Energy distribution of harmonic 1-forms and Jacobians of Riemann surfaces with a short closed geodesic

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Received: 4 April 2019 / Accepted: 8 June 2020 / Published online: 17 August 2020
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Abstract

We study the energy distribution of harmonic 1-forms on a compact hyperbolic Riemann surface S where a short closed geodesic is pinched. If the geodesic separates the surface into two parts, then the Jacobian variety of S develops into a variety that splits. If the geodesic is nonseparating then the Jacobian degenerates. The aim of this work is to get insight into this process and give estimates in terms of geometric data of both the initial surface S and the final surface, such as its injectivity radius and the lengths of geodesics that form a homology basis. The Jacobians in this paper are represented by Gram period matrices. As an invariant we introduce new families of symplectic matrices that compensate for the lack of full dimensional Gram-period matrices in the noncompact case.

Keywords Riemann surfaces · Jacobian varieties · Harmonic 1-forms · Teichmüller space

Mathematics Subject Classification 14H40 · 14H42 · 30F15 · 30F45

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1 Introduction

This paper grew out of the following question: given a compact hyperbolic Riemann surface S of genus $g \geq 2$ and a simple closed geodesic γ separating it into two parts S_1, S_2 ; if γ is fairly short, e.g. if it has length $\ell(\gamma) \leq \frac{1}{2}$, does that imply that the Jacobian of S comes close to a direct product?

We shall answer this and related questions by analyzing the energy distribution of real harmonic 1-forms on thin handles.

Energy distribution. In what follows a differential form or 1-form on a Riemann surface S (compact or not) shall always be understood to be a *real* differential 1-form. If it is harmonic we shall call it a harmonic form. Given two differential forms ω, η we denote by $\omega \wedge \eta$ the wedge product and by $\star \eta$ the Hodge star operator applied to η . The *pointwise* norm squared $\|\omega\|^2$ of ω is defined by $\|\omega\|^2 d\text{vol} = \omega \wedge \star \omega$, where $d\text{vol}$ is the volume element with respect to the hyperbolic metric of S . When necessary we write $\|\omega(p)\|^2$ to indicate that it is evaluated at point $p \in S$. The integral of an integrable function f over a domain $D \subseteq S$ shall be denoted by $\int_D f d\text{vol}$. Provided the integral exists we define the *energy* of a differential form ω over D as

$$E_D(\omega) = \int_D \|\omega\|^2 d\text{vol}. \quad (1.1)$$

When $D = S$ we write, more simply, $E_S(\omega) = E(\omega)$ and call it *the* energy of ω . We also work with the scalar product for 1-forms ω, η of class L^2 on S ,

$$\langle \omega, \eta \rangle = \int_S \omega \wedge \star \eta. \quad (1.2)$$

In this paper we make extensively use of the fact that when S is compact, then in each cohomology class of closed 1-forms on S there is a unique harmonic form and that the latter is an energy minimizer, i.e. the harmonic form is the unique element in its cohomology class that has minimal energy.

Our main technical tool will be the analysis of the energy distribution of a harmonic form in a cylinder (Sect. 3). By the Collar Lemma for hyperbolic surfaces, discussed in Sect. 2.1, any simple closed geodesic γ on S is embedded in a cylindrical neighborhood $C(\gamma)$ whose width is defined by γ , the so called standard collar. The gray shaded area in Fig. 5 is an illustration in the case where γ is separating. A first application of this analysis towards the question asked above is the following, where the constant $\mu(\gamma)$ is defined as

$$\mu(\gamma) = \exp \left(-2\pi^2 \left(\frac{1}{\ell(\gamma)} - \frac{1}{2} \right) \right). \quad (1.3)$$

Theorem 1.1 (Vanishing theorem) *Let S be a compact hyperbolic Riemann surface and let γ be a simple closed geodesic of length $\ell(\gamma) \leq \frac{1}{2}$ separating S into two parts S_1, S_2 . If σ is a nontrivial harmonic 1-form on S all of whose periods over cycles in S_2 vanish, then*

- (a) $E_{S_2}(\sigma) \leq \mu(\gamma)E(\sigma)$
- (b) $E_{S_2 \setminus C(\gamma)}(\sigma) \leq \mu^2(\gamma)E_{C(\gamma)}(\sigma)$.

In other words, if σ “lives on S_1 ” then its energy decays rapidly along $C(\gamma)$ and stays small in the rest of S_2 . The proof is given in Sect. 4. For technical reasons it is split: statement (a) appears as the first part of Theorem 4.1 and statement (b) appears as Theorem 4.2.

Jacobian and Gram period matrix. We denote by $H_1(S, \mathbb{Z})$ the first homology group and by $H^1(S, \mathbb{R})$ the vector space of all real harmonic 1-forms on S . Together with the scalar product (1.2) $H^1(S, \mathbb{R})$ is a Euclidean vector space of dimension $2g$, and $H_1(S, \mathbb{Z})$ is an Abelian group of rank $2g$.

For any homology class $[\alpha] \in H_1(S, \mathbb{Z})$ and any closed 1-form ω the *period* of ω over $[\alpha]$ is the path integral $\int_{\alpha} \omega$, defined independently of the choice of the cycle α in the homology class and we write it also in the form $\int_{\alpha} \omega = \int_{[\alpha]} \omega$. When $[\alpha]$ is the class of a simple closed curve we usually take α to be a geodesic (with respect to the hyperbolic metric on S). We call a set of $2g$ oriented simple closed geodesics

$$A = (\alpha_1, \alpha_2, \dots, \alpha_{2g-1}, \alpha_{2g})$$

a *canonical homology basis* if for $k = 1, \dots, g$, α_{2k-1} intersects α_{2k} in exactly one point, with algebraic intersection number $+1$, and if for all other couples $i < j$ one has $\alpha_i \cap \alpha_j = \emptyset$. For given A we let $(\sigma_k)_{k=1, \dots, 2g} \subset H^1(S, \mathbb{R})$ be the *dual basis of harmonic forms*

$$\int_{[\alpha_i]} \sigma_k = \delta_{ik}, \quad i, k = 1, \dots, 2g.$$

It is at the same time a basis of the lattice $\Lambda = \{n_1\sigma_1 + \dots + n_{2g}\sigma_{2g} \mid n_1, \dots, n_{2g} \in \mathbb{Z}\}$, where Λ is also defined intrinsically as the set of all $\lambda \in H^1(S, \mathbb{R})$ for which all periods are integer numbers. The quotient $J(S) = H^1(S, \mathbb{R})/\Lambda$ of the Euclidean space $H^1(S, \mathbb{R})$ by the lattice Λ is a real $2g$ -dimensional flat torus, the (real) *Jacobian variety* of the Riemann surface S (for the relation with the complex form see, e.g., [11, Chapter III]). Up to isometry, the lattice Λ is determined by the Gram matrix

$$P_S = ((\sigma_i, \sigma_j))_{i,j=1, \dots, 2g} = \left(\int_S \sigma_i \wedge \star \sigma_j \right)_{i,j=1, \dots, 2g}$$

(suppressing the mention of A). As a riemannian manifold $J(S)$ is isometric to the standard torus $\mathbb{R}^{2g}/\mathbb{Z}^{2g}$ endowed with the flat riemannian metric induced by the matrix P_S . Hence, knowing $J(S)$ is the same as knowing P_S . We call P_S the *Gram period matrix* of S with respect to A .

Going to the boundary of $\mathcal{M}_g$. Let $\mathcal{M}_g$ be the moduli space of all isometry classes of compact Riemann surfaces of genus g , $g \geq 2$ and let $\partial\mathcal{M}_g$ be its boundary in the sense of Deligne–Mumford. The members of $\partial\mathcal{M}_g$ are *Riemann surfaces with nodes* where some collars have degenerated into cusps (e.g. Bers [2]).

Several authors have studied the Jacobian under the aspect of *opening up nodes* i.e., by giving variational formulas in terms of t for the period matrix along paths F_t in $\mathcal{M}_g \cup \partial\mathcal{M}_g$ that start on the boundary, for $t = 0$, and lead inside $\mathcal{M}_g$ for $t \neq 0$; see e.g. [12, 19], [15, Appendix], [10] and, more recently, the accounts [13, 14], where one may also find additional literature.

In contrast to this, our starting point is a surface S inside $\mathcal{M}_g$, a certain distance away from the boundary. Therefore, in order to formulate an answer to the question asked above we first have to determine some element on the boundary $\partial\mathcal{M}_g$ whose (limit) Jacobian we may use for comparison. We shall apply two constructions that yield paths from S to such an element on the boundary, one uses Fenchel–Nielsen coordinates (e.g. [4, Chapter 1.7]), the other construction is grafting.

Fenchel–Nielsen construction

This way of going to the boundary seems to have been applied for the first time in [5] in connection with the small eigenvalues of the Laplace–Beltrami operator.

Fix a set of Fenchel–Nielsen coordinates corresponding to a partition of S into hyperbolic pairs of pants, where the partition is chosen such that γ is among the partitioning geodesics and $\ell(\gamma)$ is one of the coordinates. For any $t > 0$, in particular for $t \in (0, \ell(\gamma)]$, there is a Riemann surface S_t that has the same Fenchel–Nielsen coordinates as S for the same partitioning pattern, with the sole exception that the coordinate $\ell(\gamma)$ is changed to $\ell(\gamma_t) = t$. Furthermore, there is a natural marking homeomorphism $\phi_t : S \rightarrow S_t$ that sends the partitioning geodesics of S to those of S_t and preserves the twist parameters. Hence, a path $(S_t)_{t \leq \ell(\gamma)}$ in $\mathcal{M}_g$, where “ $\ell(\gamma)$ is shrinking to zero.”

If γ is a nonseparating geodesic then the limit for $t \rightarrow 0$ is a noncompact hyperbolic surface S^F of genus $g - 1$ with two cusps, and the marking homeomorphisms ϕ_t degenerate into a marking homeomorphism $\phi^F : S \setminus \gamma \rightarrow S^F$.

If γ separates S into two bordered surfaces S_1, S_2 , say of genera g_1, g_2 , then the limit is a pair of noncompact hyperbolic surfaces S_1^F, S_2^F of genera g_1, g_2 each with one cusp, and the marking homeomorphisms ϕ_t degenerate into a couple of marking homeomorphisms $\phi_i^F : S_i \setminus \gamma \rightarrow S_i^F, i = 1, 2$.

Grafting construction This is more widespread in the literature (see e.g. [16] or [9] for an account). The idea is to cut S open along γ and insert a Euclidean cylinder $[0, l] \times \gamma, l \geq 0$ with the appropriate twist parameter (details below (1.4)). The resulting family of surfaces $(S(l))_{l \geq 0}$ is a path in $\mathcal{M}_g$ that converges to a boundary point which is a surface S^G of genus $g - 1$ with two cusps if γ is nonseparating and a pair of surfaces S_1^G, S_2^G of genera g_1, g_2 each with one cusp if γ is separating. Here too we have natural marking homeomorphisms $\phi_{(l)} : S \rightarrow S(l)$ and their limits $\phi^G : S \setminus \gamma \rightarrow S^G$ respectively, $\phi_i^G : S_i \setminus \gamma \rightarrow S_i^G, i = 1, 2$.

The hyperbolic metrics in the conformal classes of S^G , respectively S_1^G, S_2^G are given by the Uniformization Theorem, but there is no explicit way known to compute them. This

Fig. 1 Starting with a surface S that has a separating simple closed geodesic γ , we approach the boundary $\partial\mathcal{M}_g$ of moduli space in two different ways

“drawback” is compensated by the better comparison with the limit Jacobians in the results below.

Figure 1 illustrates the two ways to go to the boundary in the case of a separating geodesic. The limit surfaces are depicted as noded surfaces with the two cusps pasted together at the node, i.e. along their ideal points at infinity.

Separating case. This is the context of the question asked in the beginning. We shall compare the Jacobian of S with the direct products of the Jacobians of S_1^F , S_2^F respectively, S_1^G , S_2^G in terms of Gram period matrices.

To this end we choose the homology basis $A = (\alpha_i)_{i=1,\dots,2g}$ in such a way that $\alpha_1, \dots, \alpha_{2g_1} \subset S_1$ and $\alpha_{2g_1+1}, \dots, \alpha_{2g} \subset S_2$. On S_1^F , more precisely on the one point compactification $\overline{S_1^F}$, the homology classes $[\phi_1^F \circ \alpha_i]$, $i = 1, \dots, 2g_1$ form a canonical homology basis. We let $(\sigma_i^F)_{i=1,\dots,2g_1}$ be the corresponding dual basis of harmonic forms on $\overline{S_1^F}$ and denote the associated Gram period matrix by $P_{S_1^F}$. The matrices $P_{S_2^F}$, $P_{S_1^G}$, $P_{S_2^G}$ are defined in the same way.

With this setting we have the following result, where the members in the block matrices $\begin{pmatrix} R_1 & \Omega \\ \Omega & R_2 \end{pmatrix}$ are enumerated consecutively disregarding their relative positions in the blocks, so that e.g. the first line is $r_{11}, \dots, r_{1,2g_1}, \omega_{1,2g_1+1}, \dots, \omega_{1,2g}$ and the last is $\omega_{2g,1}, \dots, \omega_{2g,2g_1}, r_{2g,2g_1+1}, \dots, r_{2g,2g}$.

Theorem 1.2 Assume that the separating geodesic γ has length $\ell(\gamma) \leq \frac{1}{2}$. Then

$$P_S = \begin{pmatrix} P_{S_1^F} & 0 \\ 0 & P_{S_2^F} \end{pmatrix} + \begin{pmatrix} R_1^F & \Omega \\ {}^t\Omega & R_2^F \end{pmatrix}, \quad P_S = \begin{pmatrix} P_{S_1^G} & 0 \\ 0 & P_{S_2^G} \end{pmatrix} + \begin{pmatrix} R_1^G & \Omega \\ {}^t\Omega & R_2^G \end{pmatrix},$$

where the remainder matrices $\Omega = (\omega_{ij})$, $R_k^F = (r_{ij}^F)$, $R_k^G = (r_{ij}^G)$ have the following bounds,

$$(i) \quad |\omega_{ij}| \leq e^{-2\pi^2(\frac{1}{\ell(\gamma)} - \frac{1}{2})} \sqrt{P_{ii}P_{jj}},$$

- (ii) $|r_{ij}^c| \leq e^{-4\pi^2(\frac{1}{\ell(\gamma)} - \frac{1}{2})} \sqrt{p_{ii} p_{jj}},$
 (iii) $|r_{ij}^f| \leq 6\ell(\gamma)^2 \sqrt{p_{ii} p_{jj}},$

and for the p_{ii}, p_{jj} we may take either, the diagonal elements of P_S or the diagonal elements of the corresponding limit matrix.

Nonseparating case. Here we adapt the homology basis $A = (\alpha_1, \dots, \alpha_{2g})$ of S to the given setting by requiring that α_2 coincides with the nonseparating geodesic γ .

The nonseparating case is quite a different world. Two complications arise from the fact that the (compactified) limit surface has genus $g - 1$ instead of g : the rank of the homology and the dimension of the Gram period matrix are not the same as for S and, in addition, the condition $\int_{[\alpha_1]} \sigma_j = 0$ for the members σ_j of the dual basis of harmonic forms disappears.

A way to overcome the first difficulty could be to find a useful concept of $2g$ by $2g$ generalized Gram period matrix that can intrinsically be attributed to the limit surface. We did not quite succeed in this. However, in Sect. 7 we shall find a substitute for the lack of such a matrix in form of a package of geometric invariants that are defined in terms of harmonic differentials. Based on this we shall define, a concept of “blown up” Gram period matrices consisting of a one parameter family of symplectic $2g$ by $2g$ matrices $P_{\mathcal{R}}(\lambda)$, $\lambda > 0$, attributable to any Riemann surface $\mathcal{R}$ of genus $g - 1$ with two cusps that is marked by the selection of a homology basis and a “twist at infinity” (Sects. 7.2 and 7.3). To formulate the main results we outline here the geometric invariants for $P_{\mathcal{R}}(\lambda)$ in the case of the grafting limit $\mathcal{R} = S^c$.

First, we describe a variant of the grafting construction better adapted to our needs. Inside the standard collar $C(\gamma)$ introduced above there is a smaller such cylindrical neighborhood $C'(\gamma)$ with boundary curves c_1, c_2 of constant distance to γ that have lengths $\ell(c_1) = \ell(c_2) = 1$. Removing $C'(\gamma)$ from S we obtain a compact surface $\mathfrak{M}$ of genus $g - 1$ with two boundary curves c_1, c_2 , the “main part” of S . The closure of the hyperbolic cylinder $C'(\gamma)$ is conformally equivalent to the Euclidean cylinder $[0, L_\gamma] \times \mathbb{S}_1$, where $\mathbb{S}_1 = \mathbb{R}/\mathbb{Z}$ is the circle of length 1 and

$$L_\gamma = \frac{\pi}{\ell(\gamma)} - \frac{2 \arcsin \ell(\gamma)}{\ell(\gamma)} \text{ with } \lim_{\ell(\gamma) \rightarrow 0} \frac{2 \arcsin \ell(\gamma)}{\ell(\gamma)} = 2 \quad (1.4)$$

(redefined in (5.4)). From the conformal point of view, S is the Riemann surface obtained out of $\mathfrak{M}$ by re-attaching $[0, L_\gamma] \times \mathbb{S}_1$. We now define S_L , for any $L > 0$, to be the Riemann surface obtained out of $\mathfrak{M}$ by attaching, in the same way, $[0, L] \times \mathbb{S}_1$ instead of $[0, L_\gamma] \times \mathbb{S}_1$. The short hand “in the same way” means that if points $p \in c_1, q \in c_2$ on the boundary of $\mathfrak{M}$ are connected by the straight line $[0, L_\gamma] \times \{y_0\}$ in $[0, L_\gamma] \times \mathbb{S}_1 \subset S$ then they are connected by the straight line $[0, L] \times \{y_0\}$ in $[0, L] \times \mathbb{S}_1 \subset S_L$.

The part $(S_L)_{L \geq L_\gamma}$ of the family of surfaces described in this way differs from the previously defined $(S(l))_{l \geq 0}$ only by an additive change of parameter. The limit surface S^c is $\mathfrak{M}$ with two copies of the infinite Euclidean cylinders $[0, \infty) \times \mathbb{S}_1$ attached (see Fig. 2).

The natural marking homeomorphism $\phi_L : S \rightarrow S_L$ is taken to be the mapping that acts as the identity from $\mathfrak{M} \subset S$ to $\mathfrak{M} \subset S_L$ and performs a linear stretch from $[0, L_\gamma] \times \mathbb{S}_1$ to $[0, L] \times \mathbb{S}_1$. In the limit, $\phi^c : S \setminus \gamma \rightarrow S^c$ is defined similarly but with the stretching of the cylinders fixed in some nonlinear way.

For any $L > 0$ the mapping ϕ_L sends the given homology basis on S to a homology basis on S_L and we have the associated Gram period matrix P_{S_L} . For S^c this is no longer fully the case and we make the following adaptations. For $j = 3, \dots, 2g$, we set $\alpha_j^c = \phi^c(\alpha_j)$. These

Fig. 2 The main part $\mathfrak{M}$ with two copies of $[0, L/2] \times \mathbb{S}_1$ attached

curves form a canonical homology basis of the compactified surface

$$\overline{S^G} = S^G \cup \{q, q'\},$$

where q, q' symbolize the two ideal points at infinity of S^G . There is the dual basis of harmonic forms $(\sigma_j^G)_{j=3, \dots, 2g}$ on $\overline{S^G}$ and we denote by

$$P_{\overline{S^G}} = \left(q_{ij}^G \right)_{i,j=3, \dots, 2g}$$

the corresponding Gram period matrix. We append two curves to the system $\alpha_3^G, \dots, \alpha_{2g}^G$, setting $\alpha_1^G = \phi^G(\alpha'_1)$, $\alpha_2^G = \phi^G(\alpha'_2)$, where α'_1 is α_1 minus the intersection point with $\gamma = \alpha_2$, and α'_2 is one of the boundary curves of $\mathfrak{M}$ oriented in such a way that it lies in the homology class of α_2 . On S^G α_2^G is a null homotopic curve and α_1^G is an arc from q to q' .

A word is to be said about the latter. In Sect. 7.2 we shall define a concept of “twist at infinity” by markings with particular classes of curves that go from cusp to cusp. From that point of view our limit surface is S^G marked with the class of α_1^G .

In addition to the curves we also append two harmonic forms τ_1^G, σ_2^G , of infinite energy, to the system $\sigma_3^G, \dots, \sigma_{2g}^G$. The first one is $\tau_1^G = df_1^G$, where f_1^G is a (real valued) harmonic function on S^G with logarithmic poles in q, q' ([11, Theorem II.4.3]). It is made unique by the condition that $\int_{\alpha_2^G} \star \tau_1^G = 1$. Since τ_1^G is exact all its periods vanish. The second form is defined by the condition that $\sigma_2^G - \star \tau_1^G$ is harmonic on $\overline{S^G}$ and that it has the periods

$$\int_{\alpha_j^G} \sigma_2^G = \delta_{2j}, \quad j = 2, \dots, 2g. \quad (1.5)$$

Even though σ_2^G is not an L^2 -form the following integrals are well defined

$$q_{2j}^G = q_{j2}^G = \int_{S^G} \sigma_2^G \wedge \star \sigma_j^G, \quad j = 3, \dots, 2g.$$

For $j = 2$ the above integral does not converge. Hence, there is no q_{22}^G . But one can define the “gist of q_{22}^G ”: since σ_2^G and $\star \tau_1^G$ have the same singularities the following quantity is well defined,

$$\pi_{22}^G = \int_{S^G} \|\sigma_2^G - \star \tau_1^G\|^2 d\text{vol}.$$

In a certain way π_{22}^G measures how much additional energy it costs for σ_2^G to satisfy the duality condition (1.5). There is also a “gist of p_{11}^G ”: if we denote, for $L > 0$, by $S_L^G \subset S^G$ the subsurface obtained out of $\mathfrak{M}$ by attaching two copies of $[0, L/2] \times \mathbb{S}_1$, then the energy $E_{S_L^G}(\tau_1^G)$ grows asymptotically like *constant* + L and we set

$$m^G = \lim_{L \rightarrow \infty} (E_{S_L^G}(\tau_1^G) - L).$$

Finally, we introduce the following limit periods, where we point out that the integral is well defined also for $j = 2$ despite the singularities of σ_2^G .

$$\kappa_j^G = - \int_{\alpha_1^G} \sigma_j^G, \quad j = 2, \dots, 2g.$$

For an overview we put the invariants together into an array.

$$\mathfrak{P}_{S^G} = \begin{pmatrix} m^G & \kappa_2^G & \kappa_3^G & \dots & \kappa_{2g}^G \\ \kappa_2^G & \pi_{22}^G & q_{23}^G & \dots & q_{2,2g}^G \\ \kappa_3^G & q_{32}^G & & & \\ \vdots & \vdots & & P_{S^G} & \\ \kappa_{2g}^G & q_{2g,2}^G & & & \end{pmatrix} \quad (1.6)$$

$\mathfrak{P}_{S^G}$ is not meant to be regarded as a matrix. However, we shall define a one parameter family of “true” matrices out of it in (1.9) and, more generally, in Sect. 7.3.

All entries of $\mathfrak{P}_{S^G}$ except m^G are defined intrinsically by the conformal structure of S^G and the given curve system $\alpha_1^G, \dots, \alpha_{2g}^G$. The entry m^G , however, makes use of the description of S^G in terms of the main part $\mathfrak{M}$ of S .

In contrast to the case of Theorem 1.2 the bounds for the error terms in the nonseparating case do not have a simple expression. We shall therefore use order notation to formulate the results. We make the following definition to indicate on what quantities the bounds depend: for real valued functions $\rho(x)$, $F(x)$, $x \in (0, +\infty)$, we say that

$$\rho(x) = \mathcal{O}_A(F(x)), \quad (1.7)$$

if $|\rho(x)| \leq c_\rho F(x)$, $x \in (0, +\infty)$, for some constant c_ρ that can be explicitly estimated in terms of g , a lower bound on $\text{sys}_\gamma(S)$ and an upper bound on the lengths $\ell(\alpha_1), \dots, \ell(\alpha_{2g})$ on S , where $\text{sys}_\gamma(S)$ is the length of the shortest simple closed geodesic on S different from γ .

For the grafting limit the result is as follows.

Theorem 1.3 *Let $p_{ij}(S_L)$ be the entries of the Gram period matrix P_{S_L} . Then for any $L \geq 4$ we have the following comparison,*

$$p_{11}(S_L) = \frac{1}{m^G + L} + \mathcal{O}_A\left(\frac{1}{L}e^{-2\pi L}\right), \quad p_{12}(S_L) = \frac{\kappa_2^G}{m^G + L} + \mathcal{O}_A\left(\frac{1}{L}e^{-\pi L}\right),$$

$$p_{1j}(S_L) = \frac{\kappa_j^G}{m^G + L} + \mathcal{O}_A\left(\frac{1}{L}e^{-2\pi L}\right), \quad j = 3, \dots, 2g,$$

$$p_{22}(S_L) = m^G + L + \pi_{22}^G + \frac{(\kappa_2^G)^2}{m^G + L} + \mathcal{O}_A\left(\frac{1}{L}e^{-\pi L}\right),$$

$$p_{ij}(S_L) = q_{ij}^G + \frac{\kappa_i^G \kappa_j^G}{m^G + L} + \mathcal{O}_A(e^{-2\pi L}), \quad i, j = 2, \dots, 2g, (i, j) \neq (2, 2).$$

For S itself in this theorem one has to take $L = L_\gamma$ with L_γ as in (1.4).

For the Fenchel–Nielsen limit the array of constants $\mathfrak{P}_{S^F}$ is similar to $\mathfrak{P}_{S^G}$ except that it shall be defined in terms of the hyperbolic metric of S^F . In analogy to (1.4) we abbreviate, for $t > 0$,

$$L_t = \frac{\pi}{t} - \frac{2 \arcsin t}{t} \text{ with } \lim_{t \rightarrow 0} \frac{2 \arcsin t}{t} = 2.$$

The result is then as follows, where for S itself one has to take $t = \ell(\gamma)$.

Theorem 1.4 *For any surface in the family $(S_t)_{t \leq \frac{1}{4}}$ of the Fenchel–Nielsen construction we have the comparison.*

$$\begin{aligned} p_{11}(S_t) &= \frac{1}{m^F + L_t} + \mathcal{O}_A(t^4), \quad p_{12}(S_t) = \frac{\kappa_2^F}{m^F + L_t} + \mathcal{O}_A(t^2) \\ p_{1j}(S_t) &= \frac{\kappa_j^F}{m^F + L_t} + \mathcal{O}_A(t^3), \quad j = 3, \dots, 2g, \\ p_{22}(S_t) &= m^F + L_t + \pi_{22}^F + \frac{(\kappa_2^F)^2}{m^F + L_t} + \mathcal{O}_A(t^2), \\ p_{ij}(S_t) &= q_{ij}^F + \frac{\kappa_i^F \kappa_j^F}{m^F + L_t} + \mathcal{O}_A(t^2), \quad i, j = 2, \dots, 2g, (i, j) \neq (2, 2). \end{aligned}$$

In Theorem 1.3 all occurrences of L are in the combined form $m^G + L$ (and a similar remark holds for Theorem 1.4). This observation suggests to translate the array $\mathfrak{P}_{S^G}$ in (1.6) (and in a similar way $\mathfrak{P}_{S^F}$) into a parametrized family of matrices $P_{S^G}(\lambda)$, $\lambda \in (0, +\infty)$, that may be regarded as a substitute for the missing Gram period matrix for S^G .

