Differences between fundamental solutions of general higher order elliptic operators and of products of second order operators

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Received: 12 February 2019 / Revised: 6 May 2020 / Published online: 11 June 2020
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Abstract

We study fundamental solutions of elliptic operators of order $2m \geq 4$ with constant coefficients in large dimensions $n \geq 2m$, where their singularities become unbounded. For compositions of second order operators these can be chosen as convolution products of positive singular functions, which are positive themselves. As soon as $n \geq 3$, the polyharmonic operator $(-\Delta)^m$ may no longer serve as a prototype for the general elliptic operator. It is known from examples of Maz'ya and Nazarov (Math. Notes 39:14–16, 1986; Transl. of Mat. Zametki 39, 24–28, 1986) and Davies (J Differ Equ 135:83–102, 1997) that in dimensions $n \geq 2m + 3$ fundamental solutions of specific operators of order $2m \geq 4$ may change sign near their singularities: there are “positive” as well as “negative” directions along which the fundamental solution tends to $+\infty$ and $-\infty$ respectively, when approaching its pole. In order to understand this phenomenon systematically we first show that existence of a “positive” direction directly follows from the ellipticity of the operator. We establish an inductive argument by space dimension which shows that sign change in some dimension implies sign change in any larger dimension for suitably constructed operators. Moreover, we deduce for $n = 2m$, $n = 2m + 2$ and for all odd dimensions an explicit closed expression for the fundamental solution in terms of its symbol. From such formulae it becomes clear that the sign of the fundamental solution for such operators depends on the dimension. Indeed, we show that we have even sign change for a suitable operator of order $2m$ in dimension $n = 2m + 2$. On the other hand we show that in the dimensions $n = 2m$ and $n = 2m + 1$ the fundamental solution of any such elliptic operator is always positive around its singularity.

Communicated by Y. Giga.

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1 Introduction and main results

1.1 General constant coefficients elliptic operators

We focus our attention to uniformly elliptic operators of order $2m$ with constant coefficients which involve only the highest order derivatives, namely

$$L = (-1)^m Q\left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}\right) = (-1)^m \sum_{i_1, \dots, i_{2m}=1, \dots, n} A_{i_1, \dots, i_{2m}} \frac{\partial}{\partial x_{i_1}} \cdots \frac{\partial}{\partial x_{i_{2m}}}, \quad (1)$$

where the $2m$ -homogeneous characteristic polynomial

$$Q(\xi) = \sum_{i_1, \dots, i_{2m}=1, \dots, n} A_{i_1, \dots, i_{2m}} \xi_{i_1} \cdots \xi_{i_{2m}}$$

is called (possibly up to a sign) the *symbol* of the operator.

Uniform ellipticity means then that Q is strictly positive on the unit sphere, i.e. there exists a constant $\lambda > 0$ such that

$$\forall \xi \in \mathbb{R}^n : \quad Q(\xi) \geq \lambda |\xi|^{2m}.$$

1.2 Fundamental solutions

In order to construct and to understand solutions u to the differential equation $Lu = f$ for a given right-hand side f , one introduces the concept of a fundamental solution $K_L(x, \cdot)$ for any “pole” $x \in \mathbb{R}^n$ which is defined as a solution to the equations $L^* K_L(x, \cdot) = \delta_x$ and $L K_L(\cdot, x) = \delta_x$ in the distributional sense where δ_x is the δ -distribution located at x . This means that for any test function $\psi \in C_0^\infty(\mathbb{R}^n)$ one has

$$\int_{\mathbb{R}^n} K_L(x, y) L\psi(y) dy = \psi(x), \quad \int_{\mathbb{R}^n} K_L(y, x) L^*\psi(y) dy = \psi(x)$$

with

$$L^* = (-1)^m \sum_{i_1, \dots, i_{2m}=1, \dots, n} \frac{\partial}{\partial x_{i_1}} \cdots \frac{\partial}{\partial x_{i_{2m}}} A_{i_1, \dots, i_{2m}}$$

being the adjoint operator of L . Because L has only constant coefficients and only of the highest even order $2m$, we have that $L = L^*$. Moreover, we may achieve that

$$K_L(x, y) = K_L(0, x - y) = K_L(0, y - x) = K_L(y, x). \quad (2)$$

For given $f \in C_0^\infty(\mathbb{R}^n)$, any fundamental solution yields a solution to the differential equation $Lu = f$ in $\mathbb{R}^n$ by putting

$$u(x) := \int_{\mathbb{R}^n} K_L(x, y) f(y) dy.$$

One should also notice that, if a fundamental solution exists, it is not unique: one may add any smooth solution of $Lv = 0$, namely $\tilde{K}_L(x, y) = K_L(x, y) + v(x - y)$ yields another fundamental solution.

1.3 Green functions

When the problem $Lu = f$ is considered in a sufficiently smooth bounded domain, one may still obtain solution and even representation formulae by means of suitable fundamental solutions. Indeed, let $\Omega \subset \mathbb{R}^n$ be a bounded smooth domain and consider the problem

$$\begin{cases} Lu = f & \text{in } \Omega, \\ B(u) = 0 & \text{on } \partial\Omega, \end{cases} \quad (3)$$

where $f \in C^{0,\gamma}(\overline{\Omega})$ and the boundary conditions verify a complementing condition, see [1]. As a typical and most frequently studied prototype one may think of Dirichlet boundary conditions

$$B_D(u) := (u, \partial_\nu, \dots, \partial_\nu^{m-1} u) = 0 \quad \text{on } \partial\Omega,$$

with ν the exterior unit normal at $\partial\Omega$. If there exists a unique solution $h_{L,\Omega,B}(x, \cdot)$ of the boundary value problem (recall that $L^* = L$)

$$\begin{cases} Lh_{L,\Omega,B}(x, \cdot) = 0 & \text{in } \Omega, \\ B(h_{L,\Omega,B}(x, \cdot)) = -B(K_L(|x - \cdot|)) & \text{on } \partial\Omega, \end{cases}$$

one can define the so called *Green function* for problem (3), given by

$$G_{L,\Omega,B}(x, y) = K_L(|x - y|) + h_{L,\Omega,B}(x, y).$$

Then the unique solution of (3) is given by

$$u(x) = \int_{\Omega} G_{L,\Omega,B}(x, y) f(y) dy.$$

Notice that in general it is not straightforward to infer the existence of such $h_{L,\Omega,B}$. However, exploiting the general elliptic theory of Agmon, Douglis, and Nirenberg [1] this is always possible in our special case when the operator L has only constant

coefficients of highest order, if Dirichlet boundary conditions $B = B_D$ are imposed and the domain is $C^{2m,\gamma}$ -smooth.

In this case, one also infers by standard estimates that the function $h_{L,\Omega,B}$ is regular in $\overline{\Omega}$. Since in large dimensions fundamental solutions have a singularity near the pole, it becomes clear that, in order to understand $G_{L,\Omega,B}$, we need first to investigate the behaviour of fundamental solutions.

1.4 Positivity questions

Positivity properties for $G_{L,\Omega,B}$ concern the question whether a positive right-hand side yields a positive solution: if u is a solution of (3), does it hold that $f \geq 0 \Rightarrow u \geq 0$? One often expects such a behaviour for physical or geometrical reasons. However, for equations of order at least 4, such a positivity preserving property will fail in general, see [7] for historical remarks and detailed references. This question concerns a *nonlocal* behaviour of the full boundary value problem and often the influence of boundary conditions spoils the expected positivity. However, physically, one would hope that when applying an extremely concentrated right-hand side—a δ -distribution—then close to this point the solution should respond in the same direction. This leads to the related but relaxed *local* question: Is a suitable fundamental solution to the differential equation positive, at least close to its pole? This question is reasonable only for large dimensions $n \geq 2m$ because only here, fundamental solutions become unbounded and they are unique only up to locally bounded regular solutions of the homogeneous equation. If $n > 2m$ one may achieve uniqueness of the fundamental solution by imposing zero (Dirichlet) boundary conditions at infinity. In this case K_L may be considered as the Green function $G_{L,\mathbb{R}^n,B_D}$ in the whole space. This means that one considers just the behaviour of the differential equation and disregards the influence of possible boundary conditions (being infinitely far apart).

1.5 Previous results

In the context of second order equations ($m = 1$), both local and nonlocal behaviours are well established. Indeed, within the class of constant coefficients operators, the Laplacian $-\Delta$ is, up to a change of coordinates, the only such operator. Its fundamental solutions are known explicitly and in particular they are positive (if $n = 2$, at least close to the pole). Moreover, the maximum principle holds for such operators, so positive data yield positive solutions (see [8]). In other words, the Green function is always positive.

When one moves to the higher order setting ($m \geq 2$), several differences arise, even for $(-\Delta)^m$ or, equivalently, for powers of second order operators with constant coefficients.

Indeed, if one investigates the positivity preserving property in bounded domains, then the answer is largely affected by the choice of boundary conditions. As an example, on the one hand, with Navier boundary conditions ($u = \Delta u = \dots = \Delta^{m-1}u = 0$) one may rewrite the problem as a second order system and thus the maximum principle implies positivity. On the other hand, this tool is in general not available when dealing

with Dirichlet boundary conditions ($u = \partial_\nu u = \dots = \partial_\nu^{m-1} u = 0$) and one cannot expect positivity, in general not even in *convex* bounded smooth domains (see [5]). Nevertheless, positivity holds in balls and their small smooth deformations (see [2,9]). We refer to [7] for an extensive survey of the topic.

However, within that class of powers of second order operators, if one restricts to a “local” question, meaning the positivity of Green functions under Dirichlet boundary conditions near the pole, the answer is still affirmative. Indeed, a uniform local positivity can be proved, namely the existence of constants $r_{m,\Omega} > 0$, $\delta_{m,\Omega} > 0$ such that $G_{(-\Delta)^m, \Omega, B_D}(x, y) > \delta_{m,\Omega} > 0$ for all $x, y \in \Omega$ with $|x - y| < r_{m,\Omega}$. This means that the negative part and the singularity of the Green function are uniformly apart.

A consequence of that result is that the size of negative part of the Green function, if present at all, is small compared to its positive part. Indeed, concerning Dirichlet problems, positivity for a rank-1-correction of the polyharmonic Green function is retrieved, namely

$$G_{(-\Delta)^m, \Omega, B_D}(x, y) + c_{m,\Omega} d_\Omega(x)^m d_\Omega(y)^m \geq 0,$$

where d_Ω denotes the distance to the boundary and $c_{m,\Omega}$ is a sufficiently large positive constant, see [9,10].

These results have been extended later on by Pulst in his PhD-dissertation [15] for formally selfadjoint positive definite operators of order $2m$ with the polyharmonic operator $(-\Delta)^m$ or an m -th power of a second order elliptic operator with constant coefficients as the leading term. Lower order terms are permitted provided they can be written in divergence form and have sufficiently smooth and uniformly bounded coefficients.

In two dimensions, i.e. $n = 2$, the symbol Q with real coefficients can be split into $2m$ linear terms. Combining mutually conjugate pairs $(\xi_1 + a_k \xi_2)$ and $(\xi_1 + \overline{a_k} \xi_2)$ of these linear terms with nonreal a_k we see that

$$Q(\xi) = c \prod_{k=1}^m \left(\xi_1^2 + (a_k + \overline{a_k}) \xi_1 \xi_2 + |a_k|^2 \xi_2^2 \right)$$

is a product of second order symbols.

However, in dimensions $n > 2$ powers of second order operators are *not* the prototype of a general operator L of order $2m$, not even in the case of constant coefficients. Moreover, it is in general not possible to rewrite L as an m -fold composition of (possibly different) second order operators. Indeed, let us simply consider the case of a homogeneous fourth order operator with a symbol of the kind

$$Q(x, y, z) = x^4 + y^4 + z^4 + \sum_{\substack{i+j+k=4 \\ 0 \leq i, j, k \leq 3}} c_{i,j,k} x^i y^j z^k$$

and suppose that it is the product of two second order polynomials q_1, q_2 . One may assume that both polynomials have their coefficients in front of x^2 equal to 1 and then, they would necessarily be of the kind

$$q_1(x, y, z) = x^2 + cy^2 + dz^2 + a_1xy + a_2xz + a_3yz$$

$$q_2(x, y, z) = x^2 + \frac{1}{c}y^2 + \frac{1}{d}z^2 + b_1xy + b_2xz + b_3yz.$$

The smooth map from $(0, \infty)^2 \times \mathbb{R}^6$ into the 12-dimensional vector space of such symbols Q which maps

$$(c, d, a_1, a_2, a_3, b_1, b_2, b_3) \mapsto q_1 \cdot q_2$$

is *not surjective*.

Concerning explicit formulae and (local) positivity properties of fundamental solutions of such general elliptic operators only little is known. Existence of fundamental solution is shown in [12] in a very general framework, and rather involved formulae are obtained. In the particular case of a *2m-homogeneous higher order uniformly elliptic operator with constant coefficients*, different implicit expressions have been found according to the parity of the dimension n . In what follows we always assume that

$$n \geq 2m.$$

For *odd* n , the general formula for a fundamental solution [12, (3.44)] simplifies as

$$K_L(x, y) = -\frac{1}{4(2\pi)^{n-1}} (-\Delta_y)^{\frac{n+1-2m}{2}} \int_{|\xi|=1} \frac{|(x-y) \cdot \xi|}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \quad (4)$$

(from [12, (3.54)]), while for *even* n one has (see [12, (3.62)])

$$K_L(x, y) = -\frac{1}{(2\pi)^n} (-\Delta_y)^{\frac{n-2m}{2}} \int_{|\xi|=1} \frac{\log |(x-y) \cdot \xi|}{Q(\xi)} d\mathcal{H}^{n-1}(\xi). \quad (5)$$

We recall that Q denotes the symbol (possibly up to a sign) of the operator L . On the other hand, motivated by questions in potential and Schrödinger semigroup theory, respectively, and without referring to (4), (5) or even [12], Maz'ya–Nazarov [14] and Davies [3] found examples of elliptic operators of order $2m \geq 4$ in dimensions $n \geq 2m+3$ with sign changing fundamental solutions. The precise range of dimensions where this phenomenon may be observed remained open as well as a systematic study, see [3, p. 85]: “It seems to be difficult to find a useful characterization of the symbols of those constant coefficient elliptic operators with this property.”

1.6 Aim and results

The aim of this paper is a systematic investigation of the behaviour of fundamental solutions - and in particular whether or not they are positive close to the pole - for this class of uniformly elliptic operators of order $2m$ with constant coefficients.

We find the above mentioned examples of sign changing fundamental solutions somehow unexpected because this means that even when applying a right hand side,

which is concentrated at some point and points into one direction, the response of any solution to the differential equation will be sign changing and so - in some regions arbitrarily close to this point - in opposite direction to the right hand side. Indeed, we show in Theorem 2.3 that “positivity” is somehow the expected behaviour related to ellipticity.

In Sect. 2.3 we establish an inductive argument by space dimension. Roughly speaking this says that for understanding in any dimension whether one finds operators with sign changing fundamental solutions it suffices to understand the behaviour in “small” dimensions.

In Sect. 3 we calculate in almost closed form fundamental solutions for some specific fourth order elliptic operators in any dimension $n \geq 5$. For a specific direction we even find a very simple closed expression. From $n = 6$ on, we observe sign change. While for $n = 6, 7$ we need a nonconvex symbol, for $n \geq 8$ even convex symbols are admissible. The examples presented here use similar symbols as in [3] and [14], but they are constructed with the help of a different method based on the Fourier transform and the residue theorem. For $n = 6$ even the observation is new—to the best of our knowledge.

These examples yield the first important result.

Theorem 1.1 *For $m = 2$ and any $n \geq 6$ there exists a uniformly elliptic (fourth order) operator L with constant coefficients such that the corresponding fundamental solution K_L is sign changing for $|x - y| \rightarrow 0$.*

For the proof, see Theorem 2.3 and Proposition 3.3.

In order to answer the question asked by Davies for a systematic understanding of this phenomenon, we find in Sect. 4 explicit formulae for fundamental solutions from which it becomes clear which kind of elliptic symbols yield positive and sign changing fundamental solutions, respectively.

In odd dimensions we find the following general elegant formula.

Theorem 1.2 *Let $n \geq 2m + 1$ be odd. Then, the fundamental solution K_L is given by*

$$K_L(x, y) = \frac{(-1)^{\frac{n-2m-1}{2}}}{2^n \pi^{n-1} |x - y|^{n-2m}} \int_{\substack{|\xi|=1 \\ (x-y) \cdot \xi = 0}} \nabla^{n-2m-1} \frac{1}{Q(\xi)} \left(\frac{x - y}{|x - y|} \otimes^{n-2m-1} \right) d\mathcal{H}^{n-2}(\xi).$$

Here, if T is a j -multilinear form and v is a vector, we use the compact tensorial notation

$$T(v^{\otimes j}) := T(\underbrace{v, v, \dots, v}_{j\text{-times}}),$$

so, in particular,

$$\nabla^j f(\xi)(v^{\otimes j}) = \sum_{h_1, \dots, h_j=1}^n \frac{\partial^j f}{\partial_{h_1} \dots \partial_{h_j}}(\xi) v_{h_1} \dots v_{h_j}.$$

To avoid redundant parenthesis we write $\frac{y}{|y|}^{\otimes 2j} := \left(\frac{y}{|y|}\right)^{\otimes 2j}$. Theorem 1.2 is proved in Sect. 4.1 and it follows directly from Theorem 4.3.

In *even dimensions*, due to the presence of the logarithm in (5), we are not able to achieve a comparable compact result, computations being much more involved. However, we show a related formula for the first “critical” dimension $n = 2m + 2$.

Theorem 1.3 *Let $n = 2m + 2$. Then, the fundamental solution K_L is given by*

$$\begin{aligned} K_L(x, y) = & \frac{1}{2^{2m+1}\pi^{2m+2}|x-y|^2} \left\{ \frac{n-2}{2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \right. \\ & + \int_{\substack{|\xi|=1 \\ (x-y) \cdot \xi > 0}} \log \left(\xi \cdot \frac{x-y}{|x-y|} \right) \left[(4m+4-n) \left(\xi \cdot \frac{x-y}{|x-y|} \right) \nabla \frac{1}{Q(\xi)} \left(\frac{x-y}{|x-y|} \right) \right. \\ & \left. \left. + 2m \frac{1}{Q(\xi)} + \nabla^2 \frac{1}{Q(\xi)} \left(\frac{x-y}{|x-y|}^{\otimes 2} \right) + \left(\xi \cdot \frac{x-y}{|x-y|} \right)^2 \Delta \frac{1}{Q(\xi)} \right] d\mathcal{H}^{n-1}(\xi) \right\}. \end{aligned}$$

The proof is given in Sect. 4.2.

The difference between even and odd dimensions here reminds us somehow of the same distinction for the wave equation. In Theorem 1.3 (even dimensional) the integration is carried out over a one-codimensional surface with a weight function, which becomes infinite at its boundary. On the other hand, in Theorem 1.2 (odd dimensional) the integration is carried out over the boundary of this surface, i.e. a 2-codimensional surface. The method of descent, as outlined in Sect. 2.3, gives further support to this observation.

Theorem 1.2 and Formula (5) allow for a first interesting result concerning *positivity* of fundamental solutions.

Corollary 1.4 (i) *If $n = 2m$, the fundamental solution K_L is positive for $|x - y| \in B_{r_L}(0)$ with some $r_L > 0$.*
(ii) *If $n = 2m + 1$, the fundamental solution K_L is always positive.*

Theorem 1.2 shows further which kind of symbol Q will e.g. in space dimension $n = 2m + 3$ yield $K(0, e_1) < 0$. For this one needs $\partial_1^2 \frac{1}{Q}(0, \xi') > 0$ for $|\xi'| = 1$. This would follow e.g. from $\partial_1 Q(0, \xi') = 0$ and $\partial_1^2 Q(0, \xi') < 0$, i.e. (only) from a nonconvex shape of the level set of Q in these points.

For an example of this kind see [3, p. 100] and pp. 20–23 of a preliminary preprint version of this article which can be found at [arXiv:1902.06503v1](https://arxiv.org/abs/1902.06503v1).

