# Local Kesten-McKay Law for Random Regular Graphs 

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#### Abstract

We study the adjacency matrices of random $d$-regular graphs with large but fixed degree $d$. In the bulk of the spectrum $[-2 \sqrt{d-1}+\varepsilon, 2 \sqrt{d-1}-\varepsilon]$ down to the optimal spectral scale, we prove that the Green's functions can be approximated by those of certain infinite tree-like (few cycles) graphs that depend only on the local structure of the original graphs. This result implies that the Kesten-McKay law holds for the spectral density down to the smallest scale and the complete delocalization of bulk eigenvectors. Our method is based on estimating the Green's function of the adjacency matrices and a resampling of the boundary edges of large balls in the graphs.


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## 1. Main Results I: Spectral Density and Eigenvectors

1.1. Introduction. Random regular graphs with fixed degree $d$ are fundamental models of sparse random graphs and they arise naturally in many different contexts. The spectral properties of their adjacency matrices are of particular interest in computer science, combinatorics, and statistical physics. The relevant topics include the theory of expanders (see e.g. [71]), quantum chaos (see e.g. [72]), and graph $\zeta$-functions (see e.g. [76]). There has been significant progress in the understanding of the spectra of (random and deterministic) regular graphs. For fixed degree these results generally concern properties of eigenvalues and eigenvectors near the macroscopic scale, and their proofs use the local tree-like structure of these graphs as an important input. On the other hand, dense regular graphs belong to the random matrix universality class and their spectral properties are known to resemble those of Wigner matrices. In this paper, we introduce an approach that allows the Green's function method of random matrix theory to make use of the local tree-like structure of the random regular graph, while it also captures key random matrix behavior.

Throughout the paper, $A=A(\mathcal{G})$ is the adjacency matrix of a (uniform) random $d$-regular graph $\mathcal{G}$ on $N$ vertices. Thus $A$ is uniformly chosen among all symmetric $N \times N$ matrices with entries in $\{0,1\}$ with $\sum_{j} A_{i j}=d$ and $A_{i i}=0$ for all $i$. Note that $A$ has the trivial constant eigenvector with eigenvalue $d$. We also use the rescaled adjacency matrix $H=A / \sqrt{d-1}$, and we denote the set of (simple) $d$-regular graphs on $N$ vertices by $\mathrm{G}_{N, d}$.

Below we first discuss some known consequences of the tree-like and of the random matrix-like structure.

Tree-like structure. It is well known that most regular graphs of a fixed degree $d \geqslant 3$ are locally tree-like in the sense that: (i) for any fixed radius $R$ (and actually for $R=$ $c \log _{d-1} N$ ), the radius- $R$ neighborhoods of almost all vertices are the same as those in the infinite $d$-regular tree; (ii) the $R$-neighborhoods of all vertices have bounded excess, which is the smallest number of edges that must be removed to yield a tree; see e.g. Proposition 4.1 below. The tree-like structure is important for the following results, valid in general for deterministic graphs and in some cases requiring randomness as well.

1. For regular graphs with locally tree-like structure, the macroscopic spectral density of $A$ converges to the Kesten - McKay law [53,63], characterized by the density $\frac{d}{d^{2}-x^{2}} \frac{1}{2 \pi} \sqrt{\left[4(d-1)-x^{2}\right]_{+}}$. For random regular graphs, the Kesten-McKay law was established on spectral scales $(\log N)^{-c}[15,32,44]$ by using the fact that the locally tree-like structure holds with high probability in neighborhoods of radius $\Omega(\log N)$.
2. For regular graphs with locally tree-like structure, the eigenvectors $v$ of $A$ are weakly delocalized: their entries are uniformly bounded by $(\log N)^{-c}\|v\|_{2}[24,32,44]$ and their $\ell^{2}$-mass cannot concentrate on a small set [24]. If, in addition, the graphs are expanders, the eigenvectors of $A$ also satisfy the quantum ergodicity property [14, 15,25].
3. For random regular graphs using the locally tree-like structure as important input, for any fixed $\varepsilon>0$, the nontrivial eigenvalues of $A$ are contained in $[-2 \sqrt{d-1}-$
$\varepsilon, 2 \sqrt{d-1}+\varepsilon]$. This was conjectured in [13] and proved in [42]; see also [20,70] for recent alternative arguments. It was also shown that the scale $\varepsilon$ can actually be taken to be $(\log N)^{-c}$ in [20].

Random matrix-like structure. For random matrices of Wigner type, precise estimates on the spectral properties of these matrices were proved (see e.g., [38,39,56,74]):

1. The spectral density in the bulk is given by the semicircle law on all scales larger than $N^{-1}$.
2. The eigenvectors are uniformly bounded in $\ell^{\infty}$-norm by $N^{-1 / 2}$ (up to logarithmic correction).
3. The extremal eigenvalues are concentrated on scale $N^{-2 / 3}$.
4. Both bulk and edge universality holds; in particular, the distributions of the extremal eigenvalues are the same as those of Gaussian matrix ensembles (Tracy-Widom distributions).
The first three properties usually can be proved via estimates on the Green's function; the proofs of universality involve Dyson Brownian Motion or other comparison methods (see [39] for a review).

For random $d$-regular graphs with $d \in\left[N^{\varepsilon}, N^{2 / 3-\varepsilon}\right]$, properties (i), (ii), and also bulk universality were proved in $[18,19]$ [the lower bound on $d$ can be relaxed to $(\log N)^{4}$ for properties (i) and (ii)]. Simulations indicate that (i)-(iv) hold for random regular graphs of fixed degree [46,50,67,68].

In this paper, we consider random regular graphs of large but fixed degree $d$. One of our key ideas to prove the properties (i) and (ii) is to use switchings to resample the boundaries of large balls (see Sect. 7). This operation preserves the local tree-like structure and it also captures sufficient global structure in random regular graphs. This resampling generalizes and adds a geometric component to the local resampling method we introduced with Knowles in [19] for random regular graphs with $d \gg \log N$. The idea of using some form of switchings in studying random regular graphs goes back at least to [64], where it was used in the enumeration of such graphs; see also [80] for further applications in enumeration. Finally, to analyze the propagation of the boundary effect to the interior of the ball in the Green's function, we explicitly compute the Green's function of the tree-like graphs.

Notation. For two quantities $X$ and $Y$ depending on $N$, we use the notations $X=O \leqslant(Y)$ if $Y$ is positive and $|X| \leqslant Y ; X=O(Y)$ if $X, Y$ are positive and there exists some universal constant $C$ such that $X \leqslant C Y ; X=o(Y), X \ll Y$ or $Y \gg X$ if $Y$ is positive and $\lim _{N \rightarrow \infty} X / Y=0 ; X=\Omega(Y)$ if $X, Y$ are positive and $\liminf _{N \rightarrow \infty} X / Y>0$. We write $\llbracket a, b \rrbracket=[a, b] \cap \mathbb{Z}$ and $\llbracket N \rrbracket=\llbracket 1, N \rrbracket$.
1.2. Spectral density and eigenvector delocalization. Our main result, Theorem 2.4, is a precise estimate on the local profile of the Green's function down to the smallest possible spectral scales, with high probability. Its statement requires several definitions, and we therefore only state it in Sect. 2. In the remainder of this section, we state some direct consequences of Theorem 2.4, which can be stated in elementary terms. The proofs of these corollaries are given in Sect. 2.4.
1.2.1. Spectral density It is well-known that, with high probability, the spectral measure of the rescaled adjacency matrix $H=A / \sqrt{d-1}$ converges weakly to the rescaled Kesten-McKay law with density given by

$$
\begin{equation*}
\rho_{d}(x)=\left(1+\frac{1}{d-1}-\frac{x^{2}}{d}\right)^{-1} \frac{\sqrt{\left[4-x^{2}\right]_{+}}}{2 \pi} . \tag{1.1}
\end{equation*}
$$

This convergence can be expressed as $m(z)=m_{d}(z)+o(1)$ for any $z \in \mathbb{C}_{+}$independent of $N$, where $m_{d}(z)$ is the Stieltjes transform of $\rho_{d}$, and $m(z)$ is the Stieltjes transform of the empirical spectral measure of $H$,

$$
\begin{equation*}
m_{d}(z)=\int \frac{1}{\lambda-z} \rho_{d}(\lambda) d \lambda, \quad m(z)=\frac{1}{N} \sum_{j=1}^{N} \frac{1}{\lambda_{j}-z} \tag{1.2}
\end{equation*}
$$

and $\mathbb{C}_{+}=\{z \in \mathbb{C}: \operatorname{Im}[z]>0\}$ is the upper half-plane. The imaginary part of the spectral parameter $z \in \mathbb{C}_{+}$determines the scale of the convergence. In particular, the convergence $m(z) \rightarrow m_{d}(z)$ for all fixed $z$ corresponds to the convergence on the macroscopic scale, i.e., for intervals containing order $N$ eigenvalues. The following theorem gives the convergence on the optimal mesoscopic scale $\operatorname{Im}[z] \gg 1 / N$, away from the spectral edges at $\pm 2$.

Theorem 1.1 (Local Kesten-McKay Law). Fix $\alpha>4, \omega \geqslant 8$ and $\sqrt{d-1} \geqslant(\omega+$ 1) $2^{2 \omega+45}$. Then with probability $1-o\left(N^{-\omega+8}\right)$ with respect to the uniform measure on $\mathrm{G}_{N, d}$,

$$
\begin{equation*}
\left|m(z)-m_{d}(z)\right|=O(\log N)^{-\alpha} \tag{1.3}
\end{equation*}
$$

uniformly for

$$
\begin{equation*}
z \in \mathcal{D}:=\left\{z \in \mathbb{C}_{+}: \operatorname{Im}[z] \geqslant \frac{(\log N)^{48 \alpha+1}}{N}, \quad|z \pm 2| \geqslant(\log N)^{-\alpha / 2+1}\right\} \tag{1.4}
\end{equation*}
$$

While Theorem 1.1 shows that the spectral density (or its Stieltjes transform, which is the trace of the Green's function) does concentrate, the individual entries of the Green's function of the random regular graph with bounded degree do not concentrate; see also Remark 2.5 below. This is different from the typical examples in random matrix theory, and it is one of the reasons that the fixed degree graphs require a more delicate analysis. For example, the random regular graph contains a triangle with probability uniformly bounded from below. For graphs with bounded degree, triangles and other short cycles have a strong local influence on the elements of the Green's function, and thus the spectrum.

The spectral density of random regular graphs at scales much larger than the typical eigenvalue spacing has been studied in $[15,32,44,78]$. Results for spectral density near the typical eigenvalue spacing only appeared very recently [19], where the semicircle law down to the optimal mesoscopic scale was established for degree $d \in\left[\xi^{4}, N^{2 / 3} \xi^{-2 / 3}\right]$ with $\xi=(\log N)^{2}$. The methods of the current paper could be extended from fixed $d$ to $d$ growing slowly with $N$, for example to the range $d_{0} \leqslant d \leqslant(\log N)^{4}$ beyond which the results of [19] apply. Thus the results of this paper complement those of [19]. For simplicity, we restrict this paper to the most interesting case of fixed degree $d$.
1.2.2. Eigenvectors Theorem 2.4 implies delocalization estimates of the eigenvectors in the bulk of the spectrum.


Fig. 1. Theorem 1.2 shows that a random $d$-regular graph has only completely delocalized eigenvectors with probability $1-o\left(N^{-\omega+8}\right)$. On the other hand, it is not difficult to show that a random $d$-regular graph has localized eigenvectors with probability $\Omega\left(N^{-d+2}\right)$. For example, a random 3-regular graph contains the subgraph shown on the left with probability $\Omega\left(N^{-1}\right)$. For comparison, also notice that an Erdős-Rényi graph with finite average degree contains localized eigenvectors with probability $\Omega(1)$; see the right figure

Theorem 1.2 (Eigenvector delocalization). Fix $\alpha>4, \omega \geqslant 8$ and $\sqrt{d-1} \geqslant(\omega+$ 1) $2^{2 \omega+45}$. Then, with probability $1-o\left(N^{-\omega+8}\right)$ with respect to the uniform measure on $\mathrm{G}_{N, d}$, the eigenvectors $v$ of $H$ whose eigenvalue $\lambda$ obeys $|\lambda \pm 2| \geqslant(\log N)^{1-\alpha / 2}$ are simultaneously delocalized:

$$
\begin{equation*}
\|v\|_{\infty} \leqslant \frac{\sqrt{2}(\log N)^{24 \alpha+1 / 2}}{\sqrt{N}}\|v\|_{2} \tag{1.5}
\end{equation*}
$$

Theorem 1.2 shows that with probability $1-o\left(N^{-\omega+8}\right)$, the eigenvectors are completely delocalized. On the other hand, it is easy to see that, with probability $\Omega\left(N^{-d+2}\right)$, the random $d$-regular graph has a localized eigenvector (see Fig. 1). In particular, (1.5) cannot hold with probability higher than polynomial in $1 / N$. Moreover, the ErdősRényi graph with finite average degree $d$ has localized eigenvectors with probability $\Omega(1)$. Thus (1.5) with probability tending to 0 is false for the Erdős-Rényi graph with finite average degree $d$.

The delocalization of eigenvectors of (random and deterministic) regular graphs has been studied in [14, 15, 24, 25,32,44,57,78] (see also [69] for a survey of results on eigenvector delocalization in random matrices). Our result implies the optimal bound of order $1 / \sqrt{N}$ (up to logarithmic corrections) on the $\ell^{\infty}$-norms of the (bulk) eigenvectors of random regular graphs.

For (deterministic) locally tree-like regular graphs, it has been proved that the eigenvectors $v$ are weakly delocalized in the sense that $\|v\|_{\infty} \leqslant(\log N)^{-c}\|v\|_{2}[24,32,44]$, and that eigenvectors cannot concentrate on a small set, in the sense that any vertex set $\mathbb{V} \subset \llbracket N \rrbracket$ with $\sum_{i \in \mathbb{V}}\left|v_{i}\right|^{2} \geqslant \varepsilon\|v\|_{2}$ must have at least $N^{c(\varepsilon)}$ elements [24]. Moreover, for (deterministic) locally tree-like regular expander graphs, it was proved that the eigenvectors $v$ satisfy a quantum ergodicity property: for all $a \in \mathbb{R}^{N}$ with $\|a\|_{\infty} \leqslant 1$ and $\sum_{i} a_{i}=0$, averages of $\left|\sum_{i} a_{i} v_{i}^{2}\right|^{2}$ over many eigenvectors $v$ are close to $0[14,15,25]$.

Theorem 1.2 and the exchangeability of the random regular graph also imply the following isotropic version of Theorem 1.2, implying that the eigenvectors are delocalized not only in the standard basis, but in any deterministic orthonormal basis. In addition, a probabilistic version of the quantum unique ergodicity property (QUE) holds for these graphs. Note that estimates (1.7), (1.8) are not uniform over all $q$ or $\mathbb{X}$. Therefore $q$ and $\mathbb{X}$ cannot be chosen depending on the random graph.

Corollary 1.3. Under the assumptions of Theorem 1.2, the following estimates hold with probability $1-o\left(N^{-\omega+8}\right)$ with respect to the uniform measure on $\mathrm{G}_{N, d}$. For any deterministic $q^{1}, \ldots, q^{M} \in \mathbb{R}^{N}$ with $\left\|q^{m}\right\|_{2}=1$ and $\sum_{i} q_{i}^{m}=0(M$ can depend on $N$ ), and for all normalized eigenvectors $v^{k}$ whose eigenvalue $\lambda_{k}$ obeys $\left|\lambda_{k} \pm 2\right| \geqslant$ $(\log N)^{1-\alpha / 2}$, we have:

1. (Isotropic delocalization) The eigenvectors are delocalized in directions $q^{m}$ :

$$
\begin{equation*}
\max _{k, m}\left|\left\langle q^{m}, v^{k}\right\rangle\right| \leqslant \frac{(\log N)^{24 \alpha+1 / 2}(\log N+\log M)^{2}}{\sqrt{N}} \tag{1.6}
\end{equation*}
$$

2. (Probabilistic QUE) The eigenvector densities are flat with respect to the test vectors $q^{m}$ :

$$
\begin{equation*}
\max _{k, m}\left|\sum_{i=1}^{N} q_{i}^{m}\left(v_{i}^{k}\right)^{2}\right| \leqslant \frac{(\log N)^{48 \alpha+1}(\log N+\log M)^{2}}{N} \tag{1.7}
\end{equation*}
$$

In particular, with probability $1-o\left(N^{-\omega+8}\right)$, simultaneously for any deterministic index sets $\mathbb{X}^{1}, \ldots, \mathbb{X}^{M} \subset \llbracket N \rrbracket$, and all eigenvectors $v^{k}$ with $\left|\lambda_{k} \pm 2\right| \geqslant(\log N)^{1-\alpha / 2}$,

$$
\begin{equation*}
\sum_{i \in \mathbb{X}^{m}}\left(v_{i}^{k}\right)^{2}=\frac{\left|\mathbb{X}^{m}\right|}{N}+O\left(\frac{(\log N)^{48 \alpha+1}(\log N+\log M)^{2} \sqrt{\left|\mathbb{X}^{m}\right|}}{N}\right) \tag{1.8}
\end{equation*}
$$

The proof of Corollary 1.3 makes strong use of the exchangeability of the random regular graph. On the other hand, the proof of Theorem 2.4, and its consequences Theorem 1.1 and Theorem 1.2, do not exploit exchangeability in a significant way, and we believe that the method could be extended, for example, to graphs with more general degree sequences.
1.3. Related results. Macroscopic eigenvalue statistics for random regular graphs of fixed degree have been studied using the techniques of Poisson approximation of short cycles $[31,52$ ] and (non-rigorously) using the replica method [66]. These results show that the macroscopic eigenvalue statistics for random regular graphs of fixed degree are different from those of a Gaussian matrix. However, this is not predicted to be the case for the local eigenvalue statistics. Spectral properties of regular directed graphs have also been studied recently [27,28].

The second largest eigenvalue $\lambda_{2}$ of regular graphs is of particular interest. For the case of fixed degree, see in particular [20,29,42,43,70]. The conjecture that the distribution of the second largest eigenvalue on scale $N^{-2 / 3}$ is the same as that of the largest eigenvalue of the Gaussian Orthogonal Ensemble [71] would imply that slightly more than half of all regular graphs are Ramanujan graphs, namely $d$-regular graphs with $\lambda_{2} \leqslant 2 \sqrt{d-1}$ (for explicit and probabilistic constructions of sequences of Ramanujan graphs, see [59,61,62]). The spectrum of random regular graphs has also received interest from the study of $\zeta$-functions, as it can be related by an exact relationship to the poles of the Ihara $\zeta$-function of regular graphs [17,49]; see also [76,77].

Another interesting direction related to the spectral properties of random regular graphs concerns the phase diagram of the Anderson model. The model was originally defined on the square lattice $\mathbb{Z}^{d}$, but only limited progress was made for the delocalization problem in this setting. A simplified model on the infinite regular tree (Bethe lattice) is
well-understood [2-10,54]; see also [11] for a review. At large disorder, it is known that the Anderson model on the random regular graph exhibits Poisson statistics [45]. The eigenstates of the Anderson model on the random regular graph have also been studied in connection with many-body localization [30,60].

In random matrix theory, the local spectral statistics of the generalized Wigner matrices are well understood; see in particular [21,34,36-41,51,74]. Many results on local eigenvalue statistics also exist for Erdős-Rényi random graphs, in particular [34,35, 47,48]; the latter results apply down to logarithmically small average degrees. Similar results have also been proved for more general degree distributions [1,12]. However, these types of results are false for the Erdős-Rényi graph with bounded average degree. For a review of other results for discrete random matrices, see also [79]. For the eigenvectors of random regular graphs with $d \in\left[N^{\varepsilon}, N^{2 / 3-\varepsilon}\right]$, the asymptotic normality was proved in [22]; see also the prior results for generalized Wigner matrices [23,55,75]. For random regular graphs of fixed degree, a Gaussian wave correlation structure for the eigenvectors was predicted in [33] and partially confirmed in [16].

## 2. Main Results II: Local Approximation of the Green's Function

2.1. Graphs. The main result of this paper, Theorem 2.4 below, is a precise local approximation result of the Green's function. It in particular implies the results stated in Sect. 1. To state it we require several definitions, which we give now.

Graphs, adjacency matrices, Green's functions. Throughout this paper, graphs $\mathcal{G}$ are always simple (i.e., have no self-loops or multiple edges) and they have vertex degrees at most $d$ (non-regular graphs are also used). The geodesic distance (length of the shortest path between two vertices) in the graph $\mathcal{G}$ is denoted by $\operatorname{dist}_{\mathcal{G}}(\cdot, \cdot)$. For any graph $\mathcal{G}$, the adjacency matrix is the (possibly infinite) symmetric matrix $A$ indexed by the vertices of the graph, with $A_{i j}=A_{j i}=1$ if there is an edge between $i$ and $j$, and $A_{i j}=0$ otherwise. Throughout the paper, we denote the normalized adjacency matrix by $H=A / \sqrt{d-1}$, where the normalization by $1 / \sqrt{d-1}$ is chosen independently of the actual degrees of the graph. Moreover, we denote the (unnormalized) adjacency matrix of a directed edge $(i, j)$ by $e_{i j}$, i.e. $\left(e_{i j}\right)_{k l}=\delta_{i k} \delta_{j l}$. The Green's function of a graph $\mathcal{G}$ is the unique matrix $G=G(z)$ defined by $G(H-z)=I$ for $z \in \mathbb{C}_{+}$, where $\mathbb{C}_{+}$is the upper half plane.

In Appendix B, several well-known properties of Green's function are summarized; they will be used throughout the paper. The Green's function $G(z)$ encodes all spectral information of $H$ (and thus of $A$ ). In particular, the spectral resolution is given by $\eta=\operatorname{Im}[z]$ : the macroscopic behavior corresponds to $\eta$ of order 1, the mesoscopic behavior to $1 / N \ll \eta \ll 1$, and the microscopic behavior of individual eigenvalues corresponds to $\eta$ below $1 / N$.

Subsets and Subgraphs. Let $\mathcal{G}$ be a graph, and denote the set of its edges by the same symbol $\mathcal{G}$ and its vertices by $\mathbb{G}$. More generally, throughout the paper, we use blackboard bold letters for set or subsets of vertices, and calligraphic letters for graphs or subgraphs. For any subset $\mathbb{X} \subset \mathbb{G}$, we define the graph $\mathcal{G}^{(\mathbb{X})}$ by removing the vertices $\mathbb{X}$ and edges adjacent to $\mathbb{X}$ from $\mathcal{G}$, i.e., the adjacency matrix of $\mathcal{G}^{(\mathbb{X})}$ is the restriction of that of $\mathcal{G}$ to $\mathbb{G} \backslash \mathbb{X}$. We write $G^{(\mathbb{X})}$ for the Green's function of $\mathcal{G}^{(\mathbb{X})}$. For any subgraph $\mathcal{X} \subset \mathcal{G}$, we denote by $\partial \mathcal{X}=\left\{v \in \mathbb{G}: \operatorname{dist}_{\mathcal{G}}(v, \mathcal{X})=1\right\}$ the vertex boundary of $\mathcal{X}$ in $\mathcal{G}$, and by $\partial_{E} \mathcal{X}=\{e \in \mathcal{G}: e$ is adjacent to $\mathcal{X}$ but $e \notin \mathcal{X}\}$ the edge boundary of $\mathcal{X}$ in $\mathcal{G}$. Moreover, for any subset $\mathbb{X} \subset \mathbb{G}$, we denote by $\partial \mathbb{X}$ and $\partial_{E} \mathbb{X}$ the vertex and edge boundaries of the subgraph induced by $\mathcal{G}$ on $\mathbb{X}$.

Neighborhoods. Given a subset $\mathbb{X}$ of the vertex set of a graph $\mathcal{G}$ and an integer $r>0$, we denote the $r$-neighborhood of $\mathbb{X}$ in $\mathcal{G}$ by $\mathcal{B}_{r}(\mathbb{X}, \mathcal{G})$, i.e., it is the subgraph induced by $\mathcal{G}$ on the set $\mathbb{B}_{r}(\mathbb{X}, \mathcal{G})=\left\{j \in \mathcal{G}: \operatorname{dist}_{\mathcal{G}}(\mathbb{X}, j) \leqslant r\right\}$. In particular $\mathcal{B}_{r}(i, \mathcal{G})$ is the radius- $r$ neighborhood of the vertex $i$.

Moreover, given vertices $i, j$ in $\mathcal{G}$ and $r>0$, we denote by $\mathcal{E}_{r}(i, j, \mathcal{G})$ the smallest subgraph of $\mathcal{G}$ that contains all paths of length at most $r$ between $i$ and $j$. Namely,

$$
\begin{align*}
\mathcal{E}_{r}(i, j, \mathcal{G}):=\{e \in \mathcal{G}: & \text { there exists a path from } i \text { to } j \\
& \text { of length at most } r \text { containing } e\} . \tag{2.1}
\end{align*}
$$

Notice that $\mathcal{E}_{2 r}(i, j, \mathcal{G}) \subset \mathcal{B}_{r}(i, \mathcal{G}) \cup \mathcal{B}_{r}(j, \mathcal{G})$.
Trees. The infinite $d$-regular tree is the unique (up to isometry) infinite connected $d$ regular graph without cycles, and is denoted by $\mathcal{Y}$. The rooted $d$-regular tree with root degree $c$ is the unique (up to isometry) infinite connected graph that is $d$-regular at every vertex except for a distinguished root vertex $o$, which has degree $c$.
2.2. Tree extension. The local approximation of the Green's function of a graph will be defined in terms of the tree extension, defined next.

Definition 2.1 (Deficitfunction). Given a graph $\mathcal{G}$ with vertex set $\mathbb{G}$ and degrees bounded by $d$, a deficit function for $\mathcal{G}$ is a function $g: \mathbb{G} \rightarrow \llbracket 0, d \rrbracket$ satisfying $\operatorname{deg}_{\mathcal{G}}(v) \leqslant d-g(v)$ for all vertices $v \in \mathbb{G}$. We call a vertex $v \in \mathbb{G}$ extensible if $\operatorname{deg}_{\mathcal{G}}(v)<d-g(v)$.

Definition 2.2 (Tree extension). Let $\mathcal{G}_{0}$ be a finite graph with deficit function $g$.

1. The tree extension (abbreviated TE ) of $\mathcal{G}_{0}$ is the (possibly infinite) graph $\mathrm{TE}\left(\mathcal{G}_{0}\right)$ defined by attaching to any extensible vertex $v$ in $\mathcal{G}_{0}$ a rooted $d$-regular tree with root degree $d-g(v)-\operatorname{deg}_{\mathcal{G}_{0}}(v)$.
2. The Green's function of $\mathcal{G}_{0}$ with tree extension, denoted $P\left(\mathcal{G}_{0}\right)$, is the Green's function of the (possibly infinite) graph $\operatorname{TE}\left(\mathcal{G}_{0}\right)$.

See Fig. 2 for an illustration of the tree extension. In our main result, stated in Sect. 2.3, we approximate the Green's function of a regular graph at vertices $i, j$ by that of the tree extension of a neighbourhood of $i, j$. This requires specification of a deficit function, which we will usually do using the following conventions for deficit functions, assumed throughout the paper.

Conventions for deficit functions. Throughout this paper, all graphs $\mathcal{G}$ are going to be equipped with a deficit function $g$. The interpretation of the deficit function $g(v)$ is that it measures the difference of the actual to the desired degree of the vertex $v$. We use the following conventions for deficit functions.

- If the deficit function of $\mathcal{G}$ is not specified explicitly, it is given by $g(v)=d-\operatorname{deg}_{\mathcal{G}}(v)$. Thus no vertex is extensible and the tree extension of $\mathcal{G}$ is trivial: $\mathcal{G}=\mathrm{TE}(\mathcal{G})$.
- If $\mathbb{X}$ is a subset of the vertices of $\mathcal{G}$, and $g$ is the deficit function of $\mathcal{G}$, then the deficit function $g^{\prime}$ of $\mathcal{G}^{(\mathbb{X})}$ is given by $g^{\prime}(v)=g+\operatorname{deg}_{\mathcal{G}}(v)-\operatorname{deg}_{\mathcal{G}^{(\mathbb{X})}}(v)$, unless specified explicitly.
Thus when removing the edges incident to $\mathbb{X}$ from $\mathcal{G}$, these are also absent in the tree extension.


Fig. 2. The left figure illustrates a finite graph $\mathcal{G}_{0}$; its extensible vertices are shown as grey circles. The right figure shows the tree extension $\operatorname{TE}\left(\mathcal{G}_{0}\right)$, in which a rooted tree (darkly shaded) is attached to every extensible vertex

- If $\mathcal{H} \subset \mathcal{G}$ is a subgraph (which was not obtained as $\mathcal{G}^{(\mathbb{X})}$ for some set $\mathbb{X}$ ), then the deficit function of $\mathcal{H}$ is given by the restriction of the deficit function of $\mathcal{G}$ on $\mathcal{H}$, unless specified explicitly.
Thus any vertex $v$ in $\mathcal{H} \subset \mathcal{G}$ has the same degree in the tree extension $\operatorname{TE}(\mathcal{H})$ as in $\mathrm{TE}(\mathcal{G})$.

The above conventions are illustrated in Fig. 3. In particular, in the case that $\mathcal{G}$ is a $d$-regular graph, the deficit function is always $g \equiv 0$, so that $\operatorname{TE}(\mathcal{G})=\mathcal{G}$. Moreover, by our conventions, the tree extension of a subgraph $\mathcal{H} \subset \mathcal{G}$ is again a $d$-regular graph.

Definition 2.3. Given an integer $r>0$, we call $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ the localized Green's function of $\mathcal{G}$ at vertices $i, j$.

Thus the localized Green's functions at $i, j$ is the Green's function of a graph that itself depends on a small neighborhood of $i, j$. However, the dependence of the graph on $i, j$ is weak, in the sense that, up to a small error, the graph $\mathcal{E}_{r}(i, j, \mathcal{G})$ could be replaced by any neighborhood of $i, j$ that is not too small and not too large; see Proposition 5.2 and Remark 5.3.

In our main result Theorem 2.4, we will show that the Green's function $G_{i j}(\mathcal{G})$ can be approximated by the localized Green's function $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$. To interpret this result, we note the following elementary properties of the localized Green's function.

- If $\operatorname{dist}(i, j)>r$, then $\mathcal{E}_{r}(i, j, \mathcal{G})$ is the empty graph; thus $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)=0$.
- If $\mathcal{E}_{r}(i, j, \mathcal{G})$ has no cycles (thus it is a tree), then $\operatorname{TE}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ is an infinite tree. In particular, if $\mathcal{G}$ is $d$-regular, then $\operatorname{TE}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ is the infinite $d$-regular tree $\mathcal{Y}$, and therefore $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)=G_{i j}(\mathcal{Y}, z)$. By a straightforward calculation (see Sect. 5), it then follows that

$$
\begin{equation*}
P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)=G_{i j}(\mathcal{Y}, z)=m_{d}(z)\left(-\frac{m_{s c}(z)}{\sqrt{d-1}}\right)^{\operatorname{dist}_{\mathcal{Y}}(i, j)} \tag{2.2}
\end{equation*}
$$

where $m_{d}$ and $m_{s c}$ are the Stieltjes transforms of the Kesten-McKay and semicircle laws; see (2.3) below.


Fig. 3. Given a graph $\mathcal{G}$ (with the standard deficit function $g=d-\operatorname{deg}_{\mathcal{G}}$ ), the top figure illustrates a subgraph $\mathcal{H} \subset \mathcal{G}$, which by our conventions inherits its deficit function from $\mathcal{G}$ by restriction. Thus all vertices in $\mathcal{H}$ have the same degrees in the tree extension $\operatorname{TE}(\mathcal{H})$ as in $\mathcal{G}=\mathrm{TE}(\mathcal{G})$. The bottom figure illustrates the graph $\mathcal{G}^{(\mathbb{X})}$ obtained by removing a vertex set $\mathbb{X}$. By our convention on the deficit function, the tree extension of $\mathcal{G}^{(\mathbb{X})}$ is then trivial

- If $\mathcal{E}_{r}(i, j, \mathcal{G})$ has bounded excess, then upper bounds similar to the right-hand side of (2.2) hold. In particular, $P_{i j}(\mathcal{E}(i, j, r), z)$ is uniformly bounded in $z \in \mathbb{C}_{+}$and decays exponentially in the distance with rate $\log \left(\left|m_{s c}(z)\right| / \sqrt{d-1}\right)$ (see Sect. 5).

Kesten-McKay and semicircle law. Throughout this paper, the Stieltjes transforms of the Kesten-McKay law and that of the closely related semicircle law play an important role. Let $\rho_{d}(x)$ be the density of the (normalized) Kesten-McKay law (1.1) and $\rho_{s c}(x):=$ $\frac{1}{2 \pi} \sqrt{\left[4-x^{2}\right]_{+}}$that of Wigner's semicircle law. We denote their Stieltjes transforms by

$$
\begin{equation*}
m_{d}(z)=\int \frac{\rho_{d}(x)}{x-z} d x, \quad m_{s c}(z):=\int \frac{\rho_{s c}(x)}{x-z} d x, \quad z \in \mathbb{C}_{+} \tag{2.3}
\end{equation*}
$$

Then $m_{d}(z)$ is explicitly related to $m_{s c}(z)$ by the equation (see also Proposition 5.1)

$$
\begin{equation*}
m_{d}(z)=\frac{1}{-z-d(d-1)^{-1} m_{s c}(z)}=\frac{m_{s c}(z)}{1-(d-1)^{-1} m_{s c}^{2}(z)} \tag{2.4}
\end{equation*}
$$

Moreover, it is well known that $m_{s c}(z)$ is a holomorphic bijection from the upper half plane $\mathbb{C}_{+}$to the upper half unit disk $\mathbb{D}_{+}:=\left\{z \in \mathbb{C}_{+}:|z|<1\right\}$, and that it satisfies the algebraic equation

$$
\begin{equation*}
z=-\left(m_{s c}(z)+\frac{1}{m_{s c}(z)}\right), \quad z \in \mathbb{C}_{+} \tag{2.5}
\end{equation*}
$$

and in particular that $\left|m_{s c}(z)\right| \leqslant 1$.
2.3. Main result. Recall that $\mathrm{G}_{N, d}$ denotes the set of simple $d$-regular graphs on the vertex set $\llbracket N \rrbracket$. Throughout the paper, we control error estimates in terms of (large powers of) the parameter

$$
\begin{equation*}
q(z):=\frac{\left|m_{s c}(z)\right|}{\sqrt{d-1}} \leqslant \frac{1}{\sqrt{d-1}}, \tag{2.6}
\end{equation*}
$$

where $z \in \mathbb{C}_{+}$. We will often omit the parameter $z$ from the notation if it is clear from the context.

Our main result is the following theorem.
Theorem 2.4. Fix $\alpha>4, \omega \geqslant 8$ and $\sqrt{d-1} \geqslant(\omega+1) 2^{2 \omega+45}$, and set $\ell_{*}=$ $\left\lfloor\alpha \log _{d-1} \log N\right\rfloor$ and $r_{*}=2 \ell_{*}+1$. Then, for $\mathcal{G}$ chosen uniformly from $\mathrm{G}_{N, d}$, the Green's function satisfies

$$
\begin{equation*}
\left|G_{i j}(\mathcal{G}, z)-P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G}), z\right)\right| \leqslant\left|m_{s c}(z)\right| q(z)^{r_{*}} \tag{2.7}
\end{equation*}
$$

with probability $1-o\left(N^{-\omega+8}\right)$, uniformly in $i, j \in \llbracket N \rrbracket$, and uniformly in $z \in \mathcal{D}$, where $\mathcal{D}$ is as in (1.4). Here we assume that $N \geqslant N_{0}(\alpha, \omega, d)$ is large enough and that $N d$ is even.

We emphasize that, for fixed $d$, the right-hand side of (2.7) converges to 0 , as $N \rightarrow \infty$, uniformly in the spectral domain $\mathcal{D}$. The constants in the statement of the theorem can be improved at the expense of a longer proof and a more complicated statement. We do not pursue this.
2.4. Interpretation of Theorem 2.4; proofs of Theorems 1.1, 1.2, and Corollary 1.3. Theorem 2.4 states that, in $\mathcal{D}$, the Green's function $G_{i j}(\mathcal{G})$ is well approximated by $P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G})\right)$, which is random, but only depends on the local graph structure of $\mathcal{G}$ near the vertices $i$ and $j$. Since the local structure of a random regular graph is well understood, the theorem has a number of consequences. Specifically, under the assumptions of the theorem, it is well known that there are $\kappa>0$ and $\delta>0$ such that, with $R=\left\lfloor\kappa \log _{d-1} N\right\rfloor$, one can assume that the radius- $R$ neighborhoods of all but $N^{\delta}$ many vertices of $\mathcal{G}$ coincide with those of the infinite $d$-regular tree, and that the $R$-neighborhoods of all other vertices have excess at most $\omega$ (see e.g. Proposition 4.1). Moreover, for the vertices $i$ that have radius- $R$ tree neighborhoods, we have (see e.g. Proposition 5.1)

$$
\begin{equation*}
P_{i i}\left(\mathcal{E}_{r_{*}}(i, i, \mathcal{G})\right)=m_{d} \tag{2.8}
\end{equation*}
$$

The vertices whose $R$-neighbourhood has bounded excess still satisfy (see e.g. Proposition 5.2)

$$
\begin{equation*}
\left|P_{i i}\left(\mathcal{E}_{r_{*}}(i, i, \mathcal{G})\right)\right| \leqslant 3\left|m_{s c}\right| / 2 \leqslant 3 / 2 \tag{2.9}
\end{equation*}
$$

Together with this information on the local graph structure, the result of Theorem 2.4 implies the results stated in Sect. 1.

Remark 2.5. The equation (2.7) implies that the individual entries of the Green's function do not concentrate. For example,

$$
G_{i i}(z)=P_{i i}\left(\mathcal{E}_{r_{*}}(i, i, \mathcal{G}), z\right)+O(\log N)^{-\alpha}
$$

and the first term on the right-hand side can be easily seen to depend strongly on the local graph structure. Its fluctuation is of order 1.

Proof of Theorem 1.1. Equations (2.7) and (2.8) imply that $G_{i i}(z)=m_{d}(z)+O\left(\mid m_{s c}(z)\right.$ $\left.\mid q(z)^{r_{*}}\right)$ for all $z \in \mathcal{D}$ and at least $N-N^{-\delta}$ vertices $i \in \llbracket N \rrbracket$. For the remaining vertices, by (2.9), we still have $\left|G_{i i}(z)\right| \leqslant 2$. Thus

$$
\begin{aligned}
m(z) & =\frac{1}{N} \sum_{i=1}^{N} G_{i i}(z) \\
& =m_{d}(z)+O\left(\left|m_{s c}(z)\right| q(z)^{r_{*}}\right)+O\left(N^{-1+\delta}\right)=m_{d}(z)+O(\log N)^{-\alpha},
\end{aligned}
$$

as claimed.
Proof of Theorem 1.2. (2.7) and (2.9) imply that $\left|G_{i i}(z)\right| \leqslant 2$ for all $i \in \llbracket N \rrbracket$ and all $z \in \mathcal{D}$. Taking $z=\lambda+\mathrm{i}(\log N)^{48 \alpha+1} / N$, it follows that

$$
2 \geqslant \operatorname{Im}\left[G_{i i}(z)\right] \geqslant \frac{\operatorname{Im}[z]\left|v_{i}\right|^{2}}{|\lambda-z|^{2}}=(\log N)^{-1-48 \alpha} N\left|v_{i}\right|^{2}
$$

which implies the claim (1.5).
Proof of Corollary 1.3. In [19, Section 8], it is proved that any exchangeable random vector $\left(Y_{i}\right)_{i=1}^{N}$ satisfies, for any (deterministic) $q \in \mathbb{R}^{N}$ with $\sum_{i} q_{i}=0$ and $\sum_{i} q_{i}^{2}=1$, and for any $p \geqslant 1$,

$$
\begin{equation*}
\mathbb{E}\left|\sum_{i=1}^{N} q_{i} Y_{i}\right|^{p}=\left(O\left(\frac{p^{2}}{\log p}\right)\right)^{p} \mathbb{E}\left|Y_{1}\right|^{p} \tag{2.10}
\end{equation*}
$$

Let $\phi$ be the indicator function of the event that for all eigenvectors $v$ with $H$-eigenvalue $|\lambda \pm 2| \geqslant(\log N)^{1-\alpha / 2}$ the estimate $\|v\|_{\infty} \leqslant \xi\|v\|_{2}$ holds, where $\xi=\sqrt{2}(\log N)^{24 \alpha+1 / 2}$ $/ \sqrt{N}$. Let $v^{k}$ be the normalized eigenvector corresponding to the $k$-th largest $H$-eigenvalue $\lambda_{k}$, and set $Y_{i}=v_{i}^{k} \phi \mathbf{1}\left(\left|\lambda_{k} \pm 2\right| \geqslant(\log N)^{1-\alpha / 2}\right)$. The $\left(Y_{i}\right)_{i=1}^{N}$ are exchangeable, by the exchangeability of the random regular graph. By (2.10) with $p=\zeta(\log \zeta)^{1 / 4}$ and Markov's inequality, for $\zeta$ large enough,

$$
\mathbb{P}\left(\phi \mathbf{1}\left(\left|\lambda_{k} \pm 2\right| \geqslant(\log N)^{1-\alpha / 2}\right) \sum_{i=1}^{N} q_{i}^{m} v_{i}^{k} \leqslant \zeta^{2} \xi\right) \geqslant 1-e^{-\zeta(\log \zeta)^{1 / 4}}
$$

By a union bound over $k \in \llbracket N \rrbracket$ and over $m \in \llbracket M \rrbracket$, it follows

$$
\mathbb{P}\left(\phi \max _{k, m} \sum_{i=1}^{N} q_{i}^{m} v_{i}^{k} \leqslant \zeta^{2} \xi\right) \geqslant 1-N M e^{-\zeta(\log \zeta)^{1 / 4}}
$$

where the maximum over $k$ is over all $k$ with $\left|\lambda_{k} \pm 2\right| \geqslant(\log N)^{1-\alpha / 2}$. Since $\mathbb{P}(\phi=$ $0)=o\left(N^{-\omega+8}\right)$, by Theorem 1.2, and choosing $\zeta=2^{-1 / 4}(\log M+\log N)$, we have

$$
\mathbb{P}\left(\max _{k, m} \sum_{i=1}^{N} q_{i}^{m} v_{i}^{k} \leqslant \frac{(\log N)^{24 \alpha+1 / 2}(\log N+\log M)^{2}}{\sqrt{N}}\right) \geqslant 1-o\left(N^{-\omega+8}\right),
$$

which implies the claim. The proof of (1.7) is analogous, using $Y_{i}=\left(v_{i}^{k}\right)^{2} \phi \mathbf{1}(|\lambda \pm 2| \geqslant$ $(\log N)^{1-\alpha / 2}$ ).

## 3. Proof Outline and Main Ideas

In this section, we give a high-level outline of the proof of Theorem 2.4, whose details occupy the remainder of the paper. The proof is based on the general principle that, for small distances, a random regular graph behaves almost deterministically, while on the other hand, for large distances, it behaves much like a random matrix.
3.1. Parameters. Throughout the paper, we fix constants $\alpha>4, \omega \geqslant 8,0<\delta<1 / \omega$, $0<\kappa<\delta /(2 \omega+2), \sqrt{d-1} \geqslant(\omega+1) 2^{2 \omega+45}$, and set $\ell_{*}=\left\lceil\alpha \log _{d-1} \log N\right\rceil$ and $r_{*}=2 \ell_{*}+1$. We also set $R=\left\lfloor\kappa \log _{d-1} N\right\rfloor$, and write $r=2 \ell+1$, where $\ell$ is a parameter chosen such that

$$
\begin{equation*}
\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket . \tag{3.1}
\end{equation*}
$$

Our argument relies on resampling the boundary edges of neighborhoods of radius $\ell$. On the one hand, to have enough randomness, we need $\ell$ to be at least $\log \log N$ to get order $\log N$ edges on the boundary. One the other hand, in Sect. 10 we need to show that removing a small ball of radius $\ell$ has a small effect on the Green's function. For this estimate, we need to take the radius $\ell$ small. To make the estimate clean, in this paper we fix $\ell$ to be of order $\log \log N$. We always assume that $N d$ is even and sufficiently large (depending on the previous parameters).
3.2. Structure of the proof. The proof consists of several sections, which we briefly describe in this section. Here, we also define several subsets of $\mathrm{G}_{N, d}$, namely the sets

$$
\Omega^{-}(z, \ell) \subset \Omega(z, \ell) \subset \Omega_{1}^{+}(z, \ell) \subset \bar{\Omega} \subset \mathrm{G}_{N, d}, \quad \Omega_{1}^{\prime}(z, \ell) \subset \bar{\Omega} \subset \mathrm{G}_{N, d}
$$

These sets depend on parameters $z \in \mathbb{C}_{+}$and $\ell \in \mathbb{N}$ (and also on the previously fixed parameters).

Small distance structure; the set $\bar{\Omega}$. The small distance behavior is captured in terms of cycles in neighborhoods of radius $R$. For any graph, we define the excess to be the smallest number of edges that must be removed to yield a graph with no cycles (a forest). Then, with $R, \omega, \delta$ as fixed above, we define the set $\bar{\Omega} \subset \mathrm{G}_{N, d}$ to consist of graphs such that

- the radius- $R$ neighborhood of any vertex has excess at most $\omega$;
- the number of vertices that have an $R$-neighborhood that contains a cycle is at most $N^{\delta}$.
The set $\bar{\Omega}$ provides rough a priori stability at small distances. All regular graphs appearing throughout the paper will be members of $\bar{\Omega}$. It is well-known that $\mathbb{P}(\bar{\Omega}) \geqslant 1-o\left(N^{-\omega+\delta}\right)$; see Proposition 4.1.

Green's function approximation; the sets $\Omega(z, \ell)$ and $\Omega^{-}(z, \ell)$. For $z \in \mathbb{C}_{+}$, we define the set $\Omega(z, \ell) \subset \bar{\Omega}$ to be the set of graphs $\mathcal{G}$ such that for any two vertices $i, j$ in $\llbracket N \rrbracket$, it holds that

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant\left|m_{s c}\right| q^{r} \tag{3.2}
\end{equation*}
$$

Our main goal is to prove that $\Omega(z, \ell)$ has high probability uniformly in the spectral domain $z \in \mathcal{D}$. That $\Omega(z, \ell)$ has high probability is not difficult to show if $|z|$ is large enough; see Sect. 6. To extend this estimate to smaller $z$, we define the set $\Omega^{-}(z, \ell) \subset$ $\Omega(z, \ell)$ by the same conditions as $\Omega(z, \ell)$, except that the right-hand side in (3.2) is smaller by a factor $1 / 2$ :

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r} . \tag{3.3}
\end{equation*}
$$

Our main goal can then be achieved as follows. We recall the spectral domain $\mathcal{D}$ from (1.4). In (16.15), we will define sets $\Lambda_{\ell}$ whose union covers $\mathcal{D}$. For any $z \in \mathcal{D} \cap \Lambda_{\ell}$, we aim to show that if $\Omega(z, \ell)$ has high probability, then the event $\Omega(z, \ell) \backslash \Omega^{-}(z, \ell)$ has very small probability, so that $\Omega^{-}(z, \ell)$ still has high probability. Then, by the Lipschitzcontinuity of the Green's function, it follows that $\Omega^{-}(z, \ell) \subset \Omega\left(z^{\prime}, \ell\right)$ for small $\left|z-z^{\prime}\right|$, and thus that $\Omega\left(z^{\prime}, \ell\right)$ also has high probability. This can then be repeated to show that $\Omega(z, \ell)$ holds for all $z \in \mathcal{D} \cap \Lambda_{\ell}$ with high probability. Since these sets $\Lambda_{\ell}$ all together cover $\mathcal{D}$, it follows that $\Omega\left(z, \ell_{*}\right)$ holds for all $z \in \mathcal{D}$ with high probability.

Local resampling. To show that $\Omega(z, \ell) \backslash \Omega^{-}(z, \ell)$ has small probability, we use the random matrix-like structure of random regular graphs at large distances. To this end, we fix a vertex, without loss of generality chosen to be 1 , and abbreviate the $\ell$-neighborhood of 1 (as a set of vertices in $\llbracket N \rrbracket$ and as a graph, respectively; see Sect. 2 for our notational conventions) by

$$
\begin{equation*}
\mathbb{T}=\mathbb{B}_{\ell}(1, \mathcal{G}), \quad \mathcal{T}=\mathcal{B}_{\ell}(1, \mathcal{G}) \tag{3.4}
\end{equation*}
$$

In Sect. 7, we resample the boundary of the neighborhood $\mathcal{T}$ by switching the boundary edges with uniformly chosen edges from the remainder of the graph. The switched graph is often denoted by $\tilde{\mathcal{G}}$. On the vertex set $\mathbb{T}$, it coincides with the unswitched graph $\mathcal{G}$, but the boundary of $\mathcal{T}$ in the switched graph $\tilde{\mathcal{G}}$ is now essentially random compared to the original graph $\mathcal{G}$.

Given $\mathcal{G}$, the switching is specified by the resampling data $\mathbf{S}$, which consists of $\mu$ independently chosen oriented edges from $\mathcal{G}^{(\mathbb{T})}$. The local resampling is implemented by switching a boundary edge of $\mathcal{T}$ with one of the independently chosen edges encoded by $\mathbf{S}$. In fact, in this operation, not all pairs of edges can be switched (are switchable in our terminology) while keeping the graph simple. Therefore, given $\mathbf{S}$, we denote by $W_{\mathbf{S}} \subset \llbracket 1, \mu \rrbracket$ the index set for switchable edges (see Sect. 7 for the definition), whose switching leaves the uniform measure on $\mathrm{G}_{N, d}$ invariant. For notational convenience, without loss of generality, we later assume that $W_{\mathbf{S}}=\{1,2,3, \ldots, \nu\}$ where $\nu \leqslant \mu$ throughout the paper (except in the definition in Sect. 7).

Switching from $\mathcal{G}$ to $\tilde{\mathcal{G}}$. Throughout Sects. $8-15$, we condition on a graph $\mathcal{G}$ that satisfies certain estimates, and only use the randomness of the switching that specifies how to
modify $\mathcal{G}$ to $\tilde{\mathcal{G}}$. By our choice of $\ell$ and using $\mathcal{T}$ has bounded excess (which we can and do assume), the number of edges in the boundary of $\mathcal{T}$ is about $(\log N)^{O(1)}$. The randomness of these edges ultimately provides access to concentration estimates, which exhibit the random matrix-like structure of the random regular graph at large distances.

Note that, if we remove the vertex set $\mathbb{T}$ from $\mathcal{G}$, our switchings have a simpler effect than in $\mathcal{G}$ : they only consist of removing the edges $\left\{b_{i}, c_{i}\right\}$ and adding instead $\left\{a_{i}, b_{i}\right\}$, for $i \in W_{\mathbf{S}}$. Therefore, instead of studying the change from $\mathcal{G}$ to $\tilde{\mathcal{G}}$ at once, it will be convenient to analyze the effect of the switching in several steps. For this, we define the following graphs (which need not be regular).
$-\mathcal{G}$ is the original unswitched graph;
$-\mathcal{G}^{(\mathbb{T})}$ is the unswitched graph with vertices $\mathbb{T}$ removed;

- $\hat{\mathcal{G}}^{(\mathbb{T})}$ is the intermediate graph obtained from $\mathcal{G}^{(\mathbb{T})}$ by removing the edges $\left\{b_{i}, c_{i}\right\}$ with $i \in W_{\mathbf{S}}$;
$-\tilde{\mathcal{G}}^{(\mathbb{T})}$ is the switched graph obtained from $\hat{\mathcal{G}}^{(\mathbb{T})}$ by adding the edges $\left\{a_{i}, b_{i}\right\}$ with $i_{\tilde{G}} \in W_{\mathbf{S}}$; and
$-\tilde{\mathcal{G}}$ is the switched graph $T_{\mathbf{S}}(\mathcal{G})$ (including vertices $\mathbb{T}$ ).
Following the conventions of Sect. 2.2, the deficit functions of these graphs are given by $d-\operatorname{deg}$, where deg the degree function of the graph considered, and we abbreviate their Green's functions by $G, G^{(\mathbb{T})}, \hat{G}^{(\mathbb{T})}, \tilde{G}^{(\mathbb{T})}$, and $\tilde{G}$ respectively.

Distance estimates. To use the local resampling, we require some estimates on the local distance structure of graphs and some a priori estimates on their Green's functions. These are collected in Sects. 8-9. In fact, we use both the usual graph distance (of the unswitched and switched graphs) and a notion of "distance" that is defined in terms of the size of the Green's function of the graph from which the set $\mathbb{T}$ is removed (again for the unswitched and switched graph).

The need for the Green's function distance arises as follows. While estimates that involve sums over the diagonal of the Green's function can be controlled quite well using only the graph distance, estimates of sums of off-diagonal terms are more delicate because the number terms is squared compared to the diagonal terms. By direct combinatorial arguments, it would be difficult to control large distances sufficiently precisely. However, to understand spectral properties, it is the size of the Green's function rather than distances themselves that is relevant; and while the size of the Green's function between two vertices is directly related to the distance between them if there are only few cycles, on a global scale (where many cycles could be present) cancellations can make the Green's function much smaller. These cancellations are captured in terms of a Ward identity, which states that the Green's function of any symmetric matrix obeys (see also Appendix B)

$$
\begin{equation*}
\frac{1}{N} \sum_{i=1}^{N}\left|G_{i j}(z)\right|^{2}=\frac{\operatorname{Im} G_{i i}(z)}{\operatorname{Im} z} \tag{3.5}
\end{equation*}
$$

Removing the neighborhood $\mathbb{T}$ and stability under resampling; the sets $\Omega_{1}^{+}(z, \ell)$. Our goal is to show that estimates on the Green's function of $\mathcal{G}$ improve near the vertex 1 under the above mentioned local resampling. For this, we work with the Green's function of the graph $\mathcal{G}^{(\mathbb{T})}$ obtained from $\mathcal{G}$ by removing the vertex set $\mathbb{T}$ (on which the graph does not change under switching).

As a preliminary step to showing that the estimates for the Green's function improve, we show that they are stable under the operation of removing $\mathbb{T}$ and resampling, i.e., roughly that the estimates analogous to those assumed continue to hold. More precisely, in Sect. 10, we show that if $\mathcal{G} \in \Omega(z, \ell)$, then the (non-regular) graph $\mathcal{G}^{(\mathbb{T})}$ obeys the analogous estimate

$$
\begin{equation*}
\left|G_{i j}\left(\mathcal{G}^{(\mathbb{T})}, z\right)-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right), z\right)\right| \leqslant 2\left|m_{s c}\right| q^{r} . \tag{3.6}
\end{equation*}
$$

We define the set $\Omega_{1}^{+}(z, \ell) \subset \bar{\Omega}$ similarly as the set $\Omega(z, \ell)$, except that $\mathcal{G}$ is replaced by the graph $\mathcal{G}^{(\mathbb{T})}$ (and with different constant), i.e., $\Omega_{1}^{+}(z, \ell)$ is the set of $\mathcal{G} \in \bar{\Omega}$ such that

$$
\begin{equation*}
\left|G_{i j}\left(\mathcal{G}^{(\mathbb{T})}, z\right)-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right), z\right)\right| \leqslant 2^{10}\left|m_{s c}\right| q^{r} \tag{3.7}
\end{equation*}
$$

Clearly, by (3.6), we have $\Omega(z, \ell) \subset \Omega_{1}^{+}(z, \ell)$. In Sect. 11, we show that if $\mathcal{G}^{(\mathbb{T})}$ obeys the (stronger) estimate (3.6), then with high probability the resampled graph obeys $\mathcal{G}^{(\mathbb{T})} \in \Omega^{+}(z, \ell)$.

Locally improved Green's function approximation; the sets $\Omega_{1}^{\prime}(z, \ell)$. We define the set $\Omega_{1}^{\prime}(z, \ell) \subset \bar{\Omega}$ of graphs satisfying the improved estimates (15.1)-(15.4) near the vertex 1 , with constant $K=2^{10}$. In Sects. $12-15$, it is proved that if we start with a graph $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, with high probability with respect to the local resampling around vertex 1 , the switched graph $\tilde{\mathcal{G}}$ belongs to $\Omega_{1}^{\prime}(z, \ell)$.

Involution. To sum up, the argument outlined above shows that, for any graph $\mathcal{G}$ in $\Omega(z, \ell)$, with high probability with respect to the randomness of the local resampling, the switched graph $\tilde{\mathcal{G}}$ is in the set $\Omega_{1}^{\prime}(z, \ell)$. However, our goal was to show that a uniform $d$-regular graph $\mathcal{G}$ is in $\Omega_{1}^{\prime}(z, \ell)$, except for an event of small probability. This follows from the statement we proved for $\tilde{\mathcal{G}}$ using that our switching acts as an involution on the larger product probability space (see Proposition 7.5).

Self-consistent equation. The sets $\Omega_{1}^{+}(z, \ell)$ and $\Omega_{1}^{\prime}(z, \ell)$ depend on the choice of vertex 1 . However, for any $i \in \llbracket N \rrbracket$, we can define $\Omega_{i}^{\prime}(z, \ell)$ in the same way, by replacing the vertex 1 in the above definitions by vertex $i$ (or using symmetry). By a union bound, then also the union of the events $\Omega_{i}^{\prime}(z, \ell)$ over $i \in \llbracket N \rrbracket$ holds with high probability. On the latter event, we derive (in Sect. 16) a self-consistent equation for the quantity

$$
Q(\mathcal{G})=\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}} G_{j j}^{(i)}(\mathcal{G}),
$$

where the sum ranges over the set of oriented edges in $\mathcal{G}$, and $G^{(i)}(\mathcal{G})$ is the Green's function of the graph $\mathcal{G}$ with vertex $i$ removed. On the infinite $d$-regular tree, it is straightforward computation to show that $G_{j j}^{(i)}(z)=m_{s c}(z)$ holds for any directed edge $(i, j)$ (see Proposition 5.1). For the random regular graph, we will show that $Q(\mathcal{G})$ obeys [see (16.6)]

$$
Q(\mathcal{G})-m_{s c}=\frac{d-2}{d-1} m_{d} m_{s c}^{2 \ell+1}\left(Q(\mathcal{G})-m_{s c}\right)+\text { error. }
$$

The main result of Sect. 16, proved using this self-consistent equation, is that, for any $z \in \mathcal{D} \cap \Lambda_{\ell}$,

$$
\bigcap_{1 \leqslant i \leqslant N} \Omega_{i}^{\prime}(z, \ell) \subset \Omega^{-}(z, \ell)
$$

where $\Lambda_{\ell} \subset \mathbb{C}_{+}$is a domain on which the self-consistent equation is not singular (see Sect. 16 for details). In the final step, we will use different choices of $\ell$ to cover the entire spectral domain $\mathcal{D}$.

Conclusion. In summary, in Sects. $10-16$, we show that the probability of $\Omega(z, \ell) \backslash$ $\Omega^{-}(z, \ell)$ is negligible. By the Lipschitz property of the Green's function, $\Omega^{-}(z, \ell) \subset$ $\Omega\left(z^{\prime}, \ell\right)$ given that $\left|z-z^{\prime}\right|$ is small enough. It follows that if $\Omega^{-}(z, \ell)$ holds with high probability, then $\Omega^{-}(z, \ell) \cap \Omega^{-}\left(z^{\prime}, \ell\right)$ holds with high probability. This can then be repeated to show that $\Omega(z, \ell)$ holds for all $z \in \mathcal{D} \cap \Lambda_{\ell}$ with high probability. The proof of Theorem 2.4 is then completed by showing that $\mathcal{D} \subset \cup_{\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket} \Lambda_{\ell}$ and thus $\Omega\left(z, \ell_{*}\right)$ holds for all $z \in \mathcal{D}$ with high probability.
3.3. Random walk picture. We conclude this section with the following random walk heuristic for the Green's function. The Green's function $G_{i j}(\mathcal{G}, z)$ has a formal expansion in terms of walks in $\mathcal{G}$ from $i$ to $j$ with complex $z$-dependent weights:

$$
\begin{equation*}
G_{i j}(\mathcal{G}, z)=-\sum_{w: i \rightarrow j}(d-1)^{-|w| / 2} z^{-|w|-1}, \tag{3.8}
\end{equation*}
$$

where the sum ranges over all walks $w$ from $i$ to $j$ of length $|w|$. In several parts of the paper, it might be useful to think about the Green's function in this picture, though we never use it directly. However, the expansion (3.8) is only absolutely convergent for $|z|>\sqrt{d-1}$, where the formal sum is dominated by the shortest walks. In our case of primary interest, $\operatorname{Im} z \ll 1$ (with $\operatorname{Re} z$ inside the spectrum of the adjacency matrix), the expansion becomes highly oscillatory and is not absolutely convergent. Long walks become dominant and the Green's function can only remain bounded due to significant cancellations.

On the tree, it is easy to compute the Green's function exactly. In particular, one finds that the Green's function is bounded for all $z \in \mathbb{C}_{+}$, and that, roughly speaking, each step of a walk contributes a factor $-m_{s c}(z) / \sqrt{d-1}$. A popular and very efficient method to exhibit the required cancellations that result from the tree structure is via nonbacktracking walks.

