

Erratum to: Dynamic hysteresis control of lift on a pitching wing

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In the original publication of the article, a term is missing in Eq. 5. The correct version of Eq. 5 is

$$\tau_1 \frac{dX}{dt} + X = X_0(\alpha_s) + X'_0(\alpha_s) \cdot (u - \tau_2 \dot{u}) \quad (5)$$

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