The situation is similar but not this clear in the even dimension $n = 2m + 2$, due to the relatively higher dimensional domain of integration and to the presence of further terms. However, thanks to the logarithmic singularity one may expect that also here, a nonconvex symbol may work. Indeed we prove in Sect. 5 the following result.

Theorem 1.5 (Examples of sign changing fundamental solutions, the even dimensional case). *For any $m \geq 2$ and $n = 2m + 2$ there exists an elliptic symbol Q of order $2m$ such that the fundamental solution of the associated operator L_Q is sign changing for $|x - y| \rightarrow 0$.*

In view of Sect. 2.3 and Theorem 2.3 we may immediately conclude the following general result.

Corollary 1.6 *For any $m \geq 2$ and $n \geq 2m + 2$ there exists an elliptic symbol Q such that the fundamental solution of the associated operator L_Q is sign changing for $|x - y| \rightarrow 0$.*

Together with Corollary 1.4 we have so obtained a complete picture of positivity and change of sign, respectively, in all “singular” dimensions $n \geq 2m$.

1.7 Notation

We denote the partial derivative as D^α or ∂_α or $\frac{\partial}{\partial \alpha}$, where α is a multi-index, with the convention that if $D^0 u = u$ for any function. Moreover, if $j \in \mathbb{N}$, $\nabla^j u$ stands for the tensor of the j -th derivatives. Finally, we denote by $\mathcal{H}^k$ the k -th dimensional Hausdorff measure.

2 Basic observations

In this section we consider only the case $n > 2m$ of large dimensions. In what follows L always denotes a uniformly elliptic operator as in (1) with constant coefficients and only of highest order $2m$. K_L denotes John’s fundamental solution as it is given in (4) and (5), respectively. By (2), without loss of generality, we may consider 0 as the pole of K_L .

2.1 Homogeneity, decay and uniqueness of John’s fundamental solution

Lemma 2.1 *For $\sigma \in \mathbb{R} \setminus \{0\}$ and $x \in \mathbb{R}^n \setminus \{0\}$ we have*

$$K_L(0, \sigma x) = |\sigma|^{2m-n} K_L(0, x). \quad (6)$$

In particular this yields for all $x \in \mathbb{R}^n \setminus \{0\}$ and all multi-indices $\alpha \in \mathbb{N}_0^n$

$$|D^\alpha K_L(0, x)| \leq C_\alpha |x|^{2m-n-|\alpha|}. \quad (7)$$

Proof In case of odd $n > 2m$, (4) shows that K_L can be obtained as $(-\Delta)^{(n+1-2m)/2}$ of a 1-homogeneous function. In case of even $n \geq 2m + 2$, the proof of Theorem 1.3 in Sect. 4.2 shows that K_L can be obtained $(-\Delta)^{(n+1-2m)/2}$ of a (-2) -homogeneous function. $K_L(0, x) = K_L(0, -x)$ follows from the corresponding property of the symbol. $\square$

Proposition 2.2 *Let K_L and $\tilde{K}_L$ be two fundamental solutions for L which both obey (6). Then*

$$K_L(0, x) \equiv \tilde{K}_L(0, x).$$

Proof Defining $u(x) := K_L(0, x) - \tilde{K}_L(0, x)$, we find a solution of $Lu = 0$ in $\mathbb{R}^n$ which thanks to elliptic regularity theory satisfies $u \in C^\infty(\mathbb{R}^n)$. To see this one may combine local elliptic L^p -estimates (see [1, Theorem 15.1]), the difference quotient method as outlined in [8, Section 7.11] and a bootstrapping argument. Since both K_L and $\tilde{K}_L$ satisfy (6) we find that for any $x \in \mathbb{R}^n \setminus \{0\}$ and any $\sigma \in \mathbb{R} \setminus \{0\}$:

$$u(x) = |\sigma|^{n-2m} u(\sigma x).$$

Since $n > 2m$ we conclude by continuity of u in 0 from letting $\sigma \rightarrow 0$ that $u(x) \equiv 0$. $\square$

2.2 Ellipticity and positive directions

We prove the existence of “positive” directions (observe our sign convention for ellipticity) for the fundamental solutions which is somehow the simpler case and which one expects from the notion of ellipticity.

Theorem 2.3 *Assume that $n > 2m$, L is a uniformly elliptic operator with constant coefficients of order $2m$ as introduced in (1) and consider the $(2m - n)$ -homogeneous fundamental solution K_L according to (4) and (5), respectively. Then there exists $y \in \mathbb{R}^n \setminus \{0\}$ such that*

$$K_L(0, y) > 0.$$

Proof We assume by contradiction that

$$\forall y \in \mathbb{R}^n \setminus \{0\} : K_L(0, y) \leq 0.$$

Certainly, $K_L(0, y) \not\equiv 0$. By continuity there exists a nonempty open set $\Omega \subset \mathbb{S}^{n-1}$ such that we have

$$\forall y \in C_\Omega : K_L(0, y) < 0$$

on the corresponding cone

$$C_\Omega := \{r\eta : \eta \in \Omega, r \in \mathbb{R} \setminus \{0\}\}.$$

We consider a fixed radially symmetric $\varphi \in C_0^\infty(\mathbb{R}^n)$ with

$$0 \leq \varphi(x) \leq 1; \quad \varphi(x) > 0 \Leftrightarrow |x| \leq \frac{1}{2}.$$

We introduce a corresponding solution (defined in the whole space) of the differential equation by

$$U(x) := \int_{\mathbb{R}^n} K_L(x, y) \varphi(y) dy = \int_{\mathbb{R}^n} K_L(0, y) \varphi(x - y) dy.$$

Since for $x \in \overline{B_{1/2}(0)}$ the intersection $(x + \mathcal{C}_\Omega) \cap B_{1/2}(0)$ is nonempty, U is strictly negative there. By compactness we find a constant $C_0 > 0$ such that

$$\forall x \in \overline{B_{1/2}(0)} : U(x) \leq -C_0 < 0.$$

Next, we introduce a scaling parameter $\sigma \in (0, 1]$ and consider for

$$\varphi_\sigma(x) := \varphi(x/\sigma)$$

the solution of the corresponding Dirichlet problem in $\overline{B_1(0)}$

$$\overline{B_1(0)} \ni x \mapsto u_\sigma(x) := \int_{B_1(0)} G(x, y) \varphi_\sigma(y) dy.$$

Here,

$$G(x, y) := G_{L, B_1(0)}(x, y) =: K_L(x, y) + h(x, y) = K_L(x, y) + h_{L, B_1(0)}(x, y)$$

denotes the corresponding Green function and its decomposition into fundamental solution and regular part. By continuous dependence on parameters and general elliptic theory (see [1]) we find that

$$\forall (x, y) \in \overline{B_{1/2}(0) \times B_{1/2}(0)} : |h(x, y)| \leq C_1$$

with a suitable constant C_1 . In what follows we consider only $x \in \overline{B_{1/2}(0)}$. By the $(2m - n)$ -homogeneity of the fundamental solution we obtain:

$$\begin{aligned} u_\sigma(\sigma x) &= \sigma^n \int_{B_1(0)} (K_L(\sigma x, \sigma y) + h(\sigma x, \sigma y)) \varphi(y) dy \\ &= \sigma^{2m} U(x) + \sigma^n \int_{B_{1/2}(0)} h(\sigma x, \sigma y) \varphi(y) dy \\ &\leq -C_0 \sigma^{2m} + \sigma^n C_1 |B_{1/2}(0)| \leq -\frac{C_0}{2} \sigma^{2m}, \end{aligned}$$

provided that $\sigma \in (0, 1]$ is chosen small enough. We fix such a suitable parameter and keep the corresponding u_σ and φ_σ fixed. We recall that we have shown:

$$\varphi_\sigma(x) > 0 \text{ in } B_{\sigma/2}(0), \quad \varphi_\sigma(x) = 0 \text{ outside } B_{\sigma/2}(0), \quad u_\sigma(x) < 0 \text{ in } B_{\sigma/2}(0).$$

This yields (we recall that λ denotes the ellipticity constant of L)

$$\begin{aligned} 0 &> \int_{B_{\sigma/2}(0)} u_\sigma(x) \varphi_\sigma(x) dx = \int_{B_1(0)} u_\sigma(x) \varphi_\sigma(x) dx = \int_{B_1(0)} u_\sigma(x) (Lu_\sigma(x)) dx \\ &\geq \lambda \|u_\sigma\|_{H_0^m(B_1(0))}^2 > 0, \end{aligned}$$

a contradiction. In the last step we used the elementary form of Gårding's inequality (see [6]) for operators, which have only constant coefficients and only of highest order, which follows from the ellipticity condition by employing the Fourier transform. $\square$

An alternative proof would follow from Corollary 1.4 and the inductive argument of Proposition 2.7 below.

2.3 An inductive argument

For simplicity we write in the remainder of this section

$$K_L(x) := K_L(0, x) = K_L(x, 0).$$

In what follows we always assume that $n - 1 > 2m$, i.e. that

$$n > 2m + 1.$$

2.3.1 A method of descent with respect to space dimension

Here we use the notation

$$x = (x', x_n) \in \mathbb{R}^{n-1} \times \mathbb{R} = \mathbb{R}^n.$$

Let L_n be an elliptic operator in $\mathbb{R}^n$ as in (1)

$$L_n = (-1)^m Q_n \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) = (-1)^m \sum_{i_1, \dots, i_{2m}=1, \dots, n} A_{i_1, \dots, i_{2m}} \frac{\partial}{\partial x_{i_1}} \cdots \frac{\partial}{\partial x_{i_{2m}}},$$

with the symbol

$$Q_n(\xi) = \sum_{i_1, \dots, i_{2m}=1, \dots, n} A_{i_1, \dots, i_{2m}} \xi_{i_1} \cdots \xi_{i_{2m}}.$$

From this we obtain an operator in $\mathbb{R}^{n-1}$ by simply “forgetting” the x_n -coordinate or by considering only functions, which do not depend on x_n :

$$\begin{aligned} L_{n-1} &= (-1)^m Q_{n-1} \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_{n-1}} \right) \\ &= (-1)^m \sum_{i_1, \dots, i_{2m}=1, \dots, (n-1)} A_{i_1, \dots, i_{2m}} \frac{\partial}{\partial x_{i_1}} \cdots \frac{\partial}{\partial x_{i_{2m}}}, \end{aligned} \quad (8)$$

with the corresponding symbol

$$Q_{n-1}(\xi') = Q_n(\xi', 0) = \sum_{i_1, \dots, i_{2m}=1, \dots, (n-1)} A_{i_1, \dots, i_{2m}} \xi_{i_1} \cdots \xi_{i_{2m}}.$$

Since

$$Q_{n-1}(\xi') = Q_n(\xi', 0) \geq \lambda |(\xi', 0)|^{2m} = \lambda |\xi'|^{2m},$$

L_{n-1} is an elliptic operator. Next we define

$$K_{n-1}(x') := \int_{\mathbb{R}} K_n(x', \xi_n) d\xi_n \quad (9)$$

and aim at showing that this is John's (unique) fundamental solution for L_{n-1} .

We prove first that we have the expected homogeneity and hence also the expected decay at ∞ .

Lemma 2.4 For $\sigma \in \mathbb{R} \setminus \{0\}$ and $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ we have:

$$K_{n-1}(\sigma x') = |\sigma|^{2m-n+1} K_{n-1}(x').$$

Proof

$$\begin{aligned} K_{n-1}(\sigma x') &= \int_{\mathbb{R}} K_n(\sigma x', \xi_n) d\xi_n = |\sigma| \int_{\mathbb{R}} K_n(\sigma x', \sigma \xi_n) d\xi_n \\ &= |\sigma|^{1+2m-n} \int_{\mathbb{R}} K_n(x', \xi_n) d\xi_n = |\sigma|^{1+2m-n} K_{n-1}(x'). \end{aligned}$$

□

Next we prove that K_{n-1} is in fact a fundamental solution for L_{n-1} .

Lemma 2.5 For all $\varphi \in C_0^\infty(\mathbb{R}^{n-1})$ we have that

$$\int_{\mathbb{R}^{n-1}} (L_{n-1}\varphi(x')) K_{n-1}(x') dx' = \varphi(0).$$

Proof For $\varphi \in C_0^\infty(\mathbb{R}^{n-1})$ we define

$$\tilde{\varphi}(x', x_n) := \varphi(x')$$

and find that

$$\begin{aligned} \int_{\mathbb{R}^{n-1}} (L_{n-1}\varphi(x')) K_{n-1}(x') dx' &= \int_{\mathbb{R}^{n-1}} (L_{n-1}\varphi(x')) \int_{\mathbb{R}} K_n(x', x_n) dx' dx_n \\ &= \int_{\mathbb{R}^n} (L_n \tilde{\varphi}(x)) K_n(x) dx. \end{aligned} \quad (10)$$

In order to proceed we need to overcome the difficulty that $\tilde{\varphi} \notin C_0^\infty(\mathbb{R}^n)$ by a suitable approximation. To this end we choose

$$\chi \in C_0^\infty(\mathbb{R}, [0, 1]), \quad \chi = \begin{cases} 1 & \text{in } [-1, 1], \\ 0 & \text{outside } [-2, 2], \end{cases}$$

and define

$$\tilde{\varphi}_k(x) := \tilde{\varphi}(x)\chi(x_n/k) = \varphi(x')\chi(x_n/k).$$

We find

$$\begin{aligned} \int_{\mathbb{R}^n} |L_n \tilde{\varphi}(x) - L_n \tilde{\varphi}_k(x)| |K_n(x)| dx &\leq \int_{\text{supp}(\varphi) \times \mathbb{R}} (1 - \chi(x_n/k)) |L_{n-1} \varphi(x')| |K_n(x)| dx' dx_n \\ &\quad + \sum_{j=1}^{2m} C_j k^{1-j} \int_{\text{supp}(\varphi) \times ([-2, -1] \cup [1, 2])} |D^{2m-j} \varphi(x')| |K_n(x', kx_n)| dx' dx_n \\ &\leq C \int_{\text{supp}(\varphi) \times ((-\infty, k) \cup (k, \infty))} |K_n(x)| dx + \sum_{j=1}^{2m} C_j k^{1-j} k^{2m-n} \leq \sum_{j=0}^{2m} C_j k^{2m-n+1-j} \\ &\leq C k^{2m-n+1} \rightarrow 0 \quad \text{as } k \rightarrow \infty, \end{aligned}$$

because we assume that $n > 2m + 1$. With this we conclude from (10)

$$\int_{\mathbb{R}^{n-1}} (L_{n-1} \varphi(x')) K_{n-1}(x') dx' = \lim_{k \rightarrow \infty} \int_{\mathbb{R}^n} (L_n \tilde{\varphi}_k(x)) K_n(x) dx = \lim_{k \rightarrow \infty} \tilde{\varphi}_k(0) = \varphi(0)$$

as claimed. $\square$

Combining Lemmas 2.4 and 2.5 with the uniqueness result of fundamental solutions with suitable degree of homogeneity from Proposition 2.2 we conclude:

Proposition 2.6 K_{n-1} as defined in (9) is John's fundamental solution for L_{n-1} as it is given in (4) and (5), respectively.

2.3.2 Understanding "small" dimensions is sufficient

Proposition 2.7 Assume that $n > 2m + 1$ and that for all elliptic operators L_{n-1} of the form (8) in $\mathbb{R}^{n-1}$ with John's corresponding fundamental solution K_{n-1} there exists a vector $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ such that $K_{n-1}(x') > 0$. Then for all elliptic operators L_n of the form (1) in $\mathbb{R}^n$ with John's corresponding fundamental solution K_n there exists a vector $x = (x', x_n) \in \mathbb{R}^n \setminus \{0\}$ such that $K_n(x') > 0$.

Proof Let L_n be an arbitrary elliptic operator of the form (1) in $\mathbb{R}^n$ with corresponding John's fundamental solution K_n . We define L_{n-1} and K_{n-1} as in Sect. 2.3.1. Then Prop. 2.6 shows that K_{n-1} is John's corresponding fundamental solution. Making use of (9), the assumption yields the existence of a vector $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ such that

$$0 < K_{n-1}(x') = \int_{\mathbb{R}} K_n(x', \xi_n) d\xi_n.$$

This shows that there exists a point $x_n \in \mathbb{R}$ which satisfies $K_n(x', x_n) > 0$. $\square$

Remark 1 Theorem 1.2 (i) and Proposition 2.7 yield a different proof of Theorem 2.3 by means of the inductive procedure.

Proposition 2.8 Assume that $n > 2m + 1$ and that there exists one elliptic operator L_{n-1} of the form (8) in $\mathbb{R}^{n-1}$ with John's corresponding fundamental solution K_{n-1} for which one finds a vector $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ such that $K_{n-1}(x') < 0$. Then there exists one elliptic operator L_n of the form (1) in $\mathbb{R}^n$ with John's corresponding fundamental solution K_n for which one finds a vector $x = (x', x_n) \in \mathbb{R}^n \setminus \{0\}$ such that $K_n(x') < 0$.

Proof Let L_{n-1} be an elliptic operator of the form (8) in $\mathbb{R}^{n-1}$ with symbol Q_{n-1} and corresponding John's fundamental solution K_{n-1} for which one finds a vector $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ such that $K_{n-1}(x') < 0$. We define

$$L_n := L_{n-1} + \partial_n^{2m}$$

which is an operator of the form (1) in $\mathbb{R}^n$ with elliptic symbol

$$Q_n(\xi', \xi_n) = Q_{n-1}(\xi') + \xi_n^{2m} \geq \lambda_{n-1} |\xi'|^{2m} + \xi_n^{2m} \geq \frac{\min\{\lambda_{n-1}, 1\}}{2m} |(\xi', \xi_n)|^{2m}.$$

The operator L_n is connected to L_{n-1} by the procedure described in Sect. 2.3.1. In particular John's fundamental solution K_{n-1} corresponding to L_{n-1} is given by (9). The assumption yields the existence of a vector $x' \in \mathbb{R}^{n-1} \setminus \{0\}$ such that

$$0 > K_{n-1}(x') = \int_{\mathbb{R}} K_n(x', \xi_n) d\xi_n.$$

This shows that there exists a point $x_n \in \mathbb{R}$ which satisfies

$$K_n(x', x_n) < 0,$$

which completes the proof. $\square$

3 Sign changing fundamental solutions for $m = 2$

On $\mathcal{S}(\mathbb{R}^n)$, the space of rapidly decreasing functions, one may define the Fourier-transformation $\mathcal{F} : \mathcal{S}(\mathbb{R}^n) \rightarrow \mathcal{S}(\mathbb{R}^n)$ by

$$(\mathcal{F}u)(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix \cdot \xi} u(x) dx. \quad (11)$$

The inverse on $\mathcal{S}(\mathbb{R}^n)$ is $(\mathcal{F}^{-1}v)(x) = (\mathcal{F}v)(-x)$. The definition of $\mathcal{F}$ in (11) can be directly extended to $u \in L^1(\mathbb{R}^n)$. For $u \in W^{1,1}(\mathbb{R}^n)$ one finds $\left(\mathcal{F}\left(\frac{\partial}{\partial x_j} u\right)\right)(\xi) = i\xi_j (\mathcal{F}u)(\xi)$ and for $u \in W^{2m,1}(\mathbb{R}^n)$ the differential equation $Lu = f$, with L as in

(1) having symbol Q , turns into $Q(\xi) (\mathcal{F}u)(\xi) = (\mathcal{F}f)(\xi)$. If $\mathcal{F}^{-1}$ is defined, then one would obtain a solution of $Lu = f$ by

$$u = \mathcal{F}^{-1} Q(\xi)^{-1} \mathcal{F}f.$$

So formally one would obtain the following expression for the corresponding fundamental solution:

$$F(x) = \left(\mathcal{F}^{-1} Q(\xi)^{-1} \mathcal{F}\delta_0 \right)(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{ix \cdot \xi} \frac{1}{Q(\xi)} d\xi, \quad (12)$$

with δ_0 the delta-distribution in 0 and $\mathcal{F}\delta_0 = (2\pi)^{-n/2}$, cf. (16) below. Due to the homogeneity of Q the integral in (12) is however not defined in $L^1(\mathbb{R}^n)$ but at most as an oscillatory integral.