Our main effort is not in exhibiting the cancellations resulting from the tree structure, but it is rather in exhibiting the cancellations of very long walks, where the tree structure ceases to be effective. To obtain these cancellations, we exploit the randomness of the random regular graph in combination with a Ward identity. Using a multiscale approach (implemented via a continuity argument), we successively prove that the Green's function remains bounded even for small $\operatorname{Im} z$, and moreover that it has good decay. Such bounds, together with linear algebra (Schur complement formula, resolvent identity), allow to obtain well-defined partially resummed versions of random walk identities, in which the crucial cancellations are accounted for nonperturbatively.

## 4. Structure of Random and Deterministic Regular Graphs

In this section, we collect some properties of random and deterministic regular graphs, which we use in the remainder of the paper.

Excess of random regular graphs. For any graph $\mathcal{G}$, we define its excess to be the smallest number of edges that must be removed to yield a graph with no cycles (a forest). It is given by

$$
\begin{equation*}
\operatorname{excess}(\mathcal{G}):=\# \operatorname{edges}(\mathcal{G})-\# v e r t i c e s(\mathcal{G})+\# \text { connected components }(\mathcal{G}) . \tag{4.1}
\end{equation*}
$$

There are different conventions for the normalization of the excess. Our normalization is such that the excess of a tree or forest is 0 . Note that if $\mathcal{H} \subset \mathcal{G}$ is a subgraph, then $\operatorname{excess}(\mathcal{H}) \leqslant \operatorname{excess}(\mathcal{G})$. We will use the following well-known estimates for the excess in random regular graphs.

Proposition 4.1. Let $\delta>0$ and $\omega \geqslant 1$ be an integer. There is $\kappa>0$ such that, if $R=\left\lfloor\kappa \log _{d-1} N\right\rfloor$, then the following holds for a uniformly chosen random $d$-regular graph $\mathcal{G}$ on $\llbracket N \rrbracket$, with probability at least $1-o\left(N^{-\omega+\delta}\right)$ for $N \geqslant N_{0}(d, \omega, \delta)$ large enough.

- All R-neighborhoods have excess at most $\omega$ :
for all $i \in \llbracket N \rrbracket$, the subgraph $\mathcal{B}_{R}(i, \mathcal{G})$ has excess at most $\omega$.
- Most $R$-neighborhoods are trees:

$$
\begin{equation*}
\mid\left\{i \in \llbracket N \rrbracket: \text { the subgraph } \mathcal{B}_{R}(i, \mathcal{G}) \text { contains a cycle }\right\} \mid \leqslant N^{\delta} . \tag{4.3}
\end{equation*}
$$

In fact, one can take $\kappa<\delta /(2 \omega+2)$.
Proof of Corollary 1.3. The statements are well known; for completeness, we sketch proofs in Appendix A.1.

Excess and the number of non-backtracking walks. The next proposition bounds the number of non-backtracking walks (NBW) between two vertices in a graph in terms of the excess of the graph. Here a non-backtracking walk of length $n$ is a sequence of vertices $\left(i_{0}, \ldots, i_{n}\right)$ such that the edge $\left\{i_{k-1}, i_{k}\right\}$ is adjacent to $\left\{i_{k}, i_{k+1}\right\}$ and such that the walks makes no steps backwards, i.e., $i_{k-1} \neq i_{k+1}$.

Proposition 4.2. Let $\mathcal{G}$ be a graph with excess at most $\omega$. Then the following hold.

- For any vertices $i, j \in \mathbb{G}$, and any $k \geqslant 1$, we have

$$
\begin{equation*}
\mid\left\{N B W \text { from } i \text { to } j \text { of length } \operatorname{dist}_{\mathcal{G}}(i, j)+k-1\right\} \mid \leqslant 2^{\omega k} . \tag{4.4}
\end{equation*}
$$

- For any subgraph $\mathcal{H} \subset \mathcal{G}$ and two vertices $i, j$ in $\mathcal{H}$ such that $\mathcal{E}_{\ell}(i, j, \mathcal{G}) \subset \mathcal{H}$, we have
$\mid\{N B W$ from $i$ to $j$ of length $\ell+k$ which are not completely in $\mathcal{H}\} \mid$

$$
\begin{equation*}
\leqslant 2^{\omega(k+1)+1} \tag{4.5}
\end{equation*}
$$

The graph $\mathcal{G}$ does not need to be regular or finite, and self-loops and multi-edges are allowed.

Proof of Corollary 1.3. The statements are presumably also well known; lacking a reference, we include their proofs in Appendix A.2.

Boundary of a neighborhood. In the remainder of the paper, given a graph $\mathcal{G}$ on $\llbracket N \rrbracket$, we will often fix a vertex, chosen without loss of generality to be 1 , and denote its $\ell$-neighborhood by $\mathcal{T}=\mathcal{B}_{\ell}(1, \mathcal{G})$, with corresponding vertex set $\mathbb{T}=\mathbb{B}_{\ell}(1, \mathcal{G})$. We further enumerate $\partial_{E} \mathbb{T}$ as $\left\{e_{1}, e_{2}, \ldots, e_{\mu}\right\}$, i.e., $e_{i}$ are the edges with one vertex in $\mathbb{T}$ and one in $\llbracket N \rrbracket \backslash \mathbb{T}$, and correspondingly $\partial \mathbb{T}$ as $\left\{a_{1}, \ldots, a_{\mu}\right\}$, where $a_{i}$ is the endpoint of $e_{i}$ not in $\mathbb{T}$. We also write $\mathbb{T}_{i}=\left\{v \in \mathcal{G}: \operatorname{dist}_{\mathcal{G}}(1, v)=i\right\}$ for $i=0,1,2, \ldots, \ell$.

Proposition 4.3. Let $\mathcal{G}$ be a d-regular graph on $\llbracket N \rrbracket$, assume that $\mathcal{B}_{R}(1, \mathcal{G})$ has excess at most $\omega$, and that $\ell \ll R$. Then the following hold.

- After removing $\mathbb{T}$, most boundary vertices of $\mathcal{T}$ are isolated from the other boundary vertices:

$$
\begin{equation*}
\left|\left\{p \in \llbracket 1, \mu \rrbracket: \exists q \in \llbracket 1, \mu \rrbracket \backslash\{p\}, \operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}\left(a_{p}, a_{q}\right) \leqslant R / 2\right\}\right| \leqslant 2 \omega . \tag{4.6}
\end{equation*}
$$

- After removing $\mathbb{T}$, any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$ can only be close to few boundary vertices of $\mathbb{T}$ :

$$
\begin{array}{r}
\left|\left\{p \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\left.\mathcal{G}^{\mathbb{T}}\right)}\left(x, a_{p}\right) \leqslant R / 2\right\}\right| \leqslant \omega+1 \\
\left|\left\{v \in \mathbb{T}_{\ell}: \operatorname{dist}_{\mathcal{G} \backslash \mathcal{T}}(x, v) \leqslant R / 2\right\}\right| \leqslant \omega+1 . \tag{4.8}
\end{array}
$$

Notice that the graph $\mathcal{G} \backslash \mathcal{T}$ is slightly larger than $\mathcal{G}^{(\mathbb{T})}$ because the edges between the vertices $\mathbb{T}_{\ell}$ and $\llbracket N \rrbracket \backslash \mathbb{T}$ are not removed.

Bound on deficit functions. Finally, we have the following deterministic bound on the deficit functions for the connected components of the subgraph obtained from $\mathcal{B}_{R}(1, \mathcal{G})$ by removing a set of vertices $\mathbb{U}$.

Proposition 4.4. Let $\mathcal{G}$ be a $d$-regular graph on $\llbracket N \rrbracket$, and assume that $\mathcal{B}:=\mathcal{B}_{R}(1, \mathcal{G})$ has excess at most $\omega$. Then the following hold.

- Let $\mathcal{A}$ be the annulus obtained by removing $\mathbb{T}$ from $\mathcal{B}$. Then the sum of the deficit function over any connected component of $\mathcal{A}$ satisfies $\sum g(v) \leqslant \omega+1$.
- Given $\mathbb{U} \subset \mathbb{B}_{\ell}(1, \mathcal{G})$, let $\mathcal{B}^{(\mathbb{U})}$ be the subgraph given by removing the vertices $\mathbb{U}$ from $\mathcal{B}$. Then the sum of the deficit function over any connected component of $\mathcal{B}^{(\mathbb{U})}$ satisfies $\sum g(v) \leqslant \omega+|\mathbb{U}|$.
For the above statements, recall that we view $\mathcal{A}$ and $\mathcal{B}^{(\mathbb{U})}$ as subgraphs of $\mathcal{B}$ (which has zero deficit function) and that their deficit functions are given by our conventions in Sect. 2.2.

In the remainder of this section, we prove Propositions 4.3 and 4.4 (Fig. 4).
4.1. Proof of Proposition 4.3. Abbreviate $\mathcal{B}=\mathcal{B}_{R}(1, \mathcal{G})$. By assumption the ball $\mathcal{B}$ has excess at most $\omega$. Let $\mathcal{A}$ be the annulus obtained by removing $\mathbb{T}$ from $\mathcal{B}$. We partition $\llbracket 1, \mu \rrbracket$ into sets $\left\{A_{1}, A_{2}, A_{3}, \ldots\right\}$, such that $i$ and $j$ are in the same set $A_{k}$ if and only if $a_{i}$ and $a_{j}$ are in the same connected component of $\mathcal{A}$. We label the sets $A_{k}$ such that $\left|A_{1}\right| \geqslant\left|A_{2}\right| \geqslant \cdots \geqslant\left|A_{\alpha}\right|>1=\left|A_{\alpha+1}\right|=\cdots$ and let $i_{j}$ be a labeling such that $A_{1} \cup \cdots \cup A_{\alpha}=\left\{i_{1}, i_{2}, \ldots, i_{\beta}\right\}$.

## Lemma 4.5.

$$
\begin{equation*}
\alpha \leqslant \omega, \quad \beta \leqslant 2 \omega, \quad\left|A_{j}\right| \leqslant \omega+1 \quad \text { for all } j \tag{4.9}
\end{equation*}
$$



Fig. 4. The two vertices $a_{i}$ which are encircled together are close in the sense that they are in the same connected component of the annulus $\mathcal{A}$. Proposition 4.3 shows that, since $\mathcal{B}$ has excess at most $\omega$, this happens for at most $2 \omega$ of the $a_{i}$. In addition, it shows that any vertex $x$ outside $\mathbb{T}$ can only be close to at most $\omega+1$ of the $a_{i}$

Proof of Corollary 1.3. For any finite graph $\mathcal{G}$, we set

$$
\begin{equation*}
\chi(\mathcal{G}):=\# \operatorname{connected} \operatorname{components}(\mathcal{G})-\operatorname{excess}(\mathcal{G})=\# \operatorname{vertices}(\mathcal{G})-\# \operatorname{edges}(\mathcal{G}) \tag{4.10}
\end{equation*}
$$

where the second equality follows from the definition (4.1) of excess $(\mathcal{G})$. In particular, for any $e \in \mathcal{G}$, we have $\chi(\mathcal{G} \backslash e)=\chi(\mathcal{G})+1$.

As a ball, $\mathcal{B}$ has by definition exactly one connected component, and by assumption it has excess at most $\omega$. Thus $\chi(\mathcal{B}) \geqslant 1-\omega$. We recall that $e_{i}$ is the edge on the boundary of $\mathcal{T}$ containing $a_{i}$. Thus the graph $\mathcal{B} \backslash\left\{e_{i_{1}}, \ldots, e_{i_{\beta}}\right\}$ has at most $\alpha+1$ connected components: the component containing the vertex 1 and the components containing the vertices $a_{i}$ with $i \in A_{j}$ for some $j \in \llbracket 1, \alpha \rrbracket$. (Notice for $i \in A_{j}$ with $j>\alpha$, we did not remove the edge $e_{i}$. Therefore $a_{i}$ is still connected to 1.) Thus $\chi\left(\mathcal{B} \backslash\left\{e_{i_{1}}, \ldots, e_{i_{\beta}}\right\}\right) \leqslant \alpha+1$. It follows that

$$
1+\alpha \geqslant \chi\left(\mathcal{B} \backslash\left\{e_{i_{1}}, \ldots, e_{i_{\beta}}\right\}\right)=\chi(\mathcal{B})+\beta \geqslant 1-\omega+\beta
$$

and thus $\beta \leqslant \alpha+\omega$. Since, by definition, we have $\beta=\sum_{i=1}^{\alpha}\left|A_{i}\right| \geqslant 2 \alpha$, the first two inequalities in (4.9) follow. The third inequality is trivial for $i>\alpha$, and for $i \leqslant \alpha$, we have

$$
\omega+\alpha \geqslant \beta=\sum_{j=1}^{\alpha}\left|A_{j}\right| \geqslant\left|A_{i}\right|+2(\alpha-1)
$$

which implies that $\left|A_{i}\right| \leqslant \omega-\alpha+2 \leqslant \omega+1$ as claimed.
Proof of (4.6). By definition, any $i, j$ such that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i}, a_{j}\right) \leqslant R / 2$ belong to the same connected component of $\mathcal{A}$. (Indeed, $a_{i}$ is at distance $\ell+1$ from the vertex 1 and $R \gg \ell$, and thus $\mathcal{B}_{R / 2}\left(a_{i}, \mathcal{G}\right) \subset \mathcal{B}$ for any $i \in \llbracket 1, \mu \rrbracket$.) In particular, if the set $A_{i}$ containing $i$ has size 1 , then for any $j \in \llbracket 1, \mu \rrbracket \backslash\{i\}$, we have $\operatorname{dist}_{\mathcal{G}}(\mathbb{T})\left(a_{i}, a_{j}\right)>R / 2$. Recalling that $\beta \leqslant 2 \omega$ is the number of $i$ for which the set $A_{i}$ containing it has size greater than 1, the claim (4.6) follows from (4.9).

Proof of (4.7). The claim is trivial if $x \notin \mathcal{B}$ since we then by definition have

$$
\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(x,\left\{a_{1}, a_{2}, \ldots, a_{\mu}\right\}\right) \geqslant R-\ell>R / 2
$$

Thus, assume that $x \in \mathcal{B}$. Let $A_{j}$ be such that $x$ and the vertices $a_{i}$ with $i \in A_{j}$ are in the same connected component of $\mathcal{A}$. We first show that those vertices $a_{p}$ with $p \in A_{k}$ where $k \neq j$ do not contribute to (4.7). Indeed, then $x$ and $a_{p}$ are in the different connected components of $\mathcal{A}$. But since $\mathcal{B}_{R / 2}\left(a_{p}, \mathcal{G}\right) \subset \mathcal{B}$, it then follows that $\operatorname{dist}_{\mathcal{G}_{\mathcal{G}}(\mathbb{T})}\left(x, a_{p}\right)>R / 2$. Therefore $\left|\left\{p \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\mathcal{G}_{\mathcal{G}}(\mathbb{T})}\left(x, a_{p}\right) \leqslant R / 2\right\}\right| \leqslant\left|A_{j}\right|$, and the claim (4.7) follows from the third inequality in (4.9).

Proof of (4.8). By the same proof, (4.7) also holds with $\ell$ replaced by $\ell-1$, i.e., with $\mathbb{T}=\mathbb{B}_{\ell}(1, \mathcal{G})$ replaced by $\mathbb{B}_{\ell-1}(1, \mathcal{G})$, including in Lemma 4.5 . This gives

$$
\left|\left\{v \in \mathbb{T}_{\ell}: \operatorname{dist}_{\mathcal{G}^{\left(\mathbb{B}_{\ell-1}(1, \mathcal{G})\right)}}(x, v) \leqslant R / 2\right\}\right| \leqslant \omega+1
$$

Then claim then follows since $\mathcal{G} \backslash \mathcal{T} \subset \mathcal{G}^{\left(\mathbb{B}_{\ell-1}(1, \mathcal{G})\right)}$.

### 4.2. Proof of Proposition 4.4.

Proof of Proposition 4.4. For the first statement, viewing the annulus $\mathcal{A}$ as a subgraph of $\mathcal{G}^{(\mathbb{T})}$, the bound (4.9) immediately implies that the sum of deficit function over any connected component of $\mathcal{A}$ satisfies $\sum g(v) \leqslant \max _{j}\left|A_{j}\right| \leqslant \omega+1$.

For the second statement, let $k=|\mathbb{U}|$ and write $\mathbb{U}=\left\{u_{1}, u_{2}, \ldots, u_{k}\right\}$. Let $\mathbb{X} \subset \llbracket N \rrbracket$ be the set of vertices of any given connected component of $\mathcal{A}$. Define

$$
B_{i}:=\mathbb{X} \cap \partial u_{i}=\left\{v_{1}^{i}, v_{2}^{i}, \ldots, v_{\left|B_{i}\right|}^{i}\right\}, \quad i=1,2, \ldots, k
$$

where $\partial u$ is the set of neighbors of the vertex $u$ in $\mathcal{G}$. Notice that $g(v)=0$ unless $v \in B_{1} \cup \cdots \cup B_{k}$. Thus

$$
\begin{equation*}
\sum_{v \in \mathbb{X}} g(v) \leqslant \sum_{i=1}^{k} \sum_{v \in B_{k}} g(v) \leqslant \sum_{i=1}^{k}\left|B_{i}\right| \leqslant|\mathbb{U}|+\sum_{i=1}^{k}\left(\left|B_{i}\right|-1\right) \tag{4.11}
\end{equation*}
$$

so that the claim follows from

$$
\begin{equation*}
\sum_{i=1}^{k}\left(\left|B_{i}\right|-1\right) \leqslant \omega \tag{4.12}
\end{equation*}
$$

To prove (4.12), we consider the graph

$$
\mathcal{H}=\mathcal{B} \backslash \bigcup_{i=1}^{k}\left\{\left\{u_{i}, v_{1}^{i}\right\},\left\{u_{i}, v_{2}^{i}\right\}, \ldots,\left\{u_{i}, v_{\left|B_{i}\right|-1}^{i}\right\}\right\} .
$$

Note that $\mathcal{H}$ is obtained from $\mathcal{B}$ by removing exactly $\sum_{i=1}^{k}\left(\left|B_{i}\right|-1\right)$ edges and that $\mathcal{H}$ is connected. Since by assumption $\mathcal{B}$ has excess at most $\omega$, after removing any $\omega+1$ edges, it cannot be connected. This implies (4.12).

## 5. Trees and Tree Extension

For the infinite regular tree and for the rooted infinite regular tree with given root degree, it is elementary to compute the Green's function explicitly, as done in the following proposition.

Proposition 5.1. Let $\mathcal{Y}$ be the infinite $d$-regular tree. For all $z \in \mathbb{C}_{+}$, its Green's function is

$$
\begin{equation*}
G_{x y}(z)=m_{d}(z)\left(-\frac{m_{s c}(z)}{\sqrt{d-1}}\right)^{\operatorname{dist} y(x, y)} \tag{5.1}
\end{equation*}
$$

Let $\mathcal{Y}_{0}$ be the rooted infinite d-regular tree with root degree d -1 . Its Green's function is

$$
\begin{equation*}
G_{x y}(z)=m_{d}(z)\left(1-\left(-\frac{m_{s c}(z)}{\sqrt{d-1}}\right)^{2 \ell(x, y)+2}\right)\left(-\frac{m_{s c}(z)}{\sqrt{d-1}}\right)^{\text {dist } y_{0}(x, y)} \tag{5.2}
\end{equation*}
$$

where $\ell(x, y)$ is the depth of the common ancestor of the vertices $x$ and $y$ in $\mathcal{Y}_{0}$. In particular, if $x$ is the root of $\mathcal{Y}_{0}$, then $G_{x x}(z)=m_{s c}(z)$.

The proof is given below. More general results for Green's functions on regular trees are discussed e.g. in [9, Section 3] and references given there.

The main results of this section are the following estimates for $P_{i j}\left(\mathcal{G}_{0}, z\right)$, the Green's function of the tree extension $\operatorname{TE}\left(\mathcal{G}_{0}\right)$ of a graph $\mathcal{G}_{0}$, as defined in Definition 2.2.

Proposition 5.2. Let $\omega \geqslant 6$ and $\sqrt{d-1} \geqslant 2^{\omega+2}$. Let $\mathcal{G}_{0}$ be a finite graph with vertex set $\mathbb{G}_{0}$ and deficit function $g$. Assume that (i) any connected component of $\mathcal{G}_{0}$ has excess at most $\omega$, and that (ii) the sum of deficit function over any connected component of $\mathcal{G}_{0}$ satisfies $\sum g(v) \leqslant 8 \omega$. Then the following holds for all $z \in \mathbb{C}_{+}$and all $i, j \in \mathbb{G}_{0}$.

1. The Green's function $P_{i j}\left(\mathcal{G}_{0}\right)$ of $\mathrm{TE}\left(\mathcal{G}_{0}\right)$ satisfies

$$
\begin{equation*}
\left|P_{i j}\left(\mathcal{G}_{0}, z\right)\right| \leqslant 2^{\omega+2}\left|m_{s c}(z)\right| q^{\operatorname{dist}_{\mathcal{G}_{0}}(i, j)}, \tag{5.3}
\end{equation*}
$$

and the diagonal terms satisfy the better estimate

$$
\begin{equation*}
\left|P_{i i}\left(\mathcal{G}_{0}, z\right)-m_{d}(z)\right| \leqslant \frac{\left|m_{s c}(z)\right|}{4} \tag{5.4}
\end{equation*}
$$

2. Let $\mathcal{H}_{0} \subset \mathcal{G}_{0}$ be a subgraph with vertex set $\mathbb{H}_{0}$. Then for any two vertices $i, j$ in $\mathcal{H}_{0}$ such that $\mathcal{E}_{\ell}(i, j) \subset \mathcal{H}_{0}$, the $i j$-th entries of the Green's functions of the tree extensions of $\mathcal{G}_{0}$ and $\mathcal{H}_{0}$ satisfy

$$
\begin{equation*}
\left|P_{i j}\left(\mathcal{G}_{0}, z\right)-P_{i j}\left(\mathcal{H}_{0}, z\right)\right| \leqslant 2^{2 \omega+3}\left|m_{s c}(z)\right| q^{\ell+1} \tag{5.5}
\end{equation*}
$$

Item (i) states that $P_{i j}\left(\mathcal{G}_{0}\right)$ is bounded and has (up to constants) the same decay as the Green's function of the infinite $d$-regular tree $\mathcal{Y}$. In particular, (5.3) and (5.4) together with (2.4) imply that

$$
\begin{equation*}
\left|P_{i j}\left(\mathcal{G}_{0}, z\right)\right| \leqslant\left(1+\delta_{i j} / 2\right)\left|m_{s c}(z)\right| \tag{5.6}
\end{equation*}
$$

Item (ii) states that $P_{i j}\left(\mathcal{G}_{0}\right)$ depends only weakly on $\mathcal{G}_{0}$. Especially, it implies the the following principle, which is used repeatedly throughout Sects. 10-15.

Remark 5.3 (Localization principle). Let $\mathbb{X}$ be a (small) set of vertices in a graph $\mathcal{G}$. For vertices $i, j \in \mathbb{X}$, it is often convenient to replace $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$, namely the $i j$-th entry of the Green's function of the graph $\operatorname{TE}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ which itself depends on $i, j$, by $P_{i j}\left(\mathcal{G}_{0}\right)$ of a graph $\mathcal{G}_{0}$ which is independent of $i, j$ and contains $\mathcal{E}_{r}(i, j, \mathcal{G})$ for $i, j \in \mathbb{X}$. In this situation, we abbreviate $P=P\left(\mathcal{G}_{0}\right)$. The estimate (5.5) then implies that $P_{i j}$ and $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ are close in the sense

$$
\begin{equation*}
\left|P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)-P_{i j}\right| \leqslant 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \tag{5.7}
\end{equation*}
$$

provided the assumptions of (5.5) are obeyed.
5.1. Proof of Proposition 5.1. The proof of Proposition 5.1 is a straightforward consequence of the Schur complement formula (B.4).

Proof. Let dist $\mathcal{Y}(x, y)=1$. The Schur complement formula implies

$$
\begin{equation*}
G_{y y}^{(x)}=\frac{-1}{z+(d-1)^{-1} \sum_{k, l \in \partial y \backslash\{x\}} G_{k l}^{(x y)}}=\frac{-1}{z+(d-1)^{-1} \sum_{k \in \partial y \backslash\{x\}} G_{k k}^{(y)}} \tag{5.8}
\end{equation*}
$$

where $\partial y$ is the set of adjacent vertices of $y$ in $\mathcal{Y}$. By homogeneity, $G_{y y}^{(x)}$ is independent of $x$ and $y$ if $\operatorname{dist} y(x, y)=1$ and therefore equal to the unique solution to the equation $m=-1 /(z+m)$ with $\operatorname{Im} m>0$, which is $m_{s c}$. Applying the Schur complement formula again, it follows that

$$
\begin{equation*}
G_{x x}=\frac{-1}{z+d(d-1)^{-1} m_{s c}}=m_{d} \tag{5.9}
\end{equation*}
$$

This proves (5.1) and (5.2) for $x=y$. The case dist $\mathcal{Y}(x, y)=1$ then follows, e.g., from

$$
\begin{equation*}
1=\sum_{y} G_{x y}\left(H_{y x}-z \delta_{y x}\right)=\frac{d}{\sqrt{d-1}} G_{x y}-z m_{d} \tag{5.10}
\end{equation*}
$$

which, using $1+z m_{d}+\frac{d}{d-1} m_{d} m_{s c}=0$, implies

$$
\begin{equation*}
G_{x y}=\frac{\sqrt{d-1}}{d}\left(1+z m_{d}\right)=-\frac{m_{d} m_{s c}}{\sqrt{d-1}}, \tag{5.11}
\end{equation*}
$$

as claimed. The general case is similar by induction.
5.2. Proof of Proposition 5.2 for $g \equiv 0$. For the proof of Proposition 5.1, we require the notion of covering of a graph. Given a graph $\mathcal{G}$, a graph $\tilde{\mathcal{G}}$ together with a surjective map $\pi: \tilde{\mathbb{G}} \rightarrow \mathbb{G}$ is a covering of $\mathcal{G}$ if for each $x \in \widetilde{\mathbb{G}}$, the restriction of $\pi$ to the neighborhood of $x$ is a bijection onto the neighborhood of $\pi(x)$ on $\mathbb{G}$. Every $d$-regular graph is covered by the infinite $d$-regular tree $\mathcal{Y}$ which is its universal covering.

The Green's functions of a graph $\mathcal{G}$ and a cover $\tilde{\mathcal{G}}$ with covering map $\pi: \tilde{\mathbb{G}} \rightarrow \mathbb{G}$ obey the following identity. For each $x \in \widetilde{\mathbb{G}}$ and $\pi(x)=i \in \mathbb{G}$, we have

$$
\begin{equation*}
G_{i j}(z)=\sum_{y: \pi(y)=j} \tilde{G}_{x y}(z) \tag{5.12}
\end{equation*}
$$

if the right-hand side is summable (see Appendix B for the elementary proof of (5.12)). In particular, if $\mathcal{G}$ is an infinite simple $d$-regular graph and $\pi: \mathbb{Y} \rightarrow \mathbb{G}$ its universal covering map, where $\mathbb{Y}$ are the vertices of $\mathcal{Y}$, then by (5.1) and (5.12), for any vertex $x \in \mathbb{Y}$ such that $\pi(x)=i$, the resolvent entries of the graph $\mathcal{G}$ are given by

$$
\begin{align*}
G_{i j} & =m_{d} \sum_{y: \pi(y)=j}\left(-\frac{m_{s c}}{\sqrt{d-1}}\right)^{\operatorname{dist} y(x, y)} \\
& =m_{d} \sum_{k \geqslant \operatorname{dist}_{\mathcal{G}}(i, j)} \mid\{\text { NBW from } i \text { to } j \text { of length } k\} \left\lvert\,\left(-\frac{m_{s c}}{\sqrt{d-1}}\right)^{k}\right., \tag{5.13}
\end{align*}
$$

where we recall that NBW is short for non-backtracking walk (or path). For the number of non-backtracking paths, recall the estimates of Proposition 4.2. Using these, the proofs of (5.3) and (5.5) are straightforward from (5.13) if $g \equiv 0$.

Proof of (5.3) for $g \equiv 0$. For vertices $i, j$ in different connected components of $\mathcal{G}_{0}$, we have $P_{i j}\left(\mathcal{G}_{0}\right)=0$ and there is nothing to prove. Therefore, we can assume that $i$ and $j$ are in the same connected component.

Since we assume $g \equiv 0$, the tree extension $\mathcal{G}_{1}=\mathrm{TE}\left(\mathcal{G}_{0}\right)$ is $d$-regular, and (5.13) implies

$$
\begin{equation*}
P_{i j}\left(\mathcal{G}_{0}, z\right)=m_{d} \sum_{k \geqslant \operatorname{dist}(i, j)} \mid\left\{\text { NBW in } \mathcal{G}_{1} \text { from } i \text { to } j \text { of length } k\right\} \left\lvert\,\left(-\frac{m_{s c}}{\sqrt{d-1}}\right)^{k}\right. \tag{5.14}
\end{equation*}
$$

Since $\mathcal{G}_{0}$ has excess at most $\omega$, the same is true for $\mathcal{G}_{1}$. By the estimates for the number of non-backtracking paths from Proposition 4.2, the right-hand side of (5.13) is summable, provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$, and

$$
\begin{aligned}
\left|G_{i j}\right| \leqslant\left|m_{d}\right| \sum_{k \geqslant 1} 2^{\omega k} q^{\operatorname{dist}_{\mathcal{G}_{0}}(i, j)+k-1} & =\left|m_{d}\right| 2^{\omega} q^{\text {dist }_{\mathcal{G}_{0}}(i, j)} \sum_{k \geqslant 1}\left(2^{\omega} q\right)^{k-1} \\
& \leqslant\left|m_{d}\right| 2^{\omega} q^{\text {dist }_{\mathcal{G}_{0}}(i, j)} \sum_{k \geqslant 0} 4^{-k} \\
& \leqslant 2^{\omega+1}\left|m_{s c}\right| q^{\text {dist }_{\mathcal{G}_{0}}(i, j)}
\end{aligned}
$$

This completes the proof if $g \equiv 0$.
Proof of (5.5) for $g \equiv 0$. As in the proof of (5.3), we can assume that $i$ and $j$ are in the same connected component of $\mathcal{G}_{0}$. By (5.13), since all the non-backtracking paths from $i$ to $j$ of length $\leqslant \ell$ are contained in $\mathcal{H}_{0}$, we have

$$
\left.\left.\begin{array}{rl}
P_{i j}\left(\mathcal{G}_{0}, z\right)-P_{i j}\left(\mathcal{H}_{0}, z\right)=m_{d} & \sum_{k} \geqslant 1
\end{array} \right\rvert\, \text { NBW from } i \text { to } j \text { of length } \ell+k, ~ 子, ~ n o t ~ c o m p l e t e l y ~ i n ~ \mathcal{H}_{0}\right\} \left\lvert\,\left(-\frac{m_{s c}}{\sqrt{d-1}}\right)^{\ell+k} .\right.
$$

By (4.5), we therefore have

$$
\begin{aligned}
\left|P_{i j}\left(\mathcal{G}_{0}, z\right)-P_{i j}\left(\mathcal{H}_{0}, z\right)\right| & \leqslant\left|m_{d}\right| \sum_{k=1}^{\infty} 2^{\omega(k+1)+1} q^{\ell+k} \\
& =\left|m_{d}\right| 2^{2 \omega+1} q^{\ell+1} \sum_{k=1}^{\infty}\left(2^{\omega} q\right)^{k-1} \leqslant 2^{2 \omega+2}\left|m_{s c}\right| q^{\ell+1}
\end{aligned}
$$

again provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$. This completes the proof if $g \equiv 0$.
5.3. Proof of Proposition 5.2 for $g \not \equiv 0$. To extend the bounds (5.3) and (5.5) to $g \not \equiv 0$, we use an alternative representation of $P_{i j}\left(\mathcal{G}_{0}\right)$ given as follows. In Definition 2.2, $P_{i j}\left(\mathcal{G}_{0}, z\right)$ is defined as the Green's function of the infinite graph obtained by attaching a $d$-regular tree at every extensible vertex of $\mathcal{G}_{0}$. The next lemma shows that it is equivalently given by attaching to every extensible vertex a self-loop with $z$-dependent complex weight. The proof of the lemma follows by application of the Schur complement formula.

Lemma 5.4. Let $z \in \mathbb{C}_{+}$. Then for vertices $i, j \in \mathbb{G}_{0}$,

$$
P_{i j}\left(\mathcal{G}_{0}, z\right)=\left(H_{2}-z\right)^{-1}
$$

where $\mathrm{H}_{2}$ is the normalized z-dependent adjacency matrix obtained by attaching to any extensible vertex $v$ in $\mathcal{G}_{0}$ a self-loop with complex weight $-m_{s c}(z)(d-g(v)-$ $\left.\operatorname{deg}_{\mathcal{G}_{0}}(v)\right) / \sqrt{d-1}$.

Proof. Let $\mathcal{G}_{1}=\mathrm{TE}\left(\mathcal{G}_{0}\right)$, and denote the normalized adjacency matrix of $\mathcal{G}_{0}$ and $\mathcal{G}_{1}$ by $H_{0}$ and $H_{1}$ respectively. Then $H_{1}$ has the block form

$$
H_{1}=\left[\begin{array}{cc}
H_{0} & B^{\prime} \\
B & D
\end{array}\right]
$$

where $D$ is the normalized adjacency matrix of several copies of $\mathcal{Y}_{0}$ (which we recall is the infinite $d$-regular tree with root degree $d-1$ ), and $B_{x y}$ is $1 / \sqrt{d-1}$ if $y$ is an extensible vertex of $\mathcal{G}_{0}$ and $x$ the root of one of the former copies of the tree $\mathcal{Y}_{0}$, and $B_{x y}=0$ otherwise. By the Schur complement formula (B.3), it follows that, for any $i, j \in \mathbb{G}_{0}$,

$$
G_{i j}\left(\mathcal{G}_{1}, z\right)=\left(H_{1}-z\right)_{i j}^{-1}=\left(H_{0}-z-B^{\prime}(D-z)^{-1} B\right)_{i j}^{-1}
$$

Since $B^{\prime}(D-z)^{-1} B$ is a diagonal matrix, indexed by the extensible vertices in $\mathcal{G}_{0}$ (which are disjoint), and since $B$ is normalized by $1 / \sqrt{d-1}$, it follows from (5.2) with $x=y$ that

$$
\left(B^{\prime}(D-z)^{-1} B\right)_{v v}=m_{s c} \mathbf{1}_{v \text { is extensible }} \frac{d-g(v)-\operatorname{deg}_{\mathcal{G}_{0}}(v)}{d-1}
$$

Thus $H_{2}=H_{0}-B^{\prime}(D-z)^{-1} B$ and the claim of the lemma follows.

As previously, we abbreviate $\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right)$, and denote by $\mathcal{G}_{2}$ the finite $z$-dependent graph with complex weight obtained by attaching at each extensible vertex $v$ of $\mathcal{G}_{0}$ a self-loop with weight $-m_{s c}(z)\left(d-g(v)-\operatorname{deg}_{\mathcal{G}_{0}}(v)\right) / \sqrt{d-1}$. Moreover, to extend (5.3) and (5.5) from $g \equiv 0$ to $g \not \equiv 0$, we denote by $\mathcal{G}_{0}^{\prime}$ the same graph as $\mathcal{G}_{0}$ but with deficit function $g \equiv 0$, by $\mathcal{G}_{1}^{\prime}=\operatorname{TE}\left(\mathcal{G}_{0}^{\prime}\right)$ its tree extension, and by $\mathcal{G}_{2}^{\prime}$ the finite $z$-dependent graph with complex weight obtained by attaching at each extensible vertex $v$ of $\mathcal{G}_{0}^{\prime}$ a selfloop with weight $-m_{s c}(z)\left(d-\operatorname{deg}_{\mathcal{G}_{0}}(v)\right) / \sqrt{d-1}$. We denote the normalized adjacency matrices of $\mathcal{G}_{2}$ and $\mathcal{G}_{2}^{\prime}$ by $H_{2}$ and $H_{2}^{\prime}$ respectively.

Proof of (5.3) for $g \not \equiv 0$. By Lemma 5.4 and the case $g \equiv 0$, we have

$$
\Gamma^{\prime}:=\max _{i, j \in \mathbb{G}_{0}}\left|G_{i j}\left(\mathcal{G}_{2}^{\prime}, z\right)\right|\left(\left|m_{s c}\right| q^{\text {dist }_{\mathcal{G}_{0}}(i, j)}\right)^{-1} \leqslant 2^{\omega+1}
$$

Our goal is to estimate

$$
\Gamma:=\max _{i, j \in \mathbb{G}_{0}}\left|G_{i j}\left(\mathcal{G}_{2}, z\right)\right|\left(\left|m_{s c}\right| q^{\mathrm{dist}_{\mathcal{G}_{0}}(i, j)}\right)^{-1}
$$

Notice that $H_{2}-H_{2}^{\prime}$ is a diagonal matrix with entries

$$
\begin{equation*}
\left(H_{2}-H_{2}^{\prime}\right)_{v v}=\frac{m_{s c} g(v)}{d-1}, \quad v \in \mathbb{G}_{0} \tag{5.15}
\end{equation*}
$$

and the resolvent formula (B.1) implies

$$
\begin{equation*}
G\left(\mathcal{G}_{2}^{\prime}, z\right)_{i j}-G\left(\mathcal{G}_{2}, z\right)_{i j}=\sum_{v \in \mathbb{G}_{0}} G_{i v}\left(\mathcal{G}_{2}^{\prime}, z\right)\left(H_{2}-H_{2}^{\prime}\right)_{v v} G\left(\mathcal{G}_{2}, z\right)_{v j} \tag{5.16}
\end{equation*}
$$

By multiplying both sides of (5.16) by $\left(\left|m_{s c}\right| q^{\operatorname{dist}_{\mathcal{G}_{0}}(i, j)}\right)^{-1}$, we obtain

$$
\begin{aligned}
& \left|G_{i j}\left(\mathcal{G}_{2}, z\right)\right|\left(\left|m_{s c}\right| q^{\mathrm{dist}_{\mathcal{G}_{0}}(i, j)}\right)^{-1} \\
& \quad \leqslant \Gamma^{\prime}+\sum_{v \in \mathbb{G}_{0}} \Gamma^{\prime} \Gamma\left|\left(H_{2}-H_{2}^{\prime}\right)_{v v}\right|\left|m_{s c}\right| q^{\mathrm{dist}_{\mathcal{G}_{0}}(i, v)+\operatorname{dist}_{\mathcal{G}_{0}}(v, j)-\operatorname{dist}_{\mathcal{G}_{0}}(i, j)} \\
& \quad \leqslant \Gamma^{\prime}+\frac{1}{d-1} \Gamma^{\prime} \Gamma \sum_{v \in \mathbb{G}_{0}} g(v) \leqslant 2^{\omega+1}+\frac{8 \omega 2^{\omega+1}}{d-1} \Gamma \leqslant 2^{\omega+1}+\Gamma / 2
\end{aligned}
$$

where the first inequality uses the triangle inequality $\operatorname{dist}_{\mathcal{G}_{0}}(i, v)+\operatorname{dist}_{\mathcal{G}_{0}}(v, j)-\operatorname{dist}_{\mathcal{G}_{0}}$ $(i, j) \geqslant 0$ and $q \leqslant 1$, and the second and third inequalities follow from the assumptions $\sum g(v) \leqslant 8 \omega, \sqrt{d-1} \geqslant 2^{\omega+2}$, and $\omega \geqslant 6$. By taking the maximum on the left-hand side of the above inequality and rearranging it, we get $\Gamma \leqslant 2^{\omega+2}$.

Proof of (5.5) for $g \not \equiv 0$. The extension to the case $g \not \equiv 0$ again follows by comparing to the case $g \equiv 0$. We define $\mathcal{H}_{2}$ and $\mathcal{H}_{2}^{\prime}$ analogously to $\mathcal{G}_{2}^{\prime}$ and $\mathcal{G}_{2}^{\prime}$. Our goal now is to bound

$$
\Gamma:=\max _{i, j \in \mathbb{H}_{0}}\left|G_{i j}\left(\mathcal{G}_{2}\right)-G_{i j}\left(\mathcal{H}_{2}\right)\right|\left(\left|m_{s c}\right| q^{\ell(i, j)+1}\right)^{-1}
$$

The resolvent identity (B.1) and (5.15) imply

$$
\begin{align*}
G_{i j}\left(\mathcal{G}_{2}^{\prime}\right)-G_{i j}\left(\mathcal{G}_{2}\right) & =\sum_{v \in \mathbb{G}_{0}} G_{i v}\left(\mathcal{G}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{G}_{2}\right),  \tag{5.17}\\
G_{i j}\left(\mathcal{H}_{2}^{\prime}\right)-G_{i j}\left(\mathcal{H}_{2}\right) & =\sum_{v \in \mathbb{H}_{0}} G_{i v}\left(\mathcal{H}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{H}_{2}\right) . \tag{5.18}
\end{align*}
$$

For vertices $i, j \in \mathbb{H}_{0}$, set
$\ell(i, j):=\max \left\{\ell:\right.$ all paths in $\mathcal{G}_{0}$ from $i$ to $j$ of length $\leqslant \ell$ are contained in $\left.\mathcal{H}_{0}\right\}$, and given any $v \in \mathbb{G}_{0}$, we abbreviate $\ell=\ell(i, j), \ell_{1}=\operatorname{dist}_{\mathcal{G}_{0}}(i, v), \ell_{2}=\operatorname{dist}_{\mathcal{G}_{0}}(v, j)$. To bound $\Gamma$, we distinguish two cases:

1. $\ell_{1}+\ell_{2} \geqslant \ell+1$. Then already (5.3) implies

$$
\left|G_{i v}\left(\mathcal{G}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{G}_{2}\right)\right|,\left|G_{i v}\left(\mathcal{H}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{H}_{2}\right)\right| \leqslant \frac{2^{2 \omega+4} g(v)}{d-1}\left|m_{s c}\right| q^{\ell+1} .
$$

2. $\quad \ell_{1}+\ell_{2} \leqslant \ell$. Then by assumption we must have $v \in \mathbb{H}_{0}$, and $\ell(i, v) \geqslant \ell-\ell_{2}$ and $\ell(v, j) \geqslant \ell-\ell_{1}$. Therefore, using the case $g \equiv 0$ for $\left|G_{i v}\left(\mathcal{G}_{2}^{\prime}\right)-G_{i v}\left(\mathcal{H}_{2}^{\prime}\right)\right|$ and (5.3) for $\left|G_{v j}\left(\mathcal{G}_{2}\right)\right|$ and $\left|G_{i v}\left(\mathcal{H}_{2}^{\prime}\right)\right|$,

$$
\begin{aligned}
& \left|G_{i v}\left(\mathcal{G}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{G}_{2}\right)-G_{i v}\left(\mathcal{H}_{2}^{\prime}\right) \frac{m_{s c} g(v)}{d-1} G_{v j}\left(\mathcal{H}_{2}\right)\right| \\
& \quad \leqslant \frac{\left|m_{s c}\right| g(v)}{d-1}\left(\left|G_{i v}\left(\mathcal{G}_{2}^{\prime}\right)-G_{i v}\left(\mathcal{H}_{2}^{\prime}\right)\right|\left|G_{v j}\left(\mathcal{G}_{2}\right)\right|+\left|G_{i v}\left(\mathcal{H}_{2}^{\prime}\right)\right|\left|G_{v j}\left(\mathcal{G}_{2}\right)-G_{v j}\left(\mathcal{H}_{2}\right)\right|\right) \\
& \quad \leqslant \frac{2^{\omega+2}\left(\Gamma+2^{2 \omega+2}\right) g(v)}{d-1}\left|m_{s c}\right| q^{\ell+1} .
\end{aligned}
$$

Taking the difference of (5.17) and (5.18), dividing both sides by $\left|m_{s c}\right| q^{\ell(i, j)+1}$, and then taking the maximum over $i, j \in \mathbb{H}_{0}$, this leads to

$$
\Gamma \leqslant 2^{2 \omega+2}+\frac{2^{\omega+2}\left(\Gamma+2^{2 \omega+2}\right)}{d-1} \sum_{v \in \mathbb{G}_{0}} g(v) .
$$

Since by assumptions $\sum g(v) \leqslant 8 \omega, \sqrt{d-1} \geqslant 2^{\omega+2}$ and $\omega \geqslant 6$, again rearranging the above expression, we get $\Gamma \leqslant 2^{2 \omega+3}$. This finishes the proof.

## 6. Initial Estimates

As the first step of the proof of Theorem 2.4, we now show that (2.7) holds whenever $|z| \geqslant 2 d-1$. Indeed, the following proposition states that (2.7) holds deterministically for $|z| \geqslant 2 d-1$ under the assumption that the graph has locally bounded excess, which is guaranteed to hold with high probability by (4.2). (Related results appear in [32].)
Proposition 6.1. Let $\omega \geqslant 6, \sqrt{d-1} \geqslant 2^{\omega+2}$ and $N \geqslant N_{0}(\omega, d)$ large enough. Let $\mathcal{G}$ be a d-regular graph on $N$ vertices, with excess at most $\omega$ in any radius- $R$ neighborhood. Then for any $z \in \mathbb{C}_{+}$with $|z| \geqslant 2 d-1$, and any $i, j \in \mathbb{G}$, the Green's function of $\mathcal{G}$ satisfies

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r} . \tag{6.1}
\end{equation*}
$$

6.1. Proof of Proposition 6.1. To prove Proposition 6.1, we need an upper bound on the entries of the Green's function. It can be obtained, for example, by the Combes-Thomas method [26].

Lemma 6.2. For any finite simple graph $\mathcal{G}$ with degree bounded by $d$, and any $z$ with $|z| \geqslant 2 d-1$,

$$
\begin{equation*}
\left|G_{i j}(z)\right| \leqslant \frac{1}{d}, \quad\left|G_{i j}(z)\right| \leqslant \frac{1}{(d-1)^{\mathrm{dist}_{\mathcal{G}}(i, j) / 2}} \tag{6.2}
\end{equation*}
$$

Proof. We denote the normalized adjacency matrix of $\mathcal{G}$ by $H$ (where we recall that the normalization of the entries is always by $1 / \sqrt{d-1}$ ). The first bound in (6.2) is immediate since the spectrum of $H$ is contained in $[-d / \sqrt{d-1}, d / \sqrt{d-1}]$, which implies that

$$
\begin{equation*}
\left|G_{i j}(z)\right| \leqslant \frac{1}{|z|-d / \sqrt{d-1}} \leqslant \frac{1}{d} \tag{6.3}
\end{equation*}
$$

To show the second bound, set $\tau=\frac{1}{2} \log (d-1)$. Fix a vertex $i$, and define the diagonal matrix $M$ by

$$
M_{j j}=\exp \left\{\tau \operatorname{dist}_{\mathcal{G}}(i, j)\right\}
$$

Then we have

$$
G_{i j} e^{\tau \mathrm{dist}_{\mathcal{G}}(i, j)}=\left\langle\delta_{j}, M G M^{-1} \delta_{i}\right\rangle=\left\langle\delta_{j},\left(M H M^{-1}-z\right)^{-1} \delta_{i}\right\rangle .
$$

The entries of the matrix $M H M^{-1}$ are given by

$$
\left(M H M^{-1}\right)_{x y}=e^{\tau\left(\operatorname{dist}_{\mathcal{G}}(i, x)-\operatorname{dist}_{\mathcal{G}}(i, y)\right)} H_{x y} .
$$

If $H_{x y} \neq 0$, then $\left|\operatorname{dist}_{\mathcal{G}}(i, x)-\operatorname{dist}_{\mathcal{G}}(i, y)\right| \leqslant 1$, and

$$
\begin{aligned}
& \max _{x} \sum_{y}\left|\left(M H M^{-1}\right)_{x y}\right| \leqslant d e^{\tau} / \sqrt{d-1} \leqslant d \\
& \max _{y} \sum_{x}\left|\left(M H M^{-1}\right)_{x y}\right| \leqslant d e^{\tau} / \sqrt{d-1} \leqslant d
\end{aligned}
$$

Therefore $\left\|M H M^{-1}\right\|_{\infty \rightarrow \infty}$ and $\left\|M H M^{-1}\right\|_{1 \rightarrow 1}$ are bounded by $d$, and by interpolation

$$
\left\|M H M^{-1}\right\|_{2 \rightarrow 2} \leqslant \sqrt{\left\|M H M^{-1}\right\|_{1 \rightarrow 1}\left\|M H M^{-1}\right\|_{\infty \rightarrow \infty}} \leqslant d
$$

Therefore, the spectrum of $M H M^{-1}$ is contained in the set $\{z \in \mathbb{C}:|z| \leqslant d\}$. In particular, for $z$ such that $|z| \geqslant 2 d-1$, its distance to the spectrum of $M H M^{-1}$ is at least 1 , and thus

$$
\left|G_{i j} e^{\tau \operatorname{dist} \mathcal{G}(i, j)}\right|=\left|\left\langle\delta_{j},\left(M H M^{-1}-z\right)^{-1} \delta_{i}\right\rangle\right| \leqslant 1,
$$

which implies (6.2). This completes the proof.

Proof of Proposition 6.1. Let $r_{0}:=\left\lceil r+1-2(r+2) \log _{d-1}\left|m_{s c}\right|\right\rceil=O(r)$. Then, for vertices $i, j$ such that $\operatorname{dist}_{\mathcal{G}}(i, j) \geqslant r_{0}$, Lemma 6.2 implies

$$
\left|G_{i j}(z)\right| \leqslant \frac{1}{(d-1)^{r_{0} / 2}} \leqslant\left|m_{s c}\right| q^{r+1}
$$

and in particular (6.1) follows since $q \leqslant 1 / \sqrt{d-1} \leqslant 1 / 2$ and $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)=0$.
Thus we can assume $\operatorname{dist}_{\mathcal{G}}(i, j)<r_{0}$. Let $\mathcal{G}_{0}:=\mathcal{B}_{r_{0}+r}(i, \mathcal{G})$, let $\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right)$ be the tree extension of $\mathcal{G}_{0}$, and let $P$ be the Green's function of $\mathcal{G}_{1}$. Then, by (5.5), we have

$$
\begin{equation*}
\left|P_{i j}-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)\right| \leqslant 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \tag{6.4}
\end{equation*}
$$

Therefore, it suffices to prove the claim with $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ replaced by $P_{i j}$, and an additional factor $1 / 2$ on the right-hand side. Let $\mathbb{T}_{0}:=\mathbb{B}_{r_{0}}(i, \mathcal{G})$ and $\partial \mathbb{T}_{0}=\{v \in \mathcal{G}$ : $\left.\operatorname{dist}_{\mathcal{G}}\left(v, \mathbb{T}_{0}\right)=1\right\}$. By the Schur complement formula (B.4),

$$
\begin{aligned}
& \left.G\right|_{\mathbb{T}_{0}}=\left(H-z-B^{\prime} G^{\left(\mathbb{T}_{0}\right)} B\right)^{-1}, \\
& \left.P\right|_{\mathbb{T}_{0}}=\left(H-z-B^{\prime} P^{\left(\mathbb{T}_{0}\right)} B\right)^{-1},
\end{aligned}
$$

where $H$ is the normalized adjacency matrix on $\mathbb{T}_{0}$ induced by $\mathcal{G}$ and $B$ is the part of the adjacency matrix of the edges from $\partial \mathbb{T}_{0}$ to $\mathbb{T}_{0}$. Taking the difference of the last two equations, for any $i, j \in \mathbb{T}_{0}$,

$$
\left|(G-P)_{i j}\right| \leqslant \sum_{x, y \in \partial \mathbb{T}_{0}}\left|\left(P B^{\prime}\right)_{i x}\right|\left(\left|G_{x y}^{\left(\mathbb{T}_{0}\right)}\right|+\left|P_{x y}^{\left(\mathbb{T}_{0}\right)}\right|\right)\left|(B G)_{y j}\right| .
$$

Since the radius- $R$ neighborhood of $i$ has excess at most $\omega$, each row of $B$ contains at most $\omega+1$ nonzero entries. Therefore, by (5.3), Lemma 6.2, and noticing that $\operatorname{dist}_{\mathcal{G}}(i, x) \geqslant$ $r_{0}+1$ and $\operatorname{dist}_{\mathcal{G}}(y, j) \geqslant r_{0}+1-\operatorname{dist}_{\mathcal{G}}(i, j)$, we have

$$
\left|\left(P B^{\prime}\right)_{i x}\right| \leqslant 2^{\omega+2}(\omega+1) q^{r_{0}+1}, \quad\left|(B G)_{y j}\right| \leqslant \frac{\omega+1}{(d-1)^{\left(r_{0}+1-\operatorname{dist} \mathcal{G}(i, j)\right) / 2}}
$$

where we recall the definition $q=\left|m_{s c}\right| / \sqrt{d-1}$. Moreover, it follows from (4.6) that

$$
\left|\left\{x \in \partial \mathbb{T}_{0}: \operatorname{dist}_{\mathcal{G}^{\left(\mathbb{T}_{0}\right)}}\left(x, \partial \mathbb{T}_{0} \backslash\{x\}\right) \leqslant R / 2\right\}\right| \leqslant 2 \omega
$$

using that $R>2 r_{0}$. Therefore, by the second bound of (6.2), $\left|G_{x y}^{\left(\mathbb{T}_{0}\right)}\right| \leqslant(d-1)^{-R / 4}$ for all $x, y \in \partial \mathbb{T}_{0}$ except for the diagonal entries and at most $4 \omega^{2}$ off-diagonal entries. By the first bound of (6.2), for these remaining entries we have $\left|G_{x y}^{\left(\mathbb{T}_{0}\right)}\right| \leqslant 1 / d$. The same bounds hold for $P^{\left(\mathbb{T}_{0}\right)}$ instead of $G^{\left(\mathbb{T}_{0}\right)}$. As a result, we obtain

$$
\begin{aligned}
\left|(G-P)_{i j}\right| & \leqslant \frac{2^{\omega+2}(\omega+1)^{2} q^{r_{0}+1}}{(d-1)^{\left(r_{0}-\operatorname{dist}_{\mathcal{G}}(i, j)+1\right) / 2}} \sum_{x, y \in \partial \mathbb{T}_{0}}\left(\left|\left(G_{x y}^{\left(\mathbb{T}_{0}\right)}|+| P^{\left(\mathbb{T}_{0}\right)}\right)_{x y}\right|\right) \\
& \leqslant \frac{2^{\omega+3}(\omega+1)^{2}\left|m_{s c}\right|^{r_{0}+1}}{(d-1)^{r_{0}+1-\operatorname{dist}_{\mathcal{G}}(i, j) / 2}}\left(\frac{\left|\partial \mathbb{T}_{0}\right|+4 \omega^{2}}{d}+\frac{\left|\partial \mathbb{T}_{0}\right|^{2}}{(d-1)^{R / 4}}\right)
\end{aligned}
$$

Using that $\left|\partial \mathbb{T}_{0}\right| \leqslant d(d-1)^{r_{0}}$, that $\left|m_{s c}\right| \leqslant 1 / d$ for $|z| \geqslant 2 d-1$, that $d-1 \geqslant 2(\omega+1)$, as well as that $R>4 r_{0}$, the right-hand side is bounded by

$$
\begin{aligned}
\left|(G-P)_{i j}\right| & \leqslant \frac{2^{\omega+3}(\omega+1)^{2}\left|m_{s c}\right|^{r_{0}+1}}{(d-1)^{r_{0}+1-\text { distg }_{\mathcal{G}}(i, j) / 2}}\left(\frac{d(d-1)^{r_{0}}+4 \omega^{2}}{d}+\frac{d^{2}(d-1)^{2 r_{0}}}{(d-1)^{R / 4}}\right) \\
& \leqslant \frac{2^{\omega+4}(\omega+1)^{2}}{(d-1)^{r_{0}+2-\text { distg }_{\mathcal{G}}(i, j) / 2}} \leqslant \frac{2^{\omega+2}}{(d-1)^{r_{0} / 2}} \leqslant 2^{\omega+2}\left|m_{s c}\right| q^{r+1},
\end{aligned}
$$

where we used that $\operatorname{dist}_{\mathcal{G}}(i, j)<r_{0}$. Together with (6.4), we conclude that

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant\left(2^{2 \omega+3}+2^{\omega+2}\right)\left|m_{s c}\right| q^{r+1} \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r} \tag{6.5}
\end{equation*}
$$

where the last inequality follows from $q=\left|m_{s c}\right| / \sqrt{d-1} \leqslant 2^{-3(\omega+2)}$, using that $\sqrt{d-1} \geqslant 2^{\omega+2}$.

## 7. Local Resampling by Switching

In this section, we define a local resampling of a random regular graph by using switchings. We effectively resample the edges on the boundary of balls of radius $\ell$, by switching them with random edges from the remainder of the graph. This resampling generalizes the local resampling introduced in [19], where switchings were used to resample the neighbors of a vertex (corresponding to $\ell=0$ ). The local resampling provides an effective access to the randomness of the random regular graph, which is fundamental for the remainder of the paper.

### 7.1. Definitions. To introduce the local resampling, we require some definitions.

Graphs and edges. We consider simple $d$-regular graphs on vertex set $\llbracket N \rrbracket$ and identify such graphs with their sets of edges throughout this section. (Deficit functions do not play a role in this section.) For any graph $\mathcal{G}$, we denote the set of unoriented edges by $E$, and the set of oriented edges by $\boldsymbol{E}:=\{(u, v),(v, u):\{u, v\} \in E\}$. For a subset $\boldsymbol{S} \subset \boldsymbol{E}$, we denote by $S$ the set of corresponding non-oriented edges. For a subset $S \subset E$ of edges we denote by $[S] \subset \llbracket N \rrbracket$ the set of vertices incident to any edge in $S$. Moreover, for a subset $\mathbb{V} \subset \llbracket N \rrbracket$ of vertices, we define $\left.E\right|_{\mathbb{V}}$ to be the subgraph of $\mathcal{G}$ induced on $\mathbb{V}$.

Switchings. A (simple) switching is encoded by a pair of oriented edges $\boldsymbol{S}=\left\{\left(v_{1}, v_{2}\right)\right.$, $\left.\left(v_{3}, v_{4}\right)\right\} \subset \boldsymbol{E}$. We assume that the two edges are disjoint, i.e. that $\left|\left\{v_{1}, v_{2}, v_{3}, v_{4}\right\}\right|=4$. Then the switching consists of replacing the two edges $\left\{v_{1}, v_{2}\right\},\left\{v_{3}, v_{4}\right\}$ by the two edges $\left\{v_{1}, v_{4}\right\},\left\{v_{2}, v_{3}\right\}$, as illustrated in Fig. 5. We denote the graph after the switching $\boldsymbol{S}$ by $T_{\boldsymbol{S}}(\mathcal{G})$, and the new edges $\boldsymbol{S}^{\prime}=\left\{\left(v_{1}, v_{4}\right),\left(v_{2}, v_{3}\right)\right\}$ by

$$
\begin{equation*}
T(\boldsymbol{S})=\boldsymbol{S}^{\prime} \tag{7.1}
\end{equation*}
$$

(Double switchings, which we used in [19], are not needed in this paper; henceforth we will therefore refer to simple switchings as switchings.)


Fig. 5. The switching encoded by the two directed edges $\boldsymbol{S}=\left\{\left(v_{1}, v_{2}\right),\left(v_{3}, v_{4}\right)\right\}$ replaces the unoriented edges $\left\{v_{1}, v_{2}\right\},\left\{v_{3}, v_{4}\right\}$ by $\left\{v_{1}, v_{4}\right\},\left\{v_{2}, v_{3}\right\}$


Fig. 6. The figure illustrates the neighborhood $\mathcal{T}=\mathcal{B}_{\ell}(1, \mathcal{G})$ (within the shaded area) and its edge boundary $\partial_{E} \mathcal{T}$, consisting of the edges $e_{i}=\left\{l_{i}, a_{i}\right\}, 1 \leqslant i \leqslant \mu$. Our local resampling switches the switchable edges $e_{i}$ (corresponding to $i \in W_{\mathbf{S}}$ ) with randomly chosen edges from the remainder of the graph (not shown). Several exceptional cases can occur. In particular, the vertices $a_{i}$ are not necessarily distinct (e.g., $a_{5}=a_{6}$ in the figure), and the boundary vertices $l_{i}$ may have different degrees in the graph obtained by removing the set $\mathcal{T}$ (e.g., $l_{1}$ has only one outgoing edge in the figure, while most of the other $l_{i}$ has two outgoing edges)

Resampling data. Our local resampling involves a center vertex, which by symmetry we now assume to be 1 , and a radius $\ell$. Given a $d$-regular graph $\mathcal{G}$, we abbreviate $\mathbb{T}=\mathbb{B}_{\ell}(1, \mathcal{G})$ and $\mathcal{T}=\mathcal{B}_{\ell}(1, \mathcal{G})$. The edge boundary $\partial_{E} \mathcal{T}$ of $\mathcal{T}$ consists of the edges in $\mathcal{G}$ with one vertex in $\mathbb{T}$ and the other vertex in $\llbracket N \rrbracket \backslash \mathbb{T}$, as illustrated in Fig. 6. Our local resampling switches the edge boundary of $\mathcal{T}$ with randomly chosen edges in $\mathcal{G}^{(\mathbb{T})}$ if the switching is admissible (see below), and leaves them in place otherwise.

To be precise, given a graph $\mathcal{G}$, we enumerate $\partial_{E} \mathcal{T}$ as $\partial_{E} \mathcal{T}=\left\{e_{1}, e_{2}, \ldots, e_{\mu}\right\}$, and orient the edges $e_{i}$ by defining $\boldsymbol{e}_{i}$ to have the same vertices as $e_{i}$ and to be directed from a vertex $l_{i} \in \mathbb{T}$ to a vertex $a_{i} \in \llbracket N \rrbracket \backslash \mathbb{T}$. The directed edges $\boldsymbol{e}_{i}=\left(l_{i}, a_{i}\right)$ are illustrated in Fig. 6. Note that $\mu$ and the edges $e_{1}, \ldots, e_{\mu}$ depend on $\mathcal{G}$.