For the translation we regard the constants q_{ij}^G as constant functions $q_{ij}^G(\lambda) = q_{ij}^G$, $i, j = 2, \dots, 2g$, $(i, j) \neq (2, 2)$; then define $q_{22}^G(\lambda) = \pi_{22}^G + \lambda$; and, for completion, $q_{1j}^G(\lambda) = q_{j1}^G(\lambda) = 0$, $j = 1, \dots, 2g$. We also complete the list $\kappa_2^G, \dots, \kappa_{2g}^G$ setting $\kappa_1^G = 1$. The definition then is

$$P_{S^G}(\lambda) = (q_{ij}^G(\lambda))_{i,j=1,\dots,2g} + \left(\frac{\kappa_i^G \kappa_j^G}{\lambda} \right)_{i,j=1,\dots,2g} \quad (1.8)$$

Theorem 1.3 now states that

$$P_{S_L} = P_{S^G}(m^G + L) + \rho^G(L), \quad (1.9)$$

with the bounds for the entries of $\rho^G(L)$ as given. There is a similar expression for Theorem 1.4.

We shall prove in Corollary 7.11 that the $P_{S^G}(\lambda)$ are symplectic matrices. We do not know, however, whether or not they are Gram period matrices of compact Riemann surfaces.

The paper is divided into seven parts: Sect. 1 is the introduction. In Sect. 2 we construct mappings used to embed Riemann surfaces with a small geodesic into the limit surfaces with cusps obtained by the Fenchel–Nielsen construction. These mappings shall be used to compare the energies of corresponding harmonic forms with each other. In Sect. 3 we give decay and dampening down estimates for harmonic forms on flat cylinders. These are later used to provide the exponential decay estimates given in Theorem 1.1–1.3. Section 4

treats the case where the shrinking curve γ is separating and Sects. 5–7 the case where γ is nonseparating. Theorems 1.3 and 1.4 are proven as Theorems 7.10 and 7.12 in Sect. 7.4.

At various places we estimate energies of harmonic forms via test forms and then simplify the results “by elementary considerations”. For the latter it is—and was—helpful to use a computer algebra system.

2 Mappings for degenerating Riemann surfaces

In this section we construct mappings used to embed Riemann surfaces with a small geodesic into the limit surfaces with cusps obtained by the Fenchel–Nielsen construction. These mappings shall be used to compare the energies of corresponding harmonic forms with each other.

2.1 Collars and cusps

We first collect a number of facts about collars and cusps that follow from the so-called *Collar Theorem*. For proofs we refer e.g. to [4, Chapter 4]. In the present section S is a surface of signature $(g, m; n)$ with a metrically complete hyperbolic metric for which the m boundary components are simple closed geodesics and the n punctures are cusps. We assume, furthermore, that $2g + m + n \geq 3$.

For any simple closed geodesic γ on S (on the boundary or in the interior) the *standard collar* $C(\gamma)$ is defined as the neighborhood

$$C(\gamma) := \{p \in S \mid \text{dist}(p, \gamma) < \text{cl}(\ell(\gamma))\}, \quad \text{where} \quad (2.1)$$

$$\text{cl}(s) := \text{arcsinh} \left(\frac{1}{\sinh(\frac{s}{2})} \right) > \ln \left(\frac{4}{s} \right). \quad (2.2)$$

By the Collar Theorem $C(\gamma)$ is an embedded cylinder; moreover, the geodesic arcs of length $\text{cl}(\gamma)$ emanating perpendicularly from γ are pairwise disjoint (except for the common initial points of pairs of opposite arcs). This allows us to use *Fermi coordinates* for points in $C(\gamma)$ by taking γ as base curve, parametrized in the form $t \mapsto \gamma(t)$, $t \in [0, 1]$, with constant speed $\ell(\gamma)$. The parameter t will also be interpreted as running through $\mathbb{S}_1$, where we set

$$\mathbb{S}_1 := \mathbb{R}/\mathbb{Z}. \quad (2.3)$$

For any $p \in C(\gamma)$ we then have Fermi coordinates (ρ, t) defined so that $|\rho|$ is the distance from p to γ and p lies on the orthogonal geodesic through $\gamma(t)$. If γ lies in the interior of S then all ρ have negative signs on one side of γ and positive signs on the other. For the case where γ is a boundary geodesic, we adopt the *convention* that all ρ shall be nonpositive. The metric tensor in these coordinates is

$$g_C = d\rho^2 + \ell(\gamma)^2 \cosh^2(\rho) dt^2. \quad (2.4)$$

Hence, if γ lies in the interior of S then $C(\gamma)$ is isometric to the cylinder

$$(-\text{cl}(\ell(\gamma)), \text{cl}(\ell(\gamma))) \times \mathbb{S}_1 \quad (2.5)$$

endowed with the metric tensor (2.4). If γ is a boundary geodesic then $C(\gamma)$ is isometric to $(-\text{cl}(\ell(\gamma)), 0] \times \mathbb{S}_1$ endowed with this metric. In this latter case we also call $C(\gamma)$ a *half collar*.

In a similar way, also by the collar theorem, there exists for any puncture q (to be understood as an isolated ideal boundary point at infinity) an open neighborhood $V(q)$ that is isometric to the cylinder

$$(-\ln(2), +\infty) \times \mathbb{S}_1 \quad (2.6)$$

endowed with the metric tensor

$$g_V = dr^2 + e^{-2r} dt^2. \quad (2.7)$$

Under this isometry any curve $\{r\} \times \mathbb{S}_1$, for $r \in (-\ln(2), +\infty)$, corresponds to a horocycle η_λ of length $\lambda = e^{-r}$ on $V(q)$ and the couples (r, t) are Fermi coordinates for points in $V(q)$ based on the curve η_1 .

We shall also look at parts of cusps: for $a > b \geq 0$ the *truncated cusp* V_a^b is defined as the annular region

$$V_a^b := \{p \in V(q) \mid p \text{ lies between } \eta_a \text{ and } \eta_b\}, \quad (2.8)$$

where ‘between’ shall allow that p lies on η_a , or η_b . When $b = 0$ the truncated cusp becomes a punctured disk and we denote it by V_a .

Finally, the collar theorem further states that all cusps are pairwise disjoint, no cusp intersects a collar, and collars belonging to disjoint simple closed geodesics are disjoint.

2.2 Conformal mappings of collars and cusps

We shall make use of the standard conformal mappings ψ_γ, ψ_q that map collars and cusps into the flat cylinder

$$Z = (-\infty, +\infty) \times \mathbb{S}_1, \quad \text{with the Euclidean metric } g_E = dx^2 + dy^2, \quad (2.9)$$

where we use (x, y) as coordinates for points in Z with $x \in (-\infty, +\infty)$, $y \in \mathbb{S}_1 = \mathbb{R}/\mathbb{Z}$, and y is treated as a real variable. It is straightforward to check that for any simple closed geodesic γ on S the mapping $\psi_\gamma : C(\gamma) \rightarrow Z$ defined in Fermi coordinates by

$$\psi_\gamma(\rho, t) = (F_\gamma(\rho), t) \quad (2.10)$$

with

$$\begin{aligned} F_\gamma(\rho) &= \frac{2}{\ell(\gamma)} \arctan \left(\tanh \left(\frac{\rho}{2} \right) \right) = \text{sign}(\rho) \frac{1}{\ell(\gamma)} \arccos \left(\frac{1}{\cosh(\rho)} \right) \\ &= \text{sign}(\rho) \frac{1}{\ell(\gamma)} \left\{ \frac{\pi}{2} - \arcsin \left(\frac{1}{\cosh(\rho)} \right) \right\} \end{aligned} \quad (2.11)$$

is conformal. Similarly, for any cusp $V(q)$ we have a conformal mapping $\psi_q : V(q) \rightarrow Z$ defined in Fermi coordinates by

$$\psi_q(r, t) = (e^r, t). \quad (2.12)$$

For later use we note that by (2.1), (2.2), (2.11) ψ_γ maps $C(\gamma)$ onto $(-M, M) \times \mathbb{S}_1$, where $M = M(\ell(\gamma))$ satisfies

$$M(\ell(\gamma)) = \frac{1}{\ell(\gamma)} \left\{ \frac{\pi}{2} - \arcsin \left(\tanh \left(\frac{\ell(\gamma)}{2} \right) \right) \right\} \geq \frac{\pi}{2\ell(\gamma)} - \frac{1}{2}, \quad (2.13)$$

and the inequality follows from elementary consideration. (M is not the same as L_γ defined in (1.4) and later used in (5.4).) In the next section we shall combine ψ_γ with ψ_q^{-1} to conformally map half collars into cusps.

2.3 Mappings of Y-pieces

The results of this section are presented in [3]. We summarize them for convenience and slightly extend them for the present needs. A *Y-piece* or *hyperbolic pair of pants* is a surface as in the preceding section that has signature $(0, 3; 0)$. To include limit cases we shall also admit signatures $(0, 2; 1)$ and $(0, 1; 2)$.

We denote by $Y = Y_{l_1, l_2, l_3}$ the Y-piece with boundary geodesics $\gamma_1, \gamma_2, \gamma_3$ of lengths $\ell(\gamma_i) = l_i$, for $i \in \{1, 2, 3\}$. For any pair γ_{i-1}, γ_i , $i = 1, 2, 3$, (indices $\mod 3$) there is a unique connecting geodesic arc a_i orthogonal to γ_{i-1} and γ_i at its end points. These arcs are called the *common perpendiculars* or *orthogeodesics* of Y . They decompose Y into two identical right angled geodesic hexagons, and there is an orientation reversing isometry $\sigma_Y : Y \rightarrow Y$, the *natural symmetry* of Y , that keeps the orthogeodesics pointwise fixed.

The boundary geodesics are parametrized with constant speed $\gamma_i : [0, 1] \rightarrow \partial Y$, with positive boundary orientation (with respect to a fixed orientation on Y) and such that $\gamma_i(0)$ coincides with the endpoint of a_i (see Fig. 3). We call this the *standard parametrization*. By the aforementioned collar theorem the sets

$$C_i = \{p \in Y \mid \text{dist}(p, \gamma_i) < \text{cl}(\ell(\gamma_i))\}$$

are pairwise disjoint embedded cylinders. Moreover, for $0 \leq \rho \leq \text{cl}(\ell(\gamma_i))$ the equidistant curves

$$\gamma_i^\rho = \{p \in Y \mid \text{dist}(p, \gamma_i) = \rho\}$$

are embedded circles. We parametrize them with constant speed in the form $\gamma_i^\rho : [0, 1] \rightarrow Y_{l_1, l_2, l_3}$, such that there is an orthogonal geodesic arc of length ρ from $\gamma_i(t)$ to $\gamma_i^\rho(t)$, $t \in [0, 1]$. This too shall be called a *standard parametrization*.

We extend these conventions to degenerated Y-pieces with cusps writing symbolically ' $\ell(\gamma_i) = 0$ ', if the i -th end is a puncture. In this case the equidistant curves are horocycles and the collar C_i is isometric to a cusp whose boundary length is equal to 2.

We also consider *restricted Y-pieces*, where parts of the collars have been cut off: Take Y_{l_1, l_2, l_3} . Select in each C_i an equidistant curve $\beta_i = \gamma_i^{\rho_i}$ (respectively, a horocycle if C_i is a cusp) of some length λ_i , possibly $\beta_i = \gamma_i$, and cut away the outer part of the collar along this curve. The thus *restricted Y-piece*, $Y_{l_1, l_2, l_3}^{\lambda_1, \lambda_2, \lambda_3}$, is the closure of the connected component of $Y_{l_1, l_2, l_3} \setminus \{\beta_1, \beta_2, \beta_3\}$ that has signature $(0, 3; 0)$.

Our mappings shall have the following two properties. A homeomorphism

$$\phi : Y \rightarrow Y'$$

of, possibly restricted, Y-pieces is called *boundary coherent* if for corresponding boundary curves β_i of Y and β'_i of Y' in standard parametrization one has $\phi(\beta_i(t)) = \beta'_i(t)$, $t \in [0, 1]$. The mapping ϕ is called *symmetric* if it is compatible with the natural symmetries, i.e. if $\phi \circ \sigma_Y = \sigma_{Y'} \circ \phi$. Since the fixed point sets of σ_Y and $\sigma_{Y'}$ are the orthogeodesics it follows, in particular, that a symmetric ϕ sends orthogeodesics to orthogeodesics.

We need, in particular, the following restriction of Y-pieces. Assume first that for some $i \in \{1, 2, 3\}$ we have $0 < \ell(\gamma_i) = \epsilon < 2$. Then we define the *reduced collar*

$$\widehat{C}_i = \{p \in Y \mid \text{dist}(p, \gamma_i) < \widehat{w}(\epsilon)\},$$

where, using (2.2),

$$\widehat{w}(\epsilon) := \log\left(\frac{2}{\epsilon}\right) < \text{cl}(\epsilon) - \log 2. \quad (2.14)$$

Fig. 3 $Y_{l_1, l_2, \epsilon}$ is quasi-conformally embedded into the Y-piece $Y_{l_1, l_2, 0}$ with a cusp. The image of γ_3 is the horocycle $h_{\hat{\epsilon}}$ of length $\hat{\epsilon}$

The inner boundary curve of $\widehat{C}_i$ has length

$$\epsilon \cosh(\widehat{w}(\epsilon)) = 1 + \frac{\epsilon^2}{4}. \quad (2.15)$$

By (2.14) we have $\widehat{C}_i \subset C_i$. For convenient notation we complete the definition by setting $\widehat{C}_i = \emptyset$ if $\ell(\gamma_i) \geq 2$.

We now extend the definition of $\widehat{C}_i$ to the case where γ_i is a puncture. In this case $\widehat{C}_i$ is defined as the subset of all points in the cusp C_i that lie outside the horocycle of length 1. With this set up we define, for all cases, the *reduced* Y-piece as

$$\widehat{Y} = Y \setminus (\widehat{C}_1 \cup \widehat{C}_2 \cup \widehat{C}_3).$$

We are ready to introduce the mappings. Let us first consider the case of a Y-piece where “one boundary geodesic is shrinking”, i.e. where $l_1, l_2 \geq 0$, and $l_3 = \epsilon > 0$ with ϵ small. In [3, Theorem 5.1], it is shown that there exists a symmetric boundary coherent quasiconformal homeomorphism $\phi : \widehat{Y}_{l_1, l_2, \epsilon} \rightarrow \widehat{Y}_{l_1, l_2, 0}$ of dilatation $\leq 1 + 2\epsilon^2$. We extend ϕ to all of Y by letting it be an isometry on $\widehat{C}_1, \widehat{C}_2$ and a conformal mapping on $\widehat{C}_3$. To compute the image set we use the preceding section: the mapping ψ_γ as in (2.10) with $\gamma = \gamma_3$ maps the closure of $\widehat{C}_3$ conformally to the flat cylinder $[-\widehat{M}, 0] \times \mathbb{S}_1$, where by (2.11) and (2.15)

$$\widehat{M} = F_{\gamma_3}(\widehat{w}(\epsilon)) = \frac{1}{\epsilon} \left(\frac{\pi}{2} - \arcsin \left(\frac{\epsilon}{1 + \frac{\epsilon^2}{4}} \right) \right) > \frac{\pi}{2\epsilon} - 1, \quad \text{for } 0 < \epsilon \leq 2, \quad (2.16)$$

and the inequality follows from elementary consideration. We then shift the cylinder forward to $[1, \widehat{M} + 1] \times \mathbb{S}_1$ and apply the inverse of the conformal mapping ψ_q defined in (2.12), where q is the corresponding puncture of $Y_{l_1, l_2, 0}$. The combination of the three mappings is our extension of ϕ to $\widehat{C}_3$. From the above expression for $\widehat{M}$ and the form of the metric tensor in (2.7) it follows that

$$\phi(\widehat{C}_3) = V_1^{\hat{\epsilon}} \quad \text{with} \quad \hat{\epsilon} := \frac{1}{\widehat{M} + 1}. \quad (2.17)$$

In particular, the boundary geodesic γ_3 of length ϵ goes to the horocycle $h_{\hat{\epsilon}}$ of length $\hat{\epsilon}$, where asymptotically $\hat{\epsilon} \sim \frac{2}{\pi}\epsilon$, as $\epsilon \rightarrow 0$.

With ϕ thus extended we have the following variant of Theorem 5.1 in [3]:

Theorem 2.1 Let $0 \leq l_1, l_2$, $0 < \epsilon \leq \frac{1}{2}$, and define $\hat{\epsilon}$ as in (2.17). Then there exists a symmetric boundary coherent quasi-conformal homeomorphism

$$\phi_Y : Y_{l_1, l_2, \epsilon} \rightarrow Y_{l_1, l_2, 0}^{\hat{\epsilon}}$$

with dilatation $q_{\phi_Y} \leq 1 + 2\epsilon^2$ and the property that the restriction of ϕ_Y to $\widehat{C}_i$ is an isometry for $i = 1, 2$, and a conformal mapping for $i = 3$.

The theorem is illustrated in Fig. 3. Note that the bound is independent of l_1 and l_2 . Applying the theorem twice we also have the following:

Theorem 2.2 Let $0 \leq l_1$, $0 < \epsilon_2, \epsilon_3 \leq \frac{1}{2}$, and define $\hat{\epsilon}_2, \hat{\epsilon}_3$ as in (2.17). Then there exists a symmetric boundary coherent quasi-conformal homeomorphism

$$\psi_Y : Y_{l_1, \epsilon_2, \epsilon_3} \rightarrow Y_{l_1, 0, 0}^{\hat{\epsilon}_2, \hat{\epsilon}_3}$$

with dilatation $q_{\psi_Y} \leq (1 + 2\epsilon_2^2)(1 + 2\epsilon_3^2)$ and the property that the restriction of ψ_Y to $\widehat{C}_i$ is an isometry for $i = 1$, and a conformal mapping for $i = 2, 3$.

2.4 Mappings between S^F and S^G

We extend the mappings of the preceding paragraph to quasi conformal mappings between S^F and S^G . For future reference the setting is slightly more general. The term *marking preserving* in the next theorem is explained in the proof.

Theorem 2.3 Let R be a hyperbolic surface of signature $(g, m; n)$ and assume that for some positive integer $l \leq m$ and some $\epsilon \in (0, \frac{1}{2}]$, the boundary geodesics $\gamma_1, \dots, \gamma_l$ satisfy

$$\ell(\gamma_1), \dots, \ell(\gamma_l) \leq \epsilon.$$

Let R^G be obtained by attaching flat cylinders $[0, \infty) \times \gamma_i$ to γ_i for $i = 1, \dots, l$, and let R^F be obtained by choosing a partition of R and shrinking $\gamma_1, \dots, \gamma_l$ to zero while keeping the remaining Fenchel–Nielsen parameters fixed. Then there exists a marking preserving quasi-conformal homeomorphism

$$\psi : R^G \rightarrow R^F$$

with dilatation $q_\psi \leq (1 + 2\epsilon^2)^2$ that, moreover, embeds the cylinders $[0, \infty) \times \gamma_i$ conformally into R^F for $i = 1, \dots, l$.

Proof By construction, we may label the Y-pieces of R and R^F and the geodesics along which they are pasted together in the form $Y_1, \dots, Y_q$ and $\gamma_{m+1}, \dots, \gamma_{m+p}$ respectively, $Y'_1, \dots, Y'_q$ and $\gamma'_{m+1}, \dots, \gamma'_{m+p}$ (with $p = 3g - 3 + m + n$, $q = 2g - 2 + m + n$) in such a way that, whenever Y_i is pasted to Y_j along γ_k with some twist parameter ϑ_k , then Y'_i is pasted to Y'_j along γ'_k with twist parameter ϑ_k .

There exists then, in the same way as in Sect. 1, a marking homeomorphism $\phi^F : R \rightarrow R^F$ that sends the Y_j to the corresponding Y'_j , $j = 1, \dots, q$, and preserves the twist parameters. (This is also a marking homeomorphism in the sense of Teichmüller theory with R understood as base surface, e.g. [4, Section 6.1].) There is a similar marking homeomorphism $\phi^G : R \rightarrow R^G$ and we shall say that a homeomorphism $\varphi : R^G \rightarrow R^F$ is *marking preserving* if the mappings $\varphi \circ \phi^G$ and ϕ^F are isotopic.

Now, if, for a given i , the boundary geodesics of Y_i are distinct from $\gamma_1, \dots, \gamma_l$, then there exists an isometry $\psi_{Y_i} : Y_i \rightarrow Y'_i$ that preserves the labelling of the boundary geodesics. If,

on the other hand, some of the boundary geodesics of Y_i are amongst $\gamma_1, \dots, \gamma_l$, then, by Theorems 2.1 and 2.2, there exists a symmetric boundary coherent quasi-conformal embedding $\psi_{Y_i} : Y_i \rightarrow Y'_i$ that preserves the labelling of the interior geodesics and has dilatation $q_{\psi_{Y_i}} \leq (1 + 2\epsilon^2)^2$. Since the mappings ψ_{Y_i} , for $i = 1, \dots, q$, are boundary coherent, and since the twist parameters for the pastings in R are the same as those for the corresponding pastings in R^F , it follows that the ψ_{Y_i} match along the boundaries and together define a quasi-conformal embedding $\psi : R \rightarrow R^F$ with dilatation $q_\psi \leq (1 + 2\epsilon^2)^2$.

The mapping ψ sends $\gamma_1, \dots, \gamma_l$ to horocycles in the cusps of R^F and, again by boundary coherence, match with the conformal mappings between the attached cylinders and the outer parts of the horocycles. We may thus extend ψ to a $(1 + 2\epsilon^2)^2$ -quasi conformal homeomorphism $\psi : R^G \rightarrow R^F$ that acts conformally on the cylinders $[0, \infty) \times \gamma_i$. Furthermore the so extended ψ sends the orthogeodesics of the pairs of pants of the partition of R^G to the orthogeodesics of the pairs of pants of the partition of R^F and is thus marking preserving. $\square$

3 Harmonic forms on a cylinder

In this section we give decay and dampening down estimates for harmonic forms on the flat cylinder $Z = (-\infty, +\infty) \times \mathbb{S}_1$ (c.f. (2.9)), where $\mathbb{S}_1 = \mathbb{R}/\mathbb{Z}$.

We use (x, y) as coordinates for points in Z with $x \in (-\infty, +\infty)$ and $y \in \mathbb{S}_1$, where y is treated as a real variable. Any real harmonic function $h(x, y)$ on Z may be written as a series

$$\begin{aligned} h(x, y) = & a_0 + b_0x \\ & + \sum_{n=1}^{\infty} (a_n \cos(2\pi ny) + b_n \sin(2\pi ny)) e^{-2\pi nx} \\ & + \sum_{n=1}^{\infty} (c_n \cos(2\pi ny) + d_n \sin(2\pi ny)) e^{2\pi nx} \end{aligned} \quad (3.1)$$

(e.g. [1, p. 253]) via the conformal mapping $(x, y) \rightarrow \exp(2\pi(x + iy))$. We decompose $h(x, y)$ into

$$h(x, y) = a_0 + b_0x + h^{\text{nl}}(x, y), \quad h^{\text{nl}}(x, y) = h^-(x, y) + h^+(x, y), \quad (3.2)$$

where h^- is the first sum in (3.1) and h^+ the second. We call $a_0 + b_0x$ the *linear part* of h and $h^{\text{nl}} = h^- + h^+$ the *nonlinear part*. The differential of h is given by

$$dh(x, y) = A(x, y)dx + B(x, y)dy$$

with

$$\begin{aligned} A(x, y) = & b_0 + 2\pi \sum_{n=1}^{\infty} n(-a_n \cos(2\pi ny) - b_n \sin(2\pi ny)) e^{-2\pi nx} \\ & + 2\pi \sum_{n=1}^{\infty} n(c_n \cos(2\pi ny) + d_n \sin(2\pi ny)) e^{2\pi nx} \\ B(x, y) = & 2\pi \sum_{n=1}^{\infty} n(-a_n \sin(2\pi ny) + b_n \cos(2\pi ny)) e^{-2\pi nx} \end{aligned}$$

$$+ 2\pi \sum_{n=1}^{\infty} n(-c_n \sin(2\pi ny) + d_n \cos(2\pi ny))e^{2\pi nx}.$$

Its pointwise squared norm is

$$\|dh(x, y)\|^2 = A^2(x, y) + B^2(x, y).$$

Integrating $\|dh(x, y)\|^2$ over $\mathbb{S}_1$ we obtain

$$\begin{aligned} \int_0^1 \|dh(x, y)\|^2 dy &= b_0^2 + 4\pi^2 \sum_{n=1}^{\infty} n^2 (a_n^2 + b_n^2) e^{-4\pi nx} + 4\pi^2 \sum_{n=1}^{\infty} n^2 (c_n^2 + d_n^2) e^{4\pi nx} \\ &= b_0^2 + \int_0^1 \|dh^-(x, y)\|^2 dy + \int_0^1 \|dh^+(x, y)\|^2 dy. \end{aligned} \quad (3.3)$$

We now prove the following pointwise and L^2 -decay estimates that shall be used at various places. (“ $d\text{vol}$ ” below is the volume element with respect to the flat metric of Z .)