The Malgrange–Ehrenpreis Theorem, see [16, Theorem IX.23], states that a distributional solution F exists for $LF = \delta_0$, whenever L is a differential operator with constant coefficients. For elliptic operators the zero sets of Q are small in $\mathbb{R}^n$, which may allow one to give a classical meaning to (12) and gives a route to the fundamental solution. In some special cases this formula even allows one to derive an (almost) explicit fundamental solution. One such case is the following class of fourth order elliptic operators:

$$L = (\Delta')^2 + \alpha \Delta' \left(\frac{\partial}{\partial x_n} \right)^2 + \left(\frac{\partial}{\partial x_n} \right)^4, \quad (13)$$

where $x' = (x_1, \dots, x_{n-1})$ and $\Delta' = \sum_{i=1}^{n-1} \left(\frac{\partial}{\partial x_i} \right)^2$.

Although L is only interesting in the present setting whenever $n \geq 5$, allow us to classify L for all dimensions.

Lemma 3.1 *For L in (13) one finds:*

1. L is elliptic, if and only if $\alpha > -2$.
2. If $\alpha \geq 2$, the operator L can be written as a product of two real second order elliptic operators.
3. If $\alpha \in (-2, 2)$, the operator L can be written as a product of two real second order elliptic operators only for $n = 2$.

Notice that the level hypersurfaces of the symbol for L are convex, if and only if $\alpha \geq 0$. For $\alpha = 2$ one recovers $L = \Delta^2$.

Proof To prove that ellipticity holds if and only if $\alpha > -2$, is elementary. For $|\alpha| \geq 2$ one may split the symbol Q for L in (13) into real quadratic polynomials by:

$$Q(\xi', \xi_n) = \left(|\xi'|^2 + \frac{\alpha + \sqrt{\alpha^2 - 4}}{2} \xi_n^2 \right) \left(|\xi'|^2 + \frac{\alpha - \sqrt{\alpha^2 - 4}}{2} \xi_n^2 \right).$$

Whenever $n = 2$ and $\alpha \in (-2, 2]$ the operator L can be split into a product of two real second order elliptic operators following:

$$Q(\xi_1, \xi_2) = \left(\xi_1^2 - \sqrt{2 - \alpha} \xi_1 \xi_2 + \xi_2^2 \right) \left(\xi_1^2 + \sqrt{2 - \alpha} \xi_1 \xi_2 + \xi_2^2 \right).$$

This last splitting in dimensions $n \geq 3$ with $\alpha \in (-2, 2)$, that is, replacing ξ_1 by $|\xi'|$, would lead to a Fourier multiplier operator of order 2 with *nonsmooth* symbol, i.e. not even to a pseudodifferential operator. $\square$

The interesting case is hence $\alpha \in (-2, 2)$ and then it is convenient to use $\alpha = 2 \cos \gamma$ with $\gamma \in (0, \pi)$. So we write

$$L_\gamma = (\Delta')^2 + 2 \cos \gamma \Delta' \left(\frac{\partial}{\partial x_n} \right)^2 + \left(\frac{\partial}{\partial x_n} \right)^4 \quad (14)$$

with corresponding symbol $Q(\xi', \xi_n) = |\xi'|^4 + 2 \cos \gamma |\xi'|^2 \xi_n^2 + \xi_n^4$. The fundamental solution for (14) is a regular distribution, so a function, which is C^∞ on $\mathbb{R}^n \setminus \{0\}$ and moreover, homogeneous of degree $4 - n$. We will recall that fact as the first step, when we prove the following result.

Proposition 3.2 *Let $n \geq 5$ and $\gamma \in (0, \pi)$. The fundamental solution $F_{n,\gamma}$ for (14) satisfies:*

- when $|x'| \neq 0$ and $x_n \neq 0$ one has

$$F_{n,\gamma}(x) = \frac{1}{2^{n-2} \Gamma\left(\frac{n-2}{2}\right) \pi^{n/2} |x'|^{n-4}} \cdot \int_0^\infty C_n(s) \frac{\exp\left(-\frac{|x_n|}{|x'|} s \cos\left(\frac{1}{2}\gamma\right)\right) \sin\left(\frac{|x_n|}{|x'|} s \sin\left(\frac{1}{2}\gamma\right) + \frac{1}{2}\gamma\right)}{2 \sin(\gamma)} s^{n-5} ds$$

with $C_n(s) := \int_0^\pi \cos(s \cos \varphi) (\sin \varphi)^{n-3} d\varphi$;

- when $|x'| = 0$ and $x_n \neq 0$ one obtains

$$F_{n,\gamma}(x) = \frac{\Gamma(n-4)}{2^{n-1} \Gamma\left(\frac{n-1}{2}\right) \pi^{(n-1)/2} |x_n|^{n-4} \sin(\gamma)} \sin\left(\frac{n-3}{2}\gamma\right). \quad (15)$$

Proof The proof is divided into 4 steps.

(i) *Fundamental solution as distribution through an inverse Fourier transform.* Let us first discuss the extensions of the Fourier transform $\mathcal{F}$ in (11). Both $\mathcal{F}$ and its inverse are well defined on $\mathcal{S}(\mathbb{R}^n)$. By definition, a sequence $(\varphi_\ell)_{\ell \in \mathbb{N}} \subset \mathcal{S}(\mathbb{R}^n)$ converges to $\varphi \in \mathcal{S}(\mathbb{R}^n)$ iff for all $k \in \mathbb{N}$ and for all multi-indices $\alpha \in \mathbb{N}_0^n$ one has $\sup_{x \in \mathbb{R}^n} ((1 + |x|)^k |D^\alpha(\varphi_\ell - \varphi)(x)|) \rightarrow 0$ as $\ell \rightarrow \infty$. The natural extension to the space of tempered distributions $\mathcal{S}(\mathbb{R}^n)'$ is then [11, Definition 7.1.9] as follows:

$$\langle \mathcal{F}\Psi, \varphi \rangle := \langle \Psi, \mathcal{F}\varphi \rangle \text{ for } \Psi \in \mathcal{S}(\mathbb{R}^n)' \text{ and } \varphi \in \mathcal{S}(\mathbb{R}^n), \quad (16)$$

with a similar version for the inverse; $\langle \cdot, \cdot \rangle$ denotes the duality between distribution and test function.

For $u \in L^1(\mathbb{R}^n)$ the $\mathcal{F}$ in (11) is well defined and one finds $\mathcal{F}u \in L^\infty(\mathbb{R}^n)$ and even the estimate $\|\mathcal{F}u\|_\infty \leq \frac{1}{(2\pi)^{n/2}} \|u\|_1$, but generically $\mathcal{F}u \notin L^1(\mathbb{R}^n)$. In general $\mathcal{F}^{-1}$ is not directly well defined on $L^\infty(\mathbb{R}^n)$. The Fourier-transformation can also be extended to $L^2(\mathbb{R}^n)$ by Plancherel and hence [11, Theorem 7.1.13] for $L^p(\mathbb{R}^n)$ with $p \in [1, 2]$. For those $p \in (1, 2]$ one finds $\mathcal{F}L^p(\mathbb{R}^n) \subset L^q(\mathbb{R}^n)$ with $q = \frac{p}{p-1} \geq 2$. So the formula in (12) needs clarification.

With the definition of the (inverse) Fourier transform in (16) one finds by [11, Theorem 7.1.20] for $n > 4$, that

$$F_{n,\gamma} := \mathcal{F}^{-1} \left(\left(\frac{1}{Q} \right) \mathcal{F}\delta_0 \right) = (2\pi)^{-n/2} \mathcal{F}^{-1} \left(\left(\frac{1}{Q} \right)^\bullet \right) \quad (17)$$

is defined in $\mathcal{S}(\mathbb{R}^n)'$ and, since $L\varphi = L^*\varphi$, is such that

$$\langle LF_{n,\gamma}, \varphi \rangle := \langle F_{n,\gamma}, L\varphi \rangle = \langle \delta_0, \varphi \rangle \quad \text{for all } \varphi \in \mathcal{S}(\mathbb{R}^n).$$

The dot in (17) is defined in [11, Theorem 3.2.3] as the unique homogeneous extension to $\mathcal{D}(\mathbb{R}^n)'$ of the same degree of homogeneity, namely -4 , of $Q^{-1} \in \mathcal{D}(\mathbb{R}^n \setminus \{0\})'$, whenever this degree is not an integer below or equal $-n$. Here $\mathcal{D}(\mathbb{R}^n)'$ is the space of Schwartz distributions. The distribution $u \in \mathcal{D}(X)'$ is homogeneous of degree a , when

$$\langle u, \varphi \rangle = t^a \langle u, t^n \varphi(t \cdot) \rangle \quad \text{for all } t > 0 \text{ and } \varphi \in \mathcal{D}(X).$$

The distribution Q^{-1} on $\mathcal{D}(\mathbb{R}^n \setminus \{0\})$, when extended to $\mathcal{D}(\mathbb{R}^n)$, can only add a combination of the δ_0 -distribution and its distributional derivatives. Since in $\mathbb{R}^n$ each such a distribution is homogeneous of degree $-n$ or less, one finds that the extension is the regular distribution, that is, the function $\xi \mapsto Q^{-1}(\xi)$ on $\mathbb{R}^n$ and we may skip the dot. By [11, Theorem 7.1.16] $F_{n,\gamma}$ with $n \geq 5$ is then homogeneous of degree $4 - n$ and by [11, Theorem 7.1.18] one finds that $F_{n,\gamma} \in \mathcal{S}(\mathbb{R}^n)'$ and that $(F_{n,\gamma})|_{\mathbb{R}^n \setminus \{0\}} \in C^\infty(\mathbb{R}^n \setminus \{0\})$ is a function. Also here the extension in 0 of this function can only add a combination of the δ_0 -distribution and its distributional derivatives and again, in $\mathbb{R}^n$ each such distribution is homogeneous of degree $-n$ or less. So indeed, one finds that also $F_{n,\gamma}$ is given by a function satisfying:

$$F_{n,\gamma}(x) = |x|^{4-n} F_{n,\gamma} \left(\frac{x}{|x|} \right).$$

With $M = \sup_{|\omega|=1} |F_{n,\gamma}(\omega)|$ one finds from this

$$|F_{n,\gamma}(x)| \leq M |x|^{4-n} \quad \text{for } x \in \mathbb{R}^n \setminus \{0\}. \quad (18)$$

(ii) *Approximation as distribution through a summability kernel.* Since we have established that $F_{n,\gamma}$ is a function, we will try next to derive a more explicit formula. Since

Q^{-1} is not an L^1 -function the direct definition of the inverse Fourier-transform just after (11) is not applicable. We will use an approximation through a special positive summability kernel k_ε , see [13, Section VI.1.9]. A positive summability kernel on $\mathbb{R}^n$ is defined as a family $(k_\varepsilon)_{\varepsilon \in (0, \varepsilon_0]} \subset C(\mathbb{R}^n)$ with $k_\varepsilon \geq 0$ satisfying:

1. for all $\varepsilon \in (0, \varepsilon_0]$: $\int_{\mathbb{R}^n} k_\varepsilon(x) dx = 1$;
2. for all $\delta > 0$: $\lim_{\varepsilon \downarrow 0} \int_{|x| > \delta} k_\varepsilon(x) dx = 0$.

The summability kernel that we use is a combination of a Gauss kernel in $x' \in \mathbb{R}^{n-1}$ and $\frac{1}{2\varepsilon} e^{-|x_n|/\varepsilon}$. We set

$$k_1(x) := \frac{1}{\sqrt{2\pi}^{n-1}} \exp\left(-\frac{1}{2}|x'|^2\right) \frac{1}{2} \exp(-|x_n|) \quad (19)$$

and define

$$k_\varepsilon(x) := \varepsilon^{-n} k_1(x/\varepsilon). \quad (20)$$

Recall that

$$\int_{\mathbb{R}} e^{-ist - \frac{1}{2}t^2} dt = \sqrt{2\pi} e^{-\frac{1}{2}s^2} \quad \text{and} \quad \int_{\mathbb{R}} e^{-ist} \frac{1}{2} e^{-|t|} dt = \frac{1}{1+s^2}.$$

So one finds $(\mathcal{F}k_\varepsilon)(\xi) = (\mathcal{F}k_1)(\varepsilon\xi)$ and

$$\begin{aligned} (\mathcal{F}k_1)(\xi) &= \frac{1}{\sqrt{2\pi}^{n-1}} \exp\left(-\frac{1}{2}|\xi'|^2\right) \frac{1}{\sqrt{2\pi}(1+\xi_n^2)} \\ &= \frac{1}{\sqrt{2\pi}^n} \frac{\exp\left(-\frac{1}{2}|\xi'|^2\right)}{1+\xi_n^2}. \end{aligned}$$

One obtains for all $\varphi \in \mathcal{S}(\mathbb{R}^n)$, exploiting $k_\varepsilon * \varphi \rightarrow \varphi$ in $\mathcal{S}(\mathbb{R}^n)$, that

$$\begin{aligned} \langle F_{n,\gamma}, \varphi \rangle &= \lim_{\varepsilon \downarrow 0} \langle F_{n,\gamma}, k_\varepsilon * \varphi \rangle = (2\pi)^{-n/2} \lim_{\varepsilon \downarrow 0} \left\langle \frac{1}{Q}, \mathcal{F}^{-1}(k_\varepsilon * \varphi) \right\rangle \\ &= \lim_{\varepsilon \downarrow 0} \left\langle \frac{1}{Q}, \left(\mathcal{F}^{-1}k_\varepsilon \right) \left(\mathcal{F}^{-1}\varphi \right) \right\rangle \quad (21) \end{aligned}$$

and from the properties of distributions:

$$\begin{aligned} \left\langle \frac{1}{Q}, \left(\mathcal{F}^{-1}k_\varepsilon \right) \left(\mathcal{F}^{-1}\varphi \right) \right\rangle &= \left\langle \overline{\mathcal{F}^{-1}k_\varepsilon} \frac{1}{Q}, \mathcal{F}^{-1}\varphi \right\rangle \\ &= \left\langle \mathcal{F}k_\varepsilon \frac{1}{Q}, \mathcal{F}^{-1}\varphi \right\rangle = \left\langle \mathcal{F}^{-1} \left(\mathcal{F}k_\varepsilon \frac{1}{Q} \right), \varphi \right\rangle. \quad (22) \end{aligned}$$

In other words $\mathcal{F}^{-1} \left(\mathcal{F}k_\varepsilon \frac{1}{Q} \right) \rightarrow F_{n,\gamma}$ for $\varepsilon \downarrow 0$ in the sense of distributions.

(iii) *Approximation as a function through the summability kernel.* Since $F_{n,\gamma}$ is a regular distribution and

$$(x, y) \mapsto F_{n,\gamma}(x) k_\varepsilon(x - y) \varphi(y) \in L^1(\mathbb{R}^n \times \mathbb{R}^n),$$

we may also write

$$\begin{aligned} \langle F_{n,\gamma}, k_\varepsilon * \varphi \rangle &= \int_{\mathbb{R}^n} F_{n,\gamma}(x) \int_{\mathbb{R}^n} k_\varepsilon(x - y) \varphi(y) dy dx \\ &= \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} F_{n,\gamma}(x) k_\varepsilon(x - y) \varphi(y) dx dy = \langle F_{n,\gamma} * k_\varepsilon, \varphi \rangle. \end{aligned} \quad (23)$$

Setting

$$f_\varepsilon(x) := (F_{n,\gamma} * k_\varepsilon)(x) \quad (24)$$

we find from (18) and (20) that

$$\begin{aligned} |f_\varepsilon(x)| &\leq \int_{y \in \mathbb{R}^n} |F_{n,\gamma}(y) k_\varepsilon(x - y)| dy \leq M \int_{y \in \mathbb{R}^n} |y|^{4-n} k_\varepsilon(x - y) dy \\ &= M(k_\varepsilon * |\cdot|^{4-n})(x) = \varepsilon^{4-n} M(k_1 * |\cdot|^{4-n})(\varepsilon^{-1}x). \end{aligned} \quad (25)$$

Since $k_1(x) \leq ce^{-|x|/2}$ for some $c > 0$, we may estimate the last expression in (25) by splitting the corresponding integral in two parts: $|x - y| < \frac{1}{2}|x|$, implying $|y| \geq \frac{1}{2}|x|$, and $|x - y| > \frac{1}{2}|x|$. Indeed, one finds for some $C_1 > 0$ that

$$\begin{aligned} (k_1 * |\cdot|^{4-n})(x) &\leq c \left(\int_{|x-y| < \frac{1}{2}|x|} e^{-|y|/2} |x - y|^{4-n} dy + \int_{|x-y| > \frac{1}{2}|x|} e^{-|y|/2} |x - y|^{4-n} dy \right) \\ &\leq c\sigma_n \left(e^{-\frac{1}{4}|x|} \int_{r=0}^{\frac{1}{2}|x|} r^{4-n+n-1} dr + \left(\frac{1}{2}|x|\right)^{4-n} \int_{r=0}^{\infty} e^{-r/2} r^{n-1} dr \right) \\ &= c\sigma_n \left(\frac{1}{64} e^{-\frac{1}{4}|x|} |x|^4 + 2^{2n-4} |x|^{4-n} \Gamma(n) \right) \leq C_1 |x|^{4-n}, \end{aligned}$$

with $\sigma_n = \int_{\mathbb{S}^{n-1}} d\omega = \frac{2\pi^{n/2}}{\Gamma(n/2)}$, the surface area of the unit sphere in $\mathbb{R}^n$. The result is that

$$|f_\varepsilon(x)| \leq \varepsilon^{4-n} M(k_1 * |\cdot|^{4-n})(\varepsilon^{-1}x) \leq C_1 \varepsilon^{4-n} |\varepsilon^{-1}x|^{4-n} = C_1 |x|^{4-n}.$$

This allows us to use Lebesgue's dominated convergence theorem to find with (21) and (23) that

$$\langle F_{n,\gamma}, \varphi \rangle = \lim_{\varepsilon \downarrow 0} \int_{\mathbb{R}^n} f_\varepsilon(x) \varphi(x) dx = \int_{\mathbb{R}^n} \lim_{\varepsilon \downarrow 0} f_\varepsilon(x) \varphi(x) dx \quad \text{for all } \varphi \in \mathcal{S}(\mathbb{R}^n) \quad (26)$$

with the last identity for any measurable $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ such that $\int_{\mathbb{R}^n} |\varphi(x)| |x|^{4-n} dx < \infty$.

(iv) *An almost explicit formula by a contour integral.* Next we will compute f_ε using the formula $\mathcal{F}^{-1} \left(\mathcal{F} k_\varepsilon \frac{1}{Q} \right)$ from (22). The symbol $Q = Q_\gamma$ for (14) satisfies

$$Q_\gamma(\xi', \xi_n) = \left(\xi_n + i e^{i\gamma/2} |\xi'| \right) \left(\xi_n - i e^{i\gamma/2} |\xi'| \right) \left(\xi_n + i e^{-i\gamma/2} |\xi'| \right) \left(\xi_n - i e^{-i\gamma/2} |\xi'| \right)$$

and the approximation f_ε of the fundamental solution $F_{n,\gamma}(x)$ for (14) becomes

$$f_\varepsilon(x) = \left(\mathcal{F}^{-1} \left(\mathcal{F} k_\varepsilon \frac{1}{Q_\gamma} \right) \right)(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{ix \cdot \xi} \frac{1}{Q_\gamma(\xi)} \frac{\exp \left(-\frac{1}{2} \varepsilon^2 |\xi'|^2 \right)}{1 + \varepsilon^2 \xi_n^2} d\xi. \quad (27)$$

Note that the integral converges near 0 for $n \geq 5$. Near ∞ the integral converges for all n .