Then we choose $\left(b_{1}, c_{1}\right), \ldots,\left(b_{\mu}, c_{\mu}\right)$ to be independent, uniformly chosen oriented edges from the graph $\mathcal{G}^{(\mathbb{T})}$, i.e., the edges of $\mathcal{G}$ that are not incident to $\mathbb{T}$, and define

$$
\begin{equation*}
\boldsymbol{S}_{i}=\left\{\boldsymbol{e}_{i},\left(b_{i}, c_{i}\right)\right\}, \quad \mathbf{S}=\left(\boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu}\right) \tag{7.2}
\end{equation*}
$$

The sets $\mathbf{S}$ will be called the resampling data for $\mathcal{G}$. By definition, the edges $e_{i}$ are distinct, but the vertices $a_{i}$ are not necessarily distinct and neither are the vertices $l_{i}$.

Admissible switchings. For $i \in \llbracket 1, \mu \rrbracket$, we define the indicator functions

$$
\begin{aligned}
I_{i} & \equiv I_{i}(\mathcal{G}, \mathbf{S}):=\mathbf{1}\left(\left|\left[S_{i}\right]\right|=4,\left.E\right|_{\left[S_{i}\right]}=S_{i}\right) \\
J_{i} & \equiv J_{i}(\mathcal{G}, \mathbf{S}):=\mathbf{1}\left(\left|\left[S_{i}\right] \cap\left[S_{j}\right]\right| \leqslant 1 \text { for all } j \neq i\right)
\end{aligned}
$$

and the set of admissible switchings

$$
\begin{equation*}
W_{\mathbf{S}} \equiv W(\mathcal{G}, \mathbf{S}):=\left\{i \in \llbracket 1, \mu \rrbracket: I_{i}(\mathcal{G}, \mathbf{S}) J_{i}(\mathcal{G}, \mathbf{S})=1\right\} \tag{7.3}
\end{equation*}
$$

The interpretation of $I_{i}=1$ is that the graph $\left.E\right|_{\left[S_{i}\right]}$ is 1-regular. The interpretation of $J_{i}=1$ is that the edges of $S_{i}$ do not interfere with the edges of any other $S_{j}$. Indeed, the condition $\left|\left[S_{i}\right] \cap\left[S_{j}\right]\right| \leqslant 1$ guarantees that the switchings encoded by $S_{i}$ and $S_{j}$ do not influence each other, meaning that $T_{S_{i}}$ and $T_{S_{j}}$ commute. We say that the index $i \in \llbracket 1, \mu \rrbracket$ is admissible or switchable if $i \in W_{\mathbf{S}}$.

Let $v:=\left|W_{\mathbf{S}}\right|$ be the number of admissible switchings and $i_{1}, i_{2}, \ldots, i_{v}$ be an arbitrary enumeration of $W_{\mathbf{S}}$. Then we define the switched graph by

$$
\begin{equation*}
T_{\mathbf{S}}(\mathcal{G}):=\left(T_{S_{i_{1}}} \circ \cdots \circ T_{S_{i_{v}}}\right)(\mathcal{G}) \tag{7.4}
\end{equation*}
$$

and the switching data by

$$
T(\mathbf{S}):=\left(T_{i}\left(\boldsymbol{S}_{\boldsymbol{i}}\right), \ldots, T_{\mu}\left(\boldsymbol{S}_{\boldsymbol{\mu}}\right)\right), \quad T_{i}\left(\boldsymbol{S}_{i}\right)= \begin{cases}T\left(\boldsymbol{S}_{i}\right) & \left(i \in W_{\mathbf{S}}\right)  \tag{7.5}\\ \boldsymbol{S}_{i} & \left(i \notin W_{\mathbf{S}}\right)\end{cases}
$$

7.2. Reversibility. To make the structure more clear, we introduce an enlarged probability space. Equivalently to the definition above, the sets $\boldsymbol{S}_{i}$ are uniformly distributed over

$$
\mathrm{S}_{i}(\mathcal{G})=\left\{\boldsymbol{S} \subset \boldsymbol{E}: \boldsymbol{S}=\left\{\boldsymbol{e}_{i}, \boldsymbol{e}\right\}, \boldsymbol{e} \text { is not incident to } \mathbb{T}\right\}
$$

i.e., the set of pairs of oriented edges in $\boldsymbol{E}$ containing $\boldsymbol{e}_{i}$ and another oriented edge in $\mathcal{G}^{(\mathbb{T})}$. Therefore $\mathbf{S}=\left(\boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu}\right)$ is uniformly distributed over the set $\mathrm{S}(\mathcal{G})=$ $\mathrm{S}_{1}(\mathcal{G}) \times \cdots \times \mathrm{S}_{\mu}(\mathcal{G})$.

Definition 7.1. For any graph $\mathcal{G} \in \mathrm{G}_{N, d}$, denote by $\iota(\mathcal{G})=\{\mathcal{G}\} \times \mathrm{S}(\mathcal{G})$ the fibre of local resamplings of $\mathcal{G}$ (with respect to vertex 1 ), and define the enlarged probability space

$$
\tilde{\mathrm{G}}_{N, d}=\iota\left(\mathrm{G}_{N, d}\right)=\bigsqcup_{\mathcal{G} \in \mathrm{G}_{N, d}} \iota(\mathcal{G})
$$

with the probability measure $\tilde{\mathbb{P}}(\mathcal{G}, \mathbf{S}):=\mathbb{P}(\mathcal{G}) \mathbb{P}_{\mathcal{G}}(\mathbf{S})=\left(1 /\left|\mathrm{G}_{N, d}\right|\right)(1 /|\mathrm{S}(\mathcal{G})|)$ for any $(\mathcal{G}, \mathbf{S}) \in \tilde{\mathrm{G}}_{N, d}$. Here $\mathbb{P}(\mathcal{G})=1 /\left|\mathrm{G}_{N, d}\right|$ is the uniform probability measure on $\mathrm{G}_{N, d}$, and for $\mathcal{G} \in \mathrm{G}_{N, d}$, we denote the uniform probability measure on $\mathrm{S}(\mathcal{G})$ by $\mathbb{P}_{\mathcal{G}}$.

Let $\pi: \tilde{\mathrm{G}}_{N, d} \rightarrow \mathrm{G}_{N, d},(\mathcal{G}, \mathbf{S}) \mapsto \mathcal{G}$ be the canonical projection onto the first component.

Proposition 7.2. $\pi$ is measure preserving: $\mathbb{P}=\tilde{\mathbb{P}} \circ \pi^{-1}$.

Proof. Note that $\pi^{-1}(\mathcal{G})=\iota(\mathcal{G})$. Therefore

$$
\begin{equation*}
\tilde{\mathbb{P}}\left(\pi^{-1}(\mathcal{G})\right)=\tilde{\mathbb{P}}(\iota(\mathcal{G}))=\sum_{\mathbf{S} \in \mathrm{S}(\mathcal{G})} \tilde{\mathbb{P}}(\mathcal{G}, \mathbf{S})=\mathbb{P}(\mathcal{G}) \sum_{\mathbf{S} \in \mathrm{S}(\mathcal{G})} \frac{1}{|\mathrm{~S}(\mathcal{G})|}=\mathbb{P}(\mathcal{G}), \tag{7.6}
\end{equation*}
$$

as claimed.
On the enlarged probability space, we define the maps

$$
\begin{array}{ll}
\tilde{T}: \tilde{\mathrm{G}}_{N, d} \rightarrow \tilde{\mathrm{G}}_{N, d}, & \tilde{T}(\mathcal{G}, \mathbf{S}):=\left(T_{\mathbf{S}}(\mathcal{G}), T(\mathbf{S})\right), \\
T: \tilde{\mathrm{G}}_{N, d} \rightarrow \mathrm{G}_{N, d}, & T(\mathcal{G}, \mathbf{S}):=\pi(\tilde{T}(\mathcal{G}, \mathbf{S}))=T_{\mathbf{S}}(\mathcal{G}) \tag{7.8}
\end{array}
$$

For the statement of the next proposition, recall that $\mathrm{G}_{N, d}$ denotes the set of simple $d$-regular graph on $\llbracket N \rrbracket$. For any finite graph $\mathcal{T}$ on a subset of $\llbracket N \rrbracket$, we define $\mathrm{G}_{N, d}(\mathcal{T}):=\left\{\mathcal{G} \in \mathrm{G}_{N, d}: \mathcal{B}_{\ell}(1, \mathcal{G})=\mathcal{T}\right\}$ to be the set of $d$-regular graphs whose radius- $\ell$ neighborhood of the vertex $i$ in $\mathcal{G}$ is $\mathcal{T}$.

Proposition 7.3. For any graph $\mathcal{T}$, we have

$$
\begin{equation*}
\tilde{T}\left(\iota\left(\mathrm{G}_{N, d}(\mathcal{T})\right)\right) \subset \iota\left(\mathrm{G}_{N, d}(\mathcal{T})\right) \tag{7.9}
\end{equation*}
$$

and $\tilde{T}$ is an involution: $\tilde{T} \circ \tilde{T}=\mathrm{id}$.
Proof. The first claim is obvious by construction. To verify that $\tilde{T}$ is an involution, let $(\mathcal{G}, \mathbf{S}) \in \tilde{\mathbf{G}}_{N, d}$ and abbreviate $(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=\tilde{T}(\mathcal{G}, \mathbf{S})$. Then, due to (7.9), the edge boundaries of the $\ell$-neighborhoods of 1 have the same number of edges $\mu$ in $\tilde{\mathcal{G}}$ and $\mathcal{G}$. Moreover, we can choose the (arbitrary) enumeration of the boundary of the $\ell$-ball in $\tilde{\mathcal{G}}$ such that, for any $i \in \llbracket 1, \mu \rrbracket$, we have $T_{i}\left(\boldsymbol{S}_{i}\right) \in \mathrm{S}_{i}(\tilde{\mathcal{G}})$. Define

$$
\tilde{W}_{\tilde{\mathbf{S}}} \equiv W(\tilde{\mathcal{G}}, \tilde{\mathbf{S}}):=\left\{i \in \llbracket 1, \mu \rrbracket: I_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}}) J_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=1\right\} .
$$

We claim that $\tilde{W}_{\tilde{\mathbf{S}}}=W_{\mathbf{S}}$. First, by definition of switchings, we have $\left[T_{i}\left(S_{i}\right)\right]=\left[S_{i}\right]$ for any $i \in \llbracket 1, \mu \rrbracket$. Thus $J_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=J_{i}(\mathcal{G}, \mathbf{S})$, and it suffices to verify that $I_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=$ $I_{i}(\mathcal{G}, \mathbf{S})$ also holds for all $i \in \llbracket 1, \mu \rrbracket$. For $i \notin W_{\mathbf{S}}$, the switching of $S_{i}$ does not take place, i.e., $\left.\tilde{\mathcal{G}}\right|_{\left[S_{i}\right]}=\left.\mathcal{G}\right|_{\left[S_{i}\right]}$ and therefore $I_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=I_{i}(\mathcal{G}, \mathbf{S})$. On the other hand, for $i \in W_{\mathbf{S}}$, the subgraph $\left.\mathcal{G}\right|_{\left[S_{i}\right]}$ is 1-regular, i.e., $I_{i}(\mathcal{G}, \mathbf{S})=1$, and the other $S_{j}$ with $j \in W_{\mathbf{S}}$ intersect $S_{i}$ at most at one vertex. Therefore, $\left.\tilde{\mathcal{G}}\right|_{\left[S_{i}\right]}=\left.T_{S_{i}} \mathcal{G}\right|_{\left[S_{i}\right]}$ and the graph $\left.\tilde{\mathcal{G}}\right|_{\left[S_{i}\right]}$ is again 1-regular, i.e., $I_{i}(\tilde{\mathcal{G}}, \tilde{\mathbf{S}})=1$ as needed.

In summary, we have verified the claim $\tilde{W}_{\tilde{\mathbf{S}}}=W_{\tilde{\mathbf{S}}}$. By definition of our switchings, it follows that $T(\tilde{\mathbf{S}})=\mathbf{S}$ and $T_{\tilde{\mathbf{S}}}(\tilde{\mathcal{G}})=\mathcal{G}$. Therefore $\tilde{T}$ is an involution.

Proposition 7.4. $\tilde{T}$ and $T$ are measure preserving: $\tilde{\mathbb{P}} \circ \tilde{T}^{-1}=\tilde{\mathbb{P}}$ and $\tilde{\mathbb{P}} \circ T^{-1}=\mathbb{P}$.
In other words, that $T$ is measure preserving means that if $\mathcal{G}$ is uniform over $\mathrm{G}_{N, d}$, and given $\mathcal{G}$, we choose $\mathbf{S}$ uniform over $\mathbf{S}(\mathcal{G})$, then $T_{\mathbf{S}}(\mathcal{G})$ is uniform over $\mathbf{G}_{N, d}$.

Proof. We decompose the enlarged probability space according to the $\ell$-neighborhood of 1 as


Fig. 7. The figure illustrates the idea of Proposition 7.5. The horizontal axis represents the set of graphs $\mathrm{G}_{N, d}$, and the vertical direction the fibres of possible switchings. In particular, the sets $\Omega, \Omega^{\prime}, \Omega^{+}, \bar{\Omega}$ are represented on the horizontal axis. The area in medium and dark grey represents $\tilde{\Omega}=T^{-1}(\Omega)$. The sets $\Omega^{\prime}$ and $\Omega^{+}$and their preimages can be illustrated analogously, but for simplicity we assume for the figure that $\Omega=\Omega^{+}$. The lightly shaded area bounded by the vertical bars is $l(\Omega)$. In (7.12), we devide $\tilde{\Omega} \backslash \tilde{\Omega}^{\prime}$ into the part contained in $\iota\left(\Omega^{+}\right)$(the second term) and the part outside of $\iota\left(\Omega^{+}\right)$(the first term). The part inside $\iota\left(\Omega^{+}\right)$is small because of assumption (iii). To bound the part outside $t\left(\Omega^{+}\right)$, we use that $\tilde{T}$ is an involution. This implies that the image under $\tilde{T}$ of the area in dark gray is contained in $l(\Omega)$ (thus its projection to the horizontal axis lies in $\Omega$ as shown in the figure), and not intersecting $\tilde{\Omega}^{+}$. Its contribution is small by assumption (ii), which implies that $l(\Omega)$ contains most of $\tilde{\Omega}^{+}$

$$
\begin{equation*}
\tilde{\mathrm{G}}_{N, d}=\bigcup_{\mathcal{T}} \tilde{\mathrm{G}}_{N, d}(\mathcal{T}), \quad \text { where } \tilde{\mathrm{G}}_{N, d}(\mathcal{T})=\iota\left(\mathrm{G}_{N, d}(\mathcal{T})\right) \tag{7.10}
\end{equation*}
$$

Notice that, given any $\mathcal{T}$, the size of the set $\mathrm{S}(\mathcal{G})$ is (by construction) independent of the graph $\mathcal{G} \in \mathrm{G}_{N, d}(\mathcal{T})$. Therefore, given any $\mathcal{T}$, the restricted measure $\tilde{\mathbb{P}} \mid \tilde{\mathrm{G}}_{N, d}(\mathcal{T})$ is uniform, i.e., proportional to the counting measure on the finite set $\tilde{\mathrm{G}}_{N, d}(\mathcal{T})$. Since, by Proposition 7.3, the map $\tilde{T}$ is an involution on $\tilde{\mathrm{G}}_{N, d}(\mathcal{T})$, it is in particular a bijection and as such preserves the uniform measure $\tilde{\mathbb{P}} \mid \tilde{\mathrm{G}}_{N, d}(\mathcal{T})$. Since $\tilde{T}$ acts diagonally in the decomposition (7.10), this implies that the map $\tilde{T}$ preserves the measure $\tilde{\mathbb{P}}$. Since $\mathbb{P}=\tilde{\mathbb{P}} \circ \pi^{-1}$ and $T=\pi \circ \tilde{T}$, it immediately follows that also $T$ is measure preserving:

$$
\tilde{\mathbb{P}} \circ T^{-1}=\tilde{\mathbb{P}} \circ \tilde{T}^{-1} \circ \pi^{-1}=\tilde{\mathbb{P}} \circ \pi^{-1}=\mathbb{P},
$$

as claimed.
The following general proposition, which makes use of the involution property of $\tilde{T}$, is central to our approach. The idea of its proof is illustrated in Fig. 7.

Proposition 7.5. Given events $\Omega \subset \Omega^{+} \subset \bar{\Omega} \subset \mathrm{G}_{N, d}$ and $\Omega^{\prime} \subset \bar{\Omega}$, assume

1. $\mathbb{P}\left(\mathrm{G}_{N, d} \backslash \bar{\Omega}\right) \leqslant q_{0}$,
2. $\mathbb{P}_{\mathcal{G}}\left(T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega} \backslash \Omega^{+}\right) \leqslant q_{1}$ for all $\mathcal{G} \in \Omega$, and
3. $\mathbb{P}_{\mathcal{G}}\left(T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega} \backslash \Omega^{\prime}\right) \leqslant q_{2}$ for all $\mathcal{G} \in \Omega^{+}$.

Then $\mathbb{P}\left(\Omega \backslash\left(\Omega \cap \Omega^{\prime}\right)\right) \leqslant q_{0}+q_{1}+q_{2}$.

Roughly, the proposition shows that if, for most graphs $\mathcal{G} \in \mathrm{G}_{N, d}$, an event holds for the switched graph $T_{\mathbf{S}}(\mathcal{G})$ with high probability under the randomness of the switching $\mathbf{S}$, then it also holds with high probability on $\mathrm{G}_{N, d}$. This enables us to condition on a (good) graph $\mathcal{G}$ for much of the paper, and then only use with the randomness of $\mathbf{S}$ which has a simple probabilistic structure.

More specifically, in our application of the proposition, the set $\bar{\Omega}$ is a large set of regular graphs obeying rough a priori estimates (there are only few cycles), the set $\Omega$ is a set of graphs for which the Green's function obeys good estimates, and the set $\Omega^{\prime}$ is a sets of graphs on which the Green's function obeys better estimates (near a given vertex). The proposition states that if with respect to the resampling most graphs obey the better estimates, then these estimates also hold on the original probability space with high probability. The sets to which the proposition will be applied are further discussed in Sect. 3. The proposition will be applied in Sect. 16.

Proof. We define $\tilde{\Omega}=T^{-1}(\Omega), \tilde{\Omega}^{\prime}=T^{-1}\left(\Omega^{\prime}\right)$ and $\tilde{\Omega}^{+}=T^{-1}\left(\Omega^{+}\right)$, and abbreviate $A \backslash B=A \backslash(A \cap B)$ for any sets $A, B$. Since

$$
\begin{equation*}
T^{-1}\left(\Omega \backslash \Omega^{\prime}\right)=T^{-1}(\Omega) \backslash T^{-1}\left(\Omega^{\prime}\right)=\tilde{\Omega} \backslash \tilde{\Omega}^{\prime} \tag{7.11}
\end{equation*}
$$

and since $T$ is measure preserving, and since $\tilde{T}$ is a measure preserving involution, we have

$$
\begin{align*}
\mathbb{P}\left(\Omega \backslash \Omega^{\prime}\right)=\tilde{\mathbb{P}}\left(\tilde{\Omega} \backslash \tilde{\Omega}^{\prime}\right) & =\tilde{\mathbb{P}}\left(\tilde{\Omega} \backslash\left(\tilde{\Omega}^{\prime} \cup \iota\left(\Omega^{+}\right)\right)\right)+\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap \tilde{\Omega}\right) \backslash \tilde{\Omega}^{\prime}\right) \\
& \leqslant \tilde{\mathbb{P}}\left(\tilde{\Omega} \backslash\left(\tilde{\Omega}^{\prime} \cup \iota\left(\Omega^{+}\right)\right)\right)+\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{\prime}\right) \\
& =\tilde{\mathbb{P}}(\hat{\Omega})+\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{\prime}\right), \tag{7.12}
\end{align*}
$$

where $\hat{\Omega}=\tilde{T}\left(\tilde{\Omega} \backslash\left(\tilde{\Omega}^{\prime} \cup \iota\left(\Omega^{+}\right)\right)\right.$. To bound the probability of $\hat{\Omega}$, we make the following observations. First, $\hat{\Omega} \subset \tilde{T}(\tilde{\Omega}) \subset \iota(\Omega)$. Second, any element $(\hat{\mathcal{G}}, \hat{\mathbf{S}}) \in \hat{\Omega}$ can be written as $\hat{\mathcal{G}}=T(\mathcal{G}, \mathbf{S})$ for some $\mathcal{G} \notin \Omega^{+}$and $\mathbf{S} \in \mathbf{S}(\mathcal{G})$. Since $\tilde{T}$ is an involution, this $(\mathcal{G}, \mathbf{S})$ must in fact be given by $(\mathcal{G}, \mathbf{S})=\tilde{T}(\hat{\mathcal{G}}, \hat{\mathbf{S}})$. Together this implies that $(\hat{\mathcal{G}}, \hat{\mathbf{S}}) \notin \tilde{\Omega}^{+}$, and thus that $\hat{\Omega}$ has no intersection with $\tilde{\Omega}^{+}$. As a result,

$$
\begin{aligned}
\mathbb{P}\left(\Omega \backslash \Omega^{\prime}\right) \leqslant & \tilde{\mathbb{P}}\left(\iota(\Omega) \backslash \tilde{\Omega}^{+}\right)+\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{\prime}\right) \\
= & \tilde{\mathbb{P}}\left(\iota(\Omega) \backslash T^{-1}(\bar{\Omega})\right)+\tilde{\mathbb{P}}\left(\left(\iota(\Omega) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{+}\right) \\
& +\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{\prime}\right) \\
\leqslant & \tilde{\mathbb{P}}\left(T^{-1}\left(\mathrm{G}_{N, d}\right) \backslash T^{-1}(\bar{\Omega})\right)+\tilde{\mathbb{P}}\left(\left(\iota(\Omega) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{+}\right) \\
& +\tilde{\mathbb{P}}\left(\left(\iota\left(\Omega^{+}\right) \cap T^{-1}(\bar{\Omega})\right) \backslash \tilde{\Omega}^{\prime}\right) \\
\leqslant & q_{0}+q_{1}+q_{2}
\end{aligned}
$$

where the second inequality follows since $\mathrm{G}_{N, d} \supset \Omega$ and the last inequality follows from the assumptions (i)-(iii).
7.3. Estimates for local resampling. In the following, we give some basic estimates for the local resampling. In particular, we show that, with high probability, most edges are switchable.

Proposition 7.6. Let $\delta>0$.

1. For any $x \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(b_{i}=x\right)=\mathbb{P}\left(c_{i}=x\right) \leqslant \frac{2}{N} \tag{7.13}
\end{equation*}
$$

2. For any positive integer $\omega$, we have

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(\left|W_{\mathbf{S}}\right|>\mu-3 \omega\right)=1-o\left(N^{-\omega+\delta}\right) . \tag{7.14}
\end{equation*}
$$

Proof. To prove (i), we recall that, for any $i$, the oriented edge $\left(b_{i}, c_{i}\right)$ is uniformly chosen from the oriented edges of $\mathcal{G}^{(\mathbb{T})}$. By definition of $\mathbb{T}$, there are at least $N d / 2-$ $\left(d+d(d-1)+\cdots d(d-1)^{\ell}\right)$ edges in $\mathcal{G}^{(\mathbb{T})}$, and since for any vertex $x \in \mathcal{G}^{(\mathbb{T})}$, the degree obeys $\operatorname{deg}_{\mathcal{G}^{(\mathbb{T})}}(x) \leqslant d$,

$$
\mathbb{P}_{\mathcal{G}}\left(b_{i}=x\right)=\mathbb{P}_{\mathcal{G}}\left(c_{i}=x\right) \leqslant \frac{d}{N d-2\left(d+d(d-1)+\cdots d(d-1)^{\ell}\right)} \leqslant \frac{2}{N}
$$

To prove (ii), we need to analyze the events $I_{i} J_{i}=0$ more carefully. We define the disjoint sets

$$
\begin{aligned}
A_{0} & =\left\{i \in \llbracket 1, \mu \rrbracket: I_{i}=0\right\}, \\
A_{1} & =\left\{i \in \llbracket 1, \mu \rrbracket \backslash A_{0}:\left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \neq i}\left[e_{j}\right]\right)\right| \geqslant 1\right\}, \\
A_{2} & =\left\{i \in \llbracket 1, \mu \rrbracket \backslash A_{0} \cup A_{1}:\left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \neq i}\left\{b_{j}, c_{j}\right\}\right)\right| \geqslant 1\right\}, \\
A_{3} & =\left\{i \in \llbracket 1, \mu \rrbracket \backslash A_{0} \cup A_{1} \cup A_{2}: \text { there exists } j \text { such that } l_{i}=l_{j}\right. \\
& \left.\quad \text { and }\left|\left[e_{i}\right] \cap\left\{b_{j}, c_{j}\right\}\right| \geqslant 1\right\},
\end{aligned}
$$

and claim that

$$
\begin{equation*}
\llbracket 1, \mu \rrbracket \backslash W_{\mathbf{S}}=\left\{i \in \llbracket 1, \mu \rrbracket: I_{i} J_{i}=0\right\} \subset A_{0} \cup A_{1} \cup A_{2} \cup A_{3} . \tag{7.15}
\end{equation*}
$$

Indeed, if $i \in \llbracket 1, \mu \rrbracket \backslash W_{\mathbf{S}}$, then $I_{i}=0$ or $J_{i}=0$. Clearly, if $I_{i}=0$ then $i \in A_{0} \subset$ $A_{0} \cup A_{1} \cup A_{2} \cup A_{3}$. On the other hand, if $J_{i}=0$, there exists some index $j \in \llbracket 1, \mu \rrbracket \backslash\{i\}$ such that $\left|\left[S_{i}\right] \cap\left[S_{j}\right]\right|>1$, and there are two possibilities (recall that $e_{i}=\left\{l_{i}, a_{i}\right\}$ and $\left.e_{j}=\left\{l_{j}, a_{j}\right\}\right)$ :

1. $\quad l_{i} \neq l_{j}$. Then either $\left|\left\{b_{i}, c_{i}\right\} \cap\left\{b_{j}, c_{j}\right\}\right| \geqslant 1$; or $\left|\left\{b_{i}, c_{i}\right\} \cap\left[e_{j}\right]\right| \geqslant 1$ and $\mid\left[e_{i}\right] \cap$ $\left\{b_{j}, c_{j}\right\} \mid \geqslant 1$.
2. $l_{i}=l_{j}$. Then either $\left|\left\{b_{i}, c_{i}\right\} \cap\left\{b_{j}, c_{j}\right\}\right| \geqslant 1$; or $\left|\left\{b_{i}, c_{i}\right\} \cap\left[e_{j}\right]\right| \geqslant 1$; or $\mid\left[e_{i}\right] \cap$ $\left\{b_{j}, c_{j}\right\} \mid \geqslant 1$.
Either way, $J_{i}=0$ implies $i \in A_{1} \cup A_{2} \cup A_{3}$, and (7.15) holds. To bound the number of elements on the right-hand side of (7.15), we first note that $\left|A_{3}\right| \leqslant 2\left|A_{0} \cup A_{1}\right|$. In fact if $i \in A_{3}$, then there exists some $j$ such that $\left|\left[e_{i}\right] \cap\left\{b_{j}, c_{j}\right\}\right| \geqslant 1$, and thus $j \in A_{0} \cup A_{1}$. Since any $\left\{b_{j}, c_{j}\right\}$ can intersect at most two edges $e_{i}$ with $l_{i}=l_{j}$,

$$
\left|A_{3}\right| \leqslant \sum_{j \in A_{0} \cup A_{1}} \mid\left\{i \in \llbracket 1, \mu \rrbracket: l_{i}=l_{j} \text { and }\left|\left\{b_{j}, c_{j}\right\} \cap\left[e_{i}\right]\right| \geqslant 1\right\}|\leqslant 2| A_{0} \cup A_{1} \mid .
$$

Therefore, it follows that

$$
\begin{align*}
& \left|\llbracket 1, \mu \rrbracket \backslash W_{\mathbf{S}}\right|=\left|\left\{i \in \llbracket 1, \mu \rrbracket: I_{i} J_{i}=0\right\}\right| \\
& \quad \leqslant 3\left|A_{0} \cup A_{1}\right|+\left|A_{2}\right| \leqslant 3\left|A_{0}\right|+3\left|A_{1}\right|+\left|A_{2}\right| . \tag{7.16}
\end{align*}
$$

We will show that

$$
\begin{equation*}
\mathbb{P}\left(\left|A_{0}\right|+\left|A_{1}\right|+\frac{1}{2}\left|A_{2}\right| \geqslant \omega\right)=o\left(N^{-\omega+\delta}\right), \tag{7.17}
\end{equation*}
$$

which implies the claim since

$$
\begin{aligned}
\mathbb{P}\left(\left|\llbracket 1, \mu \rrbracket \backslash W_{\mathbf{S}}\right| \geqslant 3 \omega\right) & \leqslant \mathbb{P}\left(3\left|A_{0}\right|+3\left|A_{1}\right|+\left|A_{2}\right| \geqslant 3 \omega\right) \\
& \leqslant \mathbb{P}\left(\left|A_{0}\right|+\left|A_{1}\right|+\frac{1}{2}\left|A_{2}\right| \geqslant \omega\right)=o\left(N^{-\omega+\delta}\right) .
\end{aligned}
$$

To prove (7.17), first notice that there is a subset $A_{2}^{\prime} \subset A_{2}$ with $\left|A_{2}^{\prime}\right| \geqslant\left|A_{2}\right| / 2$ such that $i \in A_{2}^{\prime}$ implies $\left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \notin A_{2}^{\prime}}\left\{b_{j}, c_{j}\right\}\right)\right| \geqslant 1$. Hence, if $\left|A_{0}\right|+\left|A_{1}\right|+\left|A_{2}\right| / 2 \geqslant \omega$, then there exist disjoint index sets $\tilde{A}_{0} \subset A_{0}, \tilde{A}_{1} \subset A_{1}, \tilde{A}_{2}^{\prime}=A_{2}^{\prime}$ such that $\left|\tilde{A}_{0}\right|+\left|\tilde{A}_{1}\right|+$ $\left|\tilde{A}_{2}^{\prime}\right|=\omega$ and

$$
\begin{cases}\forall i \in \tilde{A}_{0}, & I_{i}=0  \tag{7.18}\\ \forall i \in \tilde{A}_{1}, & \left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \neq i}\left[e_{j}\right]\right)\right| \geqslant 1 \\ \forall i \in \tilde{A}_{2}^{\prime}, & \left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \notin A_{2}^{\prime}}\left\{b_{j}, c_{j}\right\}\right)\right| \geqslant 1\end{cases}
$$

The condition $I_{i}=0$ is equivalent to $\operatorname{dist}_{\mathcal{G}}\left(\left\{a_{i}, l_{i}\right\},\left\{b_{i}, c_{i}\right\}\right) \leqslant 1$. Therefore, by (7.13),

$$
\begin{align*}
\mathbb{P}_{\mathcal{G}}\left(I_{i}=0\right) & \leqslant \mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\mathcal{G}}\left(\left\{a_{i}, l_{i}\right\}, b_{i}\right) \leqslant 1\right)+\mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\mathcal{G}}\left(\left\{a_{i}, l_{i}\right\}, c_{i}\right) \leqslant 1\right)  \tag{7.19}\\
& \leqslant \frac{4}{N} \#\left\{x \in \mathcal{G}^{(\mathbb{T})}: \operatorname{dist}_{\mathcal{G}}\left(\left\{a_{i}, l_{i}\right\}, x\right) \leqslant 1\right\} \leqslant \frac{8 d}{N} \tag{7.20}
\end{align*}
$$

Similarly, since $\left|\cup_{j}\left[e_{j}\right]\right| \leqslant 2 \mu$,

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(\left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \neq i}\left[e_{j}\right]\right)\right| \geqslant 1\right) \leqslant \frac{8 \mu}{N} \tag{7.21}
\end{equation*}
$$

and, for any $i \in \tilde{A}_{2}^{\prime}$, we have

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(\left\lvert\,\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \notin \tilde{A}_{1}^{\prime}}\left\{b_{j}, c_{j}\right\}|\geqslant 1| S_{j}, j \notin \tilde{A}_{2}^{\prime}\right) \leqslant \frac{8 \mu}{N} .\right.\right. \tag{7.22}
\end{equation*}
$$

Finally, there are at most $(3 \mu)^{\omega}$ disjoint sets $\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime} \subset \llbracket 1, \mu \rrbracket$ such that $\left|\tilde{A}_{0}\right|+\left|\tilde{A}_{1}\right|+$ $\left|\tilde{A}_{2}^{\prime}\right|=\omega$, and therefore

$$
\begin{aligned}
& \mathbb{P}_{\mathcal{G}}\left(\left|A_{0}\right|+\left|A_{1}\right|+\frac{1}{2}\left|A_{2}\right| \geqslant \omega\right) \\
& \quad \leqslant(3 \mu)^{\omega} \max _{\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\text { the sets } \tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime} \text { satisfy }(7.18)\right) \\
& =(3 \mu)^{\omega} \max _{\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime}} \prod_{i \in \tilde{A}_{0}} \mathbb{P}_{\mathcal{G}}\left(I_{i}=0\right) \prod_{i \in \tilde{A}_{1}} \mathbb{P}_{\mathcal{G}}\left(\left|\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \neq i}\left[e_{j}\right]\right)\right| \geqslant 1\right) \\
& \quad \prod_{i \in \tilde{A}_{2}^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\mid\left\{b_{i}, c_{i}\right\} \cap\left(\cup_{j \notin \tilde{A}_{2}^{\prime}}\left\{b_{j}, c_{j}\right\}|\geqslant 1| S_{j}, j \notin \tilde{A}_{2}^{\prime}\right)\right. \\
& \leqslant(3 \mu)^{\omega} \max _{\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime}} \prod_{i \in \tilde{A}_{0}} \frac{8 d}{N} \prod_{i \in \tilde{A}_{1}} \frac{8 \mu}{N} \prod_{i \in \tilde{A}_{2}^{\prime}} \frac{8 \mu}{N}=o\left(N^{-\omega+\delta}\right),
\end{aligned}
$$

where the maxima are over all disjoint sets $\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime} \subset \llbracket 1, \mu \rrbracket$ such that $\left|\tilde{A}_{0}\right|+\left|\tilde{A}_{1}\right|+$ $\left|\tilde{A}_{2}^{\prime}\right|=\omega$, and where we used that the probability factorizes since the sets $\tilde{A}_{0}, \tilde{A}_{1}, \tilde{A}_{2}^{\prime}$ are disjoint.

Remark 7.7. Throughout Sects. 8-15, we fix a $d$-regular graph $\mathcal{G} \in \mathrm{G}_{N, d}$ on the vertex set $\llbracket N \rrbracket$, and abbreviate its $\ell$-neighborhood of 1 by

$$
\begin{equation*}
\mathbb{T}=\mathbb{B}_{\ell}(1, \mathcal{G}), \quad \mathcal{T}=\mathcal{B}_{\ell}(1, \mathcal{G}) \tag{7.23}
\end{equation*}
$$

We also write

$$
\begin{equation*}
\mathbb{T}_{i}=\left\{v \in \mathcal{G}: \operatorname{dist}_{\mathcal{G}}(1, v)=i\right\} \tag{7.24}
\end{equation*}
$$

for the set of vertices at distance $i$ from 1 .
Further, we enumerate the boundary edges $\partial_{E} \mathcal{T}$ as $\left\{l_{i}, a_{i}\right\}$ for $i \in \llbracket 1, \mu \rrbracket$, where $l_{i} \in \mathbb{T}$ and $a_{i} \in \llbracket N \rrbracket \backslash \mathbb{T}$. We denote the resampling data by $\mathbf{S}=\left(\boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu}\right)$, where $\boldsymbol{S}_{i}=\left\{\left(l_{i}, a_{i}\right),\left(b_{i}, c_{i}\right)\right\}$ for $i \in \llbracket 1, \mu \rrbracket$, and $\left(b_{1}, c_{1}\right), \ldots,\left(b_{\mu}, c_{\mu}\right)$ are chosen independently and uniformly among oriented edges from the graph $\mathcal{G}^{(\mathbb{T})}$. We denote by $\mathrm{S}(\mathcal{G})$ the set of all possible switching data, so that $\mathbf{S}$ is uniformly distributed on S . Given switching data $\mathbf{S}$, we denote the set of admissible switchings by $W_{\mathbf{S}}$. Without loss of generality, we will assume for notational convenience that $W_{\mathbf{S}}=\{1,2,3, \ldots, \nu\}$ where $\left|W_{\mathbf{S}}\right|=v \leqslant \mu$.

To study the change of graphs before and after local resampling, we define the following graphs (which need not be regular).
$-\mathcal{G}$ is the original unswitched graph;
$-\mathcal{G}^{(\mathbb{T})}$ is the unswitched graph with vertices $\mathbb{T}$ removed;
$-\hat{\mathcal{G}}^{(\mathbb{T})}$ is the intermediate graph obtained from $\mathcal{G}^{(\mathbb{T})}$ by removing the edges $\left\{b_{i}, c_{i}\right\}$ with $i \in W_{\mathbf{S}}$;
$-\tilde{\mathcal{G}}^{(\mathbb{T})}$ is the switched graph obtained from $\hat{\mathcal{G}}^{(\mathbb{T})}$ by adding the edges $\left\{a_{i}, b_{i}\right\}$ with $i \in W_{\mathbf{S}}$; and
$-\tilde{\mathcal{G}}$ is the switched graph $T_{\mathbf{S}}(\mathcal{G})$ (including vertices $\mathbb{T}$ ).
Following the conventions of Sect. 2.2, the deficit functions of these graphs are given by $d$ - deg, where deg is the degree function of the graph considered, and we abbreviate their Green's functions by $G, G^{(\mathbb{T})}, \hat{G}^{(\mathbb{T})}, \tilde{G}^{(\mathbb{T})}$, and $\tilde{G}$ respectively.

## 8. Graph Distance Between Switched Vertices

This section provides estimates on the distances between the vertices participating in the switching, in the graph with vertices $\mathbb{T}$ removed (before and after switching). It can be helpful to think about these estimates in terms of the sets $\mathbb{K}_{x} \subset \llbracket N \rrbracket \backslash \mathbb{T}$ defined by

$$
\begin{equation*}
\mathbb{K}_{a_{i}}=\mathbb{B}_{R / 4}\left(a_{i}, \mathcal{G}^{(\mathbb{T})}\right), \quad \mathbb{K}_{x_{i}}=\mathbb{B}_{R / 4}\left(x_{i}, \mathcal{G}^{(\mathbb{T})} \backslash\left\{\left\{b_{i}, c_{i}\right\}\right\}\right), \text { where } x_{i} \in\left\{b_{i}, c_{i}\right\} \tag{8.1}
\end{equation*}
$$

and illustrated in Fig. 8. In (4.6), (4.7), it is shown that

- (4.6) except for at most $2 \omega$ many, the $\mathbb{K}_{a}$ does not intersect the other $\mathbb{K}_{a}$.
- (4.7) any $x \in \llbracket N \rrbracket \backslash \mathbb{T}$ is in at most $\omega+1$ many of the sets $\mathbb{K}_{a}$.

Roughly speaking, in this section it is shown that, for any graph $\mathcal{G} \in \bar{\Omega}$, the following estimates hold with high probability under $\mathbb{P}_{\mathcal{G}}$ :


Fig. 8. For the vertices $x \in\left\{a_{i}, b_{i}, c_{i}\right\}$ participating in the switching, we denote by $\mathbb{K}_{x}$ their radius- $R / 4$ neighborhoods in the unswitched graph, with $b_{i}$ and $c_{i}$ disconnected and the set $\mathbb{T}$ removed. The typical $\mathbb{K}_{x}$ are disjoint from the other $\mathbb{K}_{x}$, and in the typical case, the sets $\mathbb{K}_{a}$ and $\mathbb{K}_{c}$ exchange their roles under switching

- (8.2) any $x \in \llbracket N \rrbracket \backslash \mathbb{T}$ is in at most $\omega$ of the sets $\mathbb{K}_{b}$;
$-(8.3)$ any $\mathbb{K}_{a}$ intersects at most $\omega$ of the $\mathbb{K}_{b}$;
- (8.4) any $\mathbb{K}_{b}$ intersects at most $2 \omega$ of the other $\mathbb{K}_{a}, \mathbb{K}_{b}$;
- (8.5) except for at most $\omega$ many, the $\mathbb{K}_{b}$ are trees.

By symmetry, the same statements hold with $b$ replaced by $c$. More precisely, in the remainder of this section, we show that the estimates stated in the following propositions hold.

Proposition 8.1. For any graph $\mathcal{G} \in \bar{\Omega}$ (as in Sect. 3.2), the following holds with $\mathbb{P}_{\mathcal{G}}$ probability at least $1-o\left(N^{-\omega+\delta}\right)$ :

- Any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$ is far away from most vertices in $\left\{b_{1}, b_{2}, \ldots, b_{\mu}\right\}$ :

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\mathcal{G}_{(\mathbb{T})}}\left(x, b_{i}\right) \leqslant R / 2\right\}\right|<\omega . \tag{8.2}
\end{equation*}
$$

- Most indices $i \in \llbracket 1, \mu \rrbracket$ are good:

$$
\begin{align*}
\left|\mathrm{B}_{a}\right|<3 \omega, \quad \text { with } \mathrm{B}_{a}= & \{i \in \llbracket 1, \mu \rrbracket: \\
& \left.\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket \backslash\{i\}, k \in \llbracket 1, \mu \rrbracket\right\}\right) \leqslant R / 2\right\}, \tag{8.3}
\end{align*}
$$

$$
\begin{align*}
&\left|\mathrm{B}_{b}\right|<2 \omega, \quad \text { with } \mathrm{B}_{b}=\{i \in \llbracket 1, \mu \rrbracket: \\
&\left.\qquad \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 2\right\}, \tag{8.4}
\end{align*}
$$

$$
\begin{equation*}
\left|\mathrm{B}_{c}\right|<\omega, \quad \text { with } \mathrm{B}_{c}=\left\{i \in \llbracket 1, \mu \rrbracket: \mathcal{B}_{R}\left(c_{i}, \mathcal{G}^{(\mathbb{T})}\right) \text { is not a tree }\right\} . \tag{8.5}
\end{equation*}
$$

Note that $\mathrm{B}_{a}$ is the set of indices $i$ such that $\mathbb{K}_{a_{i}}$ is not disjoint from all sets other $\mathbb{K}_{a}$ and $\mathbb{K}_{b}$, and that $\mathrm{B}_{b}$ is the set of indices $i$ such that $\mathbb{K}_{b_{i}}$ is not disjoint from all other sets $\mathbb{K}_{b}$ and $\mathbb{K}_{a}$.

We will show that the estimates (8.3) and (8.4) also imply the following estimates for the switched graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$.

Proposition 8.2. Assume (8.3) and (8.4).

- For any index $i \in \llbracket 1, \mu \rrbracket \backslash\left(\mathrm{~B}_{a} \cup \mathrm{~B}_{b}\right)$,

$$
\begin{equation*}
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\left\{a_{i}, b_{i}\right\},\left\{a_{j}, b_{j}: j \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right)>R / 2 \tag{8.6}
\end{equation*}
$$

- For any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(x,\left\{a_{i}, b_{i}\right\}\right) \leqslant R / 4\right\}\right| \leqslant 5 \omega . \tag{8.7}
\end{equation*}
$$

The remainder of this section is devoted to the proofs of Propositions 8.1-8.2.
8.1. Proof of Proposition 8.1. Recall that the oriented edges $\left(b_{i}, c_{i}\right)$ are independent and distributed approximately uniformly, so that (7.13) holds. The claims essentially follow from this.

Proof of (8.2). In any graph with degree bounded by $d$, the number of vertices at distance at most $R / 2$ from vertex $x$ is bounded by $1+d+d(d-1)+\cdots+d(d-1)^{R / 2-1} \leqslant$ $2(d-1)^{R / 2}$. By (7.13) therefore

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}\left(x, b_{i}\right) \leqslant R / 2\right) \leqslant \frac{4(d-1)^{R / 2}}{N} \tag{8.8}
\end{equation*}
$$

Since the $b_{1}, \ldots, b_{\mu}$ are independent, it therefore follows that

$$
\mathbb{P}\left(\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(x, b_{i}\right) \leqslant R / 2\right\}\right| \geqslant \omega\right) \leqslant\binom{\mu}{\omega}\left(\frac{4(d-1)^{R / 2}}{N}\right)^{\omega} \ll N^{-\omega+\delta}
$$

where in the last inequality we used $\left(4(d-1)^{R / 2} \mu\right)^{\omega} \leqslant 2^{3 \omega}(d-1)^{(R / 2+\ell+1) \omega} \ll N^{\delta}$ by the choice of parameters in Sect. 3.

Proof of (8.3). Recall the annulus $\mathcal{A}$, and sets $A_{1}, A_{2}, \ldots$ from Lemma 4.5. By (4.9), $\left|A_{1} \cup \cdots \cup A_{\alpha}\right| \leqslant 2 \omega$, and for any $i \in A_{\alpha+1} \cup A_{\alpha+2} \cup \cdots, a_{i}$ is at least distance $R$ in $\mathcal{G}^{(\mathbb{T})}$ from other vertices $a_{j}$. It follows that

$$
\begin{aligned}
& \left.\mathbb{P}_{\mathcal{G}}\left(\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket \backslash\{i\}, k \in \llbracket 1, \mu \rrbracket\right\}\right)\right\}\right| \leqslant R / 2\right\} \geqslant 3 \omega\right) \\
& \left.\quad \leqslant \mathbb{P}_{\mathcal{G}}\left(\left|\left\{i \in A_{\alpha+1} \cup A_{\alpha+2} \cup \cdots: \operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}\left(a_{i},\left\{b_{1}, b_{2}, \ldots, b_{\mu}\right\}\right)\right\}\right| \leqslant R / 2\right\} \geqslant \omega\right) .
\end{aligned}
$$

By a union bound, the right-hand side is bounded by

$$
\sum_{A^{\prime}, B^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i_{1}}, b_{j_{1}}\right) \leqslant R / 2, \ldots, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i_{\omega}}, b_{j_{\omega}}\right) \leqslant R / 2\right)
$$

where $A^{\prime}=\left\{i_{1}, \ldots, i_{\omega}\right\}, B^{\prime}=\left\{j_{1}, \ldots, j_{\omega}\right\}$, and the sum over $A^{\prime}$ runs through the subsets of $A_{\alpha+1} \cup A_{\alpha+2} \cup \cdots$ with $\left|A^{\prime}\right|=\omega$, the sum over $B^{\prime}$ runs through subsets of $\llbracket 1, \mu \rrbracket$ with $\left|B^{\prime}\right|=\omega$. Notice that if $a_{k}$ and $a_{m}$ are in different connected components of $\mathcal{A}$, then $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{k}, b_{i}\right) \leqslant R / 2$ and $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{m}, b_{j}\right) \leqslant R / 2$ imply $b_{i}$ and $b_{j}$ are in different connected components of $\mathcal{A}$ (those of $a_{k}$ and $a_{m}$, respectively), and in particular then $b_{i} \neq b_{j}$. As a consequence, the indices $j_{1}, \ldots j_{\omega}$ must be distinct, and in particular
the random variables $b_{j_{1}}, \ldots, b_{j_{\omega}}$ are independent. Thus the previous expression is bounded by

$$
\begin{aligned}
& \sum_{A^{\prime}, B^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i_{1}}, b_{j_{1}}\right) \leqslant R / 2\right) \cdots \mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(a_{i_{\omega}}, b_{j_{\omega}}\right) \leqslant R / 2\right) \\
& \quad \leqslant\binom{\mu}{\omega}^{2}\left(\frac{4(d-1)^{R / 2}}{N}\right)^{\omega} \ll N^{-\omega+\delta}
\end{aligned}
$$

where we used that there are $\binom{\mu}{\omega}$ choices for $A^{\prime}$ and $B^{\prime}$ respectively, and the estimate (8.8) with $x=a_{i_{1}}, \ldots, a_{i_{\omega}}$.

Proof of (8.4). Similarly, to prove (8.4), by the union bound we have

$$
\begin{aligned}
& \mathbb{P}_{\mathcal{G}}\left(\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 2\right\}\right| \geqslant 2 \omega\right) \\
& \quad \leqslant \sum_{B^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\forall i \in B^{\prime}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 2\right),
\end{aligned}
$$

where $B^{\prime}$ runs through all subsets of $\llbracket 1, \mu \rrbracket$ with $\left|B^{\prime}\right|=2 \omega$. Next, we notice that, if for all $i \in B^{\prime}$, we have $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 2$, then there must be subset $B^{\prime \prime} \subset B^{\prime}$ with $\left|B^{\prime \prime}\right|=\omega$ such that for all $i \in B^{\prime \prime}$, we have $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash B^{\prime \prime}\right\}\right) \leqslant R / 2$. By relabeling, without loss of generality, we assume that $B^{\prime \prime}=\{\mu-\omega+1, \mu-\omega+2, \ldots, \mu\}$. Conditioned on $\boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu-\omega}$, we have

$$
\begin{aligned}
& \mathbb{P}_{\mathcal{G}}\left(\operatorname{dist}\left(b_{i},\left\{a_{1}, a_{2}, \ldots, a_{\mu}, b_{1}, b_{2}, \ldots, b_{\mu-\omega}\right\}\right) \leqslant R / 2 \mid \boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu-\omega}\right) \\
& \quad \leqslant 8 \mu(d-1)^{R / 2} / N,
\end{aligned}
$$

for any $i \in \llbracket \mu-\omega+1, \mu \rrbracket$. Therefore,

$$
\begin{aligned}
& \sum_{B^{\prime}} \mathbb{P}_{\mathcal{G}}\left(\forall i \in B^{\prime}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 2\right) \\
& \quad \leqslant \sum_{B^{\prime \prime}} \mathbb{P}_{\mathcal{G}}\left(\forall i \in B^{\prime \prime}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{i},\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash B^{\prime \prime}\right\}\right) \leqslant R / 2\right) \\
& \leqslant\binom{\mu}{\omega}\left(\frac{8 \mu(d-1)^{R / 2}}{N}\right)^{\omega} \ll N^{-\omega+\delta}
\end{aligned}
$$

since there are $\binom{\mu}{\omega}$ choices for $B^{\prime \prime}$. This completes the proof.
Proof of (8.5). By the assumption $\mathcal{G} \in \bar{\Omega}$, all except at most $N^{\delta}$ many vertices have radius- $R$ tree neighborhoods. In particular, the same holds for $\mathcal{G}^{(\mathbb{T})}$. By (7.13), it follows that
$\mathbb{P}_{\mathcal{G}}$ (the radius- $R$ neighborhood of $c_{i}$ contains cycles) $\leqslant 2 N^{-1+\delta}$.
By the union bound, and using that the number of ways to choose $\omega+1$ elements from $\mu$ elements is bounded from above by $\mu^{\omega+1}$,
$\mathbb{P}_{\mathcal{G}}\left(\mid\left\{i \in \llbracket 1, \mu \rrbracket:\right.\right.$ radius- $R$ neighborhood of $c_{i}$ contains cycles $\left.\} \mid \geqslant \omega+1\right)$

$$
\leqslant \mu^{\omega+1}\left(2 N^{-1+\delta}\right)^{\omega+1} \leqslant(2 \mu)^{\omega+1} N^{-\omega-1+(\omega+1) \delta} \ll N^{-\omega+\delta}
$$

given that $\delta<1 / \omega$ and using that $\mu \leqslant 2(d-1)^{\ell+1}=(\log N)^{O(1)}$ by the choice of parameters in Sect. 3.

### 8.2. Proof of Proposition 8.2.

Proof of (8.6). By the definition of the sets $\mathrm{B}_{a}$ and $\mathrm{B}_{b}$, for any $i \in \llbracket 1, \mu \rrbracket \backslash\left(\mathrm{~B}_{a} \cup \mathrm{~B}_{b}\right)$, we have

$$
\begin{equation*}
\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(\left\{a_{i}, b_{i}\right\},\left\{a_{j}, b_{j}: j \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right)>R / 2\right. \tag{8.9}
\end{equation*}
$$

Since $\tilde{\mathcal{G}}^{(\mathbb{T})}$ is obtained from $\mathcal{G}^{(\mathbb{T})}$ by removing the edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant \nu}$ and adding the edges $\left\{a_{i}, b_{i}\right\}_{i \leqslant v}$, the claim (8.6) directly follows from (8.9).

Proof of (8.7). We consider three cases. If dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(x,\left\{a_{i}, b_{i}\right\}\right)>R / 4$ for all $i \in \llbracket 1, \mu \rrbracket$, then the claim is trivial. If dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(x,\left\{a_{i}, b_{i}\right\}\right) \leqslant R / 4$ for some $i \in \llbracket 1, \mu \rrbracket \backslash\left(\mathrm{~B}_{a} \cup \mathrm{~B}_{b}\right)$, then (8.6) implies that

$$
\begin{aligned}
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(x,\left\{a_{j}, b_{j}\right\}\right) & \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\left\{a_{i}, a_{j}\right\},\left\{a_{j}, b_{j}\right\}\right)-\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(x,\left\{a_{i}, b_{i}\right\}\right) \\
& >R / 2-R / 4=R / 4,
\end{aligned}
$$

for any $j \in \llbracket 1, \mu \rrbracket \backslash\{i\}$. Thus $\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\tilde{\mathcal{G}}}^{(\mathbb{T})}\left(x,\left\{a_{i}, b_{i}\right\}\right) \leqslant R / 4\right\}\right|=1 \leqslant 5 \omega$ as claimed. In the remaining case, $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(x,\left\{a_{i}, b_{i}\right\}\right) \leqslant R / 4$ is only possible for $i \in$ $\mathrm{B}_{a} \cup \mathrm{~B}_{b}$. Therefore $\left|\left\{i \in \llbracket 1, \mu \rrbracket: \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(x,\left\{a_{i}, b_{i}\right\}\right) \leqslant R / 4\right\}\right| \leqslant\left|\mathrm{B}_{a} \cup \mathrm{~B}_{b}\right| \leqslant 5 \omega$ as claimed.

## 9. The Green's Function Distance and Switching Cells

The bounds provided in the Sect. 8 provide accurate control for distances at most $R / 2$. However, random vertices are typically much further from each other, and as mentioned in Sect. 3, we require stronger upper bounds on the Green's function for such large distances. These bounds are in fact a general consequence of the Ward identity,

$$
\begin{equation*}
\sum_{j}\left|G_{i j}(z)\right|^{2}=\frac{\operatorname{Im}\left[G_{i i}(z)\right]}{\operatorname{Im}[z]} \tag{9.1}
\end{equation*}
$$

which holds for the Green's function of any symmetric matrix [see (B.6)]. To make use of it, we introduce a much coarser measure of distance in terms of the size of the Green's function as follows.
9.1. Definition. Given a parameter $M>0$ (ultimately chosen in (9.4) below), we define a relation $\sim$ on $\llbracket N \rrbracket \backslash \mathbb{T}$ by setting $x \sim y$ if and only if

$$
\begin{equation*}
\max _{\substack{u \text { disit( }(x) u) \leqslant 44, v: \operatorname{dist}(y, v) \leqslant 4 r}}\left|G_{u v}^{(\mathbb{T})}(z)\right| \geqslant \frac{M}{\sqrt{N \eta}} \tag{9.2}
\end{equation*}
$$

where the distance in the maximum is with respect to the graph $\mathcal{G}^{(\mathbb{T})}$, and $\eta=\operatorname{Im}[z]$. The relation $\sim$ induces a graph $\mathcal{R}$ on the vertices $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$. We partition $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$ into its $\sim$-clusters. More precisely, we define $\mathbb{I}_{1}$ to be the vertex set consisting of the union of the connected components of $\mathcal{R}$ containing any element of $\left\{a_{1}, a_{2}, \ldots, a_{\mu}\right\}$, and we define $\mathbb{I}_{2}, \ldots, \mathbb{I}_{\kappa}$ be the vertex sets of the remaining connected components of $\mathcal{R}$.


Fig. 9. Left figure. The S-cells are clusters of vertices that are close to one of the edges $\left\{b_{i}, c_{i}\right\}$ in the sense of the Green's function distance $\sim$. The S -cell $\mathbb{S}_{1}$ contains all $a_{i}$ (the vertex boundary of $\mathcal{T}$ in the original graph) as well as those $b_{i}$ which are close to any of the $a_{i}$ in the sense of the Green's function distance. Right figure. Since the switching may decrease distances between vertices, the $S^{\prime}$-cells are defined by joining the S-cells which have vertices that are close to each other

Definition 9.1 (Cells).

- Define sets $\mathbb{S}_{1}, \mathbb{S}_{2}, \ldots, \mathbb{S}_{\kappa} \subset \llbracket 1, N \rrbracket$ called S -cells by

$$
\begin{equation*}
\mathbb{S}_{i}=\mathbb{B}_{2 r}\left(\mathbb{I}_{i}, \mathcal{G}^{(\mathbb{T})}\right) \tag{9.3}
\end{equation*}
$$

For any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$, we write $x \sim \mathbb{S}_{i}$ if there is $y \in \mathbb{I}_{i}$ such that $x \sim y$.

- Define $\mathbb{S}_{1}^{\prime}, \ldots, \mathbb{S}_{\kappa^{\prime}}^{\prime} \subset \llbracket 1, N \rrbracket$ called $S^{\prime}$-cells by combining the S-cells which are close to each other after switching: we set $\mathbb{S}_{1}^{\prime}=\mathbb{S}_{1}$ and join $S$-cells $\mathbb{S}_{i}$ and $\mathbb{S}_{j}$ with


The $S$ - and $S^{\prime}$-cells are illustrated in Fig. 9. The S-cells are defined in terms of the unswitched graph. In the switching process, distances between S-cells may decrease. This is accounted for by the coarser $\mathrm{S}^{\prime}$-cells. For later use, we note the following elementary properties of S-cells:

- For any $x \in \mathbb{S}_{i}$ and $y \in \mathbb{S}_{j}$ such that $i \neq j$ we have $\left|G_{x y}^{(\mathbb{T})}\right|<M / \sqrt{N \eta}$.
- For any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$, if $x \nsim \mathbb{S}_{i}$, then for any $y \in \mathbb{S}_{i},\left|G_{x y}^{(\mathbb{T})}\right|<M / \sqrt{N \eta}$.
- If $b_{k} \in \mathbb{S}_{i}$, then also $c_{k} \in \mathbb{S}_{i}$; and, consequently, if $b_{k} \in \mathbb{S}_{i}^{\prime}$ then $c_{k} \in \mathbb{S}_{i}^{\prime}$.
9.2. Estimates. From now on, we fix the parameters $M$ and $\omega^{\prime}$ by

$$
\begin{equation*}
M=d^{9 \ell}(\log N)^{\delta}, \quad \omega^{\prime}=\lfloor\log N\rfloor \tag{9.4}
\end{equation*}
$$

where $\delta>0$ was fixed in Sect. 3. The next proposition shows that the cells do not cluster.
Proposition 9.2. For any graph $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ (as in Sect. 3.2), with probabililty at least $1-o\left(N^{-\omega+\delta}\right)$ under $\mathbf{S}$, the following estimates hold:

- Any $x \in \llbracket N \rrbracket \backslash \mathbb{T}$ is $\sim$-connected to fewer than $\omega^{\prime}$ of $\left\{b_{1}, b_{2}, \ldots, b_{\mu}\right\}$,

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: x \sim b_{i}\right\}\right|<\omega^{\prime} . \tag{9.5}
\end{equation*}
$$

In particular, $x$ is $\sim-$ connected to at most $\omega^{\prime}$ of the S -cells.

- Except for at most $\omega^{\prime}$ many indices $i$, the vertex $b_{i}$ is a singleton in the graph $\mathcal{R}$, and thus the S -cell containing $b_{i}$ is disjoint from $\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}$ :

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: b_{i} \sim\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right\}\right|<\omega^{\prime} \tag{9.6}
\end{equation*}
$$

In particular, each S-cell contains at most $\omega^{\prime}$ of $\left\{b_{1}, b_{2}, \ldots, b_{\mu}\right\}$.

- Most $\mathrm{S}^{\prime}$-cells are far from the other vertices participating in the switching:

$$
\begin{align*}
& \mid\left\{i \in \llbracket 1, v \rrbracket: b_{i} \in \mathbb{S}_{j}^{\prime}, \text { such that } j=1\right. \text { or } \\
& \left.\quad \operatorname{dist}\left(\mathbb{S}_{j}^{\prime},\left\{a_{k}, b_{m}, c_{m}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}, m \in \llbracket 1, v \rrbracket \backslash\{i\}\right\}\right) \leqslant R / 4\right\} \mid \\
& \quad<\omega^{\prime}+5 \omega . \tag{9.7}
\end{align*}
$$

In particular, each $\mathrm{S}^{\prime}$-cell contains at most $\omega^{\prime}+5 \omega$ of $\left\{b_{1}, b_{2}, \ldots, b_{\nu}\right\}$.
In the remainder of this section, we prove the above proposition. It is essentially a straightforward consequence of the definitions, combined with union bounds.
9.3. Proof of Proposition 9.2. The following two lemmas collect some elementary properties of the Green's function graph $\mathcal{R}$ on $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\mu}\right\}$ that we require.

