) . \tag{4.20}
\end{equation*}
$$

From (4.19) and (4.20), we get

$$
\begin{equation*}
\beta Y(\beta)=\left(\frac{\beta^{2}-1}{\alpha}-\lambda\right) Y(\alpha) . \tag{4.21}
\end{equation*}
$$

As $Y(\lambda)=0$, from (4.9), it follows

$$
\begin{equation*}
\left(\lambda\left(\lambda^{2}-\alpha \lambda-1\right)-\lambda(\alpha \lambda+1)\right) Y(\alpha)=\left(\lambda^{2}-1\right) 2 \beta Y(\beta) \tag{4.22}
\end{equation*}
$$

and from (4.21) and (4.22), if we suppose $Y(\alpha) \neq 0$, we have

$$
\begin{equation*}
\alpha\left(3 \lambda^{2}-2 \alpha \lambda^{2}-4 \lambda\right)=2(\alpha \lambda+1)\left(\lambda^{2}-\alpha \lambda-1\right)-2\left(\lambda^{2}-1\right) . \tag{4.23}
\end{equation*}
$$

Derivating once again in the direction of $Y$ and bearing in mind that we suppose $Y(\alpha) \neq 0$, we obtain $\lambda^{3}=0$, that is, $\lambda=0$ and $\beta^{2}=1$. Therefore, $\beta$ is constant and $Y(\beta)=0$.

From $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, \xi\right)=0$, we have

$$
\begin{equation*}
(\phi U)(\alpha)=\frac{3 \beta}{\alpha}+\alpha \beta+\beta g\left(\nabla_{\xi} U, \phi U\right) . \tag{4.24}
\end{equation*}
$$

And $\beta^{2}=1$ and $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, U\right)=-1$ yield

$$
\begin{equation*}
g\left(\nabla_{\xi} U, \phi U\right)=-\alpha . \tag{4.25}
\end{equation*}
$$

From (4.24) and (4.25), we conclude

$$
\begin{equation*}
(\phi U)(\alpha)=\frac{3 \beta}{\alpha} . \tag{4.26}
\end{equation*}
$$

As $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \phi U\right)=1$, we get

$$
\begin{equation*}
\frac{1}{\alpha} g\left(\nabla_{\xi} U, \phi U\right)-\beta g\left(\nabla_{U} U, \phi U\right)=0 \tag{4.27}
\end{equation*}
$$

and from the Codazzi equation $g\left(\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U, U\right)=0$, it follows

$$
\begin{equation*}
g\left(\nabla_{U} U, \phi U\right)=2 \beta . \tag{4.28}
\end{equation*}
$$

From (4.27) and (4.28), bearing in mind that $\beta^{2}=1$, we have

$$
\begin{equation*}
g\left(\nabla_{\xi} U, \phi U\right)=2 \alpha \tag{4.29}
\end{equation*}
$$

Now, from (4.27) and (4.29), $\alpha$ should vanish. As this is a contradiction, we arrive to

$$
\begin{equation*}
Y(\alpha)=Y(\beta)=0 \tag{4.30}
\end{equation*}
$$

By linearity, we have $X(\alpha)=X(\beta)=0$ for any $X \in \mathbb{D}_{U}$.
The Codazzi equation $g\left(\left(\nabla_{\xi} A\right) \phi U-\left(\nabla_{\phi U} A\right) \xi, U\right)=-1$ yields

$$
\begin{equation*}
(\phi U)(\beta)=\frac{\beta^{2}-1}{\alpha^{2}}+\beta^{2}+\frac{\beta^{2}}{\alpha} g\left(\nabla_{\xi} U, \phi U\right) . \tag{4.31}
\end{equation*}
$$

As $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, \phi U\right)=1$, we have

$$
\begin{equation*}
\frac{\beta^{2}}{\alpha} g\left(\nabla_{\xi} U, \phi U\right)-\beta g\left(\nabla_{U} U, \phi U\right)=\frac{\beta^{2}-1}{\alpha^{2}} \tag{4.32}
\end{equation*}
$$

and $g\left(\left(\nabla_{U} A\right) \phi U-\left(\nabla_{\phi U} A\right) U, U\right)=0$ shows

$$
\begin{equation*}
\beta g\left(\nabla_{U} U, \phi U\right)+\beta^{2}-3-2(\phi U)(\beta)-\frac{\beta^{2}-1}{\alpha \beta}(\phi U)(\alpha)=0 . \tag{4.33}
\end{equation*}
$$