The integrand in (27) contains an analytic function of $\xi_n \in \mathbb{C}$ and we find for $\gamma \in (0, \pi)$ and $x_n > 0$ by a contour integral in $\mathbb{R} + i[0, \infty) \subset \mathbb{C}$ that

$$\begin{aligned} f_\varepsilon(x) &= \frac{1}{(2\pi)^n \varepsilon^2} \int_{\xi' \in \mathbb{R}^{n-1}} e^{ix' \cdot \xi' - \frac{1}{2} \varepsilon^2 |\xi'|^2} \int_{\xi_n \in \mathbb{R}} \frac{e^{ix_n \xi_n}}{Q(\xi', \xi_n) \left(\xi_n - \frac{i}{\varepsilon} \right) \left(\xi_n + \frac{i}{\varepsilon} \right)} d\xi_n d\xi' \\ &= \frac{2\pi i}{(2\pi)^n \varepsilon^2} \int_{\xi' \in \mathbb{R}^{n-1}} e^{ix' \cdot \xi' - \frac{1}{2} \varepsilon^2 |\xi'|^2} \\ &\quad \cdot \sum_{z \in \left\{ i e^{i\gamma/2} |\xi'|, i e^{-i\gamma/2} |\xi'|, \frac{i}{\varepsilon} \right\}} \operatorname{Res} \left(\frac{\exp(ix_n \xi_n)}{Q_\gamma(\xi', \xi_n) \left(\xi_n - \frac{i}{\varepsilon} \right) \left(\xi_n + \frac{i}{\varepsilon} \right)} \right)_{\xi_n=z} d\xi' \\ &= \frac{2\pi i}{(2\pi)^n} \int_{\xi' \in \mathbb{R}^{n-1}} e^{ix' \cdot \xi' - \frac{1}{2} \varepsilon^2 |\xi'|^2} \left(\frac{\exp(-x_n e^{i\gamma/2} |\xi'|)}{4 e^{i\gamma/2} \sin(\gamma) |\xi'|^3 (1 - \varepsilon^2 e^{i\gamma} |\xi'|^2)} \right. \\ &\quad + \frac{-\exp(-x_n e^{-i\gamma/2} |\xi'|)}{4 e^{-i\gamma/2} \sin(\gamma) |\xi'|^3 (1 - \varepsilon^2 e^{-i\gamma} |\xi'|^2)} \\ &\quad \left. - \frac{i \varepsilon^3 \exp(-x_n/\varepsilon)}{2 (1 - \varepsilon^2 e^{i\gamma} |\xi'|^2) (1 - \varepsilon^2 e^{-i\gamma} |\xi'|^2)} \right) d\xi'. \quad (28) \end{aligned}$$

Since $\gamma \in (0, \pi)$ holds and by the negative exponents in the exponential, the integral in (28) converges. The last term of (28) contains $\exp(-x_n/\varepsilon)$, which shows that

$$\left| \frac{\varepsilon^3 \exp(-x_n/\varepsilon)}{2i Q_\gamma(\varepsilon \xi', i)} \right| \leq \frac{k! \varepsilon^{k+3}}{(\varepsilon^4 |\xi'|^4 - 2 \cos \gamma \varepsilon^2 |\xi'|^2 + 1) x_n^k}.$$

Hence by taking $k > n - 4$ it follows, whenever $x_n > 0$, for $\varepsilon \downarrow 0$ that

$$\begin{aligned} & \left| \int_{\xi' \in \mathbb{R}^{n-1}} e^{ix' \cdot \xi' - \frac{1}{2} \varepsilon^2 |\xi'|^2} \frac{\varepsilon^3 \exp(-x_n/\varepsilon)}{2i Q_\gamma(\varepsilon \xi', i)} d\xi' \right| \\ & \leq \int_{y' \in \mathbb{R}^{n-1}} \frac{k! \varepsilon^{k+4-n} e^{-\frac{1}{2} |y'|^2}}{(|y'|^4 - 2 \cos \gamma |y'|^2 + 1) x_n^k} dy' \rightarrow 0. \end{aligned}$$

It remains to consider

$$\begin{aligned} F_{n,\gamma}(x) &= \lim_{\varepsilon \downarrow 0} f_\varepsilon(x) \\ &= \lim_{\varepsilon \downarrow 0} \frac{2\pi i}{(2\pi)^n} \int_{\xi' \in \mathbb{R}^{n-1}} \frac{e^{ix' \cdot \xi' - \frac{1}{2} \varepsilon^2 |\xi'|^2}}{4 \sin(\gamma) |\xi'|^3} \left(\frac{\exp(-x_n e^{i\gamma/2} |\xi'|)}{e^{i\gamma/2} (1 - \varepsilon^2 e^{i\gamma} |\xi'|^2)} - \frac{\exp(-x_n e^{-i\gamma/2} |\xi'|)}{e^{-i\gamma/2} (1 - \varepsilon^2 e^{-i\gamma} |\xi'|^2)} \right) d\xi' \\ &= \frac{2\pi i}{(2\pi)^n} \int_{\xi' \in \mathbb{R}^{n-1}} \frac{e^{ix' \cdot \xi'}}{4 \sin(\gamma) |\xi'|^3} \left(e^{-x_n e^{i\gamma/2} |\xi'| - i\gamma/2} - e^{-x_n e^{-i\gamma/2} |\xi'| + i\gamma/2} \right) d\xi' \\ &= \frac{1}{(2\pi)^{n-1}} \int_{\xi' \in \mathbb{R}^{n-1}} e^{ix' \cdot \xi'} \frac{\exp(-x_n |\xi'| \cos(\frac{1}{2}\gamma)) \sin(x_n |\xi'| \sin(\frac{1}{2}\gamma) + \frac{1}{2}\gamma)}{2 |\xi'|^3 \sin(\gamma)} d\xi', \end{aligned} \quad (29)$$

which is well-defined for $x_n > 0$. For $x_n < 0$ one replaces x_n by $|x_n|$ in (29).

For the remaining integral in (29) we proceed by using for $\xi' \in \mathbb{R}^{n-1}$ with $n \geq 4$ the coordinates

$$\xi' = \begin{pmatrix} r \cos \varphi \\ r \omega'' \sin \varphi \end{pmatrix} \text{ with } r \geq 0, \omega'' \in \mathbb{S}^{n-3} \text{ and } \varphi \in [0, \pi],$$

where $\mathbb{S}^{n-3} = \{v \in \mathbb{R}^{n-2}; |v| = 1\}$. By the rotational symmetry in $x' \in \mathbb{R}^{n-1}$ one may assume that $x' = |x'| \mathbf{e}_1$ and we find through $e^{ix' \cdot \xi'} = e^{i|x'| \xi_1} = e^{ir|x'| \cos(\varphi)}$ and $d\xi' = (\sin \varphi)^{n-3} r^{n-2} d\varphi dr d\omega''$, that

$$\begin{aligned} F_{n,\gamma}(x) &= \frac{1}{(2\pi)^{n-1}} \int_{\mathbb{S}^{n-3}} \left(\int_0^\infty \frac{\exp(-|x_n| r \cos(\frac{1}{2}\gamma)) \sin(|x_n| r \sin(\frac{1}{2}\gamma) + \frac{1}{2}\gamma)}{2r^3 \sin(\gamma)} \right. \\ & \quad \cdot \left. \left(\int_0^\pi e^{ir|x'| \cos \varphi} (\sin \varphi)^{n-3} d\varphi \right) r^{n-2} dr \right) d\omega''. \end{aligned} \quad (30)$$

Notice that

$$\int_0^\pi e^{is \cos \varphi} (\sin \varphi)^{n-3} d\varphi = \int_0^\pi \cos(s \cos \varphi) (\sin \varphi)^{n-3} d\varphi = C_n(s) \quad (31)$$

with C_n as in Lemma 3.2 and

$$C_n(0) = \int_0^\pi (\sin \varphi)^{n-3} d\varphi = \frac{\sqrt{\pi} \Gamma\left(\frac{n-2}{2}\right)}{\Gamma\left(\frac{n-1}{2}\right)} > 0.$$

We find for $|x'| \neq 0$ and $x_n \neq 0$ from (30) that

$$\begin{aligned} F_{n,\gamma}(x) &= \frac{\sigma_{n-2}}{(2\pi)^{n-1}} \int_0^\infty C_n(r|x'|) \frac{\exp(-|x_n|r \cos(\frac{1}{2}\gamma)) \sin(|x_n|r \sin(\frac{1}{2}\gamma) + \frac{1}{2}\gamma)}{2 \sin(\gamma)} r^{n-5} dr \\ &= \frac{1}{2^{n-2} \Gamma\left(\frac{n-2}{2}\right) \pi^{n/2} |x'|^{n-4}} \int_0^\infty C_n(s) \frac{\exp(-\frac{|x_n|}{|x'|} s \cos(\frac{1}{2}\gamma)) \sin(\frac{|x_n|}{|x'|} s \sin(\frac{1}{2}\gamma) + \frac{1}{2}\gamma)}{2 \sin(\gamma)} s^{n-5} ds. \end{aligned}$$

For $|x'| = 0$ and $x_n \neq 0$ one obtains

$$\begin{aligned} F_{n,\gamma}(x) &= \frac{\sigma_{n-2}}{(2\pi)^{n-1}} \frac{\sqrt{\pi} \Gamma\left(\frac{n-2}{2}\right)}{\Gamma\left(\frac{n-1}{2}\right)} \int_0^\infty \frac{\exp(-|x_n|r \cos(\frac{1}{2}\gamma)) \sin(|x_n|r \sin(\frac{1}{2}\gamma) + \frac{1}{2}\gamma)}{2 \sin(\gamma)} r^{n-5} dr \\ &= \frac{\sqrt{\pi}}{2^{n-1} \Gamma\left(\frac{n-1}{2}\right) \pi^{n/2} |x_n|^{n-4} \sin(\gamma)} \operatorname{Re} \left(i e^{-i\gamma/2} \int_0^\infty \exp(-s e^{i\gamma/2}) s^{n-5} ds \right) \\ &= \frac{1}{2^{n-1} \Gamma\left(\frac{n-1}{2}\right) \pi^{(n-1)/2} |x_n|^{n-4} \sin(\gamma)} \operatorname{Re} \left(i \left(e^{i\gamma/2} \right)^{3-n} \Gamma(n-4) \right) \\ &= \frac{\Gamma(n-4)}{2^{n-1} \Gamma\left(\frac{n-1}{2}\right) \pi^{(n-1)/2} |x_n|^{n-4} \sin(\gamma)} \sin\left(\frac{n-3}{2}\gamma\right), \end{aligned}$$

which shows (15). $\square$

Whenever $\frac{n-3}{2}\gamma$ reaches values above π , $F_{n,\gamma}$ in (15) changes sign. This is the case when $n \geq 6$, so we may conclude:

Proposition 3.3 *For all $n \geq 6$ there are $\gamma \in (0, \pi)$ such that $F_{n,\gamma}(0, \dots, 0, x_n) < 0$ for $x_n \neq 0$.*

Together with Theorem 2.3, this proposition yields the proof of Theorem 1.1. Notice that whenever $n \geq 8$, the fundamental solution changes sign even for $\gamma < \frac{1}{2}\pi$, where the level hypersurfaces of the symbol are still convex.

Fig. 1 Sign changing depending on γ for $F_{8,\gamma}$ through a sketch of g from (32). The nodal lines appear in red (dark)

Example 1 For $n = 8$ one finds that

$$C_8(s) = 16 \frac{(3-s^2) \sin s - 3s \cos s}{s^5} = \frac{16}{15} - \frac{8}{105} s^2 + \mathcal{O}(s^4).$$

We have $F_{8,\gamma}(0, \dots, 0, x_8) = \frac{\sin(\frac{5}{2}\gamma)}{40\pi^4 |x_8|^4 \sin(\gamma)}$, which is negative for $\gamma \in (\frac{2}{5}\pi, \frac{4}{5}\pi)$. To get an impression for which combinations of γ and $\beta := \arctan\left(\frac{|x_8|}{|x'|}\right)$ the fundamental solution is negative, Fig. 1 contains a graph of

$$g(\beta, \gamma) = |x|^4 F_{8,\gamma}(x) \text{ for } x = (x', x_8) \text{ with } |x_8| = |x'| \tan \beta, \quad (32)$$

which indeed only depends on $\beta, \gamma \in [0, \frac{1}{2}\pi] \times (0, \pi)$.

4 Developing John's formulae

4.1 Odd dimensions $n > 2m$: explicit fundamental solutions

In this section we prove Theorem 1.2 starting from John's formula (4). In other words, recalling that $K_L(x, y) = K_L(0, x - y)$, we shall compute the iterated Laplacian for

$$F(y) := \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{y \cdot \xi}{Q(\xi)} d\mathcal{H}^{n-1}(\xi). \quad (33)$$

4.1.1 The first iteration: ΔF

Proposition 4.1 *With the notation above, we have*

$$\nabla F(y) = \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\xi^T}{Q(\xi)} d\mathcal{H}^{n-1}(\xi), \quad (34)$$

$$\Delta F(y) = \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-2}(\xi). \quad (35)$$

Before going into details of the proof, let us remark an important consequence of Proposition 4.1.

Remark 2 In the case $n = 2m + 1$, e.g. for a fourth order elliptic operator in $\mathbb{R}^5$, (4) and (35) imply

$$K_L(x, y) = \frac{1}{32\pi^4 |x - y|} \int_{\substack{|\xi|=1 \\ (x-y) \cdot \xi = 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-2}(\xi), \quad (36)$$

which is thus a *positive* fundamental solution having the *expected order of singularity*. The only difference with the polyharmonic case is that an "angular dependent" positive factor appears. Notice that for the model polyharmonic case, as $Q_{\Delta^m}(\xi) := |\xi|^{2m}$, then such factor is identically 1 and we of course retrieve its well-known fundamental solution.

We first recall a classical result about integrations of differential forms (see for instance [4, Satz 3]).

Lemma 4.2 *Let M be an oriented hypersurface with exterior normal vector field $\nu(x)$, which means that for any admissible parametrisation Φ with $x = \Phi(t)$ we have $\det \left(\nu(x), \frac{\partial \Phi}{\partial t_1}(t), \dots, \frac{\partial \Phi}{\partial t_{n-1}}(t) \right) > 0$. Let further $A \subseteq M$ be a compact submanifold and $\mathbf{f} = (f_i)_{i=1}^n : M \rightarrow \mathbb{R}^n$ be a vector field. Then we have*

$$\int_A \mathbf{f}(x) \cdot \nu(x) dS(x) = \int_A \left(\sum_{i=1}^{n-1} (-1)^{i-1} f_i dx_1 \wedge \dots \wedge \widehat{dx_i} \wedge \dots \wedge dx_n \right),$$

with the convention that $\widehat{dx_i}$ means that this factor is missing.

Proof of Proposition 2 Step 1 Let us first compute ∇F on points $y = (y_1, 0, \dots, 0) \neq \mathbf{0}$. Here and everywhere in what follows we assume $y_1 > 0$. Then, by means of a rigid motion in $\mathbb{R}^n$, we will extend the result to the general case.

Writing $y = r\eta$, where $|\eta| = 1$, we have

$$F(y) = r \int_{\substack{|\xi|=1 \\ \eta \cdot \xi > 0}} \frac{\eta \cdot \xi}{Q(\xi)} d\mathcal{H}^{n-1}(\xi).$$

Noticing that the derivative in the first direction is indeed a normal derivative,

$$\frac{\partial^k}{\partial y_1^k} F(y_1, 0, \dots, 0) = \frac{d^k}{dr^k} F(r\eta), \quad (37)$$

therefore we infer

$$\frac{\partial}{\partial y_1} F(y_1, 0, \dots, 0) = \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{y \cdot \xi}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) = \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\xi_1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi), \quad (38)$$

$$\frac{\partial^2}{\partial y_1^2} F(y_1, 0, \dots, 0) = 0.$$

Let us now compute all other first and second derivatives, which thus involve tangential directions. Without loss of generality, we may consider just $\partial_3 F$ and $\partial_{33}^2 F$, the general case being similar. To this aim, we introduce the rotation matrix B_φ which roughly speaking exchanges the first direction with the third:

$$B_\varphi = \left[\begin{array}{ccc|c} \cos \varphi & 0 & -\sin \varphi & \mathbf{0} \\ 0 & 1 & 0 & \\ \sin \varphi & 0 & \cos \varphi & \\ \hline \mathbf{0} & & & \mathbf{I} \end{array} \right] \quad (39)$$

Moreover, define $H(\varphi) := F(B_\varphi y)$. Recalling that $y_i = 0$ for all $i > 1$ and differentiating H in $\varphi = 0$, we have

$$\begin{aligned} \left. \frac{\partial H}{\partial \varphi} \right|_{\varphi=0} &= \left. \partial_1 F|_{(y_1 \cos \varphi, 0, y_1 \sin \varphi, 0, \dots, 0)} \right|_{\varphi=0} (-\sin \varphi y_1)|_{\varphi=0} \\ &\quad + \left. \partial_3 F|_{(y_1 \cos \varphi, 0, y_1 \sin \varphi, 0, \dots, 0)} \right|_{\varphi=0} (\cos \varphi y_1)|_{\varphi=0} \\ &= y_1 \partial_3 F(y). \end{aligned} \quad (40)$$

On the other hand, by definition

$$H(\varphi) = \int_{\substack{|\xi|=1 \\ B_\varphi y \cdot \xi > 0}} \frac{B_\varphi y \cdot \xi}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \stackrel{\xi=B_\varphi \xi'}{=} \int_{\substack{|\xi'|=1 \\ y \cdot \xi' > 0}} \frac{y \cdot \xi'}{Q(B_\varphi \xi')} d\mathcal{H}^{n-1}(\xi').$$

Therefore, using Lemma 4.2,

$$\begin{aligned}
 \frac{\partial H}{\partial \varphi} \Big|_{\varphi=0} &= \int_{\substack{|\xi'|=1 \\ y \cdot \xi' > 0}} (y \cdot \xi') \frac{\partial}{\partial \varphi} \Big|_{\varphi=0} \frac{1}{Q(B_\varphi \xi')} d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} (y_1 \xi'_1) \left(-\xi'_3 \partial_1 \frac{1}{Q(\xi')} + \xi'_1 \partial_3 \frac{1}{Q(\xi')} \right) d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} (y_1 \xi'_1) \begin{pmatrix} \partial_3 \frac{1}{Q(\xi')} \\ 0 \\ -\partial_1 \frac{1}{Q(\xi')} \\ 0 \\ \vdots \\ 0 \end{pmatrix} \cdot \xi' d\mathcal{H}^{n-1}(\xi') \\
 &= y_1 \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \left(\xi'_1 \partial_3 \frac{1}{Q(\xi')} d\xi'_2 \wedge \cdots \wedge d\xi'_n \right. \\
 &\quad \left. - \xi'_1 \partial_1 \frac{1}{Q(\xi')} d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n \right).
 \end{aligned} \tag{41}$$

We observe that for the $(n-2)$ -form

$$\omega := -\frac{\xi'_1}{Q(\xi')} d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n$$

we have

$$\begin{aligned}
 d\omega &= -\left(d \frac{\xi'_1}{Q(\xi')} \right) \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n \\
 &= -\partial_1 \left(\frac{\xi'_1}{Q(\xi')} \right) d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n - \partial_3 \left(\frac{\xi'_1}{Q(\xi')} \right) d\xi'_3 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n \\
 &= -\xi'_1 \left(\partial_1 \frac{1}{Q(\xi')} \right) d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n - \frac{1}{Q(\xi')} d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n \\
 &\quad + \xi'_1 \partial_3 \frac{1}{Q(\xi')} d\xi'_2 \wedge \cdots \wedge d\xi'_n.
 \end{aligned} \tag{42}$$

Hence, by (40)–(42) and Stokes' Theorem, noticing that $\omega = 0$ on $\{\xi'_1 = 0\}$, we infer

$$\begin{aligned}
 \frac{\partial F}{\partial y_3}(y_1, 0, \dots, 0) &= \frac{1}{y_1} \frac{\partial H}{\partial \varphi} \Big|_{\varphi=0} = \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{1}{Q(\xi')} d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \cdots \wedge d\xi'_n + \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} d\omega \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{1}{Q(\xi')} \nu_3(\xi') d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{\xi'_3}{Q(\xi')} d\mathcal{H}^{n-1}(\xi').
 \end{aligned}$$

Analogously one may compute $\partial_k F(y_1, 0, \dots, 0)$ for $k \neq 1$ and then obtain

$$\frac{\partial F}{\partial y_k}(y_1, 0, \dots, 0) = \int_{\substack{|\xi'|=1 \\ y \cdot \xi' > 0}} \frac{\xi'_k}{Q(\xi')} d\mathcal{H}^{n-1}(\xi'). \quad (43)$$

Indeed, it is sufficient to consider instead of B_φ a similar matrix corresponding to a rotation in the plane $\langle y_1, y_k \rangle$. Hence, (38) and (43) yield

$$\nabla F(y_1, 0, \dots, 0) = \int_{\substack{|\xi'|=1 \\ y \cdot \xi' > 0}} \frac{(\xi')^T}{Q(\xi')} d\mathcal{H}^{n-1}(\xi').$$

Step 2 Now we want to extend this identity to a generic point $y \in \mathbb{R}^n \setminus \{0\}$. To this aim, let us write $y = |y|b_1$, where $|b_1| = 1$, and complete this unit vector to a matrix $B = (b_1 \mid \dots \mid b_n) \in SO(n)$. Notice that

$$y = |y|b_1 = B \cdot (|y|, 0, \dots, 0)^T \quad \text{and} \quad (|y|, 0, \dots, 0)^T = B^T y.$$

Moreover, define $\tilde{F} := F \circ B$. From (33) we infer for all $z \in \mathbb{R}^n \setminus \{0\}$ that

$$\tilde{F}(z) = F(Bz) = \int_{\substack{|\xi|=1 \\ Bz \cdot \xi > 0}} \frac{Bz \cdot \xi}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \stackrel{\xi=B\xi'}{=} \int_{\substack{|\xi'|=1 \\ z \cdot \xi' > 0}} \frac{z \cdot \xi'}{Q(B\xi')} d\mathcal{H}^{n-1}(\xi').$$

Therefore,

$$\begin{aligned} \nabla F(y) &= \nabla F(B(|y|, 0, \dots, 0)^T) = \nabla \tilde{F}(|y|, 0, \dots, 0) B^T \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{\xi'^T}{Q(B\xi')} d\mathcal{H}^{n-1}(\xi') \cdot B^T = \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{(B\xi')^T}{Q(B\xi')} d\mathcal{H}^{n-1}(\xi'). \end{aligned}$$

The change of variable $\xi = B\xi'$ yields finally (34).