Lemma 3.1 Assume $l > 0$ and let Z_l be the subset $Z_l = [-l, l] \times \mathbb{S}_1$ of Z . For $\delta_L, \delta_R \geq 0$ with $\delta_L + \delta_R < 2l$, set

$$D_L = \{(x, y) \in Z_l \mid -l \leq x \leq -l + \delta_L\}, \quad D_R = \{(x, y) \in Z_l \mid l - \delta_R \leq x \leq l\} \text{ and} \\ D_{\text{int}} = Z_l \setminus \{D_L \cup D_R\} \text{ (see Fig. 4)}.$$

Then for any harmonic function h on Z_l with nonlinear part $h^- + h^+$ as in (3.1), (3.2) we have

- (i) $E_{D_{\text{int}}}(dh^- + dh^+) = E_{D_{\text{int}}}(dh^-) + E_{D_{\text{int}}}(dh^+).$
- (ii) $8\pi^2 \int_{D_{\text{int}}} |h^-|^2 d\text{vol} \leq E_{D_{\text{int}}}(dh^-) \leq e^{-4\pi\delta_L} E_{Z_l}(dh^-).$
- (iii) $8\pi^2 \int_{D_{\text{int}}} |h^+|^2 d\text{vol} \leq E_{D_{\text{int}}}(dh^+) \leq e^{-4\pi\delta_R} E_{Z_l}(dh^+).$
- (iv) $4\pi^2 \int_{D_{\text{int}}} |h^{nl}|^2 d\text{vol} \leq E_{D_{\text{int}}}(dh^{nl}) \leq e^{-4\pi\delta} E_{Z_l}(dh^{nl}), \quad \delta := \min\{\delta_L, \delta_R\}.$
- (v) If $l \geq 1$ and $\delta_L \geq \frac{1}{2}$ then, for any $(x, y) \in D_{\text{int}},$

$$|h^-(x, y)|^2 < e^{-4\pi(x+l)} E_{Z_l}(dh^-), \quad \|dh^-(x, y)\|^2 < 52 e^{-4\pi(x+l)} E_{Z_l}(dh^-).$$

- (vi) If $l \geq 1$ and $\delta_R \geq \frac{1}{2}$ then, for any $(x, y) \in D_{\text{int}},$

$$|h^+(x, y)|^2 < e^{-4\pi(l-x)} E_{Z_l}(dh^+), \quad \|dh^+(x, y)\|^2 < 52 e^{-4\pi(l-x)} E_{Z_l}(dh^+).$$

- (vii) If $l \geq 1$ and $\delta := \min\{\delta_L, \delta_R\} \geq \frac{1}{2}$, then for any $(x, y) \in D_{\text{int}},$

$$|h^{nl}(x, y)|^2 < 2 e^{-4\pi\delta} E_{Z_l}(dh^{nl}), \quad \|dh^{nl}(x, y)\|^2 < 104 e^{-4\pi\delta} E_{Z_l}(dh^{nl}).$$

Proof Statement (i) is an immediate consequence of (3.3). Furthermore, (3.3) applied to h^- and integration over $[-l, l]$ yields

$$E_{Z_l}(dh^-) = \pi \sum_{n=1}^{\infty} n(a_n^2 + b_n^2) (e^{4\pi nl} - e^{-4\pi nl}). \quad (3.4)$$

Similarly,

$$E_{D_{\text{int}}}(dh^-) = \pi \sum_{n=1}^{\infty} n(a_n^2 + b_n^2) (e^{4\pi n(l-\delta_L)} - e^{-4\pi n(l-\delta_R)}). \quad (3.5)$$

Fig. 4 The Euclidean cylinder Z_l with ends D_L and D_R

From this and observing that

$$e^{4\pi n(l-\delta_L)} - e^{-4\pi n(l-\delta_R)} \leq e^{4\pi n(l-\delta_L)} - e^{-4\pi nl} \leq e^{-4\pi n\delta_L}(e^{4\pi nl} - e^{-4\pi nl})$$

we get the second inequality in (ii). Integrating $|h^-(x, y)|^2$ and $\|dh^-(x, y)\|^2$ over $\mathbb{S}_1$ we obtain in a similar fashion as in (3.3):

$$\int_0^1 |h^-(x, y)|^2 dy = \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2) e^{-4\pi nx}, \quad \int_0^1 \|dh^-(x, y)\|^2 dy = 4\pi^2 \sum_{n=1}^{\infty} n^2 (a_n^2 + b_n^2) e^{-4\pi nx}$$

which implies the first. Item (iii) is obtained in the same way. Combining (ii), (iii) and using that $(u + v)^2 \leq 2(u^2 + v^2)$ we get (iv). For item (v) we first have

$$|h^-(x, y)| \leq \sum_{n=1}^{\infty} (|a_n| + |b_n|) e^{-2\pi nx}$$

and then estimate the sums for a_n and b_n individually, beginning with a_n . Let, with a glance at (3.4),

$$s_a = \sum_{n=1}^{\infty} |a_n| e^{-2\pi nx}, \quad E_a = \pi \sum_{n=1}^{\infty} n a_n^2 (e^{4\pi nl} - e^{-4\pi nl}).$$

With $\alpha_n = |a_n| e^{2\pi nl} (n(1 - e^{-8\pi nl}))^{\frac{1}{2}}$, the two terms may be written in the form

$$s_a = \sum_{n=1}^{\infty} \alpha_n (n(1 - e^{-8\pi nl}))^{-\frac{1}{2}} e^{-2\pi n(x+l)}, \quad E_a = \pi \sum_{n=1}^{\infty} \alpha_n^2.$$

By the Cauchy–Schwarz inequality,

$$s_a^2 \leq \sum_{n=1}^{\infty} \alpha_n^2 \cdot \sum_{n=1}^{\infty} \frac{1}{n(1 - e^{-8\pi nl})} e^{-4\pi n(x+l)}.$$

The second sum is further bounded above by

$$\frac{1}{1 - e^{-8\pi l}} \sum_{n=1}^{\infty} \frac{1}{n} e^{-4\pi n(x+l)} = \frac{-1}{1 - e^{-8\pi l}} \ln(1 - e^{-4\pi(x+l)}) < \frac{3}{2} e^{-4\pi(x+l)},$$

where the simplification of the right uses that $l \geq 1$ and $4\pi(x + l) \geq 4\pi\delta_L \geq 2\pi$. Bringing everything together we get $s_a^2 < \frac{1}{2} E_a e^{-4\pi(x+l)}$. An analogous inequality holds for the b_n .

Using that $(u + v)^2 \leq 2(u^2 + v^2)$ and recalling (3.4) we get the first inequality in (v). The proof of the second inequality is following the same scheme beginning with

$$\left| \frac{\partial h^-(x, y)}{\partial x} \right| \leq 2\pi \sum_{n=1}^{\infty} n(|a_n| + |b_n|)e^{-2\pi nx}, \quad \left| \frac{\partial h^-(x, y)}{\partial y} \right| \leq 2\pi \sum_{n=1}^{\infty} n(|a_n| + |b_n|)e^{-2\pi nx}.$$

The sum s_a is now replaced by $t_a = 2\pi \sum_{n=1}^{\infty} n|a_n|e^{-2\pi nx}$, and instead of the above sum $\sum_{n=1}^{\infty} \frac{1}{n}e^{-4\pi n(x+l)}$ we now deal with $\sum_{n=1}^{\infty} ne^{-4\pi n(x+l)} = e^{4\pi(x+l)}(e^{4\pi(x+l)} - 1)^{-2}$. The inequality $s_a^2 < \frac{1}{2}E_a e^{-4\pi(x+l)}$ is taken over by $t_a^2 < 13E_a e^{-4\pi(x+l)}$ with its analog for the b_n , and the result is

$$\left| \frac{\partial h^-(x, y)}{\partial x} \right|^2 < 26e^{-4\pi(x+l)} E_{Z_l}(dh^-), \quad \left| \frac{\partial h^-(x, y)}{\partial y} \right|^2 < 26e^{-4\pi(x+l)} E_{Z_l}(dh^+).$$

Hence, the second inequality. The proof of (vi) is the same. For the proof of (vii) one uses (v) and (vi) and the fact that $E_{Z_l}(dh^{nl}) = E_{Z_l}(dh^-) + E_{Z_l}(dh^+)$. $\square$

We also need the following orthogonality lemma, where $Z' = [x_0, x_1] \times \mathbb{S}_1$. The proof is similar to that of the first part of the preceding lemma and is omitted. The term “sufficiently strongly” means that the series and the term by term differentiated series are absolutely uniformly convergent.

Lemma 3.2 (Orthogonality lemma) *Let $H, \tilde{H} : Z' \rightarrow \mathbb{R}$ be sufficiently strongly convergent series*

$$\begin{aligned} H(x, y) &= \sum_{n=1}^{\infty} \varphi_n(x) \cos(2\pi ny) + \sum_{n=1}^{\infty} \psi_n(x) \sin(2\pi ny), \\ \tilde{H}(x, y) &= \sum_{n=1}^{\infty} \tilde{\varphi}_n(x) \cos(2\pi ny) + \sum_{n=1}^{\infty} \tilde{\psi}_n(x) \sin(2\pi ny), \end{aligned}$$

and $\omega, \tilde{\omega}$ on Z' the forms

$$\begin{aligned} \omega &= b(x)dx + c dy + dH, \\ \tilde{\omega} &= \tilde{b}(x)dx + \tilde{c} dy + d\tilde{H}, \end{aligned}$$

where $b, \tilde{b} : [x_0, x_1] \rightarrow \mathbb{R}$ are continuous functions and $c, \tilde{c} \in \mathbb{R}$ are constants. Then

$$\int_{Z'} \omega \wedge \star \tilde{\omega} = \int_{x_0}^{x_1} (c\tilde{c} + b(x)\tilde{b}(x))dx + \int_{Z'} dH \wedge \star d\tilde{H}.$$

Lemma 3.3 (First dampening down lemma) *Let $Z_l = [-l, l] \times \mathbb{S}_1$ with subsets D_L, D_{int}, D_R be as in Lemma 3.1, $h : Z_l \rightarrow \mathbb{R}$ with nonlinear part $h^{nl} = h^- + h^+$ a harmonic function as in (3.2) and ω the harmonic form*

$$\omega = b_0 dx + c_0 dy + dh^{nl},$$

where $b_0, c_0 \in \mathbb{R}$ are constants. Set $\delta := \min\{\delta_L, \delta_R\}$ and $w = 2l - (\delta_L + \delta_R)$. In D_{int} we dampen down ω to

$$\omega_\chi = b_0 dx + c_0 dy + d(\chi \cdot h^{nl}),$$

where $\chi : Z_l \rightarrow \mathbb{R}$ is the cut off function with the property that $\chi = 1$ on D_L , $\chi = 0$ on D_R and χ is a linear function of x on D_{int} . Then for the three functions $h^\# = h^-, h^+, h^{nl}$ we have

$$(i) \ E_{D_{int}}(d(\chi \cdot h^\#)) \leq E_{D_{int}}(dh^\#) + \left(1 + \frac{1}{2\pi^2 w^2}\right) e^{-4\pi\delta_\#} E_{Z_l}(dh^\#),$$

where, respectively, $\delta_\# = \delta_L, \delta_R, \delta$. The dampened down form ω_χ satisfies

$$(ii) \ E_{D_{int}}(\omega_\chi) = E_{D_{int}}(b_0 dx + c_0 dy) + E_{D_{int}}(d(\chi \cdot h^{nl})),$$

$$(iii) \ E_{Z_l}(\omega_\chi) \leq E_{Z_l}(\omega) + \left(1 + \frac{1}{2\pi^2 w^2}\right) e^{-4\pi\delta} E_{Z_l}(\omega).$$

Proof Statement (ii) is an instance of Lemma 3.2. For the inequality in (i) we first have, pointwise,

$$\|d(\chi h^\#)\| = \|\chi dh^\# + h^\# d\chi\| \leq \|\chi dh^\#\| + \|h^\# d\chi\| \leq \|dh^\#\| + \frac{1}{w} |h^\#|. \quad (3.6)$$

Using that $(u + v)^2 \leq 2(u^2 + v^2)$ we further get

$$\|d(\chi h^\#)\|^2 \leq 2(\|dh^\#\|^2 + \frac{1}{w^2} |h^\#|^2).$$

Integrating over D_{int} we conclude the proof of (i) using Lemma 3.1. (For $h^\# = h^-, h^+$ we can actually replace $(1 + \frac{1}{2\pi^2 w^2})$ with $(1 + \frac{1}{4\pi^2 w^2})$, but this will not improve our later results). Statement (iii) is a consequence of the preceding ones. $\square$

The choice of $\frac{1}{100}$ for w in the next lemma has been made so as to keep the increase of energy in the dampening down process small.

Lemma 3.4 (Second dampening down lemma) *Let $Z_l = [-l, l] \times \mathbb{S}_1$ and $h : Z_l \rightarrow \mathbb{R}$ be as in the first lemma, but now assume that $l \geq 1$, $\delta_L = \frac{1}{2}$ and $w = 2l - (\delta_L + \delta_R) = \frac{1}{100}$. In D_{int} we partially dampen down ω to*

$$\omega_\chi^+ = b_0 dx + c_0 dy + dh^- + d(\chi \cdot h^+),$$

where $\chi : Z_l \rightarrow \mathbb{R}$ is the same cut off function as in Lemma 3.3. Then

$$(i) \ E_{Z_l}(\omega_\chi^+) = E_{Z_l}(b_0 dx + c_0 dy) + E_{Z_l}(dh^- + d(\chi \cdot h^+)),$$

$$(ii) \ E_{Z_l}(dh^- + d(\chi \cdot h^+)) \leq E_{Z_l}(dh^- + dh^+) + e^{-8\pi l + 5} E_{Z_l}(dh^-).$$

Proof (i) is again an instance of Lemma 3.2. For the proof of (ii) we abbreviate

$$\hat{h} = h^- + \chi \cdot h^+, \quad E^- = E_{Z_l}(dh^-), \quad E^+ = E_{Z_l}(dh^+).$$

By Lemma 3.1 (v) and (vi) (applicable since $l \geq 1$, $\delta_L = \frac{1}{2}$) we have the following bounds for $(x, y) \in D_{int}$:

$$|h^-(x, y)| < e^{-2\pi\delta_L} \sqrt{E^-}, \quad \|dh^-(x, y)\| < 8e^{-2\pi\delta_L} \sqrt{E^-}, \quad (3.7)$$

$$|h^+(x, y)| < e^{-2\pi\delta_R} \sqrt{E^+}, \quad \|dh^+(x, y)\| < 8e^{-2\pi\delta_R} \sqrt{E^+}. \quad (3.8)$$

Furthermore, since $\|d\chi(x, y)\| = \frac{1}{w}$ for $(x, y) \in D_{int}$ and $|\chi(x)| \leq 1$, the triangle inequality yields

$$\begin{aligned} \|\hat{h}(x, y)\| &\leq \|dh^-(x, y)\| + \frac{1}{w} |h^+(x, y)| + \|dh^+(x, y)\| \\ &\leq \|dh^-(x, y)\| + \left(\frac{1}{w} + 8\right) e^{-2\pi\delta_R} \sqrt{E^+}. \end{aligned}$$

Taking the squares and integrating over D_{int} we get, using (3.7),

$$E_{D_{int}}(d\hat{h}) \leq E_{D_{int}}(dh^-) + \alpha \sqrt{E^+} + \beta E^+$$

with

$$\alpha = 16 \left(\frac{1}{w} + 8 \right) e^{-2\pi(\delta_L + \delta_R)} \sqrt{E^-} \operatorname{area}(D_{int}), \quad \beta = \left(\frac{1}{w} + 8 \right)^2 e^{-4\pi\delta_R} \operatorname{area}(D_{int}). \quad (3.9)$$

Since $E_{D_{int}}(dh^-) = E_{D_{int}}(dh^{nl}) - E_{D_{int}}(dh^+)$ and $E_{D_R}(dh^{nl}) = E_{D_R}(dh^-) + E_{D_R}(dh^+)$ we get

$$E_{Z_l}(d\hat{h}) \leq E_{Z_l}(dh^{nl}) + \alpha\sqrt{E^+} + \beta E^+ - E_{Z_l \setminus D_L}(dh^+).$$

Now $E_{Z_l \setminus D_L}(dh^+)$ is close to $E_{Z_l}(dh^+)$: By (3.3)

$$E_{Z_l \setminus D_L}(dh^+) = 4\pi^2 \int_{-l+\delta_L}^l \sum_{n=1}^{\infty} n^2 (c_n^2 + d_n^2) e^{4\pi n x} dx.$$

Introducing the lower bound κ in the following elementary inequality:

$$\frac{\int_{-l+\delta_L}^l e^{4\pi n x} dx}{\int_{-l}^l e^{4\pi n x} dx} \geq \frac{\int_{-l+\delta_L}^l e^{4\pi x} dx}{\int_{-l}^l e^{4\pi x} dx} \stackrel{\text{def}}{=} \kappa$$

we get $E_{Z_l \setminus D_L}(dh^+) \geq \kappa E_{Z_l}(dh^+)$ and therefore $E_{Z_l}(d\hat{h}) \leq E_{Z_l}(dh^{nl}) + \alpha\sqrt{E^+} + (\beta - \kappa)E^+$. We are now using that $l \geq 1$, $\delta_L = \frac{1}{2}$, and $w = \frac{1}{100}$. For these values, it is easily checked that β is close to 0 and κ is close to 1, and we have the rough but sufficient estimate $\beta - \kappa < -\frac{3}{4}$. We get

$$E_{Z_l}(d\hat{h}) \leq E_{Z_l}(dh^{nl}) + \alpha\sqrt{E^+} - \frac{3}{4}E^+.$$

Finally, for $t \in [0, \infty)$ the function $\alpha\sqrt{t} - \frac{3}{4}t$ has the upper bound $\frac{1}{3}\alpha^2$, and plugging in the values of w , δ_L , δ_R into α (see (3.9)) we conclude the proof of (ii) by elementary simplification. $\square$

4 Separating case

The setting for this section is as follows. S is a compact hyperbolic Riemann surface of genus $g \geq 2$ that contains a simple closed geodesic γ of length

$$\ell(\gamma) \leq \frac{1}{2} \quad (4.1)$$

separating S into two surfaces S_1 and S_2 of signatures $(g_1, 1)$ and $(g_2, 1)$, respectively (see Fig. 5). We let $(\alpha_i)_{i=1, \dots, 2g}$ be a canonical homology basis of S , such that $(\alpha_1, \dots, \alpha_{2g_1}) \subset S_1$ and $(\alpha_{2g_1+1}, \dots, \alpha_{2(g_1+g_2)}) \subset S_2$ and let P_S be the Gram period matrix with respect to this basis. In the first part of this section we look at the energy distribution of harmonic forms that have zero periods on S_2 respectively, S_1 . In the second part we make use of this to prove Theorem 4.3.

Fig. 5 A Riemann surface S with a short separating geodesic and adjacent Y -pieces

4.1 Concentration of the energies of harmonic forms

In the first part of the next theorem we prove point (a) of Theorem 1.1. We recall $\mu(\gamma)$ from (1.3), for convenience,

$$\mu(\gamma) = \exp \left(-2\pi^2 \left(\frac{1}{\ell(\gamma)} - \frac{1}{2} \right) \right). \quad (4.2)$$

Theorem 4.1 *Let $\sigma \in H^1(S, \mathbb{R})$ be a real harmonic 1-form, such that $\int_{[\alpha]} \sigma = 0$ for all $[\alpha] \in H_1(S_2, \mathbb{Z})$. Then*

$$E_{S_2}(\sigma) \leq \mu(\gamma) E_S(\sigma). \quad (i)$$

Let, furthermore, $\tau \in H^1(S, \mathbb{R})$ be a real harmonic 1-form such that $\int_{[\beta]} \tau = 0$ for all $[\beta] \in H_1(S_1, \mathbb{Z})$. Then

$$\left| \int_S \sigma \wedge \star \tau \right| \leq \mu(\gamma) \sqrt{E_S(\sigma) E_S(\tau)}. \quad (ii)$$

Proof We look at the decay of σ in the standard collar $C = C(\gamma)$ of γ (shaded area in Fig. 5, see (2.1), (2.2) for the definition). To make use of the preceding section we shall map $C(\gamma)$ conformally to a flat cylinder using the mapping ψ_γ as in (2.10) which we repeat here, for convenience.

$$\psi_\gamma : C = C(\gamma) \rightarrow Z_M, \text{ where } Z_M = (-M, M) \times \mathbb{S}_1$$

and by (2.13)

$$M = M(\ell(\gamma)) = \frac{1}{\ell(\gamma)} \left\{ \frac{\pi}{2} - \arcsin \left(\tanh \left(\frac{\ell(\gamma)}{2} \right) \right) \right\} \geq \frac{\pi}{2\ell(\gamma)} - \frac{1}{2} > 2. \quad (4.3)$$

We denote the inverse of ψ_γ by ϕ_C :

$$\phi_C = (\psi_\gamma)^{-1} : Z_M \rightarrow C.$$

On C the form σ has only zero periods and can therefore be written as $\sigma = dF$, with a harmonic function $F : C \rightarrow \mathbb{R}$. Let $h = F \circ \phi_C$ be the corresponding harmonic function on Z_M . We decompose it into a sum

$$h(x, y) = a_0 + b_0 x + h^{\text{nl}}(x, y), \quad (4.4)$$

as in the preceding section, where h^{nl} is the nonlinear part of h . The constant a_0 may be arbitrarily chosen, we take $a_0 = 0$. With $w = \frac{1}{8}$ (a constant that has proved to be practical)

we set $\delta = M - w$ and dampen down h to H setting

$$H(x, y) = \begin{cases} b_0 x + \chi(x) h^{\text{nl}}(x, y), & \text{for } x \in (-M, 0] \\ 0 & \text{for } x \in [0, M), \end{cases} \quad (4.5)$$

where χ is the cut off function as in Lemma 3.3 that goes linearly from 1 to 0 in the interval $[-w, 0]$. Setting $\tilde{D} = [-w, 0] \times \mathbb{S}_1$ we obtain, by that lemma, clause (i), with $l = M$, $\delta_L = M - w$, $\delta_R = M$, $\delta_{\#} = \min\{\delta_L, \delta_R\} =: \delta$ and $h^{\#} = h^{\text{nl}}$,

$$E_{\tilde{D}}(dH) \leq E_{\tilde{D}}(dh) + \left(1 + \frac{1}{2\pi^2 w^2}\right) e^{-4\pi\delta} E_{Z_M}(dh).$$

In addition, we have used that by the Orthogonality Lemma 3.2 we have $E_{\tilde{D}}(dh^{\text{nl}}) \leq E_{\tilde{D}}(dh)$ and $E_{Z_M}(dh^{\text{nl}}) \leq E_{Z_M}(dh)$. An elementary calculation using that $M(\ell(\gamma)) \geq \frac{\pi}{2\ell(\gamma)} - \frac{1}{2}$ (see (4.3)) yields

$$E_{\tilde{D}}(dH) \leq E_{\tilde{D}}(dh) + e^{-2\pi^2\left(\frac{1}{\ell(\gamma)} - \frac{1}{2}\right)} E_{Z_M}(dh) = E_{\tilde{D}}(dh) + \mu(\gamma) E_{Z_M}(dh).$$

Now we set

$$s = \begin{cases} \sigma & \text{on } S_1 \setminus C \\ d(H \circ \psi_{\gamma}) & \text{on } C \\ 0 & \text{on } S_2 \setminus C. \end{cases} \quad (4.6)$$

Since all periods of σ over cycles in S_2 vanish the two forms are in the same cohomology class and so we have $E_S(\sigma) \leq E_S(s)$ by the minimizing property of harmonic forms. On the other hand, using that ϕ_C is conformal,

$$E_S(s) = E_{S_1 \setminus \phi_C(\tilde{D})}(\sigma) + E_{\tilde{D}}(dH) \leq E_{S_1}(\sigma) + \mu(\gamma) E_{Z_M}(dh). \quad (4.7)$$

Furthermore, $E_{Z_M}(dh) \leq E_S(\sigma)$. Hence, altogether

$$E_{S_2}(\sigma) \leq \mu(\gamma) E_S(\sigma). \quad (4.8)$$

This proves part (i) of Theorem 4.1. For part (ii) we first remark that $s = \sigma + dG_{\sigma}$ for some piecewise smooth function $G_{\sigma} : S \rightarrow \mathbb{R}$, given that σ and s are in the same cohomology class. By orthogonality and by Eq. (4.7) this function satisfies

$$E_S(\sigma) + E_S(dG_{\sigma}) = E_S(s) \leq E_S(\sigma) + \mu(\gamma) E_S(\sigma).$$

Hence, $E_S(dG_{\sigma}) \leq \mu(\gamma) E_S(\sigma)$. Now consider τ . Repeating the procedure with the roles of S_1, S_2 reversed we get a dampened down form t that vanishes on S_1 and can be written as $t = \tau + dG_{\tau}$ with some function $G_{\tau} : S \rightarrow \mathbb{R}$ satisfying $E_S(dG_{\tau}) \leq \mu(\gamma) E_S(\tau)$. Since t vanishes on S_1 and s vanishes on S_2 we have, again by orthogonality,

$$0 = \int_S s \wedge \star t = \int_S \sigma \wedge \star \tau + \int_S dG_{\sigma} \wedge \star dG_{\tau}.$$

By Cauchy–Schwarz, $|\int_S dG_{\sigma} \wedge \star dG_{\tau}|^2 \leq E_S(dG_{\sigma}) E_S(dG_{\tau}) \leq \mu(\gamma)^2 E_S(\sigma) E_S(\tau)$, and (ii) follows. $\square$

It is interesting to observe that for σ as in Theorem 4.1 almost all of the energy decay in the direction of S_2 takes place in the collar $C(\gamma)$: with $\mu(\gamma)$ as in (4.2) we have the following which is part (b) of Theorem 1.1

Theorem 4.2 *Let S with separating geodesic γ and $\sigma \in H^1(S, \mathbb{R})$ with all periods over cycles in S_2 vanishing be as in Theorem 4.1. Then*

$$E_{S_2 \setminus C(\gamma)}(\sigma) \leq \mu(\gamma)^2 E_{C(\gamma)}(\sigma).$$

In particular, the upper bound for the energy of σ on $S_2 \setminus C(\gamma)$ is much smaller than that for σ on S_2

Proof We take over the setting of the proof of Theorem 4.1. However, this time the constant a_0 for the function h in (4.4) is chosen such that $a_0 - b_0 M = 0$, i.e. such that the linear part $h^{\text{lin}}(x) = a_0 + b_0 x$ vanishes at the left end of the cylinder Z_M .

In a first step we take $\delta'_L = \frac{1}{2}$, $w' = \frac{1}{100}$ and partially dampen down dh as in Lemma 3.4 setting

$$H' = h^- + \chi' \cdot h^+,$$

where $h^- + h^+ = h^{\text{nl}}$ is the decomposition of the nonlinear part of h as in (3.1), (3.2), Lemma 3.4, and χ' is the cut off function that goes linearly from 1 at $x = -M + \delta'_L$ to 0 at $x = -M + \delta'_L + w'$. By Lemma 3.4 (applicable since by (4.3) $M > 1$),

$$E_{Z_M}(dH') \leq E_{Z_M}(dh^- + dh^+) + e^{-8\pi M+5} E_{Z_M}(dh^-).$$

In a second step we use Lemma 3.3 again, taking $w'' = \frac{1}{8}$, $\delta''_L = 2M - w''$, and further dampen down dH' setting

$$H'' = \chi'' \cdot h^- + \chi' \cdot h^+,$$

where χ'' is the cut off function that goes linearly from 1 at $x = M - w''$ to 0 at $x = M$. By Lemma 3.3, applied to $h^\# = h^-$,

$$\begin{aligned} E_{Z_M}(dH'') &\leq E_{Z_M}(dH') + \left(1 + \frac{1}{2\pi^2 w''^2}\right) e^{-4\pi(2M-w'')} E_{Z_M}(dh^-) \\ &\leq E_{Z_M}(dH') + e^{-8\pi M+4} E_{Z_M}(dh^-). \end{aligned}$$

We now go back to S letting s'' be the test form that coincides with σ on $S_1 \setminus C(\gamma)$, is the pull-back of dH'' on $C(\gamma)$ via ψ_γ and vanishes on $S_2 \setminus C(\gamma)$. Then $E_S(s'') = E_{S_1 \setminus C(\gamma)}(\sigma) + E_{Z_M}(dH'') \leq E_{S_1 \setminus C(\gamma)}(\sigma) + E_{Z_M}(dh^- + dh^+) + e^{-8\pi M+6} E_{Z_M}(dh^-)$ (simplifying the numerical constants). Now

$$E_S(s'') \geq E(\sigma) = E_{S_1 \setminus C(\gamma)}(\sigma) + E_{Z_M}(dh^{\text{lin}}) + E_{Z_M}(dh^- + dh^+) + E_{S_2 \setminus C(\gamma)}(\sigma).$$

This yields, altogether,

$$E_{Z_M}(dh^{\text{lin}}) + E_{S_2 \setminus C(\gamma)}(\sigma) \leq e^{-8\pi M+6} E_{Z_M}(dh^-), \quad (4.9)$$

where M is from (4.3). The theorem now follows by elementary simplification. $\square$

We remark that, by (4.9), the linear part of σ contributes very little to the total energy of σ in $C(\gamma)$.