From (4.31), (4.32), and (4.33), we have

$$
\begin{equation*}
\beta g\left(\nabla_{U} U \phi U\right)-\frac{\beta^{2}-1}{\alpha} g\left(\nabla_{\xi} U, \phi U\right)+\frac{\beta^{2}-1}{\alpha^{2}}-4=0 . \tag{4.34}
\end{equation*}
$$

Now, from (4.33) and (4.34), it follows $g\left(\nabla_{\xi} U, \phi U\right)=-4 \alpha$ and $g\left(\nabla_{U} U, \phi U\right)=\frac{1-\beta^{2}}{\alpha^{2} \beta}-$ $4 \beta$. Then, from (4.24) and (4.32), we get

$$
\begin{equation*}
(\phi U)(\alpha)=3 \beta\left(\frac{1-\alpha^{2}}{\alpha}\right) \tag{4.35}
\end{equation*}
$$

and

$$
\begin{equation*}
(\phi U)(\beta)=-3 \beta^{2}+\frac{\beta^{2}-1}{\alpha^{2}} . \tag{4.36}
\end{equation*}
$$

From all the facts we have until now, we obtain $\operatorname{grad}(\alpha)=\omega \phi U$, where $\omega=$ $3 \beta\left(\frac{1-\alpha^{2}}{\alpha}\right)$. As $g\left(\nabla_{X} \operatorname{grad}(\alpha), Y\right)=g\left(\nabla_{Y} \operatorname{grad}(\alpha), X\right)$ for any $X, Y \in T M$, we get
$X(\omega) g(\phi U, Y)-Y(\omega) g(\phi U, X)+\omega\left(g\left(\nabla_{X} \phi U, Y\right)-g\left(\nabla_{Y} \phi U, X\right)\right)=0$. Taking $Y=\xi$, this yields $\omega\left(g\left(\nabla_{X} \phi U, \xi\right)-g\left(\nabla_{\xi} \phi U, X\right)\right)=0$ for any $X \in T M$. Thus, either $\omega=0$ or $g\left(\nabla_{X} \phi U, \xi\right)=g\left(\nabla_{\xi} \phi U, X\right)$ for any $X \in T M$. If we take $X=U$, we have $-g(U, A U)=g\left(\nabla_{\xi} \phi U, U\right)$. Then, $4 \alpha^{2}+\beta^{2}=1$. This yields $4 \alpha(\phi U)(\alpha)+\beta(\phi U)(\beta)=0$. From (4.35) and (4.36), we have $9 \alpha^{2}+\beta^{2}=1$. Therefore, $\alpha=0$, which is impossible. So we have $\omega=0$ and $\alpha^{2}=1$. From (4.35) $(\phi U)(\alpha)=0$ and from $(4.36)(\phi U)(\beta)=-\left(2 \beta^{2}+1\right)$. Then, from (4.18) and the fact that $g\left(\left(\nabla_{\xi} A\right) U-\left(\nabla_{U} A\right) \xi, U\right)=0$, we have $U(\beta)=0$ and then $\operatorname{grad}(\beta)=-\left(2 \beta^{2}+1\right) \phi U$.

Applying the same reasoning to $\operatorname{grad}(\beta),-\left(1+2 \beta^{2}\right)\left(g\left(\nabla_{X} \phi U, \xi\right)-g\left(\nabla_{\xi} \phi U, X\right)\right)=0$ for any $X \in T M$. This yields $g\left(\nabla_{X} \phi U, \xi\right)=g\left(\nabla_{\xi} \phi U, X\right)$ for any $X \in T M$. Taking $X=U$, it follows $4 \alpha^{2}+\beta^{2}=1$ and being $\alpha^{2}=1, \beta^{2}=-3$, which is impossible and proves that $M$ must be Hopf.

If $M$ is Hopf with $A \xi=\alpha \xi$, from (4.1), we get $\phi R_{\xi}=R_{\xi} \phi$. Let $Y \in \mathbb{D}$ a unit vector field such that $A Y=\lambda Y$. Therefore, $\alpha \lambda Y=\alpha A \phi Y$. Then, either $\alpha=0$ and $M$ is locally congruent to a tube of radius $\frac{\pi}{4}$ around a complex submanifold of $\mathbb{C} P^{m}$, see [2], or $A \phi=\phi A$ and from Theorem $2.1, M$ is locally congruent to a type $(A)$ real hypersurface.

It is very easy to see that these real hypersurfaces satisfy (4.1), and we finish the proof.

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