Step 3 Now it is the turn of *second derivatives*. We compute them with the same method we applied so far, so first we consider the easier case $y = (y_1, 0, \dots, 0)^T$ with $y_1 > 0$ and then we extend this to a general $y \in \mathbb{R}^n \setminus \{0\}$.

Once again, we may for simplicity consider just $\partial_3 F$, the other cases being similar as already mentioned. Let B_φ be as in (39) and for $y = (y_1, 0, \dots, 0)^T$ define

$$\tilde{H}(\varphi) := \partial_3 F(B_\varphi y) = \int_{\substack{|\xi|=1 \\ B_\varphi y \cdot \xi > 0}} \frac{\xi_3}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \stackrel{\xi=B_\varphi \xi'}{=} \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \frac{(B_\varphi \xi')_3}{Q(B_\varphi \xi')} d\mathcal{H}^{n-1}(\xi').$$

Exactly as for F in (40), we have

$$\frac{\partial^2 F}{\partial y_3^2}(y_1, 0, \dots, 0) = \frac{1}{y_1} \frac{\partial \tilde{H}}{\partial \varphi} \Big|_{\varphi=0}.$$

We denote $R(z) := \frac{z_3}{Q(z)}$ for all $z \in \mathbb{R}^n$. Then we have

$$\begin{aligned}
 \frac{\partial \tilde{H}}{\partial \varphi} \Big|_{\varphi=0} &= \frac{\partial}{\partial \varphi} \Big|_{\varphi=0} \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} R(B_\varphi \xi') d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} (-\xi'_3 \partial_1 R(\xi') + \xi'_1 \partial_3 R(\xi')) d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} \begin{pmatrix} \partial_3 R(\xi') \\ 0 \\ -\partial_1 R(\xi') \\ 0 \\ \dots \\ 0 \end{pmatrix} \cdot \nu(\xi') d\mathcal{H}^{n-1}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} (\partial_3 R(\xi') d\xi'_2 \wedge \dots \wedge d\xi'_n - \partial_1 R(\xi') d\xi'_1 \wedge d\xi'_2 \wedge d\xi'_4 \wedge \dots \wedge d\xi'_n) \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} d\xi'_2 \wedge (\partial_1 R(\xi') d\xi'_1 + \partial_3 R(\xi') d\xi'_3) \wedge d\xi'_4 \wedge \dots \wedge d\xi'_n \\
 &= - \int_{\substack{|\xi'|=1 \\ \xi'_1 > 0}} d(R(\xi') d\xi'_2 \wedge d\xi'_4 \wedge \dots \wedge d\xi'_n) \\
 &= - \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} R(\xi') d\xi'_2 \wedge d\xi'_4 \wedge \dots \wedge d\xi'_n,
 \end{aligned}$$

having applied Stokes' Theorem. Let $\tilde{\nu}$ denote the exterior normal of the half-sphere on its boundary, which gives its induced orientation. Hence, using Lemma 4.2 and the definition of R ,

$$\frac{\partial \tilde{H}}{\partial \varphi} \Big|_{\varphi=0} = \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \tilde{\nu}(\xi') \cdot \begin{pmatrix} 0 \\ R(\xi') \\ 0 \\ \dots \\ 0 \end{pmatrix} d\mathcal{H}^{n-2}(\xi') = \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \frac{\xi_3'^2}{Q(\xi')} d\mathcal{H}^{n-2}(\xi').$$

Therefore, we may conclude that for all $k \in \{2, \dots, n\}$ we have

$$\frac{\partial^2 F}{\partial y_k^2}(y_1, 0, \dots, 0) = \frac{1}{|y|} \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \frac{\xi_k'^2}{Q(\xi')} d\mathcal{H}^{n-2}(\xi').$$

Recalling that $\partial_{11}^2 F(y_1, 0, \dots, 0) = 0$, we thus infer

$$\Delta F(y_1, 0, \dots, 0) = \frac{1}{|y|} \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \frac{1}{Q(\xi')} d\mathcal{H}^{n-2}(\xi'). \quad (44)$$

Step 4 Let now $y \in \mathbb{R}^n \setminus \{0\}$ which we write as $y = |y|b_1$, with $|b_1| = 1$, and let us complete this unit vector to a matrix $B := (b_1 \mid \dots \mid b_n) \in SO(n)$. Moreover, recall $\tilde{F} := F \circ B$. Then, one has

$$\Delta F(z) = \text{Tr}(\nabla^2 F(z)) = \text{Tr}(B \nabla^2 \tilde{F}|_{B^T z} B^T) = \text{Tr}(\nabla^2 \tilde{F}|_{B^T z}) = \Delta \tilde{F}(B^T z),$$

and therefore by (44),

$$\begin{aligned} \Delta F(y) &= \Delta \tilde{F}(|y|, 0, \dots, 0) \\ &= \frac{1}{|y|} \int_{\substack{|\xi'|=1 \\ B^T y \cdot \xi' = 0}} \frac{1}{Q(B\xi')} d\mathcal{H}^{n-2}(\xi') \stackrel{\xi=B\xi'}{=} \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-2}(\xi). \end{aligned}$$

□

4.1.2 The k -th iteration $\Delta^k F$ and the proof of Theorem 1.2

The following theorem provides a general formula for the iterated Laplacian of F . We will see that tangential derivatives of the symbol play a fundamental role in the formula.

Theorem 4.3

$$\Delta^k F(y) = \frac{1}{|y|^{2k-1}} \sum_{j=1}^k d_{k,j}(n, m) \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2(k-j)} \frac{1}{Q(\xi)} \left(\frac{y}{|y|} \otimes^{2(k-j)} \right) d\mathcal{H}^{n-2}(\xi), \quad (45)$$

where

$$d_{k,1}(n, m) = 1$$

and for $j = 2, \dots, k$:

$$d_{k,j}(n, m) = (-1)^{j-1} c_{k,j} \prod_{\ell=2}^j (n - 2m - (2k - 2\ell + 3)) \quad (46)$$

with (using the convention that the product is 1 whenever $j = 1$)

$$c_{k,j} = \prod_{\ell=2}^j \frac{(k - \ell + 1)(2k - 2\ell + 1)}{\ell - 1}. \quad (47)$$

Note that Theorem 1.2 is an immediate consequence of Theorem 4.3. This follows from putting $k = \frac{n-2m+1}{2}$, where $d_{k,j} = 0$ for all $j \geq 2$.

The rest of the subsection is devoted to proving Theorem 4.3, the strategy being the following. Firstly, we show that each term of the sum, namely

$$\int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi),$$

once the Laplacian is applied, produces only terms of the same kind (so only even derivatives of $\frac{1}{Q}$ are involved) with order at most $2j+2$, each of them multiplied by the same suitable power of $\frac{1}{|y|}$. This is achieved in Proposition 4.4. As a consequence, we obtain some recurrence formulae for the coefficients $d_{k,j}$ in the proof of Theorem 4.3. These relations will be important to finally prove the theorem by induction.

Let us fix $k \in \mathbb{N}$ and $j \in \{0, \dots, k-1\}$ and define

$$J_{k,j}(y) := \frac{1}{|y|^{2k-1}} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi).$$

Proposition 4.4

$$\begin{aligned} \nabla J_{k,j}(y) = \frac{1}{|y|^{2k}} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} & \left[(2j) \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j-1}, \cdot \right) - \xi^T \cdot \nabla^{2j+1} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j+1} \right) \right. \\ & \left. - (2k-1+2j) \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) \frac{y^T}{|y|} \right] d\mathcal{H}^{n-2}(\xi), \end{aligned} \quad (48)$$

$$\begin{aligned} \Delta J_{k,j}(y_1, 0, \dots, 0) &= \frac{1}{|y|^{2k+1}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left[c_0 \frac{\partial^{2j}}{\partial \xi_1'^{2j}} \frac{1}{Q}(\xi') + c_\Delta \frac{\partial^{2j-2}}{\partial \xi_1'^{2j-2}} \frac{1}{Q}(\xi') + \frac{\partial^{2j+2}}{\partial \xi_1'^{2j+2}} \frac{1}{Q}(\xi') \right] d\mathcal{H}^{n-2}(\xi'), \end{aligned} \quad (49)$$

where

$$c_0(n, m, k, j) = 2k(2k-1) + (n-1)(1-2k-2j) + 2(4j+1)(m+j) \quad (50)$$

and

$$c_\Delta(n, m, j) = 4j(2j-1)(m+j-1)(2m+2j+1-n). \quad (51)$$

Therefore, we obtain

$$\Delta J_{k,j}(y) = c_\Delta(n, m, j) J_{k+1,j-1} + c_0(n, m, k, j) J_{k+1,j} + J_{k+1,j+1}. \quad (52)$$

Proof In order to simplify the notation, as k, j are fixed, we write $J(y)$ instead of $J_{k,j}(y)$.

Step 1 Let $y = (y_1, 0, \dots, 0)$, $y_1 > 0$. First of all, writing J in polar coordinates

$$J(r, \eta) = \frac{1}{r^{2k-1}} \int_{\substack{|\xi|=1 \\ \eta \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\eta^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi),$$

by (37) one infers

$$\frac{\partial}{\partial y_1} J(y_1, 0, \dots, 0) = -\frac{2k-1}{|y|^{2k}} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi),$$

and

$$\frac{\partial^2}{\partial y_1^2} J(y_1, 0, \dots, 0) = \frac{2k(2k-1)}{|y|^{2k+1}} \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi). \quad (53)$$

As in the proof of Proposition 4.1, defining $H(\varphi) := J(B_\varphi y)$ with B_φ as in (39), we have

$$\begin{aligned} H(\varphi) &= \frac{1}{|y|^{2k-1}} \int_{\substack{|\xi|=1 \\ (B_\varphi y) \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{B_\varphi y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi) \\ &\stackrel{\xi = B_\varphi \xi'}{=} \frac{1}{|y|^{2k-1}} \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \nabla^{2j} \frac{1}{Q}(B_\varphi \xi') \left(\frac{B_\varphi y}{|y|}^{\otimes 2j} \right) d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

We may rewrite the argument as

$$\nabla^{2j} \frac{1}{Q}(B_\varphi \xi') \left(\frac{B_\varphi y}{|y|}^{\otimes 2j} \right) = \sum_{h=0}^{2j} \binom{2j}{h} \partial_{1^{2j-h} 3^h}^{2j} \frac{1}{Q}(B_\varphi \xi') \cos^{2j-h} \varphi \sin^h \varphi,$$

with the shorter notation

$$\partial_{i^k}^k := \frac{\partial^k}{\partial x_i^k}.$$

A differentiation with respect to φ yields

$$\begin{aligned} \frac{\partial H}{\partial \varphi} \Big|_{\varphi=0} &= \frac{1}{|y|^{2k-1}} \int_{\substack{|\xi'|=1 \\ \xi'_1 = 0}} \sum_{h=0}^{2j} \binom{2j}{h} \left\{ \frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j-h} 3^h}^{2j} \frac{1}{Q}(B_\varphi \xi') \right) \left(\cos^{2j-h} \varphi \Big|_{\varphi=0} \right) \left(\sin^h \varphi \Big|_{\varphi=0} \right) \right. \\ &\quad + \partial_{1^{2j-h} 3^h}^{2j} \frac{1}{Q}(\xi') \left[\left(\sin^h \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \cos^{2j-h} \varphi \right) \right. \\ &\quad \left. \left. + \left(\cos^{2j-h} \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \sin^h \varphi \right) \right] \right\} d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

Since the terms which remain must have only cosines, everything vanishes except for the term with $h = 0$ in the first sum and the one with $h = 1$ in the third. Therefore,

$$\frac{\partial H}{\partial \varphi} \Big|_{\varphi=0} = \frac{1}{|y|^{2k-1}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left\{ \frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} (B_\varphi \xi') \right) + 2j \partial_{1^{2j-1}3}^{2j} \frac{1}{Q} (\xi') \right\} d\mathcal{H}^{n-2}(\xi'). \quad (54)$$

Moreover, we compute on $\{\xi'_1 = 0\}$

$$\begin{aligned} \frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} (B_\varphi \xi') \right) &= \sum_{h=1}^n \partial_{1^{2j}h}^{2j+1} \frac{1}{Q} (\xi') \frac{\partial (B_\varphi \xi')_h}{\partial \varphi} \Big|_{\varphi=0} \\ &= \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (\xi') (-\sin \varphi \xi'_1 - \cos \varphi \xi'_3) \Big|_{\varphi=0} + \partial_{1^{2j}3}^{2j+1} \frac{1}{Q} (\xi') (\cos \varphi \xi'_1 - \sin \varphi \xi'_3) \Big|_{\varphi=0} \quad (55) \\ &= -\xi'_3 \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (\xi'). \end{aligned}$$

Inserting in (54), we infer

$$\begin{aligned} \frac{\partial J}{\partial y_3} \Big|_{(y_1, 0, \dots, 0)} &= \frac{1}{|y|} \frac{\partial H}{\partial \varphi} \Big|_{\varphi=0} \\ &= \frac{1}{|y|^{2k}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left(-\xi'_3 \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (\xi') + 2j \partial_{1^{2j-1}3}^{2j} \frac{1}{Q} (\xi') \right) d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

Of course, an analogous formula holds for any $h \in \{2, \dots, n\}$, namely

$$\frac{\partial J}{\partial y_h} \Big|_{(y_1, 0, \dots, 0)} = \frac{1}{|y|^{2k}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left(-\xi'_h \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (\xi') + 2j \partial_{1^{2j-1}h}^{2j} \frac{1}{Q} (\xi') \right) d\mathcal{H}^{n-2}(\xi').$$

Step 2 Let us now consider $y \in \mathbb{R}^n \setminus \{0\}$, so $y = |y|b_1$, where $|b_1| = 1$, and let $B = (b_1 \mid \dots \mid b_n) \in SO(n)$. Defining $\tilde{J} := J \circ B$, one has

$$\begin{aligned} \nabla J(y) &= \nabla J(B(|y|, 0, \dots, 0)^T) = \nabla \tilde{J}(|y|, 0, \dots, 0) B^T \\ &= \frac{1}{|y|^{2k}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left(\begin{array}{c} -(2k-1) \partial_{1^{2j}}^{2j} \frac{1}{Q} (B\xi') \\ 2j \partial_{1^{2j-1}2}^{2j} \frac{1}{Q} (B\xi') - \xi'_2 \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (B\xi') \\ \dots \\ 2j \partial_{1^{2j-1}n}^{2j} \frac{1}{Q} (B\xi') - \xi'_n \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (B\xi') \end{array} \right)^T d\mathcal{H}^{n-2}(\xi') \cdot B^T \\ &= \frac{1}{|y|^{2k}} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} 2j \nabla \left(\partial_{1^{2j-1}}^{2j-1} \frac{1}{Q} (B\xi') \right) \cdot B^T - (B\xi')^T \cdot \partial_{1^{2j+1}}^{2j+1} \frac{1}{Q} (B\xi') \end{aligned}$$

$$-(2k-1+2j) \begin{pmatrix} \partial_{1^{2j}}^2 \frac{1}{Q}(B\xi') \\ 0 \\ \vdots \\ 0 \end{pmatrix}^T B^T d\mathcal{H}^{n-2}(\xi').$$

Returning therefore to the variable $\xi = B\xi'$, we get

$$\begin{aligned} \nabla J(y) &= \frac{1}{|y|^{2k}} \left[2j \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j-1}, \cdot \right) d\mathcal{H}^{n-2}(\xi) \right. \\ &\quad - \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j+1} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j+1} \right) \xi^T d\mathcal{H}^{n-2}(\xi) \\ &\quad \left. - (2k-1+2j) \int_{\substack{|\xi|=1 \\ y \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{y}{|y|}^{\otimes 2j} \right) \frac{y^T}{|y|} d\mathcal{H}^{n-2}(\xi) \right], \end{aligned} \quad (56)$$

that is, (48).