Lemma 9.3. Let $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ (as in Sect. 3.2) and $x, y \in \llbracket N \rrbracket \backslash \mathbb{T}$. Then we have $x \nsucc y$ implies $\operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}(x, y)>8 r$.

Proof. We show that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(x, y) \leqslant 8 r$ implies $x \sim y$. To this end, assume that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(x, y) \leqslant 8 r$. Then there must be a vertex $u$ such that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(x, u) \leqslant 4 r$ and $\operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}(y, u) \leqslant 4 r$. Moreover, by the definition (3.7) of $\Omega_{1}^{+}(z, \ell)$ and estimate (5.4), also $\left|G_{u u}^{(\mathbb{T})}(z)\right| \geqslant\left|m_{s c}(z)\right| / 2 \geqslant M / \sqrt{N \eta}$, and thus $x \sim y$.
Lemma 9.4. Let $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ (as in Sect. 3.2) and $x \in \llbracket N \rrbracket \backslash \mathbb{T}$. Then

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(b_{i} \sim x\right) \leqslant 16(d-1)^{8 r} / M^{2} . \tag{9.8}
\end{equation*}
$$

Proof. $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ and (5.4) imply that $\operatorname{Im}\left[G_{x x}^{(\mathbb{T})}\right] \leqslant\left|G_{x x}^{(\mathbb{T})}\right| \leqslant 2$. Thus the Ward identity (B.6) implies

$$
\begin{equation*}
\sum_{i}\left|G_{x i}^{(\mathbb{T})}\right|^{2}=\operatorname{Im}\left[G_{x x}^{(\mathbb{T})}\right] / \eta \leqslant 2 / \eta . \tag{9.9}
\end{equation*}
$$

For any vertex $x \in \llbracket N \rrbracket \backslash \mathbb{T}$, set

$$
\begin{aligned}
\tilde{\mathbb{V}}_{x} & :=\left\{i \in \llbracket N \rrbracket \backslash \mathbb{T}:\left|G_{x i}^{(\mathbb{T})}\right| \geqslant M / \sqrt{N \eta}\right\}, \\
\mathbb{V}_{x} & :=\left\{i \in \llbracket N \rrbracket \backslash \mathbb{T}: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i, \bigcup_{j \in \mathbb{B}_{4 r}\left(x, \mathcal{G}^{(\mathbb{T})}\right)} \tilde{\mathbb{V}}_{j}\right) \leqslant 4 r\right\} .
\end{aligned}
$$

The inequality (9.9) implies $\left|\tilde{\mathbb{V}}_{x}\right| \leqslant 2 N / M^{2}$, and since any vertex has at most $2(d-1)^{4 r}$ vertices in its radius- $4 r$ neighborhood, we also have $\left|\mathbb{V}_{x}\right| \leqslant 8(d-1)^{8 r} N / M^{2}$. Moreover, $i \notin \mathbb{V}_{x}$ implies that $i \nsim x$. Thus

$$
\mathbb{P}_{\mathcal{G}}\left(b_{i} \sim x\right) \leqslant \mathbb{P}_{\mathcal{G}}\left(b_{i} \in \mathbb{V}_{x}\right) \leqslant \frac{2}{N}\left|\mathbb{V}_{x}\right| \leqslant 16(d-1)^{8 r} / M^{2}
$$

where the second inequality holds because $b_{i}$ is approximately uniform (7.13).

Proof of (9.5). The proof is similar to that of (8.2). By the union bound and (9.8), we have

$$
\begin{aligned}
\mathbb{P}\left(\left|\left\{i \in \llbracket 1, \mu \rrbracket: b_{i} \sim x\right\}\right| \geqslant \omega^{\prime}\right) & \leqslant\binom{\mu}{\omega^{\prime}}\left(\frac{16(d-1)^{8 r}}{M^{2}}\right)^{\omega^{\prime}} \\
& \leqslant(\log N)^{-\delta \log N} \ll N^{-\omega}
\end{aligned}
$$

where, in the second inequality, we used $\binom{\mu}{\omega^{\prime}} \leqslant \mu^{\omega^{\prime}}$ and that

$$
16 \mu d^{8 r} / M^{2} \leqslant 16 d^{\ell+1} d^{17 \ell} d^{-18 \ell}(\log N)^{-2 \delta}
$$

since $\mu \leqslant d^{\ell+1}$ and by the definition of $M$ (9.4).
Proof of (9.6). The proof is similar to that of (8.4). Indeed, by the union bound and (9.8),

$$
\begin{aligned}
& \mathbb{P}_{\mathcal{G}}\left(\left|\left\{i \in \llbracket 1, \mu \rrbracket: b_{i} \sim\left\{a_{j}, b_{k}: j \in \llbracket 1, \mu \rrbracket, k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}\right\}\right| \geqslant \omega^{\prime}\right) \\
& \quad \leqslant\binom{\mu}{\omega^{\prime} / 2}\left(\frac{16(d-1)^{8 r} \mu}{M^{2}}\right)^{\omega^{\prime} / 2} \leqslant(\log N)^{-\delta \log N / 2} \ll N^{-\omega},
\end{aligned}
$$

as needed.
Proof of (9.7). Recall the index sets $\mathrm{B}_{a}, \mathrm{~B}_{b} \subset \llbracket 1, \mu \rrbracket$ from (8.3), (8.4), and let $i \notin$ $\mathrm{B}_{a} \cup \mathrm{~B}_{b}$ be such that $b_{i} \nsim\left\{a_{k}, b_{m}: k \in \llbracket 1, \mu \rrbracket, m \in \llbracket 1, \nu \rrbracket \backslash\{i\}\right\}$. Denote the S-cell containing $b_{i}$ by $\mathbb{S}$; then $\mathbb{S}$ is not $\mathbb{S}_{1}$ and it is disjoint from $\left\{b_{k}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}\right\}$.

By the definition of $\mathrm{B}_{a}, \mathrm{~B}_{b}$ and since $b_{j}$ and $c_{j}$ are adjacent in $\mathcal{G}^{(\mathbb{T})}$ we have

$$
\begin{equation*}
\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(\left\{a_{i}, b_{i}, c_{i}\right\},\left\{a_{k}, b_{m}, c_{m}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}, m \in \llbracket 1, v \rrbracket \backslash\{i\}\right\}\right) \geqslant R / 2-2 . \tag{9.10}
\end{equation*}
$$

Since the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$ is obtained from $\mathcal{G}^{(\mathbb{T})}$ by removing edges $\left\{b_{j}, c_{j}\right\}_{j \leqslant \nu}$ and adding edges $\left\{a_{j}, b_{j}\right\}_{j \leqslant \nu}$, we also have

$$
\begin{equation*}
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\left\{a_{i}, b_{i}, c_{i}\right\},\left\{a_{k}, b_{m}, c_{m}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}, m \in \llbracket 1, v \rrbracket \backslash\{i\}\right\}\right) \geqslant R / 2-2 . \tag{9.11}
\end{equation*}
$$

Moreover, for any other S-cell $\mathbb{S}_{j} \neq \mathbb{S}, \mathbb{S}_{1}$, we have

$$
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\mathbb{S}, \mathbb{S}_{j}\right) \geqslant-2 r+\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(b_{i}, \mathbb{I}_{j}\right)-2 r \geqslant R / 2-2-4 r>2 r,
$$

where we used (9.11), $r \ll R$ and the definition (9.3) of S-cells, i.e. $\mathbb{S}=\mathbb{B}_{2 r}\left(b_{i}, \mathcal{G}^{(\mathbb{T})}\right)$ and $\mathbb{S}_{j}=\mathbb{B}_{2 r}\left(\mathbb{I}_{j}, \mathcal{G}^{(\mathbb{T})}\right)$. Thus $\mathbb{S}$ is a $\mathrm{S}^{\prime}$-cell itself, and

$$
\begin{aligned}
& \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\mathbb{S},\left\{a_{k}, b_{m}, c_{m}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}, m \in \llbracket 1, v \rrbracket \backslash\{i\}\right\}\right) \\
& \quad \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(b_{i},\left\{a_{k}, b_{m}, c_{m}: k \in \llbracket 1, \mu \rrbracket \backslash\{i\}, m \in \llbracket 1, v \rrbracket \backslash\{i\}\right\}\right)-2 r \\
& \quad \geqslant R / 2-2 r-2>R / 4,
\end{aligned}
$$

where we used $r \ll R$. Therefore only $i \in \mathrm{~B}_{a} \cup \mathrm{~B}_{b}$ or $b_{i} \sim\left\{a_{k}, b_{m}: k \in \llbracket 1, \mu \rrbracket, m \in\right.$ $\llbracket 1, \nu \rrbracket \backslash\{i\}\}$ contribute to the statement (9.7). Thus, combining (9.6) with the estimate $\left|B_{a} \cup B_{b}\right| \leqslant 5 \omega$ from (8.3), (8.4), and with (9.6), the estimate (9.7) follows.

## 10. Stability Under Removal of a Neighborhood

The following deterministic estimate shows that removing the neighborhood $\mathbb{T}$ from the graph $\mathcal{G}$ has a small effect on the Green's function in the complement of $\mathbb{T}$.

Proposition 10.1. Let $z \in \mathbb{C}_{+}$and $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$, and let $\mathcal{G} \in \bar{\Omega}$ (as in Sect. 3.2) be a graph such that, for all $i, j \in \llbracket N \rrbracket$,

$$
\begin{equation*}
\left|G_{i j}-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)\right| \leqslant\left|m_{s c}\right| q^{r} . \tag{10.1}
\end{equation*}
$$

Then, for all vertices $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$, we have

$$
\begin{equation*}
\left|G_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)\right| \leqslant 2\left|m_{s c}\right| q^{r} \tag{10.2}
\end{equation*}
$$

As discussed in Sect. 3, the removal of $\mathbb{T}$ is useful because our switchings have a smaller effect in $\mathcal{G}^{(\mathbb{T})}$ than they do in $\mathcal{G}$. Indeed, in the original graph $\mathcal{G}$, our switchings have the effect of removing two edges and adding two edges, while in $\mathcal{G}^{(\mathbb{T})}$ our switchings only remove the edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant \nu}$ and add the edges $\left\{a_{i}, b_{i}\right\}_{i \leqslant \nu}$. In the next few sections, we therefore work with $\mathcal{G}^{(\mathbb{T})}$ and its switched version $\tilde{\mathcal{G}}^{(\mathbb{T})}$, and only return to the full graph in Sect. 13.

The remainder of this section is devoted to the proof of the proposition. The main ingredients are that (i) given any $i, j$, there can only be a few vertices in $\mathbb{T}$ that are close to $i$ or $j$, by the deterministic assumption on the excess of $R$-neigborhoods, and (ii) that for all other vertices in $\mathbb{T}$, the decay of the Green's function implied by (10.1) shows that the removal of them has a small effect (Fig. 10).


Fig. 10. The innermost disk shows $\mathbb{T}$, the second largest disk the set $\mathbb{X}$, and the outermost disk $\mathcal{G}_{0}$. For any $i, j \in \mathbb{X}$, the graph $\mathcal{E}_{r}(i, j, \mathcal{G})$ is contained in $\mathcal{G}_{0}$
10.1. Step 1: removal of vertices close to $i$ or $j$. From (7.24), recall that $\mathbb{T}_{\ell}=\{v \in \mathcal{G}$ : $\left.\operatorname{dist}_{\mathcal{G}}(1, v)=\ell\right\}$ is the set of inner vertex boundary of $\mathcal{T}$. The first step of the proof of Proposition 10.1 consists of removing the vertices in $\mathbb{T}_{\ell}$ that are close to $i$ or $j$. The set of such vertices is

$$
\begin{equation*}
\left.\mathbb{U}=\left\{v \in \mathbb{T}_{\ell}: \operatorname{dist}_{\mathcal{G} \backslash \mathcal{T}}(i, v) \leqslant r\right\} \cup\left\{v \in \mathbb{T}_{\ell}: \operatorname{dist}_{\mathcal{G} \backslash \mathcal{T}}(j, v)\right\} \leqslant r\right\} \tag{10.3}
\end{equation*}
$$

where $\mathcal{G} \backslash \mathcal{T}$ is obtained from $\mathcal{G}$ by removing the subgraph $\mathcal{T}$ induced by $\mathcal{G}$ on $\mathbb{T}$ (but not removing $\mathbb{T}_{\ell}$ ). Then $|\mathbb{U}| \leqslant 2 \omega+2$ by (4.8). The following proposition shows that the Green's function remains to be locally approximated after removing $\mathbb{U}$.
Proposition 10.2. Under the assumptions of Proposition 10.1, for any vertex set $\mathbb{U} \subset \mathbb{T}$ with $|\mathbb{U}| \leqslant 2 \omega+2$,

$$
\begin{equation*}
\left|G_{i j}^{(\mathbb{U})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{U})}\right)\right)\right| \leqslant 3\left|m_{s c}\right| q^{r} / 2 . \tag{10.4}
\end{equation*}
$$

The proof of Proposition 10.2 follows a general structure that occurs repeatedly in similar estimates throughout the paper.

1. The first ingredient in this structure, which we refer to as localization, replaces the Green's function $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ of the vertex-dependent graph $\mathcal{E}_{r}(i, j, \mathcal{G})$ by the Green's function $P_{i j}=P_{i j}\left(\mathcal{G}_{0}\right)$ of a graph $\mathcal{G}_{0}$ that does not depend on $i, j$, by an application of Remark 5.3. For this, among other things, we need to verify the assumptions of Proposition 10.2.
2. The second ingredient, which we refer to as the starting point for the argument, is an algebraic relation that expresses the quantity to be estimated in a convenient form. The starting point typically follows from the Schur complement formula or the resolvent formula.
3. The third ingredient is a collection of previously established estimates required to estimate the expressions given by the starting point. It typically includes estimates on elements of Green's functions and graph distances.
The actual proofs then usually follow by combination of the above ingredients. In principle, this step is straightforward, but often several different cases need to be distinguished, which makes some of the arguments appear somewhat lengthy.

Below we provide the first instance of the strategy described above to prove Proposition 10.2.

Localization. We approximate $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ by a vertex independent Green's function $P_{i j}$ according to Remark 5.3, applied with $\mathcal{G}_{0}=\mathcal{B}_{3 r}(1, \mathcal{G})$ and $\mathbb{X}=\mathbb{B}_{2 r}(\mathbb{U}, \mathcal{G})$. We abbreviate

$$
\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right), \quad P=G\left(\mathcal{G}_{1}\right), \quad \mathcal{G}_{1}^{(\mathbb{U})}=\operatorname{TE}\left(\mathcal{G}_{0}^{(\mathbb{U})}\right), \quad P^{(\mathbb{U})}=G\left(\mathcal{G}_{1}^{(\mathbb{U})}\right)
$$

Verification of assumptions in Proposition 5.2. As subgraphs of $\mathcal{G} \in \bar{\Omega}$, the radius- $R$ neighborhoods of $\mathcal{G}_{0}$ and $\mathcal{G}_{0}^{(\mathbb{U})}$ have excess at most $\omega$. By convention, the deficit function of $\mathcal{G}_{0}$ vanishes, on each connected component of $\mathcal{G}_{0}^{(\mathbb{U})}$, the deficit function of $\mathcal{G}^{(\mathbb{U})}$ obeys $\sum g(v) \leqslant \omega+(2 \omega+2) \leqslant 8 \omega$, by Proposition 4.4. Thus the assumptions for (5.5) are verified for both graphs. For any $i, j \in \mathbb{X}$, it follows from (5.5), we have

$$
\begin{align*}
\left|P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)-P_{i j}\right| & \leqslant 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}  \tag{10.5}\\
\left|P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{U})}\right)\right)-P_{i j}^{(\mathbb{U})}\right| & \leqslant 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}, \tag{10.6}
\end{align*}
$$

provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$.

Starting point. To remove $\mathbb{U}$, we apply the Schur complement formula (B.4): for any $i, j \in \mathcal{G}^{(\mathbb{U})}$,

$$
\begin{align*}
G_{i j}-G_{i j}^{(\mathbb{U})} & =\sum_{x, y \in \mathbb{U}} G_{i x}\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1} G_{y j} \\
P_{i j}-P_{i j}^{(\mathbb{U})} & =\sum_{x, y \in \mathbb{U}} P_{i x}\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1} P_{y j} \tag{10.7}
\end{align*}
$$

Our goal is to show that the difference $G_{i j}^{(\mathbb{U})}-P_{i j}^{(\mathbb{U})}$ is small, by using that the difference of $G$ and $P$ is small. As evident from the right-hand sides of (10.7), for this we require upper bounds on the entries of $G$ and $\left(\left.G\right|_{\mathbb{U}}\right)^{-1}$ (and analogously for $P$ and $\left(\left.P\right|_{\mathbb{U}}\right)^{-1}$ ).

Green's function estimates. By assumption (10.1) and (5.3)-(5.4), we have

$$
\begin{cases}\left|G_{x x}\right| \geqslant\left|m_{d}\right|-\left|m_{s c}\right| / 4-\left|m_{s c}\right| q^{r} \geqslant 3\left|m_{s c}\right| / 5, &  \tag{10.8}\\ \left|G_{x w}\right| \leqslant 2^{\omega+2}\left|m_{s c}\right| q+\left|m_{s c}\right| q^{r} & (x \neq w), \\ \left|G_{x w}\right| \leqslant\left|m_{s c}\right| q^{r} & \left(\operatorname{dist}_{\mathcal{G}}(x, w)>r\right)\end{cases}
$$

These bounds imply the upper bounds for the entries of $\left(\left.G\right|_{\mathbb{U}}\right)^{-1}$ stated in the following claim. The claim essentially follows from the fact that the off-diagonal entries of $\left.G\right|_{\mathbb{U}}$ are much smaller than the diagonal entries which have size roughly $m_{s c}$.

Claim 10.3. Under the assumptions of Proposition 10.1 , for any $\mathbb{U} \subset \mathbb{T}$ with $|\mathbb{U}| \leqslant$ $2 \omega+2$, and any $x, y \in \mathbb{U}$,

$$
\begin{equation*}
\left|\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1}\right| \leqslant 2 /\left|m_{s c}\right|, \quad\left|\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1}\right| \leqslant 2 /\left|m_{s c}\right| . \tag{10.9}
\end{equation*}
$$

Proof. By the identity $\left.G\right|_{\mathbb{U}}\left(\left.G\right|_{\mathbb{U}}\right)^{-1}=I_{\mathbb{U} \times \mathbb{U}}$, we have

$$
\begin{equation*}
\delta_{x y}=G_{x x}\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1}+\sum_{w \in \mathbb{U} \backslash\{x\}} G_{x w}\left(\left.G\right|_{\mathbb{U}}\right)_{w y}^{-1} \tag{10.10}
\end{equation*}
$$

Let $\Gamma:=\max _{x, y \in \mathbb{U}}\left|\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1}\right|$. Then (10.8) and (10.10) imply

$$
\left|G_{x x}\right|\left|(G \mid \mathbb{U})_{x y}^{-1}\right| \leqslant \delta_{x y}+\sum_{w \in \mathbb{U} \backslash\{x\}}\left|G_{x w}\right| \Gamma \leqslant 1+\left(2^{\omega+2} q+q^{r}\right)|\mathbb{U}|\left|m_{s c}\right| \Gamma .
$$

Taking the maximum over $x, y \in \mathbb{U}$ in the equation above and using (10.8) gives

$$
\Gamma \leqslant \frac{5}{3\left|m_{s c}\right|}+\frac{5}{3}\left(2^{\omega+2} q+q^{r}\right)|\mathbb{U}| \Gamma \leqslant \frac{5}{3\left|m_{s c}\right|}+\frac{\Gamma}{6}
$$

provided that $\sqrt{d-1} \geqslant(\omega+1) 2^{\omega+6} . \Gamma \leqslant 2 /\left|m_{s c}\right|$ follows by rearranging. The same argument applies to $\left.P\right|_{\mathbb{U}}$, and we obtain (10.9).

Proof of Proposition 10.2. First consider the case that at least one of $i$ and $j$ is not in $\mathbb{X}$ (i.e. far from $\mathbb{U}$ ). Then $\mathcal{E}_{r}(i, j, \mathcal{G})=\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{U})}\right)$, and (10.4) follows directly from

$$
\begin{aligned}
\left|G_{i j}-G_{i j}^{(\mathbb{U})}\right| & =\left|\sum_{x, y \in \mathbb{U}} G_{i x}\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1} G_{y j}\right| \\
& \leqslant\left(2^{\omega+2} q+q^{r}\right) q^{r}|\mathbb{U}|^{2}\left|m_{s c}\right|^{2}\left(2 /\left|m_{s c}\right|\right) \leqslant\left|m_{s c}\right| q^{r} / 2
\end{aligned}
$$

where we used (10.8), (10.9) and that $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{\omega+7}$.
Next consider the main case $i, j \in \mathbb{X}$. By (10.5)-(10.6), it suffices to bound the right-hand side of

$$
\begin{equation*}
\left|G_{i j}^{(\mathbb{U})}-P_{i j}^{(\mathbb{U})}\right| \leqslant\left|G_{i j}-P_{i j}\right|+\sum_{x, y \in \mathbb{U}}\left|G_{i x}\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1} G_{y j}-P_{i x}\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1} P_{y j}\right|, \tag{10.11}
\end{equation*}
$$

which follows from taking difference of expressions in (10.7). By (10.1) and (10.5)(10.6), since for all vertices $i, j \in \mathbb{X}$ and $x, y \in \mathbb{U} \subset \mathbb{T}$, all subgraphs $\mathcal{E}_{r}(i, j, \mathcal{G})$, $\mathcal{E}_{r}(i, x, \mathcal{G}), \mathcal{E}_{r}(y, j, \mathcal{G}), \mathcal{E}_{r}(x, y, \mathcal{G})$ are contained in $\mathcal{G}_{0}$,

$$
\begin{equation*}
\left|G_{i j}-P_{i j}\right|,\left|G_{i x}-P_{i x}\right|,\left|G_{y j}-P_{y j}\right|,\left|G_{x y}-P_{x y}\right| \leqslant\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \tag{10.12}
\end{equation*}
$$

Together with (10.9) and the resolvent formula (B.1), it follows that

$$
\begin{align*}
\left|\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1}-\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1}\right| & =\left|\left[\left(\left.G\right|_{\mathbb{U}}\right)^{-1}\left(\left.G\right|_{\mathbb{U}}-\left.P\right|_{\mathbb{U}}\right)\left(\left.P\right|_{\mathbb{U}}\right)^{-1}\right]_{x y}\right| \\
& \leqslant 4|\mathbb{U}|^{2}\left(1+2^{2 \omega+3} q\right) q^{r} /\left|m_{s c}\right| . \tag{10.13}
\end{align*}
$$

Using (10.8), (10.9), (10.12), and (10.13), the sum on the right-hand side of (10.11) is bounded by

$$
\begin{align*}
& \sum_{x, y \in \mathbb{U}}\left|G_{i x}-P_{i x}\right|\left|\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1} G_{y j}\right|+\sum_{x, y \in \mathbb{U}}\left|P_{i x}\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1}\right|\left|G_{y j}-P_{y j}\right| \\
& \quad+\sum_{x, y \in \mathbb{U}}\left|P_{i x}\right|\left|\left(\left.G\right|_{\mathbb{U}}\right)_{x y}^{-1}-\left(\left.P\right|_{\mathbb{U}}\right)_{x y}^{-1}\right|\left|G_{y j}\right| \\
& \leqslant 4\left|m_{s c}\right| q^{r}\left(1+2^{2 \omega+3} q\right)\left(|\mathbb{U}|^{2}\left(2^{\omega+2} q+q^{r}\right)+|\mathbb{U}|^{4}\left(2^{\omega+2} q+q^{r}\right)^{2}\right) \leqslant\left|m_{s c}\right| q^{r} / 4 \tag{10.14}
\end{align*}
$$

where we used that $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$. The claim follows by combining this bound for (10.11) with (10.5)-(10.6).
10.2. Step 2: estimate of $G_{i j}^{(\mathbb{T})}$ using $G_{i j}^{(\mathbb{U})}$. Next we pass from $G_{i j}^{(\mathbb{U})}$ to $G_{i j}^{(\mathbb{T})}$. By definition of $\mathbb{U}$, there are no vertices in $\mathbb{T} \backslash \mathbb{U}$ that are close to $i$ or $j$ in the graph $\mathcal{G}^{(\mathbb{T})}$. Thus the step mostly follows from the decay of the Green's function together with the assumption that there are few cycles.

Starting point. Define $\mathcal{G}_{0}=\mathcal{B}_{3 r}(1, \mathcal{G})$ and $\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right)$ as in Sect. 10.1. The normalized adjacency matrices of $\mathcal{G}^{(\mathbb{U})}$ and $\mathcal{G}_{1}^{(\mathbb{U})}=\operatorname{TE}\left(\mathcal{G}_{0}^{(\mathbb{U})}\right)$ have the block matrix form

$$
\left[\begin{array}{cc}
H^{(\mathbb{U})} & B^{\prime} \\
B & D
\end{array}\right], \quad\left[\begin{array}{cc}
H^{(\mathbb{U})} & B_{1}^{\prime} \\
B_{1} & D_{1}
\end{array}\right]
$$

where $H^{(\mathbb{U})}$ is the normalized adjacency matrix of $\mathcal{T}^{(\mathbb{U})}$. The nonzero entries of $B$ and $B_{1}$ occur for the indices $(i, j) \in\left\{a_{1}, \ldots, a_{\mu}\right\} \times \mathbb{T}_{\ell} \backslash \mathbb{U}$ and take values $1 / \sqrt{d-1}$. Notice that $\tilde{B}_{i j}=\left(\tilde{B}_{1}\right)_{i j}$. We denote the normalized Green's functions of $\mathcal{G}^{(\mathbb{U})}$ and $\mathcal{G}_{1}^{(\mathbb{U})}$ by $G^{(\mathbb{U})}$ and $P^{(\mathbb{U})}$ respectively. By the Schur complement formula (B.4), for any $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
G_{i j}^{(\mathbb{T})}=(D-z)_{i j}^{-1}=G_{i j}^{(\mathbb{U})}-\sum_{x, y \in \mathbb{T} \backslash \mathbb{U}} G_{i x}^{(\mathbb{U})}\left(G^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1} G_{y j}^{(\mathbb{U})}, \tag{10.15}
\end{equation*}
$$

and also

$$
\begin{align*}
& \left(\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}\right)^{-1}=H^{(\mathbb{U})}-z-B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1},  \tag{10.16}\\
& \left(\left.G^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}\right)^{-1}=H^{(\mathbb{U})}-z-B^{\prime}(D-z)^{-1} B . \tag{10.17}
\end{align*}
$$

Claim 10.4. For any $x \in \mathbb{T}_{\ell} \backslash \mathbb{U}$,

$$
\begin{equation*}
\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1}\right| \leqslant 2(|z|+1) \tag{10.18}
\end{equation*}
$$

Proof. For any $x \in \mathbb{T}_{\ell} \backslash \mathbb{U}$, by (10.16) we have

$$
\begin{align*}
\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1}\right| & =\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(H^{(\mathbb{U})}-z-B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}\right)_{x y}\right| \\
& \leqslant \sum_{y \in \mathbb{T} \backslash \mathbb{U}} H_{x y}^{(\mathbb{U})}+|z|+\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}\right)_{x y}\right| \\
& \leqslant \frac{\omega+1}{\sqrt{d-1}}+|z|+\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}\right)_{x y}\right| . \tag{10.19}
\end{align*}
$$

In the last inequality, we used that the excess of $\mathcal{T}^{(\mathbb{U})}$ is at most $\omega$ so that for any $x \in \mathbb{T}_{\ell} \backslash \mathbb{U}$, we have $\operatorname{deg}_{\mathcal{T}(\mathbb{U})}(x) \leqslant \omega+1$ and thus $\sum_{y \in \mathbb{T} \backslash \mathbb{U}} H_{x y}^{(\mathbb{U})} \leqslant(\omega+1) / \sqrt{d-1}$. The terms in the last sum in (10.19) vanish unless $y \in \mathbb{T}_{\ell} \backslash \mathbb{U}$. Therefore the sum is bounded by

$$
\begin{align*}
& \sum_{\substack{i \in \llbracket 1, \mu \rrbracket \\
l_{i}=x}}\left(B_{1}^{\prime}\right)_{l_{i} a_{i}}\left|\left(D_{1}-z\right)_{a_{i} a_{i}}^{-1}\right|\left(B_{1}\right)_{a_{i} l_{i}}+\sum_{\substack{i \neq j \in \llbracket 1, \mu \rrbracket \\
l_{i}, l_{j} \in \mathbb{T} \ell \backslash}}\left(B_{1}^{\prime}\right)_{l_{i} a_{i} \mid}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right|\left(B_{1}\right)_{a_{j} l_{j}} \\
& \leqslant \frac{1}{d-1} \sum_{i \in \llbracket 1, \mu \rrbracket} 1_{x=l_{i}}\left|\left(D_{1}-z\right)_{a_{i} a_{i}}^{-1}\right|+\frac{1}{d-1} \sum_{i \neq j \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right| \tag{10.20}
\end{align*}
$$

For the first sum in (10.20), the number of vertices $a_{i}$ adjacent to $x$ is at most $d-1$. For the
 $R / 2$. For these pairs, $a_{i}$ and $a_{j}$ are in different connected components of the graph $\mathcal{G}_{1}^{(\mathbb{T})}$ which means that $\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right|=0$. Therefore there are at most $(2 \omega)^{2}$ non-vanishing terms in the second sum. We use also that

$$
\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right|=P_{a_{i} a_{j}}\left(\operatorname{TE}\left(\mathcal{G}_{0}^{(\mathbb{T})}\right)\right) \leqslant 3\left|m_{s c}\right| / 2
$$

which follows from (5.6), provided that $\sqrt{d-1} \geqslant 2^{2 \omega+3}$. Therefore,

$$
\begin{equation*}
(10.20) \leqslant\left(1+\frac{(2 \omega)^{2}}{d-1}\right) \max _{i, j \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right| \leqslant \frac{3}{2}\left|m_{s c}\right|\left(1+\frac{(2 \omega)^{2}}{d-1}\right) \tag{10.21}
\end{equation*}
$$

By combining (10.19) and (10.21), we have shown that

$$
\sum_{y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1}\right| \leqslant \frac{\omega+1}{\sqrt{d-1}}+|z|+\frac{3}{2}\left|m_{s c}\right|\left(1+\frac{(2 \omega)^{2}}{d-1}\right) \leqslant 2(|z|+1)
$$

provided that $\sqrt{d-1} \geqslant 8(\omega+1)$. This completes the proof.
Claim 10.5. For any $x, y \in \mathbb{T} \backslash \mathbb{U}$,

$$
\begin{gather*}
\left|G_{x y}^{(\mathbb{U})}-P_{x y}^{(\mathbb{U})}\right| \leqslant 2\left|m_{s c}\right| q^{r},  \tag{10.22}\\
\left.\left|G^{(\mathbb{U})}\right| \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1}-\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x y}^{-1} \mid \leqslant 48(|z|+1) q^{r} . \tag{10.23}
\end{gather*}
$$

Proof. Define matrices $\mathcal{W}$ and $\mathcal{E}$ by

$$
\begin{align*}
\left.G^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}} & =\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}+\mathcal{W},  \tag{10.24}\\
\left(\left.G^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U})^{-1}}\right. & =\left(\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U})^{-1}+\mathcal{E} .} .\right. \tag{10.25}
\end{align*}
$$

From (10.4), (10.5)-(10.6), for any $x, y \in \mathbb{T} \backslash \mathbb{U}$, we have $\left|\mathcal{W}_{x y}\right| \leqslant 2\left|m_{s c}\right| q^{r}$. We claim the same estimate holds for the entries of the matrix $\mathcal{E}$. Notice from (10.16), (10.17) that $\mathcal{E}_{x y} \neq 0$ only for $x, y \in \mathbb{T}_{\ell} \backslash \mathbb{U}$. Let $\Gamma:=\max _{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|\mathcal{E}_{x y}\right|=\max _{x, y \in \mathbb{T}_{\ell} \backslash \mathbb{U}}\left|\mathcal{E}_{x y}\right|$. By taking the product of (10.24) and (10.25),

$$
\begin{equation*}
\mathcal{E}+\left(\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}\right)^{-1} \mathcal{W} \mathcal{E}+\left(\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}\right)^{-1} \mathcal{W}\left(\left.P^{(\mathbb{U})}\right|_{\mathbb{T} \backslash \mathbb{U}}\right)^{-1}=0 . \tag{10.26}
\end{equation*}
$$

For any $x, y \in \mathbb{T} \backslash \mathbb{U}$, therefore

$$
\begin{aligned}
\left|\mathcal{E}_{x y}\right| \leqslant & \sum_{i, j \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x i}^{-1}\right|\left|\mathcal{W}_{i j}\right|\left|\mathcal{E}_{j y}\right| \\
& +\sum_{i, j \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x i}^{-1}\right|\left|\mathcal{W}_{i j}\right|\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{j y}^{-1}\right| \\
\leqslant & |\mathbb{T} \backslash \mathbb{U}|\left(2\left|m_{s c}\right| q^{r}\right) \Gamma \sum_{i \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x i}^{-1}\right| \\
& +\left(2\left|m_{s c}\right| q^{r}\right) \sum_{i \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{x i}^{-1}\right| \sum_{j \in \mathbb{T} \backslash \mathbb{U}}\left|\left(P^{(\mathbb{U})} \mid \mathbb{T} \backslash \mathbb{U}\right)_{j y}^{-1}\right| \\
\leqslant & 4(|z|+1)(d-1)^{\ell}\left(2\left|m_{s c}\right| q^{r}\right) \Gamma+4(|z|+1)^{2}\left(2\left|m_{s c}\right| q^{r}\right) \\
\leqslant & \Gamma / 2+4(|z|+1)^{2}\left(2\left|m_{s c}\right| q^{r}\right) .
\end{aligned}
$$

For the second inequality, we used $\left|\mathcal{W}_{x y}\right| \leqslant 2\left|m_{s c}\right| q^{r}$; for the third inequality we used $|\mathbb{T} \backslash \mathbb{U}| \leqslant|\mathbb{T}| \leqslant 1+d+d(d-1)+\cdots+d(d-1)^{\ell-1} \leqslant 2(d-1)^{\ell}$, and (10.18); for the last inequality, we used $r=2 \ell+1$, so that $(d-1)^{\ell} q^{r} \leqslant(d-1)^{-1 / 2}$ and $\left|z m_{s c}\right| \leqslant 2$. Taking the maximum on the right-hand side of the above inequality, and rearranging, we get

$$
\Gamma \leqslant 16(|z|+1)^{2}\left|m_{s c}\right| q^{r} \leqslant 48(|z|+1) q^{r}
$$

as claimed.

Proof of Proposition 10.1. To prove the proposition, we define $\mathbb{U}$ by (10.3), and show that

$$
\begin{equation*}
\left|G_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{U})}\right| \leqslant\left|m_{s c}\right| q^{r} / 4 \tag{10.27}
\end{equation*}
$$

This implies the claim. Indeed, the definition of $\mathbb{U}$ implies that $\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{U})}\right)=\mathcal{E}_{r}(i, j$, $\mathcal{G}^{(\mathbb{T})}$ ), and therefore (10.2) follows from (10.5)-(10.6), (10.27) and Proposition 10.2:

$$
\begin{aligned}
& \left|G_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)\right| \\
& \quad \leqslant\left|G_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{U})}\right|+\left|G_{i j}^{(\mathbb{U})}-P_{i j}^{(\mathbb{U})}\right|+\left|P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{U})}\right)\right)-P_{i j}^{(\mathbb{U})}\right| \\
& \quad \leqslant\left|m_{s c}\right| q^{r} / 4+3\left|m_{s c}\right| q^{r} / 2+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \leqslant 2\left|m_{s c}\right| q^{r} .
\end{aligned}
$$

Thus it remains to prove (10.27). By definition of $\mathbb{U}$, we have $\operatorname{dist}_{\mathcal{G}^{(\mathbb{U})}}(\{i, j\}, \mathbb{T} \backslash \mathbb{U})>$ $r$, and therefore Proposition 10.2 implies

$$
\begin{equation*}
\max _{x \in \mathbb{T} \backslash \mathbb{U}}\left\{\left|G_{i x}^{(\mathbb{U})}\right|,\left|G_{j x}^{(\mathbb{U})}\right|\right\} \leqslant 3\left|m_{s c}\right| q^{r} / 2 \leqslant 2\left|m_{s c}\right| q^{r} . \tag{10.28}
\end{equation*}
$$

Furthermore, by (10.15),

$$
\begin{align*}
\left|G_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{U})}\right| & \leqslant \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|G_{i x}^{(\mathbb{U})}\left(H^{(\mathbb{U})}-z-B^{\prime} G^{(\mathbb{T})} B\right)_{x y} G_{y j}^{(\mathbb{U})}\right| \\
& \leqslant 4\left|m_{s c}\right|^{2} q^{2 r} \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(H^{(\mathbb{U})}-z-B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}+\mathcal{E}\right)_{x y}\right| \tag{10.29}
\end{align*}
$$

with $\mathcal{E}$ as in (10.25). For the sum, we have

$$
\begin{align*}
& \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(H^{(\mathbb{U})}-z-B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}+\mathcal{E}\right)_{x y}\right| \\
& \leqslant \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}} H_{x y}^{(\mathbb{U})}+\sum_{\substack{i, j \in \llbracket 1, \mu \rrbracket \\
l_{i}, l_{j} \in \mathbb{T} \ell \backslash}}\left(B_{1}^{\prime}\right)_{l_{i} a_{i} \mid}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right|\left(B_{1}\right)_{a_{j} l_{j}} \\
& \quad+|z||\mathbb{T} \backslash \mathbb{U}|+|\mathbb{T} \backslash \mathbb{U}|^{2} \max _{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|\mathcal{E}_{x y}\right| \\
& \leqslant \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}} H_{x y}^{(\mathbb{U})}+\frac{1}{d-1} \sum_{i, j \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right| \\
& \quad+2(d-1)^{\ell}|z|+4(d-1)^{2 \ell}\left(48(|z|+1) q^{r}\right) \tag{10.30}
\end{align*}
$$

where we used $|\mathbb{T} \backslash \mathbb{U}| \leqslant 2(d-1)^{\ell}$ and (10.23). By our assumption $\mathcal{G} \in \bar{\Omega}$, the subgraph $\mathcal{T}$ has excess at most $\omega$. Therefore the total number of edges of $\mathcal{T}$ is bounded by $|\mathbb{T}|+\omega \leqslant 1+d+d(d-1)+\cdots+d(d-1)^{\ell-1}+\omega \leqslant 2(d-1)^{\ell}$, and

$$
\begin{equation*}
\sum_{x, y \in \mathbb{T} \backslash \mathbb{U}} H_{x y}^{(\mathbb{U})} \leqslant \frac{2(d-1)^{\ell}}{\sqrt{d-1}} \tag{10.31}
\end{equation*}
$$

By the same argument as for (10.21), we get

$$
\begin{align*}
& \frac{1}{d-1} \sum_{i, j \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right| \\
& \quad=\frac{1}{d-1} \sum_{i \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{i}}^{-1}\right|+\frac{1}{d-1} \sum_{i \neq j \in \llbracket 1, \mu \rrbracket}\left|\left(D_{1}-z\right)_{a_{i} a_{j}}^{-1}\right| \\
& \leqslant \frac{3\left|m_{s c}\right|}{2}\left(\frac{\mu}{d-1}+\frac{(2 \omega)^{2}}{d-1}\right) \leqslant \frac{3\left|m_{s c}\right|}{2}\left(2(d-1)^{\ell}+\frac{(2 \omega)^{2}}{d-1}\right) \tag{10.32}
\end{align*}
$$

where we used $\mu \leqslant 2(d-1)^{\ell+1}$. By combining (10.30)-(10.32), we have

$$
\begin{aligned}
& \sum_{x, y \in \mathbb{T} \backslash \mathbb{U}}\left|\left(H-z-B_{1}^{\prime}\left(D_{1}-z\right)^{-1} B_{1}+\mathcal{E}\right)_{x y}\right| \\
& \leqslant 2(d-1)^{\ell}|z|+4(d-1)^{2 \ell}\left(48(|z|+1) q^{r}\right) \\
& \quad+\frac{2(d-1)^{\ell}}{\sqrt{d-1}}+\frac{3\left|m_{s c}\right|}{2}\left(2(d-1)^{\ell}+\frac{(2 \omega)^{2}}{d-1}\right) \\
& \leqslant 5(|z|+1)(d-1)^{\ell} .
\end{aligned}
$$

Combining the above estimate with (10.29), and using $\left|z m_{s c}\right| \leqslant 2$,

$$
\begin{aligned}
\left|G_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{U})}\right| & \leqslant 4\left|m_{s c}\right|^{2} q^{2 r} 5(|z|+1)(d-1)^{\ell} \\
& \leqslant \frac{20(|z|+1)\left|m_{s c}\right|}{\sqrt{d-1}}\left|m_{s c}\right| q^{r} \leqslant\left|m_{s c}\right| q^{r} / 4
\end{aligned}
$$

This finishes the proof.

## 11. Stability Under Switching

We recall the S -cells and $\mathrm{S}^{\prime}$-cells from Definition 9.1, and the set of switching data $\mathrm{S}(\mathcal{G})$ from Sect. 7.2. The results of this section are the following stability estimates.
Proposition 11.1. Let $z \in \mathbb{C}_{+}, \mathcal{G} \in \bar{\Omega}$ (as in Sect. 3.2) be a d-regular graph, and $K \geqslant 2$ be a constant such that, for all $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
\left|G_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right), z\right)\right| \leqslant K\left|m_{s c}\right| q^{r} . \tag{11.1}
\end{equation*}
$$

Then there exists an event $F(\mathcal{G}) \subset S(\mathcal{G})$ with $\mathbb{P}_{\mathcal{G}}(F(\mathcal{G}))=1-o\left(N^{-\omega+\delta}\right)$, explicitly defined in Sect. 11.1 below, such that for any $\mathbf{S} \in F(\mathcal{G})$ such that $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$ the following hold:

- For $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
\left|\hat{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right), z\right)\right| \leqslant 2 K\left|m_{s c}\right| q^{r} \tag{11.2}
\end{equation*}
$$

$-\operatorname{For}(i) i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$ in different S -cells, or (ii) $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$ such that $j \in \mathbb{S}_{t}$ and $i \nsim \mathbb{S}_{t}$ for some $t$,

$$
\begin{equation*}
\left|\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant \frac{2 M}{\sqrt{N \eta}} \tag{11.3}
\end{equation*}
$$

- For $i, j \in \llbracket N \rrbracket \backslash \mathbb{T}$,

$$
\begin{equation*}
\left|\tilde{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \tilde{\mathcal{G}}^{(\mathbb{T})}\right), z\right)\right| \leqslant 2^{7} K^{3}\left|m_{s c}\right| q^{r} \tag{11.4}
\end{equation*}
$$

For all estimates, we assume $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$, $\omega^{\prime} q^{r} \ll 1$ and that $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}$ (where $M$ is as in (9.4)).

In particular, for any $\mathcal{G} \in \Omega(z, \ell)$, Proposition 10.1 implies that the assumptions of Proposition 11.1 are satisfied with $K=2$. Thus Propositions 10.1 and 11.1 together show that, for any graph $\mathcal{G} \in \Omega(z, \ell)$, with high probability under $\mathbf{S}$, the switched graph $\tilde{\mathcal{G}}$ belongs to $\Omega_{1}^{+}(z, \ell)$ (as in Sect. 3).
11.1. Definition of the event $F(\mathcal{G})$. We fix $M$ and $\omega^{\prime}$ by (9.4). We will prove Proposition 11.1 with the set $F(\mathcal{G}) \subset \mathrm{S}(\mathcal{G})$ defined by the following conditions on the switching data $\mathbf{S}$ :

1. At least $\mu-3 \omega$ edges are switchable, i.e. the event in the probability in (7.14) holds:

$$
\begin{equation*}
\left|W_{\mathbf{S}}\right| \geqslant \mu-3 \omega . \tag{11.5}
\end{equation*}
$$

2. All except for $\omega$ of the vertices $\left\{c_{1}, c_{2}, \ldots, c_{\mu}\right\}$ have radius- $R$ tree neighborhoods in $\mathcal{G}^{(\mathbb{T})}$, i.e. (8.5) holds.
3. The vertices $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\mu}\right\}$ do not cluster in the sense of distance, i.e. (4.6)-(4.8) and (8.2)-(8.4) hold.
4. The vertices $\left\{b_{1}, b_{2}, \ldots, b_{\mu}\right\}$ do not cluster in the sense of the Green's function, i.e. (9.5)-(9.7) hold.

Then, for any $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, we have

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}(F(\mathcal{G}))=1-o\left(N^{-\omega+\delta}\right) . \tag{11.6}
\end{equation*}
$$

Indeed, (i) follows from Proposition 7.6, (ii) follows from (8.5), (iii) follows from Propositions 4.3 and 8.1, and (iv) follows from Proposition 9.2.
11.2. Proof of (11.2). The proof of (11.2) follows the structure described below (10.4). Moreover, similarly to the proof of Proposition 10.1, we distinguish between vertices $i, j$ that are close to the edges that get removed in going from $\mathcal{G}^{(\mathbb{T})}$ to $\hat{\mathcal{G}}^{(\mathbb{T})}$ and vertices that are far from these edges. We first focus on $i, j$ that are close to those edges that get removed.

Localization. First, we replace $P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G})\right)$ by the vertex-independent Green's function $P_{i j}$, using Remark 5.3 with

$$
\begin{equation*}
\mathcal{G}_{0}=\mathcal{B}_{3 r}\left(\left\{b_{1}, b_{2}, \ldots, b_{\nu}\right\}, \mathcal{G}^{(\mathbb{T})}\right), \quad \mathbb{X}=\mathbb{B}_{2 r}\left(\left\{b_{1}, b_{2}, \ldots, b_{\nu}\right\}, \mathcal{G}^{(\mathbb{T})}\right) \tag{11.7}
\end{equation*}
$$

Moreover, we define $\hat{\mathcal{G}}_{0}$ to be the graph obtained by removing the edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant v}$ from $\mathcal{G}_{0}$. The deficit function of $\hat{\mathcal{G}}_{0}$ is defined to be the restriction of that of $\hat{\mathcal{G}}^{(\mathbb{T})}$. We abbreviate

$$
\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right), \quad P=G\left(\mathcal{G}_{1}\right), \quad \hat{\mathcal{G}}_{1}=\operatorname{TE}\left(\hat{\mathcal{G}}_{0}\right), \quad \hat{P}=G\left(\hat{\mathcal{G}}_{1}\right) .
$$

Notice that $\hat{\mathcal{G}}_{1}$ is equivalently obtained by removing the edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant \nu}$ from $\mathcal{G}_{1}$. The following properties of $\mathcal{G}_{0}$ follow from (8.3) and (8.4).

Claim 11.2. Assume (8.3) and (8.4). Then each connected component of either $\mathcal{G}_{0}$ or $\hat{\mathcal{G}_{0}}$ contains at most $5 \omega$ elements from $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$. More precisely,

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: a_{i} \in \mathbb{K}\right\}\right| \leqslant 3 \omega, \quad\left|\left\{i \in \llbracket 1, \nu \rrbracket: b_{i} \in \mathbb{K}\right\}\right| \leqslant 2 \omega, \tag{11.8}
\end{equation*}
$$

where $\mathbb{K}$ is the vertex set of any connected component of $\mathcal{G}_{0}$ or $\hat{\mathcal{G}}_{0}$.
Proof. The claim follows directly from (8.3) and (8.4) and the definitions of $\mathcal{G}_{0}$ and $\hat{\mathcal{G}_{0}}$.

Verification of assumptions in Proposition 5.2. Since both $\mathcal{G}_{0}$ and $\hat{\mathcal{G}}_{0}$ are subgraphs of $\mathcal{G} \in \bar{\Omega}$, their radius- $R$ neighborhoods have excess at most $\omega$. Let $\mathbb{K}$ be the vertex set of any connected component of $\mathcal{G}_{0}$ or $\hat{\mathcal{G}}_{0}$. Since the deficit function of $\mathcal{G}_{0}$ (respectively $\hat{\mathcal{G}}_{0}$ ) is the restriction of that of $\mathcal{G}^{(\mathbb{T})}$ (respectively $\hat{\mathcal{G}}^{(\mathbb{T})}$ ), any of the vertices $a_{i}, b_{i}, c_{i} \in \mathbb{K}$ contributes 1 to the sum of the deficit function over $\mathbb{K}$. By Claim 11.2, the sums of the deficit functions over any of the connected components of $\mathcal{G}_{0}$ and $\hat{\mathcal{G}}_{0}$ are therefore bounded by $3 \omega+2 \times 2 \omega \leqslant 8 \omega$. Thus the assumptions of (5.5) are verified for both $\mathcal{G}_{0}$ and $\hat{\mathcal{G}_{0}}$, and for any $i, j \in \mathbb{X}$,

$$
\begin{equation*}
\mid P_{i j}-P_{i j}\left(\mathcal{E}_{r}\left(\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)\left|\leqslant 2^{2 \omega+3}\right| m_{s c} \mid q^{r+1}\right. \tag{11.9}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$, and an analogous estimate holds for $\hat{P}$. Up to a small error, we can therefore use $P$ instead of $P\left(\mathcal{E}_{r}\left(\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)\right.$ and $\hat{P}$ instead of $P\left(\mathcal{E}_{r}\left(\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right.$.

Starting point. By the resolvent identity (B.1), we have:

$$
\begin{align*}
\hat{G}^{(\mathbb{T})}-G^{(\mathbb{T})} & =G^{(\mathbb{T})} \Delta \hat{G}^{(\mathbb{T})},  \tag{11.10}\\
\hat{P}-P & =P \Delta \hat{P}, \tag{11.11}
\end{align*}
$$

where $\Delta=\sum_{k=1}^{v}\left(e_{b_{k} c_{k}}+e_{c_{k} b_{k}}\right) / \sqrt{d-1}$. Taking the difference of (11.10) and (11.11), we obtain

$$
\begin{align*}
\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}= & \left(G_{i j}^{(\mathbb{T})}-P_{i j}\right)+\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left(G_{i x}^{(\mathbb{T})}-P_{i x}\right) \hat{P}_{y j} \\
& +\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}} G_{i x}^{(\mathbb{T})}\left(\hat{G}_{y j}^{(\mathbb{T})}-\hat{P}_{y j}\right) \tag{11.12}
\end{align*}
$$

where the summation is over the oriented edges

$$
\begin{equation*}
(x, y) \in \boldsymbol{E}=\left\{\left(b_{1}, c_{1}\right), \ldots,\left(b_{\nu}, c_{\nu}\right),\left(c_{1}, b_{1}\right), \ldots,\left(c_{\nu}, b_{v}\right)\right\} \tag{11.13}
\end{equation*}
$$

We regard (11.12) as an equation for $\hat{G}^{(\mathbb{T})}-\hat{P}$, and will show that $\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}$ is small as a consequence of the smallness of $G^{(\mathbb{T})}-P$.

Green's function estimates. We first collect some estimates on Green's functions, used repeatedly:

$$
\begin{cases}\left|G_{i j}^{(\mathbb{T})}\right|,\left|P_{i j}\right|,\left|\hat{P}_{i j}\right| \leqslant 2\left|m_{s c}\right|, & (\text { all } i, j),  \tag{11.14}\\ \left|G_{i j}^{(\mathbb{T})}\right| \leqslant K\left|m_{s c}\right| q^{r}, & \left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, j) \geqslant 2 r\right), \\ \left|G_{i b_{k}}^{(\mathbb{T})}\right|,\left|G_{i c_{k}}^{(\mathbb{T})}\right| \leqslant M / \sqrt{N \eta}, & \left(i, b_{k} \text { are in different S-cells, or } i \nsucc b_{k}\right)\end{cases}
$$

The first estimate follows from (5.6), and (11.1); the second estimate follows from assumption (11.1), and $P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)=0$; the last estimate holds by the definition of $\sim$ in Sect. 9.1.

Proof of (11.2) for $i, j \in \mathbb{X}$. By assumption and (11.9), the first term in (11.12) is bounded by $K\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}$. For the second term on the right-hand side of (11.12), similarly $\left|G_{i x}^{(\mathbb{T})}-P_{i x}\right| \leqslant K\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}$. Moreover, $\hat{P}_{y j}=0$ if $y$ and $j$ are in different connected components of $\hat{\mathcal{G}_{0}}$ Thus by Claim 11.2, we have $\hat{P}_{y j} \neq 0$ for at most $4 \omega$ vertices $y \in\left\{b_{i}, c_{i}: i \in \llbracket 1, \nu \rrbracket\right\}$, for which we use $\left|\hat{P}_{y j}\right| \leqslant 2\left|m_{s c}\right|$ by (11.14). Combining these bounds, the second term in (11.12) is bounded by

$$
\begin{equation*}
\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|G_{i x}^{(\mathbb{T})}-P_{i x}\right|\left|\hat{P}_{y j}\right| \leqslant 8 \omega\left(K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r+1} \tag{11.15}
\end{equation*}
$$

To estimate the last term in (11.12), we denote

$$
\Gamma:=\max _{i, j \in \mathbb{X}}\left|\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}\right| .
$$

Noticing that $\mathbb{X} \subset \cup_{i=1}^{\kappa} \mathbb{S}_{i}$, we decompose the last sum over $\boldsymbol{E}$ in (11.12) according to the cases in (11.14) as

$$
\sum_{\boldsymbol{E}}[\cdots]=\sum_{\boldsymbol{E}_{1}}[\cdots]+\sum_{\boldsymbol{E}_{2}}[\cdots]+\sum_{\boldsymbol{E}_{3}}[\cdots]
$$

where here and below $[\cdots]$ abbreviates the terms in the last sum in (11.12) and

$$
\begin{aligned}
& \boldsymbol{E}_{1}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i, b_{k} \text { are in different S-cells }\right\}, \\
& \boldsymbol{E}_{2}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i, b_{k} \text { are in the same S-cells, and dist } \mathcal{G}_{(\mathbb{T})}\left(i, b_{k}\right)>2 r\right\}, \\
& \boldsymbol{E}_{3}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i, b_{k} \text { are in the same S-cells, and dist } \mathcal{G}^{(\mathbb{T})}\left(i, b_{k}\right) \leqslant 2 r\right\} .
\end{aligned}
$$

Notice that, for any $(x, y) \in \boldsymbol{E}$, we have $\left|\left(\hat{G}^{(\mathbb{T})}-\hat{P}\right)_{y j}\right| \leqslant \Gamma$ by the definition of $\Gamma$. For $(x, y) \in \boldsymbol{E}_{1},\left|G_{i x}^{(\mathbb{T})}\right| \leqslant M / \sqrt{N \eta}$ by (11.14), and $\left|\boldsymbol{E}_{1}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$,

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant \frac{\Gamma}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{1}}\left|G_{i x}^{(\mathbb{T})}\right| \leqslant \frac{4(d-1)^{\ell+1 / 2} M \Gamma}{\sqrt{N \eta}}
$$

For $(x, y) \in \boldsymbol{E}_{2},\left|G_{i x}^{(\mathbb{T})}\right| \leqslant K\left|m_{s c}\right| q^{r}$ by (11.14), and $\left|\boldsymbol{E}_{2}\right| \leqslant 2 \omega^{\prime}$ by (9.6),

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant \frac{\Gamma}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{2}}\left|G_{i x}^{(\mathbb{T})}\right| \leqslant \frac{2 K \omega^{\prime}\left|m_{s c}\right| q^{r} \Gamma}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{3},\left|G_{i x}^{(\mathbb{T})}\right| \leqslant 2\left|m_{s c}\right|$ by (11.14), and there are at most such $2 \omega$ terms, i.e. $\left|\boldsymbol{E}_{3}\right| \leqslant 2 \omega$, by (8.2),

$$
\sum_{\boldsymbol{E}_{3}}[\cdots] \leqslant \frac{\Gamma}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{3}}\left|G_{i x}^{(\mathbb{T})}\right| \leqslant \frac{4 \omega\left|m_{s c}\right| \Gamma}{\sqrt{d-1}}
$$

Combining the sums over $\boldsymbol{E}_{1}, \boldsymbol{E}_{2}, \boldsymbol{E}_{3}$, we get

$$
\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|G_{i x}^{(\mathbb{T})}\right|\left|\hat{G}_{y j}^{(\mathbb{T})}-\hat{P}_{y j}\right| \leqslant \frac{\Gamma}{4},
$$

provided that $\sqrt{d-1} \geqslant 20 \omega, \omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} \geqslant(d-1)^{\ell+1} M$. Thus (11.12) leads to

$$
\left|\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}\right| \leqslant(1+8 \omega q)\left(K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+\Gamma / 4
$$

Taking the supremum over $i, j \in \mathbb{X}$, we obtain

$$
\Gamma \leqslant \frac{4}{3}(1+8 \omega q)\left(K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r} .
$$

From this estimate, and from (11.9) to estimate $\hat{P}_{i j}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)$, we find

$$
\begin{align*}
\left|\hat{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right| & \leqslant\left|\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}\right|+\mid \hat{P}_{i j}-P_{i j}\left(\mathcal{E}_{r}\left(\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right) \mid\right. \\
& \leqslant \frac{4}{3}(1+8 \omega q)\left(K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \\
& \leqslant 2 K\left|m_{s c}\right| q^{r}, \tag{11.16}
\end{align*}
$$

provided that $\sqrt{d-1} \geqslant 2^{2 \omega+5}$. This concludes the proof of (11.2) for $i, j \in \mathbb{X}$.
Proof of (11.2) in the remaining case. In the remaining case at least one of $i, j$ is not contained in $\mathbb{X}$; and by symmetry we can assume that $i \notin \mathbb{X}$. Then $\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)=$ $\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)$ and the graphs on both sides of the equality also have the same deficit function. It therefore suffices to show that $\left|\hat{G}_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{T})}\right|$ is small. By the resolvent identity (11.10), we have

$$
\begin{equation*}
\left|\hat{G}_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{T})}\right| \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|G_{i x}^{(\mathbb{T})}\right|\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \tag{11.17}
\end{equation*}
$$

Since $i \notin \mathbb{X}$, we have $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i,\left\{b_{k}, c_{k}\right\}\right) \geqslant 2 r$ and therefore, by (11.14),

$$
\begin{equation*}
\left|G_{i x}^{(\mathbb{T})}\right| \leqslant K\left|m_{s c}\right| q^{r} \quad \text { for any } x \in\left\{b_{i}, c_{i}: i \in \llbracket 1, v \rrbracket\right\} . \tag{11.18}
\end{equation*}
$$

For the case that exactly one of $i, j$ is in $\mathbb{X}$, i.e. $i \notin \mathbb{X}$ and $j \in \mathbb{X}$, we now decompose the set $\boldsymbol{E}$ defined in (11.13) as $\boldsymbol{E}=\boldsymbol{E}_{1}^{\prime} \cup \boldsymbol{E}_{2}^{\prime} \cup \boldsymbol{E}_{3}^{\prime}$, where

$$
\begin{align*}
& \boldsymbol{E}_{1}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, j\right) \leqslant 2 r\right\}, \\
& \boldsymbol{E}_{2}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i \sim b_{k}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, j\right)>2 r\right\}, \\
& \boldsymbol{E}_{3}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i \nsim b_{k}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, j\right)>2 r\right\} . \tag{11.19}
\end{align*}
$$

For $(x, y) \in \boldsymbol{E}_{1}^{\prime}$, since $y, j \in \mathbb{X},\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant \mid P_{y j}\left(\mathcal{E}_{r}\left(\left(y, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)|+2 K| m_{s c}\left|q^{r} \leqslant 2\right| m_{s c} \mid\right.$ by (11.16) and (5.6), and there are at most $2 \omega$ terms, i.e. $\left|\boldsymbol{E}_{1}^{\prime}\right| \leqslant 2 \omega$ by (8.2),

$$
\sum_{\boldsymbol{E}_{1}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{1}^{\prime}}\left(K\left|m_{s c}\right| q^{r}\right)\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant \frac{4 K \omega\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

where now $[\cdots]$ refers to the terms in the sum in (11.17). For $(x, y) \in \boldsymbol{E}_{2}^{\prime}$, since $y, j \in \mathbb{X},\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ by (11.16), and $\left|\boldsymbol{E}_{2}^{\prime}\right| \leqslant 2 \omega^{\prime}$ by (9.5),

$$
\sum_{\boldsymbol{E}_{2}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{2}^{\prime}}\left(K\left|m_{s c}\right| q^{r}\right)\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant \frac{2 \omega^{\prime}\left(K\left|m_{s c}\right| q^{r}\right)\left(2 K\left|m_{s c}\right| q^{r}\right)}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{3}^{\prime},\left|G_{i x}^{(\mathbb{T})}\right| \leqslant M / \sqrt{N \eta}$ by the definition of $\sim,\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ by (11.16), and $\left|\boldsymbol{E}_{3}^{\prime}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$,

$$
\sum_{\boldsymbol{E}_{3}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{3}^{\prime}} \frac{M}{\sqrt{N \eta}}\left(2 K\left|m_{s c}\right| q^{r}\right) \leqslant 8 K(d-1)^{\ell+1} q^{r+1} \frac{M}{\sqrt{N \eta}} .
$$

Combining the sums over $\boldsymbol{E}_{1}^{\prime}, \boldsymbol{E}_{2}^{\prime}, \boldsymbol{E}_{3}^{\prime}$, from (11.17) we obtain

$$
\left|\hat{G}_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{T})}\right| \leqslant K\left|m_{s c}\right| q^{r},
$$

provided that $\sqrt{d-1} \geqslant 20 \omega, \omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} \geqslant(d-1)^{\ell+1} M$. This concludes the proof of (11.2) for $i \notin \mathbb{X}$ and $j \in \mathbb{X}$,

$$
\begin{align*}
\left|\hat{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right| & =\left|\hat{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right)\right| \\
& \leqslant\left|\hat{G}_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{T})}\right|+\mid G_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(\left(i, j, \mathcal{G}^{(\mathbb{T})}\right)\right) \mid\right. \\
& \leqslant 2 K\left|m_{s c}\right| q^{r} . \tag{11.20}
\end{align*}
$$

For the case that $i, j \notin \mathbb{X}$, noticing that $\operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}\left(b_{k}, j\right)>2 r$, we decompose the set $\boldsymbol{E}$ as $\boldsymbol{E}=\boldsymbol{E}_{2}^{\prime} \cup \boldsymbol{E}_{3}^{\prime}$, where $\boldsymbol{E}_{2}^{\prime}$ and $\boldsymbol{E}_{3}^{\prime}$ are defined in (11.19). By (11.20), for any $(x, y) \in \boldsymbol{E}, P_{y j}\left(\mathcal{E}_{r}\left(y, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)=0$ and thus $\left|\hat{G}^{(\mathbb{T})}\right|_{y j} \leqslant 2 K\left|m_{s c}\right| q^{r}$. Then the same argument as above implies

$$
\left|\hat{G}_{i j}^{(\mathbb{T})}-G_{i j}^{(\mathbb{T})}\right| \leqslant K\left|m_{s c}\right| q^{r}
$$

This finishes the proof of the stability of $\hat{G}^{(\mathbb{T})}$.
11.3. Proof of (11.3). We again follow the structure described below (10.4), except that no localization step is required to prove (11.3).