For later use we also note that, by the inequalities preceding (4.9) (and using that by the Orthogonality Lemma 3.2 $E_{Z_M}(dh^- + dh^+) \leq E_{Z_M}(dh)$) the test form s'' satisfies, in particular,

$$E_S(s'') - E_S(\sigma) \leq e^{-8\pi M+6} E_S(\sigma). \quad (4.10)$$

4.2 Convergence of the Jacobians for separating geodesics

We now compare the Jacobian of S with the Jacobian of the limit surface on $\partial\mathcal{M}_g$ obtained by either the Fenchel–Nielsen or the grafting construction. Figure 6 illustrates the first case for the part S_1 with Fenchel–Nielsen limit S_1^F . The pair of pants, or Y-piece, $Y_1 \subset S_1$ with boundary geodesic γ and half collar $C(\gamma)$ is quasi conformally embedded into the degenerated Y-piece Y_1^0 with ideal boundary point q and cusp neighborhood $V(q)$, similarly to the case illustrated in Fig. 3. The remaining parts of S_1 and S_1^F are isometric. The punctured surface S_1^F and its compactification $\overline{S}_1^F$, understood as a Riemann surface in the conformal sense, have the same L^2 harmonic forms. We denote by $P_{S_1^F}$ the Gram period matrix of S_1^F with respect to the homology basis $\alpha_1, \dots, \alpha_{2g_1}$; the matrices $P_{S_2^F}$, $P_{S_1^G}$, $P_{S_2^G}$ are defined in the same way. We now prove Theorem 1.2 which we restate for convenience. The entries of the blocks R_k^Λ are named r_{ij} , those of Ω and its transpose ${}^t\Omega$ are named ω_{ij} , and the numbering, disregarding the blocks, is $i, j = 1, \dots, 2g$.

Theorem 4.3 *Assume that the separating geodesic γ has length $\ell(\gamma) \leq \frac{1}{2}$. Then*

$$P_S = \begin{pmatrix} P_{S_1^\Lambda} & 0 \\ 0 & P_{S_2^\Lambda} \end{pmatrix} + \begin{pmatrix} R_1^\Lambda & \Omega \\ {}^t\Omega & R_2^\Lambda \end{pmatrix},$$

where $\{\}^\Lambda$ stands for either $\{\}^F$ or $\{\}^G$ and the entries of the remainder matrices have the following bounds,

- (i) $|\omega_{ij}| \leq e^{-2\pi^2(\frac{1}{\ell(\gamma)} - \frac{1}{2})} \sqrt{p_{ii} p_{jj}}$,
- (ii) $|r_{ij}^G| \leq e^{-4\pi^2(\frac{1}{\ell(\gamma)} - \frac{1}{2})} \sqrt{p_{ii} p_{jj}}$,
- (iii) $|r_{ij}^F| \leq 6\ell(\gamma)^2 \sqrt{p_{ii} p_{jj}}$.

Fig. 6 The bordered Riemann surface S_1 , its Fenchel–Nielsen limit and the one point compactification viewed as a conformal surface

Proof Statement (i) is an instance of Theorem 4.1 (ii). For the proof of (ii) we take the part concerning $P_{S_1^G}$. For simplicity, we shall identify the collar $C(\gamma)$ with the conformally equivalent $Z_M = (-M, M) \times \mathbb{S}_1$ (M is from (4.3)).

We use that the surface $S' = \text{closure of } S_1 \cup C(\gamma)$, seen as a conformal surface, may be understood as a subset of the grafted surface S_1^G in a natural way: S' is S_1 with a copy of the flat cylinder $[0, M] \times \mathbb{S}_1$ attached along the boundary, and S_1^G is S_1 with a copy of $[0, \infty) \times \mathbb{S}_1$ attached. For simplicity we write $S_1^G = \tilde{S}$.

Consider now a harmonic form σ on S with vanishing periods over the cycles of S_2 and let $\tilde{\sigma}$ on $\tilde{S}$ be the harmonic form that has the same periods over $\alpha_1, \dots, \alpha_{2g_1}$ as σ . For later reference we write $\tilde{\sigma} = \Psi(\sigma)$.

We shall dampen down σ and $\tilde{\sigma}$ to test forms s and $\tilde{s}$ with supports on S' and compare the energies. To obtain s we apply to σ the two step dampening down procedure used in the proof of Theorem 4.2. Thus, s is s'' as in (4.10). By (4.10) it satisfies

$$E_S(s) \leq (1 + e^{-8\pi M+6})E_S(\sigma). \quad (4.11)$$

To obtain $\tilde{s}$ we remark that $\tilde{\sigma}$ on Z_M has a representation $\tilde{\sigma} = dh$, where we have $h(x, y) = \sum_{n=1}^{\infty} (a_n \cos(ny) + b_n \sin(ny))e^{-nx}$, i.e. dh has vanishing linear and dh^+ parts (owing to the fact that on the infinite cylinder $\tilde{\sigma}$ has finite energy). We now let $\tilde{s}$ be the test form on $\tilde{S}$ that coincides with $\tilde{\sigma}$ on $S_1 \setminus C(\gamma)$, is represented on Z_M by $d\chi \cdot h$ and vanishes on the rest. For χ we take the cut off function that goes linearly from 1 at $x = M - w$ to 0 at $x = M$, with $w = \frac{1}{8}$. By Lemma 3.3(i) applied to $h^\# = h = h^-$ with $\delta^\# = \delta_- = 2M - w$

$$E_{\tilde{S}}(\tilde{s}) \leq (1 + e^{-8\pi M+4})E_{\tilde{S}}(\tilde{\sigma}). \quad (4.12)$$

Now s , having its support on S' , may be extended by zero to $\tilde{S}$ and thus also be seen as a test form for $\tilde{\sigma}$ on $\tilde{S}$. Similarly, $\tilde{s}$ may be seen as a test form for σ on S . Hence, by (4.11) and (4.12)

$$\begin{aligned} E_{\tilde{S}}(\tilde{\sigma}) &\leq E_{\tilde{S}}(s) = E_S(s) \leq (1 + e^{-8\pi M+6})E_S(\sigma), \\ E_S(\sigma) &\leq E_S(\tilde{s}) = E_{\tilde{S}}(\tilde{s}) \leq (1 + e^{-8\pi M+4})E_{\tilde{S}}(\tilde{\sigma}). \end{aligned}$$

Now, the above mapping Ψ that sends any harmonic σ on S with vanishing periods over the cycles of S_2 to $\tilde{\sigma} = \Psi(\sigma)$ is a linear isomorphism of vector spaces. Therefore, by Lemma 4.4 below, for any $i, j = 1, \dots, 2g_1$,

$$|\langle \sigma_i, \sigma_j \rangle - \langle \tilde{\sigma}_i, \tilde{\sigma}_j \rangle| \leq e^{-8\pi M+6} \sqrt{P_{ii}P_{jj}}$$

and (ii) follows from (4.3) by elementary simplification.

For statement (iii) we use that by Theorem 2.3 there exists a quasiconformal homeomorphism $\phi : S_1^F \rightarrow S_1^G$ of dilatation $q_\phi \leq (1 + 2\ell(\gamma)^2)^2$ that extends conformally to the compactified surfaces (with the notation of Theorem 2.3 our ϕ here is ψ^{-1}). Using that $\ell(\gamma) \leq \frac{1}{2}$ we simplify the bound on the dilatation to $q_\phi \leq 1 + 5\ell(\gamma)^2$. By Lemma 4.5 below we have the following inequality for the harmonic forms σ'_i, σ'_j in the cohomology classes of $\phi^* \sigma_i, \phi^* \sigma_j$,

$$|\langle \sigma'_i, \sigma'_j \rangle - \langle \tilde{\sigma}_i, \tilde{\sigma}_j \rangle| \leq 5\ell(\gamma)^2 \sqrt{E_{S_1^G}(\tilde{\sigma}_i)E_{S_1^G}(\tilde{\sigma}_j)}.$$

Now $(\sigma'_1, \dots, \sigma'_{2g_1})$ is our chosen dual basis of harmonic forms on S_1^F whose scalar products $\langle \sigma'_i, \sigma'_j \rangle$ are the entries of the Gram period matrix $P_{S_1^F}$, and $(\tilde{\sigma}_1, \dots, \tilde{\sigma}_{2g_1})$ is the dual basis on S_1^G with $\langle \tilde{\sigma}_i, \tilde{\sigma}_j \rangle$ being the entries of $P_{S_1^G}$.

Together with (ii) this yields (iii) by elementary simplification. $\square$

Lemma 4.4 *Let U, V be Euclidean vector spaces whose norms and scalar products we denote by $\|\cdot\|$ and $\langle \cdot, \cdot \rangle$, let $\phi : U \rightarrow V$ be a linear mapping and let $\varepsilon > 0$. If $(1 - \varepsilon)\|u\|^2 \leq \|\phi(u)\|^2 \leq (1 + \varepsilon)\|u\|^2$, for all $u \in U$, then*

$$|\langle \phi(u), \phi(v) \rangle - \langle u, v \rangle| \leq \varepsilon \|u\| \|v\|, \quad \forall u, v \in U.$$

Proof We sketch the proof of this known fact, for convenience. The hypothesis and the conclusion are both scaling invariant so that we may assume that $\|u\| = \|v\| = 1$. Writing $\phi(u) = u'$ and $\phi(v) = v'$ we get, using the polarization identity,

$$\begin{aligned} \langle u', v' \rangle &= \frac{1}{4} (\|u' + v'\|^2 - \|u' - v'\|^2) \\ &\leq \frac{1}{4} (\|u + v\|^2 - \|u - v\|^2) + \frac{1}{4} \varepsilon^2 (\|u + v\|^2 + \|u - v\|^2) = \langle u, v \rangle + \varepsilon. \end{aligned}$$

In the same way one shows that $\langle u', v' \rangle \geq \langle u, v \rangle - \varepsilon$. $\square$

As a corollary one has

Lemma 4.5 *Let $\phi : R' \rightarrow R$ be a quasi conformal homeomorphism of compact Riemann surfaces, $\omega, \eta \in H^1(R, \mathbb{R})$ and $\omega', \eta' \in H^1(R', \mathbb{R})$ the harmonic forms in the cohomology classes of the induced forms $\phi^*\omega, \phi^*\eta$ on R' . If ϕ has dilatation $1 + \varepsilon$, then*

$$|\langle \omega', \eta' \rangle - \langle \omega, \eta \rangle| \leq \varepsilon \sqrt{E_R(\omega) E_R(\eta)}. \quad (4.13)$$

Proof Again we sketch the argument; for the analytic details we refer, e.g. to [17, proof of Theorem 2]. Let first τ be any closed 1-form on R . By the bound on the dilatation we have, pointwise,

$$\|\phi^*\tau\|^2 d\text{vol}(R') \leq (1 + \varepsilon) \phi^*(\|\tau\|^2 d\text{vol}(R)), \quad (4.14)$$

where $\|\cdot\|$ and $d\text{vol}$ are the pointwise norms and volume elements on the respective surfaces. Integration yields $E_{R'}(\phi^*\tau) \leq (1 + \varepsilon) E_R(\tau)$. If now τ is harmonic, and τ' the harmonic form in the cohomology class of $\phi^*\tau$ then, by the minimizing property of harmonic forms, $E_{R'}(\tau') \leq (1 + \varepsilon) E_R(\tau)$. Repeating these arguments for $\phi^{-1} : R \rightarrow R'$ we get altogether (for harmonic τ and τ'),

$$(1 - \varepsilon) E_R(\tau) \leq \frac{1}{(1 + \varepsilon)} E_R(\tau) \leq E_{R'}(\tau') \leq (1 + \varepsilon) E_R(\tau). \quad (4.15)$$

The inequality for the scalar product now follows from Lemma 4.4 $\square$

5 The forms σ_1 and τ_1

Here begins the second part of the paper. In all that follows S is a compact hyperbolic Riemann surface of genus $g \geq 2$ and γ is a *nonseparating* simple closed geodesic on S . In addition, a geodesic canonical homology basis $A = (\alpha_1, \alpha_2, \dots, \alpha_{2g-1}, \alpha_{2g})$ is given, with the intersection convention that, as in Sect. 1, α_{2k-1} intersects α_{2k} , $k = 1, \dots, g$. Furthermore, α_2 coincides with γ .

When, in a limit process, γ becomes short, then the first two members σ_1, σ_2 of the dual basis of harmonic forms become more and more singular, while the other members are hardly affected. In this section we analyze σ_1 , beginning with energy bounds in terms of a certain conformal capacity which too varies only little when $\ell(\gamma) \rightarrow 0$.

5.1 The capacity of $S^\times$

We denote by $S^\times$ the surface S cut open along the nonseparating geodesic γ . The *capacity* of $S^\times$, more generally the capacity $\text{cap}(M)$ of any connected surface M with two disjoint boundary components ∂_1, ∂_2 is defined as the infimum

$$\text{cap}(M) = \inf \{E_M(df) \mid f|_{\partial_1} = 0, f|_{\partial_2} = 1\}, \quad (5.1)$$

where the competing functions f are piecewise smooth. We shall estimate $\text{cap}(S^\times)$ when γ becomes small while all other Fenchel–Nielsen parameters of S are kept fixed. For this we look at a suitable subset $\mathfrak{M}$ of $S^\times$ whose capacity remains bounded under such a deformation. We shall define it as follows (see also Sect. 1, Fig. 2).

Let γ_1, γ_2 be the two boundary geodesics of $S^\times$. For $i = 1, 2$ we have the half collars $C(\gamma_i)$ consisting of the points at distance $< \text{cl}(\ell(\gamma))$ from γ_i (see (2.2)). The larger boundary, b_i , of $C(\gamma_i)$ is a parallel curve of length ≥ 2 , and we let c_i in $C(\gamma_i)$ be the parallel curve that has length $\ell(c_i) = 1$. It splits $C(\gamma_i)$ into two ring domains: C_i from γ_i to c_i and B_i from c_i to b_i . In what follows we shall understand C_i and B_i to be the closures of these domains. The subsurface $\mathfrak{M}$ is obtained by cutting a way the parts C_1, C_2 and taking the closure:

$$\mathfrak{M} = S^\times \setminus (C_1 \cup C_2) \cup c_1 \cup c_2. \quad (5.2)$$

In Sect. 7.2 we shall define $\mathfrak{M}$ in a similar way for a Riemann surface with a pair of cusps. We set

$$\Gamma = \frac{1}{\text{cap}(\mathfrak{M})}. \quad (5.3)$$

Then $[0, \Gamma] \times \mathbb{S}_1$ is the cylinder that has the same capacity as $\mathfrak{M}$. We shall call $\mathfrak{M}$ the *main part* of S .

To compare this with the capacity of $S^\times$ we look at the lengths of the half collars. The conformal mapping ψ_γ as in (2.10), with F_γ as in (2.11) sends the closure of $C(\gamma_1)$ onto the flat cylinder $[0, F_\gamma(\text{cl}(\ell(\gamma)))] \times \mathbb{S}_1$. The parts C_1, B_1 go to the parts

$$\left[0, \frac{1}{2}L_\gamma\right] \times \mathbb{S}_1 \quad \text{and} \quad \left[\frac{1}{2}L_\gamma, \frac{1}{2}L_\gamma + d_\gamma\right] \times \mathbb{S}_1,$$

respectively. Observe the notation: the quantity $\frac{1}{2}L_\gamma + d_\gamma$ we are using here is the same as $M(\ell(\gamma))$ in (2.13). From this equation it follows by elementary computation that

$$L_\gamma = \frac{\pi}{\ell(\gamma)} - \frac{2 \arcsin \ell(\gamma)}{\ell(\gamma)} > 4, \quad d_\gamma \geq \frac{1}{2} \quad (5.4)$$

and the inequality holds under the assumption that $\ell(\gamma) \leq \frac{1}{2}$. For C_2, B_2 we have the same properties. Since B_1, B_2 are disjoint subsets of $\mathfrak{M}$ that are conformally equivalent to $[0, d_\gamma] \times \mathbb{S}_1$ it follows immediately that

$$\text{cap}(\mathfrak{M}) \leq 1, \quad \Gamma \geq 1. \quad (5.5)$$

However, the lower bounds of $\text{cap}(\mathfrak{M})$ (e.g. Sect. 6) are more important.

From a conformal point of view, $S^\times$ is $\mathfrak{M}$ with two copies of $[0, L_\gamma/2] \times \mathbb{S}_1$ attached along c_1, c_2 . In the following, $S_L^\times$ is $\mathfrak{M}$ with two copies Z_1, Z_2 of $[0, L/2] \times \mathbb{S}_1$ attached, for some arbitrary $L > 0$.

Lemma 5.1 *There exists a universal constant $\mathfrak{z} < 2.3$ such that for any $L > 0$*

$$\frac{1}{L + \mathfrak{z}\Gamma} \leq \text{cap}(S_L^\times) \leq \frac{1}{L + \Gamma}.$$

Proof The upper bound is obtained out of the test function F that grows linearly from 0 to $\frac{L/2}{L+\Gamma}$ on Z_1 , linearly from $1 - \frac{L/2}{L+\Gamma}$ to 1 in Z_2 , and is harmonic with boundary values $\frac{L/2}{L+\Gamma}$, $1 - \frac{L/2}{L+\Gamma}$ on $\mathfrak{M}$.

For the lower bound we let f be the harmonic function that is constant equal to 0 on the left boundary of $S_L^\times$ and constant equal to 1 on the right boundary. For the harmonic 1-form $\omega = df$ we then have

$$E(\omega) = \text{cap}(S_L^\times). \quad (5.6)$$

With constants $a, b \in \mathbb{R}$ (to be dealt with at the end) we have the decomposition of f into its linear and nonlinear parts

$$f(x, y) = ax + h_1(x, y) \quad (5.7)$$

on Z_1 and

$$f(x, y) = bx + 1 - bL/2 + h_2(x, y) \quad (5.8)$$

on Z_2 . (For either cylinder we adopt the convention that $x \in [0, L/2]$ and the constant terms are deduced from the fact that the nonlinear parts have mean values $\int_0^1 h_i(x, y) dy = 0$.) We remark that (5.7) and (5.8) also hold on the adjacent ring domains $\psi_\gamma(B_1) = [L/2, L/2 + d_\gamma] \times \mathbb{S}_1$ and $\psi_\gamma(B_2) = [-d_\gamma, 0] \times \mathbb{S}_1$. Based on this we construct a form that serves as test form on $\mathfrak{M}$ by dampening down the nonlinear parts of f as follows. First on $Z_1 \cup B_1$: using the function χ that is 0 on $[0, L/2] \times \mathbb{S}_1$ and then grows linearly from 0 to 1 on $[L/2, L/2 + d_\gamma] \times \mathbb{S}_1$ we set

$$f_\chi(x, y) = ax + \chi(x, y)h_1(x, y)$$

on $Z_1 \cup B_1$. We proceed similarly on $B_2 \cup Z_2$ and complete the definition setting $f_\chi = f$ on $\mathfrak{M} \setminus (B_1 \cup B_2)$. Now f_χ is a test function on $\mathfrak{M}$ that assumes the constant value $aL/2$ on the boundary component c_1 of $\mathfrak{M}$ and $1 - bL/2$ on c_2 . The energy of the harmonic function that is constant r on one boundary and constant $r + s$ on the other boundary of $\mathfrak{M}$ can be obtained by rescaling the function that satisfies the capacity problem and is equal to $s^2 \cdot \text{cap}(\mathfrak{M})$. For $\omega_\chi = df_\chi$ we have therefore

$$E_{\mathfrak{M}}(\omega_\chi) \geq \left(1 - \frac{a+b}{2}L\right)^2 \text{cap}(\mathfrak{M}). \quad (5.9)$$

By the Dampening Down Lemma 3.3 (i) (with $\delta = 0$ and $D_{\text{int}} = Z_l = [0, d_\gamma] \times \mathbb{S}_1$ conformally equivalent to B_i) we get $E_{B_i}(\omega_\chi) \leq \mathfrak{z}E_{B_i}(\omega)$, $i = 1, 2$, with $\mathfrak{z} = 2 + 2\pi^{-2}$. Hence,

$$E_{\mathfrak{M}}(\omega_\chi) \leq \mathfrak{z}E_{\mathfrak{M}}(\omega). \quad (5.10)$$

By the Orthogonality Lemma 3.2 we further have

$$E(\omega) \geq \frac{a^2L}{2} + \frac{b^2L}{2} + E_{\mathfrak{M}}(\omega). \quad (5.11)$$

Bringing (5.9)–(5.11) together we obtain

$$E(\omega) \geq \frac{a^2 + b^2}{2}L + \frac{1}{\mathfrak{z}\Gamma} \left(1 - \frac{a+b}{2}L\right)^2. \quad (5.12)$$

Now, a and b are not known. We therefore replace the right hand side of (5.12) by the infimum over all real values of a, b . This infimum is readily seen to be achieved for $a = b = 1/(L + 3\Gamma)$, and the corresponding value of the right hand side of (5.12), somewhat accidentally, also equals $1/(L + 3\Gamma)$. This completes the proof. $\square$

If we paste the two boundary geodesics of $S_L^\times$ together, with respect to some arbitrary twisting parameter, then for the resulting surface S_L we have an analogous result. To make this precise we assume that $\alpha_1, \dots, \alpha_{2g}$ and $\sigma_1, \dots, \sigma_{2g}$ have the same meanings for S_L as for S , and that α_2 is the curve along which the two boundary curves of $S^\times$ have been pasted together. We shall, however, write $\sigma_1 = \sigma_{1,L}$ to indicate that the form is defined on S_L .

Lemma 5.2 *There exists a universal constant $3 < 2.3$ such that for any $L > 0$*

$$\frac{1}{L + 3\Gamma} \leq E(\sigma_{1,L}) \leq \frac{1}{L + \Gamma}.$$

Proof The proof is identical to the preceding one, owing to the fact that $\sigma_{1,L}$ has a primitive f_L on $S_L^\times$. We fix its additive constant such that f_L has mean value 0 on the left boundary of $S_L^\times$ and mean value 1 on the right. The splitting into linear and nonlinear parts is then again $f_L(x, y) = ax + h_1(x, y)$ on $Z_1 \cup B_1$, $f_L(x, y) = bx + 1 - bL/2 + h_2(x, y)$ on $B_2 \cup Z_2$ and the earlier arguments go through. $\square$

5.2 The form τ_1

When $\ell(\gamma) \rightarrow 0$ or when $L \rightarrow \infty$ the energy of σ_1 goes to 0, and σ_1 disappears in the limit. We introduce therefore a renormalized form that “survives”. To this end we let τ_1 be σ_1 multiplied with a constant factor such that τ_1 on the collar $C(\gamma)$ has a representation

$$\tau_1 = dx + dh_1^{\text{nl}}, \quad (5.13)$$

i.e. τ_1 is normalized so that the linear part of its representations on the flat cylinders $Z_1 \cup B_1$ and $Z_2 \cup B_2$ is equal to dx .

The form τ_1 is defined similarly on any S_L and is then written $\tau_{1,L}$. We observe that, by Theorem 5.3 below, $\tau_{1,L}$ depends only on the conformal class of S_L and not the particular description we are using here.

We shall show in Sect. 7.1, Theorem 7.3 that as $L \rightarrow \infty$, $\tau_{1,L}$ converges, locally uniformly, to the unique harmonic form $\tau_1^\mathbb{G}$ on $S^\mathbb{G}$ that has zero periods and poles with linear parts dx in the cusps.

As $L \rightarrow \infty$ the energy of $\tau_{1,L}$ and the absolute value of its period over α_1 go to infinity. This is caused by the linear part in the cylinder. We introduce therefore an *essential energy* $\mathcal{E}(\tau_{1,L})$ and an *essential period* $\mathcal{P}_1(\tau_{1,L})$ setting

$$\begin{aligned} \mathcal{E}(\tau_{1,L}) &= E_{\mathfrak{M}}(\tau_{1,L}) + E_C(\tau_{1,L}^{\text{nl}}), \\ \mathcal{P}_1(\tau_{1,L}) &= \int_{\alpha_1 \cap \mathfrak{M}} \tau_{1,L} + \int_{\alpha_1 \cap C} \tau_{1,L}^{\text{nl}}, \end{aligned} \quad (5.14)$$

where C is the inserted cylinder conformally equivalent to and identified with $[0, L] \times \mathbb{S}_1$ and for any harmonic form ω on C , ω^{nl} denotes its nonlinear part.

We first make the following observation concerning σ_1 .

Theorem 5.3 *For $\sigma_{1,L}$ on S_L the linear part in the cylinders is αdx with $\alpha = E_{S_L}(\sigma_{1,L})$.*

Proof By a well known formula for the period matrix (e.g. [11, III.2.4]) we have

$$\int_{S_L} \sigma_{1,L} \wedge \star \sigma_{1,L} = \int_{\alpha_2} \star \sigma_{1,L}.$$

The linear part of $\star \sigma_{1,L}$ is αdy . Hence, the integral on the right hand side equals α and the theorem follows. $\square$

Since $\tau_{1,L} = \frac{1}{\alpha} \sigma_{1,L}$ an immediate consequence is that

$$E(\tau_{1,L}) = \frac{1}{\alpha^2} E(\sigma_{1,L}) = \frac{1}{\alpha} = \frac{1}{E(\sigma_{1,L})}. \quad (5.15)$$

By additivity the period of $\tau_{1,L}$ over α_1 is the sum of $\mathcal{P}_1(\tau_{1,L})$ and L . On the other hand, $\tau_{1,L}$ has period $\frac{1}{\alpha}$. Hence,

$$\mathcal{P}_1(\tau_{1,L}) = \frac{1}{\alpha} - L. \quad (5.16)$$

By the Orthogonality Lemma

$$\mathcal{E}(\tau_{1,L}) = E(\tau_{1,L}) - L = \frac{1}{E(\sigma_{1,L})} - L = \frac{1}{\alpha} - L \quad (5.17)$$

from which it follows that 5.18

$$\mathcal{E}(\tau_{1,L}) = \mathcal{P}_1(\tau_{1,L}). \quad (5.18)$$

This allows us, among other things, to write

$$\sigma_{1,L} = \frac{1}{\mathcal{P}_1(\tau_{1,L}) + L} \tau_{1,L}, \quad E(\sigma_{1,L}) = \frac{1}{\mathcal{P}_1(\tau_{1,L}) + L}. \quad (5.19)$$

Combining (5.17) with Lemma 5.2 we get the following.