Step 3 Let us again consider $y = (y_1, 0, \dots, 0)$, $y_1 > 0$, and compute $\Delta J(y)$. Defining $\tilde{H}(\varphi) := \partial_{y_3} J(B_\varphi y)$, according to the splitting in (56), we have

$$\tilde{H}(\varphi) =: \frac{1}{|y|^{2k}} (2j \tilde{H}_0(\varphi) - \tilde{H}_1(\varphi) - (2k-1+2j) \tilde{H}_2(\varphi)). \quad (57)$$

Let us differentiate with respect to φ term by term. Firstly,

$$\begin{aligned} \tilde{H}_0(\varphi) &= \int_{\substack{|\xi|=1 \\ (B_\varphi y) \cdot \xi = 0}} \nabla^{2j} \frac{1}{Q}(\xi) \left(\frac{B_\varphi y}{|y|}^{\otimes 2j-1}, e_3 \right) d\mathcal{H}^{n-2}(\xi) \\ &\stackrel{\xi=B_\varphi \xi'}{=} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \nabla^{2j} \frac{1}{Q}(B_\varphi \xi) \left(\begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \vdots \\ 0 \end{pmatrix}^{\otimes 2j-1}, e_3 \right) d\mathcal{H}^{n-2}(\xi') \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h_1, \dots, h_{2j-1}=1}^n \left(\nabla^{2j} \frac{1}{Q}(B_\varphi \xi) \right)_{3, h_1, \dots, h_{2j-1}} \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{h_1} \cdots \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{h_{2j-1}} d\mathcal{H}^{n-2}(\xi') \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h=0}^{2j-1} \binom{2j-1}{h} \partial_{1^{2j-1-h} 3^{h+1}}^{2j} \frac{1}{Q}(B_\varphi \xi') \cos^{2j-1-h} \varphi \sin^h \varphi d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

Therefore we obtain

$$\begin{aligned} \frac{d}{d\varphi} \Big|_{\varphi=0} \tilde{H}_0(\varphi) &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h=0}^{2j-1} \binom{2j-1}{h} \left\{ \frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j-1-h} 3^{h+1}}^{2j} \frac{1}{Q} (B_\varphi \xi') \right) \left(\cos^{2j-1-h} \varphi \Big|_{\varphi=0} \right) \left(\sin^h \varphi \Big|_{\varphi=0} \right) \right. \\ &\quad + \partial_{1^{2j-1-h} 3^{h+1}}^{2j} \frac{1}{Q} (\xi') \left[\left(\sin^h \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \cos^{2j-1-h} \varphi \right) \right. \\ &\quad \left. \left. + \left(\cos^{2j-1-h} \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \sin^h \varphi \right) \right] \right\} d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

As in Step 1, the terms which remain are the first with $h = 0$ and the third with $h = 1$, so

$$\frac{d}{d\varphi} \Big|_{\varphi=0} \tilde{H}_0(\varphi) = \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left[\frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j-1} 3}^{2j} \frac{1}{Q} (B_\varphi \xi') \right) + (2j-1) \partial_{1^{2j-2} 3^2}^{2j} \frac{1}{Q} (\xi') \right] d\mathcal{H}^{n-2}(\xi').$$

Differentiating the first term as in (55) on $\{\xi'_1 = 0\}$,

$$\frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j-1} 3}^{2j} \frac{1}{Q} (B_\varphi \xi') \right) = \sum_{h=1}^n \partial_{1^{2j-1} 3^h}^{2j+1} \frac{1}{Q} (\xi') \left(\frac{\partial (B_\varphi \xi')_h}{\partial \varphi} \right) \Big|_{\varphi=0} = -\xi'_3 \partial_{1^{2j} 3}^{2j+1} \frac{1}{Q} (\xi'),$$

we obtain hence

$$\frac{d}{d\varphi} \Big|_{\varphi=0} \tilde{H}_0(\varphi) = \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left[(2j-1) \partial_{1^{2j-2} 3^2}^{2j} \frac{1}{Q} (\xi') - \xi'_3 \partial_{1^{2j} 3}^{2j+1} \frac{1}{Q} (\xi') \right] d\mathcal{H}^{n-2}(\xi'). \quad (58)$$

Let us now address to the second term in (57):

$$\begin{aligned} \tilde{H}_1(\varphi) &= \int_{\substack{|\xi|=1 \\ (B_\varphi y) \xi = 0}} \xi_3 \nabla^{2j+1} \frac{1}{Q} (\xi) \left(\frac{B_\varphi y^{\otimes 2j+1}}{|y|} \right) d\mathcal{H}^{n-2}(\xi) \\ &\stackrel{\xi=B_\varphi \xi'}{=} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} (B_\varphi \xi')_3 \nabla^{2j+1} \frac{1}{Q} (B_\varphi \xi') \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix}^{\otimes 2j+1} d\mathcal{H}^{n-2}(\xi') \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} (\xi'_1 \sin \varphi + \xi'_3 \cos \varphi) \sum_{h_1, \dots, h_{2j+1}=1}^n \partial_{h_1 \dots h_{2j+1}}^{2j+1} \frac{1}{Q} (B_\varphi \xi') \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix}_{h_1} \dots \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix}_{h_{2j+1}} d\mathcal{H}^{n-2}(\xi') \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} (\xi'_1 \sin \varphi + \xi'_3 \cos \varphi) \left(\sum_{h=0}^{2j+1} \binom{2j+1}{h} \partial_{1^{2j+1-h} 3^h}^{2j+1} \frac{1}{Q} (B_\varphi \xi') \cos^{2j+1-h} \varphi \sin^h \varphi \right) d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

Hence, differentiating with respect to φ , with similar computations as for $\tilde{H}_0$, we obtain:

$$\begin{aligned}
 \frac{d}{d\varphi} \Big|_{\varphi=0} \tilde{H}_1(\varphi) &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} (\xi'_1 \cos \varphi - \xi'_3 \sin \varphi) \Big|_{\varphi=0} \left(\sum_{h=0}^{2j+1} \binom{2j+1}{h} \partial_{1^{2j+1-h} 3^h} \frac{1}{Q} (B_\varphi \xi') \cos^{2j+1-h} \varphi \sin^h \varphi \right) \Big|_{\varphi=0} \\
 &+ \xi'_3 \sum_{h=0}^{2j+1} \binom{2j+1}{h} \frac{d}{d\varphi} \Big|_{\varphi=0} \left(\partial_{1^{2j+1-h} 3^h} \frac{1}{Q} (B_\varphi \xi') \right) \left(\cos^{2j+1-h} \varphi \Big|_{\varphi=0} \right) \left(\sin^h \varphi \Big|_{\varphi=0} \right) \\
 &+ \xi'_3 \sum_{h=0}^{2j+1} \binom{2j+1}{h} \partial_{1^{2j+1-h} 3^h} \frac{1}{Q} (\xi') \left[\left(\sin^h \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \cos^{2j+1-h} \varphi \right) \right. \\
 &\quad \left. + \left(\cos^{2j+1-h} \varphi \Big|_{\varphi=0} \right) \left(\frac{d}{d\varphi} \Big|_{\varphi=0} \sin^h \varphi \right) \right] \\
 &= 0 + \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \xi'_3 \left[\frac{d}{d\varphi} \Big|_{\varphi=0} \partial_{1^{2j+1}} \frac{1}{Q} (B_\varphi \xi') + (2j+1) \partial_{1^{2j+1}} \frac{1}{Q} (\xi') \right] d\mathcal{H}^{n-2}(\xi').
 \end{aligned}$$

With similar computations as in (55), we infer

$$\frac{d}{d\varphi} \Big|_{\varphi=0} \tilde{H}_1(\varphi) = \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \left[(2j+1) \xi'_3 \partial_{1^{2j+1}} \frac{1}{Q} (\xi') - (\xi'_3)^2 \partial_{1^{2j+2}} \frac{1}{Q} (\xi') \right] d\mathcal{H}^{n-2}(\xi'). \quad (59)$$

Finally, we have to consider the third term in (57):

$$\begin{aligned}
 \tilde{H}_2(\varphi) &= \int_{\substack{|\xi|=1 \\ (B_\varphi y) \xi=0}} \nabla^{2j} \frac{1}{Q} (\xi) \left(\frac{B_\varphi y}{|y|} \right)^{\otimes 2j} \left(\frac{B_\varphi y}{|y|} \right)_3 d\mathcal{H}^{n-2}(\xi) \\
 &\stackrel{\xi=B_\varphi \xi'}{=} \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h_1, \dots, h_{2j}=1}^n \partial_{h_1 \dots h_{2j}}^{2j} \frac{1}{Q} (B_\varphi \xi') \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix}_{h_1} \cdots \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix}_{h_{2j}} \sin \varphi d\mathcal{H}^{n-2}(\xi') \\
 &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h=0}^{2j} \binom{2j}{h} \partial_{1^{2j-h} 3^h} \frac{1}{Q} (B_\varphi \xi') \cos^{2j-h} \varphi \sin^{h+1} \varphi d\mathcal{H}^{n-2}(\xi').
 \end{aligned}$$

Hence,

$$\begin{aligned} & \left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}_2(\varphi) \\ &= \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \sum_{h=0}^{2j} \binom{2j}{h} \left[\left. \frac{d}{d\varphi} \right|_{\varphi=0} \left(\partial_{1^{2j-h} 3^h} \frac{1}{Q} (B_\varphi \xi') \right) \left(\cos^{2j-h} \varphi \Big|_{\varphi=0} \right) \left(\sin^{h+1} \varphi \Big|_{\varphi=0} \right) \right. \\ & \quad + \partial_{1^{2j-h} 3^h} \frac{1}{Q} (\xi') \left(\left(\sin^{h+1} \varphi \Big|_{\varphi=0} \right) \left(\left. \frac{d}{d\varphi} \right|_{\varphi=0} \cos^{2j-h} \varphi \right) \right. \\ & \quad \left. \left. + \left(\cos^{2j-h} \varphi \Big|_{\varphi=0} \right) \left(\left. \frac{d}{d\varphi} \right|_{\varphi=0} \sin^{h+1} \varphi \right) \right) \right] d\mathcal{H}^{n-2}(\xi'). \end{aligned}$$

The first two terms vanish for any choice of h , while the last one remains only for $h = 0$, so

$$\left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}_2(\varphi) = \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{1^{2j}} \frac{1}{Q} (\xi') d\mathcal{H}^{n-2}(\xi'). \quad (60)$$

Hence, recalling the splitting (57), by (58)–(60) we obtain (omitting from now on in each integral its differential $d\mathcal{H}^{n-2}(\xi')$):

$$\begin{aligned} & \left. \frac{\partial^2 J}{\partial y_3^2} \right|_{(y_1, 0, \dots, 0)} = \frac{1}{|y|} \left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}(\varphi) \\ &= \frac{1}{|y|^{2k+1}} \left[2j \left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}_0(\varphi) - \left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}_1(\varphi) - (2k-1+2j) \left. \frac{d}{d\varphi} \right|_{\varphi=0} \tilde{H}_2(\varphi) \right] \\ &= \frac{1}{|y|^{2k+1}} \left[-(2k-1+2j) \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{1^{2j}} \frac{1}{Q} (\xi') + 2j(2j-1) \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{1^{2j-2} 3^2} \frac{1}{Q} (\xi') \right. \\ & \quad \left. - (4j+1) \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \xi'_3 \partial_{1^{2j} 3} \frac{1}{Q} (\xi') + \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} (\xi'_3)^2 \partial_{1^{2j+2}} \frac{1}{Q} (\xi') \right]. \end{aligned}$$

Therefore, the same being valid for any variable y_h with $h \in \{2, \dots, n\}$, and recalling (53) if $h = 1$, we may compute the Laplacian of J :

$$\begin{aligned}
\Delta J \Big|_{(y_1, 0, \dots, 0)} &= \frac{\partial^2 J}{\partial y_1^2} \Big|_{(y_1, 0, \dots, 0)} + \sum_{h=2}^n \frac{\partial^2 J}{\partial y_h^2} \Big|_{(y_1, 0, \dots, 0)} \\
&= \frac{1}{|y|^{2k+1}} \left\{ 2k(2k-1) \int_{|\xi'|=1} \int_{\xi'_1=0} \partial_{1^{2j}}^{2j} \frac{1}{Q}(\xi') + (n-1)(1-2k-2j) \int_{|\xi'|=1} \int_{\xi'_1=0} \partial_{1^{2j}}^{2j} \frac{1}{Q}(\xi') \right. \\
&\quad + 2j(2j-1) \int_{|\xi'|=1} \sum_{\xi'_1=0}^n \partial_{1^{2j-2}h^2}^{2j} \frac{1}{Q}(\xi') - (4j+1) \int_{|\xi'|=1} \sum_{\xi'_1=0}^n \xi'_h \partial_h \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} \right)(\xi') \\
&\quad \left. + \int_{|\xi'|=1} \left(\sum_{\xi'_1=0}^n \underbrace{(\xi'_h)^2}_{|\xi'|^2=1} \right) \partial_{1^{2j+2}}^{2j+2} \frac{1}{Q}(\xi') \right\} \quad (61) \\
&= \frac{1}{|y|^{2k+1}} \left\{ [2k(2k-1) + (n-1)(1-2k-2j)] \int_{|\xi'|=1} \int_{\xi'_1=0} \partial_{1^{2j}}^{2j} \frac{1}{Q}(\xi') \right. \\
&\quad + 2j(2j-1) \int_{|\xi'|=1} \Delta' \left(\partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} \right)(\xi') - (4j+1) \int_{|\xi'|=1} \partial_v \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} \right)(\xi') \\
&\quad \left. + \int_{|\xi'|=1} \partial_{1^{2j+2}}^{2j+2} \frac{1}{Q}(\xi') \right\}.
\end{aligned}$$

Here, we denote

$$\Delta' = \partial_{22}^2 + \dots + \partial_{nn}^2.$$

By homogeneity of the symbol, one has (see Lemma 4.5 below)

$$\partial_v \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} \right) = -2(m+j) \left(\partial_{1^{2j}}^{2j} \frac{1}{Q} \right). \quad (62)$$

Moreover, in order to handle the term $\Delta \partial_{1^{2j-2}}^{2j-2} \frac{1}{Q}$, we may apply the following well-known identity

$$\Delta' u = \Delta_S u + H_S \partial_v u + \partial_{vv}^2 u \quad (63)$$

with $u = \partial_{1^{2j-2}}^{2j-2} \frac{1}{Q}$ and $S := \{|\xi'| = 1, \xi'_1 = 0\}$ the manifold on which we are integrating, and where H_S stands for the mean curvature of S , so we have $H_S = (n-2)$. Noticing that the normal derivatives in (63) may be handled as in (62), it remains the

term with the tangential part of the Laplacian. However, it vanishes when integrated on S . Hence,

$$\begin{aligned}
 \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \Delta' \left(\partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} \right) (\xi') &= (n-2) \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_v \left(\partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} \right) + \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{vv}^2 \left(\partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} \right) \\
 &\stackrel{(62)}{=} [(n-2)(-2(m+j-1)) + 2(m+j-1)(2m+2j-1)] \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} (\xi') \\
 &= 2(m+j-1)(2m+2j+1-n) \int_{\substack{|\xi'|=1 \\ \xi'_1=0}} \partial_{1^{2j-2}}^{2j-2} \frac{1}{Q} (\xi')
 \end{aligned} \tag{64}$$

Inserting (62) and (64) in (61) and summing the constants, we finally end up with (49) and thus with our formula (52). $\square$

Lemma 4.5 *Let $Q(\cdot)$ be positive and p -homogeneous. Then, one has for any multi-index $\alpha \in \mathbb{N}_0^n$ and any $x \in \mathbb{R}^n \setminus \{0\}$:*

$$x \cdot \nabla \left(D^\alpha \frac{1}{Q} \right) (x) = -(p + |\alpha|) \left(D^\alpha \frac{1}{Q} \right) (x).$$

Proof By assumption we have for $r > 0$ that

$$\frac{1}{Q}(rx) = r^{-p} \frac{1}{Q}(x).$$

Differentiation with respect to x yields:

$$r^{|\alpha|} \left(D^\alpha \frac{1}{Q} \right) (rx) = r^{-p} \left(D^\alpha \frac{1}{Q} \right) (x) \Rightarrow \left(D^\alpha \frac{1}{Q} \right) (rx) = r^{-p-|\alpha|} \left(D^\alpha \frac{1}{Q} \right) (x).$$

Differentiating now with respect to r gives:

$$x \cdot \nabla \left(D^\alpha \frac{1}{Q} \right) (rx) = (-p - |\alpha|) r^{-p-|\alpha|-1} \left(D^\alpha \frac{1}{Q} \right) (x).$$

The claim follows by putting $r = 1$. $\square$

Proof of Theorem 4.3 Notice that for $k = 1$, ΔF is already in the form (45) by Proposition 4.1. We thus proceed by induction and let us suppose that $\Delta^k F$ has the form (45) for some $k \in \mathbb{N}$, $k > 1$, with coefficients as in (46)–(47), namely

$$\Delta^k F = \sum_{j=1}^k d_{k,j}(n, m) J_{k,k-j}.$$

Applying the recursive formula (52), we thus have

$$\Delta^{k+1} F = \sum_{j=1}^{k+1} d_{k+1,j}(n, m) J_{k+1, k+1-j}$$

with

$$\begin{aligned} d_{k+1,j}(n, m) &= d_{k,j}(n, m) + d_{k,j-1}(n, m) c_0(n, m, k, k-j+1) \\ &\quad + d_{k,j-2}(n, m) c_{\Delta}(n, m, k-j+2), \end{aligned}$$

for $j = 3, \dots, k+1$. We have $d_{k,k+1}$ according to (47) and put $d_{k,0} := d_{k,-1} := 0$. Hence, for $j = 1$ and $j = 2$ we have the recurrence relations

$$\begin{aligned} d_{k+1,2} &= d_{k,2} + d_{k,1} c_0(n, m, k, k-1), \\ d_{k+1,1} &= d_{k,1}, \end{aligned}$$

and for those the formulae (46) and (47) are easily checked.

We show the shape of $d_{k+1,j}(n, m)$ for $j = 3, \dots, k+1$, the cases $j = 1, 2$ being analogous but simpler. In order to prove that $d_{k+1,j}(n, m)$ has the shape as in (45) with $k+1$, which will prove Theorem 4.3, we show that the following term is equal to 0:

$$\begin{aligned} & d_{k,j}(n, m) + d_{k,j-1}(n, m) c_0(n, m, k, k-j+1) + d_{k,j-2}(n, m) c_{\Delta}(n, m, k-j+2) \\ & - (-1)^{j-1} c_{k+1,j} \prod_{\ell=2}^j (n-2m-2k+2\ell-5) \\ & = (-1)^{j-1} \prod_{\ell=2}^{j-2} (n-2m-2k+2\ell-3) \\ & \quad \cdot \left\{ c_{k,j}(n-2m-2k+2j-5)(n-2m-2k+2j-3) \right. \\ & \quad - c_{k,j-1}(n-2m-2k+2j-5) \\ & \quad \cdot \left(2k(2k-1) + (n-1)(2j-4k-1) + 2(4k-4j+5)(m+k+1-j) \right) \\ & \quad + 4c_{k,j-2}(k+2-j)(2k+3-2j)(m+k+1-j)(-n+2m+2k-2j+5) \\ & \quad \left. - c_{k+1,j}(n-2m-2k-1)(n-2m-2k+2j-5) \right\} \\ & = (-1)^{j-1} \prod_{\ell=2}^{j-1} (n-2m-2k+2\ell-3) \\ & \quad \cdot \left\{ c_{k,j}(n-2m-2k+2j-3) \right. \\ & \quad - c_{k,j-1} \cdot \left(2k(2k-1) + (n-1)(2j-4k-1) + 2(4k-4j+5)(m+k+1-j) \right) \\ & \quad \left. - 4c_{k,j-2}(k+2-j)(2k+3-2j)(m+k+1-j) \right\} \end{aligned}$$

$$\begin{aligned}
& -c_{k+1,j}(n-2m-2k-1) \Big\} \\
& = (-1)^{j-1} \left(\prod_{\ell=2}^{j-1} (n-2m-2k+2\ell-3) \right) \left(\prod_{\ell=2}^j \frac{1}{\ell-1} \right) \left(\prod_{\ell=2}^{j-2} (k-\ell+1)(2k-2\ell+1) \right) \\
& \quad \cdot \left\{ (k-j+2)(2k-2j+3)(k-j+1)(2k-2j+1)(n-2m-2k+2j-3) \right. \\
& \quad - (j-1)(k-j+2)(2k-2j+3) \\
& \quad \cdot (2k(2k-1) + (n-1)(2j-4k-1) + 2(4k-4j+5)(m+k+1-j)) \\
& \quad - 4(j-1)(j-2)(k+2-j)(2k+3-2j)(m+k+1-j) \\
& \quad \left. - k(2k-1)(k-j+2)(2k-2j+3)(n-2m-2k-1) \right\} \\
& = (-1)^{j-1} \left(\prod_{\ell=2}^{j-1} (n-2m-2k+2\ell-3) \right) \left(\prod_{\ell=2}^j \frac{1}{\ell-1} \right) \left(\prod_{\ell=2}^{j-1} (k-\ell+1)(2k-2\ell+1) \right) \\
& \quad \cdot \left\{ (k-j+1)(2k-2j+1)(n-2m-2k+2j-3) \right. \\
& \quad - (j-1) \cdot (2k(2k-1) + (n-1)(2j-4k-1) + 2(4k-4j+5)(m+k+1-j)) \\
& \quad \left. - 4(j-1)(j-2)(m+k+1-j) - k(2k-1)(n-2m-2k-1) \right\} \\
& = (-1)^{j-1} \left(\prod_{\ell=2}^{j-1} (n-2m-2k+2\ell-3) \right) \left(\prod_{\ell=2}^j \frac{1}{\ell-1} \right) \left(\prod_{\ell=2}^{j-1} (k-\ell+1)(2k-2\ell+1) \right) \\
& \quad \cdot \left\{ (k-j+1)(2k-2j+1)(n-2m-2k+2j-3) \right. \\
& \quad - k(2k-1)(n-2m-2k+2j-3) - (n-1)(2j-4k-1)(j-1) \\
& \quad \left. - 2(j-1)(m+k-j+1)(4k-2j+1) \right\} \\
& = (-1)^{j-1} \left(\prod_{\ell=2}^j (n-2m-2k+2\ell-3) \right) \left(\prod_{\ell=2}^j \frac{1}{\ell-1} \right) \left(\prod_{\ell=2}^{j-1} (k-\ell+1)(2k-2\ell+1) \right) \\
& \quad \cdot \left\{ (k-j+1)(2k-2j+1) - k(2k-1) + (j-1)(4k-2j+1) \right\} = 0.
\end{aligned}$$

This concludes the proof of Theorem 4.3. $\square$

4.2 The even dimension $n = 2m + 2$: explicit fundamental solutions

Here we provide the proof of Theorem 1.3. The starting point is John's formula (5), according to which we have

$$K_L(0, y) = -\frac{1}{(2\pi)^n} (-\Delta_y)^{(n-2m)/2} \int_{|\xi|=1} \frac{\log |y \cdot \xi|}{Q(\xi)} d\mathcal{H}^{n-1}(\xi)$$

$$= -\frac{2}{(2\pi)^n} (-\Delta_y)^{(n-2m)/2} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log(y \cdot \xi)}{Q(\xi)} d\mathcal{H}^{n-1}(\xi). \quad (65)$$

For $n = 2m$ we immediately see that the fundamental solution of L satisfies

$$K_L(0, y) \rightarrow +\infty \text{ as } y \rightarrow 0,$$

which is similar to the case $n = 2m + 1$ above.