Starting point. Under both conditions given for (11.3), we have $\left|G_{i j}^{(\mathbb{T})}\right| \leqslant M / \sqrt{N \eta}$ by the definition of $\sim$ as in Sect. 9.1. By the resolvent identity (11.10), we therefore have

$$
\begin{equation*}
\left|\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant \frac{M}{\sqrt{N \eta}}+\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|G_{i x}^{(\mathbb{T})}\right|\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \tag{11.21}
\end{equation*}
$$

where $\boldsymbol{E}$ is as in (11.13). Notice that if $i, j$ are in different $S$-cells, then for any $(x, y) \in \boldsymbol{E}$, either $i, x$ are in different S -cells, or $y, j$ are in different S -cells. Similarly if $j \in \mathbb{S}_{t}$ and $i \nsim \mathbb{S}_{t}$ for some $t$, then for any $(x, y) \in \boldsymbol{E}$, either $\left|G_{i x}^{(\mathbb{T})}\right| \leqslant M / \sqrt{N \eta}$, or the vertices $y, j$ are in different S -cells. The claim (11.2) follows by analyzing (11.21) as an inequality for these $\hat{G}_{i j}^{(\mathbb{T})}$.

Green's function estimates. We first collect some estimates on Green's functions of $G^{(\mathbb{T})}$ and $\hat{G}^{(\mathbb{T})}$, which are repeatedly used in the proof: for $(x, y) \in \boldsymbol{E}$ as in (11.13),

$$
\begin{align*}
& \left|G_{i x}^{(\mathbb{T})}\right| \leqslant \begin{cases}2\left|m_{s c}\right|, & (\text { all } x), \\
K\left|m_{s c}\right| q^{r}, & \left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x) \geqslant 2 r\right), \\
M / \sqrt{N \eta}, & (i, x \text { are in different S-cells; }\end{cases}  \tag{11.22}\\
& \left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant \begin{cases}2\left|m_{s c}\right|, & \text { or } i \nsim \text { the S-cell containing } x), \\
2 K\left|m_{s c}\right| q^{r}, & \left(\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}(y, j) \geqslant 2 r\right) .\end{cases} \tag{11.23}
\end{align*}
$$

These estimates follow from (11.1)-(11.2), together with (5.6) for the bound for all $x, y$, and using that $P_{i x}\left(\mathcal{E}_{r}\left(i, x, \mathcal{G}^{(\mathbb{T})}\right)\right)=0$ for $^{\operatorname{dist}_{\mathcal{G}}}{ }_{(\mathbb{T})}(i, x) \geqslant 2 r$ and that $P_{y j}\left(\mathcal{E}_{r}\left(y, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)=$ 0 for $\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}(y, j) \geqslant 2 r$. The last bound in (11.22) holds by the definition of $\sim$.

Proof of (11.3), case (i). We verify (11.3) in the case that $i, j$ are in different S-cells. Denote

$$
\Gamma:=\max _{t_{1} \neq t_{2}} \max _{i \in \mathbb{S}_{t_{1}}, j \in \mathbb{S}_{t_{2}}}\left|\hat{G}_{i j}^{(\mathbb{T})}\right|
$$

and now abbreviate by $[\cdots]$ the terms in the sum in (11.21) including the $1 / \sqrt{d-1}$ prefactor. We divide the set $\boldsymbol{E}$ according to their relations to the cells $\mathbb{S}_{t_{1}}$ and $\mathbb{S}_{t_{2}}$ as $\boldsymbol{E}=\boldsymbol{E}_{1} \cup \boldsymbol{E}_{2} \cup \boldsymbol{E}_{3} \cup \boldsymbol{E}_{4} \cup \boldsymbol{E}_{5}$, where

$$
\begin{aligned}
\boldsymbol{E}_{1} & =\left\{(x, y) \in \mathbb{S}_{t_{1}}: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x) \leqslant 2 r\right\}, \\
\boldsymbol{E}_{2} & =\left\{(x, y) \in \mathbb{S}_{t_{1}}: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x)>2 r\right\}, \\
\boldsymbol{E}_{3} & =\left\{(x, y) \in \mathbb{S}_{t_{2}}: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(y, j) \leqslant 2 r\right\}, \\
\boldsymbol{E}_{4} & =\left\{(x, y) \in \mathbb{S}_{t_{2}}: \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(y, j)>2 r\right\}, \\
\boldsymbol{E}_{5} & =\left\{(x, y) \notin \mathbb{S}_{t_{1}} \cup \mathbb{S}_{t_{2}}\right\} .
\end{aligned}
$$

For $(x, y) \in \boldsymbol{E}_{1},\left|\boldsymbol{E}_{1}\right| \leqslant 2 \omega$ from (8.2), i.e. $\left|\left\{k \in \llbracket 1, v \rrbracket: \operatorname{dist}\left(i, b_{k}\right)<2 r\right\}\right| \leqslant \omega$, and $\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant \Gamma$, by the definition of $\Gamma$. Thus, by (11.22),

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant \frac{4 \omega\left|m_{s c}\right| \Gamma}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{2},\left|\boldsymbol{E}_{2}\right| \leqslant 2 \omega^{\prime}$ from (9.6), i.e. $\left|\mathbb{S}_{t_{1}} \cap\left\{b_{1}, \ldots, b_{\nu}\right\}\right| \leqslant \omega^{\prime}$. Thus, by (11.22),

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant \frac{2 K \omega^{\prime}\left|m_{s c}\right| q^{r} \Gamma}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{3},\left|\boldsymbol{E}_{3}\right| \leqslant 2 \omega$ from (8.2), and by (11.22)-(11.23),

$$
\sum_{\boldsymbol{E}_{3}}[\cdots] \leqslant \frac{M}{\sqrt{N \eta}} \frac{4 \omega\left|m_{s c}\right|}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{4},\left|\boldsymbol{E}_{4}\right| \leqslant 2 \omega^{\prime}$ from (9.6), and dist $\hat{\mathcal{G}}^{(\mathbb{T})}(y, j) \geqslant \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(y, j)>2 r$. Thus, by (11.22)-(11.23),

$$
\sum_{\boldsymbol{E}_{4}}[\cdots] \leqslant \frac{M}{\sqrt{N \eta}} \frac{4 K \omega^{\prime}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

Finally, for $(x, y) \in \boldsymbol{E}_{5}$, we use $\left|\boldsymbol{E}_{5}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$ and $\left|\hat{\boldsymbol{G}}_{y j}^{(\mathbb{T})}\right| \leqslant \Gamma$ which holds by the definition of $\Gamma$. Thus, by (11.22),

$$
\sum_{\boldsymbol{E}_{5}}[\cdots] \leqslant \frac{4(d-1)^{\ell+1} M \Gamma}{\sqrt{d-1} \sqrt{N \eta}}
$$

Combining the sums over $\boldsymbol{E}_{1}, \ldots, \boldsymbol{E}_{5}$ in (11.21) leads to

$$
\begin{aligned}
\left|\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant & \frac{M}{\sqrt{N \eta}}+\frac{\left(4 \omega\left|m_{s c}\right|+2 K \omega^{\prime}\left|m_{s c}\right| q^{r}\right) \Gamma}{\sqrt{d-1}} \\
& +\frac{\left(4 \omega\left|m_{s c}\right|+4 K \omega^{\prime}\left|m_{s c}\right| q^{r}\right)}{\sqrt{d-1}} \frac{M}{\sqrt{N \eta}}+\frac{4 M(d-1)^{\ell+1 / 2} \Gamma}{\sqrt{N \eta}} .
\end{aligned}
$$

By taking the maximum over $i, j$ as in the assumption and rearranging the inequality, we get

$$
\begin{equation*}
\Gamma \leqslant 2 M / \sqrt{N \eta} \tag{11.24}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant 20 \omega, \omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}$.
Proof of (11.3), case (ii). For $j \in \mathbb{S}_{t}$ and $i \nsucc \mathbb{S}_{t}$, we now decompose the set $\boldsymbol{E}$ according to their relations to vertex $i$ and the cell $\mathbb{S}_{t}$ as $\boldsymbol{E}=\boldsymbol{E}_{1}^{\prime} \cup \boldsymbol{E}_{2}^{\prime} \cup \boldsymbol{E}_{3}^{\prime} \cup \boldsymbol{E}_{4}^{\prime} \cup \boldsymbol{E}_{5}^{\prime}$, with

$$
\begin{aligned}
& \boldsymbol{E}_{1}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i \nsim b_{k}, b_{k} \notin \mathbb{S}_{t}\right\}, \\
& \boldsymbol{E}_{2}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i \sim b_{k}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i, b_{k}\right) \leqslant 2 r, b_{k} \notin \mathbb{S}_{t}\right\}, \\
& \boldsymbol{E}_{3}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): i \sim b_{k}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i, b_{k}\right)>2 r, b_{k} \notin \mathbb{S}_{t}\right\}, \\
& \boldsymbol{E}_{4}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): b_{k} \in \mathbb{S}_{t}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, j\right) \leqslant 2 r\right\}, \\
& \boldsymbol{E}_{5}^{\prime}=\left\{\left(b_{k}, c_{k}\right),\left(c_{k}, b_{k}\right): b_{k} \in \mathbb{S}_{t}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, j\right)>2 r\right\} .
\end{aligned}
$$

For $(x, y) \in \boldsymbol{E}_{1}^{\prime},\left|\boldsymbol{E}_{1}^{\prime}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$, and by $(11.24),\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}$, since $y, j$ are in different S-cells. Thus, combining with (11.22),

$$
\sum_{\boldsymbol{E}_{1}^{\prime}}[\cdots] \leqslant 4(d-1)^{\ell+1} \frac{2 M^{2}}{N \eta} \frac{1}{\sqrt{d-1}}
$$

For $(x, y) \in \boldsymbol{E}_{2}^{\prime}, y, j$ are in different S-cells. We have: $\left|\boldsymbol{E}_{2}^{\prime}\right| \leqslant 2 \omega$ from (8.2), i.e. $\left|\left\{k \in \llbracket 1, v \rrbracket: \operatorname{dist}\left(i, b_{k}\right) \leqslant 2 r\right\}\right| \leqslant \omega$, and $\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}$ by (11.24). Thus, by (11.22),

$$
\sum_{\boldsymbol{E}_{2}^{\prime}}[\cdots] \leqslant \frac{8 \omega\left|m_{s c}\right| M}{\sqrt{d-1} \sqrt{N \eta}}
$$

For $(x, y) \in \boldsymbol{E}_{3}^{\prime}, y, j$ are in different S-cells. We have: $\left|\boldsymbol{E}_{3}^{\prime}\right| \leqslant 2 \omega^{\prime}$ from (9.5), and $\left|\hat{G}_{y j}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}$ by (11.24). Thus, by (11.22),

$$
\sum_{\boldsymbol{E}_{3}^{\prime}}[\cdots] \leqslant \frac{4 K \omega^{\prime} q^{r+1} M}{\sqrt{N \eta}}
$$

For $(x, y) \in \boldsymbol{E}_{4}^{\prime},\left|\boldsymbol{E}_{4}^{\prime}\right| \leqslant 2 \omega$ from (8.2), and (11.22)-(11.23),

$$
\sum_{\boldsymbol{E}_{4}^{\prime}}[\cdots] \leqslant \frac{4 \omega\left|m_{s c}\right| M}{\sqrt{d-1} \sqrt{N \eta}}
$$

For $(x, y) \in \boldsymbol{E}_{5}^{\prime},\left|\boldsymbol{E}_{5}^{\prime}\right| \leqslant 2 \omega^{\prime}$ from (9.6), and dist $\hat{\mathcal{G}}^{(\mathbb{T})}(y, j) \geqslant \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(y, j) \geqslant 2 r$, since in the graph $\mathcal{G}^{(\mathbb{T})}, b_{k}$ and $c_{k}$ are adjacent. Thus, combining with (11.22)-(11.23),

$$
\sum_{\boldsymbol{E}_{5}^{\prime}}[\cdots] \leqslant \frac{4 K \omega^{\prime} q^{r+1} M}{\sqrt{N \eta}}
$$

Therefore, (11.21) can be bounded by

$$
\left|\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant \frac{M}{\sqrt{N \eta}}+\left(\frac{12 \omega\left|m_{s c}\right| M}{\sqrt{d-1} \sqrt{N \eta}}+\frac{8 K \omega^{\prime} q^{r+1} M}{\sqrt{N \eta}}+\frac{8 M^{2}(d-1)^{\ell+1 / 2}}{N \eta}\right) \leqslant \frac{2 M}{\sqrt{N \eta}}
$$

given that $\sqrt{d-1} \geqslant 20 \omega, \omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}$.
11.4. Proof of (11.4). As in previous arguments, we follow the structure described below (10.4).

Localization. The switching vertices that are not on the boundary of $\mathbb{T}$ after switching are given by $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$. From Sect. 9.1 , we recall the partition $\left\{\mathbb{I}_{1}, \mathbb{I}_{2}, \ldots, \mathbb{I}_{\kappa}\right\}$ of this set. (Thus the $\mathbb{I}_{j}$ are the connected components of the Green's function graph $\mathcal{R}$, with all connected components containing any of the vertices $a_{i}$ joined to $\mathbb{I}_{1}$.) The close vertices $\mathbb{X}_{1} \cup \mathbb{X}_{2}$ and the larger subgraph $\mathcal{G}_{0}$ are defined by

$$
\begin{align*}
\mathcal{G}_{0} & :=\mathcal{B}_{3 r}\left(\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{v}\right\}, \mathcal{G}^{(\mathbb{T})}\right)  \tag{11.25}\\
\mathbb{X}_{1} & :=\mathbb{B}_{2 r}\left(\mathbb{I}_{1}, \mathcal{G}^{(\mathbb{T})}\right), \quad \mathbb{X}_{2}:=\mathbb{B}_{2 r}\left(\mathbb{I}_{2} \cup \cdots \cup \mathbb{I}_{\kappa}, \mathcal{G}^{(\mathbb{T})}\right) \tag{11.26}
\end{align*}
$$

By our construction of S-cells and $\mathrm{S}^{\prime}$-cells, it follows that $\mathbb{X}_{1}=\mathbb{S}_{1}=\mathbb{S}_{1}^{\prime}$ and $\mathbb{X}_{2}=$ $\cup_{i=2}^{k} \mathbb{S}_{i}=\cup_{i=2}^{\kappa^{\prime}} \mathbb{S}_{i}^{\prime}$. By our conventions, the deficit function of the graph $\mathcal{G}_{0}$ is the restriction of that on $\mathcal{G}^{(\mathbb{T})}$. We define the graph $\hat{\mathcal{G}}_{0}$ by removing edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant \nu}$ from $\mathcal{G}_{0}$ and $\tilde{\mathcal{G}}_{0}$ by adding edges $\left\{a_{i}, b_{i}\right\}_{i \leqslant \nu}$ to $\hat{\mathcal{G}}_{0}$. The graphs $\hat{\mathcal{G}}_{0}$ and $\tilde{\mathcal{G}}_{0}$ are given the restricted deficit functions from $\hat{\mathcal{G}}^{(\mathbb{T})}$ and $\tilde{\mathcal{G}}^{(\mathbb{T})}$ respectively. We abbreviate

$$
\mathcal{G}_{1}=\operatorname{TE}\left(\mathcal{G}_{0}\right), \quad \hat{\mathcal{G}}_{1}=\operatorname{TE}\left(\hat{\mathcal{G}}_{0}\right), \quad \hat{P}=G\left(\hat{\mathcal{G}}_{1}\right), \quad \tilde{\mathcal{G}}_{1}=\operatorname{TE}\left(\tilde{\mathcal{G}}_{0}\right), \quad \tilde{P}=G\left(\tilde{\mathcal{G}}_{1}\right) .
$$

Notice that the graph $\hat{\mathcal{G}_{1}}$ is obtained by removing the edges $\left\{b_{i}, c_{i}\right\}_{i \leqslant \nu}$ from $\mathcal{G}_{1}$, and that the graph $\tilde{\mathcal{G}}_{1}$ is obtained by adding the edges $\left\{b_{i}, a_{i}\right\}_{i \leqslant v}$ to $\hat{\mathcal{G}}_{1}$. We use the following fact throughout this section.
Claim 11.3. If (8.3) and (8.4) hold, then each connected component of $\tilde{\mathcal{G}}_{0}$ contains at most $10 \omega$ elements in $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$, i.e.

$$
\begin{equation*}
\left|\left\{i \in \llbracket 1, \mu \rrbracket: a_{i} \in \mathbb{K}\right\}\right|+\left|\left\{i \in \llbracket 1, v \rrbracket: b_{i} \in \mathbb{K}\right\}\right| \leqslant 10 \omega, \tag{11.27}
\end{equation*}
$$

where $\mathbb{K}$ is the vertex set of any connected component of $\tilde{\mathcal{G}}_{0}$.
Proof. (11.27) is a consequence of Propositions 8.1 and 8.2. More precisely, if $a_{i} \in \mathbb{K}$ or $b_{i} \in \mathbb{K}$ for some $i \in \llbracket 1, \mu \rrbracket \backslash\left(\mathrm{~B}_{a} \cup \mathrm{~B}_{b}\right)$, then $\mathbb{K}$ is disjoint from $\left\{a_{1}, a_{2}, \ldots, a_{\mu}, b_{1}, b_{2}\right.$, $\left.\ldots, b_{\nu}\right\} \backslash\left\{a_{i}, b_{i}\right\}$. Therefore $\left|\left\{i \in \llbracket 1, \mu \rrbracket: a_{i} \in \mathbb{K}\right\}\right|+\left|\left\{i \in \llbracket 1, v \rrbracket: b_{i} \in \mathbb{K}\right\}\right| \leqslant$ $2\left|\mathrm{~B}_{a} \cup \mathrm{~B}_{b}\right| \leqslant 10 \omega$.

Verification of assumptions in Proposition 5.2. By assumption $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$. Since $\hat{\mathcal{G}}_{0}$ and $\tilde{\mathcal{G}}_{0}$ can be viewed as subgraphs of $\mathcal{G}$ and $\tilde{\mathcal{G}}$ respectively, the radius- $R$ neighborhoods of them have excess at most $\omega$. Moreover, the same argument as in Sect. 11.2 implies that the sum of the deficit functions on each connected component of $\hat{\mathcal{G}}_{0}$ and that of $\tilde{\mathcal{G}}_{0}$ are bounded by $8 \omega$. Therefore the assumptions for (5.5) are verified for both graphs $\hat{\mathcal{G}}_{0}$ and $\tilde{\mathcal{G}}_{0}$. Thus (5.3)-(5.5) hold for $\hat{P}$ and $\tilde{P}$, and as in (11.9), we can use $\hat{P}$ instead of $P\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)$ and $\tilde{P}$ instead of $P\left(\mathcal{E}_{r}\left(i, j, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)$.

Starting point. The proof is similar to that of (11.2). By the resolvent identity (B.1), we have

$$
\begin{align*}
\tilde{G}^{(\mathbb{T})}-\hat{G}^{(\mathbb{T})} & =\hat{G}^{(\mathbb{T})} \Delta \tilde{G}^{(\mathbb{T})},  \tag{11.28}\\
\tilde{P}-\hat{P} & =\hat{P} \Delta \tilde{P} \tag{11.29}
\end{align*}
$$

where $\Delta=\sum_{k=1}^{v}\left(e_{b_{k} a_{k}}+e_{a_{k} b_{k}}\right) / \sqrt{d-1}$. Taking difference of (11.28) and (11.29), we have

$$
\begin{align*}
\tilde{G}_{i j}^{(\mathbb{T})}-\tilde{P}_{i j}= & \left(\hat{G}_{i j}^{(\mathbb{T})}-\hat{P}_{i j}\right)+\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left(\hat{G}_{i x}^{(\mathbb{T})}-\hat{P}_{i x}\right) \tilde{P}_{y j} \\
& +\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}} \hat{G}_{i x}^{(\mathbb{T})}\left(\tilde{G}_{y j}^{(\mathbb{T})}-\tilde{P}_{y j}\right), \tag{11.30}
\end{align*}
$$

where the sums are over the ordered pairs

$$
\begin{equation*}
(x, y) \in \boldsymbol{E}=\left\{\left(a_{1}, b_{1}\right), \ldots,\left(a_{\nu}, b_{\nu}\right),\left(b_{1}, a_{1}\right), \ldots,\left(b_{\nu}, a_{\nu}\right)\right\} \tag{11.31}
\end{equation*}
$$

We regard (11.30) as an equation for $\tilde{G}^{(\mathbb{T})}-\tilde{P}$, and will show that $\tilde{G}^{(\mathbb{T})}-\tilde{P}$ is small, using that $\hat{G}^{(\mathbb{T})}-\hat{P}$ is small by (11.2).

Green's function estimates. We collect some estimates on Green's function, which are repeatedly used in the proof:

$$
\begin{cases}\left|\hat{G}_{i j}^{(\mathbb{T})}\right|,\left|\hat{P}_{i j}\right|,\left|\tilde{P}_{i j}\right| \leqslant 2\left|m_{s c}\right|, & (\operatorname{all} i, j),  \tag{11.32}\\ \left|\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}, & \left(\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, j) \geqslant 2 r\right), \\ \left|\hat{G}_{i b_{k}}^{(\mathbb{T})}\right|,\left|\hat{G}_{i c_{k}}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}, & \left(i, b_{k} \text { are in different S-cells; or } i \nsim b_{k}\right)\end{cases}
$$

The first estimate follows from (5.6) and (11.2); the second estimate follows from $P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)=0$ and (11.2); the last estimate is from (11.3).

Proof of (11.4) for $i, j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$. For the second term on the right-hand side of (11.30), it follows from (11.2) that $\left|\hat{G}_{i x}^{(\mathbb{T})}-\hat{P}_{i x}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}$. Moreover, again $\tilde{P}_{y j}=0$ if $y$ and $j$ are in different connected components of $\tilde{\mathcal{G}}_{0}$. Thus, by Claim 11.3, we have $\tilde{P}_{y j} \neq 0$ for at most $10 \omega$ vertices $y \in\left\{a_{i}: i \in \llbracket 1, \mu \rrbracket\right\} \cup\left\{b_{i}: i \in \llbracket 1, \nu \rrbracket\right\}$, and for these we again have $\left|\tilde{P}_{y j}\right| \leqslant 2\left|m_{s c}\right|$ by (11.32). Altogether, the second term on the right-hand of (11.30) is bounded by

$$
\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|\hat{G}_{i x}^{(\mathbb{T})}-\hat{P}_{i x} \| \tilde{P}_{y j}\right| \leqslant 20 \omega\left(2 K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r+1}
$$

To estimate the last term in (11.30), we denote

$$
\Gamma_{1}:=\max _{i, j \in \mathbb{X}_{1}}\left|\tilde{P}_{i j}-\tilde{G}_{i j}^{(\mathbb{T})}\right|, \quad \Gamma_{2}:=\max _{i \in \mathbb{X}_{2}, j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}}\left|\tilde{P}_{i j}-\tilde{G}_{i j}^{(\mathbb{T})}\right|
$$

Our goal is to prove that

$$
\begin{equation*}
\Gamma_{1}, \Gamma_{2} \leqslant 24 K^{2}\left|m_{s c}\right| q^{r} \tag{11.33}
\end{equation*}
$$

In the following, we first derive an estimate for $\Gamma_{2}$. We assume that $i \in \mathbb{S}_{t}$ for some $t \neq 1$, and $j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$. We decompose the set $\boldsymbol{E}$ [as in (11.31)] according to their relations to the S-cell $\mathbb{S}_{t}: \boldsymbol{E}=\boldsymbol{E}_{1} \cup \boldsymbol{E}_{2} \cup \boldsymbol{E}_{3}$, where

$$
\begin{aligned}
& \boldsymbol{E}_{1}=\left\{(x, y): x \notin \mathbb{S}_{t}\right\}, \\
& \boldsymbol{E}_{2}=\left\{(x, y): x \in \mathbb{S}_{t}, \operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}(i, x)<2 r\right\}, \\
& \boldsymbol{E}_{3}=\left\{(x, y): x \in \mathbb{S}_{t}, \operatorname{dist}_{\left.\mathcal{G}^{(\mathbb{T}}\right)}(i, x) \geqslant 2 r\right\} .
\end{aligned}
$$

Notice that for any $(x, y) \in \boldsymbol{E}$, by the definition of $\Gamma_{1}, \Gamma_{2}$, we always have $\left|\tilde{P}_{y j}-\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant$ $\max \left\{\Gamma_{1}, \Gamma_{2}\right\}$. For $(x, y) \in \boldsymbol{E}_{1}$, we have $\left|\boldsymbol{E}_{1}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$. Since $i, x$ are in different S-cells, by (11.32),

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{1}}\left|\hat{G}_{i x}^{(\mathbb{T})}\right| \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \frac{4(d-1)^{\ell+1}}{\sqrt{d-1}} \frac{2 M}{\sqrt{N \eta}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\}
$$

For $(x, y) \in \boldsymbol{E}_{2}$, we have $\left|\boldsymbol{E}_{2}\right| \leqslant 2 \omega$ by (4.7) and (8.2). Thus, by (11.32),

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{2}}\left|\hat{\boldsymbol{G}}_{i x}^{(\mathbb{T})}\right| \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \frac{4 \omega\left|m_{s c}\right|}{\sqrt{d-1}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\}
$$

For $(x, y) \in \boldsymbol{E}_{3}$, we have $\left|\boldsymbol{E}_{3}\right| \leqslant \omega^{\prime}$ from (9.6), and combined with (11.32),

$$
\sum_{\boldsymbol{E}_{3}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{3}}\left|\hat{G}_{i x}^{(\mathbb{T})}\right| \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \frac{2 K \omega^{\prime}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\}
$$

Combining the sums over $\boldsymbol{E}_{1}, \boldsymbol{E}_{2}, \boldsymbol{E}_{3}$, for $i \in \mathbb{X}_{2}$ and $j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$, (11.30) leads to

$$
\left|\tilde{G}_{i j}^{(\mathbb{T})}-\tilde{P}_{i j}\right| \leqslant(20 \omega q+1)\left(2 K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+\frac{8(\omega+1)}{\sqrt{d-1}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\}
$$

given $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}, \sqrt{d-1} \geqslant 20 \omega$ and $\omega^{\prime} q^{r} \ll 1$. Moreover, taking the maximum over all $i \in \mathbb{X}_{2}$ and $j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$, we get

$$
\begin{equation*}
\Gamma_{2} \leqslant(20 \omega q+1)\left(2 K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+\frac{8(\omega+1)}{\sqrt{d-1}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \tag{11.34}
\end{equation*}
$$

Next, we estimate $\Gamma_{1}$. To this end, we decompose the set $\boldsymbol{E}$ [as in (11.31)] according to the cases in (11.32) as $\boldsymbol{E}=\boldsymbol{E}_{1}^{\prime} \cup \boldsymbol{E}_{2}^{\prime} \cup \boldsymbol{E}_{3}^{\prime} \cup \boldsymbol{E}_{4}^{\prime}$, where

$$
\begin{aligned}
\boldsymbol{E}_{1}^{\prime} & =\left\{(x, y): x \in \mathbb{X}_{1}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x) \leqslant 2 r\right\}, \\
\boldsymbol{E}_{2}^{\prime} & =\left\{(x, y): x, y \in \mathbb{X}_{1}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x)>2 r\right\}, \\
\boldsymbol{E}_{3}^{\prime} & =\left\{(x, y): x \in \mathbb{X}_{1}, y \in \mathbb{X}_{2}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x)>2 r\right\}, \\
\boldsymbol{E}_{4}^{\prime} & =\left\{(x, y): x \in \mathbb{X}_{2}\right\} .
\end{aligned}
$$

For $(x, y) \in \boldsymbol{E}_{1}^{\prime},\left|\boldsymbol{E}_{1}^{\prime}\right| \leqslant 2 \omega$ from (4.7) and (8.2). $\left|\tilde{P}_{y j}-\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant \max \left\{\Gamma_{1}, \Gamma_{2}\right\}$ by the definition of $\Gamma_{1}, \Gamma_{2}$. Therefore, by (11.32),

$$
\sum_{\boldsymbol{E}_{1}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{1}^{\prime}}\left|\hat{\boldsymbol{G}}_{i x}^{(\mathbb{T})}\right| \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \frac{4 \omega\left|m_{s c}\right|}{\sqrt{d-1}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\} .
$$

For $(x, y) \in \boldsymbol{E}_{2}^{\prime},\left|\boldsymbol{E}_{2}^{\prime}\right| \leqslant 2 \omega^{\prime}$ from (9.6), and $\left|\tilde{P}_{y j}-\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant \Gamma_{1}$ from the definition of $\Gamma_{1}$. Thus, by (11.32),

$$
\sum_{\boldsymbol{E}_{2}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{2}^{\prime}}\left|\hat{G}_{i x}^{(\mathbb{T})}\right| \Gamma_{1} \leqslant 4 K \omega^{\prime} q^{r+1} \Gamma_{1}
$$

For $(x, y) \in \boldsymbol{E}_{3}^{\prime}$, we have $\left|\boldsymbol{E}_{3}^{\prime}\right| \leqslant 2 v \leqslant 4(d-1)^{\ell+1}$, and $\left|\tilde{P}_{y j}-\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant \Gamma_{2}$ from the definition of $\Gamma_{2}$. Thus, by (11.32),

$$
\sum_{\boldsymbol{E}_{3}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{3}^{\prime}}\left|\hat{\boldsymbol{G}}_{i x}^{(\mathbb{T})}\right| \Gamma_{2} \leqslant 8 K(d-1)^{\ell+1} q^{r+1} \Gamma_{2}
$$

For $(x, y) \in \boldsymbol{E}_{4}^{\prime}$, we have $\left|\boldsymbol{E}_{4}^{\prime}\right| \leqslant v \leqslant 2(d-1)^{\ell+1}$, and $\left|\tilde{P}_{y j}-\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant \max \left\{\Gamma_{1}, \Gamma_{2}\right\}$ from the definition of $\Gamma_{1}, \Gamma_{2}$. Thus, by (11.32),

$$
\sum_{\boldsymbol{E}_{4}^{\prime}}[\cdots] \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}_{4}^{\prime}}\left|\hat{\boldsymbol{G}}_{i x}^{(\mathbb{T})}\right|\left(\Gamma_{1}+\Gamma_{2}\right) \leqslant \frac{4(d-1)^{\ell+1} M}{\sqrt{d-1} \sqrt{N \eta}} \max \left\{\Gamma_{1}, \Gamma_{2}\right\}
$$

Using $r=2 \ell+1$, and combining the above estimates in (11.30), we obtain that, for all $i, j \in \mathbb{X}_{1}$,
$\left|\tilde{G}_{i j}^{(\mathbb{T})}-\tilde{P}_{i j}\right| \leqslant(20 \omega q+1)\left(2 K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+\frac{8(\omega+1)}{\sqrt{d-1}} \Gamma_{1}+\left(8 K+\frac{4 \omega+4}{\sqrt{d-1}}\right) \Gamma_{2}$,
given $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}$ and $\omega^{\prime} q^{r} \ll 1$. Taking the maximum over the left-hand side, we have

$$
\begin{equation*}
\Gamma_{1} \leqslant(20 \omega q+1)\left(2 K+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}+\frac{8(\omega+1)}{\sqrt{d-1}} \Gamma_{1}+\left(8 K+\frac{4 \omega+4}{\sqrt{d-1}}\right) \Gamma_{2} \tag{11.35}
\end{equation*}
$$

Finally, the claim (11.33) follows by combining (11.34) and (11.35), provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$. Therefore for any $i, j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$, we have

$$
\begin{align*}
\left|\tilde{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \tilde{G}^{(\mathbb{T})}\right)\right)\right| & \leqslant\left|\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}\right)_{i j}\right|+\left|\tilde{P}_{i j}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \tilde{G}^{(\mathbb{T})}\right)\right)\right| \\
& \leqslant 24 K^{2}\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \leqslant\left(24 K^{2}+1\right)\left|m_{s c}\right| q^{r}, \tag{11.36}
\end{align*}
$$

which implies the bound stated in (11.4).
Proof of (11.4) for the remaining case. For $i \notin \mathbb{X}_{1} \cup \mathbb{X}_{2}$ and $j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$, first note that $\mathcal{E}_{r}\left(i, j, \hat{G}^{(\mathbb{T})}\right)=\mathcal{E}_{r}\left(i, j, \tilde{G}^{(\mathbb{T})}\right)$ and that both graphs have the same deficit function. To prove (11.4), we will show that $\left|\tilde{G}_{i j}^{(\mathbb{T})}-\hat{G}_{i j}^{(\mathbb{T})}\right|$ is small. To this end, we start from the resolvent identity (11.28), which states that

$$
\begin{equation*}
\left|\tilde{G}_{i j}^{(\mathbb{T})}-\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in E}\left|\hat{G}_{i x}^{(\mathbb{T})}\right|\left|\tilde{G}_{y j}^{(\mathbb{T})}\right| \tag{11.37}
\end{equation*}
$$

By the definition of the sets $\mathbb{X}_{1}, \mathbb{X}_{2}$, for any $(x, y) \in \boldsymbol{E}$, we have $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}(i, x)>2 r$ and $\left|\hat{G}_{i x}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ by (11.32). We simply decompose the set $\boldsymbol{E}$ [as in (11.31)] according to their distance to the vertex $j$ as $\boldsymbol{E}=\boldsymbol{E}_{1} \cup \boldsymbol{E}_{2}$, where

$$
\begin{aligned}
& \boldsymbol{E}_{1}=\left\{(x, y): \operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}(y, j)<2 r\right\}, \\
& \boldsymbol{E}_{2}=\left\{(x, y): \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}(y, j) \geqslant 2 r\right\} .
\end{aligned}
$$

For $(x, y) \in \boldsymbol{E}_{1}$, we have $\left|\boldsymbol{E}_{1}\right| \leqslant 10 \omega$ by (11.27) in Claim 11.3. Moreover, $\left|\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant$ $\left|P_{y j}\left(\mathcal{E}_{r}\left(y, j, \tilde{G}^{(\mathbb{T})}\right)\right)\right|+\left(24 K^{2}+1\right)\left|m_{s c}\right| q^{r} \leqslant 2\left|m_{s c}\right|$ by (11.36). Thus, combining with (11.32), we have

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant 40 K \omega\left|m_{s c}\right| q^{r+1}
$$

where here $[\cdots]$ denotes the terms in the sum in (11.37). For $(x, y) \in \boldsymbol{E}_{2}$, we have $\left|\boldsymbol{E}_{2}\right| \leqslant 2 v \leqslant 2(d-1)^{\ell+1}$, and $\left|\tilde{G}_{y j}^{(\mathbb{T})}\right| \leqslant\left(24 K^{2}+1\right)\left|m_{s c}\right| q^{r}$ by (11.36), since $P_{y j}\left(\mathcal{E}_{r}(y\right.$, $\left.\left.j, \tilde{G}^{(\mathbb{T})}\right)\right)=0$. Thus, combining with (11.32),

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant 2 K\left(24 K^{2}+1\right)\left|m_{s c}\right|^{2} q^{2 r} \frac{2(d-1)^{\ell+1}}{\sqrt{d-1}}
$$

Combining the sums over $\boldsymbol{E}_{1}, \boldsymbol{E}_{2}$, we get

$$
\left|\tilde{G}_{i j}^{(\mathbb{T})}-\hat{G}_{i j}^{(\mathbb{T})}\right| \leqslant 40 K \omega q^{r+1}+2 K\left(24 K^{2}+1\right)\left|m_{s c}\right|^{2} q^{2 r} \frac{2(d-1)^{\ell+1}}{\sqrt{d-1}} \leqslant 100 K^{3}\left|m_{s c}\right| q^{r},
$$

provided that $\sqrt{d-1} \geqslant 20 \omega$. Similarly, in the case $i, j \notin \mathbb{X}_{1} \cup \mathbb{X}_{2}$, we have

$$
\begin{aligned}
\left|\tilde{G}_{i j}^{(\mathbb{T})}-\hat{G}_{i j}^{(\mathbb{T})}\right| & \leqslant \frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|\hat{G}_{i x}^{(\mathbb{T})}\right|\left|\tilde{G}_{y j}^{(\mathbb{T})}\right| \\
& \leqslant 2 K\left(24 K^{2}+1\right)\left|m_{s c}\right|^{2} q^{2 r} \frac{2(d-1)^{\ell+1}}{\sqrt{d-1}} \leqslant 100 K^{3}\left|m_{s c}\right| q^{r}
\end{aligned}
$$

Therefore, for $i \notin \mathbb{X}_{1} \cup \mathbb{X}_{2}$ and $j \in \mathbb{X}_{1} \cup \mathbb{X}_{2}$ or $i, j \notin \mathbb{X}_{1} \cup \mathbb{X}_{2}$, we obtain

$$
\begin{aligned}
\left|\tilde{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \tilde{G}^{(\mathbb{T})}\right)\right)\right| & \leqslant\left|\tilde{G}_{i j}^{(\mathbb{T})}-\hat{G}_{i j}^{(\mathbb{T})}\right|+\left|\hat{G}_{i j}^{(\mathbb{T})}-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \hat{G}^{(\mathbb{T})}\right)\right)\right| \\
& \leqslant 100 K^{3}\left|m_{s c}\right| q^{r}+2 K\left|m_{s c}\right| q^{r} \leqslant 2^{7} K^{3}\left|m_{s c}\right| q^{r} .
\end{aligned}
$$

This completes the proof of (11.4).

## 12. Improved Decay in the Switched Graph

In the graph $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G})$, the edge boundary $\partial_{E} \mathcal{T}$ and the vertex boundary $\partial \mathcal{T}$ of $\mathcal{T}$ are given by

$$
\begin{equation*}
\partial_{E} \mathcal{T}=\left\{\left(l_{1}, \tilde{a}_{1}\right),\left(l_{2}, \tilde{a}_{2}\right), \ldots,\left(l_{\mu}, \tilde{a}_{\mu}\right)\right\}, \quad \mathbb{I}:=\partial \mathcal{T}=\left\{\tilde{a}_{1}, \tilde{a}_{2}, \ldots, \tilde{a}_{\mu}\right\} \tag{12.1}
\end{equation*}
$$

where the vertices $\tilde{a}_{i}=c_{i}$ with $i \in \llbracket 1, \nu \rrbracket$ are those that get switched, and the vertices $\tilde{a}_{i}=a_{i}$ with $i \in \llbracket v+1, \mu \rrbracket$ are those for which the switching does not take place. Here recall from Remark 7.7 that we assume without loss of generality that the index set of admissible switchings is $W_{\mathbf{S}}=\llbracket 1, v \rrbracket \subset \llbracket 1, \mu \rrbracket$.

The result of this section is the following proposition, showing that (i) between most vertices in $\mathbb{I}$ the Green's function is small; (ii) for any vertex not in $\mathbb{I}$, the Green's function between it and most vertices in $\mathbb{I}$ is also small. This decay asserted by the proposition is better than that between the boundary vertices of $\mathcal{T}$ which we assumed in the unswitched graph. This improvement is crucial for the subsequent sections, in particular for the derivation of the self-consistent equation.

Proposition 12.1. Under the same assumptions as in Proposition 11.1, let $\mathbf{S} \in F(\mathcal{G})$ (as in Sect. 11.1) and assume that $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$ (as in Sect. 3.2). Then there exists $J \subset \llbracket 1, \nu \rrbracket$ with $|J| \geqslant v-\omega^{\prime}-6 \omega$ such that, for any $k \in J$,

$$
\begin{array}{ll}
\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \leqslant 2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1} & \text { if } i=\tilde{a}_{j} \text { for some } j \in \llbracket 1, \mu \rrbracket \backslash J, \\
\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \leqslant 2^{12} K^{5}\left|m_{s c}\right| q^{3 r+2} & \text { if } i=\tilde{a}_{j} \text { for some } j \in J \backslash\{k\}, \\
\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \leqslant 2^{12} K^{5}\left|m_{s c}\right| q^{2 r+1} & \text { if } i \nsim b_{k} \text { and dist} \tilde{\mathcal{G}}^{(\mathbb{T})}  \tag{12.4}\\
\left(i, a_{k}\right) \geqslant 2 r,
\end{array}
$$

provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$, that $\omega^{\prime} q^{r} \ll 1$ and that $\sqrt{N \eta} q^{3 r+2} \geqslant M$.

The proposition uses the randomness of the resampling via the properties of the Green's function that are encoded by the $\mathrm{S}^{\prime}$-cells. Indeed, recall that if $c_{k}$ was a random index, independent of $\tilde{\mathcal{G}}^{(\mathbb{T})}$ and $i$, then the size of the right-hand sides would be of order $1 / \sqrt{N \eta} \ll\left|m_{s c}\right| q^{3 r+2}$ by the Ward identity (B.6). The remainder of this section is devoted to the proof of the proposition.
12.1. Preliminaries. To prove Proposition 12.1, we use the same setup as in the proof of (11.4). Thus, from (11.25)-(11.26) and the paragraph below, recall the sets $\mathbb{X}_{1}, \mathbb{X}_{2}$ and the graphs $\mathcal{G}_{0}, \hat{\mathcal{G}}_{0}, \tilde{\mathcal{G}}_{0}$, and that the set $\mathbb{X}_{1} \cup \mathbb{X}_{2}$ is contained in $\mathbb{G}_{0}$ (the vertex set of $\mathcal{G}_{0}$ ). We also recall the $\mathrm{S}^{\prime}$-cells defined in Sect. 9.1.

We will prove Proposition 12.1 with the set $J \subset \llbracket 1, v \rrbracket$ given by the set of indices $k \in \llbracket 1, \nu \rrbracket$ such that the following conditions hold:

1. $\quad b_{k}, c_{k} \in \mathbb{X}_{2}$ (i.e. the $S$-cell containing $b_{k}$ and $c_{k}$ is not $S_{1}$ );
2. $\quad \mathcal{B}_{R}\left(c_{k}, \mathcal{G}^{(\mathbb{T})}\right)$ is a tree;
3. the $\mathrm{S}^{\prime}$-cell $\mathbb{S}^{\prime}$ containing $b_{k}$ and $c_{k}$ is not $\mathbb{S}_{1}^{\prime}$ (as implied by (i)) and satisfies

$$
\begin{equation*}
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(\mathbb{S}^{\prime},\left\{a_{m}: m \in \llbracket 1, \mu \rrbracket \backslash\{k\}\right\} \cup\left\{b_{m}, c_{m}: m \in \llbracket 1, v \rrbracket \backslash\{k\}\right\}\right)>R / 4 \tag{12.5}
\end{equation*}
$$

By the assumption $\mathbf{S} \in F(\mathcal{G})$, and using the definition of $F(\mathcal{G})$ given in Sect. 11.1, note that (8.5) and (9.7) hold. (8.5) implies that condition (ii) in the definition of $J$ is true for all $k \in \llbracket 1, \nu \rrbracket$ with at most $\omega$ exceptions. (9.7) implies condition (i), and further that condition (iii) is true for all $k \in \llbracket 1, \nu \rrbracket$ with at most $\omega^{\prime}+5 \omega$ exceptions. It follows that

$$
|J| \geqslant v-\omega^{\prime}-6 \omega
$$

as asserted in the statement of Proposition 12.1. With this definition of $J$, to prove Proposition 12.1, we now follow the structure described below (10.4) (without the localization step, which is not required here).

Starting point. For the remainder of this section, we fix $k \in J$ and denote the $\mathrm{S}^{\prime}$-cell containing $c_{k}$ by $\mathbb{S}^{\prime}$. Notice that, by the definition of $J$, the $S^{\prime}$-cell $\mathbb{S}^{\prime}$ is not $\mathbb{S}_{1}^{\prime}$, and that it is equal to the $S$-cell containing $c_{k}$. For any $i$ arising in the statement of Proposition 12.1, we either have $i \in \mathbb{I}$, in which case $i$ and $c_{k}$ are in different $S$-cells (by definition of $J$, the S-cell of $c_{k}$ does not contain any $\tilde{a}_{j}$ ), or otherwise $i \not \nsucc b_{k}$. Noticing that $b_{k}$ and $c_{k}$ are in the same S-cell, in both cases, the estimate (11.3) with $j=c_{k}$ holds. Therefore, since the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$ is given by adding the edges $\left\{a_{i}, b_{i}\right\}_{i \leqslant v}$ to $\hat{\mathcal{G}}^{(\mathbb{T})}$, by the resolvent formula (B.1), we have

$$
\begin{equation*}
\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right|=\left|\hat{G}_{i c_{k}}^{(\mathbb{T})}+\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}} \hat{G}_{i x}^{(\mathbb{T})} \tilde{G}_{y c_{k}}^{(\mathbb{T})}\right| \leqslant \frac{2 M}{\sqrt{N \eta}}+\frac{1}{\sqrt{d-1}} \sum_{(x, y) \in \boldsymbol{E}}\left|\hat{G}_{i x}^{(\mathbb{T})} \tilde{G}_{y c_{k}}^{(\mathbb{T})}\right| \tag{12.6}
\end{equation*}
$$

where the summation is over the ordered pairs

$$
\begin{equation*}
(x, y) \in \boldsymbol{E}=\left\{\left(a_{1}, b_{1}\right), \ldots,\left(a_{\nu}, b_{\nu}\right),\left(b_{1}, a_{1}\right), \ldots,\left(b_{\nu}, a_{\nu}\right)\right\} . \tag{12.7}
\end{equation*}
$$

By our assumption on $\eta$, the first term on the right-hand side of (12.6) is smaller than the right-hand sides of (12.2)-(12.4), so we only need to estimate the sum on the right-hand side of (12.6).

Green's function estimates. To estimate the sum on the right-hand side of (12.6), we use the following estimates on Green's functions, which hold for $(x, y) \in \boldsymbol{E}$ :

$$
\begin{align*}
& \left|\hat{G}_{i x}^{(\mathbb{T})}\right| \leqslant \begin{cases}2\left|m_{s c}\right| & (\text { all } x), \\
2 K\left|m_{s c}\right| q^{r} & \left(\text { dist }_{\hat{\mathcal{G}}^{(\mathbb{T})}}(i, x) \geqslant 2 r\right), \\
2 M / \sqrt{N \eta} & (i \text { and } x \text { are in different S-cells, } \\
\text { or } i \nsim \text { the S-cell containing } x),\end{cases}  \tag{12.8}\\
& \left|\tilde{G}_{y c_{k}}^{\mathbb{T}^{\mathbb{T}} \mid}\right| \leqslant \begin{cases}2\left|m_{s c}\right| & (\text { all } y), \\
2^{7} K^{3}\left|m_{s c}\right| q^{r} & \left(\text { dist }_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(y, c_{k}\right) \geqslant 2 r\right) .\end{cases} \tag{12.9}
\end{align*}
$$

The last bound in (12.8) holds by (11.3). The remaining estimates follow from Propositions 11.1, together with (5.6) for the bound for all $x, y$; using that $P_{i x}\left(\mathcal{E}_{r}\left(i, x, \hat{\mathcal{G}}^{(\mathbb{T})}\right)\right)=0$ for the bound for $\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}(i, x) \geqslant 2 r$ and using also that $P_{y c_{k}}\left(\mathcal{E}_{r}\left(y, c_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)=0$ for the bound for dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(y, c_{k}\right) \geqslant 2 r$.

Distance estimates. Since the estimates (12.8)-(12.9) depend on distances, we need some estimates on distances in the graphs $\hat{\mathcal{G}}^{(\mathbb{T})}$ and $\tilde{\mathcal{G}}^{(\mathbb{T})}$. These are summarized in the following lemma.

Lemma 12.2. Let $k \in J$ and $\mathbb{S}^{\prime}$ be the $\mathrm{S}^{\prime}$-cell that contains $c_{k}$. Then the following estimates hold.

1. In the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$, the vertex $c_{k}$ is far away from $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$ :

$$
\begin{equation*}
\operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(c_{k},\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{v}\right\}\right)>2 r \tag{12.10}
\end{equation*}
$$

2. If dist $_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, \mathbb{S}^{\prime}\right)>2 r$, then

$$
\begin{equation*}
\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant 2 r . \tag{12.11}
\end{equation*}
$$

3. If $i \in \mathbb{X}_{1}$ and $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant 2 r$, then

$$
\begin{equation*}
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, \mathbb{S}^{\prime}\right)>2 r \tag{12.12}
\end{equation*}
$$

Notice also that, by the definition of $J$, we have $\left\{m \in \llbracket 1, \nu \rrbracket: b_{m} \in \mathbb{S}^{\prime}\right\}=\{k\}$.
Proof. To prove (i), it follows from (12.5) from the definition of $J$ that

$$
\operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(c_{k},\left\{a_{m}: m \in \llbracket 1, \mu \rrbracket \backslash\{k\} \cup\left\{b_{m}: m \in \llbracket 1, v \rrbracket \backslash\{k\}\right\}\right\}>R / 4>2 r .\right.
$$

It remains to prove $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(c_{k},\left\{a_{k}, b_{k}\right\}\right\}>2 r$. Given any geodesic in $\tilde{\mathcal{G}}^{(\mathbb{T})}$ from $c_{k}$ to $\left\{a_{k}, b_{k}\right\}$, we distinguish two cases. In the first case that the geodesic contains any of the edges $\left\{a_{m}, b_{m}\right\}_{m \leqslant \nu}$, the condition (12.5) which holds by the definition of $J$, implies that its length is larger than $2 r$. In the second case that the geodesic contains none of the edges $\left\{a_{m}, b_{m}\right\}_{m \leqslant \nu}$, it a path on the graph $\hat{\mathcal{G}}^{(\mathbb{T})}$.

Therefore, to prove (i), it suffices to show that (12.10) holds with the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$ replaced by $\hat{\mathcal{G}}^{(\mathbb{T})}$. By the condition $b_{k}, c_{k} \in \mathbb{X}_{2}$, and since $b_{k}, c_{k}$ are adjacent in $\mathcal{G}^{(\mathbb{T})}$, it follows from Lemma 9.3 that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(b_{k}, a_{k}\right)>8 r$, and therefore that

$$
\operatorname{dist}_{\hat{\mathcal{G}}_{(\mathbb{T})}}\left(c_{k}, a_{k}\right) \geqslant \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(c_{k}, a_{k}\right)>8 r>2 r .
$$

Moreover, since $c_{k}$ has radius- $R$ tree neighborhood in $\mathcal{G}^{(\mathbb{T})}$, and since in $\hat{\mathcal{G}}^{(\mathbb{T})}$ the edge $\left\{b_{k}, c_{k}\right\}$ is removed compared to $\mathcal{G}^{(\mathbb{T})}$, we have

$$
\operatorname{dist}_{\hat{\mathcal{G}}_{(\mathbb{T})}}\left(b_{k}, c_{k}\right)>R>2 r .
$$

This completes the proof of (12.10) with $\tilde{\mathcal{G}}^{(\mathbb{T})}$ replaced by $\hat{\mathcal{G}}^{(\mathbb{T})}$, and thus the proof of (i).

For (ii), since $a_{k}$ and $b_{k} \in \mathbb{S}^{\prime}$ are adjacent in the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$, we have

$$
\operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(i, \mathbb{S}^{\prime}\right)-1 \geqslant 2 r .
$$

The first inequality in (12.11) is trivial since $\hat{\mathcal{G}}^{(\mathbb{T})} \subset \tilde{\mathcal{G}}^{(\mathbb{T})}$.
To prove (iii), note that any geodesic from $i$ to $\mathbb{S}^{\prime}$ in $\tilde{\mathcal{G}}^{(\mathbb{T})}$ either contains $a_{k}$, or does not contain the edge $\left\{a_{k}, b_{k}\right\}$. In the first case that the geodesic contains $a_{k}$, its length is at least $1+\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right)>2 r$, as desired. In the second case,

$$
\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, \mathbb{S}^{\prime}\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})} \backslash\left\{a_{k}, b_{k}\right\}}\left(\mathbb{X}_{1} \cup \mathbb{X}_{2} \backslash \mathbb{S}^{\prime}, \mathbb{S}^{\prime}\right)=\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(\mathbb{X}_{1} \cup \mathbb{X}_{2} \backslash \mathbb{S}^{\prime}, \mathbb{S}^{\prime}\right)>4 r
$$

where the first inequality holds since $i \in \mathbb{X}_{1} \cup \mathbb{X}_{2} \backslash \mathbb{S}^{\prime}$, and the last inequality follows from the definition of the S-cells and Lemma 9.3. Recall that the graph $\tilde{\mathcal{G}}^{(\mathbb{T})}$ is obtained from $\mathcal{G}^{(\mathbb{T})}$ by adding the edges $\left\{a_{m}, b_{m}\right\}_{m \leqslant \nu}$ and removing the edges $\left\{b_{m}, c_{m}\right\}_{m \leqslant \nu}$. And by the definition of the set $J$, we know $\left\{b_{k}, c_{k}\right\} \subset \mathbb{S}^{\prime}$ and $\left\{b_{m}, c_{m}: m \in \llbracket 1, \nu \rrbracket \backslash\{k\}\right\} \subset \mathbb{X}_{1} \cup$ $\mathbb{X}_{2} \backslash \mathbb{S}^{\prime}$. Therefore, the graph $\tilde{\mathcal{G}}^{(\mathbb{T})} \backslash\left\{a_{k}, b_{k}\right\}$ and $\mathcal{G}^{(\mathbb{T})}$ are different only on the subgraphs induced on $\mathbb{S}^{\prime}$ and $\mathbb{X}_{1} \cup \mathbb{X}_{2} \backslash \mathbb{S}^{\prime}$, and the equality in the above equation holds.
Remark 12.3. Recall the random walk representation of the Green's function from Sect. 3.3. In terms of the random walk heuristic, together with the a priori estimates (12.8)-(12.9) on the Green's function, one can understand the bounds of Proposition 12.1 as follows. For the left-hand side of (12.2), the walk with most weight is $i \rightarrow a_{k} \rightarrow b_{k} \rightarrow c_{k}$. Since $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant 2 r$ and $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(b_{k}, c_{k}\right) \geqslant 2 r$, the walks $i \rightarrow a_{k}$ and $b_{k} \rightarrow c_{k}$ each contribute at least a small factor $q^{r}$; the walk $a_{k} \rightarrow b_{k}$ has at least one step and thus contributes at least a factor $q$. Therefore $\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \lesssim q^{r} \times q \times q^{r}=q^{2 r+1}$. For the left-hand side of (12.3), the walk with most weight is $i=c_{j} \rightarrow b_{j} \rightarrow a_{j} \rightarrow a_{k} \rightarrow b_{k} \rightarrow c_{k}$, and it therefore follows that $\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \lesssim q^{r} \times q \times q^{r} \times q \times q^{r}=q^{3 r+2}$. For the left-hand side of (12.4), the walk with most weight is $i \rightarrow a_{k} \rightarrow b_{k} \rightarrow c_{k}$, and thus $\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| \lesssim q^{2 r+1}$.

The proof of Proposition 12.1 essentially follows from the heuristic described in Remark 12.3, which can be made rigorous by combining the estimates on the Green's function of (12.8)-(12.9) with those on the distances stated in Lemma 12.2. This requires a division into a number of cases and is done carefully below.

### 12.2. Proof of (12.2). Let

$$
\begin{align*}
& \Gamma_{1}:=\max \left\{\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right|: i \in \mathbb{X}_{1} \text { such that dist } \tilde{\mathcal{G}}_{(\mathbb{T})}\left(i, \mathbb{S}^{\prime}\right)>2 r\right\},  \tag{12.13}\\
& \Gamma_{2}:=\max \left\{\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right|: i \in \mathbb{X}_{2} \text { and } i \notin \mathbb{S}^{\prime}\right\} . \tag{12.14}
\end{align*}
$$

Thus $\Gamma_{1}$ is the maximal size of the Green's function between $c_{k}$ and vertices in $\mathbb{X}_{1}$ which is away from $\mathbb{S}^{\prime}$, and $\Gamma_{2}$ is the maximal size of the Green's function between $c_{k}$ and vertices in $\mathbb{X}_{2}$ which is in different $\mathrm{S}^{\prime}$-cells from $c_{k}$.

## Proposition 12.4.

$$
\begin{equation*}
\max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant 2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1}, \tag{12.15}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$, that $\omega^{\prime} q^{r} \ll 1$, and that $\sqrt{N \eta} q^{2 r+2} \geqslant M$.

Given Proposition 12.4, the claim (12.2) is an immediate consequence.
Proof of (12.2). It suffices to show that the left-hand side of (12.2) is bounded by $\max \left\{\Gamma_{1}, \Gamma_{2}\right\}$. First, if $i \in \mathbb{X}_{2}$, then $i=c_{l}$ for some $l \neq k$, and by the definition of $J$, then $c_{l} \notin \mathbb{S}^{\prime}$. Thus the left-hand sides of (12.2) is bounded by $\Gamma_{2}$. Second, if $i \in \mathbb{X}_{1}$, then either $i=a_{l}$ or $i=c_{l}$ for some $l \neq k$. In either case, by the definition of $J$, $\operatorname{dist}_{\tilde{\mathcal{G}}(\mathbb{T})}\left(i, \mathbb{S}^{\prime}\right)>R / 4-2 r>2 r$. Thus the left-hand side of (12.2) is bounded by $\Gamma_{1}$.

