

*Erratum*

## The Hamiltonian Operator Associated with Some Quantum Stochastic Evolutions

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It was kindly pointed out to us by W. von Waldenfels that Section 3.2 of [1] contains an error when the trace operator is introduced for functions in the Sobolev space  $H^\Sigma(\mathbb{R}_*^n; \mathfrak{H})$ : we claimed that there exists a *bounded* operator

$$\cdot|_{\{r_\ell=s\}} : H^\Sigma(\mathbb{R}_*^n; \mathfrak{H}) \rightarrow L^2(\mathbb{R}^{n-1}; \mathfrak{H})$$

which naturally defines the trace of each  $v$  in  $H^\Sigma(\mathbb{R}_*^n; \mathfrak{H})$  as a function  $v|_{\{r_\ell=s\}}$  in  $L^2(\mathbb{R}^{n-1}; \mathfrak{H})$ , but actually such trace  $v|_{\{r_\ell=s\}}$  is naturally defined only as a function in  $L^2_{\text{loc}}(\mathbb{R}^{n-1}; \mathfrak{H})$  and a trace operator from  $H^\Sigma(\mathbb{R}_*^n; \mathfrak{H})$  to  $L^2(\mathbb{R}^{n-1}; \mathfrak{H})$  can only be *closed*, with a domain to be specified.

Nevertheless the main result of [1], Theorem 3, is correct and provable through an adjustment of the argument.

We refer to [2] for a detailed introduction of the traces  $\cdot|_{\{r_\ell=s\}}$  and we list below the points which require an adjustment, that is the points involving  $\cdot|_{\{r_\ell=s\}}$  which are to be handled taking into account domain constraints.

1. The integration by parts formula (22) needs to be generalized [2] because  $\langle u|_{\partial Q_m} |v|_{\partial Q_m} \rangle_{\mathfrak{H}}$  is not necessarily in  $L^1(\partial Q_m)$  for every  $u$  and  $v$  in  $H^\Sigma(\mathbb{R}_*^n; \mathfrak{H})$ . Therefore, for  $\epsilon > 0$ , we introduce on  $\mathbb{R}^n$  the totally symmetric indicator function  $I_\epsilon(r) = \prod_{\ell < \ell'} \{1 - I_{(-\infty, 0)}(r_\ell r_{\ell'}) I_{[0, \epsilon]}(|r_\ell| + |r_{\ell'}|)\}$ , which vanishes when  $r$  has two small coordinates of opposite sign. Then  $I_\epsilon(r) \uparrow 1$  as  $\epsilon \downarrow 0$  and for every  $u$  and  $v$  in  $H^\Sigma(\mathbb{R}_*^n; \mathfrak{H})$  the following generalized integration by parts formula holds:

$$\begin{aligned} \int_{Q_m} \langle u | \sum_{\ell=1}^n \partial_\ell v \rangle_{\mathfrak{H}} &= - \int_{Q_m} \langle \sum_{\ell=1}^n \partial_\ell u | v \rangle_{\mathfrak{H}} \\ &+ \lim_{\epsilon \downarrow 0} \int_{\partial Q_m} \left( \sum_{\ell=1}^n \eta_m \cdot e_\ell \right) \langle (I_\epsilon u)|_{\partial Q_m} | (I_\epsilon v)|_{\partial Q_m} \rangle_{\mathfrak{H}}, \quad (22b) \end{aligned}$$

which reduces to (22), by dominated convergence, every time  $\langle u|_{\partial Q_m} | v|_{\partial Q_m} \rangle_{\mathfrak{H}}$  is in  $L^1(\partial Q_m)$ . This happens if  $u$  and  $v$  have traces  $u|_{\partial Q_m}$  and  $v|_{\partial Q_m}$  in  $L^2(\partial Q_m; \mathfrak{H})$ , or also if, independently of  $v$ ,  $u|_{\partial Q_m} = (I_\epsilon u)|_{\partial Q_m}$  for some  $\epsilon$ .