Hence, in order to obtain an explicit expression for K_L , we thus have to compute the Laplacian of

$$G(y) := \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log(y \cdot \xi)}{Q(\xi)} d\mathcal{H}^{n-1}(\xi). \quad (66)$$

Due to the logarithmic term, the calculations for even dimensions cannot be simplified similarly to the previous section. An application of Stokes' theorem would change $\log(\xi_1)$ into $\frac{1}{\xi_1}$, a non-integrable singularity. For this reason we restrict ourselves to the case $n = 2m + 2$.

The strategy is similar to the one applied in the proofs of Propositions 4.1 and 4.4.

Step 1 Let $y = (y_1, 0, \dots, 0)$ with $y_1 > 0$. Splitting G as

$$\begin{aligned} G(y) &= \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log(y_1 \xi_1)}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \\ &= \log(y_1) \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log(\xi_1)}{Q(\xi)} d\mathcal{H}^{n-1}(\xi), \end{aligned}$$

we first infer

$$\frac{\partial G}{\partial y_1}(y) = \frac{1}{y_1} \int_{\substack{|\xi|=1 \\ \xi_1 > 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) = \frac{1}{2y_1} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \quad (67)$$

as $Q(\xi) = Q(-\xi)$ by homogeneity of the symbol. Moreover,

$$\frac{\partial^2 G}{\partial y_1^2}(y) = -\frac{1}{2y_1^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi). \quad (68)$$

In order to compute the other first derivatives of G , let us split it as

$$\begin{aligned} G(y) &= \log |y| \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log\left(\frac{y}{|y|} \cdot \xi\right)}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \\ &=: \log |y| \tilde{G}_1(y) + \tilde{G}_2(y). \end{aligned}$$

Hence,

$$\frac{\partial G}{\partial y_3}(y) = \frac{y_3}{|y|^2} \tilde{G}_1(y) + \log |y| \frac{\partial \tilde{G}_1}{\partial y_3}(y) + \frac{\partial \tilde{G}_2}{\partial y_3}(y). \quad (69)$$

We use the matrix B_φ defined in (39) and define

$$\tilde{H}_1(\varphi) = \tilde{G}_1(B_\varphi y) \quad \text{and} \quad \tilde{H}_2(\varphi) = \tilde{G}_2(B_\varphi y).$$

Concerning the first term, exploiting $Q(\xi) = Q(-\xi)$, we find for any y

$$\tilde{G}_1(y) = \frac{1}{2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \quad \Rightarrow \quad \frac{\partial \tilde{G}_1}{\partial y_3}(y) = 0. \quad (70)$$

Concerning the second term, reasoning as in (40), we get

$$\begin{aligned} y_1 \frac{\partial \tilde{G}_2}{\partial y_3}(y) &= \frac{\partial \tilde{H}_2}{\partial \varphi}(\varphi) \Big|_{\varphi=0} = \frac{\partial}{\partial \varphi} \Big|_{\varphi=0} \int_{\substack{|\xi|=1 \\ \xi_1 > 0}} \frac{\log\left(\frac{y}{|y|} \cdot \xi\right)}{Q(B_\varphi \xi)} d\mathcal{H}^{n-1}(\xi) \\ &= \int_{\substack{|\xi|=1 \\ \xi_1 > 0}} \log(\xi_1) \left(-\xi_3 \partial_1 \frac{1}{Q}(\xi) + \xi_1 \partial_3 \frac{1}{Q}(\xi) \right) d\mathcal{H}^{n-1}(\xi). \end{aligned} \quad (71)$$

Therefore, by (69)–(71) we conclude

$$\begin{aligned} \frac{\partial G}{\partial y_3}(y) &= \frac{y_3}{|y|^2} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ \xi_1 > 0}} \log(\xi_1) \left(-\xi_3 \partial_1 \frac{1}{Q}(\xi) \right. \\ &\quad \left. + \xi_1 \partial_3 \frac{1}{Q}(\xi) \right) d\mathcal{H}^{n-1}(\xi) \end{aligned}$$

and, analogously, for any $k \in \{2, \dots, n\}$, one has

$$\begin{aligned} \frac{\partial G}{\partial y_k}(y_1, 0, \dots, 0) &= \frac{y_k}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \\ &\quad + \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ \xi_1 > 0}} \log\left(\xi \cdot \frac{y}{|y|}\right) \left(-\xi_k \left(\nabla \frac{1}{Q}(\xi) \cdot \frac{y}{|y|} \right) \right. \\ &\quad \left. + \left(\xi \cdot \frac{y}{|y|} \right) \partial_k \frac{1}{Q}(\xi) \right) d\mathcal{H}^{n-1}(\xi). \end{aligned}$$

Because this formula is consistent with (67), we can write it in a more compact way as

$$\begin{aligned}\nabla G(y) &= \frac{y^T}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \\ &\quad + \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \log\left(\xi \cdot \frac{y}{|y|}\right) \left(-\xi^T \left(\nabla \frac{1}{Q}(\xi) \cdot \frac{y}{|y|}\right) \right. \\ &\quad \left. + \left(\xi \cdot \frac{y}{|y|}\right) \nabla \frac{1}{Q}(\xi)\right) d\mathcal{H}^{n-1}(\xi).\end{aligned}\quad (72)$$

Step 2 Let now $y \in \mathbb{R}^n \setminus \{0\}$ so that $y = |y|b_1$ with $|b_1| = 1$, and let $B = (b_1 | \dots | b_n) \in SO(n)$. Defining

$$\tilde{G}(y) := (G \circ B)(y) = \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \frac{\log(y \cdot \xi)}{Q(B(\xi))} d\mathcal{H}^{n-1}(\xi),$$

we have

$$\nabla G(y) = \nabla G(|y|, 0, \dots, 0)^T = \nabla \tilde{G}(|y|, 0, \dots, 0)^T B^T.$$

Therefore,

$$\begin{aligned}\nabla \tilde{G}(|y|, 0, \dots, 0)^T &= \frac{1}{2|y|} e_1^T \int_{|\xi|=1} \frac{1}{Q(B(\xi))} d\mathcal{H}^{n-1}(\xi) \\ &\quad + \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \log(\xi_1) \left(-\xi^T \left(\nabla \frac{1}{Q}(B(\xi)) \cdot B e_1\right) + \xi_1 \nabla \frac{1}{Q}(B(\xi)) \cdot B\right) d\mathcal{H}^{n-1}(\xi) \\ &= \frac{1}{2|y|} e_1^T \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) \\ &\quad + \frac{1}{|y|} \int_{\substack{|\xi|=1 \\ (B^T \xi)_1 > 0}} \log((B^T \xi)_1) \left(-\xi^T B \left(\nabla \frac{1}{Q}(\xi) \cdot \frac{y}{|y|}\right) + (B^T \xi)_1 \nabla \frac{1}{Q}(\xi) \cdot B\right) d\mathcal{H}^{n-1}(\xi).\end{aligned}$$

Observing that $(B^T \xi)_1 = \frac{y \cdot \xi}{|y|}$ and multiplying by B^T shows that (72) holds also for any $y \in \mathbb{R}^n \setminus \{0\}$.

Step 3 We consider again $y = (y_1, 0, \dots, 0)$ with $y_1 > 0$ and compute $\Delta G(y)$. Similarly as in Step 1, we get

$$\begin{aligned}\partial_3^2 G(y_1, 0, \dots, 0) &= \frac{1}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \frac{1}{|y|} \frac{\partial}{\partial \varphi} \bigg|_{\varphi=0} \frac{1}{|B_\varphi y|} \int_{\substack{|\xi|=1 \\ B_\varphi y \cdot \xi > 0}} \log\left(\frac{B_\varphi y \cdot \xi}{|B_\varphi y|}\right) \\ &\quad \cdot \left(-\xi_3 \left(\nabla \frac{1}{Q}(\xi) \cdot \frac{B_\varphi y}{|B_\varphi y|}\right) + \left(\frac{\xi \cdot B_\varphi y}{|B_\varphi y|} \partial_3 \frac{1}{Q}(\xi)\right)\right) d\mathcal{H}^{n-1}(\xi).\end{aligned}$$

A change of variables and (39) imply

$$\begin{aligned} \partial_3^2 G(y_1, 0, \dots, 0) - \frac{1}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) &= \frac{1}{y_1} \frac{1}{|y|} \frac{\partial}{\partial \varphi} \Big|_{\varphi=0} \int_{\xi_1>0}^{\xi_1=1} \log(\xi_1) \\ &\cdot \left(-(\xi_1 \sin \varphi + \xi_3 \cos \varphi) \nabla \frac{1}{Q(B_\varphi \xi)} \cdot \begin{pmatrix} \cos \varphi \\ 0 \\ \sin \varphi \\ 0 \\ \dots \\ 0 \end{pmatrix} + \xi_1 \partial_3 \frac{1}{Q(B_\varphi \xi)} \right) d\mathcal{H}^{n-1}(\xi) \\ &= \frac{1}{y_1^2} \int_{\xi_1>0}^{\xi_1=1} \log(\xi_1) \left(-\xi_1 \partial_1 \frac{1}{Q} - \xi_3 \partial_3 \frac{1}{Q} + \xi_3^2 \partial_1^2 \frac{1}{Q} + \xi_1^2 \partial_3^2 \frac{1}{Q} - 2\xi_1 \xi_3 \partial_{13}^2 \frac{1}{Q} \right) d\mathcal{H}^{n-1}(\xi). \end{aligned}$$

As the same holds for any $k \in \{2, \dots, n\}$, we infer

$$\begin{aligned} \partial_3^2 G(y_1, 0, \dots, 0) &= \frac{1}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \frac{1}{|y|^2} \int_{\xi_1>0}^{\xi_1=1} \log \left(\xi \cdot \frac{y}{|y|} \right) \\ &\cdot \left(-\xi_1 \partial_1 \frac{1}{Q} - \xi_k \partial_k \frac{1}{Q} + \xi_k^2 \partial_1^2 \frac{1}{Q} + \xi_1^2 \partial_k^2 \frac{1}{Q} - 2\xi_1 \xi_k \partial_{1k}^2 \frac{1}{Q} \right) d\mathcal{H}^{n-1}(\xi). \end{aligned}$$

This together with (68) yields (omitting from now on the differentials)

$$\begin{aligned} \Delta G(y_1, 0, \dots, 0) &= \frac{n-2}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q} + \frac{1}{|y|^2} \int_{\xi_1>0}^{\xi_1=1} \log \left(\xi \cdot \frac{y}{|y|} \right) \left[-(n-1) \xi_1 \partial_1 \frac{1}{Q} \right. \\ &\quad \left. - \sum_{k=2}^n \xi_k \partial_k \frac{1}{Q} + \left(\sum_{k=2}^n \xi_k^2 \right) \partial_1^2 \frac{1}{Q} + \xi_1^2 \left(\sum_{k=2}^n \partial_k^2 \frac{1}{Q} \right) - 2\xi_1 \left(\sum_{k=2}^n \xi_k \partial_k \left(\partial_1 \frac{1}{Q} \right) \right) \right] \\ &= \frac{n-2}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q} + \frac{1}{|y|^2} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \log \left(\xi \cdot \frac{y}{|y|} \right) \left[-(n-2) \xi_1 \partial_1 \frac{1}{Q} - \xi \cdot \nabla \frac{1}{Q} \right. \\ &\quad \left. + \partial_1^2 \frac{1}{Q} + \xi_1^2 \Delta \frac{1}{Q} - 2\xi_1 \xi \cdot \nabla \left(\partial_1 \frac{1}{Q} \right) \right]. \end{aligned}$$

Step 4 Let now $y \in \mathbb{R}^n \setminus \{0\}$. Reasoning as in Step 2 and using the same notation as there we obtain

$$\begin{aligned} \Delta G(y) &= \Delta \tilde{G}(B^T y) = \Delta \tilde{G}((|y|, 0, \dots, 0)^T) = \frac{n-2}{2|y|^2} \int_{|\xi|=1} \frac{1}{Q} + \frac{1}{|y|^2} \int_{\xi_1>0}^{\xi_1=1} \log(\xi \cdot e_1) \\ &\cdot \left[-(n-2)(\xi \cdot e_1) \left(e_1 \cdot \left(\nabla \frac{1}{Q}(B\xi) \cdot B \right) - \xi \cdot \left(\nabla \frac{1}{Q}(B\xi) \cdot B \right) \right) \right. \\ &\quad \left. + e_1^T \cdot B^T D \nabla^2 \frac{1}{Q}(B\xi) B \cdot e_1 \right] \end{aligned}$$

$$+ (\xi \cdot e_1)^2 \Delta \frac{1}{Q} (B\xi) - 2(\xi \cdot e_1) \left(\xi^T \cdot B^T \nabla^2 \frac{1}{Q} (B\xi) B \cdot e_1 \right) \Big]. \quad (73)$$

Recalling that $B \cdot e_1 = \frac{y}{|y|}$, (73) implies

$$\begin{aligned} \Delta G(y) &= \frac{n-2}{2} \frac{1}{|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \frac{1}{|y|^2} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \log \left(\xi \cdot \frac{y}{|y|} \right) \\ &\quad \cdot \left[- (n-2) \left(\xi \cdot \frac{y}{|y|} \right) \left(\nabla \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} \right) - \xi \cdot \nabla \frac{1}{Q(\xi)} + \frac{y^T}{|y|} \cdot \nabla^2 \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} \right. \\ &\quad \left. + \left(\xi \cdot \frac{y}{|y|} \right)^2 \Delta \frac{1}{Q(\xi)} - 2 \left(\xi \cdot \frac{y}{|y|} \right) \left(\xi^T \cdot \nabla^2 \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} \right) \right] d\mathcal{H}^{n-1}(\xi). \end{aligned}$$

Finally, due to the $2m$ -homogeneity of Q by means of Lemma 4.5 we have

$$\begin{aligned} \forall \xi \in \mathbb{S}^{n-1} : \quad \xi \cdot \nabla \frac{1}{Q(\xi)} &= -2m \frac{1}{Q(\xi)}, \\ \xi^T \cdot \nabla^2 \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} &= -(2m+1) \left(\nabla \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} \right). \end{aligned}$$

Hence the previous formula simplifies to

$$\begin{aligned} \Delta G(y) &= \frac{n-2}{2} \frac{1}{|y|^2} \int_{|\xi|=1} \frac{1}{Q(\xi)} d\mathcal{H}^{n-1}(\xi) + \frac{1}{|y|^2} \int_{\substack{|\xi|=1 \\ y \cdot \xi > 0}} \log \left(\xi \cdot \frac{y}{|y|} \right) \\ &\quad \cdot \left((4m+4-n) \left(\xi \cdot \frac{y}{|y|} \right) \left(\nabla \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} \right) + 2m \frac{1}{Q(\xi)} \right. \\ &\quad \left. + \frac{y^T}{|y|} \cdot \nabla^2 \frac{1}{Q(\xi)} \cdot \frac{y}{|y|} + \left(\xi \cdot \frac{y}{|y|} \right)^2 \Delta \frac{1}{Q(\xi)} \right) d\mathcal{H}^{n-1}(\xi) \end{aligned} \quad (74)$$

and, recalling (2), the proof is concluded.

5 Further examples: sign change of suitable fundamental solutions for $n \geq 2m + 2$

Proposition 2.8 shows that in any space dimension $n \geq 2m + 2$ there exists an elliptic operator L of the form (1) in $\mathbb{R}^n$ with corresponding fundamental solution K_L , where one finds a vector $y \in \mathbb{R}^n \setminus \{0\}$ such that $K_L(0, y) < 0$, provided we are able to construct such an operator of order $2m$ in space dimension $n = 2m + 2$. Together with Theorem 2.3 this will show that K_L is sign changing near the origin, i.e. near its singularity. In view of Theorem 2.3 this will prove Theorem 1.1.

The starting point to obtain such a result is formula (5), according to which we have in dimension $n = 2m + 2$

$$K_L(0, y) = \frac{1}{(2\pi)^n} \Delta G(y),$$

where G is defined in (66) and $\Delta G(y)$ is calculated in (74).

We consider the symbol

$$Q_\alpha(\xi', \xi_n) = |\xi'|^{2m} - \alpha |\xi'|^{2m-2} \xi_n^2 + \xi_n^{2m},$$

which for $m = 2$ reduces to the symbol of the operator L as in (13). First, we find a threshold parameter $\alpha_m^* > 0$ so that Q_α is elliptic for $\alpha < \alpha_m^*$. Then, for such symbols we compute ΔG in a suitable point. Finally, exploiting the form of the “limiting” symbol $Q_{\alpha_m^*}$, we will find that for $\alpha < \alpha_m^*$ but close to it the sign of ΔG in such a point is negative. Notice that for such α the sublevels of Q_α are non-convex. Together with the observation that $\text{sgn}(K_L(0, y)) = \text{sgn}(\Delta G(y))$ for any $y \in \mathbb{R}^n$ —an immediate consequence of (65)—this proves the existence of operators of order $2m$ in $\mathbb{R}^{2m+2}$ whose fundamental solution attains negative values in some directions.

Lemma 5.1 Q_α is a symbol of an elliptic operator provided $\alpha < \alpha_m^* := m(m-1)^{\frac{1}{m}-1}$.

Proof Since ellipticity for $\alpha \leq 0$ is obvious, we consider only $\alpha > 0$. Notice that $Q_\alpha(\xi', 0) = |\xi'|^{2m} > 0$ and that $Q_\alpha(\xi', \xi_n) = Q_\alpha(\xi', |\xi_n|)$, so we may assume that $\xi_n > 0$.

Let us write $\xi_n = \sqrt{s}|\xi'|$ for $s > 0$, so that $Q_\alpha(\xi', \sqrt{s}|\xi'|) = |\xi'|^{2m} f(s)$, where $f(s) := s^m - \alpha s + 1$. Then $f'(s) > 0$ provided $s > \left(\frac{\alpha}{m}\right)^{\frac{1}{m-1}}$. This implies that Q_α is elliptic if and only if

$$f\left(\left(\frac{\alpha}{m}\right)^{\frac{1}{m-1}}\right) = \alpha^{\frac{m}{m-1}} \left(m^{-\frac{m}{m-1}} - m^{-\frac{1}{m-1}}\right) + 1 > 0,$$

namely for $\alpha < m(m-1)^{\frac{1}{m}-1} = \alpha_m^*$. □

Remark 3 Notice that, as a consequence of the proof of Lemma 5.1 the symbol $Q_{\alpha_m^*}$ is degenerate elliptic and that f vanishes of order 2 at $\left(\frac{\alpha_m^*}{m}\right)^{\frac{1}{m-1}} = (m-1)^{-\frac{1}{m}} =: \gamma_m$. Indeed, $f''(\gamma_m) > 0$.