Proof of Proposition 12.4. We first derive a bound for $\Gamma_{1}$. Let $i$ obey the conditions in the definition of $\Gamma_{1}$ in (12.13). We divide the sum over the set $\boldsymbol{E}$ in (12.6) according to the cases in (12.8)-(12.9) as $\boldsymbol{E}=\boldsymbol{E}_{1} \cup \cdots \cup \boldsymbol{E}_{5}$, where

$$
\begin{aligned}
& \boldsymbol{E}_{1}=\left\{\left(a_{k}, b_{k}\right)\right\} \\
& \boldsymbol{E}_{2}=\left\{\left(b_{k}, a_{k}\right)\right\}, \\
& \boldsymbol{E}_{3}=\left\{\left(b_{l}, a_{l}\right): l \neq k, b_{l} \in \mathbb{X}_{2}\right\}, \\
& \boldsymbol{E}_{4}=\left\{\left(a_{l}, b_{l}\right): l \neq k, b_{l} \in \mathbb{X}_{2}\right\}, \\
& \boldsymbol{E}_{5}=\left\{\left(a_{l}, b_{l}\right),\left(b_{l}, a_{l}\right): l \neq k, b_{l} \in \mathbb{X}_{1}\right\} .
\end{aligned}
$$

For $\left(a_{k}, b_{k}\right) \in \boldsymbol{E}_{1}$, we have $\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{k}\right) \geqslant 2 r$ by (12.11) and $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(b_{k}, c_{k}\right) \geqslant 2 r$ by (12.10). Thus, by (12.8)-(12.9),

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant \frac{\left(2 K\left|m_{s c}\right| q^{r}\right)\left(2^{7} K^{3}\left|m_{s c}\right| q^{r}\right)}{\sqrt{d-1}}
$$

For $\left(b_{k}, a_{k}\right) \in \boldsymbol{E}_{2}$, we have $b_{k} \in \mathbb{X}_{2}$ and $i \in \mathbb{X}_{1}$, which implies $i$ and $b_{k}$ are in different S-cells. Thus, by (12.8)-(12.9),

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant \frac{2 M}{\sqrt{N \eta}} \frac{2\left|m_{s c}\right|}{\sqrt{d-1}} \leqslant \frac{4 q M}{\sqrt{N \eta}}
$$

For $\left(b_{l}, a_{l}\right) \in \boldsymbol{E}_{3}$, we again have that $i$ and $b_{l}$ are in different S-cells (since $b_{l} \in \mathbb{X}_{2}$ ) and $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(a_{l}, c_{k}\right) \geqslant 2 r$ by (12.10). Thus, by (12.8)-(12.9) and $\left|\boldsymbol{E}_{3}\right| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$,

$$
\sum_{\boldsymbol{E}_{3}}[\cdots] \leqslant \frac{M}{\sqrt{N \eta}} 2^{9} K^{3}(d-1)^{\ell+1} q^{r+1}
$$

For $\left(a_{l}, b_{l}\right) \in \boldsymbol{E}_{4}$, there are at most $\omega+1$ indices $l$ such that $\operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i, a_{l}\right) \leqslant \operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}\left(i, a_{l}\right)<$ $2 r$ by (4.7), and at most $\left|\boldsymbol{E}_{4}\right| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$ indices such that dist $\hat{\mathcal{G}}^{(\mathbb{T})}\left(i, a_{l}\right) \geqslant 2 r$. Moreover, we have $b_{l} \in \mathbb{X}_{2}$ and also $b_{l} \notin \mathbb{S}^{\prime}$ by the definition of $J$. Thus, by (12.8) and the definition of $\Gamma_{2}$,

$$
\sum_{\boldsymbol{E}_{4}}[\cdots] \leqslant\left((\omega+1) \frac{2\left|m_{s c}\right|}{\sqrt{d-1}}+2(d-1)^{\ell+1} \frac{2 K\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}\right) \Gamma_{2}
$$

For $(x, y) \in \boldsymbol{E}_{5}$, there are at most $10 \omega$ pairs $(x, y) \in \boldsymbol{E}_{5}$ such that dist $\tilde{\mathcal{G}}_{(\mathbb{T})}(i, x)<$ $2 r$ by (8.7) in Proposition 8.2, at most $2 \omega^{\prime}$ pairs such that dist $\tilde{\mathcal{G}}_{(\mathbb{T})}(i, x) \geqslant 2 r$ since $\left|\mathbb{X}_{1} \cap\left\{b_{1}, \ldots, b_{\nu}\right\}\right| \leqslant \omega^{\prime}$ by (9.6). Thus, by (12.8) and $\left|\tilde{G}_{y c_{k}}^{(\mathbb{T})}\right| \leqslant \Gamma_{1}$

$$
\sum_{E_{5}}[\cdots] \leqslant\left(10 \omega \frac{2\left|m_{s c}\right|}{\sqrt{d-1}}+2 \omega^{\prime} \frac{2 K\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}\right) \Gamma_{1}
$$

Combining the sums over $\boldsymbol{E}_{1}, \ldots \boldsymbol{E}_{5}$, and taking the maximum over $i$ obeying the conditions in the definition of $\Gamma_{1}$ in (12.13), we get

$$
\begin{align*}
\Gamma_{1} \leqslant & \left(2+4 q+2^{9} K^{3}\right) \frac{M}{\sqrt{N \eta}}+2^{8} K^{4}\left|m_{s c}\right| q^{2 r+1} \\
& +\left(20 \omega q+4 K \omega^{\prime} q^{r+1}\right) \Gamma_{1}+(2(\omega+1) q+4 K) \Gamma_{2} \tag{12.16}
\end{align*}
$$

To bound $\Gamma_{2}$, let $i \in \mathbb{X}_{2}$ be as in the definition of $\Gamma_{2}$. Let $\mathbb{S}^{\prime \prime}$ be the $\mathrm{S}^{\prime}$-cell containing $i$, and notice that $\mathbb{S}^{\prime} \neq \mathbb{S}^{\prime \prime}, \mathbb{S}_{1}^{\prime}$ from the definition of $\Gamma_{2}$. We now divide $\boldsymbol{E}=\boldsymbol{E}_{1}^{\prime} \cup \cdots \cup \boldsymbol{E}_{4}^{\prime}$ where

$$
\begin{align*}
& \boldsymbol{E}_{1}^{\prime}=\left\{(x, y): x \in X_{1}\right\}  \tag{12.17}\\
& \boldsymbol{E}_{2}^{\prime}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{S}^{\prime}\right\}=\left\{\left(b_{k}, a_{k}\right)\right\},  \tag{12.18}\\
& \boldsymbol{E}_{3}^{\prime}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{S}^{\prime \prime}\right\}  \tag{12.19}\\
& \boldsymbol{E}_{4}^{\prime}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{X}_{2} \backslash\left(\mathbb{S}^{\prime} \cup \mathbb{S}^{\prime \prime}\right)\right\} . \tag{12.20}
\end{align*}
$$

For $(x, y) \in \boldsymbol{E}_{1}^{\prime}, i$ and $x$ are in different $S$-cells (since $x \in \mathbb{X}_{1}$ and $i \in \mathbb{X}_{2}$ ) and $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(y, c_{k}\right)>2 r$ by $(12.10)$. Since $\left|\boldsymbol{E}_{1}^{\prime}\right| \leqslant 2 \mu \leqslant 4(d-1)^{\ell+1}$

$$
\sum_{\boldsymbol{E}_{1}^{\prime}}[\cdots] \leqslant 4(d-1)^{\ell+1} \frac{2 M}{\sqrt{N \eta}} \frac{2^{7} K^{3}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

For $\left(b_{k}, a_{k}\right) \in \boldsymbol{E}_{2}^{\prime}, i$ and $b_{k}$ are in different $S$-cells since $i \in \mathbb{S}^{\prime \prime}$ and $b_{k} \in \mathbb{S}^{\prime}$ by assumption. Moreover, we have $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(a_{k}, c_{k}\right)>2 r$ by (12.10). Thus

$$
\sum_{\boldsymbol{E}_{2}^{\prime}}[\cdots] \leqslant \frac{2 M}{\sqrt{N \eta}} \frac{2^{7} K^{3}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

For $\left(b_{l}, a_{l}\right) \in \boldsymbol{E}_{3}^{\prime}$, there are at most $5 \omega$ indices $l$ such that dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(i, b_{l}\right)<2 r$ by (8.7) in Proposition 8.2, and at most $\left|\boldsymbol{E}_{3}^{\prime}\right| \leqslant\left|\left\{l \in \llbracket 1, v \rrbracket: b_{l} \in \mathbb{S}^{\prime \prime}\right\}\right| \leqslant \omega^{\prime}+5 \omega$ indices such that $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(i, b_{l}\right) \geqslant 2 r$ by (9.7). Moreover, $\left|\tilde{G}_{a_{l} c_{k}}^{(\mathbb{T})}\right| \leqslant \Gamma_{1}\left(\right.$ since dist $_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(a_{l}, \mathbb{S}^{\prime}\right)>$ $R / 4-2 r>2 r$ by the definition of $J$ ). Thus

$$
\sum_{\boldsymbol{E}_{3}^{\prime}}[\cdots] \leqslant\left(5 \omega \frac{2\left|m_{s c}\right|}{\sqrt{d-1}}+\left(\omega^{\prime}+5 \omega\right) \frac{2 K\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}\right) \Gamma_{1}
$$

For $\left(b_{l}, a_{l}\right) \in \boldsymbol{E}_{4}^{\prime}, i$ and $b_{l}$ are in different S-cells; $a_{l}$ and $c_{k}$ are in different S-cells (since $a_{l} \in \mathbb{S}_{1}^{\prime}$ and $c_{k} \in \mathbb{S}^{\prime}$; there are at most $\left|\boldsymbol{E}_{4}^{\prime}\right| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$ terms. Thus

$$
\sum_{\boldsymbol{E}_{4}^{\prime}}[\cdots] \leqslant 2(d-1)^{\ell+1} \frac{2 M}{\sqrt{N \eta}} \frac{\Gamma_{1}}{\sqrt{d-1}}
$$

Combining the sums over $\boldsymbol{E}_{1}^{\prime}, \ldots, \boldsymbol{E}_{4}^{\prime}$, and taking the maximum over $i$ obeying the conditions in the definition of $\Gamma_{2}$, we get

$$
\begin{align*}
\Gamma_{2} \leqslant & \left(2+2^{10} K^{3}+2^{8} K^{3} q^{r+1}\right) \frac{M}{\sqrt{N \eta}} \\
& +\left(10 \omega q+2 K\left(\omega^{\prime}+5 \omega\right) q^{r+1}+\frac{4(d-1)^{\ell+1 / 2} M}{\sqrt{N \eta}}\right) \Gamma_{1} . \tag{12.21}
\end{align*}
$$

In summary, in (12.16) and (12.21), we have shown that

$$
\Gamma_{1} \leqslant \mathfrak{a}+\mathfrak{b} \Gamma_{1}+\mathfrak{c} \Gamma_{2}, \quad \Gamma_{2} \leqslant \mathfrak{d}+\mathfrak{e} \Gamma_{1},
$$

where $\mathfrak{a}, \mathfrak{b}, \mathfrak{c}, \mathfrak{d}, \mathfrak{e}$ are explicit constants given in (12.16) and (12.21). By plugging the second estimate into the first one, noticing $\mathfrak{b}+\mathfrak{c e}<1$, and using the explicit values of $\mathfrak{a}, \mathfrak{b}, \mathfrak{c}, \mathfrak{d}, \mathfrak{e}$, it follows that
$\Gamma_{1} \leqslant(\mathfrak{a}+\mathfrak{c d}) /(1-(\mathfrak{b}+\mathfrak{c e})) \leqslant 2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1}, \quad \Gamma_{2} \leqslant \mathfrak{d}+\mathfrak{e} \Gamma_{1} \leqslant 2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1}$, provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$, that $\omega^{\prime} q^{r} \ll 1$, and that $\sqrt{N \eta} q^{2 r+2} \geqslant M$.
12.3. Proofs of (12.4) and (12.3).

Proof of (12.4). To bound the left-hand side of (12.4), consider first the case that $i \in$ $\mathbb{X}_{1} \cup \mathbb{X}_{2}:\left(\right.$ (i) if $i \in \mathbb{X}_{1}$ and dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(i, a_{k}\right) \geqslant 2 r$, it follows by (12.12) that dist $\tilde{\mathcal{G}}^{(\mathbb{T})}\left(i, \mathbb{S}^{\prime}\right)>$ $2 r$. Thus the left-hand side of (12.4) is bounded by $\Gamma_{1}$; (ii) if $i \in \mathbb{X}_{2}$ and $i \nsim b_{k}$, then $i \notin \mathbb{S}^{\prime}$, and the left-hand side of (12.4) is bounded by $\Gamma_{2}$. Therefore (12.4) follows from Proposition 12.4.

For the remaining case $i \notin \mathbb{X}_{1} \cup \mathbb{X}_{2}$ and $i \nsim b_{k}$, we bound the sum over $\boldsymbol{E}$ in (12.6). By the definition of $\mathbb{X}_{1}$ and $\mathbb{X}_{2}, \operatorname{dist}_{\mathcal{G}^{(\mathbb{T})}}\left(i,\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}\right)>2 r$, and therefore also in $\hat{\mathcal{G}}^{(\mathbb{T})} \subset \mathcal{G}^{(\mathbb{T})}$. Thus (12.8) implies $\left|\hat{G}_{i x}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ for all $x \in$ $\left\{a_{1}, \ldots, a_{\nu}, b_{1}, \ldots, b_{v}\right\}$.

For $(x, y)=\left(a_{k}, b_{k}\right),\left(b_{k}, a_{k}\right)$, we have $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(y, c_{k}\right)>2 r$ by (12.10), and thus $\left|\tilde{G}_{y c_{k}}^{(\mathbb{T})}\right| \leqslant 2^{7} K^{3}\left|m_{s c}\right| q^{r}$ by (12.9). The remaining $y \neq a_{k}, b_{k}$ satisfy either the condition in (12.13) or in (12.14). Therefore $\left|\tilde{G}_{y c_{k}}^{(\mathbb{T})}\right| \leqslant \max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \Gamma_{1}$, and there are at most $2 \mu \leqslant 2 d(d-1)^{\ell}$ such terms.

In summary, we have shown

$$
\begin{aligned}
\left|\tilde{G}_{i c_{k}}^{(\mathbb{T})}\right| & \leqslant \frac{2 M}{\sqrt{N \eta}}+2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1}+\left(2 K q^{r+1}\right)\left(2 d(d-1)^{\ell}\right) \Gamma_{1} \\
& \leqslant 2^{12} K^{5}\left|m_{s c}\right| q^{2 r+1},
\end{aligned}
$$

provided that $\sqrt{N \eta} \geqslant M q^{-2 r-2}$, where we used $r=2 \ell+1$.
Proof of (12.3). It remains to estimate $\tilde{G}_{c_{j} c_{k}}^{(\mathbb{T})}$ for $j \in J \backslash\{k\}$. As previously, we denote by $\mathbb{S}^{\prime}$ the $S^{\prime}$-cell containing $c_{k}$, and now denote by $\mathbb{S}^{\prime \prime}$ the $S^{\prime}$-cell containing $c_{j}$. The estimates
in Lemma 12.2 on distances from $c_{k}$ also apply with $c_{k}$ replaced by $c_{j}$. Similarly to the bound of $\Gamma_{2}$, we use formula (12.6) and devide $\boldsymbol{E}$ as $\boldsymbol{E}=\boldsymbol{E}_{1} \cup \cdots \cup \boldsymbol{E}_{5}$, where

$$
\begin{aligned}
& \boldsymbol{E}_{1}=\left\{(x, y): x \in \mathbb{X}_{1}, x \neq a_{k}\right\}, \\
& \boldsymbol{E}_{2}=\left\{\left(a_{k}, b_{k}\right)\right\}, \\
& \boldsymbol{E}_{3}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{S}^{\prime}\right\}=\left\{\left(b_{k}, a_{k}\right)\right\}, \\
& \boldsymbol{E}_{4}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{S}^{\prime \prime}\right\}=\left\{\left(b_{j}, a_{j}\right)\right\}, \\
& \boldsymbol{E}_{5}=\left\{\left(b_{l}, a_{l}\right): b_{l} \in \mathbb{X}_{2} \backslash\left(\mathbb{S}^{\prime} \cup \mathbb{S}^{\prime \prime}\right)\right\} .
\end{aligned}
$$

Notice that for any $x \in\left\{a_{1}, \ldots, a_{v}, b_{1}, \ldots, b_{v}\right\} \backslash\left\{b_{j}\right\}$, by the definition of $J, x, c_{j}$ are in different S-cells, and thus $\left|\hat{G}_{c_{j} x}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}$ by (12.8). Moreover, by the definition of $J$, for any $y \in\left\{a_{m}, b_{m}: m \in \llbracket 1, \nu \rrbracket \backslash\{k\}\right\}$, we have $\operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(y, \mathbb{S}^{\prime}\right)>R / 4-2 r>2 r$ and thus $y$ satisfies the condition either in (12.13) or in (12.14). It follows that $\left|\tilde{\boldsymbol{G}}_{y c_{k}}^{(\mathbb{T})}\right| \leqslant$ $\max \left\{\Gamma_{1}, \Gamma_{2}\right\} \leqslant \Gamma_{1}$. For $(x, y) \in \boldsymbol{E}_{1}$. Since $\left|\boldsymbol{E}_{1}\right| \leqslant 2 \mu \leqslant 4(d-1)^{\ell+1}$, it follows that

$$
\sum_{\boldsymbol{E}_{1}}[\cdots] \leqslant 4(d-1)^{\ell+1} \frac{2 M}{\sqrt{N \eta}} \frac{\Gamma_{1}}{\sqrt{d-1}}
$$

For $(x, y)=\left(a_{k}, b_{k}\right) \in \boldsymbol{E}_{2}$. By $(12.10), \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(b_{k}, c_{k}\right)>2 r$, and thus $\left|\tilde{G}_{b_{k} c_{k}}^{(\mathbb{T})}\right| \leqslant$ $2^{7} K^{3}\left|m_{s c}\right| q^{r}$.

$$
\sum_{\boldsymbol{E}_{2}}[\cdots] \leqslant \frac{2 M}{\sqrt{N \eta}} \frac{2^{7} K^{3}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

For $(x, y)=\left(b_{k}, a_{k}\right) \in \boldsymbol{E}_{3}$. By $(12.10), \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(a_{k}, c_{k}\right)>2 r$, and thus $\left|\tilde{G}_{a_{k} c_{k}}^{(\mathbb{T})}\right| \leqslant$ $2^{7} K^{3}\left|m_{s c}\right| q^{r}$.

$$
\sum_{\boldsymbol{E}_{3}}[\cdots] \leqslant \frac{2 M}{\sqrt{N \eta}} \frac{2^{7} K^{3}\left|m_{s c}\right| q^{r}}{\sqrt{d-1}}
$$

For $(x, y)=\left(b_{j}, a_{j}\right) \in \boldsymbol{E}_{4}$, by (12.10) with $c_{k}$ replaced by $c_{j}$, we have the distance estimates

$$
\operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(c_{j},\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{v}\right\}>2 r\right.
$$

In particular, $\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}\left(c_{j}, b_{j}\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(c_{j}, b_{j}\right)>2 r$, and $\left|\hat{G}_{c_{j} b_{j}}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ by (12.8). Thus

$$
\sum_{\boldsymbol{E}_{4}}[\cdots] \leqslant \frac{2 K\left|m_{s c}\right| q^{r}}{\sqrt{d-1}} \Gamma_{1}
$$

For $(x, y) \in \boldsymbol{E}_{5}$, since $\left|\boldsymbol{E}_{5}\right| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$, it follows that

$$
\sum_{E_{5}}[\cdots] \leqslant 2(d-1)^{\ell+1} \frac{2 M}{\sqrt{N \eta}} \frac{\Gamma_{1}}{\sqrt{d-1}}
$$

The above discussion combined with (12.15) leads to the estimate

$$
\begin{aligned}
\left|\tilde{G}_{c_{j} c_{k}}^{(\mathbb{T})}\right| & \leqslant \frac{M}{\sqrt{N \eta}}\left(2+2^{9} K^{3} q^{r+1}+12(d-1)^{\ell+1 / 2} \Gamma_{1}\right)+2 K q^{r+1} \Gamma_{1} \\
& \leqslant 2^{12} K^{5}\left|m_{s c}\right| q^{3 r+2}
\end{aligned}
$$

provided that $\sqrt{N \eta} q^{3 r+2} \geqslant M$.

## 13. Stability Estimate for the Switched Graph

Proposition 13.1. Under the assumptions of Propositions 11.1, for $\mathbf{S} \in F(\mathcal{G})$ (as in Sect. 11.1) such that $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$ (as in Sect. 3.2), the Green's function of the switched graph satisfies the weak stability estimate that for all $i, j \in \llbracket N \rrbracket$,

$$
\begin{equation*}
\left|\tilde{G}_{i j}(z)\right| \leqslant\left|\tilde{G}_{j j}(z)\right| \leqslant 2 \tag{13.1}
\end{equation*}
$$

Moreover, the off-diagonal entries of the Green's function satisfy the following improved estimates around vertex 1 . For all vertices $x \in \llbracket 2, N \rrbracket$,

$$
\begin{equation*}
\left|\tilde{G}_{1 x}-P_{1 x}\left(\mathcal{E}_{r}(1, x, \tilde{\mathcal{G}})\right)\right| \leqslant(\omega+1) 2^{2 \omega+14} K^{3}\left|m_{s c}\right| q^{r+1} \tag{13.2}
\end{equation*}
$$

For all estimates, we assume that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \omega^{\prime 2} q^{\ell} \ll$ 1 and $\sqrt{N \eta} q^{3 r+2} \geqslant M$.
13.1. Preparation of the proof. As in (12.1), we denote by $\partial_{E} \mathcal{T}$ the boundary edges of $\mathcal{T}$ in the switched graph $\tilde{\mathcal{G}}$, and the corresponding boundary vertex set by $\mathbb{I}=$ $\left\{\tilde{a}_{1}, \tilde{a}_{2}, \ldots, \tilde{a}_{\mu}\right\}$. Let $J$ be the index set of Proposition 12.1. Throughout the following proof, $C$ represents constants that may differ from line to line, but depends only on the constant $K$ of (11.1) and the excess $\omega$. As in previous proofs, we follow the structure described below (10.4).

Localization. To prove Proposition 15.1, we replace $P_{i j}\left(\mathcal{E}_{r}(i, j, \tilde{\mathcal{G}})\right)$ by a vertex independent Green's function $P_{i j}$ according to Remark 5.3, applied with $\tilde{\mathcal{G}}_{0}=\mathcal{B}_{3 r}(1, \tilde{\mathcal{G}})$ and $\mathbb{X}=\mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$. We abbreviate

$$
\tilde{\mathcal{G}}_{1}=\mathrm{TE}\left(\tilde{\mathcal{G}}_{0}\right), \quad \tilde{P}=G\left(\tilde{\mathcal{G}}_{1}\right), \quad \tilde{\mathcal{G}}_{1}^{(\mathbb{T})}=\mathrm{TE}\left(\tilde{\mathcal{G}}_{0}^{(\mathbb{T})}\right), \quad \tilde{P}^{(\mathbb{T})}=G\left(\tilde{\mathcal{G}}_{1}^{(\mathbb{T})}\right)
$$

Notice that $\tilde{\mathcal{G}}_{1}^{(\mathbb{T})}$ is the same as removing the vertices $\mathbb{T}$ from $\tilde{\mathcal{G}}_{1}$, and thus $\tilde{P}^{(\mathbb{T})}=$ $G^{(\mathbb{T})}\left(\tilde{\mathcal{G}}_{1}\right)$.
Claim 13.2. Let $k \in J$ (as in Sect. 12.1), and let $\mathbb{K}$ be the connected component of $\tilde{\mathcal{G}}_{0}$ containing $\tilde{a}_{k}=c_{k}$. Then

$$
\begin{equation*}
\left\{m \in \llbracket 1, \mu \rrbracket: \tilde{a}_{m} \in \mathbb{K}\right\}=\{k\}, \tag{13.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\max _{i \in \mathbb{K}} \operatorname{dist}_{\tilde{\mathcal{G}}(\mathbb{T})}\left(i, \tilde{a}_{k}\right) \leqslant 3 r . \tag{13.4}
\end{equation*}
$$

Proof. (13.3) follows from the condition (12.5) in the definition of $J$, i.e. from dist $\tilde{\mathcal{G}}_{(\mathbb{T})}$ $\left(\tilde{a}_{k},\left\{\tilde{a}_{m}: m \in \llbracket 1, \mu \rrbracket \backslash\{k\}\right\}\right)>R / 4>6 r$. (13.4) follows from (13.3) and the construction of the subgraph $\tilde{\mathcal{G}}_{0}$.

Verification of assumptions in Proposition 5.2. As subgraphs of $\tilde{\mathcal{G}}$, both $\tilde{\mathcal{G}}_{0}$ and $\tilde{\mathcal{G}}_{0}^{(\mathbb{T})}$ have excess at most $\omega$. The deficit function $g$ of $\tilde{\mathcal{G}}_{0}$ vanishes. By Proposition 4.3, on each connected components of $\tilde{\mathcal{G}}_{0}^{(\mathbb{T})}$, the deficit function obeys $\sum g(v) \leqslant \omega+1 \leqslant 8 \omega$. Thus the assumptions for (5.5) are verified for both graphs $\tilde{\mathcal{G}}_{0}$ and $\tilde{\mathcal{G}}_{0}^{(\mathbb{T})}$, and we have (5.7):

$$
\begin{equation*}
\left|P_{i j}\left(\mathcal{E}_{r}(i, j, \tilde{\mathcal{G}})\right)-\tilde{P}_{i j}\right|,\left|P_{i j}\left(\mathcal{E}_{r}\left(i, j, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)-\tilde{P}_{i j}^{(\mathbb{T})}\right| \leqslant 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \tag{13.5}
\end{equation*}
$$

for $i, j \in \mathbb{X}$, provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$.
Starting point. The normalized adjacency matrices of $\tilde{\mathcal{G}}$ and $\tilde{\mathcal{G}}_{1}$ respectively have the block form

$$
\left[\begin{array}{cc}
H & \tilde{B}^{\prime} \\
\tilde{B} & D
\end{array}\right], \quad\left[\begin{array}{cc}
H & \tilde{B}_{1}^{\prime} \\
\tilde{B}_{1} & D_{1}
\end{array}\right],
$$

where $H$ is the normalized adjacency matrix for $\mathcal{T}$, and $\tilde{B}$ (respectively $\tilde{B}_{1}$ ) corresponds to the edges from $\mathbb{I}$ to $\mathbb{T}_{\ell}$, where $\mathbb{I}$ is the set of boundary vertices of $\mathcal{T}$ in the switched graph $\tilde{\mathcal{G}}$ as defined in (12.1), and $\mathbb{T}_{\ell}$ is the inner vertex boundary of $\mathcal{T}$ as in (7.24). To be precise, the nonzero entries of $\tilde{B}$ and $\tilde{B}_{1}$ occur for the indices $(i, j) \in \mathbb{I} \times \mathbb{T}_{\ell}$ and take values $1 / \sqrt{d-1}$. Notice that $\tilde{B}_{i j}=\left(\tilde{B}_{1}\right)_{i j}$; in the rest of this section we will therefore not distinguish $B$ and $\tilde{B}$.

By the Schur Complement formula (B.3), we have

$$
\begin{align*}
& \left.\tilde{G}\right|_{\mathbb{T}}=\left(H-z-\tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})} \tilde{B}\right)^{-1},  \tag{13.6}\\
& \left.\tilde{P}\right|_{\mathbb{T}}=\left(H-z-\tilde{B}^{\prime} \tilde{P}^{(\mathbb{T})} \tilde{B}\right)^{-1}, \tag{13.7}
\end{align*}
$$

and, by the resolvent identity (B.1), the difference of (13.6) and (13.7) is

$$
\begin{equation*}
\left.\tilde{G}\right|_{\mathbb{T}}-\left.\tilde{P}\right|_{\mathbb{T}}=(\tilde{G}-\tilde{P}) \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}+\tilde{P} \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P} \tag{13.8}
\end{equation*}
$$

In terms of the random walk heuristic described in Sect. 3.3, (13.8) has the interpretation that only walks that exit $\mathbb{T}$ contribute (see Fig. 11). We will adopt suggestive terminology corresponding to the random walk picture below. By Proposition 12.1, the Green's function $\tilde{G}^{(\mathbb{T})}$ is small between most vertices in $\mathbb{I}$. This is the main reason that the right-hand side of (13.8) is small. In the following, we analyze the various contributions precisely.
13.2. Boundary. The following lemma estimates the weight of "walks" from $x \in \mathbb{T}$ to $\mathbb{T}_{\ell}$, the inner vertex boundary of $\mathcal{T}$. It depends on the distance of $x$ to the boundary, or equivalently that from $x$ to 1 .

Lemma 13.3. Assume that $\tilde{\mathcal{G}}_{0}$ has excess at most $\omega$. For vertices $x \in \mathbb{T}_{\ell_{1}}$, i.e. $x$ is at distance $\ell_{1}$ from vertex 1 , we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x}\right| \leqslant(\omega+1) 2^{\omega+3}\left(\ell_{1}+1\right)\left|m_{s c}\right|^{\ell-\ell_{1}+1}(d-1)^{\left(\ell-\ell_{1}\right) / 2+1} . \tag{13.9}
\end{equation*}
$$



Fig. 11. Only walks that exit $\mathbb{T}$ contribute to (13.8)

For vertices $x \in \mathbb{T}_{\ell_{1}}$ and $y \in \mathbb{T}_{\ell_{2}}$, with $\ell_{1} \geqslant \ell_{2}$, we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x} \| \tilde{P}_{l_{k} y}\right| \leqslant \frac{(\omega+1)^{2} 2^{2 \omega+6}\left(\ell_{1}-\ell_{2}+2\right)}{(d-1)^{\left(\ell_{1}-\ell_{2}\right) / 2-1}}\left|m_{s c}\right|^{2 \ell-\ell_{1}-\ell_{2}+2} \tag{13.10}
\end{equation*}
$$

The proof of the lemma uses the following combinatorial estimate on the distances of a vertex $x$ to $\mathbb{T}_{\ell}$ (which is the inner vertex boundary of $\mathcal{T}$ ).

Lemma 13.4. Assume that the graph $\tilde{\mathcal{G}}_{0}=\mathcal{B}_{3 r}(1, \mathcal{G})$ has excess at most $\omega$. Given $x \in \mathbb{T}_{\ell_{1}}$, let $L_{x}$ be the multiset consisting of $2(\omega+1)(d-1)^{\ell-\ell_{3}}$ copies of the number $q^{\ell+\ell_{1}-2 \ell_{3}}$ for $\ell_{3} \in \llbracket 0, \ell_{1} \rrbracket$, and let $K_{x}$ be the multiset $K_{x}=\left\{q^{\text {dist }_{\tilde{\mathcal{G}}_{0}}(x, i)}: i \in \mathbb{T}_{\ell}\right\}$. Then the $k$-th largest number of $K_{x}$ is smaller than or equal to the $k$-th largest number of $L_{x}$.

We postpone the proof of the lemma to Appendix A.3. Given the lemma, the proof of Lemma 13.3 is completed as follows.

Proof of Lemma 13.3. To prove (13.9), we use

$$
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x}\right| \leqslant(d-1) \sum_{i \in \mathbb{T}_{\ell}}\left|\tilde{P}_{i x}\right| \leqslant 2^{\omega+2}(d-1)\left|m_{s c}\right| \sum_{i \in \mathbb{T}_{\ell}} q^{\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(x, i)}
$$

by Proposition 5.2. Defining the multiset $L_{x}$ as in Lemma 13.4, the inequality continuous with

$$
\begin{aligned}
& 2^{\omega+2}(d-1)\left|m_{s c}\right| \sum_{i \in \mathbb{T}_{\ell}} q^{\text {dist }_{\tilde{\mathcal{G}}_{0}}(x, i)} \\
& \quad \leqslant 2^{\omega+2}(d-1)\left|m_{s c}\right|(2 \omega+2) \sum_{\ell_{3}=0}^{\ell_{1}}(d-1)^{\ell-\ell_{3}} q^{\ell+\ell_{1}-2 \ell_{3}} \\
& \quad \leqslant(\omega+1) 2^{\omega+3}\left(\ell_{1}+1\right)\left|m_{s c}\right|^{\ell-\ell_{1}+1}(d-1)^{\left(\ell-\ell_{1}\right) / 2+1}
\end{aligned}
$$

This finishes the proof of (13.9).

For the proof of (13.10), we use

$$
\begin{aligned}
& \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x} \| \tilde{P}_{l_{k} y}\right| \\
& \leqslant(d-1) \sum_{i \in \mathbb{T}_{\ell}}\left|\tilde{P}_{i x}\right|\left|\tilde{P}_{i y}\right| \leqslant 2^{2 \omega+4}\left|m_{s c}\right|^{2}(d-1) \sum_{i \in \mathbb{T}_{\ell}} q^{\text {dist }} \tilde{\mathcal{G}}_{0}(x, i) q^{\text {dist }}{ }_{\mathcal{G}_{0}}(y, i) .
\end{aligned}
$$

We define the multisets $L_{x}$ and $L_{y}$ as in Lemma 13.4. More precisely, $L_{x}$ consists of $2(\omega+1)(d-1)^{\ell-\ell_{3}}$ copies of $q^{\ell+\ell_{1}-2 \ell_{3}}$ for $\ell_{3} \in \llbracket 0, \ell_{1} \rrbracket$, and $L_{y}$ consists of $2(\omega+1)(d-$ $1)^{\ell-\ell_{3}}$ copies of $q^{\ell+\ell_{2}-2 \ell_{3}}$ for $\ell_{3} \in \llbracket 0, \ell_{2} \rrbracket$. By the rearrangement inequality, we have

$$
\begin{aligned}
& \sum_{i \in \mathbb{T}_{\ell}} q^{\text {dist }_{\mathcal{G}_{0}}(x, i)} q^{\text {dist }} \tilde{\mathcal{G}}_{0}(y, i) \\
& \leqslant 4(\omega+1)^{2}\left(\sum_{\ell_{3}=0}^{\ell_{2}}(d-1)^{\ell-\ell_{3}} q^{\ell+\ell_{1}-2 \ell_{3}} q^{\ell+\ell_{2}-2 \ell_{3}}\right. \\
& \left.\quad+\sum_{\ell_{3}=\ell_{2}+1}^{\ell_{1}}(d-1)^{\ell-\ell_{3}} q^{\ell+\ell_{1}-2 \ell_{3}} q^{\ell-\ell_{2}}\right) \\
& \leqslant \frac{4(\omega+1)^{2}\left(\ell_{1}-\ell_{2}+2\right)}{(d-1)^{\left(\ell_{1}-\ell_{2}\right) / 2}}\left|m_{s c}\right|^{2 \ell-\ell_{1}-\ell_{2}}
\end{aligned}
$$

This finishes the proof of (13.10).
Remark 13.5. In the worst case, when $x=1$, we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x}\right| \leqslant(\omega+1) 2^{\omega+3}\left|m_{s c}\right|^{\ell+1}(d-1)^{\ell / 2+1} \tag{13.11}
\end{equation*}
$$

Moreover, when $x, y \in \mathbb{T}_{\ell_{1}}$, we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x}\right|\left|\tilde{P}_{l_{k} y}\right| \leqslant(\omega+1)^{2} 2^{2 \omega+7}\left|m_{s c}\right|^{2 \ell-2 \ell_{1}+2}(d-1) . \tag{13.12}
\end{equation*}
$$

These special cases will be used below.
13.3. Outside $\mathbb{T}$. The following proposition shows that the weight of "walks" outside $\mathbb{T}$ is small. It essentially follows from Proposition 12.1.

Proposition 13.6. Under the assumptions of Proposition 13.1, for any vertex $j \in \llbracket N \rrbracket \backslash \mathbb{T}$ such that $\operatorname{dist}_{\tilde{\mathcal{G}}}(1, j) \leqslant 2 r$, we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r} \tag{13.13}
\end{equation*}
$$

Moreover, for any vertex $j \in \llbracket N \rrbracket \backslash \mathbb{T}$ such that dist $_{\tilde{\mathcal{G}}}(1, j)>2 r$, we have

$$
\begin{equation*}
\sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r} \tag{13.14}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r}, \tag{13.15}
\end{equation*}
$$

where the constants $C$ depend only on the excess $\omega$ and $K$ (from Proposition 11.1). For all estimates, we assume $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} q^{3 r+2} \geqslant M$.

Claim 13.7. Let $j \in \llbracket N \rrbracket \backslash \mathbb{T}$ be as in the statement of Proposition 13.6. Then

$$
\begin{align*}
& \left|\left\{k \in \llbracket 1, v \rrbracket: \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(j, a_{k}\right) \leqslant R / 4\right\}\right| \leqslant 5 \omega,  \tag{13.16}\\
& \left|\left\{k \in \llbracket 1, v \rrbracket: \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(j, \tilde{a}_{k}\right) \leqslant R / 2\right\}\right| \leqslant \omega+1 . \tag{13.17}
\end{align*}
$$

Proof. The first claim follows from (8.7). The second one follows from (4.7) by considering the graph $\tilde{\mathcal{G}}$, since by our assumption $\tilde{\mathcal{G}} \in \bar{\Omega}$, the $R$-neighborhood $\mathcal{B}_{R}(1, \tilde{\mathcal{G}})$ has excess at most $\omega$.

Proof of Proposition 13.6. Recall the index set $J \subset \llbracket 1, v \rrbracket$ defined previously in Sect. 12.1. To prove (13.13), we decompose $\llbracket 1, \mu \rrbracket$ according to the relations between $\left\{a_{k}\right.$, $\left.b_{k}, c_{k}\right\}$ and vertex $j$ as $\llbracket 1, \mu \rrbracket=J_{1} \cup J_{2}$, where

$$
\begin{aligned}
& J_{1}=\left\{k \in J: j \nsucc b_{k}, \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(j, a_{k}\right) \geqslant 2 r, \text { and } \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(j, \tilde{a}_{k}\right) \geqslant R / 2\right\}, \\
& J_{2}=\llbracket 1, \mu \rrbracket \backslash J_{1} .
\end{aligned}
$$

By the defining relation (11.5) of $F(\mathcal{G})$ and Proposition 12.1, we have $|J| \geqslant v-$ $\omega^{\prime}-6 \omega \geqslant \mu-\omega^{\prime}-9 \omega$. Combining with (13.16), (13.17) and (9.5), which states that $\left|\left\{k \in \llbracket 1, v \rrbracket: j \sim b_{k}\right\}\right|<\omega^{\prime}$, we get

$$
\left|J_{1}\right| \geqslant \mu-2 \omega^{\prime}-15 \omega, \quad\left|J_{2}\right| \leqslant 2 \omega^{\prime}+15 \omega
$$

Bounding by the total number of terms, we also have $\left|J_{1}\right| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$. Now, for $k \in J_{1}$, we have $\tilde{a}_{k}=c_{k}$ and the conditions for (12.4) are satisfied. Moreover, for $k \in J_{1}$, we have $\operatorname{dist}_{\tilde{\mathcal{G}}_{(\mathbb{T})}}\left(\tilde{a}_{k}, j\right) \geqslant R / 2$, and therefore by (13.4) the vertices $\tilde{a}_{k}$ and $j$ are in different connected components of $\tilde{\mathcal{G}}_{0}^{(\mathbb{T})} ;$ it follows that $\left|\tilde{P}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right|=0$. Therefore, by (12.4),

$$
\begin{align*}
\sum_{k \in J_{1}}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| & =\sum_{k \in J_{1}}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \\
& \leqslant 2(d-1)^{\ell+1}\left(2^{12} K^{5}\left|m_{s c}\right| q^{2 r+1}\right) \leqslant 2^{13} K^{5}\left|m_{s c}\right| q^{r} \tag{13.18}
\end{align*}
$$

For $k \in J_{2}$, by (11.4) and (13.5),

$$
\begin{equation*}
\sum_{k \in J_{2}}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \leqslant\left(2 \omega^{\prime}+16 \omega\right)\left(2^{7} K^{3}+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r} \tag{13.19}
\end{equation*}
$$

Then (13.13) follows by combining (13.18) and (13.19).
For (13.14), again, we split the sum over $J_{1}$ and over $J_{2}$ as above. For $k \in J_{1}$, similarly to (13.13), we have

$$
\begin{equation*}
\sum_{k \in J_{1}}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \leqslant 2(d-1)^{\ell+1} 2^{12} K^{5}\left|m_{s c}\right| q^{2 r+1} \leqslant 2^{13} K^{5}\left|m_{s c}\right| q^{r} \tag{13.20}
\end{equation*}
$$

For $k \in J_{2}$, we note that $\operatorname{dist}_{\tilde{\mathcal{G}}}\left(\tilde{a}_{k}, j\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}}(1, j)-\operatorname{dist}_{\tilde{\mathcal{G}}}\left(1, \tilde{a}_{k}\right) \geqslant 2 r-\ell>r$, so that $P_{\tilde{a}_{k} j}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, j, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)=0$. Therefore, by (11.4), we have

$$
\begin{equation*}
\sum_{k \in J_{2}}\left|\tilde{G}_{\tilde{a}_{k} j}^{(\mathbb{T})}\right| \leqslant\left(2 \omega^{\prime}+15 \omega\right) 2^{7} K^{3}\left|m_{s c}\right| q^{r} \tag{13.21}
\end{equation*}
$$

Again (13.14) follows by combining (13.20) and (13.21).
For (13.15), we split the sum over

$$
\begin{aligned}
\{k \neq m \in \llbracket 1, \mu \rrbracket\}= & \{k \neq m \in \llbracket 1, \mu \rrbracket \backslash J\} \cup\{k \in \llbracket 1, \mu \rrbracket \backslash J, m \in J\} \\
& \cup\{k \in J, m \in \llbracket 1, \mu \rrbracket \backslash J\} \cup\{k \neq m \in J\} .
\end{aligned}
$$

Since $|\llbracket 1, \mu \rrbracket \backslash J| \leqslant \omega^{\prime}+9 \omega$, for $k \neq m \in \llbracket 1, \mu \rrbracket \backslash J$, by Proposition 11.1 and (13.5),

$$
\sum_{k \neq m \in \llbracket 1, \mu \rrbracket \backslash J}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right| \leqslant\left(\omega^{\prime}+9 \omega\right)^{2}\left(2^{7} K^{3}+2^{2 \omega+3} q\right)\left|m_{s c}\right| q^{r}
$$

For $k \in \llbracket 1, \mu \rrbracket \backslash J, m \in J$, by (13.3) $\tilde{a}_{k}$ and $\tilde{a}_{m}$ are in different connected components of $\tilde{\mathcal{G}}_{0}^{(\mathbb{T})}$, and thus $\left|\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{m}\right.}\right|=0$. By (12.2),

$$
\begin{aligned}
\sum_{k \in \llbracket 1, \mu \rrbracket \backslash J, m \in J}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})}\right| & =\sum_{k \in \llbracket 1, \mu \rrbracket \backslash J, m \in J}\left|\tilde{G}_{i j}^{(\mathbb{T})}\right| \\
& \leqslant\left(\omega^{\prime}+9 \omega\right) 2(d-1)^{\ell+1}\left(2^{9} K^{4}\left|m_{s c}\right| q^{2 r+1}\right) \\
& \leqslant\left(\omega^{\prime}+9 \omega\right) 2^{10} K^{4}\left|m_{s c}\right| q^{r}
\end{aligned}
$$

The same estimate holds for $k \in J, m \in \llbracket 1, \mu \rrbracket \backslash J$. For $k \neq m \in J$, the same reasoning as above gives $\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}=0$. By (12.3) and noticing that $|J| \leqslant \mu \leqslant 2(d-1)^{\ell+1}$, we have

$$
\begin{aligned}
\sum_{k \neq m \in J}\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right| & =\sum_{k \neq m \in J}\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right| \\
& \leqslant 4(d-1)^{2 \ell+2} 2^{12} K^{5}\left|m_{s c}\right| q^{3 r+2} \leqslant 2^{14} K^{5}\left|m_{s c}\right| q^{r}
\end{aligned}
$$

Now (13.15) follows by combining the above four cases.
13.4. Proof of (13.2). The proof of (13.2) follows essentially from (13.8) and the fact the difference of $\tilde{G}^{(\mathbb{T})}$ and $\tilde{P}^{(\mathbb{T})}$ is small (Proposition 11.1).

Claim 13.8. For all $x \in \mathbb{T}$,

$$
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| \leqslant(\omega+1) 2^{2 \omega+13} K^{3}\left|m_{s c}\right| q^{r}
$$

Moreover, for $x \in \mathbb{T} \backslash\{1\}$, we have the stronger estimate

$$
\begin{equation*}
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| \leqslant(\omega+1) 2^{2 \omega+14} K^{3}\left|m_{s c}\right| q^{r+1} \tag{13.22}
\end{equation*}
$$

Proof of Proposition 13.6. Let $\Gamma_{1}=\max _{x \in \mathbb{T}}\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right|$. Then the first term on the right-hand side of (13.8) is bounded by

$$
\begin{align*}
& \left|\left((\tilde{G}-\tilde{P}) \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{1 x}\right| \\
& \quad \leqslant \frac{\Gamma_{1}}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket} \sum_{m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right|\left|\tilde{P}_{l_{m} x}\right| \\
& \quad \leqslant \frac{\Gamma_{1}\left(C \omega^{\prime} q^{r+1}\right)}{\sqrt{d-1}} \sum_{m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{m} x}\right| \\
& \quad \leqslant \Gamma_{1}\left(C \omega^{\prime} q^{r+1}\right)\left((\omega+1) 2^{\omega+3}\left|m_{s c}\right|^{\ell+1}(d-1)^{(\ell+1) / 2}\right) \\
& \quad \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{\ell+1} \Gamma_{1}, \tag{13.23}
\end{align*}
$$

where we used (13.13) and (13.11). Next we bound the second term on the right-hand side of (13.8). For, say $x \in \mathbb{T}_{\ell_{1}}$, we have

$$
\begin{align*}
\left|\left(\tilde{P} \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{1 x}\right| \leqslant & \left.\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{1 l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right| \| \tilde{P}_{l_{k} x} \right\rvert\, \\
& +\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{1 l_{k}}\left\|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right\| \tilde{P}_{l_{m} x}\right| . \tag{13.24}
\end{align*}
$$

By (5.3) and (5.6), for any $k, m \in \llbracket 1, \mu \rrbracket$,

$$
\begin{equation*}
\left|\tilde{P}_{1 l_{k}}\right| \leqslant 2^{\omega+2}\left|m_{s c}\right| q^{\ell}, \quad\left|\tilde{P}_{l_{m} x}\right| \leqslant 2\left|m_{s c}\right| . \tag{13.25}
\end{equation*}
$$

We can estimate the first term in (13.24) in the following way:

$$
\begin{aligned}
& \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{1 l_{k}}\left\|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right\| \tilde{P}_{l_{k} x}\right| \\
& \quad \leqslant 2^{\omega+2} q^{\ell+1}\left(2^{7} K^{3}+2^{2 \omega+3} q\right) q^{r+1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{l_{k} x}\right| \\
& \leqslant(\omega+1) 2^{2 \omega+5}\left(\ell_{1}+1\right)\left(2^{7} K^{3}+2^{2 \omega+3} q\right) q^{r+\ell_{1}},
\end{aligned}
$$

where in the first inequality we used (13.25), (11.4) and (13.5), in the second inequality we used estimate (13.9). For the second term in (13.24), we have

$$
\begin{aligned}
& \frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{1 l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})} \| \tilde{P}_{l_{m} x}\right| \\
& \leqslant 2^{\omega+2} q^{\ell+1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right|(2 q) \leqslant C \omega^{\prime 2} q^{r+\ell+2},
\end{aligned}
$$

where we used (13.15) and (13.25). It follows that

$$
\begin{align*}
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| \leqslant & C \omega^{\prime}\left|m_{s c}\right| q^{\ell+1} \Gamma_{1} \\
& +(\omega+1) 2^{2 \omega+5}\left(\ell_{1}+1\right)\left(2^{7} K^{3}+2^{2 \omega+3} q\right) q^{r+\ell_{1}}+C \omega^{\prime 2} q^{r+\ell+2} \tag{13.26}
\end{align*}
$$

By taking the maximum over $x \in \mathbb{T}$ and rearranging it, we have $\Gamma_{1} \leqslant(\omega+1) 2^{2 \omega+13} K^{3} \mid$ $m_{s c} \mid q^{r}$, provided that $\omega^{\prime 2} q^{\ell} \ll 1$ and $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$.

For (13.22), it follows from (13.26), the estimate of $\Gamma_{1}$ and $\ell_{1} \geqslant 1$,

$$
\begin{align*}
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| & \leqslant C \omega^{\prime} q^{r+\ell+1}+(\omega+1) 2^{2 \omega+6}\left(2^{7} K^{3}+2^{2 \omega+3} q\right) q^{r+1}+C \omega^{\prime 2} q^{r+\ell+2} \\
& \leqslant(\omega+1) 2^{2 \omega+6}\left(2^{7} K^{3}+1\right) q^{r+1} \tag{13.27}
\end{align*}
$$

provided that $\omega^{\prime 2} q^{\ell} \ll 1$ and $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$.
Proof of (13.2). For $x \in \mathbb{T} \backslash\{1\}$, the estimate (13.2) follows from (13.27) and (13.5):

$$
\begin{aligned}
& \left|\tilde{G}_{1 x}-P_{1 x}\left(\mathcal{E}_{r}(1, x, \tilde{\mathcal{G}})\right)\right| \leqslant\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right|+\left|P_{1 x}\left(\mathcal{E}_{r}(1, x, \tilde{\mathcal{G}})\right)-\tilde{P}_{1 x}\right| \\
& \quad \leqslant(\omega+1) 2^{2 \omega+6}\left(2^{7} K^{3}+1\right) q^{r+1}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} \leqslant(\omega+1) 2^{2 \omega+14} K^{3}\left|m_{s c}\right| q^{r+1}
\end{aligned}
$$

Thus it only remains to prove (13.2) for $x \notin \mathbb{T}$.
For $x \in \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}}) \backslash \mathbb{T}$, we have by the Schur complement formula (B.4):

$$
\tilde{G}=-\tilde{G} \tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})}, \quad \tilde{P}=-\tilde{P} \tilde{B}^{\prime} \tilde{P}^{(\mathbb{T})}
$$

Therefore, by taking the difference of these two equations,

$$
\begin{align*}
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| \leqslant & \frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{1 l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}-\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \\
& +\frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| . \tag{13.28}
\end{align*}
$$

For the first term in (13.28), notice that by combining (13.25) and (13.22), we have

$$
\begin{equation*}
\left|\tilde{G}_{1 l_{k}}\right| \leqslant\left|\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right|+\left|\tilde{P}_{1 l_{k}}\right| \leqslant 2^{\omega+3}\left|m_{s c}\right| q^{\ell} . \tag{13.29}
\end{equation*}
$$

The first term in (13.28) is bounded by

$$
\frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{1 l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}-\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \leqslant C q^{\ell+1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}-\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime} q^{r+\ell+1},
$$

where we used (13.13). For the second term in (13.28), since $\tilde{\mathcal{G}} \in \bar{\Omega}$, its radius- $R$ neighborhood of vertex 1 has excess at most $\omega$. By (4.7) there are at most $\omega+1$ indices $k \in \llbracket 1, \mu \rrbracket$, such that $\tilde{a}_{k}$ is in the same connected component as $x$ in the graph $\tilde{\mathcal{G}}_{0}$. Thus, $\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}$ are zero for all $k \in \llbracket 1, \mu \rrbracket$ except for at most $\omega+1$ of them, and they are bounded $\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \leqslant 2\left|m_{s c}\right|$ by (5.6).

$$
\frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \leqslant(\omega+1)^{2} 2^{2 \omega+15} K^{3}\left|m_{s c}\right| q^{r+2},
$$

where we used (13.22). Combining the arguments above, they lead to

$$
\left|\tilde{G}_{1 x}-\tilde{P}_{1 x}\right| \leqslant 2^{5} K^{3}\left|m_{s c}\right| q^{r+1}+C \omega^{\prime} q^{r+\ell+1}
$$

given that $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$. The estimate (13.2) for $x \in \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}}) \backslash \mathbb{T}$ follows, provided $\omega^{\prime 2} q^{\ell} \ll 1$.

For $x \notin \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$, we have

$$
\begin{align*}
\left|\tilde{G}_{1 x}\right| & \leqslant \frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{1 l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \\
& \leqslant 2^{\omega+3} q^{\ell+1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime} q^{r+\ell+1} \ll q^{r+1} \tag{13.30}
\end{align*}
$$

where we used (13.29) and (13.14). This finishes the proof of (13.2).

### 13.5. Proof of (13.1).

Proof of (13.1). For $x, y \in \mathbb{T}$, we denote $\Gamma=\max _{x, y \in \mathbb{T}}\left\{\left|\tilde{G}_{x y}-\tilde{P}_{x y}\right|\right\}$. Then, by the Schur complement formula (13.8),

$$
\begin{equation*}
\left|\tilde{G}_{x y}-\tilde{P}_{x y}\right| \leqslant\left|\left((\tilde{G}-\tilde{P}) \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{x y}\right|+\left|\left(\tilde{P} \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{x y}\right| . \tag{13.31}
\end{equation*}
$$

The estimate of the first term follows the same argument as that for (13.23):

$$
\left|\left((\tilde{G}-\tilde{P}) \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{x y}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{\ell+1} \Gamma \leqslant \Gamma / 2
$$

For the second term, similarly, we have

$$
\begin{aligned}
& \left|\left(\tilde{P} \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{P}\right)_{x y}\right| \\
& \quad \leqslant \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{x l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right|\left|\tilde{P}_{l_{k} y}\right| \\
& \quad+\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{x l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right|\left|\tilde{P}_{l_{m} y}\right| \\
& \quad \leqslant \frac{C\left|m_{s c}\right| q^{r}}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{x l_{k}}\right|\left|\tilde{P}_{l_{k} y}\right|+(C q)^{2} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right| \\
& \quad \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r},
\end{aligned}
$$

where we bounded $\left|\tilde{P}_{x l_{k}}\right|,\left|\tilde{P}_{l_{m} y}\right| \leqslant C\left|m_{s c}\right|$ and used the estimates (11.4), (13.12) and (13.15). Therefore, by taking supremum of both sides of (13.31) and rearranging, we have $\Gamma \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r}$.

For $x \in \mathbb{T}$ and $y \in \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}}) \backslash \mathbb{T}$, the same argument as for (13.28) implies:

$$
\begin{aligned}
& \left|\tilde{G}_{x y}-\tilde{P}_{x y}\right| \\
& \quad \leqslant \frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}-\tilde{G}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right|+\frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x l_{k}}-\tilde{P}_{x l_{k}}\right|\left|\tilde{P}_{\tilde{a}_{k} x}^{(\mathbb{T})}\right| . \\
& \quad \leqslant C q \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{\tilde{a}_{k} y}^{(\mathbb{T})}-\tilde{G}_{\tilde{a}_{k} y}^{(\mathbb{T})}\right|+C \omega^{\prime 2} q^{r+1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{\tilde{a}_{k} y}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r+1} .
\end{aligned}
$$

where we bounded $\left|\tilde{G}_{x l_{k}}\right| \leqslant C\left|m_{s c}\right|$, and used the estimate (13.13), the bound for $\Gamma$ and the fact that for all $k \in \llbracket 1, \mu \rrbracket$ with at most $\omega+1$ exceptions, $\tilde{P}_{\tilde{a}_{k} y}^{(\mathbb{T})}=0$.

For $x \in \mathbb{T}$ and $y \notin \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$, similarly, we have:

$$
\left|\tilde{G}_{x y}\right| \leqslant \frac{1}{\sqrt{d-1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x l_{k}}\right|\left|\tilde{G}_{\tilde{a}_{k} y}^{(\mathbb{T})}\right| \leqslant C q \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} y}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r+1}
$$

where we bounded $\left|\tilde{G}_{x l_{k}}\right| \leqslant C\left|m_{s c}\right|$ and used the estimate (13.14).
For $x, y \in \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}}) / \mathbb{T}$, we have the Schur complement formula (B.3):

$$
\begin{aligned}
& \tilde{G}=\tilde{G}^{(\mathbb{T})}+\tilde{G}^{(\mathbb{T})} \tilde{B} \tilde{G} \tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})}, \\
& \tilde{P}=\tilde{P}^{(\mathbb{T})}+\tilde{P}^{(\mathbb{T})} \tilde{B} \tilde{P} \tilde{B}^{\prime} \tilde{P}^{(\mathbb{T})} .
\end{aligned}
$$

By taking the difference,

$$
\begin{aligned}
\tilde{G}-\tilde{P}= & \tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}+\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) \tilde{B} \tilde{G}^{\prime} \tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})} \\
& +\tilde{P}^{(\mathbb{T})} \tilde{B}(\tilde{G}-\tilde{P}) \tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})}+\tilde{P}^{(\mathbb{T})} \tilde{B} \tilde{P} \tilde{B}^{\prime}\left(\tilde{G}^{(\mathbb{T})}-\tilde{P}^{(\mathbb{T})}\right) .
\end{aligned}
$$

Notice that $\left|\tilde{G}_{x y}^{(\mathbb{T})}-\tilde{P}_{x y}^{(\mathbb{T})}\right| \leqslant C\left|m_{s c}\right| q^{r},\left|\tilde{G}_{l_{k} l_{m}}\right| \leqslant C\left|m_{s c}\right|,\left|\tilde{P}_{l_{k} l_{m}}\right| \leqslant C\left|m_{s c}\right|$ and $\mid \tilde{G}_{l_{k} l_{m}}-$ $\tilde{P}_{l_{k} l_{m}}\left|\leqslant C \omega^{\prime 2}\right| m_{s c} \mid q^{r}$, we have

$$
\begin{align*}
& \left|\tilde{G}_{x y}-\tilde{P}_{x y}\right| \leqslant C\left|m_{s c}\right| q^{r}+\sum_{k, m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{x \tilde{a}_{k}}^{(\mathbb{T})}\right| \frac{C\left|m_{s c}\right|}{d-1}\left|\tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})}\right| \\
& \quad+\sum_{k, m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{x \tilde{a}_{k}}^{(\mathbb{T})}\right| \frac{C \omega^{\prime 2}\left|m_{s c}\right| q^{r}}{d-1}\left|\tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})}\right|+\sum_{k, m \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{x \tilde{a}_{k}}^{(\mathbb{T})}\right| \frac{C\left|m_{s c}\right|}{d-1}\left|\tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{m} y}^{(\mathbb{T})}\right| . \tag{13.32}
\end{align*}
$$

The following estimates follow from Proposition 13.6:

$$
\begin{aligned}
& \sum_{k \in \llbracket 1, \mu \rrbracket}\left|P_{x \tilde{a}_{k}}^{(\mathbb{T})}\right|, \sum_{m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})}\right| \leqslant C\left|m_{s c}\right|, \\
& \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x \tilde{a}_{k}}^{(\mathbb{T})}-P_{x \tilde{a}_{k}}^{(\mathbb{T})}\right|, \sum_{m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{m y} y}^{(\mathbb{T})}-P_{\tilde{a}_{m y} y}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r} .
\end{aligned}
$$

Therefore (13.32) simplifies to

$$
\left|\tilde{G}_{x y}-\tilde{P}_{x y}\right| \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r} .
$$

Finally, for $x \notin \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$ or $y \notin \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$, by symmetry we assume $x \notin \mathbb{B}_{2 r}(1, \tilde{\mathcal{G}})$, we have

$$
\begin{aligned}
\left|\left(\tilde{G}^{(\mathbb{T})} \tilde{B} \tilde{G} \tilde{B}^{\prime} \tilde{G}^{(\mathbb{T})}\right)_{x y}\right| & \left.\leqslant \frac{1}{d-1} \sum_{k, m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x \tilde{a}_{k}}^{(\mathbb{T})}\right|\left|\tilde{G}_{l_{k} l_{m}}\right| \tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})} \right\rvert\, \\
& \leqslant \sum_{k, m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{x \tilde{a}_{k}}^{(\mathbb{T})}\right| \frac{C\left|m_{s c}\right|}{d-1}\left|\tilde{G}_{\tilde{a}_{m} y}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r+2}
\end{aligned}
$$

where we used (13.14), thus,

$$
\left|\tilde{G}_{x y}-\tilde{G}_{x y}^{(\mathbb{T})}\right| \leqslant C \omega^{\prime}\left|m_{s c}\right| q^{r+2}
$$

Altogether we proved that

$$
\left|\tilde{G}_{i j}-\tilde{P}_{i j}\left(\mathcal{E}_{r}(i, j, \tilde{\mathcal{G}})\right)\right| \leqslant C\left|m_{s c}\right| \omega^{\prime 2} q^{r} \ll q^{\ell+1}
$$

provided that $\omega^{\prime 2} q^{\ell} \ll 1$. The weak stability estimates (14.10) follows by combining with (5.6). This finishes the proof of (13.1).

## 14. Concentration in the Switched Graph

The result of this section is the following proposition, which shows that the average of the Green's function of $\tilde{\mathcal{G}}^{(\mathbb{T})}$ over the vertex boundary of $\mathbb{T}$ concentrates under resampling of the edge boundary of $\mathbb{T}$. This part is where the condition that the edge boundary contains $\gg \log N$ edges is important.

More precisely, recall the vertex boundary $\mathbb{I}=\left\{\tilde{a}_{1}, \tilde{a}_{2}, \ldots, \tilde{a}_{\mu}\right\}$ of $\mathcal{T}$ in $\tilde{\mathcal{G}}$ from (12.1). For any finite graph $\mathcal{H}$ (not necessarily regular and not necessary on $N$ vertices), we define

$$
\begin{equation*}
Q(\mathcal{H}, z)=\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}} G_{j j}^{(i)}(\mathcal{H}, z) \tag{14.1}
\end{equation*}
$$

where $\boldsymbol{E}$ denotes the set of oriented edges of $\mathcal{H}$, and $G^{(i)}(\mathcal{H}, z)$ the Green's function of the graph obtained from $\mathcal{H}$ by removing the vertex $i$. Notice that we always normalize (14.1) by $N d$, irregardless of the actual number of oriented edges in $\mathcal{H}$ (which can be smaller than $N d$ ).

Proposition 14.1. Sets $\Omega_{1}^{+}(z, \ell)$ and $\bar{\Omega}$ are as defined in Sect. 3.2. Let $z \in \mathbb{C}_{+}$and $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$. Then there exists an event $F^{\prime}(\mathcal{G}) \subset F(\mathcal{G})($ as in Sect. 11.1) with probability $\mathbb{P}_{\mathcal{G}}\left(F^{\prime}(\mathcal{G})\right)=1-o\left(N^{-\omega+\delta}\right)$ such that for any $\mathbf{S} \in F^{\prime}(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$,

$$
\begin{align*}
& \left|\frac{1}{\mu} \sum_{k=1}^{\mu}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-P_{\tilde{a}_{k} \tilde{a}_{k}}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, \tilde{a}_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right)-\left(Q(\tilde{\mathcal{G}})-m_{s c}\right)\right| \\
& \quad \leqslant \frac{2(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{\sqrt{\mu}}, \tag{14.2}
\end{align*}
$$

provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \omega^{\prime 2} q^{\ell} \ll 1$ and $\sqrt{N \eta} q^{3 r+2} \geqslant$ M.

To prove Proposition 14.1, in Lemma 14.3, we first show a similar statement for the unswitched graph $\mathcal{G}^{(\mathbb{T})}$ in which the problem becomes a concentration problem of independent random variables. Then we prove Proposition 14.1 by comparision, using the estimates of Proposition 11.1, and the fact that the change from $Q(\tilde{\mathcal{G}}, z)$ to $Q\left(\mathcal{G}^{(\mathbb{T})}, z\right)$ is small (Lemma 14.4). Proposition 11.1 is applicable since, by the definition of set $\Omega_{1}^{+}(z, \ell)$ in Sect. 3, any graph $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ satisfies the assumptions in Proposition 11.1 with $K=2^{10}$.

The following proposition is used repeatedly in this section. It follows from exactly the same argument as Proposition 10.2, and we therefore omit the proof.