Lemma 5.4 *The essential energy of $\tau_{1,L}$ on S_L has the following bounds, where $\Gamma = 1/\text{cap}(\mathfrak{M})$ and $\mathfrak{z} \leq 2.3$ is the constant as in Lemmas 5.1, 5.2*

$$\Gamma \leq \mathcal{E}(\tau_{1,L}) = \mathcal{P}_1(\tau_{1,L}) \leq \mathfrak{z}\Gamma.$$

$\square$

In Sect. 7 we shall compare $\mathcal{E}(\tau_{1,L})$ with the corresponding essential energy of the harmonic form τ_1^G on the limit surface S^G . For this we prove here the following preparatory lemma.

Lemma 5.5 *Assume $L \geq 1$. Then, for any $\tilde{L} \geq L$ we have*

$$|\mathcal{E}(\tau_{1,L}) - \mathcal{E}(\tau_{1,\tilde{L}})| < e^{-2\pi L} \min\{\mathcal{E}(\tau_{1,L}), \mathcal{E}(\tau_{1,\tilde{L}})\}.$$

Proof The technique is to begin with the forms $\sigma_{1,L}$ on S_L and $\sigma_{1,\tilde{L}}$ on $S_{\tilde{L}}$ which both have period 1 over the first base cycle, then dampen their nonlinear parts down so as to obtain comparison test forms and finally translate the result to $\tau_{1,L}$ and $\tau_{1,\tilde{L}}$ using (5.17).

In the flat cylinder $Z = [-\frac{1}{2}(L+1), \frac{1}{2}(L+1)] \times \mathbb{S}_1$ the form $\sigma_{1,L}$ has a representation $\sigma_{1,L} = dH = \alpha dx + dh$, where h is the nonlinear part of H . With a constant $v \leq \frac{1}{2}(L+1)$ to be determined later (we shall take $v = \frac{1}{8}$) we set

$$d = \frac{1}{2}(L+1) - v, \quad D_{\text{int}} = [-v, v] \times \mathbb{S}_1 = \left[-\frac{1}{2}(L+1) + d, \frac{1}{2}(L+1) - d\right] \times \mathbb{S}_1$$

and let χ be the cut off function in Z that is equal to 1 outside of the part D_{int} , goes linearly down from 1 to 0 on $[-v, 0] \times \mathbb{S}_1$ and then linearly up again from 0 to 1 on $[0, v] \times \mathbb{S}_1$. We

let $\sigma_{1,\chi}$ be the form that coincides with $\sigma_{1,L}$ outside of D_{int} and inside has the representation $\sigma_{1,\chi} = \alpha dx + d(\chi h)$. Its period over the first base cycle is again equal to 1. By Lemma 3.3 (iii) applied twice (with $w = v$ and $\delta = d$) its energy satisfies

$$E(\sigma_{1,\chi}) \leq E(\sigma_{1,L}) + 2 \left(1 + \frac{1}{2\pi^2 v^2} \right) e^{-4\pi d} (E(\sigma_{1,L}) - \alpha^2(L+1)).$$

Here $E(\sigma_{1,L}) - \alpha^2(L+1)$ is an upper bound for the energy of the nonlinear part of $\sigma_{1,L}$ in Z . Abbreviating

$$\mu = 2 \left(1 + \frac{1}{2\pi^2 v^2} \right) e^{-4\pi d}$$

and recalling that $E(\sigma_{1,L}) = \alpha$ we rewrite the inequality in the form

$$E(\sigma_{1,\chi}) \leq (1+m)\alpha \quad \text{with} \quad m = \mu \cdot (1 - \alpha(L+1)).$$

In a similar way, on $\tilde{Z} = [-\frac{1}{2}(\tilde{L}+1), \frac{1}{2}(\tilde{L}+1)] \times \mathbb{S}_1$ the form $\sigma_{1,\tilde{L}}$ has a representation $\sigma_{1,\tilde{L}} = d\tilde{H} = \tilde{\alpha}dx + d\tilde{h}$, where $\tilde{h}$ is the nonlinear part of $\tilde{H}$. Here we set

$$\tilde{D}_{\text{int}} = \left[-\frac{1}{2}(\tilde{L}+1) + d, \frac{1}{2}(\tilde{L}+1) - d \right]$$

and let $\tilde{\chi}$ be the cut off function on $\tilde{Z}$ that is equal to 1 outside of $\tilde{D}_{\text{int}}$, goes linearly down from 1 to 0 for $x \in [-\frac{1}{2}(\tilde{L}+1) + d, -\frac{1}{2}(\tilde{L}+1) + d + v]$, remains 0 until $x = \frac{1}{2}(\tilde{L}+1) - d - v$ and then goes linearly up again from 0 to 1 for $x \in [\frac{1}{2}(\tilde{L}+1) - d - v, \frac{1}{2}(\tilde{L}+1) - d]$. We let $\sigma_{1,\tilde{\chi}}$ be the form that coincides with $\sigma_{1,\tilde{L}}$ outside of $\tilde{D}_{\text{int}}$ and inside has the representation $\sigma_{1,\tilde{\chi}} = \tilde{\alpha}dx + d(\tilde{\chi}\tilde{h})$. Its period over the first base cycle is 1. In the same way as before we have the inequality

$$E(\sigma_{1,\tilde{\chi}}) \leq (1+\tilde{m})\tilde{\alpha} \quad \text{with} \quad \tilde{m} = \mu \cdot (1 - \tilde{\alpha}(\tilde{L}+1)).$$

On the part $D = [-\frac{1}{2}(\tilde{L}-L), \frac{1}{2}(\tilde{L}-L)] \times \mathbb{S}_1$ of $\tilde{Z}$ the form $\sigma_{1,\tilde{\chi}}$ coincides with $\tilde{\alpha}dx$. Therefore, if $\sigma_{1,\tilde{\chi}}^-$ is the restriction of $\sigma_{1,\tilde{\chi}}$ to $S_{\tilde{L}} \setminus D$ and if we identify $S_{\tilde{L}} \setminus D$ with S_L (by gluing the ends of $S_{\tilde{L}} \setminus D$ together with the same twist), then $\sigma_{1,\tilde{\chi}}^-$ becomes a test form on S_L with period over the first base cycle equal to $1 - \tilde{\alpha}(\tilde{L}-L)$ and energy

$$E(\sigma_{1,\tilde{\chi}}^-) = E(\sigma_{1,\tilde{\chi}}) - \tilde{\alpha}^2(\tilde{L}-L).$$

In a converse way we may cut open Z in the middle, insert D and extend $\sigma_{1,\chi}$ to a test form $\sigma_{1,\chi}^+$ on $S_{\tilde{L}}$ by defining it to be equal to αdx on D . Then $\sigma_{1,\chi}^+$ has period $1 + \alpha(\tilde{L}-L)$ over the first base cycle and its energy is

$$E(\sigma_{1,\chi}^+) = E(\sigma_{1,\chi}) + \alpha^2(\tilde{L}-L).$$

To get comparison forms with periods 1 we set, abbreviating $\tilde{L} = \tilde{L} - L$,

$$s_{1,\tilde{\chi}}^- = \frac{1}{1-\tilde{\alpha}\tilde{L}} \sigma_{1,\tilde{\chi}}^-, \quad s_{1,\chi}^+ = \frac{1}{1+\alpha\tilde{L}} \sigma_{1,\chi}^+.$$

We now have $\alpha = E(\sigma_{1,L}) \leq E(s_{1,\tilde{\chi}}^-) = (1-\tilde{\alpha}\tilde{L})^{-2} E(\sigma_{1,\tilde{\chi}}^-)$ and $\tilde{\alpha} = E(\sigma_{1,\tilde{L}}) \leq E(s_{1,\chi}^+) = (1+\alpha\tilde{L})^{-2} E(\sigma_{1,\chi}^+)$. From the earlier relations we get

$$\alpha \leq \frac{\tilde{\alpha}}{(1-\tilde{\alpha}\tilde{L})^2} (1+\tilde{m}-\tilde{\alpha}\tilde{L}), \quad \tilde{\alpha} \leq \frac{\alpha}{(1+\alpha\tilde{L})^2} (1+m+\alpha\tilde{L}).$$

We are ready to estimate the difference $\Delta = \mathcal{E}(\tau_{1,\tilde{L}}) - \mathcal{E}(\tau_{1,L})$. By (5.17), $\Delta = \frac{1}{\tilde{\alpha}} - \frac{1}{\alpha} - \tilde{L}$, and the above inequalities yield

$$-\frac{m}{\alpha} \leq -\frac{m(1 + \alpha\tilde{L})}{\alpha(1 + m + \alpha\tilde{L})} \leq \Delta \leq \frac{\tilde{m}(1 - \tilde{\alpha}\tilde{L})}{\tilde{\alpha}(1 + \tilde{m} - \tilde{\alpha}\tilde{L})} \leq \frac{\tilde{m}}{\tilde{\alpha}}.$$

By (5.17) and the definition of m and $\tilde{m}$ we have $\frac{m}{\alpha} \leq \frac{\mu}{\alpha}(1 - \alpha L) = \mu \mathcal{E}(\tau_{1,L})$, $\frac{\tilde{m}}{\tilde{\alpha}} \leq \frac{\mu}{\tilde{\alpha}}(1 - \tilde{\alpha}\tilde{L}) = \mu \mathcal{E}(\tau_{1,\tilde{L}})$. This yields, anticipating on the right hand side that $\mu < 1$,

$$|\mathcal{E}(\tau_{1,L}) - \mathcal{E}(\tau_{1,\tilde{L}})| \leq \mu \max\{\mathcal{E}(\tau_{1,L}), \mathcal{E}(\tau_{1,\tilde{L}})\} \leq \frac{\mu}{1 - \mu} \min\{\mathcal{E}(\tau_{1,L}), \mathcal{E}(\tau_{1,\tilde{L}})\}.$$

The value of μ depends on the choice of v and is close to its minimum for $v = 1/8$ for which case we have the upper bound $\mu \leq \exp(-2\pi L - 2)$ and the lemma follows. $\square$

In the next lemma we estimate the variation of the essential energy of τ_1 under quasi-conformal mappings. It will be used in Sect. 7 to compare $\mathcal{E}(\tau_1^G)$ with $\mathcal{E}(\tau_1^F)$. We prove the lemma for the following situation. The mapping $\phi : R' \rightarrow R$ is a $(1 + \varepsilon)$ -quasi conformal homeomorphism between compact hyperbolic surfaces of genus g . On R' and R nonseparating simple closed geodesics γ', γ of lengths $\ell(\gamma') = \ell(\gamma)$ are given and ϕ maps the standard collar $C(\gamma')$ conformally (and, hence, isometrically) to $C(\gamma)$. We denote by σ_1, σ'_1 the first elements of the dual bases corresponding to homology bases on R, R' that have as second member $\alpha_2 = \gamma, \alpha'_2 = \gamma'$, and τ_1, τ'_1 are the renormalizations of σ_1, σ'_1 whose linear parts in the collars are equal to dx .

Lemma 5.6 *Under the above conditions for the compact Riemann surfaces R, R' we have*

$$|\mathcal{E}(\tau_1) - \mathcal{E}(\tau'_1)| \leq \frac{\varepsilon}{1 - \varepsilon} \min\{\mathcal{E}(\tau_1), \mathcal{E}(\tau'_1)\}.$$

Proof We let $\mathfrak{M} \subset R, \mathfrak{M}' \subset R'$ be the main parts with respect to the cylinders $C(\gamma), C(\gamma')$ as in (5.2). By Lemma 5.3 the linear parts of σ_1 and σ'_1 in the collars are αdx and $\alpha' dx$ respectively, with $\alpha = E_R(\sigma_1)$ and $\alpha' = E_{R'}(\sigma'_1)$. Now $\phi^*\sigma_1$ is in the cohomology class of σ'_1 and therefore $\alpha' \leq E_{R'}(\phi^*\sigma_1)$. Since ϕ is $(1 + \varepsilon)$ -quasi conformal on $\mathfrak{M}'$ and conformal on $R' \setminus \mathfrak{M}'$ we get

$$\alpha' \leq (1 + \varepsilon)E_{\mathfrak{M}}(\sigma_1) + E_{R \setminus \mathfrak{M}}(\sigma_1) = \varepsilon E_{\mathfrak{M}}(\sigma_1) + \alpha$$

(using that pointwise, as in (4.14), $\|(\phi^*\sigma_1)(p)\|^2 d\text{vol}(R') \leq (1 + \varepsilon)\|\sigma_1(\phi(p))\|^2 \phi^*(d\text{vol}(R))$ for $p \in \mathfrak{M}'$). By the Orthogonality Lemma

$$E_{\mathfrak{M}}(\sigma_1) \leq E_R(\sigma_1) - \alpha^2 L = \alpha - \alpha^2 L.$$

It follows that

$$\alpha' \leq \alpha + \varepsilon(\alpha - \alpha^2 L).$$

Using that the essential energies are given by $\mathcal{E}(\tau_1) = \frac{1}{\alpha} - L$ and $\mathcal{E}(\tau'_1) = \frac{1}{\alpha'} - L$ (5.17) we get

$$\mathcal{E}(\tau_1) - \mathcal{E}(\tau'_1) = \frac{1}{\alpha} - \frac{1}{\alpha'} \leq \frac{1}{\alpha} \cdot \frac{\varepsilon(1 - \alpha L)}{1 + \varepsilon(1 - \alpha L)} \leq \frac{\varepsilon(1 - \alpha L)}{\alpha} = \varepsilon \mathcal{E}(\tau_1).$$

Hence, $(1 - \varepsilon)\mathcal{E}(\tau_1) \leq \mathcal{E}(\tau'_1)$. Applying this result to ϕ^{-1} we have, in the same way, $(1 - \varepsilon)\mathcal{E}(\tau'_1) \leq \mathcal{E}(\tau_1)$. The two inequalities together yield Lemma 5.6. $\square$

5.3 Bounds for $\text{cap}(\mathfrak{M})$ and Γ

The estimates in Lemmas 5.2, 5.4, 5.5 and 5.6 are in terms of $\Gamma = 1/\text{cap}(\mathfrak{M})$ which is an analytic constant. We further estimate $\text{cap}(\mathfrak{M})$ geometrically using the following quantities: $d_{\mathfrak{M}}$ is the distance between the two boundary components and $\rho_{\mathfrak{M}} := \frac{1}{4} \min\{1, \text{sys}(\mathfrak{M})\}$, where $\text{sys}(\mathfrak{M})$ is the *systole*, i.e. the length of the shortest closed geodesic on $\mathfrak{M}$. With these constants we have the following rough upper and lower bounds for the capacity:

Theorem 5.7

$$\frac{\rho_{\mathfrak{M}}}{d_{\mathfrak{M}}} < \text{cap}(\mathfrak{M}) = \frac{1}{\Gamma} < \min \left\{ \frac{4\pi(g-1)}{d_{\mathfrak{M}}^2}, 1 \right\}.$$

Proof The inequality $\frac{1}{\Gamma} \leq 1$ is given in (5.5). For the second inequality we follow the lines of [18] where a stronger result is proved.

For the lower bound we consider the harmonic function h on $\mathfrak{M}$ that realizes the boundary conditions $h|_{c_1} = 0, h|_{c_2} = 1$ and restrict it to the ribbon $W = \{p \in \mathfrak{M} \mid \text{dist}(p, A) \leq \rho_{\mathfrak{M}}\}$, where A is the shortest geodesic from c_1 to c_2 . This geodesic has length $d_{\mathfrak{M}}$ and is orthogonal to the boundary at the endpoints. By the size of $\rho_{\mathfrak{M}}$ the geodesic arcs of length $\rho_{\mathfrak{M}}$ emanating orthogonally from A are pairwise disjoint. This follows by the lines of the proof of the main theorem in [6], where a corresponding result is shown for the diameter of a Riemann surface. Introducing Fermi coordinates for W based on A we get therefore a coordinate description of W that makes it isometric to the set

$$W' = \{(x, y) \in \mathbb{R}^2 \mid 0 \leq x \leq d_{\mathfrak{M}}, -\rho_{\mathfrak{M}} \leq y \leq \rho_{\mathfrak{M}}\}$$

endowed with the Riemannian metric $ds^2 = \cosh^2(y)dx^2 + dy^2$. This is true except for a negligible difference at the left and right end of W' which will not affect our rough estimates. Now W' in turn is conformally equivalent to the flat strip (with the standard Euclidean metric) $W'' = \{(x, y) \in \mathbb{R}^2 \mid 0 \leq x \leq d_{\mathfrak{M}}, -\rho'' \leq y \leq \rho''\}$, where $\rho'' = 2 \arctan(\tanh \frac{1}{2} \rho_{\mathfrak{M}})$ (use (2.11) with $\ell(\gamma)$ replaced by 1). Identifying W with W'' we can now write

$$\begin{aligned} \text{cap}(\mathfrak{M}) &> \int_{W''} \|dh\|^2 d\text{vol} = \int_{-\rho''}^{\rho''} \int_0^{d_{\mathfrak{M}}} \left(\frac{\partial h}{\partial x} \right)^2 + \left(\frac{\partial h}{\partial y} \right)^2 dx dy \\ &\geq \int_{-\rho''}^{\rho''} \int_0^{d_{\mathfrak{M}}} \left(\frac{\partial h}{\partial x} \right)^2 \geq \int_{-\rho''}^{\rho''} \frac{1}{d_{\mathfrak{M}}} dy = \frac{2\rho''}{d_{\mathfrak{M}}} > \frac{\rho_{\mathfrak{M}}}{d_{\mathfrak{M}}}. \end{aligned}$$

For the upper bound we take the test function $f = \frac{1}{d_{\mathfrak{M}}} F$ on $\mathfrak{M}$, where F is defined by the condition $F(p) = \text{dist}(p, c_1)$ if $d(p, c_1) \leq \frac{1}{2}d_{\mathfrak{M}}$, $F(p) = d_{\mathfrak{M}} - \text{dist}(p, c_2)$ if $d(p, c_2) \leq \frac{1}{2}d_{\mathfrak{M}}$ and $F(p) = \frac{1}{2}d_{\mathfrak{M}}$ in the remaining cases. Now $\|dF\| \leq 1$, $\|df\| \leq \frac{1}{d_{\mathfrak{M}}}$ and $\text{cap}(\mathfrak{M}) \leq \int_{\mathfrak{M}} \|df\|^2 d\text{vol} \leq \text{area}(\mathfrak{M})d_{\mathfrak{M}}^{-2} = 4\pi(g-1)d_{\mathfrak{M}}^{-2}$. $\square$

6 Relaxed dual basis

As pointed out in Sect. 1 two difficulties arise in the nonseparating case: the homology changes in the limit and the normalization condition $\int_{\alpha_1} \sigma_j = 0$, for $j = 2, \dots, 2g$ disappears. In this section we deal with the second problem by introducing a weaker concept of dual basis of harmonic forms $\sigma_1, \tau_2, \tau_3, \dots, \tau_{2g}$, where the τ_j have the same periods as the σ_j . However, the condition $\int_{\alpha_1} \tau_j = 0$ is dropped and replaced by the condition that the energy of these

forms is minimal. This allows us to compare the energy of elements in a dual basis on S with the energy of elements of the relaxed basis on the limit surface. The harmonic forms of this basis have some nice properties that are interesting by themselves. In Sect. 7 we use them to prove Theorems 1.3 and 1.4.

6.1 The forms τ_j for $j = 2, \dots, 2g$

Let again S be a compact Riemann surface of genus $g \geq 2$, γ a nonseparating simple closed geodesic on S , $\alpha_1, \dots, \alpha_{2g}$ a canonical homology basis with $\alpha_2 = \gamma$ enumerated such that α_{2j-1} intersects α_{2j} , $j = 1, \dots, g$, and $\sigma_1, \dots, \sigma_{2g}$ the dual basis of harmonic 1-forms. As earlier we extend these notions to any surface in the family $(S_L)_{L>0}$, write, however, most of the time σ_i instead of $\sigma_{i,L}$, $i = 1, \dots, 2g$, and similarly for τ_1 and the forms τ_j introduced next.

We introduce the modified basis $\sigma_1, \tau_2, \tau_3, \dots, \tau_{2g}$ on S_L by the following stipulations, for $j = 2, \dots, 2g$:

- (a) $\int_{\alpha_i} \tau_j = \delta_{ij}$, $i = 2, \dots, 2g$;
- (b) τ_j is the harmonic form with the minimal energy that satisfies (a).

We call $(\sigma_1, \tau_2, \dots, \tau_{2g})$ the *relaxed dual basis*. (An alternative is to view $(\tau_1, \tau_2, \dots, \tau_{2g})$ as the relaxed dual basis despite the fact that τ_1 does not have period 1).

It is easy to see that τ_j is also an energy minimizer among *all* closed 1-forms that satisfy

- (a) We introduce the periods

$$\kappa_j = \kappa_{j,L} = - \int_{\alpha_1} \tau_j, \quad j = 2, \dots, 2g. \quad (6.1)$$

Again, if it is clear from the context we will use κ_j instead of $\kappa_{j,L}$, $j = 2, \dots, 2g$. By (a) and because $\sigma_1, \dots, \sigma_{2g}$ is a dual basis we then have

$$\sigma_j = \tau_j + \kappa_j \sigma_1, \quad j = 2, \dots, 2g. \quad (6.2)$$

Lemma 6.1 *For $j = 2, \dots, 2g$ we have*

$$\langle \tau_j, \sigma_1 \rangle = 0.$$

Proof If ω is a harmonic 1-form on S that, for given j , satisfies the condition $\int_{\alpha_i} \omega = \delta_{ij}$, for $i = 2, \dots, 2g$, then $\omega = \sigma_j + t\sigma_1$, for some $t \in \mathbb{R}$. The function $f(t) = E(\sigma_j + t\sigma_1) = E(\sigma_j) + 2t\langle \sigma_j, \sigma_1 \rangle + t^2 E(\sigma_1)$ has a unique minimum at $t_0 = -\langle \sigma_j, \sigma_1 \rangle / E(\sigma_1)$. Hence,

$$\tau_j = \sigma_j + t_0 \sigma_1 = \sigma_j - \frac{\langle \sigma_j, \sigma_1 \rangle}{E(\sigma_1)} \sigma_1,$$

and the lemma follows. $\square$

Taking in (6.2) the scalar product with σ_1 we now get

$$\kappa_j = \frac{\langle \sigma_1, \sigma_j \rangle}{\langle \sigma_1, \sigma_1 \rangle}, \quad j = 2, \dots, 2g. \quad (6.3)$$

For the next lemma we consider an annular neighborhood $\mathcal{C}$ of γ ($\mathcal{C}$ need not be a distance neighborhood) and a conformal mapping ψ that sends $\mathcal{C}$ onto a flat cylinder $Z = (-m_1, m_2) \times \mathbb{S}_1$ for some $m_1, m_2 > 0$. For the cylinder we use the notation as in

Sect. 3. In particular, x is the variable that runs through $[-m_1, m_2]$ and y runs through $\mathbb{S}_1 = \mathbb{R}/\mathbb{Z}$. The mapping ψ is assumed to be such that the image of γ is the circle $\{0\} \times \mathbb{S}_1$. The couple (Z, ψ) serves as a coordinate system for $\mathcal{C}$, and by abuse of notation we write $f = f \circ \psi^{-1}$ for the representation of functions on $\mathcal{C}$, and $\omega = (\psi^{-1})^* \omega$ for 1-forms on $\mathcal{C}$.

Lemma 6.2 *On $\mathcal{C}$ the τ_j have vanishing linear dx -terms, $j = 2, \dots, 2g$.*

Proof Without loss of generality we assume that $m_1 = m_2 = m$. We first consider the case $j \geq 3$. Then τ_j on $\mathcal{C}$ has a representation

$$\tau_j = adx + dh^{\text{nl}}, \quad (6.4)$$

where dh^{nl} is the nonlinear part with a harmonic function h^{nl} . We have to show that $a = 0$. We shall achieve this by dampening down, using the function

$$F(x, y) = \begin{cases} 0, & \text{for } x \leq 0 \\ ax & \text{for } 0 \leq x \leq m/2 \\ am/2 & \text{for } x \geq m/2. \end{cases}$$

Interpreting F as a function on $\mathcal{C}$ we define the closed form $\omega_F = dF$ on $\mathcal{C}$ and $\omega_F = 0$ on $S \setminus \mathcal{C}$. The difference $t_j = \tau_j - \omega_F$ has periods $\int_{\alpha_i} t_j = \delta_{ij}$, for $i = 2, \dots, 2g$. By the energy minimizing property of τ_j we have

$$E(t_j) \geq E(\tau_j). \quad (6.5)$$

Outside of the part $D = [0, \frac{m}{2}] \times \mathbb{S}_1$ the forms τ_j and t_j coincide. On D we may write

$$\tau_j = t_j + dF = t_j + adx,$$

where by (6.4) $t_j = dh^{\text{nl}}$. By the Orthogonality Lemma,

$$E_D(\tau_j) = E_D(t_j) + a^2 E_D(dx).$$

Since τ_j and t_j coincide outside of D we also have

$$E(\tau_j) = E(t_j) + a^2 E_D(dx). \quad (6.6)$$

Now (6.5) and (6.6) imply $a = 0$. The proof for the case $j = 2$ is the same except that instead of (6.4) we have $\tau_2 = adx + dy + dh^{\text{nl}}$, and on D we have $t_2 = dh^{\text{nl}} + dy$, where we recall that dx and dy are orthogonal on D . $\square$

Remark 6.3 As a consequence of Lemma 6.2 τ_1 can be written as a linear combination

$$\tau_1 = \star \tau_2 + \sum_{k=3}^{2g} c_k \tau_k.$$

For the proof we note that, by the lemma, $\tau_1 - \star \tau_2$ and $\tau_3, \dots, \tau_{2g}$ have vanishing linear parts, while σ_1 has linear part cdx with $c \neq 0$ and τ_2 has linear part dy . Hence, in the basis representation $\tau_1 - \star \tau_2 = c_1 \sigma_1 + c_2 \tau_2 + \sum_{k=3}^{2g} c_k \tau_k$ we must have $c_1 = c_2 = 0$.

6.2 Essential energy and the periods κ_j

In this section we investigate the convergence of the periods κ_j (see (6.1)) as $\ell(\gamma) \rightarrow 0$ and also under the grafting construction. In order to avoid repetitions we prove the main technical lemma (Lemma 6.4) in a slightly more general context. Furthermore, in order to remain in the realm of compact surfaces we carry out the comparison with compact surfaces that have a thin handle and cover the cusp case by a limiting argument in Sect. 7.

The setting for the lemma is as follows. $S_L^\times$ is the surface as in the preceding section consisting of the main part $\mathfrak{M}$ (5.2) to which two flat cylinders $[0, L/2] \times \mathbb{S}_1$ are attached, and S_L results from $S_L^\times$ by pasting together the two boundaries. These surfaces shall be compared with a second pair, $\tilde{S}_L^\times$, $\tilde{S}_L$, defined in a similar way with some main part $\tilde{\mathfrak{M}}$ to which cylinders of lengths $\tilde{L}/2$ are attached. Furthermore, it is assumed that

$$\tilde{L} \geq L > 4 \quad (6.7)$$

and that a marking preserving $q\phi$ -quasiconformal boundary coherent homeomorphism $\phi : \mathfrak{M} \rightarrow \tilde{\mathfrak{M}}$ is given that acts conformally near the boundary and thus extends to an embedding of $S_L^\times$ into $\tilde{S}_L^\times$ that acts isometrically on the flat cylinders. Finally, we assume that the pastings are such that the twist parameters of S_L and $\tilde{S}_L$ are the same. By this we mean that, as in the grafting construction, if line $[0, L] \times \{y_0\}$ of the inserted cylinder $[0, L] \times \mathbb{S}_1$ in S_L is pasted to the boundary points p_1, p_2 of $\mathfrak{M}$, then line $[0, \tilde{L}] \times \{y_0\}$ of the inserted cylinder $[0, \tilde{L}] \times \mathbb{S}_1$ in $\tilde{S}_L$ is pasted to the boundary points $\phi(p_1), \phi(p_2)$ of $\tilde{\mathfrak{M}} = \phi(\mathfrak{M})$.