In this section we need to consider $\alpha < \alpha_m^*$ but close to α_m^* . The sublevel sets of such Q_α are nonconvex. However, as pointed out in [3, p. 100] and Prop. 3.3 above one may also have sign changing fundamental solutions for $\alpha < 0$ in dimensions $n \geq 2m + 4$, where the sublevel sets of Q_α are convex. See Fig. 2.

(a) $m = 2, \alpha = -1$ (b) $m = 2, \alpha = 1$ **Fig. 2** The shape of sublevel sets of Q_α for $\alpha < 0$ (left) and $\alpha > 0$ (right)*Computation of $\Delta G_\alpha(e_n)$.*

By the peculiar form of Q_α we choose $y = e_n$ and we write G_α instead of G to stress the dependence on the parameter α . By (74), recalling that all integrals are on $S := \mathbb{S}^{n-1}$, so $\xi_n = \sqrt{1 - |\xi'|^2}$, we get

$$\begin{aligned} \Delta G_\alpha(e_n) &= \int_{|\xi'| < 1} \frac{2m}{Q_\alpha(\xi', \sqrt{1 - |\xi'|^2})} \frac{d\xi'}{\sqrt{1 - |\xi'|^2}} + \frac{1}{2} \int_{|\xi'| < 1} \frac{\log(1 - |\xi'|^2)}{\sqrt{1 - |\xi'|^2}} \\ &\quad \cdot \left((2m+2)\sqrt{1 - |\xi'|^2} \partial_n \frac{1}{Q_\alpha}(\xi', \sqrt{1 - |\xi'|^2}) + \frac{2m}{Q_\alpha(\xi', \sqrt{1 - |\xi'|^2})} \right. \\ &\quad \left. + (2 - |\xi'|^2) \partial_n^2 \frac{1}{Q_\alpha}(\xi', \sqrt{1 - |\xi'|^2}) + (1 - |\xi'|^2) \Delta' \frac{1}{Q_\alpha}(\xi', \sqrt{1 - |\xi'|^2}) \right) d\xi', \end{aligned} \quad (75)$$

where $\Delta' := \sum_{k=1}^{n-1} \partial_k^2$. Exploiting the form of Q_α and writing $Q_\alpha(\xi') := Q_\alpha(\xi', \sqrt{1 - |\xi'|^2})$, one has

$$\begin{aligned} \partial_n \frac{1}{Q_\alpha} \Big|_S &= - \frac{\partial_n Q_\alpha}{Q_\alpha^2} \Big|_S = - \frac{2m\xi_n^{2m-1} - 2\alpha\xi_n|\xi'|^{2m-2}}{Q_\alpha(\xi)^2} \Big|_S \\ &= \frac{-2m(1 - |\xi'|^2)^{\frac{2m-1}{2}} + 2\alpha|\xi'|^{2m-2}(1 - |\xi'|^2)^{1/2}}{Q_\alpha(\xi')^2}, \end{aligned} \quad (76)$$

$$\begin{aligned} \partial_n^2 \frac{1}{Q_\alpha} \Big|_S &= \left(- \frac{\partial_n^2 Q_\alpha}{Q_\alpha^2} + \frac{2(\partial_n Q_\alpha)^2}{Q_\alpha^3} \right) \Big|_S \\ &= \frac{-2m(2m-1)\xi_n^{2m-2} + 2\alpha|\xi'|^{2m-2}}{Q_\alpha(\xi)^2} \Big|_S + \frac{2(2m\xi_n^{2m-1} - 2\alpha\xi_n|\xi'|^{2m-2})^2}{Q_\alpha(\xi)^3} \Big|_S \\ &= \frac{-2m(2m-1)(1 - |\xi'|^2)^{m-1} + 2\alpha|\xi'|^{2m-2}}{Q_\alpha(\xi')^2} \\ &\quad + 2 \cdot \frac{4m^2(1 - |\xi'|^2)^{2m-1} + 4\alpha^2(1 - |\xi'|^2)|\xi'|^{4m-4} - 8\alpha m|\xi'|^{2m-2}(1 - |\xi'|^2)^m}{Q_\alpha(\xi')^3}. \end{aligned} \quad (77)$$

Analogously we find for $k = 1, \dots, n-1$

$$\begin{aligned}
 \partial_k \frac{1}{Q_\alpha} \Big|_S &= -\frac{\partial_k Q_\alpha}{Q_\alpha^2} \Big|_S = \frac{(2m-2)\alpha \xi_n^2 |\xi'|^{2m-4} \xi_k - 2m |\xi'|^{2m-2} \xi_k}{Q_\alpha(\xi)^2} \Big|_S \\
 &= \frac{(2m-2)\alpha(1-|\xi'|^2) |\xi'|^{2m-4} \xi_k - 2m |\xi'|^{2m-2} \xi_k}{Q_\alpha(\xi')^2}, \\
 \partial_k^2 \frac{1}{Q_\alpha} \Big|_S &= \left(-\frac{\partial_k^2 Q_\alpha}{Q_\alpha^2} + \frac{2(\partial_k Q_\alpha)^2}{Q_\alpha^3} \right) \Big|_S \\
 &= \frac{(2m-2)\alpha \xi_n^2 ((2m-4) |\xi'|^{2m-6} \xi_k^2 + |\xi'|^{2m-4}) - 2m (|\xi'|^{2m-2} + (2m-2) |\xi'|^{2m-4} \xi_k^2)}{Q_\alpha(\xi)^2} \Big|_S \\
 &\quad + 2 \cdot \frac{(2m-2)^2 \alpha^2 \xi_n^4 |\xi'|^{4m-8} \xi_k^2 + 4m^2 |\xi'|^{4m-4} \xi_k^2 - 4m(2m-2) \alpha \xi_n^2 |\xi'|^{4m-6} \xi_k^2}{Q_\alpha(\xi)^3} \Big|_S \\
 &= \frac{(2m-2)\alpha(1-|\xi'|^2) ((2m-4) |\xi'|^{2m-6} \xi_k^2 + |\xi'|^{2m-4}) - 2m (|\xi'|^{2m-2} + (2m-2) |\xi'|^{2m-4} \xi_k^2)}{Q_\alpha(\xi')^2} \\
 &\quad + 2 \cdot \frac{(2m-2)^2 \alpha^2 (1-|\xi'|^2)^2 |\xi'|^{4m-8} \xi_k^2 + 4m^2 |\xi'|^{4m-4} \xi_k^2 - 4m(2m-2) \alpha (1-|\xi'|^2) |\xi'|^{4m-6} \xi_k^2}{Q_\alpha(\xi')^3}.
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 \Delta' \frac{1}{Q_\alpha} \Big|_S &= \sum_{k=1}^{n-1} \partial_k^2 \frac{1}{Q_\alpha} \Big|_S = \frac{(2m-2)(4m-3)\alpha(1-|\xi'|^2) |\xi'|^{2m-4} - 2m(4m-1) |\xi'|^{2m-2}}{Q_\alpha(\xi')^2} \\
 &\quad + \frac{2|\xi'|^{4m-8}}{Q_\alpha(\xi')^3} ((2m-2)^2 \alpha^2 (1-|\xi'|^2)^2 |\xi'|^2 + 4m^2 |\xi'|^6 - 4m(2m-2) \alpha |\xi'|^4 (1-|\xi'|^2)). \quad (78)
 \end{aligned}$$

We insert (76)–(78) into (75) and write it in polar coordinates. Let σ_n denote as before the $(n-1)$ -dimensional volume of the unit sphere in $\mathbb{R}^n$. We obtain

$$\begin{aligned}
 \frac{\Delta G_\alpha(e_n)}{\sigma_{n-1}} &= \int_0^1 \frac{2mr^{2m}}{\sqrt{1-r^2} Q_\alpha(r)} dr \\
 &\quad + \int_0^1 \frac{\log(1-r^2) r^{2m}}{\sqrt{1-r^2}} \left[(2m+2) \left(\frac{-m(1-r^2)^m + \alpha(1-r^2) r^{2m-2}}{Q_\alpha(r)^2} \right) \right. \\
 &\quad + \frac{m}{Q_\alpha(r)} - (2-r^2) \frac{m(2m-1)(1-r^2)^{m-1} - \alpha r^{2m-2}}{Q_\alpha(r)^2} \\
 &\quad + 4(2-r^2) \frac{m^2(1-r^2)^{2m-1} + \alpha^2(1-r^2) r^{4m-4} - 2\alpha m r^{2m-2} (1-r^2)^m}{Q_\alpha(r)^3} \\
 &\quad + \frac{4(1-r^2) r^{4m-6}}{Q_\alpha(r)^3} ((m-1)^2 \alpha^2 (1-r^2)^2 + m^2 r^4 - 2m(m-1) \alpha r^2 (1-r^2)) \\
 &\quad \left. + (1-r^2) \frac{(m-1)(4m-3)\alpha(1-r^2) r^{2m-4} - m(4m-1) r^{2m-2}}{Q_\alpha(r)^2} \right] dr \\
 &= \int_0^1 \frac{2mr^{2m}}{\sqrt{1-r^2} Q_\alpha(r)} dr + \int_0^1 \frac{\log(1-r^2) r^{2m}}{\sqrt{1-r^2}} \left[\frac{m}{Q_\alpha(r)} \right. \\
 &\quad \left. + \frac{N_2(r^2)}{Q_\alpha(r)^2} + \frac{4(1-r^2) N_3(r^2)}{Q_\alpha(r)^3} \right] dr, \quad (79)
 \end{aligned}$$

where

$$\begin{aligned} N_2(t) = & -(2m+2)(1-t)(m(1-t)^{m-1} - \alpha t^{m-1}) \\ & + (2-t)(-m(2m-1)(1-t)^{m-1} + \alpha t^{m-1}) \\ & + (1-t)t^{m-2}((m-1)(4m-3)\alpha(1-t) - m(4m-1)t) \end{aligned} \quad (80)$$

and, after some algebra,

$$\begin{aligned} N_3(t) = & (2-t)(m(1-t)^{m-1} - \alpha t^{m-1})^2 + t^{2m-3}((m-1)\alpha(1-t) - mt)^2 \\ =: & (2-t)R_1(t)^2 + t^{2m-3}R_2(t)^2. \end{aligned} \quad (81)$$

The goal is to understand the behaviour of $\Delta G_\alpha(e_n)$ as $\alpha \uparrow \alpha_m^*$. By Remark 3, we know that $Q_{\alpha_m^*}(r) := Q_{\alpha_m^*}(r, \sqrt{1-r^2}) = \tilde{Q}(r^2)(1 - (1 + \gamma_m)r^2)^2$ where $\tilde{Q}$ is a positive polynomial of degree $m-2$. Actually, it is easy to show that (cf. Lemma 5.1)

$$f(s)|_{\alpha=\alpha_m^*} = s^m - \alpha_m^* s + 1 = \left(\sum_{k=0}^{m-2} \frac{m-1-k}{m-1} \gamma_m^{-k-2} s^k \right) (s - \gamma_m)^2.$$

Therefore, recalling the value of $\gamma_m = (m-1)^{\frac{1}{m}}$ and substituting $s = \frac{1-r^2}{r^2}$, we get

$$Q_{\alpha_m^*}(r) = \left(\sum_{k=0}^{m-2} \frac{m-1-k}{(m-1)^{\frac{m-k-2}{m}}} (1-r^2)^k r^{2m-4-2k} \right) (1 - (1 + \gamma_m)r^2)^2.$$

Notice that the singularity that $Q_{\alpha_m^*}$ would produce at $r_0 := (1 + \gamma_m)^{-1/2}$ is not integrable. Moreover, we shall see that, although the numerator of the second integral in (79) vanishes precisely at the same point, it is not strong enough to compensate such a singularity.

Computation of $\Delta G_{\alpha_m^}(e_n)$.*

Let $t = r^2$, $t_0 := r_0^2 = \frac{1}{1+\gamma_m}$ and define

$$N(t) := mQ_*(t)^2 + N_2(t)Q_*(t) + 4(1-t)N_3(t), \quad (82)$$

where $Q_*(t) := Q_{\alpha_m^*}(\sqrt{t})$.

Step 1: $N(t_0) = 0$.

Because $Q_*(t_0) = 0$, we just need to show that $N_3(t_0) = 0$. First,

$$R_1(t_0) = m \left(\frac{\gamma_m}{1 + \gamma_m} \right)^{m-1} - \alpha_m^* \left(\frac{1}{1 + \gamma_m} \right)^{m-1} = \frac{m\gamma_m^{m-1} - \alpha_m^*}{(1 + \gamma_m)^{m-1}} = 0 \quad (83)$$

by the definitions of α_m^* and γ_m . Moreover,

$$R_2(t_0) = (m-1)\alpha_m^* \frac{\gamma_m}{1+\gamma_m} - m \frac{1}{1+\gamma_m} = \frac{m}{1+\gamma_m} \left((m-1)^{\frac{1}{m}} \gamma_m - 1 \right) = 0. \quad (84)$$

Step 2: $N'(t_0) = 0$.

Since t_0 is a zero of Q_* of order 2,

$$N'(t_0) = 2m Q_*(t_0) Q'_*(t_0) + N'_2(t_0) Q_*(t_0) + N_2(t_0) Q'_*(t_0) + 4(1-t_0) N'_3(t_0) - 4N_3(t_0) = 4(1-t_0) N'_3(t_0).$$

By (81) and (83)–(84) it is clear that $N'_3(t_0) = 0$.

Step 3: $N''(t_0) \neq 0$.

Similarly as before, by (82) and $Q_*(t_0) = Q'_*(t_0) = N_3(t_0) = N'_3(t_0) = 0$ we get

$$N''(t_0) = N_2(t_0) Q''_*(t_0) + 4(1-t_0) N''_3(t_0). \quad (85)$$

Because of (81) and (83)–(84), we have

$$\begin{aligned} N''_3(t_0) &= 2(2-t_0) (R'_1(t_0))^2 + 2t_0^{2m-3} (R'_2(t_0))^2 \\ &= 2 \frac{2\gamma_m+1}{1+\gamma_m} (m-1)^2 \left(\frac{m\gamma_m^{m-2} + m(m-1)^{\frac{1}{m}-1}}{(1+\gamma_m)^{m-2}} \right)^2 + 2 \frac{\left(m(m-1)^{\frac{1}{m}} + m \right)^2}{(1+\gamma_m)^{2m-3}} \\ &= \frac{2m^2}{(1+\gamma_m)^{2m-3}} \left(\left(2(m-1)^{-\frac{1}{m}} + 1 \right) (m-1)^{\frac{2}{m}} \left((m-1)^{\frac{1}{m}} + 1 \right)^2 \right. \\ &\quad \left. + \left((m-1)^{\frac{1}{m}} + 1 \right)^2 \right) = \frac{2m^2}{(1+\gamma_m)^{2m-3}} \left((m-1)^{\frac{1}{m}} + 1 \right)^4. \end{aligned} \quad (86)$$

Next, we may rewrite

$$N_2(t) = -(2m+2)(1-t)R_1(t) + (2-t)M_1(t) + (1-t)t^{m-2}M_2(t), \quad (87)$$

where

$$M_1(t) = -m(2m-1)(1-t)^{m-1} + \alpha_m^* t^{m-1}$$

and

$$M_2(t) = (m-1)(4m-3)\alpha_m^*(1-t) - m(4m-1)t.$$

Evaluating on t_0 , we get

$$\begin{aligned} M_1(t_0) &= \frac{m}{(1+\gamma_m)^{m-1}} \left(-(2m-1)(m-1)^{\frac{1}{m}-1} + (m-1)^{\frac{1}{m}-1} \right) = \frac{-2m(m-1)^{\frac{1}{m}}}{(1+\gamma_m)^{m-1}}, \\ M_2(t_0) &= (m-1)(4m-3)m(m-1)^{\frac{1}{m}-1} \frac{\gamma_m}{1+\gamma_m} - m(4m-1) \frac{1}{1+\gamma_m} = \frac{-2m}{1+\gamma_m}. \end{aligned}$$

Since $R_1(t_0) = 0$, from (87) we infer

$$\begin{aligned} N_2(t_0) &= \frac{2\gamma_m + 1}{1 + \gamma_m} \cdot \frac{-2m(m-1)^{\frac{1}{m}}}{(1 + \gamma_m)^{m-1}} + \frac{\gamma_m}{(1 + \gamma_m)^{m-1}} \cdot \frac{-2m}{1 + \gamma_m} \\ &= \frac{-2m}{(1 + \gamma_m)^m} \left[\left(2(m-1)^{-\frac{1}{m}} + 1 \right) (m-1)^{\frac{1}{m}} + (m-1)^{-\frac{1}{m}} \right] \quad (88) \\ &= \frac{-2m(m-1)^{-\frac{1}{m}}}{(1 + \gamma_m)^m} \left((m-1)^{\frac{1}{m}} + 1 \right)^2. \end{aligned}$$

Next, $Q_{\alpha_m^*}(r, \sqrt{1-r^2})|_{r=\sqrt{t}} = Q_*(t) = t^m - \alpha_m^*(1-t)t^{m-1} + (1-t)^m$, therefore

$$\begin{aligned} Q_*''(t_0) &= m(m-1)(1-t_0)^{m-2} - \alpha_m^*(m-1)(m-2)(1-t_0)t_0^{m-3} \\ &\quad + (2\alpha_m^* + m)(m-1)t_0^{m-2} \\ &= \frac{m(m-1)}{(1 + \gamma_m)^{m-2}} \left[(m-1)^{\frac{2}{m}-1} - (m-1)^{\frac{1}{m}-1}(m-2)(m-1)^{-\frac{1}{m}} \right. \quad (89) \\ &\quad \left. + 2(m-1)^{\frac{1}{m}-1} + 1 \right] = \frac{m}{(1 + \gamma_m)^{m-2}} \left((m-1)^{\frac{1}{m}} + 1 \right)^2. \end{aligned}$$

Hence, according to (85), (86), (88), and (89) we finally obtain

$$N''(t_0) = \frac{6m^2(m-1)^{-\frac{1}{m}}}{(1 + \gamma_m)^{2m-2}} \left((m-1)^{\frac{1}{m}} + 1 \right)^4 > 0.$$

As a consequence of Steps 1–3, we have thus proved that t_0 is a zero of N of order 2 and, moreover, that it is also a minimum, thus $N(t) > 0$ for t close to t_0 . This yields $\Delta G_{\alpha_m^*}(e_n) = -\infty$: indeed, the second integral in (79) has a non-integrable singularity at $r_0 = \sqrt{t_0} \in (0, 1)$ of the kind $(r - r_0)^{-4}$ which prevails on the one in the first integral, of the kind $(r - r_0)^{-2}$. The negative sign comes from $\log(1 - r^2) < 0$ as $r \in (0, 1)$.

Proof of Theorem 1.5 By pointwise convergence $\Delta G_\alpha(e_n) \rightarrow \Delta G_{\alpha_m^*}(e_n)$ as $\alpha \uparrow \alpha_m^*$, we may apply Fatou's lemma and obtain

$$\limsup_{\alpha \uparrow \alpha_m^*} \Delta G_\alpha(e_n) \leq \Delta G_{\alpha_m^*}(e_n) = -\infty$$

and conclude that for $\alpha < \alpha_m^*$ and close to α_m^* one has $\Delta G_\alpha(e_n) < 0$. This behaviour is well observable in Fig. 3, where the graph of $\alpha \mapsto \Delta G_\alpha(e_n)$ is displayed for $m = 2$ (here $\alpha_2^* = 2$).

The proof is completed recalling that $\operatorname{sgn}(K_\alpha(0, e_n)) = \operatorname{sgn}(\Delta G_\alpha(e_n))$, K_α being the fundamental solution of the operator whose symbol is Q_α . $\square$

Fig. 3 The graph of $\Delta G_\alpha(e_n)$ for $m = 2$ with $\alpha \in [0, 1.95]$

Acknowledgements Open Access funding provided by Projekt DEAL.

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