Lemma 14.2. Given $z \in \mathbb{C}_{+}$, a constant $K^{\prime} \geqslant 2$, and $\mathcal{G} \in \bar{\Omega}$. Let $\mathcal{H}$ be one of the graphs $\mathcal{G}^{(\mathbb{T})}, \hat{\mathcal{G}}^{(\mathbb{T})}, \tilde{\mathcal{G}}^{(\mathbb{T})}$ or $\tilde{\mathcal{G}}$, and suppose that

$$
\begin{equation*}
\left|G_{i j}(\mathcal{H}, z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{H}), z\right)\right| \leqslant K^{\prime}\left|m_{s c}\right| q^{r} . \tag{14.3}
\end{equation*}
$$

Then, for any vertices $i, j$ in $\mathcal{H}^{(x)}$, we have

$$
\begin{equation*}
\left|G_{i j}\left(\mathcal{H}^{(x)}, z\right)-P_{i j}\left(\mathcal{E}_{r}\left(i, j, \mathcal{H}^{(x)}\right), z\right)\right| \leqslant 2 K^{\prime}\left|m_{s c}\right| q^{r} \tag{14.4}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant(\omega+1)^{2} 2^{2 \omega+10}$. Here all graphs have deficit function $g=$ $d$ - deg, and we recall that $\mathcal{H}^{(x)}$ is the graph obtained from $\mathcal{H}$ by removing the vertex $x$.
14.1. Estimate for the unswitched graph. The next lemma shows concentration of a certain average of the Green's function in the unswitched graph.

Lemma 14.3. For any $z \in \mathbb{C}_{+}$and $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, we define the set $F^{\prime}(\mathcal{G}) \subset F(\mathcal{G})($ as in Sect. 11.1) such that

$$
\begin{align*}
& \left|\frac{1}{\mu} \sum_{k=1}^{\mu}\left(G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \mathcal{G}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right)-\left(Q\left(\mathcal{G}^{(\mathbb{T})}\right)-m_{s c}\right)\right| \\
& \quad \leqslant \frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{\sqrt{\mu}} . \tag{14.5}
\end{align*}
$$

Then $\mathbb{P}_{\mathcal{G}}\left(F^{\prime}(\mathcal{G})\right)=1-o\left(N^{-\omega+\delta}\right)$.
Proof of (13.1). Let

$$
X_{k}=G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \mathcal{G}^{\left(\mathbb{T} b_{k}\right)}\right)\right), \quad k \in \llbracket 1, \mu \rrbracket .
$$

Conditioned on the graph $\mathcal{G}^{(\mathbb{T})}$, the random sets $\boldsymbol{S}_{1}, \boldsymbol{S}_{2}, \ldots, \boldsymbol{S}_{\mu}$ are independent and identically distributed, and thus $X_{1}, X_{2}, \ldots, X_{\mu}$ are i.i.d random variables. By Lemma 14.2 and the assumption that $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, for any $k \in \llbracket 1, \mu \rrbracket$, we have

$$
\left|X_{k}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}
$$

where $K=2^{10}$. By Azuma's inequality for independent random variables, it therefore follows that

$$
\begin{equation*}
\mathbb{P}_{\mathcal{G}}\left(\left|\frac{1}{\mu} \sum_{k=1}^{\mu} X_{k}-\mathbb{E}\left[X_{k}\right]\right| \geqslant \frac{2 K t\left|m_{s c}\right| q^{r}}{\sqrt{\mu}}\right) \leqslant e^{-t^{2} / 2} \tag{14.6}
\end{equation*}
$$

In the following, we still need to estimate $\mathbb{E}\left[X_{k}\right]$. Let $\boldsymbol{E}$ be the set of oriented edges of $\mathcal{G}^{(\mathbb{T})}$. By definition, $\mathbb{T}$ is the $\ell$ neighborhood of the vertex 1 , and by the trivial bound it intersects at most $d+d(d-1)+\cdots+d(d-1)^{\ell} \leqslant 2(d-1)^{\ell+1}$ edges. Thus $N d-4(d-1)^{\ell+1} \leqslant|\boldsymbol{E}| \leqslant N d$. Using that, by Lemma 14.2, we also have $\left|G_{i i}^{(\mathbb{T} j)}-P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right)\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$, it follows that

$$
\begin{align*}
\mathbb{E}\left[X_{k}\right] & =\frac{1}{|\boldsymbol{E}|} \sum_{(i, j) \in \boldsymbol{E}} G_{i i}^{(\mathbb{T} j)}-P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right) \\
& =\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}} G_{i i}^{(\mathbb{T} j)}-P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right)+O \leqslant\left(\frac{8 K\left|m_{s c}\right| q^{r}(d-1)^{\ell+1}}{N d}\right) \\
& =Q\left(\mathcal{G}^{(\mathbb{T})}\right)-\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}} P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right)+O \leqslant\left(\frac{8 K}{N}\right) . \tag{14.7}
\end{align*}
$$

Moreover, since by assumption $\mathcal{G} \in \bar{\Omega}$, all except for at most $N^{\delta}$ vertices have radius- $R$ tree neighborhoods in $\mathcal{G}$, and therefore

$$
\begin{aligned}
& \mid\left\{i \in \llbracket 1, N \rrbracket \backslash \mathbb{T}: \mathcal{B}_{r}\left(i, \mathcal{G}^{(\mathbb{T})}\right) \text { is not a } d \text {-regular tree }\right\} \mid \\
& \quad \leqslant \mid\left\{i \in \llbracket 1, N \rrbracket: \mathcal{B}_{r}(i, \mathcal{G}) \text { is not a tree }\right\}\left|+\left|\left\{i \in \llbracket 1, N \rrbracket: \operatorname{dist}_{\mathcal{G}}(i, \mathbb{T}) \leqslant r\right\}\right|\right. \\
& \quad \leqslant N^{\delta}+2(d-1)^{r+\ell} \leqslant 2 N^{\delta} .
\end{aligned}
$$

For the vertices $i$ contained in the set on the left-hand side, we have the bound $\mid P_{i i}\left(\mathcal{E}_{r}(i, i\right.$, $\left.\left.\mathcal{G}^{(\mathbb{T} j)}\right)\right)|\leqslant 2| m_{s c} \mid$ from (5.4). For the other vertices $i$, whose $r$-neighborhood in $\mathcal{G}^{(\mathbb{T})}$ is a $d$-regular tree, we have the equality $P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right)=m_{s c}$. Therefore

$$
\begin{equation*}
\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}} P_{i i}\left(\mathcal{E}_{r}\left(i, i, \mathcal{G}^{(\mathbb{T} j)}\right)\right)=m_{s c}+O_{\leqslant}\left(8 N^{-1+\delta}\right) \tag{14.8}
\end{equation*}
$$

Combining (14.7), (14.8), and taking $t=(\log N)^{1 / 2+\delta} /(4 K)$ in (14.6), we get

$$
\begin{aligned}
& \mathbb{P}_{\mathcal{G}}\left(\left|\frac{1}{\mu} \sum_{i=1}^{\mu} X_{i}-\left(Q\left(\mathcal{G}^{(\mathbb{T})}\right)-m_{s c}\right)\right| \geqslant \frac{2 K t\left|m_{s c}\right| q^{r}}{\sqrt{\mu}}+\frac{10}{N^{1-\delta}}\right) \\
& \quad \leqslant e^{-(\log N)^{1+2 \delta} /\left(32 K^{2}\right)} .
\end{aligned}
$$

Since $N^{-1+\delta} \ll(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r} / \sqrt{\mu}$, it follows that (14.5) holds with overwhelming probability, and we can define $F^{\prime}(\mathcal{G}) \subset F(\mathcal{G})$ as claimed with probability

$$
\mathbb{P}_{\mathcal{G}}\left(F^{\prime}(\mathcal{G})\right) \geqslant \mathbb{P}_{\mathcal{G}}(F(\mathcal{G}))-e^{-(\log N)^{1+2 \delta} /\left(32 K^{2}\right)}=1-o\left(N^{-\omega+\delta}\right),
$$

where we used (11.6). This completes the proof.
14.2. Changing $Q\left(\mathcal{G}^{(\mathbb{T})}\right)$ to $Q(\tilde{\mathcal{G}})$. The next lemma shows that we can replace $Q\left(\mathcal{G}^{(\mathbb{T})}\right)$ by $Q(\mathcal{G})$ up to a small error. It follows from the general insensitivity of the quantity $Q$ to small changes of the graph.

Lemma 14.4. For $z \in \mathbb{C}_{+}, \mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ and $\mathbf{S} \in F(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$, we have

$$
\begin{equation*}
\left|Q\left(\mathcal{G}^{(\mathbb{T})}, z\right)-Q(\tilde{\mathcal{G}}, z)\right| \leqslant \frac{36 d^{2 \ell+2}}{N \eta} \tag{14.9}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \omega^{\prime 2} q^{\ell} \ll 1$ and $\sqrt{N \eta} q^{3 r+2} \geqslant$ M.

The proof of Lemma 14.4 uses Lemma 14.5 below, which is a direct consequence of the Ward identity (B.6).

Lemma 14.5. Given a graph $\mathcal{G}$ with degree bounded by $d$. We denote by $\boldsymbol{E}$ the set of oriented edges of $\mathcal{G}$, by $H$ its normalized adjacency matrix, and by $G=(H-z)^{-1}$ its Green's function. Then, if for some $z \in \mathbb{C}_{+}$and any $(i, j) \in \boldsymbol{E}$, it holds that

$$
\begin{equation*}
\left|G_{i j}(z)\right| \leqslant\left|G_{j j}(z)\right| \leqslant 2, \tag{14.10}
\end{equation*}
$$

then for any vertex $x \in \mathcal{G}$,

$$
\begin{equation*}
\sum_{(i, j) \in \boldsymbol{E}}\left|G_{i x}^{(j)}(z)\right|^{2} \leqslant \frac{8 d}{\eta} \tag{14.11}
\end{equation*}
$$

Proof. By the Schur complement formula (B.5) and the Ward identity (B.6), we obtain

$$
\begin{aligned}
\sum_{(i, j) \in \boldsymbol{E}}\left|G_{i x}^{(j)}\right|^{2} & =\sum_{(i, j) \in \boldsymbol{E}}\left|G_{i x}-\frac{G_{i j} G_{j x}}{G_{j j}}\right|^{2} \leqslant \sum_{(i, j) \in \boldsymbol{E}} 2\left|G_{i x}\right|^{2}+2\left|\frac{G_{i j} G_{j x}}{G_{j j}}\right|^{2} \\
& \leqslant 4 \sum_{(i, j) \in \boldsymbol{E}}\left|G_{i x}\right|^{2} \leqslant 4 \sum_{i} \operatorname{deg}_{\mathcal{G}}(i)\left|G_{i x}\right|^{2} \leqslant \frac{4 d \operatorname{Im}\left[G_{x x}\right]}{\eta} \leqslant \frac{8 d}{\eta}
\end{aligned}
$$

as claimed.
We will prove Lemma 14.4 in two steps, by proving

$$
\begin{equation*}
\left|Q\left(\mathcal{G}^{(\mathbb{T})}\right)-Q\left(\hat{\mathcal{G}}^{(\mathbb{T})}\right)\right| \leqslant \frac{d \mu}{2 N \eta}, \quad\left|Q\left(\hat{\mathcal{G}}^{(\mathbb{T})}\right)-Q\left(\tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right| \leqslant \frac{d \mu}{2 N \eta} \tag{14.12}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|Q\left(\tilde{\mathcal{G}}^{(\mathbb{T})}\right)-Q(\tilde{\mathcal{G}})\right| \leqslant \frac{34 d^{2 \ell+2}}{N \eta} \tag{14.13}
\end{equation*}
$$

Then (14.9) follows by combining (14.12) and (14.13), and using that $\mu \leqslant 2(d-1)^{\ell+1}$. In preparation, we recall from Proposition 13.1 that, for all vertices $i, j \in \llbracket N \rrbracket$,

$$
\begin{equation*}
\left|\tilde{G}_{i j}(z)\right| \leqslant\left|\tilde{G}_{j j}(z)\right| \leqslant 2 \tag{14.14}
\end{equation*}
$$

Proof of (14.12). The proofs of both estimates in (14.12) are analogous, and we only prove the first one. Denote by $\boldsymbol{E}$ the set of oriented edges of $\hat{\mathcal{G}}^{(\mathbb{T})}$, and by $\Delta=$ $\sum_{k=1}^{v}\left(e_{b_{k} c_{k}}+e_{c_{k} b_{k}}\right) / \sqrt{d-1}$ the difference of the normalized adjacency matrices of the graphs $\hat{\mathcal{G}}^{(\mathbb{T})}$ and $\mathcal{G}^{(\mathbb{T})}$. Then by the resolvent formula (B.1),

$$
\begin{aligned}
\sum_{(i, j) \in \boldsymbol{E}}\left|\hat{G}_{i i}^{(\mathbb{T} j)}-G_{i i}^{(\mathbb{T} j)}\right| & \leqslant \sum_{x, y} \sum_{(i, j) \in \boldsymbol{E}}\left|\hat{G}_{i x}^{(\mathbb{T} j)} \Delta_{x y} G_{y i}^{(\mathbb{T} j)}\right| \\
& \leqslant \sum_{x, y} \Delta_{x y}\left(\sum_{(i, j) \in \boldsymbol{E}}\left|\hat{G}_{i x}^{(\mathbb{T} j)}\right|^{2} \sum_{(i, j) \in \boldsymbol{E}}\left|G_{y i}^{(\mathbb{T} j)}\right|^{2}\right)^{1 / 2} \leqslant \frac{16 d \mu}{\eta \sqrt{d-1}},
\end{aligned}
$$

where we used (14.11) [and that both graphs $\mathcal{G}^{(\mathbb{T})}$ and $\hat{\mathcal{G}}^{(\mathbb{T})}$ satisfy condition (14.10) by the definition of $\Omega_{1}^{+}(z, \ell)$ and (11.2)]. Therefore,

$$
\begin{align*}
\left|Q\left(\mathcal{G}^{(\mathbb{T})}\right)-Q\left(\hat{\mathcal{G}}^{(\mathbb{T})}\right)\right| & \leqslant \frac{1}{N d} \sum_{k \in \llbracket 1, \nu \rrbracket}\left|G_{b_{k} b_{k}}^{\left(\mathbb{T} c_{k}\right)}+G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right|+\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}}\left|\hat{G}_{i i}^{(\mathbb{T} j)}-G_{i i}^{(\mathbb{T} j)}\right| \\
& \leqslant \frac{4 v\left|m_{s c}\right|}{N d}+\frac{16 d \mu}{N \eta \sqrt{d-1}} \leqslant \frac{d \mu}{2 N \eta}, \tag{14.15}
\end{align*}
$$

where in the estimate of the first term, we used $\left|G_{b_{k} b_{k}}^{\left(\mathbb{T} c_{k}\right)}\right|,\left|G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant 2\left|m_{s c}\right|$ which follows from combining (3.7), Lemma 14.2, and (5.4).

Proof of (14.13). The normalized adjacency matrices of $\tilde{\mathcal{G}}$ takes the block form

$$
\left[\begin{array}{cc}
H & \tilde{B}^{\prime} \\
\tilde{B} & D
\end{array}\right],
$$

where $H$ is the normalized adjacency matrix for $\mathcal{T}$, and $\tilde{B}$ corresponds to the edges from $\mathbb{I}$ to $\mathbb{T}_{\ell}$, where $\mathbb{I}$ is the set of boundary vertices of $\mathcal{T}$ in the switched graph $\tilde{\mathcal{G}}$ as defined in (12.1). We denote by $\boldsymbol{E}$ the set of oriented edges of $\tilde{\mathcal{G}}^{(\mathbb{T})}$. By the Schur complement formula (B.3), we have

$$
\sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{i i}^{(\mathbb{T} j)}-\tilde{G}_{i i}^{(j)}\right| \leqslant \frac{1}{d-1} \sum_{k, m \in \llbracket 1, \mu \rrbracket} \sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{i \tilde{a}_{k}}^{(\mathbb{T} j)} \tilde{G}_{l_{k} l_{m}}^{(j)} \tilde{G}_{\tilde{a}_{m} i}^{(\mathbb{T} j)}\right| .
$$

It follows from (14.14) and (B.5) that $\left|\tilde{G}_{l_{k} l_{m}}^{(j)}\right| \leqslant 4$. Therefore the above expression is bounded by

$$
\begin{aligned}
\sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{i i}^{(\mathbb{T} j)}-\tilde{G}_{i i}^{(j)}\right| & \leqslant \frac{4}{d-1} \sum_{k, m \in \llbracket 1, \mu \rrbracket} \sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{i \tilde{a}_{k}}^{(\mathbb{T} j)} \tilde{G}_{\tilde{a}_{m} i}^{(\mathbb{T} j)}\right| \\
& \leqslant \frac{4}{d-1} \sum_{k, m \in \llbracket 1, \mu \rrbracket}\left(\sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{i \tilde{a}_{k}}^{(\mathbb{T} j)}\right|^{2} \sum_{(i, j) \in \boldsymbol{E}}\left|\tilde{G}_{\tilde{a}_{m} i}^{(\mathbb{T} j)}\right|^{2}\right)^{1 / 2} \\
& \leqslant \frac{32 d \mu^{2}}{\eta(d-1)} \leqslant \frac{32 d^{2 \ell+2}}{\eta}
\end{aligned}
$$

where we used (14.11) (since $\tilde{\mathcal{G}}^{(\mathbb{T})}$ satisfies condition (14.10) thanks to the definition of $\Omega_{1}^{+}(z, \ell)$ and (11.4)). Therefore, we have

$$
\begin{align*}
\left|Q\left(\tilde{\mathcal{G}}^{(\mathbb{T})}\right)-Q(\tilde{\mathcal{G}})\right| & \leqslant \frac{1}{N d} \sum_{\{i, j\} \text { incident to } \mathbb{T}}\left|\tilde{G}_{i i}^{(j)}+\tilde{G}_{j j}^{(i)}\right|+\frac{1}{N d} \sum_{(i, j) \in E}\left|\tilde{G}_{i i}^{(\mathbb{T} j)}-G_{i i}^{(j)}\right| \\
& \leqslant \frac{16(d-1)^{\ell+1}}{N d}+\frac{32 d^{2 \ell+2}}{N \eta} \leqslant \frac{34 d^{2 \ell+2}}{N \eta} \tag{14.16}
\end{align*}
$$

where for the first term we used $\left|\tilde{G}_{i i}^{(j)}\right|,\left|\tilde{G}_{j j}^{(i)}\right| \leqslant 4$ from (14.14) and (B.5).
14.3. Adding of switched vertices. Recall the index set $J \subset \llbracket 1, v \rrbracket$ from Proposition 12.1. In this subsection, we show that the following lemma.

Lemma 14.6. For $z \in \mathbb{C}_{+}, \mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ and $\mathbf{S} \in F(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$, for any $k \in J$, we have

$$
\begin{equation*}
\left|\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant 16 q^{2 r} \tag{14.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\tilde{G}_{c_{k} c_{k}}^{(\mathbb{T})}-\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant 2^{10} K^{4}\left|m_{s c}\right| q^{2 r}, \tag{14.18}
\end{equation*}
$$

where $K=2^{10}$. For both estimates, we assume $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+\right.$ 1) $K\}$, $\omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} q^{2 r} \geqslant M$.

To prove Lemma 14.6 we need the estimates summarized in the following lemma.
Lemma 14.7. Let $z \in \mathbb{C}_{+}, \mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, and $\mathbf{S} \in F(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$. Then for any index $k \in J$, the vertex $c_{k}$ is far away from $\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$ :

$$
\begin{equation*}
\operatorname{dist}_{\hat{\mathcal{G}}^{(\mathbb{T})}}\left(c_{k},\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}\right) \geqslant \operatorname{dist}_{\tilde{\mathcal{G}}^{(\mathbb{T})}}\left(c_{k},\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}\right)>2 r \tag{14.19}
\end{equation*}
$$

Moreover, for any $x \in\left\{a_{1}, \ldots, a_{\mu}, b_{1}, \ldots, b_{\nu}\right\}$,

$$
\begin{equation*}
\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}, \quad\left|\tilde{G}_{c_{k} x}^{(\mathbb{T})}\right| \leqslant 2^{7} K^{3}\left|m_{s c}\right| q^{r}, \quad\left|\hat{G}_{b_{k} b_{k}}^{(\mathbb{T})}\right| \geqslant\left|m_{s c}\right| / 2 \tag{14.20}
\end{equation*}
$$

where $K=2^{10}$ and we assume that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}$, $\omega^{\prime} q^{r} \ll 1$ and $\sqrt{N \eta} \geqslant M(d-1)^{\ell+1}$.

Proof. (14.19) is (12.10). The first two estimates in (14.20) follow from (14.19) and $K=2^{10}$ in Proposition 11.1. The last estimate in (14.20) follows by taking $K=2^{10}$ in Proposition 11.1 and (5.4).

Proof of Lemma 14.6. Notice that for $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, the assumptions in Proposition 11.1 hold for $K=2^{10}$. By the resolvent identity (B.1),

$$
\left|\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant \sum_{x, y}\left|\hat{G}_{c_{k} x}^{\left(\mathbb{T} b_{k}\right)}\right|\left|\Delta_{x y}\right|\left|\hat{G}_{y c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right|
$$

where $\Delta=\sum_{m \in \llbracket 1, \nu \rrbracket \backslash\{k\}}\left(e_{c_{m} b_{m}}+e_{b_{m} c_{m}}\right) / \sqrt{d-1}$. By our choice of the index set $J$, $\left\{b_{k}, c_{k}\right\}$ and $\left\{b_{m}, c_{m}: m \in \llbracket 1, v \rrbracket \backslash\{k\}\right\}$ are in different S-cells. Thus $\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right|,\left|\hat{G}_{b_{k} x}^{(\mathbb{T})}\right| \leqslant$ $2 M / \sqrt{N \eta}$ by (11.3). Therefore, using (B.5), and notice $\left|\hat{G}_{b_{k} b_{k}}^{(\mathbb{T})}\right| \geqslant\left|\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})}\right|$, we get

$$
\left|\hat{G}_{c_{k} x}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right|+\left|\frac{\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})} \hat{G}_{b_{k} x}^{(\mathbb{T})}}{\hat{G}_{b_{k} b_{k}}^{(\mathbb{T})}}\right| \leqslant\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right|+\left|\hat{G}_{b_{k} x}^{(\mathbb{T})}\right| \leqslant \frac{4 M}{\sqrt{N \eta}}
$$

The same estimate holds for $\left|\hat{G}_{y c_{k}}^{(\mathbb{T})}\right|$. Thus the second term is bounded by

$$
\sum_{x, y}\left|\hat{G}_{c_{k} x}^{\left(\mathbb{T} b_{k}\right)}\right|\left|\Delta_{x y} \| \hat{G}_{y c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \leqslant 4(d-1)^{\ell+1 / 2}\left(\frac{2 M}{\sqrt{N \eta}}\right)^{2} \leqslant 16 q^{2 r}
$$

provided that $\sqrt{N \eta} \geqslant M q^{-3 r / 2}$. Similarly, now setting $\Delta=\sum_{m=1}^{v}\left(e_{a_{m} b_{m}}+e_{b_{m} a_{m}}\right) /$ $\sqrt{d-1}$, by the resolvent identity (B.1) and (B.5), we have

$$
\begin{align*}
\left|\tilde{G}_{c_{k} c_{k}}^{(\mathbb{T})}-\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| & \leqslant\left|\tilde{G}_{c_{k} c_{k}}^{(\mathbb{T})}-\hat{G}_{c_{k} c_{k}}^{(\mathbb{T})}\right|+\left|\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-\hat{G}_{c_{k}}^{(\mathbb{T})}\right| \\
& \leqslant \sum_{x, y}\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right|\left|\Delta_{x y}\right|\left|\tilde{G}_{y c_{k}}^{(\mathbb{T})}\right|+\left|\frac{\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})} \hat{G}_{b_{k} c_{k}}^{(\mathbb{T})}}{\hat{G}_{b_{k} b_{k}}^{(\mathbb{T})}}\right| \tag{14.21}
\end{align*}
$$

For the last term in (14.21), by (14.20), $\left|\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})}\right| \leqslant 2 K\left|m_{s c}\right| q^{r}$ and $\left|\hat{G}_{b_{k} b_{k}}^{(\mathbb{T})}\right| \geqslant\left|m_{s c}\right| / 2$, and therefore

$$
\left|\frac{\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})} \hat{G}_{b_{k} c_{k}}^{(\mathbb{T})}}{\hat{G}_{b_{k} b_{k}}^{(\mathbb{T}}}\right| \leqslant \frac{\left(2 K\left|m_{s c}\right| q^{r}\right)^{2}}{\left|m_{s c}\right| / 2}=8 K^{2}\left|m_{s c}\right| q^{2 r} .
$$

For the sum on the right-hand side of (14.21), we can split it into two,

$$
\sum_{x, y}\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\left\|\Delta_{x y}\right\| \tilde{G}_{y c_{k}}^{(\mathbb{T})}\right|=\left|\hat{G}_{c_{k} b_{k}}^{(\mathbb{T})}\left\|\Delta_{b_{k} a_{k}}\right\| \tilde{G}_{a_{k} c_{k}}^{(\mathbb{T})}\right|+\sum_{(x, y) \neq\left(b_{k}, a_{k}\right)}\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\left\|\Delta_{x y}\right\| \tilde{G}_{y c_{k}}^{(\mathbb{T})}\right|
$$

Again, we have $\left|\hat{G}_{c_{k} x}^{(\mathbb{T})}\right| \leqslant 2 M / \sqrt{N \eta}$, for $x \in\left\{b_{m}: m \in \llbracket 1, \nu \rrbracket \backslash\{k\}\right\} \cup\left\{a_{m}: m \in \llbracket 1, \nu \rrbracket\right\}$. Combining with (14.20), it follows that

$$
\begin{align*}
& \leqslant \frac{\left(2 K\left|m_{s c}\right| q^{r}\right)\left(2^{7} K^{3}\left|m_{s c}\right| q^{r}\right)}{\sqrt{d-1}}+\frac{2 M}{\sqrt{N \eta}} \frac{4(d-1)^{\ell+1}}{\sqrt{d-1}}\left(2^{7} K^{3}\left|m_{s c}\right| q^{r}\right)+8 K^{2}\left|m_{s c}\right| q^{2 r}  \tag{14.18}\\
& \leqslant 2^{10} K^{4}\left|m_{s c}\right| q^{2 r}
\end{align*}
$$

provided that $\sqrt{N \eta} q^{2 r} \geqslant M$.
14.4. Proof of Proposition 14.1. Finally, using the previous lemmas, we can proof Proposition 14.1.

Proof of Proposition 14.1. For $k \in J$, the $r$-neighborhood of $c_{k}$ is a $d$-regular tree with root degree $d-1$ in any of the graphs $\mathcal{G}^{\left(\mathbb{T} b_{k}\right)}, \hat{\mathcal{G}}^{\left(\mathbb{T} b_{k}\right)}$ and $\tilde{\mathcal{G}}^{(\mathbb{T})}$; therefore, by (5.2),

$$
\begin{aligned}
P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \mathcal{G}^{\left(\mathbb{T} b_{k}\right)}\right)\right) & =P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \hat{\mathcal{G}}^{\left(\mathbb{T} b_{k}\right)}\right)\right) \\
& =P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)=m_{s c}
\end{aligned}
$$

On the other hand, for the indices $k \in \llbracket 1, \mu \rrbracket \backslash J$, by (3.7), Proposition 11.1, and Lemma 14.2, using that for $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, the assumption of Proposition 11.1 holds with $K=2^{10}$, we have

$$
\begin{align*}
& \left|G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \mathcal{G}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right| \leqslant 2 K\left|m_{s c}\right| q^{r}, \\
& \left|\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \hat{\mathcal{G}}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right| \leqslant 4 K\left|m_{s c}\right| q^{r}, \\
& \left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-P_{\tilde{a}_{k}} \tilde{a}_{k}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, \tilde{a}_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right| \leqslant 2^{7} K^{3}\left|m_{s c}\right| q^{r} . \tag{14.22}
\end{align*}
$$

The above estimates (14.22) and (14.17) give

$$
\begin{align*}
& \left\lvert\, \frac{1}{\mu} \sum_{k=1}^{\mu}\left(G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \mathcal{G}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right)\right. \\
& \quad-\left(\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \hat{\mathcal{G}}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right) \mid \\
& \quad \leqslant \frac{6 K(\mu-|J|)\left|m_{s c}\right| q^{r}}{\mu}+\frac{1}{\mu} \sum_{k \in J}\left|G_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \\
& \quad \leqslant \frac{6 K\left(\omega^{\prime}+9 \omega\right)\left|m_{s c}\right| q^{r}}{\mu}+\left(8 K^{2}\left|m_{s c}\right| q^{2 r}+16 q^{2 r}\right) \leqslant \frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{4 \sqrt{\mu}} . \tag{14.23}
\end{align*}
$$

Moreover, by the above estimates (14.22), (14.18) and using $\tilde{a}_{k}=c_{k}$ for $k \in J$, we have

$$
\begin{align*}
& \left\lvert\, \frac{1}{\mu} \sum_{k=1}^{\mu}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-P_{\tilde{a}_{k}} \tilde{a}_{k}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, \tilde{a}_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right)\right. \\
& \quad-\left(\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}-P_{c_{k} c_{k}}\left(\mathcal{E}_{r}\left(c_{k}, c_{k}, \hat{\mathcal{G}}^{\left(\mathbb{T} b_{k}\right)}\right)\right)\right) \mid \\
& \quad \leqslant \frac{\left(4 K+2^{7} K^{3}\right)(\mu-|J|)\left|m_{s c}\right| q^{r}}{\mu}+\frac{1}{\mu} \sum_{k \in J}\left|\tilde{G}_{c_{k} c_{k}}^{(\mathbb{T})}-\hat{G}_{c_{k} c_{k}}^{\left(\mathbb{T} b_{k}\right)}\right| \\
& \quad \leqslant \frac{\left(4 K+2^{7} K^{3}\right)\left(\omega^{\prime}+9 \omega\right)\left|m_{s c}\right| q^{r}}{\mu}+2^{10} K^{4}\left|m_{s c}\right| q^{2 r} \leqslant \frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{4 \sqrt{\mu}} . \tag{14.24}
\end{align*}
$$

In the above estimates we used $\ell \geqslant 4 \log _{d-1} \log N$ by (3.1) so that $\sqrt{\mu} \gg \log N=\omega^{\prime}$. The left-hand side of (14.2) is bounded by

$$
|(14.5)|+|(14.9)|+|(14.24)|+|(14.5)| \leqslant \frac{2(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{\sqrt{\mu}}
$$

provided that $\sqrt{N \eta} q^{3 r+2} \geqslant M$.

## 15. Improved Approximation in the Switched Graph

The results of this section are the following proposition, stating that the Green's function obeys better estimates than the original one near vertex 1 . As in the previous sections, we write $\tilde{\mathcal{G}}=T_{\mathbf{S}}(\mathcal{G})$ and assume that $\mathbf{S} \in F^{\prime}(\mathcal{G})$ (as in Lemma 14.3) is such that $\tilde{\mathcal{G}}=$ $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$ (as in Sect. 3.2). Throughout the proof, $C$ represents constants depending only on the constant $K$ from (11.1) and the excess $\omega$, which may be different from line to line.

Proposition 15.1. Under the assumptions of Propositions 11.1, for $\mathbf{S} \in F^{\prime}(\mathcal{G})$ such that $\tilde{\mathcal{G}}=T_{\mathbf{S}} \mathcal{G} \in \bar{\Omega}$, the Green's function of the switched graph satisfies the following improved estimates near vertex 1 .
(i) For the vertex $x=1$,

$$
\begin{align*}
\tilde{G}_{11}= & P_{11}\left(\mathcal{E}_{r}(1,1, \tilde{\mathcal{G}})\right)+\frac{m_{d}^{2} m_{s c}^{2 \ell} \mu}{(d-1)^{(\ell+1)}}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right) \\
& +O_{\leqslant}\left(2^{2 \omega+10} K^{3}\left|m_{s c}\right| q^{r+1}\right) . \tag{15.1}
\end{align*}
$$

(ii) For all vertices $x \in \llbracket 2, N \rrbracket$,

$$
\begin{equation*}
\left|\tilde{G}_{1 x}-P_{1 x}\left(\mathcal{E}_{r}(1, x, \tilde{\mathcal{G}})\right)\right| \leqslant(\omega+1) 2^{2 \omega+14} K^{3}\left|m_{s c}\right| q^{r+1} \tag{15.2}
\end{equation*}
$$

Moreover, if the vertex 1 has radius- $R$ tree neighborhood in the graph $\tilde{\mathcal{G}}$, then the following stronger estimates hold.
(i') For the vertex $x=1$,

$$
\begin{equation*}
\tilde{G}_{11}=m_{d}+m_{d}^{2} m_{s c}^{2 \ell} \frac{d}{d-1}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right)+O_{\leqslant}\left(\frac{4(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{\sqrt{d(d-1)^{\ell}}}\right) \tag{15.3}
\end{equation*}
$$

(ii') For the the average of $\tilde{G}_{1 x}$ over the vertices $x$ adjacent to 1 ,

$$
\begin{align*}
\frac{1}{d} \sum_{1 \sim x} \tilde{G}_{1 x}+\frac{m_{d} m_{s c}}{\sqrt{d-1}}= & \frac{-m_{d}^{2} m_{s c}^{2 \ell-1}\left(1+m_{s c}^{2}\right)}{\sqrt{d-1}}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right) \\
& +O_{\leqslant}\left(\frac{16(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r+1}}{\sqrt{d(d-1)^{\ell}}}\right) \tag{15.4}
\end{align*}
$$

For all estimates we assume that $\sqrt{d-1} \geqslant \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \omega^{\prime 2} q^{\ell} \ll 1$ and $\sqrt{N \eta} q^{3 r+2} \geqslant M$, and the global quantity $Q(\tilde{\mathcal{G}})$ is as defined in (14.1).

We use the same set-up as in Sect. 13, and notice that (15.2) is (13.2).
15.1. Proof of (15.1) and (15.3). By (13.8), we have

$$
\begin{align*}
\tilde{G}_{11}-\tilde{P}_{11}= & \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket} \tilde{P}_{1 l_{k}}^{2}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right) \\
& +\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket} \tilde{G}_{1 l_{k}} \tilde{P}_{1 l_{m}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right) \\
& +\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right) \tilde{P}_{1 l_{k}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right) . \tag{15.5}
\end{align*}
$$

For the last term on the right-hand side of (15.5), we have

$$
\begin{aligned}
& \left|\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right) \tilde{P}_{1 l_{k}}\left(\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right)\right| \\
& \leqslant \sum_{k \in \llbracket 1, \mu \rrbracket} C q^{r+2} q^{\ell+1}\left(\left|m_{s c}\right| q^{r}\right) \\
& \leqslant C\left|m_{s c}\right| q^{r+\ell+2}
\end{aligned}
$$

where we used (13.22) for the first factor, (13.25) for the second factor, and (11.4) for the last factor. For the second term on the right-hand side of (15.5), we have

$$
\begin{aligned}
& \left|\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket} \tilde{G}_{1 l_{k}} \tilde{P}_{1 l_{m}}\left(\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right)\right| \\
& \leqslant C\left(q^{\ell+1}\right)\left(q^{\ell+1}\right) \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right)\right| \\
& \leqslant C q^{2 \ell+2}\left(\omega^{\prime 2}\left|m_{s c}\right| q^{r}\right) \leqslant C\left|m_{s c}\right| q^{r+\ell+2},
\end{aligned}
$$

provided that $\omega^{\prime 2} q^{\ell} \ll 1$, where we used (13.29) for the first factor, (13.25) for the second factor, and (13.15) for the last factor. Therefore (15.5) is bounded by

$$
\begin{equation*}
\tilde{G}_{11}-\tilde{P}_{11}=\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket} \tilde{P}_{1 l_{k}}^{2}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}\right)+O\left(\left|m_{s c}\right| q^{r+\ell+2}\right) \tag{15.6}
\end{equation*}
$$

where the implicit constant depends only on the excess $\omega$ and $K$ from (11.1).
Proof of (15.3). If the radius- $R$ neighborhood of the vertex 1 is a tree, then by Proposition 5.1,

$$
\tilde{P}_{1 l_{k}}^{2}=\frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{\ell}}, \quad \tilde{P}_{11}=m_{d}
$$

and

$$
\begin{equation*}
\tilde{G}_{11}-m_{d}=\frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{\ell+1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right)+O\left(\left|m_{s c}\right| q^{r+\ell+2}\right) . \tag{15.7}
\end{equation*}
$$

Notice that $\mu=d(d-1)^{\ell}$ under the assumption that the $R$-neighborhood is a tree. Moreover, for all $k \in \llbracket 1, \mu \rrbracket$,

$$
\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}=\tilde{P}_{\tilde{a}_{k}} \tilde{a}_{k}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, \tilde{a}_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)=m_{s c},
$$

and by Proposition 14.1, we can simplify (15.7) to get

$$
\begin{equation*}
\tilde{G}_{11}=m_{d}+\frac{d}{d-1} m_{d}^{2} m_{s c}^{2 \ell}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right)+O \leqslant\left(\frac{4(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{\sqrt{d(d-1)^{\ell}}}\right) \tag{15.8}
\end{equation*}
$$

This finishes the proof of (15.3).
Proof of (15.1). Since by assumption $\tilde{\mathcal{G}} \in \bar{\Omega}$, the radius- $R$ neighborhood of the vertex 1 has excess at most $\omega$. Therefore, there are at most $2 \omega(d-1)^{\ell}$ indices $k \in \llbracket 1, \mu \rrbracket$ such that the non-backtracking path from 1 to $l_{k}$ of length $\ell$ is not unique. Let

$$
J^{\prime}=\left\{k \in \llbracket 1, \mu \rrbracket: \text { non-backtracking path from } 1 \text { to } l_{k} \text { of length } \ell \text { is unique }\right\} .
$$

For $k \in J^{\prime}$, by (5.14) in the proof of Proposition 5.2, we have

$$
\left|\tilde{P}_{1 l_{k}}-\frac{m_{d}\left(-m_{s c}\right)^{\ell}}{(d-1)^{\ell / 2}}\right| \leqslant\left|m_{d}\right| \sum_{k \geqslant 2} 2^{\omega k} q^{\ell+k-1} \leqslant 2^{2 \omega}\left|m_{d}\right| \frac{3}{2} q^{\ell+1},
$$

provided that $\sqrt{d-1} \geqslant 2^{\omega+2}$. Therefore, for all $k \in J^{\prime}$, the following estimate holds

$$
\frac{\tilde{P}_{1 l_{k}}^{2}}{d-1}=\frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{\ell+1}}+O_{\leqslant}\left(2^{2 \omega+2} q^{2 \ell+3}\right) .
$$

For $k \in \llbracket 1, \mu \rrbracket \backslash J^{\prime}$ by (13.25), we have $\left|\tilde{P}_{1 l_{k}}\right| \leqslant 2^{\omega+2}\left|m_{s c}\right| q^{\ell}$. Notice that $\left|J^{\prime}\right| \leqslant \mu \leqslant$ $d(d-1)^{\ell}$ and $\left|\llbracket 1, \mu \rrbracket \backslash J^{\prime}\right| \leqslant 2 \omega(d-1)^{\ell}$, it follows that

$$
\begin{align*}
& \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{P}_{1 l_{k}}^{2}-\frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{\ell}}\right|=\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket \backslash J^{\prime}}(\cdots)+\frac{1}{d-1} \sum_{k \in J^{\prime}}(\cdots) . \\
& \leqslant 2 \omega(d-1)^{\ell} 2^{2 \omega+5} q^{2 \ell+2}+d(d-1)^{\ell} 2^{2 \omega+2} q^{2 \ell+3} \leqslant 2^{2 \omega+2}(d q+16 \omega) q^{2} \tag{15.9}
\end{align*}
$$

Combining (15.9), (11.4) and (13.5), (15.6) leads to

$$
\begin{align*}
\tilde{G}_{11}-\tilde{P}_{11}= & \frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{(\ell+1)}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right) \\
& +O_{\leqslant}\left(2^{2 \omega+2}(d q+16 \omega) q^{2} \max _{k \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right|\right) \\
= & \frac{m_{d}^{2} m_{s c}^{2 \ell}}{(d-1)^{(\ell+1)}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}} \tilde{a}_{k}\left(\mathcal{E}_{r}\left(\tilde{a}_{k}, \tilde{a}_{k}, \tilde{\mathcal{G}}^{(\mathbb{T})}\right)\right)\right)+\mathcal{E} \tag{15.10}
\end{align*}
$$

where the error term is bounded

$$
\begin{aligned}
|\mathcal{E}| \leqslant & 2^{2 \omega+2}(d q+16 \omega) q^{2}\left(2^{7} K^{3}\left|m_{s c}\right| q^{r}+2^{2 \omega+3}\left|m_{s c}\right| q^{r+1}\right) \\
& +\left|m_{d}\right|^{2} \mu 2^{2 \omega+3}\left|m_{s c}\right| q^{r+1} /(d-1)^{\ell+1} \\
\leqslant & 3 \times 2^{2 \omega+8} K^{3}\left|m_{s c}\right| q^{r+1},
\end{aligned}
$$

provided that $\sqrt{d-1} \geqslant 2^{6} \omega$. Therefore, by Proposition 14.1, we can simplify (15.10) to get

$$
\begin{equation*}
\tilde{G}_{11}=\tilde{P}_{11}\left(\mathcal{E}_{r}(1,1, \tilde{\mathcal{G}})\right)+\frac{m_{d}^{2} m_{s c}^{2 \ell} \mu}{(d-1)^{(\ell+1)}}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right)+O_{\leqslant}\left(2^{2 \omega+10} K^{3}\left|m_{s c}\right| q^{r+1}\right) \tag{15.11}
\end{equation*}
$$

This finishes the proof of (15.1).

### 15.2. Proof of (15.4).

Proof of (15.4). For any vertex $x$ adjacent to 1 , by (13.8), we have

$$
\begin{align*}
\tilde{G}_{1 x}-\tilde{P}_{1 x}= & \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket} \tilde{P}_{1 l_{k}} \tilde{P}_{x l_{k}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right) \\
& +\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket} \tilde{G}_{1 l_{k}} \tilde{P}_{x l_{m}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}\right) \\
& +\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right) \tilde{P}_{x l_{k}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right) . \tag{15.12}
\end{align*}
$$

For the last term on the right-hand side of (15.12),

$$
\left.\begin{aligned}
\left\lvert\, \frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{1 l_{k}}-\tilde{P}_{1 l_{k}}\right) \tilde{P}_{x l_{k}}\left(\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})}-\tilde{a}_{k}\right.\right. \\
\left.\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}\right)
\end{aligned}\left|\leqslant C q^{r+2} q^{r+1} \sum_{k \in \llbracket 1, \mu \rrbracket}\right| \tilde{P}_{x l_{k}} \right\rvert\,
$$

where in the first inequality, we used (13.22) for the first factor, and (11.4) for the last factor; in the second inequality, we used (13.9) for the case $x \in \mathbb{T}_{1}$. For the second term on the right-hand side of (15.12), we have

$$
\begin{aligned}
\left|\frac{1}{d-1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket} \tilde{G}_{1 l_{k}} \tilde{P}_{x l_{m}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{m}\right)\right| & \leqslant C q^{2 \ell+1} \sum_{k \neq m \in \llbracket 1, \mu \rrbracket}\left|\tilde{G}_{\tilde{a}_{k} \tilde{a}_{m}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})}\right| \\
& \leqslant C \omega^{\prime 2}\left|m_{s c}\right| q^{r+2 \ell+1} \\
& \leqslant C\left|m_{s c}\right| q^{r+\ell+1}
\end{aligned}
$$

provided that $\omega^{\prime 2} q^{\ell} \ll 1$, where we used (13.15). Therefore, they together lead to

$$
\begin{equation*}
\tilde{G}_{1 x}-\tilde{P}_{1 x}=\frac{1}{d-1} \sum_{k \in \llbracket 1, \mu \rrbracket} \tilde{P}_{1 l_{k}} \tilde{P}_{x l_{k}}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right)+O\left(\left|m_{s c}\right| q^{r+\ell+1}\right) \tag{15.13}
\end{equation*}
$$

where the implicit constant depends only on the excess $\omega$ and $K$. Especially, if vertex 1 has radius- $R$ neighborhood, then by Proposition 5.1

$$
\begin{aligned}
& \tilde{P}_{1 x}=-\frac{m_{d} m_{s c}}{\sqrt{d-1}}, \quad \tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}=m_{s c} \\
& \tilde{P}_{1 l_{k}}=\frac{m_{d}\left(-m_{s c}\right)^{\ell}}{(d-1)^{\ell / 2}}, \quad \tilde{P}_{x l_{k}}=m_{d}\left(\frac{-m_{s c}}{\sqrt{d-1}}\right)^{\operatorname{dist}_{\tilde{\mathcal{G}}}\left(x, l_{k}\right)}
\end{aligned}
$$

for any index $k \in \llbracket 1, \mu \rrbracket$. Thus averaging (15.13) over all the vertices $x$ adjacent to 1 (in the following, we write $x \sim 1$ when the vertex $x$ is adjacent to 1 ), we get

$$
\begin{aligned}
& \frac{1}{d} \sum_{x \sim 1} \tilde{G}_{1 x}+\frac{m_{d} m_{s c}}{\sqrt{d-1}} \\
& \quad=\frac{1}{d(d-1)} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}-\tilde{P}_{\tilde{a}_{k}}^{(\mathbb{T})} \tilde{a}_{k}\right) \sum_{x \sim 1} \tilde{P}_{1 l_{k}} \tilde{P}_{x l_{k}}+O\left(\left|m_{s c}\right| q^{r+\ell+1}\right) \\
& \quad=\frac{m_{d}\left(-m_{s c}\right)^{\ell}}{d(d-1)^{\ell / 2+1}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}\right) \sum_{x \sim 1} \tilde{P}_{x l_{k}}+O\left(\left|m_{s c}\right| q^{r+\ell+1}\right) \\
& \quad=\frac{-m_{d}^{2} m_{s c}^{2 \ell-1}\left(1+m_{s c}^{2}\right)}{d(d-1)^{\ell+1 / 2}} \sum_{k \in \llbracket 1, \mu \rrbracket}\left(\tilde{G}_{\tilde{a}_{k} \tilde{a}_{k}}^{(\mathbb{T})}-\tilde{P}_{\tilde{a}_{k}}^{\left(\mathbb{T} \tilde{a}_{k}\right.}\right)+O\left(\left|m_{s c}\right| q^{r+\ell+1}\right) \\
& \quad=\frac{-m_{d}^{2} m_{s c}^{2 \ell-1}\left(1+m_{s c}^{2}\right)}{\sqrt{d-1}}\left(Q(\tilde{\mathcal{G}})-m_{s c}\right)+O \leqslant\left(\frac{16(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r+1}}{\sqrt{d(d-1)^{\ell}}}\right) .
\end{aligned}
$$

In the third line, we used the fact that for any index $k \in \llbracket 1, \mu \rrbracket$, among the $d$ children of vertex 1 , one of them is distance $\ell-1$ to the vertex $l_{k}$, and the others are distance $\ell+1$ to the vertex $l_{k}$. In the last line, we used Proposition (14.1), and $\left|m_{d}^{2} m_{s c}^{2 \ell-1}\left(1+m_{s c}^{2}\right)\right| \leqslant 4$. This finishes the proof of Proposition 15.1.

## 16. Proof of Main Results

In this section, we use the estimates established in the previous sections to prove Theorem 2.4.
16.1. Summary of estimates. By combining the propositions of the previous sections, we obtain the following sequence of propositions, relating the sets

$$
\Omega^{-}(z, \ell) \subset \Omega(z, \ell) \subset \Omega_{1}^{+}(z, \ell) \subset \bar{\Omega} \subset \mathrm{G}_{N, d}, \quad \Omega_{1}^{\prime}(z, \ell) \subset \bar{\Omega} \subset \mathrm{G}_{N, d}
$$

defined in Sect. 3.2. We also recall the parameters from Sect. 3.1, assume that

$$
\begin{equation*}
\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket, \quad r=2 \ell+1, \tag{16.1}
\end{equation*}
$$

and (9.4), namely that

$$
\begin{equation*}
\omega^{\prime}=\lfloor\log N\rfloor, \quad M=(d-1)^{9 \ell}(\log N)^{\delta} . \tag{16.2}
\end{equation*}
$$

Since, for $|z| \geqslant 2 d-1$, the claim of Theorem 2.4 follows from Proposition 6.1, it suffices to prove the claim of Theorem 2.4 on the following slightly smaller domain

$$
\begin{equation*}
\mathcal{D}^{*}:=\left\{z \in \mathbb{C}_{+}:|z| \leqslant 2 d, \quad \operatorname{Im}[z] \geqslant \frac{(\log N)^{48 \alpha+1}}{N}, \quad|z \pm 2| \geqslant(\log N)^{-\alpha / 2+1}\right\} \tag{16.3}
\end{equation*}
$$

which is the intersection of $\mathcal{D}$ [as in (1.4)] with $\left\{z \in \mathbb{C}_{+}:|z| \leqslant 2 d\right\}$.
Proposition 16.1 (Initial estimates). Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for $N \geqslant N(\omega, d, \delta)$ large enough, we have

$$
\begin{equation*}
\mathbb{P}(\bar{\Omega})=1-o\left(N^{-\omega+\delta}\right) \tag{16.4}
\end{equation*}
$$

Moreover, for any $z \in \mathbb{C}_{+}$such that $|z| \geqslant 2 d-1$, we have $\bar{\Omega} \subset \Omega^{-}(z, \ell)$.
Proof. The estimate (16.4) follows from Proposition 4.1, and the inclusion $\bar{\Omega} \subset \Omega^{-}(z, \ell)$ from Proposition 6.1.

Given a graph $\mathcal{G}$ and a vertex $i$, we resample the edge boundary of $\mathcal{B}_{\ell}(i, \mathcal{G})$ using switchings; without loss of generality we assume $i=1$. Denote the resampled graph by $T_{\mathbf{S}}(\mathcal{G})$ (which depends on the choice of $i$ ); $\mathbf{S}$ is the resampling data (whose distribution depends on $\mathcal{G}$ ).

Proposition 16.2 (Stability under resampling). Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for $z \in \mathcal{D}^{*}, N \geqslant N(\alpha, \omega, d, \delta)$ large enough, and any $\mathcal{G} \in \Omega(z, \ell)$, the following holds. (i) $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$. (ii) There exists a set $F(\underline{\mathcal{G}}) \subset \mathbf{S}(\mathcal{G})$ with $\mathbb{P}_{\mathcal{G}}(F(\mathcal{G}))=1-o\left(N^{-\omega+\delta}\right)$ such that for any $\mathbf{S} \in F(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$, we have $T_{\mathbf{S}}(\mathcal{G}) \in \Omega_{1}^{+}(z, \ell)$.

Proof. The first statement $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$ follows from Proposition 10.1, and the second statement follows from Proposition 11.1 with $K=2$.

Proposition 16.3. (Improvement under resampling) Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for $z \in \mathcal{D}^{*}$, $N \geqslant N(\alpha, \omega, d, \delta)$ large enough, and any $\mathcal{G} \in \Omega_{1}^{+}(z, \ell)$, there exists a set $F^{\prime}(\mathcal{G}) \subset \mathrm{S}(\mathcal{G})$ with $\mathbb{P}_{\mathcal{G}}\left(F^{\prime}(\mathcal{G})\right)=1-o\left(N^{-\omega+\delta}\right)$ such that for any $\mathbf{S} \in F^{\prime}(\mathcal{G})$ with $T_{\mathbf{S}}(\mathcal{G}) \in \bar{\Omega}$, we have $T_{\mathbf{S}}(\mathcal{G}) \in \Omega_{1}^{\prime}(z, \ell)$.

Proof. The definition of the set $F^{\prime}(\mathcal{G})$ and its properties are given in Proposition 14.1. The final statement $T_{\mathbf{S}}(\mathcal{G}) \in \Omega_{1}^{\prime}(z, \ell)$ follows from Propositions 11.1 and 15.1 by taking $K=2^{10}$ 。

The improvement under resampling above applies to the switched graphs $T_{\mathbf{S}}(\mathcal{G})$. However, by general properties of $T$, it implies an improvement on the original space of graphs.

Proposition 16.4. (Improvement on original space) Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for $z \in \mathcal{D}^{*}$, we have

$$
\begin{equation*}
\mathbb{P}\left(\Omega(z, \ell) \backslash\left(\Omega(z, \ell) \cap \Omega_{1}^{\prime}(z, \ell)\right)\right)=o\left(N^{-\omega+\delta}\right) \tag{16.5}
\end{equation*}
$$

Proof. By Propositions 16.1-16.3, the conditions of Proposition 7.5 are satisfied with $q_{0}, q_{1}, q_{2}=o\left(N^{-\omega+\delta}\right)$, and $\bar{\Omega}$ as in Sect. $3, \Omega=\Omega(z, \ell), \Omega^{+}=\Omega_{1}^{+}(z, \ell)$, and $\Omega^{\prime}=\Omega_{1}^{\prime}(z, \ell)$. Therefore, Proposition 7.5 implies

$$
\mathbb{P}\left(\Omega(z, \ell) \backslash\left(\Omega(z, \ell) \cap \Omega_{1}^{\prime}(z, \ell)\right)\right)=o\left(N^{-\omega+\delta}\right)
$$

which was the claim.
Clearly, by the same argument or by symmetry, (16.5) also holds with vertex 1 replaced by any other vertex $i \in \llbracket N \rrbracket$. In particular, for any graph in the intersection of the $\Omega_{i}^{\prime}(z, \ell)$ over $i \in \llbracket N \rrbracket$, we have the following improved estimates for the entries of its Green's function.

Proposition 16.5 (Self-consistent equation). Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for any $z \in \mathcal{D}^{*}$ [as in (16.3)] and $N \geqslant N(\alpha, \omega, d, \delta)$ large enough, with probability $1-o\left(N^{-\omega+1+\delta}\right)$, we have

$$
\begin{equation*}
Q(\mathcal{G})-m_{s c}=\frac{d-2}{d-1} m_{d} m_{s c}^{2 \ell+1}\left(Q(\mathcal{G})-m_{s c}\right)+O\left(\frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{(d-1)^{(\ell+1) / 2}}\right) \tag{16.6}
\end{equation*}
$$

Proof. As noted above, the same statement as in Proposition 16.4 holds with vertex 1 replaced by any other vertex $i \in \llbracket N \rrbracket$. On the union of the $\Omega_{i}^{\prime}(z, \ell)$, the improvement then holds for all $i$ simultaneously, and by a union bound

$$
\mathbb{P}\left(\Omega(z, \ell) \backslash \cap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}(z, \ell)\right) \leqslant \sum_{i=1}^{N} \mathbb{P}\left(\Omega(z, \ell) \backslash \Omega_{i}^{\prime}(z, \ell)\right)=o\left(N^{-\omega+1+\delta}\right) .
$$

For any graph $\mathcal{G} \in \cap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}(z, \ell)$, by the definition of $\Omega_{i}^{\prime}(z, \ell)$ (as in Sect. 3), we have

$$
\begin{align*}
G_{i i}(\mathcal{G}, z)= & P_{i i}\left(\mathcal{E}_{r}(i, i, \mathcal{G}), z\right)+\frac{m_{d}^{2} m_{s c}^{2 \ell} \mu}{(d-1)^{(\ell+1)}}\left(Q(\mathcal{G})-m_{s c}\right) \\
& +O_{\leqslant}\left(2^{2 \omega+40}\left|m_{s c}\right| q^{r+1}\right), \tag{16.7}
\end{align*}
$$

and, for any $j \neq i$, we have the bound

$$
\begin{equation*}
\left|G_{i j}(\mathcal{G}, z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant(\omega+1) 2^{2 \omega+44}\left|m_{s c}\right| q^{r+1} \tag{16.8}
\end{equation*}
$$

In the following, we derive an approximate self-consistent equation for $Q(\mathcal{G})-m_{s c}$. Using the Green's function identity (B.5), notice that

$$
\begin{align*}
Q(\mathcal{G})-m_{s c}=\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}}\left(G_{j j}^{(i)}-m_{s c}\right) & =\frac{1}{N d} \sum_{(i, j) \in \boldsymbol{E}}\left(G_{j j}-\frac{G_{i j} G_{i j}}{G_{i i}}-m_{s c}\right) \\
& =\frac{1}{N} \sum_{i}\left(G_{i i}-\frac{1}{d} \sum_{j: j \sim i} \frac{G_{i j} G_{i j}}{G_{i i}}-m_{s c}\right), \tag{16.9}
\end{align*}
$$

where $\boldsymbol{E}$ is the set of oriented edges of $\mathcal{G}$, and where here $j \sim i$ means that the vertices $i$ and $j$ are adjacent to each other. Since $\mathcal{G} \in \bar{\Omega}$, at least $N-N^{\delta}$ of the vertices of $\mathcal{G}$ have radius- $R$ tree neighborhoods. The contribution to $Q(\mathcal{G})-m_{s c}$ from those vertices which do not have radius- $R$ tree neighborhoods is $O\left(N^{\delta-1}\right)$. For any vertex $i$ that has radius- $R$ tree neighborhood, by the definition of $\Omega_{i}^{\prime}(z, \ell)$,

$$
\begin{align*}
G_{i i}-m_{d}= & m_{d}^{2} m_{s c}^{2 \ell} \frac{d}{d-1}\left(Q(\mathcal{G})-m_{s c}\right) \\
& +O\left(\frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{(d-1)^{(\ell+1) / 2}}\right),  \tag{16.10}\\
\frac{1}{d} \sum_{j \sim i} G_{i j}+\frac{m_{d} m_{s c}}{\sqrt{d-1}}= & \frac{-m_{d}^{2} m_{s c}^{2 \ell-1}\left(1+m_{s c}^{2}\right)}{\sqrt{d-1}}\left(Q(\mathcal{G})-m_{s c}\right) \\
& +O\left(\frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r+1}}{(d-1)^{(\ell+1) / 2}}\right) . \tag{16.11}
\end{align*}
$$

Also, by the stability estimate Claim 13.8, for any vertex $i$ with radius- $R$ tree neighborhood, and vertex $j$ adjacent to $i$, we have $\left|G_{i i}-m_{d}\right|=O\left(\left|m_{s c}\right| q^{r}\right)$ and $\mid G_{i j}-$ $m_{d} m_{s c} / \sqrt{d-1} \mid=O\left(\left|m_{s c}\right| q^{r}\right)$, where the implicit constant depends only on $\omega$. It follows that

$$
\begin{align*}
& \frac{G_{i j} G_{i j}}{G_{i i}}-\frac{m_{d} m_{s c}^{2}}{d-1} \\
& \quad=\frac{-\frac{2 m_{d}^{2} m_{s c}}{\sqrt{d-1}}\left(G_{i j}+\frac{m_{d} m_{s c}}{\sqrt{d-1}}\right)-\frac{m_{d}^{2} m_{s c}^{2}}{d-1}\left(G_{i i}-m_{d}\right)+m_{d}\left(G_{i j}+\frac{m_{d} m_{s c}}{\sqrt{d-1}}\right)^{2}}{m_{d} G_{i i}} \\
& \quad=-\frac{2 m_{s c}}{\sqrt{d-1}}\left(G_{i j}+\frac{m_{d} m_{s c}}{d-1}\right)-\frac{m_{s c}^{2}}{d-1}\left(G_{i i}-m_{d}\right)+O\left(q^{2 r}\right) . \tag{16.12}
\end{align*}
$$

Combining (16.10)-(16.12), we get

$$
\begin{aligned}
G_{i i}-\frac{1}{d} \sum_{j: j \sim i} \frac{G_{i j} G_{i j}}{G_{i i}}-m_{s c}= & \frac{d-2}{d-1} m_{s c}^{2 \ell+1} m_{d}\left(Q(\mathcal{G})-m_{s c}\right) \\
& +O\left(\frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{(d-1)^{(\ell+1) / 2}}\right)
\end{aligned}
$$

for all vertices $i$ which have radius- $R$ tree neighborhoods. Averaging the last equation over $i \in \llbracket N \rrbracket$, by (16.9) we then obtain (16.6), as claimed.

The equation (16.6) implies

$$
\begin{equation*}
Q(\mathcal{G})-m_{s c}=\left(1-\frac{d-2}{d-1} m_{d} m_{s c}^{2 \ell+1}\right)^{-1} O\left(\frac{(\log N)^{1 / 2+\delta}\left|m_{s c}\right| q^{r}}{(d-1)^{(\ell+1) / 2}}\right) \tag{16.13}
\end{equation*}
$$

provided that the term in the first bracket does not vanish. To use this equation to show that the left-hand side is small, we require a lower bound on the term in the first bracket on the right-hand side. Since $1-(d-2) m_{d} m_{s c}^{2 \ell+1} /(d-1)$ may be zero on the spectral domain $\mathcal{D}^{*}$, such a bound only holds on an $\ell$-dependent subset of the spectral domain, which we now define. (In Sect. 16.2, we will use the flexibility in the choice of $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$ to recover the entire spectral domain.)