For the grafting construction we shall have $\tilde{\mathfrak{M}} = \mathfrak{M}$ with ϕ the identity mapping; in the Fenchel–Nielsen construction $\tilde{\mathfrak{M}}$ is the main part of the surface $\tilde{S}$ with geodesic $\tilde{\gamma}$ that results from the construction and ϕ is the q -quasiconformal mapping as in Theorem 2.3 with $q \leq (1 + 2\ell^2(\gamma))^2$, and $\tilde{L} = L_{\tilde{\gamma}}$.

As for the bases, the quasiconformal mapping $\phi : \mathfrak{M} \rightarrow \tilde{\mathfrak{M}}$ extends to a topological mapping $\varphi : S_L \rightarrow \tilde{S}_L$ that operates on the cylinders by stretching them in the x -direction. We define $\tilde{\alpha}_i = \varphi(\alpha_i)$, for $i = 1, \dots, 2g$, and let $\tilde{\sigma}_1, \dots, \tilde{\sigma}_{2g}$ be the dual basis of harmonic forms for $\tilde{\alpha}_1, \dots, \tilde{\alpha}_{2g}$ on $\tilde{S}_L$. Finally, for $j = 2, \dots, 2g$, $\tilde{\tau}_j$ on $\tilde{S}_L$ is the analog of τ_j on S_L .

As L becomes large, the energies of $\tau_3, \dots, \tau_{2g}$ remain bounded owing to the fact that their linear parts vanish in the cylinder $[0, L] \times \mathbb{S}_1$ (using Lemma 6.2). This is not the case for τ_2 . For this reason we define for τ_2 and, more generally, for any linear combination $\tau = a_2\tau_2 + \dots + a_{2g}\tau_{2g}$ an *essential energy* $\mathcal{E}(\tau)$ as in (5.14) setting

$$\mathcal{E}(\tau) = E_{\mathfrak{M}}(\tau) + E_C(\tau^{\text{nl}}), \quad (6.8)$$

where C is the cylinder $C = S_L \setminus \mathfrak{M}$ which we identify with the conformally equivalent $[0, L] \times \mathbb{S}_1$ and $()^{\text{nl}}$ denotes the nonlinear part. For later use we also define the scalar product

$$\langle \omega, \eta \rangle_{\mathfrak{M}} \stackrel{\text{def}}{=} \int_{\mathfrak{M}} \omega \wedge \star \eta + \int_{C(\gamma)} \omega^{\text{nl}} \wedge \star \eta^{\text{nl}}. \quad (6.9)$$

for ω and η in the span of $(\tau_i)_{i=2, \dots, 2g}$.

By the Orthogonality Lemma $\mathcal{E}(\tau)$ may also be defined as follows,

$$\mathcal{E}(\tau) = E(\tau) - a_2^2 L. \quad (6.10)$$

On $\tilde{S}_L$ we define $\mathcal{E}$ in an analogous way. For the comparison of these energies and also for the comparison of the periods κ_j of τ_j over α_1 and $\tilde{\kappa}_j$ of $\tilde{\tau}_j$ over $\tilde{\alpha}_j$, $j = 2, \dots, 2g$ we

introduce the following constants,

$$\mu_L = e^{-2\pi L}, \quad \nu_L = \frac{1}{12}\mu_L q_\phi + q_\phi - 1, \quad \rho_L = \left[q_\phi \left(1 + \frac{1}{12}\mu_L \right) \right]^2 - 1. \quad (6.11)$$

Lemma 6.4 *Under the condition of the above setting we have, for any $\tau = a_2\tau_2 + \cdots + a_{2g}\tau_{2g}$ on S_L and the corresponding $\tilde{\tau} = a_2\tilde{\tau}_2 + \cdots + a_{2g}\tilde{\tau}_{2g}$ on $\tilde{S}_L$,*

$$|\mathcal{E}(\tau) - \mathcal{E}(\tilde{\tau})| < \nu_L \min\{\mathcal{E}(\tau), \mathcal{E}(\tilde{\tau})\}. \quad (6.12)$$

For ω, η in the span of $(\tau_i)_{i=2,\dots,2g}$ and $\tilde{\omega}, \tilde{\eta}$ in the span of $(\tilde{\tau}_i)_{i=2,\dots,2g}$ we have

$$|\langle \omega, \eta \rangle_{\mathfrak{M}} - \langle \tilde{\omega}, \tilde{\eta} \rangle_{\tilde{\mathfrak{M}}}| \leq \nu_L \min\{\mathcal{E}^{1/2}(\omega)\mathcal{E}^{1/2}(\eta), \mathcal{E}^{1/2}(\tilde{\omega})\mathcal{E}^{1/2}(\tilde{\eta})\}. \quad (6.13)$$

Furthermore, for $j = 2, \dots, 2g$,

$$|\kappa_j - \tilde{\kappa}_j|^2 < 3\rho_L(1 + 3\Gamma) \min\{\mathcal{E}(\tau_j), \mathcal{E}(\tilde{\tau}_j)\}. \quad (6.14)$$

Proof By Lemma 6.2, τ and $\tilde{\tau}$ have vanishing linear dx terms. Furthermore, the dy -terms of τ_j and $\tilde{\tau}_j$ are $\delta_{2j}dy$ because $\int_{\alpha_2} \tau_j = \int_{\tilde{\alpha}_2} \tilde{\tau}_j = \delta_{2j}$, $j = 2, \dots, 2g$. Hence, τ and $\tilde{\tau}$ have the same linear term a_2dy on the flat cylinders. Taking $w = \frac{1}{8}$ we dampen down the nonlinear terms of τ and $\tilde{\tau}$ using the same cut off function χ that equals 1 up to distance $L/2 - w$ from $\mathfrak{M}$, respectively $\tilde{\mathfrak{M}}$, then goes down linearly to 0 from distance $L/2 - w$ to distance $L/2$ and remains 0 on the rest (distances with respect to the flat metric of $Z = [-L/2, L/2] \times \mathbb{S}_1$ and $\tilde{Z} = [-\tilde{L}/2, \tilde{L}/2] \times \mathbb{S}_1$).

In the following we think of S_L and $S_L^\times$ as “sitting on the left hand side,” while $\tilde{S}_L$ and $\tilde{S}_L^\times$ “sit on the right hand side”. The mapping ϕ then goes from the left to the right.

The dampened down form $\tilde{\tau}_\chi$ may be restricted to the subset $\tilde{S}_L^\times$ of $\tilde{S}_L$, then be pushed in the left direction to $S_L^\times$ via the quasiconformal mapping ϕ^{-1} and, upon arrival, be extended to S_L . The so extended form shall be denoted by $\tilde{\tau}^\leftarrow$. As a result of the dampening down procedure $\tilde{\tau}^\leftarrow$ is a test form in the cohomology class of τ . In a converse way, we push in the right direction the dampened down form τ_χ to $\tilde{S}_L^\times$ and extend it by a_2dy to a test form $\tau^\rightarrow$ on $\tilde{S}_L$ in the cohomology class of $\tilde{\tau}$. It follows, using the Orthogonality Lemma 3.2 that

$$\mathcal{E}(\tau) \leq \mathcal{E}(\tilde{\tau}^\leftarrow), \quad \mathcal{E}(\tilde{\tau}) \leq \mathcal{E}(\tau^\rightarrow). \quad (6.15)$$

Observe that the dampening down process takes place in a subset of the respective cylinders $[-d_\gamma - L/2, L/2 + d_\gamma] \times \mathbb{S}_1$ and $[-d_{\tilde{\gamma}} - \tilde{L}/2, \tilde{L}/2 + d_{\tilde{\gamma}}] \times \mathbb{S}_1$, where by (5.4) $d_\gamma, d_{\tilde{\gamma}} > \frac{1}{2}$. Hence, Lemma 3.3 (with $l = L/2 + \frac{1}{2}$, $dh^\#$ the nonlinear term of $\tilde{\tau}$, respectively $\tilde{\tau}$, $\delta_\# = l - w$, and $w = \frac{1}{8}$) yields that $\mathcal{E}(\tau_\chi) < (1 + \frac{1}{12}\mu_L)\mathcal{E}(\tau)$ and $\mathcal{E}(\tilde{\tau}_\chi) < (1 + \frac{1}{12}\mu_L)\mathcal{E}(\tilde{\tau})$. Since ϕ and ϕ^{-1} act isometrically on the cylinders and are q_ϕ -quasiconformal on $\mathfrak{M}$ and $\tilde{\mathfrak{M}}$, it follows from [17] (or Lemma 4.5) that the essential energy increases at most by a factor q_ϕ . This yields

$$\mathcal{E}(\tilde{\tau}^\leftarrow) \leq q_\phi \left(1 + \frac{1}{12}\mu_L \right) \mathcal{E}(\tilde{\tau}), \quad \mathcal{E}(\tau^\rightarrow) < q_\phi \left(1 + \frac{1}{12}\mu_L \right) \mathcal{E}(\tau). \quad (6.16)$$

Now (6.15) and (6.16) imply (6.12).

The operator that associates to any $\omega = c_2\tau_2 + \cdots + c_{2g}\tau_{2g} \in H^1(S_L, \mathbb{R})$ the form $\tilde{\omega} = c_2\tilde{\tau}_2 + \cdots + c_{2g}\tilde{\tau}_{2g} \in H^1(\tilde{S}_L, \mathbb{R})$ is linear. Hence, using (6.12) in Lemma 4.4 inequality (6.13) follows.

We turn to the proof of (6.14) and apply the preceding notations and results to the forms $\tau = \tau_j$, $\tilde{\tau} = \tilde{\tau}_j$. Since the dampening down process on S_L and $\tilde{S}_L$ acts as the identity in

the neighborhoods of the boundaries of the collars, and since ϕ preserves line integrals, the period $\tilde{\kappa}_j$ is not affected and, hence,

$$\int_{\alpha_1} (\tilde{\tau}_j^{\leftarrow} - \tau_j) = -\tilde{\kappa}_j + \kappa_j.$$

Since the periods of $\tilde{\tau}_j^{\leftarrow} - \tau_j$ over the remaining base cycles vanish we have therefore on S_L

$$\tilde{\tau}_j^{\leftarrow} = \tau_j - (\tilde{\kappa}_j - \kappa_j)\sigma_{1,L} + df_j$$

for some function f_j . By Lemma 6.1 the forms on the right hand side are mutually orthogonal so that

$$E(\tilde{\tau}_j^{\leftarrow}) = E(\tau_j) + (\tilde{\kappa}_j - \kappa_j)^2 E(\sigma_{1,L}) + E(df_j).$$

Since $E(\tilde{\tau}_j^{\leftarrow} - \tau_j) = (\tilde{\kappa}_j - \kappa_j)^2 E(\sigma_{1,L}) + E(df_j)$ and since $\tilde{\tau}_j^{\leftarrow}$ and τ_j have the same linear part (dy if $j = 2$ and 0 if $j \geq 3$) we get

$$E(\tilde{\tau}_j^{\leftarrow} - \tau_j) = E(\tilde{\tau}_j^{\leftarrow}) - E(\tau_j) = \mathcal{E}(\tilde{\tau}_j^{\leftarrow}) - \mathcal{E}(\tau_j).$$

Now if $\mathcal{E}(\tilde{\tau}_j) \leq \mathcal{E}(\tau_j)$, then by the first inequality in (6.16)

$$\mathcal{E}(\tilde{\tau}_j^{\leftarrow}) - \mathcal{E}(\tau_j) \leq \mathcal{E}(\tilde{\tau}_j^{\leftarrow}) - \mathcal{E}(\tilde{\tau}_j) \leq (q_\phi(1 + \frac{1}{12}\mu_L) - 1)\mathcal{E}(\tilde{\tau}_j).$$

If, on the other hand, $\mathcal{E}(\tilde{\tau}_j) > \mathcal{E}(\tau_j)$, then by the first inequality in (6.16), the second inequality in (6.15) and the second inequality in (6.16)

$$\mathcal{E}(\tilde{\tau}_j^{\leftarrow}) - \mathcal{E}(\tau_j) \leq q_\phi \left(1 + \frac{1}{12}\mu_L\right) \mathcal{E}(\tilde{\tau}_j) - \mathcal{E}(\tau_j) \leq \left([q_\phi \left(1 + \frac{1}{12}\mu_L\right)]^2 - 1\right)\mathcal{E}(\tau_j).$$

Altogether

$$E(\tilde{\tau}_j^{\leftarrow} - \tau_j) \leq \rho_L \min\{\mathcal{E}(\tau_j), \mathcal{E}(\tilde{\tau}_j)\}.$$

Now $\tilde{\tau}_j^{\leftarrow}$ and τ_j have vanishing linear dx -part. We dampen down $(\tilde{\tau}_j^{\leftarrow} - \tau_j)$ using the cut off function χ' that goes linearly from 1 to 0 within distance $\frac{1}{2}$ from $\mathfrak{M}$ and then remains zero. The resulting form is denoted by θ_j . Its period over α_1 is still $-(\tilde{\kappa}_j - \kappa_j)$. By Lemma 3.3 applied twice (with $l = \frac{1}{4}$, $\delta_\# = \delta = 0$ and $w = \frac{1}{2}$) the energy of θ_j has the upper bound

$$E(\theta_j) \leq 3E(\tilde{\tau}_j^{\leftarrow} - \tau_j) \leq 3\rho_L \min\{\mathcal{E}(\tau_j), \mathcal{E}(\tilde{\tau}_j)\}.$$

That Lemma 3.3 is indeed applicable follows from the fact that ϕ acts isometrically on the cylinders, whose lengths, by (6.7), are $\geq L/2 > 2$ and, hence, θ_j is harmonic in the domain where the dampening down process takes place. Now θ_j may also be interpreted as a test form on the surface S_1 that is obtained by attaching cylinders $[0, \frac{1}{2}] \times \mathbb{S}_1$ to $\mathfrak{M}$ and then pasting the boundaries together with the same twist parameter as S_L . This means that if points $p \in c_1$, $q \in c_2$ on the boundary of $\mathfrak{M}$ are connected by the straight line $[0, L] \times \{y_0\}$ in $[0, L] \times \mathbb{S}_1 \subset S_L$ then they are connected by the straight line $[0, 1] \times \{y_0\}$ in $[0, 1] \times \mathbb{S}_1 \subset S_1$. Only this time, the cutting and pasting takes place at $L/2 \times \mathbb{S}_1$ and $\frac{1}{2} \times \mathbb{S}_1$, respectively. On S_1 we have the following decomposition (where $\sigma_{1,1}$ is $\sigma_{1,L}$ with $L = 1$): $\theta_j = -(\tilde{\kappa}_j - \kappa_j)\sigma_{1,1} + dF_j$ for some function F_j . By Lemma 5.2, applied to the case $L = 1$, we have $E(\sigma_{1,1}) \geq \frac{1}{1+3\Gamma}$. Altogether we have

$$|\kappa_j - \tilde{\kappa}_j|^2 \frac{1}{1+3\Gamma} \leq 3\rho_L \min\{\mathcal{E}(\tau_j), \mathcal{E}(\tilde{\tau}_j)\}$$

and (6.14) follows. $\square$

6.3 Bounds for κ_j

Lemma 6.5 For $j = 3, \dots, 2g$ we have on S_L

$$|\kappa_j| \leq \sqrt{\mathcal{E}(\tau_2) E(\tau_j)} < \sqrt{\mathcal{E}(\tau_2) E(\sigma_j)}.$$

Proof We use the following identity for closed differentials θ, η ,

$$\int_{S_L} \theta \wedge \eta = \sum_{k=1}^g \left[\int_{\alpha_{2k}} \theta \int_{\alpha_{2k-1}} \eta - \int_{\alpha_{2k-1}} \theta \int_{\alpha_{2k}} \eta \right] \quad (6.17)$$

(e.g. [11, III.2.3]). Taking $\theta = \tau_2$, $\eta = \tau_j$, ($j \geq 3$), we get $\int_{S_L} \tau_2 \wedge \tau_j = \int_{\alpha_1} \tau_j = -\kappa_j$. Hence,

$$\kappa_j = \langle \tau_2, \star \tau_j \rangle, \quad j = 3, \dots, 2g. \quad (6.18)$$

By Lemma 6.2 τ_j has vanishing linear part in the cylinder $C = S_L \setminus \mathfrak{M}$ (which we identify with the conformally equivalent $[0, L] \times \mathbb{S}_1$). Using the Orthogonality Lemma we may thus write

$$\int_C \tau_2 \wedge \tau_j = \int_C \tau_2^{\text{nl}} \wedge \tau_j,$$

where $(\cdot)^{\text{nl}}$ is the nonlinear part. Setting

$$\hat{\tau}_2 = \begin{cases} \tau_2^{\text{nl}} & \text{on } C \\ \tau_2 & \text{on } S_L \setminus C \end{cases}$$

we get

$$\int_{S_L} \tau_2 \wedge \tau_j = \int_{S_L} \hat{\tau}_2 \wedge \tau_j.$$

(The fact that $\hat{\tau}_2$ is discontinuous at the boundary of C is not a problem here because we are only looking at integrals). We now use the Cauchy–Schwarz inequality:

$$\left| \int_{S_L} \hat{\tau}_2 \wedge \tau_j \right|^2 \leq E(\hat{\tau}_2) E(\tau_j).$$

On the right hand side $E(\hat{\tau}_2) = \mathcal{E}(\tau_2)$. This yields

$$|\langle \tau_2, \star \tau_j \rangle| \leq \sqrt{\mathcal{E}(\tau_2) E(\tau_j)}.$$

The first inequality of the lemma follows together with (6.18); the second inequality follows from (6.2) and Lemma 6.1 (which also holds on any S_L): $E(\sigma_j) = E(\tau_j + \kappa_j \sigma_1) = E(\tau_j) + \kappa_j^2 E(\sigma_1)$. $\square$

Remark 6.6 For $j = 2$ relation (6.17) is not conclusive. Indeed, by replacing α_1 with $\alpha_1 + k\alpha_2$, $k \in \mathbb{Z}$, one may arbitrarily increase $|\kappa_2|$ without affecting $\mathcal{E}(\tau_2)$, $E(\tau_j)$, $E(\sigma_j)$, $j = 3, \dots, 2g$. Hence, there is no a priori bound for $|\kappa_2|$ in terms of these quantities.

However, if in (6.17) we take $\theta = \star \tau_1$ and $\eta = \tau_2$, we get using Lemma 6.1 and observing that $\int_{\alpha_2} \star \tau_1 = 1$ (because τ_1 has linear part dx in C)

$$\kappa_2 = \int_{\alpha_1} \star \tau_1. \quad (6.19)$$

The relation shows that if in the choice of the canonical homology basis on S one begins with $\alpha_2 (= \gamma)$ and α_1 , then κ_2 is independent of the choice of $\alpha_3, \dots, \alpha_{2g}$.

A rough estimate of κ_2 in a different form shall be given in Lemma 6.9.

6.4 Bounds for the dual basis

The estimates in Lemmas 6.4 and 6.5 are in terms of the harmonic quantities $\mathcal{E}(\tau_1)$, $\mathcal{E}(\tau_2)$ and $E(\sigma_3), \dots, E(\sigma_{2g})$. In Sect. 5 a geometric upper bound for $\mathcal{E}(\tau_1)$ is obtainable via Lemma 5.4 and Theorem 5.7. We conclude this section with geometric bounds for the remaining quantities.

The first lemma provides bounds for the energies of τ_k on S_L and for the matrix entries $p_{kk}(S_L)$, $k \geq 3$, in terms of the lengths of the geodesics $\alpha_3, \dots, \alpha_{2g-1}, \alpha_{2g}$ of the canonical homology basis on the original surface S . In view of the intersection convention for this basis (Sect. 1) we set, for $k = 1, \dots, 2g$

$$\hat{k} = \begin{cases} k-1 & \text{if } k \text{ is even,} \\ k+1 & \text{if } k \text{ is odd.} \end{cases}$$

In the following we write $\tau_{k,L}, \kappa_{k,L}$ for τ_k and κ_k on S_L , $k = 2, \dots, 2g$.

Lemma 6.7 *For $k = 3, \dots, 2g$ we have*

$$E(\tau_{k,L}) = p_{kk}(S_L) - \kappa_{k,L}^2 p_{11}(S_L), \quad p_{kk}(S_L) \leq \frac{\ell(\alpha_{\hat{k}})}{\pi - 2 \arcsin \tanh \frac{1}{2} \ell(\alpha_{\hat{k}})}.$$

Proof The expression for $E(\tau_{k,L}) = \langle \tau_{k,L}, \tau_{k,L} \rangle$ follows from (6.2) and Lemma 6.1. To prove the inequality we construct a test form for σ_k on S_L using the hyperbolic metric on $\mathfrak{M}$. The standard collar $C(\alpha_{\hat{k}})$ on S is contained in $\mathfrak{M}$, by the Collar Lemma. It may therefore also be seen as a subset of S_L . There is a conformal homeomorphism ψ from the closure of $C(\alpha_{\hat{k}})$ to $Z = [-M, M] \times \mathbb{S}_1$ with M as in (2.13). Now let f on Z be defined by $f(x, y) = \frac{1}{2M}(x+M)$, for $x \in [-M, M]$, $y \in \mathbb{S}_1$. Then df and its pullback $\eta = \psi^* df$ on $C(\alpha_{\hat{k}})$ have energy $\frac{1}{2M}$. Setting $\psi = 0$ outside $C(\alpha_{\hat{k}})$ we get an admissible test form for σ_k , and the upper bound follows. $\square$

We add that for $\ell(\alpha_{\hat{k}}) \rightarrow \infty$ the upper bound grows asymptotically like $\frac{1}{4} \ell(\alpha_{\hat{k}}) \exp(\frac{1}{2} \ell(\alpha_{\hat{k}}))$.

In the second lemma we prove a geometric upper bound for $\mathcal{E}(\tau_{2,L})$. It is more elaborate since it involves the entire homology basis $A = (\alpha_1, \dots, \alpha_{2g})$. The geometric quantity we use is

$$w_A = \min \left\{ \frac{1}{4}, \frac{1}{4} \text{sys}(\mathfrak{M}), \text{cl}(\ell(\alpha_3)), \dots, \text{cl}(\ell(\alpha_{2g})) \right\} \quad (6.20)$$

with the systole of $\mathfrak{M}$ as in Sect. 5.3 and the widths cl of the standard collars as in (2.2).

Lemma 6.8 *For any $L > 0$, we have*

$$\mathcal{E}(\tau_{2,L}) = E(\sigma_{2,L}) - L - \kappa_{2,L}^2 p_{11}(S_L), \quad E(\sigma_{2,L}) < L + \frac{\pi g}{w_A^2}.$$

Proof The first statement is as in Lemma 6.7. For the second statement we construct a test form $s_{2,L}$ for $\sigma_{2,L}$ on S_L whose representation in the cylinder $Z_L = \{(x, y) \mid x \in [0, L], y \in \mathbb{S}_1\}$ attached to $\mathfrak{M}$ along c_1, c_2 coincides with dy .

For this we take the shortest geodesic $\mathcal{A}$ in $\mathfrak{M}' = \mathfrak{M} \setminus (\alpha_3 \cup \dots \cup \alpha_{2g})$ that connects the boundary curves c_1, c_2 with each other. Such a geodesic exists because the boundary of $\mathfrak{M}'$ has interior angles $< \pi$ at all of its vertices; if there are several such geodesics we take any of them. By the Collar Theorem $\mathcal{A}$ does not intersect any of the collars $C(\alpha_k)$ and thus has distance $\text{dist}(\mathcal{A}, \alpha_k) \geq w_A$, for $k = 3, \dots, 2g$. As in the proof of Theorem 5.3 the geodesic segments of length w_A emanating orthogonally from $\mathcal{A}$ (in both directions) are pairwise disjoint and sweep out a ribbon $\mathcal{W}$. In Fermi coordinates based on $\mathcal{A}$ the ribbon becomes

$$\{(\rho, t) \mid -w_A \leq \rho \leq w_A, 0 \leq t \leq \ell(\mathcal{A})\},$$

with the metric tensor $ds^2 = d\rho^2 + \cosh^2(\rho)dt^2$. We let f be the function on $\mathcal{W}$ that is defined in these coordinates by $f(\rho, t) = \frac{\rho}{2w_A}$. Its differential has norm $\|df(\rho, t)\| = \frac{1}{2w_A}$ and as $\mathcal{W} \subset S$ its energy has the upper bound

$$E_{\mathcal{W}}(df) = \frac{1}{4w_A^2} \text{area}(\mathcal{W}) < \frac{1}{4w_A^2} \text{area}(S) = \frac{1}{4w_A^2} 4\pi(g-1). \quad (6.21)$$

We now interpolate f in the annular regions $B_1, B_2 \subset \mathfrak{M}$ (adjacent to the boundary of $\mathfrak{M}$, see Sect. 5.1, prior to (5.2)) so that its differential matches with the differential dy on the attached cylinder Z_L . We complete the construction of $s_{2,L}$ by setting it to be dy on Z_L , df on the domain in $\mathfrak{M}$ where f (together with its interpolation) is defined, and setting $s_{2,L} = 0$ on the remaining part of $\mathfrak{M}$. The form is in the cohomology class of $\sigma_{2,L}$ and has the energy bound

$$E(s_{2,L}) \leq L + \frac{1}{4w_A^2} 4\pi(g-1) + \mathfrak{p},$$

where $\mathfrak{p}$ is the energy cost of the interpolation. A rough but somewhat tedious argument which we omit shows that the interpolation can be carried out with $\mathfrak{p} < 2$, and the lemma follows. $\square$

In the next lemma we write $\kappa_{2,L} = \kappa_2(S_L)$, for clarity.

Lemma 6.9 *There exists an effective constant K depending on g , on a lower bound of $\text{sys}(\mathfrak{M})$ and on an upper bound of $\ell(\alpha_1)$ on S such that for any $S_L, L \geq L_\gamma$ one has $|\kappa_2(S_L)| \leq K$.*

Proof By (6.3) using Cauchy–Schwarz we have on $S = S_{L_\gamma}$

$$|\kappa_2(S)|^2 \leq \frac{\langle \sigma_2, \sigma_2 \rangle}{\langle \sigma_1, \sigma_1 \rangle},$$

where by Lemma 5.2 $\frac{1}{\langle \sigma_1, \sigma_1 \rangle} \leq L_\gamma + \mathfrak{z}\Gamma$ and by Theorem 5.7 Γ is bounded above in terms of the systole of $\mathfrak{M}$ and g . Furthermore, by (6.14)

$$|\kappa_2(S) - \kappa_2(S_L)|^2 < 3\rho_{L_\gamma}(1 + \mathfrak{z}\Gamma)\mathcal{E}(\tau_2(S)),$$

where $\mathcal{E}(\tau_2(S))$ has a bound in terms of $g \text{ sys}(\mathfrak{M})$ and $\ell(\alpha_1)$ on S by Lemma 6.8. It suffices therefore to prove an upper bound of $E(\sigma_2)$ on S . For this we need an embedded ribbon around α_1 .