Analogously, for every  $u$  and  $v$  in  $H^1_{\text{symm}}((\mathbb{R}_* \times J)^n; \mathcal{H})$ , the correct version of (23) is the following generalized integration by parts formula [2]:

$$\begin{aligned} \left\langle u \left| \sum_{\ell=1}^n \partial_\ell v \right. \right\rangle_{L^2((\mathbb{R} \times J)^n; \mathcal{H})} &= - \left\langle \sum_{\ell=1}^n \partial_\ell u | v \right\rangle_{L^2((\mathbb{R} \times J)^n; \mathcal{H})} \\ &+ n \lim_{\epsilon \downarrow 0} \left\{ \langle (I_\epsilon u)|_{\{r_n=0^-\}} | (I_\epsilon v)|_{\{r_n=0^-\}} \rangle_{\mathfrak{H} \otimes L^2((\mathbb{R} \times J)^{n-1}; \mathcal{H})} \right. \\ &\left. - \langle (I_\epsilon u)|_{\{r_n=0^+\}} | (I_\epsilon v)|_{\{r_n=0^+\}} \rangle_{\mathfrak{H} \otimes L^2((\mathbb{R} \times J)^{n-1}; \mathcal{H})} \right\}. \end{aligned} \tag{23b}$$

2. The unbounded operators  $a(s)$  and their domains  $\mathcal{V}_s$  are to be defined just by Eqs. (32) and (25) of [1], which therefore imply that a vector  $\Phi$  in  $\mathcal{V}_s$  needs to have every single component  $\Phi_n$  with square integrable trace  $\langle \| \Phi_n |_{\{r_n=s\}} \| \rangle_{\mathfrak{H} \otimes L^2((\mathbb{R} \times J)^{n-1}; \mathcal{H})} < \infty \forall n$ .

3. Proposition 3 can still be proved as in [1], but domain constraints for  $a(0^-)$  and  $a(0^+)$  are to be dealt with more carefully. Clearly Eq. (36) can always be extended by linearity and it can also be extended by continuity (bounded convergence) to a vector  $\Phi$  in  $\mathcal{V}_{0^\pm}$  every time there is a sequence of vectors  $\Phi_N$  in  $\mathcal{V}_{0^\pm}$  satisfying (36) such that  $\Phi_N \rightarrow \Phi$  in  $\mathcal{K}$ ,  $E \Phi_N \rightarrow E \Phi$  in  $\mathcal{K}$  and  $a(s) \Phi_N \rightarrow a(s) \Phi$  in  $\mathfrak{H} \otimes \mathcal{K}$  for  $s = 0^-, 0^+$ . So the validity of (36) can be extended from  $\mathcal{E}(H^1(\mathbb{R}_*; \mathfrak{H}))$  to  $n$ -particle vectors in  $\text{span} \left\{ v^{\otimes n} \otimes h \mid v \in H^1(\mathbb{R}_*; \mathfrak{H}), h \in \mathcal{H} \right\}$  and then to  $n$ -particle vectors in  $H^1(\mathbb{R}_*; \mathfrak{H})^{\otimes n} \otimes \mathcal{H}$ ; thanks to Theorem 4 in [2], since the latter space includes  $\mathfrak{D}(\mathbb{R}_*^n; \mathfrak{H}^{\otimes n} \otimes \mathcal{H}) \cap L^2_{\text{symm}}((\mathbb{R} \times J)^{n-1}; \mathcal{H})$ , Eq. (36) can be extended also to all  $n$ -particle vectors belonging to  $\mathcal{V}_{0^\pm}$  and finally to all vectors in  $\mathcal{V}_{0^\pm}$ .

4. Proposition 6 can still be proved as in [1], even if only the generalized integration by parts formula (23b) is available. The integration by parts formula is applied to prove that  $U_t \Phi$  belongs to  $\mathcal{V}_{0^-}$  and with (23b) there is a limit w.r.t.  $\epsilon \downarrow 0$  which has to be commuted with the integrations in the scalar products. Such operations can be commuted if the vector  $\Upsilon$  in  $\mathcal{V}_0$  is assumed to have components  $\Upsilon_n$  vanishing in a neighborhood of all the coordinate hyperedges  $\{r_j = r_\ell = 0\}$ ,  $j \neq \ell$ . Then, thanks to Lemma 8 in [2], this class of vectors is large enough to get the thesis.

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**References**

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2. Gregoratti, M.: Traces of Sobolev functions with one square integrable directional derivative. Math. Meth. Appl. Sci. **29**, No. 2, 157–171 (2006)