First, we define the Joukowsky transform $\phi$ to be the holomorphic bijection from the upper half unit disk $\mathbb{D}_{+}$to the upper half plane $\mathbb{C}_{+}$given by

$$
\phi: w \in \mathbb{D}_{+} \mapsto-\left(w+w^{-1}\right) \in \mathbb{C}_{+}
$$

It is the functional inverse of $z \mapsto m_{s c}(z)$, i.e. $m_{s c}(\phi(w))=w$. For any $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$ as in (3.1), we define the small error parameter

$$
\begin{equation*}
\varepsilon_{\ell}:=\frac{(\log N)^{1 / 2+2 \delta}}{(d-1)^{(\ell+1) / 2}} \ll(\log N)^{1-\alpha / 2}, \tag{16.14}
\end{equation*}
$$

as well as the sets $\tilde{\Lambda}_{\ell} \subset \mathbb{D}_{+}$and $\Lambda_{\ell} \subset \mathbb{C}_{+}$by

$$
\begin{equation*}
\tilde{\Lambda}_{\ell}:=\left\{m_{s c}(z): z \in \mathbb{C}_{+},\left|1-\frac{d-2}{d-1} m_{s c}^{2 \ell+1}(z) m_{d}(z)\right| \geqslant \varepsilon_{\ell}\right\}, \quad \Lambda_{\ell}:=\phi\left(\tilde{\Lambda}_{\ell}\right) \tag{16.15}
\end{equation*}
$$

Proposition 16.6 (Self-consistent equation). Under the assumptions of Theorem 2.4, and the choices of parameters given in (16.1) and (16.2), for any $z \in \mathcal{D}^{*}$ [as in (16.3)] and $N \geqslant N(\alpha, \omega, d, \delta)$ large enough, we have

$$
\mathbb{P}\left(\Omega(z, \ell) \backslash \cap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}(z, \ell)\right)=o\left(N^{-\omega+1+\delta}\right)
$$

Moreover, for $z \in \mathcal{D}^{*} \cap \Lambda_{\ell}$ and any $\mathcal{G} \in \bigcap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}(z, \ell)$, the normalized Green's function of $\mathcal{G}$ satisfies, for any $i, j \in \llbracket N \rrbracket$,

$$
\left|G_{i j}(\mathcal{G}, z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant(\omega+1) 2^{2 \omega+44}\left|m_{s c}\right| q^{r+1}
$$

where $r=2 \ell+1$.
Proof. Let $z \in \mathcal{D}^{*} \cap \Lambda_{\ell}$. Then by the definition of the set $\tilde{\Lambda}_{\ell}$ in (16.15), we have

$$
\left|1-\frac{d-2}{d-1} m_{s c}^{2 \ell+1} m_{d}\right| \geqslant \frac{(\log N)^{1 / 2+2 \delta}}{(d-1)^{(\ell+1) / 2}}
$$

and (16.13) implies

$$
\left|Q(\mathcal{G})-m_{s c}\right|=O\left(\left|m_{s c}\right| q^{r}(\log N)^{-\delta}\right),
$$

where the implicit constant depends only on $\omega$. Plugging the above expression into (16.7), we get

$$
G_{i i}(\mathcal{G}, z)=P_{i i}\left(\mathcal{E}_{r}(i, i, \mathcal{G}), z\right)+O_{\leqslant}\left(\left(1+2^{2 \omega+40}\right)\left|m_{s c}\right| q^{r+1}\right),
$$

for $N$ large enough. This finishes the proof of Proposition 16.6 by combining with (16.8).
16.2. Decomposition of the spectral domain. The following lemma gives a precise description of the sets $\tilde{\Lambda}_{\ell}$, stating that, except for two small regions near $\pm 1$, the half disk $\mathbb{D}_{+}$is contained in the union of the sets $\tilde{\Lambda}_{\ell}$, i.e., in $\cup_{\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket} \tilde{\Lambda}_{\ell}$. To be precise, we define the spectral domains

$$
\begin{align*}
& \mathcal{D}_{\ell}=\left\{z \in \mathbb{C}_{+}:|z| \leqslant 2 d, \quad \operatorname{Im}[z] \geqslant(d-1)^{24 \ell} \log N / N, \quad|z \pm 2| \geqslant 4 \varepsilon_{\ell}\right\},  \tag{16.16}\\
& \tilde{\mathcal{D}}_{\ell}=\mathbb{D}_{+} \backslash\left\{w=e^{\mathrm{i} \theta} r \in \mathbb{D}_{+}:|\theta| \leqslant \varepsilon_{\ell}, 1-\varepsilon_{\ell} \leqslant r<1\right\} . \tag{16.17}
\end{align*}
$$

Lemma 16.7. For any $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$, define $\tilde{\Lambda}_{\ell}$ as in (16.15). Then $\mathbb{D}_{+} \backslash \tilde{\Lambda}_{\ell}$ is contained in

$$
\begin{aligned}
& \left\{w=e^{\mathrm{i} \theta} r: 0<\theta \leqslant \varepsilon_{\ell}, 1-\varepsilon_{\ell} \leqslant r<1\right\} \cup \\
& \left\{w=e^{\pi \mathrm{i}} e^{\mathrm{i} \theta} r:-\varepsilon_{\ell} \leqslant \theta<0,1-\varepsilon_{\ell} \leqslant r<1\right\} \cup \\
& \bigcup_{k=1}^{\ell}\left\{w=e^{\frac{k \pi \mathrm{i}}{} e^{\mathrm{i} \theta}} e^{\theta} r:|\theta| \leqslant \frac{2 \pi}{d(\ell+1)}, 0<r<1\right\} .
\end{aligned}
$$

As a consequence, for any $\theta_{0} \in(0, \pi)$, there exists some $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$ such that

$$
\begin{equation*}
\tilde{\mathcal{D}}_{\ell} \cap\left\{w=e^{\mathrm{i} \theta_{0}} r: 0<r<1\right\} \subset \tilde{\Lambda}_{\ell} \tag{16.18}
\end{equation*}
$$

Proof. By the definition of the set $\tilde{\Lambda}_{\ell}$, its complement is

$$
\left|1-\frac{d-2}{d-1} m_{s c}^{2 \ell+1} \frac{m_{s c}}{1-m_{s c}^{2} /(d-1)}\right|<\varepsilon \ell .
$$

This implies that

$$
\left|1-\frac{m_{s c}^{2}}{d-1}-\frac{d-2}{d-1} m_{s c}^{2 \ell+2}\right|<2 \varepsilon_{\ell},
$$

and therefore

$$
\begin{equation*}
\left|1-m_{s c}^{2 \ell+2}\right|<\left|\frac{m_{s c}^{2}}{d-1}-\frac{m_{s c}^{2 \ell+2}}{d-1}\right|+2 \varepsilon_{\ell}<\frac{2}{d-1}+2 \varepsilon_{\ell} . \tag{16.19}
\end{equation*}
$$

From direct computation, for any $0 \leqslant r \leqslant 1$ and $\theta \in[-\pi, \pi]$, we have the following simple estimate:

$$
\begin{equation*}
\frac{1-r}{2}+\frac{\sqrt{r}|\theta|}{\pi} \leqslant\left|1-e^{\mathrm{i} \theta} r\right| \leqslant(1-r)+|\theta| . \tag{16.20}
\end{equation*}
$$

Therefore (16.19) implies

$$
m_{s c} \in \bigcup_{k=0}^{\ell+1}\left\{w=e^{\frac{k \pi \mathrm{i}}{\ell+1}} e^{\mathrm{i} \theta} r \in \mathbb{D}_{+}:|\theta| \leqslant \frac{2 \pi}{d(\ell+1)}, 0<1-r^{2(\ell+1)} \leqslant \frac{5}{d}\right\}
$$

We have better estimates if $m_{s c}=e^{\mathrm{i} \theta} r$ or $m_{s c}=e^{\mathrm{i} \pi} e^{\mathrm{i} \theta} r$, for some $|\theta| \leqslant \frac{2 \pi}{d(\ell+1)}$ and $0<1-r^{2(\ell+1)} \leqslant \frac{5}{d}$. In this case, on the complement of $\tilde{\Lambda}_{\ell}$,

$$
\left|\frac{d-2}{d-1}\left(1-m_{s c}^{2 \ell+2}\right)\right| \leqslant\left|\frac{1-m_{s c}^{2}}{d-1}\right|+2 \varepsilon \ell .
$$

Combining the above expression with (16.20), we get

$$
\frac{d-2}{d-1}\left(\frac{1-r^{2(\ell+1)}}{2}+\frac{2(\ell+1) r^{(\ell+1)}|\theta|}{\pi}\right) \leqslant \frac{1}{d-1}\left(1-r^{2}+2|\theta|\right)+2 \varepsilon_{\ell}
$$

It follows that $|\theta| \leqslant \varepsilon_{\ell}$ and $1-\varepsilon_{\ell} \leqslant r<1$. This finishes the proof of the first statement.
For the second statement, if $\theta_{0} \in\left(0,\left(1-\frac{2}{d}\right) \frac{\pi}{\ell_{*}+1}\right) \cup\left(\left(1+\frac{2}{d}\right) \frac{\ell_{*} \pi}{\ell_{*}+1}, \pi\right)$, then $\left\{z=e^{\mathrm{i} \theta_{0}} r\right.$ : $0 \leqslant r \leqslant 1\} \cap \tilde{\mathcal{D}}_{\ell_{*}} \subset \tilde{\Lambda}_{\ell_{*}}$. In the following we consider the case, $\theta_{0} \in\left[\left(1-\frac{2}{d}\right) \frac{\pi}{\ell_{*}+1},(1+\right.$ $\left.\left.\frac{2}{d}\right) \frac{\ell_{*} \pi}{\ell_{*}+1}\right]$. We use the convention that $(a \bmod \pi) \in[-\pi / 2, \pi / 2)$, for any $a \in \mathbb{R}$. If we can find some $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$, such that $\left((\ell+1) \theta_{0} \bmod \pi\right) \in[-\pi / 2,-\pi / 8] \cup[\pi / 8, \pi / 2)$, then there exists some integer $k$ such that

$$
-\frac{3 \pi}{8(\ell+1)} \leqslant\left|\theta_{0}-\frac{k \pi}{\ell+1}-\frac{\pi}{2(\ell+1)}\right| \leqslant \frac{3 \pi}{8(\ell+1)}
$$

and thus $\left\{z=e^{\mathrm{i} \theta_{0}} r: 0<r<1\right\} \in \tilde{\Lambda}_{\ell}$. In the following we prove such $\ell$ exists. By symmetry we assume $\theta_{0} \in\left[\left(1-\frac{2}{d}\right) \frac{\pi}{\ell_{*}+1}, \frac{\pi}{2}\right]$. We consider the following numbers,

$$
\begin{equation*}
\left(\ell_{*}+1\right) \theta_{0} \bmod \pi,\left(\ell_{*}+2\right) \theta_{0} \bmod \pi, \ldots,\left(2 \ell_{*}+1\right) \theta_{0} \bmod \pi . \tag{16.21}
\end{equation*}
$$

If $\left(\left(\ell_{*}+1\right) \theta_{0} \bmod \pi\right) \in[-\pi / 2,-\pi / 8] \cup[\pi / 8, \pi / 2)$, then we can take $\ell=\ell_{*}$. Otherwise, we assume $\left(\left(\ell_{*}+1\right) \theta_{0} \bmod \pi\right) \in(-\pi / 8, \pi / 8)$. Since $\left(2 \ell_{*}+1\right) \theta_{0}-\left(\ell_{*}+1\right) \theta_{0}=$ $\ell_{*} \theta_{0} \geqslant\left(1-\frac{2}{d}\right) \frac{\ell_{*} \pi}{\ell_{*}+1} \geqslant \frac{\pi}{2}$, the above sequence (16.21) can not all stay in the interval $(-\pi / 8, \pi / 8)$. Say $(\ell+1) \theta_{0} \bmod \pi$ is the first number in the above sequence which is not in $(-\pi / 8, \pi / 8)$. We can take this $\ell$, then $\left(\ell \theta_{0} \bmod \pi\right) \in(-\pi / 8, \pi / 8)$, and $\left((\ell+1) \theta_{0} \bmod \pi\right) \in[-\pi / 2,-3 \pi / 8) \cup[\pi / 8, \pi / 2)$. This finishes the proof.

Lemma 16.8. 1. For the choice of parameters in (16.1)-(16.2), for any $z \in \mathcal{D}_{\ell}$, all of the conditions in Propositions 6.1, 10.1, 11.1 and 15.1 are satisfied for $K \in\left\{2,2^{10}\right\}$; i.e.,

$$
\begin{aligned}
\sqrt{d-1} \geqslant & \max \left\{(\omega+1)^{2} 2^{2 \omega+10}, 2^{8}(\omega+1) K\right\}, \quad \omega^{\prime 2} q^{\ell} \ll 1, \\
& \sqrt{N \operatorname{Im}[z]} q^{3 r+2} \gg M .
\end{aligned}
$$

2. For any $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$, we have

$$
\begin{equation*}
\mathcal{D}^{*} \subset \mathcal{D}_{\ell} \subset \phi\left(\tilde{\mathcal{D}}_{\ell}\right) \tag{16.22}
\end{equation*}
$$

Proof. It is straightforward to check that (i) holds. In the following, we therefore only prove (ii). For this, notice that $(d-1)^{24 \ell} \leqslant(d-1)^{48 \ell_{*}} \leqslant(\log N)^{48 \alpha}$, and that in combination with (16.14), it follows that $\mathcal{D}^{*} \subset \mathcal{D}_{\ell}$. For the second inclusion in (16.22), observe that, for any $w=e^{\mathrm{i} \theta} r$ such that $0<\theta \leqslant \varepsilon_{\ell}$ and $1-\varepsilon_{\ell} \leqslant r \leqslant 1$, we have

$$
|\phi(w)+2|=\left|e^{\mathrm{i} \theta} r+\frac{1}{e^{\mathrm{i} \theta} r}-2\right|<4 \varepsilon_{\ell},
$$

and that we have similar estimates for $w=e^{\mathrm{i} \pi} e^{\mathrm{i} \theta} r$ with $-\varepsilon_{\ell} \leqslant \theta \leqslant 0$ and $1-\varepsilon_{\ell} \leqslant$ $r \leqslant 1$. Therefore,

$$
\left\{z \in \mathbb{C}_{+}:|z \pm 2| \geqslant 4 \varepsilon_{\ell}\right\} \subset \phi\left(\tilde{\mathcal{D}}_{\ell}\right)
$$

and $\mathcal{D}_{\ell} \subset \phi\left(\tilde{\mathcal{D}}_{\ell}\right)$ follows. This finishes the proof of (16.22).
16.3. Proof of Theorem 2.4. We define a lattice on $\mathbb{D}_{+}$by

$$
\tilde{L}:=\left\{e^{\mathrm{i} \theta} r \in \mathbb{D}_{+}: \theta \in \frac{\pi \mathbb{Z}}{N^{3}}, r \in \frac{\mathbb{Z}}{N^{3}}\right\} .
$$

The image of $\tilde{L}$ under the Joukowsky transform defines a discrete approximation of $\mathcal{D}^{*}$ by

$$
\begin{equation*}
L:=\phi(\tilde{L}) \cap \mathcal{D}^{*} \tag{16.23}
\end{equation*}
$$

Notice that $\mathcal{D}^{*}$ can indeed be well approximated by $L$, in the sense that for any $z \in \mathcal{D}^{*}$ there is some $z^{\prime} \in L$ such that $\left|z-z^{\prime}\right|=(\log N)^{O(1)} / N^{3}$. Therefore, by the following claim, we only need to prove Theorem 2.4 for $z \in L$. The claim is a consequence of the Lipschitz property of Green's function.

Claim 16.9. For any $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$, and $z, z^{\prime} \in \mathcal{D}^{*}$ with $\left|z-z^{\prime}\right|=(\log N)^{O(1)} / N^{3}$, we have

$$
\Omega^{-}(z, \ell) \subset \Omega\left(z^{\prime}, \ell\right)
$$

Proof. For any graph $\mathcal{G} \in \Omega^{-}(z, \ell)$, the Green's function of its normalized adjacency matrix satisfies

$$
\left|G_{i j}(z)-G_{i j}\left(z^{\prime}\right)\right| \leqslant\left|z-z^{\prime}\right| \sum_{m=1}^{N}\left|G_{i m}(z) G_{m j}\left(z^{\prime}\right)\right| \leqslant(\log N)^{O(1)} / N
$$

where we used $\left|z-z^{\prime}\right|=(\log N)^{O(1)} / N^{3},\left|G_{i m}(z)\right|=O(1)$ from the definition (3.3) of $\Omega^{-}(z, \ell)$ and (5.6), as well as the trivial bound $\left|G_{m j}\left(z^{\prime}\right)\right| \leqslant 1 / \eta \leqslant N$. Moreover, the same estimate holds for $\left|P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z^{\prime}\right)\right|$. As a result,

$$
\begin{aligned}
\left|G_{i j}\left(z^{\prime}\right)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z^{\prime}\right)\right| & =\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right|+(\log N)^{O(1)} / N \\
& \leqslant\left|m_{s c}\right| q^{r}
\end{aligned}
$$

and the claim follows.

Claim 16.10. For any $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$, we have

$$
\Omega^{-}(z, \ell) \subset \Omega^{-}\left(z, \ell_{*}\right),
$$

provided that $\sqrt{d-1} \geqslant 2^{2 \omega+3}$.
Proof. Let $\mathcal{G} \in \Omega^{-}(z, \ell)$. Then, by (5.5) in Proposition 5.2,

$$
\begin{aligned}
& \left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G}), z\right)\right| \\
& \quad \leqslant\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right|+\left|P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G}), z\right)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \\
& \quad \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r}+\delta_{r \neq r_{*}} 2^{2 \omega+3}\left|m_{s c}\right| q^{2 \ell_{*}+2} \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r_{*}},
\end{aligned}
$$

provided that $\sqrt{d-1} \geqslant 2^{2 \omega+3}$. Therefore, $\mathcal{G} \in \Omega^{-}\left(z, \ell_{*}\right)$, as claimed.
Proof of Theorem 2.4. For any $\theta_{0} \in \frac{\pi \mathbb{Z}}{N^{3}} \cap(0, \pi)$, the Joukowsky transform $\phi$ sends the ray $\left\{w=e^{\mathrm{i} \theta_{0}} r: 0<r<1\right\}$ to a branch of some hyperbola. With $\theta_{0}$ fixed, we consider the set

$$
\left\{r \in \frac{\mathbb{Z}}{N^{3}}: \phi\left(e^{\mathrm{i} \theta_{0}} r\right) \in \mathcal{D}^{*}\right\}=\left\{\frac{k_{0}}{N^{3}}, \frac{k_{0}+1}{N^{3}}, \frac{k_{0}+2}{N^{3}}, \ldots, \frac{k_{1}}{N^{3}}\right\},
$$

for some $0<k_{0} \leqslant k_{1}<N^{3}$, and denote

$$
z_{k}=\phi\left(\frac{e^{\mathrm{i} \theta_{0}} k}{N^{3}}\right), \quad 1 \leqslant k \leqslant N^{3}
$$

One can check that $k_{0} / N^{3} \geqslant 1 /(3 d),\left|z_{k_{0}}\right| \geqslant 2 d-1$, and $\left|z_{k+1}-z_{k}\right| \leqslant 10 d^{2} / N^{3}$ for $k_{0} \leqslant k \leqslant k_{1}$.

By Proposition 16.7, there exists some $\ell \in \llbracket \ell_{*}, 2 \ell_{*} \rrbracket$ such that $\tilde{\mathcal{D}}_{\ell} \cap\left\{e^{\mathrm{i} \theta_{0}} r: 0<\right.$ $r<1\} \subset \tilde{\Lambda}_{\ell}$. Therefore, combining with (16.22), we have $z_{k_{0}}, z_{k_{0}+1}, \ldots, z_{k_{1}} \in \Lambda_{\ell}$. By Proposition 16.1, $\bar{\Omega} \subset \Omega^{-}\left(z_{k_{0}}, \ell\right)$, and

$$
\begin{equation*}
\mathbb{P}\left(\Omega^{-}\left(z_{k_{0}}, \ell\right)\right)=1-o\left(N^{-\omega+\delta}\right) \tag{16.24}
\end{equation*}
$$

For any $k_{0} \leqslant k \leqslant k_{1}-1$, it follows from Claim 16.9 that

$$
\begin{equation*}
\Omega^{-}\left(z_{k}, \ell\right) \subset \Omega\left(z_{k+1}, \ell\right) \tag{16.25}
\end{equation*}
$$

By Proposition 16.6, we have

$$
\begin{equation*}
\mathbb{P}\left(\Omega\left(z_{k+1}, \ell\right) \backslash \cap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}\left(z_{k+1}, \ell\right)\right)=o\left(N^{-\omega+1+\delta}\right), \tag{16.26}
\end{equation*}
$$

and

$$
\begin{equation*}
\cap_{i \in \llbracket N \rrbracket} \Omega_{i}^{\prime}\left(z_{k+1}, \ell\right) \subset \Omega^{-}\left(z_{k+1}, \ell\right) \tag{16.27}
\end{equation*}
$$

provided that $\sqrt{d-1} \geqslant(\omega+1) 2^{2 \omega+45}$. It follows from combining (16.25)-(16.27) that

$$
\begin{equation*}
\mathbb{P}\left(\Omega^{-}\left(z_{k}, \ell\right) \backslash \Omega^{-}\left(z_{k+1}, \ell\right)\right)=o\left(N^{-\omega+1+\delta}\right) . \tag{16.28}
\end{equation*}
$$

By definition, on the set $\cap_{k=k_{0}}^{k_{1}} \Omega^{-}\left(z_{k}, \ell\right)$, we have

$$
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r}(i, j, \mathcal{G}), z\right)\right| \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r},
$$

for any $z=z_{k_{0}}, z_{k_{0}+1}, \ldots, z_{k_{1}}$. Moreover, combining (16.24) and (16.28), the above holds with high probability,

$$
\begin{equation*}
\mathbb{P}\left(\cap_{k=k_{0}}^{k_{1}} \Omega^{-}\left(z_{k}, \ell\right)\right)=1-\left(k_{1}-k_{0}+1\right) o\left(N^{-\omega+1+\delta}\right)=1-o\left(N^{-\omega+4+\delta}\right) \tag{16.29}
\end{equation*}
$$

Combining with Claim 16.10, the estimate (16.29) implies

$$
\mathbb{P}\left(\cap_{k=k_{0}}^{k_{1}} \Omega^{-}\left(z_{k}, \ell_{*}\right)\right)=1-o\left(N^{-\omega+4+\delta}\right)
$$

The above argument is independent of $\theta_{0} \in \frac{\mathbb{Z}}{N^{3}} \cap(0, \pi)$. Thus, by a union bound, with probability at least $1-o\left(N^{-\omega+7+\delta}\right)$, uniformly in $z \in L$, we have

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G}), z\right)\right| \leqslant \frac{1}{2}\left|m_{s c}\right| q^{r_{*}} \tag{16.30}
\end{equation*}
$$

Since for any $z \in \mathcal{D}^{*}$, there is some $z^{\prime} \in L$ such that $\left|z-z^{\prime}\right|=(\log N)^{O(1)} / N^{3}$, the Lipschitz property of Green's function, Claim 16.9, implies that the above estimate (16.30) holds uniformly for $z \in \mathcal{D}^{*}$, with possibly a slightly larger constant:

$$
\begin{equation*}
\left|G_{i j}(z)-P_{i j}\left(\mathcal{E}_{r_{*}}(i, j, \mathcal{G}), z\right)\right| \leqslant\left|m_{s c}\right| q^{r_{*}} . \tag{16.31}
\end{equation*}
$$

This is (2.7), and thus the proof of Theorem 2.4 is complete.

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## A. Combinatorial Estimates for Random Regular Graphs

## A.1. Proof of Proposition 4.1.

Proof of (4.2). For $\omega=1$, a proof of the statement is given in [58, Lemma 2.1] or [20, Lemma 7], for example. The more general statement follows from the same proof. More precisely, in [58, (2.4)], it is shown that for any $i \in \llbracket N \rrbracket$, the excess $X_{i}$ in $\mathcal{B}_{R}(i, \mathcal{G})$ is stochastically dominated by a binomial random variable with $n=d(d-1)^{R}$ trials and success probability $p=d(d-1)^{R-1} / N$. It follows that

$$
\begin{aligned}
\mathbb{P}\left(X_{i}>\omega\right) & =O\left(\binom{d(d-1)^{R}}{\omega+1}\left(\frac{d(d-1)^{R-1}}{N}\right)^{\omega+1}\right) \\
& =O\left(N^{-\omega-1}(d-1)^{2 R(\omega+1)}\right)=O\left(N^{-\omega-1+2 \kappa(\omega+1)}\right)
\end{aligned}
$$

By a union bound, and using $\kappa<\delta /(2 \omega+2)$, therefore

$$
\mathbb{P}\left(X_{i}>\omega \text { for some } i \in \llbracket N \rrbracket\right)=O\left(N^{-\omega+2 \kappa(\omega+1)}\right)=o\left(N^{-\omega+\delta}\right),
$$

as claimed.

Proof of (4.3). The claim follows from [65, Theorem 4], for example. Indeed, if $\mathcal{B}_{R}(i, \mathcal{G})$ is not a tree, then some edge in $\mathcal{B}_{R}(i, \mathcal{G})$ must lie on a cycle of length at most $k=2 R$, and any edge that lies on such a cycle is in $\mathcal{B}_{R}(j, \mathcal{G})$ for at most $2(d-1)^{R}$ vertices $j \in \llbracket N \rrbracket$. Thus

$$
\begin{equation*}
\mid\left\{i \in \llbracket N \rrbracket: \mathcal{B}_{R}(i, \mathcal{G}) \text { is not a tree }\right\} \mid \leqslant 2(d-1)^{R} X=2 N^{\kappa} X \tag{A.1}
\end{equation*}
$$

where $X$ is the number of edges in $\mathcal{G}$ which lie on cycles of length at most $k$. With $k=2 R$ and $A \geqslant 2$ in [65, Theorem 4], we obtain

$$
\begin{equation*}
\mathbb{P}(X=M) \leqslant\left(e^{5(A-1)} A^{-5 A}\right)^{(d-1)^{k}} \leqslant e^{-c(d-1)^{k}}=e^{-c N^{2 \kappa}} \tag{A.2}
\end{equation*}
$$

if $M=20 A k(d-1)^{k}$, where $c$ is some universal constant. Let $M_{0}=40 k(d-1)^{k} \leqslant$ $80 R(d-1)^{2 R} \leqslant 80 R N^{2 \kappa}$. By a union bound, then

$$
\begin{equation*}
\mathbb{P}\left(X \geqslant M_{0}\right) \leqslant N e^{-c N^{2 \kappa}} \leqslant e^{-c N^{2 \kappa} / 2} \tag{A.3}
\end{equation*}
$$

Thus, with probability $1-e^{-c N^{2 \kappa} / 2}$, and using $\kappa<\delta /(2 \omega+2) \leqslant \delta / 4, R=\left\lfloor\kappa \log _{d-1}\right.$ $N\rfloor \ll N^{\kappa}$, we have

$$
\begin{equation*}
\mid\left\{i \in \llbracket N \rrbracket: \mathcal{B}_{R}(i, \mathcal{G}) \text { is not a tree }\right\} \mid \leqslant 2 N^{\kappa} X \leqslant 2 N^{\kappa} M_{0} \leqslant 160 R N^{3 \kappa} \leqslant N^{\delta}, \tag{A.4}
\end{equation*}
$$

which is better than claimed.

## A.2. Proof of Proposition 4.2.

Proof of (4.4). We fix vertices $i, j$ and an integer $k$. Given a graph $\mathcal{G}$, we denote by $t_{k}(\mathcal{G})$ the total number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}}(i, j)+k$. We modify the graph $\mathcal{G}$ in the three steps such that, in each step, $t_{k}$ does not decrease, and the excess remains the same. Then it suffices to prove (4.4) for the final graph.
Step 1. Given an edge $e=\{x, y\} \in \mathcal{G}$ that is not a self-loop and not on a geodesic from $i$ to $j$, we shrink the edge $e$ to a point (remove $e$ and identify its incident vertices), and so obtain a new graph $\mathcal{G}^{\prime}$. There is a bijection between the oriented edges of the graph $\mathcal{G} \backslash\{e\}$ and those of the graph $\mathcal{G}^{\prime}$.

Now we show that the total number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}}(i, j)+k=\operatorname{dist}_{\mathcal{G}^{\prime}}(i, j)+k$ in $\mathcal{G}^{\prime}$ is at least $t_{k}$. Let $\left(\boldsymbol{e}_{1}, \boldsymbol{e}_{2}, \boldsymbol{e}_{3}, \ldots\right)$ be any non-backtracking path from $i$ to $j$ in the graph $\mathcal{G}$ that is not a geodesic. If some $\boldsymbol{e}_{\beta}$ is $(x, y)$ or $(y, x)$, we remove it from the path and view the remaining part as a path from $i$ to $j$ in the graph $\mathcal{G}^{\prime}$. In this way we get a shorter path from $i$ to $j$ in $\mathcal{G}^{\prime}$. The new path is still non-backtracking, and we can recover the original path in $\mathcal{G}$ from the new path in $\mathcal{G}^{\prime}$ since $x \neq y$. Therefore, the total number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}}(i, j)+k=\operatorname{dist}_{\mathcal{G}^{\prime}}(i, j)+k$ in $\mathcal{G}^{\prime}$ is at least $t_{k}$.

We repeat this procedure with edges $e$ (not on a geodesic) chosen arbitrarily as long as possible. This creates a new graph $\mathcal{G}_{1}$ (which may depend on the choice of edges in the steps) with vertex set $\mathbb{G}_{1}$. By construction, the edges in $\mathcal{G}_{1}$ are either self-loops or on geodesics from $i$ to $j$. Thus the vertex set of $\mathcal{G}_{1}$ decomposes into

$$
\begin{equation*}
\mathbb{G}_{1}=\mathbb{V}_{0} \cup \mathbb{V}_{1} \cup \cdots \cup \mathbb{V}_{\operatorname{dist}_{\mathcal{G}_{1}}(i, j)}, \quad \text { where } \mathbb{V}_{m}:=\left\{v \in \mathbb{G}_{1}: \operatorname{dist}_{\mathcal{G}_{1}}(i, v)=m\right\} \tag{A.5}
\end{equation*}
$$

or equivalently, $\mathbb{V}_{\text {dist }_{\mathcal{G}_{1}}(i, j)-m}:=\left\{v \in \mathbb{G}_{1}: \operatorname{dist}_{\mathcal{G}_{1}}(v, j)=m\right\}$. In particular, $\mathbb{V}_{0}=\{i\}$ and $\mathbb{V}_{\text {dist }_{\mathcal{G}_{1}}(i, j)}=\{j\}$. Any edge in $\mathcal{G}_{1}$ is either a self-loop or has one vertex in $\mathbb{V}_{m}$ and the other vertex in $\mathbb{V}_{m+1}$, for some $m \in \llbracket 0$, $\operatorname{dist}_{\mathcal{G}_{1}}(i, j)-1 \rrbracket$. The excess of $\mathcal{G}_{1}$ is $\omega$.
Step 2. Given two edges $e=\left\{v_{m}, v_{m+1}\right\}$ and $e^{\prime}=\left\{v_{m}, v_{m+1}^{\prime}\right\}$ with $v_{m} \in \mathbb{V}_{m}$ and $v_{m+1} \neq v_{m+1}^{\prime} \in \mathbb{V}_{m+1}$, we remove the edge $e^{\prime}$ and identify $v_{m+1}^{\prime}$ with $v_{m+1}$, thus creating a new graph $\mathcal{G}_{1}^{\prime}$. Again there is a bijection between the oriented edges of the graph $\mathcal{G}_{1} \backslash\left\{e^{\prime}\right\}$ and those of the graph $\mathcal{G}_{1}^{\prime}$.

Now we show that the total number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}}(i, j)+k=\operatorname{dist}_{\mathcal{G}_{1}^{\prime}}(i, j)+k$ in $\mathcal{G}_{1}^{\prime}$ is at least $t_{k}$. Let $\left(\boldsymbol{e}_{1}, \boldsymbol{e}_{2}, \boldsymbol{e}_{3}, \ldots\right)$ be any nonbacktracking path from $i$ to $j$ in the graph $\mathcal{G}_{1}$. If $\boldsymbol{e}_{\beta}=\left(v_{m+1}^{\prime}, v_{m}\right)$ and $\boldsymbol{e}_{\beta+1} \neq\left(v_{m}, v_{m+1}\right)$, we replace $\boldsymbol{e}_{\beta}$ by $\left(v_{m+1}, v_{m}\right)$; if $\boldsymbol{e}_{\beta}=\left(v_{m+1}^{\prime}, v_{m}\right)$ and $\boldsymbol{e}_{\beta+1}=\left(v_{m}, v_{m+1}\right)$, we remove both $\boldsymbol{e}_{\beta}$ and $\boldsymbol{e}_{\beta+1}$; if $\boldsymbol{e}_{\beta}=\left(v_{m}, v_{m+1}^{\prime}\right)$ and $\boldsymbol{e}_{\beta-1} \neq\left(v_{m+1}, v_{m}\right)$, we replace $\boldsymbol{e}_{\beta}$ by $\left(v_{m}, v_{m+1}\right)$; if $\boldsymbol{e}_{\beta}=\left(v_{m}, v_{m+1}^{\prime}\right)$ and $\boldsymbol{e}_{\beta-1}=\left(v_{m+1}, v_{m}\right)$, we remove both $\boldsymbol{e}_{\beta}$ and $\boldsymbol{e}_{\beta-1}$. Then we view the remaining part as a path from $i$ to $j$ in the graph $\mathcal{G}_{1}^{\prime}$, whose length is at most as long as that of the original path. The new path is still non-backtracking, we can recover the original path in $\mathcal{G}_{1}$ from the new path in $\mathcal{G}_{1}^{\prime}$ since $v_{m+1} \neq v_{m+1}^{\prime}$. Therefore the total number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}}(i, j)+k=\operatorname{dist}_{\mathcal{G}_{1}^{\prime}}(i, j)+k$ in $\mathcal{G}_{1}^{\prime}$ is at least $t_{k}$.

For any $m \in \llbracket 0, \operatorname{dist}_{\mathcal{G}_{1}}(i, j)-2 \rrbracket$, if in the new $\operatorname{graph}\left|\left\{v: \operatorname{dist}_{\mathcal{G}_{1}}(i, v)=m+1\right\}\right| \geqslant 2$, we can repeat the above process to reduce it by one. We repeat this procedure as long as possible, choosing at every step edges $e$ and $e^{\prime}$ arbitrarily such that the conditions are satisfied. Finally, we obtain a graph $\mathcal{G}_{2}$ (which again is not unique) that has exactly $\operatorname{dist}_{\mathcal{G}_{2}}(i, j)+1$ vertices, $\left\{v_{0}=i, v_{1}, v_{2}, \ldots, v_{\text {dist }_{\mathcal{G}_{2}}(i, j)}=j\right\}$, such that dist $\mathcal{G}_{\mathcal{G}_{2}}\left(i, v_{m}\right)=m$ for $m \in \llbracket 0$, $\operatorname{dist}_{\mathcal{G}_{2}(i, j)} \rrbracket$. The excess of $\mathcal{G}_{2}$ is $\omega$.
Step 3. In the final step, given any edge $e$ from $v_{m}$ to $v_{m+1}$, if it is the only edge from $v_{m}$ to $v_{m+1}$, we shrink it to a point. This preserves non-backtracking paths, and it reduces the distance between $i$ and $j$ by one. By shrinking all edges of multiplicity one, we obtain a graph $\mathcal{G}_{3}$. The number of non-backtracking paths from $i$ to $j$ of length less than $\operatorname{dist}_{\mathcal{G}_{3}}(i, j)+k$ is at least $t_{k}$, and the excess of $\mathcal{G}_{3}$ is $\omega$.

Final step. To bound the number of non-backtracking paths from $i$ to $j$ in $\mathcal{G}$, it suffices to estimate the number of non-backtracking paths from $i$ to $j$ in the graph $\mathcal{G}_{3}$. Let $\ell=\operatorname{dist}_{\mathcal{G}_{3}}(i, j), s$ be the total number of self-loops in $\mathcal{G}_{3}, w_{m}+1$ the multiplicity of the edge $\left\{v_{m-1}, v_{m}\right\}$, for $m \in \llbracket 1, \ell \rrbracket$, and set $w=\max _{1 \leqslant m \leqslant \ell w_{m}}$. Since $\mathcal{G}_{3}$ has excess $\omega$, $s+\sum_{m=1}^{\ell} w_{m}=\omega$. The maximum degree of the graph $\mathcal{G}_{3}$ is bounded by $2 s+2 w+2$. Now any non-backtracking path from $i$ to $j$ of length $\ell+k$ necessarily contains the edges $\left(v_{0}, v_{1}\right),\left(v_{1}, v_{2}\right), \ldots,\left(v_{\ell-1}, v_{\ell}\right)$, and for each of them there are $w_{1}+1, w_{2}+2, \ldots, w_{\ell}+1$ choices respectively. For other steps, there are at most $2 s+1+2 w$ choices. The total number of such paths is bounded by

$$
\begin{equation*}
\binom{\ell+k}{\ell}(2 s+1+2 w)^{k} \prod_{m=1}^{\ell}\left(w_{m}+1\right) \tag{A.6}
\end{equation*}
$$

under the condition $s+\sum_{m=1}^{\ell} w_{m}=\omega$. Note that (A.6) increases if we decrease $s$ by 1 and increase some $w_{m}$ in such a way that $w$ increases by 1 . Therefore (A.6) achieves its maximum at $s=0$. We denote

$$
a_{k}:=\binom{\ell+k}{\ell}(1+2 w)^{k} \prod_{m=1}^{\ell}\left(w_{m}+1\right)
$$

Since $1+n \leqslant 2^{n}$ for any $n \in \mathbb{N}_{0}$ and $\sum_{m=1}^{\ell} w_{m}=\omega$, we then have $a_{0} \leqslant \prod_{m=1}^{\ell}\left(w_{m}+\right.$ $1) \leqslant 2^{\omega}$. For $a_{k}$ with $k \geqslant 1$, notice that $\omega=\sum_{m=1}^{\ell} w_{m} \geqslant w+(\ell-1)$ so that $w \leqslant \omega-(\ell-1)$, and thus

$$
\begin{aligned}
a_{k} \leqslant \frac{\ell+k}{k}(1+2 w) a_{k-1} & \leqslant(\ell+1)(2 \omega-2 \ell+3) a_{k-1} \\
& \leqslant \frac{(2 \omega+5)^{2}}{8} a_{k-1} \leqslant\left(2^{\omega}-1\right) a_{k-1}
\end{aligned}
$$

given that $\omega \geqslant 6$. Therefore

$$
t_{k} \leqslant a_{0}+a_{1}+\cdots+a_{k-1} \leqslant 2^{\omega}\left(1+\left(2^{\omega}-1\right)+\cdots\left(2^{\omega}-1\right)^{k-1}\right) \leqslant 2^{\omega k}
$$

This finishes the proof.
Proof of (4.5). Let $\mathbb{H}$ be the vertex set of $\mathcal{H}, \omega_{0}$ be the excess of the subgraph $\mathcal{H}$, and $\overline{\mathcal{H}}$ the subgraph induced by $\mathcal{G}$ on $\mathbb{H}$. If dist $\mathcal{G}_{\mathcal{G}}(i, j) \geqslant \ell+1$, then (4.4) implies

$$
\text { \#\{non-backtracking paths from } i \text { to } j \text { of length } \ell+k \text {, not completely in } \mathcal{H}\}
$$

$\leqslant \#\{$ non-backtracking paths from $i$ to $j$ of length $\ell+k\} \leqslant 2^{\omega k}$,
and the claim (4.5) follows. Therefore, in the following, assume that $\operatorname{dist}_{\mathcal{G}}(i, j) \leqslant \ell$, and also that $\mathcal{H}, \mathcal{G}$ are connected (otherwise, we can replace $\mathcal{H}$ by its connected component containing $i$ and $j$, and $\mathcal{G}$ by its connected component containing $\mathcal{H}$ ). For any nonbacktracking path from $i$ to $j$ which is not completely contained in $\mathcal{H}$, let $\boldsymbol{e}$ be the first edge in the path which does not belong to $\mathcal{H}$. There are three possibilities for such edge $e:$ (i) $e \in \mathcal{H}$. We denote the set of such edges by $E_{1}$. (ii) If we remove $e$ from $\mathcal{G}$, then $\mathcal{G} \backslash\{e\}$ breaks into two connected components. It is necessary that the component not containing $i, j$ contains cycles. We denote the set of such edges by $E_{2}$. (iii) $e \notin \overline{\mathcal{H}}$, and if we remove $e$ from $\mathcal{G}, \mathcal{G} \backslash\{e\}$ is still connected. We denote the set of such edges by $E_{3}$.

We consider the graph $\mathcal{G} \backslash\left\{E_{1} \cup E_{2} \cup E_{3}\right\}$, from $\mathcal{G}$ by removing edges $E_{1} \cup E_{2} \cup E_{3}$. It consists some many connected components, one corresponds to the graph $\mathcal{H}$, others are in one-to-one correspondence with the connected components of $\mathcal{G} \backslash \mathcal{H}$, the graph from removing $\mathcal{H}$ from $\mathcal{G}$. Notice from the definition of these edge sets $E_{1}, E_{2}, E_{3}$, each connected component of $\mathcal{G} \backslash \overline{\mathcal{H}}$ contains exactly one edges in $E_{2}$ or at least two edges in $E_{3}$. Therefore, $\mathcal{G} \backslash\left\{E_{1} \cup E_{2} \cup E_{3}\right\}$ has at most $1+\left|E_{2}\right|+\left|E_{3}\right| / 2$ connected components, where 1 represents the component $\mathcal{H}$. For the excess of $\mathcal{G} \backslash\left\{E_{1} \cup E_{2} \cup E_{3}\right\}$, since its subgraph $\mathcal{H}$ has excess $\omega_{0}$, and each new components, due to removing of edges in $E_{2}$, has excess at least $1, \mathcal{G} \backslash\left\{E_{1} \cup E_{2} \cup E_{3}\right\}$ has excess at least $\omega_{0}+\left|E_{2}\right|$.

## Claim A.1.

$$
\begin{equation*}
2\left|E_{1}\right|+\left|E_{2}\right|+\left|E_{3}\right| \leqslant 2\left(\omega-\omega_{0}\right) \tag{A.7}
\end{equation*}
$$

Proof. To prove (A.7), for any finite graph $\mathcal{X}$, set

$$
\begin{equation*}
\chi(\mathcal{X})=\# \operatorname{connected} \text { components }\left(\mathcal{G}_{0}\right)-\operatorname{excess}\left(\mathcal{G}_{0}\right) \tag{A.8}
\end{equation*}
$$

By the definition of excess, $\chi(\mathcal{X})=\# \operatorname{vertices}\left(\mathcal{G}_{0}\right)-\#$ edges $\left(\mathcal{G}_{0}\right)$, we have $\chi(\mathcal{X} \backslash e)=$ $\chi(\mathcal{X})+1$ for any graph $\mathcal{X}$ and any edge $e$ in $\mathcal{X}$. Since the graph $\mathcal{G}$ is connected and has excess at most $\omega$, it follows that $\chi(\mathcal{G}) \geqslant 1-\omega$. Thus if we remove $E_{1} \cup E_{2} \cup E_{3}$
from $\mathcal{G}$, the remaining graph has excess at least $\omega_{0}+\left|E_{2}\right|$ and at most $1+\left|E_{2}\right|+\left|E_{3}\right| / 2$ connected components. Therefore

$$
\begin{aligned}
1+\left|E_{2}\right|+\left|E_{3}\right| / 2-\left|E_{2}\right|-\omega_{0} & \geqslant \chi\left(\mathcal{G} \backslash\left(E_{1} \cup E_{2} \cup E_{3}\right)\right) \\
& \geqslant 1-\omega+\left|E_{1}\right|+\left|E_{2}\right|+\left|E_{3}\right|,
\end{aligned}
$$

and thus $\left|E_{1}\right|+\left|E_{2}\right|+\left|E_{3}\right| / 2 \leqslant \omega-\omega_{0}$. (A.7) follows.
In the following we count the number of length $\ell+k$ non-backtracking paths from $i$ to $j$, containing $\boldsymbol{e}=\left(i_{1}, j_{1}\right)$ as the first edge not in $\mathcal{H}$, i.e., $\left\{i_{1}, j_{1}\right\} \in E_{1} \cup E_{2} \cup E_{3}$. Let $\operatorname{dist}_{\mathcal{G}}\left(i, i_{1}\right)=\ell_{1}$ and $\operatorname{dist}_{\mathcal{G}}\left(j_{1}, j\right)=\ell_{2}$. Since $\left\{i_{1}, j_{1}\right\}$ is not in $\mathcal{H}$, it is necessary that $\ell_{1}+\ell_{2} \geqslant \ell$. Thus, $\boldsymbol{e}$ must be the $\ell_{1}+1, \ell_{1}+2, \ldots$, or $\left(\ell_{1}+k\right)$-th step in the path. The total number of such non-backtracking paths is bounded by

$$
\sum_{k_{1}=1}^{k} \#\left\{\text { non-backtracking paths from } i \text { to } i_{1} \text { of length } \ell_{1}+k_{1}-1 \text {, in } \mathcal{H}\right\}
$$

$\times \#\left\{\right.$ non-backtracking paths from $j_{1}$ to $j$ of length $\ell+k-\ell_{1}-k_{1}$, in $\left.\mathcal{G}\right\}$

$$
\leqslant \sum_{k_{1}=1}^{k} 2^{\omega_{0} k_{1}} 2^{\omega\left(k-k_{1}+1\right)} \leqslant 2^{\omega(k+1)} \sum_{k_{1}=1}^{k} 2^{\left(\omega_{0}-\omega\right) k_{1}}
$$

Since by (A.7), $2\left|E_{1}\right|+\left|E_{2}\right|+\left|E_{3}\right| \leqslant 2\left(\omega-\omega_{0}\right)$, there are at most $2\left(\omega-\omega_{0}\right)$ choices for the oriented edge $\boldsymbol{e}$, the total number of such non-backtracking paths is bounded by
\#\{non-backtracking paths from $i$ to $j$ of length $\ell+k$, not completely in $\mathcal{H}\}$

$$
\leqslant 2\left(\omega-\omega_{0}\right) 2^{\omega(k+1)} \sum_{k_{1}=1}^{k} 2^{\left(\omega_{0}-\omega\right) k_{1}} \leqslant 2^{\omega(k+1)+1}
$$

This completes the proof.
A.3. Proof of Lemma 13.4. To understand the distances $\operatorname{dist}_{\tilde{\mathcal{G}}}(x, i)$ for all $i \in \mathbb{T}_{\ell}$, we need some more notations. A simple pruning[42, Definition 4.4] is the operation of removing one leaf and its incident edge from a graph. By repeating pruning on the graph $\tilde{\mathcal{G}}_{0}$, we get a graph $\tilde{\mathcal{G}}_{2}$ with vertex set $\tilde{\mathbb{G}}_{2}$, such that it contains at most two leave vertices: 1 and $x$.

## Claim A.2.

$$
\begin{equation*}
\left|\tilde{\mathbb{G}}_{2} \cap \mathbb{T}_{k}\right| \leqslant 2 \omega+1, \quad 0 \leqslant k \leqslant \ell . \tag{A.9}
\end{equation*}
$$

Proof. For $k=0$, (A.9) holds trivially, $\left|\tilde{\mathbb{G}}_{2} \cap \mathbb{T}_{0}\right|=1 \leqslant 2 \omega+1$. For $k \geqslant 1$, say $\tilde{\mathbb{G}}_{2} \cap \mathbb{T}_{k}=$ $\left\{v_{1}, v_{2}, \ldots, v_{m}\right\}$. By our construction of $\tilde{\mathcal{G}}_{2}$, there are vertices $v_{1}^{\prime}, v_{2}^{\prime}, \ldots, v_{m}^{\prime} \in \mathbb{T}_{k-1}$ such that the edges $\left\{v_{1}^{\prime}, v_{1}\right\},\left\{v_{2}^{\prime}, v_{2}\right\}, \ldots,\left\{v_{m}^{\prime}, v_{m}\right\} \in \tilde{\mathcal{G}}_{2}$. For any $i \in \llbracket 1, m \rrbracket$, if we remove the edge $\left\{v_{i}^{\prime}, v_{i}\right\}$ from $\tilde{\mathcal{G}}_{2}$, the graph $\tilde{\mathcal{G}}_{2}$ will either still be connected; or it will break into two connected components, one contains vertex 1 , and the other contains vertex $x$ or some cycles. Let $m_{1}, m_{2}$ the number of edges in the first case and second case respectively. If we remove all edges $\left\{v_{1}^{\prime}, v_{1}\right\},\left\{v_{2}^{\prime}, v_{2}\right\}, \ldots,\left\{v_{m}^{\prime}, v_{m}\right\}$, there will be
at most $1+m_{1} / 2+m_{2}$ connected components, and at least excess $m_{2}-\mathbf{1}_{m_{2}>0}$ left. Notice that the graph $\tilde{\mathcal{G}}_{2}$ is connected and has excess at most $\omega$. Recall the function $\chi$ as in (A.8), we have

$$
\begin{aligned}
1+m_{2}+m_{1} / 2-\left(m_{2}-\mathbf{1}_{m_{2}>0}\right) & \geqslant \chi\left(\tilde{\mathcal{G}}_{2} \backslash\left\{\left\{v_{1}^{\prime}, v_{1}\right\}, \ldots,\left\{v_{m}^{\prime}, v_{m}\right\}\right\}\right) \\
& \geqslant 1-\omega+m_{1}+m_{2}
\end{aligned}
$$

Therefore $m_{1}+m_{2} \leqslant 2 \omega+1$, and the claim follows.
With the above preparations, we can prove Lemma 13.4 as follows.
Proof of Lemma 13.4. Fix a geodesic $\mathcal{P}$ (viewed as a sequence of oriented edges) in $\tilde{\mathcal{G}}_{0}$ from vertex $x$ to vertex $i \in \mathbb{T}_{\ell}$, there are three possibilities for its step $\left(v^{\prime}, v\right)$ : (i) the edge is downward, i.e. $\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)=\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}\left(1, v^{\prime}\right)+1$; (ii) the edge is horizontal, i.e. $\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)=\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}\left(1, v^{\prime}\right)$, in this case $v \in \tilde{\mathbb{G}}_{2}$; (iii) the edge is upward, i.e. $\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)=\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}\left(1, v^{\prime}\right)-1$, in this case $v \in \tilde{\mathbb{G}}_{2}$. We denote $\left(v^{\prime}, v\right)$ the last step in $\mathcal{P}$, which is horizontal or upward. Then $v \in \tilde{\mathbb{G}}_{2}$ and we say the vertex $i$ is associated with the vertex $v$ (which may not be unique). By our choice of $\left(v^{\prime}, v\right)$, the steps from $v$ to $i$ in $\mathcal{P}$ are all downward, thus $v \in \mathbb{T}$. Moreover, we have the estimate: for any vertex $i \in \mathbb{T}_{\ell}$ associated with $v$

$$
\begin{aligned}
\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(x, i) & \geqslant\left|\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, x)-\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)\right|+\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(v, i) \\
& =\left|\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, x)-\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)\right|+\left|\ell-\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(1, v)\right| .
\end{aligned}
$$

Especially, if $v \in \mathbb{T}_{\ell_{3}}$, i.e. $v$ is distance $\ell_{3}$ from vertex 1 , the above relation simplifies to

$$
\operatorname{dist}_{\tilde{\mathcal{G}}_{0}}(x, i) \geqslant\left|\ell_{1}-\ell_{3}\right|+\left(\ell-\ell_{3}\right)
$$

and by noticing $q<1$, we have

$$
q^{\text {dist }_{\tilde{\mathcal{G}}_{0}}(x, i)} \leqslant\left\{\begin{array}{cl}
q^{\ell+\ell_{1}-2 \ell_{3}}, & \text { if } \ell_{3} \leqslant \ell_{1}  \tag{A.10}\\
q^{\ell-\ell_{1}}, & \text { if } \ell_{3} \geqslant \ell_{1}
\end{array}\right.
$$

In this way, each vertex $i \in \mathbb{T}_{\ell}$ is associated with some vertex $v \in \tilde{\mathbb{G}}_{2}$. If $v \in \tilde{\mathbb{G}}_{2} \cap \mathbb{T}_{\ell_{3}}$, the total number of vertices in $\mathbb{T}_{\ell}$ associated with $v$ is at most $(d-1)^{\ell-\ell_{3}}$, since they are all distance $\ell-\ell_{3}$ away from $v$. The total number of vertices $i \in \mathbb{T}_{\ell}$ associated with some $v \in \widetilde{\mathbb{G}}_{2} \cap\left\{\mathbb{T}_{\ell_{1}} \cup \mathbb{T}_{\ell_{1}+1} \cdots \cup \mathbb{T}_{\ell}\right\}$ is bounded by $(2 \omega+1)\left(1+(d-1)+\cdots+(d-1)^{\ell_{1}}\right) \leqslant$ $2(\omega+1)(d-1)^{\ell_{1}}$, provided that $d \geqslant 2 \omega+3$. Notice that we have the decomposition

$$
\left.\begin{array}{l}
\left\{q^{\text {dist }} \tilde{\mathcal{G}}_{0}(x, i)\right. \\
\quad=\bigcup_{\ell_{3} \in \llbracket 0, \ell_{1}-1 \rrbracket}\left\{q^{\text {dist }} \tilde{\mathcal{G}}_{0}(x, i)\right. \\
\left.\quad \cup i \in \mathbb{T}_{\ell}, i \text { is associated with some } v \in \tilde{\mathbb{G}}_{2} \cap \mathbb{T}_{\ell_{3}}\right\} \\
\quad \cup\left\{q^{\text {dist }} \tilde{\mathcal{G}}_{0}(x, i)\right.
\end{array} i \in \mathbb{T}_{\ell}, i \text { is associated with some } v \in \tilde{\mathbb{G}}_{2} \cap\left\{\mathbb{T}_{\ell_{1}} \cup \mathbb{T}_{\ell_{1}+1} \cdots \cup \mathbb{T}_{\ell}\right\}\right\} .
$$

Lemma 13.4 follows by combining with (A.10) and (A.9).

## B. Properties of the Green's Functions

Throughout this paper, we repeatedly use some (well-known) identities for Green's functions, which we collect in this appendix.
B.1. Resolvent identity. The following well-known identity is referred as resolvent identity: for two invertible matrices $A$ and $B$ of the same size, we have

$$
\begin{equation*}
A^{-1}-B^{-1}=A^{-1}(B-A) B^{-1}=B^{-1}(B-A) A^{-1} \tag{B.1}
\end{equation*}
$$

B.2. Schur complement formula. Given an $N \times N$ matrix $M$ and an index set $\mathbb{T} \subset \llbracket N \rrbracket$, recall that we denote by $\left.M\right|_{\mathbb{T}}$ the $\mathbb{T} \times \mathbb{T}$-matrix obtained by restricting $M$ to $\mathbb{T}$, and that by $M^{(\mathbb{T})}=\left.M\right|_{\llbracket N \| \backslash \mathbb{T}}$ we denote the matrix obtained by removing the rows and columns with indices in $\mathbb{T}$. Thus, for any $\mathbb{T} \subset \llbracket N \rrbracket$, any symmetric matrix $H$ can be written (up to rearrangement of indices) in the block form

$$
H=\left[\begin{array}{ll}
A & B^{\prime}  \tag{B.2}\\
B & D
\end{array}\right]
$$

with $A=\left.H\right|_{\mathbb{T}}$ and $D=H^{(\mathbb{T})}$. The Schur complement formula asserts that, for any $z \in \mathbb{C}_{+}$,

$$
\begin{align*}
G & =(H-z)^{-1} \\
& =\left[\begin{array}{cc}
\left(A-B^{\prime} G^{(\mathbb{T})} B\right)^{-1} & -\left(A-B^{\prime} G^{(\mathbb{T})} B\right)^{-1} B^{\prime} G^{(\mathbb{T})} \\
-G^{(\mathbb{T})} B\left(A-B^{\prime} G^{(\mathbb{T})} B\right)^{-1} G^{(\mathbb{T})}+G^{(\mathbb{T})} B\left(A-B^{\prime} G^{(\mathbb{T})} B\right)^{-1} B^{\prime} G^{(\mathbb{T})}
\end{array}\right], \tag{B.3}
\end{align*}
$$

where $G^{(\mathbb{T})}=(D-z)^{-1}$. Throughout the paper, we often use the following special cases of (B.3):

$$
\begin{align*}
\left.G\right|_{\mathbb{T}} & =\left(A-B^{\prime} G^{(\mathbb{T})} B\right)^{-1}, \\
\left.G\right|_{\mathbb{T}^{c}}-G^{(\mathbb{T})} & =\left.\left.G\right|_{\mathbb{T}^{c} \mathbb{T}}\left(\left.G\right|_{\mathbb{T}}\right)^{-1} G\right|_{\mathbb{T}} c \\
\left.G\right|_{\mathbb{T} \mathbb{T}^{c}} & =-\left.G\right|_{\mathbb{T}} B^{\prime} G^{(\mathbb{T})}, \tag{B.4}
\end{align*}
$$

as well as the special case

$$
\begin{equation*}
G_{i j}^{(k)}=G_{i j}-\frac{G_{i k} G_{k j}}{G_{k k}} \tag{B.5}
\end{equation*}
$$

B.3. Ward identity. For any symmetric $N \times N$ matrix $H$, its Green's function $G(z)=$ $(H-z)^{-1}$ satisfies the Ward identity

$$
\begin{equation*}
\sum_{j=1}^{N}\left|G_{i j}(z)\right|^{2}=\frac{\operatorname{Im} G_{j j}(z)}{\eta} \tag{B.6}
\end{equation*}
$$

where $\eta=\operatorname{Im}[z]$. This identity follows from (B.1) with $A=H-z$ and $B=(H-z)^{*}$. In particular, (B.6) provides a bound for the sum $\sum_{j=1}^{N}\left|G_{i j}(z)\right|^{2}$ in terms of the diagonal of the Green's function. For an explanation why this algebraic identity has the interpretation of a Ward, see e.g. [73, p.147].
B.4. Covering map. For any vertex $i$, the vector $\left(G_{i 1}, G_{i 2}, G_{i 3}, \ldots\right) \in \ell^{2}(\llbracket N \rrbracket)$ is uniquely determined by the following relations:

$$
\begin{align*}
1+z G_{i i} & =\frac{1}{\sqrt{d-1}} \sum_{k: i \sim k} G_{i k} \\
z G_{i j} & =\frac{1}{\sqrt{d-1}} \sum_{k: j \sim k} G_{i k} \tag{B.7}
\end{align*}
$$

where $l \sim k$ denotes that $l$ and $k$ are adjacent in $\mathcal{G}$, i.e., that $A_{k l}=1$.
Lemma B.1. Given a covering $\pi: \tilde{\mathcal{G}} \rightarrow \mathcal{G}$ of graphs, denote the Green's function of $\tilde{\mathcal{G}}$ by $\tilde{G}$ and that of $\mathcal{G}$ by $G$. Then for all vertices $i, j$ in $\mathcal{G}$, the Green's functions obey

$$
\begin{equation*}
G_{i j}=\sum_{y: \pi(y)=j} \tilde{G}_{x y} . \tag{B.8}
\end{equation*}
$$

Proof of (B.8). We give the proof for simple graphs $\mathcal{G}, \tilde{\mathcal{G}}$. (The statement also holds for graphs with self-loops and multiple edges if $\sum_{k: i \sim k}$ is interpreted as the sum of all the oriented edges ( $i, k$ ); especially, a self-loop should be counted twice.) Clearly, $\tilde{G}$ satisfies the relations (B.7) with $G$ replaced by $\tilde{G}$. For any fixed $x \in \tilde{\mathcal{G}}$ such that $\pi(x)=i$, we can define:

$$
\begin{equation*}
G_{i j}=\sum_{y: \pi(y)=j} \tilde{G}_{x y}, \tag{B.9}
\end{equation*}
$$

if the right-hand side is summable. Assuming that for any $j$ the right-hand side of (B.9) is well defined, we verify that $\left(G_{i j}\right)_{j}$ satisfies the relation (B.7), and thus that it gives the Green's function of $H$. Indeed,

$$
\begin{aligned}
1+z G_{i i} & =1+z \sum_{y: \pi(y)=i} \tilde{G}_{x y} \\
& =1+z \tilde{G}_{x x}+z \sum_{y: \pi(y)=i, y \neq x} \tilde{G}_{x y} \\
& =\frac{1}{\sqrt{d-1}} \sum_{w: w \sim x} \tilde{G}_{x w}+\frac{1}{\sqrt{d-1}} \sum_{y: \pi(y)=i, y \neq x} \sum_{w: w \sim y} \tilde{G}_{x w} \\
& =\frac{1}{\sqrt{d-1}} \sum_{y: \pi(y)=i} \sum_{w: w \sim y} \tilde{G}_{x w} .
\end{aligned}
$$

Since there are no self-loops or multi-edges in our graph $\mathcal{G}$, for any $y_{1} \neq y_{2}$ with $\pi\left(y_{1}\right)=\pi\left(y_{2}\right)=i$ and $w_{1} \sim y_{1}$ and $w_{2} \sim y_{2}$, it is necessary that $w_{1} \neq w_{2}$. Therefore:

$$
\frac{1}{\sqrt{d-1}} \sum_{y: \pi(y)=i} \sum_{w: w \sim y} \tilde{G}_{x w}=\frac{1}{\sqrt{d-1}} \sum_{k: i \sim k} \sum_{w: \pi(w)=k} \tilde{G}_{x w}=\frac{1}{\sqrt{d-1}} \sum_{k: i \sim k} G_{i k}
$$

Similarly, for the second relation (B.7),

$$
\begin{aligned}
z G_{i j}=z \sum_{y: \pi(y)=j} \tilde{G}_{x y} & =\frac{1}{\sqrt{d-1}} \sum_{y: \pi(y)=j} \sum_{w: w \sim y} \tilde{G}_{x w} \\
& =\frac{1}{\sqrt{d-1}} \sum_{k: j \sim k} \sum_{w: \pi(w)=k} \tilde{G}_{x w}=\frac{1}{\sqrt{d-1}} \sum_{k: j \sim k} G_{i k}
\end{aligned}
$$

as needed.

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