Let w be the supremum of all δ such that geodesic segments of length δ emanating orthogonally from α_1 are pairwise disjoint. Then there exists a segment η of length $2w$ on S that meets α_1 orthogonally on both endpoints. Lift α_1 to the universal covering of S . On this lift there is an arc a of length $\ell(\alpha_1)$ having two lifts η', η'' of η at its endpoints. On their other endpoints there are further lifts α'_1, α''_1 of α_1 . Since α_1 is a simple geodesic the latter do

not intersect each other. Hence a right angled geodesic hexagon with three consecutive sides of lengths $2w$, $\ell(\alpha_1)$, $2w$. This hexagon consists of two isometric pentagons each having a pair of consecutive sides $2w$, $\frac{1}{2}\ell(\alpha_1)$. By trigonometry $\sinh(2w) \sinh(\frac{1}{2}\ell(\alpha_1)) > 1$. Hence, a lower bound of w in terms of $\ell(\alpha_1)$.

Taking the function f_2 on the ribbon of width w that grows linearly along the orthogonal geodesics from 0 on one boundary to 1 on the other and setting $s_2 = df_2$ on the ribbon and $s_2 = 0$ outside we get a test function for σ_2 on S with the required energy bound. $\square$

7 Period matrix for a surface with two cusps

If we pinch a nonseparating simple closed geodesic then the limit surface has two cusps. A cusp neighborhood is conformally equivalent to a flat cylinder $Z_1 = (-\infty, 0] \times \mathbb{S}_1$ of infinite length. In this section we first look at the L^2 harmonic forms on this surface to which we add the harmonic forms whose linear part is dx and dy , respectively in the cylinder and show how these can be seen as the limits of forms in $(S_L)_L$. (As earlier x is the coordinate in the direction of $(-\infty, 0]$ and y is in the direction of $\mathbb{S}_1$.) Then we look at the compactified limit surface that has genus $g - 1$ instead of g . Two difficulties arise: the rank of the homology and the dimension of the Gram period matrix are not the same as for S and, in addition, the condition $\int_{\alpha_1} \sigma_j = 0$ for the members σ_j of the dual basis of harmonic forms disappears.

As announced in the Introduction (Sect. 1) we overcome the first difficulty by introducing an array of invariants attributed to the limit surface as a substitute for the missing Gram period matrix. The array may also be translated into a parametrized family of matrices that constitutes a variant of this substitute (Sect. 7.3). With the help of these invariants we then prove the main theorems Theorems 1.3 and 1.4 from the Introduction.

7.1 The space $H^{1,\nu}(\mathcal{R}, \mathbb{R})$

In the grafting construction the limit surface S^G is represented in the form $S^G = Z_1 \cup \mathfrak{M} \cup Z_2$, where $\mathfrak{M}$ is the main part of S and Z_1 , Z_2 are the attached infinite cylinders which we normalize here in the form

$$Z_1 = (-\infty, 0] \times \mathbb{S}_1, \quad Z_2 = [0, \infty) \times \mathbb{S}_1.$$

With respect to the complete hyperbolic metric in its conformal class (albeit unknown explicitly) the surface has also a representation $S^G = Z_1 \cup \mathfrak{M}^G \cup Z_2$, where $\mathfrak{M}^G$ is the main part of S^G obtained by cutting away the cusps along the horocycles of length 1.

To cover both representations we consider in this section, more generally, an arbitrary conformal Riemann surface $\mathcal{R}$ of signature $(g - 1, 0; 2)$, represented in the form

$$\mathcal{R} = Z_1 \cup \mathfrak{K} \cup Z_2, \tag{7.1}$$

where $\mathfrak{K}$ is a conformal Riemann surface of signature $(g - 1, 2; 0)$ and the cylinders Z_1 , Z_2 , are attached along the two boundaries of $\mathfrak{K}$ with respect to some fixed pasting rules. We denote by $\overline{\mathcal{R}}$ the two point compactification of $\mathcal{R}$ obtained by adding ideal points at infinity v_1, v_2 to Z_1, Z_2 , respectively.

The space of L^2 harmonic forms on $\mathcal{R}$ is naturally identified with the space $H^1(\overline{\mathcal{R}}, \mathbb{R})$ of harmonic 1-forms on $\overline{\mathcal{R}}$ and is denoted by $H^1(\mathcal{R}, \mathbb{R})$.

In addition to these we consider harmonic forms with *logarithmic poles*. By the existence theorem of real harmonic functions with logarithmic poles ([11, Theorem II.4.3]) there exists

on $\mathcal{R}$, up to a change of sign, a unique exact harmonic 1-form τ_1 with logarithmic poles at v_1, v_2 . With the appropriate choice of sign this form has the following representation in the cylinders Z_1, Z_2 ,

$$\tau_1 = dx + \tau_1^{\text{nl}}, \quad (7.2)$$

where the nonlinear part τ_1^{nl} is exponentially decaying for $x \rightarrow -\infty$ in Z_1 and for $x \rightarrow +\infty$ in Z_2 . We now define the space

$$H^{1,v}(\mathcal{R}, \mathbb{R}) = \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \tau_1, \star\tau_1\}. \quad (7.3)$$

Observe that in $Z_1 \cup Z_2$ any $\omega \in H^{1,v}(\mathcal{R}, \mathbb{R})$ has a representation

$$\omega = adx + bdy + \omega^{\text{nl}}$$

with the same a, b in Z_1 as in Z_2 , and that $a = b = 0$ iff $\omega \in H^1(\mathcal{R}, \mathbb{R})$. Analogously to (6.9) we define the finite scalar product for $\omega, \eta \in H^{1,v}(\mathcal{R}, \mathbb{R})$,

$$\langle \omega, \eta \rangle_{\mathfrak{R}} \stackrel{\text{def}}{=} \int_{\mathfrak{R}} \omega \wedge \star \eta + \int_{Z_1 \cup Z_2} \omega^{\text{nl}} \wedge \star \eta^{\text{nl}}. \quad (7.4)$$

By the exponential decay of the nonlinear parts the integral on the right is well defined. Since any harmonic form that vanishes in $\mathfrak{R}$ vanishes everywhere the product defined by (7.4) is positive definite and, hence, a scalar product. It is not intrinsic but shall serve its purpose.

Since $\star(\omega^{\text{nl}}) = (\star\omega)^{\text{nl}}$ we have

$$\langle \star\omega, \star\eta \rangle_{\mathfrak{R}} = \langle \omega, \eta \rangle_{\mathfrak{R}}. \quad (7.5)$$

We also introduce the *essential energy* with respect to this product, respectively $\mathfrak{R}$,

$$\mathcal{E}_{\mathfrak{R}}(\omega) \stackrel{\text{def}}{=} \langle \omega, \omega \rangle_{\mathfrak{R}}. \quad (7.6)$$

We now prove two properties of τ_1 . For the proof we introduce the following notation which will also be used later on. For any $L > 0$ we consider the finite cylinders $Z_{1,L} = [-\frac{1}{2}L, 0] \times \mathbb{S}_1$, $Z_{2,L} = [0, \frac{1}{2}L] \times \mathbb{S}_1$, and let

$$\mathcal{R}_L^\times = Z_{1,L} \cup \mathfrak{R} \cup Z_{2,L}$$

be the subsurface of $\mathcal{R}$ obtained by attaching the two cylinders to $\mathfrak{R}$ with the same pasting rules as for Z_1, Z_2 in the definition of $\mathcal{R}$.

Lemma 7.1

- (i) If $\omega \in \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \star\tau_1\}$ then $\langle \tau_1, \omega \rangle_{\mathfrak{R}} = 0$.
- (ii) If $\omega \in H^1(\mathcal{R}, \mathbb{R})$ then $\langle \star\tau_1, \omega \rangle_{\mathfrak{R}} = 0$.

Proof By virtue of the Orthogonality Lemma we have

$$\langle \tau_1, \omega \rangle_{\mathfrak{R}} = \lim_{L \rightarrow \infty} \left(\int_{\mathfrak{R}} \tau_1 \wedge \star\omega + \int_{Z_{1,L} \cup Z_{2,L}} \tau_1^{\text{nl}} \wedge \star\omega^{\text{nl}} \right) = \lim_{L \rightarrow \infty} \int_{\mathcal{R}_L^\times} \tau_1 \wedge \star\omega.$$

τ_1 being exact it is of the form $\tau_1 = dF$ with a harmonic function F on $\mathcal{R}$ whose nonlinear part in Z_1, Z_2 is exponentially decaying for $x \rightarrow -\infty$ respectively, $x \rightarrow +\infty$. By Stokes' theorem and because $\star\omega$ is of the form $\star\omega = adx + \star\omega^{\text{nl}}$ for some constant a we have

$$\int_{\mathcal{R}_L^\times} \tau_1 \wedge \star\omega = \int_{\mathcal{R}_L^\times} dF \wedge \star\omega = \int_{\mathcal{R}_L^\times} d(F\star\omega) = \int_{\partial\mathcal{R}_L^\times} F\star\omega = \int_{\partial\mathcal{R}_L^\times} F\star\omega^{\text{nl}}.$$

Since $|F|$ has at most linear growth while $\|\star\omega^n\|$ is exponentially decaying for $x \rightarrow -\infty$, respectively $x \rightarrow +\infty$, the right hand side goes to zero as $L \rightarrow \infty$ and point (i) of the lemma follows. Point (ii) follows from (i) and (7.5) since for $\omega \in H^1(\mathcal{R}, \mathbb{R})$ we also have $\star\omega \in H^1(\mathcal{R}, \mathbb{R})$. $\square$

Lemma 7.2

$$\mathcal{E}_{\mathfrak{K}}(\tau_1) = \lim_{L \rightarrow \infty} E_{\mathcal{R}_L^\times}(\tau_1) - L.$$

Proof This is straightforward, using the Orthogonality Lemma:

$$\begin{aligned} \mathcal{E}_{\mathfrak{K}}(\tau_1) &= E_{\mathfrak{K}}(\tau_1) + \lim_{L \rightarrow \infty} E_{Z_{1,L} \cup Z_{2,L}}(\tau_1^n) = E_{\mathfrak{K}}(\tau_1) + \lim_{L \rightarrow \infty} (E_{Z_{1,L} \cup Z_{2,L}}(\tau_1) - L) \\ &= \lim_{L \rightarrow \infty} (E_{\mathcal{R}_L^\times}(\tau_1) - L). \end{aligned}$$

$\square$

For the convergence of the period matrices we need the convergence of harmonic forms. To cover all cases we consider the grafting in terms of $\mathcal{R} = Z_1 \cup \mathfrak{K} \cup Z_2$ as defined in (7.1). To this end we define $\mathcal{R}_L$ to be the compact Riemann surface obtained from $\mathcal{R}_L^\times$ by pasting together the two boundary curves by the rule that any point $(\frac{1}{2}L, y)$ on the boundary of $Z_{2,L}$ is identified with the point $(-\frac{1}{2}L, y)$ on the boundary of $Z_{1,L}$. In $\mathcal{R}_L$ the pasted cylinders form the subset

$$Z_L \stackrel{\text{def}}{=} Z_{2,L} \cup_{\text{pg}} Z_{1,L} \subset \mathcal{R}_L,$$

where $\cup_{\text{pg}}$ means disjoint union modulo pasting. By abuse of notation we write $Z_L = [0, L] \times \mathbb{S}_1$. As in the case of S , for any $L > 0$ there is a marking homeomorphism $\phi_L : \mathcal{R}_1 \rightarrow \mathcal{R}_L$ that acts as the identity from $\mathfrak{K} \subset \mathcal{R}_1$ to $\mathfrak{K} \subset \mathcal{R}_L$ and sends $[0, 1] \times \mathbb{S}_1$ to $[0, L] \times \mathbb{S}_1$ by the rule $\phi_L(x, y) = (Lx, y)$.

On $\mathcal{R}_1$ we choose a canonical homology basis $(\alpha_1, \dots, \alpha_{2g})$ such that α_2 is the boundary curve c_1 of $\mathfrak{K}$. Setting $\alpha_{i,L} = \phi_L(\alpha_i)$, $i = 1, \dots, 2g$, we get a corresponding homology basis on $\mathcal{R}_L$, and we let $(\sigma_{1,L}, \dots, \sigma_{2g,L})$ be the dual basis of harmonic forms on $\mathcal{R}_L$, and $(\tau_{1,L}, \tau_{2,L}, \dots, \tau_{2g,L})$ the modified basis with $\tau_{1,L}$ as in Sect. 5.2 and the $\tau_{j,L}$ as in Sect. 6.1. We recall from Remark 6.3 that $\tau_{1,L}$ can be written as linear combination $\tau_{1,L} = \star\tau_{2,L} + \sum_{k=3}^{2g} c_{k,L} \tau_{k,L}$ and thus has linear part dx in Z_L .

As $L \rightarrow \infty$ these forms converge. To bring this statement into correct form we associate to any harmonic form ω on $\mathcal{R}_L$ (as e.g. the $\tau_{j,L}$) a form $\omega^\times$ on $\mathcal{R}$ in the following way: first we let $\omega^\times$ be the restriction of ω to $\mathcal{R}_L^\times$, then we interpret $\mathcal{R}_L^\times$ as subset of $\mathcal{R}$ and finally we extend (discontinuously) $\omega^\times$ to all of $\mathcal{R}$ defining it to be zero outside $\mathcal{R}_L$. The statement is now as follows.

Theorem 7.3 (Convergence theorem) *Let $\mathcal{R} = Z_1 \cup \mathfrak{K} \cup Z_2$ be a conformal Riemann surface as in (7.1) and let the forms $\tau_{j,L}^\times$ be constructed as above for $j = 1, \dots, 2g$ and $L \in \mathbb{R}$. As $L \rightarrow \infty$ we have*

- (i) $\tau_{1,L}^\times$ converges uniformly on compact sets on $\mathcal{R}$ to τ_1 ;
- (ii) $\tau_{j,L}^\times$ converges uniformly on compact sets to a harmonic form $\tau_j \in H^{1,v}(\mathcal{R}, \mathbb{R})$, $j = 2, \dots, 2g$.

Proof This is an adaption of [7,8], where a more general result is proved. We begin with the $\tau_{2,L}$. To get suitable test forms for them we fix a smooth closed 1-form θ_2 on $\mathfrak{K}$ that has vanishing periods over $\alpha_3, \dots, \alpha_{2g}$ and matches with dy along the boundary of the inserted

cylinder $Z_L = \{(x, y) \mid x \in [0, L], y \in \mathbb{S}_1\}$. Setting $\theta_{2,L} = \theta_2$ on $\mathfrak{K}$ and $\theta_{2,L} = dy$ on Z_L we get a test form with energy $E(\theta_{2,L}) = \vartheta + L$ where $\vartheta = E_{\mathfrak{K}}(\theta_2)$. On the other hand, $E(\tau_{2,L}) \geq L$ by the Orthogonality Lemma. Thus,

$$L \leq E(\tau_{2,L}) \leq \vartheta + L.$$

It follows that the energies of all $\tau_{2,L}^\times$ on $\mathfrak{K}$ and also the energies of their nonlinear parts in the infinite cylinders Z_1, Z_2 are uniformly bounded by ϑ . Since the forms are harmonic one can now, using Harnack's inequality, apply the Arzelà–Ascoli diagonal argument to get a sequence of lengths $\{L_n\}_{n=1}^\infty$ with $L_n \rightarrow \infty$ such that $\tau_{2,L_n}^\times$ converges uniformly on compact sets to a harmonic form τ_2 on $\mathcal{R}$ satisfying $\mathcal{E}_{\mathfrak{K}}(\tau_2) \leq \vartheta$ and $\int_{\alpha_2} \tau_2 = 1, \int_{\alpha_k} \tau_2 = 0, k = 3, \dots, 2g$. Now τ_2 is uniquely determined by these properties and the Arzelà–Ascoli argument applied a second time implies that the entire family $\tau_{2,L}^\times$ converges to τ_2 . Since all $\tau_{2,L}$ have linear part dy (by Lemma 6.2) the same is true for τ_2 . Finally, since $\mathcal{E}_{\mathfrak{K}}(\tau_2)$ is finite it follows that τ_2 belongs to $H^{1,v}(\mathcal{R}, \mathbb{R})$.

For $\tau_{k,L}, k = 3, \dots, 2g$, the proof is the same except that the linear parts vanish. Here the energies of the limit forms τ_k are finite and, since isolated singularities of L^2 harmonic differentials are removable, we have

$$\tau_k \in H^1(\mathcal{R}, \mathbb{R}), \quad k = 3, \dots, 2g. \quad (7.7)$$

For the proof of statement (i) we write $\tau_{1,L} = \star \tau_{2,L} + \sum_{k=3}^{2g} c_{k,L} \tau_{k,L}$ (Remark 6.3), where $c_{k,L} = -\int_{\alpha_k} \star \tau_{2,L}$. By the convergence of the $\tau_{k,L}, k = 3, \dots, 2g$, and since they have vanishing linear parts it follows that $\mathcal{E}_{\mathfrak{K}}(\tau_{1,L})$ is bounded above by some constant that does not depend on L . We can therefore apply the same argument for $\tau_{1,L}$ as for $\tau_{2,L}$ and use the uniqueness property of τ_1 to conclude the proof. $\square$

7.2 Twist at infinity

Let $\mathcal{R}$ be as before, but this time equipped with its complete hyperbolic metric. We represent it in the form $\mathcal{R} = V_1 \cup \mathfrak{M}^\mathcal{R} \cup V_2$ where V_1, V_2 are the cusp neighborhoods of the ideal points at infinity v_1, v_2 , cut off along the horocycles of length 1

$$\begin{aligned} V_1 &= \{(x, y) \mid x \in (-\infty, 0], y \in \mathbb{S}_1\}, \text{ with the hyperbolic metric } ds^2 = \frac{dx^2 + dy^2}{(x-1)^2}, \\ V_2 &= \{(x, y) \mid x \in [0, +\infty), y \in \mathbb{S}_1\}, \text{ with the hyperbolic metric } ds^2 = \frac{dx^2 + dy^2}{(x+1)^2}. \end{aligned} \quad (7.8)$$

The curves $y = \text{constant}$ in V_1, V_2 are geodesics. We shall call them *cusp geodesics*.

The part $\mathfrak{M}^\mathcal{R}$ is the closure of $\mathcal{R} \setminus \{V_1 \cup V_2\}$ and shall be called the *main part* of $\mathcal{R}$ with respect to the hyperbolic metric. In the cases $\mathcal{R} = S^G$ and $\mathcal{R} = S^F$ we shall, respectively, use the notation $\mathfrak{M}^G$ and $\mathfrak{M}^F$ for it.

When $\mathcal{R}$ arises e.g. as the Fenchel–Nielsen limit of a family (S_t) in which $\alpha_{2,t}$ shrinks to zero then, as mentioned earlier, two problems arise: a degree of freedom is lost since the twist parameter along $\alpha_{2,t}$ disappears, and secondly, the homology of $\alpha_{1,t}$ disappears. We eliminate both problems by introducing families of curves from v_1 to v_2 on $\mathcal{R}$ that play the role of “twist parameters at infinity”.

We shall say that a parametrized curve $\alpha : \mathbb{R} \rightarrow \mathcal{R}$ is an *admissible curve* if on $\overline{\mathcal{R}}$ one has $\lim_{s \rightarrow -\infty} \alpha(s) = v_1, \lim_{s \rightarrow +\infty} \alpha(s) = v_2$ and if, furthermore, α is asymptotic to a cusp geodesic in either of the two cusps. *Asymptotic* in V_1 (and similarly in V_2) means that if the

part of α in V_1 with respect to the above coordinates is written in the form $\alpha(s) = (x(s), y(s))$, then $y(s)$ converges to some y_0 for $s \rightarrow -\infty$.

Remark 7.4 From the asymptotic property it follows that for any admissible curve α from v_1 to v_2 in $\mathcal{R}$ and any harmonic form $\omega \in \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \star\tau_1\}$ the integral $\int_\alpha \omega$ is well defined and finite.

A homotopy between admissible curves from v_1 to v_2 on $\mathcal{R}$ shall be called an *admissible homotopy* if in both cusps the curves remain asymptotic to their respective cusp geodesics. Such a homotopy is, of course, only possible if in either cusp the initial and the end curve is asymptotic to the same geodesic.

It turns out that the concept of admissible homotopy is too restrictive and we shall slightly weaken it. Before doing so we prove the following, where we return to the representation of $\mathcal{R}$ used in Sect. 7.1

Lemma 7.5 *Assume $\mathcal{R}$ is represented in the form $\mathcal{R} = Z_1 \cup \mathfrak{R} \cup Z_2$ as in (7.1). Then the straight lines $y = \text{const}$ in the cylinders are asymptotic to cusp geodesics.*

We note that this lemma is evident for the limit surface $S^G = V_1 \cup \mathfrak{M}^G \cup V_2$, represented with respect to the complete hyperbolic metric that arises from the Uniformization Theorem, where V_1, V_2 are the hyperbolic cusps as in 7.8 and $\mathfrak{M}^G$ is the main part with respect to the hyperbolic metric of S^G . However, we also need this statement for the representation $S^G = Z_1 \cup \mathfrak{M} \cup Z_2$, where $\mathfrak{M}$ is the main part of S and the coordinate lines $y = \text{const}$. in the cylinders are not geodesics with respect to the hyperbolic metric of S^G .

Proof This can be shown by using that passing from V_i to Z_i is a change of conformal coordinate systems in a neighborhood of $v_i \in \mathcal{R}$ ($i=1,2$), and that for such changes the overlap map is biholomorphic. We use an other approach that measures the angle between the coordinate lines and the geodesics in terms of τ_1 . We do, however, not estimate the constants.

We begin with Z_2 . Since τ_1 is exact and has linear part dx it is of the form $\tau_1 = dh$ with a harmonic function $h(x, y) = x + h^{\text{nl}}(x, y)$, where by Lemma 3.1 the nonlinear part satisfies $|h^{\text{nl}}(x, y)| \leq c_1 e^{-2\pi x}$, $\|dh^{\text{nl}}(x, y)\| \leq c_2 e^{-2\pi x}$ for some constants c_1, c_2 . For x large enough the first property implies that h grows asymptotically like x , and the second property implies that the gradient $\text{grad}h(x, y)$ at (x, y) and the “horizontal” coordinate line $[0, +\infty) \times \{y\}$ through (x, y) form an absolute angle $\leq 2c_2 e^{-2\pi x}$.

Now we turn to V_2 , where we write the coordinates as $\tilde{x}, \tilde{y}$. Here τ_1 is $d\tilde{h}$ with some harmonic function $\tilde{h}(\tilde{x}, \tilde{y})$, and the horizontal coordinate lines are geodesics. We have the same angle estimates (with different constants). Furthermore, since $\tilde{h}(\tilde{x}, \tilde{y})$ grows asymptotically like $\tilde{x}$ there exists a constant c_3 (possibly negative) such that if $(\tilde{x}, \tilde{y})$ in V_2 and (x, y) in Z_2 represent the same point p of $\mathcal{R}$, then $x \geq \tilde{x} + c_3$.

The two angle estimates together with the inequality $x \geq \tilde{x} + c_3$ imply that for some positive constant c_4 and $\tilde{x}$ large enough the horizontal coordinate line (in the sense of Z_2) through $(\tilde{x}, \tilde{y})$ and the cusp geodesic through $(\tilde{x}, \tilde{y})$ form an angle $\angle(\tilde{x}, \tilde{y}) \leq c_4 e^{-2\pi \tilde{x}}$. This is sufficient to prove that the coordinate line is asymptotic to one of the cusp geodesics. In V_1 the proof is the same. $\square$

We now relax slightly the notion of admissible homotopy classes by allowing “synchronized twists” in the cusps. We define this in terms of an arbitrary description $\mathcal{R} = Z_1 \cup \mathfrak{R} \cup Z_2$ and then give an intrinsic characterization. For this we use twist homeomorphisms J_1, J_2 :

$\mathcal{R} \rightarrow \mathcal{R}$ defined as follows. Choose any constant $b \in \mathbb{R}$ and let $\beta : [0, 1] \rightarrow \mathbb{S}_1$ be the path $\beta(s) = bs \pmod{1}$ (e.g. if $b = 2$ then β goes twice around $\mathbb{S}_1$.) For any $x_0 \leq 0$ (respectively, $x_0 \geq 0$) we then have a path in Z_1 (respectively, Z_2) $s \mapsto (x_0, \beta(s))$, $s \in [0, 1]$.

Next, choose any $a_1 \leq 0$, $a_2 \geq 0$ and define the cut off functions

$$\chi_1(x) = \begin{cases} 1 & \text{if } x \leq a_1 - 1, \\ a_1 - x & \text{if } a_1 - 1 \leq x \leq a_1, \\ 0 & \text{if } a_1 \leq x \leq 0, \end{cases} \quad \chi_2(x) = \begin{cases} 0 & \text{if } 0 \leq x \leq a_2, \\ x - a_2 & \text{if } a_2 \leq x \leq a_2 + 1, \\ 1 & \text{if } x \geq a_2 + 1. \end{cases}$$

This allows us to define homeomorphisms $J_1, J_2 : \mathcal{R} \rightarrow \mathcal{R}$ setting

$$\text{on } Z_1 : J_1(x, y) = (x, y + \beta(\chi_1(x))), \quad \text{on } Z_2 : J_2(x, y) = (x, y + \beta(\chi_2(x)))$$

and letting J_1 be the identity mapping on $\mathcal{R} \cup Z_2$, and J_2 the identity mapping on $Z_1 \cup \mathcal{R}$. Under the mappings J_i the parts in the cylinders on the left of a_1 and on the right of a_2 are then both rotated by the angle $2\pi b$. We shall call these mappings *twist homeomorphisms* with twist parameter b .

The next lemma characterizes b in an intrinsic way. For the lemma we recall that by the remark subsequent to (7.3) any $\omega \in \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \star\tau_1\}$ has linear part $w dy$ in Z_1 and Z_2 for some $w \in \mathbb{R}$.

Lemma 7.6 *Let $J_1, J_2 : \mathcal{R} \rightarrow \mathcal{R}$ be twist homeomorphisms with twist parameter b as above and $\omega \in \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \star\tau_1\}$ a harmonic form with linear part $w dy$ in Z_1, Z_2 . Then for any admissible curve α from v_1 to v_2 we have*

$$\int_{J_1 \circ \alpha} \omega = \int_{\alpha} \omega - wb, \quad \int_{J_2 \circ \alpha} \omega = \int_{\alpha} \omega + wb.$$

Proof Let a_1, a_2 be the constants in the definition of J_1, J_2 as above. If we replace a_1, a_2 , by some other values $a'_1 \leq -1, a'_2 \geq 1$, and keep b fixed, then the twist homeomorphisms J'_1, J'_2 based on these new constants have the property that $J_i \circ \alpha$ and $J'_i \circ \alpha$ are homotopic with a homotopy that is the identity outside some compact region and thus $\int_{J_i \circ \alpha} \omega = \int_{J'_i \circ \alpha} \omega$ ($i = 1, 2$). This implies that for $i = 1, 2$, the difference $d_i := \int_{J_i \circ \alpha} \omega - \int_{\alpha} \omega$, seen as a function of a_i is the constant function. Now, if $a_1 \rightarrow -\infty$ and $a_2 \rightarrow +\infty$, then, by the exponential decay of the nonlinear part of ω in the cylinders, d_1 converges to $-bw$ and d_2 converges to bw . $\square$

We now define two admissible curves α, α' from v_1 to v_2 to be *twist equivalent* if there exists an admissible homotopy of α into a curve α'' and a pair of twist homeomorphisms J_1, J_2 with the same twist parameter b such that $\alpha' = J_1 \circ J_2 \circ \alpha''$.

It is a routine exercise to show that this is an equivalence relation thus splitting the admissible curves from v_1 to v_2 into *twist equivalence classes*. The next lemma shows, among other things, that this definition does not depend on the choice of the representation $\mathcal{R} = Z_1 \cup \mathcal{R} \cup Z_2$.

Lemma 7.7

- (i) *If two admissible curves α, α' from v_1 to v_2 on $\mathcal{R}$ are twist equivalent then $\int_{\alpha} \omega = \int_{\alpha'} \omega$ for any $\omega \in \text{span}\{H^1(\mathcal{R}, \mathbb{R}), \star\tau_1\}$.*
- (ii) *If two admissible curves α, α' from v_1 to v_2 on $\mathcal{R}$ are homotopic on $\overline{\mathcal{R}}$ then they are twist equivalent if and only if $\int_{\alpha} \star\tau_1 = \int_{\alpha'} \star\tau_1$.*

Proof (i) From the exponential decay of the nonlinear parts of ω in the cylinders it follows that if α and α'' are homotopic by an admissible homotopy, then the integrals over α and α'' are the same. By Lemma 7.6 the same is true for the integrals over α'' and $J_1 \circ J_2 \circ \alpha''$ if J_1 and J_2 have the same twist parameter b .

(ii) Now assume that α and α' are homotopic on $\bar{\mathcal{R}}$ (meaning that after a parameter change the curves are extended to v_1, v_2 for endpoints and then the homotopy acts on the extended curves keeping v_1, v_2 fixed). This condition is equivalent to saying that there exists an admissible homotopy from α to some admissible curve α'' and two twist homeomorphisms J_1, J_2 with some twist parameters b_1, b_2 (that do not coincide, in general) such that $\alpha' = J_1 \circ J_2 \circ \alpha''$. By (i) we have $\int_{\alpha} \star \tau_1 = \int_{\alpha''} \star \tau_1$, and by Lemma 7.6 $\int_{\alpha''} \star \tau_1 = b_2 - b_1 + \int_{J_1 \circ J_2 \circ \alpha''} \star \tau_1 = b_2 - b_1 + \int_{\alpha'} \star \tau_1$. If we now assume that $\int_{\alpha} \star \tau_1 = \int_{\alpha'} \star \tau_1$ then $b_1 = b_2$ and thus α and α' are twist equivalent. This proves (ii) in the “if” direction. The “only if” direction is a special case of (i). $\square$

For future reference we associate a twist parameter ϑ with any twist class using the representation $\mathcal{R} = V_1 \cup \mathcal{M}^{\mathcal{R}} \cup V_2$ as in the beginning of this section. Let c_i be the common boundary of $\mathcal{M}^{\mathcal{R}}$ and $V_i, i = 1, 2$. For the arcs of curves in $\mathcal{M}^{\mathcal{R}}$ with initial point on c_1 and endpoint on c_2 we have the homotopy classes with endpoints moving freely on c_1, c_2 . These classes are in natural one-to-one correspondence with the homotopy classes of curves from v_1 to v_2 in $\bar{\mathcal{R}}$. Furthermore, in each class there is a unique *orthogeodesic*, i.e. a geodesic arc that meets c_1, c_2 orthogonally at its endpoints.

Let now A_0 be an orthogeodesic from c_1 to c_2 (Fig. 7) and take $\vartheta \in \mathbb{R}$. Along c_1 we attach an arc $a_{1,\vartheta}$ of oriented length ϑ whose endpoint coincides with the initial point of A_0 ; we attach a similar arc $a_{2,\vartheta}$ along c_2 whose initial point coincides with the endpoint of A_0 . With respect to the earlier described coordinates for V_1, V_2 (where the y -coordinates are taken mod 1) these arcs may be parametrized as $A_{1,\vartheta}(s) = (-1, \vartheta s + y_1), A_{2,\vartheta}(s) = (1, \vartheta s + y_2), s \in [0, 1]$ for appropriate y_1, y_2 . By further attaching cusp geodesics $A_1 \subset V_1$ to the initial point of $A_{1,\vartheta}$ and $A_2 \subset V_2$ to the endpoint of $A_{2,\vartheta}$ we get an admissible curve

$$A_{1,\vartheta} = A_1 A_{1,\vartheta} A_0 A_{2,\vartheta} A_2 \quad (7.9)$$

from v_1 to v_2 as depicted in Fig. 7. By Lemmas 7.6 and 7.7 we have the following.

Remark 7.8 $A_{1,\vartheta}$ represents a twist equivalence class of admissible curves from v_1 to v_2 on $\mathcal{R}$. Conversely, any twist equivalence class is represented by a polygon as in (7.9) with uniquely determined orthogeodesic A_0 and uniquely determined ϑ . We call ϑ the *twist parameter* of the class and $A_{1,\vartheta}$ its representative in *normal form*.

We also remark by virtue of Lemma 7.6 that for any fixed A_0 there exists a constant c_0 such that

$$\int_{A_{1,\vartheta}} \star \tau_1 = \vartheta + c_0, \quad \text{for all } \vartheta \in \mathbb{R}. \quad (7.10)$$

Fig. 7 Twist equivalence class represented by a polygon in normal form. The twist is ϑ

By fixing an orthogeodesic A_0 or, what amounts to the same, a homotopy class of admissible curves from v_1 to v_2 on $\overline{\mathcal{R}}$ we can blow up $\mathcal{R}$ into a one parameter family by marking it with the twist equivalence classes occurring in (7.9). For $\mathcal{R}$ marked with $A_{1,\vartheta}$ we may then call ϑ its *twist parameter at infinity*.

7.3 Period matrix with a parameter

Let $\mathcal{R} = V_1 \cup \mathfrak{M}^{\mathcal{R}} \cup V_2$ be as above and mark it with the twist equivalence class of some admissible curve $\mathcal{A}_1$ from v_1 to v_2 . Let α_2 be the boundary curve of V_1 and select a canonical homology basis $\alpha_3, \dots, \alpha_{2g}$ of $\overline{\mathcal{R}}$ satisfying

$$\mathcal{A}_1 \cap \alpha_j = \emptyset, \quad j = 3, \dots, 2g.$$

To this configuration we shall associate a parametrized family of $2g$ by $2g$ matrices $P_{\mathcal{R}}(\lambda)$, $\lambda > 0$, where the notation suppresses the mention of the curve system. Here the parameter λ is related to the length of the attached cylinders.

Let $(\tau_3, \dots, \tau_{2g})$ be the dual basis of harmonic forms for $(\alpha_3, \dots, \alpha_{2g})$ on $\overline{\mathcal{R}}$ (restricted to $\mathcal{R}$), τ_1 the exact form with linear parts dx in V_1, V_2 as in Sect. 7.1 and set

$$\tau_2 = \star \tau_1 - \sum_{k=3}^{2g} \left(\int_{\alpha_k} \star \tau_1 \right) \tau_k \quad (7.11)$$

so that τ_2 has period 1 over α_2 and period 0 over $\alpha_3, \dots, \alpha_{2g}$. With these forms we define

$$q_{ij} = \int_{\mathcal{R}} \tau_i \wedge \star \tau_j, \quad i, j = 2, \dots, 2g, \quad (i, j) \neq (2, 2) \quad (7.12)$$

The matrix $Q = (q_{i,j})_{i,j \geq 3}$ is the Gram period matrix of $\overline{\mathcal{R}}$ with respect to the homology basis $(\alpha_3, \dots, \alpha_{2g})$. For $j \geq 3$ the integrals q_{2j} and q_{j2} are well defined by the Orthogonality Lemma since the τ_j have vanishing linear parts in the cusps (given that $\tau_j \in L^2(\mathcal{R})$, $j \geq 3$). For $(i, j) = (2, 2)$ the integral is infinite and we define a substitute

$$\pi_{22} = E(\tau_2 - \star \tau_1) \quad (7.13)$$

which is again finite given that τ_2 and $\star \tau_1$ have the same linear parts. We also note that, for any representation $\mathcal{R} = Z_1 \cup \mathcal{R} \cup Z_2$,

$$\pi_{22} = \mathcal{E}_{\mathcal{R}}(\tau_2) - \mathcal{E}_{\mathcal{R}}(\tau_1). \quad (7.14)$$

Writing $\tau_2 = \star \tau_1 + \omega_2$, where ω_2 and also $\star \omega_2$ belong to $H^1(\mathcal{R}, \mathbb{R})$ we have, by Lemma 7.1, $\mathcal{E}_{\mathcal{R}}(\tau_2) = \langle \star \tau_1, \star \tau_1 \rangle_{\mathcal{R}} + \langle \omega_2, \omega_2 \rangle_{\mathcal{R}} = \mathcal{E}_{\mathcal{R}}(\star \tau_1) + E(\omega_2)$.

We complete the definitions setting

$$q_{1j} = q_{j1} = 0, \quad j = 1, \dots, 2g. \quad (7.15)$$

Finally, we define the κ constants as

$$\kappa_1 \stackrel{\text{def}}{=} 1, \quad \kappa_j \stackrel{\text{def}}{=} - \int_{\mathcal{A}_1} \tau_j, \quad j = 2, \dots, 2g. \quad (7.16)$$

In the case where $\mathcal{R}$ is the limit surface S^G or S^F the constants will, respectively, be denoted by

$$q_{ij}^G, \pi_{22}^G, \kappa_j^G, \quad q_{ij}^F, \pi_{22}^F, \kappa_j^F, \quad i, j = 1, \dots, 2g, \quad (i, j) \neq (2, 2). \quad (7.17)$$

Definition 7.9 $P_{\mathcal{R}}(\lambda)$, $\lambda > 0$, is the matrix function with the following entries based on (7.12)–(7.16),

$$p_{ij}(\lambda) = q_{ij} + \frac{\kappa_i \kappa_j}{\lambda}, \quad i, j = 1, \dots, 2g, \quad (i, j) \neq (2, 2),$$

$$p_{22}(\lambda) = \pi_{22} + \lambda + \frac{\kappa_2^2}{\lambda}.$$

The analog of Theorem 4.3 in the nonseparating case is now as follows, where the $\mathcal{O}_A$ -symbol is as in (1.7). (The theorem is a restatement of Theorem 1.3, the proof follows in Sect. 7.4).

Theorem 7.10 *Let S be a compact Riemann surface of genus $g \geq 2$, γ a nonseparating geodesic of length $\ell(\gamma) \leq \frac{1}{4}$ on S and $(S_L)_{L \geq 4}$ with limit S^G the corresponding grafting family. Choose a canonical homology basis $A = (\alpha_1, \alpha_2, \dots, \alpha_{2g})$ with $\alpha_2 = \gamma$ and let P_{S_L} , $P_{S^G}(\lambda)$ be the corresponding Gram period matrices. Finally set $\mathfrak{m}^G = \mathcal{E}_{\mathfrak{M}}(\tau_1^G)$, where $\mathfrak{M}$ is the main part of S with respect to γ . Then for all $L \geq 4$,*

$$P_{S_L} = P_{S^G}(\mathfrak{m}^G + L) + \rho^G(L),$$

where the entries of the error term $\rho^G(L)$ have the following growth rates

$$\begin{aligned} \rho_{1j}^G(L) &= \mathcal{O}_A\left(\frac{1}{L}e^{-2\pi L}\right), & \text{for } j = 1, \dots, 2g, \quad j \neq 2, \\ \rho_{2j}^G(L) &= \mathcal{O}_A\left(\frac{1}{L}e^{-\pi L}\right), & \text{for } j = 1, \dots, 2g, \\ \rho_{ij}^G(L) &= \mathcal{O}_A\left(e^{-2\pi L}\right), & \text{for } i, j = 3, \dots, 2g. \end{aligned}$$

The Gram period matrix P of a compact Riemann surface is known to be symplectic where, in accordance with our conventions for a canonical homology basis (Sect. 1), P is called *symplectic* in our context, if $\mathbf{J}P\mathbf{J} = \mathbf{J}$ for the block diagonal matrix

$$\mathbf{J} = \begin{pmatrix} 0 & 1 & & 0 \\ -1 & 0 & & \\ & & \ddots & \\ 0 & & 0 & 1 \\ & & & -1 & 0 \end{pmatrix}. \quad (7.18)$$

As a consequence of the theorem we have the following.

Corollary 7.11 *The matrices $P_{\mathcal{R}}(\lambda)$ are symplectic for all $\lambda > 0$.*

Proof Any $\mathcal{R}$ can be understood as a limit S^G of some family $(S_L)_{L \geq 4}$. Using the fact that the matrices P_{S_L} are symplectic for every L we have, writing $S^G = \mathcal{R}$, $\mathfrak{m}^G + L = \lambda$ and $\rho^G(L) = r(\lambda)$,

$$\mathbf{J} = P_{S_L}\mathbf{J}P_{S_L} = P_{\mathcal{R}}(\lambda)\mathbf{J}P_{\mathcal{R}}(\lambda) + \Omega(\lambda)$$

with $\Omega(\lambda) = P_{\mathcal{R}}(\lambda)\mathbf{J}r(\lambda) + r(\lambda)\mathbf{J}P_{\mathcal{R}}(\lambda) + r(\lambda)\mathbf{J}r(\lambda)$. Now $\mathbf{J}$ is constant, $P_{\mathcal{R}}(\lambda)\mathbf{J}P_{\mathcal{R}}(\lambda)$ is a rational function of λ and $\Omega(\lambda)$ is exponentially decaying as $\lambda \rightarrow \infty$. This is only possible if $P_{\mathcal{R}}(\lambda)\mathbf{J}P_{\mathcal{R}}(\lambda)$ is constant and $\Omega(\lambda)$ vanishes identically. $\square$

For $t > 0$, we set

$$L_t = \frac{\pi}{t} - \frac{2 \arcsin t}{t} \quad \text{with} \quad \lim_{t \rightarrow 0} \frac{2 \arcsin t}{t} = 2.$$

Then we obtain for the Fenchel–Nielsen construction:

Theorem 7.12 Let $(S_t)_{t \leq \ell(\gamma)}$ with limit S^F be the Fenchel–Nielsen family of S and set $\mathfrak{m}^F = \mathcal{E}_{\mathfrak{M}^F}(\tau_1^F)$, where $\mathfrak{M}^F$ is the main part of S^F . For the Gram period matrices P_{S_t} and P_{S^F} we have

$$P_{S_t} = P_{S^F}(\mathfrak{m}^F + L_t) + \rho^F(t),$$

where the entries of the error term $\rho^F(t)$ have the following growth rates

$$\begin{aligned} \rho_{11}^F(t) &= \mathcal{O}_A(t^4), & \rho_{12}^F(t) &= \mathcal{O}_A(t^2) & \rho_{1j}^F(t) &= \mathcal{O}_A(t^3), & j = 3, \dots, 2g, \\ \rho_{ij}^F(t) &= \mathcal{O}_A(t^2), & i, j &= 2, \dots, 2g. \end{aligned}$$

7.4 Proof of Theorems 1.3 and 1.4

We now prove Theorems 7.10 and 7.12 respectively Theorems 1.3 and 1.4.

Proof of Theorem 7.10 In this proof the following notation is used: $\tau_{1,L}, \tau_{2,L}, \dots, \tau_{2g,L}$ is the relaxed dual basis on S_L , and $\tau_1^G, \tau_2^G, \dots, \tau_{2g}^G$ are the harmonic forms on S^G as above for the case $\mathcal{R} = S^G$. We recall the center part $\mathfrak{M}$ common to all S_L which also serves as center part of S^G and abbreviate the essential energies

$$\mathfrak{m}_L = \mathcal{E}_{\mathfrak{M}}(\tau_{1,L}), \quad \mathfrak{m}^G = \mathcal{E}_{\mathfrak{M}}(\tau_1^G).$$

The q_{ij} in the inequalities that follow are the constants in the Definition 7.9 for the matrix family $P_{S^G}(\lambda)$,

$$q_{ij}(S^G) = \langle \tau_i^G, \tau_j^G \rangle_{\mathfrak{M}}, \quad i, j = 2, \dots, 2g, \quad (7.19)$$

where we recall that

$$\langle \omega, \eta \rangle_{\mathfrak{M}} \stackrel{\text{def}}{=} \int_{\mathfrak{M}} \omega \wedge \star \eta + \int_{C(\gamma)} \omega^{\text{nl}} \wedge \star \eta^{\text{nl}}, \quad (7.20)$$

for $\omega, \eta \in H^{1,v}(S^G, \mathbb{R})$ ((7.4) with $\mathcal{R} = \mathfrak{M}$). In particular, $q_{ii}(S^G) = E(\tau_i^G)$, $i = 3, \dots, 2g$, and $q_{22}(S^G) = \mathcal{E}_{\mathfrak{M}}(\tau_2^G)$, where by (7.14)

$$\mathcal{E}_{\mathfrak{M}}(\tau_2^G) = \pi_{22} + \mathcal{E}_{\mathfrak{M}}(\tau_1^G) = \pi_{22} + \mathfrak{m}^G. \quad (7.21)$$

Finally, we recall the periods introduced in (6.1) which we now write $\kappa_{2,L}, \dots, \kappa_{2g,L}$ while $\kappa_2^G, \dots, \kappa_{2g}^G$ denote the corresponding periods on S^G .

By Lemmas 5.4, 5.5 and the Convergence Theorem 7.3

$$|\mathfrak{m}_L - \mathfrak{m}^G| < e^{-2\pi L} \min\{\mathfrak{m}_L, \mathfrak{m}^G\}, \quad \Gamma \leq \mathfrak{m}_L, \mathfrak{m}^G \leq \mathfrak{z}\Gamma, \quad (7.22)$$

with $\mathfrak{z} < 2.3$. Furthermore, for $j = 2$ an application of (6.14) in Lemma 6.4 together with Theorem 7.3 yields

$$|\kappa_{2,L} - \kappa_2^G|^2 < 3\rho_L(1 + \mathfrak{z}\Gamma)q_{22}(S^G). \quad (7.23)$$

Here $\rho_L < e^{-2\pi L}$ is from (6.11). For $j \geq 3$ we obtain a better upper bound via inequality (6.13) in Lemma 6.4: taking $\omega = \tau_{j,L}$, $\eta = \star \tau_{j,L}$ and $\tilde{\omega} = \tau_j^G$, $\tilde{\eta} = \star \tau_j^G$ we get, in combination with (6.18) and Theorem 7.3,

$$|\kappa_{j,L} - \kappa_j^G| = |\langle \tau_{j,L}, \star \tau_{j,L} \rangle_{\mathfrak{M}} - \langle \tau_j^G, \star \tau_j^G \rangle_{\mathfrak{M}}| \leq \nu_L \sqrt{q_{22}(S^G)} \sqrt{q_{jj}(S^G)}, \quad j = 3, \dots, 2g, \quad (7.24)$$

where $\nu_L < e^{-2\pi L}$ is again from (6.11). Finally, we recall Lemmas 6.9 and 6.5

$$|\kappa_{2,L}| \leq K, \quad |\kappa_{j,L}| \leq \sqrt{\mathcal{E}(\tau_{2,L}) E(\tau_{j,L})}, \quad j = 3, \dots, 2g, \quad (7.25)$$

where K is a constant estimated in terms of g , $\text{sys}(\mathfrak{M})$ and $\ell(\alpha_1)$ on S . Here $\text{sys}(\mathfrak{M})$ is the length of the shortest closed geodesic on $\mathfrak{M}$ and thus the shortest closed geodesic on S different from γ . With the notation used for the definition of the $\mathcal{O}_A$ -symbol (below (1.7)): $\text{sys}(\mathfrak{M}) = \text{sys}_\gamma(S)$.

By (5.18) and (5.19) (where $\mathcal{E} = \mathcal{E}_{\mathfrak{M}}$) we have

$$p_{11}(S_L) = E(\sigma_{1,L}) = \frac{1}{\mathcal{E}_{\mathfrak{M}}(\tau_{1,L}) + L} = \frac{1}{m_L + L}.$$

Together with (7.22) this yields

$$p_{11}(S_L) = \frac{1}{m^G + L} + \rho_{11}^G(L) \text{ with } |\rho_{11}^G(L)| \leq \frac{e^{-2\pi L}}{m^G + L}. \quad (7.26)$$

By (6.2), (6.3) and Lemma 6.1 we have

$$p_{1j}(S_L) = \kappa_{j,L} p_{11}(S_L), \quad p_{ij}(S_L) = \langle \tau_{i,L}, \tau_{j,L} \rangle + \kappa_{i,L} \kappa_{j,L} p_{11}(S_L), \quad i, j = 2, \dots, 2g. \quad (7.27)$$

We now write, for $j = 2, \dots, 2g$,

$$p_{1j}(S_L) = \frac{\kappa_j^G}{m^G + L} + \rho_{1j}^G(L), \quad \text{with } \rho_{1j}^G(L) = \frac{\kappa_{j,L} - \kappa_j^G}{m^G + L} + \frac{\kappa_{j,L}(m^G - m_L)}{(m_L + L)(m^G + L)}, \quad (7.28)$$

By Lemmas 6.7 and 6.8 the energies $q_{kk}(S^G)$, $\mathcal{E}(\tau_{2,L})$, $E(\tau_{j,L})$ in (7.24), (7.25) are effectively bounded above in terms of g , $\text{sys}_\gamma(S) = \text{sys}(\mathfrak{M})$ and $\max\{\ell(\alpha_1), \dots, \ell(\alpha_{2g})\}$. The same holds, by Theorem 5.7, for Γ . Hence, by (7.22)–(7.25)

$$\rho_{12}^G(L) = \mathcal{O}_A\left(\frac{1}{L}e^{-\pi L}\right), \quad \rho_{1j}^G(L) = \mathcal{O}_A\left(\frac{1}{L}e^{-2\pi L}\right), \quad j = 3, \dots, 2g. \quad (7.29)$$

In a similar way, using (7.27), we write, for $i, j = 2, \dots, 2g$,

$$p_{ij}(S_L) = \langle \tau_i^G, \tau_j^G \rangle_{\mathfrak{M}} + [L]_{ij} + \frac{\kappa_i^G \kappa_j^G}{m^G + L} + \rho_{ij}^G(L), \quad \text{with} \\ \rho_{ij}^G(L) = r_{ij}^G(L) + \frac{\kappa_i^G r_j + \kappa_j^G r_i + r_i r_j}{m^G + L + r_L} - \frac{\kappa_i^G \kappa_j^G r_L}{(m^G + L + r_L)(m^G + L)},$$

where $[L]_{22} = L$, $[L]_{ij} = 0$, if $(i, j) \neq (2, 2)$, and

$$r_{ij}^G(L) = \langle \tau_{i,L}, \tau_{j,L} \rangle_{\mathfrak{M}} - \langle \tau_i^G, \tau_j^G \rangle_{\mathfrak{M}}, \quad r_i = \kappa_{i,L} - \kappa_i^G, \quad \text{and } r_L = m_L - m^G.$$

Using (7.24) we get

$$|r_{ij}^G(L)| \leq \nu_L \mathcal{E}_{\mathfrak{M}}^{1/2}(\tau_i^G) \mathcal{E}_{\mathfrak{M}}^{1/2}(\tau_j^G) = \nu_L \sqrt{q_{ii}(S^G)} \sqrt{q_{jj}(S^G)}, \quad i, j = 2, \dots, 2g.$$

By (7.19), (7.21), $\langle \tau_i^G, \tau_j^G \rangle_{\mathfrak{M}} + [L]_{ij} = q_{ij}(S^G)$, if $(i, j) \neq (2, 2)$, and $\langle \tau_2^G, \tau_2^G \rangle_{\mathfrak{M}} + [L]_{22} = m^G + L + \pi_{22}$. We thus have

$$p_{ij}(S_L) = q_{ij}(S^G) + \frac{\kappa_i^G \kappa_j^G}{L} + \rho_{ij}^G(L), \quad i, j \geq 2, (i, j) \neq (2, 2), \\ p_{22}(S_L) = m^G + L + \pi_{22} + \frac{(\kappa_2^G)^2}{m^G + L} + \rho_{22}^G(L), \quad (7.30)$$

and, in a similar way as before,

$$\rho_{22}^G(L) = \mathcal{O}_A\left(\frac{1}{L}e^{-\pi L}\right), \quad \rho_{ij}^G(L) = \mathcal{O}_A(e^{-2\pi L}), \quad i, j = 2, \dots, 2g, (i, j) \neq (2, 2). \quad (7.31)$$

With (7.26) and the pairs (7.28), (7.29) and (7.30), (7.31) the proof of Theorem 1.3 and Theorem 7.10 respectively are now complete. $\square$

Proof of Theorem 7.12 The notation is as in the proof before, except that we now use the Fenchel–Nielsen construction, which changes any notation $()^G$ to $()^F$. In this case we have

$$L = L_t = \frac{\pi}{t} - \frac{2 \arcsin t}{t}.$$

We recall that

$$\mathfrak{m}_L = \mathcal{EM}(\tau_{1,L}), \quad \mathfrak{m}^F = \mathcal{EM}(\tau_1^F).$$

In view of the geometric bounds from Sects. 5 and 6 the theorem is a consequence of the following inequalities.

$$\begin{aligned} |\rho_{11}^F(L)| &= \mathcal{O}_A(t^4), \quad |\rho_{12}^F(L)| = \mathcal{O}_A(t^2), \quad |\rho_{1j}^F(L)| = \mathcal{O}_A(t^3), \quad \text{for } j = 3, \dots, 2g, \\ |\rho_{ij}^F(L)| &= \mathcal{O}_A(t^2), \quad \text{for } i, j = 2, \dots, 2g. \end{aligned} \quad (7.32)$$

Following the lines of the proof of Lemma 5.5, but adding a quasiconformal map to compare the energies on S_L and S^F together with the Convergence Theorem 7.3 we obtain now

$$|\mathfrak{m}_L - \mathfrak{m}^F| = \mathcal{O}_A(t^2). \quad (7.33)$$

The estimate for $\rho_{11}^F(L)$ then follows from (5.15) and the above inequality.

The remaining inequalities follow in the same steps as in the previous proof, noting that now v_L and ρ_L are of order $\mathcal{O}_A(t^2)$ as the quasi-conformal map is involved. Furthermore by definition $\frac{1}{L} = \frac{1}{L_t}$ is of order $\mathcal{O}_A(t)$. $\square$

Acknowledgements Open access funding provided by EPFL Lausanne.

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